R88D-KN□□□-ECT, R88D-KN□□□-ML2, R88D-KT□

Accurax G5 rotary drive

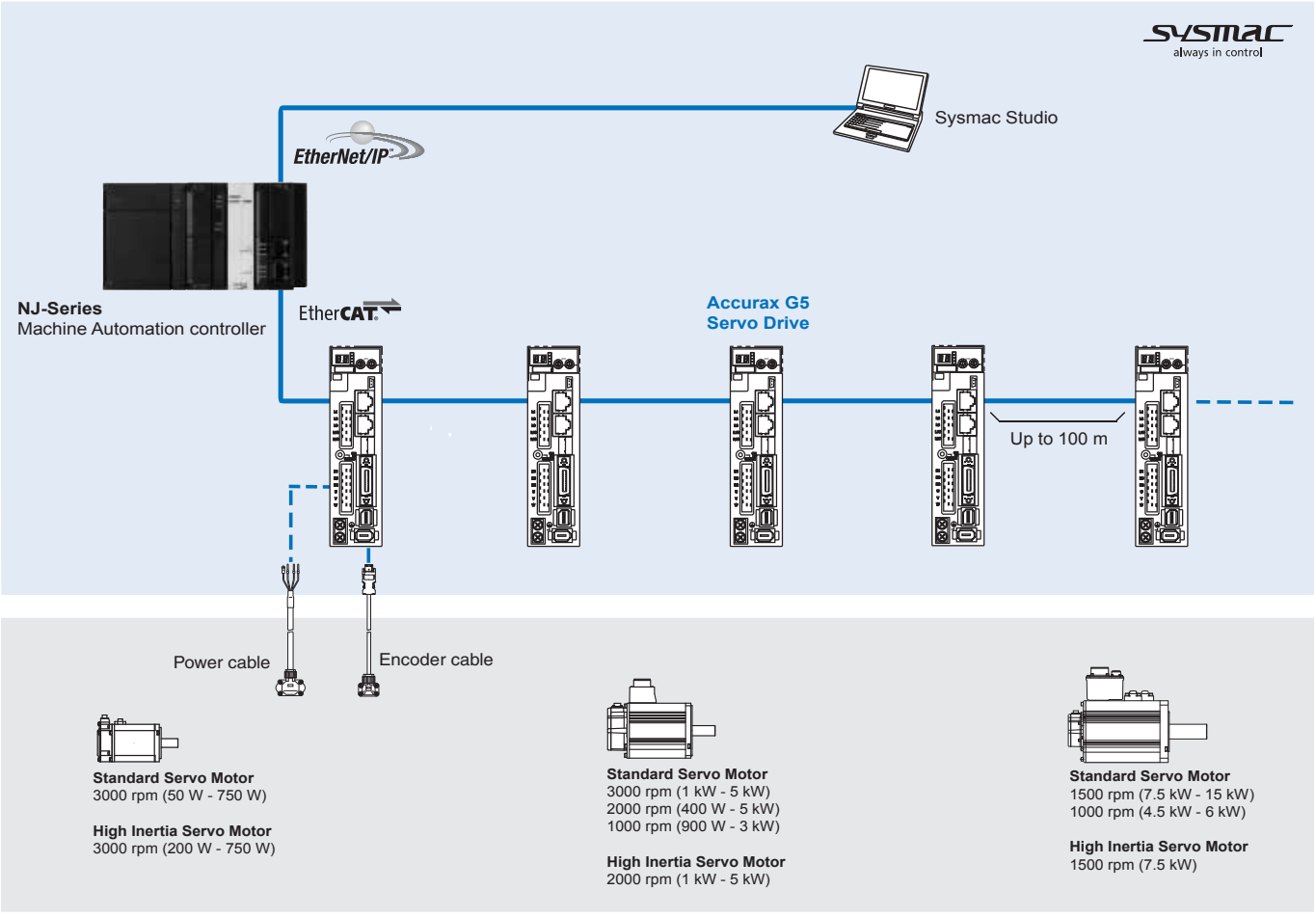
Accurate motion control in a compact size servo drive family. EtherCAT and safety built-in.

- EtherCAT, ML-II and Analog/pulse servo drive models
- Safety conforming ISO13849-1 PL-d
- High-response frequency of 2 kHz
- High resolution provided by 20 bits encoder
- Drive Programming: embedded indexer functionality in the Analogue/pulse models
- External encoder input for full closed loop
- Real time auto-tuning
- Advanced tuning algorithms (Anti-vibration function, torque feedforward, disturbance observer)

Ratings

- 230 VAC single-phase 100 W to 1.5 kW (8.59 Nm)
- 400 VAC three-phase 600 W to 15 kW (95.5 Nm)

System configuration



Servo motor supported

Standard servo motors

Accurax G5 rotary servo motor						Accurax G5 servo drive models		
	Voltage	Speed	Rated torque	Capacity	Model	EtherCAT	Analog/pulse	MECHATROLINK-II
	230 V	3000 min^{-1}	0.16 Nm	50 W	R88M-K05030(H/T)-□	R88D-KN01H-ECT	R88D-KT01H	R88D-KN01H-ML2
			0.32 Nm	100 W	R88M-K10030(H/T)-□	R88D-KN01H-ECT	R88D-KT01H	R88D-KN01H-ML2
			0.64 Nm	200 W	R88M-K20030(H/T)-□	R88D-KN02H-ECT	R88D-KT02H	R88D-KN02H-ML2
			1.3 Nm	400 W	R88M-K40030(H/T)-□	R88D-KN04H-ECT	R88D-KT04H	R88D-KN04H-ML2
			2.4 Nm	750 W	R88M-K75030(H/T)-□	R88D-KN08H-ECT	R88D-KT08H	R88D-KN08H-ML2
			3.18 Nm	1000 W	R88M-K1K030(H/T)-□	R88D-KN15H-ECT	R88D-KT15H	R88D-KN15H-ML2
			4.77 Nm	1500 W	R88M-K1K530(H/T)-□	R88D-KN15H-ECT	R88D-KT15H	R88D-KN15H-ML2
	400 V		2.39 Nm	750 W	R88M-K75030(F/C)-□	R88D-KN10F-ECT	R88D-KT10F	R88D-KN10F-ML2
			3.18 Nm	1000 W	R88M-K1K030(F/C)-□	R88D-KN15F-ECT	R88D-KT15F	R88D-KN15F-ML2
			4.77 Nm	1500 W	R88M-K1K530(F/C)-□	R88D-KN15F-ECT	R88D-KT15F	R88D-KN15F-ML2
			6.37 Nm	2000 W	R88M-K2K030(F/C)-□	R88D-KN20F-ECT	R88D-KT20F	R88D-KN20F-ML2
			9.55 Nm	3000 W	R88M-K3K030(F/C)-□	R88D-KN30F-ECT	R88D-KT30F	R88D-KN30F-ML2
			12.7 Nm	4000 W	R88M-K4K030(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
			15.9 Nm	5000 W	R88M-K5K030(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
230V (1 kW - 1.5 kW) 400V (400 W - 5 kW)	230 V	2000 min^{-1}	4.77 Nm	1000 W	R88M-K1K020(H/T)-□	R88D-KN10H-ECT	R88D-KT10H	R88D-KN10H-ML2
			7.16 Nm	1500 W	R88M-K1K520(H/T)-□	R88D-KN15H-ECT	R88D-KT15H	R88D-KN15H-ML2
	400 V		1.91 Nm	400 W	R88M-K40020(F/C)-□	R88D-KN06F-ECT	R88D-KT06F	R88D-KN06F-ML2
			2.86 Nm	600 W	R88M-K60020(F/C)-□	R88D-KN06F-ECT	R88D-KT06F	R88D-KN06F-ML2
			4.77 Nm	1000 W	R88M-K1K020(F/C)-□	R88D-KN10F-ECT	R88D-KT10F	R88D-KN10F-ML2
			7.16 Nm	1500 W	R88M-K1K520(F/C)-□	R88D-KN15F-ECT	R88D-KT15F	R88D-KN15F-ML2
			9.55 Nm	2000 W	R88M-K2K020(F/C)-□	R88D-KN20F-ECT	R88D-KT20F	R88D-KN20F-ML2
7.5 kW - 15 kW			14.3 Nm	3000 W	R88M-K3K020(F/C)-□	R88D-KN30F-ECT	R88D-KT30F	R88D-KN30F-ML2
			19.1 Nm	4000 W	R88M-K4K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
			23.9 Nm	5000 W	R88M-K5K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
		1500 min^{-1}	47.8 Nm	7500 W	R88M-K7K515C-□	R88D-KN75F-ECT	R88D-KT75F	–
			70.0 Nm	11000 W	R88M-K11K015C-□	R88D-KN150F-ECT	R88D-KT150F	–
			95.5 Nm	15000 W	R88M-K15K015C-□	R88D-KN150F-ECT	R88D-KT150F	–
	230 V	1000 min^{-1}	8.59 Nm	900 W	R88M-K90010(H/T)-□	R88D-KN15H-ECT	R88D-KT15H	R88D-KN15H-ML2
	400 V		8.59 Nm	900 W	R88M-K90010(F/C)-□	R88D-KN15F-ECT	R88D-KT15F	R88D-KN15F-ML2
			19.1 Nm	2000 W	R88M-K2K010(F/C)-□	R88D-KN30F-ECT	R88D-KT30F	R88D-KN30F-ML2
			28.7 Nm	3000 W	R88M-K3K010(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
			43.0 Nm	4500 W	R88M-K4K510C-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
			57.3 Nm	6000 W	R88M-K6K010C-□	R88D-KN75F-ECT	R88D-KT75F	–

High inertia servo motors

Accurax G5 rotary servo motor						Accurax G5 servo drive models		
	Voltage	Speed	Rated torque	Capacity	Model	EtherCAT	Analog/pulse	MECHATROLINK-II
	230 V	3000 min^{-1}	0.64 Nm	200 W	R88M-KH20030(H/T)-□	R88D-KN02H-ECT	R88D-KT02H	R88D-KN02H-ML2
			1.3 Nm	400 W	R88M-KH40030(H/T)-□	R88D-KN04H-ECT	R88D-KT04H	R88D-KN04H-ML2
200 W - 750 W			2.4 Nm	750 W	R88M-KH75030(H/T)-□	R88D-KN08H-ECT	R88D-KT08H	R88D-KN08H-ML2
	400 V	2000 min^{-1}	4.77 Nm	1000 W	R88M-KH1K020(F/C)-□	R88D-KN10F-ECT	R88D-KT10F	R88D-KN10F-ML2
			7.16 Nm	1500 W	R88M-KH1K520(F/C)-□	R88D-KN15F-ECT	R88D-KT15F	R88D-KN15F-ML2
1 kW - 5 kW			9.55 Nm	2000 W	R88M-KH2K020(F/C)-□	R88D-KN20F-ECT	R88D-KT20F	R88D-KN20F-ML2
			14.3 Nm	3000 W	R88M-KH3K020(F/C)-□	R88D-KN30F-ECT	R88D-KT30F	R88D-KN30F-ML2
			19.1 Nm	4000 W	R88M-KH4K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
			23.9 Nm	5000 W	R88M-KH5K020(F/C)-□	R88D-KN50F-ECT	R88D-KT50F	R88D-KN50F-ML2
7.5 KW		1500 min^{-1}	47.8 Nm	7500 W	R88M-KH7K515C-□	R88D-KN75F-ECT	R88D-KT75F	–

Type designation

Servo drive

R88D-KN01H-ECT

- Accurax G5 Series servo drive
- Drive Type
  - T: Analog/pulse type
  - N: Network type
- Capacity and Voltage

Voltage	Code	Output
230 V	01H	100 W
	02H	200 W
	04H	400 W
	08H	750 W
	10H	1 kW
	15H	1.5 kW
400 V	06F	600 W
	10F	1.0 kW
	15F	1.5 kW
	20F	2.0 kW
	30F	3.0 kW
	50F	5.0 kW
	75F	7.5 kW
	150F	15.0 kW

- Model
  - Blank: Analog/pulse type
  - ECT: EtherCAT comms
  - ML2: MECHATROLINK-II comms

Servo drive specifications

Single-phase, 230 V

Servo drive type		R88D-K□	01H□	02H□	04H□	08H□	10H□	15H□
Applicable servo motor		R88M-K□	05030(H/T)-□	20030(H/T)-□	40030(H/T)-□	75030(H/T)-□	1K020(H/T)-□	1K030(H/T)-□
			10030(H/T)-□	–	–	–	–	1K530(H/T)-□
			–	–	–	–	–	1K520(H/T)-□
			–	–	–	–	–	90010(H/T)-□
Basic specifications	Max. applicable motor capacity W		100	200	400	750	1000	1500
	Continuous output current Arms		1.2	1.6	2.6	4.1	5.9	9.4
	Input power	Main circuit	Single-phase/3-phase, 200 to 240 VAC +10 to –15% (50/60 Hz)					
	Supply	Control circuit	Single-phase, 200 to 240 VAC +10 to –15% (50/60 Hz)					
	Control method		IGBT-driven PWM method, sinusoidal drive					
	Feedback		Serial encoder (incremental/absolute value)					
	Conditions: Usage/storage temperature		0 to +55°C/–20 to 65°C					
	Conditions: Usage/storage humidity		90% RH or less (non-condensing)					
	Conditions: Altitude		1000m or less above sea level					
	Conditions: Vibration/shock resistance (max.)		5.88 m/s^2 10 to 60 Hz (Continuous operation at resonance point is not allowed) / 19.6 m/s^2					
	Configuration		Base mounted					
	Approx. weight	kg	0.8		1.1	1.6	1.8	

Three-phase, 400 V

Servo drive type		R88D-K□	06F□	10F□	15F□	20F□	30F□	50F□	75F□	150F□
Applicable servo motor		R88M-K□	40020(F/C)-□	75030(F/C)-□	1K030(F/C)-□	2K030(F/C)-□	3K030(F/C)-□	4K030(F/C)-□	6K010C-□	11K015C-□
			60020(F/C)-□	1K020(F/C)-□	1K530(F/C)-□	2K020(F/C)-□	3K020(F/C)-□	5K030(F/C)-□	7K515C-□	15K015C-□
			–	–	1K520(F/C)-□	–	2K010(F/C)-□	4K020(F/C)-□	–	–
			–	–	90010(F/C)-□	–	–	5K020(F/C)-□	–	–
			–	–	–	–	–	4K510C-□	–	–
			–	–	–	–	–	3K010(F/C)-□	–	–
Basic specifications	Max. applicable motor capacity	kW	0.6	1.0	1.5	2.0	3.0	5.0	7.5	15.0
	Continuous output current	Arms	1.5	2.9	4.7	6.7	9.4	16.5	22.0	33.4
	Input power	Main circuit	3-phase, 380 to 480 VAC +10 to –15% (50/60Hz)							
	Supply	Control circuit	24 VDC ±15%							
	Control method		IGBT-driven PWM method, sinusoidal drive							
	Feedback	Serial encoder	Incremental or absolute encoder						Absolute encoder	
	Conditions: Usage/storage temperature		0 to 55°C/–20 to 65°C							
	Conditions: Usage/storage humidity		90% RH or less (non-condensing)							
	Conditions: Altitude		1000 m or less above sea level							
	Conditions: Vibration/shock resistance		5.88 m/s^2 10 to 60 Hz (Continuous operation at resonance point is not allowed)/19.6 m/s^2							
	Configuration		Base mounted							
	Approx. weight	kg	1.9			2.7	4.7		13.5	21.0

General specifications (for EtherCAT servo drives)

Performance		Frequency characteristics	2 kHz
EtherCAT interface	Command input		EtherCAT commands (for sequence, motion, data setting/reference, monitor, adjustment, and other commands).
	Drive Profile[*1]		CSP, CSV, CST, Homing and Position Profile modes (CiA402 Drive Profile) Homing mode Position profile mode Dual touch probe function (Latch function) Torque limit function
I/O signal	Sequence input signal		Multi-function input × 8 by parameter setting (forward/reverse drive prohibition, emergency stop, external latch, origin proximity, forward/reverse torque limit, general purpose monitor input).
	Sequence output signal		1 × servo drive error output 2 × multi-function outputs by parameters setting (servo ready, brake release, torque limit detection, zero speed detection, warning output, position completion, error clear attributed, programmable output …)
Integrated functions	USB communications	Interface	Personal computer/ Connector mini-USB
		Communications standard	Compliant with USB 2.0 standard
		Function	Parameter setting, status monitoring and tuning
	EtherCAT communications	Communications protocol	IEC 61158 Type 12, IEC 61800-7
		Physical layer	100BASE-TX (IEEE802.3)
		Connectors	RJ45 × 2 ECAT IN: EtherCAT input × 1 ECAT OUT: EtherCAT output × 1
		Communications media	Category 5 or higher (cable with double, aluminium tape and braided shielding is recommended)
		Communications distance	Distance between nodes: 100 m max.
		LED indicators	RUN × 1 ERR × 1 L/A IN (Link/Activity IN) × 1 L/A OUT (Link/activity OUT) × 1
	Autotuning		Automatic motor parameter setting. One parameter rigidity setting. Inertia detection.
	Dynamic brake (DB)		Built-in. Operates during main power OFF, servo alarm, servo OFF or overtravel.
	Regenerative processing		Internal resistor included in models from 600 W to 5 kW. Regenerative resistor externally mounted (option).
	Overtravel (OT) prevention function		DB stop, deceleration stop or coast to stop during P-OT, N-OT operation
	Encoder divider function		Gear ratio
	Protective functions		Overcurrent, overvoltage, undervoltage, overspeed, overload, encoder error, overheat...
	Analog monitor functions for supervision		Analog monitor of motor speed, speed reference, torque reference, command following error, analog input... The monitoring signals to output and their scaling can be specified with parameters. Number of channels: 2 (Output voltage: ±10V DC)
	Panel operator	Display functions	2 × digit 7-segment LED display shows the drive status, alarm codes, parameters...
		Switches	2 × rotary switches for setting the node address
	CHARGE lamp		Lits when the main circuit power supply is turned ON.
	Safety terminal	Functions	Safety Torque OFF function to cut off the motor current and stop the motor. Output signal for failure monitoring function.
		Conformed standards	EN ISO13849-1:2008 (PL- d, Performance Level d), IEC61800-5 -2:2007 (function STO, Safe Torque OFF), EN61508:2001 (Safety Integrity Level 2, SIL2), EN954-1:1996 (CAT3).
	External encoder feedback		Serial signal and line-driver A-B-Z encoder for full-closed control

[*1] The CSV, CST and Homing modes are supported in the servo drive with version 2.0 or higher.

General specifications (for MECHATROLINK-II servo drives)

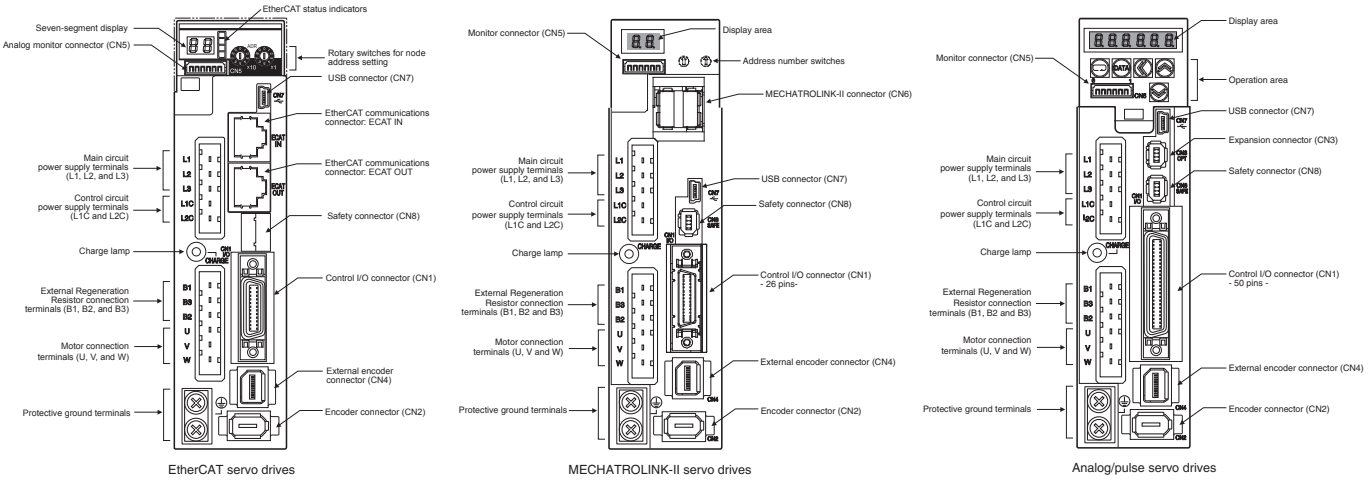
Control mode			Position control, velocity control, torque control, full-closed control.
Performance		Frequency characteristics	2 kHz
		Speed zero clamp	Preset velocity command can be clamped to zero by the speed zero clamp input.
		soft start time setting	0 to 10 s (acceleration, deceleration can be set separately).
Command input		MECHATROLINK-II communication	MECHATROLINK-II commands (for sequence, motion, data setting/reference, monitor, adjustment and other commands)
I/O signal	Sequence input signal		Multi-function input × 8 by parameter setting (forward/reverse drive prohibition, emergency stop, external latch, origin proximity, forward/reverse torque limit, general purpose monitor input).
	Sequence output signal		It is possible to output three types of signal form incl.: brake release, servo ready, servo alarm, positioning complete, motor rotation speed detection, torque limit detection, zero speed detection, speed coincidence detection, warning, position command status, speed limit detection, alarm output, speed command status.
Integrated functions	USB communications	Interface	Personal computer/ Connector mini-USB
		Communications standard	Compliant with USB 2.0 standard
		Function	Parameter setting, status monitoring and tuning
	MECHATROLINK-II communications	Communications protocol	MECHATROLINK-II
		Station address	41H to 51 FH (max. number of slaves: 30)
		Transmission speed	10 Mbps
		Transmission cycle	1, 2 & 4 ms
		Data length	32 bytes
	Autotuning		Automatic motor parameter setting. One parameter rigidity setting. Inertia detection.
	Dynamic brake (DB)		Built-in. Operates during main power OFF, servo alarm, servo OFF or overtravel.
	Regenerative processing		Internal resistor included in models from 600 W to 5 kW. Regenerative resistor externally mounted (option).
	Overtravel (OT) prevention function		DB stop, deceleration stop or coast to stop during P-OT, N-OT operation
	Encoder divider function		Optional division possible
	Protective functions		Overcurrent, overvoltage, undervoltage, overspeed, overload, encoder error, overheat...
	Analog monitor functions for supervision		Analog monitor of motor speed, speed reference, torque reference, command following error, analog input... The monitoring signals to output and their scaling can be specified with parameters. Number of channels: 2 (Output voltage: ±10V DC)
	Panel operator	Display functions	2-digit 7-segment LED display shows the drive status, alarm codes, parameters...
			MECHATROLINK-II communications status LED indicator (COM)
		Switches	2 × rotary switches for setting the MECHATROLINK-II node address
	CHARGE lamp		Lits when the main circuit power supply is turned ON.
	Safety terminal	Functions	Safety Torque OFF function to cut off the motor current and stop the motor. Output signal for failure monitoring function.
		Conformed standards	EN ISO13849-1:2008 (PL- d, Performance Level d), IEC61800-5 -2:2007 (function STO, Safe Torque OFF), EN61508:2001 (Safety Integrity Level 2, SIL2), EN954-1:1996 (CAT3).
	External encoder feedback		Serial signal and line-driver A-B-Z encoder for full-closed control

General specifications (for Analog/pulse servo drives)

Control modes			External control	(1) position control, (2) velocity control, (3) torque control, (4) position/velocity control, (5) position/torque control, (6) velocity/torque control and (7) full-closed control.
			Internal positioning	Drive Programming: indexer functionality enabled by parameter.
Speed/torque control	**Performance**		Frequency characteristics	2 kHz
			Speed zero clamp	Preset velocity command can be clamped to zero by the speed zero clamp input.
			Soft start time setting	0 to 10 s (acceleration, deceleration can be set separately). S-curve acceleration/deceleration is also available.
	Input signal	Speed control	Speed reference voltage	6 VDC at rated speed: set at delivery (the scale and polarity can be set by parameters)
			Torque limit	3 VDC at rated torque (torque can be limited separately in positive/negative direction).
			Preset speed control	Preset speed is selectable from 8 internal settings by digital inputs.
		Torque control	Torque reference voltage	3 VDC at rated torque: set at delivery (the scale and polarity can be set by parameters).
			Speed limit	Speed limit can be set by parameter.
Position control	**Input signal**	Command pulse	Input pulse type	Sign + pulse train, 90° phase displacement 2-phase pulse (A-phase+ B-phase) or CCW/CW pulse train
			Input pulse frequency	4 Mpps max. (200 Kpps max. at open collector).
			Command pulse scaling (Electronic Gear)	Applicable scaling ratio: 1/1000 to 1000 Any value of 1 to 2^{30} can be set for numerator (encoder resolution) and denominator (command pulse resolution per motor revolution). The combination has to be within the range shown above.
Full-closed control	**Input signal**	Command pulse	Input pulse type	Sign + pulse train, 90° phase displacement 2-phase pulse (A-phase+ B-phase) or CCW/CW pulse train
			Input pulse frequency	4 Mpps max. (200 Kpps max. at open collector).
			Command pulse scaling (Electronic Gear)	Applicable scaling ratio: 1/1000 to 1000 Any value of 1 to 2^{30} can be set for numerator (encoder resolution) and denominator (command pulse resolution). The combination has to be within the range shown above.
	External encoder scaling			Applicable scaling ratio: 1/20 to 160 Any value of 1 to 2^{30} can be set for numerator (encoder resolution) and denominator (external encoder resolution per motor revolution). The combination has to be within the range shown above.
Drive Programming	Functionality selection			Functionality enabled by parameter.
	Supported functionality			G5 Analogue/pulse servo drive with firmware 1.10 or higher.
	Software			CX-Drive version 2.30 or higher.
	Communication			The program can be downloaded via USB communication (CX-Drive)
	Command types			Move relative, Move absolute, Jog, Homing, Deceleration stop, Velocity update, Timer, Output signal control, Jump, Conditional branching,
	Number of commands			Up to 32 commands (0 to 31)
	Command execution			Strobe input to execute the selected command or to execute a complex sequence (combination of various commands).
	Command selection			Up to 5 digital inputs to select the individual commands or sequences

I/O signal	Position signal output		A-phase, B.phase, Z-phase line driver output and Z-phase open-collector output.
	Sequence input signal	External control	- Multi-function input × 10 by parameter setting: servo ON, control mode switching, forward/reverse drive prohibition, vibration filter switching, gain switching, electronic gear switching, error counter reset, pulse prohibition, alarm reset, internal speed selection, torque limit switching, zero speed, emergency stop, inertia ratio switching, velocity/torque command sign. - Dedicated input × 1 (SEN: sensor ON, ABS data request).
		Internal positioning (Drive programming mode)	- Multi-function input × 10 by parameter setting: servo ON, forward/reverse drive prohibition, damping filter switching, gain switching, alarm reset, torque limit switching, emergency stop, immediate stop, deceleration stop input, inertia ratio switching, latch input, origin proximity input, strobe and 5 × input command selection. - Dedicated input × 1 (SEN: sensor ON, ABS data request).
	Sequence output signal	External control	- 3 × outputs signals configured by parameter settings: brake release, servo ready, servo alarm, positioning complete, motor rotation speed detection, torque limit detection, zero speed detection, speed coincidence detection, warning, position command status, speed limit detection, speed command status. - 1 output fixed to Alarm output.
		Internal positioning (Drive programming enabled)	3 × outputs signals configured by parameter settings: ready, Brake, position completed, motor speed detection, torque limit status, zero speed detection, speed conformity, warning, position command status, position completed, drive programming command output and output during drive programming. - 1 output fixed to Alarm output.
Integrated functions	USB Communications	Interface	Personal computer/ Connector mini-USB
		Communications standard	Compliant with USB 2.0 standard
		Function	Parameter setting, status monitoring and tuning
	Autotuning		Automatic motor parameter setting. One parameter rigidity setting. Inertia detection.
	Dynamic brake (DB)		Built-in. Operates during main power OFF, servo alarm, servo OFF or overtravel.
	Regenerative processing		Internal resistor included in models from 600 W to 5 kW. Regenerative resistor externally mounted (option).
	Overtravel (OT) prevention function		DB stop, deceleration stop or coast to stop during P-OT, N-OT operation
	Encoder divider function		Optional division possible
	Electronic gearing (Numerator/Denominator)		Up to 4 electronic gear numerators by combining with inputs.
	Internal speed setting function		8 speeds may be set internally
	Protective functions		Overcurrent, overvoltage, undervoltage, overspeed, overload, encoder error, overheat...
	Analog monitor functions for supervision		Analog monitor of motor speed, speed reference, torque reference, command following error, analog input... The monitoring signals to output and their scaling can be specified by parameters. Number of channels: 2 (Output voltage: ±10V DC)
	Panel operator	Display functions	6-digit 7-segment LED display shows the drive status, alarm codes, parameters...
		Panel operator keys	Used to set/monitor parameters and drive condition (5 key switches).
	CHARGE lamp		Lits when the main circuit power supply is turned ON.
	Safety terminal	Functions	Safety torque OFF function to cut off the motor current and stop the motor. Output signal for failure monitoring function.
		Conformed standards	EN ISO13849-1:2008 (PL- d, Performance Level d), IEC61800-5 -2:2007 (function STO, Safe Torque OFF), EN61508:2001 (Safety Integrity Level 2, SIL2), EN954-1:1996 (CAT3).
	External encoder feedback		Serial signal and line-driver A-B-Z encoder for full-closed control
	Expansion connector		Serial bus for option board

Servo drive part names



Note: The above pictures show 230 V servo drives models only. The 400 V servo drives have 24 VDC power input terminals for control circuit instead of L1C and L2C terminals.

I/O specifications

Terminals specifications (for all servo drives)

Symbol	Name	Function
L1	Main power supply input terminal	AC power input terminals for the main circuit **Note:** for single-phase servo drives connect the power supply input to L1 and L3.
L2		
L3		
L1C	Control power supply input terminal	AC power input terminals for the control circuit (for 200 V single/three-phase servo drives only).
L2C		
24 V		DC power input terminals for the control circuit (for 400 V three-phase servo drives only).
0 V		
B1	External regeneration resistor connection terminals	Servo drives 200 V below 750 W: no internal resistor is connected. Leave B2 and B3 open. Connect an external regenerative resistor between B1 and B2. Servo drives from 600 W to 5 kW: short-circuit in B2 and B3 for internal regenerative resistor. If the internal regenerative resistor is insufficient, connect an external regenerative resistor between B1 and B2 and remove the wire between B2 and B3.
B2		
B3		
U	Servo motor connection terminals	Terminals for outputs to the servomotor.
V		
W		

I/O signals (CN1) - Input signals (for EtherCAT and MECHATROLINK-II servo drives)

Pin No.	Signal name	Function	
6	I-COM	± pole of external DC power. The power must use 12 V to 24 V (±5%)	
5	E-STOP	Emergency stop	The signal name shows the factory setting. The function can be changed by parameter setting.
7	P-OT	Forward run prohibited	
8	N-OT	Reverse run prohibited	
9	DEC	Origin proximity	
10	EXT3	External latch input 3	
11	EXT2	External latch input 2	
12	EXT1	External latch input 1	
13	SI-MON0	General purpose monitor input 0	
14	BTP-I	Connecting pin for the absolute encoder backup battery. Do not connect when a battery is connected to the encoder cable (CN2 connector).	
15	BTN-I		
17	–	Terminals not used. Do not connect.	
18	–		
19	–		
20	–		
21	–		
22	–		
23	–		
24	–		
–	PCL	Forward torque limit	The function of input signals allocated to pins 5 and 7 to 13 can be changed with these options by parameters settings.
	NCL	Reverse torque limit	
	SI-MON1	General-purpose monitor input 1	
	SI-MON2	General-purpose monitor input 2	
Shell	FG	Shield ground. Connected to frame ground if the shield wire of the I/O signal cable is connected to the connector shell.	
16	GND	Signal ground. It is insulated with power supply (I-COM) for the control signal in the servo drive.	

I/O signals (CN1) - Output signals (for EtherCAT and MECHATROLINK-II servo drives)

Pin No.	Signal name	Function	
1	BRK-OFF+	External brake release signal	
2	BRK-OFF		
25	S-RDY+	Servo ready: ON when there is no servo alarm and control/main circuit power supply is ON	
26	S-RDY–		
3	ALM+	Servo alarm: Turns OFF when an error is detected	
4	ALM–		
–	INP1	Position completed output 1	The function of output signals allocated to pins 1, 2, 25 and 26 can be changed with these options by parameters settings
	TGON	Speed detection	
	T_LIM	Torque limit	
	ZSP	Zero speed	
	VCMP	Speed command status	
	INP2	Position completed output 2	
	WARN1	Warning 1	
	WARN2	Warning 2	
	PCMD	Position command status	
	V_LIM	Speed limit	
	ALM-ATB	Error clear attribute (for ECT model only)	
	R-OUT1	Programmable output 1 (for ECT model only)	
	R-OUT2	Programmable output 2 (for ECT model only)	

I/O signals (CN1) - Input signals (for Analog/pulse servo drives)

Pin No.	Control mode	Signal name	Function	
1	Position/ Full closed loop	+24 VCW	Reference pulse input for line driver and open collector according to parameter setting. Input mode: Sign + pulse string Reverse/forward pulse (CCW/CW pulse) Two-phase pulse (90° phase differential)	
3		+CW		
4		–CW		
2		+24 VCW		
5		+CCW		
6		–CCW		
44		+CWLD	Reference pulse input for line driver only. Input mode: Reverse/forward pulse (CCW/CW pulse)	
45		–CWLD		
46		+CCWLD		
47		–CCWLD		
14	Speed	REF	Speed reference input: ±10 V/rated motor speed (input gain can be modified using a parameter).	
	Torque	TREF1	Torque reference input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
		VLIM	Speed limit input: ±10 V/rated motor speed (input gain can be modified using a parameter).	
15	–	AGND1	Analog signal ground	
16	Torque	TREF2	Torque reference input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
	Position/Speed Full closed loop	PCL	Forward torque limit input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
18		NCL	Reverse torque limit input: ±10 V/rated motor torque (input gain can be modified using a parameter).	
17	–	AGND1	Analog signal ground	
7	Common	+24 VIN	Control power supply input for sequence signals: users must provide the +24 V power supply (12 to 24 V).	
29		RUN	Servo ON: this turn ON the servo.	
26	Position/Full closed loop	DFSEL1	Vibration filter switching 1	Enables vibration filter according parameter setting.
27	Common	GSEL	Gain switching	Enables gain value according parameter setting.
28	Position/Full closed loop	GESEL1	Electronic gear switching 1	Switches the numerator fro electronic gear ratio.
	Speed	VSEL3	Internal speed selection 3	Input to select the desired speed setting during internally speed operation. The speed selection is combining this input with VSEL1 and VSEL2 inputs.
30	Position/Full closed loop	ECRST	Error counter reset input.	Resets the position error counter.
	Speed	VSEL2	Internal speed selection 2	Input to select the desired speed setting during internally speed operation. The speed selection is combining this input with VSEL1 and VSEL3 inputs.
31	Common	RESET	Alarm reset input.	Release the alarm status. The error counter is reset when the alarm is reset.
32	Position/Speed/ Torque	TVSEL	Control mode switching	Position ↔ speed Position ↔ torque Torque ↔ speed } Enables control mode switching
33	Position	IPG	Pulse prohibition input. Digital input to inhibit the position reference pulse.	
	Speed	VSEL1	Internal speed selection 1	Input to select the desired speed setting during internally speed operation. The speed selection is combining this input with VSEL2 and VSEL3 inputs.
8	Common	NOT	Reverse run prohibited	Overtravel prohibited: stops servomotor when movable part travels beyond the allowable range of motion.
9		POT	Forward run prohibited	
20	Position/Speed/ Torque	SEN	Sensor ON input. Initial data request signal when using an absolute encoder.	
13		SENGND	Sensor ON signal ground.	
42	Common	BAT (+)	Backup battery connection terminals when the absolute encoder power is interrupted. Do not connect when a absolute encoder battery cable for backup is used.	
43		BATGND (–)		
50		FG	Frame ground	
–	–	TLSEL	Torque limit switch	The function of input signals allocated to pins 8, 9 and 26 to 33 can be changed with these options by parameters settings
		DFSEL2	Vibration filter switching 2	
		GESEL2	Electronic gear switching 2	
		VZERO	Zero speed	
		VSIGN	Speed command signal	
		TSIGN	Torque command signal	
		E-STOP	Emergency stop	
		JSEL	Inertia ratio switching	
	Drive Programming	EXT1	Latch input 1	
		HOME	Origin proximity input	
		H-STOP	Immediate stop input	
		S-STOP	Deceleration stop input	
		STB	Strobe	
		B-SEL1	Command selection input 1	
		B-SEL2	Command selection input 2	
		B-SEL4	Command selection input 4	
		B-SEL8	Command selection input 8	
		B-SEL16	Command selection input 16	
12	–	Terminals not used. Do not connect.		
40	–			
41	–			

I/O signals (CN1) - Output signals (for Analog/pulse servo drives)

Pin No.	Control mode	Signal name	Function	
21	Position/ Full closed loop	+A	Encoder phase A+	Encoder signals (or external scale signals during full closing control) are output according Encoder Dividing Numerator parameter. This is the line-driver output (equivalent to R422). The maximum output frequency is 4 Mbps. Phase Z is output for encoder signals (or external scale signals during full closing control). This is the line-driver output (equivalent to R422).
22		–A	Encoder phase A–	
48		+B	Encoder phase B+	
49		–B	Encoder phase B–	
23		+Z	Encoder phase Z+	
24		–Z	Encoder phase Z–	
19		Z	Encoder phase-Z output	Phase Z is output for encoder signals (or external scale signals during full closing control). Open-collector output.
25		ZCOM	Encoder phase-Z common	
11	Common	BKIR	Brake release signal output	Timing signal for operating the electromagnetic brake on a motor.
10		BKIRCOM		
35		READY	Servo ready: ON if there is not servo alarm when the control/main circuit power supply is turned ON.	
34		READYCOM		
37		/ALM	Servo alarm: turns OFF when an error is detected.	
36		ALMCOM		
39	Speed/torque	TGON	Motor rotation speed detection. This output turns ON when the motor rotation speed reaches the speed set in a parameter.	
39	Position/ Full closed loop	INP1	Positioning complete output 1: turns ON when position error is equal to setting parameter.	
38		INP1COM		
–	–	INP2	Position complete output 2	The function of output signals allocated to pins 11, 10, 34 to 39 can be changed with these options by parameters settings.
		P-CMD	Position command status	
		ZSP	Zero speed	
		WARN1	Warning 1	
		WARN2	Warning 2	
		ALM-ATB	Error clear attribute	
		VCMP	Speed conformity output	
		V-CMD	Speed command status	
		V-LIMIT	Speed limit detection	
		T-LIMIT	Torque limit detection	
	Drive Programming	B-CTRL1	Drive Programming output 1	
		B-CTRL2	Drive Programming output 2	
		B-CTRL3	Drive Programming output 3	
		B-BUSY	Output during Drive Programming	
		HOME-CMP	Origin search complete	

External encoder connector (CN4) - (for all servo drives)

Pin No.	Signal name	Function
1	E5V	External scale power supply output. Use at 5.2 V ±5% and at or below 250 mA.
2	E0V	This is connected to the control circuit ground connected to connector CN1.
3	PS	External scale signal I/O (serial signal).
4	/PS	
5	EXA	External scale signal input (Phase A, B, and Z signals). Performs the input and output of phase A, B and Z signals.
6	/EXA	
7	EXB	
8	/EXB	
9	EXZ	
10	/EXZ	
Shell	FG	Shield ground

Monitor connector (CN5) - (for all servo drives)

Pin No.	Signal name	Function
1	AM1	Analog monitor output 1. Outputs the analog signal for the monitor. Use the parameters setting to select the output to monitor. Default setting: Motor rotation speed 1 V/(1000 r/min).
2	AM2	Analog monitor output 2. Outputs the analog signal for the monitor. Use the parameters setting to select the output to monitor. Default setting: Motor rotation speed 1 V/(1000 r/min).
3	GND	Ground for analog monitors 1, 2.
4	–	Terminals not used. Do not connect.
5	–	
6	–	

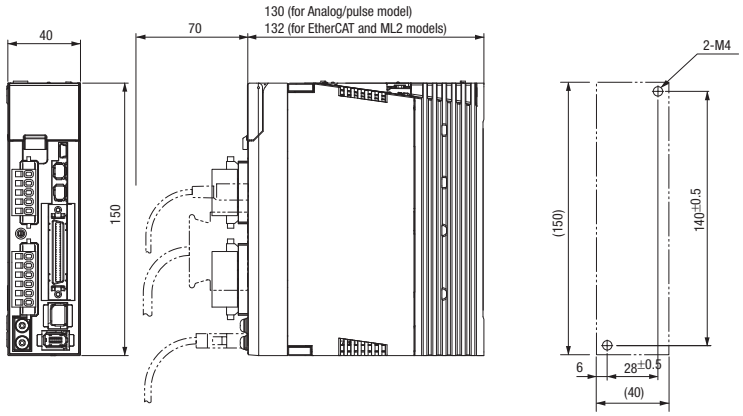
Safety connector (CN8) - (for all servo drives)

Pin No.	Signal name	Function
1	–	Not used. Do not connect
2	–	
3	SF1–	Safety input 1 & 2. This input turns OFF the power transistor drive signals in the servo drive to cut off the current output to the motor.
4	SF1+	
5	SF2–	
6	SF2+	
7	EDM–	A monitor signal is output to detect a safety function failure.
8	EDM+	
Shell	FG	Frame ground.

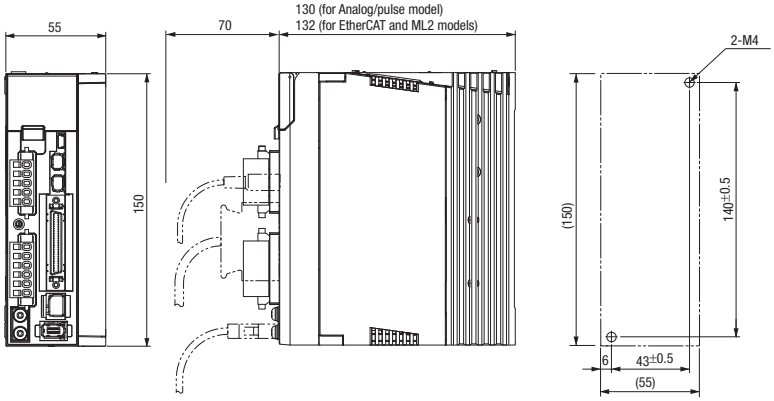
Dimensions

Servo drives

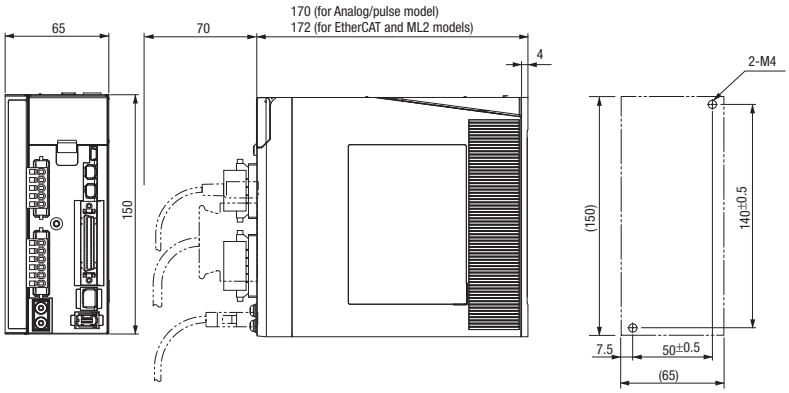
R88D-KT01/02H, R88D-KN01/02H-□ (230 V, 100 to 200 W)



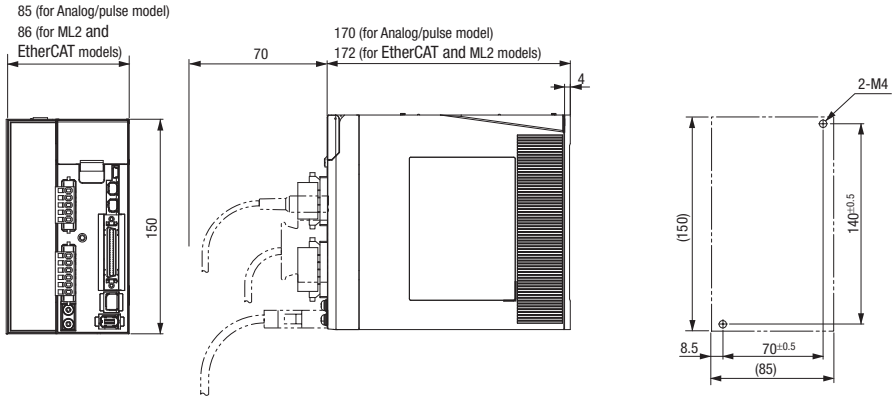
R88D-KT04H, R88D-KN04H-□ (230 V, 400 W)



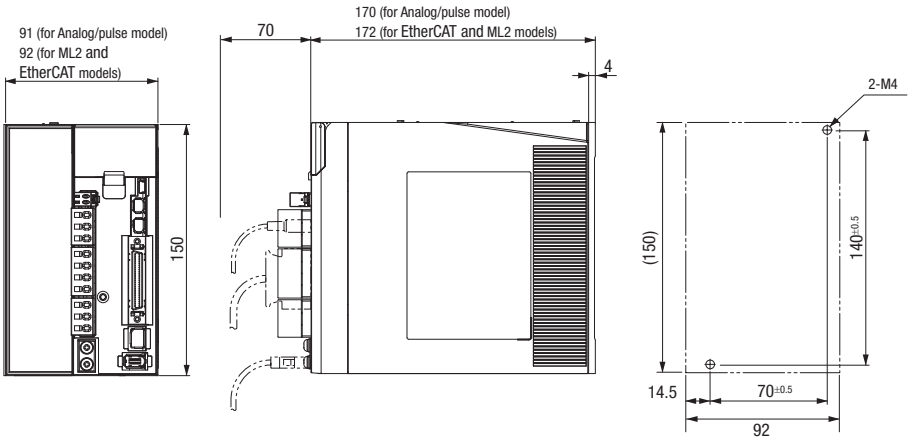
R88D-KT08H, R88D-KN08H-□ (230 V, 750 W)



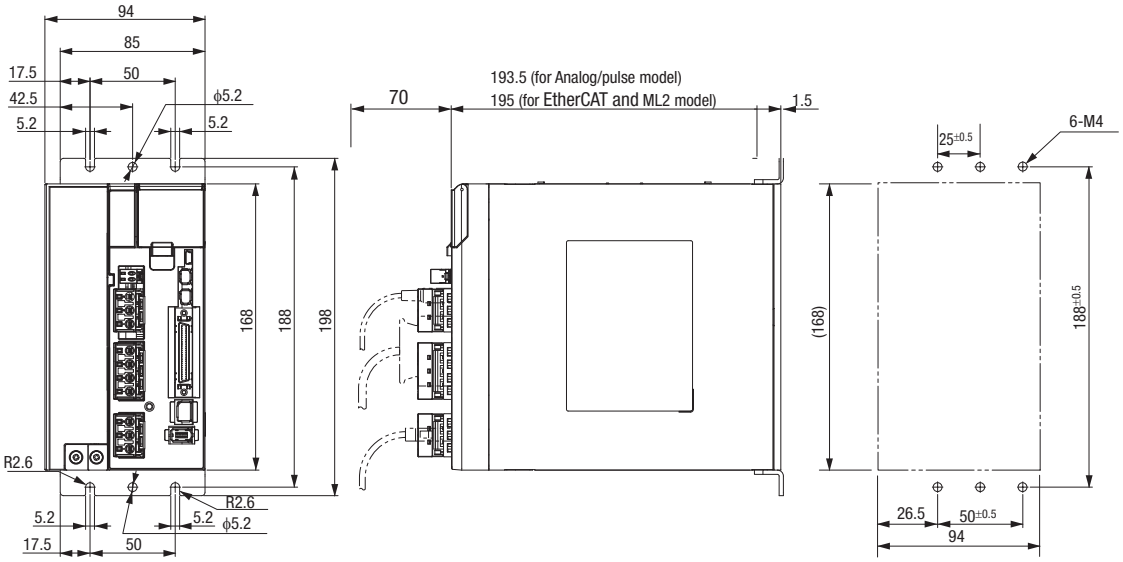
R88D-KT10/15H, R88D-KN10/15H-□ (230 V, 1 to 1.5 kW)



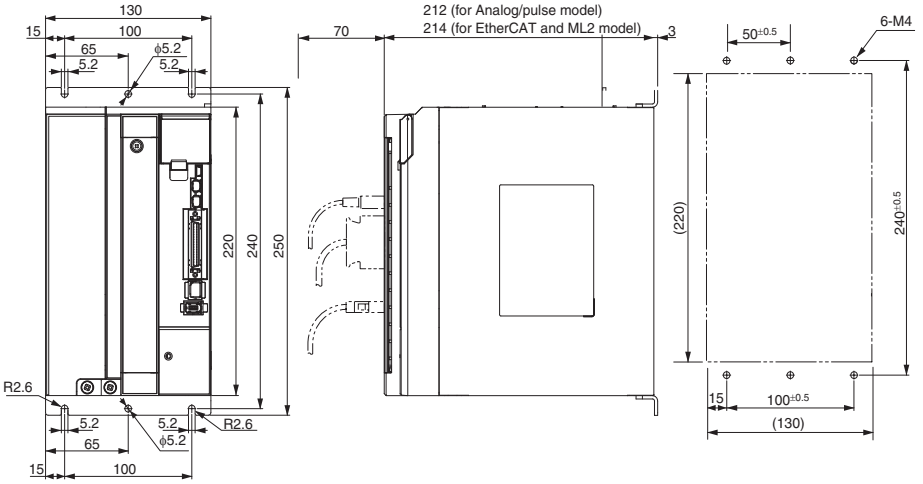
R88D-KT06/10/15F, R88D-KN06/10/15F-□ (400 V, 600 W to 1.5 kW)



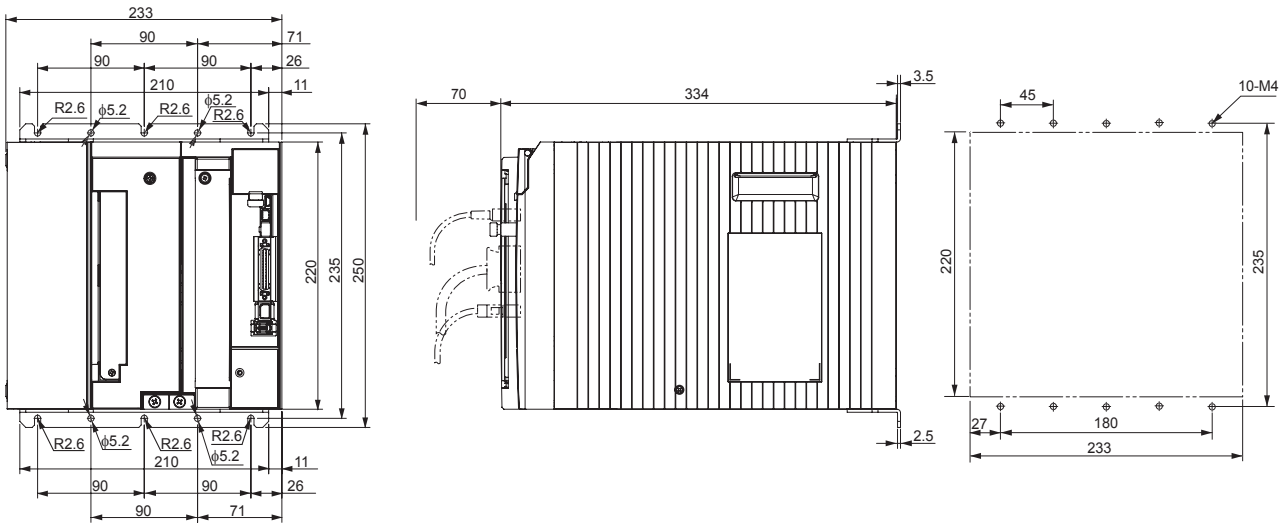
R88D-KT20F, R88D-KN20F-□ (400 V, 2 kW)



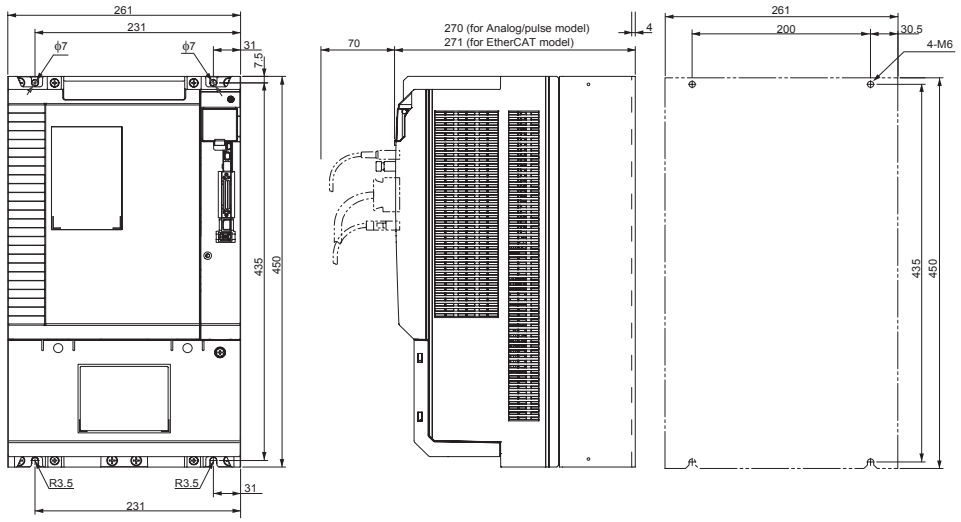
R88D-KT30/50F, R88D-KN30/50F-□ (400 V, 3 to 5 kW)



R88D-KT75F, R88D-KN75H-ECT (400 V, 7.5 kW)

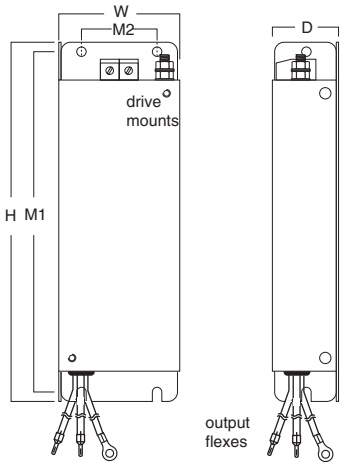


R88D-KT150F, R88D-KN150H-ECT (400 V, 15 kW)



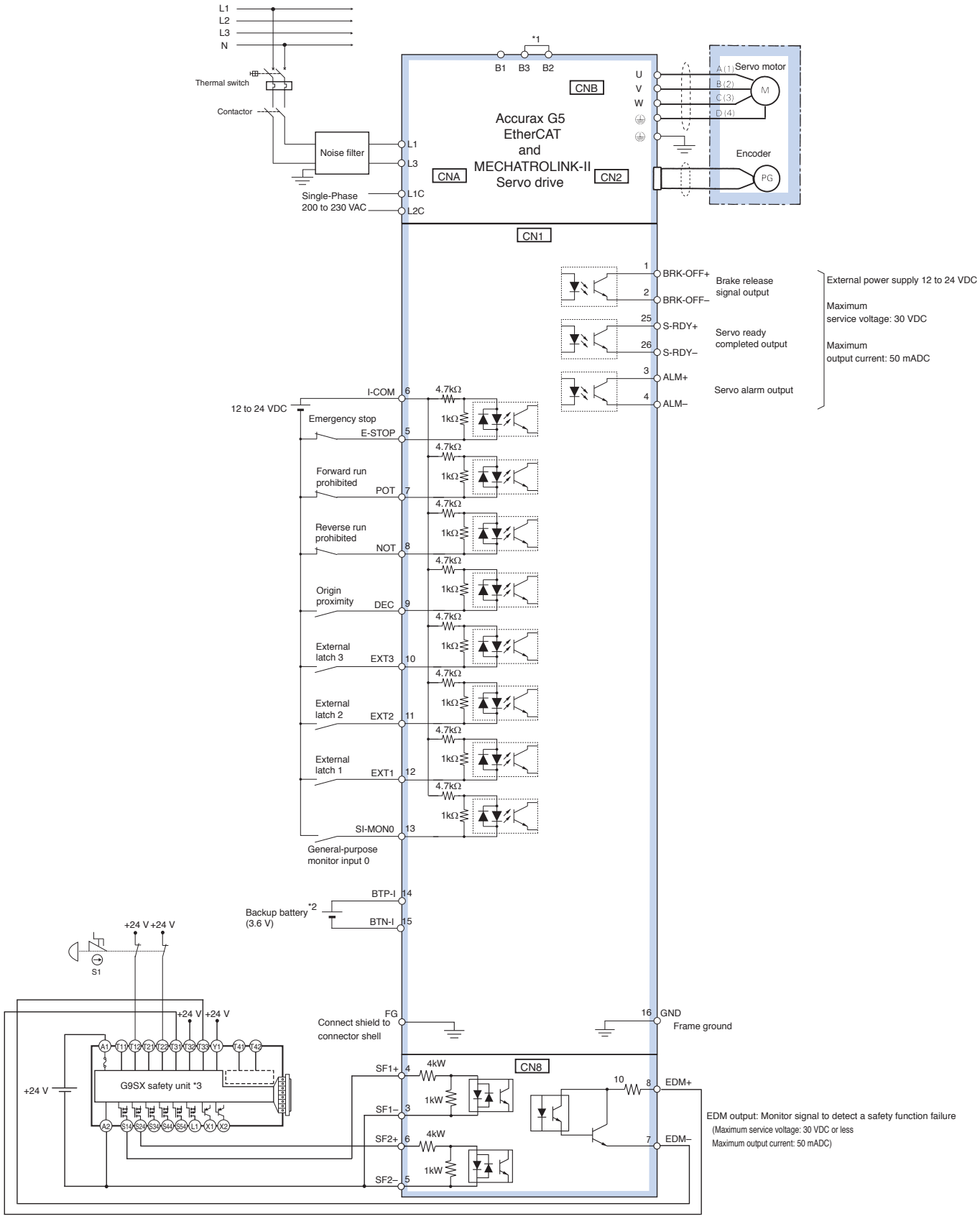
Filters

Filter model	External dimensions			Mount dimensions	
	H	W	D	M1	M2
R88A-FIK102-RE	190	42	44	180	20
R88A-FIK104-RE	190	57	30	180	30
R88A-FIK107-RE	190	64	35	180	40
R88A-FIK114-RE	190	86	35	180	60
R88A-FIK304-RE	196	92	40	186	70
R88A-FIK306-RE	238	94	40	228	70
R88A-FIK312-RE	291	130	40	278	100
R88A-FIK330-RE	310	233	50	293	180
R88A-FIK350-RE	506	261	52	491	200



Installation

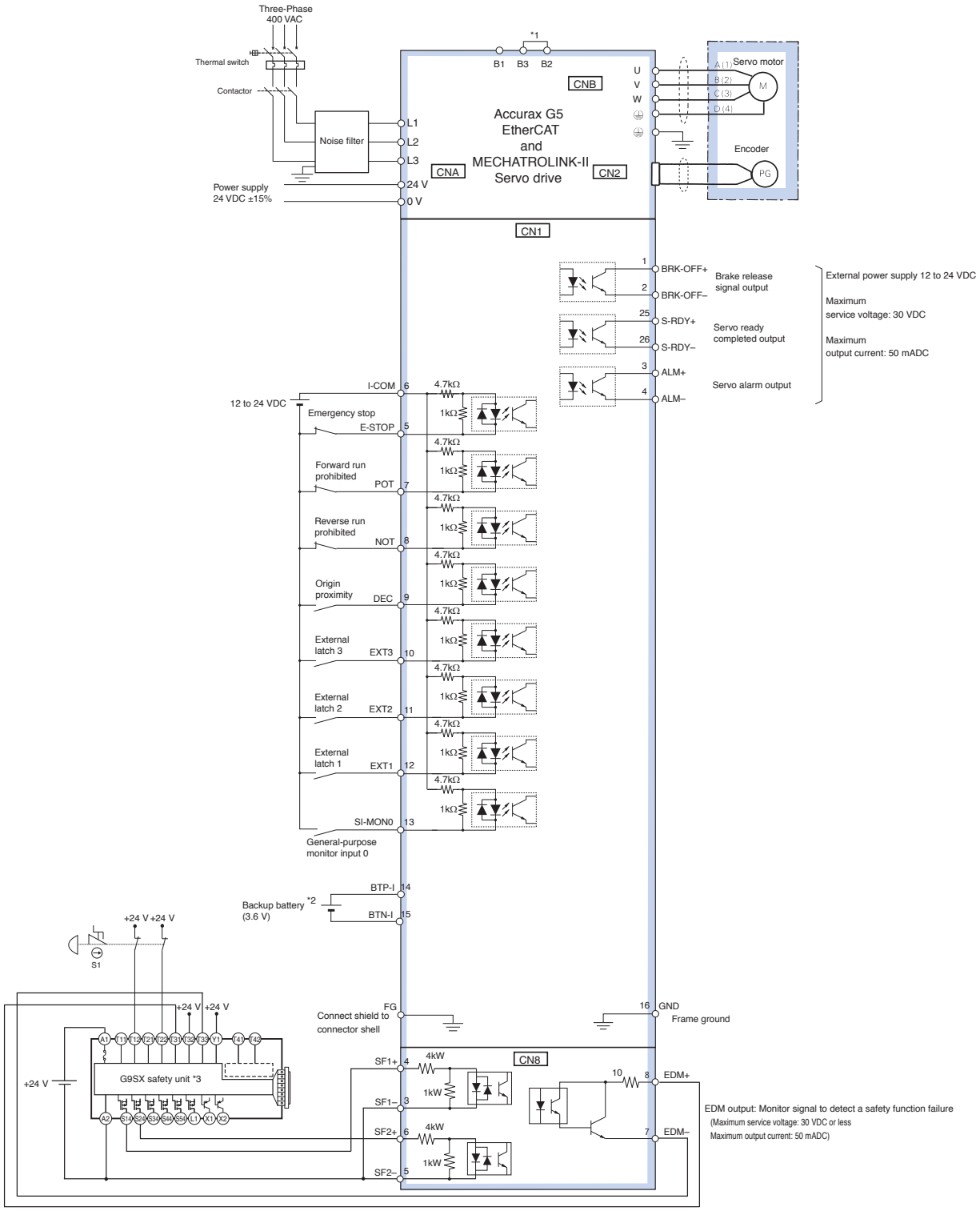
Single-phase, 230 VAC (for EtherCAT and MECHATROLINK-II servo drives)



*1 For servo drives from 750 W, B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 5 and 7 to 13, and output function of pins 1, 2, 25 and 26, can be changed via parameter settings.

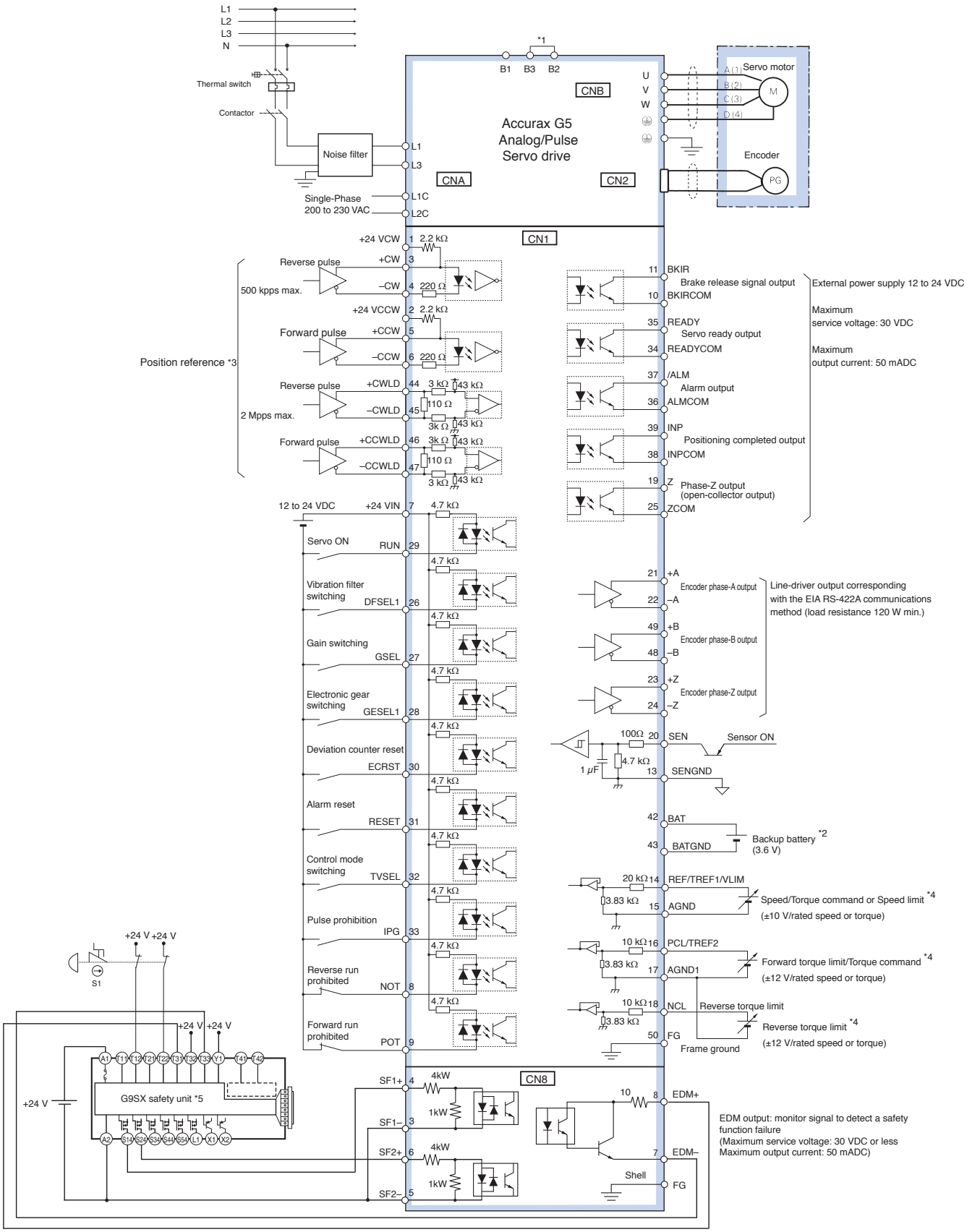
Three-phase, 400 VAC (for EtherCAT and MECHATROLINK-II servo drives)



*1 Normally B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 5 and 7 to 13, and output function of pins 1, 2, 25 and 26, can be changed via parameter settings.

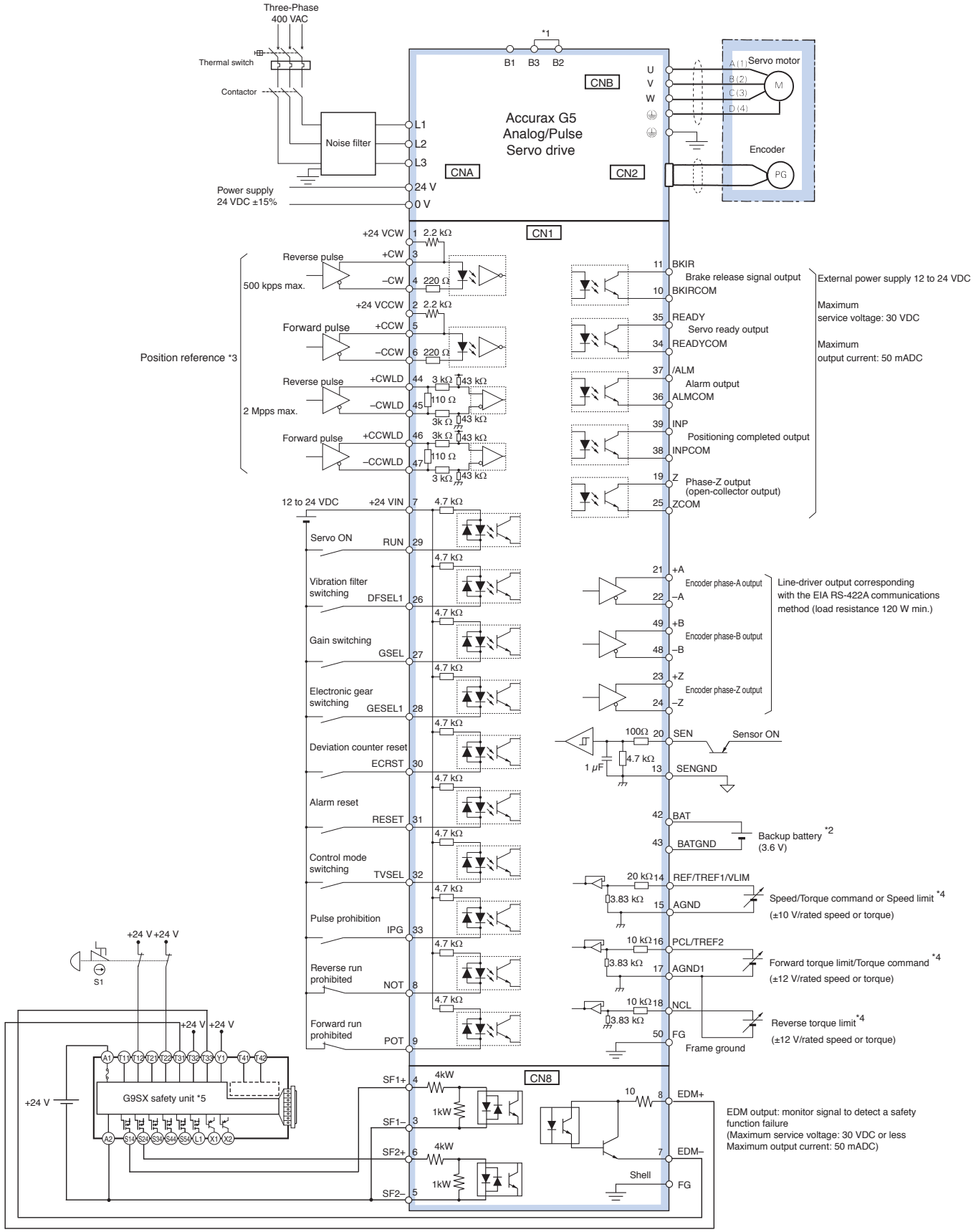
Single-phase, 230 VAC (for Analog/pulse servo drives)



*1 For servo drives from 750 W, B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Only available in Position control mode.
*4 The input function depends on control mode used (Position, speed or torque control).
*5 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 8,9 and 26 to 33, and output function of pins 10, 11, 34, 35, 38 and 39, can be changed via parameter settings.

Three-phase, 400 VAC (for Analog/pulse servo drives)

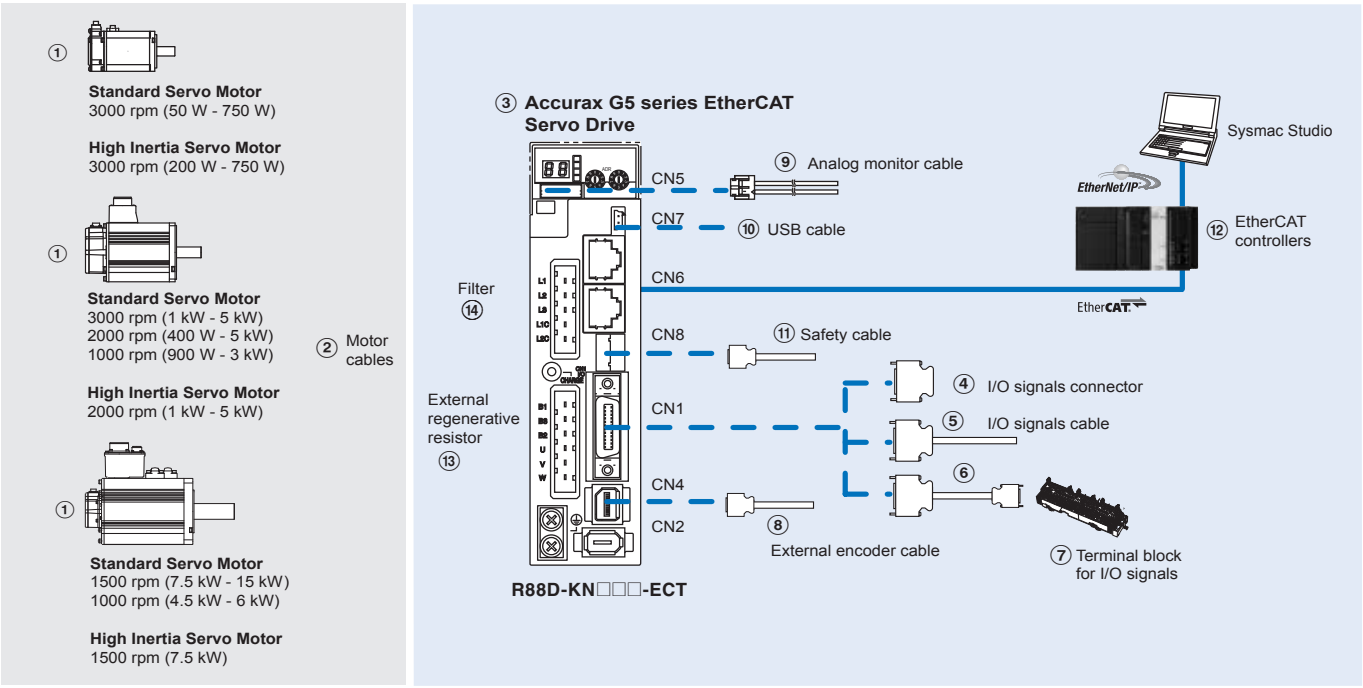


*1 Normally B2 and B3 are short-circuited. If the internal regenerative resistor is insufficient, remove the wire between B2 and B3 and connect an external regenerative resistor between B1 and B2.
*2 For use only with an absolute encoder. If a backup battery is connected to CN1 I/O connector, an encoder cable with a battery is not required.
*3 Only available in Position control mode.
*4 The input function depends on control mode used (Position, speed or torque control).
*5 Wiring diagram example using the G9SX safety unit. If a safety unit is not used, keep the factory safety bypass connector installed in the CN8.

Note: The input function of pins 8,9 and 26 to 33, and output function of pins 10, 11, 34, 35, 38 and 39, can be changed via parameter settings.

Ordering information

Accurax G5 series EtherCAT reference configuration



Note: The symbols ①②③④⑤... show the recommended sequence to select the components in Accurax G5 servo system

Servo motors, power & encoder cables

Note: ①② Refer to the Accurax G5 servo motor chapter for servomotor, motor cables or connectors selection

Servo drives

Symbol	Specifications		Servo drive models	① Compatible G5 series rotary servo motors	
				Standard models	High Inertia models
③	1 phase 230 VAC	100 W	R88D-KN01H-ECT	R88M-K05030(H/T)-□	–
				R88M-K10030(H/T)-□	–
		200 W	R88D-KN02H-ECT	R88M-K20030(H/T)-□	R88M-KH20030(H/T)-□
		400 W	R88D-KN04H-ECT	R88M-K40030(H/T)-□	R88M-KH40030(H/T)-□
		750 W	R88D-KN08H-ECT	R88M-K75030(H/T)-□	R88M-KH75030(H/T)-□
		1.0 kW	R88D-KN10H-ECT	R88M-K1K020(H/T)-□	–
		1.5 kW	R88D-KN15H-ECT	R88M-K1K030(H/T)-□	–
				R88M-K1K530(H/T)-□	–
				R88M-K1K520(H/T)-□	–
				R88M-K90010(H/T)-□	–
	3 phase 400 VAC	600 W	R88D-KN06F-ECT	R88M-K40020(F/C)-□	–
				R88M-K60020(F/C)-□	–
		1.0 kW	R88D-KN10F-ECT	R88M-K75030(F/C)-□	–
				R88M-K1K020(F/C)-□	R88M-KH1K020(F/C)-□
		1.5 kW	R88D-KN15F-ECT	R88M-K1K030(F/C)-□	–
				R88M-K1K530(F/C)-□	–
				R88M-K1K520(F/C)-□	R88M-KH1K520(F/C)-□
				R88M-K90010(F/C)-□	–
		2.0 kW	R88D-KN20F-ECT	R88M-K2K030(F/C)-□	–
				R88M-K2K020(F/C)-□	R88M-KH2K020(F/C)-□
		3.0 kW	R88D-KN30F-ECT	R88M-K3K030(F/C)-□	–
				R88M-K3K020(F/C)-□	R88M-KH3K020(F/C)-□
				R88M-K2K010(F/C)-□	–
		5.0 kW	R88D-KN50F-ECT	R88M-K4K030(F/C)-□	–
				R88M-K5K030(F/C)-□	–
				R88M-K4K020(F/C)-□	R88M-KH4K020(F/C)-□
				R88M-K5K020(F/C)-□	R88M-KH5K020(F/C)-□
				R88M-K4K510C-□	–
				R88M-K3K010(F/C)-□	–
		7.5 kW	R88D-KN75F-ECT	R88M-K6K010C-□	–
				R88M-K7K515C-□	R88M-KH7K515C-□
		15 kW	R88D-KN150F-ECT	R88M-K11K015C-□	–
				R88M-K15K015C-□	–

Signals cables for I/O general purpose (CN1)

Symbol	Description	Connect to		Model
④	I/O connector kit (26 pins)	For I/O general purpose	–	R88A-CNW01C
⑤	I/O signals cable	For I/O general purpose	1 m	R88A-CPKB001S-E
			2 m	R88A-CPKB002S-E
⑥	Terminal block cable	For I/O general purpose	1 m	XW2Z-100J-B34
			2 m	XW2Z-200J-B34
⑦	Terminal block (M3 screw and for pin terminals)		–	XW2B-20G4
	Terminal block (M3.5 screw and for fork/round terminals)		–	XW2B-20G5
	Terminal block (M3 screw and for fork/round terminals)		–	XW2D-20G6

External encoder cable (CN4)

Symbol	Name		Model
⑧	External encoder cable	5 m	R88A-CRKM005SR-E
		10 m	R88A-CRKM010SR-E
		20 m	R88A-CRKM020SR-E

Analog monitor (CN5)

Symbol	Name		Model
⑨	Analog monitor cable	1 m	R88A-CMK001S

USB personal computer cable (CN7)

Symbol	Name		Model
⑩	USB mini-connector cable	2 m	AX-CUSBM002-E

Cable for safety (CN8)

Symbol	Name		Model
⑪	Safety cable	3 m	R88A-CSK003S-E

EtherCAT controllers

Symbol	Name		Model
⑫	NJ-series	CPU unit	NJ501-1500 (64 axes)
			NJ501-1400 (32 axes)
			NJ501-1300 (16 axes)
			NJ301-1200 (8 axes)
			NJ301-1100 (4 axes)
		Power supply unit	NJ-PA3001 (220 VDC)
			NJ-PD3001 (24 VDC)
	Trajexia stand-alone	Motion control unit	TJ2-MC64 (64 axes)
		EtherCAT master unit	TJ2-ECT64 (64 axes)
			TJ2-ECT16 (16 axes)
			TJ2-ECT04 (4 axes)
	Position controller unit for CJ1 PLC series		CJ1W-NCF8□ (16 axes)
			CJ1W-NC88□ (8 axes)
			CJ1W-NC48□ (4 axes)
			CJ1W-NC281(2 axes)

External regenerative resistor

Symbol	Regenerative resistor unit model	Specifications
⑬	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

Filters

Symbol	Applicable servodrive	Filter model	Manufacturer	Rated current	Leakage current	Rated voltage
⑭	R88D-KN01H-ECT, R88D-KN02H-ECT	R88A-FIK102-RE	Rasmi Electronics Ltd	2.4 A	3.5 mA	250 VAC single-phase
	R88D-KN04H-ECT	R88A-FIK104-RE		4.1 A	3.5 mA	
	R88D-KN08H-ECT	R88A-FIK107-RE		6.6 A	3.5 mA	
	R88D-KN10H-ECT, R88D-KN15H-ECT	R88A-FIK114-RE		14.2 A	3.5 mA	
	R88D-KN06F-ECT, R88D-KN10F-ECT, R88D-KN15F-ECT	R88A-FIK304-RE		4 A	0.3 mA / 32 mA*1	400 VAC three-phase
	R88D-KN20F-ECT	R88A-FIK306-RE		6 A	0.3 mA / 32 mA*1	
	R88D-KN30F-ECT, R88D-KN50F-ECT	R88A-FIK312-RE		12.1 A	0.3 mA / 32 mA*1	
	R88D-KN75F-ECT	R88A-FIK330-RE		22 A	0.3 mA / 40 mA*1	
	R88D-KN150F-ECT	R88A-FIK350-RE		44 A	2 mA / 130 mA*1	

*1 Momentary peak leakage current for the filter at switch-on/off.

Connectors

Specifications	Model
External encoder connector (for CN4)	R88A-CNK41L
Safety I/O signal connector (for CN8)	R88A-CNK81S

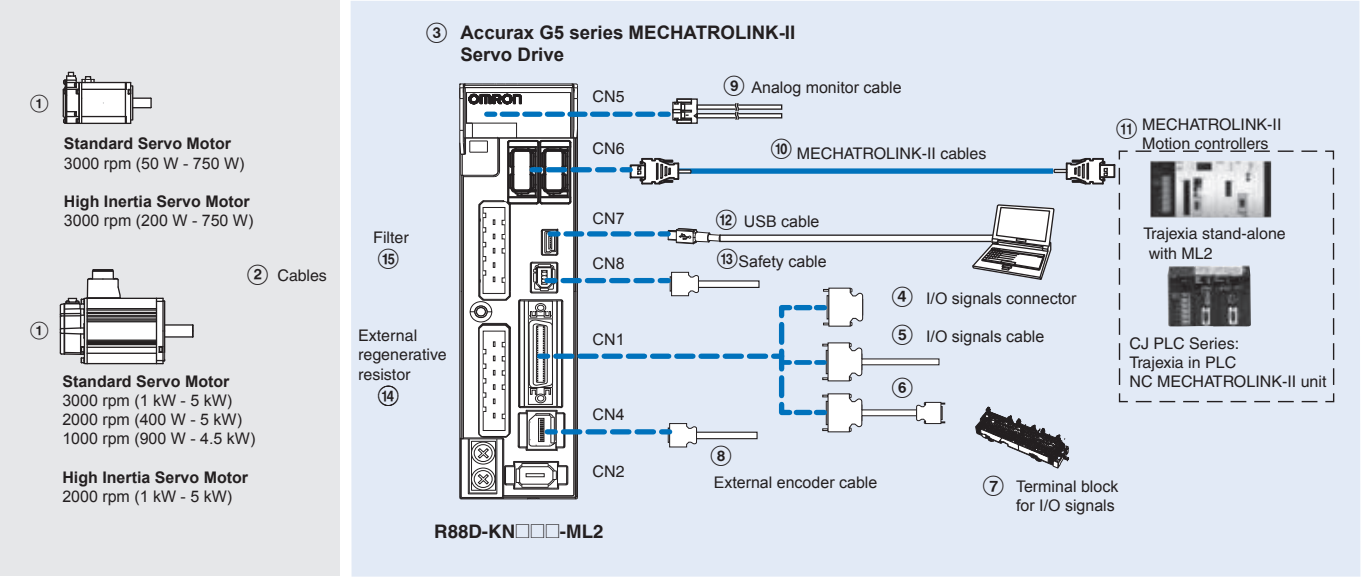
Computer software

Specifications	Model
Sysmac Studio version 1.0 or higher	SYSMAC-SE2□□□
CX-Drive version 2.10 or higher	CX-DRIVE 2.10
CX-One software package including CX-Drive 2.10 or higher	CX-ONE

Note: If CX-One is installed on the same computer as Sysmac Studio, it must be CX-One v4.2 or higher

Ordering information

Accurax G5 series MECHATROLINK-II reference configuration



Note: The symbols ①②③④⑤... show the recommended sequence to select the components in Accurax G5 servo system

Servo motors, power & encoder cables

Note: ①② Refer to the Accurax G5 servo motor chapter for servomotor, motor cables or connectors selection

Servo drives

Symbol	Specifications		Servo drive models	① Compatible G5 series rotary servo motors	
				Standard models	High inertia models
③	1 phase 230 VAC	100 W	R88D-KN01H-ML2	R88M-K05030(H/T)-□	–
				R88M-K10030(H/T)-□	–
		200 W	R88D-KN02H-ML2	R88M-K20030(H/T)-□	R88M-KH20030(H/T)-□
		400 W	R88D-KN04H-ML2	R88M-K40030(H/T)-□	R88M-KH40030(H/T)-□
		750 W	R88D-KN08H-ML2	R88M-K75030(H/T)-□	R88M-KH75030(H/T)-□
		1.0 kW	R88D-KN10H-ML2	R88M-K1K020(H/T)-□	–
		1.5 kW	R88D-KN15H-ML2	R88M-K1K030(H/T)-□	–
				R88M-K1K530(H/T)-□	–
				R88M-K1K520(H/T)-□	–
				R88M-K90010(H/T)-□	–
	3 phase 400 VAC	600 W	R88D-KN06F-ML2	R88M-K40020(F/C)-□	–
				R88M-K60020(F/C)-□	–
		1.0 kW	R88D-KN10F-ML2	R88M-K75030(F/C)-□	–
				R88M-K1K020(F/C)-□	R88M-KH1K020(F/C)-□
		1.5 kW	R88D-KN15F-ML2	R88M-K1K030(F/C)-□	–
				R88M-K1K530(F/C)-□	–
				R88M-K1K520(F/C)-□	R88M-KH1K520(F/C)-□
				R88M-K90010(F/C)-□	–
		2.0 kW	R88D-KN20F-ML2	R88M-K2K030(F/C)-□	–
				R88M-K2K020(F/C)-□	R88M-KH2K020(F/C)-□
		3.0 kW	R88D-KN30F-ML2	R88M-K3K030(F/C)-□	–
				R88M-K3K020(F/C)-□	R88M-KH3K020(F/C)-□
				R88M-K2K010(F/C)-□	–
		5.0 kW	R88D-KN50F-ML2	R88M-K4K030(F/C)-□	–
				R88M-K5K030(F/C)-□	–
				R88M-K4K020(F/C)-□	R88M-KH4K020(F/C)-□
				R88M-K5K020(F/C)-□	R88M-KH5K020(F/C)-□
				R88M-K4K510C-□	–
				R88M-K3K010(F/C)-□	–

Control cables (CN1)

Symbol	Description	Connect to		Model
④	I/O connector kit (26 pins)	For I/O general purpose	–	R88A-CNW01C
⑤	I/O signals cable		1 m	R88A-CPKB001S-E
			2 m	R88A-CPKB002S-E
⑥	Terminal block cable	For I/O general purpose	1 m	XW2Z-100J-B34
			2 m	XW2Z-200J-B34
⑦	Terminal block (M3 screw and for pin terminals)		–	XW2B-20G4
	Terminal block (M3.5 screw and for fork/round terminals)		–	XW2B-20G5
	Terminal block (M3 screw and for fork/round terminals)		–	XW2D-20G6

External encoder cable (CN4)

Symbol	Name	Length	Model
⑧	External encoder cable	5 m	R88A-CRKM005SR-E
		10 m	R88A-CRKM010SR-E
		20 m	R88A-CRKM020SR-E

Analog monitor (CN5)

Symbol	Name	Length	Model
⑨	Analog monitor cable	1 m	R88A-CMK001S

MECHATROLINK-II cables (CN6)

Symbol	Specifications	Length	Model
⑩	MECHATROLINK-II Terminator resistor	–	JEPMC-W6022-E
	MECHATROLINK-II cables	0.5 m	JEPMC-W6003-A5-E
		1 m	JEPMC-W6003-01-E
		3 m	JEPMC-W6003-03-E
		5 m	JEPMC-W6003-05-E
		10 m	JEPMC-W6003-10-E
		20 m	JEPMC-W6003-20-E
		30 m	JEPMC-W6003-30-E

USB personal computer cable (CN7)

Symbol	Name	Length	Model
⑫	USB mini-connector cable	2m	AX-CUSBM002-E

Cable for Safety Functions (CN8)

Symbol	Description	Model
⑬	Safety connector with 3 m cable (with loose wires at one end)	R88A-CSK003S-E

External regenerative resistor

Symbol	Regenerative resistor unit model	Specifications
⑭	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

MECHATROLINK-II Motion controllers

Symbol	Name		Model
⑪	Trajexia stand-alone	Motion control unit	TJ2-MC64 (64 axes)
			TJ1-MC16 (16 axes)
			TJ1-MC04 (4 axes)
		ML2 master unit	TJ1-ML16 (16 axes)
			TJ1-ML04 (4 axes)
	Trajexia-PLC motion controller		CJ1W-MCH72 (30 axes)
			CJ1W-MC472 (4 axes)
	Position Controller Unit for CJ1 PLC		CJ1W-NCF71 (16 axes)
			CJ1W-NC471 (4 axes)
			CJ1W-NC271 (2 axes)
	Position Controller Unit for CS1 PLC		CS1W-NCF71 (16 axes)
			CS1W-NC471 (4 axes)
			CS1W-NC271 (2 axes)

Filters

Symbol	Applicable servodrive	Filter model	Manufacturer	Rated current	Leakage current	Rated voltage
⑮	R88D-KN01H-ML2, R88D-KN02H-ML2	R88A-FIK102-RE	Rasmi Electronics Ltd	2.4 A	3.5 mA	250 VAC single-phase
	R88D-KN04H-ML2	R88A-FIK104-RE		4.1 A	3.5 mA	
	R88D-KN08H-ML2	R88A-FIK107-RE		6.6 A	3.5 mA	
	R88D-KN10H-ML2, R88D-KN15H-ML2	R88A-FIK114-RE		14.2 A	3.5 mA	
	R88D-KN06F-ML2, R88D-KN10F-ML2, R88D-KN15F-ML2	R88A-FIK304-RE		4 A	0.3 mA/32 mA*1	400 VAC three-phase
	R88D-KN20F-ML2	R88A-FIK306-RE		6 A	0.3 mA/32 mA*1	
	R88D-KN30F-ML2, R88D-KN50F-ML2	R88A-FIK312-RE		12.1 A	0.3 mA/32 mA*1	

*1 Momentary peak leakage current for the filter at switch-on/off.

Connectors

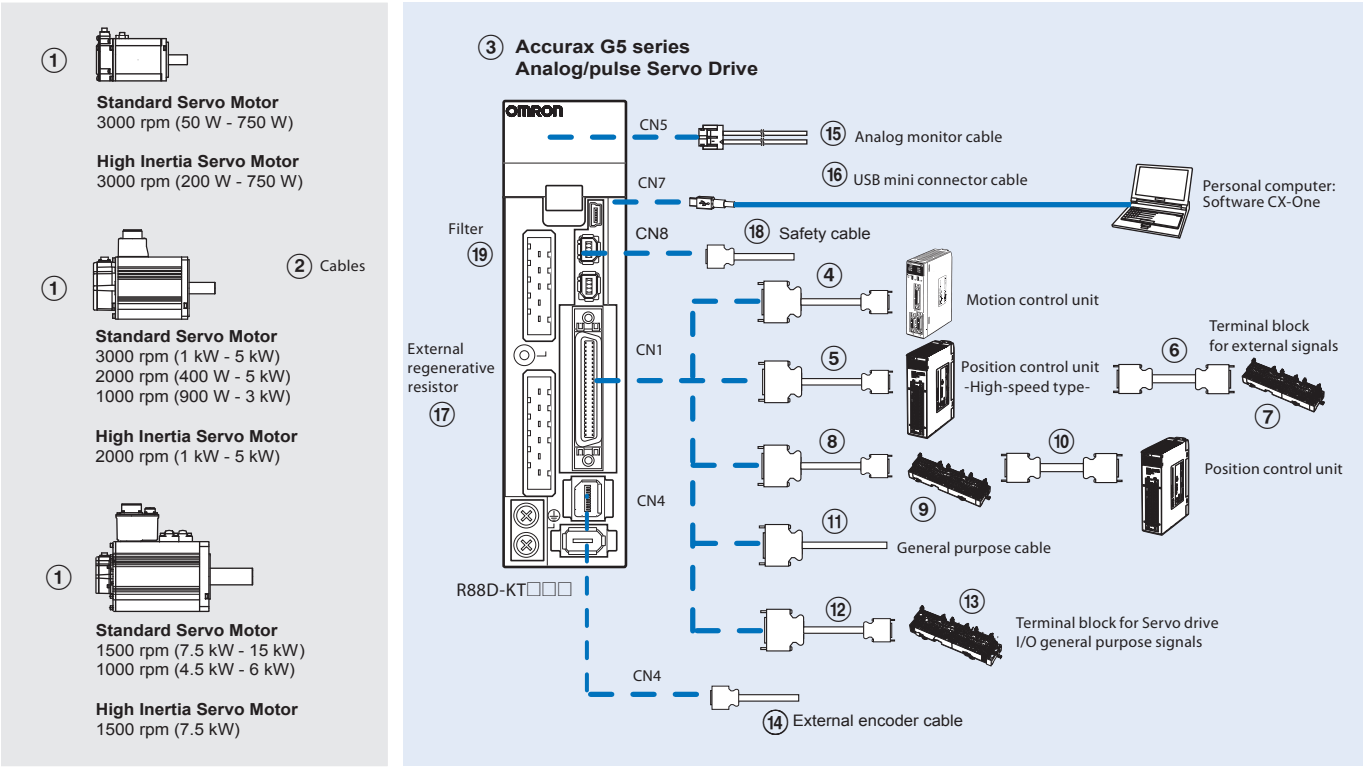
Specifications	Model
External encoder connector (for CN4)	R88A-CNK41L
Safety I/O signal connector (for CN8)	R88A-CNK81S

Computer software

Specifications	Model
CX-Drive version 1.91 or higher	CX-DRIVE 1.91
CX-One software package including CX-Drive 1.91 or higher	CX-ONE

Ordering information

Accurax G5 series Analog/pulse reference configuration



Note: The symbols ①②③④⑤... show the recommended sequence to select the components in Accurax G5 servo system

Servo motors, power & encoder cables

Note: ①② Refer to the Accurax G5 servo motor chapter for servomotor, motor cables or connectors selection

Servo drives

Symbol	Specifications		Servo drive models*1	① Compatible Accurax G5 series rotary servo motors	
				Standard models	High inertia models
③	1 phase 230 VAC	100 W	R88D-KT01H	R88M-K05030(H/T)-□	–
				R88M-K10030(H/T)-□	–
		200 W	R88D-KT02H	R88M-K20030(H/T)-□	R88M-KH20030(H/T)-□
		400 W	R88D-KT04H	R88M-K40030(H/T)-□	R88M-KH40030(H/T)-□
		750 W	R88D-KT08H	R88M-K75030(H/T)-□	R88M-KH75030(H/T)-□
		1.0 kW	R88D-KT10H	R88M-K1K020(H/T)-□	–
		1.5 kW	R88D-KT15H	R88M-K1K030(H/T)-□	–
				R88M-K1K530(H/T)-□	–
				R88M-K1K520(H/T)-□	–
				R88M-K90010(H/T)-□	–
	3 phase 400 VAC	600 W	R88D-KT06F	R88M-K40020(F/C)-□	–
				R88M-K60020(F/C)-□	–
		1.0 kW	R88D-KT10F	R88M-K75030(F/C)-□	–
				R88M-K1K020(F/C)-□	R88M-KH1K020(F/C)-□
		1.5 kW	R88D-KT15F	R88M-K1K030(F/C)-□	–
				R88M-K1K530(F/C)-□	–
				R88M-K1K520(F/C)-□	R88M-KH1K520(F/C)-□
				R88M-K90010(F/C)-□	–
		2.0 kW	R88D-KT20F	R88M-K2K030(F/C)-□	–
				R88M-K2K020(F/C)-□	R88M-KH2K020(F/C)-□
		3.0 kW	R88D-KT30F	R88M-K3K030(F/C)-□	–
				R88M-K3K020(F/C)-□	R88M-KH3K020(F/C)-□
				R88M-K2K010(F/C)-□	–
		5.0 kW	R88D-KT50F	R88M-K4K030(F/C)-□	–
				R88M-K5K030(F/C)-□	–
				R88M-K4K020(F/C)-□	R88M-KH4K020(F/C)-□
				R88M-K5K020(F/C)-□	R88M-KH5K020(F/C)-□
				R88M-K4K510C-□	–
				R88M-K3K010(F/C)-□	–
		7.5 kW	R88D-KT75F	R88M-K6K010C-□	–
				R88M-K7K515C-□	R88M-KH7K515C-□
		15 kW	R88D-KT150F	R88M-K11K015C-□	–
				R88M-K15K015C-□	–

*1 Drive Programming – embedded indexer functionality – is available in the Accurax G5 Analogue/pulse models with firmware 1.10 or higher.

Control cables (CN1)

Symbol	Description	Connect to		Model
④	Control cable (1 axis)	Motion control units CS1W-MC221 CS1W-MC421	1 m	R88A-CPG001M1
			2 m	R88A-CPG002M1
			3 m	R88A-CPG003M1
			5 m	R88A-CPG005M1
	Control cable (2 axes)	Motion control units CS1W-MC221 CS1W-MC421	1 m	R88A-CPG001M2
			2 m	R88A-CPG002M2
			3 m	R88A-CPG003M2
			5 m	R88A-CPG005M2
⑤	Control cable (line-driver output for 1 axis)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434	1 m	XW2Z-100J-G9
			5 m	XW2Z-500J-G9
			10 m	XW2Z-10MJ-G9
	Control cable (open-collector output for 1 axis)	Position control units (high-speed type) CJ1W-NC214 CJ1W-NC414	1 m	XW2Z-100J-G13
			3 m	XW2Z-300J-G13
	Control cable (line-driver output for 2 axes)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434	1 m	XW2Z-100J-G1
			5 m	XW2Z-500J-G1
			10 m	XW2Z-10MJ-G1
	Control cable (open-collector output for 2 axes)	Position control units (high-speed type) CJ1W-NC214 CJ1W-NC414	1 m	XW2Z-100J-G5
			3 m	XW2Z-300J-G5
⑥	Terminal block cable for external signals (for input common, forward/reverse run prohibited inputs, emergency stop input, origin proximity input and interrupt input)	Position control units (high-speed type) CJ1W-NC234 CJ1W-NC434 CJ1W-NC214 CJ1W-NC414	0.5 m	XW2Z-C50X
			1 m	XW2Z-100X
			2 m	XW2Z-200X
			3 m	XW2Z-300X
			5 m	XW2Z-500X
			10 m	XW2Z-010X
⑦	Terminal block for external signals (M3 screw, pin terminals)		–	XW2B-20G4
	Terminal block for ext. signals (M3.5 screw, fork/round terminals)		–	XW2B-20G5
	Terminal block for ext. signals (M3 screw, fork/round terminals)		–	XW2D-20G6
⑧	Cable from servo relay unit to servo drive	CS1W-NC1□3, CJ1W-NC1□3, C200HW-NC113, CS1W-NC2□3/4□3, CJ1W-NC2□3/4□3, C200HW-NC213/413, CQM1H-PLB21 or CQM1-CPU43	1 m	XW2Z-100J-B25
			2 m	XW2Z-200J-B25
		CJ1M-CPU21/22/23	1 m	XW2Z-100J-B31
			2 m	XW2Z-200J-B31
⑨	Servo relay unit	Position control units CS1W-NC1□3, CJ1W-NC1□3 or C200HW-NC113	–	XW2B-20J6-1B (1 axis)
		Position control units CS1W-NC2□3/4□3, CJ1W-NC2□3/4□3 or C200HW-NC213/413	–	XW2B-40J6-2B (2 axes)
		CQM1H-PLB21 or CQM1-CPU43	–	XW2B-20J6-3B (1 axis)
		CJ1M-CPU21/22/23	–	XW2B-20J6-8A (1 axis) XW2B-40J6-9A (2 axes)
⑩	Position control unit connecting cable	CQM1H-PLB21	0.5 m	XW2Z-050J-A3
			1 m	XW2Z-100J-A3
		CS1W-NC113 or C200HW-NC113	0.5 m	XW2Z-050J-A6
			1 m	XW2Z-100J-A6
		CS1W-NC213/413 or C200HW-NC213/413	0.5 m	XW2Z-050J-A7
			1 m	XW2Z-100J-A7
		CS1W-NC133	0.5 m	XW2Z-050J-A10
			1 m	XW2Z-100J-A10
		CS1W-NC233/433	0.5 m	XW2Z-050J-A11
			1 m	XW2Z-100J-A11
		CJ1W-NC113	0.5 m	XW2Z-050J-A14
			1 m	XW2Z-100J-A14
		CJ1W-NC213/413	0.5 m	XW2Z-050J-A15
			1 m	XW2Z-100J-A15
		CJ1W-NC133	0.5 m	XW2Z-050J-A18
			1 m	XW2Z-100J-A18
		CJ1W-NC233/433	0.5 m	XW2Z-050J-A19
			1 m	XW2Z-100J-A19
		CJ1M-CPU21/22/23	0.5 m	XW2Z-050J-A33
			1 m	XW2Z-100J-A33
⑪	General purpose cable	For general purpose controllers	1 m	R88A-CPG001S
			2 m	R88A-CPG002S
⑫	Terminal block cable	For general purpose controllers	1 m	XW2Z-100J-B24
			2 m	XW2Z-200J-B24
⑬	Terminal block (M3 screw and for pin terminals)		–	XW2B-50G4
	Terminal block (M3.5 screw and for fork/round terminals)		–	XW2B-50G5
	Terminal block (M3 screw and for fork/round terminals)		–	XW2D-50G6

External encoder cable (CN4)

Symbol	Name		Model
⑭	External encoder cable	5 m	R88A-CRKM005SR-E
		10 m	R88A-CRKM010SR-E
		20 m	R88A-CRKM020SR-E

Analog monitor (CN5)

Symbol	Name		Model
⑮	Analog monitor cable	1 m	R88A-CMK001S

USB personal computer cable (CN7)

Symbol	Name		Model
⑯	USB mini-connector cable	2 m	AX-CUSBM002-E

External regenerative resistor

Symbol	Regenerative resistor unit model	Specifications
⑰	R88A-RR08050S	50 Ω, 80 W
	R88A-RR080100S	100 Ω, 80 W
	R88A-RR22047S	47 Ω, 220 W
	R88A-RR50020S	20 Ω, 500 W

Cable for Safety Functions (CN8)

Symbol	Description	Model
⑱	Safety connector with 3 m cable (with loose wires at one end)	R88A-CSK003S-E

Filters

Symbol	Applicable servodrive	Filter model	Manufacturer	Rated current	Leakage current	Rated voltage
⑲	R88D-KT01H, R88D-KT02H	R88A-FIK102-RE	Rasmi Electronics Ltd	2.4 A	3.5 mA	250 VAC single-phase
	R88D-KT04H	R88A-FIK104-RE		4.1 A	3.5 mA	
	R88D-KT08H	R88A-FIK107-RE		6.6 A	3.5 mA	
	R88D-KT10H, R88D-KT15H	R88A-FIK114-RE		14.2 A	3.5 mA	
	R88D-KT06F, R88D-KT10F, R88D-KT15F	R88A-FIK304-RE		4 A	0.3 mA / 32 mA*1	400 VAC three-phase
	R88D-KT20F	R88A-FIK306-RE		6 A	0.3 mA / 32 mA*1	
	R88D-KT30F, R88D-KT50F	R88A-FIK312-RE		12.1 A	0.3 mA / 32 mA*1	
	R88D-KT75F	R88A-FIK330-RE		22 A	0.3 mA / 40 mA*1	
	R88D-KT150F	R88A-FIK350-RE		44 A	2 mA / 130 mA*1	

*1 Momentary peak leakage current for the filter at switch-on/off.

Connectors

Specifications	Model
I/O connector kit -50 pins-(for CN1)	R88A-CNU11C
External encoder connector (for CN4)	R88A-CNK41L
Safety I/O signal connector (for CN8)	R88A-CNK81S

Computer software

Specifications	Model
CX-Drive version 2.10 or higher	CX-DRIVE 2.10
CX-One software packaging including CX-Drive 2.10 or higher	CX-ONE

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

Cat. No. I101E-EN-04A In the interest of product improvement, specifications are subject to change without notice.

OMRON

Terms and Conditions of Sale

1. Offer; Acceptance. These terms and conditions (these "Terms") are deemed part of all quotes, agreements, purchase orders, acknowledgments, price lists, catalogs, manuals, brochures and other documents, whether electronic or in writing, relating to the sale of products or services (collectively, the "Products") by Omron Electronics LLC and its subsidiary companies ("Omron"). Omron objects to any terms or conditions proposed in Buyer's purchase order or other documents which are inconsistent with, or in addition to, these Terms.
2. Prices; Payment Terms. All prices stated are current, subject to change without notice by Omron. Omron reserves the right to increase or decrease prices on any unshipped portions of outstanding orders. Payments for Products are due net 30 days unless otherwise stated in the invoice.
3. Discounts. Cash discounts, if any, will apply only on the net amount of invoices sent to Buyer after deducting transportation charges, taxes and duties, and will be allowed only if (i) the invoice is paid according to Omron's payment terms and (ii) Buyer has no past due amounts.
4. Interest. Omron, at its option, may charge Buyer 1-1/2% interest per month or the maximum legal rate, whichever is less, on any balance not paid within the stated terms.
5. Orders. Omron will accept no order less than $200 net billing.
6. Governmental Approvals. Buyer shall be responsible for, and shall bear all costs involved in, obtaining any government approvals required for the importation or sale of the Products.
7. Taxes. All taxes, duties and other governmental charges (other than general real property and income taxes), including any interest or penalties thereon, imposed directly or indirectly on Omron or required to be collected directly or indirectly by Omron for the manufacture, production, sale, delivery, importation, consumption or use of the Products sold hereunder (including customs duties and sales, excise, use, turnover and license taxes) shall be charged to and remitted by Buyer to Omron.
8. Financial. If the financial position of Buyer at any time becomes unsatisfactory to Omron, Omron reserves the right to stop shipments or require satisfactory security or payment in advance. If Buyer fails to make payment or otherwise comply with these Terms or any related agreement, Omron may (without liability and in addition to other remedies) cancel any unshipped portion of Products sold hereunder and stop any Products in transit until Buyer pays all amounts, including amounts payable hereunder, whether or not then due, which are owing to it by Buyer. Buyer shall in any event remain liable for all unpaid accounts.
9. Cancellation; Etc. Orders are not subject to rescheduling or cancellation unless Buyer indemnifies Omron against all related costs or expenses.
10. Force Majeure. Omron shall not be liable for any delay or failure in delivery resulting from causes beyond its control, including earthquakes, fires, floods, strikes or other labor disputes, shortage of labor or materials, accidents to machinery, acts of sabotage, riots, delay in or lack of transportation or the requirements of any government authority.
11. Shipping; Delivery. Unless otherwise expressly agreed in writing by Omron:
    a. Shipments shall be by a carrier selected by Omron; Omron will not drop ship except in "break down" situations.
    b. Such carrier shall act as the agent of Buyer and delivery to such carrier shall constitute delivery to Buyer;
    c. All sales and shipments of Products shall be FOB shipping point (unless otherwise stated in writing by Omron), at which point title and risk of loss shall pass from Omron to Buyer; provided that Omron shall retain a security interest in the Products until the full purchase price is paid;
    d. Delivery and shipping dates are estimates only; and
    e. Omron will package Products as it deems proper for protection against normal handling and extra charges apply to special conditions.
12. Claims. Any claim by Buyer against Omron for shortage or damage to the Products occurring before delivery to the carrier must be presented in writing to Omron within 30 days of receipt of shipment and include the original transportation bill signed by the carrier noting that the carrier received the Products from Omron in the condition claimed.
13. Warranties. (a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied. (b) Limitations. OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right. (c) Buyer Remedy. Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty. See http://www.omron247.com or contact your Omron representative for published information.
14. Limitation on Liability; Etc. OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY. Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.
15. Indemnities. Buyer shall indemnify and hold harmless Omron Companies and their employees from and against all liabilities, losses, claims, costs and expenses (including attorney's fees and expenses) related to any claim, investigation, litigation or proceeding (whether or not Omron is a party) which arises or is alleged to arise from Buyer's acts or omissions under these Terms or in any way with respect to the Products. Without limiting the foregoing, Buyer (at its own expense) shall indemnify and hold harmless Omron and defend or settle any action brought against such Companies to the extent based on a claim that any Product made to Buyer specifications infringed intellectual property rights of another party.
16. Property; Confidentiality. Any intellectual property in the Products is the exclusive property of Omron Companies and Buyer shall not attempt to duplicate it in any way without the written permission of Omron. Notwithstanding any charges to Buyer for engineering or tooling, all engineering and tooling shall remain the exclusive property of Omron. All information and materials supplied by Omron to Buyer relating to the Products are confidential and proprietary, and Buyer shall limit distribution thereof to its trusted employees and strictly prevent disclosure to any third party.
17. Export Controls. Buyer shall comply with all applicable laws, regulations and licenses regarding (i) export of products or information; (iii) sale of products to "forbidden" or other proscribed persons; and (ii) disclosure to non-citizens of regulated technology or information.
18. Miscellaneous. (a) Waiver. No failure or delay by Omron in exercising any right and no course of dealing between Buyer and Omron shall operate as a waiver of rights by Omron. (b) Assignment. Buyer may not assign its rights hereunder without Omron's written consent. (c) Law. These Terms are governed by the law of the jurisdiction of the home office of the Omron company from which Buyer is purchasing the Products (without regard to conflict of law principles). (d) Amendment. These Terms constitute the entire agreement between Buyer and Omron relating to the Products, and no provision may be changed or waived unless in writing signed by the parties. (e) Severability. If any provision hereof is rendered ineffective or invalid, such provision shall not invalidate any other provision. (f) Setoff. Buyer shall have no right to set off any amounts against the amount owing in respect of this invoice. (g) Definitions. As used herein, "including" means "including without limitation"; and "Omron Companies" (or similar words) mean Omron Corporation and any direct or indirect subsidiary or affiliate thereof.

Certain Precautions on Specifications and Use

1. Suitability of Use. Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases but the following is a non-exhaustive list of applications for which particular attention must be given:
   (i) Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this document.
   (ii) Use in consumer products or any use in significant quantities.
   (iii) Energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
   (iv) Systems, machines and equipment that could present a risk to life or property. Please know and observe all prohibitions of use applicable to this Product.
   NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON'S PRODUCT IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.
2. Programmable Products. Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.
3. Performance Data. Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.
4. Change in Specifications. Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.
5. Errors and Omissions. Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

OMRON
AUTOMATION & SAFETY

OMRON AUTOMATION AND SAFETY • THE AMERICAS HEADQUARTERS • Chicago, IL USA • 847.843.7900 • 800.556.6766 • www.omron247.com

OMRON CANADA, INC. • HEAD OFFICE
Toronto, ON, Canada • 416.286.6465 • 866.986.6766 • www.omron247.com

OMRON ELECTRONICS DE MEXICO • HEAD OFFICE
México DF • 52.55.59.01.43.00 • 01-800-226-6766 • mela@omron.com

OMRON ELECTRONICS DE MEXICO • SALES OFFICE
Apodaca, N.L. • 52.81.11.56.99.20 • 01-800-226-6766 • mela@omron.com

OMRON ELETRÔNICA DO BRASIL LTDA • HEAD OFFICE
São Paulo, SP, Brasil • 55.11.2101.6300 • www.omron.com.br

OMRON ARGENTINA • SALES OFFICE
Cono Sur • 54.11.4783.5300

OMRON CHILE • SALES OFFICE
Santiago • 56.9.9917.3920

OTHER OMRON LATIN AMERICA SALES
54.11.4783.5300

OMRON EUROPE B.V. • Wegalaan 67-69, NL-2132 JD, Hoofddorp, The Netherlands. • +31 (0) 23 568 13 00 • www.industrial.omron.eu

Authorized Distributor:

Automation Control Systems
• Machine Automation Controllers (MAC) • Programmable Controllers (PLC)
• Operator interfaces (HMI) • Distributed I/O • Software

Drives & Motion Controls
• Servo & AC Drives • Motion Controllers & Encoders

Temperature & Process Controllers
• Single and Multi-loop Controllers

Sensors & Vision
• Proximity Sensors • Photoelectric Sensors • Fiber-Optic Sensors
• Amplified Photomicrosensors • Measurement Sensors
• Ultrasonic Sensors • Vision Sensors

Industrial Components
• RFID/Code Readers • Relays • Pushbuttons & Indicators
• Limit and Basic Switches • Timers • Counters • Metering Devices
• Power Supplies

Safety
• Laser Scanners • Safety Mats • Edges and Bumpers • Programmable Safety Controllers • Light Curtains • Safety Relays • Safety Interlock Switches

I101-EN-04A 10/14 Note: Specifications are subject to change. Printed in U.S.A.

Printed on recycled paper.

X-ON Electronics

Largest Supplier of Electrical and Electronic Components

Click to view similar products for Controllers ***category:***

Click to view products by Omron ***manufacturer:***

Other Similar products are found below :

61FGPN8DAC120 CV500SLK21 70177-1011 F03-03 HAS C F03-31 81550401 FT1A-C12RA-W 88981106 H2CAC24A H2CRSAC110B R88A-CRGB003CR-E R88ARR080100S R88A-TK01K DCN1-1 DRT2ID08C DTB4896VRE DTB9696CVE DTB9696LVE E53-AZ01 E53E01 E53E8C E5C4Q40J999FAC120 E5CWLQ1TCAC100240 E5GNQ03PFLKACDC24 B300LKL21 NSCXDC1V3 NSH5-232CW-3M NT20SST122BV1 NV-CN001 OAS-160-N C40PEDRA K31S6 K33-L1B K3MA-F 100-240VAC K3TX-AD31A 89750101 L595020 SRM1-C02 SRS2-1 FT1A-C14SA-S G32X-V2K 26546803 26546805 PWRA440A CPM1AETL03CH CV500SLK11 3G2A5BI081 3G2A5IA122 3G2A5LK010E 3G2A5OA223