## General-purpose Encoder with External Diameter of 40 mm

- Incremental model
- External diameter of 40 mm .
- Resolution of up to 2,000 ppr.


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## Ordering Information

Encoders [Refer to Dimensions on page 4.]

| Power supply voltage | Output configuration | Resolution (pulses/rotation) | Model |
| :---: | :---: | :---: | :---: |
| 5 to 24 VDC | NPN open-collector output | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600 | E6B2-CWZ6C (resolution) 0.5M <br> Example: E6B2-CWZ6C 10P/R 0.5M |
|  |  | 720, 800, 1,000, 1,024 |  |
|  |  | 1,200, 1,500, 1,800, 2,000 |  |
| 12 to 24 VDC | PNP open-collector output | 100, 200, 360, 500, 600 | E6B2-CWZ5B (resolution) 0.5M <br> Example: E6B2-CWZ5B 100P/R 0.5M |
|  |  | 1,000 |  |
|  |  | 2,000 |  |
| 5 to 12 VDC | Voltage output | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600 | E6B2-CWZ3E (resolution) 0.5M <br> Example: E6B2-CWZ3E 10P/R 0.5M |
|  |  | 1,000 |  |
|  |  | 1,200, 1,500, 1,800, 2,000 |  |
| 5 VDC | Line-driver output | 10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600 | E6B2-CWZ1X (resolution) 0.5M <br> Example: E6B2-CWZ1X 10P/R 0.5M |
|  |  | 1,000, 1,024 |  |
|  |  | 1,200, 1,500, 1,800, 2,000 |  |

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

| Name | Model | Remarks |
| :--- | :--- | :--- |
| Couplings | E69-C06B | Provided with the product. |
|  | E69-C68B | Different end diameter |
|  | E69-C610B | Different end diameter |
|  | E69-C06M | Metal construction |
| Flanges | E69-FBA |  |
|  | E69-FBA02 | E69-2 Servo Mounting Bracket provided. |
| Servo Mounting Bracket | E69-2 | --- |
| Refer to Accessories for details. |  |  |

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## Ratings and Specifications

| Item | Model | E6B2-CWZ6C | E6B2-CWZ5B | E6B2-CWZ3E | E6B2-CWZ1X |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Power supply voltage |  | 5 VDC $-5 \%$ to 24 VDC <br> $+15 \%$, ripple ( $p-p$ ): $5 \%$ max. | 12 VDC $-10 \%$ to 24 VDC <br> $+15 \%$, ripple (p-p): 5\% max. | 5 VDC $-5 \%$ to 12 VDC <br> $+10 \%$, ripple ( $p-p$ ): $5 \%$ max. | 5 VDC $\pm 5 \%$, ripple ( $p-p$ ): 5\% max. |
| Current consumption *1 |  | 80 mA max. | 100 mA max. |  | 160 mA max. |
| Resolution (pulses/rotation) |  | $\begin{aligned} & 10,20,30,40,50,60,100 \\ & 200,300,360,400,500,600 \\ & 720,800,1,000,1,024, \\ & 1,200,1,500,1,800,2,000 \end{aligned}$ | $\begin{aligned} & 100,200,360,500,600 \\ & 1,000,2,000 \end{aligned}$ | $\begin{aligned} & 10,20,30,40,50,60,100 \\ & 200,300,360,400,500,600 \\ & 1,000,1,200,1,500,1,800 \\ & 2,000 \end{aligned}$ | $\begin{aligned} & 10,20,30,40,50,60,100 \\ & 200,300,360,400,500,600 \\ & 1,000,1,024,1,200,1,500 \\ & 1,800,2,000 \end{aligned}$ |
| Output phases |  | Phases A, B, and Z |  |  | Phases $\mathrm{A}, \overline{\mathrm{A}}, \mathrm{B}, \overline{\mathrm{B}}, \mathrm{Z}$, and $\overline{\mathrm{Z}}$ |
| Phase difference between outputs |  | $90^{\circ} \pm 45^{\circ}$ between A and $\mathrm{B}(1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T})$ |  |  |  |
| Output configuration |  | NPN open-collector output | PNP open-collector output | Voltage output (NPN output) | Line driver output *2 |
| Output capacity |  | Applied voltage: 30 VDC max. <br> Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA ) | Applied voltage: 30 VDC max. <br> Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA ) | Output resistance: $2 \mathrm{k} \Omega$ Sink current: 20 mA max. Residual voltage: 0.4 V max. (at sink current of 20 mA ) | AM26LS31 equivalent Output current High level: $\mathrm{lo}=-20 \mathrm{~mA}$ Low level: Is $=20 \mathrm{~mA}$ Output voltage: $\mathrm{Vo}=2.5 \mathrm{~V}$ min. $\mathrm{Vs}=0.5 \mathrm{~V}$ max. |
| Maximum response frequency *3 |  | 100 kHz | 50 kHz | 100 kHz |  |
| Rise and fall times of output |  | $1 \mu \mathrm{~s}$ max. (Control output voltage: 5 V , Load resistance: $1 \mathrm{k} \Omega$, Cable length: 2 m max.) | $1 \mu \mathrm{~s}$ max. (Cable length: 2 m | max., Sink current: 10 mA ) | $0.1 \mu \mathrm{~s}$ max. (Cable length: 2 m max., $\mathrm{lo}=-20 \mathrm{~mA}$, $\mathrm{Is}=$ 20 mA ) |
| Starting torque |  | $0.98 \mathrm{mN} \cdot \mathrm{m}$ max. |  |  |  |
| Moment of inertia |  | $1 \times 10^{-6} \mathrm{~kg} \cdot \mathrm{~m}^{2}$ max.; $3 \times 10^{-7} \mathrm{~kg} \cdot \mathrm{~m}^{2} \mathrm{max}$. at $600 \mathrm{P} / \mathrm{R}$ max. |  |  |  |
| Shaft loading | Radial | 30 N |  |  |  |
|  | Thrust | 20 N |  |  |  |
| Maximum permissible speed |  | 6,000 r/min |  |  |  |
| Protection circuits |  | Power supply reverse polarity protection, Load short-circuit protection |  |  | --- |
| Ambient temperature range |  | Operating: -10 to $70^{\circ} \mathrm{C}$ (with no icing), Storage: -25 to $85^{\circ} \mathrm{C}$ (with no icing) |  |  |  |
| Ambient humidity range |  | Operating/Storage: 35\% to 85\% (with no condensation) |  |  |  |
| Insulation resistance |  | $20 \mathrm{M} \Omega \mathrm{min}$. (at 500 VDC ) between current-carrying parts and case |  |  |  |
| Dielectric strength |  | $500 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}$ for 1 min between current-carrying parts and case |  |  |  |
| Vibration resistance |  | Destruction: 10 to $500 \mathrm{~Hz}, 150 \mathrm{~m} / \mathrm{s}^{2}$ or 2-mm double amplitude for 11 min 3 times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Shock resistance |  | Destruction: $1,000 \mathrm{~m} / \mathrm{s}^{2} 3$ times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Degree of protection |  | IEC 60529 IP50 |  |  |  |
| Connection method |  | Pre-wired Models (Standard cable length: 500 mm ) |  |  |  |
| Materials |  | Case: ABS, Main unit: Aluminum, Shaft: SUS420J2 |  |  |  |
| Weight (packed state) |  | Approx. 100 g |  |  |  |
| Accessories |  | Coupling, Hexagonal wrench, Instruction manual |  |  |  |

*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. The quality is equivalent to AM26LS31.
*3. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

$$
\frac{\text { Maximum response frequency }}{\text { Resolution }} \times 60
$$

This means that the E6B2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

## I/O Circuit Diagrams

| Model/Output Circuits | Output mode | Connection |  |
| :---: | :---: | :---: | :---: |
| E6B2-CWZ6C |  |  |  |
|  | E6B2-CWZ6C NPN Open-collector Output Model E6B2-CWZ5B PNP Open-collector Output Model |  |  |
| E6B2-CWZ5B |  | Color Brown | Terminal <br> Power supply <br> $(+V c c)$ |
|  | Note: Phase A is $1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T}$ faster than phase $B$. <br> Note: Phase A is $1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T}$ slower than phase $B$. | Black | Output phase A |
|  | The ONs in the above timing chart mean that the output transistor is ON | White | Output phase B |
|  | and the OFFs mean that the output transistor is OFF. | Orange | Output phase Z |
| Shield GND |  | Blue | 0 V (common) |



## E6B2-CWZ3E Voltage Output Model

$\begin{array}{ll}\text { Direction of rotation: CW } & \text { Direction of rotation: CCW } \\ \text { (as viewed from end of shaft) } & \text { (as viewed from end of shaft) }\end{array}$


Note: Phase A is $1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T} \quad$ Note: Phase $A$ is $1 / 4 \mathrm{~T} \pm 1 / 8 \mathrm{~T}$ faster than phase $B$. slower than phase $B$.

## E6B2-CWZ1X

## E6B2-CWZ1X Line Driver Output Model

Direction of rotation: CW (as viewed from end of shaft)

Direction of rotation: CCW (as viewed from end of shaft)


| Color | Terminal |
| :---: | :---: |
| Brown | Power supply <br> $(+V c c)$ |
| Black | Output phase <br> A |
| Black/red <br> stripes | Output phase <br> $\overline{\mathrm{A}}$ |
| White | Output phase <br> B |
| White/red <br> stripes | Output phase <br> $\overline{\mathrm{B}}$ |
| Orange | Output phase <br> Z |
| Orange/ <br> red <br> stripes | Output phase <br> $\bar{Z}$ |
| Blue | 0 V (common) |
| Re: Res |  |

Note: Receiver: AM26LS32 equivalent

Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.
2. The phase A, phase B, and phase Z circuits are all identical.
3. Normally, connect GND to 0 V or to an external ground.

## Safety Precautions

## Refer to Warranty and Limitations of Liability.

| $\leqq$ WARNING |
| :--- |
| This product is not designed or rated for ensuring |
| safety of persons either directly or indirectly. |
| Do not use it for such purposes. |

## Precautions for Safe Use

Incorrect wiring may damage internal circuits.

## Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

## - Mounting

- Origin Indication

It is easy to adjust the position of phase $Z$ with the origin indication function. The following illustration shows the relationship between phase $Z$ and the origin. Set cut face $D$ to the phase $Z$ origin as shown in the illustration.


- Do not extend the length of the cable to more than 2 m . If the cable must be more than 2 m , use a Model with a Line-driver Output (max. length: 100 m ).


## - Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

Dimensions

## Encoder

## E6B2-C



5 -dia. vinyl-insulated round cable with 8 conductors
(Conductor cross section: $0.2 \mathrm{~mm}^{2}$, Insulation
diameter: 1.0 mm ), Standard length: 0.5 m

## Accessories (Order Separately)

Couplings
E69-C06B
E69-C68B
Flanges
E69-FBA
E69-FBA02

E69-C610B
E69-C06M
Refer to Accessories for details.

## Servo Mounting Bracket

E69-2

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[^0]:    Refer to Accessories for details.

