Digital Indicators
K3HB Series (Pulse Input Series)

The K3HB Series has been made complete with the addition of Digital Signal Input Models.

- Easy recognition of judgment results using two-color display that can be switched between red and green.
- Equipped with a position meter for monitoring operating status trends.
- External event inputs allows using various measurement and discrimination applications.
- Series expanded to include DeviceNet models.
- Short body with depth of only 95 mm (see note) (from behind the front panel).
- UL certification (Certification Mark License).
- CE Marking conformance by third party assessment body.
- Water-resistant enclosure conforms to NEMA 4X (equivalent to IP66).

Note: Depth of 97 mm for DeviceNet models.

⚠ Refer to *Common Precautions* on page 30.

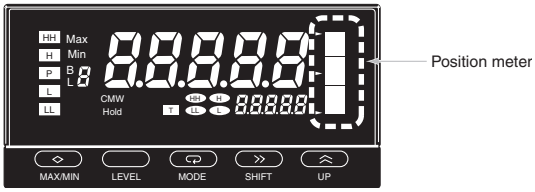
Features

Red-Green Display Allows Easy Recognition of Judgment Results

The measurement value display can be set to switch between red and green in accordance with the status of comparative outputs. This means that the status can be easily seen at a distance.

Position Meter Enables Easy Monitoring of Operating Status Trends

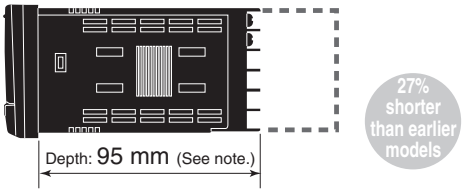
The present value with respect to the measurement or display range (full scale) can be viewed on a bar display. The operating status can be grasped intuitively, allowing easy judgment of levels and threshold values.



Note: This function is different from the single-LED display of the K3HB-C.

Short Body with Depth of Only 95 mm (from Behind the Front Panel)

A short body of only 95 mm (see note) contributes to the development of slimmer and smaller control panels and installations.



(The depth is 100 mm when mounted to the terminal cover.)

Note: Depth of DeviceNet models is 97 mm.

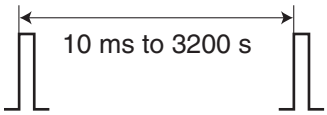
50 kHz High-speed Pulse Measurement (K3HB-R)

Supports high-speed pulse measurement (up to 50 kHz) of rotary encoders or any ON/OFF pulse signal, which enables rotational measurement of objects rotating at high speeds.

Note: No-voltage contacts of up to 30 Hz are supported.

Measurement of Wide Range of Pulse Interval Times (K3HB-P)

Measures and displays the results of the pulse interval between two points. The pulse interval measurement range is broad, from 10 ms to 3,200 s.



High-speed Up/Down Counting Pulse Measurement (K3HB-C)

Perfect for high-speed measurement of rotary encoders or any ON/OFF pulse signals. Cumulative pulse input is 50 kHz, quadrature pulse inputs are 25 kHz, and up/down pulse inputs are 30 kHz.

Note: No-voltage contacts of up to 30 Hz are supported.

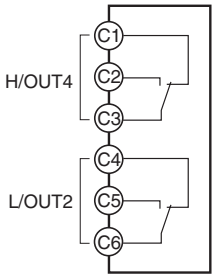
Features

Many I/O Variations for Discrimination, Control, and Information Applications

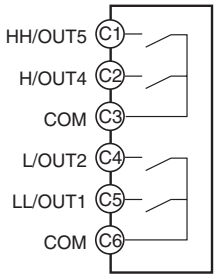
Digital Indicators are used in a wide variety of applications, from an electronic measurement value display or equipment/device operating status display to a host communications interface in monitoring and control systems. OMRON provides a complete lineup for a variety of input and control output applications to meet all your application requirements.

Relay Outputs

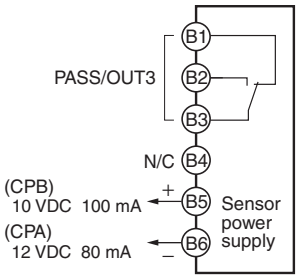
H and L: SPDT



HH, H, L, and LL: SPST-NO

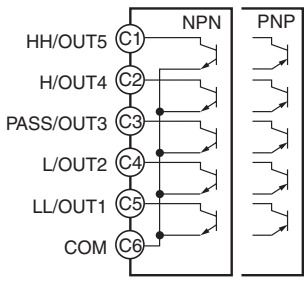


PASS: SPDT



Transistor Outputs

NPN or PNP



Communications Output

RS-232 or RS-485

RS-232C or RS-485

Linear Output

Voltage Output or Current Output

0 to 20 mA DC/
4 to 20 mA DC
or
0 to 5 VDC/
1 to 5 VDC/
0 to 10 VDC

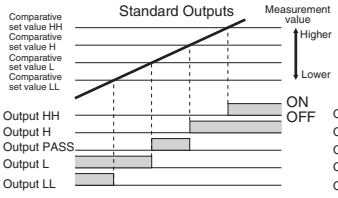
DeviceNet

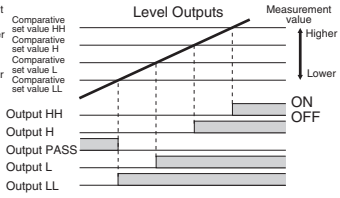
BCD Output

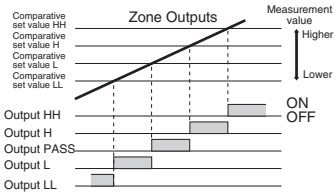
NPN Open Collector

Select a Comparative Output Pattern to Suit the Discrimination or Control Application

- The output pattern for comparative outputs can be selected. In addition to high/low comparison with set values, output based on level changes is also possible. (Use the type of output pattern appropriate for the application.)



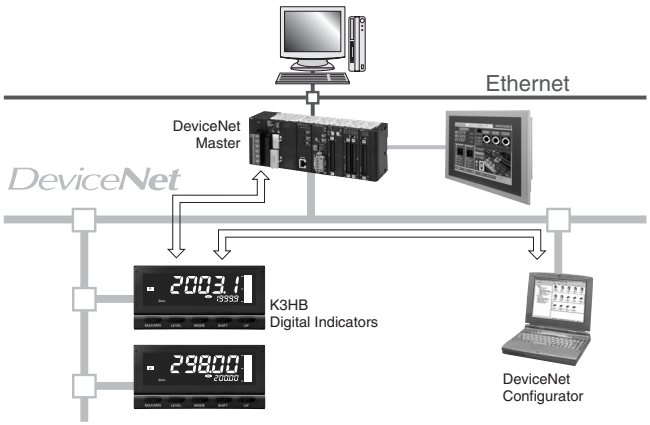




Note: The HH, H, L or LL outputs must be set in that order for the zone outputs to output correctly.
(This is because the comparative set values and outputs for standard and level outputs are in a 1-to-1 relationship, whereas the meaning of zone outputs depends on the settings of all the comparative set values.)

Lineup Includes DeviceNet Models Enabling High-speed Data Communications with PLCs without Special Programming

- DeviceNet compliance enables high-speed data transmission by allocating setting and monitoring parameters in the I/O memory of the PLC. This capability greatly reduces labor spent in developing communications programs.



Note: The applications provided in this catalog are intended as reference only. Do not attempt to use any of them in real systems without first confirming machine and device functions and safety. For applications that require safety, ensure that there is sufficient leeway in ratings and performances, install fail-safe measures, and take any other safety measures required by the application. In addition, contact your nearest OMRON representative and confirm specifications.

K3HB-series Product Lineup

■ K3HB-R Rotary Pulse Indicator (Page 4)

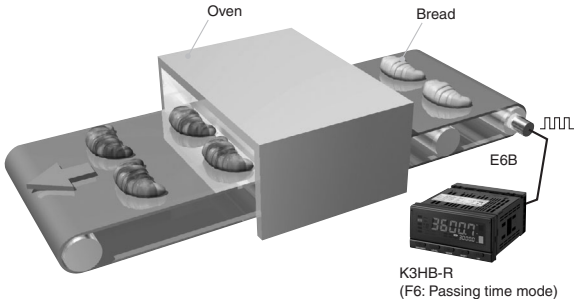
Performs High-speed Rotation Measurement and Passing Time Measurement

Rotary Pulse Input Model: K3HB-R

K3HB-RNB: NPN input/voltage pulse input
K3HB-RPB: PNP input

- Input types: rpm/circumferential speed, absolute ratio, error ratio, error, concentration, and passing time
- Measurement range: 0.5 mHz to 50 kHz

Displaying Bread Baking Time



■ K3HB-P Time Interval Indicator (Page 10)

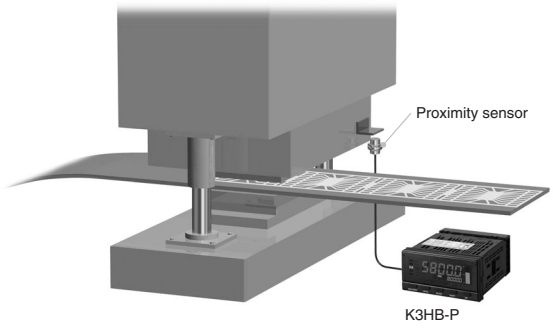
Measuring Passing Speed between Two Points and Providing Time Judgments

Pulse Input Model: K3HB-P

K3HB-PNB: NPN input/voltage pulse input
K3HB-PPB: PNP input

- Inputs: Passing speed, cycle, time difference, time band, measuring length, interval
- Measurement ranges: Functions F1, F3, and F4: 10 ms to 3200 s
  Function F2: 20 ms to 3200 s
  Functions F5 and F6: 0 to 4 gigacounts

Measuring Shot Speed



■ K3HB-C Up/Down Counting Pulse Indicator (Page 15)

Measuring and Monitoring High-speed Up/Down Pulses

Up/down Counting Pulse Input Model: K3HB-C

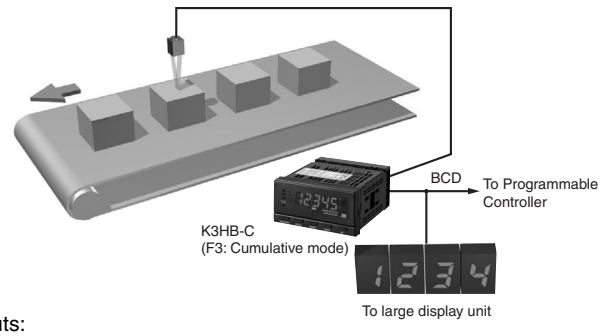
K3HB-CNB: NPN input/voltage pulse input

- Inputs: Individual inputs (up/down), quadrature inputs (up/down), cumulative input
- Response frequency: Individual inputs: 30 kHz, quadrature inputs: 25 kHz, cumulative input: 50 kHz

Note: No-voltage contacts of up to 30 Hz are supported.

- Measurement ranges: Functions F1 and F2: ±2 gigacounts
  Function F3: 0 to 4 gigacounts

Counting Workpieces



Rotary Pulse Indicator
K3HB-R

Digital Rotary Pulse Meter Capable of 50 kHz Measurements

- Measures High-speed Pulses at 50 kHz.
  Provides high-speed pulse measurements up to 50 kHz of rotary encoder or ON/OFF pulse signals and can perform rotating measurement of high-speed rotating objects.

Note: No-voltage contacts of up to 30 Hz are supported.

- Six Measurement Operations Including Rotation (rpm)/ Circumferential Speed, Ratio, and Cumulative
  One Rotary Pulse Meter has 6 rotary pulse measurement functions to support a variety of pulse measurement applications. Select the best function for your application from the following: rotation (rpm)/ circumferential speed, absolute ratio, error ratio, error, flow rate ratio, and passing time.

NEW

⚠ Refer to *Common Precautions* on page 30.

Model Number Structure

■ Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets.

Base Units

K3HB-R □ □□□□
1 5

1. Input Sensor Codes
NB: NPN input/voltage pulse input
PB: PNP input

5. Supply Voltage
100-240 VAC:100 to 240 VAC
24 VAC/VDC: 24 VAC/VDC

Optional Board

Sensor Power Supply/Output Boards

K33-□
2

Relay/Transistor Output Boards

K34-□
3

Event Input Boards

K35-□
4

Base Units with Optional Boards

K3HB-R□-□□□ □□□□
1 2 3 4 5

2. Sensor Power Supply/Output Type Codes
None: None
CPA: Relay output (PASS: SPDT) + Sensor power supply (12 VDC±10%, 80 mA) (See note 1.)
L1A: Linear current output (DC0(4)-20 mA) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
L2A: Linear voltage output (DC0(1)-5 V, 0 to 10 V) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
A: Sensor power supply (12 VDC ±10%, 80 mA)
FLK1A: Communications (RS-232C) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
FLK3A: Communications (RS-485) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)

3. Relay/Transistor Output Type Codes
None: None
C1: Relay contact (H/L: SPDT each)
C2: Relay contact (HH/H/LL/L: SPST-NO each)
T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
BCD: BCD output + transistor output (NPN open collector: HH/H/PASS/L/LL)
DRT: DeviceNet (See note 2.)

4. Event input Type Codes
None: None
1: 5 points (M3 terminal blocks) NPN open collector
2: 8 points (10-pin MIL connector) NPN open collector
3: 5 points (M3 terminal blocks) PNP open collector
4: 8 points (10-pin MIL connector) PNP open collector

Note: 1. CPA can be combined with relay outputs only.
2. Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, BCD communications, or DeviceNet communications.

Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs with 8-pin connector)
K32-BCD: Special BCD Output Cable

Specifications

■ Ratings

Supply voltage		100 to 240 VAC, 24 VAC/VDC, DeviceNet power supply: 24 VDC
Allowable power supply voltage range		85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC
Power consumption (See note 1.)		100 to 240 VAC: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)
Current consumption		DeviceNet power supply: 50 mA max. (24 VDC)
Input		No-voltage contact, voltage pulse, open collector
External power supply		12 VDC ±10%, 80 mA (models with external power supply only)
Event inputs (See note 2.)	**Startup compensation timer input**	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max. ON current at 0 Ω: 4 mA max. Max. applied voltage: 30 VDC max. OFF leakage current: 0.1 mA max.
	Hold input	
	Reset input	
	Bank input	
Output ratings (depends on the model)	**Relay output**	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations
	Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 μA max.
	Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA: Load: 500 Ω max, Resolution: Approx. 10,000, Output error: ±0.5% FS Linear output 0 to 5 VDC, 1 to 5 VDC, 0 to 10 VDC: Load: 5 kΩ max, Resolution: Approx. 10,000, Output error: ±0.5% FS (1 V or less: ±0.15 V; not output for 0 V or less)
Display method		Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green))
Main functions		Scaling function, measurement operation selection, averaging, previous average value comparison, output hysteresis, output OFF delay, output test, teaching, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset
Ambient operating temperature		−10 to 55°C (with no icing or condensation)
Ambient operating humidity		25% to 85%
Storage temperature		−25 to 65°C (with no icing or condensation)
Altitude		2,000 m max.
Accessories		Watertight packing, 2 fixtures, terminal cover, unit stickers, instruction manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)

Note: 1. DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.

2. PNP input types are also available.

3. For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

■ Characteristics

Display range		−19,999 to 99,999
Measurement accuracy (at 23±5°C)		Functions F1, F6: ±0.006% rgd ±1 digit (for voltage pulse/open collector sensors) Functions F2 to F5: ±0.02% rgd ±1 digit (for voltage pulse/open collector sensors)
Measurement range		Functions F1 to F6: 0.5 mHz to 50 kHz (for voltage pulse/open collector sensors)
Input signals		No-voltage contact (30-Hz max. with ON/OFF pulse width of 15 ms min.) Voltage pulse (50-KHz max. with ON/OFF pulse width of 9 μs min.; ON voltage: 4.5 to 30 V; OFF voltage: −30 to 2 V; input impedance: 10 kΩ) Open collector (50-KHz max. with ON/OFF pulse width of 9 μs min.)
Connectable sensors		ON residual voltage: 3 V max. OFF leakage current: 1.5 mA max. Load current: Must have a switching capacity of 20 mA or higher. Must be able to properly switch load currents of 5 mA or less.
Comparative output response time (transistor output)		Functions F1 to F6: 100 ms max. (time until the comparative output is made when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)
Linear output response time		Functions F1 to F6: 110 ms max. (time until the final analog output value is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%.)
Insulation resistance		20 MΩ min. (at 500 VDC)
Dielectric strength		2,300 VAC for 1 min between external terminals and case
Noise immunity		100 to 240 VAC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 μs/100 ns) 24 VAC/VDC models: ±1,500 V at power supply terminals in normal or common mode (waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)
Vibration resistance		Frequency: 10 to 55 Hz; Acceleration: 50 m/s^2, 10 sweeps of 5 min each in X, Y, and Z directions
Shock resistance		150 m/s^2 (100 m/s^2 for relay outputs) 3 times each in 3 axes, 6 directions
Weight		Approx. 300 g (Base Unit only)
Degree of protection	**Front panel**	Conforms to NEMA 4X for indoor use (equivalent to IP66)
	Rear case	IP20
	Terminals	IP00 + finger protection (VDE0106/100)
Memory protection		EEPROM (non-volatile memory) Number of rewrites: 100,000
Applicable standards		UL61010C-1, CSA C22.2 No. 1010.1 (evaluated by UL) EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II EN61326: 1997, A1: 1998, A2: 2001
EMC		EMI: EN61326+A1 industrial applications Electromagnetic radiation interference CISPR 11 Group 1, Class A: CISPRL16-1/-2 Terminal interference voltage CISPR 11 Group 1, Class A: CISPRL16-1/-2 EMS: EN61326+A1 industrial applications Electrostatic Discharge Immunity EN61000-4-2: 4 kV (contact), 8 kV (in air) Radiated Electromagnetic Field Immunity EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4 to 2 GHz) Electrical Fast Transient/Burst Immunity EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line) Surge Immunity EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line) Conducted Disturbance Immunity EN61000-4-6: 3 V (0.15 to 80 MHz) Power Frequency Magnetic Immunity EN61000-4-8: 30 A/m (50 Hz) continuous time Voltage Dips and Interruptions Immunity EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)

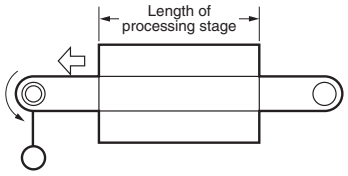
Operation

■ Functions (Operating Modes)

F1 to F6

Functions F1 to F6 provide rpm/circumferential speed and other calculation displays by measuring continuous pulses (frequencies).

Example



Function name	Function No.
Rpm/circumferential speed	F1
Absolute ratio	F2
Error ratio	F3
Rotational difference	F4
Flow rate ratio	F5
Passing time	F6

F1: Displays rotation (rpm) or circumferential speed for one input.

F2 to F5: Displays the calculation result for two rotation (rpm) speeds.

F6: Displays the passing time calculated from the circumferential speed and the length of the processing stage for one input.

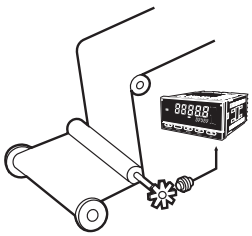
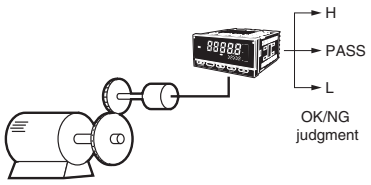
The basic principle used by the Digital Indicator to calculate the rotation speed (rpm) display is to count the ON/OFF time (T) for input sensor or other device inputs using the internal system clock, and then automatically calculate the frequency. This frequency (f) is multiplied by 60 and displayed as the rotation (rpm) speed.

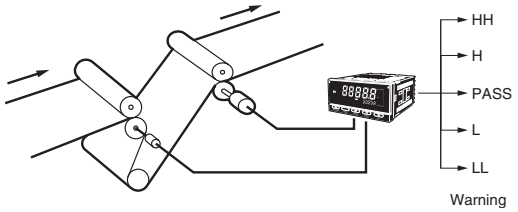
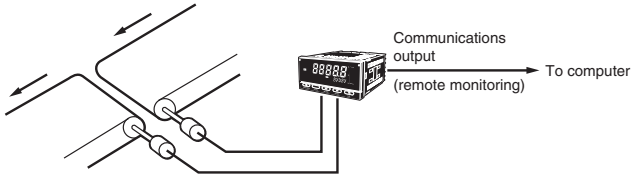
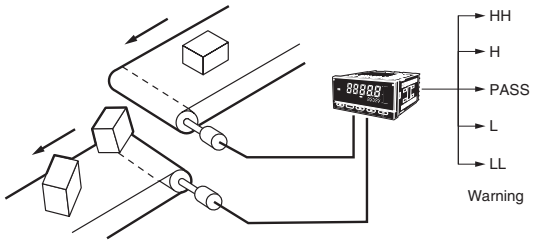
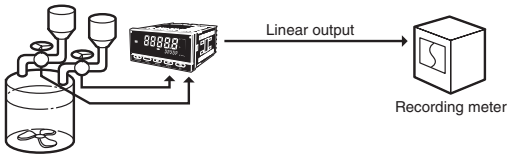
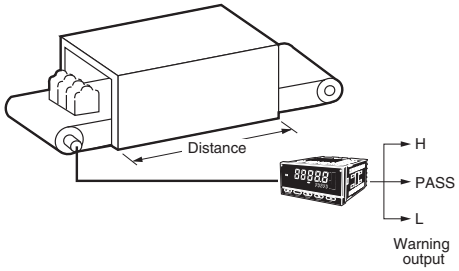
Input sensor or other input pulse ON/OFF time (T) = 

Frequency (f) = $\frac{1}{T}$

- Rotation speed (rpm) = f × 60
- Circumferential speed = Roll circumference × Rotation speed (rpm)
- Passing time= $\frac{\text{Length of processing stage}}{\text{Circumferential speed}}$

These calculations are automatically made internally and displayed whenever any input pulse is received.

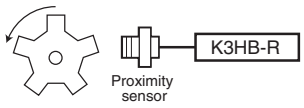
<table>
<tr><th>Function</th><th>Operation</th><th>Operation image (application)</th></tr>
<tr><td>F1
Rpm/circumferential speed/
Instantaneous flowrate</td><td>Measures frequency for input A and displays the rotation (rpm) or circumferential speed proportional to the input frequency.
<table>
<tr><th>Calculation</th><th>Display unit</th><th>Prescale value (α)</th></tr>
<tr><td rowspan="2">Rotation speed</td><td>rpm</td><td>1/N</td></tr>
<tr><td>rps</td><td>1/60 N</td></tr>
<tr><td rowspan="2">Frequency (of input pulse)</td><td>Hz</td><td>1/60</td></tr>
<tr><td>kHz</td><td>1/60000</td></tr>
<tr><td rowspan="5">Circumferential speed</td><td>mm/s</td><td>1000 πd/60 N</td></tr>
<tr><td>cm/s</td><td>100 πd/60 N</td></tr>
<tr><td>m/s</td><td>πd/60 N</td></tr>
<tr><td>m/min</td><td>πd/N</td></tr>
<tr><td>km/h</td><td>0.06 πd/N</td></tr>
<tr><td rowspan="2">Instantaneous flowrate</td><td>ℓ/min</td><td rowspan="2">Check the output specifications of the input device and calculate the prescale value from the following equation:
Display value D = fa × 60 × α</td></tr>
<tr><td>ℓ/h</td></tr>
</table>
N = Pulses per rotation
πd = Circumferential length per rotation</td><td>Measuring roller winding speed
 
Measuring motor speed (for product testing)
 
</td></tr>
</table>

Function	Operation	Operation image (application)
F2 Absolute ratio	Multiples input B divided by input A ($\frac{B}{A}$) by 100 and displays the ratio as a percentage (%). Display unit: %	Measuring the speed ratio between two rollers 
F3 Error ratio	Multiplies the error between input A and input B ($\frac{B}{A}-1$) by 100 and displays the ratio as a percentage (%). Display unit: %	Measuring the line speed error ratio between two conveyors 
F4 Rotational difference	Displays the difference between input A and input B (B - A) as the rotation (rpm) speed error or circumferential speed error. (Display unit: rpm, rps, rph, Hz, kHz, mm/s, m/s m/min, km/h l/min, l/h, etc.)	Measuring the rotation (rpm)/circumferential speed error (absolute error) between two conveyors 
F5 Flow rate ratio	Displays the flow rate ratio of B from inputs A and B ($\frac{B}{A+B}$) as a ratio (%). Display unit: %	Monitoring liquid mixture flow rate ratio 
F6 Passing time	Passing time (s) = $1/fa \times \alpha$ fa: Input frequency (Hz) Set the prescale value for the desired display unit using the following table for reference. N = Pulses per rotation πd = Circumferential length per rotation (m) L = Length of process (m)	Displaying the passing time for a conveyor line 

Calculation	Display unit	Prescale value (α)
Passing time	s	L/(πd/N)

■ What Is Prescaling?

To make calculations using the input pulse to display rotation (rpm) or circumferential speed, the number of pulses per rotation or the length of the circumference must be multiplied by a certain coefficient. This coefficient is called the prescale value.



Rotation speed (rpm) = f × 60 × a

f: Input pulse frequency (No. of pulses per second)

a: Prescale value

If there are 5 pulses per rotation, then

a = 1/5 (= 0.2 = 2×10^{-1})

and an accurate rotation speed (rpm) can be calculated.

The actual setting is X = 2.0000 (mantissa) and Y = 10^{-1} (exponent).

■ What Is the Auto-zero Function?

(Set this function before using the Digital Indicator.)

If a function F1 to F6 is set, the frequency can be force-set to zero if there is no input pulse for a set period. This period is called the auto-zero time. Set the auto-zero time to slightly longer than the longest input pulse interval. (The display will not easily return to zero if the auto-zero time is too long or left at the default setting.)

Time Unit Settings

Setting	Meaning
SCAL	Prescale value menu setting
oCLo	Minute display
H.oo.SS	h.mm.ss display
oo.SS.d	mm.ss.d display (d = tenths of a second)

Note: Time unit can be set only when passing time (F6) is selected.

Input Type Setting

	NO: Voltage pulse high	NC: Voltage pulse low
No-contact or voltage pulse input	00	01
Contact	10	11

Note: Set to 10 or 11 when there is a large variation in the display. The largest measurement range is 30 Hz.

Timer Interval Indicator
K3HB-P

Digital Time Interval Meter for Measuring Passing Speed, Time, or Cycle between Two Points.

- Measures Wide Range of Pulse Interval Times
  Measures, calculates, and displays pulse intervals between two points. Wide range for pulse interval measurements, from 10 ms to 3,200 s, max.
- Six Measurement Operations, Including Passing Speed, Time, and Cycle Measurement between Two Points
  One Digital Time Interval Meter has six measurement functions, to support a variety of pulse interval measurement applications. Select the best function for your application from the following: Passing speed, cycle, time difference, time band, measuring length, and interval.

NEW

⚠ Refer to *Common Precautions* on page 30.

Model Number Structure

■ Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets.

Base Units

K3HB-P □ □□□
1 5

1. Input Sensor Codes
NB: NPN input/voltage pulse input
PB: PNP input

5. Supply Voltage
100-240 VAC: 100 to 240 VAC
24 VAC/VDC: 24 VAC/VDC

Optional Board

Sensor Power Supply/Output Boards

K33-□
2

Relay/Transistor Output Boards

K34-□
3

Event Input Boards

K35-□
4

Base Units with Optional Boards

K3HB-P□-□□□ □□□
1 2 3 4 5

2. Sensor Power Supply/Output Type Codes
None: None
CPA: Relay output (PASS: SPDT) + Sensor power supply (12 VDC±10%, 80 mA) (See note 1.)
L1A: Linear current output (DC0(4)-20 mA) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
L2A: Linear voltage output (DC0(1)-5 V, 0 to 10 V) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
A: Sensor power supply (12 VDC ±10%, 80 mA)
FLK1A: Communications (RS-232C) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
FLK3A: Communications (RS-485) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)

3. Relay/Transistor Output Type Codes
None: None
C1: Relay contact (H/L: SPDT each)
C2: Relay contact (HH/H/LL/L: SPST-NO each)
T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
BCD: BCD output + transistor output (NPN open collector: HH/H/PASS/L/LL)
DRT: DeviceNet (See note 2.)

4. Event input Type Codes
None: None
1: 5 points (M3 terminal blocks) NPN open collector
2: 8 points (10-pin MIL connector) NPN open collector
3: 5 points (M3 terminal blocks) PNP open collector
4: 8 points (10-pin MIL connector) PNP open collector

Note: 1. CPA can be combined with relay outputs only.
2. Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, a linear output, or DeviceNet communications.

Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs with 8-pin connector)
K32-BCD: Special BCD Output Cable

Specifications

■ Ratings

Supply voltage		100 to 240 VAC, 24 VAC/VDC, DeviceNet power supply: 24 VDC
Allowable power supply voltage range		85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC
Power consumption (See note 1.)		100 to 240 VAC: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)
Current consumption		DeviceNet power supply: 50 mA max. (24 VDC)
Input		No-voltage, voltage pulse, open collector
External power supply		12 VDC 10%, 80 mA (for models with external power supplies only)
Event inputs (See note 2.)	**Hold input**	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max. ON current at 0 Ω: 4 mA max. Max. applied voltage: 30 VDC max. OFF leakage current: 0.1 mA max.
	Reset input	
	Bank input	
Output ratings (depends on the model)	**Relay output**	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations
	Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 μA max.
	Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA: Load: 500 Ω max, Resolution: Approx. 10,000, Output error: ±0.5% FS Linear output 0 to 5 VDC, 1 to 5 VDC, 0 to 10 VDC: Load: 5 kΩ max, Resolution: Approx. 10,000, Output error: ±0.5% FS (1 V or less: ±0.15 V; not output for 0 V or less)
Display method		Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green))
Main functions		Scaling function, measurement operation selection, output hysteresis, output OFF delay, output test, teaching, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset
Ambient operating temperature		−10 to 55°C (with no icing or condensation)
Ambient operating humidity		25% to 85%
Storage temperature		−25 to 65°C (with no icing or condensation)
Altitude		2,000 m max.
Accessories		Watertight packing, 2 fixtures, terminal cover, unit stickers, instruction manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)

Note: 1. DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.

2. PNP input types are also available.

3. For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

■ Characteristics

<table>
<tr><td colspan="2">Display range</td><td>−19,999 to 99,999</td></tr>
<tr><td colspan="2">Measurement accuracy (at 23±5°C)</td><td>±0.08% rgd ±1 digit (for voltage pulse/open collector sensors)</td></tr>
<tr><td colspan="2">Measurement range</td><td>Functions F1, F3, and F4: 10 ms to 3,200 s
Function F2: 20 ms to 3,200 s
Functions F5 and F6: 0 to 4 gigacounts</td></tr>
<tr><td colspan="2">Input signals</td><td>• No-voltage contact (30 Hz max. with ON/OFF pulse width of 15 ms min.)
•Voltage pulse
<table>
<tr><th>Mode</th><th>Input frequency range</th><th>ON/OFF pulse width</th><th>ON voltage</th><th>OFF voltage</th><th>Input impedance</th></tr>
<tr><td>F1 to F4</td><td>0 to 50 kHz</td><td>9 μs min.</td><td>4.5 to 30 V</td><td>−30 to 2 V</td><td>10 kΩ</td></tr>
<tr><td>F5, F6</td><td>0 to 30 kHz</td><td>16 μs min.</td><td></td><td></td><td></td></tr>
</table>
•Opencollector
<table>
<tr><th>Mode</th><th>Input frequency range</th><th>ON/OFF pulse width</th></tr>
<tr><td>F1 to F4</td><td>0 to 50 kHz</td><td>9 μs min.</td></tr>
<tr><td>F5, F6</td><td>0 to 30 kHz</td><td>16 μs min.</td></tr>
</table>
Note: The Digital Time Interval Meter will malfunction if a pulse greater than the input frequency range is input. SYSERR may appear on the display.</td></tr>
<tr><td colspan="2">Connectable sensors</td><td>ON residual voltage: 3 V max.
OFF leakage current: 1.5 mA max.
Load current: Must have a switching capacity of 20 mA or higher.
Must be able to properly switch load currents of 5 mA or less.</td></tr>
<tr><td colspan="2">Comparative output response time (transistor output)</td><td>2 ms max. (time until the comparative output is made when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%)</td></tr>
<tr><td colspan="2">Linear output response time</td><td>10 ms max. (time until the final analog output value is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%)</td></tr>
<tr><td colspan="2">Insulation resistance</td><td>20 MΩ min. (at 500 VDC)</td></tr>
<tr><td colspan="2">Dielectric strength</td><td>2,300 VAC for 1 min between external terminals and case</td></tr>
<tr><td colspan="2">Noise immunity</td><td>100 to 240 VAC models:
±1,500 V at power supply terminals in normal or common mode
(waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)
24 VAC/VDC models:
±1,500 V at power supply terminals in normal or common mode
(waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)</td></tr>
<tr><td colspan="2">Vibration resistance</td><td>Frequency: 10 to 55 Hz; Acceleration: 50 m/s², 10 sweeps of 5 min each in X, Y, and Z directions</td></tr>
<tr><td colspan="2">Shock resistance</td><td>150 m/s² (100 m/s² for relay outputs) 3 times each in 3 axes, 6 directions</td></tr>
<tr><td colspan="2">Weight</td><td>Approx. 300 g (Base Unit only)</td></tr>
<tr><td rowspan="3">Degree of protection</td><td>Front panel</td><td>Conforms to NEMA 4X for indoor use (equivalent to IP66)</td></tr>
<tr><td>Rear case</td><td>IP20</td></tr>
<tr><td>Terminals</td><td>IP00 + finger protection (VDE0106/100)</td></tr>
<tr><td colspan="2">Memory protection</td><td>EEPROM (non-volatile memory)
Number of rewrites: 100,000</td></tr>
<tr><td colspan="2">Applicable standards</td><td>UL61010C-1, CSA C22.2 No. 1010.1 (evaluated by UL)
EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II
EN61326: 1997, A1: 1998, A2: 2001</td></tr>
<tr><td colspan="2">EMC</td><td>EMI: EN61326+A1 industrial applications
Electromagnetic radiation interference
CISPR 11 Group 1, Class A: CISPRL16-1/-2
Terminal interference voltage
CISPR 11 Group 1, Class A: CISPRL16-1/-2
EMS: EN61326+A1 industrial applications
Electrostatic Discharge Immunity
EN61000-4-2: 4 kV (contact), 8 kV (in air)
Radiated Electromagnetic Field Immunity
EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4GHz to 2 GHz)
Electrical Fast Transient/Burst Immunity
EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line)
Surge Immunity
EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line)
Conducted Disturbance Immunity
EN61000-4-6: 3 V (0.15 to 80 MHz)
Power Frequency Magnetic Immunity
EN61000-4-8: 30 A/m (50 Hz) continuous time
Voltage Dips and Interruptions Immunity
EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)</td></tr>
</table>

Operation

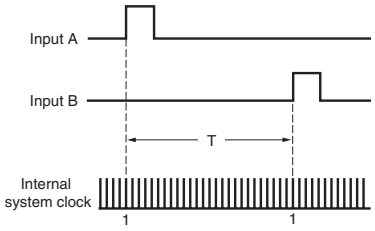
■ Functions (Operating Modes)

F1 to F6

These functions use the internal system clock to measure the time between pulses or the pulse ON time and then display time measurements or a variety of other calculations.

Function name	Function No.
Passing speed	F 1
Cycle	F2
Time difference	F3
Time band	F4
Measuring length	F5
Interval	F6

Example: F1 Passing Speed

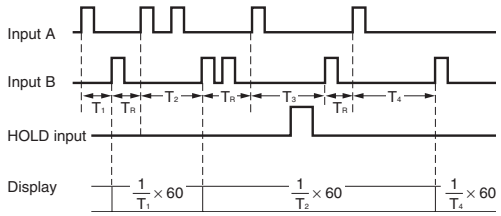
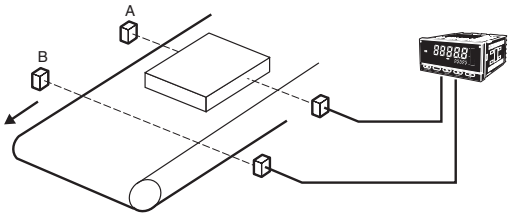
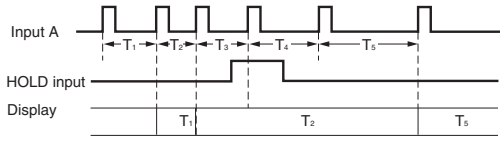
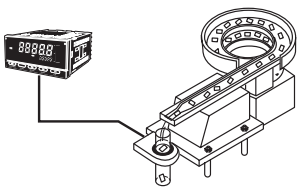
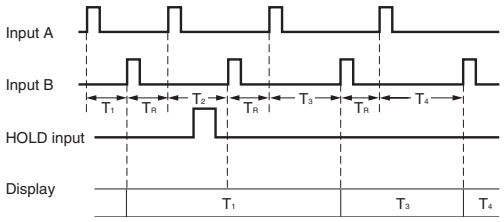
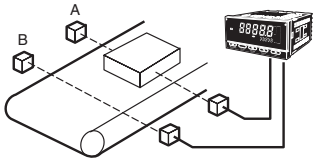
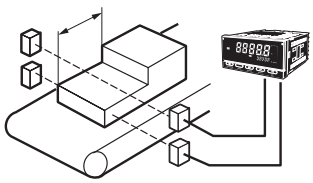


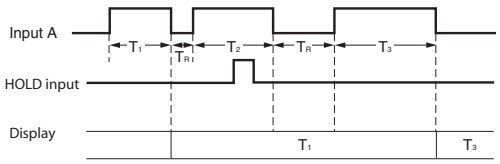
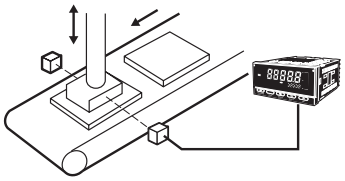
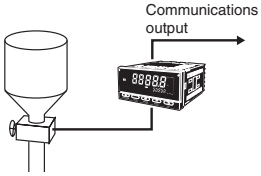
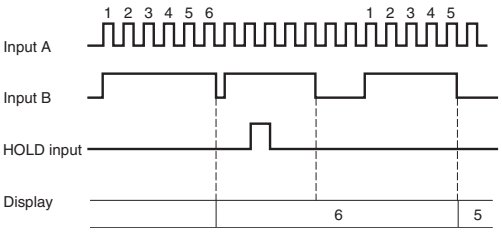
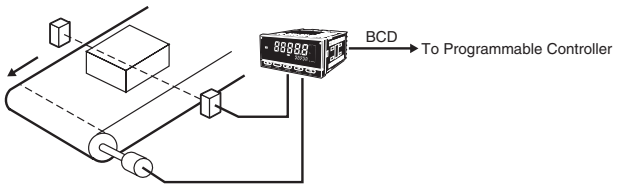
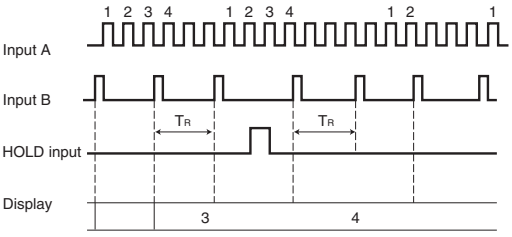
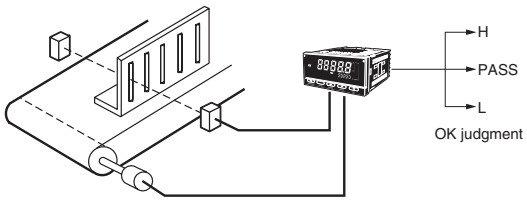
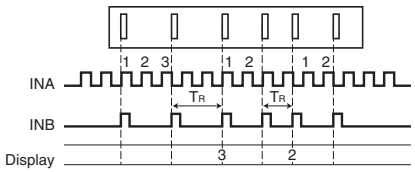
The time (T) between input A pulse and input B pulse is measured by the internal system clock. If, for example, the system clock measures 100,000 counts during time T, then

T = 1 system clock count (0.5 μs) × 100,000

T = 0.05 s

F1 (the passing speed) is calculated internally using the formula $\frac{1}{T} \times 60$ (m/min), and the display, in this example, would be $\frac{1}{0.05\,s} \times 60 =$ 1200 (m/min).

Function	Operation	Operation image (application)
F1 Passing speed	The reciprocal of the time (T) from input A ON to input B ON is multiplied by 60 and displayed.  • Recovery time (T_R) of 20 ms is required before starting the next measurement. (Display unit: mm/s, m/s m/min, km/h, etc.)	Measuring workpiece passing speed between A and B 
F2 Cycle	Measures and displays input A cycle (T).  Measurement range: 20 ms to 3,200 s (Display unit: ms, s, min., min.s.1/10 s)	Measuring feed cycles for parts 
F3 Time difference	Displays the time (T) from input A ON to input B ON.  Measurement range: 10 ms to 3,200 s • Recovery time (TR) of 20 ms is required before starting the next measurement. (Display unit: ms, s, min., min.s.1/10 s)	Measuring workpiece passing time between A and B  Measuring the length of a workpiece step by changing prescale values. 

Function	Operation	Operation image (application)
F4 Time band	Displays input A ON time (T).  Measurement range: 10 ms to 3,200 s • Recovery time (TR) of 20 ms is required before starting the next measurement. (Display unit: ms, s, min., min.s.1/10 s)	Monitoring the ON time of a printing press  Managing the valve release time 
F5 Measuring length	Displays the number of input A pulses while input B is ON.  • Recovery time (TR) of 20 ms is required before starting the next measurement. (Display unit: mm, cm, m, etc.)	Measuring workpiece length 
F6 Interval	Displays the number of input A pulses from when input B turns ON until input B turns ON again. Measurement is made every other time input B turns ON.  • Recovery time (TR) of 20 ms is required before starting the next measurement. (Display unit: mm, cm, m, etc.)	Measuring slit intervals  

■ What Is Prescaling?

To make calculations using the input pulse to display the passing speed between two points, the distance between the two points and the display unit must be set and the internally measured time multiplied by a certain coefficient. This coefficient is called the prescale value. (For information on settings details, refer to the User's Manual.)

Time Unit Settings

Setting	Meaning
SCAL	Prescale value menu setting
mi.n	Minute display
H.mm.SS	h.mm.ss display
mm.SS.d	mm.ss.d display (d = tenths of a second)

Input Type Setting

	NO: Voltage pulse high	NC: Voltage pulse low
No-contact or voltage pulse input	00	01
Contact	10	11

Note: Set to 10 or 11 when there is a large variation in the display. The largest measurement range is 30 Hz.

Up/Down Counting Pulse Indicator
K3HB-C

Measure High-speed Up/down Pulses with this Up/down Pulse Meter.

- Perfect for Measuring Rotary Encoder and ON/OFF Pulse Signals at High Speed

  Cumulative pulse input is 50 kHz, quadrature pulse inputs are 25 kHz, and up/down pulse inputs are 30 kHz.

Note: No-voltage contacts of up to 30 Hz are supported.

- The count value can be converted to any value.

  The length equivalent for any pulse can be set to any desired value.

  This is effective for feed amount and position monitor displays.

⚠ Refer to *Common Precautions* on page 30.

NEW

Model Number Structure

■ Model Number Legend

Base Units and Optional Boards can be ordered individually or as sets.

Base Units

K3HB-C □ □□□
1 5

1. **Input Sensor Codes**
   NB: NPN input/voltage pulse input
   PB: PNP input
5. **Supply Voltage**
   100-240 VAC: 100 to 240 VAC
   24 VAC/VDC: 24 VAC/VDC

Optional Board

Sensor Power Supply/Output Boards

K33-□
2

Relay/Transistor Output Boards

K34-□
3

Event Input Boards

K35-□
4

Base Units with Optional Boards

K3HB-C□-□□□ □□□
1 2 3 4 5

2. **Sensor Power Supply/Output Type Codes**
   None: None
   CPA: Relay output (PASS: SPDT) + Sensor power supply (12 VDC±10%, 80 mA) (See note 1.)
   L1A: Linear current output (DC0(4)-20 mA) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
   L2A: Linear voltage output (DC0(1)-5 V, 0 to 10 V) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
   A: Sensor power supply (12 VDC ±10%, 80 mA)
   FLK1A: Communications (RS-232C) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
   FLK3A: Communications (RS-485) + Sensor power supply (12 VDC±10%, 80 mA) (See note 2.)
3. **Relay/Transistor Output Type Codes**
   None: None
   C1: Relay contact (H/L: SPDT each)
   C2: Relay contact (HH/H/LL/L: SPST-NO each)
   T1: Transistor (NPN open collector: HH/H/PASS/L/LL)
   T2: Transistor (PNP open collector: HH/H/PASS/L/LL)
   BCD: BCD output + transistor output (NPN open collector: HH/H/PASS/L/LL)
   DRT: DeviceNet (See note 2.)
4. **Event input Type Codes**
   None: None
   1: 5 points (M3 terminal blocks) NPN open collector
   2: 8 points (10-pin MIL connector) NPN open collector
   3: 5 points (M3 terminal blocks) PNP open collector
   4: 8 points (10-pin MIL connector) PNP open collector

Note: 1. CPA can be combined with relay outputs only.
2. Only one of the following can be used by each Digital Indicator: RS-232C/RS-485 communications, a linear output, or DeviceNet communications.

Accessories (Sold Separately)

K32-DICN: Special Cable (for event inputs with 8-pin connector)
K32-BCD: Special BCD Output Cable

Specifications

■ Ratings

Supply voltage		100 to 240 VAC, 24 VAC/VDC, DeviceNet power supply: 24 VDC
Allowable power supply voltage range		85% to 110% of the rated power supply voltage, DeviceNet power supply: 11 to 25 VDC
Power consumption (See note 1.)		100 to 240 VAC: 18 VA max. (max. load) 24 VAC/DC: 11 VA/7 W max. (max. load)
Current consumption		DeviceNet power supply: 50 mA max. (24 VDC)
Input		No-voltage, voltage pulse, open collector
External power supply		12 VDC±10% 80 mA
Event inputs	**Hold input**	NPN open collector or no-voltage contact signal ON residual voltage: 2 V max. ON current at 0 Ω: 4 mA max. Max. applied voltage: 30 VDC max. OFF leakage current: 0.1 mA max.
	Reset input	
	Bank input	
Output ratings (depends on the model)	**Relay output**	250 VAC, 30 VDC, 5 A (resistive load) Mechanical life expectancy: 5,000,000 operations, Electrical life expectancy: 100,000 operations
	Transistor output	Maximum load voltage: 24 VDC, Maximum load current: 50 mA, Leakage current: 100 μA max.
	Linear output	Linear output 0 to 20 mA DC, 4 to 20 mA: Load: 500 Ω max, Resolution: Approx. 10,000, Output error: ±0.5% FS Linear output 0 to 5 VDC, 1 to 5 VDC, 0 to 10 VDC: Load: 5 kΩ max, Resolution: Approx. 10,000, Output error: ±0.5% FS (1 V or less: ±0.15 V; not output for 0 V or less)
Display method		Negative LCD (backlit LED) display 7-segment digital display (Character height: PV: 14.2 mm (green/red); SV: 4.9 mm (green))
Main functions		Scaling function, measurement operation selection, output hysteresis, output OFF delay, output test, display value selection, display color selection, key protection, bank selection, display refresh period, maximum/minimum hold, reset
Ambient operating temperature		−10 to 55°C (with no icing or condensation)
Ambient operating humidity		25% to 85%
Storage temperature		−25 to 65°C (with no icing or condensation)
Altitude		2,000 m max.
Accessories		Watertight packing, 2 fixtures, terminal cover, unit stickers, instruction manual. DeviceNet models also include a DeviceNet connector (Hirose HR31-5.08P-5SC(01)) and crimp terminals (Hirose HR31-SC-121) (See note 3.)

Note: 1. DC power supply models require a control power supply capacity of approximately 1 A per Unit when power is turned ON. Particular attention is required when using two or more DC power supply models. The OMRON S8VS-series DC Power Supply Unit is recommended.

2. For K3HB-series DeviceNet models, use only the DeviceNet Connector included with the product. The crimp terminals provided are for Thin Cables.

■ Characteristics

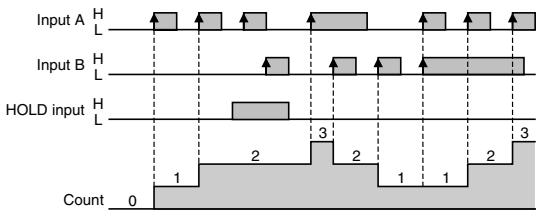
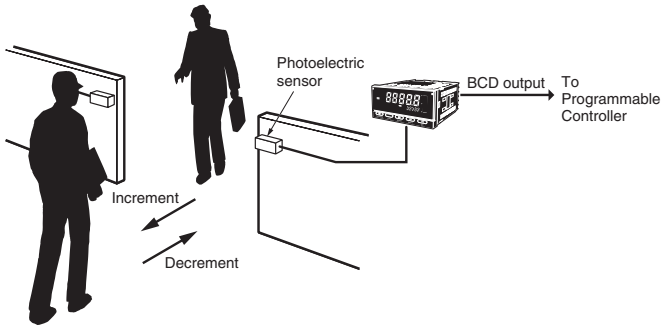
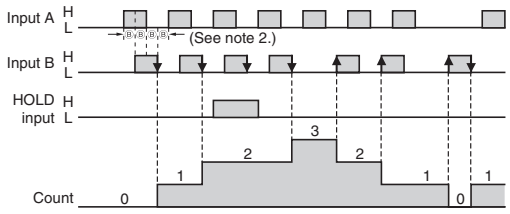
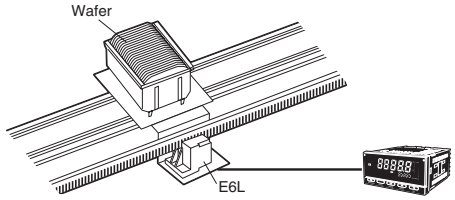
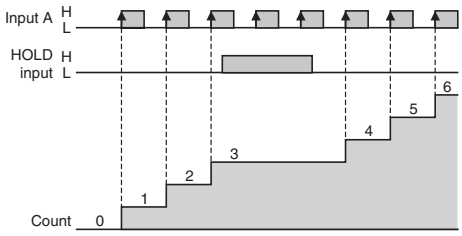
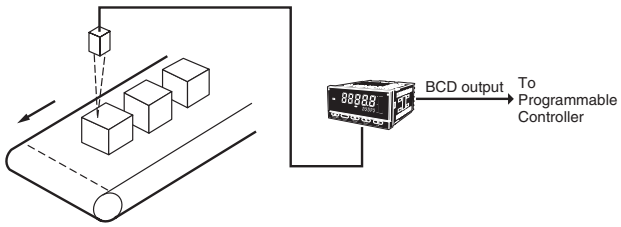
<table>
<tr><td colspan="2">Display range</td><td>–19,999 to 99,999</td></tr>
<tr><td colspan="2">Measurement range</td><td>Functions F1, F2: ±2 gigacounts
Functions F3 : 0 to 4 gigacounts</td></tr>
<tr><td colspan="2">Input signals</td><td>• No-voltage contact (30 Hz max. with ON/OFF pulse width of 15 ms min.)
• Voltage pulse
<table>
<tr><th>Mode</th><th>Input frequency range</th><th>ON/OFF pulse width</th><th>ON voltage</th><th>OFF voltage</th><th>Input impedance</th></tr>
<tr><td>F1</td><td>0 to 30 kHz</td><td>16 μs min.</td><td rowspan="3">4.5 to 30 V</td><td rowspan="3">–30 to 2 V</td><td rowspan="3">10 kΩ</td></tr>
<tr><td>F2</td><td>0 to 25 kHz</td><td>20 μs min.</td></tr>
<tr><td>F3</td><td>0 to 50 kHz</td><td>9 μs min.</td></tr>
</table>
• Open collector
<table>
<tr><th>Mode</th><th>Input frequency range</th><th>ON/OFF pulse width</th></tr>
<tr><td>F1</td><td>0 to 30 kHz</td><td>16 μs min.</td></tr>
<tr><td>F2</td><td>0 to 25 kHz</td><td>20 μs min.</td></tr>
<tr><td>F3</td><td>0 to 50 kHz</td><td>9 μs min.</td></tr>
</table>
Note: The Up/Down Counting Pulse Meter will malfunction if a pulse greater than the input frequency range is input. SYSERR may appear on the display.</td></tr>
<tr><td colspan="2">Connectable sensors</td><td>ON residual voltage: 3 V max.
OFF leakage current: 1.5 mA max.
Load current: Must have a switching capacity of 20 mA or higher.
Must be able to properly switch load currents of 5 mA or less.</td></tr>
<tr><td colspan="2">Max. No. of display digits</td><td>5 (–19999 to 99999)</td></tr>
<tr><td colspan="2">Comparative output response time</td><td>1 ms max.: Transistor output; 10 ms max.: Relay contact output
(time until the comparative output is made when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%)</td></tr>
<tr><td colspan="2">Linear output response time</td><td>10 ms max. (time until the final analog output value is reached when there is a forced sudden change in the input signal from 15% to 95% or 95% to 15%)</td></tr>
<tr><td colspan="2">Insulation resistance</td><td>20 MΩ min. (at 500 VDC)</td></tr>
<tr><td colspan="2">Dielectric strength</td><td>2,300 VAC for 1 min between external terminals and case</td></tr>
<tr><td colspan="2">Noise immunity</td><td>100 to 240 VAC models:
±1,500 V at power supply terminals in normal or common mode
(waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)
24 VAC/VDC models:
±1,500 V at power supply terminals in normal or common mode
(waveform with 1-ns rising edge and pulse width of 1 μs/100 ns)</td></tr>
<tr><td colspan="2">Vibration resistance</td><td>Frequency: 10 to 55 Hz; Acceleration: 50 m/s^2, 10 sweeps of 5 min each in X, Y, and Z directions</td></tr>
<tr><td colspan="2">Shock resistance</td><td>150 m/s^2 (100 m/s^2 for relay outputs) 3 times each in 3 axes, 6 directions</td></tr>
<tr><td colspan="2">Weight</td><td>Approx. 300 g (Base Unit only)</td></tr>
<tr><td rowspan="3">Degree of protection</td><td>Front panel</td><td>Conforms to NEMA 4X for indoor use (equivalent to IP66)</td></tr>
<tr><td>Rear case</td><td>IP20</td></tr>
<tr><td>Terminals</td><td>IP00 + finger protection (VDE0106/100)</td></tr>
<tr><td colspan="2">Memory protection</td><td>EEPROM (non-volatile memory)
Number of rewrites: 100,000</td></tr>
<tr><td colspan="2">Applicable standards</td><td>UL61010C-1, CSA C22.2 No. 1010.1 (evaluated by UL)
EN61010-1 (IEC61010-1): Pollution degree 2/Overvoltage category II
EN61326: 1997, A1: 1998, A2: 2001</td></tr>
<tr><td colspan="2">EMC</td><td>EMI: EN61326+A1 industrial applications
Electromagnetic radiation interference
CISPR 11 Group 1, Class A: CISPRL16-1/-2
Terminal interference voltage
CISPR 11 Group 1, Class A: CISPRL16-1/-2
EMS: EN61326+A1 industrial applications
Electrostatic Discharge Immunity
EN61000-4-2: 4 kV (contact), 8 kV (in air)
Radiated Electromagnetic Field Immunity
EN61000-4-3: 10 V/m 1 kHz sine wave amplitude modulation (80 MHz to 1 GHz, 1.4 to 2 GHz)
Electrical Fast Transient/Burst Immunity
EN61000-4-4: 2 kV (power line), 1 kV (I/O signal line)
Surge Immunity
EN61000-4-5: 1 kV with line (power line), 2 kV with ground (power line)
Conducted Disturbance Immunity
EN61000-4-6: 3 V (0.15 to 80 MHz)
Power Frequency Magnetic Immunity
EN61000-4-8: 30 A/m (50 Hz) continuous time
Voltage Dips and Interruptions Immunity
EN61000-4-11: 0.5 cycle, 0°/180°, 100% (rated voltage)</td></tr>
</table>

Operation

■ Functions (Operating Modes)

F1 to F3

Function name	Function No.
Individual inputs	F1
Phase differential inputs	F2
Pulse counting input	F3

Function	Operation	Operation image (application)
F1 Individual inputs	Counts input A as incremental pulses and input B as decremental pulses. The count is incremented on the rising edge of input A and decremented on the rising edge of input B. If both inputs rise at the same time, the count is not changed. The count is incremented when input B is later than input A and decremented when input B is earlier than input A. 	Counting the number of people entering an area 
F2 Phase differential inputs	This function is normally used when connected to an incremental rotary encoder. The count is incremented on the falling edge of input B when input A is OFF. The count is decremented on the rising edge of input B when input A is OFF. 	Detecting position and speed on a semiconductor wafer conveyor line 
F3 Pulse counting input	Counted on the rising edge of input A 	Counting the number of workpieces 

Note: 1. Meaning of H and L in Display

Symbol / Input method	No-voltage input
H	Short-circuit
L	Open

2. Requires at least half the minimum signal width. If there is less than half, a ±1 count error may occur.

Input Type Setting

	NO: Voltage pulse high	NC: Voltage pulse low
No-contact or voltage pulse input	00	01
Contact	10	11

■ What Is Prescaling?

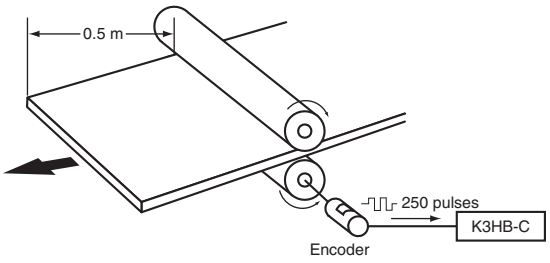
Prescaling converts the count value to any numeric value.

To display □□□□.□ mm in a system that outputs 250 pulses for a 0.5-m feed,

the length per pulse = 500 mm (0.5 m) ÷ 250 = 2.

1. The prescale value for the K3HB-C is set using the mantissa X × exponent Y, so the prescale value = 2.0000 × 10°,
X = 2.000, and Y = 00.

2. Next, set the decimal point position for one digit to the right of the decimal point: ₀₀₀₀.₀



Common Specifications

■ Event Input Ratings

K3HB-R	S-TMR, HOLD, RESET, BANK1, BANK2, BANK4	
K3HB-P/-C	HOLD, RESET, BANK1, BANK2, BANK4	
Contact	ON: 1 kΩ max., OFF: 100 kΩ min.	
No-contact	ON residual voltage:	2 V max.
	OFF leakage current:	0.1 mA max.
	Load current:	4 mA max.
	Maximum applied voltage:	30 VDC max.

■ Output Ratings

Contact Output

Item	Resistive loads (250 VAC, cosϕ=1; 30 VDC, L/R=0 ms)	Inductive loads (250 VAC, closed circuit, cosϕ=0.4; 30 VDC, L/R=7 ms)
Rated load	5 A at 250 VAC 5 A at 30 VDC	1 A at 250 VAC 1 A at 30 VDC
Rated through current	5 A	
Mechanical life expectancy	5,000,000 operations	
Electrical life expectancy	100,000 operations	

Transistor Outputs

Maximum load voltage	24 VDC
Maximum load current	50 mA
Leakage current	100 μA max.

Linear Output

Item / Outputs	0 to 20 mA	4 to 20 mA	0 to 5 V	1 to 5 V	0 to 10 V
Allowable load impedance	500 Ω max.		5 kΩ min.		
Resolution	Approx. 10,000				
Output error	±0.5% FS		±0.5% FS (±0.15 V for 1 V or less and no output for 0 V)		

Serial Communications Output

Item / Type	RS-232C, RS-485
Communications method	Half duplex
Synchronization method	Start-stop synchronization (asynchronous)
Baud rate	9600/19200/38400 bps
Transmission code	ASCII
Data length	7 bits or 8 bits
Stop bit length	2 bits or 1 bit
Error detection	Vertical parity and FCS
Parity check	Odd, even

BCD Output I/O Ratings (Input Signal Logic: Negative)

I/O signal name			Item		Rating
Inputs	**K3HB-R/P** REQUEST HOLD MAX MIN RESET	**K3HB-C** REQUEST COMPEN-SATION RESET	Input signal		No-voltage contact input
			Input current for no-voltage input		10 mA
			Signal level	ON voltage	1.5 V max.
				OFF voltage	3 V min.
Outputs	DATA POLARITY OVER DATA VALID RUN		Maximum load voltage		24 VDC
			Maximum load current		10 mA
			Leakage current		100 μA max.
	K3HB-R/P HH H PASS L LL	**K3HB-C** OUT1 OUT2 OUT3 OUT4 OUT5	Maximum load voltage		24 VDC
			Maximum load current		50 mA
			Leakage current		100 μA max.

Refer to the *K3HB Communications User's Manual* (Cat. No. N129) for details on serial and DeviceNet communications.

DeviceNet Communications

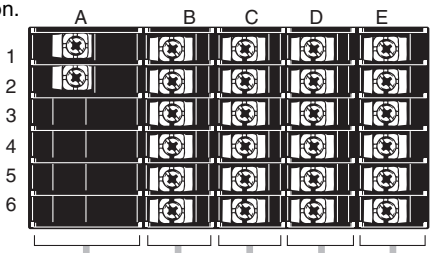
<table>
<tr><td colspan="2">Communications protocol</td><td>Conforms to DeviceNet</td></tr>
<tr><td rowspan="3">Supported communications</td><td>Remote I/O communications</td><td>Master-Slave connection (polling, bit-strobe, COS, cyclic)
Conforms to DeviceNet communications standards.</td></tr>
<tr><td>I/O allocations</td><td>Allocate any I/O data using the Configurator.
Allocate any data, such as DeviceNet-specific parameters and variable area for Digital Indicators.
Input area: 2 blocks, 60 words max.
Output area: 1 block, 29 words max.
(The first word in the area is always allocated for the Output Execution Enabled Flags.)</td></tr>
<tr><td>Message communications</td><td>Explicit message communications
CompoWay/F communications commands can be executed
(using explicit message communications)</td></tr>
<tr><td colspan="2">Connection methods</td><td>Combination of multi-drop and T-branch connections (for trunk and drop lines)</td></tr>
<tr><td colspan="2">Baud rate</td><td>DeviceNet: 500, 250, or 125 Kbps (automatic follow-up)</td></tr>
<tr><td colspan="2">Communications media</td><td>Special 5-wire cable (2 signal lines, 2 power supply lines, 1 shield line)</td></tr>
<tr><td colspan="2">Communications distance</td><td>
<table>
<tr><th>Baud rate</th><th>Network length (max.)</th><th>Drop line length (max.)</th><th>Total drop line length (max.)</th></tr>
<tr><td>500 Kbps</td><td>100 m max.
(100 m max.)</td><td>6 m max.</td><td>39 m max.</td></tr>
<tr><td>250 Kbps</td><td>100 m max.
(250 m max.)</td><td>6 m max.</td><td>78 m max.</td></tr>
<tr><td>125 Kbps</td><td>100 m max.
(500 m max.)</td><td>6 m max.</td><td>156 m max.</td></tr>
</table>
The values in parentheses are for Thick Cable.
</td></tr>
<tr><td colspan="2">Communications power supply</td><td>24-VDC DeviceNet power supply</td></tr>
<tr><td colspan="2">Allowable voltage fluctuation range</td><td>11 to 25-VDC DeviceNet power supply</td></tr>
<tr><td colspan="2">Current consumption</td><td>50 mA max. (24 VDC)</td></tr>
<tr><td colspan="2">Maximum number of nodes</td><td>64 (DeviceNet Configurator is counted as one node when connected.)</td></tr>
<tr><td colspan="2">Maximum number of slaves</td><td>63</td></tr>
<tr><td colspan="2">Error control checks</td><td>CRC errors</td></tr>
<tr><td colspan="2">DeviceNet power supply</td><td>Supplied from DeviceNet communications connector</td></tr>
</table>

Connections

■ External Connection Diagrams

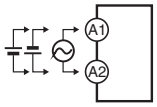
Terminal Arrangements

Note: Refer to “Internal Block Diagram” on page 24 for information on isolation.



A Operating Power Supply

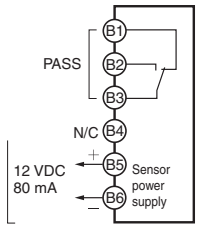
100 to 240 VAC
24 VAC/VDC



*Check the required power supply type.

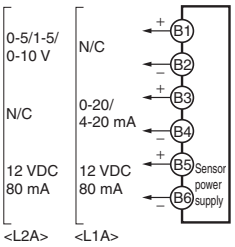
B Sensor Power Supply/Output

Sensor power supply + PASS output



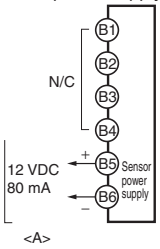
<CPA>

Sensor power supply + linear output



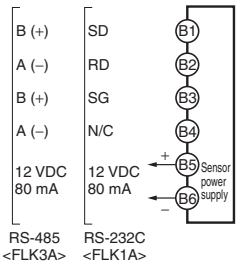
<L2A> <L1A>

Sensor power supply



<A>

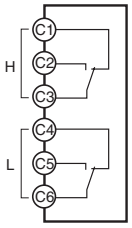
Sensor power supply + communications



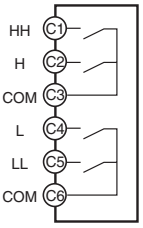
RS-485 <FLK3A>
RS-232C <FLK1A>

C Relays, Transistors, BCD and DeviceNet

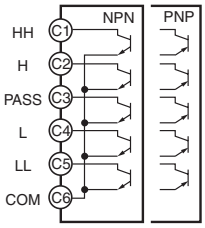
Relay Outputs <C1>



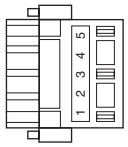
Relay Outputs <C2>



Transistor Outputs <T1> <T2>



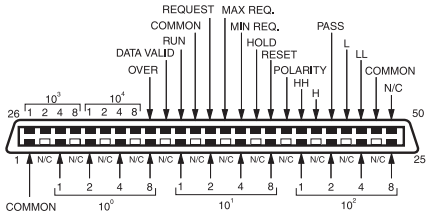
DeviceNet Connector (Included) <DRT>



1: V– (Power supply cable: Black)
2: CAN L (Communications cable: Blue)
3: Shield
4: CAN H (Communications cable: White)
5: V+ (Power supply cable: Red)
Applicable Connector:
HR31-5.08P-5SC (01)
(HIROSE ELECTRIC CO., LTD.)
* Attach the provided crimp terminals.

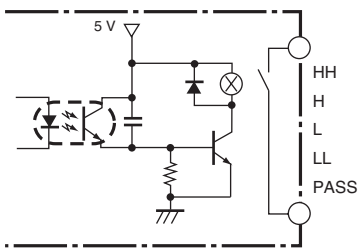
BCD (NPN Open Collector): <BCD>
Applicable Connector (Sold separately)
HDR-E50MAG1
(HONDA TSUSHIN KOGYO CO., LTD.)
Special Cable (Sold separately)
K32-BCD (OMRON)
(HDR-E50MAG1 with 0.3-m cable)

The BCD COMMON is shared.
The pins indicated in the above diagram as blank (white) boxes have been removed.

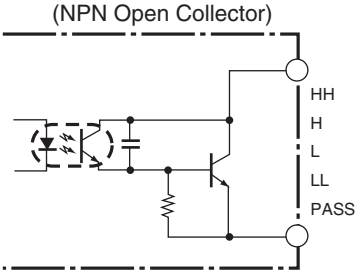


*Only one of the following can be used for each Digital Indicator: communications, BCD, or DeviceNet.

Contact Outputs



Transistor Outputs (NPN Open Collector)



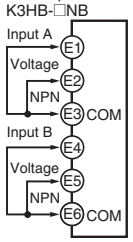
Safety Standards Conformance

- Always use a EN/IEC-compliant power supply with reinforced insulation or double insulation for the DeviceNet power supply.
- The product must be used indoors for the above applicable standards to apply.

E Pulse Inputs

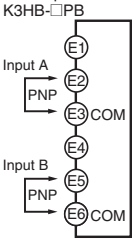
- Rotary Pulse Meter: K3HB-R
- Timer Interval Meter: K3HB-P
- Up/Down Counting Pulse Meter: K3HB-C

NPN Input: K3HB-□NB



Note: E3 and E6, as well as B6, are internally connected.

PNP Input: K3HB-□PB

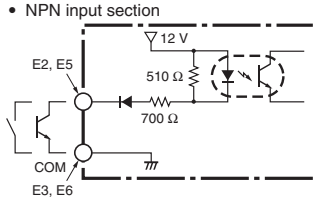


Note: E3 and E6, as well as B5, are internally connected.

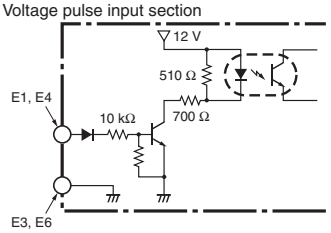
K3HB-R
K3HB-P
K3HB-C

NPN Input Model

- NPN input section

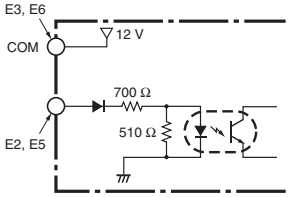


- Voltage pulse input section



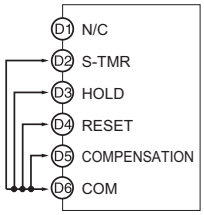
K3HB-R
K3HB-P

PNP Input Model

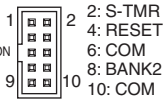


D Event Inputs

Models with Terminal Blocks <1> <3>



Models with Connectors <2> <4>

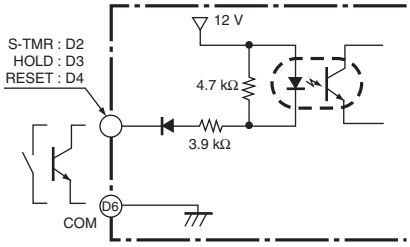


1: N/C
3: HOLD
5: COMPENSATION
7: BANK4
9: BANK1
2: S-TMR
4: RESET
6: COM
8: BANK2
10: COM

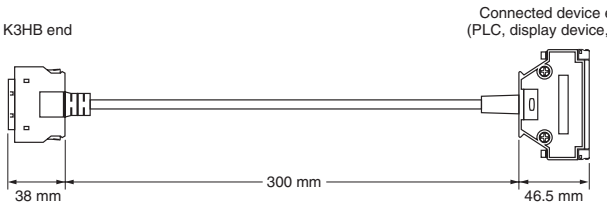
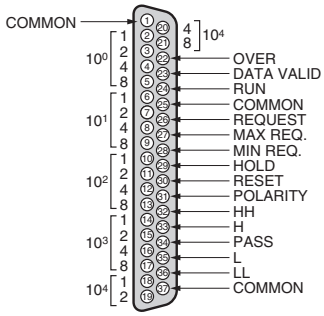
- Applicable Connector (Sold separately)
  XG4M-1030 (OMRON)
- Special Cable (Sold separately)
  K32-DICN (OMRON)
  (XG4M-1030 with 3-m cable)

The following signals depend on the model:
S-TMR: Used by the K3HB-R only.
COMPENSATION: Used by the K3HB-C only.

- Use terminal pin D6 as the common terminal.
- Use NPN open collector or no-voltage contacts for event input.
  PNP types are also available.



BCD Output Cable

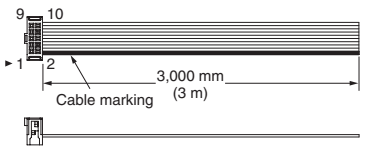
Model	Shape	Pin arrangement
K32-BCD		

Cover: HDR-E50LPA5
(manufactured by Honda Tsushin Co., Ltd)
Connector: HDR-E50MAG1
(manufactured by Honda Tsushin Co., Ltd)

D-sub connector (37-pin female)
Cover: 17JE-37H-1A (manufactured by DDK)
Connector: Equivalent to 17JE-13370-02
(manufactured by DDK)
Stand: 17L-002A (manufactured by DDK)

Note: The BCD Output Cable has a D-sub plug. Cover: 17JE-37H-1A (manufactured by DDK); Connector: equivalent to 17JE-23370-02 (D1) (manufactured by DDK)

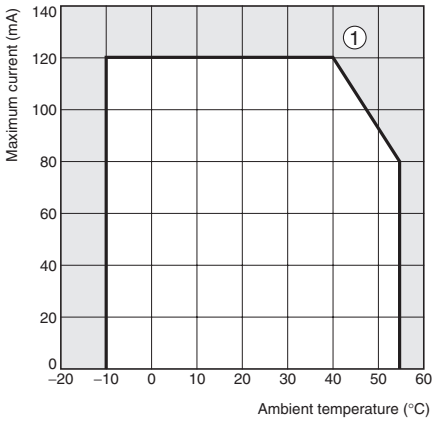
Special Cable (for Event Inputs with 8-pin Connector)

Model	Appearance	Wiring
K32-DICN		See table below

Pin No.	Signal name
1	N/C
2	S-TMR
3	HOLD
4	RESET
5	N/C
6	COM
7	BANK4
8	BANK2
9	BANK1
10	COM

■ Derating Curve for Sensor Power Supply (Reference Values)

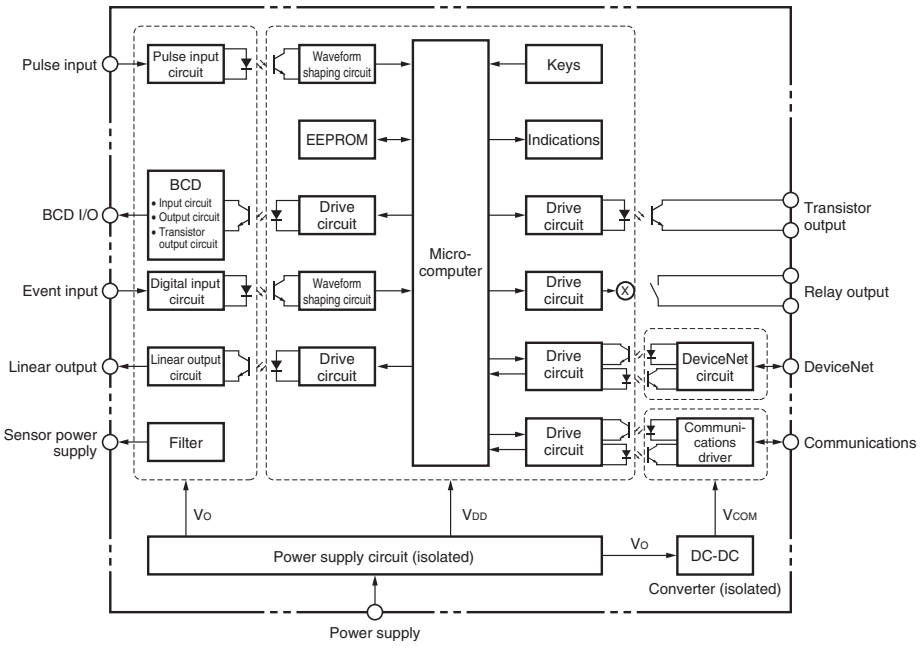
For 12V



Note: 1. The above values were obtained under test conditions with the standard mounting. The derating curve will vary with the mounting conditions, so be sure to adjust accordingly.

2. Internal components may be deteriorated or damaged. Do not use the Digital Indicator outside of the derating range (i.e., do not use it in the area labeled (1), above).

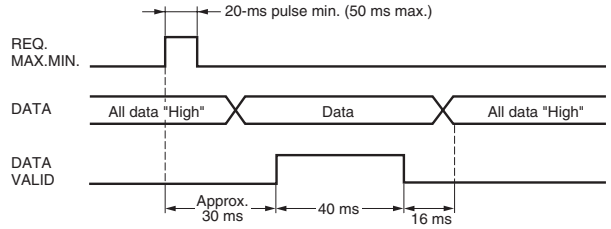
■ Internal Block Diagram



■ BCD Output Timing Chart

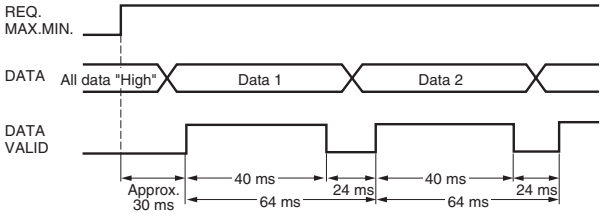
A REQUEST signal from a Programmable Controller or other external device is required to read BCD data.

Single Sampling Data Output



The data is set in approximately 30 ms from the rising edge of the REQUEST signal and the DATA VALID signal is output.
When reading the data from a Programmable Controller, start reading the data when the DATA VALID signal turns ON.
The DATA VALID signal will turn OFF 40 ms later, and the data will turn OFF 16 ms after that.

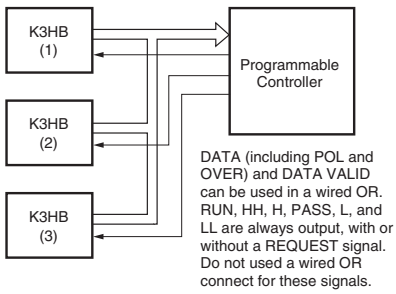
Continuous Data Output

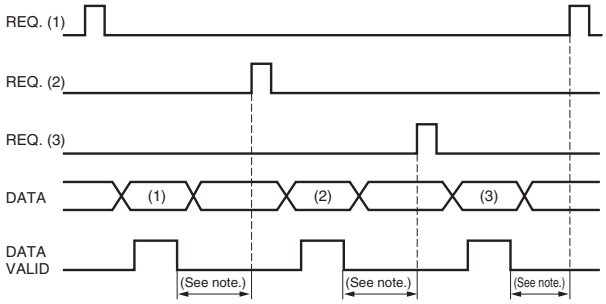


Measurement data is output every 64 ms while the REQUEST signal remains ON.

Note: If HOLD is executed when switching between data 1 and data 2, either data 1 or data 2 is output depending on the timing of the hold signal. The data will not go LOW.

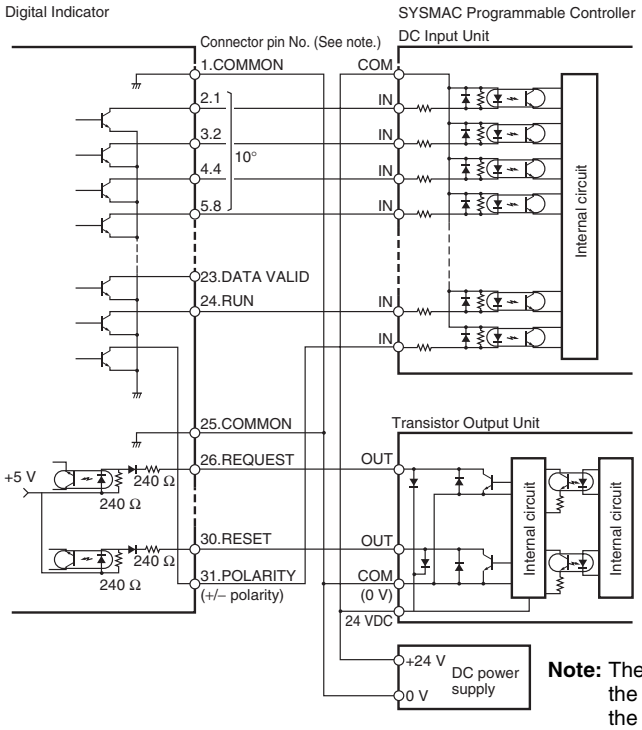
• The K3HB BCD output model has an open collector output, so wired OR connection is possible



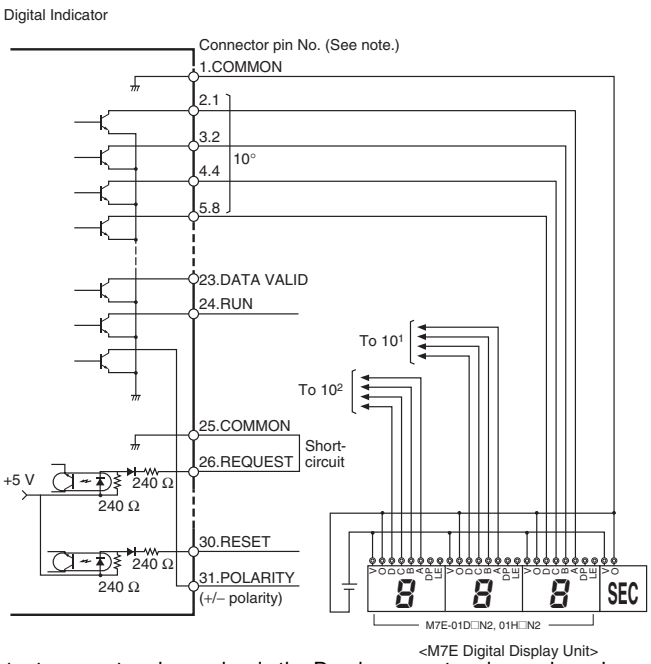


Note: Leave 20 ms min. between DATA VALID turning OFF and the REQUEST signal.

Programmable Controller Connection Example



Display Unit Connection Example



<M7E Digital Display Unit>

Note: The BCD output connector pin number is the D-sub connector pin number when the BCD Output Cable (sold separately) is connected. This number differs from the pin number for the Digital Indicator narrow pitch connector (manufactured by Honda Tsushin Kogyo Co., Ltd.).

Refer to the following User's Manual for application precautions and other information required when using the Digital Indicator:
K3HB-R/P/C Digital Indicator User's Manual (Cat. No. N136)
The manual can be downloaded from the following site in PDF format: OMRON Industrial Web http://www.fa.omron.co.jp

■ Component Names and Functions

Max./Min. status indicator

Turns ON when the maximum value or minimum value is displayed in the RUN level.

Level/bank display

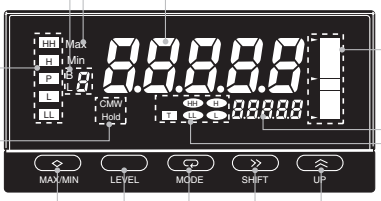
In RUN level, displays the bank if the bank function is ON. (Turns OFF if the bank function is OFF.)
In other levels, displays the current level.

Comparative output status indicators

Display the status of comparative outputs.

Status indicators

Display	Function
CMW	Lit when communications writing is ON (enabled) and not lit when OFF (prohibited).
Hold	Turns ON/OFF when hold input turns ON/OFF.



PV display

Displays PVs, maximum values, minimum values, parameter names, and error names.

Position meter

Displays the position of the PV with respect to a desired scale.

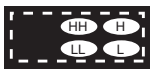
SV display

Displays SV and monitor values.

SV display status indicators

K3HB-R

Indicator	Function
T	Turns ON when parameters for which teaching can be performed are displayed.
HH, H, L, LL	In RUN level, turn ON when the comparative set value HH, H, L, or LL is displayed.



K3HB-P

Indicator	Function
HH, H, L, LL	In RUN level, turn ON when the comparative set value HH, H, L, or LL is displayed.

K3HB-C

Indicator	Function
T	Turns ON when parameters for which teaching can be performed are displayed.
5, 4, 3, 2, 1	In RUN level, turn ON when the comparative set value 1, 2, 3, 4, or 5 is displayed.

MAX/MIN Key

Used to switch the display between the PV, maximum value, and minimum value and to reset the maximum and minimum values.

LEVEL Key

Used to switch level.

MODE Key

Used to switch the parameters displayed.

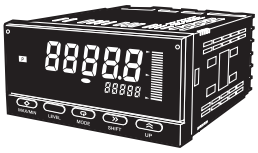
SHIFT Key

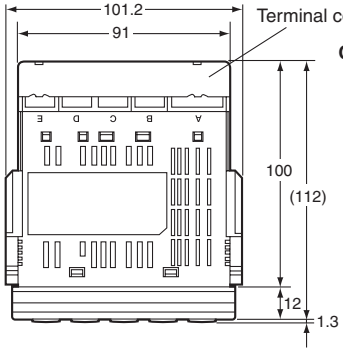
Used to change parameter settings. When changing a set value, this key is used to move along the digits.

UP Key

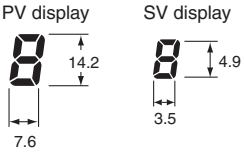
When changing a set value, this key is used to change the actual value.
When a measurement value is displayed, this key is used to execute or clear the forced-zero function or to execute teaching.

■ Dimensions

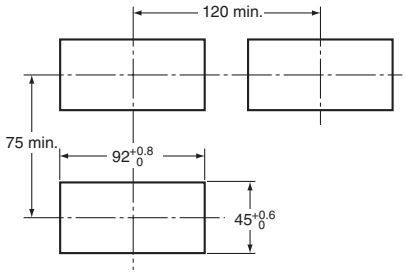


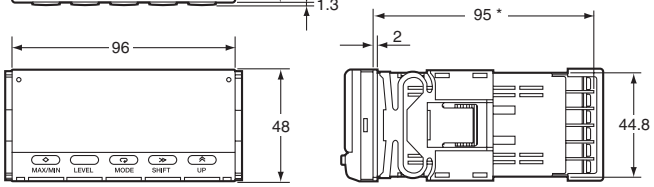


Character Size for Main Display (mm)



Panel Cutout Dimensions





*DeviceNet models: 97 mm

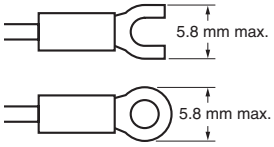
Terminal: M3, Terminal Cover: Accessory

Wiring Precautions

- For terminal blocks, use the crimp terminals suitable for M3 screws.
- Tighten the terminal screws to the recommended tightening torque of approx. 0.5 N·m.
- To prevent inductive noise, separate the wiring for signal lines from that for power lines.

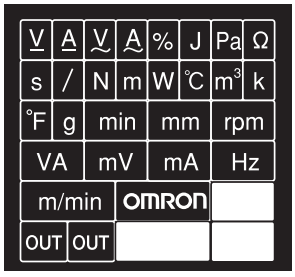
Wiring

- Use the crimp terminals suitable for M3 screws shown below.



Unit Stickers (included)

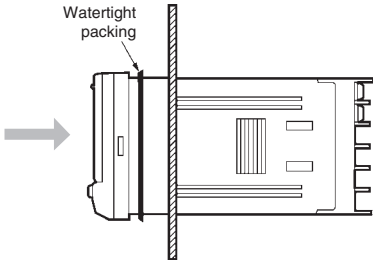
- No unit stickers are attached to the Digital Indicator.
- Select the appropriate units from the unit sticker sheets provided.



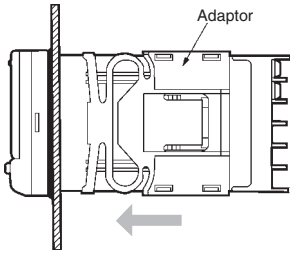
Note: For measurements for commercial purposes, be sure to use the unit required by any applicable laws or regulations.

Mounting Method

1. Insert the K3HB into the mounting cutout in the panel.
2. Insert watertight packing around the Unit to make the mounting watertight.

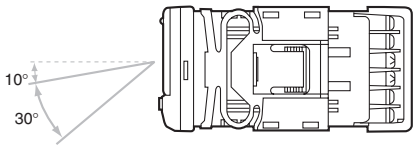


3. Insert the adapter into the grooves on the left and right sides of the rear case and push until it reaches the panel and is fixed in place.



LCD Field of Vision

The K3HB is designed to have the best visibility at the angles shown in the following diagram.



Waterproof Packing

The waterproof packing ensures a level of waterproofing that conforms to NEMA 4X. Depending on the operating environment, deterioration, contraction, or hardening may occur and replacement may be necessary. In this case, consult your OMRON representative.

Main Functions

■ Main Functions and Features

Measurement

Function FUnC R P C

The K3HB-R has the following six functions for receiving and displaying input pulses.

F1: Rotation (rpm)/circumferential speed

F2: Absolute ratio

F3: Error ratio

F4: Rotational difference

F5: Flow rate ratio

F6: Passing time

The K3HB-P has the following six functions for receiving and displaying input pulses.

F1: Passing speed

F2: Cycle

F3: Time difference

F4: Time band

F5: Measuring length

F6: Interval

The K3HB-C has the following three functions for receiving and displaying input pulses.

F1: Individual inputs

F2: Phase differential inputs

F3: Pulse counting input

Filters

Average Processing AuG-t, AuG-n R

Average processing of input signals with extreme changes or noise smooths out the display and makes control stable.

Input Types in-tA, in-tb R P
in-tA C

Specify the types of sensor connected to input A and input B.

Input Compensation

Auto-zero Times AtZA, AtZb R

The frequency is forced to zero if there is no pulse input for a set period.

Input Compensation CoMPn, Co̅M̅-P C

The display can be changed to a preset compensation value using the compensation input.

Key Operations

Teaching R C

The present measurement value can be used as a scaling value.

Key Protection R P C

Key protection restricts level or parameter changes using the keys to prevent unintentional key operations and malfunctions.

Outputs

Comparative Output Pattern oUt-P R P C

Standard, zone, and level comparative output patterns can be selected for comparative outputs.

Hysteresis HYS R

Prevents comparative outputs from chattering when the measurement value fluctuates slightly near the set value.

Output Refresh Stop o-StP R P

Holds the output status when a comparative result output other than PASS turns ON.

PASS Output Change PASS R P

Comparative results other than PASS and error signals can be output from the PASS output terminal.

Output OFF Delay oFF-d R P C

Delays turning OFF comparatives for a set period. This can be used to provide sufficient time to read the comparative output ON status when the comparative result changes at short intervals.

Shot Output SHot R P C

Turns ON the comparative output for a specific time.

Output Logic oUt-n R P C

Reverses the output logic of comparative results.

Startup Compensation Timer S-tnr R

Measurements can be stopped for a set time using an external input.

Output Test tESt R P C

Output operation can be checked without using actual input signals by using the keys to set a test measurement value.

Linear Outputs LSEtC, LSEtv, LSEtH, LSEtL R P C

A current or voltage proportional to the change in the measurement value can be output.

Standby Sequence Stdby R P

The comparison outputs can be kept OFF until the measurement value enters the PASS range.

Display

Display Value Selection diSP R P C

The display value can be set to the present value, the maximum value, or the minimum value.

Display Color Selection CoLor R P C

The present value display color can be set to green or red. The color of the present value can also be switched according to the comparative output.

Display Refresh Period drEF R P C

When the input changes rapidly, the display refresh period can be lengthened to control flickering and make the display easier to read.

Position Meter Po5-t, Po5-H, Po5-L R P C

The present measurement value can be displayed as a position in relation to the scaling width on a 20-gradation position meter.

Prescale P5.Au, P5.AY, P5.bu, P5.bY R P C

The input signal can be converted and displayed as any value.

Comparative Set Value Display Su.dSP R P C

Select whether or not to display the comparative value during operation.

Display auto-return rEt R P C

Automatically returns the display to RUN level when there are no key operations (e.g., max./min. switching, bank settings using keys).

Other

Max./Min. Hold R P

Holds the maximum and minimum measurement values.

Bank Selection bnK-C R P C

Switch between 8 comparative value banks using the keys on the front panel or external inputs. A set of set comparative values can be selected as a group.

Bank Copy CoPY R P C

Any bank settings can be copied to all banks.

Interruption Memory nEno C

The measured value can be recorded when the power supply is interrupted.

User Calibration R P C

The K3HB can be calibrated by the user.

Common Precautions

■ Precautions

⚠ WARNING

Do not touch the terminals while power is being supplied. Doing so may possibly result in electric shock. Make sure that the terminal cover is installed before using the product.

Always provide protective circuits in the network. Without protective circuits, malfunctions may possibly result in accidents that cause serious injury or significant property damage. Provide double or triple safety measures in external control circuits, such as emergency stop circuits, interlock circuits, or limit circuits, to ensure safety in the system if an abnormality occurs due to malfunction of the product or another external factor affecting the product's operation.

⚠ CAUTION

Do not allow pieces of metal, wire clippings, or fine metallic shavings or filings from installation to enter the product. Doing so may occasionally result in minor electric shock, fire, or malfunction.

Do not use the product in locations where flammable or explosive gases are present. Doing so may occasionally result in minor or moderate explosion, causing minor or moderate injury, or property damage.

Do not attempt to disassemble, repair, or modify the product. Doing so may occasionally result in minor or moderate injury due to electric shock.

Do not use the equipment for measurements within Measurement Categories II, III or IV (according to IEC61010-1). Doing so may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment. Use the equipment for measurements only within the Measurement Category for which the product is designed.

Perform correct setting of the product according to the application. Failure to do so may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment.

Ensure safety in the event of product failure by taking safety measures, such as installing a separate monitoring system. Product failure may occasionally prevent operation of comparative outputs, resulting in damage to the connected facilities and equipment.

Tighten the screws on the terminal block and the connector locking screws securely using a tightening torque within the following ranges. Loose screws may occasionally cause fire, resulting in minor or moderate injury, or damage to the equipment.

Terminal block screws: 0.43 to 0.58 N·m

Connector locking screws: 0.18 to 0.22 N·m

Make sure that the product will not be adversely affected if the DeviceNet cycle time is lengthened as a result of changing the program with online editing. Extending the cycle time may cause unexpected operation, occasionally resulting in minor or moderate injury, or damage to the equipment.

Before transferring programs to other nodes or changing I/O memory of other nodes, check the nodes to confirm safety. Changing the program or I/O memory of other nodes may occasionally cause unexpected operation, resulting in minor or moderate injury, or damage to the equipment.

Precautions for Safe Use

1. Do not use the product in the following locations.
   - Locations subject to direct radiant heat from heating equipment
   - Locations where the product may come into contact with water or oil
   - Locations subject to direct sunlight
   - Locations where dust or corrosive gases (in particular, sulfuric or ammonia gas) are present
   - Locations subject to extreme temperature changes
   - Locations where icing or condensation may occur
   - Locations subject to excessive shocks or vibration
2. Do not use the product in locations subject to temperatures or humidity levels outside the specified ranges or in locations prone to condensation. If the product is installed in a panel, ensure that the temperature around the product (not the temperature around the panel) does not go outside the specified range.
3. Provide sufficient space around the product for heat dissipation.
4. Use and store the product within the specified temperature and humidity ranges. If several products are mounted side-by-side or arranged in a vertical line, the heat dissipation will cause the internal temperature of the products to rise, shortening the service life. If necessary, cool the products using a fan or other cooling method.
5. The service life of the output relays depends on the switching capacity and switching conditions. Consider the actual application conditions and use the product within the rated load and electrical service life. Using the product beyond its service life may result in contact welding or burning.
6. Install the product horizontally.
7. Mount to a panel between 1 and 8-mm thick.
8. Use the specified size of crimp terminals (M3, width: 5.8 mm max.) for wiring. To connect bare wires, AWG22 (cross section: 0.326 mm^2) to AWG14 (cross section: 2.081 mm^2) to wire the power supply terminals and AWG28 (cross section: 0.081 mm^2) to AWG16 (cross section: 1.309 mm^2) for other terminals. (Length of exposed wire: 6 to 8 mm)
9. In order to prevent inductive noise, wire the lines connected to the product separately from power lines carrying high voltages or currents. Do not wire in parallel with or in the same cable as power lines. Other measures for reducing noise include running lines along separate ducts and using shield lines.
10. Ensure that the rated voltage is achieved no longer than 2 s after turning the power ON.
11. Allow the product to operate without load for at least 15 minutes after the power is turned ON.
12. Do not install the product near devices generating strong high-frequency waves or surges. When using a noise filter, check the voltage and current and install it as close to the product as possible.
13. Do not use thinner to clean the product. Use commercially available alcohol.
14. Be sure to confirm the name and polarity for each terminal before wiring the terminal block and connectors.
15. Use the product within the noted supply voltage and rated load.
16. Do not connect anything to unused terminals.
17. Output turns OFF when the mode is changed or settings are initialized. Take this into consideration when setting up the control system.
18. Install an external switch or circuit breaker that complies with applicable IEC60947-1 and IEC60947-3 requirements and label them clearly so that the operator can quickly turn OFF the power.
19. Use the specified cables for the communications lines and stay within the specified DeviceNet communications distances. Refer to the User's Manual (Cat. No. N129) for details on communications distance specifications and cables.

20. Do not pull the DeviceNet communications cables with excessive force or bend them past their natural bending radius.

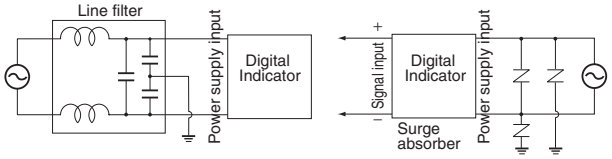
21. Do not connect or remove connectors while the DeviceNet power is being supplied. Doing so will cause product failure or malfunction.

22. Use cables with heat resistance of 70°C min.

■ Noise Countermeasures

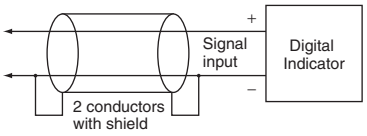
1. Do not install the product near devices generating strong high-frequency waves or surges, such as high-frequency welding and sewing machines.

2. Mount a surge suppressor or noise filter to peripheral devices generating noise, in particular, motors, transformers, solenoids, and magnet coils.



3. In order to prevent inductive noise, wire the lines connected to the terminal block separately from power lines carrying high voltages or currents. Do not wire in parallel with or in the same cable as power lines. Other measures for reducing noise include running lines along separate ducts and using shield lines.

Example of Countermeasures for Inductive Noise on Input Lines



4. If a noise filter is used for the power supply, check the voltage and current, and install the noise filter as close to the product as possible.

5. Reception interference may occur if the product is used close to a radio, television, or wireless.

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Warranty and Limitations of Liability

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The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products.

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this catalog.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

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ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Cat. No. N135-E1-02 **In the interest of product improvement, specifications are subject to change without notice.**

OMRON Corporation
Industrial Automation Company

Industrial Devices and Components Division H.Q.
Measuring Components Department
Shiokoji Horikawa, Shimogyo-ku,
Kyoto, 600-8530 Japan
Tel: (81)75-344-7080/Fax: (81)75-344-7189

Printed in Japan
0305 (0804)

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