## OmROח

## CP1H/CP1L



## All-in-one Package PLCs with Condensed Multi-functionality. A Wide Variety of Built-in Functions Expand Application Capabilities and Shorten the Design Time Required for the Growing Number and Increasing Complexity of Ladder Programs



The Ultimate High-performance Package-type PLC
Three types of CPU Unit are available to meet applications requiring advanced functionality: - The CP1H-X with pulse outputs for 4 axes. - The CP1H-Y with $1-\mathrm{MHz}$ pulse I/O.

- The CP1H-XA with built-in analog I/O.


A Standard Package-type PLC
Complete with a standard-feature USB port, CP1L CPU Units are available for applications with as few as $101 / O$ points. Whether you need simple sequence control or pulse I/O and a serial port, the CP1L PLCs give you an economical choice from among 10-, 14-,



[^0]
UPU Units 8
Expansion Units. .....  10
Functions .....  12
-Pulse Outputs. .....  12
14- Serial Communications. .16

- Ethernet Communications... 1- Analog I/O. .19-USB Peripheral Port 20
-LCD Displays and Settings...
Support Software...............
CPU Unit Functions. 22
Connecting Expansion Unitand Expansion I/O Units....... 26
CPU Unit Specifications..... 28 ..... 28
Option Unit Specifications... 4
Expansion I/O UnitSpecifications. 44
Expansion UnitSpecifications.. 46
Dimensions .....  48
nstructions. .....  51
Ordering Information. .....  55OMRON Function Block
Library.. 62
SMARTSTEP 2AC Servo Drivers withPulse String Inputs. 64


## A Wide Range of CPU Units Allows You to Select the Ideal Model.



## Expansion Units Provide for a Wider Range of Applications.

## SYSMAC CP1【

- Using Only CP1W Units with the CP1H

$\bullet$ Up to 7 CP1W/CPM1A Expansion Units and Expansion I/O Units can be connected Note: Some Expansion Units and Expansion I/O Units have certain restrictions on use.
(For details, refer to page 24.)
-Using CJ-series Special I/O Units, CJ-series CPU Bus Units, and CP1W Units with the CP1H

$\bullet$ Up to 7 CP1W/CPM1A Expansion Units and Expansion I/O Units can be connected. CP1W/CPM1A Expansion Units and Expansion IO Units and CJ Units can be used simultaneously. CP1W-CN811 I/O Connecting Cable is required.

CP1H Application Examples


SYSMAC CP1凸
-CP1L-M30D $\square-\square / C P 1 L-M 40 D \square-\square / C P 1 L-M 60 D \square-\square$

-CP1L-L14D $\square-\square / C P 1 L-L 20 D \square-\square$


- One CP1W/CPM1A Expansion Unit or Expansion I/O Unit can be connected.

■CP1H/CP1L Communications Interface Options


■CP1L Application Examples


Sequence Control with Clock Functio Shopping Mall Fountain Control


Maximize Efficiency by Selecting the Optimu m CPU Unit for Your Applications.

|  |  | CP1H |  |  | CP1L |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Y CPU Units <br> CP1H-Y20DT-D <br> DC power supply, 12 DC inputs, 8 transistor (sinking) outputs Two line-driver inputs <br> Two line-driver outputs | XA CPU Units <br> CP1H-XA40DR-A <br> AC power supply, 24 DC inputs, <br> 16 relay outputs, 4 analog inputs, <br> 2 analog outputs <br> CP1H-XA40DT-D <br> DC power supply, 24 DC inputs, 16 transistor (sinking) outputs, 4 analog inputs, 2 analog outputs <br> CP1H-XA40DT1-D <br> DC power supply, 24 DC inputs, 16 transistor (sourcing) outputs, 4 analog inputs, 2 analog outputs | X CPU Units <br> CP1H-X40DR-A <br> AC power supply, 24 DC inputs, 16 relay outputs <br> CP1H-X40DT-D <br> DC power supply, 24 DC inputs, 16 transistor (sinking) outputs <br> CP1H-X40DT1-D <br> DC power supply, 24 DC inputs, <br> 16 transistor (sourcing) outputs | M Type 60 Points <br> CP1L-M60DR-A <br> AC power supply, <br> 36 DC inputs, 24 relay outputs <br> CP1L-M60DT-A <br> AC power supply, 36 DC inputs, <br> 24 transistor (sinking) outputs <br> CP1L-M60DR-D <br> DC power supply, <br> 36 DC inputs, 24 relay outputs <br> CP1L-M60DT-D <br> DC power supply, 36 DC inputs, 24 transistor (sinking) outputs <br> CP1L-M60DT1-D <br> DC power supply, 36 DC inputs, <br> 24 transistor (sourcing) outputs | M Type 40 Points <br> CP1L-M40DR-A <br> AC power supply, 24 DC inputs, <br> 16 relay outputs <br> CP1L-M40DT-A <br> AC power supply, 24 DC inputs, <br> 16 transistor (sinking) outputs <br> CP1L-M40DR-D <br> DC power supply, 24 DC inputs, <br> 16 relay outputs <br> CP1L-M40DT-D <br> DC power supply, 24 DC inputs, <br> 16 transistor (sinking) outputs <br> CP1L-M40DT1-D <br> DC power supply, 24 DC inputs, <br> 16 transistor (sourcing) outputs | M Type 30 Points <br> CP1L-M30DR-A <br> DC power supply, 18 DC inputs, 12 relay outputs <br> CP1L-M30DT-A <br> AC power supply, 18 DC inputs, <br> 12 transistor (sinking) outputs <br> CP1L-M30DR-D <br> DC power supply, 18 DC inputs, 12 relay outputs <br> CP1L-M30DT-D <br> DC power supply, 18 DC inputs, <br> 12 transistor (sinking) outputs <br> CP1L-M30DT1-D <br> DC power supply, 18 DC inputs, <br> 12 transistor (sourcing) outputs | L Type 20 Points <br> CP1L-L20DR-A <br> AC power supply, 12 DC inputs, 8 relay outputs <br> CP1L-L20DT-A <br> AC power supply, 12 DC inputs, 8 transistor (sinking) outputs <br> CP1L-L20DR-D DC power supply, 12 DC inputs, 8 relay outputs <br> CP1L-L20DT-D <br> DC power supply, 12 DC inputs, 8 transistor (sinking) outputs <br> CP1L-L20DT1-D <br> DC power supply, 12 DC inputs, 8 transistor (sourcing) outputs | L Type 14 Points <br> CP1L-L14DR-A <br> AC power supply, 8 DC inputs, 6 relay outputs <br> CP1L-L14DT-A <br> AC power supply, 8 DC inputs, 6 transistor (sinking) outputs <br> CP1L-L14DR-D <br> ${ }^{\mathrm{D} C}$ power supply, 8 DC inputs, 6 relay outputs <br> CP1L-L14DT-D <br> DC power supply, 8 DC inputs, 6 transistor (sinking) outputs <br> CP1L-L14DT1-D <br> DC power supply, 8 DC inputs, 6 transistor (sourcing) outputs | L Type 10 Points <br> CP1L-L10DR-A <br> AC power supply, <br> 6 DC inputs, 4 relay outputs <br> CP1L-L10DT-A <br> AC power supply, 6 DC inputs, <br> 4 transistor (sinking) outputs <br> CP1L-L10DR-D <br> DC power supply, <br> 6 DC inputs, 4 relay outputs <br> CP1L-L10DT-D <br> DC power supply, 6 DC inputs, <br> 4 transistor (sinking) outputs <br> CP1L-L10DT1-D <br> DC power supply, 6 DC inputs, 4 transistor (sourcing) outputs |
| ת ת ת | Pulse outputs (only for transistor outputs) | 1 MHz for two axes (line driver outputs) 100 kHz for two axes (four axes total) | 100 KHz for | four axes |  |  | 100 kHz for two axes |  |  |  |
| 888 | Counters | 1 MHz (single-phase), 500 KHz (differential phases) for two axes (line driver outputs), 100 kHz (singlephasel), 50 kHz (differential phases) for two axes (four axes total) | 100 kHz (single-phase), 50 | kHz (differential phases) |  | 100 kHz (single-phase) for | or four axes, or 50 kHZ differe | ntial phases) for two axes |  |  |
| Hit | Serial communications |  | erial ports can be added as optior -232C or RS-422A/485 Option | ions <br> Boards). |  | optional serial ports can be ad RS-232C or RS-422A/485 Option | ded <br> Boards). | One optional seri (either an RS-232C or R | port can be added 422A/485 Option Board). | - |
| 믄 | Ethernet communications | When using CP1 | rnet ports can be added as an W-CIF41 Ver.1.0, one Ethernet p | option. <br> ort can be added. |  | hernet ports can be added as an 1W-CIF41 Ver.1.0, one Etherne | option. <br> can be added. | One Ethernet port can | be added as an option. | - |
| 파 | USB peripheral port | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| Amator | Built-in analog I/0 | - | 4 analog inputs and 2 analog outputs (resolution: 6,000 or 12,000) | - | - | - | - | - | - | - |
| (1) | Memory Cassette | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| L00 | LCD display settings | An LCD Option Boar | d can be added as an option to | option board slot 1 . |  | LCD Option Board can be adde an option to option board slot |  | An LCD Option Bo an option to op | d can be added as on board slot 1. | - |
| 四 | Function blocks (ladder diagrams or ST language) | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes |
| ¢ | Inverter positioning | - | - | - | Yes | Yes | Yes | Yes | Yes | Yes |
| 昭 | 7-segment display | Yes | Yes | Yes | - | - | - | - | - | - |
| 20 | Program capacity |  | ${ }^{20 K}$ steps |  |  | 10K | steps |  | 5 K steps |  |
| 5 | Data memory capacity |  | 32 K words |  |  | 32 K | words |  | 10 K words |  |
| (17) | High-speed processing | 0.1 us/ | D instruction, 0.3 us/MOV instr | uction |  |  | s/LD instruction, 1.84 us/M | istruction |  |  |




CP1H Only


Up to Four Axes Are Standard.
Advanced Power for High-precision Positioning Control.


A Full Range of Functions
Origin Search Function (ORG Instruction) Origin searches are possible with a single ORG instruction.
Positioning with Trapezoidal Acceleration and Deceleration (PLS2 Instruction)


Interrupt Feeding (ACC and PLS2 Instructions)


Applicable CPU Units and Functions



100 kHz for 4 axes


100 kHz for 2 axes

High-speed Counters
Differential Phases for Up to Four Axes Are Standard. Easily Handles Multi-axis Control with a Single Unit.


Applicable CPU Units and Functions


1 MHz (single-phase), 500 kHz 1 MHz (single-phase), 500 kHz
(differential phases) for two axes, 100 kHz (single-phase), 50 kHz (differential phases) for two axes (four axes total)


100 kHz (single-phase) 100 kHz (single-phase),
50 kHz (differential phases) for four axes

CP1L CPU Unit


100 kHz (single-phase) for four axes, or 50 kHZ ( phases) for two axes

Inverter Positioning High-speed Positioning


■Overview of Inverter Positioning
 PLC, but pulses can be outputructions normally output pulses from the counter according to the cerand setting in the instruction (such as PLS2)
(2)

The amount of pulses input to the error counter is converted to a speed
command and output to the inverter. A command to the inverter is created
in command and output to the inverter. A command to the inverter is create
in the ladder program using this speed command (proportional to the
pulses remaining in the error conter) When RS. pulses remaining in the error counter). When RS -485 communications ar
executed, ladder programming for communicating with the inverter is created. When analog outputs are executed, ladder programming for nalog outputs is created.
(3)

When a run/stop command is executed for the inverter, the motor is
rotated and feedback pulses (for the amount of movement) are output from
rta rotated and feedback pulses for the amount of movement) are output fro
the encoder to the CP1L. The error counter value is decremented by these
feedback pulses. The CP1L continues sending commands to the inverter eedback pulses. The CPIL continues sending commands to tede inverter
until positioning is completed. This enables accurate positioning to the until positioning is completed. This enables accura
position output by the first position command.

Applicable CPU Units and Functions


Inverter positioning function for two axes

## Serial Communications

A Standard USB Port and Two Serial Ports Enable Connecti ons and Communications with a Wide Range of Components.
Up to two Option Boards can be mounted for RS-232C or RS-422A/485 communications. A peripheral USB port has been added to connect to a personal computer for a total of three communications ports, making it easy to simultaneously connect to a PT, various components (such as Inverters, Temperature Controllers, and Smart Sensors), Serial PLC Link for linking to other PLCs, and a personal computer.


Applicable CPU Units and Functions


Serial PLC Links


## Modbus-RTU Easy Master

Connecting inverter speed control is made simple using the Modbus-RTU Easy Master. When the address, function, and data for a slave levice a preset in fixed mem ary (DM Area), message can be sent received simply by turning ON an AR Area bit (A640:00 for port 1 or A64100 for port 2) in the PLC


Easy Communications Programming Using OMRON Function Blocks
-The OMRON Function Blocks provide function blocks for communicating with Temperature Controllers

OMRON Function Blocks are provided for operations such as for setting SPs and reading PVs for Temperature Controllers by communication

Ethernet Communications
Two ports can be used as an Ethernet port to perform Ethernet communications between the $\mathrm{CP} 1 \mathrm{H} / \mathrm{CP} 1 \mathrm{~L}$ and a host computer.

Connect to a general-purpose LAN simply by mounting a CP1W-CIF41 Ethernet Option Board to an option board slot on any of the CPU Units in the CP1H/CP1L except a CPIL-L10.
Perform monitoring and programming with the CX-Programmer, or communicate between a host computer and the CP1H/CP1L using Ethernet by connecting with the FINS/TCP or FINS/UDP protocols which are supported by all OMRON PLCs.


Applicable CPU Units and Functions


Four Input Words and
Analog Control and Monitoring with Only a Single CPU Unit



Applicable CPU Units and Functions


[^1]

- Complete with CP1W/CPM1A Analog Units.


All CP-series CPU Units Provide a USB Port as a Standard Feature. FA Integrated Tool Package The built-in USB port lets you connect to a personal computer CX- ne


The CP1HCP1L down.
(The CP1H/CP1L USB port is used only for
connecting to a Programming Device.)
Note: Programming Consoles (CQM1H-PROO1 C200H-PROO27, etc.) cannot be used with
CP1H and CPIL CPU Units.

The Structured Text (ST) Language Makes Math Operations Even Easier.

In addition to ladder programming, function blo logic can be written in ST language, which
conforms to IEC $61131-3$. Arithmetic processing is also possible with ST, including processing of absolute values, square roots, logarithms, an trigonometric functions (SIN, COS, and TAN),
Processing that is difficult to write in ladder programming becomes easy using structured text.


High-speed Processing


The normal inputs can be set in the PLC Setup as interrut, quickresponse, or ocounter inpust. There are 8 normal inputs for the CP1H-
XXX for the CPIL with 14 points.)


Note: The CP1HCP1L CPU Units support the same function blocks
and ST language as CSS C $J$-series CPU Units with unit version 3.0. Are at Least Six Times Faster and MOV Instructions Are 26 Times Faster.
Processing speed has been increased not only for basic instructions but also for special instructions a yately 50 speeds up the entire system.


Compact Display and Setting Device
LCD Displays and Setting Available to Mount on CPU Unit for Easy Maintenance anc Startup Adjustments
Data values in the PLC can be easily monitored or changed by adding the new LCD Option Board. enables visually checking the operation status, such as error occurrence and error details. Registe advance functions that you use often to quickly perform settings and confirm operation. Functionality also be expanded to items not included in the CPU Unit, such as calendars and timers.


## Monitoring and Changing Data Values

## - I/O Monitoring

All memory area values
can be monitored and changed. Switch between decimal and hexadecima or monitor 2-word high-speed counter values, in decimal.
Visual Checking of Status with Display
of PLC Error Details

- I/O Monitoring



## 

Simply press the up and down keys to quickl display up to 16 registered monitor screens.

- User Monitor Settings and Messages

Up to seven fixed characters and the present value word data can be displayed. Simply press the up a down keys from the initial screen to perform monitoring. Of course, you can also change the settings. Plus, up to 48 characters can be set in advance and then displayed when a specified bit turns ON. This makes onsite setting and confirming faster

Expanded Functionality with Calendar Timer and Other Items Not Included in the CPU Uni

- Variety of Additional Functions

You can use calendar timers, weekly timers, and daily timers. Sixteen of each timer type can be set
 the error log.

Applicable CPU Units and Functions
CP1H
Can be mounted to
option board slot 1 .


Can be mounted to

CP1L
CPU Units with 14 points or 20 I/O points


Can be mounted to option board slot 1 .
and Startup.
Increased Program Reusability.
Integrated OMRON PLCs and Component Support Software

| FA Integrated Tool Package $\begin{aligned} & \text { CX-One } \\ & \text { Configuration }\end{aligned}$ | 1 Network Sofiware | CX-Integrator CX-FLnet CX-Protocol CX-ConfiguratorFDT Network Configurato |
| :---: | :---: | :---: |
| N- ne | 2 PLC Software | CX-Programmer CX-Simulator |
| The CX-One is an FA Integrated Tool Package for connecting, setting, and programming OMRON components, including PLCs. CP1H/CP1L programming and settings can be | (3) HMII Sofiware | SwitchBox Utility <br> Cx-Designer <br> Ladder Monitr software included. (See note 1.) <br> NW-Designer (See note 2.) |
| done with just the CX-Programmer, but the CX-One provides Support Software for setting and programming PTs, Temperature | (4) Motion Controller | CX-Drive <br> CX-Motion-NCF CX-Motion-MCH CX-Position <br> Motion |
| Controllers, and many other components. Using the CX-One makes programming and | (5) PLC Sofiware | CX-Process Tool NS-series Face Plate Auto-Builder |
| setup easy, shortening the total lead time required for starting up machines and | (6) Component Software | CX-Thermo |

Easy-to-use Programming Software.
Programming with Function Blocks (Ladder Diagrams/ST Language) Is Also Standard.

## CX-Programmer

- Easy Operation Simplifies Programming and Debugging.

- The Password Function Enables Protecting Important Programs.


Improved Functional Connectivity with HMI Design Software and Integration of Component Software Configured with an NS-series PT
CX-Designer
The CX-Designer can be started from the CX Integrator's NT Link Window. It can be used to design HMI screens. In addition, the Smar Active Parts (SAP) Library is provided with the $C$-Designer to enable easily cre
setting screens for devices such as Temperature Controllers.


## Memory Cassette

Data, such as programs and initial memory values, can be stored on a Memory Cassette (optional) and copied to other systems
The Memory Cassette can also be used when
installing new versions of application programs.

CP1W-MEOSM


## . . Clock Function

All CP1H/CP1L CPU Units have a built-in clock.
Shopping Mall Fountain Control
Controlling a Fountain for a Period of Time


- Analog Inputs Are Made Simple

An analog adjustment and an external analog setting
input connector are provided.


External Analog Setting Input Connector 7 -segmentid isplay.
This connecto is esolution. Each CP1HICP1L CPU Unit has one of these connectors built in. A device, such as a potentiometer, can be onnected to enable direct manual operation and contron from a onnecting cable ( 1 m ) is included with the CPU Unit.

## Status Displayed on

 7-segment Display (CP1H only)The 7 -segment display provides two display digit In addition to displaying error codes for errors detected by the PLC, codes can be displayed on th display from the ladder program
formantenance as well, allowing problems that arise during system operation to be grasped without using any Support Software.


## ■ Battery-free Operation

The values in the DM Area ( 32 K words) are saved in the CPU Unit's built-in flash memory as initia
values, and can be read at startup
Battery-free operation can be used to enable saving Area, turning OFF the power, and then using then same data again for the next production run. (This is ideal for machinery that is only used seasonally.)

## Note:

A battery is required for the clock function and to retain the status of $H R$ Area bits and counter values.
A battery is provided as a standard feature with the CPU Unit. - The ustery is programided as a sladder progrard feature is stored in the built-in flash The user program (ladder program) is stored in
memory, so no battery is required to back it up.

## CP1H CPU Unit Nomenclature



## CP1L CPU Unit Nomenclature



- CP1L CPU Units (L Type)
with 20 or 14 Points

- CP1L CPU Units (L Type)
with 10 Points



Restrictions on the Number of CP1H Expansion Unit and I/O Unit Connections
Up to seven Expansion Units and Expansion I/O Units can be connected when a CP1H CPU Unit is used, but the following restrictions apply. Observe these restrictions when using the models in the shaded areas in the following tables. A maximum total of 15 input words is allocated for Expansion Units and a maximum total of 15
output words is allocated for Expansion Units and Expansion I/O Units.
Words Allocated to CP1W Expansion Units and Expansion I/O Units

| Unittype |  | $\frac{\text { Model }}{\text { CPIW-40EDR }}$ | Input ${ }^{\text {Outp }}$ |  |
| :---: | :---: | :---: | :---: | :---: |
| Expansion I/O Units | 40/0 points |  | 2 | 2 |
|  |  | CPIW-40EDT |  |  |
|  |  | CPIW-40EDT |  |  |
|  | 32 outputs | CPWW-32ER | - | 4 |
|  |  | CPIW-32ET |  |  |
|  |  | CPIW-32ET1 |  |  |
|  | 2010 points | CPIW-20EDR1 | 1 | 1 |
|  |  | CPIW-20EDT |  |  |
|  |  | CPIW-20EDT1 |  |  |
|  | 16 outputs | CPIW-16ER | - | 2 |
|  |  | CPIW-16ET |  |  |
|  |  | CPIW-16ET1 |  |  |
|  | 8 inputs | CPW-8ED | 1 | - |
|  | 8 outputs | CPIW-8ER | - | 1 |
|  |  | CPWW-8ET |  |  |
|  |  | CPIW-8ET1 |  |  |
| Analog Units | 2 2analog inuts, 12 analog output | CPIW-MAD11 | 2 | 1 |
|  | 4 analog inputs | CPIW-AD041 | 4 | 2 |
|  | 4 analog outputs | CPIW-DA041 | - | 4 |
|  | 2 analog outputs | CP1W-DA021 | - | 2 |
| TemperatureSensor Units | 2 thermocouple inputs | CPIW-TS001 | 2 | - |
|  | 4 thermocouple inputs | CPIW-TS002 | 4 | - |
|  |  | CPIW-TS101 | 2 | - |
|  | ¢platinum resistares themometer inuts | CPIW-TS102 | 4 | - |
| CompoBus/S <br> I/O Link Unit | 8 inputs and 8 outputs | CPIW-SkT21 | 1 | 1 |

Four words ser Unit, so so mo more than three Units Unit is allocated our words per Unit, so no more than three Units can be connected (A words $\times \times$ Units $=12$ wordss. It would then be possible to omount a
combination of other $U$ Uits to use the remaining three input and 15 output words.
Examples of Possible Combinations


## Using CP1W-CN811 I/O Connecting Cable

- //O Connecting Cable can be connected to any Unit from the CP1H/CP1L CPU Unit to the third Expansion Unit o Expansion I/O Unit (i.e., the fourth Unit).
- Only one I/O Connecting Cable can be used in each CP1H or CP1L PLC. Expansion Units and Expansion I/O Units still apply.


Using CJ-series Special I/O Units or CPU Bus Units with a CP1H CPU Unit
Up to two CJ-series Special I/O Units or CPU Bus Units can be connected by using a CP1W-EXT01 CJ Unit Adapter. The number of Units that can be used is as described below.

## CJ Unit Adapter CP1W-EXTO1 <br> End Cover



| Unit name | Model |  | Unit name | del | cisme |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Analog <br> Input Units | CJIW-AD042 | 0.52 A | Position Control <br> Units | CJIW-NC113 |  |
|  | CJIW-ADO81-V1 | 0.42 A |  | CJ1W-NC213 |  |
|  | CJIW-ADO41-V1 |  |  | CJIW-Nc413 | ${ }_{0} 0.3$ |
| AnalogOutput Units | CJIW-DA042V | 0.40 A |  | CJIW-NC133 | 0.25 |
|  | CJIW-DA08V | 0.14 A |  | CJIW-NC233 |  |
|  | CJIW-DA08C |  |  | CJIW-Nc433 | 0.36 |
|  | CJIW-DA041 | 0.12 A | High-speed Counter <br> Unit | cJiw-cto21 | 0.25 A |
|  | CJ1W-DA021 |  |  |  |  |
| $\begin{array}{\|l\|l\|} \hline \text { Analog } \\ 1 / 0 \text { Unit } \end{array}$ | CJIW-mad42 | 0.58 A | ID Sensor Units | cJIw-v680c11 | $\begin{aligned} & 0.26 \mathrm{~A} \\ & \left(\begin{array}{l} 2.4 \mathrm{CO} \\ 0.13 \mathrm{~A}) \end{array}\right. \end{aligned}$ |
| Process <br> Input Units | CJIW-PH41U | 0.30 A |  | C.JIW-V680C12 |  |
|  | CJIW-ADO4U | 0.32 A |  | CJIW-V680cti | $\underbrace{(24 \mathrm{VC}}_{(0.26 \mathrm{~A})}$ |
|  | ${ }_{\text {CJIW-PSS51 }}$ | 0.25 A |  | CJIW-V600c 11 | $\begin{gathered} 0.26 \mathrm{~A} \\ \substack{124 \mathrm{VVC} \\ 2102} \end{gathered}$ |
|  | CJIW-PTS15 | 0.18 A |  | CJIW-v600C12 | $\begin{gathered} 0.32 \mathrm{~A} \\ 2(240 \mathrm{C} \end{gathered}$ |
|  | CJIW-PTS16 |  |  |  |  |
|  | CJIW-PDC15 |  | $\begin{aligned} & \text { Serial } \\ & \text { Communications } \\ & \text { Units } \end{aligned}$ | CJIW-SCU42 |  |
| TemperatureControl Units | CJIW-TC001 | 0.25 A |  | CJIW-SCU22 | $0.28 \mathrm{~A}^{*}$ |
|  | CJIW-Tcoos |  |  | CJ1W-SCU32 | 0.40 A |
|  | CJIW-TCoou |  |  | CJIW-SCU41-V1 | ${ }^{0.38 \mathrm{~A}^{*}}$ |
|  | CJIW-TC101 |  |  | Culw-SCu21-V1 | ${ }^{0.28 \mathrm{~A}^{*}}$ |
|  | CJIW-TC102 |  |  | Cu1w-SCU31-V1 | 0.38 A |
|  | CJIW-TC103 |  | ernet Unit | CJIW-ETN21 | 0.37 A |
|  | CJIW-TCLIO4 |  | EtherNetIP Unit | CJIWEEIP21 | 0.41 A |
|  |  |  | Devicenet Unit | CJIW-DRM21 | 0.33 A |
| Master Unit | CJIW-SRM21 | 0.15 A | Controler Link Unit | cJiw-CLK23 | 0.35 A |
| $\begin{aligned} & \text { Componet } \\ & \text { Master Unit } \end{aligned}$ | cJIW-CRM21 | 0.40 A | MECHATROLINK-II Position Control Unit | CJIW-NC271 | ${ }^{0.36}$ |
|  |  |  |  | CJlw-Nc471 |  |
|  |  |  |  | CJIW-CCF71-MA |  |
| I I/O Units or CPU Bus Units are used with a used is two CJ -series Units and seven |  |  | MECHATROLINK-II Motion Control Unit | cJiw-mсн71 | 0.6 A |
| an 2 A for 5 V and 1 A for 24 V , and the total |  |  | F-net Unit | CJIW-LIN22 | ${ }^{0.37}$ |
|  |  |  | Storage/Processing | Culw-spuol-v2 | 0.56 A |

CP1H CPU Unitit the maximum number of Units that can be CP1WCPPMA Expansion Units and Expansion IO Units current consumption must be the no more than the 30 W .
Check the toatal current consumption to be sure these limits are not exceeded referring to page 29 for the
CPIH CPU Unit and CPIW Expansion Unit and Expans CP1H CPU Unit and CPP Expansion Unit and Ex
table for CU-series Unit current consumptions.



## CPU Unit Specifications

## ■ I／O Bits and I／O Allocations

With CP1H and CP1L CPU Units，the beginning input and output words（CIO 0 and CIO 100）are allocated by the CPU Unit one or two words at a time．I／O bits are allocated in word units in order of connection to Expansion Units and Expansion I／O Units connected to a CPU Unit．

| CPU Unit | Allocated words |  |
| :---: | :---: | :---: |
|  | Inputs | Outputs |
| CP1H CPU Unit with $401 / 0$ points | ClO 0 and ClO 1 | ClO 100 and ClO 101 |
| CP1L CPU Unit with 10，14，or 20 lO points | ClO 0 | CIO 100 |
| CP1L CPU Unit with 30 or 40 IO points | ClO 0 and ClO 1 | C10 100 and C1O 101 |
| CP1L CPU Unit with 60 lO points | $\mathrm{ClO} 0, \mathrm{ClO} 1$ ，and ClO 2 | ClO 100，ClO 101，and ClO102 |

Note：For details on the number of words allocated to Expansion Units and Expansion I／O Units，refer to Words Allocated to CPIW Expansion Units and Expansion I／O Units on page 26
－Example：／／O Bit Allocations When Expansion Units Are Connected
PU Unit with 40 IV Points＋Temperature Sensor Unit＋Analog Output Unit＋Expansion I／O Unit with 40 I／O Points


|  | Unitwith 40 IOP Pa | Temperatue Sesisor | Analo Outut Unit | Expansion 10 Unitw with 4010 OPoints |
| :---: | :---: | :---: | :---: | :---: |
| Inputs |  | C102 ${ }^{\text {to }}$ 5 | None |  |
| Outputs |  | None |  |  |


| TypeModel | AC power supply models | DC power supply models |
| :---: | :---: | :---: |
|  | CP1H－7प्－A <br> CP1L－70］－A | $\begin{aligned} & \text { CP1H-a-D } \\ & \text { CP1L- } \end{aligned}$ |
| Power supply | 00 to $240 \mathrm{VAC} 50 / 60 \mathrm{~Hz}$ | VD |
| Operating voltage range | 85264 VAC | 20.4 to 26.4 VDC |
| Power consumption | 100 VA max．（CP1H－प［ID－A） <br> 50 VA max．（CP1L－M60／－M40／－M30ПI－A）（See next page．） <br> 30 VA max．（CP1L－L20／－L14／－L10DI－A） | 50 W max．（CP1H－םपП－D） 20 W max．（CP1L－M60／－M40／－M30ロロ－D）（See next page．） 13 W max．（CP1L－L20／－L14／－L10 |
| Inrush current（See note．） | 100 to 120 VAC inputs： <br> 20 A max．（for cold start at room temperature） 8 ms max． <br> 200 to 240 VAC inputs： <br> 40 A max．（for cold start at room temperature）， 8 ms max． | 30 A max．（for cold start at room temperature） 20 ms max． |
| External power supply | 300 mA at 24 VDC （CP1H，CP1L－M60／－M40／－M30Пロ－A） 200 mA at 24 VDC（CP1L－L20／－L14／－L10 1 I－A） | None |
| Insulation resistance | $20 \mathrm{M} \Omega$ min．（at 500 VDC ）between the external $A C$ terminals and GR terminals | No insulation between primary and secondary for DC power supply |
| Dielectric strength | $2,300 \mathrm{VAC}$ at $50 / 60 \mathrm{~Hz}$ for 1 min between the external AC and GR terminals，leakage current： 5 mA max． | No insulation between primary and secondary for DC power supply |
| Noise immunity | Conforms to IEC 61000－4－4． 2 kV （power supply line） |  |
| Vibration resistance | Conforms to JIS C0040． 10 to $57 \mathrm{~Hz}, 0.075-\mathrm{mm}$ amplitude， 57 minutes each．Sweep time： 8 minutes $\times 10$ sweeps $=$ total time | 150 Hz ，acceleration： $9.8 \mathrm{~m} / \mathrm{s}^{2}$ in $\mathrm{X}, \mathrm{Y}$ ，and Z directions for 80 80 minutes） |
| Shock resistance | Conforms to JIS C0041． $147 \mathrm{~m} / \mathrm{s}^{2}$ three times each in $X, Y$ ，and | directions |
| Ambient operating tempera－ ture | 0 to $55^{\circ} \mathrm{C}$ |  |
| Ambient humidity | 10\％to 90\％（with no condensation） |  |
| Ambient operating environ－ <br> ment | No corrosive gas |  |
| Ambient storage temperature | -20 to $75^{\circ} \mathrm{C}$（Excluding batery．） |  |
| Power holding time | $10 \mathrm{~ms} \mathrm{min}$. | 2 ms min． |

Note：The above values are for a cold start at room temperature for an AC power supply，and for a cold start for a DC power supply
he above values are for a cold start at room temperature tor an AC power supply，and for a cold start for a DC power supply．
A thermistor wwit low－temperature current suppression characteristics）is used in the inrush current contro circuitry
will the will not be sufficiently cooled it the ambient temperature is high or it a ho start is pertormed when the power supply has been OFF for only y short time．In
breakers for external l ircurits．
A capacitor charge－tyee delay circuit is used in the inrush current control circuitry for the DC power supply．The capacitor will not be charged if a hot start is
A capacitor charge－type delay circuit is used in the inrush current control circuitry for the DC power supply．The capacitor will not be charged if a hot start is
periormed when the power supply has been OFF for only a short time，so in those cases the inrush current values may be higher（as much as two times
higher）than those shown above．

## Current Consumption

The power consumption shown on page 28 is the maximum power consumption. To obtain the correct power consumption for the system config uration, calculate the power consumption for the external power supply from the current consumption given below for the CPU Unit, Expansion Units, and Expansion I/O Units. (When using CJ-series Units with the CP1H, add the current consumption for the CJ-series Units shown on page

- CPU Units

| Model | Current consumption |  | External power supply24 VDC (See note 5 .) |
| :---: | :---: | :---: | :---: |
|  | 5 VDC | 24 VDC |  |
| CP1H-X40DR-A | 0.42 A | 0.07 A | 0.3 A max. (0.9 A max.) |
| CP1H-X40DT-D | 0.50 A | 0.01 A | --- |
| CP1H-X40DT1-D | 0.50 A | 0.02 A | --- |
| CPIH-XA40DR-A | 0.43 A | 0.18 A | 0.3 A max. (0.8 A max.) |
| CP1H-XA40DT-D | 0.51 A | 0.12 A | -- |
| CP1H-XA40DT1-D | 0.51 A | 0.15 A | -- |
| CP1H-Y20DT-D | 0.55 A | --- | --- |
| CP1L-M60DR-A | 0.25 A | 0.14 A | 0.3 A max. (0.5 A max.) |
| CP1L-M60DT-A | 0.39 A | 0.03 A | 0.3 A max. (0.6 A max.) |
| CP1L-M60DR-D | 0.25 A | 0.14 A | --- |
| CP1L-M60DT-D | 0.39 A | 0.03 A | --- |
| CP1L-M60DT1-D | 0.39 A | 0.03 A | --- |
| CP1L-M40DR-A | 0.22 A | 0.08 A | 0.3 A max. (0.6 A max.) |
| CP1L-M40DT-A | 0.31 A | 0.03 A | 0.3 A max. (0.6 A max.) |
| CP1L-M40DR-D | 0.22 A | 0.08 A | --- |
| CP1L-M40DT-D | 0.31 A | 0.03 A | --- |
| CP1L-M400T1-D | 0.31 A | 0.03 A | --- |
| CP1L-M30DR-A | 0.21 A | 0.07 A | 0.3 A max. (0.6 A max.) |
| CP1L-M30DT-A | 0.28 A | 0.03 A | 0.3 A max. (0.6 A max.) |
| CP1L-M30DR-D | 0.21 A | 0.07 A | -- |
| CP1L-M30DT-D | 0.28 A | 0.03 A | -- |
| CP1L-M30DT1-D | 0.28 A | 0.03 A | --- |
| CP1L-L20DR-A | 0.20 A | 0.05 A | 0.2 A max. |
| CP1L-L20DT-A | 0.24 A | 0.03 A | 0.2 A max. |
| CP1L-L20DR-D | 0.20 A | 0.05 A | --- |
| CP1L-L20DT-D | 0.24 A | 0.03 A | --- |
| CP1L-L20DT1-D | 0.24 A | 0.03 A | --- |
| CP1L-L14DR-A | 0.18 A | 0.04 A | 0.2 A max. |
| CP1L-L14DT-A | 0.21 A | 0.03 A | 0.2 A max. |
| CP1L-L14DR-D | 0.18 A | 0.04 A | --- |
| CP1L-L14DT-D | 0.21 A | 0.03 A | -- |
| CP1L-L14DT1-D | 0.21 A | 0.03 A | --- |
| CP1L-L10DR-A | 0.16 A | 0.03 A | 0.2 A max. |
| CP1L-L100T-A | 0.18 A | 0.03 A | 0.2 A max. |
| CP1L-L10DR-D | 0.16 A | 0.03 A | --- |
| CP1L-L10DT-D | 0.18 A | 0.03 A | --- |
| CP1L-L10DT1-D | 0.18 A | 0.03 A | --- |

Note: 1. The current
2. CPU Units with DC power do not provide an external power supply.
. The current consumptions given in the following table must be added to the current consumption of the CPU Unit if an Expansion Unit or Expansion //O Unit
is connected.
5. Values in parenthesescare the maximum external powers supply for a CPU Unit to which an Expenansion I/O Unit is not connected. Refer to the CP1L CPU Unit Values in parentheses are the maximum external power supply for a CPU Unit to which an Expansion
Operation Manual (Cat No. W462) or CP1H CP Unit Operation Manual (Cat No. W450) for details.

## CPU Unit Specifications

- Expansion Units and Expansion I/O Units

| Unit name |  | Model | Current consumption |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | 5 VDC | 24 VDC |
| Expansion I/O Units | 40 I/O points 24 inputs 16 output |  | CP1W-40EDR | 0.080 A | 0.090 A |
|  |  | CP1W-40EDT | 0.160 A | --- |
|  |  | CP1W-40EDT1 |  |  |
|  | 32 outputs | CP1W-32ER | 0.049 A | 0.131 A |
|  |  | CP1W-32ET | 0.113 A | --- |
|  |  | CP1W-32ET1 |  |  |
|  | 20 I/O points 12 inputs 8 outputs | CP1W-20EDR1 | 0.103 A | 0.044 A |
|  |  | CP1W-20EDT | 0.130 A | --- |
|  |  | CP1W-20EDT1 |  |  |
|  | 16 outputs | CP1W-16ER | 0.042 A | 0.090 A |
|  |  | CP1W-16ET | 0.076 A | --- |
|  |  | CP1W-16ET1 |  |  |
|  | 8 inputs | CP1W-8ED | 0.018 A | --- |
|  | 8 outputs | CP1W-8ER | 0.026 A | 0.044 A |
|  |  | CP1W-8ET | 0.075 A | --- |
|  |  | CP1W-8ET1 |  |  |
| Analog Input Unit | 4 inputs | CP1W-AD041 | 0.100 A | 0.090 A |
| Analog Output Unit | 4 outputs | CP1W-DA041 | 0.080 A | 0.124 A |
|  | 2 outputs | CP1W-DA021 | 0.095 A | 0.040 A |
| Analog I/O Unit | 2 inputs and 1 output | CP1W-MAD11 | 0.083 A | 0.110 A |
| Temperature Sensor Units | $K$ or $J$ thermocouple inputs | CP1W-TS001 | 0.040 A | 0.059 A |
|  |  | CP1W-TS002 |  |  |
|  | Pt or JPt platinum resistance thermometer inputs | CP1W-TS101 | 0.054 A | 0.073 A |
|  |  | CP1W-TS102 |  |  |
| CompoBus/S IO Link Unit | 8 inputs and 8 outputs | CP1W-SRT21 | 0.029 A | --- |


| Type |  | CP1H-XA CPU Units | CP1H-X CPU Units | CP1H-Y CPU Units |
| :---: | :---: | :---: | :---: | :---: |
| Item Models |  |  | CP1H-X | CP1H-YपIT-D |
| Control met |  | Stored program method |  |  |
| $1 / 0$ control method |  | Cyclic scan with immediate refreshing |  |  |
| Program language |  | Ladder diagram |  |  |
| Function blocks |  | Maximum number of function block definitions: 128 Maximum number of instances: 256 Languages usable in function block definitions: Ladder diagrams, structured text (ST) |  |  |
| Instruction length |  | 1 to 7 steps per instruction |  |  |
| Instructions |  | Approx. 500 (function codes: 3 digits) |  |  |
| Instruction execution time |  | Basic instructions: $0.10 \mu \mathrm{~s}$ min. Special instructions: 0.15 us min. |  |  |
| Common processing time |  | 0.7 ms |  |  |
| Program capacity |  | 20 K steps |  |  |
| Number of tasks |  | 288 (32 cyclic tasks and 256 interrupt tasks) |  |  |
|  | Scheduled interrupt tasks | 1 (interrupt task No. 2, fixed) |  |  |
|  | Input interrupt tasks | 8 (interrupt task No. 140 to 147, fixed) |  | 6 (interrupt task No. 140 to 145, fixed) |
|  |  | (Interrupt tasks can also be speciified and executed for high-speed counter interrupts.) |  |  |
| Maximum subroutine number |  | 256 |  |  |
| Maximum jump number |  | 256 |  |  |
| I/O areas(See note.) | Input bits | 1,600 bits ( 100 words): ClO 0.00 to ClO 99.15 (The 24 built-in inputs are allocated in CIO 0.00 to CIO 0.11 and CIO 1.00 to ClO 1.11.) |  |  |
|  | Output bits | 1,600 bits ( 100 words): CIO 100.00 to CIO 199.15 (The 16 built-in outputs are allocated in CIO 100.00 to CIO 100.07 and CIO 101.00 to CIO 101.07.) |  |  |
|  | $\begin{array}{\|l} \hline \text { Built-in Analog } \\ \text { Inputs } \end{array}$ | CIO 200 to CIO 203 |  | --- |
|  | Built-in Analog Out-uts | CIO 210 to ClO 211 |  | --- |
|  | Serial PLC Link Area | 1,440 bits (90 words): CIO 3100.00 to ClO 3189.15 (CIO 3100 to CIO 3189) |  |  |
| Work bits |  | 8,192 bits (512 words): W0.00 to W511.15 (W0 to W511) <br> CIO Area: 37,504 bits ( 2,344 words): CIO 3800.00 to CIO 6143.15 (CIO 3800 to CIO 6143 ) |  |  |
| TR Area |  | 16 bits: TR0 to TR15 |  |  |
| Holding Area |  | 8,192 bits (512 words): $\mathrm{H0} 0.00$ to H511.15 (H0 to H511) |  |  |
| Area |  | Read-only (Write-prohibited): 7168 bits ( 448 words): A0.00 to A447.15 (A0 to A447) Read/Write: 8192 bits ( 512 words): A448.00 to A959.15 (A448 to A959) |  |  |
| Timers |  | 4,096 bits: T0 to T4095 |  |  |
| Counters |  | 4,096 bits: C0 to C4095 |  |  |
| DM Area |  | 32 Kwords: D0 to D32767 |  |  |
| Data Register Area |  | 16 registers (16 bits): DR0 to DR15 |  |  |
| Index Register Area |  | 16 registers (32 bits): : R00 to IR15 |  |  |
| Task Flag Area |  | 32 flags (32 bits): TK0000 to TK0031 |  |  |
| Trace Memory |  | 4,000 words ( 500 samples for the trace data maximum of 31 bits and 6 words.) |  |  |
| Memory Cassette |  | A special Memory Cassette (CP1W-ME05M) can be mounted. Note: Can be used for program backups and auto-booting. |  |  |
| Clock function |  | Supported. Accuracy (monthly deviation): -4.5 min to -0.5 min (ambient temperature: $55^{\circ} \mathrm{C}$ ), -2.0 min to +2.0 min (ambient temperature: $25^{\circ} \mathrm{C}$ ), -2.5 min to +1.5 min (ambient temperature: $0^{\circ} \mathrm{C}$ ) |  |  |
| Communications functions |  | One built-in peripheral port (USB 1.1): For connecting Support Sotware only. |  |  |
|  |  | A maximum of two Serial Communications Option Boards can be mounted. |  |  |
|  |  | A maximum of two Ethernet Option Boards can be mounted. When using CP1W-CIF41 Ver.1.0, one Ethernet Option Board can be mounted. |  |  |
| Memory backup |  | Flash memory: User programs, parameters (such as the PLC Setup), comment data, and the entire DM Area can be saved to flash memory as initial values. <br> Battery backup: The Holding Area, DM Area, and counter values (flags, PV) are backed up by a battery. |  |  |
| Battery service life |  | 5 years at $25^{\circ} \mathrm{C}$. (Use the replacement battery within two years of manufacture.) |  |  |
| Built-in input terminals |  | 40 (24 inputs, 16 outputs) |  | 20 (12 inputs, 8 outputs) Line-driver inputs: Two axes for phases A, B, and Z Line-driver outputs: Two axes for CW and CCW |
| Number of connectable Expansion (I/O) Units |  | CP Expansion I/O Units: 7 max.; CJ-series Special I/O Units or CPU Bus Units: 2 max. |  |  |
| Max. number of I/O points |  | 320 (40 built in +40 per Expansion (/IO) Unit $\times 7$ Units) |  | 300 (20 built in +40 per Expansion (IVO) Unit $\times 7$ Units) |
| Interrupt inputs |  | 8 inputs (Shared by the external interrupt inputs (counter mode) and the quick-response inputs.) |  | 6 inputs (Shared by the external interrupt inputs (counter mode) and the quick-response inputs.) |
| Interrupt input counter mode |  | 8 inputs (Response frequency: 5 kHz max. for all interrupt inputs), 16 bits <br> Up or down counters |  | 6 inputs (Response frequency: 5 kHz max. for all interrupt inputs), 16 bits Up or down counters |
| Quick-response inputs |  |  |  | 6 points (Min. input pulse width: $50 \mu \mathrm{~s}$ max.) |
| Scheduled i | interrupts | $\begin{array}{\|l\|} \hline 8 \text { points (Min. input pulse width: } 50 \mu \mathrm{~s} \text { max.) } \\ \hline 1 \end{array}$ |  |  |

## CPU Unit Specifications

| Item | $\begin{array}{r} \text { Type } \\ \text { Models } \end{array}$ | CP1H－XA CPU Units | CP1H－X CPU Units | CP1H－Y CPU Units |
| :---: | :---: | :---: | :---: | :---: |
|  |  | CP1H－XA | CP1H－X | CP1H－Y |
| High－speed counters |  | 4 inputs：Differential phases（ 4 x ）， 50 kHz or <br> Single－phase（pulse plus direction，up／down，increment）， 100 kHz <br> Value range： 32 bits，Linear mode or ring mode <br> interrupts：Target value comparison or range comparison |  | 2 inputs：Differential phases（4x）， 500 kHz or Single－phase， <br> 1 MHz and <br> 2 inputs：Differential phases（ 4 x ）， 50 kHz or Single－phase （pulse plus direction，up／down，increment）， 100 kHz <br> Value range： 32 bits，Linear mode or ring mode Interrupts：Target value comparison or range comparison |
| Pulse outputs （models with transistor out－ puts only） | Pulse out－ <br> puts | Trapezoidal or S－curve acceleration and deceleration <br> （Duty ratio： $50 \%$ fixed） <br> 4 outputs， 1 Hz to 100 kHz （CCW／CW or pulse plus direction） |  | Trapezoidal or S－curve acceleration and deceleration （Duty ratio：50\％fixed） <br> 2 outputs， 1 Hz to 1 MHz （CCW／CW or pulse plus direction） <br> 2 outputs， 1 Hz to 100 kHz （CCW／CW or pulse plus direction） |
|  | PWM out－ puts | Duty ratio：0．0\％to 100．0\％（Unit：0．1\％） <br> 2 outputs， 0.1 to 6553.5 Hz （Accuracy：$\pm 5 \%$ at 1 kHz ） |  |  |
| Built－in analog IO terminals |  | 4 analog inputs and 2 analog outputs | None |  |
| Analog control |  | 1 （Setting range： 0 to 255） |  |  |
| External analog input |  | 1 input（Resolution： $1 / 256$ ，Input range： 0 to 10 V ，not isolated |  |  |

Note：The memory area．
（Cat．No．PO52）．

| Item | Type | CP1L－M60 | $\underset{\text {（40 LL－M40 }}{\text {（40 }}$ | CP1L－M30 | CP1L－L20 | $\underset{\text {（14 p－Lints）}}{ }$ | CP1L－L10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Models | CP1L－M60T－ロ | CP1L－M40 | CP1L－M300［－］ | CP1L－L20］ロ－ロ | CP1L－L14 ${ }^{\text {ala－］}}$ | CP1L－L10［－－ |
| Control method |  | Stored program method |  |  |  |  |  |
| $1 / 0$ control method |  | Cyclic scan with immediate refreshing |  |  |  |  |  |
| Program language |  | Ladder diagram |  |  |  |  |  |
| Function blocks |  | Maximum number of function block definitions： 128 Maximum number of instances： 256 Languages usable in function block definitions：Ladder diagrams，structured text（ST） |  |  |  |  |  |
| Instruction length |  | 1 to 7 steps per instruction |  |  |  |  |  |
| Instructions |  | Approx． 500 （tunction codes： 3 digits） |  |  |  |  |  |
| Instruction execution time |  | Basic instructions： 0.55 Hs min．Special instructions： 4.1 us min． |  |  |  |  |  |
| Common processing time |  | 0.4 ms |  |  |  |  |  |
| Program capacity |  | 10 K steps |  |  | 5 K steps |  |  |
| Number of tasks |  | 288 （32 cyclic tasks and 256 interrupt tasks） |  |  |  |  |  |
|  | Scheduled inter－ rupt tasks | 1 （interrupt task No．2，fixed） |  |  |  |  |  |
|  | Input interrupt tasks | 6 （interrupt task No． 140 to 145，fixed） |  |  |  | $\begin{array}{\|l} \hline \begin{array}{l} 4 \text { (interrupt task No. } \\ 140 \text { to } 143, \text { fixed) } \end{array} \\ \hline \end{array}$ | $\begin{aligned} & 2 \text { (interrupt task No. } \\ & 140 \text { to } 141, \text { fixed) } \\ & \hline \end{aligned}$ |
|  |  | （Interrupt tasks can also be specified and executed for high－speed counter interrupts and executed．） |  |  |  |  |  |
| Maximum subroutine number |  | 256 |  |  |  |  |  |
| Maximum jump number |  | 256 |  |  |  |  |  |
| $\left\lvert\, \begin{aligned} & 1 / 0 \\ & \text { areas } \end{aligned}\right.$ | Input bits | 36：CIO 0.00 to CIO 0．11，CIO 1.00 to ClO 1．11，and CIO 2.00 to CIO 2.11 | $\begin{aligned} & 24: \mathrm{ClO} 0.00 \text { to } \mathrm{ClO} \\ & 0.11 \text { and CIO } \\ & \text { to ClO } 1.11 .11 .00 \end{aligned}$ | 18： CIO 0.00 to ClO 0.11 and CIO 1.00 to CIO 1.05 | 12： ClO 0.00 to ClO 0.11 | 8： ClO 0.00 to ClO 0.07 | 6：${ }^{\text {Colo }} 0.00$ to ClO |
|  | Output bits | $\begin{aligned} & \text { 24: CIO } 100.00 \text { to } \\ & \text { COO 100.07, } \\ & \text { CIO } 101.00 \text { to ClO } \\ & \text { 101.07, and CIO } \\ & \text { 102.00 to CIO } \\ & \text { 102.07 } \end{aligned}$ | 24：CIO 0.00 to CIO 0.11 and ClO 1.00 to ClO 1.11 | 12：CIO 100.00 to CIO 100.07 and CIO 101.00 to CIO 101.03 | $\begin{aligned} & \text { 8: CIO } 100.00 \text { to } \\ & \text { CIO } 100.07 \end{aligned}$ | $\begin{aligned} & \text { 6: CIO } 100.00 \text { to } \\ & \text { CIO } 100.05 \end{aligned}$ | $\begin{aligned} & \text { 4: CIO } 100.00 \text { to } \\ & \text { CIO } 100.03 \end{aligned}$ |
|  | 1：1 Link Area | 1,024 bits（ 64 words）： ClO 3000.00 to ClO 3063.15 （ClO 3000 to ClO 3063 ） |  |  |  |  |  |
|  | Serial PLC Link Area | 1，440 bits（90 words）：ClO 3100．00 to CIO 3189.15 （ClO 3100 to CIO 3189 ） |  |  |  |  |  |
| Work bits |  | 8,192 bits（ 512 words）：W000．00 to W511．15（W0 to W511） CIO Area： 37,504 bits（2，344 words）： CIO 3800.00 to CIO 6143.15 （CIO 3800 to CIO 6143 ） |  |  |  |  |  |
| TR Area |  | 16 bits：TRO to TR15 |  |  |  |  |  |
| Holding Area |  | 8，192 bits（512 words）： H 0.00 to H 511.15 （H0 to H511） |  |  |  |  |  |
| AR Area |  | Read－only（Write－prohibited）： 7168 bits（ 448 words）：A0．00 to A447．15（A0 to A447） Read／Write： 8192 bits（ 512 words）：A448．00 to A959．15（A448 to A959） |  |  |  |  |  |
| Timers |  | 4，096 bits：T0 to T4095 |  |  |  |  |  |
| Counters |  | 4，096 bits：C0 to C4095 |  |  |  |  |  |
| DM Area |  | 32 Kwords：D0 to D32767 ${ }^{\text {a }}$（10 Kwords：D0 to D9999，D32000 to D32767 |  |  |  |  |  |
| Data Register Area |  | 16 registers（16 bits）：DR0 to DR15 |  |  |  |  |  |
| Index Register Area |  | 16 registers（32 bits）：IR0 to R15 |  |  |  |  |  |
| $\begin{array}{\|l\|} \hline \text { Task Flag Area } \\ \hline \text { Trace Memory } \\ \hline \end{array}$ |  | 32 flags（32 bits）：Tk0000 to TK0031 |  |  |  |  |  |
|  |  | 4,000 words（ 500 samples for the trace data maximum of 31 bits and 6 words．） |  |  |  |  |  |
|  |  | A special Memory Cassette（CP1W－ME05M）can be mounted．Note：Can be used for program backups and auto－booting． |  |  |  |  |  |


| Item | $\begin{array}{r} \text { Type } \\ \text { Models } \end{array}$ | CP1L-M60 (60 points) | CP1L-M40 (40 points) | CP1L-M30 ( 30 points) | CP1L-L20 (20 points) | CP1L-L14 (14 points) | CP1L-L10 (10 points) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | CP1L-M60 | CP1L-M40 | CP1L-M30-7-7 | CP1L-L20 | CP1L-L14 | CP1L-L10 ${ }^{\text {a }}$ |
| Clock function |  | Supported. Accuracy (monthly deviation): -4.5 min to -0.5 min (ambient temperature: $55^{\circ} \mathrm{C}$ ), <br> -2.0 min to +2.0 min (ambient temperature: $25^{\circ} \mathrm{C}$ ), -2.5 min to +1.5 min (ambient temperature: $0^{\circ} \mathrm{C}$ ) |  |  |  |  |  |
| Communications functions |  | One built-in peripheral port (USB 1.1): For connecting Support Software only. |  |  |  |  |  |
|  |  | A maximum of two Serial Communications Option Boards can be mounted. |  |  | A maximum of one Serial Communications Option Board can be mounted. |  | Not supported. |
|  |  | A maximum of two Ethernet Option Board can be mounted. When using CP1W-CIF41 Ver.1.0, one Ethernet Option Board can be mounted |  |  | A maximum of one Ethernet Option Board can be mounted. |  | Not supported. |
| Memory backup |  | Flash memory: User programs, parameters (such as the PLC Setup), comment data, and the entire DM Area can be saved to flash memory as initial values. <br> Battery backup: The Holding Area, DM Area, and counter values (flags, PV) are backed up by a battery. |  |  |  |  |  |
| Battery service life |  | 5 years at $25^{\circ} \mathrm{C}$. (Use the replacement battery within two years of manufacture.) |  |  |  |  |  |
| Built-in input terminals |  | 60 (36 inputs, 24 outputs) | 40 (24 inputs, 16 outputs) | 30 (184 inputs, 12 outputs) | 20 (12 inputs, 8 outputs) | 14 (8 inputs, 6 outputs) | 10 (6 inputs, 4 outputs) |
| Number of connectable Expansion Units and Expansion I/O Units |  | CP-series Expansion Unit and Expansion I/O Units: 3 max. |  |  | CP-series Expansion Units and Expansion I/O Units: 1 max. |  | Not supported. |
| Max. number of //O points |  | $\begin{array}{\|l\|l\|} \hline 180 \text { (60 built in }+40 \\ \text { per Expansion (1/0) } \\ \text { Unit } \times 3 \text { Units) } \end{array}$ | $\begin{aligned} & 160 \text { (40 built in }+40 \\ & \text { per Expansion (I/O) } \\ & \text { Unit } \times 3 \text { Units) } \end{aligned}$ | $\begin{aligned} & 150 \text { (30 built in }+40 \\ & \text { per Expansion (/VO) } \\ & \text { Unit } \times 3 \text { Units) } \end{aligned}$ | $\begin{aligned} & 60 \text { (20 built in }+40 \\ & \text { per Expansion (I/O) } \\ & \text { Unit } \times 1 \text { Unit) } \end{aligned}$ | $\begin{aligned} & 54 \text { (14 built in }+40 \\ & \text { per Expansion (I/O) } \\ & \text { Unit } \times 1 \text { Unit) } \end{aligned}$ | 10 (10 built in) |
| Interrupt |  | 6 inputs (Response time: 0.3 ms |  |  |  | 4 inputs (Response time: 0.3 ms ) | $\begin{aligned} & \text { 2 inputs (Response } \\ & \text { time: } 0.3 \mathrm{~ms} \text { ) } \end{aligned}$ |
| Interrupt inputs counter mode |  | 6 inputs (Response frequency: 5 kHz max. for all interrupt inputs), 16 bits Up or down counters |  |  |  | 4 inputs (Response frequency: <br> 5 kHz max. for all interrupt inputs), 16 bits <br> Up or down counters | 2 inputs (Response frequency: <br> 5 kHz max. for all interrupt inputs), 16 bits <br> Up or down <br> counters |
| Quick-response inputs |  | 6 points (Min. input pulse width: 50 us max.) |  |  |  | 4 points (Min. input pulse width: $50 \mu \mathrm{~s}$ max.) | 2 points (Min. input pulse width: $50 \mu \mathrm{~s}$ max. |
| Scheduled interrupts |  | 1 lese |  |  |  |  |  |
| High-speed counters |  | 4 counters, 2 axes (24-VDC input) 4 inputs: Differential phases (4x), 50 kHz Single-phase (pulse plus direction, up/down, increment), 100 kHz Value range: 32 bits, Linear mode or ring mode Interrupts: Target value comparison or range comparison |  |  |  |  |  |
| Pulse outputs (models with transistor out puts only) | Pulse outputs | Trapezoidal or S-curve acceleration and deceleration (Duty ratio: $50 \%$ fixed) 2 outputs, 1 Hz to 100 kHz (CCW/CW or pulse plus direction) |  |  |  |  |  |
|  | $\begin{aligned} & \text { PWM } \\ & \text { outputs } \end{aligned}$ | Duty ratio: $0.0 \%$ to $100.0 \%$ (specified in increments of $0.1 \%$ or $1 \%$ ) <br> 2 outputs, 0.1 to 6553.5 Hz or 1 to $32,800 \mathrm{~Hz}$ (Accuracy: $+1 \% / 0 \%$ at 0.1 Hz to $10,000 \mathrm{~Hz}$ and $+5 \% / 0 \%$ at $10,000 \mathrm{~Hz}$ to $32,800 \mathrm{~Hz}$ ) |  |  |  |  |  |
| Analog control |  | 1 (Setting range: 0 to 255) |  |  |  |  |  |
| External analog input |  | 1 input (Resolution: 1/256, Input range: 0 to 10 V ). Not isolated. |  |  |  |  |  |

## CPU Unit Specifications

## Terminal Block Arrangement

- CP1H-XA and X CPU Units with DC Power supply




## Built-in Input Area

- CP1H-XA and X CPU Units

| PLC Setup |  | Input operation |  |  | High-speed counter operation | Pulse output origin search function set to be used. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Normal inputs | Interrupt inputs | Quick-response inputs | High-speed counters | Origin search |
| Clo 0 | 00 | Normal input 0 | Interrupt input 0 | Quick-response input 0 |  | Pulse 0: Origin input signal |
|  | 01 | Normal input 1 | Interrupt input 1 | Quick-response input 1 | High-speed counter 2 (phase-Z/reset) | Pulse 0: Origin proximity input signal |
|  | 02 | Normal input 2 | Interrupt input 2 | Quick-response input 2 | High-speed counter 1 (phase-Z/reset) | Pulse output 1: Origin input signal |
|  | 03 | Normal input 3 | Interrupt input 3 | Quick-response input 3 | High-speed counter 0 (phase-Z/reset) | Pulse output 1: Origin proximity input signal |
|  | 04 | Normal input 4 |  |  | High-speed counter 2 (phase-A, increment, or count input) |  |
|  | 05 | Normal input 5 |  |  | High-speed counter 2 (phase-B, decrement, or direction input) |  |
|  | 06 | Normal input 6 |  |  | High-speed counter 1 (phase-A, increment, or count input) |  |
|  | 07 | Normal input 7 |  |  | High-speed counter 1 (phase-B, decrement, or direction input) |  |
|  | 08 | Normal input 8 |  |  | High-speed counter 0 (phase-A, increment, or count input) |  |
|  | 09 | Normal input 9 |  |  | High-speed counter 0 (phase-B, decrement, or direction input) |  |
|  | 10 | Normal input 10 |  |  | High-speed counter 3 (phase-A, increment, or count input) |  |
|  | 11 | Normal input 11 |  |  | High-speed counter 3 (phase-B, decrement, or direction input) |  |
| ClO 1 | 00 | Normal input 12 | Interrupt input 4 | Quick-response input 4 | High-speed counter 3 (phase-Z/reset) | Pulse output 2: Origin input signal |
|  | 01 | Normal input 13 | Interrupt input 5 | Quick-response input 5 |  | Pulse output 2 : Origin proximity input signal |
|  | 02 | Normal input 14 | Interrupt input 6 | Quick-response input 6 |  | Pulse output 3: Origin input signal |
|  | 03 | Normal input 15 | Interrupt input 7 | Quick-response input 7 |  | Pulse output 3: Origin proximity input signal |
|  | 04 | Normal input 16 |  |  |  |  |
|  | 05 | Normal input 17 |  |  |  |  |
|  | 06 | Normal input 18 |  |  |  |  |
|  | 07 | Normal input 19 |  |  |  |  |
|  | 08 | Normal input 20 |  |  |  |  |
|  | 09 | Normal input 21 |  |  |  |  |
|  | 10 | Normal input 22 |  |  |  |  |
|  | 11 | Normal input 23 |  |  |  |  |

## - Built-in Output Area

## - CP1H-XA and CP1H-X CPU Units



## CPU Unit Specifications

## Terminal Block Arrangemen

- CP1H-Y CPU Units


Note: Supply 24 VDC to the
Built-in Input Area
Lhedine

| PLC Setup |  | Input operation setting |  |  | High-speed counter operation setting | Pulse output origin search function set to be used. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Normal inputs | Interrupt inputs | Quick-response inputs | High-speed counters | Origin search |
| A0 |  |  |  |  | High-speed counter 0 (phase-A. increment, or count input) fixed |  |
| s0 |  |  |  |  | High-speed counter 0 (phase-B, decrement, or direction input) fixed |  |
| $z 0$ |  |  |  |  | High-speed counter 0 (phase-Z/resel) fixed | Pulse 0: Orioin input signal (ine diviver) |
| A1 |  |  |  |  | High-speed counter 1 (phase-A, increment, or count input) fixed |  |
| B1 |  |  |  |  | High-speed counter 1 (phase-B. decrement, or direction input) fixed |  |
| Z1 |  |  |  |  | High-speed counter 1 (phase-Z/resel) fixed | Puise 1: Origin input signal (line diviver) |
| C10 0 | Bit 00 | Normal input 0 | Interrupt 0 | Quick-esponse input 0 |  | Pulse 2: Origin proximity input signal |
|  | Bit 01 | Normal input 1 | Interrupt 1 | Quick-esponse input 1 | High-speed counter 2 (phase-Z/reset) |  |
|  | Bit 04 | Normal input 2 |  |  | High-speed counter 2 (phase-A, increment, or count input) |  |
|  | Bit 05 | Normal input 3 |  |  | High-speed counter 2 (phase-B, decrement, or direction input) |  |
|  | Bit 10 | Normal input 4 |  |  | High-speed counter 3 (phase-A, increment, or count input) |  |
|  | Bit 11 | Normal input 5 |  |  | High-speed counter 2 (phase-B, decrement, or direction input) | Pulse 3: Origin proximity input signal |
| C10 1 | Bit 00 | Normal input 6 | Interrupt 2 | Quick-esponse input 2 | High-speed counter 2 (phase-Z/reset) | Pulse 3: Origin input signal |
|  | Bit 01 | Normal input 7 | Interrupt 3 | Quick-response input 3 |  | Pulse 2: Origin input signal |
|  | Bit 02 | Normal input 8 | Interrupt 4 | Quick-esponse input 4 |  | Pulse 1: Origin input signal (open collector) |
|  | Bit 03 | Normal input 9 | Interrupt 5 | Quick-esponse input 5 |  | Pulse 0: Origin input signal (open collector) |
|  | Bit 04 | Normal input 10 |  |  |  | Pulse 1: Origin proximity input signal |
|  | Bit 05 | Normal input 11 |  |  |  | Pulse 0: Origin proximity input signal |

These areas are for line-driver inputs, so they can be used only for high-speed counters (1 MHz) and not for other purposes, such as normal inputs.


## CPU Unit Specifications

```
Input Terminal Block Arrangement (Top Block)
CP1L (60 Inputs)
**)
*)
DC Power Supop\s Models
```



```
*NC
CP1L (40 Inputs) - CP1L (20 Inputs)
*,
****|O0
```




```
- CP1L (30 inputs)
L4 L2N COM 01 03 05 05 07 07 09 11 年01 03 05 
```



```
.0. PC Powe Supply Models 
```

- CP1L (20 Inputs)


| $\Leftrightarrow$ | $\Theta$ | 00 | 02 | 04 | 06 | 08 | 10 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

${ }_{\text {Inputs }(\text { ClO }}^{2}$ o)


| Nc | © | 00 | 02 | 04 | 06 | 08 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

CP1L (14 Inputs)


|  | $\Theta$ | 00 | 02 | 04 | 06 | NC | NC |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |



- CP1L (10 Inputs)


| A\| | 官\| | 00 | 02 | 04 |
| :--- | :--- | :--- | :--- | :--- |


| DC Power Supply Models |  |  |
| :--- | :--- | :--- |
| 1 | com 01 | 03 |



CPU Unit Specifications

| $\begin{gathered} \text { Number of } \\ \text { inputs } \end{gathered}$ | Input terminal block Input operation |  |  |  |  | High-speed counter operation <br> Operation settings <br> - High-speed counters enabled <br> - Phase-Z signal reset |  | Origin search |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Word | Bit | Normal inputs | Interrupt inputs | Quick-response inputs |  |  | Origin searches enabled for pulse outputs 0 and 1 |  |  |
|  |  |  |  |  |  | Single-phase (increment pulse input) | Two-phase (differential phase x4, up/down, or pulse plus direction) | CPU Units with 20 to 60 points | CPU Units with 14 points | CPU Units with 10 points |
| 14 | CıO 0 | 00 | $\begin{aligned} & \text { Normal } \\ & \text { input } 0 \end{aligned}$ | --- | --- | High-speed counter 0 (increment) | High-speed counter 0 (phase-A, increment, or count input) | -- | --- | --- |
|  |  | 01 | $\begin{aligned} & \text { Normal } \\ & \text { input } 1 \end{aligned}$ | --- | --- | High-speed counter 1 (increment) | High-speed counter 0 (phase-B, decrement, or count input) | --- | --- | --- |
|  |  | 02 | $\begin{aligned} & \text { Normal } \\ & \text { input } 2 \end{aligned}$ | --- | --- | High-speed counter 2 (increment) | High-speed counter 1 (phase-A, increment or count input) | --- | $\begin{gathered} \text { Pulse } \\ \text { output 0: } \\ \text { Origin } \\ \text { proximity } \\ \text { input } \\ \text { signal } \end{gathered}$ | --- |
|  |  | 03 | Normal | --- | --- | High-speed counter 3 (incremen) | High-speed counter 1 (phase-B, decrement, or count input) | -- | Pulse output Origin proximity input signal | Pulse output o: orin proxinity input ingnal |
|  |  | 04 | $\begin{aligned} & \text { Normal } \\ & \text { inout } 4 \end{aligned}$ | Interrupt input 0 | Quick-response input 0 | Counter 0, phaseZ/reset input | High-speed counter 0 (phase-Z/reset) | --- | --- | --- |
|  |  | 05 | $\begin{aligned} & \text { Normal } \\ & \text { input } 5 \end{aligned}$ | Interrupt input 1 | Quick-response input 1 | Counter 1, phaseZ/reset inpu | High-speed counter 1 (phase-Z/reset) | --- | -- | Pulse output 0: Origin input signal- |
|  |  | 06 | Normal input 6 | Interrupt input 2 | Quick-response input 2 | Counter 2, phaseZ/reset input |  | Pulse output 0 Origin input signal |  | --- |
|  |  | 07 | Normal input 7 | Interrupt input 3 | Quick-response input 3 | Counter 3, phase- $Z$ /reset input Z/reset input |  | Pulse output 1: Origin input signal |  | --- |
| 20 |  | 08 | Normal input 8 | Interrupt input 4 | Quick-response input 4 | --- |  | --- | --- | --- |
|  |  | 09 | Normal input 9 | Interrupt input 5 | Quick-response input 5 | --- |  | --- | --- | --- |
|  |  | 10 | $\begin{aligned} & \text { Normal } \\ & \text { input } 10 \end{aligned}$ | --- | --- | --- |  |  | -- | --- |
|  |  | 11 | $\begin{gathered} \text { Normal } \\ \text { input } 11 \end{gathered}$ | -- | --- | -- |  | Pulse output 1: Origin proximity input signal | --- | -- |
| 30 | ClO 1 | 00 | Normal input 12 | --- | --- | --- |  | --- | --- | --- |
|  |  | to | to | to | to | to | to | to | to | to |
|  |  | 05 | Normal input 17 | --- | --- | --- | --- | --- | --- | --- |
| 40 |  | 06 | Normal input 18 | --- | --- | --- | --- | --- | --- | --- |
|  |  | to | to | to | to | to | to | to | to | to |
|  |  | 11 | Normal input 23 | --- | --- | --- | --- | -- | --- | --- |
| 60 | ClO 2 | 00 | Normal input 24 | --- | --- | --- | --- | --- | --- | --- |
|  |  | to | to | to | to | to | to | to | to | to |
|  |  | 11 | Normal input 35 | --. | -- | --. | --- | --. | --- | --. |

## CPU Unit Specifications

■ Output Terminal Block Arrangement (Bottom Block) - CP1L (60 Outputs)


DC Power Supply Modeds



- CP1L (40 Outputs)


an

| NC | 00 | 01 | 02 | 02 | 03 | 04 | 04 | 06 | 00 | 01 | 03 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 04 | 04 | 04 |  |  |  |  |  |  |  |  |  |



- CP1L (30 Outputs)

| AC Power Supply Models |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| + | 00 | 01 | 02 | 02 | 04 | 05 |


DC Power Supply Models

| NC | 00 | 01 | 02 | 04 | 05 | 07 | 00 | 02 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 0 |  |  |  |  |  |  |


| NC | com | com | com | 03 | com | 06 | com | 01 | 00 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

## - CP1L (20 Outputs)





- CP1L (14 Outputs)



- CP1L (10 Outputs)

|compombom 03
colo 100




## - Built-in Output Area

| Number ofoutputs | Output Terminal Block |  | When the <br> instructions to <br> the right are not <br> executed | When a pulse output instruction (SPED, ACC, PLS2, or ORG) is executed |  | When the origin search function is set to be used in the PLC Setup, and an origin search is executed by the ORG instruction |  | When the PWM instruction is executed |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Word | Bit | Normal output | Fixed duty ratio pulse output |  |  |  | Variable duty ratio |
|  |  |  |  | cw/ccw | Pulse plus direction | When the origin search function is used |  | PWM output |
|  |  |  |  |  |  | CPU Units with 14 to 60 points | CPU Units with 10 point |  |
| 10 | C10 100 | 00 | Normal output 0 | Pulse output 0 (CW) | Pulse output 0 (pulse) | --- | --- | --- |
|  |  | 01 | Normal output 1 | Pulse output ( (CCW) | Pulse output 0 (direction) | --- | --- | PWM output 0 |
|  |  | 02 | Normal output 2 | Pulse output 1 (CW) | Pulse output 1 (pulse) | --- | --- | --- |
|  |  | 03 | Normal output 3 | Pulse output 1 (CCW) | Pulse output 1 (direction) | --- | Origin search 0 (Error counter reset output) | PWM output 1 |
| 14 |  | 04 | Normal output 4 | --- | --- | Origin search 0 <br> (Error counter <br> reset output) | --- | --- |
|  |  | 05 | Normal output 5 | --- | --- | Origin search 1 (Error counter reset output) | --- | --- |
| 20 |  | 06 | Normal output 6 | --- | --- | --- | --- | --- |
|  |  | 07 | Normal output 7 | --- | --- | --- | --- | --- |
| 3040 | CIO 101 | 00 | Normal output 8 | --- | --- | --- | --- | --- |
|  |  | to | to | to | to | to | to | to |
|  |  | 03 | Normal output 11 | --- | --- | --- |  | --- |
|  |  | 04 | Normal output 12 | --- | --- | --- |  | --- |
|  |  | to | to | to | to | to | to | to |
|  |  | 07 | Normal output 15 | -- | -- | -- | --- | --- |
| 60 | C10 102 | 01 | Normal output 16 | --- | --- | --- | --- | --- |
|  |  | to | to | to | to | to | to | to |
|  |  | 07 | Normal output 23 | --- | --- | --- | -- | --- |

## Input Specifications

| ITEM | Specifications |  |  |
| :---: | :---: | :---: | :---: |
|  | High-speed counter inputs (phases A and B) | Interrupt inputs and quick-response inputs | Normal inputs |
| CP1L | ClO 0.00 to CIO 0.03 | CIO 0.04 to ClO 0.09 | $\begin{gathered} \mathrm{CIO} 0.10, \mathrm{CIO} 0.11, \\ \text { CIO } 1.00 \mathrm{ot}, \mathrm{CIO} 1.11, \text { and } \\ \mathrm{CIO} 2.00 \text { to } 2.11 \end{gathered}$ |
| CPIH-XAX CPU Units | ClO 0.04 to ClO 0.11 | $\begin{aligned} & \mathrm{CIO} 0.00 \text { to } \mathrm{CIO} 0.03 \text { and } \\ & \mathrm{CIO} 1.00 \text { to } \mathrm{ClO} 1.03 \end{aligned}$ | CIO 1.04 to ClO 1.11 |
| CP1H-Y CPU Units | Clo 0.04, Clo 0.05, Clo 0.10, Clo 0.11 | $\begin{gathered} \text { CIO } 0.00, \mathrm{CIO} 0.01 \text { and } \\ \mathrm{CIO} 1.00 \text { to } \mathrm{COO} 1.03 \\ \hline \end{gathered}$ | C10 1.04, C10 1.05 |
| Input voltage | 24 VDC +10\%/-15\% |  |  |
| Applicable sensors | 2 -wire sensors or 3 -wire sensors |  |  |
| Input impedance | $3.0 \mathrm{k} \Omega$ |  | $4.7 \mathrm{k} \Omega$ |
| Input current | 7.5 mA typical |  | 5 mAtypical |
| ON voltage | 17.0 VDC min. |  | 14.4 VDC min. |
| OFF voltage/current | 1 mA max . at 5.0 VDC |  |  |
| ON delay | 2.5 ¢ smax . | 50 нs max. | $1 \mathrm{~ms} \mathrm{max}$. |
| OFF delay | 2.5 ms max. | 50 нs max. | $1 \mathrm{~ms} \mathrm{max}$. |
| Circuit configuration |  |  |  |

- High-speed Counter Function Input Specifications

CP1LCPU Units (Input bits: CIO 0.00 to ClO 0.03$)$
CP1H-XAX CPU Units (Input bits: ClO 0.04 to
CP1H-Y CPU Units (Input bits: ClO $0.04, \mathrm{ClO} 0.05, \mathrm{ClO} 0.10, \mathrm{ClO} 0.11$ )


- Interrupt Input Counter Mode

CP1H-XAX CPU Units (Input bits: CIO 0.00 (to Colo 0.03 , CIO 1.00 to CIO 1.03 )


- High-speed Counter Inputs (Line-driver Inputs)

CP1H-Y CPU Units

| Item | Specifications |  |
| :---: | :---: | :---: |
| High-speed counter inputs | Phases A and B | Phase Z |
| Input voltage | RS-422A line-driver, AM26LS31 or equivalent Note: The power supply voltage on the line-driver must be $5 \mathrm{~V} \pm 5 \%$ max |  |
| Input type | Line-driver input |  |
| Input current | 10 mA typical | 13 mA typical |
| Circuit configuration |  |  |

## CPU Unit Specifications

| Item | Specifications |  |  |
| :---: | :---: | :---: | :---: |
| ONOFF delay | - Pulse plus direction input mode <br> - Increment mode <br> - Up/down input mode | - Differential phase input mode |  |

## - CPU Units with Relay Outputs <br> 

Note: Under the worst conditions, the service life of output contacts is as showr | Under the wo |
| :--- |
| on the lt. |

The service life of relays is as shown in the following diagram as a guide.
line



- CPU Units with Transistor Outputs (Sinking/Sourcing)


Note: 1. Do not apply a voltage or connect a load to an output terminal exceeding the maximum switching capacity.
2. Fuses cannot be replaced by the user.
3. Also do not exceed 0.9 A for the total for CIO 100.00 to CIO 100.03. (CIO 100.00 to ClO 100.03 is diferent common.) 3. Also do not exceed 0.9 A for the total for ClO 100.00 10 C 10 10.03. (CIo $100.0015{ }^{\circ} \mathrm{C}$


- Pulse outputs
CPIL CPU Units: Output bits CIO 100.00 to CIO 100.03

| Item | Specifications |
| :---: | :---: |
| Max. switching capacity | 30 mA at 4.75 to 26.4 VD |
| Min. switching capacity | 7 mA at 4.75 to 26.4 VDC |
| Max. output frequency | 100 kHz |
| Output waveform |  |

Note: 1. The above values assume a resistive load and do not consider the in Pedance of the cable connecting the load
The pulse widths during actual use may be smaller than the ones show
above due to pulse distortion caused by connecting cabbe impedance.
3. The OFF and ON refer to the output transistor. The output transistor is $O$ ON at evel "L".

- Pulse Outputs (Line-driver Outputs)

CPIH-Y CPU Units

| Item | Specifications |  |
| :--- | :--- | :--- |
| Pulse outputs | Line-driver outputs, Am26LS31 or equivalent |  |
| Max. output current | 20 mA |  |
| Max. output frequency | 1 MHz |  |
|  |  |  |
| Circuit contiguration |  |  |
|  |  |  |
|  |  |  |
|  |  |  |
|  |  |  |

- Pulse outputs

CP1L CPU Units: Output bits ClO100.01, C1O 100.03
CP1H-XAXXY CPU Units: Output bits C10101.00, CIO 101.01

| Item | Specifications |
| :--- | :--- | Max. switching capait | Max. output frequency | CP1H: $1 \mathrm{kHz}, \mathrm{CP1L}: 32.8 \mathrm{kHz}$ |
| :--- | :--- |
| PW |  | | PWM output precision | ON duty $+5 \%,-0 \%$ at output frequency of 1 kHz |
| :--- | :--- |



ON duty $=\frac{\text { ton }}{T} \times 100 \%$
Note: 1. The above values assume a resistive load and do not consider the in pedance of the cable concecting the load.
2. The pulse widths during actual use may be smaler than the ones show above due to pulse distortion caused by connecting cabbe impedance. at level "L"

Connect a load of 20 mA or less to the out
if a current of more than 20 mA is output.

Built-in Analog Input Switch (Factory Settings)
Built-in Analog I/O Terminal Block Arrangement

00000000
00000000

## CPU Unit Specifications

■Serial Communications Specifications (CP1W-C1F01/-CIF11)



| Transmission Distance |  | 100 m (distance between hub and node) |
| :---: | :---: | :---: |
| Item |  | FINS Communications Service Specifications |
| Number of nodes |  | 254 |
| Message length |  | 1016 bytes max. |
| Size of bufter |  | 8k |
| Communications Function |  | FINS Communications Service (UDP/IP, TCP/IP) |
| FINS/UDP method | Protocol used | UDPIP |
|  | Port number | 9600 (defaut) Can be changed. |
|  | Protection | No |
| FINS/TCP method | Protocol used | TCPIP |
|  | Number of connections | Up to 2 simultaneous connections and only one connection can be set to client |
|  | Port number | 9600 (defaut) Can be changed. |
|  | Protection | Yes (Specification of client IP addresses when unit is used as a server) |

Note: 1. CX-Programmer version 8.1 or higher (CX-One version 3.1 or higher) is required.
2. Use CX-Integrator version 2.33 or higher (CX-One version 3.1 or higher) when the system needs to be set the routing tables. However, CX-Integrator does
not support the other functions, using CPIW-CIF41, such as transterring the parameers and network structure.
3. To connect the CP1H/CP1L CPUs with the NS-series Programmable Terminals via Ethernet using CPIW-CIF 41 , make sure that the system version of NS

## LDC Option Board (CP1W-DAM01)

- Specifications

| Item | Function |
| :---: | :---: |
| Mounting port | CP1H/CP1L: Option board slot 1 <br> Note: The LCD Option Board cannot be used for the CP1L-L10. |
| Communications protocol | Peripheral bus (Turn ON DIP switch pin 4.) |
| Weight | 30 g max. |
| Number of display characters | 4 rows $\times 12$ characters: 48 characters max. |
| Display characters | $5 \times 7$ dots (alphanumeric, Japanese kana, and symbolss). Display switchable between Japanese katakana and English. |
| Backlight | Electroluminescence (EL): Normal: Lit green; Error: Flashing red |



## Expansion I/O Unit Specifications

■ CP1W-40EDR/40EDT/40EDT1/32ER/32ET/32ET1/20EDR1/20EDT/20EDT1/16ER/16ET/16ET1/8ED/8ER/8ET/8ET1 Expansion I/O Units


- DC Inputs (CP1W-40EDR/40EDT/40EDT1/20EDR1/20EDT/20EDT1/8ED)

| Item | Specifications |
| :---: | :---: |
| Input voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |
| Input impedance | 4.7 k ת |
| Input current | 5 mAtypical |
| ON voltage | 14.4 VDC min. |
| OFF voltage | 5.0 VDC max. |
| ON delay | 0 to $32 \mathrm{~ms} \mathrm{max}. \mathrm{(Default:} 8 \mathrm{~ms}$ ) (See note 1. ) |
| OFF delay | 0 to $32 \mathrm{~ms} \mathrm{max}. \mathrm{(Default:} 8 \mathrm{~ms}$ ) (See note 1. ) |
| Circuit contiguration |  |

- Relay Outputs (CP1W-40EDR/32ER/20EDR1/16ER/8ER)




## Expansion Unit Specifications

■CP1W-AD041/DA041/DA021/MAD11 Analog Units
Analog values that are input are converted to binary data and stored in the input area, or binary data is output as analog values.


| Item | Model | CP1W-AD041 |  |
| :---: | :---: | :---: | :---: |
|  |  | Input voltage | Input curr |
| Number of inputs |  | 4 |  |
| Input signal range |  | 0 to $5 \mathrm{~V}, 1$ to 5 V , 0 to $10 \mathrm{~V},-10$ to 10 V | 0 to 20 mA 4 to 20 mA |
| Max. rated input |  | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ |
| External input impedance |  | $1 \mathrm{M} \Omega$ min. | Approx. $250 \Omega$ |
| Resolution |  | 6000 |  |
| Overall accura- <br> cy | $25^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ of full scale | $\pm 0.4 \%$ of full scale |
|  | $\begin{aligned} & 0 \text { to } \\ & 55^{\circ} \mathrm{C} \end{aligned}$ | $\pm 0.6 \%$ of full scale | $\pm 0.8 \%$ of full scale |
| Conversion time |  | $2.0 \mathrm{~ms} / \mathrm{point}$ |  |
| $\begin{aligned} & \text { A/D conversion } \\ & \text { data } \end{aligned}$ |  | Binary data with resolution of 6,000 Full scale for -10 to 10 V : F448 to 0BB8 hex Full scale for other ranges: 0000 to 1770 hex |  |
| Averaging |  | Supported. |  |
| Open-circuit detection |  | Supported. |  |
| Insulation resistance |  | $20 \mathrm{M} \Omega$ min. (at 250 VDC , between isolated circuits) |  |
| Dielectric strength |  | 500 VAC for 1 min (between isolated circuits) |  |
| Isolation method |  | Photocoupler isolation (between analog inputs and secondary internal circuits). No isolation between input signals. |  |


| Item | Model | CP1W-DA041/DA021 |  |
| :---: | :---: | :---: | :---: |
|  |  | Input voltage | Input current |
| Number of outputs |  | DA041: 4, DA021: 2 |  |
| Output signal range |  | $\begin{array}{\|l\|l} 0 \text { oto } 5 \mathrm{~V}, 0 \text { to } 10 \mathrm{~V}, \\ \text { or }-10 \text { to } 10 \mathrm{~V} \end{array}$ | 0 to 20 mA or 4 to 20 mA |
| Allowable external output load resistance |  | $2 \mathrm{k} \Omega$ min. | $350 \Omega$ max. |
| External output impedance |  | $0.5 \Omega$ max. | --- |
| Resolution |  | 6000 |  |
| Overall accuracy | $25^{\circ} \mathrm{C}$ | $\pm 0.4 \%$ of full scale |  |
|  | $\begin{aligned} & 0 \text { to } \\ & 55^{\circ} \mathrm{C} \end{aligned}$ | $\pm 0.8 \%$ of full scale |  |
| Conversion time |  | $2.0 \mathrm{~ms} / \mathrm{point}$ |  |
| D/A conversion data |  | Binary data with resolution of 6,000 <br> Full scale for -10 to 10 V: F448 to OBB8 hex Full scale for other ranges: 0000 to 1770 hex |  |
| Insulation resistance |  | $20 \mathrm{M} \Omega$ min. (at 250 VDC between isolated circuits) |  |
| Dielectric strength |  | 500 VAC for 1 min between isolated circuits |  |
| Isolation method |  | Photocoupler isolation between analog inputs and secondary internal circuits. No isolation between analog input signals. |  |

■ Analog I/O Unit: CP1W-MAD11

| Item | Model |  | CP1W-MAD11 |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Voltage //0 | Current $1 / 0$ |
| Analog Section | Number of inputs |  | 2 inputs |  |
|  | Input signal range |  | 0 to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V}, 0$ to 10 V , or -10 to 10 V | 0 to $20 \mathrm{~mA}, 4$ to 20 mA |
|  | Max. rated input |  | $\pm 15 \mathrm{~V}$ | $\pm 30 \mathrm{~mA}$ |
|  | External input impedance |  | $1 \mathrm{M} \Omega$ min. | $250 \Omega$ |
|  | Resolution |  | 1/6000 (full scale) |  |
|  | Overall accuracy | $25^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ of full scale | $\pm 0.4 \%$ of full scale |
|  |  | 0 to $55^{\circ} \mathrm{C}$ | $\pm 0.6 \%$ of full scale | $\pm 0.8 \%$ of full scale |
|  | A/D conversion data |  | Binary data (hexadecimal, 4 digits) <br> -10 to 10 V: F448 to OBB8 hex <br> Full scale for other ranges: 0000 to 1770 hex |  |
| AnalogOutputSectionSceinote 1.) | Averaging |  | Supported (Set for each input using a DIP switch.) |  |
|  | Disconnection detection |  | Supported |  |
|  | Number of outputs |  |  |  |
|  | External output max. current |  | 1 to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to 10 V | 0 to $20 \mathrm{~mA}, 4$ to 20 mA |
|  |  |  | --- |  |
|  | Allowable external output load resistance |  | $1 \mathrm{k} \Omega$ min. | $600 \Omega$ max. |
|  | External input impedance |  | $0.5 \Omega$ max. | --- |
|  | Resolution |  | 1/6000 (full scale) |  |
|  | Overall accuracy | $25^{\circ} \mathrm{C}$ | $\pm 0.4 \%$ of full scale |  |
|  |  | 0 to $55^{\circ} \mathrm{C}$ | $\pm 0.8 \%$ of full scale |  |
|  | Data setting |  |  |  |
|  | D/A conversion data |  | Binary data (hexadecimal, 4 digits) <br> -10 to 10 V: F448 to OBB8 hex <br> Full scale for other ranges: 0000 to 1770 hex |  |
| Conversion time (See note 2.) Isolation method |  |  | $2 \mathrm{ms/point}$ ( 6 ms for all points) |  |
|  |  |  |  |  |  |

[^2]2. The conversion time is the total time for 2 analog inputs and 1 analog output.

Expansion Unit Specifications

## Temperature Sensor Units: CP1W-TS001/TS002/TS101/TS102

By mounting a Temperature Sensor Unit to the PLC, inputs can be obtained from thermocouples or platinum resistance thermometers, and tem perature measurements can be converted to binary data (4-digit hexadecimal) and stored in the input area of the CPU Unit.


## - Specifications

| Item Model | CP1W-TS001/002 | CP1W-TS101/102 |
| :---: | :---: | :---: |
| Number of inputs | 2 (TS001), 4 (TS002) | 2 (TS101), 4 (TS102) |
| Input types | K, J switchable (Note: Same for all inputs.) | Pt100, JPt100 switchable (Note: Same for all inputs.) |
| Indication accuracy | (The larger of the indicated value: $\pm 0.5 \%$ and $\pm 2^{\circ} \mathrm{C}$ (See note.)) $\pm 1$ digit max. digit max. | (The larger of the indicated value: $\pm 0.5 \%$ and $\pm 1^{\circ} \mathrm{C}$ ) $\pm 1$ digit max. |
| Conversion time | $250 \mathrm{~ms} / 2$ points (TS001, TS101); $250 \mathrm{~ms} / 4$ points (TS002, TS102) |  |
| Converted temperature data | Binary (4-digit hexadecima) |  |
| Isolation method | Photocoupler isolation between the temperature input signals. |  |

(The rotary switch can be used to make the following range and input type settings.)

| Input type | Range ${ }^{\circ} \mathrm{C}$ ) | Range ( $\left.{ }^{\circ} \mathrm{F}\right)$ |
| :---: | :---: | ---: |
| K | -200 to 1300 | -300 to 2300 |
|  | 0.0 to 500.0 | 0.0 to 900.0 |
| J | -100 to 850 | -100 to 1500 |
|  | 0.0 to 400.0 | 0.0 to 750.0 |

input Temperature Ranges for CP1W-TS101/102 (The rotary switch can be used to make the following range and input type settings.)

| Input type | Range ${ }^{\circ}$ C) | Range $\left({ }^{\circ} \mathrm{F}\right)$ |
| :---: | :---: | :---: |
| Pt100 | -200.0 t 650.0 | -300 to 1200.0 |
| JPt100 | -200.0 to 650.0 | -300 to 1200.0 |

CP1W-SRT21 CompoBus/S I/O Link Unit
The CompoBus/S I/O Link Unit functions as a slave for a CompoBus/S Master Unit (or an SRM1 CompoBus/S Master Control Unit) to form an I/O Link with 8 inputs and 8 outputs between the CompoBus/S //O Link Unit and the Master Unit,


| Item Model | CP1W-SRT21 |
| :---: | :---: |
| Master/Slave | CompoBus/S Slave |
| Number of /O Dits | 8 input bits, 8 output bits |
| Number of words occupied in CP1H/CP1L IO memory | 1 input word, 1 output word (Allocated in the same way as for other Expansion Units) |
| Node number setting | Set using the DIP switch (before the CPU Unit is turned ON.) |

SRM1 Series (or 8 Units for CQM1-SRM21-V1).

## Dimensions

■CPU Units
CP1H CPU Un
CP1H CPU Units (X/XA/Y Types)


> Weight:
> $740 \mathrm{~g} \mathrm{max}. \mathrm{supply):}$
> $740 \mathrm{gmax}$. . DC power supply):
> 590 g max


CP1L CPU Units with 40 I/O Points


CP1L CPU Units with 30 I/O Points


Dimensions

## CP1L CPU Units with 14 or 20 I/O Points



## CP1L CPU Units with 10 I/O Points



## Dimensions

■xpansion Units and Expansion I/O Units CP1W-20ED $\square$
CP1W-16ED
CP1W-AD041/CP1W-DA041/CP1W-DA021
CP1W-MAD11/CP1W-TS $\square \square \square$


■ CJ-series Special I/O Units and CPU Bus Units


■CJ Unit Adaptor
CP1W-EXT01


CP1H
Example: Two CJ-series Units (31-mm widths) Connected Using a CJ Unit Adapter


## A Wealth of Instructions

## Floating-point Decima

Instruction, and More
Just like the CS/CJ-series PLCs, the CP1H and CP1L have
-
Example: PID Instructions with Autotuning
Autotuning of PID constants is enabled using the PID CONTROL . The ilimit cycle method is used for tuning, so tuning is completed in a short time.


## - Sequence Input Instructions

| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| LOAD | LD | -- |
| LOAD NOT | LD NOT | --- |
| AND | AND | -- |
| AND NOT | AND NOT | -- |
| OR | OR | --- |
| OR NOT | OR NOT | --- |
| AND LOAD | AND LD | --- |
| OR LOAD | ORLD | --- |
| NOT | NOT | 520 |
| CONDITION ON | UP | 521 |
| CONDITION OFF | Down | 522 |
| LOAD BIT TEST | LD TST | 350 |
| LOAD BIT TEST NOT | LD TSTN | 351 |
| AND BIT TEST | AND TST | 350 |
| AND BIT TEST NOT | $\begin{array}{\|l\|l\|} \hline \text { AND } \\ \text { TSTN } \end{array}$ | 351 |
| OR BIT TEST | OR TST | 350 |
| OR BIT TEST NOT | OR TSTN | 351 |

- Sequence Output Instructions

| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| code |  |  |$|$| OUTPUT | OUT |
| :--- | :--- |

- Sequence Control Instructions

| Instruction |  | Mnemonic | Function |
| :---: | :---: | :---: | :---: |
| END |  | END | 001 |
| NO OPERATION |  | NOP | 000 |
| INTERLOCK |  | 14 | 002 |
| INTERLOCK CLEAR |  | ILC | 003 |
| MULTI-INTERLOCK DIFFERENTIATION HOLD |  | MLLH | 517 |
| MULTI-INTERLOCKDIFFERENTIATIONRELEASE |  | MLLR | 518 |
| MULT-INTERLOCKCLEAR |  | MLLC | 519 |
| JUMP |  | JMP | 004 |
| JUMP END |  | JME | 005 |
| CONDITIONAL JUMP |  | CJP | 510 |
| CONDITIONAL JUMP NOT |  | CJPN | 511 |
| MULTIPLE JUMP |  | JMP | 515 |
| MULTIPLE JUMP END |  | JME0 | 516 |
| FOR LOOP |  | FOR | 512 |
| BREAK LOOP |  | BREAK | 514 |
| NEXT LOOPS |  | NEXT | 513 |
| - Timer and Counter Instructions |  |  |  |
| Instruction |  | Mnemonic | $\begin{aligned} & \text { Function } \\ & \text { code } \end{aligned}$ |
| TIMER | BCD | тIM | -- |
|  | BIN | timX | 550 |
| COUNTER | BCD | CNT |  |
|  | BIN | CNTX | 546 |
| $\begin{aligned} & \text { HIGH-SPEED } \\ & \text { TIMER } \end{aligned}$ | BCD | TIMH | 015 |
|  | BIN | tIMHX | 551 |
| $\begin{array}{\|l\|} \hline \text { ONE-MS } \\ \text { TIMER } \end{array}$ | BCD | тМНН | 540 |
|  | BIN | тМННХ | 552 |
| $\begin{array}{\|l} \hline \text { ACCUMULA- } \\ \text { TIVE TIMER } \\ \hline \end{array}$ | BCD | тדוM | 087 |
|  | BIN | TTIMX | 555 |
| LONG TIMER | BCD | TIML | 542 |
|  | BIN | TIMLX | 553 |
| MULTI-OUT-PUT TIMER | BCD | мтім | 543 |
|  | BIN | mTIMX | 554 |
| $\begin{aligned} & \text { REVERSIBLE } \\ & \text { COUNTER } \end{aligned}$ | BCD | CNTR | 012 |
|  | BIN | CNTRX | 548 |
| RESET TIMER/ COUNTER | BCD | CNR | 545 |
|  | BIN | CNRX | 547 |

## Data Comparison Instruction

## Instructions

| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| MOVE | MOV | 021 |
| DOUBLE MOVE | MOVL | 498 |
| MOVE NOT | MVN | 022 |
| DOUBLE MOVE NOT | MVNL | 499 |
| MOVE BIT | MOVB | 082 |
| MOVE DIGIT | MOVD | 083 |
| MULTIPLE BIT TRANSFER | XFRB | 062 |
| BLOCK TRANSFER | XFER | 070 |
| BLOCK SET | BSET | 071 |
| DATA EXCHANGE | XCHG | 073 |
| DOUBLE DATA EXCHANGE | XCGL | 562 |
| SINGLE WORD DISTRIBUTE | DIST | 080 |
| DATA COLLECT | COLL | 081 |
| MOVE TO REGISTER | MOVR | 560 |
| MOVE <br> TIMER/COUNTER PV TO REGISTER | MOVRW | 561 |

- Data Shift Instructions

| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| SHIFT REGISTER | SFT | 010 |
| REVERSIBLE SHIFT REGISTER | SFTR | 084 |
| ASYNCHRONOUS SHIFT REGISTER | ASFT | 017 |
| WORD SHIFT | WSFT | 016 |
| ARITHMETIC SHIFT LEFT | ASL | 025 |
| DOUBLE SHIFT LEFT | ASLL | 570 |
| ARITHMETIC SHIFT RIGHT | ASR | 026 |
| DOUBLE SHIFT RIGHT | ASRL | 571 |
| ROTATE LEFT | ROL | 027 |
| DOUBLE ROTATE LEFT | ROLL | 572 |
| ROTATE LEFT WITHOUT CARRY | RLNC | 574 |
| DOUBLE ROTATE LEFT WITHOUT CARRY | RLNL | 576 |
| ROTATE RIGHT | ROR | 028 |
| DOUBLE ROTATE <br> RIGHT | RORL | 573 |
| ROTATE RIGHT WITHOUT CARRY | RRNC | 575 |
| DOUBLE ROTATE RIGHT WITHOUT CARRY | RRNL | 577 |
| ONE DIGIT SHIFT LEFT | SLD | 074 |
| ONE DIGIT SHIFT RIGHT | SRD | 075 |
| SHIFT N-BIT DATA LEFT | NSFL | 578 |
| SHIFT N-BIT DATA RIGHT | NSFR | 579 |
| SHIFT N-BITS LEFT | NASL | 580 |
| DOUBLE SHIFT NBITS LEFT | NSLL | 582 |
| SHIFT N-BITS RIGHT | NASR | 581 |
| DOUBLE SHIFT NBITS RIGHT | NSRL | 583 |


| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| INCREMENT BINARY | ++ | 590 |
| DOUBLE <br> INCREMENT BINARY | + + | 591 |
| DECREMENT BINARY | -- | 592 |
| DOUBLE DECREMENT BINARY | --L | 593 |
| INCREMENT BCD | + + B | 594 |
| DOUBLE INCREMENT BCD | + +BL | 595 |
| DECREMENT BCD | --B | 596 |
| DOUBLE <br> DECREMENT BCD | --BL | 597 |

- Symbol Math Instructions

| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| SIGNED BINARY ADD WITHOUT CARRY | + | 400 |
| DOUBLE SIGNED BINARY ADD WITHOUT CARRY | +L | 401 |
| SIGNED BINARY | +C | 402 |
| DOUBLE SIGNED BINARY ADD WITH CARRY | +CL | 403 |
| BCD ADD WITHOUT CARRY | +B | 404 |
| DOUBLE BCD ADD WITHOUT CARRY | +BL | 405 |
| BCD ADD WITH CARPY CARRY | +BC | 406 |
| DOUBLE BCD ADD WITH CARRY | +BCL | 407 |
| SIGNED BINARY SUBTRACT WITHOUT CARRY | - | 410 |
| DOUBLE SIGNED BINARY SUBTRACT WITHOUT CARRY | -L | 411 |
| SIGNED BINARY SUBTRACT WITH CARRY | -c | 412 |
| DOUBLE SIGNED BINARY WITH CARRY | -CL | 413 |
| BCD SUBTRACT WITHOUT CARRY | -B | 414 |
| DOUBLE BCD SUBTRACT WITHOUT CARRY | -BL | 415 |
| BCD SUBTRACT WITH CARRY | -BC | 416 |
| DOUBLE BCD SUBTRACT WITH CARRY | -BCL | 417 |
| SIGNED BINARY MULTIPLY | * | 420 |
| DOUBLE SIGNED BINARY MULTIPLY | * | 421 |
| UNSIGNED BINARY MULTIPLY | * | 422 |
| DOUBLE UNSIGNED BINARY MULTIPLY | *UL | 423 |
| BCD MULTIPLY | *B | 424 |
| DOUBLE BCD MULTIPLY | *BL | 425 |
| SIGNED BINARY | ' | 430 |


| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| code |  |  |$|$

- Data Conversion Instructions

| Instruction | Mnemonic | Function |
| :---: | :---: | :---: |
| BCD-TO-BINARY | BIN | 023 |
| DOUBLE BCD-TODOUBLE BINARY | BINL | 058 |
| BINARY-TO-BCD | BCD | 024 |
| DOUBLE BINARY-TODOUBLE BCD | BCDL | 059 |
| 2'S COMPLEMENT | NEG | 160 |
| DOUBLE 2'S COMPLEMENT | NEGL | 161 |
| 16-BIT TO 32-BIT SIGNED BINARY | SIGN | 600 |
| DATA DECODER | MLPX | 076 |
| DATA ENCODER | DMPX | 077 |
| ASCII CONVERT | ASC | 086 |
| ASCII TO HEX | HEX | 162 |
| COLUMN TO LINE | LINE | 063 |
| LINE TO COLUMN | COLM | 064 |
| SIGNED BCD-TOBINARY | BINS | 470 |
| DOUBLE SIGNED BCD-TO-BINARY | BISL | 472 |
| SIGNED BINARY-TOBCD | BCDS | 471 |
| DOUBLE SIGNED BINARY-TO-BCD | BDSL | 473 |
| GRAY CODE CONVERSION | GRY | 474 |

- Special Math Instructions

| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| code |  |  |
| BINARY ROOT | ROTB | 620 |
| BCD SQUARE ROOT | ROOT | 072 |
| ARITHMTII | APR | 069 |
| PROCESS | ARS |  |
| FLLATTING POINT | FDIV | 079 |
| DIVIDE |  |  |
| BIT COUNTER | BCNT | 067 |

## - Logic Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| LOGICAL AND | ANDW | 034 |
| DOUBLE LOGICAL | ANDL | 610 |
| AND |  |  |
| LOGICAL OR | ORW | 035 |
| DOUBLE LOGICAL | ORWL | 611 |
| OR | EXCLSIVE OR | XORW |
| EXLULE | 036 |  |
| DOUBLE EXCLUSIVE | XORL | 612 |
| OR |  |  |
| EXCLUSIVE NOR | XNRW | 037 |
| DOUBLE EXCLUSIVE <br> NOR | XNRL | 613 |
| COMPLEMENT | COM | 029 |
| DOUBLE <br> COMPLEMENT | COML | 614 |


| - Floating-point Math Instructions |
| :--- |
| Instruction Mnemonic Function <br> code   |
| FLOATING TO 16-BIT |
| FIX | 450

- Double-precision Floating-point

| Instruction | Mnemonic | $\begin{aligned} & \text { Function } \\ & \text { code } \end{aligned}$ |
| :---: | :---: | :---: |
| DOUBLE FLOATING <br> TO 16-BIT BINARY | FIXD | 841 |
| DOUBLE FLOATING TO 32-BIT BINARY | FIXLD | 842 |
| 16-BIT BINARY TO | DBL | 843 |
| 32-BIT BINARY TO | DBLL | 844 |
| DOUBLE FLOATINGPOINT ADD | +D | 845 |
| DOUBLE FLOATING- POINT SUBTRACT | -D | 846 |
| DOUBLE FLOATING- POINT MUTIPIY | * ${ }^{\text {d }}$ | 847 |
| DOUBLE FLOATING- POINT DIVIDE | ID | 848 |
| DOUBLE DEGREES | RADD | 849 |
| DOUBLE RADIANS TO DEGREES | DEGD | 850 |
| DOUBLE SIIE | SIND | 851 |
| DOUBLE COSIINE | COSD | 852 |
| DOUBLE TANGENT | TAND | 853 |
| DOUBLE ARC SIINE | ASIND | 854 |
| DOUBLE ARC | ACOSD | 855 |


| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| DOUBLE ARC TANGENT | ATAND | 856 |
| DOUBLE SQUARE ROOT | SQRTD | 857 |
| DOUBLE EXPONENT | EXPD | 858 |
| DOUBLE LOGARITHM | LOGD | 859 |
| DOUBLE EXPONENTIAL POWER | PWRD | 860 |
| double symbol COMPARISON | $\begin{aligned} & \mid \mathrm{LD,AND}, \\ & \mathrm{OR} \\ & +\quad \\ & =\mathrm{D},<>\mathrm{D}, \\ & <\mathrm{D},<=\mathrm{D}, \\ & >\mathrm{D},>=\mathrm{D} \end{aligned}$ | $\begin{aligned} & 335(=\mathrm{D}) \\ & 336(<>\mathrm{D}) \\ & 337<(<\mathrm{D}) \\ & 338 \\ & \mathrm{D}) \\ & 339(>\mathrm{D}) \\ & 340 \\ & \mathrm{D}) \end{aligned}$ |

- Table Data Processing Instructions

| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| code |  |  |$|$| Ond |
| :--- | :--- |

- Data Control Instructions

| Instruction | Mnemonic | Function |
| :---: | :---: | :---: |
| PID CONTROL | PID | 190 |
| PID CONTROL WITH AUTO TUNING | PIDAT | 191 |
| LIMIT CONTROL | LMT | 680 |
| DEAD BAND CONTROL | BAND | 681 |
| DEAD ZONE CONTROL | ZONE | 682 |
| TIMEPROPORTIONAL OUTPUT | TPO | 685 |
| SCALING | SCL | 194 |
| SCALING 2 | SCL2 | 486 |
| SCALING 3 | SCL3 | 487 |
| AVERAGE | AVG | 195 |

- Subroutine Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| SUBROUTINE CALL | SBS | 091 |
| SUBROUTINE ENTRY | SBN | 092 |
| SUBOUTINE | RI |  | |  |  |  |
| :--- | :--- | :--- |
| SUBOUTIN CALL | SBS | 091 |
| SUBROUTINE ENTRY | SBN | 092 | | SUBROUTINE | RET | 09 |
| :--- | :--- | :--- | :--- |
| RETURN | 093 |  | REACRO


| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| GLOBAL |  |  |
| SUBROTINE CALL | GSBN | 751 |
| GLOBAL |  |  |
| SUBROTINE ENTRY | GRET | 752 |
| GLOBAL <br> SUBROUTINE <br> RETURN | GSBS | 750 |

- Interrupt Control Instructions

| Instruction | Mnemonic | $\begin{array}{\|c\|} \hline \begin{array}{c} \text { Function } \\ \text { code } \end{array} \\ \hline \end{array}$ |
| :---: | :---: | :---: |
| SET INTERRUPT MASK | MSKS | 690 |
| READ INTERRUPT MASK | MSKR | 692 |
| CLEAR INTERRUPT | CLI | 691 |
| DISABLE INTERRUPTS | D | 693 |
| ENABLE INTERRUPTS | EI | 694 |

- High-speed Counter and Pulse

Output Instructions

| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| MODE CONTROL | INI | 880 |
| HIGH-SPEED COUNTER PV READ | PRV | 881 |
| COUNTER FREQUENCY CONVERT | PRV2 | 883 |
| COMPARISONTABLE LOAD | CTBL | 882 |
| SPEED OUTPUT | SPED | 885 |
| SET PULSES | PULS | 886 |
| PULSE OUTPUT | PLS2 | 887 |
| ACCELERATION CONTROL | ACC | 888 |
| ORIGIN SEARCH | ORG | 889 |
| PULSE WITH VARIABLE DUTY FACTOR | PWM | 891 |

## - Step Instructions

Step Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| STEP DEFINE | STEP | 008 |
| STEP START | SNXT | 009 |

## - Basic I/O Unit Instructions

| Instruction | Mnemonic | Function code |
| :---: | :---: | :---: |
| IO REFRESH | IORF | 097 |
| 7-SEGMENT DECODER | SDEC | 078 |
| DIGITAL SWITCH INPUT | DSW | 210 |
| TEN KEY INPUT | TKY | 211 |
| HEXADECIMAL KEY INPUT | HKY | 212 |
| MATRIX INPUT | MTR | 213 |
| 7-SEGMENT DISPLAY OUTPUT | 7SEG | 214 |
| $\begin{aligned} & \text { INTELLIGENT I/O } \\ & \text { READ } \end{aligned}$ | IORD | 222 |
| INTELLIGENT I/O WRITE | IOWR | 223 |
| CPU BUS I/O REFRESH | DLNK | 226 |

## Instructions



- Network Instructions
\(\begin{array}{l}- Network Instructions <br>

\)|  Instruction  |  Mnemonic  |  Function  |
| :--- | :--- | :--- |
|  code  |  |  | <br>

\hline NETWORK SEND\end{array} $\left.\begin{array}{l}\text { SEND }\end{array}\right) 090$

- Display Instructions

| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| code |  |  |$|$| DISPLAY MESSAGE | MSG |
| :--- | :--- |
| 7-SEGMENT LED <br> WORD DATA <br> DISPLAY | SCH |
| 7-SEGMENT LED <br> CONTROL | SCTRL |


| Instruction | Mnemonic | Function |
| :---: | :---: | :---: |
| CALENDAR ADD | CADD | 730 |
| CALENDAR SUBTRACT | CSUB | 731 |
| HOURS TO SECONDS | SEC | 065 |
| SECONDS TO HOURS | HMS | 066 |
| CLOCK ADJUSTMENT | DATE | 735 |

- Debugging Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| TRAAE MEMORY <br> SAMPLING | TRSM | 045 |

## Failure Diagnosis Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| FAlLURE ALARM | FAL | 006 |
| SEVERE FAILURE | FALS | 007 |
| ALRM | 0 |  |
| FALURE POINT | FPD | 269 |
| DETECTION |  |  |

\(\begin{array}{l}- Other Instructions <br>

\)|  Instruction  |  Mnemonic  |  Function  |
| :--- | :--- | :--- |
|  code  |  |  | <br>

\hline SET CARRY\end{array} STC $) 040$

- Block Programming Instructions

| Instruction | Mnemonic | Function |
| :--- | :--- | :--- |
| code |  |  |$|$| BLOCK PROGRAM | BPRG |
| :--- | :--- |
| BEGIN |  | 096


| LOOP | LOOP | 809 |
| :--- | :--- | :--- |
| Block Programming Instructions |  |  |

- Block Programming Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| LEND | CONDITI <br> ON LEND | 810 |
| ONND | LEND Bit <br> Operand | 810 |
| LEND NOT | LEND <br> LET Bit <br> OPerand | 810 |


| Instruction | Mnemonic | $\begin{aligned} & \text { Function } \\ & \text { code } \end{aligned}$ |
| :---: | :---: | :---: |
| MOV STRING | MOV\$ | 664 |
| CONCATENATE | +\$ | 656 |
| GET STRING LEFT | LEFTS | 652 |
| GET STRING RIGHT | RGHTS | 653 |
| GET STRING MIDDLE | MID\$ | 654 |
| FIND IN STRING | FIND\$ | 660 |
| STRING LENGTH | LENS | 650 |
| REPLACE IN STRING | RPLC\$ | 661 |
| DELETE STRING | DELS | 658 |
| EXCHANGE STRING | XCHG\$ | 665 |
| CLEAR STRING | CLR\$ | 666 |
| INSERT INTO STRING | INS\$ | 657 |
| String Comparison | $\begin{aligned} & \text { LD, AND, } \\ & \text { OR+ } \\ & =\$, \\ & <\$, \\ & <\$ \$ \\ & <=\$ \\ & <=\$, \\ & >\$, \\ & >=\$ \end{aligned}$ |  |

- Task Control Instructions

- Model Conversion Instructions
- Model Conversion Instructions

| Instruction | Mnemonic | Function <br> code |
| :--- | :--- | :--- |
| BLOCK TRANSFER | XFERC | 565 |
| SIIGLE WORD | DISTC | 566 |
| DISTRIBUTE | DATA COLECTT | COLLC |
| MOVE BIT | MOVBC | 567 |
| BIT COUNTER | BCNTC | 621 |

$\begin{array}{llll} & \text { BPClial Instructions for Function }\end{array}$ Blocks

| Instruction | Mnemonic | cunction <br> code |
| :--- | :--- | :--- |
| VARIABLE ID | GETID | 286 |

## Ordering Information

■ CPU Units . .....  56

- Options for CPU Units .....  57
- Programming Devices .....  58
- Expansion Units .....  59
- I/O Connecting Cable .....  59
- Optional Products, Maintenance Products and DIN Track Accessories .....  59
■CJ-series Special I/O Units and CPU Bus Units. .....  60


## Standards and Directives

- International Standards
- The standards are abbreviated as follows: U: UL, U1:

UL (Class I Division 2 Products for Hazardous
Locations), C: CSA, UC: cULus, UC1: CULus (Class 1 Locations), C: CSAA, UC: cULLus, UC1: CULus (Class
Division 2 Products for Hzardous
Locations), CU: cUL, $\mathrm{N}: \mathrm{NK}$, L : Looyd, and CE: EC Directives. - Contact your OMRON representative for further
details and applicable conditions for these standards.

- EC Directives

The EC Directives applicable to PLCs include the EMC Directives and the Low Voltage Directive. OMRON
complies with these directives as described below.

- EMC Directives

EMC Directives
Applicable Standard
Applicabie Standard
EMI: EN61000-6-4
EMS:
EMS: EN61131-2 and EN61000-6-2 (See note.) LCS are electrical devices that are incorIntallations. OMRON PLLs contorm to
ne related EMC standards so that the de the related EMC standards so that the de-
vices and machines into which they are built can more easily conform to EMC
standards. The actual PLCs have been standards. The actual PLCS have been
checked to ensure conformity to EMC checked to ensure conformity to EMC
standards. Whether these standards are satisfied for the actual system, how
must be checked by the customer EMC-related performance will vary depending on the configuration, wiring, and
other conditions of the equipment or conother conalitions of the equipment or con-
trol panel in which the PLC is instaled. trol panel in which the PLC is instaled.
The customer must, therefore, perform fil nal checks to confirm that the overall ma-
chine or device conforms to EMC chine or
standards.
Note: The applicable EMS standards
depend on the product.

- Low Voltage Directive
Applicable Standard: EN61131-2

Devices that operate at voltages from 50
to 1,000 VAC or 75 to 150 VDC must sat-
r 75 to 150 VDC must sal
With PLCS, this applies to Power Supply Units and I/O Units that operate in these
Voltage ranges. form to EN6 $1131-2$, which is the applica
ble standard for PLCs.

## Ordering Information

| CPU Unit | Specifications |  |  |  |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CPU type | $\begin{aligned} & \text { Power } \\ & \text { supply } \\ & \hline \end{aligned}$ | Output method | Inputs | Outputs |  |  |
|  | Memory capacity: 20K steps High-speed counters: $100 \mathrm{kHz}, 4$ axes Pulse outputs: $100 \mathrm{kHz}, 4$ axes (Models with transistor outputs only) | $\begin{gathered} \text { AC power } \\ \text { supply } \end{gathered}$ | Relay output | 24 | 16 | CP1H-X40DR-A | $\begin{aligned} & \mathrm{UC}, \mathrm{~N}, \mathrm{~N}, \\ & \mathrm{~L}, \mathrm{CE}, \end{aligned}$ |
|  |  | DC powersupply | Transistor output (sinking) |  |  | CP1H-X40DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1H-X40DT1-D |  |
| CP1H-XA CPU Units | Memory capacity: 20K steps High-speed counters: $100 \mathrm{kHz}, 4$ axes <br> Pulse outputs: 100 kHz, 4 axes (Models with transistor outputs only) <br> Analog inputs: 4 <br> Analog outputs: 2 | AC power supply | Relay output | 24 | 16 | CP1H-XA40DR-A |  |
|  |  | $\begin{array}{\|l\|l\|} \text { DC power } \\ \text { supply } \end{array}$ | Transistor output (sinking) |  |  | CP1H-XA40DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1H-XA40DT1-D |  |
|  | Memory capacity: 20K steps High-speed counters: <br> $1 \mathrm{MHz}, 2$ axes <br> 100 kHz , 2 axes <br> Pulse outputs: $1 \mathrm{MHz}, 2$ axes <br> 100 kHz, 2 axes | DC power supply | Transistor output (sinking) | $\begin{gathered} 12 \\ + \\ \text { line-driver } \\ \text { input, } \\ 2 \text { axes } \end{gathered}$ | 8 <br> + <br> line-driver <br> output, <br> 2 axes | CP1H-Y20DT-D |  |

Note: 1. CPIH PLCs are supported by CX-Programmer version 6.2 or higher.
2. Purchase a separately sold Option Unit if you will use RS-232C, RS-422A485, Ethernet, or LCD.

| CPU Unit | Specifications |  |  |  |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CPU type | Power supply | Output method | Inputs | Outputs |  |  |
| CP1L-M CPU Units with 60Points | Memory capacity: 10 K steps High-speed counters: $100 \mathrm{kHz}, 4$ axes Pulse outputs: 100 kHz , 2 axes (Models with transistor outputs only) | $\begin{gathered} \text { AC power } \\ \text { supply } \end{gathered}$ | Relay output | 36 | 24 | CP1L-M60DR-A | $\begin{aligned} & \mathrm{UC} 1, \mathrm{~N}, \\ & \mathrm{~L}, \mathrm{CE}, \end{aligned}$ |
|  |  |  | Transistor output (sinking) |  |  | CP1L-M60DT-A |  |
|  |  | $\begin{gathered} \text { DC power } \\ \text { supply } \end{gathered}$ | Relay output |  |  | CP1L-M60DR-D |  |
|  |  |  | Transistor output (sinking) |  |  | CP1L-M60DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1L-M60DT1-D |  |
| CP1L-M CPU Units with 40 Points | Memory capacity: 10K steps <br> High-speed counters: <br> 100 kHz, 4 axes <br> Pulse outputs: 100 kHz, 2 axes (Models with transistor outputs only) | $\begin{aligned} & \text { AC power } \\ & \text { supply } \end{aligned}$ | Relay output | 24 | 16 | CP1L-M40DR-A | $\begin{aligned} & \text { UC1, } \mathrm{N}, \\ & \mathrm{~L}, \mathrm{CE}, \end{aligned}$ |
|  |  |  | Transistor output (sinking) |  |  | CPIL-M40DT-A |  |
|  |  | $\begin{gathered} \text { DC power } \\ \text { supply } \end{gathered}$ | Relay output |  |  | CP1L-M40DR-D |  |
|  |  |  | Transistor output (sinking) |  |  | CPIL-M40DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1L-M400T1-D |  |
| CP1L-M CPU Units with 30Points | Memory capacity: 10K steps High-speed counters: <br> $100 \mathrm{kHz}, 4$ axes <br> Pulse outputs: 100 kHz, 2 axes (Models with transistor outputs only) | $\begin{array}{\|l} \hline \text { AC power } \\ \text { supply } \end{array}$ | Relay output | 18 | 12 | CP1L-M30DR-A | $\begin{aligned} & \text { UC1, N, }, \\ & \mathrm{L}, \mathrm{CE}, \end{aligned}$ |
|  |  |  | Transistor output (sinking) |  |  | CP1L-M30DT-A |  |
|  |  | $\begin{aligned} & \text { DC power } \\ & \text { supply } \end{aligned}$ | Relay output |  |  | CP1L-M30DR-D |  |
|  |  |  | Transistor output (sinking) |  |  | CP1L-M30DT-D |  |
|  |  |  | Transistor output sourcing) |  |  | CP1L-M30DT1-D |  |
| CP1L-L CPU Units with 20Points | Memory capacity: 5K steps High-speed counters: $100 \mathrm{kHz}, 4$ axes Pulse outputs: $\mathbf{1 0 0} \mathbf{~ k H z}$, 2 axes (Models with transistor outputs only) | $\begin{aligned} & \text { AC power } \\ & \text { supply } \end{aligned}$ | Relay output | 12 | 8 | CP1L-L20DR-A | $\begin{aligned} & \text { UC1,N, }, \\ & \mathrm{L}, \mathrm{CE}, \end{aligned}$ |
|  |  |  | Transistor output <br> (sinking) |  |  | CP1L-L20DT-A |  |
|  |  | $\begin{aligned} & \text { DC power } \\ & \text { supply } \end{aligned}$ | Relay output |  |  | CP1L-L20DR-D |  |
|  |  |  | Transistor output (sinking) |  |  | CP1L-L20DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1L-L20DT1-D |  |

Ordering Information

| CPU Unit | Specifications |  |  |  |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | CPU type | Power supply | Output method | Inputs | Outputs |  |  |
| CP1L-L CPU Units with 14Points | Memory capacity: 5 K steps High-speed counters: $100 \mathrm{kHz}, 4$ axes Pulse outputs: $100 \mathrm{kHz}, 2$ axes (Models with transistor outputs only) | $\begin{aligned} & \text { AC power } \\ & \text { supply } \end{aligned}$ | Relay output | 8 | 6 | CP1L-L14DR-A | $\begin{aligned} & \mathrm{UC1,N,} \\ & \mathrm{~L}, \mathrm{CE}, \end{aligned}$ |
|  |  |  | Transistor output (sinking) |  |  | CP1L-L14DT-A |  |
|  |  | $\begin{array}{\|l\|l\|} \hline \text { DC power } \\ \text { supply } \end{array}$ | Relay output |  |  | CP1L-L14DR-D |  |
|  |  |  | Transistor output (sinking) |  |  | CP1L-L14DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1L-L14DT1-D |  |
| CP1L-L CPU Units with 10 Point | Memory capacity: 5K steps High-speed counters: $100 \mathrm{kHz}, 4$ axes Pulse outputs: $\mathbf{1 0 0} \mathbf{k H z}$, 2 axes (Models with transistor outputs only) | AC powersupply | Relay output | 6 | 4 | CP1L-L10DR-A | $\begin{aligned} & \mathrm{UC1,N,N,} \\ & \mathrm{~L}, \mathrm{CE} \end{aligned}$ |
|  |  |  | Transistor output (sinking) |  |  | CP1L-L100t-A |  |
|  |  | $\begin{gathered} \text { DC power pupply } \\ \text { supe } \end{gathered}$ | Relay output |  |  | CP1L-L10DR-D |  |
|  |  |  | Transistor output (sinking) |  |  | CPIL-L10DT-D |  |
|  |  |  | Transistor output (sourcing) |  |  | CP1L-L10DT1-D |  |


2. Purchase an Option Unit (sold separataty) if you will use RS-232C, RS-422AA 485 , Ethemet, or LCD.
$\square$ Options for CPU Units

| Name |  | Specifications | Model | Standards |
| :---: | :---: | :---: | :---: | :---: |
| RS-232C Option Board |  | Can be mounted in either CPU Unit Option Board slot 1 or 2. Note: Cannot be used for the CP1L-L10. | CP1W-CIF01 | $\begin{aligned} & \mathrm{UC1,N,} \begin{array}{l} \mathrm{L}, \mathrm{CE} \end{array}, ~ \end{aligned}$ |
| RS-422A/485 Option Board |  |  | CP1W-CIF11 |  |
| RS-422A/485 (Isolated-type) Option Board |  |  | CP1W-CIF12 | $\begin{aligned} & \mathrm{uc}, \mathrm{~N}, \mathrm{~N}, \\ & \mathrm{~L}, \mathrm{CE} \end{aligned}$ |
| Ethernet Option Board |  | Can be mounted in either CPU Unit Option Board slot 1 or 2. <br> Note: 1. Cannot be used for the CP1L-L10. <br> 2. When using CP1W-CIF41 Ver. 1.0, one Ethernet port can be added | CP1W-CIF41 | $\begin{aligned} & \text { UC1, N, } \\ & \text { L, CE } \end{aligned}$ |
| LCD Option Board |  | Can be mounted only in the CPU Unit Option Board slot 1 . Note: Cannot be used for the CP1L-L10. | CP1W-DAMO1 | $\begin{aligned} & u C 1, L, L, \\ & N, C E \end{aligned}$ |
| Memory Cassette |  | Can be used for backing up programs or auto-booting. | CP1W-ME05M | UC1, N, L, CE |

## Ordering Information

## Programming Devices

| Name | Specifications |  |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Number of licenses | Media |  |  |
| FA Integrated Tool Package CX-One Lite Version 4. | CX-One Lite is a subset of the complete CX-One package that provides only the Support Software required for micro PLC applications. CX-One Lite runs on the following OS OS: Windows XP (Service Pack 3 or higher), Vista or 7 Note: Except for Windows XP 64-bit version. CX-One Lite Ver. 4. $\square$ includes Micro PLC Edition CXProgrammer Ver. 9. C . | 1 license | CD | CXONE-LT01C-v4 | --- |
| FA Integrated Tool Package CX-One Ver. 4. | CX-One is a package that integrates the Support Software for OMRON PLCs and components. CX-One runs on the following OS. <br> OS: Windows XP (Service Pack 3 or higher), Vista or 7 Note: Except for Windows XP 64-bit version. <br> CX-One Ver. $4 . \square$ includes CX-Programmer Ver. 9.■. | $\begin{array}{\|l\|} 1 \text { license } \\ \text { (See note 3.) } \end{array}$ | DVD (See note 4.) | CXONE-ALO1D-V4 | -- |
| $\begin{aligned} & \text { Programming Device } \\ & \text { Connecting Cable for } \\ & \text { CP1W-CIFO1 RS-232C } \\ & \text { Option Board } \\ & \text { (See note 5.) } \end{aligned}$ | Connects DOS computers, D-Sub 9-pin (Length: 2.0 m ) | For anti-static connectors |  | xW2Z-200S-cv | -- |
|  | Connects DOS computers, D-Sub 9-pin (Length: 5.0 m ) |  |  | xW2Z-500S-cv |  |
|  | Connects DOS computers, D-Sub 9-pin (Length: 2.0 m ) |  |  | xW2Z-200s-v |  |
|  | Connects DOS computers, D-Sub 9-pin (Length: 5.0 m ) |  |  | xW2z-500S-v |  |
| USB-Serial Conversion Cable (See note 5.) | USB-RS-232C Conversion Cable (Length: 0.5 m ) and PC driver (on a CD-ROM disc) are included. <br> Complies with USB Specification 1.1 <br> On personal computer side: USB (A plug connector, male) <br> On PLC side: RS-232C (D-sub 9-pin, male) <br> Driver: Supported by Windows 98 , Me, 2000, and XP |  |  | CS1w-CIF31 | N |

Note: 1. CP1H PLCS are supported by CX-Programmer version 6.2 or higher.
CP1LPLCS are supported by CX-Programmer version 7.2 or ingher, except for 10 -point and 60 -point CPU Units.
The 10 -point and 60 -point CPU Units are supported by CX-Programmer version 7.3 or higher.
Update The CX-Programmer version automatically from the website using CX-Programmer version 7.0 (included with CX-One version 2.0).
Update The CX-Programmer version automatically from the website using CX-Programme
2. The CX-One and CX-One Lite cannot be simultaneously installed on
3. Mult licenses are available for the CX-One ( $3,10,30$ or 50 licenses).
4. The CX-One is also available on $C D$ (CXON
5. Cannot be used with a peripheral USB port.
5. Cannot be used with a peripheral USB port.
To connect to a personal computer via a peripheral USB port, use commercially-available USB cable (A or B type, male).

| Support Software in CX-One |  | Cx-One Lite Ver.4. | $\begin{aligned} & \text { Cx-One } \\ & \text { Ver.4. } \end{aligned}$ | Support Software in CX-One |  | CX-One Lite Ver.4. $\square$ | $\begin{aligned} & \text { Cx-One } \\ & \text { Ver.4. } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Micro PLC Edition CX-Programmer | Ver.9.] | Yes | No | CX-Drive | Ver.2. | Yes | Yes |
| CX-Programmer | Ver.9.] | No | Yes | CX-Process Tool | Ver.5.] | No | Yes |
| CX-Integrator | Ver.2.] | Yes | Yes | Faceplate Auto-Builder for NS | ver.3. $\square$ | No | Yes |
| Switch Box Utility | Ver.1.] | Yes | Yes | CX-Designer | Ver.3. $\square$ | Yes | Yes |
| CX-Protocol | Ver.1.] | No | Yes | NV-Designer | Ver. $1 . \square$ | Yes | Yes |
| Cx-Simulator | Ver.1.] | Yes | Yes | CX-Thermo | Ver.4. | Yes | Yes |
| CX-Position | Ver.2.] | No | Yes | CX-ConfiguratorFDT | Ver. $1 . \square$ | Yes | Yes |
| CX-Motion-NCF | Ver.1.] | No | Yes | CX-FLnet | Ver. $1 . \square$ | No | Yes |
| CX-Motion-MCH | Ver.2.] | No | Yes | Network Configurator | Ver.3. $\square$ | Yes | Yes |
| CX-Motion | Ver.2.] | No | Yes | CX-Server | Ver.4.] | Yes | Yes |

Ordering Information

| Name | Output method | Inputs | Outputs | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Expansion I/O Units | Relay | 24 | 16 | CP1W-40EDR | N, L, CE |
|  | Transistor (sinking) |  |  | CP1W-40EDT |  |
|  | Transistor (sourcing) |  |  | CP1W-40EDT1 |  |
|  | Relay | --- | 32 | CP1W-32ER | N, L, CE |
|  | Transistor (sinking) |  |  | CP1W-32ET |  |
|  | Transistor (sourcing) |  |  | CP1W-32ET1 |  |
|  | Relay | 12 | 8 | CP1W-20EDR1 | U, C, N, L, CE |
|  | Transistor (sinking) |  |  | CP1W-20EDT |  |
|  | Transistor (sourcing) |  |  | CP1W-20EDT1 |  |
|  | Relay | --- | 16 | CP1W-16ER | N, L, CE |
|  | Transistor (sinking) |  |  | CP1W-16ET |  |
|  | Transistor (sourcing) |  |  | CP1W-16ET1 |  |
|  | --- | 8 | --- | CP1W-8ED | U, C, N, L, CE |
|  | Relay | --- | 8 | CP1W-8ER |  |
|  | Transistor (sinking) |  | 8 | CP1W-8ET |  |
|  | Transistor (sourcing) |  |  | CP1W-8ET1 |  |
| Analog Input Unit | Analog (resolution: 1/6000) | 4 | --- | CP1W-AD041 | UC1, N, L, CE |
| Analog Output Unit | Analog (resolution: 1/6000) | -- | 4 | CP1W-DA041 |  |
|  |  |  | 2 | $\text { CP1W-DA02 } \frac{\text { NEW }}{1}$ | UC1, CE |
| Analog I/O Unit | Analog (resolution: 1/6000) | 2 | 1 | CP1W-MAD11 | U, C, N, L, CE |
| CompoBus/S I/O Link Unit | --- | $\begin{gathered} 8 \\ \text { (//O link input bits) } \end{gathered}$ | $\begin{gathered} 8 \\ \text { (//O link input bits) } \end{gathered}$ | CP1W-SRT21 | U, C, N, L, CE |
| Temperature SensorUnit | 2 thermocouple inputs |  |  | CP1W-TS001 |  |
|  | 4 thermocouple inputs |  |  | CP1W-TS002 |  |
|  | 2 platinum resistance thermometer inputs |  |  | CP1W-TS101 |  |
|  | 4 platinum resistance thermometer inputs |  |  | CP1W-TS102 |  |

CP1L (L Type) CPU Units with 10 points do not support Expansion Units.
■I/O Connecting Cable

| Name | Specifications | Model | Standards |
| :--- | :--- | :--- | :--- |
| IO Connecting Cable | 80 cm (for CP1W/CPM1A Expansion Units) | CP1W-CN811 | UC1, N, L, CE |

Note: An I/O Connecting Cable (approx. 6 cm ) for horizontal connection is provided with CP1W/CPM1A Expansion Units.
■Optional Products, Maintenance Products and DIN Track Accessories

| Name | Specifications | Model | Standards |
| :---: | :---: | :---: | :---: |
| Battery Set | For CP1H CPU Units <br> (Use batteries within two years of manufacture.) | CJIW-batoi | --- |
| DIN Track | Length: 0.5 m ; Height: 7.3 mm | PFP-50N |  |
|  | Length: 1 m ; Height: 7.3 mm | PFP-100N |  |
|  | Length: 1 m ; Height: 16 mm | PFP-100N2 |  |
| End Plate | There are 2 stoppers provided with CPU Units and I/O Interface Units as standard accessories to secure the Units on the DIN Track. | PFP-M |  |

## Ordering Information

■CJ-series Special I/O Units and CPU Bus Units

| Category | Name | Specifications | Model | Standards |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{array}{\|l\|} \hline \text { CP1H CPU } \\ \text { Unit options } \\ \hline \end{array}$ | CJ Unit Adapter | Adapter for connecting CJ-series Special I/O Units and CPU Bus Units (includes CJ -series End Cover) | CP1W-EXT01 | $\begin{aligned} & \mathrm{UC} 1, \mathrm{~N}, \mathrm{~L}, \\ & \mathrm{CE} \end{aligned}$ |
| CJ1 Special I/O Units | Analog Input Units | 4 inputs ( 1 to $5 \mathrm{~V}(1 / 10,000), 0$ to $10 \mathrm{~V}(1 / 20,000),-5$ to $5 \mathrm{~V}(1 / 20,000)$, -10 to $10 \mathrm{~V}(1 / 40,000)$, and 4 to $20 \mathrm{~mA}(1 / 10,000)$ ) <br> Conversion Period: $20 \mu \mathrm{~s} / 1$ point, $25 \mu \mathrm{~s} / 2$ points, $30 \mu \mathrm{~s} / 3$ points, $35 \mu \mathrm{~s} / 4$ points | CJIW-AD042 | UC1, CE |
|  |  | 8 inputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: 1/8,000, Conversion speed: $250 \mu$ s/input max. (Can be set to $1 / 4,000$ resolution and $1 \mathrm{~ms} / \mathrm{m}_{\text {input.) }}$ | CJ1W-AD081-V1 | UC1, N, L, <br> CE |
|  |  | 4 inputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: 18,000, Conversion speed: $250 \mu \mathrm{~S}$ /input max. (Can be set to $1 / 4,000$ resolution and $1 \mathrm{~ms} / \mathrm{m}_{\text {input.) }}$ | CJIW-AD041-V1 |  |
|  | Analog Output Units | 4 outputs ( 1 to $5 \mathrm{~V}(1 / 10,000), 0$ to $10 \mathrm{~V}(1 / 20,000)$, and -10 to $10 \mathrm{~V}(1 / 40,000)$ Conversion Period: $20 \mu \mathrm{~s} / 1$ point, $25 \mu \mathrm{~s} / 2$ points, $30 \mu \mathrm{~s} / 3$ points, $35 \mu \mathrm{~s} / 4$ points | CJiW-DA042V | UC1, CE |
|  |  | 8 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to 10 V ) Resolution: 1/4,000; Conversion speed: $1 \mathrm{~ms} /$ output max (Can be set to $1 / 8000,250 \mu \mathrm{~s} /$ output.) | CJIW-DA08V | $\begin{aligned} & \mathrm{UC} 1, \mathrm{~N}, \mathrm{~L}, \\ & \mathrm{CE} \end{aligned}$ |
|  |  | 8 outputs ( 4 to 20 mA ) <br> Resolution: 1/4,000; Conversion speed: $1 \mathrm{~ms} / 0 u t p u t$ max. <br> (Can be set to $18,000,250 \mu \mathrm{~s} /$ output.) | CJIW-DA08C | UC1, N, CE |
|  |  | 4 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: $1 / 4,000$, Conversion speed: $1 \mathrm{~ms} /$ point max. | CJIW-DA041 | $\operatorname{ucE}_{\mathrm{CE}, \mathrm{~N}, \mathrm{~L},}$ |
|  |  | 2 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: 1/4,000, Conversion speed: $1 \mathrm{~ms} /$ point max. | CJ1w-DA021 |  |
|  | Analog I/O Unit | 4 inputs, 2 outputs ( 1 to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V},-10$ to $10 \mathrm{~V}, 4$ to 20 mA ) Resolution: 1/4000; Conversion speed: $1 \mathrm{~ms} /$ point max (Can be set to $1 / 8,000,500 \mu \mathrm{~s} / \mathrm{point}$.) | CJ1W-MAD42 |  |
|  | Process Input Units | 4 fully universal inputs: Pt100 (3-wire), JPt100 (3-wire), Pt1000 (3-wire), Pt100 (4 wire), K, J, T, E, L, U, N, R, S, B, WRe5-26, PLII, 4 to 20 mA , 0 to $20 \mathrm{~mA}, 1$ to $5 \mathrm{~V}, 0$ to $1.25 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to $10 \mathrm{~V}, \pm 100-\mathrm{mV}$ selectable range, -1.25 to $1.25 \mathrm{~V},-5$ to $5 \mathrm{~V},-10$ to $10 \mathrm{~V}, \pm 10-\mathrm{V}$ selectable range Potentiometer resolution/conversion speed: 1/256,000 (conversion cycle: $60 \mathrm{~ms} / 4$ points), $1 / 64,000$ (conversion cycle: $10 \mathrm{~ms} / 4$ points), 1/16,000 (conversion cycle: $5 \mathrm{~ms} / 4$ points) | CJ1W-PH41U (See note 1.) | UC1, CE |
|  |  | 4 fully universal inputs: Pt100, JPt100, Pt1000, K, J, T, L, R, S, B, 4 to $20 \mathrm{~mA}, 0$ to $20 \mathrm{~mA}, 1$ to $5 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 0$ to 10 V Conversion speed: $250 \mathrm{~ms} / 4$ points | CJIW-AD04U | UC1, L, CE |
|  |  | 4 inputs, B, J, K, L, R, S, T; Conversion speed: $250 \mathrm{~ms} / 4$ inputs | CJ1W-PTS51 | UC1, CE |
|  |  | 4 inputs, Pt100 $\Omega$ (JIS, IEC), JPt100 $\Omega$, Conversion speed: $250 \mathrm{~ms} / 4$ inputs | CJIW-PTS52 |  |
|  |  | 2 inputs, B, E, J, K, L, N, R, S, T, U, W, Re5-26, PL $\pm 100 \mathrm{mV}$, Resolution: 1/64,000; Conversion speed: $10 \mathrm{~ms} / 2$ inputs | CJ1W-PTS15 |  |
|  |  | 2 inputs, Pt100, JPt100, Pt50, Ni508.4; <br> Resolution: $1 / 64,000$; Conversion speed: $10 \mathrm{~ms} / 2$ inputs | CJ1W-PTS16 |  |
|  |  | 2 inputs, 0 to $1.25 \mathrm{~V},-1.25$ to $1.25 \mathrm{~V}, 0$ to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V},-5$ to $5 \mathrm{~V}, 0$ to 10 V , -10 to $10 \mathrm{~V}, \pm 10-\mathrm{V}$ selectable range, 0 to $20 \mathrm{~mA}, 4$ to 20 mA | CJ1W-PDC15 |  |
|  | Temperature ControlUnits | 4 loops, thermocouple input, NPN output | CJIW-TC001 | $\operatorname{uct}_{\mathrm{CE}} \mathrm{C}, \mathrm{~N}, \mathrm{~L},$ |
|  |  | 4 loops, thermocouple input, PNP output | CJ1W-TC002 |  |
|  |  | 2 loops, thermocouple input, NPN output, heater burnout detection function | CJ1W-TC003 |  |
|  |  | 2 loops, thermocouple input, PNP output, heater burnout detection function | CJIW-TC004 |  |
|  |  | 4 loops, platinum resistance thermometer input, NPN output | CJ1W-TC101 |  |
|  |  | 4 loops, platinum resistance thermometer input, PNP output | CJ1W-TC102 |  |
|  |  | 2 loops, platinum resistance thermometer input, NPN output, heater burnout detection function | CJ1W-TC103 |  |
|  |  | 2 loops, platinum resistance thermometer input, PNP output, heater burnout detection detection function | CJIW-TC104 |  |
|  | $\underset{\substack{\text { High-speed Counter } \\ \text { Unit }}}{ }$ | 2 inputs, max. input frequency: 500 kpps | CJ1W-CT021 | $\begin{aligned} & \mathrm{UC} 1, \mathrm{~N}, \mathrm{~L}, \\ & \mathrm{CE} \end{aligned}$ |
|  | Position Control Units | Pulse train, open collector output, 1 axis | CJIW-NC113 | UC1, CE |
|  |  | Pulse train, open collector output, 2 axes | CJ1W-NC213 |  |
|  |  | Pulse train, open collector output, 4 axes | CJIW-NC413 |  |
|  |  | Pulse train, line driver output, 1 axis | CJ1W-NC133 |  |
|  |  | Pulse train, line driver output, 2 axes | CJ1W-NC233 |  |
|  |  | Pulse train, line driver output, 4 axes | CJIW-NC433 |  |
|  | Space Unit | --- | CJ1W-SP001 |  |
|  | ID Sensor Units | For V680 Series, 1 RW Head | CJ1W-V680C11 | Uc, CE |
|  |  | For V680 Series, 2 RW Heads | CJ1W-V680C12 |  |
|  |  | For V600 Series, 1 RW Head | CJ1W-V600C11 |  |
|  |  | For V600 Series, 2 RW Heads | CJ1W-V600C12 |  |
|  | CompoNet Master Unit | Word slaves: 2,048 points, Bit slaves: 512 points | CJ1W-CRM21 | $\begin{aligned} & \mathrm{U}, \mathrm{U} 1, \mathrm{~N}, \mathrm{~L}, \\ & \mathrm{CE} \end{aligned}$ |
|  | CompoBus/S Master Unit | CompoBus/S remote I/O, 256 points max. | CJ1W-SRM21 | $\begin{aligned} & \mathrm{UC} 1, \mathrm{~N}, \mathrm{~L}, \\ & \mathrm{CE} \end{aligned}$ |

Note: 1. If a CJ1W-PH41U is used, do not use a CP1H CPU Unit with relay contact outputs or Expansion Units with relay contact outputs.
2. Refer to the CJ1 catalog (Cat. No. P052) for information on the CJ1 Special IO Units.

Ordering Information

| Category | Name | Specifications |  | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CJ1 CPUBus Units Bus Units | Controller Link Units | Wired (shielded twisted-pair cable) |  | CJ1W-CLK23 | $\begin{aligned} & \hline \text { UC1, N, L, } \\ & \text { CE } \end{aligned}$ |
|  | Serial Communications Units | 1 RS-232C port and 1 RS-422A485 port |  | CJ1W-SCU42 | UC1, N, CE |
|  |  | 2 RS -232C ports |  | CJ1W-SCU22 |  |
|  |  | 2 RS-422AA485 ports |  | CJ1W-SCU32 |  |
|  |  | 1 RS-232C port and 1 RS-422A/485 port |  | CJ1W-SCU41-V1 | $\mathrm{UCE}_{\mathrm{CE}}^{\mathrm{UE}, \mathrm{~N}, \mathrm{~L},}$ |
|  |  | 2 RS -232C ports |  | CJ1W-SCU21-V1 |  |
|  |  | 2 RS-422A/485 ports |  | CJ1W-SCU31-V1 |  |
|  | EtherNetIP Unit | Shielded twisted-pair cable (STP), category 5 or 5 e or higher Tag data links and message communications supported |  | CJ1W-EIP21 |  |
|  | Ethernet Unit | 100Base-TX |  | CJ1W-ETN21 |  |
|  | DeviceNet Unit | Functions as master and/or slave; allows control of 32,000 points max. per master |  | CJ1W-DRM21 |  |
|  | MECHATROLINK-II Position Control Unit | Control commands sent using MECHATROLINK-II synchronized communications 6 axes max., direct operation from ladder diagram, control modes: position/ speed/torque | 2 axes | CJ1W-NC271 | UC1, CE |
|  |  |  | 4 axes | CJ1W-NC471 |  |
|  |  |  | 16 axes | CJ1W-NCF71 |  |
|  |  |  | 16 axes | CJIW-NCF71-MA |  |
|  | MECHATROLINK-II Motion Control Unit | Position, speed, and torque commands sent via MECHATROLINK-II <br> Special motion control language | 32 axes max. <br> (Real axes: 20, Virtual axes: 2) | CJ1w-mCH71 |  |
|  | F-net Unit | 100Base-TX |  | CJ1W-FLN22 |  |
|  | SYSMAC SPU | High-speed data collection unit |  | CJ1W-SPU01-V2 |  |

## - Industrial Switching Hubs

| Product name | Appearance | Specifications |  |  | Accesories | $\begin{gathered} \text { Current } \\ \text { consumption (A) } \end{gathered}$ | Model | Standards |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Functions | No. of pors | Failure detection |  |  |  |  |
| Industrial Switching Hubs | 部 | Quality of Service (QOS): <br> EtherNet/IP control data priority Failure detection: <br> Broadcast storm and LSI error detection 10/100BASE-TX Auto-Negotiation | 3 | No | - Power supply connector | 0.22 | W4S1-03B | Uc, CE |
|  | \% |  | 5 | No |  | 0.22 | W4S1-05B |  |
|  |  |  | 5 | Yes | - Power supply connector <br> - Connector for <br> informing error | 0.22 | W4S1-05C | CE |

## OMRON Function Block Library

OMn using the CP1H use the CP1H OMRON Function Block for positioning
When using the CP1L, use the CP1M-CPU21/22/23 OMRON Function Block for positioning.


OMRON Function Block Library
OMRON Function Block Library for E5CN and E5CN-U-series Temperature Controller Serial Communications

| FB name | Function name | ptio |
| :---: | :---: | :---: |
| E5xx003_St | Stop | Stops operation for Temperature Controller channel. |
| E5xN004_ExecuteAT | Execute AT | Starts AT for Temperature Controller channel. |
| E5xN005_Cancelat | Cancel AT | Cancels AT for Temperature Controller channel. |
| E5xx200_ReadVariable | Read variable | Reads one item from specified variable area. |
| E5xx201_ReadStatus | Read status | Reads status of specified Temperature Controller channel. |
| -E5xx202_ReadPV | Read PV | Reads PV of specified Temperature Controller channel. |
| E5xx203_ReadSP | Read SP | Reads SP f specified Temperature Controller channel. |
| -E5xx204_ReadCoolingMV | Read cooling MV | Reads cooling MV of specified Temperature Controler channel. |
| -55xx205_ReadHeatingMV | Read heating MV | Reads heating MV of specified Temperature Controller channel. |
| E5xx400_WriteVariable | Write variable | Writes one data item to specified variable area. |
| -E5xx403_WriteSP | Write SP | Sets SP for specified Temperature Controller channel. |
| E55x600_SetComm | Set communications | Sets PLC serial port to default communications settings of Temperature Controller. |

Note: These OMRON Function Block can be used for only serial port 2 (the eort on the right) for CP1H and CP1L-M30-M40-M60 CPU Units
They can be used for serial port 1 only on CPILL-L114-1/20 CPI Units (which have only one serial port)
OMRON Function Block Library for E5AR and E5ER-series Temperature Controller Serial Communications

| FB name | Function name | Description |
| :---: | :---: | :---: |
| E5xx003_Stop | Stop | Stops operation for Temperature Controller channels. |
| -E5xN004_ExecuteAT | Execute AT | Starts AT for Temperature Controller channels. |
| E5xN005_Cancelat | Cancel AT | Cancels AT for Temperature Controller channels. |
| E5xx200_ReadVariable | Read variable | Reads one item in specified variable area. |
| EE5xx201_ReadStatus | Read status | Reads status of specified Temperature Controller channel. |
| E5xx202_ReadPV | Read PV | Reads PV of specified Temperature Controller channel. |
| E5xx203_ReadSP | Read SP | Reads SP of specified Temperature Controller channel. |
| -E5xx204_ReadCoolingMV | Read cooling MV | Reads cooling MV of specified Temperature Controller channel. |
| -E5xx205_ReadHeatingMV | Read heating MV | Reads heating MV of specified Temperature Controller channel. |
| E5xxR206_ReadValveOpening | Read valve opening | Reads valve opening monitor value of specified Temperature Controller channel. |
| E5xx400_WriteVariable | Write variable | Writes one data item to specified variable area. |
| -E5xx403_WriteSP | Write SP | Sets SP for specified Temperature Controller channel. |
| E5x $\times 600$ SetComm | Set communications | Sets PLC serial port to initial communications settings of Temperature Controller. |

Note: These OMRON Function Block can be used for only serial port 2 (hhe port on the right) for CP1H and CP1L-M30/-M40/-M60 CPU Units.
They can beed for serial port 1 only on CP1L-L14/-L20 CPU Units (which have only one serial port).
Cannot be used for the CP1L-L10.

- OMRON Function Block Library for E5ZN-series Temperature Controller Serial

Communications

| FB name | Function name | Description |
| :---: | :---: | :---: |
| E5xx001_ExeOperation | Execute command | Executes specified command. |
| -E5xx002_Run | Run | Starts operation for specified Temperature Controller channel. |
| -E5xx003_Stop | Stop | Stops operation for specitied Temperature Controller channel. |
| -E5xN004_ExecuteAT | Execute AT | Starts AT for Temperature Controller channels. |
| -E5xN005_Cancelat | Cancel AT | Cancels AT for Temperature Controller channels. |
| E5xx200_ReadVariab | Read variab | Reads one item in spec |
| EE5xx201_ReadStatus | Read status | Reads status of specified Temperature Controller channel. |
| -E5xx202_ReadPV | Read PV | Reads PV of specified Temperature Controller channel. |
| EE5xx203_ReadSP | Read SP | Reads SP of specified Temperature Controller channel. |
| E5xx204_ReadCoolingMV | Read cooling MV | Reads cooling MV of specified Temperature Controler channel. |
| EE5xx20_ReadHeatingMV | Read heating MV | Reads heating MV of specified Temperature Controller channel. |
| E5xx400_WriteVariable | Write variable | Writes one data item to specified variable area. |
| -E5xx403_WriteSP | Write SP | Sets SP for speciified Temperature Controller channel. |
| E5xx600_SetComm | Set communications | Sets PLC serial port to default communications settings of Temperature Controlle |

Note: These OMRON Function Block can be used for only serial port 2 (the port on the right) for CP1H and CP1L-M30-M40-M60 CPU Units.
hey can be used for serial port 1 only on CP1L-L14-L20 CPU Units (which have only one serial port)
Cannot be used for the CP1L-L10.

## SMARTSTEP 2 AC Servo Drivers with Pulse String Inputs R88M-G/R7D-BP

## Advanced Functionality and Performance Packed into a

 Super-compact Body- Compact AC Servo Drives

Compared to the SNA
Suppressing Vibration of Low-rigidity Mechanisms during Acceleration/Deceleration
The damping control function can suppress vibration of low-rigidity mechanisms or devices whose ends tend to vibrate,

- Easy Adjustment

The realtime autotuning function automatically estimates the load inertia of the machine in realtime and sets the optimal gain.
The adaptive filter automatically suppresses vibration caused by resonance.

- Compatible with Command Pulse of $90^{\circ}$ Phase Difference Inputs

In addition to conventional CW/CCW inputs (2 pulse inputs) and SIGN/PULS inputs ( 1 pulse input), the SMARTSTEP 2 supports $90^{\circ}$ phase difference inputs. This makes it possible to input encoder output signals directly into the Servo Drive for simplified synchronization control.
A Wide Range of Pulse Setting Functions
A wide range of pulse setting functions, such as the command pulse multiplying, electronic gear, and encoder dividing, enable you to perform pulse settings suitable for your device or system.

- Simplified Speed Control with Internal Speed Settings

Four internal speed settings allow the speed to be easily switched by using external signals.


The number of motor encoder pulses output by the Servo Drive can be freely set in
the range of 1 to 2,500 pulses per rotation. A parameter can also be set to change the phase.

## Servo Drive-Servomotor Combinations

- Combinations of Cylinder-type 3,000-r/min Servomotors and Servo Drivers

| Voltage | Servo Driver | Servomotor |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Pulse-string input | Rated output | Without brake | With brake |
| Single-phase 100-V | R7D-BPA5L | 50 W | R88M-G05030H | R88M-G05030H-B |
|  | R7D-BP01L | 100 W | R88M-G10030L | R88M-G10030L-B |
|  | R7D-BP02L | 200 W | R88M-G20030L | R88M-G20030L-B |
| Single-phase 200-V | R7D-BP01H | 50 W | R88M-G05030H | R88M-G05030H-B |
|  |  | 100 W | R88M-G10030H | R88M-G10030H-B |
|  | R7D-BP02HH | 200 W | R88M-G20030H | R88M-G20030H-B |
|  | R7D-BP-04H | 400 W | R88M-G40030H | R88M-G40030H-B |
| Three-phase 200-V | R7D-BP01H | 50 W | R88M-G05030H | R88M-G05030H-B |
|  |  | 100 w | R88M-G10030H | R88M-G10030H-B |
|  | R7D-BPO2H | 200 W | R88M-G20030H | R88M-G20030H-B |
|  | R7D-BP04H | 400 W | R88M-G40030H | R88M-G40030H-B |

- Combinations of Flat-type $3,000-\mathrm{r} / \mathrm{min}$ Servomotors and Servo Drivers

| Voltage | Servo Driver | Servomotor |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Pulse-string input | Rated output | Without brake | With brake |
| Single-phase 100-v | R7D-BP01L | 100 W | R88M-G10030L | R88M-G10030L-B |
|  | R7D-BP02L | 200 W | R88M-G20030L | R88M-G20030L-B |
| Single-phase 200-V | R7D-BP01H | 100 W | R88M-G10030H | R88M-G10030H-B |
|  | R7D-BP02HH | 200 W | R88M-G20030H | R88M-G20030H-B |
|  | R7D-BP-04H | 400 W | R88M-G40030H | R88M-G40030H-B |
| Three-phase 200-V | R7D-BP01H | 100 W | R88M-G10030H | R88M-G10030H-B |
|  | R7D-BPO2H | 200 W | R88M-G20030H | R88M-G20030H-B |
|  | R7D-BP04H | 400 W | R88M-G40030H | R88M-G40030H-B |

Note: For information on SMARTSTEP 2, refer to the SMARTSTEP 2 Catalog (Cat. No. 1813).

## Read and Understand this Catalog

lease read and understand this catalog before purchasing the product. Please consult your OMRON representative if you have any questions or comments.

## Warranty and Limitations of Liability

## WARRANTY

OMRON's exclusive warranty is that the products are free from defects in materials and workmanship for a period of one year (or other period if specified) from date of sale by OMRON.
OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, REGARDING NON-INFRINGEMENT, MERCHANTABILITY, OR FITNESS FOR PARTICULAR PURPOSE OF THE PRODUCTS. ANY BUYER OR USER ACKNOWLEDGES THAT THE BUYER OR USER ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. OMRON DISCLAIMS ALL OTHER WARRANTIES, EXPRESS OR IMPLIED.

## LIMITATIONS OF LIABILITY

OMRON SHALL NOT BE RESPONSIBLE FOR SPECIAL, INDIRECT, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED ON CONTRACT, WARRANTY, NEGLIGENCE, OR STRICT LIABILITY.
In no event shall the responsibility of OMRON for any act exceed the individual price of the product on which liability is asserted. NO EVENT SHALL OMRON BE RESPONSIBLE FOR WARRANTY, REPAIR, OR OTHER CLAIMS REGARDING TH PRODUCTS UNLESS OMRON'S ANALYSIS CONFIRMS THAT THE PRODUCTS WERE PROPERLY HANDLED, STORED, NSTALLED, AND MAINTAINED AND NOT SUBJECT TO CONTAMINATION, ABUSE, MISUSE, OR INAPPROPRIATE MODIFICATION OR REPAIR.

Application Considerations
SUITABILITY FOR USE
OMRON shall not be responsible for conformity with any standards, codes, or regulations that apply to the combination of the product in the customer's application or use of the product.
Take all necessary steps to determine the suitability of the product for the systems, machines, and equipment with which it will be used.
Know and observe all prohibitions of use applicable to this product.
NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOU NSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRO RRODUCT IS PROPERLY RATED AND INSTALIED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

## PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof

## Disclaimers

## CHANGE IN SPECIFICATIONS

Product specifications and accessories may be changed at any time based on improvements and other reasons. Consult with your OMRON representative at any time to confirm actual specifications of purchased product.

## DIMENSIONS AND WEIGHTS

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown

## PERFORMANCE DATA

Performance data given in this catalog is provided as a guide for the user in determining suitability and does not constitute warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

## SYSMAC

CP1H/CP1L

Note: Do not use this document to operate the Unit



Wide Lineup of CPU Units with USB Port on All Models.
Multi-functionality Condensed into One-package PLCs
 Pscksg
realǐzing

## X-ON Electronics

Largest Supplier of Electrical and Electronic Components
Click to view similar products for Controllers category:
Click to view products by Omron manufacturer:

Other Similar products are found below :
61FGPN8DAC120 CV500SLK21 70177-1011 F03-03 HAS C F03-31 81550401 FT1A-C12RA-W 88981106 H2CAC24A H2CRSAC110B R88A-CRGB003CR-E R88ARR080100S R88A-TK01K DCN1-1 DRT2ID08C DTB4896VRE DTB9696CVE DTB9696LVE E53-AZ01 E53E01 E53E8C E5C4Q40J999FAC120 E5CWLQ1TCAC100240 E5GNQ03PFLKACDC24 B300LKL21 NSCXDC1V3 NSH5-232CW-3M NT20SST122BV1 NV-CN001 OAS-160-N C40PEDRA K31S6 K33-L1B K3MA-F 100-240VAC K3TX-AD31A 89750101 L595020 SRM1-C02 SRS2-1 FT1A-C14SA-S G32X-V2K 26546803 26546805 PWRA440A CPM1AETL03CH CV500SLK11 3G2A5BI081 3G2A5IA122 3G2A5LK010E 3G2A5OA223


[^0]:    For positioning or communications, simply enter the set values for the instructions. Even complicated functions can be easily programmed using the OMRON Function Block (FB) Library.

[^1]:    Four analog input words Two analog output words

[^2]:    the can be used at the same time for analog outputs, but the total output current must not exceed 21 mA

