OMRON





Harmonised motor and machine control

MOTOR CONTROL

200% starting torque

- Near stand-still operation (0.5 Hz)
- Smooth control of high inertia loads
- Control of fast cyclic loads

Torque control in open loop

- Ideal for low to medium torque applications
- Can replace a flux vector or servo drive in suitable systems

Motor control

- Surface Permanent Magnet Motor
- Interior Permanent Magnet Motor
- Induction Motor

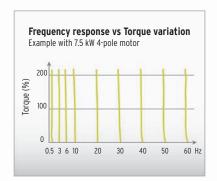
One parameter auto-tuning

 Just by entering the kW rating of the motor the MX2-V1 gives you smooth





Torque master



The MX2-V1 delivers 200% starting torque near stand-still (0.5 Hz) and can operate in torque control in open loop mode. This allows the MX2-V1 to be used in applications where closed loop AC vector drives were previously used.

Easy network integration



Standard industrial networks, such as EtherCAT, CompoNet or DeviceNet as options. High-speed EtherCAT provides solutions for the entire system from input to output with Sysmac Series.

Easy communications setting



Built-in RS-485 Modbus communications. OMRON Function Blocks are available for the CP H/L and CJ-series PLCs. Those control the MX2-V1 via Modbus communications easily.

Safety in Control

Safety is embedded in the MX2-V1, according to ISO 13849-1, Cat. 3, with two safety inputs and an External Device Monitoring (EDM) output.

No external contactors on the motor side are required, meaning simpler wiring for the user.

Safety embedded; ISO 13849-1, Cat. 3



Dual contactors at the output of the inverter are no longer required.

Direct connection to a safety controller ensures compliance to ISO 13849-1 Cat.3 PLd.

Safety function: IEC 61800-5-2 "Safe Torque Off (STO)"

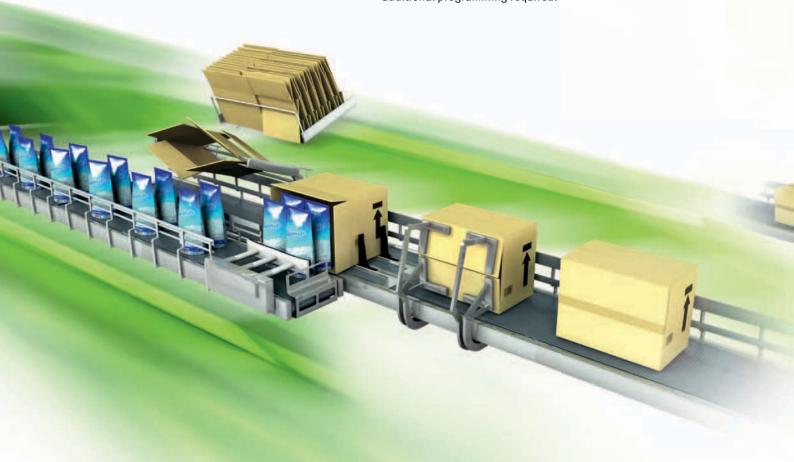
MOTOR CONTROL Permanent magnet motors



The PM motor conforming to highefficiency regulations can be controlled. The PM motor promotes further energy saving and achieves earth-friendly machine control.

Position and run!

The MX2-V1 is a drive and position controller in one, ideal for modular machines where moderate positional accuracy is required. Speed synchronisation is also possible, with no additional programming required.



Speed synchronisation



With no external hardware required, and via standard parameter settings, speed synchronisation can be achieved. The MX2-V1 will act as a speed follower to an external pulse generator/encoder signal up to 32 KHz.

Positioning functionality



Specially developed application functionality enables the MX2-V1 to solve simple positioning tasks without the need for an external controller. Up to 8 positions, plus home, can be selected by the user, and furthermore, the MX2-V1 can be switched between speed and position mode.

Program and play!

The MX2-V1 gives you the power to create smart solutions using PLC functionality, as standard. Via an intuitive flow chart programming tool, you can create programs with up to 1000 lines of code and with 5 tasks running in parallel.



Multi-function Compact Inverter

MX2-Series V1 type

Born to drive machines

- Positioning functionality.
- Fieldbus communications with optional unit EtherCAT, CompoNet and DeviceNet
- Drive Programming.
- Current vector Control.
- High Starting torque: 200% at 0.5 Hz.
- Safety function * EN ISO13849-1 Cat.3 PLd IEC 61800-5-2 "Safe Torque Off (STO)"
- Speed range up to 580 Hz.
- * When optional DeviceNet communication unit or CompoNet communication unit is mounted onto the MX2-series V1 type, the inverter will not conform to the safety standards.



Performance Specifications

Inverter MX2-series V1 type

3-phase 200 V Class

Fun	ction nan	ne					3-	phase 200	V				
Model name	(3G3MX	2-)	A2001-V1	A2002-V1	A2004-V1	A2007-V1	A2015-V1	A2022-V1	A2037-V1	A2055-V1	A2075-V1	A2110-V1	A2150-V1
Applicable motor	kW	СТ	0.1	0.2	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15
	KVV	VT	0.2	0.4	0.75	1.1	2.2	3.0	5.5	7.5	11	15	18.5
capacity	НР	СТ	1/8	1/4	1/2	1	2	3	5	7 1/2	10	15	20
, ,	ПР	VT	1/4	1/2	1	1 1/2	3	4	7 1/2	10	15	20	25
Rated	200 V	СТ	0.2	0.5	1.0	1.7	2.7	3.8	6.0	8.6	11.4	16.2	20.7
output	200 V	VT	0.4	0.6	1.2	2.0	3.3	4.1	6.7	10.3	13.8	19.3	23.9
capacity	240 V	СТ	0.3	0.6	1.2	2.0	3.3	4.5	7.2	10.3	13.7	19.5	24.9
[kVA]	240 V	VT	0.4	0.7	1.4	2.4	3.9	4.9	8.1	12.4	16.6	23.2	28.6
Rated input	voltage				3-	phase 20	0 V - 15%	to 240 V +	- 10%, 50/	60 Hz ± 5	%		
Rated input	current	СТ	1.0	1.6	3.3	6.0	9.0	12.7	20.5	30.8	39.6	57.1	62.6
[A]		VT	1.2	1.9	3.9	7.2	10.8	13.9	23.0	37.0	48.0	68.0	72.0
Rated outpu	ıt voltage	•	3-phase 200 to 240 V (The output cannot exceed the incoming voltage).										
Rated outpu	ıt	СТ	1.0	1.6	3.0	5.0	8.0	11.0	17.5	25.0	33.0	47.0	60.0
current [A]		VT	1.2	1.9	3.5	6.0	9.6	12.0	19.6	30.0	40.0	56.0	69.0
Short-time of braking toro (Discharge R connected)	ue (%)		50	50	50	50	50	20	20	20	20	10	10
Braking Resistor	Regenera braking	ative			Built-i	n Braking	Resistor of	circuit (sep	arate Disc	harge Res	sistor)		
circuit *	Min. cor resistan	nectable ce $[\Omega]$	100	100	100	50	50	35	35	20	17	17	10
Weight [kg]			1.0	1.0	1.1	1.2	1.6	1.8	2.0	3.3	3.4	5.1	7.4
Dimensions (width × height) [mm]			68 ×	128		108	× 128	140 × 128	140 >	× 260	180 × 296	220 × 350	
Dimensions	(depth)	[mm]	10	09	122.5	145.5	17	0.5	170.5	15	55	17	75

^{*} The BRD usage is 10%.

3-phase 400 V Class

Function name							3-phas	e 400 V				
Model name (3G3MX2-)			A4004-V1	A4007-V1	A4015-V1	A4022-V1	A4030-V1	A4040-V1	A4055-V1	A4075-V1	A4110-V1	A4150-V1
Applicable motor capacity	kW	СТ	0.4	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15
	KW	VT	0.75	1.5	2.2	3.0	4.0	5.5	7.5	11	15	18.5
	НР	СТ	1/2	1	2	3	4	5	7 1/2	10	15	20
		VT	1	2	3	4	5	7 1/2	10	15	20	25
Rated	380 V	СТ	1.1	2.2	3.1	3.6	4.7	6.0	9.7	11.8	15.7	20.4
output	360 V	VT	1.3	2.6	3.5	4.5	5.7	7.3	11.5	15.1	20.4	25.0
capacity	480 V	СТ	1.4	2.8	3.9	4.5	5.9	7.6	12.3	14.9	19.9	25.7
[kVA]	400 V	VT	1.7	3.4	4.4	5.7	7.3	9.2	14.5	19.1	25.7	31.5
Rated input	voltage				3-phas	se 380 V -	15% to 48	0 V + 10%	6, 50/60 H	z ± 5%		
Rated input	current	СТ	1.8	3.6	5.2	6.5	7.7	11.0	16.9	18.8	29.4	35.9
[A]		VT	2.1	4.3	5.9	8.1	9.4	13.3	20.0	24.0	38.0	44.0
Rated outpu	ıt voltage	•	3-phase 380 to 480 V (The output cannot exceed the incoming voltage).									
Rated outpu	ut	СТ	1.8	3.4	4.8	5.5	7.2	9.2	14.8	18.0	24.0	31.0
current [A]		VT	2.1	4.1	5.4	6.9	8.8	11.1	17.5	23.0	31.0	38.0
Short-time of braking toro (Discharge R connected)	que (%)		50	50	50	20	20	20	20	20	10	10
Braking Resistor	Regener braking	ative	Built-in Braking Resistor circuit (separate Discharge Resistor)									
circuit *	Min. cor resistar	nnectable ice [Ω]	180	180	180	100	100	100	70	70	70	35
Weight [kg]		1.5	1.6	1.8	1.9	1.9	2.1	3.5	3.5	4.7	5.2	
Dimensions (width × height) [mm]				108 × 128			140 × 128	140	× 260	180	× 296	
Dimensions	(depth)	[mm]	143.5		17	0.5		170.5	15	55	17	75

^{*} The BRD usage is 10%.

1-phase 200 V Class

Fun	ction nar	ne	1-phase 200 V						
Model name	(3G3MX	(2-)	AB001-V1	AB002-V1	AB004-V1	AB007-V1	AB015-V1	AB022-V1	
	Ī.,,,	СТ	0.1	0.2	0.4	0.75	1.5	2.2	
Applicable motor capacity	kW	VT	0.2	0.4	0.55	1.1	2.2	3.0	
	НР	СТ	1/8	1/4	1/2	1	2	3	
	пР	VT	1/4	1/2	3/4	1 1/2	3	4	
Rated	200 V	СТ	0.2	0.5	1.0	1.7	2.7	3.8	
output	200 V	VT	0.4	0.6	1.2	2.0	3.3	4.1	
capacity	240 V	СТ	0.3	0.6	1.2	2.0	3.3	4.5	
[kVA]	240 V	VT	0.4	0.7	1.4	2.4	3.9	4.9	
Rated input voltage			1	-phase 200 \	/ - 15% to 24	0 V + 10%, 5	50/60 Hz ± 59	%	
Rated input	current	СТ	1.3	3.0	6.3	11.5	16.8	22.0	
[A]		VT	2.0	3.6	7.3	13.8	20.2	24.0	
Rated outpu	ut voltage	•	3-phase 200 to 240 V (The output cannot exceed the incoming voltage).						
Rated outpu	ut	СТ	1.0	1.6	3.0	5.0	8.0	11.0	
current [A]		VT	1.2	1.9	3.5	6.0	9.6	12.0	
Short-time of braking toro (Discharge R connected)	que (%)		50	50	50	50	50	20	
Braking Resistor	Regener braking	ative	Built-	in Braking R	esistor circuit	(separate Di	scharge Res	istor)	
circuit *	Min. connectable resistance [Ω]		100	100	100	50	50	35	
Weight [kg]			1.0	1.0	1.1	1.6	1.8	1.8	
Dimensions [mm]	Dimensions (width × height) [mm]			68 × 128		108 × 128			
Dimensions	(depth)	[mm]	10	09	122.5		170.5		

^{*} The BRD usage is 10%.

Function Specifications

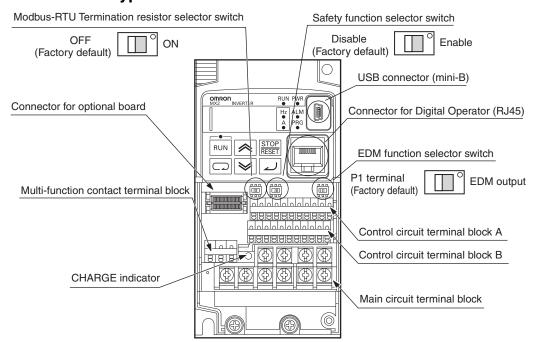
	Function name	Specifications			
Enc	closure ratings *1	Open type (IP20)			
	Control method	Phase-to-phase sinusoidal modulation PWM			
	Output frequency range *2	0.10 to 400 Hz (or 580 Hz in the high-frequency mode; restrictions apply)			
		Digital command: ±0.01% of the max. frequency, Analog command: ±0.2% of the max. frequency			
	Frequency precision *3	(25±10°C)			
	Frequency setting resolution	Digital setting: 0.01 Hz, Analog setting: One-thousandth of the maximum frequency			
_	Voltage/Frequency characteristics	V/f characteristics (constant/reduced torque) Sensorless vector control, V/f control with speed feedback			
Control	Overload current rating	Heavy load rating (CT): 150%/60 s Light load rating (VT): 120%/60 s			
J	Instantaneous overcurrent protection	200% of the value of heavy load rating (CT)			
	Acceleration/Deceleration time	0.01 to 3600 s (linear/curve selection), acceleration/deceleration 2 setting available			
	Carrier frequency adjustment range	2 to 15 kHz (with derating)			
	Starting torque	200%/0.5 Hz (sensorless vector control)			
	External DC injection braking	Starts at a frequency lower than that in deceleration via the STOP command, at a value set lower than that during operation, or via an external input. (Level and time settable).			
Pro	tective functions	Overcurrent, overvoltage, undervoltage, electronic thermal, temperature error, ground fault overcurrent at power-on status, rush current prevention circuit, overload limit, incoming overvoltage, external trip, memory error, CPU error, USP error, communication error, overvoltage suppression during deceleration, protection upon momentary power outage, emergency cutoff, etc.			
=	Frequency settings	Digital Operator External analog input signal: 0 to 10 VDC/4 to 20 mA, Modbus communication (Modbus-RTU)			
Input signal	RUN/STOP command	Digital Operator External digital input signal (3-wire input supported), Modbus communication (Modbus-RTU)			
but	Multi-function input *4	7 points (Functions can be selected from among 68)			
Ξ	Analog input *5	2 points (Voltage FV terminal: 10 bits/0 to 10 V, Current FI terminal: 10 bits/4 to 20 mA)			
	Pulse input	1 point (RP terminal: 32 kHz max., 5 to 24 VDC)			
_	Multi-function output *4	2 points (P1 and P2, Functions can be selected from among 47)			
ign	Relay output *4	1 point (SPDT contact (MC, MA, MB), Functions can be selected from among 47)			
Output signal	Analog output (Frequency monitor) *6	1 point (AM terminal: Voltage 10 bits/0 to 10 V) (Frequency, current selectable)			
ō	Pulse output	1 point (MP terminal: 32 kHz max., 0 to 10 V)			
tions	RS-422	RJ45 connector (for Digital Operator)			
ommunications	RS-485	Control circuit terminal block, Modbus communication (Modbus-RTU)			
Comn	USB	USB1.1, mini-B connector			
Oth	er functions	AVR function, V/f characteristics switching, upper/lower limit, 16-step speeds, starting frequency adjustment, jogging operation, carrier frequency adjustment, PID control, frequency jump, analog gain/bias adjustment, S shape acceleration/deceleration, electronic thermal characteristics, level adjustment, restart function, torque boost function, fault monitor, soft lock function, frequency conversion display, USP function, motor 2 control function, UP/DWN, overcurrent control function, etc.			
nent .	Ambient operating temperature *7	-10 to 50°C (However, derating is required).			
ironn	Ambient storage temperature	-20°C to 65°C			
Operating environment	Ambient operating humidity	20% to 90% RH (with no condensation)			
eratin	Vibration resistance	5.9 m/s ² (0.6G), 10 to 55 Hz			
o	Application environment	At a maximum altitude of 1,000 m; indoors (without corrosive gases or dust)			
Ñ	EtherCAT Communication Unit	3G3AX-MX2-ECT			
Options	CompoNet Communication Unit	3G3AX-MX2-CRT-E			
o	DeviceNet Communication Unit	3G3AX-MX2-DRT-E			
		550 0000 = 200 =			

	F	unction name	Specifications
Oth	er option		DC reactor, AC reactor, radio noise filter, input noise filter, output noise filter, regenerative braking unit, Braking Resistor, etc.
standard		Machinery Directives	EN ISO 13849-1: 2008 Pld EN 61800-5-2 EN 60204-1
	EC directive	EMC Directive	EN 61800-3: 2004
International		Low-voltage Directive	EN 61800-5-1: 2007
Inte	UL/cUL		UL508C

- Protection method complies with JEM 1030.
- To operate the motor at over 50/60 Hz, contact the motor manufacturer to find out the maximum allowable speed of revolution.
- For the stable control of the motor, the output frequency may exceed the maximum frequency set in A004 (A204) by 2 Hz max. In the VT (light load) mode and the PM motor mode, the available functions are limited compared with the CV (heavy load) mode. For some parameters, the default data and setting range also differ.
- *5 By default, the maximum frequency is adjusted to 9.8 V for a voltage input of 0 to 10 VDC and to 19.8 mA for a current input of 4 to 20 mA, respectively. If necessary, adjust the default parameter settings.
- The analog voltage and current values for the multi-function monitor output terminals show values that can only be used as a guide for analog meter connection. The maximum output value may differ from 10 V or 20 mA due to the variability of the analog output circuit. If necessary, adjust the default parameter settings.
- Derating of the rated output current of the inverter may be required depending on the heavy/light load mode selection, operating ambient temperature, side-by-side installation, and carrier frequency setting. Use the inverter in an appropriate environment according to USER'S MANUAL (Cat.No.1585).
- Note: 1. The applicable motor is a 3-phase standard motor. For using any other type, be sure that the rated current does not exceed that of the Inverter.
 - Output voltage decreases according to the level of the power supply voltage.
 - The braking torque at the time of capacitor feedback is an average deceleration torque at the shortest deceleration (when it stops from 50 Hz). It is not a continuous regeneration torque. Also, the average deceleration torque varies depending on the motor loss. The value is reduced in operation over 50 Hz.

Components and Functions

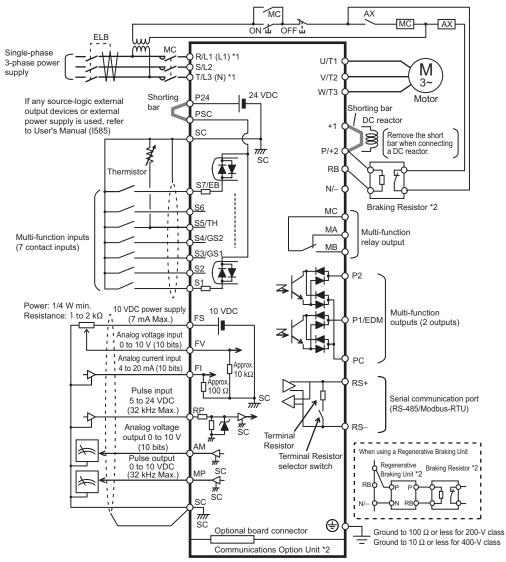
Inverter MX2-series V1 type



Name	Function
Modbus-RTU Termination resistor selector switch	Use this Terminal Resistor selector switch for RS-485 terminals on the control circuit terminal block. When this switch is turned ON, the internal 200Ω Resistor is connected.
Safety function selector switch	Turn this switch ON when using the safety function. Turn OFF the power before turning this switch ON/OFF. For details, refer to USER'S MANUAL (Cat.No.I585).
EDM function selector switch	Turn this switch ON when using the EDM output of the safety function. Turn OFF the power before turning this switch ON/OFF.For details, refer to USER'S MANUAL (Cat.No.I585).
USB connector	Use this mini-B USB connector to connect a PC. Even when the Inverter is being operated by a PC, etc., via USB connection, it can still be operated using the Digital Operator.
Connector for Digital Operator	Use this connector to connect the Digital Operator.
Connector for optional board	Use this connector to mount the optional board. (Communications Units and other options can be connected.)
Control circuit terminal blocks A and B	These terminal blocks are used to connect various digital/analog input and output signals for inverter control, etc.
Multi-function contact terminal block	Use this SPDT contact terminal block for relay outputs.
Main circuit terminal block	Use this terminal block to connect an output to the motor and Braking Resistor, etc. Also, use this terminal block to connect the inverter to the main power supply.
CHARGE indicator (Charge indicator LED)	This LED indicator is lit if the DC voltage of the main circuit (between terminals P/+2 and N/-) remains approx. 45 V or above after the power has been cut off. Before wiring, etc. confirm that the Charge LED indicator is turned OFF.

Note: This illustration shows the terminal block with the front cover removed.

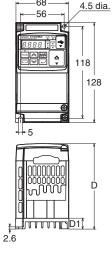
Connection Diagram

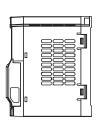


^{*1} Connect to terminals L1 and N on a single-phase, 200-V Inverter (3G3MX2-AB $\Box\Box$ -V1).

Dimensions (Unit: mm)

3G3MX2-AB001-V1 3G3MX2-AB002-V1 3G3MX2-AB004-V1 3G3MX2-A2001-V1 3G3MX2-A2002-V1 3G3MX2-A2004-V1 3G3MX2-A2007-V1

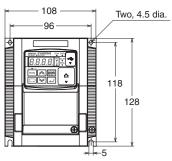


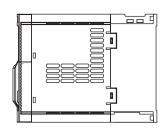


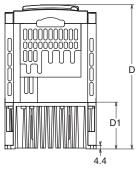
Power supply	Model	W [mm]	H [mm]	D [mm]	D1 [mm]
1-phase	3G3MX2-AB001-V1 3G3MX2-AB002-V1			109	13.5
200 V	3G3MX2-AB004-V1			122.5	27
3-phase	3G3MX2-A2001-V1 3G3MX2-A2002-V1	68	128	109	13.5
200 V	3G3MX2-A2004-V1			122.5	27
	3G3MX2-A2007-V1			145.5	50

^{*2} Optional.

3G3MX2-AB007-V1 3G3MX2-AB015-V1 3G3MX2-AB022-V1 3G3MX2-A2015-V1 3G3MX2-A2022-V1 3G3MX2-A4004-V1 3G3MX2-A4007-V1 3G3MX2-A4015-V1 3G3MX2-A4022-V1 3G3MX2-A4030-V1

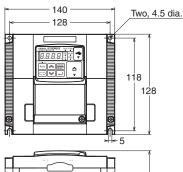


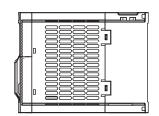


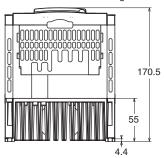


Power supply	Model	W [mm]	H [mm]	D [mm]	D1 [mm]
1-phase 200 V	3G3MX2-AB007-V1 3G3MX2-AB015-V1 3G3MX2-AB022-V1			170.5	55
3-phase 200 V	3G3MX2-A2015-V1 3G3MX2-A2022-V1	108	100		
	3G3MX2-A4004-V1	108	128	143.5	28
3-phase 400 V	3G3MX2-A4007-V1 3G3MX2-A4015-V1 3G3MX2-A4022-V1 3G3MX2-A4030-V1			170.5	55

3G3MX2-A2037-V1 3G3MX2-A4040-V1

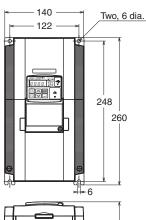


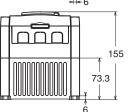




Power supply	Model	W [mm]	H [mm]	D [mm]	D1 [mm]
3-phase 200 V	3G3MX2-A2037-V1	140	128	170.5	55
3-phase 400 V	3G3MX2-A4040-V1	140	120	170.5	55

3G3MX2-A2055-V1 3G3MX2-A2075-V1 3G3MX2-A4055-V1 3G3MX2-A4075-V1

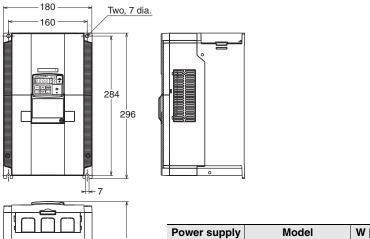




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Power supply	Model	W [mm]	H [mm]	D [mm]	D1 [mm]
3-phase 200 V	3G3MX2-A2055-V1 3G3MX2-A2075-V1	140	260	155	73.3
3-phase 400 V	3G3MX2-A4055-V1 3G3MX2-A4075-V1	140	200	155	73.3

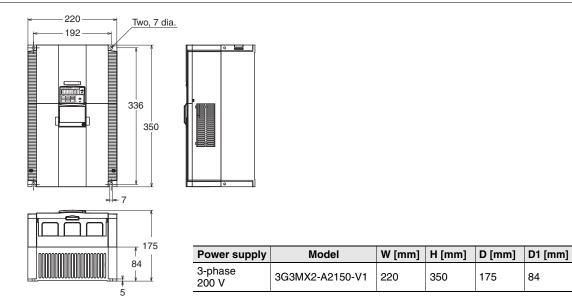
3G3MX2-A2110-V1 3G3MX2-A4110-V1 3G3MX2-A4150-V1



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		175 97
	5	

Power supply	Model	W [mm]	H [mm]	D [mm]	D1 [mm]
3-phase 200 V	3G3MX2-A2110-V1	180	296	175	97
3-phase 400 V	3G3MX2-A4110-V1 3G3MX2-A4150-V1	100	290	175	97

3G3MX2-A2150-V1



Communication Unit

MX2-Series EtherCAT Communication Unit 3G3AX-MX2-ECT

This is the communication unit to connect the Multi-function Compact Inverter MX2 to EtherCAT network. This communication unit passed the conformance test of EtherCAT.

Common Specifications

Item		Specifications					
Power supply		Supplied from the inverter					
Protective struct	ure	Open type (IP20)					
Ambient operating temperature		−10 to +50°C					
Ambient storage temperature		-20 to +65°C					
Ambient operating humidity		20% to 90% RH (with no condensation)					
Vibration resistance		5.9 m/s ² (0.6 G), 10 to 55 Hz					
Application envir	onment	At a maximum altitude of 1,000 m; indoors (without corrosive gases or dust)					
Weight		100 g max.					
UL/cUL		UL508C					
International standard	EC directive	EMC Directive :EN61800-3: 2004 Low Voltage Directive :EN61800-5-1: 2003					

EtherCAT Communications Specifications

Item	Specifications
Communications standard	IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile
Physical layer	100BASE-TX (IEEE802.3)
Connector	RJ45 × 2 (shielded type) ECAT IN : EtherCAT input ECAT OUT : EtherCAT output
Communications media	Category 5 or higher (cable with double, aluminum tape and braided shielding) is recommended.
Communications distance	Distance between nodes: 100 m max.
Process data	Fixed PDO mapping PDO mapping
Mailbox (CoE)	Emergency messages, SDO, SDO responses, and information
Distributed clock	FreeRun mode (asynchronous)
LED display	L/A IN (Link/Activity IN) × 1 L/A OUT (Link/Activity OUT) × 1 RUN × 1 ERR × 1
CiA402 drive profile	Velocity mode

EtherCAT Communication Unit Version Information

As a Sysmac Device, the MX2-series Multi-function Compact Inverter is designed to provide optimal functionality and enhanced operability when used in conjunction with a Machine Automation Control such as NJ/NX series and the automation software Sysmac Studio.

Unit Versions

Unit	Model	Unit version				
Offit	Wiodei	Ver.1.0	Ver1.1			
EtherCAT Communication Unit for MX2-Series	3G3AX-MX2-ECT	G3AX-MX2-ECT Supported Su				
Compatible Sysmac Studio version (To connect the NJ Controller)		Version1.05 or higher*	Version1.05 or higher			
Compatible Sysmac Studio version (To connect the NX Controller)		Version1.13 or higher*	Version1.13 or higher			

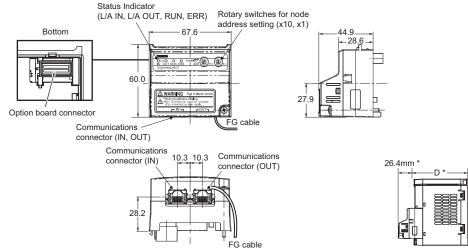
^{*} The function that was enhanced by the upgrade for Unit version1.1 can not be used. For detail, refer to "Function Support by Unit Version".

Function Support by Unit Version

Unit Model Unit version Item	Unit version 1.0	Unit version 1.1
Store-function of back-up number of parameters	Not supported	Supported
Initializing function as parameters.	Not supported	Supported

Dimensions (Unit: mm)





^{*}After the EtherCAT Communication Unit is installed, dimension D of the inverter increases by 26.4 mm.

(Dimension D of the inverter varies depending on the capacity. Refer to the MX2-series V1 type USER'S MANUAL (Cat.No.I585))

MX2-Series CompoNet Communication Unit 3G3AX-MX2-CRT-E

This is the communication unit to connect the Multi-function Compact Inverter MX2 to CompoNet network.

Common Specification

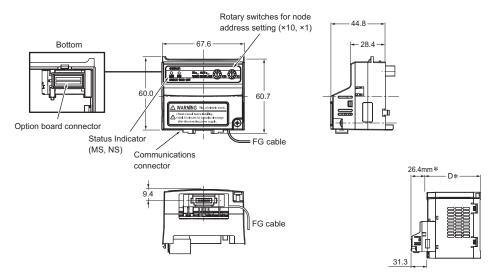
Item		Specification				
Power supply		Supplied from the inverter				
Protective structure		IP20				
Ambient operating temperature		– 10 to 50 °C				
Ambient storage temperature		– 20 to 65 °C				
Ambient operating humidity		20 to 90%RH (with no condensation)				
Vibration resistance		5.9m/s ² (0.6G), 10 to 55Hz				
Application environment		At a maximum altitude of 1,000 m; indoors (without corrosive gases or dust)				
Insulation resistance		500VAC (between isolated circuits)				
Weight		Approx. 170g				
UL/cUL		UL508				
International standard	50 II II	EN61800-3: 2004 (2004/108/EC) Second environment, Category C3				
	EC directive	EN61800-5-1: 2007 (2006/95/EC) SELV				

CompoNet Communications Specifications

Item	Specification
Slave type	Word Slave Unit (Mixed)
Certification	CompoNet Conformance Tested
CompoNet Profile	AC Drive (0x02)
Node Address	0 to 63, set with inverter parameter P190 or the rotary switches.
Communication power supply	- (External power not required)
Baud rates supported	4 Mbps, 3 Mbps, 1.5 Mbps, 93.75 kbps. Automatically detecting baud rate of Master Unit
Default Connection path	Supported, set with inverter parameter P046
Supported Assemblies	Basic Remote IO (Output assembly 20, Input assembly 70) Extended Speed IO (21, 71) Extended Speed and Torque Control (123, 173) Special IO (100, 150) Extended Control IO (101, 151) Extended Control IO and Multi function IO monitor (101, 153) Flexible Format (139, 159) Extended Speed and Acceleration Control (110, 111)
EDS file	Depending on the MX2 inverter model

Dimensions (Unit: mm)

3G3AX-MX2-CRT-E



^{*} After the CompoNet Communication Unit is installed, dimension D of the inverter increases by 26.4 mm. (Dimension D of the inverter varies depending on the capacity. Refer to the MX2-series V1 type USER'S MANUAL (Cat.No.I585))

MX2-Series DeviceNet Communication Unit 3G3AX-MX2-DRT-E

This is the communication unit to connect the Multi-function Compact Inverter MX2 to DeviceNet network.

Common Specification

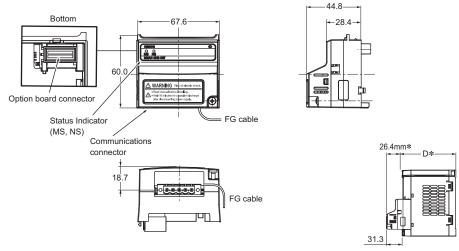
Item		Specification				
Power supply		Supplied from the inverter				
Protective structure		P20				
Ambient operating temperature		- 10 to 50 °C				
Ambient storage temperature		- 20 to 65 °C				
Ambient operating humidity		20 to 90%RH (with no condensation)				
Vibration resistance		5.9m/s ² (0.6G), 10 to 55Hz				
Application environment		At a maximum altitude of 1,000 m; indoors (without corrosive gases or dust)				
Insulation resistance		500VAC (between isolated circuits)				
Weight		Approx. 170g				
UL/cUL		UL508				
International standard	EQ discouling	EN61800-3: 2004 (2004/108/EC) Second environment, Category C3				
	EC directive	EN61800-5-1: 2007 (2006/95/EC) SELV				

DeviceNet Communications Specifications

Item	Specification
Certification	DeviceNet Conformance Tested
DeviceNet Profile	AC Drive (0x02)
Supported connections	Remote I/O: Master-Slave connection Poll Bit-Strobe COS Cyclic Explicit Messages Conform to DeviceNet specifications
Communication power supply	11 to 25VDC (MAX 50 mA, type 20 mA)
Unit device address range	MAC ID 0 to 63, set with inverter parameter P192
Baud rates supported	125, 250, or 500kbps. Automatically detects baud rate of Master Unit.
Default Connection path	Supported, set with inverter parameter P046
Supported Assemblies	Basic Remote IO (Output assembly 20, Input assembly 70) Extended Speed IO (21, 71) Extended Speed and Torque Control (123, 173) Special IO (100, 150) Extended Control IO (101, 151) Extended Control IO and Multi function IO monitor (101, 153) Flexible Format (139, 159) Extended Speed and Acceleration Control (110, 111) In case the DeviceNet master is configured using user allocation, only the input / output pairs can be configured.
EDS file	Depending on the MX2 Inverter model

Dimensions (Unit: mm)

3G3AX-MX2-DRT-E



* After the DeviceNet Communication Unit is installed, dimension D of the inverter increases by 26.4 mm. (Dimension D of the inverter varies depending on the capacity. Refer to the MX2-series V1 type USER'S MANUAL (Cat.No.I585))

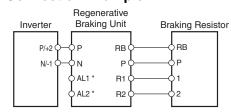
Options

Regenerative Braking Unit 3G3AX-RBU□□

Used with a Braking Resistor when the deceleration time of the motor is needed to be reduced in the MX2.



Connection Example



The alarm output terminals for the Regenerative Braking Unit.

Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the built-in resistor or optional Braking Resistor is activated.

Specifications

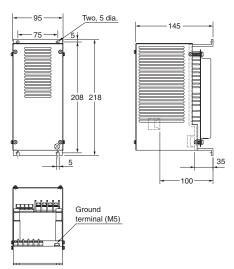
Built-in Resistance Type (3G3AX-RBU21/-RBU22/-RBU41)

Class		3-phase 2	00-V class	3-phase 400-V class		
N	Model name (3G3AX-)	RBU21	RBU22	RBU41*1		
Connection res	sistance	17 Ω min. 17 Ω min.		34 Ω min.		
Operating voltage ON/OFF		ON: 362.5 ± 5 V OFF: 355 ± 5 V (-5% or -10% setting available)	ON: 725 ± 5 V OFF: 710 ± 5 V (-5% or -10% setting available)			
Operation indi	cation	LED ON (Lit)				
Parallel interlo	cking operation function*2	5 units max.				
	Internal resistance	120 W, 180 W	120 W, 20 W	120 W, 180 W x 2 in series		
	Allowable consecutive ON time	10 s max.	0.5 s max.	10 s max.		
Built-in resistor	Allowable operation cycle	Cycle 1/10 (ON for 10 s, OFF for 90 s)	Cycle 1/80 (ON for 0.5 s, OFF for 40 s)	Cycle 1/10 (ON for 10 s, OFF for 90 s)		
	Power consumption	Instantaneous 0.73 kW Short-time rating 120 W	Instantaneous 6.6 kW Short-time rating 120 W	Instantaneous 1.46 kW Short-time rating 240 W		
Protective function	Built-in resistor overheat protection	Cooling fin temperatureRelay ope Recovers at approximately 170°C c Built-in temperature fuse (recover) Rating of contact250 V AC 200mA 12 V DC 500mA (R load) VDC 200mA (R load) Minimum load1mA (R load)	r lower. y impossible)* ³	igher.		
	Ambient temperature	-10 to 50°C				
	Ambient storage temperature	-20 to 65°C				
Operating environment	Ambient operating humidity	20% to 90% (with no condensation)				
CHAILOIMIEUL	Vibration	5.9 m/s ² (0.6G) 10 to 55 Hz				
	Location	At a maximum altitude of 1,000 m (without corrosive gases or dust)				
Paint color	•	Munselle 5Y7/1 (cooling fan: aluminum ground color)				

To use the braking resistor (Model: 3G3AX-RAB/RBB/RBC) for the 400-V class regenerative braking unit, be sure to remove the built-in resistor and connect two resistors of the same model in series. Using a 400-V class regenerative braking unit with only a single braking resistor connected may cause damage to the braking

Dimensions (Unit: mm)

3G3AX-RBU21/-RBU22/-RBU41



Use DIP switches to set the number of connected units.

The built-in resistor has a thermal fuse. If the alarm terminals are not connected, the fuse may blow out in order to prevent the resistor from burning due to overheating. If the fuse blows out, the built-in resistor must be replaced.

Braking Resistor 3G3AX-RBA/-RBB/-RBC

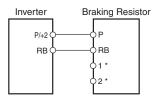
Consumes the regenerative motor energy with a resistor to reduce deceleration time.







Connection Example



* The alarm output terminals for the Braking Resistor. Provide a circuit to turn off the primary power supply for the Inverter when the temperature relay of the Braking Resistor is activated.

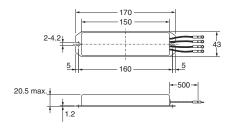
Specifications

Model		(3		ct type BA□□□	□)	(3		rd type BB□□□	□)		um capacity BAX-RBC⊟		
		1201	1202	1203	1204	2001	2002	3001	4001	4001	6001	12001	
Resistance	Capacity		120) W		200) W	300 W	400 W	400 W	600 W	1200 W	
Resistance	Resistance (W)	180	100	50	35	180	100	50	35	50	35	17	
Allowable braking	ngfrequency (%)	5	2.5	1.5	1.0	10	7.5	7.5	7.5		10		
Allowable contin	nuousbraking time (s)	20	12	5	3		30		20		10		
Weight (kg)			0.	27		0.	97	1.68	2.85	2.5	3.6	6.5	
Fault detection function		Minimur Normall	Built-in thermal (Contact capacity: 240 V AC 2 A max.) Minimum current: 5 mA, Normally ON (NC contact) Built-in temperature fuse (recovery impossible)*					Built-in temperature relay, Normally ON (NC contact) Contact capacity:240 V AC 3 A (R load), 0.2 A (L load), 36 V DC 2 A (R load)					
	Ambient operating temperature	-10 to 50°C											
	Ambient storage temperature	-20 to 65°C											
General specifications	Ambient operating humidity	20% to	20% to 90% (RH) with no condensation										
	Vibration	5.9 m/s	(0.6 G) 1	0 to 55 H	Iz Compl	ies with .	IISC0911						
	Location	At a ma	ximum al	titude of	1,000 m	(without o	corrosive	gases or	dust)				
	Cooling method	Self-cod	ling										

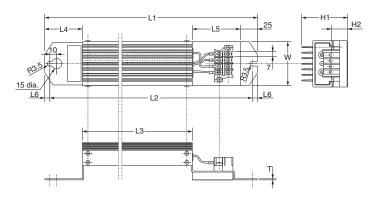
^{*} Built-in resistors are equipped with thermal fuses. If the alarm is not connected, the fuse may blow to prevent burnout due to overheating. If the fuse blows, the built-in resistor will need to be replaced.

Dimensions (Unit: mm)

3G3AX-RBA



3G3AX-RBB



	Model	Dimensions (mm)						
G3AX-RBC4001	Wodel	L1	L2	L3	L4	L5	L6	
	3G3AX-RBB2001	310	295	160	55	70	7.5	
100 — 100 —	3G3AX-RBB2002	310	295	160	55	70	7.5	
	3G3AX-RBB3001	470	455	320	55	70	7.5	

3G3AX-RBB4001

Model	1	Dimensio	ons (mm)	Weight	Screw	
Wodei	H1	H2	W	Т	(kg)	size	
3G3AX-RBB2001	67	12	64	1.6	0.97		
3G3AX-RBB2002	67	12	64	1.6	0.97	M3.5	
3G3AX-RBB3001	67	12	64	1.6	1.68	IVIS.5	
3G3AX-RBB4001	94	15	76	2	2.85		

422

300

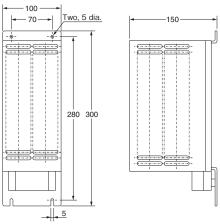
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60

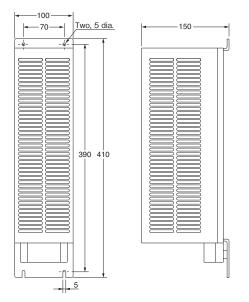
6.5

435

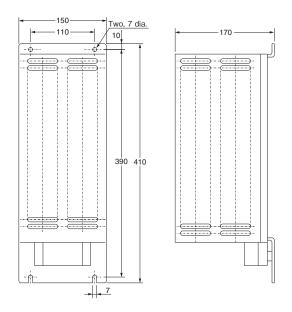
3G



3G3AX-RBC6001

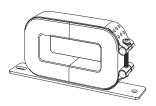


3G3AX-RBC12001



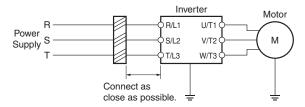
Radio Noise Filter 3G3AX-ZCL□

Connected to the inverter input/output cables to reduce noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line.





Connection Example



Note 1: Wind each of three phase wires in the same direction. 2: Can be used on both the input and output sides of the Inverter.

Specifications 3G3AX-ZCL1

Applicable		200 V	class			400 V	class	
Inverter	In	put	ou	tput	In	put	ou	tput
capacity (kW)	Quan- tity	No. of turns						
0.2	1	4	1	4		_	_	
0.4	1	4	1	4	1	4	1	4
0.75	1	4	1	4	1	4	1	4
1.5	1	4	1	4	1	4	1	4
2.2	1	4	1	4	1	4	1	4
3.0	1	4	1	4	1	4	1	4
3.7	1	4	1	1 4		_		_
4.0		_		_	1	4	1	4
5.5	1	4	1	4	1	4	1	4
7.5	1	4	1	4	1	1 4		4
11	1	3	1	3	1 4		1	4
15	1	2	1	2	1	4	1	4

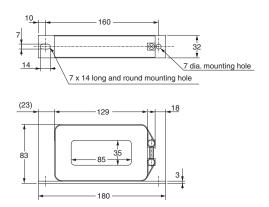
Specifications 3G3AX-ZCL2

Applicable		200 V	class			400 V	class		
Inverter	In	put	ou	tput	In	put	ou	tput	
capacity (kW)	Quan- tity	No. of turns							
0.1	1	4	1	4			_		
0.2	1	4	1	4		_			
0.4	1	4	1	4	1	4	1	4	
0.75	1	4	1	4	1	4	1	4	
1.5	1	4	1	4	1	4	1	4	
2.2	1	4	1	4	1	4	1	4	
3.0	1	4	1	4	1	4	1	4	
3.7	1	4	1	4		_		_	
4.0		_		_	1 4		1	4	
5.5	1	3	1	3	1 4		1	4	
7.5	1	2	1	2	1	4	1	4	

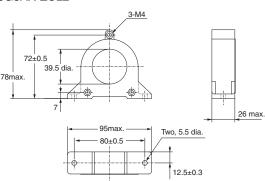
Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

Dimensions (Unit: mm)

3G3AX-ZCL1

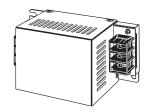


3G3AX-ZCL2

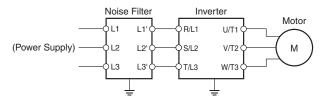


Input Noise Filter 3G3AX-NFI□□

Reduces noise coming into the inverter from the power supply line and noise flowing from the inverter into the power supply line. Connect as close to the Inverter as possible.



Connection Example



Specifications

Power supply	Model	Inverter model	Rated input current In (A) at an ambient temperature of 50°C	Powerloss (W)	Leakage current (mA/phase) at 60 Hz
	3G3AX-NFI21	3G3MX2-A2001-V1	3×6 A	3	< 1.5 (250 V)
	3G3AX-NFI21	3G3MX2-A2002-V1	3×6 A	3	< 1.5 (250 V)
	3G3AX-NFI21	3G3MX2-A2004-V1	3×6 A	3	< 1.5 (250 V)
	3G3AX-NFI22	3G3MX2-A2007-V1	3×10 A	4	< 1.5 (250 V)
3-phase 200	3G3AX-NFI23	3G3MX2-A2015-V1	3×20 A	6	< 1.5 (250 V)
VÁC	3G3AX-NFI23	3G3MX2-A2022-V1	3×20 A	6	< 1.5 (250 V)
	3G3AX-NFI24	3G3MX2-A2037-V1	3×30 A	9	< 1.5 (250 V)
	3G3AX-NFI25	3G3MX2-A2055-V1	3×40 A	12	< 1.5 (250 V)
	3G3AX-NFI26	3G3MX2-A2075-V1	3×60 A	17	< 1.5 (250 V)
	3G3AX-NFI27	3G3MX2-A2110-V1	3×80 A	21	< 1.5 (250 V)
	3G3AX-NFI21	3G3MX2-AB001-V1	3×6 A	3	< 1.5 (250 V)
	3G3AX-NFI21	3G3MX2-AB002-V1	3×6 A	3	< 1.5 (250 V)
1 000	3G3AX-NFI22	3G3MX2-AB004-V1	3×10 A	4	< 1.5 (250 V)
1-phase 200 VAC	3G3AX-NFI23	3G3MX2-AB007-V1	3×20 A	6	< 1.5 (250 V)
	3G3AX-NFI24 3G3AX-NFI23*	3G3MX2-AB015-V1	3 × 30 A 3 × 20 A	9 6	< 1.5 (250 V)
	3G3AX-NFI24	3G3MX2-AB022-V1	3×30 A	9	< 1.5 (250 V)
	3G3AX-NFI41	3G3MX2-A4004-V1	3×7 A	2	< 7.5 (480 V)
	3G3AX-NFI41	3G3MX2-A4007-V1	3×7 A	2	< 7.5 (480 V)
	3G3AX-NFI41	3G3MX2-A4015-V1	3×7 A	2	< 7.5 (480 V)
	3G3AX-NFI42	3G3MX2-A4022-V1	3×10 A	4	< 7.5 (480 V)
3-phase 400	3G3AX-NFI42	3G3MX2-A4030-V1	3×10 A	4	< 7.5 (480 V)
VÁC	3G3AX-NFI43	3G3MX2-A4040-V1	3×20 A	6	< 7.5 (480 V)
	3G3AX-NFI43	3G3MX2-A4055-V1	3×20 A	6	< 7.5 (480 V)
	3G3AX-NFI44	3G3MX2-A4075-V1	3 × 30 A	9	< 7.5 (480 V)
	3G3AX-NFI45	3G3MX2-A4110-V1	3 × 40 A	12	< 7.5 (480 V)
	3G3AX-NFI46	3G3MX2-A4150-V1	3×50 A	15	< 7.5 (480 V)

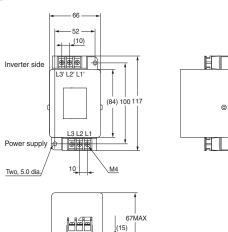
^{*} With the 3G3AX-NFI23, only the CT rating is supported.

Model	Case enclosure rating	Terminal size	Wire dia.	Weight (kg)
3G3AX-NFI21	Plastic, IP00	M4	1.25 mm ²	0.5
3G3AX-NFI22	Plastic, IP00	M4	2 mm²	0.6
3G3AX-NFI23	Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
3G3AX-NFI24	Plastic, IP00	M4	5.5 mm ²	0.8
3G3AX-NFI25	Plastic, IP00	M5	8 mm²	1.4
3G3AX-NFI26	Plastic, IP00	M5	14 mm ²	1.8
3G3AX-NFI27	Metal, IP00	M6	22 mm ²	3.6
3G3AX-NFI41	Plastic, IP00	M4	1.25 mm², 2 mm²	0.7
3G3AX-NFI42	Plastic, IP00	M4	2 mm²	0.7
3G3AX-NFI43	Plastic, IP00	M4	2 mm², 3.5 mm²	0.7
3G3AX-NFI44	Plastic, IP00	M4	5.5 mm ²	0.8
3G3AX-NFI45	Plastic, IP00	M5	8 mm²	1.4
3G3AX-NFI46	Plastic, IP00	M5	14 mm ²	1.6

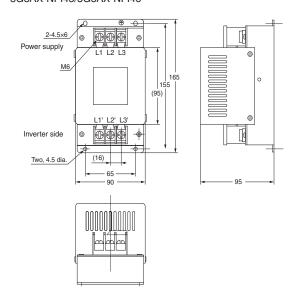
Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

Dimensions (Unit: mm)

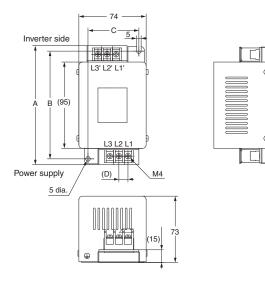




3G3AX-NFI25/3G3AX-NFI26 3G3AX-NFI45/3G3AX-NFI46

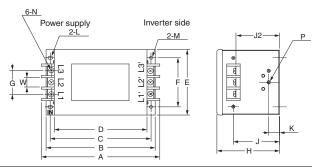


3G3AX-NFI23/3G3AX-NFI24 3G3AX-NFI41/3G3AX-NFI42 3G3AX-NFI43/3G3AX-NFI44



Model		Dimension	ons (mm)	
wodei	Α	В	С	D
3G3AX-NFI23	128	118	56	10
3G3AX-NFI24	144	130	56	11
3G3AX-NFI41	144	130	56	11
3G3AX-NFI42	144	130	56	11
3G3AX-NFI43	144	130	56	11
3G3AX-NFI44	144	130	56	11

3G3AX-NFI27



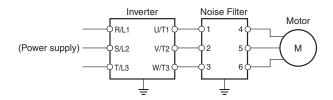
Model								Dim	ensions	s (mm)						
Model	Α	В	С	D	E	F	G	Н	J	J2	K	L	М	N	Р	W
3G3AX-NFI27	217	200	185	170	120	90	44	115	85	82	20	R2.75 Length 7	5.5 dia.	M6	M4	17

Output Noise Filter 3G3AX-NFO

Reduces noise generated by the Inverter. Connect as close to the Inverter as possible.



Connection Example

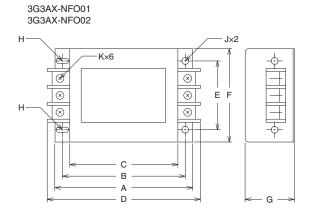


Specifications

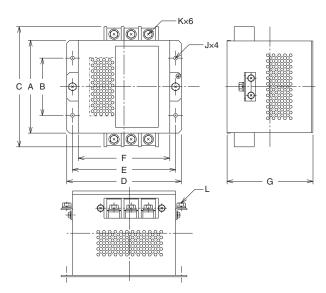
		Rated		Inverter model		Weight
Power supply	Model	current (A)	3-phase AC 200 V class	1-phase AC 200 V class	3-phase AC 400 V class	Weight (kg)
	3G3AX-NFO01	6	3G3MX2-A2001-V1 /-A2002-V1/-A2004-V1	3G3MX2-AB001-V1 /-AB002-V1 /-AB004-V1	3G3MX2-A4004-V1 /-A4007-V1	0.7
3-phase, 3-wire	3G3AX-NFO02	12	3G3MX2-A2007-V1 /-A2015-V1	3G3MX2-AB007-V1 /-AB015-V1	3G3MX2-A4015-V1 /-A4022-V1/-A4030-V1	0.9
Rated voltage 500 VAC	3G3AX-NFO03	25	3G3MX2-A2022-V1 /-A2037-V1	3G3MX2-AB022-V1	3G3MX2-A4040-V1 /-A4055-V1/-A4075-V1	2.1
	3G3AX-NFO04	50	3G3MX2-A2055-V1 /-A2075-V1	-	3G3MX2-A4110-V1 /-A4150-V1	3.7
	3G3AX-NFO05	75	3G3MX2-A2110-V1 /-A2150-V1	_	_	5.7

Note: Select options by the maximum applicable motor capacity of heavy and light load rating.

Dimensions (Unit: mm)



3G3AX-NFO03/3G3AX-NFO04/3G3AX-NFO05



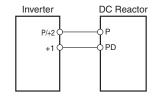
Model	Α	В	С	D	E	F	G	Н	J	K	L
3G3AX-NFO01	140	125	110	156	70	95	50	R: 2.25mm Length: 6mm	4.5 mm dia.	M4	-
3G3AX-NFO02	160	145	130	176	80	110	70	R: 2.75mm Length: 7mm	5.5 mm dia.	M4	-
3G3AX-NFO03	112	80	154	160	145	130	120	_	6.5 mm dia.	M4	-
3G3AX-NFO04	162	100	210	200	180	160	150	_	6.5 mm dia.	M5	M5
3G3AX-NFO05	182	100	230	220	200	180	170	_	6.5 mm dia.	M6	M6

DC Reactor 3G3AX-DL

Used to suppress harmonic current generated from the Inverter.

Suppresses harmonic current better than the AC Reactor and can be used with the AC Reactor.

Connection Example



Specifications

		Inv	erter			DC reactor specifications						
Voltage class	Max. applicable motor capacity (kW)	Model	Heavy load: CT, Light load: VT mode	Max. applicable motor capacity (kW)	Rated input current (A)	Model	Inductance (mH)	Heat generation (W)	Operating ambient temperature/ humidity	Location		
	0.1	3G3MX2-	Heavy load *	0.1	1.0	20241/						
	0.1	A2001-V1	Light load	0.2	1.2	3G3AX- DL2002	21.4					
	0.2	3G3MX2-	Heavy load *	0.2	1.6	DLEOOL		8				
	0.2	A2002-V1	Light load	0.4	1.9	3G3AX-	10.7					
	0.4	3G3MX2-	Heavy load *	0.4	3.3	DL2004	10.7					
	0.4	A2004-V1	Light load	0.75	3.9	3G3AX-	6.75					
	0.75	3G3MX2-	Heavy load *	0.75	6.0	DL2007	0.75	10				
	0.75	A2007-V1	Light load	1.1	7.2	3G3AX-	3.51	10				
	1.5	3G3MX2-	Heavy load *	1.5	9.0	DL2015	3.51			At an		
	1.5	A2015-V1	Light load	2.2	10.8	3G3AX-	2.51	13		altitude of		
3-phase	2.2	3G3MX2-	Heavy load *	2.2	12.7	DL2022	2.51	13	-10 to 50°C	1,000 m max.;		
200-V	2.2	A2022-V1	Light load	3.0	13.9	3G3AX-	1.60	20	-10 to 50 C	indoors		
class		3G3MX2-	Heavy load *	3.7	20.5	DL2037	1.00	20	20% to 90%	(without		
	3.7	A2037-V1	Light load	5.5	23.0	3G3AX- DL2055	1.11	26		corrosive gases or dust)		
	5.5	3G3MX2-	Heavy load *	5.5	30.8					dust)		
	5.5	5 A2055-V1	Light load	7.5	37.0	3G3AX- DL2075	0.84	36				
	7.5	3G3MX2-	Heavy load *	7.5	39.6	DLLLOTO						
	7.5	A2075-V1	Light load	11	48.0	3G3AX-	0.50	50				
	44	3G3MX2-	Heavy load *	11	57.1	DL2110	0.59	52 60				
	11	A2110-V1	Light load	15	68.0	3G3AX-	0.44		-			
		3G3MX2-	Heavy load *	15	62.6	DL2150	0.44	60				
	15	A2150-V1	Light load	18.5	72.0	3G3AX- DL2220	0.30	63				
	0.4	3G3MX2-	Heavy load *	0.1	1.3							
	0.1	AB001-V1	Light load	0.2	2.0	3G3AX- DL2002	21.4					
	0.0	3G3MX2-	Heavy load *	0.2	3.0	DLZOOZ		8				
	0.2	AB002-V1	Light load	0.4	3.6	3G3AX-	10.7			At an		
	0.4	3G3MX2-	Heavy load *	0.4	6.3	DL2004	10.7			altitude of 1,000 m		
Single-	0.4	AB004-V1	Light load	0.55	7.3	3G3AX-	0.75		−10 to 50°C	max.;		
phase 200-V	0.75	3G3MX2-	Heavy load *	0.75	11.5	DL2007	6.75	10		indoors		
Class	0.75	AB007-V1	Light load	1.1	13.8	3G3AX-	0.54	10	20% to 90%	(without corrosive		
	4.5	3G3MX2-	Heavy load *	1.5	16.8	8 DL2015	3.51			gases or		
	1.5	AB015-V1	Light load	2.2	20.2		0.54	10	1	dust)		
		000111/0	Heavy load *	2.2	22.0	DLCCCC	2.51	13				
			3G3MX2- AB022-V1	Light load	3.0	24.0	3G3AX- DL2037	1.60	20			

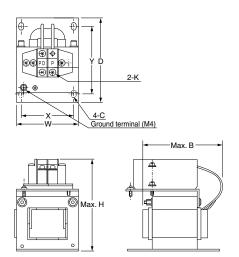
		Inv	erter				DC	reactor spe	cifications	
Voltage class	Max. applicable motor capacity (kW)	Model	Heavy load: CT, Light load: VT mode	Max. applicable motor capacity (kW)	Rated input current (A)	Model	Inductance (mH)	Heat generation (W)	Operating ambient temperature/ humidity	Location
	0.4	3G3MX2- A4004-V1	Heavy load *	0.4	1.8	3G3AX- DL4004	43.0			
		A4004-V I	Light load	0.75	2.1	3G3AX-	07.0			
	0.75	3G3MX2-	Heavy load *	0.75	3.6	DL4007	27.0	10		
	1.5	A4007-V1	Light load	1.5	4.3	3G3AX-	14.0			
		3G3MX2-	Heavy load *	1.5	5.2	DL4015	14.0			
		A4015-V1	Light load	2.2	5.9	3G3AX-	10.1	13		At an altitude of
	2.2	3G3MX2-	Heavy load *	2.2	6.5	DL4022	10.1	10		
	2.2	A4022-V1	Light load	3.0	8.1					
	3.0	3G3MX2- A4030-V1	Heavy load *	3.0	7.7	3G3AX-	6.4	20		1,000 m
3-phase 400-V	0.0		Light load	4.0	9.4	DL4037		20	–10 to 50°C	max.; indoors
class	4.0	3G3MX2-	Heavy load *	4.0	11.0			20% to 90%	(without	
	1.0	A4040-V1	Light load	5.5	13.3	3G3AX-	4.41	26		corrosive
	5.5	3G3MX2-	Heavy load *	5.5	16.9	DL4055				gases or dust)
	0.0	A4055-V1	Light load	7.5	20.0	3G3AX-	3.35	36		,
	7.5	3G3MX2-	Heavy load *	7.5	18.8	DL4075	0.00			
		A4075-V1	Light load	11	24.0	3G3AX-	2.33	52		
	11	3G3MX2-	Heavy load *	11	29.4	DL4110		<u> </u>		
		A4110-V1	Light load	15	38.0	3G3AX-	1.75	60		
		3G3MX2-	Heavy load *	15	35.9		•			
	15	15 3G3MX2- A4150-V1	Light load	18.5	44.0	3G3AX- DL4220	1.2	67		

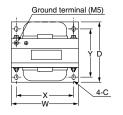
^{*} The DC reactor model for the heavy-load mode is selected with reference to the rated current value of a general-purpose motor, which is 85% of the rated output current of the inverter. If you intend to constantly drive a motor whose rated current value exceeds 85% of the rated output current of the inverter, use the DC reactor model selected for the light-load mode.

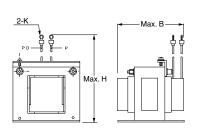
Dimensions (Unit: mm)

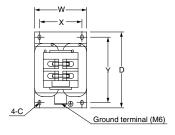
Inverter			Applicable				Dim	nensio	ns (m	ım)				Standard
input power supply	Model	Fig. No.	Motor capacity (kW)	w	D	н	A	В	х	Y	С	к	Weight (kg)	applicable wire
	3G3AX-DL2002		0.1, 0.2	66	90	98	_	85	56	72	5.2 × 8	M4	8.0	1.25 mm ² min.
	3G3AX-DL2004		0.4	66	90	98	_	95	56	72	5.2 × 8	M4	1.0	1.25 mm ² min.
	3G3AX-DL2007	Fia 1	0.55, 0.75	66	90	98	_	105	56	72	5.2 × 8	M4	1.3	2 mm² min.
	3G3AX-DL2015	Fig. 1	1.1, 1.5	66	90	98	_	115	56	72	5.2 × 8	M4	1.6	2 mm² min.
3-phase/	3G3AX-DL2022		2.2	86	100	116	_	105	71	80	6×9	M4	2.1	2 mm² min.
1-phase 200	3G3AX-DL2037		3.0, 3.7	86	100	118	_	120	71	80	6×9	M4	2.6	3.5 mm ² min.
VAC	3G3AX-DL2055		5.5	111	100	210	_	110	95	80	7×11	M5	3.6	8 mm² min.
	3G3AX-DL2075	Fig. 2	7.5	111	100	212	_	120	95	80	7×11	M6	3.9	14 mm² min.
	3G3AX-DL2110		11	146	120	252	_	110	124	96	7×11	M6	6.5	22 mm² min.
	3G3AX-DL2150		15	146	120	256	_	120	124	96	7×11	M8	7.0	38 mm² min.
	3G3AX-DL2220	Fig. 3	18.5	120	175	356	140	145	98	151	7×11	M8	9.0	60 mm² min.
	3G3AX- DL4004		0.4	66	90	98	_	85	56	72	5.2 × 8	M4	0.8	1.25 mm ² min.
	3G3AX-DL4007		0.75	66	90	98	_	95	56	72	5.2 × 8	M4	1.1	1.25 mm ² min.
	3G3AX-DL4015		1.5	66	90	98	_	115	56	72	5.2 × 8	M4	1.6	2 mm² min.
	3G3AX-DL4022	Fig. 1	2.2	86	100	116	_	105	71	80	6×9	M4	2.1	2 mm² min.
3-phase 400	3G3AX-DL4037		3.0	86	100	116	_	120	71	80	6×9	M4	2.6	2 mm² min.
VAC	3G3AX-DL4055		5.5	111	100	138	_	110	95	80	7×11	M4	3.6	3.5 mm ² min.
	3G3AX-DL4075		7.5	111	100	138	_	115	95	80	7×11	M4	3.9	3.5 mm ² min.
	3G3AX-DL4110	F: 0	11	146	120	250	-	105	124	96	7×11	M5	5.2	5.5 mm ² min.
	3G3AX-DL4150	Fig. 2	15	146	120	252	_	120	124	96	7×11	M6	7.0	14 mm² min.
	3G3AX-DL4220	Fig. 3	18.5	120	175	352	140	145	98	151	7×11	M6	9.5	22 mm² min.

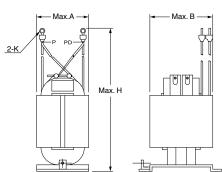
Fig. 1 Fig. 2 Fig. 3











Connection Example

AC Reactor 3G3AX-AL

Connect the AC Reactor if the capacity of the power supply is much larger than that of the Inverter or the power factor is required to be improved.

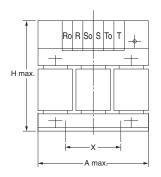
Specifications

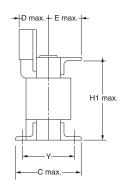
Inverter							AC reactor specifications						
Voltage class	Max. applicable motor capacity (kW)	Model	Heavy load: CT, Light load: VT mode	Max. applicable motor capacity (kW)	Rated input current (A)	Model	Inductance (mH)	Heat generation (W)	Operating ambient temperature/ humidity	Location			
	0.1	3G3MX2-	Heavy load	0.1	1.0								
		A2001-V1	Light load	0.2	1.2								
	0.2	3G3MX2-	Heavy load	0.2	1.6			12					
		A2002-V1 3G3MX2-	Light load Heavy load	0.4 0.4	1.9 3.3	3G3AX- AL2025	2.8		10				
	0.4	A2004-V1	Light load	0.4	3.9		2.8						
		3G3MX2-	Heavy load	0.75	6.0								
	0.75	A2007-V1	Light load	1.1	7.2								
		3G3MX2-	Heavy load	1.5	9.0					At an			
	1.5	A2015-V1	Light load	2.2	10.8				-	altitude o 1,000 m			
3-phase		3G3MX2-	Heavy load	2.2	12.7	3G3AX-	0.88	25	-10 to 50°C	max.;			
200-V	2.2	A2022-V1	Light load	3.0	13.9	AL2055	0.00	20	-10 10 30 0	indoors			
class		3G3MX2-	Heavy load	3.7	20.5				20% to 90%	(without			
	3.7	A2037-V1	Light load	5.5	23.0	3G3AX-				corrosive			
		3G3MX2-	Heavy load	5.5	30.8	AL2110	0.35	50		gases or			
	5.5	A2055-V1	Light load	7.5	37.0					dust)			
		3G3MX2-	Heavy load	7.5	39.6	6							
	7.5	A2075-V1	Light load	11	48.0								
		3G3MX2-	Heavy load	11	57.1	3G3AX-	0.18	50					
	11	A2110-V1	Light load	15	68.0	AL2220							
			Heavy load	15	62.6								
	15	3G3MX2- A2150-V1	Light load	18.5	72.0	3G3AX- AL2330	0.09	85	-				
	0.1	3G3MX2-	Heavy load	0.1	1.3								
	0.1	AB001-V1	Light load	0.2	2.0	3G3AX- AL2025 2.8							
	0.2	3G3MX2-	Heavy load	0.2	3.0		0.0	12		At an altitude of			
		AB002-V1	Light load	0.4	3.6		2.8	12					
Single-	0.4	3G3MX2-	Heavy load	0.4	6.3		0.88			10 to 50°C	1,000 m		
phase	0.4	AB004-V1	Light load	0.55	7.3				−10 to 50°C	max.; indoors (without corrosive gases or dust)			
200-V	0.75	3G3MX2-	Heavy load	0.75	11.5	3G3AX-			20% to 90%				
Class	0.75	AB007-V1	Light load	1.1	13.8	AL2055		25	2070 10 0070				
	1.5	3G3MX2-	Heavy load	1.5	16.8	ALZUUU							
	1.5	AB015-V1	Light load	2.2	20.2	3G3AX-							
	2.2	3G3MX2-	Heavy load	2.2	22.0	AL2110	0.35	50	50				
		AB022-V1	Light load	3.0	24.0								
	0.4	3G3MX2-	Heavy load	0.4	1.8								
		A4004-V1	Light load	0.75	2.1								
	0.75	3G3MX2-	Heavy load	0.75	3.6	3G3AX-	7.7	12					
		A4007-V1	Light load	1.5	4.3	AL4025							
	1.5	3G3MX2-	Heavy load	1.5	5.2								
		A4015-V1	Light load	2.2	5.9					At an			
	2.2	3G3MX2-	Heavy load	2.2	6.5	00041				altitude o			
		A4022-V1	Light load	3.0	8.1	3G3AX-	3.5	25		1,000 m			
3-phase	3.0	3G3MX2-	Heavy load	3.0	7.7	AL4055			−10 to 50°C	max.;			
400-V		A4030-V1	Light load	4.0	9.4					indoors			
class	4.0	3G3MX2- A4040-V1	Heavy load	4.0	11.0				20% to 90%	(without			
			Light load	5.5 5.5	13.3 16.9	3G3AX-	1.3	50		corrosive			
	5.5	3G3MX2- A4055-V1	Heavy load			AL4110	1.3	50		gases or			
			Light load	7.5 7.5	20.0 18.8	1				dust)			
	7.5	3G3MX2- A4075-V1	Heavy load	11	24.0	3C24V							
		3G3MX2-	Light load Heavy load	11	29.4	3G3AX- AL4220	0.74	60					
	11	A4110-V1	Light load	15	38.0								
		3G3MX2-	Heavy load	15	35.9	3G3AX-	0.36	an					
	15					AL4330	0.36	90					

Dimensions (Unit: mm)

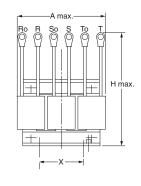
Inverter		Applicable					Dime	nsions	(mm)					Weight
input power supply	Model	motor capacity (kW)	Α	С	D	E	Н	H1	X	Υ	J	K	w	(kg)
	3G3AX-AL2025	0.1 to 1.5	120	82	60	40	150	94	50	67	6	4	9.5	2.8
3-phase	3G3AX-AL2055	2.2 to 3.7	120	98	60	40	150	94	50	75	6	4	9.5	4.0
200 VAC (Single-phase	3G3AX-AL2110	5.5, 7.5	150	103	70	55	170	108	60	80	6	5.3	12.0	5.0
200 VAC)	3G3AX-AL2220	11, 15	180	113	75	55	190	140	90	90	6	8.4	16.5	10.0
,	3G3AX-AL2330	18.5	180	113	85	60	230	140	125	90	6	8.4	22.0	11.0
	3G3AX-AL4025	0.4 to 1.5	130	82	60	40	150	94	50	67	6	4	9.5	2.7
0 1	3G3AX-AL4055	2.2, 3.7	130	98	60	40	150	94	50	75	6	5	12.5	4.0
3-phase 400 VAC	3G3AX-AL4110	5.5, 7.5	150	116	75	55	170	106	60	98	6	5	12.5	6.0
400 VAC	3G3AX-AL4220	11, 15	180	103	75	55	190	140	100	80	6	5.3	12.0	10.0
	3G3AX-AL4330	18.5	180	123	85	60	230	140	100	100	6	6.4	16.5	11.5

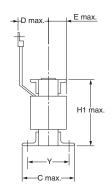
3G3AX-AL2025 3G3AX-AL2055



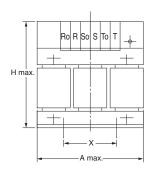


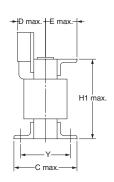
3G3AX-AL2110/3G3AX-AL2220 3G3AX-AL2330



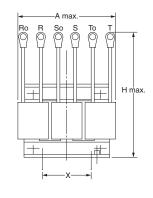


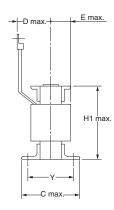
3G3AX-AL4025/3G3AX-AL4055 3G3AX-AL4110





3G3AX-AL4220/3G3AX-AL4330





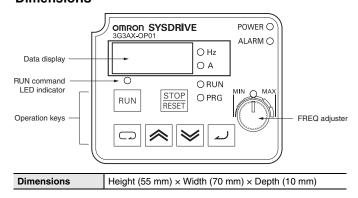
Digital Operator

Used to set parameters, perform various monitoring, and start and stop the Inverter.

3G3AX-OP01



Dimensions



Digital operator extension cable 3G3AX-OPCN□

Used to install the Digital Operator away from the Inverter.



3G3AX-OPCN1 (Cable length: 1 m) **3G3AX-OPCN3** (Cable length: 3 m)

Ordering Information

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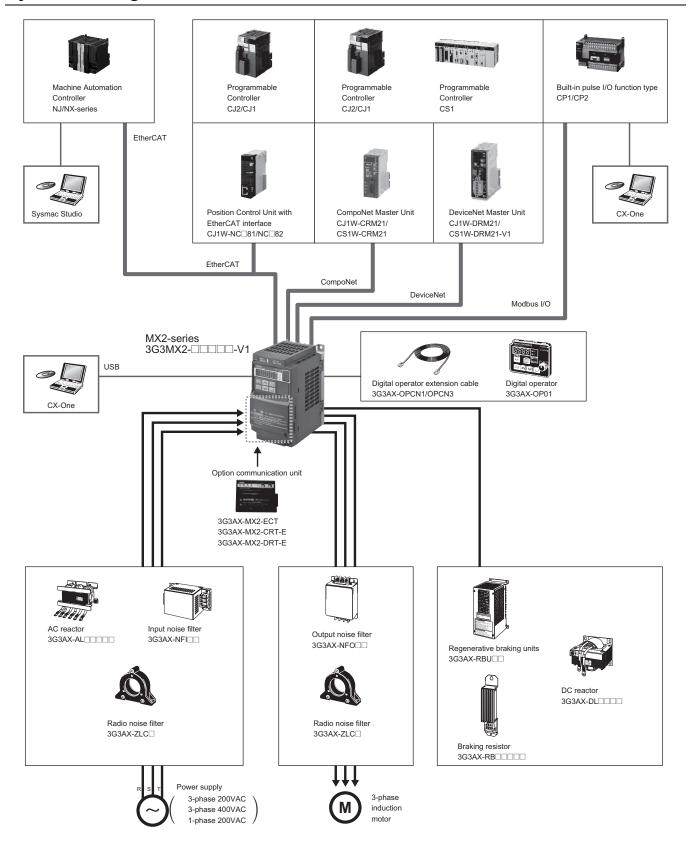
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System Configuration



Interpreting Model Numbers



1) Voltage class

В	1-phase 200 VAC (200-V class)
2	3-phase 200 VAC (200-V class)
4	3-phase 400 VAC (400-V class)

2) Max. applicable motor capacity (CT)

,	• •
001	0.1 kW
002	0.2 kW
004	0.4 kW
007	0.75 kW
015	1.5 kW
022	2.2 kW
030	3.0 kW
037	3.7 kW
040	4.0 kW
055	5.5 kW
075	7.5 kW
110	11 kW
150	15 kW

3)	Area	
3)	Area	

-V1	Japan and areas other than China and Europe
-ZV1	China
-E	Europe

Ordering Information

3G3MX2 Inverter Models

Note: Inverters with model numbers ending in "-V1" are designed to be used in areas other than China and Europe. Refer to the above "Interpreting Model Numbers" for the model numbers for China and Europe.

Data d volta va	Emplooring matinus	Max. applicable	motor capacity	Model		
Rated voltage	Enclosure ratings	CT: Heavy load	VT: Light load	Iviodei		
		0.1kW	0.2 kW	3G3MX2-A2001-V1		
		0.2 kW	0.4 kW	3G3MX2-A2002-V1		
		0.4 kW	0.75 kW	3G3MX2-A2004-V1		
		0.75 kW	1.1 kW	3G3MX2-A2007-V1		
		1.5 kW	2.2 kW	3G3MX2-A2015-V1		
3-phase 200 VAC	IP20	2.2 kW	3.0 kW	3G3MX2-A2022-V1		
		3.7 kW	5.5 kW	3G3MX2-A2037-V1		
		5.5 kW	7.5 kW	3G3MX2-A2055-V1		
		7.5 kW	11 kW	3G3MX2-A2075-V1		
		11 kW	15 kW	3G3MX2-A2110-V1		
		15 kW	18.5 kW	3G3MX2-A2150-V1		
		0.4 kW	0.75 kW	3G3MX2-A4004-V1		
		0.75 kW	1.5 kW	3G3MX2-A4007-V1		
		1.5 kW	2.2 kW	3G3MX2-A4015-V1		
		2.2 kW	3.0 kW	3G3MX2-A4022-V1		
2 mbass 400 VAC	IP20	3.0 kW	4.0 kW	3G3MX2-A4030-V1		
3-phase 400 VAC	IP20	4.0 kW	5.5 kW	3G3MX2-A4040-V1		
		5.5 kW	7.5 kW	3G3MX2-A4055-V1		
		7.5 kW	11 kW	3G3MX2-A4075-V1		
		11 kW	15 kW	3G3MX2-A4110-V1		
		15 kW	18.5 kW	3G3MX2-A4150-V1		
		0.1 kW	0.2 kW	3G3MX2-AB001-V1		
		0.2 kW	0.4 kW	3G3MX2-AB002-V1		
1-phase 200 VAC	IP20	0.4 kW	0.55 kW	3G3MX2-AB004-V1		
1-pilase 200 VAC	IFZU	0.75 kW	1.1 kW	3G3MX2-AB007-V1		
		1.5 kW	2.2 kW	3G3MX2-AB015-V1		
		2.2 kW	3.0 kW	3G3MX2-AB022-V1		

Communication Unit

Name	Model
EtherCAT Communication Unit	3G3AX-MX2-ECT
CompoNet Communication Unit	3G3AX-MX2-CRT-E
DeviceNet Communication Unit	3G3AX-MX2-DRT-E

Related Options

Name		Model	
	2 phase 200 VAC	General purpose with Braking resistor	3G3AX-RBU21
Regenerative Braking Units	3-phase 200 VAC	High Regeneration purpose with Braking resistor	3G3AX-RBU22
	3-phase 400 VAC	General purpose with Braking resistor	3G3AX-RBU41
		Resistor 120 W, 180 Ω	3G3AX-RBA1201
	Compact type	Resistor 120 W, 100 Ω	3G3AX-RBA1202
		Resistor 120 W, 5 Ω	3G3AX-RBA1203
		Resistor 120 W, 35 Ω	3G3AX-RBA1204
	Other decidence	Resistor 200 W, 180 Ω	3G3AX-RBB2001
Braking Resistor		Resistor 200 W, 100 Ω	3G3AX-RBB2002
	Standard type	Resistor 300 W, 50 Ω	3G3AX-RBB3001
		Resistor 400 W, 35 Ω	3G3AX-RBB4001
		Resistor 400 W, 50 Ω	3G3AX-RBC4001
	Medium capacity type	Resistor 600 W, 35 Ω	3G3AX-RBC6001
		Resistor 1200 W, 17 Ω	3G3AX-RBC12001

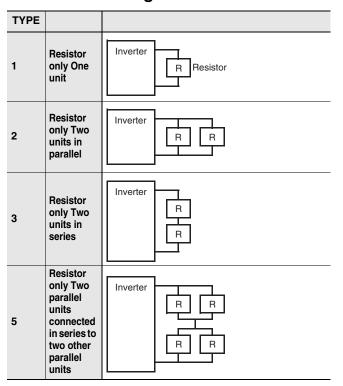
Regenerative Braking Unit and Braking Resistor Combination

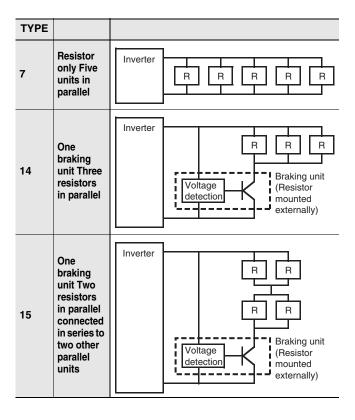
Inverter			Usage conditions		Regenerative braking unit		Braking resistor		0	Restrictions	
Voltage	Max.applicable motor capacity (kW)	Model	%ED *1 [%]	Approximate braking torque [% *2]	Model	Number of units	Model	Number of units	Connection configuration	Allowable continuous braking time(s)	$\begin{array}{c} \text{Min.} \\ \text{connectable} \\ \text{resistance} \\ [\Omega] \end{array}$
	0.1	3G3MX2-A2001-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	1	1	20	100
	0.1	3G3MX2-AB001-V1	10.0%	220%	Dulli-III IIIVerter		3G3AX-RBB2001	1	1	30	100
	0.2	3G3MX2-A2002-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	1	1	20	100
	0.2	3G3MX2-AB002-V1	10.0%	220%	built-in inverter		3G3AX-RBB2001	1	1	30	100
	0.4	3G3MX2-A2004-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	1	1	20	100
	0.4	3G3MX2-AB004-V1	10.0%	220%	built-in inverter		3G3AX-RBB2001	1	1	30	100
	0.75	3G3MX2-A2007-V1 3G3MX2-AB007-V1	3.0%	120%	Built-in Inverter		3G3AX-RBA1201	1	1	20	50
			10.0%	120%	built-in inverter		3G3AX-RBB2001	1	1	30	50
	1.5	3G3MX2-A2015-V1 3G3MX2-AB015-V1	2.5%	110%	Built-in Inverter		3G3AX-RBA1202	1	1	12	50
			10.0%	215%			3G3AX-RBC4001	1	1	10	50
	2.2	3G3MX2-A2022-V1 3G3MX2-AB022-V1	3.0%	150%	Built-in Inverter		3G3AX-RBB3001	1	1	30	35
200-V Class			10.0%	150%	Duilt-iii iiiveitei		3G3AX-RBC4001	1	1	10	35
	3.7	3G3MX2-A2037-V1	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	1	1	20	35
	3.7		10.0%	125%	Duilt-iii iiiveitei		3G3AX-RBC6001	1	1	10	35
	5.5	3G3MX2-A2055-V1	3.0%	120%	Built-in Inverter		3G3AX-RBB3001	2	2	30	20
	5.5	3G3WAZ-A2055-V I	10.0%	120%	Duilt-iii iiiveitei		3G3AX-RBC4001	2	2	10	20
	7.5	3G3MX2-A2075-V1	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	2	2	20	17
	7.5	3G3WX2-A2U75-V1	10.0%	125%	built-in inverter		3G3AX-RBC6001	2	2	10	17
			3.0%	90%	Built-in Inverter		3G3AX-RBC12001	1	1	10	17
	11	3G3MX2-A2110-V1	10.0%	90%	Duilt-III IIIVerter		3G3AX-RBC12001	1	1	10	17
			10.0%	125%	3G3AX-RBU23 *3	1	3G3AX-RBC6001	3	14	10	4
	15	3G3MX2-A2150-V1	3.0%	110%	Built-in Inverter		3G3AX-RBB3001	5	7	30	10
	15	3U3IVIAZ-AZ 13U-V I	10.0%	110%	Duilt-in inverter		3G3AX-RBC4001	5	7	10	10

Inverter			Usage conditions		Regenerative braking unit		Braking resistor		Connection	Restrictions	
Voltage	Max.applicable motor capacity (kW)	Model	%ED *1 [%]	Approximate braking torque [% *2]	Model	Number of units	Model	Number of units	configuration	Allowable continuous braking time(s)	$\begin{array}{c} \text{Min.} \\ \text{connectable} \\ \text{resistance} \\ [\Omega] \end{array}$
	0.4	3G3MX2-A4004-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	2	3	20	180
	0.4	3G3WA2-A4004-V1	10.0%	220%	built-in inverter		3G3AX-RBB2001	2	3	30	180
	0.75	3G3MX2-A4007-V1	3.0%	220%	Built-in Inverter		3G3AX-RBA1201	2	3	20	180
	0.75	3G3WA2-A4007-V1	10.0%	220%	built-in inverter		3G3AX-RBB2001	2	3	30	180
	1.5	3G3MX2-A4015-V1	3.0%	120%	Built-in Inverter		3G3AX-RBA1201	2	3	20	180
		3G3WX2-A4U15-V1	10.0%	120%	Built-in inverter		3G3AX-RBB2001	2	3	30	180
	2.2	3G3MX2-A4022-V1	2.5%	150%	Built-in Inverter		3G3AX-RBA1202	2	3	12	100
			10.0%	220%			3G3AX-RBC4001	2	3	10	100
	3.0	3G3MX2-A4030-V1	2.5%	110%	Built-in Inverter		3G3AX-RBA1202	2	3	12	100
			10.0%	215%			3G3AX-RBC4001	2	3	10	100
400-V	4.0	3G3MX2-A4040-V1	3.0%	165%	Built-in Inverter		3G3AX-RBB3001	2	3	30	100
Class	4.0		10.0%	165%			3G3AX-RBC4001	2	3	10	100
		0000000 44055 1/4	3.0%	120%	Duilt in Inventor		3G3AX-RBB3001	2	3	30	70
	5.5	3G3MX2-A4055-V1	10.0%	120%	Built-in Inverter		3G3AX-RBC4001	2	3	10	70
	7.5	0000000 00000 000	3.0%	125%	Duilt in Inventor		3G3AX-RBB4001	2	3	20	70
	7.5	3G3MX2-A4075-V1	10.0%	125%	Built-in Inverter		3G3AX-RBC6001	2	3	10	70
			3.0%	85%	D 111 1 1		3G3AX-RBB4001	2	3	20	70
	11	3G3MX2-A4110-V1	10.0%	85%	Built-in Inverter		3G3AX-RBC6001	2	3	10	70
		SOUNZ ATTO-VI	10.0%	120%	3G3AX-RBU41 *3	1	3G3AX-RBC4001	4	15	10	34
	15	3G3MX2-A4150-V1	3.0%	125%	Built-in Inverter		3G3AX-RBB4001	4	5	20	35
	15	3G3NIX2-A4150-V1	10.0%	125%	built-in inverter		3G3AX-RBC6001	4	5	10	35

^{*1 %}ED shows the ratio that can be used for braking (deceleration time) among operating time of one task period.

Connection configuration





^{*2} Approximate breaking torque is shown in % of rating torque of the motor (100%).

^{*3} Please remove the built-in resistor.

Nome		Specifications of Inverte	r	Model
Name	Voltage class	CT: Heavy load	VT: Light load	Model
		0.1 kW	0.2 kW	
		0.2 kW	0.4 kW	
		0.4 kW	0.75 kW	20247.701.0
		0.75 kW	1.1 kW	3G3AX-ZCL2
		1.5 kW	2.2 kW	
	3-phase 200 VAC	2.2 kW	3.0 kW	
	·	3.7 kW	5.5 kW	
		5.5 kW	7.5 kW	3G3AX-ZCL1 (3G3AX-ZCL2)
		7.5 kW	11 kW	
		11 kW	15 kW	3G3AX-ZCL1
		15 kW	18.5 kW	
		0.1 kW	0.2 kW	
		0.2 kW	0.4 kW	
adio Noise Filter		0.4 kW	0.55 kW	
	1-phase 200 VAC	0.75 kW	1.1 kW	G3AX-ZCL2
		1.5 kW	2.2 kW	
		2.2 kW	3.0 kW	
		0.4 kW	0.75 kW	
		0.4 kW	1.5 kW	
		0.75 kW	2.2 kW	
		1.5 KW 2.2 kW	2.2 kW 3.0 kW	2G2AV-7CL2 /2C2AV 7CL4\
	3-phase 400 VAC		4.0 kW	3G3AX-ZCL2 (3G3AX-ZCL1)
		3.0 kW		
		4.0 kW	5.5 kW	
		5.5 kW	7.5 kW	
		7.5 kW	11 kW	
		11 kW	15 kW	3G3AX-ZCL1
		15 kW	18.5 kW	
		0.1 kW	0.2 kW	
		0.2 kW	0.4 kW	3G3AX-NFI21
		0.4 kW	0.75 kW	
		0.75 kW	1.1 kW	3G3AX-NFI22
		1.5 kW	2.2 kW	3G3AX-NFI23
	3-phase 200 VAC	2.2 kW	3.0 kW	SGOAX-III 125
		3.7 kW	5.5 kW	3G3AX-NFI24
		5.5 kW	7.5 kW	3G3AX-NFI25
		7.5 kW	11 kW	3G3AX-NFI26
		11 kW	15 kW	3G3AX-NFI27
		15 kW	18.5 kW	3G3AX-NFI28
		0.1 kW	0.2 kW	OOOAY NEIGH
		0.2 kW	0.4 kW	3G3AX-NFI21
put Noise Filter	4 1	0.4 kW	0.55 kW	3G3AX-NFI22
	1-phase 200 VAC	0.75 kW	1.1 kW	3G3AX-NFI23
		1.5 kW	2.2 kW	3G3AX-NFI23 *
		2.2 kW	3.0 kW	3G3AX-NFI24
		0.4 kW	0.75 kW	
		0.75 kW	1.5 kW	3G3AX-NFI41
		1.5 kW	2.2 kW	
		2.2 kW	3.0 kW	
		3.0 kW	4.0 kW	3G3AX-NFI42
	3-phase 400 VAC			
		4.0 kW	5.5 kW	3G3AX-NFI43
		5.5 kW	7.5 kW	OOOAY NEIA
		7.5 kW	11 kW	3G3AX-NFI44
		11 kW	15 kW	3G3AX-NFI45
		15 kW	18.5 kW	3G3AX-NFI46

 $^{^{\}star}\,$ Only the CT rating is supported.

		Model		
Name	Voltage class	Specifications of Inverter Voltage class CT: Heavy load VT: Light load		
	3	0.1 kW	0.2 kW	
		0.2 kW	0.4 kW	3G3AX-NFO01
		0.4 kW	0.75 kW	
		0.75 kW	1.1 kW	
	0001/40	1.5 kW	2.2 kW	3G3AX-NFO02
	3-phase 200 VAC	2.2 kW	3.0 kW	OCCAY NECCO
		3.7 kW	5.5 kW	3G3AX-NFO03
		5.5 kW	7.5 kW	20247 115024
		7.5 kW	11 kW	3G3AX-NFO04
		11 kW	15 kW	3G3AX-NFO05
		0.1 kW	0.2 kW	00047 NE004
		0.2 kW	0.4 kW	3G3AX-NFO01
ataunt Malan Ellen	4 -1 000 1/40	0.4 kW	0.55 kW	OCCAY NECCO
utput Noise Filter	1-phase 200 VAC	0.75 kW	1.1 kW	3G3AX-NFO02
		1.5 kW	2.2 kW	2C2AV NEO02
		2.2 kW	3.0 kW	3G3AX-NFO03
		0.4 kW	0.75 kW	2C2AV NEO04
		0.75 kW	1.5 kW	3G3AX-NFO01
		1.5 kW	2.2 kW	
		2.2 kW	3.0 kW	3G3AX-NFO02
	0 = 1 = 2 400 1/40	3.0 kW	4.0 kW	
	3-phase 400 VAC	4.0 kW	5.5 kW	
		5.5 kW	7.5 kW	3G3AX-NFO03
		7.5 kW	11 kW	
		11 kW	15 kW	0004Y NE004
		15 kW	18.5 kW	3G3AX-NFO04
		0.1 kW	0.2 kW	3G3AX-DL2002
		0.2 kW	0.4 kW	3G3AX-DL2004
		0.4 kW	0.75 kW	3G3AX-DL2007
		0.75 kW	1.1 kW	3G3AX-DL2015
		1.5 kW	2.2 kW	3G3AX-DL2022
	3-phase 200 VAC	2.2 kW	3.0 kW	3G3AX-DL2037
		3.7 kW	5.5 kW	3G3AX-DL2055
		5.5 kW	7.5 kW	3G3AX-DL2075
		7.5 kW	11 kW	3G3AX-DL2110
		11 kW	15 kW	3G3AX-DL2150
		15 kW	18.5 kW	3G3AX-DL2220
		0.1 kW	0.2 kW	3G3AX-DL2002
		0.2 kW	0.4 kW	3G3AX-DL2004
C Reactor	1 where 000 V/40	0.4 kW	0.55 kW	3G3AX-DL2007
	1-phase 200 VAC	0.75 kW	1.1 kW	3G3AX-DL2015
		1.5 kW	2.2 kW	3G3AX-DL2022
		2.2 kW	3.0 kW	3G3AX-DL2037
		0.4 kW	0.75 kW	3G3AX-DL4007
		0.75 kW	1.5 kW	3G3AX-DL4015 *
		1.5 kW	2.2 kW	3G3AX-DL4022
		2.2 kW	3.0 kW	000AV DI 400T
	0.46. 4003410	3.0 kW	4.0 kW	3G3AX-DL4037
	3-phase 400 VAC	4.0 kW	5.5 kW	3G3AX-DL4055
		5.5 kW	7.5 kW	3G3AX-DL4075 *
		7.5 kW	11 kW	3G3AX-DL4110 *
		11 kW	15 kW	3G3AX-DL4150
		15 kW	18.5 kW	3G3AX-DL4220

Name		Specifications of Inverter				
Name	Voltage class	CT: Heavy load	VT: Light load	Model		
		0.1 kW	0.2 kW			
		0.2 kW	0.4 kW	3G3AX-AL2025		
		0.4 kW	0.75 kW	JGSAX-AL2025		
		0.75 kW	1.1 kW			
		1.5 kW	2.2 kW	3G3AX-AL2055		
	3-phase 200 VAC	2.2 kW	3.0 kW	JGSAX-AL2055		
		3.7 kW	5.5 kW	3G3AX-AL2110		
		5.5 kW	7.5 kW	3G3AX-AL2110 *		
		7.5 kW	11 kW	3G3AX-AL2220		
		11 kW	15 kW	3G3AX-AL2220 *		
		15 kW	18.5 kW	3G3AX-AL2330		
		0.1 kW	0.2 kW	3G3AX-AL2025		
		0.2 kW	0.4 kW			
C Reactor	1 mhana 200 VAC	0.4 kW	0.55 kW	JG3AA-AL2U25		
	1-phase 200 VAC	0.75 kW	1.1 kW			
		1.5 kW	2.2 kW	3G3AX-AL2055 *		
		2.2 kW	3.0 kW	3G3AX-AL2110		
		0.4 kW	0.75 kW	00047 41 4005		
		0.75 kW	1.5 kW	3G3AX-AL4025		
		1.5 kW	2.2 kW			
		2.2 kW	3.0 kW	3G3AX-AL4055		
	2 mhana 400 VAC	3.0 kW	4.0 kW			
	3-phase 400 VAC	4.0 kW	5.5 kW	3G3AX-AL4110		
		5.5 kW	7.5 kW	3G3AX-AL4110 *		
		7.5 kW	11 kW	3G3AX-AL4220		
		11 kW	15 kW	3G3AX-AL4220 *		
		15 kW	18.5 kW	3G3AX-AL4330		

* Only the CT rating is supported.

Note: When using the Inverter for light load rating, select the model with one size larger capacity (rated current).

Name	Cable length(m)	Model
Digital Operator	-	3G3AX-OP01
Connection cable	1m	3G3AX-OPCN1
Connection cable	3m	3G3AX-OPCN3

Recommended EtherCAT Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

Cable with Connectors

Item	Appearance	Recommended manufacturer	Cable length(m) *1	Model
Cable with Connectors on Both Ends			0.3	XS6W-6LSZH8SS30CM-Y
(RJ45/RJ45)			0.5	XS6W-6LSZH8SS50CM-Y
Standard RJ45 plugs type *1		OMBON	1	XS6W-6LSZH8SS100CM-Y
Wire Gauge and Number of Pairs: AWG26, 4-pair cable		OMRON	2	XS6W-6LSZH8SS200CM-Y
Cable Sheath material: LSZH *2			3	XS6W-6LSZH8SS300CM-Y
Cable color: Yellow *3	4		5	XS6W-6LSZH8SS500CM-Y
Cable with Connectors on Both Ends			0.3	XS5W-T421-AMD-K
(RJ45/RJ45)			0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1		OMBON	1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs:	***	OMHON	2	XS5W-T421-DMD-K
AWG22, 2-pair cable			5	XS5W-T421-GMD-K
Cable color: Light blue			10	XS5W-T421-JMD-K
Cable with Connectors on Both Ends		OMRON	0.5	XS5W-T421-BM2-SS
(M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *4 M12/Smartclick Connectors			2	XS5W-T421-DM2-SS
Wire Gauge and Number of Pairs:			3	XS5W-T421-EM2-SS
AWG22, 2-pair cable			5	XS5W-T421-GM2-SS
Cable color: Black			10	XS5W-T421-JM2-SS
Cable with Connectors on Both Ends			0.5	XS5W-T421-BMC-SS
(M12 Straight/RJ45) Shield Strengthening Connector cable *4			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors		OMBON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type		OMRON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair cable			5	XS5W-T421-GMC-SS
Cable color: Black			10	XS5W-T421-JMC-SS

^{*1} Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available. Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available. For details, refer to Cat.No.G019.

Cables / Connectors

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
	_	Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 x 4P CP *
Cables	_	Kuramo Electric Co.	KETH-SB *
	_	SWCC Showa Cable Systems Co.	FAE-5004 *
RJ45 Connectors	_	Panduit Corporation	MPS588-C *

^{*} We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	_	Kuramo Electric Co.	KETH-PSB-OMR *
Cables	_	JMACS Japan Co., Ltd.	PNET/B *
RJ45 Assembly Connector		OMRON	XS6G-T421-1 *

^{*} We recommend you to use above cable and connector together.

^{*2} The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

^{*3} Cables colors are available in blue, yellow, or Green.

^{*4} For details, contact your OMRON representative.

Software

How to Select Required Support Software for Your Controller

The required Support Software depends on the Controller to connect. Please check the following table when purchasing the Support Software.

Item	Omron PLC System	Omron Machine Automation Controller System
Controller	CS, CJ, CP, and other series	NJ/NX-series
Inverter	Inverter MX2-series V1 type Inverter MX2-series V1 type with EtherCAT Communication Unit (Applicable to the CJ series only.) Inverter MX2-series V1 type with CompoNet Communication Unit Inverter MX2-series V1 type with DeviceNet Communication Unit	Inverter MX2-series V1 type Inverter MX2-series V1 type with EtherCAT Communication Unit Inverter MX2-series V1 type with CompoNet Communication Unit Inverter MX2-series V1 type with DeviceNet Communication Unit
Software	FA Integrated Tool Package CX-One	Automation Software Sysmac Studio

FA Integrated Tool Package CX-One

Product name	Specifications	Number of licenses	Media	Model	Standards
FA Integrated Tool Package CX-One Ver. 4.□	The CX-One is a comprehensive software package that integrates Support Software for OMRON PLCs and components. CX-One runs on following OS. Windows 7 (32-bit/64-bit version) / Windows 8 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version) CX-One Version.4. includes CX-Drive Ver.2. For details, refer to the CX-One catalog (Cat. No. R134)	1 license *	DVD	CXONE-AL01D-V4	-

^{*} Multi licenses (3, 10, 30, or 50 licenses) and DVD media without licenses are also available for the CX-One.

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

Product name	Specifications	Number of licenses	Media	Model	Standards
Sysmac Studio Standard Edition Ver.1.□□	The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-	_ (Media only)	Sysmac Studio (32 bit) DVD	SYSMAC-SE200D	-
	series Industrial PC, EtherCAT Slave, and the HMI. Sysmac Studio runs on the following OS. Windows 7 (32-bit/64-bit version) / Windows 8 (32-bit/64-bit version)/ Windows 10 (32-bit/64-bit version)* 1 The Sysmac Studio Standard Edition DVD includes	_ (Media only)	Sysmac Studio (64 bit) DVD	SYSMAC-SE200D-64	-
	Support Software to set up EtherNet/IP Units, DeviceNet slaves, Serial Communications Units, and Support Software for creating screens on HMIs (CX- Designer). For details, refer to your OMRON website.	1 license *2	-	SYSMAC-SE201L	-

^{*1} Model "SYSMAC-SE200D-64" runs on Windows 10 (64 bit).

^{*2} Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

Overview of Inverter Selection

For detail of Inverter selection, refer to the MX2 series V1 type User's Manual. (Man.No.I585).

Motor Capacity Selection

Before selecting an invertor, first the motor should be chosen.In selecting the motor, first calculate the load inertia for the applications, and then calculate the required capacity and torque.

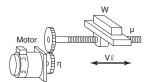
Make a simple selection (use Formulas for the required output power)

This method of calculation helps select a motor by calculating the output (W) required by the motor to maintain its regular rotations. It does not include calculation of the effect of acceleration/deceleration. Therefore, make allowance for the calculated value to select a motor. This calculation method can be applied to applications that operate constantly such as fans, conveyers, agitators etc.

This calculation method must not be applied to the following applications:

- •Those requiring instant start-up.
- •Those that frequently repeat operation and stop.
- •Those that have a large inertia at the power transfer part.
- •Those that have an inefficient power transfer part.

● For Straight-Line Operation: Normal Power PO (kW)

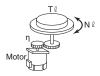


$$P_0 = \frac{\mu \cdot W \cdot V\ell}{6120 \cdot n}$$

u: Friction Coefficient

W: Mass of Straight-Line travelling part (kg) Vℓ: Speed of Straight-Line Travelling part (m/min) η: Decelerator (Transfer part) Efficiency

●For Rotating Operation: Normal Power PO (kW)



$$P_o (kW) = \frac{2\pi \cdot T\ell \cdot N\ell}{60 \cdot \eta} \times 10^{-3}$$

Tℓ: Load Torque (Load Shaft) (N·m) N ℓ: Load Shaft Rotation Speed (r/min) η: Transfer part (η≤1)

Detailed Selection Method (R.M.S Algorithm)

This method helps to select a motor by calculating the effective torque and maximum torque required to achieve a certain pattern of operation for the application. It selects a motor that is optimal for a particular operation pattern.

Calculate the inertia with a Motor Shaft **Conversion Value**

Calculate inertias of all the components with the formula for inertia calculation shown below to convert them to a motor conversion value.



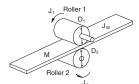
$$J_W = J_1 + J_2 = \left(\frac{M_1 \cdot D^2}{8} + \frac{M_2 \cdot D^2}{4}\right) \times 10^{-6} (kg \cdot m^2)$$

- J, : Cylinder Inertia (kg·m²)
- M.: Mass of Cylinder (kg)
- J₂: Inertia from Object (kg·m²)
- Ma: Mass of Object (kg)

$$J_{w} = J_{1} + J_{2} + J_{3} + J_{4} = \left(\frac{M_{1} \cdot D_{1}^{2}}{8} + \frac{M_{2} \cdot D_{2}^{2}}{8} \cdot \frac{D_{1}^{2}}{D_{2}^{2}} + \frac{M_{3} \cdot D_{1}^{2}}{4} + \frac{M_{4} \cdot D_{1}^{2}}{4}\right) \times 10^{-6} (kg \cdot m^{2})$$

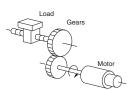


- Jw: Inertia (kg·m²)
- D.: Cylinder 1 Diameter (mm)
- J1: Cylinder 1 Inertia (kg·m²)
- Da: Cylinder 2 Diameter (mm)
- J₂: Inertia from Cylinder 2 (kg·m²) J₂: Inertia from Object (kg·m²)
- M,: Mass of Cylinder 1 (kg) Ma: Mass of Cylinder 2 (kg)
- M.: Mass of Object (kg)
- J₄: Inertia from Belt (kg·m²)



$$J_{w} = J_{1} + \left(\frac{D_{1}}{D_{2}}\right)^{2} J_{2} + \frac{M \cdot D_{1}^{2}}{4} \times 10^{-6} (kg \cdot m^{2})$$

- J₁: Roller 1 Inertia (kg·m²)
- J2: Roller 2 Inertia (kg·m²)
- D.: Roller 1 Diameter (mm)
- D₂: Roller 2 Diameter (mm)
- M : Work Equivalent Mass (kg)



$$J_1 = J_1 + G^2(J_2 + J_w) (kg \cdot m^2)$$

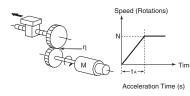
- J.: Load Inertia of Motor Shaft Conversion (kg·m²)
- J...: Load Inertia (kg·m²)
- J.: Gear Inertia on Motor Side (kg·m²)
- J₂: Gear Inertia on Load Side (kg·m²)
- Z, : Number of Gear Teeth on Motor Side
- Z : Number of Gear Teeth on Load Side

Gear Ratio G = Z./Z.

Calculate Motor Shaft Conversion Torque and **Effective Torque**

Calculate the acceleration torque from the load torque calculated from both the motor shaft conversion value and the motor rotor inertia. Then Combine this acceleration torque and the Load torque calculated from the friction force and the external force that are applied to the load. Now you get the required torque to operate a motor.

Acceleration Torque



Acceleration Torque
$$(T_A)$$

$$T_A = \frac{2\pi N}{60t_A} \left(J_M + \frac{J_L}{\eta} \right) (N \cdot m)$$

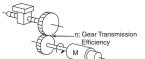
- T_A: Acceleration/Deceleration Torque (N·m)
- J_L: Motor Shaft Conversion Load Inertia (kg·m2)
- J_M : Inertial of Motor Itself (kg·m²)
- η : Gear Transmission Efficiency
- N: Motor Rotation Speed (r/min)

Motor Shaft Conversion Load Torque (External Force/Friction)

F: External (Friction is generally, $F = \mu W$

$$T_W = F \cdot \frac{D}{2} \times 10^{-3} \, (\text{N} \cdot \text{m})$$

μ: Friction Coefficient W: Mass of Moving Part)



$$T_L = T_w \cdot \frac{G}{\eta} (N \cdot m)$$

- T_1 : Motor Shaft Conversion Load Torque (N·m)
- Z,: Number of Gear Teeth on Motor Side
- Z₂: Number of Gear Teeth on Load Side

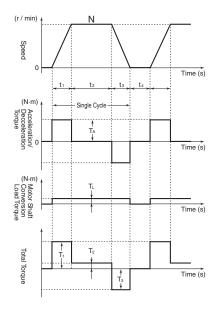
Gear (Deceleration) Ratio G = Z₁/Z₂

Calculation of Total Torque and Effective Torque

Effective Torque: TRMS (N·m)

$$= \sqrt{\frac{\sum (T_i)^2 \cdot t_i}{\sum t_i}} = \sqrt{\frac{T_1^2 t_1 + T_2^2 \cdot t_2 + T_3^2 \cdot t_3 + T_4^2 \cdot t_4}{t_1 + t_2 + t_3 + t_4}}$$

Maximum Torque: $T_{MAX} = T_1 = T_A + T_L$



Note: Please make use of the Servo Motor selection software, which can calculate the motor shaft conversion inertia and effective/maximum torque, as above.

Motor Selection

Use the formula below to calculate the motor capacity from the effective torque and the maximum torque that were obtained above. Select the larger of the two generated values as the motor capacity. Select a motor the capacity of which is larger than the calculated value and makes allowance for an error.

Motor Capacity corresponding to Effective Torque Motor Capacity (kW) = 1.048·N·T_{RMS}·10⁻⁴ N: Maximum Rotations (r/min)

• Motor Capacity capable of Providing Maximum Torque

Motor Capacity (kW) = $1.048 \cdot N \cdot T_{MAX} \cdot 10^{-4} / 1.5$ N: Maximum Rotations (r/min)

Inverter Capacity Selection

Select an inverter that can be used for the selected motor in the process of "Motor Selection".

Generally, select an inverter which fits the maximum applicable motor capacity of the selected motor.

After selecting an inverter, check if it meets with all of the following conditions. If it does not, select an inverter that has a one class larger capacity and check the feasibility again.

Motor Rated Current \leq Inverter Rated Output Current Maximum Time of Continuous Torque Output Time in an Application \leq 1 minute

Note: 1. Where the inverter overload capacity is "120% of Rated Output Current for 1 minute", check it for 0.8 minute.

2. Where a 0 Hz sensor-less vector control is being used, or where torque must be maintained for 0 (r/min) rotation speed and where 150% of the rated torque is frequently required, use an invertor which is one rank larger than the one selected by the above method.

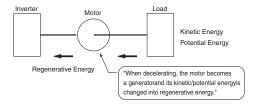
Outline of Braking Resistor Selection Importance of Braking Resistor

If the regenerative energy generated in deceleration or descent in an application is too great, the main circuit of an inverter may have an increased voltage and it may be damaged.

Because the inverter usually contains the overvoltage LAD stop function, it is not actually damaged. However, the motor stops detecting an error, making a stable and continuous operation disabled. Therefore, you must discharge the regenerative energy outside of the inverter.

• What is Regenerative Energy?

A load connected to a motor has kinetic energy when rotating, and potential energy when it is located in a high position. When the motor decelerates, or when the load descends, the energy is returned to an inverter. It is known as regeneration, and the energy generated by the phenomenon is known as regenerative energy.



Preventing Breaking Resistence

The following are methods to prevent the connection of braking resistance.

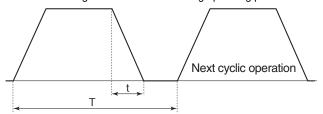
These methods will make the deceleration time increase, so check if it will not cause problems.

- Enable the deceleration stall prevention (enabled in factory settings) (It will automatically increase deceleration time not to cause an overvoltage to stop the motor).
- Set a longer deceleration time. (Cause the regenerative energy to decrease per unit of time.)
- Disable Free-Run. (Prevent the regenerative energy from returning to an inverter.)

Make a Simple Selection for Braking Resistors

It can be a simple selecting method by using the ratio of time in which regenerative energy is produced in a normal operating pattern.

Calculate the usage ratio from the following operating pattern.



Usage Rate = $t/T \times 100$ (% ED)

- t: Deceleration Time (Regenerative Time)
- T: Single Cycle Operation Time

%ED is the unit used for a usage rate.

The usage rate is used as the ratio of deceleration time (regenerative operation time) to simplify the selection of the braking options.

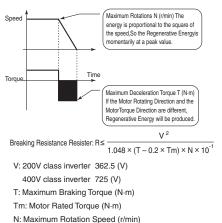
◆ For Models with a Built-in Braking Circuit (3G3MX2 Max. 22 kW)

Select the braking resistor based on the usage rate calculated from the operation patterns.

Refer to the braking resistor list described in the User's manual and catalog, and connect it according to your Inverter.

When the usage ratio for the braking resistor selected on the previous page exceeds 10% ED, or when an extremely large braking torque is required, use the method below to calculate a regenerative energy and make your selection.

Calculation of Required Braking Resistor

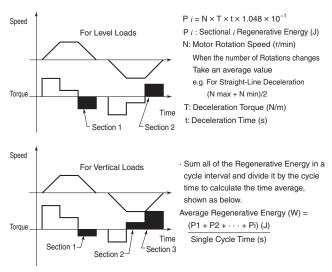


Note: Calculate a braking torque using the above "Motor Capacity Selection".

Calculation of Average Regenerative Energy

Regenerative Energy is produced when the motor rotation direction and the torque direction are opposite.

Use the following formula to calculate a regenerative energy per cycle interval.



- **Note: 1.** Forward rotation direction is forward for the speed, and the torque in the forward rotation direction is forward for the torque.
 - Calculate a braking torque using the above "Motor Capacity Selection".

Braking Resistor Selection

Select a Braking Resistor from the required braking resistance and average regenerative energy on the left.

- Required Braking Resistence ≥ Resistence of Braking Resistor ≥ Minimum Connection Resistence of Invertor or Regenerative Braking Unit
- Average Regenerative Energy ≤ Permissible Power for Braking Resister
- Note: 1. If a resistance that has a less then the minimum connectable value is connected on an inverter or regenerative braking resistor unit, the internal breaking transistor can be damaged. When the required braking resistance is less than the minimum connectable resistance, change the inverter or regenerative energy braking to the one having a larger capacity and a minimum connection resistance less than the required braking resistance.
 - 2. Two or more regenerative braking units can be operated in parallel. Refer to the following formula to know the braking resistance value in such a case. Braking Resistence(Ω) = (Required Braking Resistance as calculated above) × (No. of Units in use)
 - 3. Do not use the above formula to select a generative braking resistance value. 150W does not reflect a permissible power capacity, but the maximum rated power per unit of resistance. The actual permissible power varies according to a resistance.

Related Manuals

Man. No.	Model	Manual
1585	3G3MX2-□□□□□-V1	Multi-function Compact Inverter MX2 series V1 type USER'S MANUAL
1580	3G3WAZ-UUUU-VI	Drive Programming USER'S MANUAL
1570	3G3MX2-□□□□	Multi-function Compact Inverter MX2-series USER'S MANUAL
1574	3G3AX-MX2-ECT	MX2 series / MX2 series V1 type/ RX series V1 type EtherCAT Communication Unit USER'S MANUAL
I581	3G3AX-MX2-DRT-E	MX2 series / MX2 series V1 type/ RX series V1 type DeviceNet Communication Unit USER'S MANUAL
1582	3G3AX-MX2-CRT-E	MX2 series / MX2 series V1 type/ RX series V1 type CompoNet Communication Unit USER'S MANUAL
W463	CXONE-AL□□D-V□	CX-One FA Integrated Tool Package Setup Manual
W453	CXONE-AL□D-V□/WS02-DRVC01	CX-Drive OPERATION MANUAL
W504	SYSMAC-SE2	Sysmac Studio Version 1 Operation Manual

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OMRON Corporation Industrial Automation Company

Tokyo, JAPAN

Contact: www.ia.omron.com

Regional Headquarters
OMRON EUROPE B.V.

Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON ASIA PACIFIC PTE. LTD.

No. 438A Alexandra Road # 05-05/08 (Lobby 2),
Alexandra Technopark,
Singapore 119967
Tel: (65) 6835-3011/Fax: (65) 6835-2711

OMRON ELECTRONICS LLC

2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD. Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200 **Authorized Distributor:**

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