


## Long-distance Communications Mode Eliminates Wiring Restrictions for More Efficient System Desig

## System Design

With conventional High-speed Communications Mode, the following restrictions on the number of branching points and cable length had to be considered when designing the system.
With a Special Flat Cable or a 4-conductor VCTF cable:
Main line length $A: 30 \mathrm{~m}$ max. Branch line lengths $B, C$, and $D: 3 \mathrm{~m}$ max. Total branch line length $B+C+D: 30 \mathrm{~m}$ max.


Baud rate: 750 kbps (in High-speed Communications Mode)

* With 2-conductor VCTF cable (in High-speed Communications Mode), main line length: 100 m max

Using CompoBus/S Long-distance Communications Mode (with a Special Flat Cable or a 4 conductor VCTF cable) removes restrictions on main and branch line lengths. Branch freely up to a total cable length of 200 m


Greatly Saves Wiring and Installation Effort and Time for System Maintenance and Expansion

## Programmable Slaves

## A slave with the complex functional

Programmable Slaves combine devices, such as sensors and actuators, into one functional unit that is treated as a DeviceNet slave.
Programmable Slaves greatly facilitate device distribution and functional organization. They help standardize programming between units and reduce the amount of programming required at the master. I/O and operational checks can be performed for each functional unit, rather than waiting for final system assembly, as with conventional distributed I/O systems.

## DeviceNet ${ }_{w}$

Multiword I/O links and explicit messages are used to control slaves from the master. Log data for communications can be sent in one opessages. 1,024 - poin Explicit
Messages

## Devicenet- Compo Cusis Comoosus/s Caleway

## ity needed for distributed blocks.

## - Functions

OMRON Programmable Slaves function as DeviceNet slaves, yet they provide PLC functionality to enable easy system expansion and create new potential.


High-speed
Counter
Pulse Output
Interrupt
Inputs
Clackark
Clock
RS-232C
Connected to bar code readers, Programmable Terminals, and other devices, the Programmable Slave processes data locally to reduce the load on the master.

Nopropoocol
Communicaions NT Links $\quad$ Host Links


## Expansion Units

(3 max.)
Just one Unit is required for each distributed block, reducing the number of interfaces for multipoin communications to, in turn, reduce costs.


## CompoBus/S

Less wiring is required for terminal block expansions, connections to remote devices (such as signal lights or pushbutton switches), and connections to pneumatic valves and other non-OMRON products

$(0.8 \mathrm{~ms}, 100 \mathrm{~m}) \quad(\mathrm{mms}, 500 \mathrm{~m}$

## CompoBus/S Products

## Master Units

CPU Units with CompoBus/S Master CompoBus/S Master Control Units

Without RS-232C port With RS-232C port


CompoBus/S Master Units
Master Unit with 256 points
Master Unit with 128 points


C200HW-SRM21-V1


QM1-SRM21-V1
SYSMAC Board with CompoBus/S Master Functions


200PC-ISA $\square 3$-SRM

## Slave Units



|  | m |
| :---: | :---: |
| \% | \% |
| 4 50, | - |
|  | 15 |

## Connections to a Wider Range of Slaves Ensured by Upgraded Models

|  | Master | Conventional models | New | models |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | SRM21-V1 <br> RM21-V1 <br> C01-V2 <br> SA03-SRM <br> SA13-SRM <br> 00C (NEW) <br> 10C (NEW) <br> C-DRT (NEW) C-DRT (NEW) |
|  |  | NKE-made Uniwire | Communi | ations mode |
| Slave |  | CompoBus/S Send Unit SDD-CS1 | High-speed communications mode | Long-distance communications mode |
|  | SRT1 Series FND-X $\square$-SRT | $\begin{aligned} & \hline \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{array}{\|l\|l\|} \hline \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \hline \text { No } \\ & \text { No } \end{aligned}$ |
| Existing product | SRT2-AD04 SRT2-DA02 | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  | SRT2-V $\square 08 \mathrm{~S}(-1)$ SRT2-DD08S(-1) SRT2-7D16ML(-1) SRT2-RO $\square 16$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{array}{\|l\|l\|} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  | $\begin{aligned} & \text { SRT2-V } \square 08 \mathrm{~S}(-1) \\ & \text { SRT2-■D16(-1) } \\ & \text { SRT2-RO } \square 08 \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{array}{\|l\|l\|} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Ye } \end{aligned}$ |
|  | CPM2C-SRT21 | Yes | Yes | Yes |
|  | SRT2-पD32ML(-1) | Yes | Yes | Yes |
|  | CPM1A-SRT21 | Yes | Yes | Yes |
| New product | $\begin{aligned} & \hline \text { SRTT-ID04CL(-1) } \\ & \text { SRT2-ODO4L(-1) } \\ & \text { SRTTIDOCLL-(-1) } \\ & \text { SRT2-ODOBCL(-1) } \\ & \hline \end{aligned}$ | $\begin{aligned} & \hline \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{array}{\|l\|l} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  | SRT2-ID08S SRT2-ND08S SRT2-OD08S | $\begin{aligned} & \hline \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{array}{\|l\|l\|} \hline \text { Yes } \\ \text { Yes } \\ \text { Yes } \end{array}$ | $\begin{aligned} & \hline \text { Yes } \\ & \text { Yes } \\ & \text { Yes } \end{aligned}$ |
|  | SRT2-ID16P SRT2-OD16P | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ | $\begin{aligned} & \text { Yes } \\ & \text { Yes } \end{aligned}$ |

Note: 1. In high-speed communications mode, the maximum transmission distance is 100 m at a baud rate of $750 \mathrm{kbps}$. In long-distance communications mode (i.e., a newly available mode), the maximum transmission distance is 500 m at a baud rate of 93.75 kbps ,

| Company | Product | Model number | Communications mode |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | High-speed communications mode | Long-distance communications mode |
| CKD | Solenoid valve for saving wiring effort | 4TB1/2/3/4 Series | Yes | Yes (See note.) |
|  |  | 4G Series | Yes | Yes (See note.) |
|  |  | MN4SO Series | Yes | Yes (See note.) |
|  | Parect regulator | SDA-C | Yes | Yes |
| SMC | Solenoid valve for SI manifold use | VQ, SY, SX, SQ, SZ Series | Yes | Yes (See note.) |
| Koganei | F-series solenoid valve | YS2A1, YS2A2 | Yes | Yes |
|  | X80M/X88M Series | YS1A1, YS1A2 | Yes | Yes |
|  | JA-series solenoid valve | YS5A1, YS5A2 | Yes | Yes |
|  | PA, PB-series solenoid valve | YS4A1, YS4A2 | Yes | Yes |

Rete: Refer to the maker for information on long-distance commication mode

## CompoBus/S Connection Examples

High-speed ON/OFF Bus Communications in Remote I/O Systems


Special Flat Cable Connection
Master


Note: Cabtire cable and flat cable cannot be used together.

## omron

Ultra-compact, Thin-profile CPM2C CPU Unit with CompoBus/S Master Offering High-speed Bus Communications with No Complicated Wiring

Ultra-compact, thin-profile design ideal for on-site applications
Ultra-compact at $40 \times 90 \times 65 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$ with 10 I/O points and CompoBus/S Master offers versatile expandability to construct systems meeting on-site needs.

- A large number of expansion I/O points reduces system construction cost.
Up to three Expansion Terminals can be
connected. Furthermore connected. Furthermore, CompoBus/S Remot
Terminals can be used for expansion I/O points. Not only in-panel wiring but also external wiring is simplified. Furthermore, the miniaturization of the control panel reduces cable, terminal block, and
wiring costs.
- Easy System Designing, Modification, and Expansion
CompoBus/S Remote Terminals with high-speed bus communications and no complicated wiring can be used as expansion terminal blocks with expansion is reserved at the designing stage.
A calendar/clock ensures easy machinery control,
including data collection and error logs with date and time stamps. This functionality can be used as a weekly timer as well.



## Control Panel



## Ordering Information

| Unit |  | Inputs | Outputs | Clock | Model |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 10 points (6 inputs/4 <br> outputs) | Connector model | 6 points at 24 VDC | 4 transistor sinking outputs | Yes | CPM2C-S100C |
|  |  |  | 4 transistor sourcing outputs | Yes | CPM2C-S110C |

## Specifications

■ General Specifications

| Item |  | Specification |
| :---: | :---: | :---: |
| Control method |  | Stored program method |
| I/O control method |  | Cyclic scan method (Immediate refreshing can be performed with IORF(97).) |
| Programming language |  | Ladder diagram |
| Instruction length |  | 1 step per instruction <br> 1 to 5 words per instruction |
| Instructions | Basic instructions | 14 |
|  | Special instructions | 105 instructions, 185 variations |
| Execution time | Basic instructions | $0.64 \mu \mathrm{~s}$ (LD instruction) |
|  | Special instructions | $7.8 \mu \mathrm{~s}$ (MOV instruction) |
| Program capacity |  | 4,096 words |
| Max. I/O capacity |  | CPU Unit only: 10 points <br> Expansion I/O Unit: 96 points (32-point Expansion I/O Unit x 3 ) <br> (Up to 3 Expansion Units can be connected.) <br> CompoBus/S: 256 points ( 362 points in total) |
| Input bits |  | IR 00000 to IR 00915 (Bits not used for input bits can be used for work bits.) |
| Output bits |  | IR 01000 to IR 01915 <br> (Bits not used for output bits can be used for work bits.) |
| CompoBus/S input bits |  | 128 bits: IR 02000 to IR 02715 (words IR 020 to IR 027) |
| CompoBus/S output bits |  | 128 bits: IR 03000 to IR 03715 (words IR 030 to IR 037) |
| Work bits |  |  |
| Special bits (SR area) |  | 440 bits: SR 22800 to SR 25507 (words SR 228 to SR 255) |
| Temporary bits (TR area) |  | 8 bits: ( $\operatorname{TR} 0$ to TR 7) |
| Holding bits (HR area) |  | 320 bits: HR 0000 to HR 1915 (words HR 00 to HR 19) |
| Auxiliary bits (AR area) |  | 384 bits: AR 0000 to AR 2315 (words AR 00 to AR 23) These include CompoBus/S slave status flags (words AR 04 to AR 07). |
| Link bits (LR area) |  | 256 points: LR 0000 to LR 1515 (words LR 00 to LR 15) |
| Timers/Counters |  | 256 timers/counters: TIM/CNT 000 to TIM/CNT 255 <br> 1-ms timers: TMHH (--) <br> 10-ms timers: TIMH (15) <br> 100-ms timers TIM <br> 1-s/10-s timers: TIML (--) <br> Decrementing counters: CNT <br> Reversible counters: CNTR (12) |
| Data memory | Read/Write | 2,048 words (DM 0000 to DM 2047) The Error Log is contained in DM 2000 to DM 2021. |
|  | Read only | 456 words (DM 6144 to DM 6599) |
|  | PC Setup | 56 words (DM 6600 to DM 6655) |
| Basic interrupt functions | Interrupt inputs | 2 interrupts (Used for both counter mode interrupts inputs and quick-response inputs. |
|  | Scheduled interrupts | 1 interrupt |


| Item |  | Specification |
| :---: | :---: | :---: |
| High-speed counter functions | High-speed counters | 1 counter (single phase at 20 kHz or 2 phases at 5 kHz ) |
|  | $\begin{aligned} & \hline \text { Counter } \\ & \text { interrupts } \\ & \hline \end{aligned}$ | 1 interrupt (set value comparison or set-value range comparison) |
|  | Interrupt inputs (counter mode) | 2 interrupts (Used for both external interrupts inputs and quick-response inputs.) |
|  | Count-up interrupts | 2 interrupts (Used for both external interrupts inputs and quick-response inputs.) |
| Quick-response inputs |  | 2 points (Used for both external interrupts inputs and counter mode interrupt inputs.) Min. input pulse width: $50 \mu \mathrm{~s}$ max. |
| Pulse output |  | 2 points with no acceleration/deceleration, <br> 10 Hz to 10 kHz each, and no direction control: 1 point with trapezoid acceleration/deceleration, <br> 10 Hz to 10 kHz with direction control: or 2 points with variable duty-ratio outputs |
| Synchronized pulse control |  | 1 point |
| Input time constant <br> (ON response time = OFF response time) |  | Can be set for CPU Unit inputs and Expansion Unit inputs only ( $1,2,3,5,10,20,40$, or 80 ms ) |
| Clock |  | Equipped with clock (built-in RTC) |
| Communications functions |  | Peripheral port: Supports Host Link, peripheral bus, no-protocol communications, and Programming Console connections. <br> RS-232C port: Supports Host Link, no-protocol communications, 1-to-1 Link, or 1-to-1 NT Link connections. |
| Power failure backup function |  | Data in HR, AR, Counter (CNT), and Data Memory (DM) areas is held. |
| Memory backup |  | Non-volatile (flash) memory: Program, read-only DM area, and PC Setup |
|  |  | Memory backup (lithium battery: 2 years lifetime): DM area, HR area, AR area, and counter values |
| Self-diagnostic functions |  | CPU error (watchdog timer), memory errors, communications errors, setting errors, battery errors, and expansion I/O bus errors |
| Program check |  | No END instruction, programming errors (checked when operation is started) |
| Programming devices | Programming Console | C200H-PRO27, CQM1-PRO01, or CQM1H-PRO01 |
|  | SSS | IBM PC/AT or compatible (SYSMAC Support Software version 1.1 or higher) |
|  | CPT | Windows |
|  | CX-P | Windows |

Note: Connecting Cable (CPM2C-CN111, CS1W-CN114, or CS1W-CN118) is required to connect to the communications peripheral /RS-232C port.

- Communications Specifications

| Communications method | Special CompoBus/S protocol |
| :--- | :--- |
| Manchester coding |  |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The baud rate is switched using DM settings (default setting is 750 kbps ).

## Dimensions

Note: All units are in millimeters unless otherwise indicated. CPM2C-S100C CPM2C-S110C


Note: Refer to CPM2C-S Programmable Controller Operation Manual (W377) for detailed specifications.

## omron

## Programmable Slaves

## Multi-functional Slave for Distributed

## Blocks

An entire installation consisting of sensors and actua tors is handled as a DeviceNet slave.
duction of standard units while standardizing pro duction of standard units while standardizing pro ventional distributed I/O control networks do not allow I/O checks or operation checks until all devices on the networks are assembled and connected. Program mable Slaves, however, allow I/O and operation checks on any distributed unit independently.

- DeviceNet Slave Functions

Supports multi-word $1 / O$ Links and message communications, making it possible for the maste to control the data of all the slaves on the network. Data that does not need immediate transmission, message communications.

- CompoBus/S Master Functions Connects to remote signal lights, pushbutton
switches, terminal blocks, and pneumatic valves from other companies over VCTF or easy-tobranch flat cable.

- RS-232C Communications Connects to the BCRs and PTs to process data alleviating the load on the master
- Expansion Unit (Up to Three Units) A single node is used to control distributed blocks and decrease the size of the communications block in multi-point operation, thus making the cost reduction of the system possible.


Ordering Information

| Unit |  | Inputs | Outputs | Clock | Model |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 10 points (6 inputs/4 <br> outputs) | Connector model | 6 points at 24 VDC | 4 transistor sinking outputs | Yes | CPM2C-S100C-DRT |
|  |  |  | 4 transistor sourcing outputs | Yes | CPM2C-S110C-DRT |

## Specifications

- General Specifications

| Item |  | Specification |
| :---: | :---: | :---: |
| Control method |  | Stored program method |
| I/O control method |  | Cyclic scan method (Immediate refreshing can be performed with IORF(97).) |
| Programming language |  | Ladder diagram |
| Instruction length |  | 1 step per instruction 1 to 5 words per instruction |
| Instructions | Basic instructions | 14 |
|  | Special instructions | 105 instructions, 185 variations |
| Execution time | Basic instructions | $0.64 \mu \mathrm{~s}$ (LD instruction) |
|  | Special instructions | $7.8 \mu \mathrm{~s}$ (MOV instruction) |
| Program capacity |  | 4,096 words |
| Max. I/O capacity |  | CPU Unit only: 10 points <br> Expansion I/O Unit: 96 points (32-point Expansion I/O Unit x 3 ) (Up to 3 Expansion Units can be connected.) CompoBus/S: 256 points ( 362 points in total) |
| Input bits |  | IR 00000 to IR 00915 <br> (Bits not used for input bits can be used for work bits.) |
| Output bits |  | IR 01000 to IR 01915 <br> (Bits not used for output bits can be used for work bits.) |
| CompoBus/S input bits |  | 128 bits: IR 02000 to IR 02715 (words IR 020 to IR 027) |
| CompoBus/S output bits |  | 128 bits: IR 03000 to IR 03715 (words IR 030 to IR 037) |
| Work bits |  | 672 bits: IR 02800 to IR 02915 (words IR 028 to IR 029) <br>  IR 03800 to IR 03915 (words IR 038 to IR 039) <br>  IR 04000 to IR 04915 (words IR 040 to IR 049) <br>  IR 20000 to IR 22715 (words IR 200 to IR 227) |
| Special bits (SR area) |  | 440 bits: SR 22800 to SR 25507 (words SR 228 to SR 255) |
| Temporary bits (TR area) |  | 8 bits: (TR 0 to TR 7) |
| Holding bits (HR area) |  | 320 bits: HR 0000 to HR 1915 (words HR 00 to HR 19) |
| Auxiliary bits (AR area) |  | 384 bits: AR 0000 to AR 2315 (words AR 00 to AR 23) These include CompoBus/S slave status flags (words AR 04 to AR 07). |
| Link bits (LR area) |  | 256 points: LR 0000 to LR 1515 (words LR 00 to LR 15) |
| Timers/Counters |  | 256 timers/counters: TIM/CNT 000 to TIM/CNT 255 <br> 1-ms timers: TMHH (--) <br> 10-ms timers: TIMH (15) <br> 100-ms timers TIM <br> 1-s/10-s timers: TIML (--) <br> Decrementing counters: CNT <br> Reversible counters: CNTR (12) |
| Data memory | Read/Write | 2,048 words (DM 0000 to DM 2047) <br> The Error Log is contained in DM 2000 to DM 2021. |
|  | Read only | 456 words (DM 6144 to DM 6599) |
|  | PC Setup | 56 words (DM 6600 to DM 6655) |
| DeviceNet slave functions |  | DeviceNet Remote I/O Link <br> No. of I/O Link points: 1,024 max. <br> Explicit message communications <br> Any PC data area can be accessed from the master |
| Basic interrupt functions | Interrupt inputs | 2 interrupts (Used for both counter mode interrupts inputs and quick-response inputs. |
|  | Scheduled interrupts | 1 interrupt |


| Item |  | Specification |
| :---: | :---: | :---: |
| $\begin{array}{\|l\|} \hline \begin{array}{l} \text { High-speed } \\ \text { counter } \\ \text { functions } \end{array} \\ \hline \end{array}$ | High-speed counters | 1 counter (single phase at 20 kHz or 2 phases at 5 kHz ) |
|  | Count er interrupts | 1 interrupt (set value comparison or set-value range comparison) |
|  | Interrupt inputs (counter mode) | 2 interrupts (Used for both external interrupts inputs and quick-response inputs.) |
|  | Count-up interrupts | 2 interrupts (Used for both external interrupts inputs and quick-response inputs.) |
| Quick-response inputs |  | 2 points (Used for both external interrupts inputs and counter mode interrupt inputs.) Min. input pulse width: $50 \mu \mathrm{~s}$ max. |
| Pulse output |  | 2 points with no acceleration/deceleration, <br> 10 Hz to 10 kHz each, and no direction control: 1 point with trapezoid acceleration/deceleration, <br> 10 Hz and 10 kHz with no direction control: or 2 points with variable duty-ratio outputs |
| Synchronized pulse control |  | 1 point |
| Input time constant <br> (ON response time $=$ OFF response time) |  | Can be set for CPU Unit inputs and Expansion Unit inputs only (1, 2, 3, 5, 10, 20, 40, or 80 ms ) |
| Clock |  | Equipped with clock (built-in RTC) |
| Communications functions |  | Peripheral port: Supports Host Link, peripheral bus, no-protocol communications, and Programming Console connections. <br> RS-232C port: Supports Host Link, no-protocol communications, 1-to-1 Link, or 1-to-1 NT Link connections. |
| Power failure backup function |  | Data in HR, AR, Counter (CNT), and Data Memory (DM) areas is held. |
| Memory backup |  | Non-volatile (flash) memory: Program, read-only DM area, and PC Setup |
|  |  | Memory backup (lithium battery: 2 years lifetime): DM area, HR area, AR area, and counter values |
| Self-diagnostic functions |  | CPU error (watchdog timer), memory errors, communications errors, setting errors, battery errors, and expansion I/O bus errors |
| Program check |  | No END instruction, programming errors (checked when operation is started) |
| Programming devices | Programming Console | C200H-PRO27, CQM1-PRO01, or CQM1H-PRO01 |
|  | SSS | IBM PC/AT or compatible (SYSMAC Support Software version 1.1 or higher) |
|  | CPT | Windows |
|  | CX-P | Windows |

Note: Connecting Cable (CPM2C-CN111, CS1W-CN114, or CS1W-CN118) is required to connect to the communications peripheral /RS-232C port.

## Communications Specifications

## DeviceNe

| Communications protocol |  | DeviceNet |
| :---: | :---: | :---: |
| Connection form |  | Combination of multi-drop and T-branch connections (see note 1) |
| Baud rate |  | 500,250 , or 125 kbps (switchable) |
| Communications media |  | Special 5 -conductor cable (2 signal lines, 2 power supply lines, and 1 shield line) |
| Communications distance | Baud rate |  |
| Max. number of connecting nodes |  | 64 (63 slaves and 1 master) |
| Error control checks |  | CRC error, node address duplication check, and scan list verification |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The maximum network length is the distance from the master to the farthest node
3. When Thin Cable is used for the main line, the main line must be 100 m or less in length.

| Communications method |  | Special CompoBus/S protocol |
| :---: | :---: | :---: |
| Coding method |  | Manchester coding |
| Connection form |  | Combination of multi-drop method and T-branch connections (see note 1) |
| Baud rate |  | High-speed Communications Mode: 750 kbps Long-distance Communications Mode: 93.75 kbps (see note 2) |
| Communications cycle time | High-speed Communications Mode | 0.5 ms (with 8 input and 8 output slaves connected) |
|  |  | 0.8 ms (with 16 input and 16 output slaves connected) |
|  | Long-distance Communications Mode | 4.0 ms (with 8 input and 8 output slaves connected) |
|  |  | 6.0 ms (with 16 input and 16 output slaves connected) |
| Communications media |  | 2-conductor cable (VCTF $0.75 \times 2$ ), 4 -conductor cable (VCTF $0.75 \times 4$ ), or Special Flat Cable |
| Communications distance | High-speed Communications Mode | 2-conductor VCTF cable: <br> Main line length: $\quad 100 \mathrm{~m}$ max. <br> Branch line length: 3 m max. <br> Total branch line length: 50 m max. <br> Special Flat Cable, 4-conductor VCTF cable: <br> Main line length: $\quad 30 \mathrm{~m}$ max. <br> Branch line length: $\quad 3 \mathrm{~m}$ max. <br> Total branch line length: 30 m max. <br> When Special Flat Cable is used to connect fewer than 16 Slaves, the main line can be up to 100 m long and the total branch line length can be up to 50 m .) |
|  | Long-distance Communications Mode | 2-conductor VCTF cable: <br> Main line length: $\quad 500 \mathrm{~m}$ max. <br> Branch line length: $\quad 6 \mathrm{~m}$ max. <br> Total branch line length: 120 m max. <br> Special Flat Cable, 4-conductor VCTF cable: <br> Variable branch wiring (total cable length 200 m max.) <br> (There are no limits on the branching format or main, branch, or total line lengths. The terminator must be connected to the point in the system farthest from the master.) |
| Maximum number of nodes |  | 32 |
| Error control checks |  | Manchester code check, frame length check, and parity check |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The baud rate is switched using DM settings (default setting is 750 kbps ).

## Dimensions

Note: All units are in millimeters unless otherwise indicated CPM2C-S100C-DRT
CPM2C-S110C-DRT


Note: Refer to CPM2C-S Programmable Controller Operation Manual (W377) for detailed specifications.

## omron

## Master Control Units (S-Controllers) <br> SRM1-C01-V2/C02-V2

## Subminiature, Stand-alone Model with

## CompoBus/S Master and SYSMAC

## Controller Functions

- Maximum number of Remote I/O points per Master 256
Maximum number of Slaves per Master: 32
Communications cycle time: 0.5 ms max. (at baud rate 750 kbps ).
- Communications distance: Extended to 500 m Communications distance: Exte
- Additional instructions (PID, SCL, NEG, ZCP) Additional instructions (PID,
ensure analog compatibility.
■ RS-232C port incorporated (SRM1-C02-V2).
Ordering Information

| Specifications |  | Model |
| :--- | :--- | :--- |
| Built-in stand-alone controller functions | Without RS-232C | SRM1-C01-V2 |
|  | With RS-232C | SRM1-C02-V2 |

## Specifications

| Number of I/O points | 256 points (128 inputs/128 outputs) <br> 128 points ( 64 inputs/64 outputs) <br> Selectable by DM setting. The default setting is 256 points. |
| :---: | :---: |
| Max. number of Slaves per Master | $\begin{array}{\|l} \hline 256 \text { points: } 32 \\ 128 \text { points: } 16 \\ \hline \end{array}$ |
| I/O words | Input words: 000 to 007 Output words: 010 to 017 |
| Programming language | Ladder diagram |
| Types of instruction | 14 basic and 81 special instructions (125 instructions in total) |
| Execution time | LD instruction: $0.97 \mu \mathrm{~s}$ <br> MOV instruction: $9.1 \mu \mathrm{~s}$ |
| Program capacity | 4,096 words |
| Data memory | 2,022 + 512 (read-only) words |
| Timers/Counters | 128 timers/counters |
| Work bits | 640 bits |
| Memory backup | Flash memory (without battery): User programs <br> Lithium battery: Data memory etc. (Battery life: 10 years min. at an ambient temperature of $25^{\circ} \mathrm{C}$.) |
| Peripheral port | 1 point |
| RS-232C port | 1 point (SRM1-C02 only) <br> Host Link, NT Link, 1:1 Link, or no protocol |
| Programming tool | Programming Consoles: CQM1-PRO01-E, C200H-PRO27-E <br> CX-Programmer (Supported for versions 2 or later.) <br> WS02-CXP1-E <br> SYSMAC Support Software (MS-DOS version): C500-ZL3AT1-E |

## - Communications Specifications

| Communications method |  | CompoBus/S protocol |
| :---: | :---: | :---: |
| Coding method |  | Manchester coding method |
| Connection method |  | Multi-drop method and T-branch method (see note 1) |
| Communications baud rate |  | $750,000 \mathrm{bps} / 93,750 \mathrm{bps}$ (see note 2) |
| Communications cycle time | High-speed communications mode | 0.5 ms with 8 Slaves for inputs and 8 Slaves for outputs |
|  |  | 0.8 ms with 16 Slaves for inputs and 16 Slaves for outputs |
|  | Long-distance communications mode | 4.0 ms with 8 Slaves for inputs and 8 Slaves for outputs |
|  |  | 6.0 ms with 16 Slaves for inputs and 16 Slaves for outputs |
| Communications cable |  | 2-conductor VCTF cable ( $0.75 \times 2$ ), 4 -conductor VCTF cable ( $0.75 \times 4$ ) Dedicated flat cable |
| Communications distance | High-speed communications mode |  |
|  | Long-distance communications mode | 2-conductor VCTF cable: <br> Main line length: $\quad 500 \mathrm{~m}$ max. <br> Branch line length: 6 m max. <br> Total branch line length: 120 mmax . <br> Flat cable, 4-conductor VCTF cable: <br> Variable branch wiring (total cable length 200 m max.) <br> (There are no limits on the branching format or main, branch, or total line lengths. The terminator must be connected to the point in the system farthest from the master.) |
| Max. number of connecting nodes |  | 32 |
| Error control chec |  | Manchester code check, frame length check, and parity check |


| Error control checks | Manchester code check, frame length check, and parity check |
| :--- | :--- |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The communications baud rate is switched using DM settings (default setting is $750,000 \mathrm{bps}$ )

- General Specifications

| Supply voltage | 24 VDC |
| :---: | :---: |
| Allowable supply voltage | 20.4 to 26.4 VDC |
| Power consumption | 3.5 W max. |
| Inrush current | 12.0 A max. |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $57 \mathrm{~Hz}, 0.075-\mathrm{mm}$ amplitude, 57 to 150 Hz , acceleration: $9.8 \mathrm{~m} / \mathrm{s}^{2}$ in $\mathrm{X}, \mathrm{Y}$, and Z directions for 80 minutes each <br> (Time coefficient; 8 minutes $\times$ coefficient factor $10=$ total time 80 minutes) |
| Shock resistance | $147 \mathrm{~m} / \mathrm{s}^{2}$ three times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ Storage: $-20^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$ |
| Humidity | 10\% to $90 \%$ (with no condensation) |
| Atmosphere | Must be free from corrosive gas. |
| Terminal screw size | M3 |
| Power interrupt time | DC type: $2 \mathrm{~ms} \mathrm{min}$. |
| Weight | 150 g max. |

## Nomenclature



## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRM1-C01/C02-V2


The above dimensions apply to the SRM1-C02-V2. The SRM1-C01-V2 has no RS-232C port.

## Precautions

For details on safety precautions, refer to the CompoBus/S Master Control Units Operation Manual (W318).

## omROn

## Master Unit

## Master Unit for CS1, C200HX, C200HG,

## C200HE, and C200HS

- A maximum of 256 I/O points available.
- Connects to a maximum of 32 Slaves.
- Communications cycle time: 0.5 ms max. (at baud rate 750 kbps )
- Communications distance: Extended to 500 m max. (at baud rate 93.75 kbps ).
- Connection to Analog Terminals now supported


Ordering Information

| PC | Max. number of I/O points | Model |
| :--- | :---: | :--- |
| C200HX (-Z), C200HG (-Z), C200HE (-Z), <br> C200HS, CS1 | 256 points (128 inputs/128 outputs) | C200HW-SRM21-V1 |

Specifications

- Communications Specifications

| Communications method | CompoBus/S protocol |
| :--- | :--- |
| Coding method | Manchester coding method |
| Connection method | Multi-drop method and T-branch method (see note 1 ) |

Note: 1. A terminator must be connected to the point in the system farthest from the Master.
2. The communications baud rate is switched with the DIP switch.

## Unit Specifications

| Current consumption |  | 150 mA max. at 5 VDC |
| :---: | :---: | :---: |
| Number of // points |  | 256 points (128 inputs/128 outputs), 128 points (64 inputs/64 outputs) (swithable) |
| Number of occupied words |  | 256 points: $\quad 20$ words ( 8 input words/ 8 output words, 4 status data) 128 points: 10 words ( 4 input words $/ 4$ output words, 2 status data) |
| PLC |  | CS1, C200HX (-ZE), C200HG (-ZE), C200HE (-ZE), C200HS |
| Number ofMaster Units mountable | C200HE | 128 points: 10, 256 points: 5 |
|  | C200HG-CPU33/43 | 128 points: 10, 256 points: 5 |
|  | C200HG-CPU53/63 | 128 points: 16, 256 points: 8 |
|  | C200HX-CPU34/44 | 128 points: 10, 256 points: 5 |
|  | C200HX-CPU54/64 | 128 points: 16, 256 points: 8 |
|  | C200HS | 128 points: 10, 256 points: 5 |
|  | CS1 | 128 points: 16,256 points: 8 |
| Number of points per node number |  | 8 points |
| Max. number of Slaves per Master |  | 32 |
| Status data |  | Communications Error Flag and Active Slave Node (see note) |
| Weight |  | 200 g max. |
| Approved standards |  | UL 508 (E95399), CSA C22.2 No. 142 (LR51460) |

UL 508 (E95399), CSA C22.2 No. 142 (LR51460)

Ratings

## Nomenclature



Dimensions
Note: All units are in millimeters unless otherwise indicated


Precautions
Refer to the CompoBus/S Operation Manual (W266-E1) before using the Unit.

## omROn

## Master Unit

## Master Unit for CQM1/CQM1

- A maximum of 128 I/O points available (Possible to set 32,64 , or $128 \mathrm{I} / \mathrm{O}$ points).
Connects to a maximum of $16 / 32$ Slaves
Communications cycle time: 0.5 ms max. (at baud rate 750 kbps ).
Communications distance: Extended to 500 m max. (at baud rate 93.75 kbps )
- Connection to Analog Terminals now supported.


Ordering Information

| PLC | Max. number of //O points | Model |
| :--- | :--- | :--- |
| CQM1-series PLC | 128 points (64 inputs/64 outputs) | CQM1-SRM21-V1 |

Specifications

- Communications Specifications

| Communications method | CompoBus/S protocol |
| :--- | :--- |
| Coding method | Manchester coding method |
| Connection method | Multi-drop method and T-branch method (see note 1 ) |

Note: 1. A terminator must be connected to the point in the system farthest from the Master:
2. The communications baud rate is switched with the DIP switch.

- Unit Specifications

| Current consumption | 180 mA max. at 5 VDC |
| :---: | :---: |
| Number of I/O points | 128 points ( 64 inputs/64 outputs), 64 points ( 32 inputs/32 outputs), 32 points (16 inputs/16 outputs) (switchable) |
| Number of occupied words | 128 points: 4 input words/4 output words 64 points: 2 input words/2 output words 32 points: 1 input word/1 output word |
| PC | 128 points: CQM1-CPU41-EV1/CPU42-EV1/CPU43-EV1/CPU44-EV1 <br> 64 points: CQM1-CPU11-E/CPU21-E/CPU41-EV1/CPU42-EV1/CPU43-EV1/CPU44-EV1 <br> 32 points: CQM1-CPU11-E/CPU21-E/CPU41-EV1/CPU42-EV1/CPU43-EV1/CPU44-EV1 |
| Number of points per node number | 4/8 points (switchable) |
| Max. number of Slaves per Master | 32 (4 points per node number) |
| Status data | Alarm terminal output |
| Weight | 200 g max. |
| Approved standards | UL 508 (E95399), CSA C22.2 No. 142 (LR51460) |

- Alarm Output Specifications

- Ratings

The ratings of the Unit are the same as those for the CQM1.
Nomenclature


## Dimensions

Note: All units are in millimeters unless otherwise indicated.
CQM1-SRM21-V1


Precautions
Refer to the CompoBus/S Operation Manual (W266-E1) before using the Unit.

## omROn

SYSMAC Boards with CompoBus/S Master

## Intelligent Computer Board that

 Integrates SYSMAC C200HX/HG/HE andCompoBus/S Master Functions
Equipped with Backup Power Supply
System
Can be mounted to an ISA bus, the standard bus for IBM compatible computers, thus contributing to the downsizing of installations using computers.

- Communications between the SYSMAC Board and the computer are performed via an ISA bus, enabling a communications speed much highe than with RS-232C communications
- Incorporates CompoBus/S communications func tions. Simply connect a CompoBus/S Slave to enable distributed control of I/O in remote locations
A power supply sub-board is also available. This makes it possible to provide power externally, and allows control to be continued even when the computer power supply is interrupted.

Data settings at CompoBus/S Slaves are reflected utomatically.
Enables communications at a maximum distance
of 500 m (at a baud rate of 93.75 kbps ).
Conforms to EC Directives.


Ordering Information

| PLC | Max. number of I/O points | Model |
| :--- | :---: | :--- |
| C200HG-CPU43 | 256 points (128 inputs/128 outputs) | C200PC-ISA03-SRM |
| C200HX-CPU64 |  | C200PC-ISA13-SRM |

## Specifications

## - Communications Specifications

| Communications method |  | CompoBus/S protocol |
| :---: | :---: | :---: |
| Coding method |  | Manchester coding method |
| Connection method |  | Multi-drop method and T-branch method (see note) |
| Communications baud rate |  | $750,000 \mathrm{bps}, 93,750 \mathrm{bps}$ |
| Communications cycle time |  | 0.5 ms with 8 Slaves for inputs and 8 Slaves for outputs 0.8 ms with 16 Slaves for inputs and 16 Slaves for outputs |
| Communications cable |  | 2-conductor VCTF cable ( $0.75 \times 2$ ), 4-conductor VCTF cable ( $0.75 \times 4$ ) Special Flat Cable |
| Communications distance | High-speed communications mode | 2-conductor VCTF cable: <br> Main line length: <br> 100 m max <br> Branch line length: 3 m max. <br> Total branch line length: 50 m max. <br> Special Flat Cable, 4 -conductor VCTF cable: <br> Main line length: 30 m max. <br> Branch line length: $\quad 3 \mathrm{~m}$ max. <br> Total branch line length: 30 m max. <br> (When Special Flat Cable is used to connect fewer than 16 Slaves, the main line can be up to 100 m long and the total branch line length can be up to 50 m .) |
|  | Long-distance communications mode | 2-conductor VCTF cable: <br> Main line length: <br> 500 m max. <br> Branch line length: $\quad 6 \mathrm{~m}$ max. <br> Total branch line length: 120 mmax . <br> Special Flat Cable, 4-conductor VCTF cable: <br> Variable branch wiring (total cable length 200 m max.) <br> (There are no limits on the branching format or main, branch, or total line lengths. <br> The terminator must be connected to the point in the system farthest from the master.) |
| Max. number of connecting nodes |  | 32 |
| Error control checks |  | Manchester code check, frame length check, and parity check |

Error control checks A A terminator must be connected to the point in the system farthest from the Master.
Note: A terminator must be conn
$\square$ Unit Specifications

| Power supply voltage | 4.875 to 5.25 VDC |
| :---: | :---: |
| Current consumption | 0.5 A max. (see note 1) |
| Number of I/O points | 256 points (128 inputs/128 outputs), 128 points ( 64 inputs/64 outputs), (switchable) |
| Number of occupied words | 256 points: 20 words ( 8 input words, 8 output words, and 4 status data words) (see note 2 ) <br> 128 points: 10 words ( 4 input words, 4 output words, and 2 status data words) |
| Number of points per node number | 8 points |
| Max. number of Slaves per Master | 32 |
| Status data | Communications Error Flag and Active Slave Node (see note 2) |
| Weight | 350 g max. |

2. The occupied words are in the IR area.

## omron

I/O Link Unit

## I/O Link Unit for CPM2C

- Operates as a Slave of the CompoBus/S Master

Unit.

- Exchanges eight inputs and eight outputs with the Master.
- Bears the CE marking.


Ordering Information
CompoBus I/O Link Unit
CompoBus I/O Link Unit

| Name | Specifications | Model |
| :---: | :--- | :--- |
| CompoBus/S I/O Link Unit | Number of points for $/ /$ O links: <br> 8 inputs and 8 outputs | CPM2C-SRT21 |

## Application Examples

## - Conveyor Line

Processing speed can be increased and system setup labor reduced by creating a distributed system with a CPM2C at each conveyor


## Specifications

| Item | CPM2C-SRT21 |
| :--- | :--- |
| Master/Slave | CompoBus/S Slave |
| Number of I/O points | 8 inputs and 8 outputs |
| Number of words occupied in | 1 input word and 1 output word (allocated in the same way as for other Expansion Units) |
| CPM2C's I/O memory |  |$\quad$ DIP switch $\quad$| Node address setting | 1 W |
| :--- | :--- |
| Power consumption | 150 g |
| Weight |  |

Note: For details of CPM2C PLCs, refer to the CPM2C catalog (Cat. No. P049).

Dimensions
CPM2C-SRT21


Installation
■ Number of I/O Units Connectable
Up to 5 Expansion Units can be connected to CPM2C PLCs. There are, however, only 9 input words and 9 output words that can be allocated to Expansion I/O Units: words IR 001 to IR 009 for inputs (the CPU Unit's inputs are allocated to IR 001) and words IR 011 to IR 019 for outputs (the Example


CPU Unit

## omron

## I/O Link Unit

## I/O Link Unit for CPM2A/CPM1A

- Operates as a Slave of the CompoBus/S Master Unit.
- Exchanges eight inputs and eight outputs with the
Master.
- Approved by UL and CSA standards, and bears the CE marking.


Specifications

| Master/Slave | CompoBus/S Slave |
| :--- | :--- |
| Number of /O points | 8 inputs and 8 outputs |
| Number of words occupied in CPM2A's | 1 input word and 1 output word (allocated in the same way as for other Expansion Units) |
| IO memory | Node address setting |

Note: For details of CPM1A PLCs, refer to the CPM1A catalog (Cat. No. P039). For details of CPM2A PLCs, refer to the CPM2A catalog (Cat. No. P049)

## Dimensions



Installation

- Connection Examples


Note: A single CompoBus/S /O Link Unit together with a maximum of two other Expansion //O Units can be connected to the CPM1A or CPM2A CPU Unit

## omROn

Transistor Remote I/O Terminals
Long-distance Communications
Supported by SRT2 Models
(Long-distance/High-speed
Communications Selection)
Ultra-compact at $80 \times 48 \times 50(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}) \mathrm{mm}$ for 4 -point and 8 -point terminals and $105 \times 48 \times 50(\mathrm{~W} \times$ $H \times D) \mathrm{mm}$ for 16 -point terminals.

- Two independent power supplies can be used because the I/O terminals are insulated from the internal circuits.
- DIN track mounting and screw mounting are both supported.

Ordering Information

| I/O classification | Internal I/O circuit common | 1/0 points | Rated voltage | I/O rated voltage | Model |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | NPN (+ common) | 4 | 24 VDC | 24 VDC | SRT2-ID04 |
|  | PNP (- common) |  |  |  | SRT2-ID04-1 |
| Output | NPN (- common) |  |  |  | SRT2-OD04 |
|  | PNP (+ common) |  |  |  | SRT2-OD04-1 |
| Input | NPN (+ common) | 8 |  |  | SRT2-ID08 |
|  | PNP (- common) |  |  |  | SRT2-ID08-1 |
| Output | NPN (- common) |  |  |  | SRT2-OD08 |
|  | PNP (+ common) |  |  |  | SRT2-OD08-1 |
| Input | NPN (+ common) | 16 |  |  | SRT2-ID16 |
|  | PNP (- common) |  |  |  | SRT2-ID16-1 |
| Output | NPN (- common) |  |  |  | SRT2-OD16 |
|  | PNP (+ common) |  |  |  | SRT2-OD16-1 |

Note: For more details about connections supported by the Master Unit, refer to page 25.
Specifications

## - Ratings

Inputs

| Input current | 6 mA max./point |
| :--- | :--- |
| ON delay time | 1.5 ms max. |
| OFF delay time | 1.5 ms max. |
| ON voltage | 15 VDC min. between each input terminal and V |
| OFF voltage | 5 VDC max. between each input terminal and V |
| OFF current | 1 mA max. |
| Insulation method | Photocoupler |
| Input indicators | LED (yellow) |

## Outputs

| Rated output current | 0.3 A/point |
| :--- | :--- |
| Residual voltage | 0.6 V max. |
| Leakage current | 0.1 mA max. |
| Insulation method | Photocoupler |
| Output indicators | LED (yellow) |

## Characteristics

| Communications power supply voltage | 14 to 26.4 VDC |
| :---: | :---: |
| IO power supply voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |
| IO power supply current | 1 A max. |
| Current consumption (see note) | 50 mA max a 24 VDC |
| Connection method | Multi-drop method and T-branch method |
| Connecting Units | 4-point and 8-point Terminals: 16 Input Terminals and 16 Output Terminals per Master <br> 16-point Terminals: 8 Input Terminals and 8 Output Terminals per Master |
| Dielectric strength | 500 VAC for 1 min (1-mA sensing current between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistan | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |
| Shock resistance | $\begin{array}{\|ll} \hline \text { Malfunction: } & 200 \mathrm{~m} / \mathrm{s}^{2} \\ \text { Destruction: } & 300 \mathrm{~m} / \mathrm{s}^{2} \\ \hline \end{array}$ |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions |
| Terminal strength | No damage when 50 N pull load was applied for 10 s |
| Screw tightening torque | 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: ${ }_{-20^{\circ}}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ |
| Weight | 4-point and 8-point Terminals:  <br> $\begin{array}{l}80 \mathrm{~g} \text { max. } \\ 16 \text {-point Terminals: }\end{array}$  <br> 10 g max.  |
| Approved standards (4/8 points) | UL 508, CSA C22. 2 No. 14 |

Note: The above current consumption is the value with all 4 and 8 and 16 points turned ON excluding the current consumption of the external sensor connected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal.

## Nomenclature



Node Number Settings

| Indicator | Display | Color | Meaning |
| :---: | :---: | :---: | :---: |
| PWR | Lit | Green | The communications power supply is ON. |
|  | Not lit |  | The communications power supply is OFF. |
| сомм | Lit | Yellow | Normal communications |
|  | Not lit |  | A communications error has occurred or the Unit is in standby status. |
| ERR | Lit | Red | A communications error has occurred. |
|  | Not lit |  | Normal communications or the Unitis is in standby status. |
| 0 to 7 | Lit | Yellow | The corresponding I/O signal is ON . |
|  | Not lit |  | The corresponding / / signal is OFF. |

Output HOLD/CLEAR Mode

2. This function is available to Output Terminals only.

| Node number | Pin 3 | Pin 4 | Pin 5 | Pin 6 |
| :---: | :---: | :---: | :---: | :---: |
|  | 8 | 4 | 2 | 1 |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | ON |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

Note: 1. The node number is factory-set to 0 .
2. For node number settings, refer to the CompoBus/S Operation Manual (W266-E1),

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT2-ID04 (-1)
SRT2-ODO4 (-1)
SRT2-ID08 (-1) SRT2-ID08 ( -1 )
SRT2-ODO8 ( -1 )


SRT2-ID16 (-1)
SRT2-OD16
SRT2-OD16 (-1)



Installation
■ Internal Circuit Configuration


SRT2-ID08


SRT2-OD08
SRT2-ID08-1


SRT2-OD08-1


SRT2-ID16 SRT2-ID16-1


## External Connections (NPN Models)

## nput



Two-wire Sensors
SRT2-ID04


SRT2-ID08 and SRT2-ID16 with NPN Output


SRT2-ID08 and SRT2-ID16


Output


SRT2-OD08 and SRT2-ID16


- Terminal Arrangement and I/O Device Connection Example (PNP Models)

Note: The connections examples shown are for PNP models.
Input


## External Connections (PNP Models)

Input
SRT2-ID04-1 with NPN Output
(2)

Two-wire Sensors
SRT2-IDO4-1


SRT2-ID08-1 and SRT2-ID16-1 with NPN Outpu


SRT2-ID08-1 and SRT2-ID16-1


Output


■ Terminal Arrangement and I/O Device Connection Example (PNP Models)
Note: The connections examples shown are for NPN models.


Precautions
Refer to the CompoBus/S Operation Manual (W266-E1) before using the Unit

## omron

Transistor Remote I/O Terminals with 3-tier Terminal Block

## Models with 3-tier Terminals (16 Points)

## Added to the Remote I/O Terminal

## Series.

Six Models are Available Depending on the NPN or PNP Configuration, Inpu Points, I/O Points, or Output Points

Incorporates easy-to-wire terminals each connect ing to a single wire.
Reduces designing and wiring effort
Incorporates a removable circuit block of cassette construction.

Ordering Information

| I/O classification | Internal I/O circuit <br> common | I/O points |  | I/O connection method |
| :--- | :--- | :--- | :--- | :--- |

## Specifications

$\square$ Ratings
Inputs

| Input current | 6 mA max./point at 24 V and 3 mA min./point at 17 V |
| :---: | :---: |
| ON delay time | 1.5 ms max . |
| OFF delay time | 1.5 ms max. |
| ON voltage | NPN: 15 VDC min. between V terminals and each input terminal PNP: 15 VDC min. between $G$ terminals and each input terminal |
| OFF voltage | NPN: 5 VDC max. between V terminals and each input terminal PNP: 5 VDC max. between $G$ terminals and each input terminal |
| OFF current | 1 mA max. |
| Insulation method | Photocoupler |
| Outputs |  |
| Rated output current | 0.5 A max./point |
| Residual voltage | 1.2 V max. |
| ON delay time | 0.5 ms max. |
| OFF delay time | 1.0 ms max . |
| Leakage current | 0.1 mA max. |
| Insulation method | Photocoupler |

## Characteristics

| Communications power supply voltage | 14 to 26.4 VDC |
| :---: | :---: |
| I/O power supply voltage | 24 VDC +10\%/-15\% |
| I/O power supply current | 4 A max./common |
| Current consumption (see note) | 50 mA max . at 24 VDC |
| Connection method | Multi-drop method and T-branch method |
| Dielectric strength | 500 VAC between insulated circuits |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage with 100 N pull load applied in all directions. |
| Terminal strength | No damage with 100 N pull load applied |
| Screw tightening torque | 0.3 to $0.5 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ <br> Storage: $-25^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ |
| Ambient humidity | Operating: $25 \%$ to $85 \%$ (with no condensation) |
| Weight | 300 g max. |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external se
nected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal.

## Nomenclature


Address Setting Switch

| Node address | Setting (Hex) |
| :--- | :--- |
| 0 | 0 |
| 1 | 1 |
| 2 | 2 |
| 3 | 3 |
| 4 | 4 |
| 5 | 5 |
| 6 | 6 |
| 7 | 7 |


| Node address | Setting (Hex) |
| :--- | :--- |
| 8 | 8 |
| 9 | 9 |
| 10 | A |
| 11 | B |
| 12 | C |
| 13 | D |
| 14 | E |
| 15 | F |

## Dimensions



Installation

- Internal Circuit Configuration


SRT2-ID16T-1


- External Connections


Output (NPN Models) SRT2-OD16T
SRT2-MD16T
(88) (89)
$\left.\begin{array}{l}\text { (V) } \\ \text { (G) } \\ \text { (G) }\end{array}\right]$
(G) (6)
$\mathrm{L1} \quad \mathrm{~L}$

Input (PNP Models) SRT2-ID16T-1
SRT2-MD16T-1 SRT2-MD16T
(68)
(8i)
(v) (v)
(G) (G)

Output (PNP Models) SRT2-OD16T-1
SRT2-MD16T-1


## omROn

Relay-mounted Remote I/O Terminals SRT2-R
Ultra-miniature 8-point and 16-point

## Relay-mounted Terminals

- Ultra-compact
(8-point models: $101 \times 51 \times 51 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$; 16-point models: $156 \times 51 \times 51 \mathrm{~mm}(W \times H \times D))$
- Power MOS FET Relay and Relay models.
- DIN track mounting and screw mounting are available.

Ordering Information

| Classification | //0 points | Rated voltage | Relay coil rating | Model | Applicable relay |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Relay output | 8 points | 24 VDC | 24 VDC | SRT2-ROC08 | G6D-1A |
|  | 16 points |  |  | SRT2-ROC16 |  |
| Power MOS FET relay output | 8 points |  |  | SRT2-ROF08 | G3DZ-2R6PL |
|  | 16 points |  |  | SRT2-ROF16 |  |

Note: For details about connections to the Master Unit, refer to page 12.
Specifications

- Ratings

Relay Output

| Item | SRT2-ROC08, SRT2-ROC16 |
| :--- | :--- |
| Applicable relay | G6D-1A (one for each output point) |
| Rated load | 3 A at $250 \mathrm{VAC}, 3 \mathrm{~A}$ at 30 VDC (resistive load) |
| Rated carry current | 3 A (see note 1 ) |
| Max. contact voltage | $250 \mathrm{VAC}, 30 \mathrm{VDC}$ |
| Max. contact current | 3 A |
| Max. switching capacity | $730 \mathrm{VA}(\mathrm{AC}), 90 \mathrm{~W}$ (DC) |
| Min. permissible load (see note 2) | 10 mA at 5 VDC |
| Life expectancy | Electrical: 100,000 operations min. (rated load, at 1,800 operations/h) <br> Mechanical: $20,000,000$ operations min. (at 18,000 operations/h) |
| Note: 1. The maximum permissible current of COM0 to COM7 is 3 A. |  |

Note: 1. The maximum permissible current of COMO to COM7 is 3 A .
2. This value fulfills the Preference value of opening/closing at a rate of 120 times per min (ambient operating environment and deter-
mination criteria according to JIS C5442). Power MOS FET Relay Output

| Item | SRT2-ROF08, SRT2-ROF16 |
| :--- | :--- |
| Applicable relay | G3DZ-2R6PL (one for each output point) |
| Load voltage | 3 to $264 \mathrm{VAC}, 3$ to 125 VDC |
| Load current | $100 \mu \mathrm{~A}$ to 0.3 A |
| Inrush current | $6 \mathrm{~A}(10 \mathrm{~ms})$ |

$\square$ Characteristics

| Power supply voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |
| :---: | :---: |
| Current consumption (see note) | 350 mA max. at 24 VDC |
| Connection method | Multi-drop method and T-branch method |
| Connecting Units | 8-point Units: 16 per Master 16-point Units: 8 per Master |
| Dielectric strength | 2,000 VAC for 1 min (1-mA sensing current) between all output terminals and power supply, between communication terminals, and between contacts of different polarities <br> 500 VAC for 1 min ( $1-\mathrm{mA}$ sensing current) between all output terminals and power supply, between communication terminals, and between all power supply terminals and communications terminals |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 0.75-\mathrm{mm}$ double amplitude |
| Shock resistance | $\begin{array}{\|l} \text { Malfunction: } 100 \mathrm{~m} / \mathrm{s}^{2} \\ \text { Destruction: } 300 \mathrm{~m} / \mathrm{s}^{2} \end{array}$ |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions |
| Terminal strength | No damage when 50 N pull load was applied for 10 s |
| Screw tightening torque | 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ |
| Weight | 8-point models: $145 \mathrm{~g} \mathrm{max.}, \mathrm{16-point} \mathrm{models:} 240 \mathrm{~g}$ max. |
| Approved standards | UL 508, CSA C22. 2 No. 14 |


| Approved standards | UL 508, CSA C22.2 No. 14 |
| :--- | :--- |
| Note: The above current consumption is a value with all the points tur |  |

Note: The above current consumption is a value with all the points turned ON including the current consumption of the G6D coil for th
Remote Output Terminal, and the G3DZ's input current.
Reference Data


G3DZ-2R6PL Switching current (A)
Load Current vs. Ambient Tempera-



These graphs show the characteristics
for when the SRT2-ROC for when the SRT2-
model is mounted.

Inrush Current Resistivity


## Nomenclature



## Output HOLD/CLEAR Mode

| Mode | Pin 1 | Setting |
| :--- | :--- | :--- |
| HOLD | ON | Output status is maintained when a communications error occurs. |
| CLEAR | OFF | Output status is cleared when a communications error occurs. |
| Note: | 1. Pin 1 is factory-set to OFF. |  |


Node Number Settings

| Node number | Pin 3 | Pin 4 | Pin 5 | Pin 6 |
| :---: | :---: | :---: | :---: | :---: |
|  | 8 | 4 | 2 | 1 |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | ON |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

Note: 1. The node number is factory-set to 0 .
2. For node number setting, refer to the CompoBus/S Operation Manual (W266-E1).

## Dimensions

Note: All units are in millimeters unless otherwise indicated.

SRT2-ROC08
SRT2-ROF08



SRT2-ROC16
SRT2-ROF16
SRT2-ROF16


Mounting Holes
Two, 4.2 dia. or M4




## Installation

## - Internal Circuit Configuration

SRTT-ROCO8
SRT2-ROC16


Note: The G3DZ-2R6PL Power MOS FET Relay is inserted into

- External Connections


■ Terminal Arrangement and I/O Device Connection Example
Output
SRT2-ROC16


Note: 1. Dotted lines indicate internal connections.
SRT2-ROC08 and SRT2-ROF08 have the 0 to 7 and COM0 to COM3 terminals only 2. The above is a connection example of the SRT2-ROC16 with G6D Relays mounted
G3DZ Power MOS FET Relays are mounted to the SRT2-ROF08 and SRT2-ROF16.

## Precautions

Refer to the CompoBus/S Operation Manual (W266-E1) before using the Unit

## omron

Transistor Remote I/O Terminals with Connectors (32 Points)

## Subminiature 32-point Remote Terminal

## with Connectors

- Compact dimensions: $35 \times 60 \times 80(\mathrm{~W} \times \mathrm{D} \times \mathrm{H})$

Long-distance and high-speed communications modes available.

- Downsizing enabled with 32 -point MIL connector for I/O connection.


Ordering Information

| $\begin{gathered} \hline \mathrm{I} / \mathrm{O} \\ \text { classification } \end{gathered}$ | Internal I/O circuit common | 1/O points | I/O connection method | Rated voltage for communications power supply | Rated voltage for I/O power supply | Model |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Input | NPN (+ common) | 32 | MIL connector | 24 VDC | 24 VDC | SRT2-ID32ML |
|  | PNP (- common) |  |  |  |  | SRT2-ID32ML-1 |
| Output | NPN (- common) |  |  |  |  | SRT2-OD32ML |
|  | PNP (+ common) |  |  |  |  | SRT2-OD32ML-1 |
| Input and output | NPN <br> (input: + common; <br> output - common) |  |  |  |  | SRT2-MD32ML |
|  | PNP <br> (input: - common; <br> output: + common) |  |  |  |  | SRT2-MD32ML-1 |
| Mounting hook B (see note) |  |  |  |  |  | SRT2-ATT02 |

Note: Mounting hook B is required when not mounting to a DIN track.
Specifications

## - Ratings

Inputs

| Item | SRT2-ID32ML | SRT2-MD32ML | SRT2-ID32ML-1 | SRT2-MD32ML-1 |
| :---: | :---: | :---: | :---: | :---: |
| ON voltage | 15 VDC min. (Between each input terminal and V .) |  | 15 VDC min. (Between each input terminal and G.) |  |
| OFF voltage | 5 VDC max. (Between each input terminal and V .) |  | 5 VDC max. (Between each input terminal and G.) |  |
| OFF current | 1.0 mA max. |  |  |  |
| Input current | 6.0 mA max. at 24 VDC <br> 3.0 mA max. at 17 VDC <br> (Between each input terminal and V .) |  | 6.0 mA max. at 24 VDC <br> 3.0 mA max. at 17 VDC <br> (Between each input terminal and G.) |  |
| Input impedance | $4.4 \mathrm{k} \Omega$ |  |  |  |
| ON delay time | 1.5 ms max. |  |  |  |
| OFF delay time | 1.5 ms max. |  |  |  |
| Number of circuits | $\begin{array}{\|l} 32 \text { points/common, } \\ 1 \text { circuit } \end{array}$ | 16 points/common, 1 circuit | 32 points/common, 1 circuit | 16 points/common, 1 circuit |


| Item | SRT2-OD32ML | SRT2-MD32ML | SRT2-OD32ML-1 | SRT2-MD32ML-1 |
| :---: | :---: | :---: | :---: | :---: |
| Output current | 0.3 A/point 4-A common (See notes 1 and 3.) | 0.3 A/point <br> 2-A common <br> (See notes 2 and 3. ) | 0.3 A/point 4-A common (See notes 1 and 3.) | 0.3 A/point <br> 2-A common <br> (See notes 2 and 3. ) |
| Residual voltage | 1.2 V max. (Between the 0.3-A DC output terminal and G .) |  | 1.2 V max. (Between the 0.3-A DC output terminal and V .) |  |
| Leakage current | 0.1 mA max. (Between the 24-VDC output terminal and G.) |  | 0.1 mA max. (Between the 24-VDC output terminal and V.) |  |
| ON delay time | 0.5 ms max. |  |  |  |
| OFF delay time | 1.5 ms max. |  |  |  |
| Insulation method | Photocoupler |  | Photocoupler |  |
| Number of circuits | 32 points/common, 1 circuit | 16 points/common, 1 circuit | 32 points/common, 1 circuit | 16 points/common, 1 circuit |

Note: 1. Ensure that the total external load current does not exceed 4 A .
2. Ensure that the
3. Ensure that the current per terminal for the $\mathrm{V} / \mathrm{G}$ terminals does not exceed 1 A

- Characteristics

| Communications power supply voltage | 14 to 26.4 VDC |
| :---: | :---: |
| I/O power supply voltage | 20.4 to 26.4 VDC |
| Current consumption for communications power supply (also used for internal circuits; see note) | ID32MLID32ML-1: 50 mA MD32ML/MD32ML-1: 60 mA OD32ML/OD32ML-1:70 mA |
| Dielectric strength | 500 VAC for 1 min (Detection current: 1 mA between insulated circuits.) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 0.7-\mathrm{mm}$ double amplitude or $50 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | $150 \mathrm{~m} / \mathrm{s}^{2}$ |
| Ambient temperature | $\begin{array}{\|ll} \hline \text { Operating: } & -10^{\circ} \mathrm{C} \text { to } 55^{\circ} \mathrm{C} \text { (with no icing or condensation) } \\ \text { Storage: } & -25^{\circ} \mathrm{C} \text { to } 65^{\circ} \mathrm{C} \end{array}$ |
| Ambient humidity | Operating: 25\% to 85\% (with no condensation) |
| Weight | ID32ML/ID32ML-1/MD32ML/MD32ML-1: Approx. 100 g max. OD32ML/OD32ML-1: Approx. 90 g |

$\begin{array}{ll}\text { Note: } & \text { The above current consumption is the value with all points turned ON excluding the current consumption of the external sen } \\ \text { nected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal. }\end{array}$
Applicable Connectors

| Type |  | Model | Remarks |
| :---: | :---: | :---: | :---: |
| Flat cable, pressure-welded |  | XG4M-4030-T | --- |
| Stranded wire, pressurewelded | Socket | XG5M-4032-N | For AWG 24 |
|  |  | XG5M-4035-N | For AWG 28 to 26 |
|  | Semi-cover | XG5S-2001 | --- |
|  | Hood cover | XG5S-4022 |  |

## Nomenclature

Names of Components


Relationship between
/O Indicators and Connector


| Display | Name | Color | Status | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply indicator | Green | Lit | Power is being supplied by the communications power supply. |
|  |  |  | Not lit | Power is not being supplied by the communications power supply. |
| COMM1 | Communications indicators | Yellow | Lit | I/ O is being exchanged normally. |
|  |  |  | Not lit | A communications error has occurred, or the Unit is on standby. |
| ERR1ERR2 | Communications error indicators | Red | Lit | A communications error has occurred. |
|  |  |  | Not lit | I/O is being exchanged normally, or the Unit is on standby. |
| 0 to 15 | 1/0 | Yellow | Lit | The corresponding input or output is ON . |
|  |  |  | Not lit | The corresponding input or output is OFF, or on standby. |

## Operation

- Switch Settings

Rotary switch


Node address
setting

DIP switch


Output HOLD/CLEAR Setting (SRT2-OD/MD32ML(-1)) Reserved for system use (SRT2-ID32ML(-1)) Communications mode setting

## Node Address

The node address is set to one of the following hexadecimal values

| Node <br> address | Setting <br> (hexadecimal) | Node <br> address | Setting <br> (hexadecimal) |
| :--- | :--- | :--- | :--- |
| 0 | 0 | 8 | 8 |
| 1 | 1 | 9 | 9 |
| 2 | 2 | 10 | A |
| 3 | 3 | 11 | B |
| 4 | 4 | 12 | C |
| 5 | 5 | 13 | D |
| 6 | 6 | 14 | E |
| 7 | 7 | 15 | F |

Note: 1. Note the following points when using with the C200HW-
SRM21-V1/SRM1-CO - -V2:
Note the follown 1 poins-V2:
SRM21-V1/SRM1-CO $\square$ -

## Communications Mode Setting

The communications mode is set using SW3 of the DIP switch in the way shown below.

| SW3 | Communications mode | Communications <br> distance | Communications <br> speed | Communications cycle <br> time |
| :--- | :--- | :--- | :--- | :--- |
| OFF | High-speed <br> communications mode | 100 mmax. | 750 kbps | $0.5 \mathrm{~ms} / 0.8 \mathrm{~ms}$ |
| ON | Long-distance <br> communications mode | 500 m max. | 93.75 kbps | $4.0 \mathrm{~ms} / 6.0 \mathrm{~ms}$ |

[^0] data is held or cleared when a communications error occurs.

| SW4 (HOLD) | Setting |
| :--- | :--- |
| OFF | Output status is cleared. |
| ON | Output status is held. |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.


SRT2-ATT02

$$
\begin{array}{|cc|}
\hline 0 \\
0 \\
-325- & \begin{array}{c}
0 \\
0 \\
0
\end{array} \\
\hline
\end{array}
$$

Installation

- Internal Circuit Configuration



## - Terminal Arrangement




## Precautions

For details on available communications connectors, refer to page 105.
Communications Connector Pin Arrangement


## Applicable Cables

| Model | Connected product | Applicable Cable | Remarks |
| :---: | :---: | :---: | :---: |
| SRT2-ID32ML | $\begin{aligned} & \hline \text { G7TC-ID16 } \\ & \text { G7TC-IA16 } \end{aligned}$ | $\begin{array}{\|l\|} \hline \text { G79-150-25-D1 }(50 \mathrm{~cm}) \\ \text { G79-175-50-D1 }(75 \mathrm{~cm}) \\ \hline \end{array}$ | --- |
| SRT2-MD32ML | Input side: <br> G7TC-ID16 <br> G7TC-IA16 <br> Output side: <br> G7TC-OC16/OC18 <br> G70D-SOC16/VSOC16 <br> G70A-ZOC16-3 | $\begin{aligned} & \text { G79-M50-25-D1 }(50 \mathrm{~cm}) \\ & \text { G79-M75-50-D1 }(75 \mathrm{~cm}) \end{aligned}$ | Inputs and outputs are distinguished by color. The tube for the input side is red and the tube for the output side is yellow. |
| SRT2-OD32ML | $\begin{aligned} & \text { G7TC-OC16/OC08 } \\ & \text { G70D-SOC16/VSOC16 } \\ & \text { G70A-ZOC16-3 } \end{aligned}$ | $\begin{aligned} & \text { G79-O50-25-D1 }(50 \mathrm{~cm}) \\ & \text { G79-O75-50-D1 }(75 \mathrm{~cm}) \end{aligned}$ | --- |
| SRT2-ID32ML-1 | G70A-ZIM16-5 | $\begin{aligned} & \hline \text { G79-150-25-D2 }(50 \mathrm{~cm}) \\ & \text { G79-175-50-D2 }(75 \mathrm{~cm}) \\ & \hline \end{aligned}$ | --- |
| SRT2-MD32ML-1 | Input side: G70A-ZIM16-5 <br> Output side: G70A-ZOC16-4 G70D-SOC16-1 | G79-M50-25-D2 $(50 \mathrm{~cm})$ G79-M75-50-D2 (75 cm) | Inputs and outputs are distinguished by color. The tube for the input side is red and the tube for the output side is yellow. |
| SRT2-OD32ML-1 | $\begin{aligned} & \text { G70A-ZOC-16-4 } \\ & \text { G70D-SOC 16-1 } \end{aligned}$ | $\begin{aligned} & \text { G79-O50-25-D1 }(50 \mathrm{~cm}) \\ & \text { G79-O75-50-D1 }(75 \mathrm{~cm}) \\ & \hline \end{aligned}$ | --- |
|  | G7TC-OC16-1 | $\begin{array}{\|l\|} \hline \text { G79-150-25-D1 }(50 \mathrm{~cm}) \\ \text { G79-175-50-D1 }(75 \mathrm{~cm}) \\ \hline \end{array}$ | --- |


| Model | Connected product | Applicable Cable | Remarks |
| :---: | :---: | :---: | :---: |
| $\begin{array}{\|l\|} \hline \begin{array}{l} \text { All } \\ \text { models } \end{array} \\ \hline \end{array}$ | XW2B-40GXW2B-40G5XW2D-40G6 | XW2Z-C25K <br> ( 25 cm ) | XW2B-40G4 |
|  |  | XW2Z-C50K <br> ( 50 cm ) |  |

Cables with Stranded Wires

| Model | Connected <br> product | Applicable <br> Cable | Remarks |
| :--- | :--- | :--- | :--- |
| All <br> models | --- | G79-A200C-D1 <br> $(2 \mathrm{~m})$ | -- |

## omROn

## Compact Remote I/O Terminals that

## Save Wiring Effort and Enable

Long-distance or high-speed communications mode is selectable
Incorporates I/O connectors making it possible to minimize the size

- I/O connectors save wiring effort.
- Flexible DIN track mounting is possible through a DIN track attachment.
- Eight-point sensor connector models and 16-point Eight-point sensor connector models and
MIL connector models are the same size



## - Features

Vertical or horizontal DIN track mounting according to the available space is possible,
Saves space and easily connects to other devices without wiring effort.


Ordering Information

| 1/0 classification | Internal I/O circuit common | 1/O points | I/O connection method | Model |
| :---: | :---: | :---: | :---: | :---: |
| Digital input | NPN (+ common) | 8 | Sensor connector | SRT2-VID08S |
|  | PNP (- common) |  |  | SRT2-VID08S-1 |
| Digital output | NPN (- common) |  |  | SRT2-VOD08S |
|  | PNP (+ common) |  |  | SRT2-VOD08S-1 |
| Digital input | NPN (+ common) | 16 | MIL connector | SRT2-VID16ML |
|  | PNP (- common) |  |  | SRT2-VID16ML-1 |
| Digital output | NPN (- common) |  |  | SRT2-VOD16ML |
|  | PNP (+ common) |  |  | SRT2-VOD16ML-1 |
| Mounting hook A |  |  |  | SRT2-ATT01 |
| Mounting hook B |  |  |  | SRT2-ATT02 |

[^1]Specifications

## - Ratings

Inputs

| Item | SRT2-VID08S <br> SRT2-VID08S-1 | SRT2-VID16ML <br> SRT2-VID16ML-1 |
| :--- | :--- | :--- |
| Input current | 6 mA max./point at 24 V, 3 mA max./point at 17 V |  |
| ON delay time | 1.5 ms max. |  |
| OFF delay time | 1.5 ms max. |  |
| ON voltage | 15 VDC min. (Between each input terminal and V: NPN. Between each input and G: PNP.) |  |
| OFF voltage | 5 VDC max. (Between each input terminal and V: NPN. Between each input and G: PNP.) |  |
| OFF current | 1 mA max. |  |
| Insulation method | Photocoupler |  |
| Maximum number of inputs | 8 | 12 |
| Number of circuits | 8 points/common, 1 circuit | 16 points/common, 1 circuit |

Number of circuits
Outputs

| Item | SRT2-VID08S <br> SRT2-VID08S-1 <br> Rated output current | 0.3 A/point |
| :--- | :--- | :--- |

Number of circuits

## Characteristics

| $\begin{array}{\|l} \hline \begin{array}{l} \text { Communications power supply } \\ \text { voltage } \end{array} \\ \hline \end{array}$ | 14 to 26.4 VDC |
| :---: | :---: |
| 1/O power supply voltage | 20.4 to $26.4 \mathrm{VDC}(24 \mathrm{VDC}+10 \% /$ - $15 \%$ ) |
| I/O power supply current | Sensor connector: 2.4 A max., MIL connector: 2.0 A max. |
| Current consumption (see note) | 50 mA max. at 24 VDC |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}\left(50 \mathrm{~m} / \mathrm{s}^{2}\right.$ for SRT2-ATT02) |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Dielectric strength | 500 VAC (between insulated circuits) |
| Ambient temperature | $\begin{array}{\|ll} \hline \text { Operating: } & -10^{\circ} \mathrm{C} \text { to } 55^{\circ} \mathrm{C} \text { (with no icing or condensation) } \\ \text { Storage: } & -25^{\circ} \mathrm{C} \text { to } 65^{\circ} \mathrm{C} \end{array}$ |
| Ambient humidity | $\begin{array}{\|ll} \hline \text { Operating: } & 25 \% \text { to } 85 \% \text { (with no condensation) } \\ \text { Storage: } & 25 \% \text { to } 85 \% \end{array}$ |
| Mounting strength | No damage when 100 N pull load was applied in all directions (40 N load for SRT2-ATT02) |
| Terminal strength | No damage when the following loads were applied: Communications connector: 100 N Sensor connector: 40 N MIL connector: 100 N |
| Screw tightening torque | Communications connector: $0.25 \mathrm{~N} \cdot \mathrm{~m}$ |
| Node address setting | Settings made at DIP switch (set before supplying power for Slave communications) |
| Weight | Approx. 75 g max. |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external s
nected to the input Remote Terminal and the current consumption of the load connected to the output Remote Terminal

## Nomenclature

SRT2-VID08S/SRT2-VID08S-1
SRT2-VOD08S/SRT2-VOD08S-1
(Sensor Connector Models) (Sensor Connector Models)

SRT2-VID16ML/SRT2-VID16ML-1 SRT2-VOD16ML/SRT2-VOD16ML-1
(MIL Connector Models)
Communications
Connectors


Output HOLD/CLEAR Mode Setting
Output HOLD/CLEAR Mode

| SW8 (HOLD) |
| :--- |
| OFF |


| OFF | Output status is sleared. |
| :--- | :--- |

ON $\quad$ Output status is maintained
Communications Mode Settin
Communications Mode
SW7 (DR)
OFF

| OFF |
| :--- | :--- |
| On |

$\qquad$
Reserved for System Use (Always OFF)
Node Address Setting



## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT2-VID08S
SRT2-VID08S-1
SRT2-VODO8S


SRT2-VID16ML
SRT2-VID16ML-1 SRT2-VOD16ML SRT2-VOD16ML-1


SRT2-ATT01


SRT2-ATT02

$\square$

Installation

- Internal Circuit Configuration


SRT2-VODOBS


SRT2-VOD16ML


SRT2-VID08S-1


SRT2-VOD08S-1

$\underset{\text { V® }}{\text { SRT-VID16ML-1 }}$


SRT2-VOD16ML-1


## ■ Terminal Arrangement and I/O Device Connection Examples

SRT2-VID08S


SRT2-VID16ML-1
SRT2-VOD16ML


Note: 1. $V$ terminals and $G$ terminals are respectively connected internally.
When supplying power for $/ \mathrm{O}$ from communications connectors, power can be supplied to the sensor output devices from V and G terminals.
2. When using an inductive load (solenoid, valve etc.), either use one with an internal reverse electromotive force absorption diode or attach a diode externally.

## Precautions

Refer to the CompoBus/S Operation Manual (W266-E1) before
using the Unit.
Communications Connector Pin Arrangement


The following solderless terminals are recommended.

- Manufacturer: Weidmuller


The following product is a dedicated tool.

- Manufacturer: Weidmuller

Sensor Connector Pin Arrangement

## SRT2-VID08S/VID08S-1 SRT2-VOD08S/VOD08S-1

 Note: The XS8A-0441 or XS8A-0442 Connector is not provided with the SRT2-VID or SRT2-VOD. Place an order for the
connector separately.
Applicable Cables

| Connectable product | Model |  | Applicable Cable |
| :---: | :---: | :---: | :---: |
| 1 VO Block |  | $\leftrightarrow$ | G79.050C (L $=500 \mathrm{~mm}$ ) |
|  |  |  |  |
|  |  |  | G79.025C ( $\mathrm{L}=250 \mathrm{~mm}$ ) |
| Connector-Terminal Conversion Unit | xW2B Series |  |  |
| Digital Display Unit | M7F |  |  |
| 10 Block | $\begin{aligned} & \hline \text { G7TC-ID16 } \\ & \text { G7TC-1A16 } \\ & \text { G7TC-OC16-1 } \end{aligned}$ | $\leftrightarrow$ | G79-150C ( $\mathrm{L}=500 \mathrm{~mm}$ ) |
|  |  |  | G79-125C (L = 250 mm ) |

## omron

## Waterproof Terminals

## Eight Waterproof Terminal Models

## Emphasizing Cost Efficiency

- Reduced Labor

Connection using connectors reduces the lead time required for installation. No tools are required for connection to a variety of devices.

- Reduced Wiring

Signal line wiring has been reduced so that the Terminal can
other devices.

- Relay Box not Required

Environment-resistant, dust-tight, drip-proo
construction (IP67) enables direct on-site
mounting.

- Easier Maintenance

Significant reductions not only in setup time but also
maintenance time

- Reduced Space, Improved Operability

Compact design ( $160 \times 54 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H})$ ) (8-point Settings and connections can be performed usin the switch and connectors on the front side of the Terminal
■ System Configuration


Ordering Information

| Input/Output | Internal I/O circuit common | 1/O points | I/O connections method | Rated voltage for I/O power supply | Model |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Inputs | NPN (+ common) | 4 points | Sensor I/O connector | 24 VDC | SRT2-ID04CL |
|  |  | 8 points |  |  | SRT2-ID08CL |
|  | PNP (- common) | 4 points |  |  | SRT2-ID04CL-1 |
|  |  | 8 points |  |  | SRT2-ID08CL-1 |
| Outputs | NPN (- common) | 4 points |  |  | SRT2-OD04CL |
|  |  | 8 points |  |  | SRT2-OD08CL |
|  | PNP (+ common) | 4 points |  |  | SRT2-OD04CL-1 |
|  |  | 8 points |  |  | SRT2-OD08CL-1 |

## Specifications

■ General Specifications

| Item | SRT2-ID04CL SRT2-ID04CL-1 SRT2-OD04CL SRT2-OD04CL-1 | SRT2-ID08CL SRT2-ID08CL-1 SRT2-OD08CL SRT2-OD08CL-1 |
| :---: | :---: | :---: |
| Communications power supply voltage | 14 to 26.4 VDC (supplied via communications connectors) |  |
| I/O power supply voltage | 20.4 to 26.4 VDC ( $^{24} \mathrm{VDC}_{-15 \% /+10 \% \text { ) }}$ |  |
| Communications current consumption | 15 mA max. | 20 mA max. |
| Ambient temperature | Operating: $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing) <br> Storage: $-25^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ |  |
| Ambient humidity | Operating: $25 \%$ to $85 \%$ (with no condensation) <br> Storage: $25 \%$ to $85 \%$ (with no condensation) |  |
| Connector tightening torque | 0.39 to $0.49 \mathrm{~N} \cdot \mathrm{~m}$ |  |
| Enclosure rating | IEC IP67 |  |
| Mounting method | Mounted using M5 screws |  |
| Weight | Approx. 180 g | Approx. 240 g |

■ Communications Media/Distances

| Communications medium |  | 4-conductor cable (VCTF, $0.75 \mathrm{~mm}^{2} \times 4$ ) |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { Communications } \\ & \text { distance } \end{aligned}$ | High-speed Communications Mode | 4-conductor VCTF cable: Main line length: $\quad 30 \mathrm{~m}$ max. Branch line length: $\quad 3 \mathrm{~m}$ max. Total branch line length: 30 m max. (When 4-conductor VCTF cable is used to connect fewer than 16 Slaves, the main line can be up to 100 m long and the total branch line length can be up to 50 m .) cel |
|  | Long-distance Communications Mode | 4-conductor VCTF cable: <br> Variable branch wiring (total cable length 200 m max.) <br> (There are no limits on the branching format or main, branch, or total line lengths. The terminator must be connected to the point in the system farthest from the master.) |


| Item | SRT2-ID04CL SRT2-ID04CL-1 | SRT2-ID08CL SRT2-ID08CL-1 |
| :---: | :---: | :---: |
| Input current | For input voltage of 24 VDC: 6 mA max. per point For input voltage of $17 \mathrm{VDC}: 3 \mathrm{~mA}$ min. per point |  |
| Input impedance | $4.4 \mathrm{k} \Omega$ |  |
| ON delay time | 1.5 ms max. |  |
| OFF delay time | 1.5 ms max. |  |
| ON voltage | 15 VDC min. |  |
| OFF voltage | 5 VDC max. |  |
| OFF current | 1 mA max. |  |
| Number of circuits | 4 points with 1 common | 8 points with 1 common |

## ■ Output Specifications

| Item | SRT2-OD04CL SRT2-OD04CL-1 | SRT2-OD08CL SRT2-OD08CL-1 |
| :---: | :---: | :---: |
| Rated output current | 0.5 A per point (2 A per common) | 0.5 A per point (2.4 A per common) |
| Residual voltage | 1.2 V max. |  |
| Leakage current | 0.1 mA max. |  |
| ON delay time | 0.5 ms max. |  |
| OFF delay time | 1.5 ms max. |  |
| Number of circuits | 4 points with 1 common | 8 points with 1 common |

## - Applicable Connectors

Power Supply Connectors

| Model | Specification |
| :--- | :--- |
| XS2C-D4 $\square \square$ | Assembling-type connector (crimp, <br> soldering, or screw) socket |
| XS2W-D42 $\square-\square \square \square-\square$ | Cable with connector on each end |
| XS2F-D42 $\square-\square 80-\square$ | Cable with connector at one end <br> (socket end) |
| XS2R-D427-5 | T-branch connector |

I/O Connectors

| Model | Specification |
| :--- | :--- |
| XS2G-D4 $\square \square$ | Assembling type connector (crimp, <br> soldering, or screw) Socket |
| XS2H-D421- $\square \square \square-\square$ | Cable with connector at one end <br> (plug end) |
| XS2W-D42 $\square-\square \square \square-\square$ | Cable with connector on each end |
| XS2Z-12 | Waterproof cover |
| XS2Z-15 | Dust cover |

Communications Connector

| Model | Specification |
| :--- | :--- |
| XS2R-D427-5 | T-branch connector |
| SRS2-1 | Connector with terminating resistor <br> (plug) |
| XS2G-D4S7 | Assembling-type connector (for <br> 4-conductor VCTF cable) plug <br> (See note.) |
| XS2C-D4S7 | Assembling-type connector (for <br> 4 -conductor VCTF socket) socket <br> (See note.) |

Note: The XS2G-D4S7 and XS2C-D4S7 will be released soon.

## Assembling-type Connector Socket



Note: Only the XS2C-D4S7 with a diameter of 7 mm can be used for communications.

[^2]| Appearance | Applicable cable external dia. | Cable pull-outdirection | No. of poles | Connection method |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | Crimp | Solder | Screw |
|  | 6 dia. (5 to 6 dia.) | Straight | 4 | XS2G-D4C1 | XS2G-D421 | XS2G-D4S1 |
|  |  | L-shaped |  | -- | XS2G-D422 | XS2G-D4S2 |
|  | 5 dia. (4 to 5 dia.) | Straight |  | XS2G-D4C3 | XS2G-D423 | XS2G-D4S3 |
|  |  | L-shaped |  | --- | XS2G-D424 | XS2G-D4S4 |
|  | 3 dia. (3 to 4 dia.) | Straight |  | XS2G-D4C5 | XS2G-D425 | XS2G-D4S5 |
|  |  | L-shaped |  | --- | XS2G-D426 | XS2G-D4S6 |
|  | 7 dia. | Straight |  | --- | --- | XS2G-D4S7 (see note) |

Note: Only the XS2G-D4S7 with a diameter of 7 mm can be used for communications.

## Connectors with Cables (Single-end Socket Each) Power Supply

| Appearance | Cable pull-out direction | No. of cable conductor | Cable length (m) | Standard cable | $\begin{gathered} \text { Robot cable } \\ \text { (vibration resistive) } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 4 | 1 | XS2F-D421-C80-A | XS2F-D421-C80-R |
|  |  |  | 2 | XS2F-D421-D80-A | XS2F-D421-D80-R |
|  |  |  | 5 | XS2F-D421-G80-A | XS2F-D421-G80-R |
|  |  |  | 10 | XS2F-D421-J80-A | XS2F-D421-J80-R |
|  | L-shaped | 4 | 1 | XS2F-D422-C80-A | XS2F-D422-C80-R |
|  |  |  | 2 | XS2F-D422-D80-A | XS2F-D422-D80-R |
|  |  |  | 5 | XS2F-D422-G80-A | XS2F-D422-G80-R |
|  |  |  | 10 | XS2F-D422-J80-A | XS2F-D422-J80-R |

Connectors with Cables (Sockets and Plugs)
Power Supply and $1 / \mathrm{O}$

| Appearance | Cable pull-out direction | No. of cable conductor | Cable length (m) | Standard cable |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | StraightStraight | 4 | 1 | XS2W-D421-C81-A | XS2W-D421-C81-R |
|  |  |  | 2 | XS2W-D421-D81-A | XS2W-D421-D81-R |
|  |  |  | 5 | XS2W-D421-G81-A | XS2W-D421-G81-R |
|  | L-shapedL-shaped |  | 2 | XS2W-D422-D81-A | --- |
|  |  |  | 5 | XS2W-D422-G81-A |  |
|  | Straightl-shaped |  | 2 | XS2W-D423-D81-A |  |
|  |  |  | 5 | XS2W-D423-G81-A |  |
|  | L-shaped/Straight |  | 2 | XS2W-D424-D81-A |  |
|  |  |  | 5 | XS2W-D424-G81-A |  |

Connectors with Cables (Single-end Connector Each)

| Appearance | Cable pull-out direction | No. of cable conductor | Cable length ( m ) | Standard cable |
| :---: | :---: | :---: | :---: | :---: |
|  | Straight | 3 | 0.3 | XS2H-D421-ACO-A |
|  |  | 4 |  | XS2H-D421-A80-A |
|  |  | 3 | 1 | XS2H-D421-CCO-A |
|  |  | 4 |  | XS2H-D421-C80-A |

## Connector Covers

| Appearance | Product | Model | Application |
| :---: | :--- | :--- | :--- |
|  | T-branch Connector | Branching communications lines and <br> power lines |  |
|  | Connector Terminator (plug) | SRS2-1 | Waterproof terminator |
|  | Waterproof cover | xS2Z-12 | Covers tor unused IOO connectors |
|  |  |  |  |
|  | Dust cover |  |  |

## Dimensions

Note: All units are in millimeters unless otherwise indicated
Models with 4 points
SRT2-IDO4CL/SRT2-IDO4CL-1
SRT2-OD04CL/SRT2-ODO4CL-1



Mounting Dimensions
Three, M5 or 5.3-dia. holes


Models with 8 points SRT2-ID08CL/SRT2-IDO8CL-1
SRT2-OD08CL/SRT2-ODO8CL-1


Mounting Dimensions


Installation

- Internal Circuit Diagrams


SRT2-ODO $\square C L$ (NPN)
SRT2-ODO $\square C L-1$ (PNP)



## Connections Diagrams for Connectors

$$
\begin{aligned}
& \text { Communications Connector } \\
& \text { Communication } \\
& \begin{array}{l}
\text { Signal } \\
\text { BDH }
\end{array}
\end{aligned}
$$

IDO $\square(-1)$ Power
Supply Connecto ODO $\square(-1)$ Power ODuply $(-1)$ Power
Supply C


IDO $\square$ Input Connector (NPN)
 IDO $\square$ - 1 Input Connector (PNP)


ODO $\square$ Outpu Connect
(NPN) Solenoid and

opo Output Connect
(PNP) Solenoid and Solenoid and
Voltage


## omROn

## Sensor Terminals

## Connector Connection Models that

Allows Easy Connection to Sensors and Output Devices

- Sensors with easy-to-wire connectors are easily attached or detached.
- Connects to 2-wire sensors
- Remote teaching of the Sensor Terminal is possible with the PLC by using output signals of the Senso Terminal
- DIN track mounting and screw mounting are available.


Ordering Information

| Classification | Internal I/O circuit common | I/O points | Model |
| :--- | :--- | :--- | :--- |
| For input | NPN (-common) | 8 input points | SRT2-ID08S |
| For //O | NPN (-common) | 4 input/4 output points | SRT2-ND08S |
| For output | NPN (- common) | 8 output points | SRT2-OD08S |

Specifications

## - Ratings

Input

| Item |  |
| :--- | :--- |
| Input current | 10 mA max./point |
| ON delay time | 1 ms max. |
| OFF delay time | 1.5 ms max. |
| ON voltage | 12 VDC min. between each input terminal and $\mathrm{V}_{\mathrm{CC}}$, the external sensor power supply |
| OFF voltage | 4 VDC max. between each input terminal and $\mathrm{V}_{\mathrm{CC}}$, the external sensor power supply |
| OFF current | 1 mA max. |
| Insulation method | Photocoupler |
| Input indicator | LED (yellow) |

Output

| Item | SRT2-ND08S | SRT2-OD08S |
| :--- | :--- | :--- |
| Rated output current | $20 \mathrm{~mA} /$ point | $300 \mathrm{~mA} /$ point |
| Residual voltage | $1 \mathrm{~V} \mathrm{max}$. | $0.6 \mathrm{~V} \mathrm{max}$. |
| ON delay time | 1 mm max. | -- |
| OFF delay time | 1.5 mm max. | -- |
| Leakage current | 0.1 mA max. |  |
| Insulation method | Photocoupler |  |
| Output indicator | LED (yellow) |  |

## Characteristics

| Communications power supply voltage (see note 1) | 14 to 26.4 VDC |
| :---: | :---: |
| Current consumption (see note 2) | $50 \mathrm{~mA} \mathrm{max}$. |
| Connection method | Multi-drop method and T-branch method |
| Dielectric strength | 500 VAC for 1 min (1-mA sensing current between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4 2 kV (power lines) |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |
| Shock resistance | Malfunction: $200 \mathrm{~m} / \mathrm{s}^{2}$ Destruction: $300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting method | M4 screw mounting or $35-\mathrm{mm}$ DIN track mounting |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions (except the DIN track directions and a pulling force of 10 N ) |
| Terminal strength | No damage when 50 N pull load was applied for 10 s in all directions Tighten each screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ |
| Weight | SRT2-ID08S/OD08S: 100 g max., SRT2-ND08S: $80 \mathrm{~g} \mathrm{max}$. |

Note: 1. The communications power supply voltage must be 20.4 to 26.4 VDC if the Unit is connected to 2 -wire proximity sensors.
2. The above current consumption is a value with all the points turned OFF excluding the current consumption of the sensor connected
2. The above current consul
to the Sensor Terminal.

- External Sensor Power Supply

| Power supply voltage | 13.5 to 26.4 VDC |
| :--- | :--- |
| Current consumption | 500 mA max. in total |

## Nomenclature

SRT2-ID08S
SRT2-ND08S


| Indicator | Name | Display | Color | Meaning |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Lit | Green | The communications power supply is ON. |  |
|  |  | Not lit |  | The communications power supply is OFF. |  |
| COMM | Communication | Lit | Yellow | Normal communications |  |
|  |  | Not lit |  | A communications error has occurred or the Unit is in standby status. |  |
| ERR | Communication error | Lit | Red | A communications error has occurred. |  |
|  |  | Not lit |  | Normal communications or the Unit is in standby status. |  |
| 0 to 3 <br> (4 inputs/outputs) <br> 0 to 7 (8 inputs) <br> 0 . | Input | Lit | Yellow | The corresponding input is ON . |  |
|  |  | Not lit |  | The corresponding input is OFF or the Unit is in standby status. |  |
| $\begin{aligned} & 0 \text { to } 3 \\ & \text { (4 inputs/outputs) } \end{aligned}$ | Output | Lit | Yellow | The corresponding output is ON. |  |
|  |  | Not lit |  | The corresponding output is OFF or the Unit is in standby status. |  |
| Switch Setting <br> All pins are factory-set to OFF. |  |  |  | Pin 5 (Communications Mode Setting) |  |
|  |  |  |  | Pin 5 | Communications mode |
|  |  |  |  | OFF | High-speed communications mode |
|  |  |  |  | ON | Long-distance communications mode |

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N
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Pin 6 (Output HOLD/CLEAR Mode)
(SRT2-ND08S Only)
(SRT2-ND08S Only)

| HOLD | Function |
| :--- | :--- |
| OFF | Output status is cleared when a <br> communications error occurs. |
| ON | Output status is maintained when a <br> communications error occurs. |

Node Number Settings

| Node number | $\mathbf{l}$ |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| 0 | OFF | OFF | OFF | $\mathbf{4}$ |
| 1 | ON | OFF | OFF |  |
| 2 | OFF | ON | OFF | OFF |
| 3 | ON | ON | OFF | OFF |
| 4 | OFF | OFF | OFF | OFF |
| 5 | ON | OFF | ON | OFF |
| 6 | OFF | ON | ON | OFF |
| 7 | ON | ON | ON |  |
| 8 | OFF | OFF | ON | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | OFF | ON | OFF | ON |
| 11 | ON | ON | OFF | ON |
| 12 | OFF | OFF | OFF | ON |
| 13 | ON | OFF | ON | ON |
| 14 | OFF | ON | ON | ON |
| 15 | ON | ON | ON | ON |

SRT2-ODO8S

| Indicator | Name | Display | Color | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Lit | Green | The communications power supply is ON . |
|  |  | Not lit |  | The communications power supply is OFF. |
| COMM | Communication | Lit | Yellow | Normal communications |
|  |  | Not lit |  | A communications error has occurred or the Unit is in standby status. |
| ERR | Communication error | Lit | Red | A communications error has occurred. |
|  |  | Not lit |  | Normal communications or the Unit is in standby status. |
| OUTO to 7 | Output | Lit | Yellow | The corresponding output is ON . |
|  |  | Not lit |  | The corresponding output is OFF or the Unit is in standby status. |

## Switch Setting

ETVETB
$\begin{array}{r}123456 \\ \hline 124\end{array}$


# Pin 5 (Communications Mode Setting) 

| Pin 5 | Communications mode |
| :--- | :--- |
| OFF | High-speed communications mode |
| ON | Long-distance communications mode |

Pin 6 (Output HOLD/CLEAR Mode)

| HOLD | Function |
| :--- | :--- |
| OFF | Output status is cleared when a <br> communicitaios error occurs. |
| ON | Output status is maintained when a <br> communications error occurs. |

Node Number Settings

| Node number | 4 | 3 | 2 | 1 |
| :---: | :---: | :---: | :---: | :---: |
| 0 | OFF | OFF | OFF | OFF |
| 1 | OFF | OFF | OFF | ON |
| 2 | OFF | OFF | ON | OFF |
| 3 | OFF | OFF | ON | ON |
| 4 | OFF | ON | OFF | OFF |
| 5 | OFF | ON | OFF | ON |
| 6 | OFF | ON | ON | OFF |
| 7 | OFF | ON | ON | ON |
| 8 | ON | OFF | OFF | OFF |
| 9 | ON | OFF | OFF | ON |
| 10 | ON | OFF | ON | OFF |
| 11 | ON | OFF | ON | ON |
| 12 | ON | ON | OFF | OFF |
| 13 | ON | ON | OFF | ON |
| 14 | ON | ON | ON | OFF |
| 15 | ON | ON | ON | ON |

## Dimensions

## Note: All units are in millimeters unless otherwise indicated.



SRT2-ND08S



Cable Connector for SRT2- $\square$ D08S

| Applicable conductor size $\left(\mathbf{m m}^{2}\right)$ | Model |
| :--- | :--- |
| 0.3 to 0.5 | XS8A-0441 |
| 0.14 to 0.2 | XS8A-0442 |
| 0.3 to 0.5 | XS8BB-0443 |

XS8A-044 $\square$ (Cable Connector)


XS8B-0443 (Relay Socket)


Calculate the cable conductor size as explained below.
he following information is given on each sensor cable: Cable dia. (Number of conductors/Conductor dia.)
解ductor size $\left(\mathrm{mm}^{2}\right)=(\text { Conductor dia. } / 2)^{2} \times \pi \times$ Number of conductors
4 dia. $(18 / 0.12)$
Conductor size
( $\left.\mathrm{mm}^{2}\right)=(0.12 / 2)^{2} \times 3.14 \times 18 \approx 0.20$

Installation

- Internal Circuit Configuration


SRT2-OD08S


- External Connections

SRT2-ID08S
SRT2-ND08S
Sensor with Teaching Function Sensor with External Diagnostic functio Sensor with Bank-swit ing Function


- Terminal Arrangement and I/O Device Connection Example



## Precautions

Refer to the CompoBus/S Operation Manual (W266-E1) before

## using the Un

## General Safety Precautions

Installation Environment
Do not install the Unit in the following places.

- Places with water, oil, or chemical sprayed on the Unit.

Places with rapid temperature changes

- Places with high humidity resulting in condensation
- Places with intense electric and magnetic fields.
- Places with excessive vibration or shock.

Wiring
To prevent inductive noise, do not wire power lines or high-tension To prevent inductive noise, do not
nes along with or near the cables,
Make sure that the polarity of each terminal is correct.
Make sure that the communications path and power line are con
nected correctly. ected correctly.
Secure the cables properly. Do not pull the cables with strong force,
otherwise the cables may be disconnected from the terminals or therwise the cables mat.
connectors of the Unit.
Do not touch the Unit when the Unit is used in places with high amb ent temperatures because the surface temperature of the Unit may be high.
, surface will be damaged or discolored.
Correct Use
Use the Unit under its rated conditions.
Mount the Unit with M4 screws or to DIN tracks securely.
Typical Causes of Communications Errors

- The cables are not connected correctly.

The node number setting is incorrect

- The baud rate setting is incorrect.
- There is a strong noise source, such as an inverter motor, near the Unit. Install the Unit as far as possible from the noise source


## Othe

Use OMRON's XS8A-0441 or XS8A-0442 Connectors with the
Insert each connector into the Unit until the connector snaps in
place. Make sure that terminal number 1 of the connector is on the place. Make sure that terminal number 1 of the connector is on the ock lever side when inserting the connector
Refer to the CompoBus/S Operation Manual (W266-E1) for wiring Refer to th
the Unit.

## omron

CompoBus/S Sensor Amplifier Terminals

## Snap On to Connect and

Save Wiring Effort

- The 4-channel fiber photoelectric amplifiers in Terminals with connectors offer a low cost and space savings
- Connection of miniature and aluminum-detecting proximity sensors is supported.
- The product lineup included Terminal Block Units for easy connection to sensors with amplifiers, limit switches, etc.


Connect to up to eight channels of sensors by using Expansion Blocks.

- Features



## Ordering Information

| Classification | I/O points | Connection Unit | Model |
| :---: | :---: | :---: | :---: |
| Communications | 4 | $\begin{aligned} & \hline \text { E3X-NT■/E3X-DAD/E2CD-T1 } \\ & \text { 6/E39-JID01 (4 Units max.) } \end{aligned}$ | SRT1-TID04S |
|  |  | E3X-NM16 (1 Unit max.) | SRT1-TKD04S |
| Expansion |  | $\begin{aligned} & \text { E3X-NT } \square / E 3 X-D A 16 / E 2 C \square-T 1 \\ & \text { 6/E39-JID01 (4 Units max.) } \end{aligned}$ | SRT1-XID04S |
|  |  | E3X-NM16 (1 Unit max.) | SRT1-XKD04S |

## ote: Long-distance co munications mode is not supported.

## Connection Units

|  | Classification | Specifications | Model |
| :---: | :---: | :---: | :---: |
| Photoelectric Sensor | Models with E3X-N-type connector | General-purpose, 1 channel | E3X-NT16 |
|  |  | Multi-functional, 1 channel | E3X-NT26 |
|  |  | Long distance, high accuracy, 1 channel | E3X-NH16 |
|  |  | Multi-functional, 4 channels | E3X-NM16 |
|  | Models with E3X-DA-type connector | Digital, general-purpose, 1 channel | E3X-DA16 |
| Proximity Sensor | Models with E2CY-type connector | Used to detect aluminum | E2CY-T16 |
|  | Models with E2C-T-type connector | Miniature | E2C-T16 |
| Terminal Block Unit |  | One input point | E39-JID01 |

## Specifications

## Characteristics

## CompoBus/S Sensor Amplifier Terminals

| Item | Communication Terminals |  | Expansion Terminals |  |
| :---: | :---: | :---: | :---: | :---: |
| Model | SRT1-TID04S | SRT1-TKD04S | SRT1-XID04S | SRT1-XKD04S |
| Communications power supply voltage | 14 to 26.4 VDC (See note 1) |  | --- | --- |
| I/O points | 4 input points |  |  |  |
| Connected Sensors | $\begin{array}{\|l} \text { Total of four E3X-NT } \square 6, \\ \text { E3XX-NH16, E3X-NA16, } \\ \text { E2C T-T16, or } \\ \text { E39-ID01 (See note 2) } \\ \hline \end{array}$ | One E3X-NM16 (See note 2) | Total of four E3X-NT■6, E3X-NH16, E3X-DA16, E2C口-T16, or E39-JID01 | One E3X-NM16 |
| Current consumption | 60 mA max. (See note 3) 10 mA max. (See note 3) 500 VAC for 1 min (1-mA sensing current between insulated circuits) |  |  |  |
| Dielectric strength |  |  |  |  |
| Noise immunity | Power supply normal: $\pm 600 \mathrm{~V}$ for 10 minutes with a pulse width of 100 ns to $1 \mu \mathrm{~s}$ Power supply common: $\pm 1,500 \mathrm{~V}$ for 10 minutes with a pulse width of 100 ns to $1 \mu \mathrm{~s}$ |  |  |  |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |  |  |  |
| Shock resistance | Malfunction: $200 \mathrm{~m} / \mathrm{s}^{2}$Destruction: $\quad 300 \mathrm{~m} / \mathrm{s}^{2}$ |  |  |  |
| Mounting method | M4 screw mounting or 35-mm DIN track mounting |  |  |  |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions (except the DIN track directions and a pulling force of 10 N |  |  |  |
| Terminal strength | No damage when 49 N pull load was applied for 10 s in all directions. Tighten each screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$. |  |  |  |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |  |  |  |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ |  |  |  |
| Weight | 70 gmax . | 65 g max . | 45 g max. | 35 g max. |

Note: 1. The communications power supply voltage must be 20.4 to 26.4 VDC if the Terminal is connected to 2 -wire proximity sensors.
2. When adding Connection Units, use SRT1-XID04S or SRT1-XKD04S.
3. The value does not include the current consumption of Connection Units.

| Model | E3X-DA16 | E3X-NH16 | E3X-NT16 | E3X-NT26 | E3X-NM16 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Current consumption | 75 mA max. |  | 50 mA max. |  | 150 mA |
| Response time | High-speed mode: <br> 0.25 ms (operate/release) Standard mode: <br> 1 ms (operate/release) Long-distance mode: 4 ms (operate/release) 4.0 ms max. when connected to the SRT1-GDD04S (standard mode) | 1 ms max. ( 4.0 ms max when connected to the $\qquad$ | $500 \mu \mathrm{~S}$ max. ( 2.0 ms max. when connected to the SRT1- $\square$ D04S) |  |  |
| Timer function | OFF-delay timer (settable in the range 0 to 200 ms in 5 -ms units) | Not available |  | OFF-delay timer (fixed to 40 ms ) |  |
| Remote teaching input | Not available |  |  | Available (Remote teaching disabled) |  |
| Indicator | Operation indicator (orange), 7-segment digital incident level display (red), 7 -segment digital incident level percentage display (red), inciden level and threshold 2-color indication bar (green and red), 7 -segment digital threshold display (red) | Operation indicator (orange) 8 -level incident level indicator (green) 13-level threshold indicator (red) |  |  |  |
| Teaching confirmation function | Indicators (red/green LED) and buzzer |  |  |  |  |
| Output | Light ON and Dark ON switch selectable |  |  |  |  |
| Ambient illumination | Sunlight: 20,000 lux max.; incandescent lamp: 10,000 lux max. | Sunlight: 10,000 lux max.; incandescent lamp: 3,000 lux max. |  |  |  |
| Insulation resistance | $20 \mathrm{M} \Omega$ max. (at 500 VDC ) |  |  |  |  |
| Dielectric strength | $1,000 \mathrm{VAC}$ at $50 / 60 \mathrm{~Hz}$ for 1 min |  |  |  |  |
| Vibration resistance | Destruction:10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |  |  |  |  |
| Shock resistance | Destruction:500 m/s ${ }^{2} 3$ times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |  |
| Mounting method | Connected to the SRT1-■DD04S using connectors. |  |  |  |  |
| Mounting strength | No damage when 49 N pull load was applied for 10 s in all directions. |  |  |  |  |
| Ambient temperature | Operating: $-25^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-30^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ (with no icing or condensation) | Operating: $-25^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation)Storage: $\quad-40^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ (with no icing or condensation) |  |  |  |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ (with no condensation)Storage: $\quad 35 \%$ to $85 \%$ (with no condensation) |  |  |  |  |
| Weight | 60 gmax . | 30 g max. | 30 g max. | 30 g max. | 60 g max. |


| Supply voltage | 12 to $24 \mathrm{VDC} \pm 10 \%$, ripple (p-p): $10 \%$ max. |
| :---: | :---: |
| Current consumption | 40 mA max. |
| Sensing distance adjustment range | 10\% min. of stable sensing distance |
| Adjustment method | Teaching |
| Differential travel | 10\% max. of sensing distance in FINE mode. $15 \%$ max. of sensing distance in NORM mode. |
| Response time | Refer to the response frequency of the Sensor Head in use. |
| Control output | NPN open collector output of 100 mA max . with a max. residual voltage of 1 V |
| Self-diagnostic output | NPN open collector output of 100 mA max . with a max. residual voltage of 1 V |
| Circuit protection | Reverse polarity, surge voltage, and load short-circuit (for both control output and diagnosis output) |
| Cord length compensation | Freely cut or extended within a range between 0.5 and 5 m |
| Indicators | Operation indicator (orange) <br> Excess gain level indicators (ON in green with sensing object in proximity and ON in orange with no sensing object in proximity) <br> Fine-tuning indicator (green) |
| Ambient temperature | Operating: -10 to $55^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ (with no condensation) |
| Influence of temperature on sensing distance (at $23^{\circ} \mathrm{C}$ ) | $\pm 10 \%$ max. ( $-10^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ ) |
| Insulation resistance | $50 \mathrm{M} \Omega \mathrm{min}$. (at 500 VDC ) between current carry parts and case |
| Dielectric strength | $1,000 \mathrm{VAC}(50 / 60 \mathrm{~Hz})$ for 1 min between current carry parts and case |
| Vibration resistance | Destruction: 10 to $150 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude or $100 \mathrm{~m} / \mathrm{s}^{2}$ for 2 hours each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Shock resistance | Destruction: $300 \mathrm{~m} / \mathrm{s}^{2}$ for 3 hours each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Mounting method | Connected to the SRT1-■पD04S using connectors. |
| Mounting strength | No damage when 49 N pull load was applied for 10 s in all directions. |
| Degree of protection | IEC60529 IP50 with the sensor cord and protective cover attached |
| Material | Case: PTB resin Cover: PC |
| Teaching monitor function | Orange and green indicators shared by operation and excess gain indication |
| Output status | Normally open or normally closed selectable |
| Weight (packaged state) | Approx. 30 g |


| Item |  |  | Sensor Head |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | E2C-CR5B2 | $\begin{aligned} & \text { E2C-CR8A } \\ & \text { E2C-CR8B } \end{aligned}$ | $\begin{aligned} & \text { E2C-X1A } \\ & \text { E2C-C1A } \end{aligned}$ | E2C-x1R5A |
| Supply voltage |  |  | 12 to $24 \mathrm{VDC} \pm 10 \%$ (operation: 10 to $26.4 \mathrm{VDC)}$ ), ripple (p-p): $\pm 10 \%$ max. |  |  |  |
| Current consumption |  |  | 50 mA max. |  |  |  |
| Sensing distance adjustment range(see note 1) | Setting distance for teaching without sensing object (see note 2) |  | 0.4 mm min. | 0.72 mm min. | 0.9 mm min. | 1.35 mm min. |
|  | Setting distance for teaching with and without sensing object or positioning teaching | $\begin{aligned} & 0+0 \\ & 40^{\circ} \mathrm{C} \end{aligned}$ | 0.1 to 0.7 mm | 0.16 to 1.2 mm | 0.2 to 1.5 mm | 0.3 to 2 mm |
|  |  | $\begin{aligned} & 0 \text { to } \\ & 5_{5}^{\circ} \mathrm{C} \end{aligned}$ | 0.1 to 0.5 mm | 0.16 to 0.8 mm | 0.2 to 1.0 m | 0.3 to 1.5 mm |
| Temperature influence |  |  | $\pm 25 \%$ max. of sensing distance at $23^{\circ} \mathrm{C}(0$ to $55^{\circ} \mathrm{C}$ ) | $\pm 10 \%$ max. of sensing distance at $23^{\circ} \mathrm{C}\left(0\right.$ to $55^{\circ} \mathrm{C}$ ) |  |  |
| Differential travel |  |  | $15 \%$ max. of sensing distance | 10\% max. of sensing distance |  |  |
| Response time |  |  | Refer to the response frequency of the Proximity Sensor in use. |  |  |  |
| Control output |  |  | NPN open collector output of 100 mA max. at 26.4 V with a residual voltage of 1 V max NO/NC selectable (NO: ON with a sensing object) |  |  |  |
| Cord length compensation |  |  | 3 m only 1,2, or 3 m selectable |  |  |  |
| Indicators |  |  | Operation indicator (orange) and stability indicator (green) |  |  |  |
| Teaching monitor function |  |  | Indicators (orange and green) also used for stability indication. |  |  |  |
| Ambient temperature |  |  | Operating: 0 to $55^{\circ} \mathrm{C}$ (with no icing or condensation) |  |  |  |
| Ambient humidity |  |  | Operating: 35\% to 95\% (with no icing) |  |  |  |
| Voltage influence |  |  | $\pm 1 \%$ max. of sensing distance within a range of $90 \%$ to $110 \%$ of the rated power supply voltage |  |  |  |
| Insulation resistance |  |  | $50 \mathrm{M} \Omega$ min. at 500 VDC between current carry parts and case |  |  |  |
| Dielectric strength |  |  | 1,000 VAC ( $50 / 60 \mathrm{~Hz}$ ) for 1 min between current carry parts and case |  |  |  |
| Vibration resistance |  |  | Destruction: 10 to $55 \mathrm{~Hz}, 1.5 \mathrm{~mm}$ double amplitude for 2 hours each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Mounting method |  |  | Connected to the SRT1-ם D04S using connectors. |  |  |  |
| Mounting strength |  |  | No damage when 49 N pull load was applied for 10 s in all directions. |  |  |  |
| Degree of protection |  |  | IEC60529 IP50 |  |  |  |
| Weight |  |  | Approx. $\mathbf{3 0 \mathrm { g }}$ |  |  |  |

Note: 1. Perform positioning teaching within the stable sensing distance, otherwise reset failures may result when the E2C-T is in operation If a fine-difference teaching is performed with and without a sensing object, reset failures may result when the E2C-T is in operation even if teaching is successful.
to

## Terminal Block Uni

| Model | E39-JID01 |
| :---: | :---: |
| Input current | 10 mA max. |
| ON voltage | 12 VDC min. between input terminal and external sensor power supply |
| OFF voltage | 4 VDC max. between input terminal and external sensor power supply |
| OFF current | 1 mA max. |
| ON delay time | $1 \mathrm{~ms} \mathrm{max}. \mathrm{(connected} \mathrm{to} \mathrm{SRT1-} \mathrm{\square} \mathrm{\square D04S)}$ |
| OFF delay time | 1.5 ms max. (connected to SRT1-■[D04S) |
| Input indicators | LED (Orange) |
| External sensor current capacity | 50 mA max. |
| Vibration resistance | 10 to $55 \mathrm{~Hz}, 1.5-\mathrm{mm}$ double amplitude |
| Shock resistance | Malfunction: $\quad 200 \mathrm{~m} / \mathrm{s}^{2}$ Destruction: $\quad 300 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting method | M4 screws or $35-\mathrm{mm}$ DIN track mounting |
| Mounting strength | No damage when 50 N pull load was applied for 10 s in all directions (except the DIN track directions and a pulling force of 10 N ) |
| Terminal strength | No damage when 49 N pull load was applied for 10 s in all directions. Tighten each screw to a torque of 0.6 to $1.18 \mathrm{~N} \cdot \mathrm{~m}$. |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) Storage: $\quad-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to 85\% |
| Weight | 25 g max. |

## Nomenclature

SRT1-TIDO4S
SRT1-TKDO4S


Indicators

| Indicator | Name | Display | Color | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Lit | Green | The communications power supply is ON . |
|  |  | Not lit |  | The communications power supply is OFF. |
| COMM | Communications | Lit | Yellow | Normal communications. |
|  |  | Not lit |  | A communications error has occurred or the Unit is in standby status. |
| ERR | Communications error | Lit | Red | A communications error has occurred. |
|  |  | Not |  | Norma |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT1-TIDOAS

Mounting Holes

SRT1-XIDO4S



SRT1-XKD04S

Mounting Holes



E3X-NT $\square 6$


E3X-NH16


E3X-DA16


E39-JD01


E2CY-T16


E2C-T16


Installation

- Internal Circuit Configuration E39-JID01



## Precautions

| Refer to the CompoBus／S Operation Manual（W266－E1）before using General－purpose Sensors and the Equivalent CompoBus／S Sensors |  |  |
| :---: | :---: | :---: |
| CompoBus／S product | General－purpose product product | Difference |
| E3X－NT16 | E3X－NT11 | External |
| E3X－NT26 | E3X－NT21 | appearance only |
| E3X－NM16 | E3X－NM11 |  |
| E3X－NH16 | E3X－NH11 |  |
| E3X－DA16 | E3X－DA11 |  |
| E2CY－T16 | E2CY－T11 |  |
| E2C－T16 | E2C－T11 |  |

## General Safety Precautions

Connection Units
Use only the Connection Units listed in this data sheet for the Sen
E39－JID01 Terminal Block Unit
not apply any voltage to the Terminal Block Unit

## Correct Use

Expanding Sensor Amplifier Terminals
Remove the cover from the side of the SRT1－TロD04S．（See
Figure 1．）
Figure 1．）
When the cover is removed，you can see the expansio
ector inside．
Connect this expansion connector to the connector located


Figure 1


Attaching and Removing Connection Units

| Attaching and Removing Connection Units |
| :--- |
| Sensor Amplifier Terminal Connection Unit <br> SRT1－TID04S E3XX－DA16 <br> SRT1－XID04S E3X－NTD6 <br> E339－JID01  <br> E3X－NH  <br> E2C  <br> E2C－T－T16  <br> E2C－T16  |

（SRT1－TID04S，SRT1－XID04S，E3X－NT $\square 6$, E39－JID01）
Attaching Connection Units
1．Hook Section A of the Connection Unit onto Section B of the Sensor Amplifier Terminal．
2．Push in the Connection Unit until Section C locks inside


## Botom View雨渭品

Removing Connection Units
1．While pushing Section D，pull the Connection Unit in direction
2．When Section D releases from the lock，the Connection Unit can be removed．


## Attaching or Removing Connection Unit

| Sensor Amplifier Terminal | Connection Unit |
| :--- | :--- |
| SRT1-TKD04S | E3X-NM16 |
| SRT1-XKD04S |  |

Attaching Connection Unit

1. Hook Section A of the Connection Unit onto Section B of the - Hook Section A of the Conn
2. Push in the Connection Unit until Section C locks inside



Removing Connection Unit

1. While pushing Section D, pull the Connection Unit in direction
2. When Section D releases from the lock, the Connection Unit can be removed.


## Channel Numbers

Channel numbers 1 to 4 of the E3X-NM16 correspond to contac umbers 0 to 3 of the SRT1-TKD04S, and to contact numbers 4 to 7
of the SRT1-XKD04S.

## OmROn

## Analog Input Terminal

## Compact Analog Input Model is the

## Same Shape as 16 -point Remote I/O

Terminals
Allows flexible input point settings up to a maximum f four points.
Resolution: 1/6,000
Takes only 1 ms to exchange each input point.

- Wide input ranges available
- $105 \times 48 \times 50(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$


Ordering Information


500 VAC tor min beiween communications power supply, analog input, and communications terminals (see note)
Note: There is no insulation between analog inputs.

- Characteristics

| Communications power supply voltage | 14 to 26.4 VDC (possible to provide through Special Flat Cable) |
| :---: | :---: |
| Current consumption | 100 mA max. |
| Connection method | Multi-drop method and T-branch method |
| Dielectric strength | 500 VAC (between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0-\mathrm{mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage with 100 N pull load applied in all directions. |
| Terminal strength | No damage with 100 N pull load applied |
| Screw tightening torque | 0.3 to $0.5 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | $\begin{array}{\|ll} \hline \text { Operating: } & -10^{\circ} \mathrm{C} \text { to } 55^{\circ} \mathrm{C} \\ \text { Storage: } & -25^{\circ} \mathrm{C} \text { to } 65^{\circ} \mathrm{C} \\ \hline \end{array}$ |
| Ambient humidity | Operating: $25 \%$ to $85 \%$ (with no condensation) |
| Weight | Approx. 120 g |

## Nomenclature

## SRT2-AD04



DIN Track Mounting Hook

| Indicator | Name | Color | Display | Meaning |
| :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Green | Lit | The communications power supply is ON . |
|  |  |  | Not lit | The communications power supply is OFF. |
| COMM | Communication | Yellow | Lit | Normal communications |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |
| ERR | Communication error | Red | Lit | A communications error has occurred. |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |
| U.ERR | Unit error | Red | Lit | An error has occurred in the Unit. |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |

## DIP Switch (SW101)



| Pin 1 | Pin 2 | Input points |
| :---: | :---: | :---: |
| OFF | OFF | 4 points (default setting) |
| OFF | ON | 3 points (inputs 0 to 2 enabled) |
| ON | OFF | 2 points (inputs 0 and 2 enabled) |
| ON | ON | 1 point (input 0 enabled) |
| Pin 3 | Communications mode |  |
| OFF | High-speed communications (default setting) |  |
| ON | Long-distance communications |  |
| Pin 4 | Be sure to turn OFF. |  |
| Pin No. |  | Node address |
| Pin 5 | $2^{3}$ |  |
| Pin 6 | $2^{2}$ |  |
| Pin 7 | $2^{1}$ |  |
| Pin 8 | $2^{0}$ |  |


| Pin 1 | Pin 2 | Pin 3 | Range for inputs 0, 1 |
| :---: | :---: | :---: | :---: |
| Pin 4 | Pin 5 | Pin 6 | Range for inputs 2, 3 |
| OFF | OFF | OFF | 0 to 5 (V) (default setting) |
| ON | OFF | OFF | 1 to 5 (V) |
| OFF | ON | OFF | 0 to 10 (V) |
| ON | ON | OFF | -10 to 10 (V) |
| OFF | OFF | ON | 4 to 20 (mA) |
| ON | OFF | ON | 0 to 20 (mA) |
| Do not make any settings other than the ones listed above. |  |  |  |
| Pin 7 | Mean value processing |  |  |
| OFF | Without mean value processing (default setting) |  |  |
| ON | With mean value processing (mean for 8 operations) |  |  |
| Pin 8 | Be sure to turn OFF. |  |  |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT2-AD04


Installation

■ Internal Circuit Configuration SRT2-AD04


- Terminal Arrangement

SRT2-ADO4


Note: When the input is current input, short-circuit the " $\mathrm{V}_{+}$" terminals and the "Il" terminals. When short-circuiting, use the short-circuiting tool provided as an accessory.

## Precautions

Refer to the CompoBus/S Operation Manual (W266-E1) before
using the Unit.

## OmROn

## Analog Output Terminal

Compact Analog Output Model is the
Same Shape as 16-point Remote I/O
Terminals
Two output points or 1 output point is selectable.

- Resolution: 1/6,000
- $105 \times 48 \times 50(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$

Ordering Information

| Classification | I/O points | Model |
| :---: | :---: | :---: |
| Analog Output Terminal | 1 or 2 (selectable with DIP switch) | SRT2-DA02 | Note: For details about connecting the SRT2-DA02 to the Master Unit, refer to page 25,

Specifications

## - Ratings

Output

| Item |  | Voltage output | Current output |
| :---: | :---: | :---: | :---: |
| External output permissibleload resistance load resistance |  | $5 \mathrm{k} \Omega$ min. | $600 \Omega$ max. |
| Output impedance |  | $0.5 \Omega$ max. | --- |
| Resolution |  | 1/6,000 (FS) |  |
| $\begin{array}{\|l\|l\|} \hline \text { Total } \\ \text { accuracy } \end{array}$ | $25^{\circ} \mathrm{C}$ | $\pm 0.4 \%$ FS |  |
|  | -10 to $55^{\circ} \mathrm{C}$ | $\pm 0.8 \%$ FS |  |
| Conversion time |  | $2 \mathrm{~ms} / 2$ points and $2 \mathrm{~ms} / 1$ point |  |
| Dielectric strength |  | 500 VAC for 1 min between communications power supply, analog output, and communications terminals (see note) |  |

500 VAC for 1 min between

## - Characteristics

| Communications power supply voitage | 14 to 26.4 VVC (power supply possibie from Special Flat Cabie) |
| :---: | :---: |
| Current consumption (see note) | 170 mA max. |
| Connection method | Multi-drop method and T-branch method |
| Dielectric strength | 500 VAC (between insulated circuits) |
| Noise immunity | Conforms to IEC61000-4-4, 2 kV (power lines) |
| Vibration resistance | 10 to $150 \mathrm{~Hz}, 1.0 \mathrm{~mm}$ double amplitude or $70 \mathrm{~m} / \mathrm{s}^{2}$ |
| Shock resistance | $200 \mathrm{~m} / \mathrm{s}^{2}$ |
| Mounting strength | No damage when 100 N pull load was applied in all directions |
| Terminal strength | No damage when 100 N pull load was applied |
| Screw tightening torque | 0.3 to $0.5 \mathrm{~N} \cdot \mathrm{~m}$ |
| Ambient temperature | $\begin{array}{ll} \hline \text { Operating: } & -10^{\circ} \mathrm{C} \text { to } 55^{\circ} \mathrm{C} \\ \text { Storage: } & -25^{\circ} \mathrm{C} \text { to } 65^{\circ} \mathrm{C} \\ \hline \text { S } \end{array}$ |
| Ambient humidity | Operating: $25 \%$ to 85\% (with no condensation) |
| Weight | Approx. 100 g |

[^3]
## Nomenclature

SRT2-DA02


| Indicator | Name | Color | Display | Meaning |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| PWR | Power supply | Green | Lit | The communications power supply is ON. |  |  |  |
|  |  |  | Not lit | The communications power supply is OFF. |  |  |  |
| COMM | Communication | Yellow | Lit | Normal communications |  |  |  |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |  |  |  |
| ERR | Communication error | Red | Lit | A communications error has occurred. |  |  |  |
|  |  |  | Not lit | Normal communications or the Unit is in standby status. |  |  |  |
| U.ERR | Unit error | Red | Lit | An error has occurred in the Unit. |  |  |  |
|  |  |  | Not lit | A communications error has occurred or the Unit is in standby status. |  |  |  |
| DIP Switch (SW101) <br> (Open cover to access.) |  |  |  | DIP Switch (SW102) <br> (Open cover to access.) |  |  |  |
|  |  |  |  |  |  |  |  |
|  |  |  |  | Pin 1 | Pin 2 | Pin 3 | Range for output 0 |
| $\rightarrow \mathrm{ON}$ |  |  |  | Pin 4 | Pin 5 | Pin 6 | Range for output 1 |
| Pin 1 | Be sure to turn OFF. |  |  | OFF | OFF | OFF | 0 to 5 (V) (default setting) |
| Pin |  |  |  | ON | OFF | OFF | 1 to 5 (V) |
| Pin 2 | Output points |  |  | OFF | ON | OFF | 0 to 10 (V) |
| OFF | 2 points (default setting) |  |  | ON | ON | OFF | -10 to 10 (V) |
| ON | 1 point (output 0 enabled) |  |  | OFF | OFF | ON | 4 to 20 (mA) |
| Pin 3 | Communications mode |  |  | Do not make any settings other than the ones listed above. |  |  |  |
| OFF | High-speed communications (default setting) |  |  | Pin 7 | Pin 8 | Output during communications error |  |
| ON | Long-distance communications |  |  | OFF | OFF | Clear at the output lower limit when communications error occurs. (default setting) |  |
| Pin 4 | Be sure to turn OFF. |  |  |  |  |  |  |
| Pin No. | Node addresses |  |  | OFF | ON | Clear at the output upper limit when communications error occurs. |  |
| Pin 5 | $2^{3}$ |  |  | ON | OFF | Clear at the output lower limit when communications error occurs (however, if the range is -10 to 10 V , the output will be 0 ). |  |
| Pin 6 | $2^{2}$ |  |  |  |  |  |  |
| Pin 7 | $2^{1}$ |  |  |  |  |  |  |
| Pin 8 | $2^{0}$ |  |  | ON | ON | Output held when communications error occurs. |  |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT2-DA02


$$
\phi^{\text {Two, 4.2 dia. or M4 }}-\infty
$$

Installation

■ Internal Circuit Configuration SRT2-DA02


■ Terminal Arrangement
SRT2-DA02


| BD |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| L | BS | NC | NC | NC | $\mathrm{O-}$ | NC | $1-$ |

## Precautions

Refer to the CompoBus/S Operation Manual (W266-E1) before using the Uni

## omron

## Remote I/O Modules

## Module Type that Allows PCB Mounting

- Compact size at $60 \times 16 \times 35(\mathrm{~W} \times \mathrm{H} \times \mathrm{D})$
- Lineup now includes the 16 -point input model and 16 -point output model.


Ordering Information

| I/O classification | Internal /O circuit common | $1 / 0$ points | Rated voltage | I/O rated voltage | Model |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Input | NPN (+ common) | 16 | 24 VDC | 24 VDC | SRT2-ID16P |
| Output | NPN (-common) |  |  |  | SRT2-OD16P |

## Specifications

- Ratings

Input (SRT2-ID16P)

|  | Input current |
| :--- | :--- |
| ON delay time | 2 mA max./point |
| OFF delay time | 1.5 ms max. |
| ON voltage | 1.5 ms max. |
| OFF voltage | 15 VDC min. between each innut terminal and $\mathrm{BS}+$ terminal |

Output (SRT2-OD16P)

| Rated output current | 0.2 A /point, 0.6 A /common |
| :--- | :--- |
| Residual voltage | 0.6 V max. between each output terminal and G terminal at 0.2 A |
| Leakage current | 0.1 mA max. between each output terminal and G terminal at 24 VDC |

- Characteristics

| Communications power supply voltage | 20.4 to 26.4 VDC |
| :---: | :---: |
| 10 power supply voltage | $24 \mathrm{VDC}+10 \% /-15 \%$ |
| Current consumption (see note) | 60 mA max. |
| Connection method | Multi-drop method and T-branch method |
| Connecting Units | 8 Input Terminals and 8 Output Terminals per Master |
| Dielectric strength | 500 VAC for 1 min (1-mA sensing current between insulated circuits) |
| 5-V output current | $20 \mathrm{~mA} \mathrm{max}$. ( $5 \mathrm{~V} \pm 0.5 \mathrm{~V}$ ) |
| LED drive current (COMM, ERR) | $10 \mathrm{~mA} \mathrm{max}$. ( 5 VDC ) |
| SW carry current (ADRO to 3, HOLD) | 1 mA max. |
| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ (with no icing or condensation) <br> Storage: $-20^{\circ} \mathrm{C}$ to $65^{\circ} \mathrm{C}$ (with no icing or condensation) |
| Ambient humidity | Operating: $35 \%$ to $85 \%$ |
| Weight | 35 g max . |

Note: The above current consumption is the value with all points turned ON excluding the current consumption of the external sensor connected to the input model and the current consumption of the load connected to the output model.

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SRT2-ID16P
SRT2-OD16P


Installation
■ Internal Circuit Configuration


- External Connections

Input Module (SRT2-ID16P)
Output Module (SRT2-OD16P)


Node Number Settings and
Output HOLD/CLEAR Mode


Note: Refer to the CompoBus/S Operation Manual (W266-E1) for details on the switch.

Precautions
Refer to the CompoBus/S Operation Manual (W266-E1) before

## orrect Use

Noise Protection Circuit
Add the following protection circuit if noise is generated from the power supply, input section, or output section.


Input Section Noise Protection Circuit

$\mathrm{R}_{1}$ : Resistor for limiting photocoupler's input
D: Diode for protecting the photocoupler
C: Condenser for absorbing noise
$\mathrm{R}_{2}$ : Resistor for limititing the operating leve
PHC: Photocoupler
V: $\quad$ DC power supply

Indicators


R: LED current limiting resistor
R: $\begin{aligned} & \text { LED 1: current } \\ & \text { LED } \\ & \text { LED2: } \\ & \text { LED for } \operatorname{ERM} M\end{aligned}$
The maximum current for LED1 and 2 is 10 mA .
The 5 -V Output Terminals have positive power supplies (maximum output current of 20 mA ) for the ERR and COMM LEDs. Recom mended LED colors are red for ERR and yellow for COMM.

Output Section Noise Protection Circuit


C: Capacitance of $0.1 \mu \mathrm{~F}$ min.
R: Limiting resistor
SA: Varistor $\quad$ Diode for protecting against counterelectromotive PHC: Photocoupler
V: DC power supply
-v Output Terminals
The 5 -V Output Terminals have positive power supplies (maximum
 shown below. Recommended LED colors are red for ERR and yel
low for COMM.

Wiring Method


R: LED current limiting resistor
LED1: LED for COMM
The maximum current for the LED1 and 2 is 10 mA .

## Cleaning the PCB

- Perform soldering using a soldering iron at a temperature between 280 and $300^{\circ} \mathrm{C}$ in less than 3 seconds, or at
temperature less than $280^{\circ} \mathrm{C}$ in less than 5 seconds.
nure less han 2 in liess than 5 second.
Do not clean the PCB flux either using highly acidic or alkaline detergents, or using ultrasonic cleaning.
NC Terminals
C terminals are used internally. Do not make any connections to the NC terminals.


## omron

## Position Drivers

## Advanced Servodrivers with Positioner

Functions
DIO and CompoBus/S Models are Newly Added

- Servodriver and positioner are combined into one Unit
Conventional U-series, U-series UE type, H -series,
and M-series AC Servomotors can be used.
- Feeder control/DTP control and single operation automatic incremental/continuous operation ar vailable.
Easy to set, operate, and adjust.


Ordering Information

| Specifications |  |  | Model |
| :--- | :--- | :--- | :--- |
| CompoBus/S models | For 200-VAC input | 6 A | FND-X06H-SRT |
|  |  | 12 A | FND-X12H-SRT |
|  |  | 25 A | FND-X25H-SRT |
|  | 50 A | FND-X50H-SRT |  |
|  | For 100-VAC input | 6 A | FND-X06L-SRT |
|  |  | 12 A | FND-X12L-SRT |

Note: For details, refer to OMNUC FND-X-series User's Manual (I524).
Specifications

- General Specifications

| Ambient temperature | Operating: $0^{\circ} \mathrm{C}$ to $55^{\circ} \mathrm{C}$ <br> Storage: $-10^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |
| :---: | :---: |
| Ambient humidity | Operating: $35 \%$ to $90 \%$ (with no icing) <br> Storage: $35 \%$ to $90 \%$ (with no icing) |
| Operating atmosphere | No corrosive gases |
| Dielectric strength | $1,500 \mathrm{VAC}_{\text {RMS }}$ for 1 min at $50 / 60 \mathrm{~Hz}$ |
| Insulation resistance | $5 \mathrm{M} \Omega \mathrm{min}$. (at 500 VDC ) between power input terminals and between the power terminal and the case |
| Vibration resistance | 10 to 150 Hz in $\mathrm{X}, \mathrm{Y}$, and Z directions with $0.10-\mathrm{mm}$ single amplitude; acceleration: $9.8 \mathrm{~m} / \mathrm{s}^{2}$ max.; time coefficient: 8 min; 4 sweeps |
| Shock resistance | $98 \mathrm{~m} / \mathrm{s}^{2}$ max., three times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |
| Degree of protection | Built into panel (IP00) |

- Performance Specifications

| DIO models (see note 1) |  | FND-X06L | FND-X12L | FND-X06H | FND-X12H | FND-X25H | FND-X50H |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CompoBus/S models(see note 1) |  | FND-X06L-SRT | FND-X12L-SRT | FND-X06H-SRT | FND-X12H-SRT | FND-X25H-SRT | FND-X50H-SRT |
| Item |  |  |  |  |  |  |  |
| Continuous output current (0-P) |  | 2.0 A | 3.0 A | 2.0 A | 4.8 A | 8.0 A | 20 A |
| Momentary maximum output current (0-P) |  | 6.0 A | 12 A | 6.0 A | 12 A | 25 A | 50 A |
| $\begin{aligned} & \text { Input } \\ & \text { power } \\ & \text { soupply } \end{aligned}$ | Main circuit | Single-phase 100/115 VAC (85 to 127 V) $50 / 60 \mathrm{~Hz}$ (The same terminals are used for the main circuit and the control circuit.) |  | Single-phase 200/240 VAC ( 170 to 264 V ) $50 / 60 \mathrm{~Hz}$ (The same terminals are used for the main circuit and the control circuit.) |  |  | 3-phase 200/240 VAC (170 to 264 V) $50 / 60 \mathrm{~Hz}$ |
|  | Control <br> circuit |  |  | Single-phase 200/240 VAC (170 to 264 V) $50 / 60 \mathrm{~Hz}$ |
| $\begin{array}{\|l\|l\|} \hline \begin{array}{l} \text { Position/s } \\ \text { peed } \\ \text { feedback } \end{array} \end{array}$ | $\begin{aligned} & \text { U Series } \\ & \text { (INC) } \end{aligned}$ | 30 to 750 W: Optical incremental encoder, 2,048 pulses/revolution 1 to 2 kW : Optical incremental encoder, 4,096 pulses/revolution |  |  |  |  |  |
|  | USeries (ABS) | 30 to 750 W: Optical absolute encoder, 1,024 pulses/revolution 1 to 2 kW : Optical absolute encoder, 8,192 pulses/revolution |  |  |  |  |  |
|  | $\stackrel{\text { U-UE }}{ }$ | Optical incremental encoder, 1,024 pulses/revolution |  |  |  |  |  |
|  | HSeries | Magnetic incremental encoder 2,000 pulses/revolution |  |  |  |  |  |
|  | M Series | Resolver, absolute accuracy $0.18^{\circ}$ max.; ambient temperature $25^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Applicable load <br> inertia | $\begin{aligned} & \hline \text { USeries } \\ & \text { (INC) } \end{aligned}$ | Maximum of 30 times motor's rotor inertia |  |  |  |  | Maximum of 30 times motor's rotor inertia |  | Maximum of 20 times motor's rotor for $1-\mathrm{kW}$ motor) | Maximum of 10 times motor's rotor inertia |
|  | $\begin{array}{\|l\|} \hline \text { U Series } \\ \text { (ABS) } \end{array}$ | Maximum of 20 times motor's rotor inertia |  | Maximum of 20 times motor's rotor inertia |  | Maximum of 18 times motor's rotor inertia (10 times for $1-\mathrm{kW}$ for 1 -kW motor) | $\begin{aligned} & \text { Maximum of } 10 \\ & \text { times motor's rotor } \\ & \text { ineritia } \end{aligned}$ |
|  | $\underset{\text { Series }}{\text { U-UE }}$ | Maximum of 30 times motor's rotor inertia |  | Maximum of 30 times motor's rotor inertia |  | Maximum of 20 times motor's rotor inertia | --- |
|  | HSeries | Maximum of 10 times motor's rotor inertia |  |  |  |  |  |
|  | M Series | Maximum of 10 times motor's rotor inertia |  |  |  |  |  |
| Inverter method |  | PWM method based on IGBT |  |  |  |  |  |
| PWM frequency |  | 10 kHz |  |  |  |  |  |
| Weight |  | Approx. 1.5 kg |  | Approx. 1.5 kg |  | Approx. 2.5 kg | Approx. 4.5 kg |
| Frequency response (speed control) |  | 100 Hz (at a load inerria equivalent to motor's rotor ineriia) |  |  |  |  |  |
| Position loop gain |  | 1 to 200 (rad/s) |  |  |  |  |  |
| Feed forward |  | 0\% to 200\% of speed reference |  |  |  |  |  |
| Pulse rate |  | $1 / 32,767 \leq$ (pulse rate 1 / pulse rate 2 ) $\leq 32,767 / 1$ |  |  |  |  |  |
| Positioning completion width |  | 1 to 32,767 (pulses) |  |  |  |  |  |
| Acceleration/Decelerati on time |  | 0 to 9,999 (ms); acceleration and deceleration times set separately. Two types can be set for each. S-curve acceleration/deceleration function available (filter time constant: 0.00 to 32.76 s ). |  |  |  |  |  |
| Sequence input |  | 19 pts. (limit inputs, origin proximity, RUN command, START, alarm reset, origin search, JOG operation, teaching, point selection, position data, deceleration stop) <br> Photocoupler input: 24 VDC, 8 mA <br> External power supply: $24 \mathrm{VDC} \pm 1 \mathrm{~V}, 150 \mathrm{~mA}$ min. |  |  |  |  |  |
| Sequence output |  | 5 pts. (brake output, READY, origin search completion, origin, teaching, motor running, positioning completion, alarm, point output, position selection, speed selection) <br> Open collector output: 24 VDC, 40 mA |  |  |  |  |  |
|  | Speed monitor | $3 \mathrm{~V} /$ motor's rated speed (output accuracy: approx. $\pm 10 \%$ ) |  |  |  |  |  |
|  | Current | 3 V /motor's maximum current (output accuracy: approx. $\pm 10 \%$ ) |  |  |  |  |  |
| Regenerative absorption capacity |  | $13 \mathrm{~W}+17 \mathrm{~J}$ | $17 \mathrm{~W}+17 \mathrm{~J}$ | $13 \mathrm{~W}+17 \mathrm{~J}$ | $24 \mathrm{~W}+17 \mathrm{~J}$ | $37 \mathrm{~W}+22 \mathrm{~J}$ | $160 \mathrm{~W}+38 \mathrm{~J}$ |
| Protective functions |  | Overcurrent, overvoltage, voltage drop, resolver disconnection, power status error, clock stopped, overcurrent (soft), speed amp saturation, motor overload, temporary overload, resolver error, speed over, error counter over, parameter setting error, backup error, absolute encoder checksum error, absolute encoder absolute error, absolute encoder over speed, encoder data not transmitted, BCD data error, present value undetermined, PTP data not set |  |  |  |  |  |

Note:

[^4]
## Dimensions

Note: All units are in millimeters unless otherwise indicated.
200-VAC FND-X06H-SRT/-X12H-SRT
100-VAC FND-X06L-SRT/-X12L-SRT


200-VAC FND-X25H-SRT


Mounting Holes


## 200-VAC FND-X50H-SRT



## OmROn

## Peripheral Devices

## Special Flat Cable Allows

## Communication Path Extension

 and T-branching with Ease

Ordering Information
VCTF Cable Products

| Product | Appearance | Model | Specification |
| :--- | :---: | :--- | :--- |
| Terminal-block Terminator |  | SRS1-T | Resistance: $100 \Omega$ |
| T-branch Connector |  | XS2R-D427-5 | Used to branch <br> communications lines and <br> power lines. <br> (Waterproof specifications) |
| Connector Terminator (plug) |  | Waterprof terminating <br> resistance |  |

## Special Flat Cable Products

| Product | Appearance | Model | Specification |
| :--- | :---: | :--- | :--- |
| Branch Connector | SCN1-TH4 | Used with Special Flat Cable. |  |
| Extension Connector |  |  |  |
| Connector Terminator | SCN1-TH4E | Used with Special Flat Cable. |  |
|  |  | SCN1-TH4T |  |
| Special Flat Cable |  | Used with Special Flat Cable. |  |

Note: Branch Connectors and Extension Connectors are sold in blocks of 10 Units.
Four-core VCTF Cable Products

| Product | Appearance | Model | Specification |
| :---: | :---: | :--- | :--- |
| Assembling Connector | XS2C-D4S7 | Communications Connector plug <br> for 4-conductor VCTF cable |  |
|  |  | Communications connector socket <br> for 4-conductor VCTF cable |  |

## Specifications

## - Ratings/Characteristics

| Rated current | 4 A |
| :--- | :--- |
| Contact resistance | $20 \mathrm{~m} \Omega$ max. |
| Insulation resistance | $1,000 \mathrm{M} \Omega$ min. (at 500 VDC$)$ |
| Withstand voltage | $1,000 \mathrm{VAC}$ for 1 min, leakage current: 1 mA max. |
| Cable pulling strength | $50 \mathrm{~N}(5.1 \mathrm{kgf})$ min. |
| Operating temperature | $-20^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |


| Operating temperature | $-20^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ |
| :--- | :--- |

$\square$ Materials

| Housing | PA66 resin (ULL94V-2) <br> Branching and extension: Gray <br> Terminatr: Black |
| :--- | :--- |
| Cover | Phosphor bronze and nickel base, tin plated |
| Contact |  |

## Dimensions

Note: All units are in millimeters unless otherwise indicated.
SCN1-TH4 Branch Connector
SCN1-TH4E Extension Conne


SRS1-T Terminal-block Terminator


Mounting Holes


## Precautions

Refer to the CompoBus/S Operation Manual (W266-E1) before
using the Unit.

## Ordering Information

Note: Abbreviations for standards: U: UL, C: CSA, CE: EC Directive

| Product | Appearance | Model | Specifications | Standards |
| :---: | :---: | :---: | :---: | :---: |
| CPM2C CPU Units with CompoBus/S Master |  | CPM2C-S100C | Incorporates CPM2C CPU Unit and controller functions 6 inputs and 4 outputs (sinking) | $\begin{aligned} & \hline U \\ & \text { U } \\ & \text { CE } \\ & \text { (see } \\ & \text { note) } \end{aligned}$ |
|  |  | CPM2C-S110C | Incorporates CPM2C CPU Unit and controller functions 6 inputs and 4 outputs (sourcing) |  |
| Programmable Slaves |  | CPM2C-S100C-DRT | Incorporates CPM2C CPU Unit and controller functions 6 inputs and 4 outputs (sinking) | $\begin{array}{\|l\|} \hline U \\ \text { U } \\ \text { CE } \\ \text { (see } \\ \text { note) } \end{array}$ |
|  |  | CPM2C-S110C-DRT | Incorporates CPM2C CPU Unit and controller functions 6 inputs and 4 outputs (sourcing) |  |
| Master Control Units | 告 | SRM1-C01-V2 | Stand-alone model with built-in controller functions No RS-232C port, 256 I/O points (128 inputs and 128 outputs) | $\begin{array}{\|l\|} \hline U \\ C \\ \text { CE } \\ \text { (see } \\ \text { note) } \end{array}$ |
|  |  | SRM1-C02-V2 | Stand-alone model with built-in controller functions No RS-232C port, 256 I/O points (128 inputs and 128 outputs) |  |
| Master Units |  | C200HW-SRM21-V1 | For CS1, C200HX/HG/HE (-ZE), and C200HS 128 inputs and 128 outputs (256 points in total) | $\begin{array}{\|l\|} \hline U \\ \text { C } \\ \text { CE } \\ \text { (see } \\ \text { note) } \end{array}$ |
|  |  | CQM1-SRM21-V1 | For CQM1 and CQM1H 64 inputs and 64 outputs (128 points in total) |  |
| SYSMAC Boards with CompoBus/S Master |  | C200PC-ISA03-SRM | For C200HG-CPU43 128 inputs and 128 outputs (256 points in total) | $\begin{aligned} & \text { CE } \\ & \text { (see } \\ & \text { note) } \end{aligned}$ |
|  |  | C200PC-ISA13-SRM | For C200HX-CPU64 128 inputs and 128 outputs (256 points in total) |  |

Note: Long-distance communications mode is not supported.

| Product | Appearance | Model | Specifications | Standards |
| :---: | :---: | :---: | :---: | :---: |
| I/O Link Units |  | CPM2C-SRT21 | For CPM2C <br> 8 inputs and 8 outputs | $\begin{array}{\|l\|} \hline \text { CE } \\ \text { (see } \\ \text { note) } \end{array}$ |
|  |  | CPM1A-SRT21 | For CPM1A/CPM2A 8 inputs and 8 outputs |  |


| Product | Appearance | Model | Specifications | Stan- dards |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \hline \text { Transistor Remote I/O } \\ & \text { Terminals } \end{aligned}$ |  | SRT2-ID04 SRT2-ID04-1 SRT2-OD04 SRT2-OD04-1 | 4 NPN inputs (+ common) 4 PNP inputs (-common) 4 NPN outputs (- common) 4 PNP outputs ( + common) | UCCE(seenote) |
|  |  | SRT2-ID08 SRT2-ID08-1 SRT2-OD08 SRT2-OD08-1 | 8 NPN inputs (+ common) 8 PNP inputs ( - common) 8 NPN outputs (- common) 8 PNP outputs (+ common) |  |
|  |  | SRT2-ID16 SRT2-ID16-1 SRT2-OD16 SRT2-OD16-1 | 16 NPN inputs (+ common) 16 PNP inputs (- common) 16 NPN outputs (- common) 16 PNP outputs ( + common) |  |
| Transistor Remote I/O Terminals with 3-tier Terminal Block |  | SRT2-ID16T <br> SRT2-ID16T-1 <br> SRT2-MD16T <br> SRT2-MD16T-1 <br> SRT2-OD16T <br> SRT2-OD16T-1 | 16 NPN inputs (+ common) 16 PNP inputs (- common) 16 NPN I/O points (inputs: + common; outputs: - common) 16 PNP I/O points (inputs: - common; outputs: + common) 16 NPN outputs (- common) 16 PNP outputs (+ common) | $\begin{array}{\|l\|} \hline U \\ \text { C } \\ \text { CE } \\ \text { (see } \\ \text { note) } \end{array}$ |
| $\begin{aligned} & \hline \text { Relay-mounted Remote I/O } \\ & \text { Terminals } \end{aligned}$ |  | SRT2-ROC08 | 8 relay outputs | $\begin{aligned} & \text { U } \\ & \text { CE } \\ & \text { CE } \\ & \text { (soe } \\ & \text { note) } \end{aligned}$ |
|  |  | SRT2-ROC16 | 16 relay outputs |  |
|  |  | SRT2-ROF08 | 8 power MOS FET relay outputs |  |
|  |  | SRT2-ROF16 | 16 power MOS FET relay outputs |  |
| Transistor Remote I/O Terminals with Connectors |  | SRT2-ID32ML SRT2-ID32ML-1 | 32 NPN transistor inputs (+ common) 32 PN transistor inputs (- comman) | $\begin{aligned} & \text { CE } \\ & \text { (see } \\ & \text { note } \end{aligned}$ |
|  |  | SRT2-OD32ML SRT2-OD32ML-1 SRT2-MD32ML SRT2-MD32ML-1 | 32 NPN transistor outputs <br> (- common) <br> 32 PNP transistor outputs <br> (+ common) <br> 32 NPN transistor I/O points (inputs: <br> + common; outputs: - common) <br> 32 PNP transistor I/O points (inputs: <br> - common; outputs: + common) |  |
|  |  | SRT2-VID08S SRT2-VID08S-1 SRT2-VOD08S SRT2-VOD08S-1 | ```8 NPN transistor inputs (+ common) 8 \text { PNP transistor inputs (- common)} 8NPN transistor outputs (- common) 8 PNP transistor outputs (+ common)``` | $\begin{array}{\|l\|} \hline \mathrm{U} \\ \mathrm{C} \\ \text { CE } \\ \text { (see } \\ \text { note) } \\ \hline \end{array}$ |
|  | 者 | SRT2-VID16ML SRT2-VID16ML-1 SRT2-VOD16ML SRT2-VOD16ML-1 | 16 NPN transistor inputs (+ common) <br> 16 PNP transistor inputs (- common) <br> 16 NPN transistor outputs (- common) <br> 16 PNP transistor outputs (+ common) |  |
|  |  | $\begin{aligned} & \hline \text { SRT2-ATT01 } \\ & \text { SRT2-ATTO2 } \\ & \hline \end{aligned}$ | Mounting hook A Mounting hook B |  |


| Product |  | Appearance | Model | Specifications | Stan- |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Waterproof Transistor Terminals |  |  | SRT2-ID04CL SRT2-ID04CL-1 SRT2-OD04CL SRT2-OD04CL-1 | ```4 NPN transistor inputs (+ common) 4 PNP transistor inputs (- common) 4 NPN transistor outputs (- common) 4 PNP transistor outputs (+ common)``` | $\begin{array}{\|l\|} \hline \text { CE } \\ \text { (see } \\ \text { note) } \end{array}$ |
|  |  |  | SRT2-ID08CL SRT2-ID08CL-1 SRT2-OD08CL SRT2-OD08CL-1 | ```8 NPN transistor inputs (+ common) 8 PNP transistor inputs (- common) 8 NPN transistor outputs (- common) 8 PNP transistor outputs (+ common)``` |  |
| Sensor Terminals |  | $6$ | SRT2-ID08S SRT2-ND08S SRT2-OD08S | Sensor Terminals 8 inputs (NPN) 4 automatic teaching points (NPN) 8 outputs | --- |
| CompoBus/S Sensor Amplifier Terminals |  |  | SRT1-TID04S SRT1-TKD04S | 4 communications points 4 communications points (to connect to the E3X-NM16) | --- |
|  |  | SRT1-XID04S SRT1-XKD04S | $\begin{aligned} & 4 \text { expansion points } \\ & 4 \text { expansion points (to connect to } \\ & \text { the EX-NM16) } \end{aligned}$ |  |
| Connection Units (see note) | Photoelectric Sensors |  |  | E3X-NT16 <br> E3X-NT26 <br> E3X-DA16 | 1-channel general-purpose teaching 1-channel multi-functional, general-purpose teaching high-precision bar-display teaching 1-channel digital model | $\begin{aligned} & \text { U } \\ & \text { C } \\ & \text { CE } \\ & \text { (see } \\ & \text { note) } \end{aligned}$ |
|  |  |  | E3X-NM16 | 4-channel multi-functional, general-purpose teaching |  |  |
|  | Proximity Sensors |  | $\begin{aligned} & \text { E2CY-T16 } \\ & \text { E2C-T16 } \end{aligned}$ | Aluminum detection Compact model with teaching function | $\begin{aligned} & \mathrm{U} \\ & \mathrm{C} \end{aligned}$ |  |
|  | Terminal Block Unit |  | E39-JID01 | One input point | --- |  |
| Analog Input Terminal |  |  | SRT2-AD04 | 1 to 4 inputs (set with DIP switch) | $\begin{array}{\|l\|} \hline U \\ C \\ \text { CE } \\ \text { (see } \\ \text { note ) } \\ \hline \end{array}$ |  |
| Analog Output Terminal |  |  | SRT2-DA02 | 1 or 2 outputs (set with DIP switch) |  |  |
| Remote I/O Modules |  |  | SRT2-ID16P SRT2-OD16P | 16 NPN inputs (+ common) 16 NPN outputs (- common) | --- |  |
| Position Drive CompoBus/S | rs for |  | FND-X06H-SRT FND-X12H-SRT FND-X25H-SRT FND-X50H-SRT FND-X06L-SRT FND-X12L-SRT | 6 A at 200-VAC input 12 A at $200-\mathrm{VAC}$ input 25 A at $200-\mathrm{VAC}$ input 50 A at $200-\mathrm{VAC}$ input 6 A at $100-\mathrm{VAC}$ input 12 A at 100 -VAC input | $\begin{aligned} & \text { UCE } \\ & \text { (see } \\ & \text { (soe) } \\ & \text { cote } \end{aligned}$ |  |

Note: The Position Driver cannot be used in long-distance communications mode.

## Peripheral Devices

| Product | Appearance | Model | Specifications | Stan- |
| :---: | :---: | :---: | :---: | :---: |
| Terminal-block Terminator |  | SRS1-T | $100 \Omega$ | --- |
| T-branch Connector | (3) | XS2R-D427-5 | Waterproof |  |
| Connector Terminator (plug) |  | SRS2-1 | Waterproof terminator |  |

## Special Flat Cable Products

| Product | Appearance | Model | Specifications | Standards |
| :---: | :---: | :---: | :---: | :---: |
| Branch Connector | N. M | SCN1-TH4 | Connector for Special Flat Cable | --- |
| Extension Connector |  | SCN1-TH4E |  |  |
| Connector Terminator |  | SCN1-TH4T |  |  |
| Special Flat Cable |  | SCA1-4F10 | 100 m |  |

Four-conductor VCTF Cable Products

| Product | Appearance | Model | Specifications | Stan- <br> dards |
| :---: | :---: | :--- | :--- | :--- |
| Assembling Connector | XS2C-D4S7 | Connector plug for 4-conductor <br> VCTF cable communications | -- |  |
|  |  | XS2G-D4S7 | Connector socket for 4-conductor <br> VCTF cable communications |  |

Note: Information on EC Directives
Individual OMRON products that comply with EC Directives conform to the common emission standards of EMC Directives. Howeve, the emission characteristics of these products installed on customers' equipment may vary depending on the configuration, wiring layout, and other conditions of the control panel used. For this reason, customers are requested to check whether the emission chara teristics of the entire machine or equipment comply with the EMC Directives.

## X-ON Electronics

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[^0]:    ## Output HOLD/CLEAR Setting for Communications Errors (SRT2-OD/MD32ML (-1)) The setting of SW4 of the DIP switch determines whether outp

[^1]:    Note: For details about connecting the SRT2-VID or SRT2-VOD to the Master Unit, refer to page 25.

[^2]:    Assembling-type Connector Plug

[^3]:    Note: The above current consumption is the value with all point turned ON excluding the current consumption of the external load

[^4]:    When using the
    motors ( $-\mathrm{HA},-\mathrm{TA},-\mathrm{VA},-\mathrm{XA},-\mathrm{H}$, or -V modelis).
    2. For the monitor output, the monitor items and voltage polarity can be set by parameter UP-25 (monitor output selection)

