

# Absolute Rotary Encoder

**E6C2-A** 

Use the Tough E6C2-A (Rated IP64 for Degree of Protection) Combined with a PLC or Cam Positioner for Optimum Control and Ease-of-Use

- Incorporates a sealed bearing, meeting IP64 for durability
- Compact: 50-mm diameter x 38-mm height
- 8 mm-dia. stainless steel shaft is twice as strong as conventional shafts
- Reliable bearing and metal slit plate ensure shock resistance of 1000 m/s <sup>2</sup>





# **Ordering Information**

## **■ ABSOLUTE ROTARY ENCODERS**

Appearance	Connection method	Connecting device	Resolution (p/r)	Part number
	Cable	Programmable Controller	256, 360, 720, 1,024	E6C2-AG5C 256 E6C2-AG5C 360 E6C2-AG5C 720 E6C2-AG5C 1024
	Connector	H8PS Cam Positioner	256	E6C2-AG5C-C 256

Note: The H8PS can be connected to the E6C2-AG5C-C but not to the E6C2-AG5C.

## ■ ACCESSORIES (ORDER SEPARATELY)

Refer to Dimensions section for details

Item		Part number
Coupling		E69-C08B
Flange		E69-FCA-03
		E69-FCA-04
Extension cable	5 m	E69-DF5
	10 m	E69-DF10
	15 m	E69-DF15
	20 m	E69-DF20

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### ■ RATINGS/CHARACTERISTICS

Daniel Committee		40.1/0.0-10% - 0.4.1/0.0+15%		
Power supply voltage		12 VDC <sup>-10%</sup> to 24 VDC <sup>+15%</sup> , ripple (p-p) 5% max.		
Current consumption		70 mA max.		
Resolution (See Note 1)		256, 360, 720, 1,024 P/R		
Output code (absolute)		Gray code		
Output configuration		NPN open collector		
Output capacity	Applied voltage	30 VDC max.		
	I <sub>sink</sub>	35 mA max.		
	Residual voltage	0.4 V max.		
Max. response frequency	(See Note 2)	20 kHz		
Logic		Negative logic output (H=0, L=1)		
Rotational direction		Clockwise, as viewed from the face of the shaft		
Rise and fall times of outp	ut	1 μs max. (cable length: 2m; I <sub>sink</sub> : 35 mA max.)		
Starting torque		100 gf • cm (0.087 in • lbf) max. at room temperature 150 gf • cm (0.13 in • lbf) max. at low temperature		
Moment of inertia		15 g • cm <sup>2</sup> (1.5 x 10 <sup>-6</sup> kg • m <sup>2</sup> ) or 0.005 lb • in <sup>2</sup> max.		
Shaft loading Radial		8 kgf (78.4N) or 17.6 lbf		
	Thrust	5 kgf (49N) or 11.0 lbf		
Maximum permissible rota	ation	5,000 rpm		
Ambient temperature	Operating	-10°C to 70°C (14°F to 158°F) with no icing		
	Storage	-25°C to 85°C (-13°F to 185°F) with no icing		
Ambient humidity	Operating	35% to 85% (with no condensation)		
Insulation resistance		20 $M\Omega$ min. (at 100 VDC) between carry parts and case		
Dielectric strength		500 VAC, 50/60 Hz for 1 min between carry parts and case		
Vibration resistance		Destruction: 10 to 500 Hz, 1.0-mm single amplitude or 150 m/s <sup>2</sup> (approx. 15G) for 11 min. 3 times each in X, Y, and Z axes		
Shock resistance		Destruction: 1,000 m/s <sup>2</sup> (approx. 100G) 3 times each in X, Y, and Z axes		
Degree of protection		IEC IP64		
Weight		300 g (0.66 lbs) with 2-m cable		

Note: 1. A gray code signal with a remainder of 76 is used for a resolution of 360 per rotation and a gray code signal with a remainder of 152 is used for a resolution of 720 per rotation. Therefore, the code signal for a resolution of 360 per rotation uses addresses 76 through 435 and that for a resolution of 720 per rotation uses addresses 152 through 871.

2.	The electrical maximum response rotation is determined by using the resolution and maximum response frequency in the fol
	lowing formula.

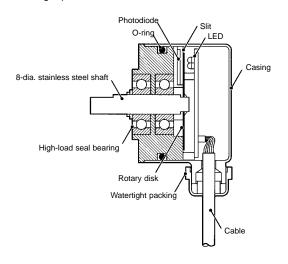
Electrical maximum response rotation (rpm) =	Maximum response frequency	
Electrical maximum response rotation (ipin) =	Resolution	x 60

Therefore, a signal cannot follow electrically if the actual rotation exceeds the maximum response rotation.

## Connections

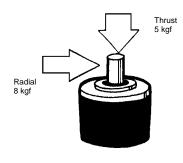
#### **■ DURABLE DESIGN**

The E6C2-A incorporates a high-performance LED, custom-made diode array, high-density printed circuit board, and a compact, watertight, seal bearing that withstands heavy loads, thus ensuring high mechanical durability, watertight performance, and compactness. The O-ring applied to the casing and a watertight packing applied to the cable connector enhance the watertight performance of the E6C2-A.



#### **■ SHAFT STRENGTH**

The E6C2-A has a stainless steel shaft that is 8 mm in diameter and approximately twice as strong as OMRON's conventional Rotary Encoder shaft. The E6C2-A also has a reliable bearing and metal slit plate, ensuring a shock resistance of 1,000 m/s².



## Operation

## **■ CONNECTIONS**

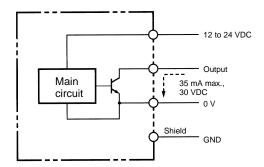
## **Cable Specifications**

	Output signal E6C2-AG5C				
Wire color	8-bit (256)	9-bit (360)	10-bit (720, 1,024)		
Light blue	NC	NC	2 <sup>9</sup>		
Pink	NC	28	28		
Purple	2 <sup>5</sup>	2 <sup>5</sup>	2 <sup>5</sup>		
Orange	2 <sup>1</sup>	21	21		
Brown	2 <sup>0</sup>	2 <sup>0</sup>	20		
White	2 <sup>7</sup>	2 <sup>7</sup>	2 <sup>7</sup>		
Blue	2 <sup>4</sup>	2 <sup>4</sup>	2 <sup>4</sup>		
Yellow	2 <sup>2</sup>	2 <sup>2</sup>	2 <sup>2</sup>		
Green	2 <sup>3</sup>	2 <sup>3</sup>	2 <sup>3</sup>		
Gray	2 <sup>6</sup>	2 <sup>6</sup>	2 <sup>6</sup>		
	Shield (GND)	Shield (GND)			
Red	12 to 24 VDC	12 to 24 VDC			
Black	0 V (Common)	0 V (Common)			

## **■ CONNECTOR SPECIFICATIONS**

	Output signal	
	E6C2-AG5C-C	
Pin number	8-bit (256)	
1	NC	
2	NC	
3	2 <sup>5</sup>	
4	21	
5	20	
6	2 <sup>7</sup>	
7	2 <sup>4</sup>	
8	2 <sup>2</sup>	
9	23	
10	2 <sup>6</sup>	
11	Shield (GND)	
12	12 to 24 VDC	
13	0 V (Common)	

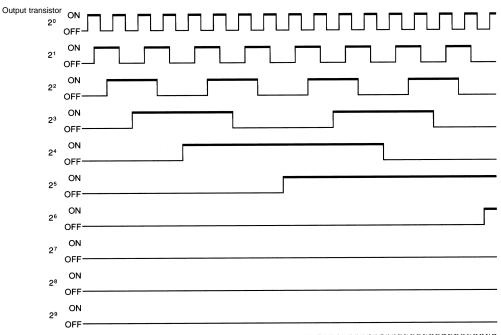
### **■ OUTPUT CIRCUIT DIAGRAM**



Note: Each output bit uses the same circuit.

## ■ OUTPUT MODE

Rotating direction: CW, as viewed from the face of the shaft.

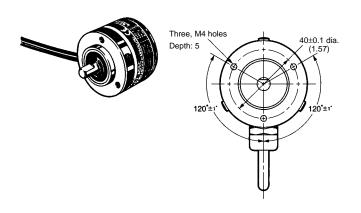


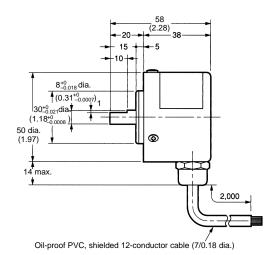
Address 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 65 75 85 96 06 162 63 64 65

## **Dimensions**

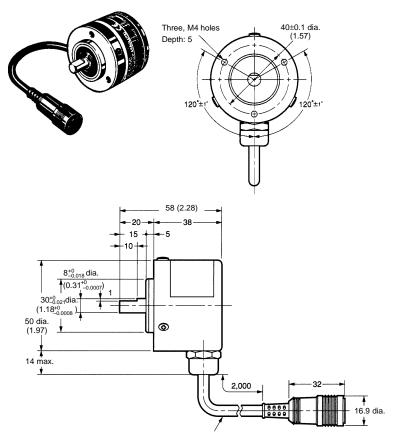
Unit: mm (inch)

### **■** E6C2-AG5C





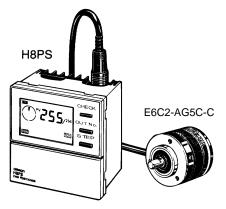
## **■** E6C2-AG5C-C



Oil-proof PVC, shielded 12-conductor cable (7/0.18 dia.)

## Installation \_\_\_\_\_

## ■ CONNECTING E6C2-AG5C-C TO H8PS CAM POSITIONER



Model	Mounting method	Output configuration	
H8PS-8B	Flush	NPN transistor output	
H8PS-8BP		PNP transistor output	
H8PS-8BF	Surface/Track	NPN transistor output	
H8PS-8BFP		PNP transistor output	

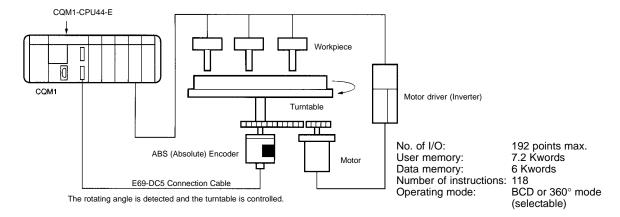
### **Specifications**

Rated voltage	24 VDC		
Cam resolution	1.4° (a resolution of 256 per rotation)		
Outputs	Open-collector transistor output NPN: H8PS-8B(F) PNP: H8PS-8B(F)P		
	Cam outputs: 8 lines (Output No. 1 to 8) 30 VDC max., 100 mA max. (residual voltage: 2 V max.)		
	RUN OUT: Turns ON in Run and Test modes, OFF in Program mode in case of error 30 VDC max., 100 mA max. (residual voltage: 2 V max.)		
	TACHOMETER: 60-ppr signal output for rpm meter 30 VDC max., 30 mA max. (residual voltage: 0.5 V max. for NPN models, 2 V max. for PNP models)		
Encoder response	330 rpm		
Functions	Origin compensation (zero shift) Rotating direction selection Angle display selection Teaching		

#### **■ CONNECTING E6C2-AG5C TO PROGRAMMABLE CONTROLLER**

#### Example of Connection to CQM1-CPU44-E High-capacity CPU Unit with Absolute Interface and RS-232C Port

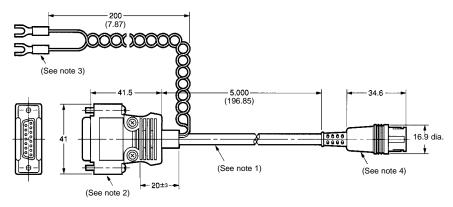
Position data can be directly input as 8, 10, or 12-bit gray code signals from Absolute Encoders to the CQM1-CPU44-E. The position data input is backed up during power failures. Therefore, the origin return operation is not required after the power supply resumes. Furthermore, the origin compensation function of the E6C2-AG5C makes it possible to use any position for the origin.



#### **Input Specifications**

Input voltage	24 VDC+10%/_15%
Input impedance	5.4 kΩ
Input current	4 mA (TYP.)
ON voltage	16.8 VDC min.
OFF voltage	3.0 VDC max.
Counting speed	4 kHz max.
Input code	Gray code (8, 10, or 12 bits)

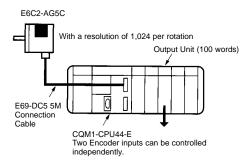
### E69-DC5 5M Connection Cable for CQM1-CPU44-E (Order Separately)



- Note: 1. 6-dia. oil-proof PVC, shielded 12-conductor cable (7/0.18 dia.); standard length: 5 m
  - 2. Connected to CQM1-CPU44-E.
  - 3. 12 to 24 VDC
  - 4. Connected to Encoder.

## System Configuration Using a Resolution of 1,024 per Rotation

A combination of the CQM1-CPU4-4E and E6C2-AG5C ensures easy output angle setting for cam control in 360° or BCD mode.

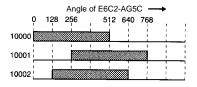


#### Mode Setting of CQM1-CPU44-E

Set port 1 to BCD mode and 10 bits

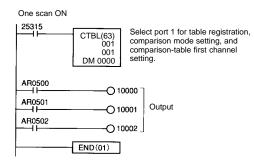
DM 6643 0001

#### **Output Timing**



#### **Ladder Program Example**

Use the CTBL instruction of the CQM1-CPU44-E to register a maximum of eight comparison tables for output angle setting.



#### **Example of DM Setting for Comparison Table**

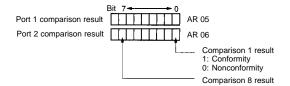
DM0000	0000	Lower limit 1	
0001	0512	Upper limit 1	Bit AR 0500
0002	0000	Subroutine number 1	Dit 7 11 C 0000
0003	0256	Lower limit 2	
0004	0768	Upper limit 2	Bit AR 0501
0005	0000	Subroutine number 2	
0006	0128	Lower limit 3	
0007	0640	Upper limit 3	Bit AR 0502
8000	0000	Subroutine number 3	
0009	0000	Lower limit 4	
0022 0023	0000 0000	Upper limit 8 Subroutine number 8	Not used.

Note: An upper or lower limit can be set with integers in BCD mode and 5° increments in 360° mode. Subroutine numbers are set for interrupt processing.

#### Internal Bits of CQM1-CPU44-E

#### • Range Comparison Result

Each bit of the CQM1-CPU44-E CPU Unit's words AR 05 and AR 06 turns ON only when the comparison range coincides with the angle of E6C2-AG5C.



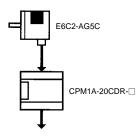
#### Present Value Read

The gray code signals of the E6C2-AG5C are automatically converted into BCD or 360° code signals and read through the CQM1-CPU44-E CPU Unit's words AR 232 and AR 234. The present value can be used for ladder programs.

Port 1 angle \* \* \* \* Word 232

Port 2 angle \* \* \* \* Word 234

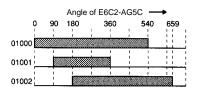
# ■ CONNECTING TO CPM1A USING A RESOLUTION OF 720 PER ROTATION



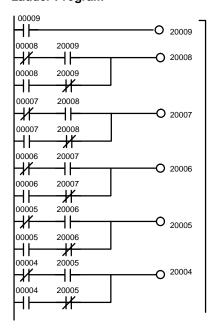
### Wiring Between E6C2-AG5C and CPM1A

Output signal from E6C2-AG5C	Input signal to CPM1A
Brown (2 <sup>0</sup> )	00000
Orange (2 <sup>1</sup> )	00001
Yellow (2 <sup>2</sup> )	00002
Green (2 <sup>3</sup> )	00003
Blue (2 <sup>4</sup> )	00004
Purple (2 <sup>5</sup> )	00005
Gray (2 <sup>6</sup> )	00006
White (2 <sup>7</sup> )	00007
Pink (2 <sup>8</sup> )	00008
Light blue (2 <sup>9</sup> )	00009

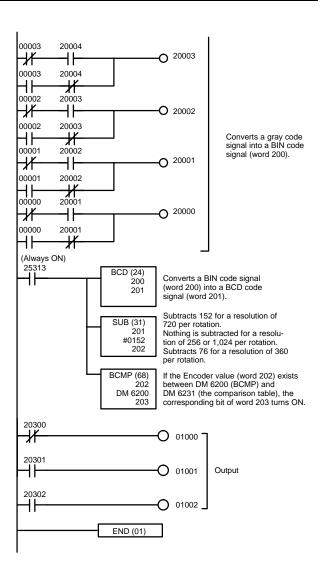
## **Output Timing**



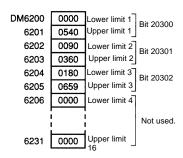
#### **Ladder Program**



Converts a gray code signal into a BIN code signal (word 200).

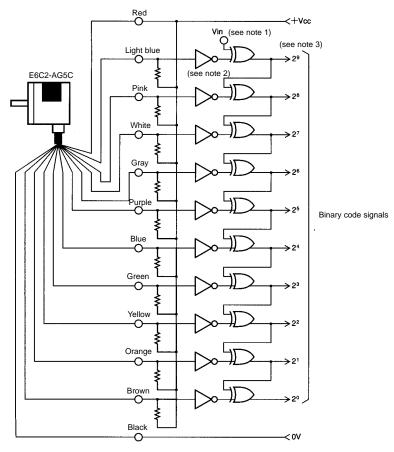


#### **Example of DM Setting for Comparison Table**



### **■ GRAY-TO-BINARY CONVERSION CIRCUIT REFERENCE**

Note: This circuit example is for 10-bit signals. For 9-bit signals, input Vin into the XOR of 2<sup>8</sup>, and for 8-bit signals, input Vin into the XOR of 2<sup>7</sup>.



Note: 1. Signal can be converted into positive-logic binary code signals if 0 V is connected to Vin.

- 2. Inverter
- 3. Exclusive OR (EOR)

NOTE: DIMENSIONS SHOWN ARE IN MILLIMETERS. To convert millimeters to inches divide by 25.4.

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