D5A

CSM_D5A_DS_E_2_2

High-precision Switch for Detecting Micron-unit Displacement

- Ideal for detecting and measuring wear of cutting tools or for original point of work.
- Ceramic plungers on M5, M8, and slim models for superior abrasion resistance and resistance to temperature changes.
- Direct input possible to microprocessors and programmable controllers.
- A version with screw-type cable connector available for easy installation and maintenance.

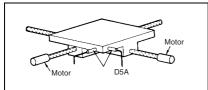


Be sure to read *Safety Precautions* on page 5 to 6 and *Safety Precautions for All Limit Switches*.



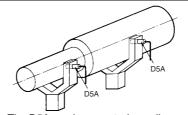
Application Examples

Origin Position Control of an X-Y Table



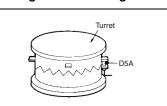
Origin can be set to a desired position and the origin position can be controlled using the D5A.

Coaxiality Inspection



The D5A can be mounted on a jig used for checking deviation to inspect its coaxiality.

Checking Turret Indexing Position



Set the D5A on the turret indexing position to check if the turret is engaged properly at the specified position.

Ordering Information

Contact Output Models (NC Contact)

| Actuator | Туре | Operation Indicator | Repeat accuracy | Operating force OF max. | Cable lead outlet | | Degree of | Model |
|---------------|-----------|------------------------|-----------------|-------------------------|-------------------|--------|------------|----------|
| Actuator | | | | | Lead outlet | Length | protection | Wodel |
| | | — None | 1 μm max. | 0.29 N | Pre-wired 1 m | | IP40 - | D5A-1100 |
| | M5 | | | 0.49 N | | 1 m | | D5A-1200 |
| | | | 3 μm max. | 0.29 N | | | | D5A-2100 |
| Pin plunger — | | | | 0.49 N | | | | D5A-2200 |
| Pili piuligei | M8 M16 | | 1 μm max. | 0.49 N | | 1 1111 | IP67 | D5A-3200 |
| | | | | 0.98 N | | | | D5A-3300 |
| | | | 3 μm max. | 2.45 N | | | | D5A-7400 |
| | | | | 2.45 N | | | | D5A-7403 |

Solid-state Output Models (PNP Transistor Output)

| A -44 | Tuma | Operation | D | Operating force OF max. | Cable lead of | utlet | Degree of protection | Model |
|-------------------|--------|-----------|-----------------|-------------------------|---------------|--------|----------------------|----------|
| Actuator | Туре | Indicator | Repeat accuracy | | Lead outlet | Length | | |
| | M8 | | | 0.49 N | | | | D5A-3210 |
| | IVIO | | 1 um may | 0.98 N | | | | |
| Pin plunger — | Slim | | 1 μm max. | 0.49 N | Pre-wired | 1 m | | D5A-5210 |
| Pili pluligei | SIIIII | | | 0.98 N | l m | | | D5A-5310 |
| | M16 | 3 | 3 μm max. | 2.45 N | | | ı | D5A-7410 |
| | | | | | Connector | 1 | | D5A-7413 |
| | | Provided | d | 0.00 M | Pre-wired | 3 m | - IP67 | D5A-8511 |
| Top plunger 🔼 | | | | | | 5 m | | D5A-8512 |
| Top plunger | | | | | Connector | 3 m | | D5A-8514 |
| | Limit | | 3 μm max. | | | 5 m | | D5A-8515 |
| | LIIIII | | o μπ max. | 3.92 N | Pre-wired | 3 m | | D5A-9511 |
| Bevel plunger — P | | | | | Fie-wired | 5 m | | D5A-9512 |
| | | | | | Connector | 3 m | | D5A-9514 |
| | | | | | Connector | 5 m | | D5A-9515 |

OMRON 1

Specifications

Ratings

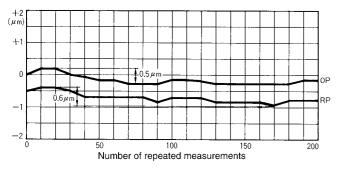
| Item | Electrical ratings | | | |
|---------------------------|--|--|--|--|
| Contact output models | M5, M8, M16 Type: 10 mA at 24 VAC 10 mA at 12 VDC | | | |
| Solid-state output models | 100 mA at 5 to 24 VDC±10% Leakage current: 0.15 mA max. Residual voltage: 3 V max. Power consumption: 3 mW max. | | | |

Engineering Data

Repeat Accuracy Examples (Reference Data) M5 Type (Contact Output) With Repeat Accuracy of 1 µm max.

D5A-1

Series



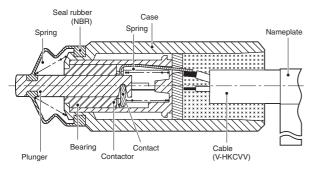
Characteristics

| Degree of protection D5A-1□, D5A-2□: IP40 Other than the above models: IP67 M5 (D5A-1□□ series), M8, slim type:1 μm max. M5 (D5A-2□□ series), M16, limit type:3 μm max. I,000,000 operations min. I,000,000 operations min. (Contact output models: 24 VAC, 10 mA, resistive load, Solid-state output models: 24 VAC, 100 mA, resistive load) M5, M8, M16, slim type: 10 μm max. Limit type: 20 μm max. Limit type: 20 μm max. Limit type: 20 μm max. In μm/s to 0.5 m/s M3, M16, slim type: 10 μm max. M5 (M6 Hz) M5 (M6 Hz) M5 (M7 M2) M | | | | | | |
|--|----------------------------|--------------|---|--|--|--|
| M5 (D5A-2 □□□ series), M16, limit type:3 μm max. Mechanical 10,000,000 operations min. | Degree of prot | ection | | | | |
| M5 (D5A-2 □□□ series), M16, limit type:3 μm max. Mechanical 10,000,000 operations min. | _ | ** | M5 (D5A-1 □□□ series), M8, slim type:1 μm max. | | | |
| Durability *2 Electrical 1,000,000 operation min. (Contact output models: 24 VAC, 10 mA, resistive load, Solid-state output models: 24 VAC, 100 mA, resistive load) Deviation in electrical durability after 1,000,000 operations M5, M8, M16, slim type: 10 μm max. Deviation speed 1 μm/s to 0.5 m/s Rated frequency 50/60 Hz Insulation resistance 100 MΩ min. (at 250 VDC) between each terminal and non-current-carrying metal part Contact resistance (Initial value) *4 800 mΩ max. (initial) with 1 m cable, 2.4 Ω max. (initial) with 5 m cable Dielectric strength 1,000 VAC, 50/60 Hz for 1 min between each terminal and non-current-carrying metal part Vibration resistance Malfunction Shock resistance Mechanical 1,000 m/s² max. Malfunction 10 to 55 Hz, 1.5-mm double amplitude Shock resistance Malfunction M5, M8, slim type: ±20 × 10-6/°C max. Limit type: ±40 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating tymidity 35% to 85%RH | Repeat accuracy 1 | | | | | |
| Durability *2 Electrical Contact output models: 24 VAC, 10 mA, resistive load, Solid-state output models: 24 VAC, 100 mA, resistive load) M5, M8, M16, slim type: 10 μm max. | | Mechanical | 10,000,000 operations min. | | | |
| durability after 1,000,000 operations Limit type: $20 \mu m$ max. Operating speed $1 \mu m/s$ to $0.5 m/s$ Rated frequency $50/60 \text{ Hz}$ Insulation resistance $100 \text{ M}\Omega$ min. (at 250 VDC) between each terminal and non-current-carrying metal part Contact resistance (Initial value) *4 $800 \text{ m}\Omega$ max. (initial) with 1 m cable, 2.4Ω max. (initial) with 3 m cable Dielectric strength $1,000 \text{ VAC}$, $50/60 \text{ Hz}$ for 1 min between each terminal and non-current-carrying metal part Vibration resistance Malfunction Shock resistance Mechanical $1,000 \text{ m/s}^2$ max. Mischance Malfunction $10 \text{ to } 55 \text{ Hz}$, 1.5-mm double amplitude Temperature coefficient *3 10 m/s^2 max. Mischance Malfunction 10 m/s^2 max. Mischance Ma | Durability *2 | Electrical | (Contact output models: 24 VAC, 10 mA, resistive load, Solid-state output models: 24 VAC, | | | |
| | | | M5, M8, M16, slim type: 10 μm max. | | | |
| Rated frequency 50/60 Hz Insulation resistance 100 MΩ min. (at 250 VDC) between each terminal and non-current-carrying metal part Contact resistance (Initial value) *4 800 mΩ max. (initial) with 1 m cable, 2.4 Ω max. (initial) with 3 m cable, 4 Ω max. (initial) with 5 m cable Dielectric strength 1,000 VAC, 50/60 Hz for 1 min between each terminal and non-current-carrying metal part Vibration resistance Malfunction Shock resistance Mechanical 1,000 m/s² max. Malfunction 300 m/s² max. M5, M8, slim type: $\pm 20 \times 10^{-6}$ °C max. Limit type: $\pm 50 \times 10^{-6}$ °C max. Limit type: $\pm 50 \times 10^{-6}$ °C max. Ambient operating tymidity 35% to 85%RH | | r 1,000,000 | Limit type: 20 μm max. | | | |
| Insulation resistance $100 \text{ M}\Omega$ min. (at 250 VDC) between each terminal and non-current-carrying metal part Contact resistance (Initial value) *4 $800 \text{ m}\Omega$ max. (initial) with 1 m cable, 2.4Ω max. (initial) with 3 m cable, 4Ω max. (initial) with 5 m cable Dielectric strength $1,000 \text{ VAC}$, $50/60 \text{ Hz}$ for 1 min between each terminal and non-current-carrying metal part Vibration resistance Malfunction Shock resistance Mechanical $1,000 \text{ m/s}^2$ max. Malfunction 300 m/s^2 max. Malfunction 300 m/s^2 max. Temperature coefficient *3 M5, M8, slim type: $\pm 20 \times 10^{-6}$ /°C max. Limit type: $\pm 50 \times 10^{-6}$ /°C max. Limit type: $\pm 50 \times 10^{-6}$ /°C max. Ambient operating tymidity 35% to 85% RH | Operating spe | ed | 1 μm/s to 0.5 m/s | | | |
| Institution resistance nal and non-current-carrying metal part Contact resistance (Initial value) *4 800 mΩ max. (initial) with 1 m cable, 2.4 Ω max. (initial) with 3 m cable, 4 Ω max. (initial) with 5 m cable Dielectric strength 1,000 VAC, 50/60 Hz for 1 min between each terminal and non-current-carrying metal part Vibration resistance Malfunction 10 to 55 Hz, 1.5-mm double amplitude Shock resistance Mechanical 1,000 m/s² max. M5, M8, slim type: $\pm 20 \times 10^{-6}$ °C max. Limit type: $\pm 40 \times 10^{-6}$ °C max. Limit type: $\pm 50 \times 10^{-6}$ °C max. Ambient operating tymidity Ambient operating hymidity Ambient operating hymidity Ambient operating hymidity 35% to 85%RH | Rated frequen | су | 50/60 Hz | | | |
| Contact resistance (Initial value) *4 Dielectric strength 1,000 VAC, 50/60 Hz for 1 min between each terminal and non-current-carrying metal part Vibration resistance Malfunction Shock Mechanical 1,000 m/s² max. Temperature coefficient *3 M5, M8, slim type: ±20 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating type: ±50 × 10-6/°C with no icing) Ambient operating hymidity. 35% to 85%RH | Insulation resi | stance | | | | |
| Vibration resistance Malfunction 10 to 55 Hz, 1.5-mm double amplitude Shock resistance Malfunction 10 to 55 Hz, 1.5-mm double amplitude 1,000 m/s² max. Malfunction 300 m/s² max. M5, M8, slim type: ±20 × 10-6/°C max. M6 type: ±40 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating type: ±20 × 10-6/°C max. Ambient operating type: ±50 × 10-6/°C with no icing) Ambient operating hymidity. 35% to 85%RH | | | 2.4 Ω max. (initial) with 3 m cable, | | | |
| resistance Malfunction 10 to 55 Hz, 1.5-mm double amplitude Shock resistance Malfunction 300 m/s² max. Malfunction 300 m/s² max. M5, M8, slim type: ±20 × 10-6/°C max. M16 type: ±40 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating type: ±50 × 10-6/°C max. | Dielectric stre | ngth | | | | |
| Malfunction 300 m/s² max. M5, M8, slim type: ±20 × 10-6/°C max. M16 type: ±40 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating temperature −20°C to +75°C (with no icing) Ambient operating humidity 35% to 85%RH | | Malfunction | 10 to 55 Hz, 1.5-mm double amplitude | | | |
| Temperature coefficient *3 M5, M8, slim type: ±20 × 10-6/°C max. M16 type: ±40 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating type: ±50 × 10-6/°C max. -20°C to +75°C (with no icing) Ambient operating hymidity. 35% to 85%RH | | Mechanical | 1,000 m/s² max. | | | |
| Temperature coefficient *3 M16 type: ±40 × 10-6/°C max. Limit type: ±50 × 10-6/°C max. Ambient operating temperature | resistance | Malfunction | 300 m/s ² max. | | | |
| temperature —20°C to +/5°C (with no icing) Ambient operating humidity 35% to 85%RH | Temperature coefficient *3 | | M16 type: ±40 × 10-6/°C max. | | | |
| Ambient operating humidity | | nting | −20°C to +75°C (with no icing) | | | |
| | Ambient operat | ing humidity | 0071100071111 | | | |

- Note: The above figures are initial values.
 *1. Contact your OMRON sales representative for measurement conditions of the repeat accuracy.
- *2. Durability values are calculated at an operating temperature of +5°C to +35°C, and an operating humidity of 40% to 70%RH. Contact your OMRON sales representative for more detailed information on other operating environments.
- *3. The value indicates the operating position change rate for a change of 1°C in the ambient temperature. The specifications depend on the model. Contact your OMRON sales representative for details.
- *4. Values for contact output models.

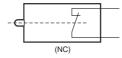
Structure and Nomenclature

Structure



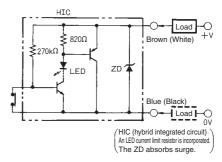
Contact Form/Output Circuit Diagram **Contact Output Models**

M5, M8, M16 type



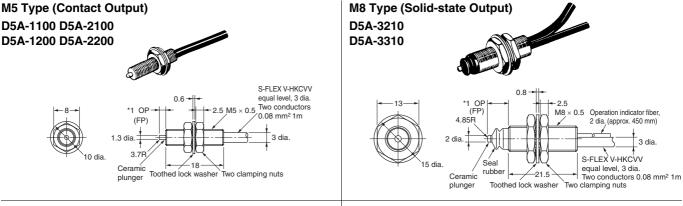
Note: NO Switches are not available with contact output models.

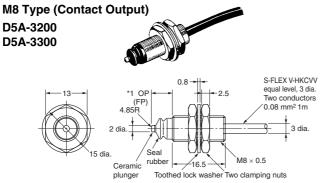
Solid-state Output Models (PNP Transistor Output) M8, Slim, M16, Limit type

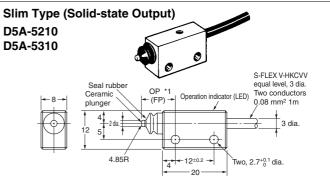


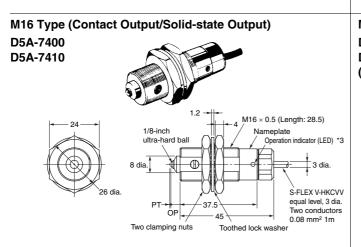
Note: The load may be connected to either the +V or 0 V terminal. Core wire colors have been changed accompanying changes in standards. The old core wire colors are given in parentheses.

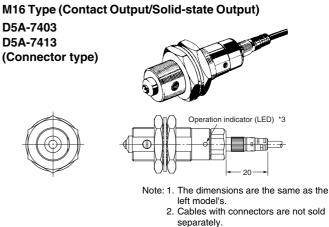
(Unit: mm)











Note: 1. Unless otherwise specified, a tolerance of ± 0.4 mm applies to all dimensions.

2. Special screw dimensions apply to the case screws (pitch: 0.5 mm). Mounting is not possible with standard tapping. Use the provided special nuts.

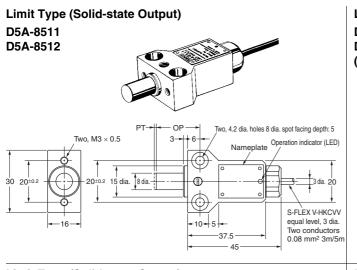
| Operating characteristics | ı | Model | D5A-1100 *2 D5A-2100 *2 | D5A-1200 *2 D5A-2200 *2 | D5A-3200 _{*2} D5A-3210 | D5A-3300 _{*2} D5A-3310 | D5A-5210 *2 | D5A-5310 *2 | D5A-7400, D5A-7410 D5A-7403, D5A-7413 |
|--|----------------|------------------------------|------------------------------|------------------------------|------------------------------------|------------------------------------|------------------------------|------------------------------|--|
| Operating force Pretravel Overtravel Movement Differential | OF PT OT | max. max. min. max. | 0.29 N 1.5 mm 5 μm | 0.49 N 1.5 mm 5 μm | 0.49 N 1.5 mm 5 μm | 0.98 N 1.5 mm 5 μm | 0.49 N 1.5 mm 5 μm | 0.98 N 1.5 mm 5 μm | 2.45 N 1 mm 2 mm 5 μm |
| Operating Position Free Position | OP FP | *1 | (2 mm) | (2 mm) | (6.5 mm) | (6.5 mm) | 10.5±0.4 mm | 10.5±0.4 mm | (4.4 mm) (5 mm) |

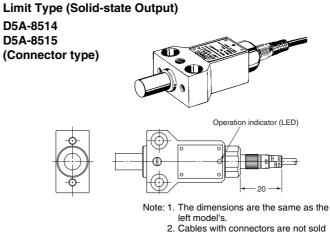
^{*1.} The operating position of these types is the same as the free position because of high sensitivity (repeat accuracy: 1 µm max.). This does not apply to M16 limit switch types.

OMRON

Total movement is 1.9 to 2.1 mm. Set the appropriate stroke (plunging depth) to 1.0 to 1.5 mm from the FP.

^{*3.} Not available in the contact output type.

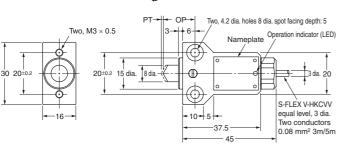




Limit Type (Solid-state Output)

D5A-9511 D5A-9512





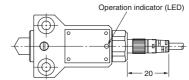
Limit Type (Solid-state Output)

D5A-9514 D5A-9515 (Connector type)



separately.





Note: 1. The dimensions are the same as the left model's.

2. Cables with connectors are not sold separately.

Note: Unless otherwise specified, a tolerance of ± 0.4 mm applies to all dimensions.

| Operating characteristics | Model | D5A-8511, -8514 D5A-8512, -8515 | D5A-9511, -9514 D5A-9512, -9515 |
|------------------------------|---------|------------------------------------|------------------------------------|
| Operating force | OF max. | 3.93 N | 3.93 N |
| Pretravel | PT max. | 1 mm | 1 mm |
| Overtravel | OT min. | 5 mm | 4 mm |
| Movement Differential | MD max. | 5 μm | 5 μm |
| Operating Position | OP | 21.0±0.4 mm | 15.2±0.4 mm |
| Free Position | FP | (21.8mm) | (15.8mm) |

Safety Precautions

Refer to Safety Precautions for All Limit Switches.

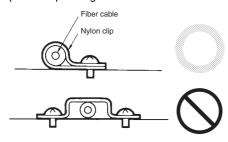
Precautions for Correct Use

Handling of Fiber Cable

- Do not pull or impose any force exceeding 29.42 N on the fiber cable.
- Make sure that the bending radius of the fiber cable is as large as possible and at least R20 mm.
- The 40-mm portion of the fiber cable on the connector end as shown below must not be bent.



• Do not impose compressing loads on the fiber cable.



- The fiber cable can be cut with OMRON's E39-F4 Cutting Tool.
- Do not impose any force exceeding 29.42 N on the cable, otherwise the cord may break. Make sure that the bending radius of the cable is at least 20 mm.

Mounting

- The screw sections of cases for M5, M8, and M16 types have special dimensions. Do not use the mounting dimensions specified for standard types.
- For the mounting dimensions, refer to the following figures and tables.



| Туре | | M | 18 | | |
|----------------------------|--------------------|-----------------|--------------------|---------------------|--|
| Size | M5 Contact output | | Solid-state output | M16 | |
| A (Mounting hole) | 5.2±0.1 mm dia. | 8.2±0.1 mm dia. | | 16.2±0.1 mm dia. | |
| B (Panel thickness) | 3 to 10 mm | 5 to 8 mm | 5 to 13 mm | 10 to 17 mm | |
| C (Toothed lock washer) | 10 mm dia. | 15 mm dia. | | 26 mm dia. | |

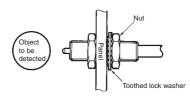


| | Siz | Type ze | Slim | Limit | |
|---|---------------|------------------|------------------|-----------|--|
| | Α | Mounting pitch | 12±0.2 mm | 20±0.2 mm | |
| В | Tapping | M2.6 | M4 | | |
| | Mounting hole | 2.8 ±0.2 mm dia. | 4.2 ±0.2 mm dia. | | |

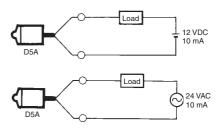
• Do not tighten the nut with too much force. Be sure to apply the torque shown in this table.

| Туре | Appropriate tightening torque |
|-------|-------------------------------|
| M5 | 0.98 N⋅m max. |
| M8 | 2.94 N⋅m max. |
| M16 | 9.81 N·m max. |
| Slim | 0.29 N·m max. (M2.6 screw) |
| Limit | 1.47 N⋅m max. (M4 screw) |

 When mounting the Switch to a panel, be sure to use the toothed lock washer attached as an accessory (to M5, M8, and M16 types only). Use the washer on the panel surface opposite the object to be detected by the Switch.



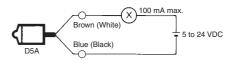
Connection of Contact Output



Consideration of polarity is not required.

Connection of Solid-state Output

- Be sure to connect the load to the power source in series.
- The operating state of the Switch can be checked by the LED operation indicator (lights when the Switch is in operation) incorporated in the solid-state output circuit.
- The output residual voltage is approximately 3 V. Therefore, exercise care when selecting the load and setting the supply voltage. The residual voltage, however, can be easily calculated because it is almost constant and is free from the influence of fluctuation in the load current.



Note: The lead wire colors of the D5A have been changed in compliance with the latest applicable JIS standards.

Colors in parentheses are previous ones.

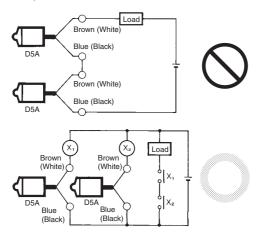
[Example]

- (1) In the above circuit, suppose the MY relay rated at 12 VDC is used as the load. Since the must operate voltage of the relay is 80% or less than the rated voltage, it is $12 \times 0.8 = 9.6$ V. The supply voltage, in turn, is 3 + 9.6 = 12.6 V.
- Therefore, the relay may not operate with a 12 V power source.
- (2) However, if the relay rated at 24 VDC is employed, the must operate voltage and supply voltage of the relay are respectively 19.2 V and 22.2 V. The relay therefore can operate with a 24 V power source.
- When a solid-state circuit is turned OFF, leakage current of 0.15 mA (max.) flows, causing some voltages to remain in the load. For this reason, be sure to check the must release voltage of the load before using it.

5

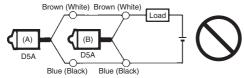
Series Connection of Switches

The Solid-state Output-type Switches must not be connected in series. To obtain the same effect as a series connection, form an AND gate with a relay inserted between the Switch and load.

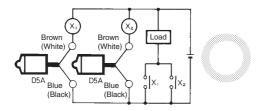


Parallel Connection of Switches

 In principle, two or more D5A's should not be used in an OR configuration.



 However, they can be connected in parallel provided that both switches A and B in the above figure do not operate at the same time and that the load does not have to be kept energized. In this circuit, however, the leakage current is increased, multiplied by the number of Switches connected in parallel. Consequently, the Switch may not release properly. To keep the load energized, connect a relay to each of the Switches as shown below.

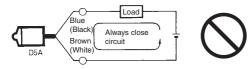


Connection to Power Source

 Be sure to connect the Switch to the power source via the load. If directly connected to the power source, the internal elements of the Switch may be damaged.



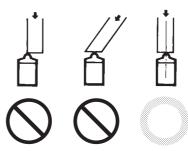
 Correctly connect the white and black lead wires to the positive and negative sides, respectively, of the power source. Although the D5A will not be damaged even if the polarity is reversed by mistake, if this happens, the Switch maintains the ON state (i.e., the contact is kept open) regardless of the presence or absence of the object to be detected.



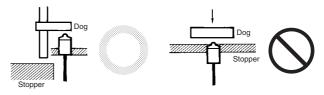
The core wire colors have been changed to meet new standards. Make sure that the wires are connected correctly.

Others

 Adjust the mounting of the D5A until the stroke of the pin plunger and top plunger is aligned with the stroke of the operating body.
 Special attention should be paid to the ceramic pushbutton unit. It might be damaged if undue shock is applied.

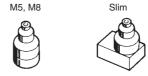


- The harder the material for the dog and the more solidly the mounting base is fitted, the more accurately a minute displacement is detected.
- When a limit switch type (D5A-8 \(\subseteq \), D5A-9 \(\subseteq \)) is used, apply grease to the dog to reduce friction between it and the plunger.
 Do not apply grease to pin plungers, otherwise the grease may stick to the contacts or generate gas that may cause contact failures.
- Be sure to use dogs made of hard materials for bevel or top plungers and apply grease to the surface of the dogs. The hardness (Hv) of a bevel plunger is 2,000 or over, for which it is recommended that a dog that has an Hv value of 1,000 or less be used
- Do not fail to provide a stopper so as to prevent the enclosure of the D5A from being used as the stoppers.

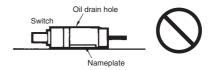


- Attach an appropriate cover for the protection of the D5A from machining oil or cuttings. No protective cover is, however, provided together with the Switch.
- Exercise care that excessive force is not applied to the ceramic plunger of M5, M8, or slim type.
 If the possibility exists that strong shock may be applied to the plunger when the Switch is being mounted, use a protective cap.

The plunger may not release if it is depressed with too great a force. Set its stroke by referring to the OT value indicated in Operating Characteristics.



 Do not mount the Switch with its nameplate facing downwards (i.e., in the direction of gravity), otherwise the oil drain hole will not work effectively.



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