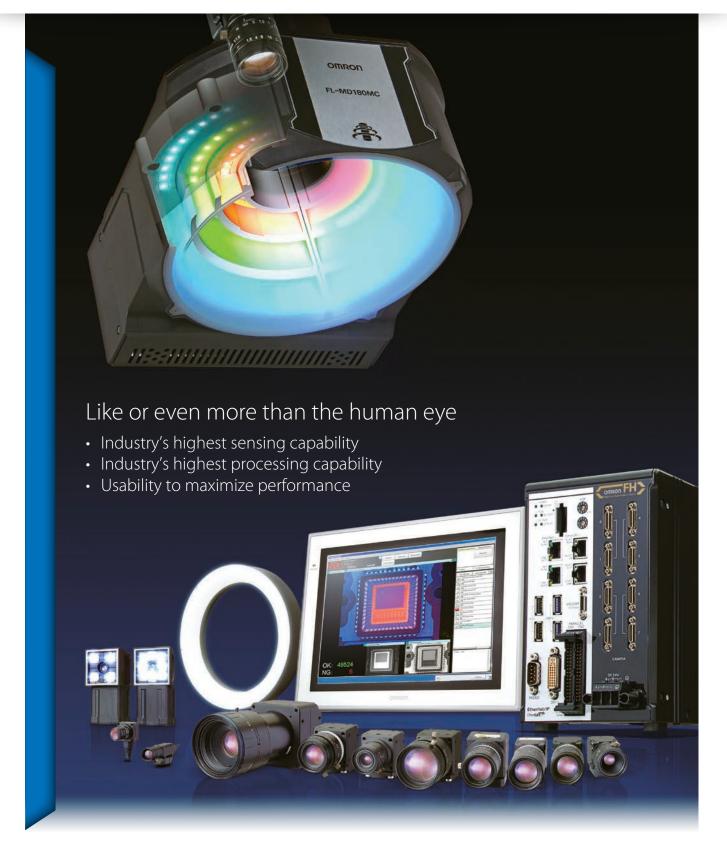


# Vision System FH Series





# High-speed, high-accuracy inspection and - like or even more than the human eye

Many cameras are installed in almost all production processes to automate quality inspections and ensure security and safety. This means that the amount of image information is increasing. Moreover, changes in products require higher levels of performance for vision systems used for automation.

In these circumstances, Omron further developed our FH Series to meet rapidly growing automation needs and higher performance requirements.

We help you solve your inspection and measurement issues through integration of high-speed, high-resolution compact cameras jointly developed with Omron Sentech Co., Ltd. and our unique algorithms.

Packed with technologies, this vision system will enable more customers to easily employ image processing.

We offer products which bring automation to manufacturing sites, contributing to manufacturing around the world.



.......

# measurement

# Automation of external inspection



New lights and new filtering technologies make difficult-to-see defects visible

# MDMC Light Scratches and dirt on surface **Broken** wires .... ..... ------------

## Wide field of view for positioning



Up to 80 Mpix cameras provide a wide field of view and high resolution to capture objects with size variations or complex shapes



# Storing all inspection images



Large-volume image data for complex applications and quality control can be processed at extremely high speeds



Industry's first\*1 MDMC\*2 Light

# Clearly shows defects by flexibly illumination colors and angles

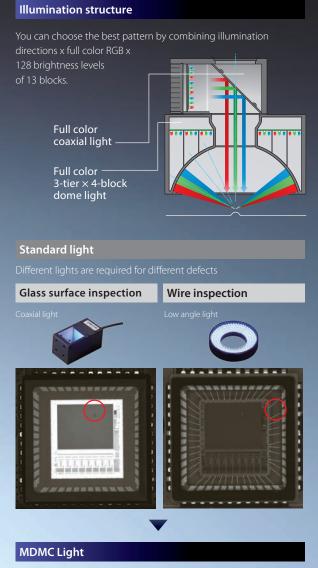
This light can be adjusted to defects by freely combining the illumination directions, colors, and light intensities. Even if new objects or inspection items are added after installation, there is no need to add or change the light—just change the illumination pattern. The lighting patterns can be registered as setting data, facilitating duplicating production





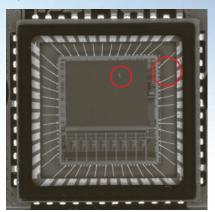
# 

# changing



One light clearly shows both broken wires and dirt on elements

Inspection for broken wires and dirt on elements



## **Photometric Stereo Light**

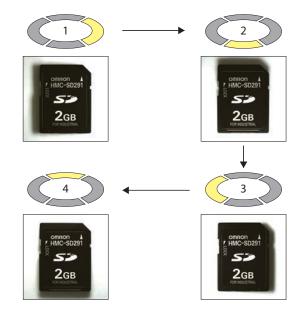
#### Shows defects accurately

The new FH Photometric Stereo Light can be used with standard or high-resolution cameras up to 20.4 Mpix. To detect dents and surface damages with high accuracy choose a 5, 12 or 20.4 Mpix high-speed camera.



#### **Principle explanation**

Four lights are lit in turn, and variations in brightness are analyzed. Printed characters with little variation in brightness even under different illumination directions are extracted as texture, and a dent with huge variation in brightness is extracted as a shape.



# Industry's highest\* Speed and Resolution

Carlos and a subscription

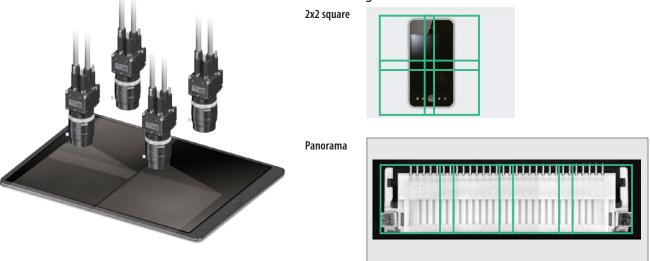
# Industry's highest\* image resolution by new high resolution cameras

# Expand the field of view by combining images at high speeds

#### Panorama shooting with multiple cameras

and a full of the full of the

Our unique panorama image processing enables images shot by up to four cameras to be combined into one image. An overall image of a wide or large object can be captured, which is impossible using a conventional method that simultaneously transfers images from multiple cameras.



<Combining methods>

\* Based on Omron investigation in June 2018.

# of 80 Mpix

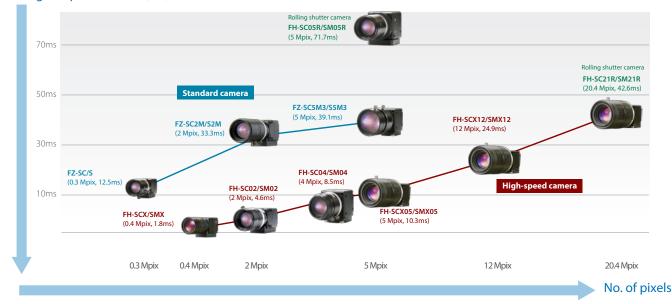
# Ultra-high-speed sensing technology in a compact design

High-resolution cameras capture a wide field of view, which can cause image transfer bottlenecks that increase production cycle times. We use a new CMOS image element and dual transfer technology to capture high-resolution images and transfer images at high speeds.

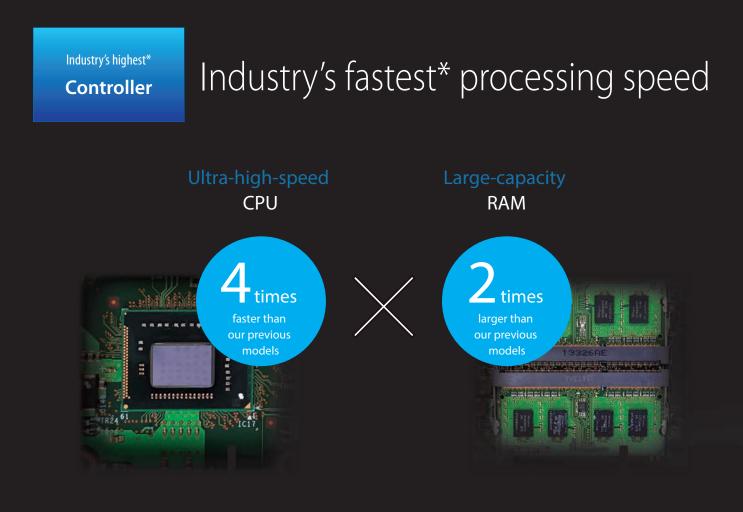
This facilitates applications that previously required multiple cameras or a mechanism to move a camera.

# A wide variety of cameras, from 0.3 to 20.4 Mpix

You can select the best combination of camera and lens for your application.



#### Image acquisition time (ms)



# Large capacity for image processing

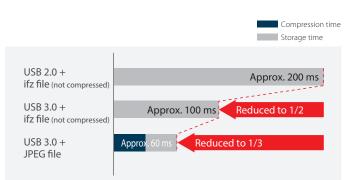
As the use of high-resolution cameras or multiple images for highquality inspections or wide-field inspections is increasing, vision sensors that can handle increasing data volumes are required. The FH-5050 High-speed, Large-capacity Controller has two times the RAM capacity of our previous models, enabling up to four 20.4 Mpix cameras to be connected. In addition, its CPU processes captured images 4 times faster than our previous models.

# High-speed image storage

#### [USB 3.0 ports] [High-speed image compression]

Image data is so large that conventional controllers could not store all images due to limited storage time and capacity. The new highspeed, large-capacity controller has USB 3.0 ports and algorithms improved to compress image data at high speed, enabling all images to be stored to meet increasing needs in quality control.

Controller	Camera		
	12 Mpix x 4	20.4 Mpix x 4	
FH-1050 Series FH-3050 Series	$\checkmark$	-	
FH-2050 Series FH-5050 Series	$\checkmark$	~	



The times in the figure above are provided for reference only and their accuracy cannot be guaranteed.

- They are measured under the following conditions:
- FH-5050 Controller
- 5 Mpix monochrome images
- Size of converted JPEG file: 0.6 MB

\* Based on Omron investigation in June 2018.



# 



Intel® Core™i7 processor

Machine control network Cycle: 125  $\mu$ S



Data output High-speed interface **USB 3.0** 

High-speed, Large-capacity Controller FH-5050 Series

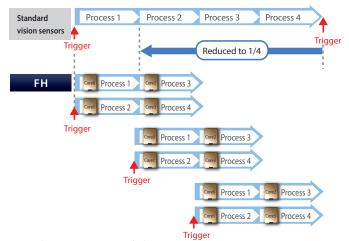
# High-speed measurement

The improved algorithms of processing items significantly increase processing speed.



# Parallel processing of multiple lines

#### Trigger interval reduced by up to 75%\*



#### Process multiple lines without waiting



\* Compared to processing using standard vision sensors.

# GUI for designers

# Intuitive design interface reduces complexity

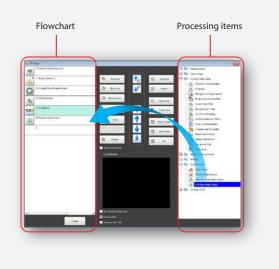


# Build measurement process with flowchart programming

#### Inspection and measurement flow design

Just drag and drop pre-installed processing items to build a measurement process.

The processing order can be defined, facilitating conditional branching.

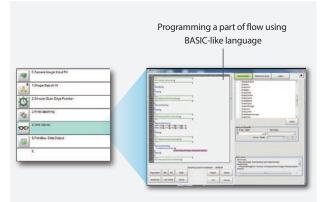


#### Unit Macro

Macros let you easily achieve flow control that normally requires complex programming from the user interface. The BASIC-like programming language facilitates the macro creation.

#### Example:

Some of the often-used processing (e.g., scene change + measurement start, data read + save) can be combined into one unit. This unit can be reused for other controllers.



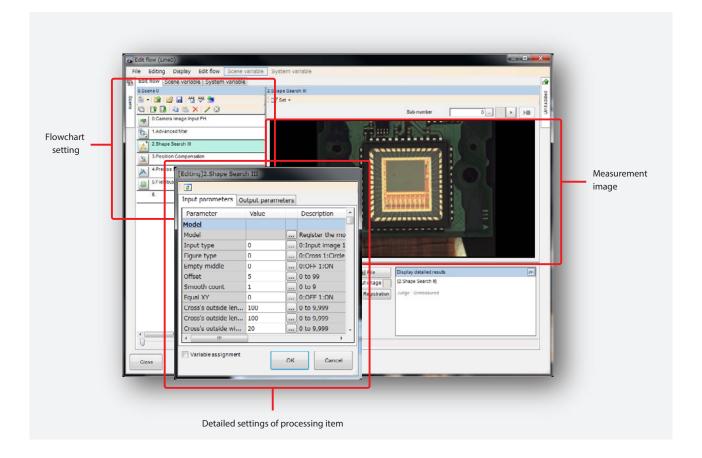
# 

# Simple setting with menus

#### Total Design Management Editor

The FH Series has a new design interface that allows you to design complex measurement processes while managing variables.

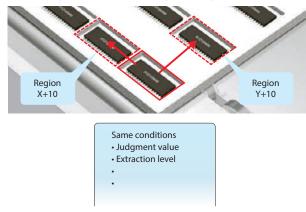
This simple GUI manages complicated branching processes and data sharing across measurement scenes and eliminates the need to switch screens.



#### Example 1: Repeat same measurement while shifting region

Previously, to inspect aligned parts or divided regions, the same processing items needed to be set many times, which made the inspection flowchart long. The FH Series allows you to combine variables and calculation to refer the same processing item repeatedly while shifting the measurement region.

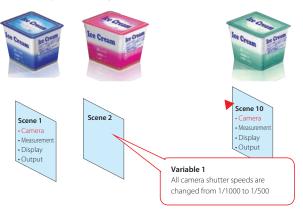




#### Example 2: Set a common value for scenes

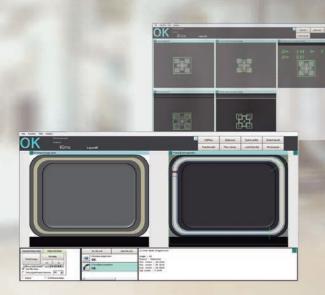
A variable can be used when the same parameter is used for two or more scenes or processing items, such as camera shutter speed and reference point for positioning. This simplifies the inspection flowchart, reducing setting errors and preventing you from forgetting to change settings.





# GUI for operators

# Operation interface optimized for use at production sites

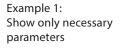


Drag & drop pre-installed interface to easily customize to your needs.

# Prevent incorrect operation at production site

#### Show only parameters you change everyday

The processing item setting window includes parameters for initial setting and for daily adjustments. To prevent incorrect operation, you can customize the adjustment window to show only parameters that are required for your daily operation.





Example 2: Show a wizard



Just select objects from the list of dialog boxes and Easy setting place them. No programming required.

in any desired position

when the button is pressed can be set



### Show only menus you need

Hide unnecessary windows to make operation easy and avoid problems due to incorrect operations.

#### Customized operation interface



Enlarge the result to see it more easily

The display size can be changed by dragging.

#### Add short-cut buttons to daily functions

Buttons can be added easily from the menu.

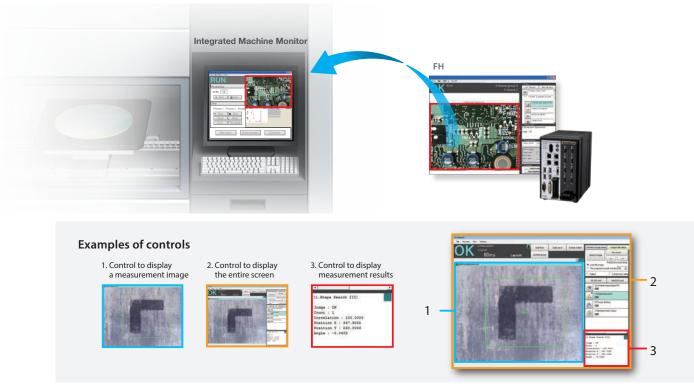


Scene switch	Screen capture	Transfer data
Operation log	Security settings	NG analyzed
User data tool	Communication Command Macro	Data save

# More customization for machine monitors

#### Supports .NET controls for integration into user applications

Microsoft.Net controls are supported to integrate the FH interfaces into a PC-based HMI. You can display FH screens and measurement results by dragging the controls to your HMI software.



Note. Ask your Omron representative about obtaining controls.

#### Application Producer development environment to develop original interfaces

The Application Producer (FH-AP1) provides a development environment that lets you customize software pre-installed in the FH Controller. Original interfaces can be created and used with the FH Controller.

#### Example: Show your desired logo on startup screen



Development environment Application Producer

Change configuration files for the FH Controller and create installation files



Install the created files on the FH Controller



The customized interface can be used

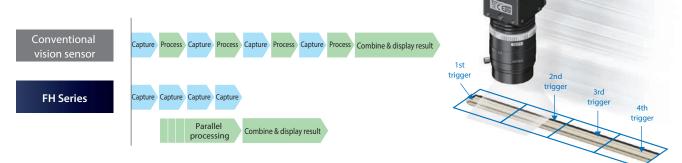
# Processing item library

# Software for high-speed, high-precision inspections and measurements

Image input **8** processing items

# Multi-trigger Imaging combines measurements fully using multi-core processor

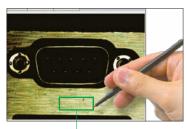
When multiple images are used for measurement, the conventional vision sensor repeats processing after image capture until all images are processed because only one trigger can be input in one flow. In contrast, the Multi-trigger Imaging function to input multiple shutter triggers in one flow allows the FH Series to capture images and process them in parallel, leveraging the speed of the multi-core processor.





# Easy to create HDR images

The Camera Image Input HDR processing item can create optimized HDR images under variable ambient conditions. Normally, to create an HDR image, you must set the imaging conditions for each shooting. However with the FH Series, once you specify the optimum area to capture on the image, the vision system automatically adjusts the shutter speed while capturing images and combines the images.



Optimized for the bright part

#### Image optimized for the specified area



Optimized for the entire field of view



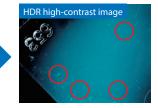
Optimized for the dark part

#### **High-Contrast Mode**

Multiple images are combined together and then averaged to reduce their noise component, after which the images are enlarged. This way, only the contrast of the area of interest and its background can be increased.



Low contrast makes the surface appear uniform.



Many scratches and soiled areas can be found.



# **OMRON** [ 15

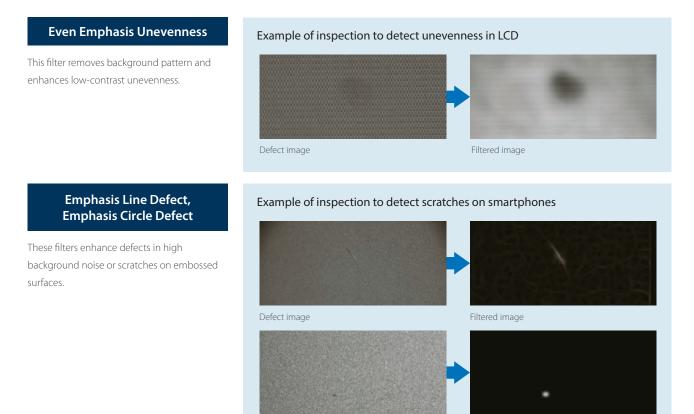
## Filtering



30 filters in Advanced Filter

#### Filters to detect low-contrast defects

The FH Series provides various filters to enhance linear defects in noise and low-contrast defects which cannot be detected by conventional image processing. High-quality external inspection can be achieved by combining filters.



#### Filters widely used for image processing

Guided Filter, LoG (Laplacian of Gaussian) Filter, and other new filters that are widely used for image processing are added.

Defect image

#### **Guided Filter**

This filter preserves edges while smoothing the background. Even if an image contains significant noise, the

filtered image can be registered as a model for Fine Matching.



Noise image



Filtered image

Filtered image

# Inspection & measurement

processing items

34

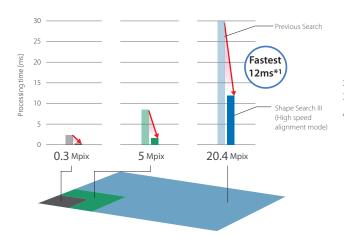


# Object detection algorithm Shape Search III

The Shape Search III provides both speed and robustness that are required for high-accuracy positioning. The processing speed of the FH-5050 Controller was further increased.

#### Fastest searching time of 12 ms\*1 with 20.4 Mpix camera

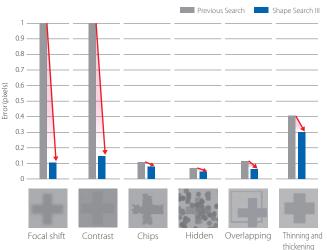
A 20.4 Mpix camera can search a positioning mark in as fast as 12 ms \*1 and a 5 Mpix camera, which is mostly used for alignment applications, in as fast as 2 ms.



\*1. The value measured under our specified conditions is provided for reference.

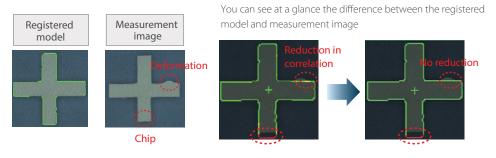
#### Ultra-high-accuracy, robust positioning

Stable position detection required for ultra-high-accuracy, robust positioning is possible even under the adverse conditions, such as changes of environments and materials, which occur far too often in actual measurement applications.



#### Visualization of comparisons enables easy setting of high-precision searching Patented/Patent Pending \*2

Advanced searching is accompanied by many parameters that must be tuned to match the application. However, it is difficult for the person making the settings to see the internal process. Normally, a lot of time and effort is required to maximize tool performance. But with Shape Search III, you can visualize comparisons between the model data and a part of the measurement object to easily see when comparisons are not optimally matched. Visualization of the comparison level allows for parameters to be adjusted to quickly obtain the best performance.



You can adjust a parameter called the Acceptable Distortion Level to enable measurements without reducing the correlation even if there is distortion. You can easily adjust this parameter while monitoring the comparison.

\*2. Patent status as of June 2018

US:US9286669, Europe:Pending, China:ZL201410138793.3, Japan:JP6197340

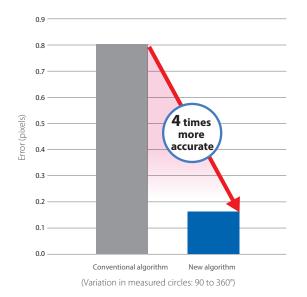
# **OMRON** [ 17

# 🔅 Circular Scan Edge Position accurately detects a circle

The new noise removal algorithm significantly increased robustness. The center and radius of a circle can be obtained accurately from a part of the circle.

#### High accuracy

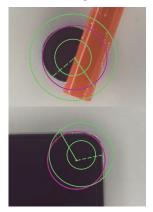
The new algorithm achieves four times higher accuracy than our previous models.



#### Robustness

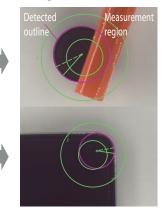
The new noise removal algorithm accurately detects a whole circle from a part of the circle.

Conventional algorithm



The circle is not on the outline of the object

New algorithm



The outline of the object is detected accurately

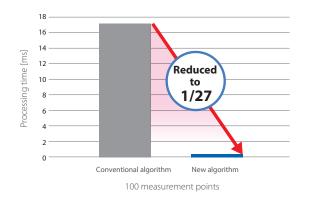
-----

# Scan Edge Position increases speed and stability

The algorithm has been completely redeveloped to drastically increase processing speed and noise removal capability.

#### High speed

Processing time is reduced to 1/27 of our previous models. Even when measurement points increase, the processing time is within 10 ms.

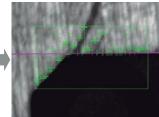


#### Stability

The new noise removal algorithm accurately estimates lines even when the edges are unclear due to variations in objects or disturbance.

#### Conventional algorithm

#### New algorithm



#### Powerful 2D code reading

Print Quality Grading Function • ISO/IEC 15415 • ISO/IEC TR29158

The dedicated algorithm for stable 2D code reading under adverse conditions is implemented. Data based on the print quality specifications can be output, which contributes to stable printing.

#### Changing ambient brightness After processing/washing Chips due to reflection Waterdrops and dirt Scratched damage Low contrast Poor printing quality in high-speed line Poorly printed on coarse surface Variations in start positions Uneven line spacing Molding variations of forged object ..... .:: \_\_\_\_ .... .......... Improved recognition rate and increased speed Previous 2D Code 2D Code II Recognition rate 2 times \* High speed 3 times \* 100 60 50 80 Recognition rate [%] Processing time [ms] 40 60 30 40 20 20 10 0 0

and dirt spacing \*. The average value measured under our specified conditions is provided for reference.

Waterdrops

Reflection

Low contrast

Uneven line

. .

Molding

variations

Reflection

Low contrast

and dirt

Waterdrops

For other processing items, see

Uneven line

spacing

.....



Molding

variations

# **DCE** Stable reading of difficult-to-read characters (OCR)

Printed characters can be too close to each other, and characters can be printed on curved surfaces. Even in these cases, stable reading is possible.

Touching characters

Curved character strings



#### Easy installation with built-in dictionary

Many previous character reading methods required dictionary setup before usage, which was a tedious step. The built-in dictionary developed through our long and rich experiences on FA sites includes a variety of fonts and possible character variations, eliminating the need of dictionary setup. You can also add non-conventional characters when special fonts are read.



For other processing items, see

Index selection from list



**ABS** Character Inspection for special fonts

Japanese characters

Character Inspection recognizes characters based on pattern search using the dictionary set up by the user. This search-based reading enables special fonts and non-alphanumeric characters to be inspected. Automatically extracting a model and selecting an index from the list help you easily set up your dictionary.

#### Inspection of special fonts

Special fonts





#### Easy dictionary setup

Automatic model extraction



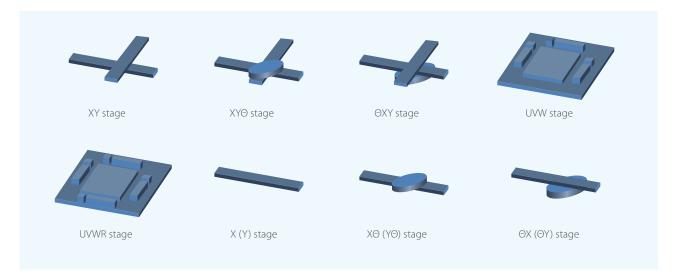


# Inspection & measurement 39 support items



# Stage Data for single axis + $\theta$ axis stage alignment

The single axis +  $\theta$  axis stages which are popular today as well as UVW stages can be used. The use of the same axis for both handling and positioning simplifies machine configuration.



# Manual Position Setting avoids stopping a machine

When an object cannot be detected, you can set the mark positions manually. The FH Series outputs the travel distance of the external device by referring the manually set values and measured coordinates. Manual Position Setting allows the FH Series to continue positioning without stopping the production line.



# **OMRON** 21

# Connecting robots

The dialog boxes for the FH Series and programs for various vendors' robots greatly reduce set-up time for robot applications.

**Robot applications** 









Pick

Offset compensation

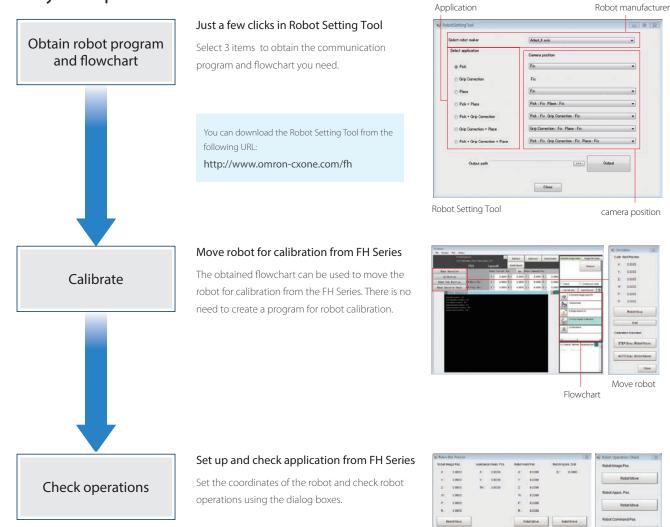
Place

Combination

## Setting FH Vision System **Robot Setting Tool**

Verified robot communication programs and flowcharts required for robot applications are provided. You don't need to design communications and create a flowchart to set up a robot application.

# Easy 3-step robot connection



Set the coordinates of the robot

Check robot operations

Flexible machine control

# Seamless connection with Omron

# EtherCAT<sup>®</sup> for high-speed data transfer, from position detection to starting axis motion

You can use EtherCAT to connect NJ/NX Machine Automation Controllers and 1S/G5 AC Servo System to increase the control speed of everyday communications protocols from position detection to starting axis motion.

#### Data communications cycle: 125 µs

#### Communications cycle



#### Time from trigger input to producing measurement results



Note: The times given above are typical times. They depend on parameter settings

# Integrated development





#### The Integrated Development Environment can be used to configure

and simulate the FH Series.

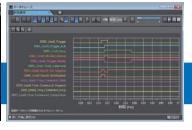
# Verification

#### Advanced system debugging

#### **3D Simulation**

Machine movement can be simulated based on measurement results of vision systems

#### Data tracing



Inputs and outputs of vision systems can be traced as a time series.

Integrated Development Environment Automation Software Sysmac Studio

# products makes production lines more efficient



# Select the best combination for

Software assets can be shared between controllers. This allows you to install devices with the capabilities you need, anywhere

#### Cameras

Choose the right camera to suit your required number of pixels. Easy-to-use cameras with built-in light are also available.

No. of pixels	High-speed camera	Standard camera	Rolling shutter camera	Camera with built-in light
20.4 Mpix*	-	-	FH-S□21R	-
12 Mpix	FH-S□X12	-		-
5 Mpix	FH-S□X05	FZ-S□5M3	FH-S□05R	-
2 Mpix	FH-S□02	FZ-S□2M		-
0.4 Mpix/ 0.3 Mpix	FH-S□X	FZ-S□	-	FZ-SQDDDD

\* 20.4 Mpix Cameras can be used with the FH-5050/2050-series

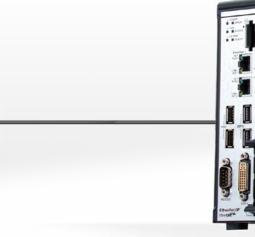
High-speed, Large-capacity Controllers.

Versatile selection

#### Controllers

Select a controller based on the required processing speed and network.

	Series	CPU
High-speed,	FH-5050 Series	Intel <sup>®</sup> Core™ i7 processor 4 cores
Large-capacity Controller	FH-2050 Series	Intel® Celeron® processor 2 cores
Standard Controller	FH-3050 Series	Intel <sup>®</sup> Core <sup>™</sup> i7 processor 4 cores
Standard Controller	FH-1050 Series	Intel® Celeron® processor 2 cores
Lite Controller	FH-L550 Series	Intel® Atom® processor 2 cores





Omron offers a complete line-up of lights required for image processing. The use of the camera-mount lighting controller allows you to control lighting conditions from the FH Controller, making system configuration simple.

#### External lighting controller

Description	LED	High-brightness LED
Camera-mount Lighting Controller	FLV-TCC	FL-TCC
Bar Light	FLV-BR	FL-BR
Direct Ring Light	FLV-DR	FL-DR
Low Angle Ring Light	FLV-DL	-
Coaxial Light	FLV-CL	-
Shadowless Light	FLV-FR/FP/FS/FQ	
Spot Light	FLV-EP	-
Direct Back/Edge Type Light	FLV-DB/FB	-
Dome Light	FLV-DD	-
Photometric Stereo Light*	-	FL-PS

\* The FL-TCC Camera-mount Lighting Controller cannot be used. Use the FLV-TCC1PS Lighting Controller for Photometric Stereo Light.

#### Built-in lighting controller

Description	Model
MDMC Light	FLD-MD

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

#### Camera cables

The cable line-up includes bend-resistant cables and right-angle cables. Use the FZ-VSJ Cable Extension Unit for cable extensions.

Description	Model
Camera Cable	FZ-VS
Right-angle Camera Cable	FZ-VSL
Bend-resistant Camera Cable	FZ-VSB3 □□M
Bend-resistant Right-angle Camera Cable	FZ-VSLB3
Cable Extension Unit	FZ-VSJ

# your application

you need them.

Performance	Memory	No. of connectable cameras	Fieldbus
****	RAM 8 GB, ROM 32 GB	8 max.	PROFINET, EtherNet/IP™, EtherCAT
***	RAM 8 GB, ROM 32 GB	8 max.	PROFINET, EtherNet/IP™, EtherCAT
****	RAM 3 GB, ROM 4 GB	8 max.	PROFINET, EtherNet/IP™, EtherCAT
**	RAM 3 GB, ROM 4 GB	8 max.	PROFINET, EtherNet/IP™, EtherCAT
*	RAM 3 GB, ROM 4 GB	4 max.	PROFINET, EtherNet/IP™

 $\star$ : The more starts, the higher the performance.

#### Application producer

This development environment enables you to customize FH functions. It includes sample codes and wizards that will help you develop your own interfaces and processing items.

Description	Model
DVD for installation	FH-AP1
Software license	FH-AP1L





#### Touch panel monitor

The touch panel monitor is optimized for the operation of the FH Series.

Description	Model
Touch Panel Monitor 12.1 inches	FH-MT12
DVI-Analog Conversion Cable for Touch Panel Monitor	FH-VMDA
USB Cable for Touch Panel Monitor	FH-VUAB

\* RS-232C cables for long-distance connections are also available. Refer to Ordering Information for details.

The development environment for the Sysmac platform allows you to configure and simulate the FH Series on your PC.



Description	Model
DVD for installation	SYSMAC-SE200D
Software license (Vision Edition)	SYSMAC-VE001L

# Vision System FH-Series

## High-speed, high-accuracy inspection and measurement - like or even more than the human eye

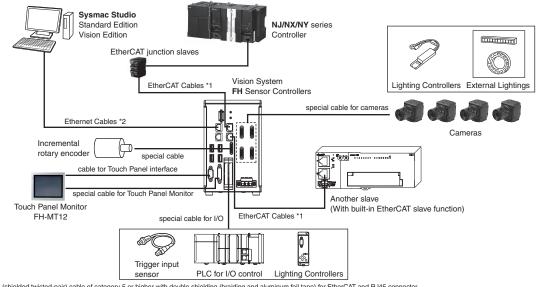
- Industry's highest sensing capability \*
- Industry's highest processing capability \*
- Usability to maximize performance
- \* Based on Omron investigation in June 2018.



# System configuration

#### EtherCAT connections for FH series

Example of the FH Sensor Controllers (4-camera type)



\*1. To use STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT and RJ45 connector. \*2. To use STP (shielded twisted-pair) cable of category 5 or higher for Ethernet and RJ45 connector.

# **Ordering Information**

### FH Series Sensor Controllers

	Item	CPU	No. of cameras	Output	Model
			2	NPN/PNP	FH-5050
		Intel <sup>®</sup> Core <sup>™</sup> i7 processor 4 cores	4	NPN/PNP	FH-5050-10
	High-speed, Large-capacity		8	NPN/PNP	FH-5050-20
	Controller	Intel® Celeron® processor 2 cores	2	NPN/PNP	FH-2050
Contents			4	NPN/PNP	FH-2050-10
			8	NPN/PNP	FH-2050-20
			2	NPN/PNP	FH-3050
		Intel <sup>®</sup> Core <sup>™</sup> i7 processor 4 cores	4	NPN/PNP	FH-3050-10
			8	NPN/PNP	FH-3050-20
	Standard Controller		2	NPN/PNP	FH-1050
		Intel® Celeron® processor 2 cores	4	NPN/PNP	FH-1050-10
			8	NPN/PNP	FH-1050-20

26

Item	CPU	No. of cameras	Output	Model
		2	NPN/PNP	FH-L550
Box-type controllers	Intel <sup>®</sup> Atom <sup>®</sup> processor 2 cores	4	NPN/PNP	FH-L550-10

#### **Cameras**

	ltem	Lens mount	Descriptions	Color / Monochrome	Image Acquisition Time *1	Model
	Digital CMOS Cameras	0 manut	20.4 million pixels	Color	10.0	FH-SC21R
	(Lens required)	C mount	(Supported controller: FH-5050(-□)/2050(-□) Series) *2	Monochrome	42.6 ms *3	FH-SM21R
				Color	0.4.0 ±0	FH-SCX12
			12 million pixels *2	Monochrome	24.9 ms *3	FH-SMX12
	High-speed Digital		5 million pixels	Color	10.3 ms *3	FH-SCX05
	CMOS Cameras	C mount	5 million pixels	Monochrome	10.31115 3	FH-SMX05
pre la	(Lens required)		400.000 pixels	Color	1.9ms	FH-SCX
O Marine			400,000 pixels	Monochrome	1.9015	FH-SMX
	High-speed Digital	N40 mount	40 million minute to	Color	05 7	FH-SC12
Gjiz.	CMOS Cameras (Lens required)	M42 mount	12 million pixels *2	Monochrome	25.7 ms *3	FH-SM12
			A 1111 1 1	Color	0.5 +0	FH-SC04
			4 million pixels	Monochrome	8.5 ms *3	FH-SM04
S.	High-speed Digital			Color	1 a ta	FH-SC02
	CMOS Cameras (Lens required)	C mount	2 million pixels	Monochrome	4.6 ms *3	FH-SM02
	(Lens required)			Color		FH-SC
021			300,000 pixels	Monochrome	3.3 ms	FH-SM
	Digital CMOS Cameras (Lens required)	C mount	5 million pixels	Color		FH-SC05R
				Monochrome	71.7ms	FH-SM05R
				Color	- 38.2 ms	FZ-SC5M3
CHI				Monochrome		FZ-S5M3
			5 million pixels	Monochrome	rome 62.5 ms F2	
OT B			0 million minale	Color		FZ-SC2M
	Digital CCD Cameras (Lens required)	C mount	2 million pixels	Monochrome	33.3 ms	FZ-S2M
	(Lens required)			Color	10.5	FZ-SC
			300,000 pixels	Monochrome	12.5 ms	FZ-S
	High-speed Digital			Color	10	FZ-SHC
	CCD Cameras (Lens required)	C mount	300,000 pixels	Monochrome	4.9 ms	FZ-SH
			200,000 pixel flat time	Color	10 E ma	FZ-SFC
	Small Digital	Lenses for small	300,000-pixel flat type	Monochrome	12.5 ms	FZ-SF
	- CCD Cameras (Lens required)	camera required	000.000 sizel s	Color	10.5	FZ-SPC
			300,000-pixel pen type	Monochrome	12.5 ms	FZ-SP
-			Narrow view	Color		FZ-SQ010F
Ì	Intelligent - Compact Digital CMOS Camera	Built-in lens	Standard view	Color	16.7 ms	FZ-SQ050F
C			Wide View (long-distance)	Color	10.7 110	FZ-SQ100F
			Wide View (short-distance)	Color		FZ-SQ100N

\*1 The image acquisition time does not include the image conversion processing time of the sensor controller. The camera image input time varies depending on the sensor controller model, number of cameras, and camera settings. Check before you use the camera.
\*2 Up to four cameras of this model can be connected to one controller. Up to eight cameras including other models can be connected to an FH-5050-20, 3050-20, 2050-20 or 1050-20.
\*3 Frame rate in high speed mode when the camera is connected using two camera cables. For other conditions, refer to the table on the next page.

Model		FH- SM02	FH- SC02	FH- SM04	FH- SC04	FH- SM12	FH- SC12	FH- SMX	FH- SCX	FH- SMX05	FH- SCX05	FH- SMX12	FH- SCX12	FH- SM21R	FH- SC21R	
2 Cables		High Speed Mode *6	4.6	4.6 ms		8.5 ms 25.7 ms		10.3 ms		24.9 ms		42.6 ms				
Image Acquisition	laye	Standard Mode	9.7	ms	17.9	) ms	51.3	ms	-		22.1	ms	53.5	5 ms	90.1	ms
Time *4	1 Cables	High Speed Mode *6	9.2	ms	17.0 ms		51.3	sms	1.9 ms		20.6 ms		50.0 ms		83.3 ms	
	i Cables	Standard Mode	19.3	3 ms	35.8	3 ms	102.	0 ms	3.8	ms	44.1	ms	106.4	4 ms	175.4	4 ms

\*4 The image acquisition time does not include the image conversion processing time of the sensor controller.
\*5 Two Camera ports of the controller are used per one camera.
\*6 Up to 5 m Camera Cable length.

#### **Camera Cables**

Item	Descriptions	Model *3
• •	Camera Cable Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VS3 □M
Q,	Bend resistant Camera Cable Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VSB3 □M
	Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VSL3 □M
, Ò	Bend resistant Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VSLB3 □M
Q	Long-distance Camera Cable Cable length: 15 m *2	FZ-VS4 15M
Q	Long-distance Right-angle Camera Cable *1 Cable length: 15 m *2	FZ-VSL4 15M
<b>\$</b>	Cable Extension Unit Up to two Extension Units and three Cables can be connected. (Maximum cable length: 45 m *2)	FZ-VSJ

\*1 \*2

This Cable has an L-shaped connector on the Camera end. The maximum cable length depends on the camera being connected, and the model and length of the cable being used. For further information, refer to the *Cameras / Cables Connection Table and Maximum Extension Length Using Cable Extension Units FZ-VSJ* table. When a High-speed Digital CMOS Camera FH-S02/-S04/-S12/-S21R is used in the high speed mode of transmission speed, two camera cables are required. Insert the cables length into 0 in the model number as follows. 2 m = 2, 3 m = 3, 5 m = 5, 10 m = 10

\*3

### **Cameras / Cables Connection Table**

					High-sp	eed Digital CMOS	cameras			
			300,000-pixel	2 millio	on-pixel	4 millio	n-pixel	12 millio	on-pixel	
Camera Cables	Model	Cable	FH-SM/SC	FH-SM0	)2/SC02	FH-SM0	04/SC04	FH-SM12/SC12		
		length	-	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	
Camera Cables	FZ-VS3 FZ-VSL3	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
		3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	Yes	No	Yes	No	Yes	No	Yes	
Bend resistant		2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cable		10 m	Yes	No	Yes	No	Yes	No	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	No	Yes	

					High-speed Digita	al CMOS cameras			
			400,00	0-pixel	5 millio	on-pixel	12 milli	on-pixel	
Camera Cables	Model	Cable	FH-SM	IX/SCX	FH-SMX	05/SCX05	FH-SMX12/SCX12		
		length	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select	
Camera Cables	FZ-VS3 FZ-VSL3	2 m	Yes	Yes	Yes	Yes	Yes	Yes	
		3 m	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes	
		10 m	No	Yes	No	Yes	No	Yes	
Bend resistant		2 m	Yes	Yes	Yes	Yes	Yes	Yes	
camera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes	Yes	Yes	Yes	Yes	
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes	Yes	Yes	Yes	
Camera Cable		10 m	No	Yes	No	Yes	No	Yes	
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	No	Yes	No	Yes	No	Yes	

				Digital CM	OS Camera		Di	igital CCD camer	as
			5 million-pixel	20.4 mill	ion-pixel	5 million-pixel	300,000-pixel	2 million-pixel	5 million-pixel
Camera Cables	Model	Cable length	FH-SM05R/ SC05R	FH-SM21	R/SC21R	FZ-S5M3/ SC5M3	FZ-S/SC	FZ-S2M/SC2M	FZ-S5M2
			_	High speed mode of transmission speed select	Standard mode of transmission speed select	-	-	_	-
	FZ-VS3 FZ-VSL3	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cables Right-angle		3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	No	Yes	No	Yes	Yes	No
Bend resistant		2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
camera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cable		10 m	Yes	No	Yes	No	Yes	Yes	No
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	Yes	No

Camera Cables	Model	Cable	Small digital CCD cameras Pen type / flat type	High-speed Digital CCD cameras	Intelligent Compact Digital CMOS Camera
	Model	length	FZ-SF/SFC FZ-SP/SPC	FZ-SH/SHC	FZ-SQ□
	FZ-VS3 FZ-VSL3	2 m	Yes	Yes	Yes
		3 m	Yes	Yes	Yes
		5 m	Yes	Yes	Yes
		10 m	Yes	Yes	Yes
Bend resistant	FZ-VSB3	2 m	Yes	Yes	Yes
		3 m	Yes	Yes	Yes
Right-angle	FZ-VSLB3	5 m	Yes	Yes	Yes
Camera Čable		10 m	Yes	Yes	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	Yes	Yes

## **FH-Series**

### Maximum Extension Length Using Cable Extension Units FZ-VSJ

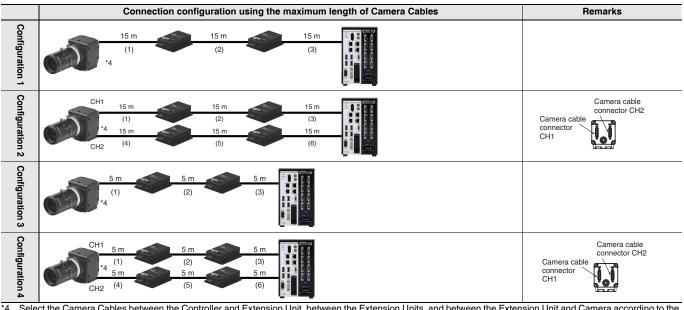
		Transmission	No. of CH used	Maximum cable length	Max. number of	•	e Extension Units FZ-VSJ
Item	Model	speed (*1)	for connection (*2)	using 1 Camera Cable (*1)	connectable Extension Units	Max.cable length	Connection configuration
	FH-SM/SC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
	FH-SMX/SCX	Standard		15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
High-speed Digital CMOS Cameras	FII-SMA/SCA	High speed		5 m (Using FZ-VS⊡/VSL⊡)	2	15 m	[Configuration 3] Camera cable: 5 m $\times$ 3 Extension Unit: 2
		Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
	FH-SM02/SC02 FH-SM04/SC04 FH-SM12/SC12		2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: 15 m × 6 Extension Unit: 4
	FH-SM12/SC12 FH-SMX05/SCX05 FH-SMX12/SCX12	High speed	1	5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2
		nign speed	2	5 m (Using FZ-VS⊡/VSL⊡)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m $\times$ 6 Extension Unit: 4
	FH-SM21R/SC21R	Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
			2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: $15 \text{ m} \times 6$ Extension Unit: 4
Digital CMOS		High speed	1	15 m (Using FZ-VS4/VSL4)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2
Cameras			2	5 m (Using FZ-VS⊡/VSL⊡)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m $\times$ 6 Extension Unit: 4
	FH-SM05R/SC05R			15 m (Using FZ-VS□/VSL□)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
	FZ-S5M3/SC5M3			5 m (Using FZ-VS⊟/VSL⊟)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2
Digital	FZ-S/SC FZ-S2M/SC2M			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
CCD Cameras	FZ-S5M2			5 m (Using FZ-VS⊡/VSL⊡)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2
Small Digital CCD Cameras Flat type/ Pen type	FZ-SF/SFC FZ-SP/SPC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2
High-speed Digital CCD Cameras	FZ-SH/SHC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m X 3 Extension Unit: 2
Intelligent Compact Digital CMOS Camera	FZ-SQ			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m X 3 Extension Unit: 2

\*1 The FH-S enables switching between standard and high speed modes. In high speed mode, images can be transferred approximately two times faster than in standard mode, but the connectable cable length will be shorter.

\*2 The FH-S has two channels to connect Camera Cables. Connection to two channels makes image transfer two times faster than connection to one channel: high speed mode using two channels can transfer approximately four times as many images as standard mode using one channel.

\*3 Each channel can be used to connect up to two Cable Extension Units: up to four extension units, two channels x two units, can be connected by using two channels.

#### **Connection Configuration**



Select the Camera Cables between the Controller and Extension Unit, between the Extension Units, and between the Extension Unit and Camera according to the connected Camera. Different types or lengths of Camera Cables can be used for (1), (2), and (3) as well as for (4), (5), and (6). However, the type and length of Camera Cable (1) must be the same as those of Camera Cable (4), (2) must be the same as (5), and (3) must be the same as (6).

## **Touch Panel Monitor**

Item	Descriptions	Model
	Touch Panel Monitor 12.1 inches For FH Sensor Controllers *	FH-MT12

\* FH Series Sensor Controllers version 5.32 or higher is required.

#### **Touch Panel Monitor Cables**

Item	Descriptions	Model
<i>1</i> <b>9</b>	DVI-Analog Conversion Cable for Touch Panel Monitor Cable length: 2 m, 5 m or 10 m	FH-VMDA □M *1
	RS-232C Cable for Touch Panel Monitor Cable length: 2 m, 5 m or 10 m	XW2Z-□□□PP-1 *2
, Ó,	USB Cable for Touch Panel Monitor Cable length: 2 m or 5 m	FH-VUAB 🗆 M*1

\*1 Insert the cables length into  $\Box$  in the model number as follows. 2 m = 2, 5 m = 5, 10 m = 10

\*2 Insert the cables length into  $\square$  in the model number as follows. 2 m = 200, 5 m = 500, 10 m = 010.

A video signal cable and an operation signal cable are required to connect the Touch Panel Monitor.

Signal	Cable	2 m	5 m	10 m
Video signal	DVI-Analog Conversion Cable	Yes	Yes	Yes
Touch panel operation signal	USB Cable	Yes	Yes	No
	RS-232C Cable	Yes	Yes	Yes

#### Parallel I/O Cables/Encoder Cable

Item	Descriptions	Model
~	Parallel I/O Cable *1 Cable length: 2m, 5m or 15m	<b>XW2Z-S013-</b> □ *2
$\sim$	Parallel I/O Cable for Connector-terminal Conversion Unit *1 Cable length: 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m Connector-Terminal Block Conversion Units can be connected (Terminal Blocks Recommended Products: OMRON XW2R-□34G-T)	XW2Z-000EE *3
And the second second	Connector-Terminal Block Conversion Units, General-purpose devices	XW2R-□34GD-T *4
∕ <b>♀</b>	Encoder Cable for line-driver Cable length: 1.5 m	FH-VR 1.5M

2 Cables are required for all I/O signals.

Insert the cables length into  $\square$  in the model number as follows. 2 m = 2, 5 m = 5, 15 m = 15 Insert the cables length into  $\square$  in the model number as follows. 0.5 m = 050, 1 m = 100, 1.5 m = 150, 2 m = 200, 3 m = 300, 5 m = 500 Insert the wiring method into  $\square$  in the model number as follows. Phillips screw = J, Slotted screw (rise up) = E, Push-in spring = P Refer to the XW2R Series catalog (Cat. No. G077) for details. \*2 \*3 \*4

#### Parallel Converter Cable

When you change to connect the F series, FZ5 series, or FZ5-L series to FH series Sensor Controller, you can convert by using the appropriate parallel converter cable of FH-VPX series under the usable condition.

Item	Applicable Model		Usable Condition	Model
	FZ series		<ul> <li>Do not use RESET signal. *</li> <li>Use with COMIN and COMUT are same power source.</li> </ul>	FH-VPX-FZ
$\overline{\mathcal{Q}}$	FZ  -L35x series		• Do not use RESET signal. *	FH-VPX-FZL
	F160 series	F160-C10	<ul> <li>Do not use RESET signal. *</li> <li>Use with COMIN and COMOUT are same power source.</li> <li>Do not use DI5 and DI6.</li> </ul>	FH-VPX-F160
	F210 series	F210-C10	Do not use RESET signal. *	
<b>~</b> )	F210 Selles	F210-C10-ETN	<ul> <li>Use with COMIN and COMOUT are same power source.</li> </ul>	FH-VPX-F210
	F500 series	F500-C10	Do not use DI8 and DI9.	

\* Even if RESET signal cannot be use by conversion, conversion is possible to convert satisfying other usable condition. **Note:** Cannot be used for the F160-C10CP/-C10CF.

#### **Recommended EtherCAT and EtherNet/IP Communications Cables**

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT. Use Straight or cross STP (shielded twisted-pair) cable of category 5 or higher for EtherNet/IP. Cable with Connectors

Item	Appearance	Recommended manufacturer	Cable length (m)	Model
			0.3	XS6W-6LSZH8SS30CM-Y
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6LSZH8SS50CM-Y
Standard RJ45 plugs type *1 Wire Gauge and Number of Pairs: AWG26, 4-pair Cable		OMBON	1	XS6W-6LSZH8SS100CM-Y
Cable Sheath material: LSZH *2		OMRON	2	XS6W-6LSZH8SS200CM-Y
Cable color: Yellow *3			3	XS6W-6LSZH8SS300CM-Y
			5	XS6W-6LSZH8SS500CM-Y
			0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1		OMRON	1	XS5W-T421-CMD-K
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable			2	XS5W-T421-DMD-K
able color: Light blue			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
		OMRON	0.5	XS5W-T421-BM2-SS
Cable with Connectors on Both Ends (M12 Straight/M12 Straight)			1	XS5W-T421-CM2-SS
Shield Strengthening Connector cable *4			2	XS5W-T421-DM2-SS
M12/Smartclick Connectors			3	XS5W-T421-EM2-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GM2-SS
			10	XS5W-T421-JM2-SS
			0.5	XS5W-T421-BMC-SS
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable *4			1	XS5W-T421-CMC-SS
M12/Smartclick Connectors	11 st	ONDON	2	XS5W-T421-DMC-SS
Rugged RJ45 plugs type		OMRON	3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

\*1 Cables with standard RJ45 plugs are available in the following lengths: 0.2 m, 0.3 m, 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m, 7.5 m, 10 m, 15 m, 20 m. Cables with rugged RJ45 plugs are available in the following lengths: 0.3 m, 0.5 m, 1 m, 2 m, 3 m, 5 m, 10 m, 15 m. For details, refer to the Industrial Ethernet Connectors Catalog (Cat. No. G019).

\*2 The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PÚR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

\*3 Cables colors are available in yellow, green, and blue.

\*4 For details, contact your OMRON representative.

#### Cables / Connectors

Item		Recommended manufacturer	Model
Products for EtherCAT or EtherNet/IP		Hitachi Cable, Ltd.	NETSTAR-C5E SAB 0.5 x 4P *1
(1000BASE-T/100BASE-TX) Wire gauge and number of pairs:	Cable	Kuramo Electric Co.	KETH-SB *1
		SWCC Showa Cable Systems Co.	FAE-5004 <b>*1</b>
AWG24, 4-pair cable	RJ45 Connector	Panduit Corporation	MPS588-C <b>*1</b>
	0-64	Kuramo Electric Co.	KETH-PSB-OMR *2
Products for EtherCAT or EtherNet/IP	Cable	JMACS Japan Co., Ltd.	PNET/B <b>*2</b>
(100BASE-TX/10BASE-T) Wire gauge and number of pairs: AWG22, 2-pair cable	RJ45 Assembly Connector	OMRON	XS6G-T421-1 <b>*2</b>

\*1 We recommend you to use the above Cable and RJ45 Connector together.

\*2 We recommend you to use the above Cable and RJ45 Assembly Connector together.

Automation Software Sysmac Studio Please purchase a DVD and licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. The license does not include the DVD.

Item	Specifications			Model
nem	Specifications	Number of licenses	Media	Woder
	The Sysmac Studio is the software that provides an integrated envi-	(Media only)	DVD *1	SYSMAC-SE200D
	ronment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU	1 license	-	SYSMAC-SE201L
	Units, NY-series Industrial PC, EtherCat Slave, and the HMI.	3 license	-	SYSMAC-SE203L
Sysmac Studio Standard Edition Windows 8 (32-bit/ Windows 8 (32-bit/	Sysmac Studio runs on the following OS.	10 license	-	SYSMAC-SE210L
	on       Windows 8 (32-bit/64-bit version) /       3         Windows 8.1 (32-bit/64-bit version) /       Windows 8.1 (32-bit/64-bit version) /       4         Windows 10 (32bit/64-bit version)       This software provides functions of the Vision Edition.       5         Refer to OMRON website for details such as supported models and functions.       5         o       Sysmac Studio Vision Edition is a limited license that provides selected functions required for FH-series/       1	30 license		SYSMAC-SE230L
Ver.1.		50 license	_	SYSMAC-SE250L
Sysmac Studio Vision Edition Ver.1		1 license	_	SYSMAC-VE001L
Sysmac Studio Robot Additional Option *3	Sysmac Studio Robot Additional Option is a license to enable the Vision & Robot integrated simulation.	1 license	_	SYSMAC-RA401L

Note: 1. Site licenses are available for users who will run Sysmac Studio on multiple computers. Ask your OMRON sales representative for details. 2. Sysmac Studio version 1.07 or higher supports the FH Series. Sysmac Studio does not support the FH-L550/-L550-10.

The same media is used for both the Standard Edition and the Vision Edition. With the Vision Edition, you can use only the setup functions for FH-series/FQ-M-series Vision Sensors. This product is a license only. You need the Sysmac Studio Standard Edition DVD media to install it. \*1 \*2 \*3

**Development Environment** 

Please purchase a CD-ROM and licenses the first time you purchase the Application Producer. CD-ROMs and licenses are available individually. The license does not include the CD-ROM.

Product	Specifications	Number of Model Standards licenses	Media	Model
	Software components that provide a development environment to further customize the standard controller features of the FH Series. System requirements: CPU: Intel Pentium Processor (SSE2 or higher) OS: Windows 7 Professional (32/64bit) or Enterprise(32/64bit) or Ultimate (32/64bit), Windows 8 Pro(32/64bit) or Enterprise(32/64bit),	— (Media only)	CD-ROM	FH-AP1
Application Producer	Windows 8.1 Pro(32/64bit) or Enterprise(32/64bit) .NET Framework: .NET Framework 3.5 SP1 or higher Memory: At least 2 GB RAM Available disk space: At least 2 GB Browser: Microsoft® Internet Explorer 6.0 or later Display: XGA (1024 × 768), True Color (32-bit) or higher Optical drive: CD/DVD drive The following software is required to customize the software: Microsoft® Visual Studio® 2008 Professional or Microsoft® Visual Studio® 2010 Professional or Microsoft® Visual Studio® 2012 Professional	1 license	-	FH-AP1L

## **FH-Series**

Item		Descriptions				
	LCD Monitor 8.4 inches				FZ-M08	
	LCD Monitor Cable			2 m	FZ-VM 2M	
•9			FH sensor controller, please use on Connector FH-VMRGB.	5 m	FZ-VM 5M	
0	DVI-I -RGB Conversion Co	onnector			FH-VMRGB	
	USB Memory		2 GB		FZ-MEM2G	
i.			8 GB		FZ-MEM8G	
SP	SD Card		2 GB	2 GB		
2dm			4 GB		HMC-SD491	
tion of	Display/USB Switcher				FZ-DU	
	Mouse Recommended Pr	oducts				
-	Driverless wired mouse		buse driver to be installed is not supported.)			
1900		3 port	Power supply voltage:	Current consumption: 0.08 A	GX-JC03	
	<ul> <li>EtherCAT junction slaves</li> </ul>	6 port	- 20.4 to 28.8 VDC (24 VDC -15 to 20%)	Current consumption:	GX-JC06	
		-		0.17 A Current consumption:	W404 00D	
	Industrial Switching Hubs for EtherNet/IP and Ether-	3 port	Failure detection: None	0.08 A	W4S1-03B W4S1-05B	
200	net	5 port	Failure detection: None	Current consumption:		
E		5 port	Failure detection: Supported	0.12 A	W4S1-05C	
_	Calibration Plate	l			FZD-CAL	
		DIN rail mounting (For Lite Controll	FH-XDM-L			
	Common items related to DIN rail (for FH-L550/-L550-10)	related to DIN rail			Length: 75.5/95.5/115.5/200 cm     Height: 7.5mm     Material: Iron     Surface: Conductive	NS 35/7,5 PERF
		DIN 35mm rail	PHOENIX CONTACT	Length:75.5/95.5/115.5/200 cm     Height: 15mm     Material: Iron     Surface: Conductive	NS 35/15 PERF	
DIS TO		End plate	PHOENIX CONTACT	Need 2 pieces each Sensor Con- troller	CLIPFIX 35	
				LED	FLV Series	
			External lighting controller	High-brightness LED	FL-BR/DR Serie	
_	External Lights			Photometric Stereo Light	FL-PS Series	
			Built-in lighting controller	MDMC Light	FL-MD Series	
				Mounting Bracket	FQ-XL	
	For Intelligent Compact Dig	gital CMOS Came	ra	Mounting Brackets	FQ-XL2	
				Polarizing Filter Attachment	FQ-XF1	
7	Mounting Bracket for FZ-S	□, FH-S□05R, FZ	FZ-S-XLC			
	Mounting Bracket for FZ-S	2M			FZ-S2M-XLC	
_	Mounting Bracket for FZ-S	H			FZ-SH-XLC	
—	Mounting Bracket for FH-S	□, FZ-S□5M□, FI	H-S□X05, FH-S□X12, FH-S□21	R	FH-SM-XLC	
	Mounting Bracket for FH-S	⊡12			FH-SM12-XLC	
	M42 - F Mount Conversion	Adapter			FH-ADF/M42-10	

\* Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

#### Lenses

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

			Recommended lens			
Resolution	Camera Model	Size of image element	Standard Lens	Telecentric Lens	Vibrations and Shocks Resistant Lens	
	FZ-SF/SFC		FZ-LES Series			
300,000-pixel	FZ-SP/SPC		FZ-LES Series			
	FZ-S/SC	1/3" equivalent				
	FZ-SH/SHC				VS-MCA Series	
	FH-SM/SC		SV-V Series	VS-TCH Series	VS-MC Series Non-telecentric Macro	
400,000-pixel	FH-SMX/SCX	1/2.9" equivalent	-		VS-MC Series	
	FZ-S2M/SC2M	1/1.8" equivalent	SV-H Series			
2 million-pixel	FH-SM02/SC02	2/3" equivalent	VS-H1 Series	VS-TEV Series	VS-MCA Series VS-MC Series	
4 million-pixel	FH-SM04/SC04	1" equivalent	-		VS-MCH Series	
	FH-SM05R/SC05R	1/2.5" equivalent			VS-MCA Series	
5 million-pixel	FZ-S5M3/SC5M3 FZ-S5M2	2/3" equivalent	SV-H Series	VS-TCH Series	VS-MC Series Non-telecentric Macro	
	FH-SMX05/SCX05	2/3" equivalent	-		VS-MC Series	
10 million nivel	FH-SMX12/SCX12	1.1" equivalent	VS-LLD Series	VS-TEV Series		
12 million-pixel	FH-SM12/SC12	1.76" equivalent	VS-L/M42-10 Series		VS-MCL/M42 Series	
20.4 million-pixel	FH-SM21R/SC21R	1" equivalent	VS-LLD Series	VS-TEV Series	VS-MCH Series	

## **FH-Series**

# **Ratings and Specifications (FH Sensor Controllers)**

## High-speed, Large-capacity Controller

	ller Series		High-speed	FH-5050 Series Large-capacity Contr	oller (4 cores)	High-spee	FH-2050 Series d, Large-capacity Con	troller (2 cores)			
Type Sensor Contro	ller Model		FH-5050	FH-5050-10	FH-5050-20	FH-2050	FH-2050-10	FH-2050-20			
Parallel IO			NPN/PNP (common)	l.							
		Standard	Yes								
	Operation	Double Speed Multi-input	Yes								
	Mode	Non-stop adjustment mode	Yes								
		Multi-line random-trigger mode	Yes (Maximum 8 lines	s) *1							
	Parallel Proce		Yes	i	1	i	-				
	Number of Co	nectable Camera	2	4	8	2	4	8			
	Supported Camera	FH-S series camera	All of the FH-S series connectable.	cameras are	All of the FH-S series cameras are connectable. *2	All of the FH-S serie connectable.	es cameras are	All of the FH-S ser cameras are connectable. *2			
ain unctions	Camera I/F	FZ-S series camera	All of the FZ-S series cameras are connectable.								
		per of Captured Images	Refer to page 39.								
		per of Logging Images to Sensor									
	Controller		3	stem FH/FZ5 Series L	<i>Iser's Manual</i> (Cat. No. 2	2365).					
	Possible Num		128								
	Operating	USB Mouse		driver is unnecessary ty	/pe)						
	on UI	Touch Panel	Yes (RS-232C/USB c								
	Setup			flow using Flow editin							
	Language			mplified Chinese, Trac	itional Chinese, Korean	, German, French, Sp	anish, Italian, Vietname	ese, Polish			
	Serial Commu		RS-232C × 1								
	Ethernet	Protocol	Non-procedure (TCP/	UUP)							
	Communication		1000BASE-T × 2								
	EtherNet/IP Co	ommunication	Yes (Target/Ethernet								
	PROFINET Co	mmunication	Yes (Slave/Ethernel								
			Conformance class								
	EtherCAT Con	munication			T Communications Spe	cifications.					
E	Parallel I/O		12 inputs/31 outputs:     Use 1 Line.     Operation mode: Except Multi-line random-trigger mode.     17 inputs/37 outputs:     Use 2 Lines.     Operation mode: Multi-line random-trigger mode.     14 inputs/29 outputs:     Use 3 to 4 Lines.								
			Operation mode: Multi-line random-trigger mode.     19 inputs/34 outputs:     Use 5 to 8 Lines.     Operation mode: Multi-line random-trigger mode.								
	Encoder Interface		Input voltage: 5 V ± 5% Signal: R5-422A Line Driver Level Phase A/B/Z: 1 MHz								
	Monitor Interface USB I/F		DVI-I output (Analog RGB & DVI-D single link) × 1								
			USB3.0 host × 2 (BUS Power: Port5 V/0.5 A)								
				USB2.0 host × 4 (BUS Power: Port5 V/0.5 A)							
	SD Card I/F		SDHC × 1								
r	Main		POWER: Green ERROR: Red RUN: Green ACCESS: Yellow								
ndicator	Ethernet		NET RUN1: Green           LINK/ACT1: Yellow           NET RUN2: Green           LINK/ACT2: Yellow								
amps	SD Card		SD POWER: Green SD BUSY, Yellow								
			ECAT RUN: Green LINK/ACT IN: Green								
	EtherCAT		LINK/ACT OUT: Green ECAT ERR: Red								
ower-supply			20.4 VDC to 26.4 VD	<u> </u>							
	<ul><li>camera</li><li>When connect</li></ul>	ing an intelligent compact digital cting the following light or lighting									
urrent onsumption	FLV-TCC1 FLV-TCC1 • When conne ing controlle	hout an external power supply , FLV-TCC4, FLV-TCC3HB EP, FL-TCC1 cting the following light or light- r S, FL-MD⊡MC	5.6 A max.	7.7 A max.	12.2 A max.	4.6 A max.	6.6 A max.	11.2 A max.			
uile in Edui	Other than abo		4.5 A max.	5.5 A max.	7.3 A max.	3.5 A max.	4.3 A max.	6.3 A max.			
uilt-in FAN			Yes			Operating: 0°C to	50°C				
	Ambient temp	erature range	Operating: 0°C to +45°C         Operating: 0°C to +50°C           Storage: -20 to +65°C (with no icing or condensation)         Storage: -20 to +65°C (with no icing or condensation)								
	Ambienthur	dity range	Operating:35 to 85%RH								
	Ambient humi		Storage: 35 to 85%RH (with no condensation)								
	Ambient atmo	sphere	No corrosive gases								
	Vibration tolerance		Oscillation frequency: 10 to 150 Hz Half amplitude: 0.1 mm Acceleration: 15 m/s <sup>2</sup> Sweep time: 8 minute/count Sweep count: 10 Vibration direction: up and down/front and behind/left and right								
	Vibration toler	ance	Sweep count: 10	and down/front and b	sinna/ion and right	Impact force: 150 m/s <sup>2</sup> Test direction: up and down/front and behind/left and right					
	Vibration toler Shock resistar		Sweep count: 10 Vibration direction: up Impact force: 150 m/s	2							
sage nvironment	Shock resistan Noise immunity		Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct infusion: 2kV, • I/O line Direct infusion: 1kV,	<sup>2</sup> down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls	l/left and right se width: 50ns, Burst cor se width: 50ns, Burst cor						
	Shock resistan	ice	Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct infusion: 2kV, • I/O line Direct infusion: 1kV, Type D grounding (10	2 down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls 0 Ω or less grounding	l/left and right se width: 50ns, Burst cor se width: 50ns, Burst cor						
	Shock resistan Noise immunity Grounding	ice	Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct infusion: 2kV, • I/O line Direct infusion: 1kV. Type D grounding (10 190 mm × 115 mm ×	$^{2}$ down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls O $\Omega$ or less grounding 182.5 mm	l/left and right se width: 50ns, Burst cor se width: 50ns, Burst cor						
vironment	Shock resistan Noise immunity Grounding Dimensions	ice	Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and Direct infusion: 2kV, V/O line Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm × Note Height: Including	$^2$ down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls 0 $\Omega$ or less grounding 182.5 mm the feet at the base.	Vleft and right se width: 50ns, Burst cor se width: 50ns, Burst cor resistance) *3	ntinuation time: 15ms	/0.75ms, Period: 300ms	s, Application time: 1			
ternal	Shock resistan Noise immunity Grounding Dimensions Weight	Fast Transient Burst	Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct infusion: 2kV, • I/O line Direct infusion: 1kV, Type D grounding (10 190 mm × 115 mm × Note Height: Including Approx. 3.4 kg	$^{2}$ down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls O $\Omega$ or less grounding 182.5 mm	l/left and right se width: 50ns, Burst cor se width: 50ns, Burst cor						
ternal	Shock resistan Noise immunity Grounding Dimensions	Fast Transient Burst	Sweep count: 10 Vibration direction: up Impact force: 150 m/s Test direction: up and • DC power Direct infusion: 2kV, • I/O line Direct infusion: 1kV Type D grounding (10 190 mm × 115 mm × Note Height: Including Approx. 3.4 kg IEC60529 IP20	2 down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls 0 Ω or less grounding 182.5 mm the feet at the base. Approx. 3.6 kg	Vleft and right se width: 50ns, Burst cor se width: 50ns, Burst cor resistance) *3	ntinuation time: 15ms	/0.75ms, Period: 300ms	s, Application time: 1			
	Shock resistan Noise immunity Grounding Dimensions Weight	Fast Transient Burst	Sweep count: 10 Vibration direction: up and DE power Direct infusion: 2kV, V/O line Direct infusion: 2kV, V/O line Direct infusion: 1kV Type D grounding (1C 190 mm x-115 mm x- Note Height: Including Approx. 3.4 kg IEC60529 IP20 Cover: zinc-plated ste	$^{2}$ down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls O $\Omega$ or less grounding 182.5 mm the feet at the base. Approx. 3.6 kg	Vleft and right se width: 50ns, Burst cor se width: 50ns, Burst cor resistance) *3	ntinuation time: 15ms	/0.75ms, Period: 300ms	s, Application time: 1			
ternal	Shock resistant Noise immunity Grounding Dimensions Weight Degree of prot	Fast Transient Burst	Sweep count: 10 Vibration direction: up and • DC power Direct infusion: 2kV. • I/O line Direct infusion: 1kV. Type D grounding (10 190 mm × 115 mm × Note Height: Including Approx. 3.4 kg IEC60529 IP20 Cover: zinc-plated ste Side plate: alluminum	$^2$ down/front and behind Pulse rising: 5ns, Puls Pulse rising: 5ns, Puls 0 $\Omega$ or less grounding 182.5 mm the feet at the base. Approx. 3.6 kg el plate (A6063)	Vleft and right se width: 50ns, Burst cor se width: 50ns, Burst cor resistance) *3	ntinuation time: 15ms	/0.75ms, Period: 300ms	s, Application time: 1			

\*1 According to the CPU performance, FH-2050 series is recommended to use up to two lines in this mode.
\*2 Up to eight cameras can be connected in total including up to four 12 or 20.4 million-pixel cameras.
\*3 Existing third class grounding

#### **Standard Controller**

Sensor Contro Type				FH-3050 Series andard Controller (4 c		FH-1050 Series Standard Controller (2 cores)			
Sensor Contro Parallel IO	ller Model		FH-3050 NPN/PNP (common)	FH-3050-10	FH-3050-20	FH-1050	FH-1050-10	FH-1050-20	
aranerio		Standard	Yes						
	Operation	Double Speed Multi-input	Yes						
	Mode	Non-stop adjustment mode	Yes	vo) *1					
	Parallel Proce	Multi-line random-trigger mode	Yes (Maximum 8 line Yes	s) " I					
		nnectable Camera	2	4	8	2	4	8	
			All of the FH-S series	s cameras except FH-	All of the FH-S series	All of the FH-S series	es cameras except FH-	All of the FH-S seri	
	Supported Camera	FH-S series camera	SM21R/SC21R		cameras except FH- SM21R/SC21R *2	SM21R/SC21R		cameras except F SM21R/SC21R *2	
/lain Functions	Guinera	FZ-S series camera	All of the FZ-S series	cameras are connecta					
	Camera I/F	1	OMRON I/F						
		ber of Captured Images	Refer to page 39.			2005)			
	Possible Number	of Logging Images to Sensor Controller	128	ystem FH/FZ5 Series L	<i>Iser's Manual</i> (Cat. No. 2	2365).			
	Operating	USB Mouse		driver is unnecessary t	vpe)				
	on UI	Touch Panel		connection: FH-MT12)	//				
	Setup	1		g flow using Flow editir					
	Language			Simplified Chinese, Trac	litional Chinese, Korean	, German, French, Sp	oanish, Italian, Vietname	se, Polish	
	Serial Commu		RS-232C × 1						
	Ethernet Communication	Protocol I/F	Non-procedure (TCP 1000BASE-T × 2	/UDP)					
	EtherNet/IP Co		Yes (Target/Ethernet	t nort)					
	PROFINET Co		Yes (Slave/Etherne	1 /					
			<ul> <li>Conformance class</li> </ul>						
	EtherCAT Con	nmunication			T Communications Spe	cifications.			
			<ul> <li>12 inputs/31 output</li> <li>Use 1 Line.</li> </ul>	IS:					
				Except Multi-line rando	om-trigger mode.				
			<ul> <li>17 inputs/37 output</li> <li>Use 2 Lines.</li> </ul>	ts:					
External Interface	Parallel I/O		<ul> <li>Operation mode:</li> </ul>	Multi-line random-trigg	er mode.				
			<ul> <li>14 inputs/29 output</li> <li>14 inputs/29 output</li> </ul>						
			Use 3 to 4 Lines.     Operation mode: Multi-line random-trigger mode.						
			<ul> <li>19 inputs/34 output</li> </ul>	ts:					
			<ul> <li>Use 5 to 8 Lines.</li> <li>Operation mode:</li> </ul>	Multi-line random-trigg	or modo				
			Input voltage: 5 V ± 5		er moue.				
	Encoder Inter	ace	Signal: RS-422A Line Driver Level						
	Monitor Interf		Phase A/B/Z: 1 MHz						
	Monitor Interface USB I/F		DVI-I output (Analog RGB & DVI-D single link) × 1 USB2.0 host × 4 (BUS Power: Port5 V/0.5 A)						
	SD Card I/F		SDHC × 1						
			POWER: Green						
	Main		ERROR: Red RUN: Green						
			ACCESS: Yellow	-					
			NET RUN1: Green NET RUN1: Green LINK/ACT1: Yellow NET RUN: Green LINK/ACT1: Yellow						
ndicator	Ethernet SD Card		LINK/ACT: Yellow	NET RUN2: Green		LINK/ACT: Yellow	NET RUN2: Green		
amps			SD POWER: Green						
			SD BUSY: Yellow						
			ECAT RUN: Green						
	EtherCAT		LINK/ACT IN: Green LINK/ACT OUT: Green						
			ECAT ERR: Red						
ower-supply			20.4 VDC to 26.4 VD	)C		i			
		g an intelligent compact digital camera cting the following light or lighting	1						
	controller with	thout an external power supply	1						
Current		, FLV-TCC4, FLV-TCC3HB	5.0 A max.	7.0 A max.	11.5 A max.	4.7 A max.	6.5 A max.	10.9 A max.	
consumption	FLV-TCC1EP, FL-TCC1 • When connecting the following light or light-		1						
	ing controlle	r ∕S, FL-MD⊡MC	1						
	Other than ab		4.1 A max.	4.8 A max.	6.8 A max.	3.6 A max.	4.3 A max.	6.2 A max.	
Built-in FAN	o lifer than up		Yes	norrinan	0.077 max	0.071 max	norrinax	0.271110.0	
	Ambient temp	erature range	Operating: 0°C to +5						
	Amplent temp	cratare range	Storage: -20 to +65°C (with no icing or condensation)						
	Ambient humi	dity range	Operating:35 to 85%RH Storage: 35 to 85%RH (with no condensation)						
	Ambient atmo	sphere	No corrosive gases						
			Oscillation frequency: 10 to 150 Hz						
			Half amplitude: 0.1 mm Acceleration: 15 m/s <sup>2</sup>						
Usage	Vibration toler	ance	Sweep time: 8 minute/count						
Environment			Sweep count: 10 Vibration direction: up and down/front and behind/left and right						
			Impact force: 150 m/s <sup>2</sup>						
	Shock resista		Test direction: up and down/front and behind/left and right						
	Noise		<ul> <li>DC power Direct infusion: 2kV</li> </ul>	. Pulse risina: 5ns. Pul	se width: 50ns. Burst co	ntinuation time: 15ms	/0.75ms, Period: 300ms	Application time: 1 r	
	immunity	Fast Transient Burst	<ul> <li>I/O line</li> </ul>	-					
	Grounding			/, Pulse rising: 5ns, Pul 00 Ω or less grounding		nunuation time: 15ms	0.75ms, Period: 300ms	, Application time: 1 r	
			190 mm × 115 mm ×		issistance 3				
	Dimensions		Note Height: Includin	g the feet at the base.	<del></del>				
xternal	Weight		Approx. 3.2 kg	Approx. 3.4 kg	Approx. 3.4 kg	Approx. 3.2 kg	Approx. 3.4 kg	Approx. 3.4 kg	
eatures	Degree of prot	ection	IEC60529 IP20 Cover: zinc-plated ste	ool plato					
	Case material		Side plate: aluminum	(A6063)					
			Instruction Sheet (Ja	panese and English); 1	, Installation Instruction I	Manual for FH series	:1, Bewer estimate (FUL MOU	); 1 (mol-)	
			General Compliance	information and Instruct ra cable: 2 (FH-3050, F	tions for EU:1, Member H-1050), 4 (FH-3050-10	registration sheet: 1, ). FH-1050-10). 8 (FH	Power source (FH-XCN I-3050-20, FH-1050-20)	): I (male),	
ccessories									
Accessories		performance, FH-1050 series				,			

### **Lite Controllers**

Sensor Controller Series				0 Series			
Type Sensor Control	ler Model		Elite Co	FH-L550-10			
Parallel IO			NPN/PNP (common)	11-230-10			
		Standard	Yes				
		Double Speed Multi-input	Yes				
	Operation Mode	Non-stop adjustment	Yes				
		mode	100				
		Multi-line random-trigger mode	No				
	Parallel Processir		Yes				
	Number of Conne	-	2	4			
	Supported	FH-S series camera	All of the FH-S series cameras except FH-SM21R/SC21R				
Main Func-	Camera	FZ-S series camera	All of the FZ-S series cameras are connectable.				
lions	Camera I/F		OMRON I/F				
	Possible Number	of Captured Images	Refer to page 39.				
		of Logging Images to	Refer to the Vision System FH/FZ5 Series User's Manual (Cat. No. Z	365).			
	Sensor Controller						
	Possible Number		128				
	UI Operations	USB Mouse	Yes (wired USB driver-less type)				
	Sotup	Touch Panel	Yes (RS-232C/USB connection: FH-MT12) Create the processing flow using Flow editing.				
	Setup Language		Japanese, English, Simplified Chinese, Traditional Chinese, Korean,	German French Spanish Italian Vietnamese Polish			
	Serial Communica	ation	RS-232C × 1	מסוווענו, דוסווסוו, סימווסוו, וומוומוו, אופעומווופטפ, דטווטוו			
	Ethernet	Protocol	Non-procedure (TCP/UDP)				
	Communication	I/F	1000BASE-T × 1				
	EtherNet/IP Com		Yes (Target/Ethernet port)				
			Yes (Slave/Ethernet port)				
	PROFINET Comm		Conformance class A				
External	EtherCAT Commu	inication	No				
External Interface			High-speed input: 1     Named anode 0				
	Parallel I/O		Normal speed: 9     High-speed output: 4				
			Normal speed: 23				
	Encoder Interface		None				
	Monitor Interface		DVI-I output (Analog RGB & DVI-D single link) × 1				
	USB I/F		USB2.0 host × 1: BUS Power: Port 5 V/0.5 A				
			USB3.0 × 1: BUS Power: Port 5 V/0.5 A SDHC × 1				
	SD Card I/F		POWER: Green				
	Main		ERROR: Red				
	Main		RUN: Green				
Indicator			ACCESS: Yellow				
Lamps	Ethernet		NET RUN: Green LINK/ACT: Yellow				
	000		SD POWER: Green				
	SD Card		SD BUSY: Yellow				
	EtherCAT		None				
Power-supply v			20.4 VDC to 26.4 VDC				
		an intelligent compact dig-					
	ital camera • When connecting	g the following light or					
	lighting controll	er without an external					
Current	power supply		2.7 A max.	4.4 A max.			
consumption	FLV-TCC1, FI	_V-TCC4, FLV-TCC3HB FL-TCC1					
	<ul> <li>When connecting</li> </ul>	g the following light or					
	lighting controll FL-TCC1PS, I						
	Other than above		1.5 A max.	2.0 A max.			
Built-in FAN	other than above		No	2.0 A mdA.			
	1		Operating: 0°C to 55°C				
	Ambient temperat	ure range	Storage: -25 to +70°C				
	Ambient humidity	range	Operating and Storage: 10 to 90%RH (with no condensation)				
	Ambient atmosph	-	No corrosive gases				
	Vibration tolerand	e	5 to 8.4 Hz with 3.5 mm amplitude, 8.4 to 150 Hz, accelera				
			100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)				
Usage Envi- ronment	Shock resistance		Impact force: 150 m/s <sup>2</sup> Test direction: up and down/front and behind/left and right				
onment			DC power				
			Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns,				
	Noise immunity	Fast Transient Burst	Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1 min				
	initiatity		<ul> <li>I/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns,</li> </ul>				
			Burst continuation time: 15ms/0.75ms, Period: 300ms, Application t	time: 1 min			
	Grounding		Type D grounding (100 $\Omega$ or less grounding resistance) *				
	Dimensions		200 mm $\times$ 80 mm $\times$ 130 mm				
External	Weight		Approx. 1.5 kg	Approx. 1.5 kg			
Features	Degree of protect	ion	IEC60529 IP20				
	Case materials		PC				
			Instruction Sheet (Japanese and English): 1, Installation Instruction N	Janual for FH-L series:1			
Accessories			General Compliance Information and Instructions for EU:1, Member r	registration sheet: 1			

\* Existing third class grounding

#### Maximum Number of Loading Images during Multi-input

Camera	Model	Max. Number of Loading Images during Multi-input *1
Intelligent Compact Digital CMOS Cameras *2	FZ-SQ010F/-SQ050F/-SQ100F/-SQ100N	256
300,000 pixels CCD/CMOS Cameras	FZ-S/-SC/-SF/SFC/-SH/-SHC/-SP/-SPC FH-SM/-SC	256
400,000 pixels CMOS Cameras	FH-SMX/-SCX	256
2 million pixels CCD Cameras	FZ-S2M/-SC2M	64
2 million pixels CMOS Cameras	FH-SM02/-SC02	51
4 million pixels CMOS Cameras	FH-SM04/-SC04	32
5 million pixels CCD/CMOS Cameras	FZ-S5M3/-SC5M3/-S5M2 FH-SMX05/-SCX05/-SM05R/-SC05R	25
12 million pixels CMOS Cameras	FH-SM12/-SC12/-SMX12/-SCX12	10
20.4 million pixels CMOS Cameras	FH-SM21R/-SC21R	6

When using two camera cables for connection, the maximum number of loaded images during multi-input is twice the number given in the table. The multi-input function cannot be used when the built-in light of an intelligent compact digital camera is used. Refer to the *Vision System FH/FZ5 Series User's Manual* (Cat. No. Z340) for details. \*1 \*2

## **Ratings and Specifications (Cameras)**

### **High-speed Digital CMOS cameras**

Image elements       CMOS image elements (1/3-inch equivalent)       CMOS image elements (2/3-inch equivalent)       CMOS image elements (1-inch equivalent) <th< th=""><th>valent) Color 2 (V)</th></th<>	valent) Color 2 (V)
Effective pixels         640 (H) × 480 (V)         2040 (H) × 1088 (V)         2040 (H) × 2048 (V)         4084 (H) × 307           Imaging area H x V (opposing corner)         4.8 × 3.6 (6.0 mm)         11.26 × 5.98 (12.76 mm)         11.26 × 11.26 (15.93 mm)         22.5 × 16.9 (28           Pixel size         7.4 (µm) × 7.4 (µm)         5.5 (µm) × 5.5 (µm) × 5.5 (µm)         5.5 (µm) × 5.5 (µm) × 5.5 (µm)         5.5 (µm) × 5.5 (µm	2 (V)
Imaging area H x V (opposing corner) $4.8 \times 3.6 (6.0 \text{ mm})$ $11.26 \times 5.98 (12.76 \text{ mm})$ $11.26 \times 11.26 (15.93 \text{ mm})$ $22.5 \times 16.9 (26.92 \text{ mm})$ Pixel size $7.4 (\mu \text{m}) \times 7.4 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m}) \times 5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ Shutter functionElectronic shutter; Shutter speeds can be set from $20 \text{ ms}$ to 100 ms.Electronic shutter; Shutter speeds can be set from $25 \mu \text{ s to 100 ms}$ .Electronic shutter; Shutter speeds can be set from $25 \mu \text{ s to 100 ms}$ . $4 \text{ to 3072 lines}$ Partial function $1 \text{ to 480 lines}$ $2 \text{ to 480 lines}$ $1 \text{ to 1088 lines}$ $2 \text{ to 2048 lines}$ $4 \text{ to 3072 lines}$	( )
(opposing corner) $4.8 \times 3.6 (6.0 \text{ mm})$ $11.26 \times 5.98 (12.76 \text{ mm})$ $11.26 \times 11.26 (15.93 \text{ mm})$ $22.5 \times 16.9 (26.93 \text{ mm})$ Pixel size $7.4 (\mu \text{m}) \times 7.4 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m}) \times 5.5 (\mu \text{m}) \times 5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m})$ $5.5 (\mu \text{m}) \times 5.5 (\mu \text{m}) \times 5.$	8.14 mm)
Shutter function       Electronic shutter; Shutter speeds can be set from 20 ms to 100 ms.       Electronic shutter; Shutter speeds can be set from 25 μs to 100 ms.       Electronic shutter; Shutter speeds can be set from 25 μs to 100 ms.         Partial function       1 to 480 lines       2 to 480 lines       1 to 1088 lines       2 to 2048 lines       4 to 3072 lines	
Shutter function       Shutter speeds can be set from 20 ms to 100 ms.       Electronic shutter; Shutter speeds can be set from 25 μs to 100 ms.       Shutter speeds can be set from 25 μs to 100 ms.       Shutter speeds can be set from 25 μs to 100 ms.         Partial function       1 to 480 lines       2 to 480 lines       1 to 1088 lines       2 to 1088 lines       1 to 2048 lines       2 to 2048 lines       4 to 3072 lines	(μm)
	can be set from
Frame rate (Image Acquisition Time *1)         308 fps (3.3 ms)         219 fps (4.6 ms) *2         118 fps (8.5 ms) *2         38.9 fps (25.7	ms) *2
Lens mounting C mount M42 mount	
Field of vision, installation distance         Selecting a lens according to the field of vision and installation distance	
Ambient temperature range Operating: 0 to 40 °C, Storage: -25 to 65 °C (with no icing or condensation)	
Ambient humidity range Operating and storage: 35% to 85% (with no condensation)	
Weight         Approx.105 g         Approx.110 g         Approx.320 g	
Accessories Instruction manual	
Model FH-SMX FH-SCX FH-SMX05 FH-SCX05 FH-SMX12	FH-SCX12
Image elements CMOS image elements (1/2.9-inch equivalent) CMOS image elements (2/3-inch equivalent) CMOS image elements (1.	1-inch equivalen
Color/Monochrome Monochrome Color Monochrome Color Monochrome Col	or
Effective pixels         720 (H) × 540 (V)         2448 (H) × 2048 (V)         4092 (H) × 3000 (V)	
Imaging area H x V (opposing corner)         4.97 × 3.73 (6.21 mm)         8.45 × 7.07 (11.01 mm)         14.12 × 10.35 (17.5 mm)	
Pixel size         6.9 (μm) × 6.9 (μm)         3.45 (μm) × 3.45 (μm)	
Shutter function         Electronic shutter; Shutter speeds can be set from 1 ms to 100 ms.         Electronic shutter; Shutter speeds can be set from	m 15 μs to 100 ms
Partial function 4 to 540 lines (4-line increments) 4 to 2048 lines (4-line increments) 4 to 3000 lines (4-line incre	ements)
Frame rate (Image Acquisition Time *1)         523.6 fps (1.9 ms)         97.2 fps (10.3 ms) *2         40.1 fps (24.9 ms) *2	
Lens mounting C mount	
Field of vision,	
installation distance Selecting a lens according to the field of vision and installation distance	
Installation distance         Selecting a tens according to the field of vision and installation distance           Ambient temperature range         Operating: 0 to 50 °C, Storage: -25 to 65 °C (with no icing or condensation)         Operating: 0 to 40 °C, Storage: -25 to 65 °C (with no icing or condensation)	
Installation distance         Selecting a tens according to the field of vision and installation distance           Ambient temperature range         Operating: 0 to 50 °C, Storage: -25 to 65 °C         Operating: 0 to 40 °C, Storage: -25 to 65 °C	
Installation distance         Selecting a tens according to the field of vision and installation distance           Ambient temperature range         Operating: 0 to 50 °C, Storage: -25 to 65 °C (with no icing or condensation)         Operating: 0 to 40 °C, Storage: -25 to 65 °C (with no icing or condensation)	

\*1 The image acquisition time does not include the image conversion processing time of the sensor controller.
\*2 Frame rate in high speed mode when the camera is connected using two camera cables.

### **Digital CMOS Cameras**

Model	FH-SM05R	FH-SC05R	FH-SM21R	FH-SC21R	FZ-S5M3	FZ-SC5M3	
Image Elements	CMOS image elements	(1/2.5-inch equivalent)	CMOS image element	CMOS image elements (1-inch equivalent)		CMOS image elements (2/3-inch equivalent)	
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color	
Effective Pixels	2592 (H) × 1944 (V)		5544 (H) × 3692 (V)		2448 (H) × 2048 (V)		
Imaging area $H \times V$ (opposing corner)	5.70 × 4.28 (7.13 mm	)	13.31 × 8.86 (16.00 n	nm)	8.45 × 7.07 (11.01 m	m)	
Pixel Size	2.2 (μm) × 2.2 (μm)		2.4 (μm) × 2.4 (μm)		3.45 (μm) × 3.45 (μm	ı)	
Scan Type	Progressive						
Shutter Method	Rolling shutter (Globa	I reset mode supported	)		Global shutter		
Shutter Function	Electronic shutter; Shutter speeds can be set from 500 to 10000 ms in multiples of 50 μs		Electronic shutter; Shutter speeds can be set from 50 $\mu s$ to 100 ms.		Electronic shutter; Shutter speeds can be set from 20 $\mu s$ to 100 ms.		
Partial function	4 to 1944 lines (2-line	increments)	1848 to 3692 lines		4 to 2048 lines		
Frame rate (Image Acquisition Time *)	14 fps (71.7ms)		23.5 fps (42.6ms)		25.6 fps (38.2ms)		
Lens Mounting	C mount						
Field of vision, Installation distance	Selecting a lens according to the field of vision and installation distance						
Ambient temperature range			Operating: 0 to +40°C Storage: -20 to 65°C (with no icing or condensation)		Operating: 0 to +40°C Storage: -30 to 65°C (with no icing or cond		
Ambient humidity range	Operating: 35 to 85%	RH, Storage: 35 to 85%	RH (with no condense	ition)			
Weight	Approx. 52 g		Approx. 85 g				
Accessories	Instruction Sheet		Instruction Sheet, Ge	neral Compliance Inforr	mation and Instructions	s for EU	

\* The image acquisition time does not include the image conversion processing time of the sensor controller.

40

### **Digital CCD Cameras**

Model	FZ-S	FZ-SC	FZ-S2M	FZ-SC2M	FZ-S5M2
Image elements	Interline transfer readin CCD image elements (		Interline transfer rea CCD image element	ding all pixels, s (1/1.8-inch equivalent)	Interline transfer reading all pixels, CCD image elements (2/3-inch equivalent)
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome
Effective pixels	640 (H) × 480 (V)		1600 (H) × 1200 (V)	· ·	2448 (H) × 2044 (V)
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0mm)		7.1×5.4 (8.9mm)		8.4×7.1 (11mm)
Pixel size	7.4 (μm) × 7.4 (μm)		4.4 (µm) $\times$ 4.4 (µm)	4.4 (μm) × 4.4 (μm)	
Shutter function	Electronic shutter; select shutter speeds from 20 µs to 100 ms				
Partial function	12 to 480 lines		12 to 1200 lines	12 to 1200 lines	
Frame rate (Image Acquisition Time *)	80 fps (12.5 ms)		30 fps (33.3 ms)	30 fps (33.3 ms)	
Lens mounting	C mount				
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance				
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C (with no icing or condensation)		Storage: -25 to 65 °C	Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)	
Ambient humidity range	Operating and storage:	35% to 85% (with no co	ondensation)		
Weight	Approx. 55 g		Approx. 76 g		Approx. 140 g
Accessories	Instruction manual				ł

\* The image acquisition time does not include the image conversion processing time of the sensor controller.

### **Small CCD Digital Cameras**

Model	FZ-SF	FZ-SFC	FZ-SP	FZ-SPC		
Image elements	Interline transfer reading all pixel	nterline transfer reading all pixels, CCD image elements (1/3-inch equivalent)				
Color/Monochrome	Monochrome	Color	Monochrome	Color		
Effective pixels	640 (H) × 480 (V)	·	-			
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0mm)	8 × 3.6 (6.0mm)				
Pixel size	7.4 ( $\mu$ m) $\times$ 7.4 ( $\mu$ m)					
Shutter function	Electronic shutter; select shutter	Electronic shutter; select shutter speeds from 20 μm to 100 ms				
Partial function	12 to 480 lines					
Frame rate (Image Acquisition Time *)	80 fps (12.5ms)					
Lens mounting	Special mount (M10.5 P0.5)					
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance					
Ambient temperature range	Operating: 0 to 50 °C (camera amp) 0 to 45 °C (camera head) Storage: -25 to 65 °C (with no icing or condensation)					
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)					
Weight	Approx. 150 g					
Accessories	Instruction manual, installation bracket, Four mounting brackets (M2)					

\* The image acquisition time does not include the image conversion processing time of the sensor controller.

### **High-speed Digital CCD Cameras**

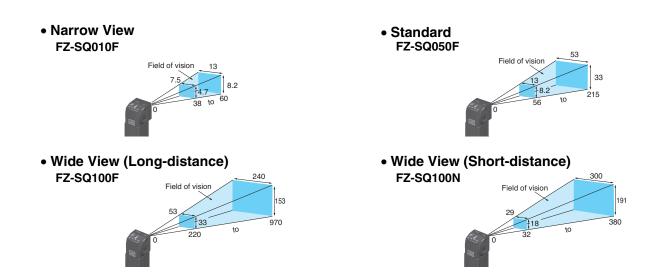
Model	FZ-SH	FZ-SHC		
Image elements	Interline transfer reading all pixels, CCD image elements (1/3-inch equivalent)			
Color/Monochrome	Monochrome Color			
Effective pixels	640 (H) × 480 (V)			
Imaging area H x V (opposing corner)	4.8×3.6 (6.0mm)			
Pixel size	7.4 (μm) × 7.4 (μm)			
Shutter function	Electronic shutter; select shutter speeds from 1/10 to 1/50,000 s			
Partial function	12 to 480 lines			
Frame rate (Image Acquisition Time *)	204 fps (4.9ms)			
Field of vision, installation distance	Selecting a lens according to the field of vision and installation dis- tance			
Ambient temperature range	Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)			
Weight	Approx. 105 g			
Accessories	Instruction manual			

\* The image acquisition time does not include the image conversion processing time of the sensor controller.

### Intelligent Compact Digital CMOS Cameras

Model	FZ-SQ010F	FZ-SQ050F	FZ-SQ100F	FZ-SQ100N			
Image elements	CMOS color image elements (1/	CMOS color image elements (1/3-inch equivalent)					
Color/Monochrome	Color	Color					
Effective pixels	752 (H) × 480 (V)						
Imaging area H x V (opposing corner)	4.51 × 2.88 (5.35mm)						
Pixel size	6.0 (μm) × 6.0 (μm)	5.0 (μm) × 6.0 (μm)					
Shutter function	1/250 to 1/32,258						
Partial function	8 to 480 lines						
Frame rate (Image Acquisition Time *1)	60 fps (16.7 ms)						
Field of vision	$7.5 \times 4.7$ to $13 \times 8.2$ mm	$13\times8.2$ to $53\times33$ mm	$53\times33$ to $240\times153$ mm	$29 \times 18$ to $300 \times 191$ mm			
Installation distance	38 to 60 mm	56 to 215 mm	220 to 970 mm	32 to 380 mm			
LED class *2	Risk Group2						
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C						
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)						
Weight	Approx. 150 g	Approx. 150 g Approx. 140 g					
Accessories	Mounting bracket (FQ-XL), polar	izing filter attachment (FQ-XF	), instruction manual and warning	label			

\*1 The image acquisition time does not include the image conversion processing time of the sensor controller.
 \*2 Applicable standards: IEC62471-2



## **Ratings and Specifications (Cable, Monitor)**

### Camera Cables

Model	FZ-VS3 (2 m)	FZ-VSB3 (2 m)	FZ-VSL3 (2 m)	FZ-VSLB3 (2 m)	
Туре	Standard	Bend resistant	Right-angle	Bend resistant Right-angle	
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times				
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)				
Ambient humidity range	Pe Operation and storage: 40 to 70%RH (with no condensation)				
Ambient atmosphere	No corrosive gases				
Material	Cable sheath, connector: PVC				
Minimum bending radius	69mm	69mm	69mm	69mm	
Weight	Approx. 170 g	Approx. 180 g	Approx. 170 g	Approx. 180 g	

#### **Cable Extension Unit**

Model	FZ-VSJ
Power supply voltage *1	11.5 to 13.5 VDC
Current consumption *2	1.5 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 240 g
Accessories	Instruction Sheet and 4 mounting screws

\*1 A 12-VDC power supply must be provided to the Cable Extension Unit when connecting the Intelligent Compact Camera, or the Lighting Controller.

\*2 The current consumption shows when connecting the Cable Extension Unit to an external power supply.

#### **Touch Panel Monitor**

#### Long-distance Camera Cables

Model	FZ-VS4 (15 m)	FZ-VSL4 (15 m)		
Туре	Standard	Right-angle		
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times			
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)			
Ambient atmosphere	ohere No corrosive gases			
Material	Cable sheath, connector: PVC			
Minimum bending radius	78 mm			
Weight	Approx. 1400 g			

### **Encoder Cable**

Model	FH-VR
Vibration resistiveness	10 to 150 Hz single amplitude 0.1 mm 3 directions, 8 strokes, 10 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -10 to 60 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable Jacket: Heat, oil and flame resistant PVC Connector: polycarbonate resin
Minimum bending radius	65 mm
Weight	Approx. 104 g

Model		FH-MT12				
	Display area	12.1 inch				
	Resolution	1024 (V) × 768 (H)				
	Number of color	16,700,000 colors (8 bit/color)				
	Brightness	500cd/m <sup>2</sup> (Typ)				
Major Function	Contrast Ratio	600:1 (Typ)				
Major Function External interface Ratings Operating Environment	Viewing angle	Left and right: each 80°, upward: 80°, downward: 60°				
	Backlight Unit	LED, edge-light				
	Backlight lifetime	About 100,000hour				
	Touch panel	4wire resistive touch screen				
External interface	Video input	analog RGB				
	Tauch manual simul	USB				
	Touch panel signal	RS-232C				
Ratings	Power supply voltage	24 VDC (21.6 to 26.4 VDC)				
	Current consumption	0.5A				
naungs	Insulation resistance	Between DC power supply and Touch Panel Monitor FG: 20 M $\Omega$ or higher (rated vol age 250 V)				
eternal interface atings perating peration	Ambient temperature range	Operating: 0 to 50°C, Storage: -20 to +65°C (with no icing or condensation)				
	Ambient humidity range	Operating and Storage: 20 to 85 %RH (with no icing or condensation)				
Operating	Ambient environment	No corrosive gas				
environment	Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm (Max. acceleration 15 m/s <sup>2</sup> ) 10 times for 8 minutes for each three direction				
	Degree of protection	Panel mounting: IP65 on the front				
Operation	L	Touch pen				
	Mounting	Panel mounting, VESA mounting				
Structure	Weight	Approx.2.6 kg				
	Material	Front panel: PC/PBT, Front Sheet: PET, Rear case: SUS				

### **Touch Panel Monitor Cables**

Model	FH-VMDA (2 m)	FH-VUAB (2 m)	XW2Z-200PP-1 (2 m)				
Cable type	DVI-Analog Conversion Cable USB Cable RS-232C		RS-232C Cable				
Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm,	10 to 150 Hz, one-side amplitude 0.1 mm, 10 times for 8 minutes for each three direction					
Ambient Temperature	Operating Condition: 0 to 50°C, Storage C	Operating Condition: 0 to 50°C, Storage Condition: -10 to 60°C (with no icing or condensation)					
Ambient Humidity	Operating Condition: 35 to 85%RH, Storage	Operating Condition: 35 to 85%RH, Storage Condition: 35 to 85%RH (with no icing or condensation)					
Ambient environment	No corrosive gases						
Material	Cable outer sheath, Connector: PVC		Cable outer sheath: PVC, Connector: ABS/Ni Plating				
Minimum bend radius	linimum bend radius 36 mm 2		59 mm				
Weight	Approx.220 g	Approx.75 g	Approx.162 g				

#### **LCD Monitor**

Model	FZ-M08
Size	8.4 inches
Туре	Liquid crystal color TFT
Resolution	1,024 × 768 dots
Input signal	Analog RGB video input, 1 channel
Power supply voltage	21.6 to 26.4 VDC
Current consumption	Approx. 0.7 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no con- densation)
Weight	Approx. 1.2 kg
Accessories	Instruction Sheet and 4 mounting brackets

#### **LCD Monitor Cable**

Model	FZ-VM				
Vibration resistiveness	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times				
Ambient temperature range	Operation: 0 to 50 °C; Storage: -20 to 65 °C (with no icing or condensation)				
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)				
Ambient atmosphere	No corrosive gases				
Material	Cable sheath: heat-resistant PVC Connector: PVC				
Minimum bending radius	75 mm				
Weight	Approx. 170 g				

Note: When you connect a LCD Monitor FZ-M08 to FH sensor controller, please use it in combination with a DVI-I -RGB Conversion Connector FH-VMRGB.

## **EtherCAT Communications Specifications**

Item		Specifications			
Communications standard		IEC61158 Type 12			
Physical layer		100 BASE-TX (IEEE802.3)			
Modulation		Base band			
Baud rate		100 Mbps			
Topology		Depends on the specifications of the EtherCAT master.			
Transmission Media		Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)			
Transmission Distance		Distance between nodes: 100 m or less			
Node address setting		00 to 99			
External connection terminals	6	$RJ45 \times 2$ (shielded) IN: EtherCAT input data, OUT: EtherCAT output data			
Ormal/manaius DDO data siasa	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *			
Send/receive PDO data sizes	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *			
Mailhau data sina	Input	512 bytes			
Mailbox data size	Output	512 bytes			
Mailbox	•	Emergency messages, SDO requests, and SDO information			
Refreshing methods		I/O-synchronized refreshing (DC)			

This depends on the upper limit of the master.

### **Version Information**

#### FH Series and Programming Devices

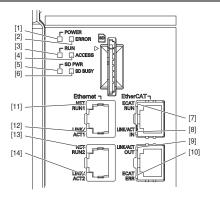
Use the latest version of Sysmac Studio Standard Edition/Vision Edition.

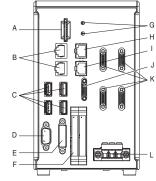
FH Series	Version of FH Series Corresponding version of Sysmac Studio Standard Edition/Vision Edition				
	Version 6.11	Will be supported soon. (Add the ESI file* until it is supported.)			
	Version 5.72	Supported by version 1.18 or higher.			
	Version 5.71	Supported by version 1.18 or higher.			
FH-5050 (-□) FH-3050 (-□)	Version 5.60	Supported by version 1.15 or higher.			
FH-2050 (-□)	Version 5.50	Supported by version 1.14.89 or higher.			
FH-1050 (-🗆)	Version 5.30	Supported by version 1.10.80 or higher.			
	Version 5.20	Supported by version 1.10 or higher.			
	Version 5.10	Supported by version 1.07.43 or higher.			
	Version 5.00	Supported by version 1.07 or higher. Not supported by version 1.06 or lower.			

\* Please add the ESI file to the Sysmac Studio to use the FH-series Sensor Controller version 6.10 with the Sysmac Studio. Please contact your OMRON sales representative regarding the ESI file.

### **Components and Functions**

Sensor Controllers High-speed, Large-capacity Controller Standard Controller (4-camera type)





	Name	Description				
[1]	POWER LED	Lit while power is ON.				
[2]	ERROR LED	Lit when an error has occurred.				
[3]	RUN LED Lit while the layout turned on output setting is displayed.					
[4]	ACCESS LED Blinks while the internal nonvolatile memory is accessed.					
[5]	SD POWER LED	Blinks while power is supplied to the SD memory card and the card is usable.				
[6]	SD BUSY LED	Blinks while the SD memory card is accessed.				
[7]	EtherCAT RUN LED	Lit while EtherCAT communications are usable.				
[8]	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications.				
[9]	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications.				
[10]	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.				
[11]	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.				
[12]	EtherNet LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.				
[13]	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.				
[14]	EtherNet LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.				

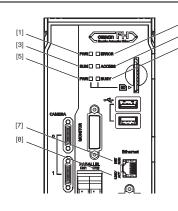
	Name	Description					
А	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation Otherwise measurement time may be affected or data may be destroyed.					
		Connect an EtherNet device.					
		FH-1050/FH-3050 Series         FH-1050-10/FH-1050-20           FH-1050/FH-3050 Series         FH-3050-10/FH-3050-20           FH-2050 Series/FH-5050 Series         FH-2050 Series/FH-5050 Series					
В	EtherNet connector	Ethernet port, Ethernet port, and PROFINET port are sharing use.					
С	USB connector	Connect a USB device. Do not plug or unplug it during measurement operation. Otherwise measurement time may be affected or data may be destroyed.					
D	RS-232C connector	Connect an external device such as a programmable controller.					
E	DVI-I connector	Connect a monitor.					
F	I/O connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.					
G	EtherCAT address setup volume	Used to set a node address (00 to 99) as an EtherCAT communication device.					
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.					
I	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.					
J	Encoder connector	Connect an encoder.					
К	Camera connector	Connect cameras.					
L	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground line. Be sure to ground the controller alone.					

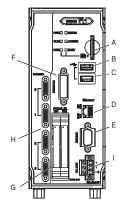
\* Use the attachment power terminal connector (male) of FH-XCN series.

For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual (Z366).

### Lite Controllers

(4-camera type)





	LED name	Description
[1]	PWR LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD PWR LED	Lit while power is supplied to the SD memory card and the card is usable.
[6]	SD BUSY LED	Lit when access to the SD memory card.
[7]	Ethernet NET RUN LED	Lit while Ethernet communications are usable.
[8]	Ethernet LINK/ACT LED	Blinks when connected with an Ethernet device, and blinks while performing communications.

[4]

	Connector name	Description				
А	SD memory card installation connector	stall the SD memory card. Do not plug or unplug the SD memory card during measurement operation. herwise measurement time may be affected or data may be destroyed.				
В	USB 2.0 connector Connects to USB 2.0. Do not insert or remove during loading or writing of measurement or data The measurement time can be longer or data can be damaged.					
С	USB 3.0 connector	Connects to USB 3.0. Do not insert or remove during loading or writing of measurement or data. The measurement time can be longer or data can be damaged. USB 3.0 has a high ability to supply the bus power. Use the Sensor Controller by combining USB 3.0, faster transport can be realized.				
D	Ethernet connector	Connect an Ethernet device. Ethernet port, EtherNet/IP port, and PROFINET port are sharing use.				
E	RS-232C connector	Connect an external device such as a programmable controller.				
F	DVI-I connector	Connect a monitor.				
G	Parallel connector (control lines, data lines) Connect the controller to external devices such as a sync sensor.					
н	Camera connector	Connect a camera.				
I	Power supply terminal connector Connect a Camera. Power supply terminal connector Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground I Be sure to ground the FH Sensor Controller alone.					

\* Use the attachment power terminal connector (male) of FH-XCN-L series. For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual(Z366).

### **Processing Items**

Group	Icon		Processing Item F		Corresponding Page in the Group Catalog			Processing Item	Corresponding Page in the Catalog
	•	Search	Used to identify the shapes and calculate the position of measurement objects.	P16		M.	Camera Image Input FH	To input images from cameras. And set up the conditions to input images from camer- as. (For FH Sensor Controllers only)	
	1	Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.	P16	-		Camera Image	Create high-dynamic range images by ac- quiring several images with different con-	•
	*	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.	P16		Lite	Input HDR Camera Image	ditions. HDR function for FZ-SQ Intelligent Com-	
	••	ECM Search	Used to search the similar part of model form input image. Detect the evaluation			M.	Input HDRLite Photometric Stereo Image	pact Cameras. Capture images under different illumina- tion directions using a photometric stereo	
	-	EC Circle Search	value and position. Extract circles using "round " shape infor- mation and get position, radius and quan-			<u> </u>	Input	light. To switch the cameras used for measure-	
			tity in high preciseness. Used to search the similar part of model		Input Image	1	Camera Switch	ment. Not input images from cameras again. To switch the images used for measure-	
		Shape Search II	from input image regardless of environ- mental changes. Detect the evaluation value and position.	P16	-	i.	Measurement Image Switching	ment. Not input images from camera again.	
	H A	Shape Search III	Robust detection of positions is possible at high-speed and with high precision incor- porating environmental fluctuations, such as differences in individual shapes of the workpieces, pose fluctuations, noise su-	P16		(종) (종) (종) (종)	Multi-trigger Imaging	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measure- ment for each image. Insert the Multi-trig- ger Imaging to the top of the flow.	
		EC Corner	perimposition and shielding. This processing item measures a corner position (corner) of a workpiece.			······································	Multi-trigger	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measure-	
	-1	Ec Cross	The center position of a crosshair shape is measured using the lines created by the			비를 비슷	Imaging Task	ment for each image. Insert this process- ing item to the top of the processing which requires imaging for multiple times.	
	*		edge information on each side of the crosshair. Used when various kinds of products on			<b></b>	Position Compensation	Used when positions are differed. Correct measurement is performed by correcting position of input images	P18
		Classification	the assembly line need to be sorted and identified.	P16			Filtering	position of input images. Used for processing images input from cameras in order to make them easier to	P18
	-	Edge Position	Measure position of measurement objects according to the color change in measurement area.	P16			Backgrond	be measured. To enhance contrast of images by extract-	P18
		Edge Pitch	Detect edges by color change in measure- ment area. Used for calculating number of pins of IC and connectors.	P16	-		Suppression Brightness	ing color in specified brightness. Track brightness change of entire screen and remove gradual brightness	P18
	ŧŧ	Scan Edge	Measure peak/bottom edge position of workpieces according to the color change	P16			Correct Filter Color Gray Filter	change such as uneven brightness. Color image is converted into monochrome im-	P18
		Position Scan Edge	in separated measurement area. Measure max/min/average width of work-	D10			Extract Color	ages to emphasize specific color. Convert color image to color extracted im-	P18
	*	Width Circular Scan	pieces according to the color change in separated measurement area. Measure center axis, diameter and radius	P16	-		Filter Anti Color	age or binary image. To remove the irregular color/pattern by uniformizing max.2 specified colors.	P18
	Č Š	Edge Position Circular Scan	of circular workpieces. Measure center axis, width and thickness	P16	Compensate		Shading Stripes Removal	Remove the background pattern of vertical, horizontal and diagonal	P19
leasurement	$\Diamond$	Edge Width	of ring workpieces. Calculate approximate lines from the edge	P16	image		Filter II Polar	stripes. Rectify the image by polar transformation.	
		Intersection	information on two sides of a square work- piece to measure the angle formed at the intersection of the two lines.	P16			Transformation	Useful for OCR or pattern inspection print- ed on circle. Rectify the trapezoidal deformed	P18
	*	Color Data	Used for detecting presence and mixed varieties of products by using color aver-		- - -		Trapezoidal Correction	How the alignment marks would move on	P18
		Gravity and Area	age and deviation. Used to measure area, center of gravity of workpices by extracting the color to be			<u>+</u> /	Machine Simulator	the image when each stage or robot axis is controlled can be checked.	
		Labeling	measured. Used to measure number, area and gravi- ty of workpieces by extracting registered				Image Subtraction	The registered model image and measurement image are compared and only the different pixels are	
	<b>*</b>	Labeling	color. Selecting one region of extracted Label-					extracted and converted to an image. Process the images acquired from camer- as in order to make them easier to mea-	
		Label Data	ing, and get that measurement. Area and Gravity position can be got and judged. Used for appearance measurement of				Advanced filter	sure. This processing item consolidates existing image conversion filtering into one processing item and adds extra functions.	P18
	×	Defect	plain-color measurement objects such as defects, stains and burrs.	P16			Panorama	Combine multiple image to create one big image.	P18
	×	Precise Defect	Check the defect on the object. Parame- ters for extraction defect can be set pre- cisely.	P16		-O¢	Unit Macro	Advanced arithmetic processing can be easily incorporated into workflow as Unit	P20
		Fine Matching	Difference can be detected by overlapping and comparing (matching) registered fine	P16			Unit Calculation	Macro processing items. This function is convenient when the user wants to calculate a value using an original	
	AB	Character	images with input images. Recognize character according correlation search with model image registered in	P17			Macro	calculation formula or change the set val- ue or system data of a processing item.	P20
		Inspect Date Verification	[Model Dictionary]. Reading character string is verified with in-	P17			Calculation	Used when using the judge results and measured values of ProcItem which are registered in processing units.	
	Date 08-02-1		ternal date. Register character pattern as dictionary.	P17		*	Line Regression	Used for calculating regression line from plural measurement coodinate.	
	A	Model Dictionary	The pattern is used in [Character Inspec- tion]. Recognize 2D code and display where the			Ċ,	Circle Regression	Used for calculating regression circle from plural measurement coordinate.	
		2DCode II *1	code quality is poor. Recognize 2D code and display where the	P17	Support	<b>f</b>	Precise Calibration	Used for calibration corresponding to trape- zoidal distortion and lens distortion.	P15
	<u></u>	2DCode *2 Barcode *3	code quality is poor. Recognize barcode, verify and output de-	P17	measurement	User	User Data	Used for setting of the data that can be used as common constants and variables in scene group data.	P21
		OCR	coded characters. Recognize and read characters in	P17 P17			Set Unit Data	Used to change the ProcItem data (setting parameters,etc.) that has been set up in a	
		OCR User	images as character information. Register dictionary data to use for OCR.	P17		<b>1</b>	Get Unit Data	scene. Used to get one data (measured results, setting parameters,etc.) of ProcItem that	
		Dictionary Circle Angle	Used for calculating angle of inclination of circular measurement objects.				Set Unit Figure	has been set up in a scene. Used for re-setting the figure data (model,	
		Glue Bead	You can inspect coating of a specified col- or for gaps or runoffs along the coating	P17		1950 1957	Get Unit Figure	measurement area ) registered in an unit. Used for get the figure data (model, mea-	
		Inspection	path.				Soc Shire i yure	surement area ) registered in an unit. Used for displaying the information about re-	

Group	lcon	Processing Item		Corresponding Page in the Catalog	Group	lcon	Processing Item		Corresponding Page in the Catalog
Support measure- ment		Image Logging	Used for saving the measurement images to the memory and USB memory.			-	Conditional Branch	Used where more than two kinds of prod- ucts on the production line need to detect- ed separately.	•
	∕⊒→	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.			± 00-	End	This ProcItem must be set up as the last processing unit of a branch.	
	5	Data Logging	Used for saving the measurement data to the memory and USB memory.			<b>1</b>	DI Branch	Same as ProcItem "Branch". But you can change the targets of conditional branching via external inputs.	
	۵	Elapsed Time	Used for calculating the elapsed time since the measurement trigger input. Processing is stopped only at the set time. The			-→	Control Flow Normal	Set the measurement flow processing into the wait state in which the specific no-pro- tocol command can be executed.	
		Wait	standby time is set by the unit of [ms]. Focus setting is supported.	P15		₽	Control Flow PLC Link	Set the measurement flow processing into the wait state in which the specific PLC	
	<b>4</b>	Focus Iris	Focus and aperture setting is supported.	P15			Control Flow	Link command can be executed. Set the measurement flow processing into the wait state in which the specific parallel	
		Parallelize	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time.				Parallel Control Flow Fieldbus	command can be executed. Set the measurement flow processing into the wait state in which the specific Field- bus command can be executed.	
	LB.		This processing item is placed at the top of processing to be performed in parallel.			SWITCH	Selective Branch	Easily branch to multiple destinations.	
		Parallelize Task	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed immediate-		Branch	<b></b>	Conditional Execution (If)	The measurement flow is divided accord- ing to the comparison result obtained us- ing the set expressions and conditions.	
		Statistics	ly before processing to be performed in parallel between Parallelize and Parallel- ize End. Used when you need to calculate an aver-			5	Conditional Execution (Else)	Insert between the Conditional Execution (If) processing item and End If processing item. The measurement flow is divided ac- cording to the comparison result obtained using the set expressions and conditions.	
		Referrence Calib	age of multiple measurement results. Calibration data and distortion compensa- tion data held under other processing			¢٦	Loop	The set processes are repeated until the loop count reaches the specified number, and then the next process starts.	
		Position Data Calculation	items can be referenced. The specified position angle is calculated from the measured positions.	P14		¢2	Loop Suspension	Insert between the Loop processing item and End Loop processing item. Used to stop the loop before the loop count reach-	
	<u>·+/</u> /	Stage Data	Sets and stores data related to stages.					es the specified number. Used to set conditions. The measurement	
	<b>PD</b>	Robot Data	Sets and stores data related to robots.			\$	Select Execution (Select)	flow is divided according to the compari- son result obtained using the conditions given by expressions.	
		Vision Master Calibration	This processing item automatically calcu- lates the entire axis movement amount of the control equipment necessary for cali- bration.	P15		<b>^</b>	Select Execution (Case)	Used to make a judgment. The measure- ment flow is divided according to the com- parison result obtained using the conditions given by expressions.	
		PLC Mastoer Calibration	Calibration data is created using a com- munication command from PLC.	P15	Output result	31.32.33 41.4	Result Output (I/ O)	Output data to the external devices such as a programmable controller or a PC via PLC Link, Parallel interface, Fieldbus in- terface (EtherCAT, EtherNet/IP (other than message communication), PROFI-	
	ţ	Convert Position Data	The position angle after the specified axis movement is calculated.	P14					
	+/	Movement Single Position	The axis movement that is required to match the measured position angle to the reference position angle is calculated.	P14				NET). Output data to the external devices such as a programmable controller or a PC with	
		Movement Multi Points	The axis movements that are required to match the measured position angles to the corresponding reference position angles are calculated.	P14		123,ABC	Result Output (Message)	non-procedure mode via the serial inter- face or EtherNet/IP (message communi- cation). This processing item allows you to save the logging data as a ".csv" file into	
	+	Detection Point	Obtains position/angle information by re- ferring to the coordinate values measured with the Measurement Processing Unit.				Data Output	the Sensor Controller as well. Used when you need to output data to the external devices such as PLC or PC via	
	+\$	Manual Position Setting	Used to change the measurement coordi- nates X and Y of the measurement pro- cessing unit.				Parallel Data Output	serial ports. Used when you need to output data to the external devices such as PLC or PC via	
		Camera Calibration	By setting the camera calibration, the measurement result can be converted and output as actual dimensions.	-		<b>1</b>	Parallel Judgement	parallel ports. Used when you need to output judgement results to the external devices such as PLC or PC via parallel ports.	
	<b>₽</b>	Data Save	The set data can be saved in the controller main unit or as scene data. The data is held even after the FH/FZ power is turned off.				Output Fieldbus Data Output	Outputs data to an external device, such as a Programmable Controller, through a fieldbus interface.	
	<u>, </u>	Conveyor Calibration	Conveyor Calibration is used to calibrate camera, conveyor, and robots for conveyor tracking application.		Display result	OK	Result Display	Used for displaying the texts or the figures in the camera image.	
		Scene	The specified scene is copied to the cur- rent scene.				Display Image File	Display selected image file.	
	®	System Information	Obtain system information (e.g., memory and disk space and I/O input signal status)			NG	Display Last NG Image	Display the last NG images.	
			of the Sensor Controller.	<u> </u>			Conveyor Panorama Display	Display images of the tracking area as a panoramic image.	
							Display Image Hold	Processing item to retain images, includ- ing measurement results.	

 
 Display Image Hold
 Processing item to retain images, includ-ing measurement results.

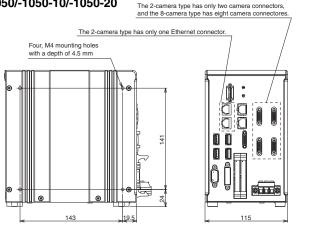
 2D Codes that can be read : Data Matrix (ECC200), 2D Codes that can be read : Data Matrix (ECC200), 2D Codes that can be read : JAN/EAN/UPC (including add-on codes), Code 39, Codabar (NW-7), ITF (Interleaved 2 of 5), Code 93, Code 128, GS1-128, GS1 DataBar (RSS-14 / RSS Limited / RSS Expanded), Pharmacode
 \*1 \*2 \*3

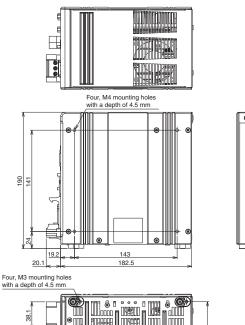
### **Dimensions**

#### **Sensor Controllers**

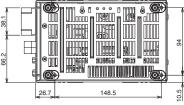
#### High-speed, Large-capacity Controllers/Standard Controllers

FH-5050/-5050-10/-5050-20 FH-2050/-2050-10/-2050-20 FH-3050/-3050-10/-3050-20 FH-1050/-1050-10/-1050-20

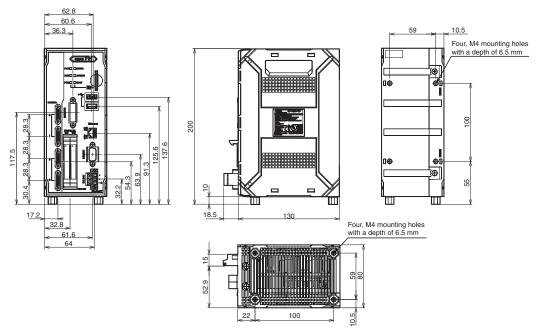






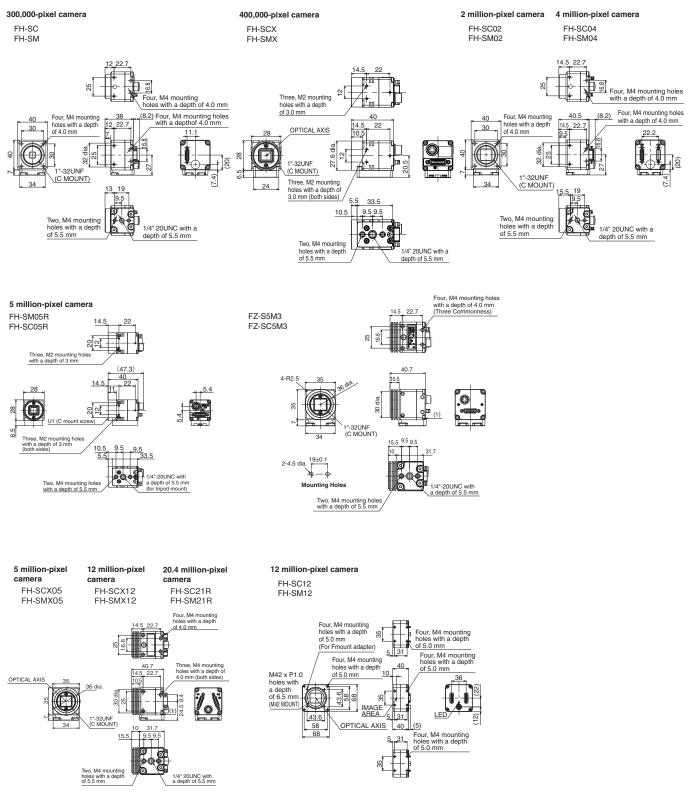


**Lite Controllers** FH-L550/-L550-10

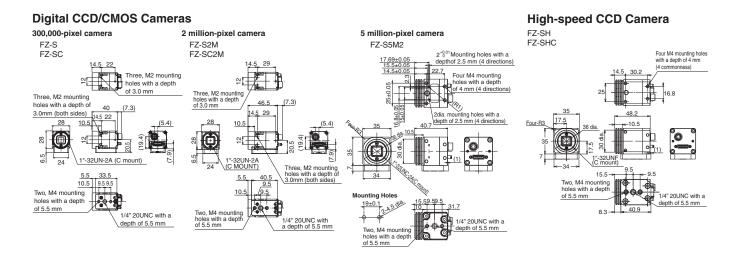


#### Cameras

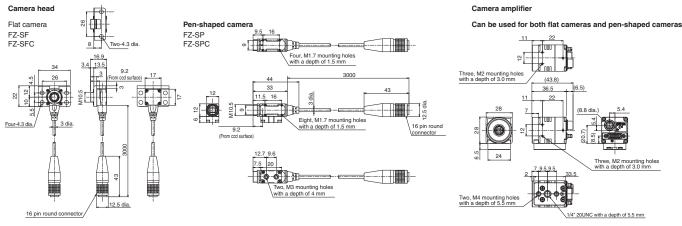
#### High-speed Digital CMOS Camera/Digital CMOS Camera



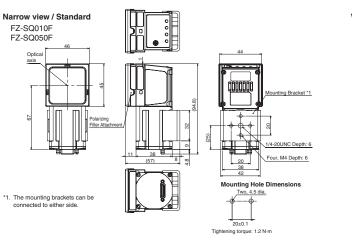
50

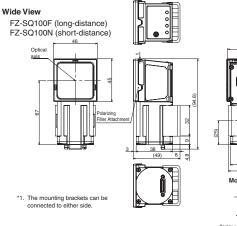


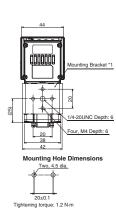




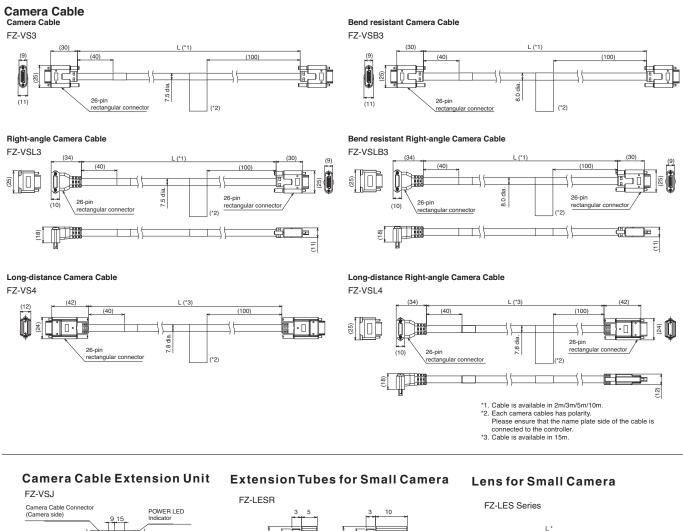
#### Intelligent Compact Digital CMOS Cameras

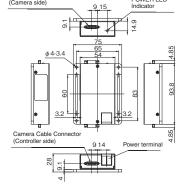


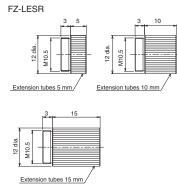


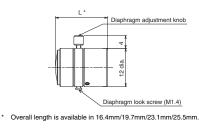


### Cables

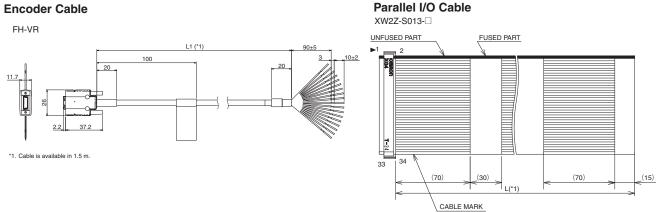








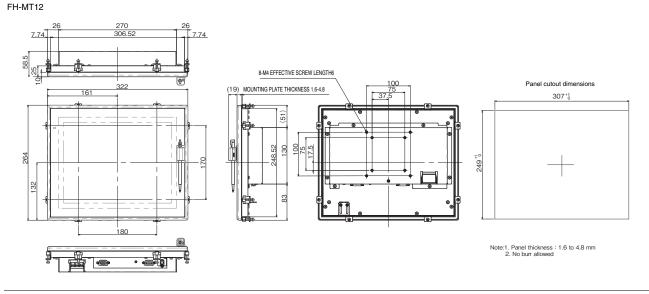
#### **Encoder Cable**



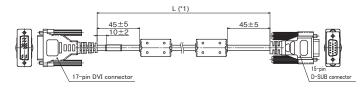
\*1. Cable is available in 2m/5m

### **Touch Panel Monitor**

#### Panel cutout dimensions

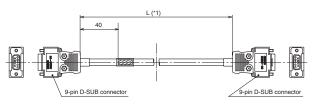


#### **DVI-Analog Conversion Cable for Touch Panel Monitor** FH-VMDA



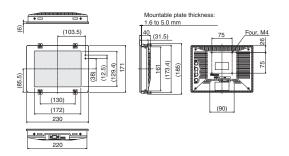
#### **RS-232C Cable for Touch Panel Monitor**

XW2Z-DDPP-1



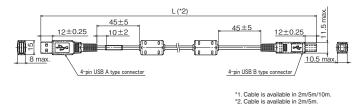
#### **LCD** Monitor

FZ-M08



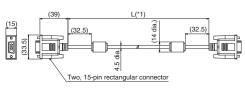
#### **USB Cable for Touch Panel Monitor**

FH-VUAB



#### **LCD Monitor Cable**

FZ-VM

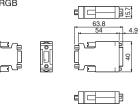


\*1. Cable is available in 2m/5m.

37

#### **DVI-I -RGB Conversion Connector**

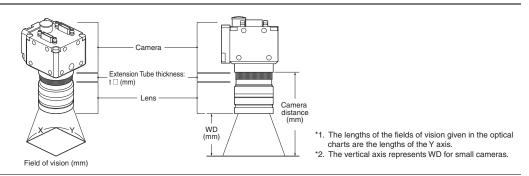




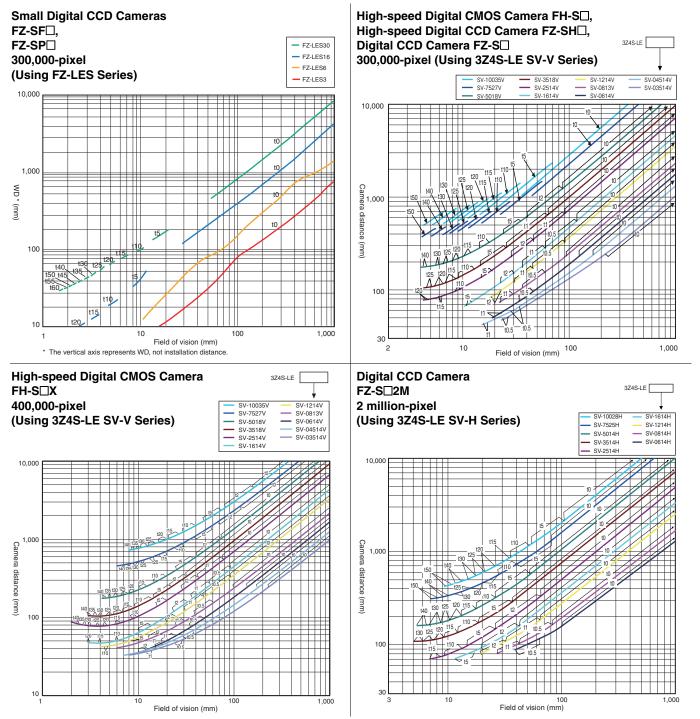
## FH-Series Optical Chart

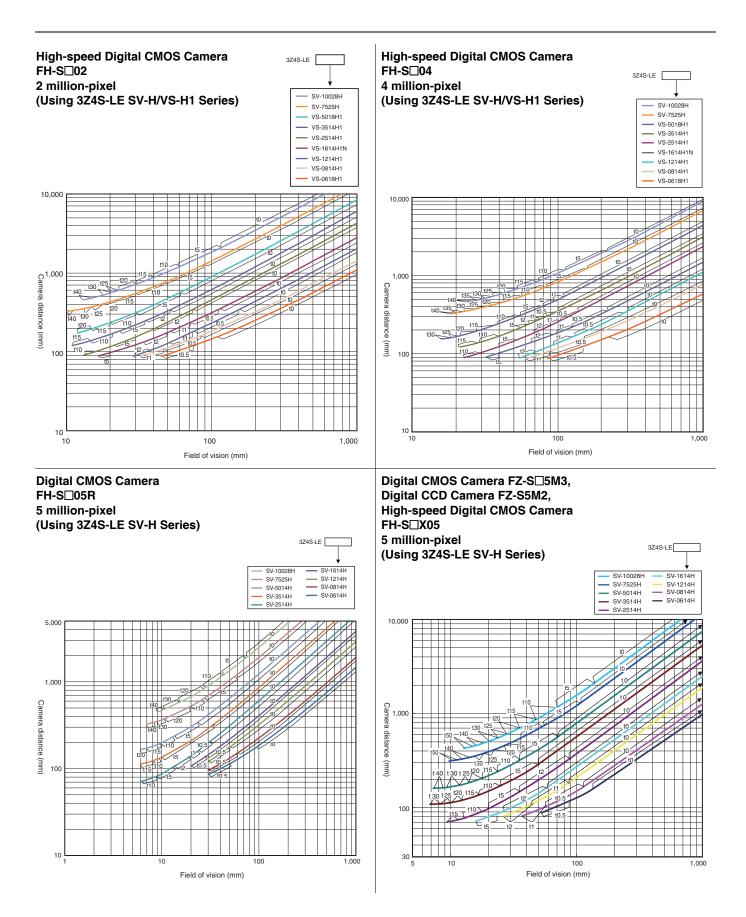
#### **Meaning of Optical Chart**

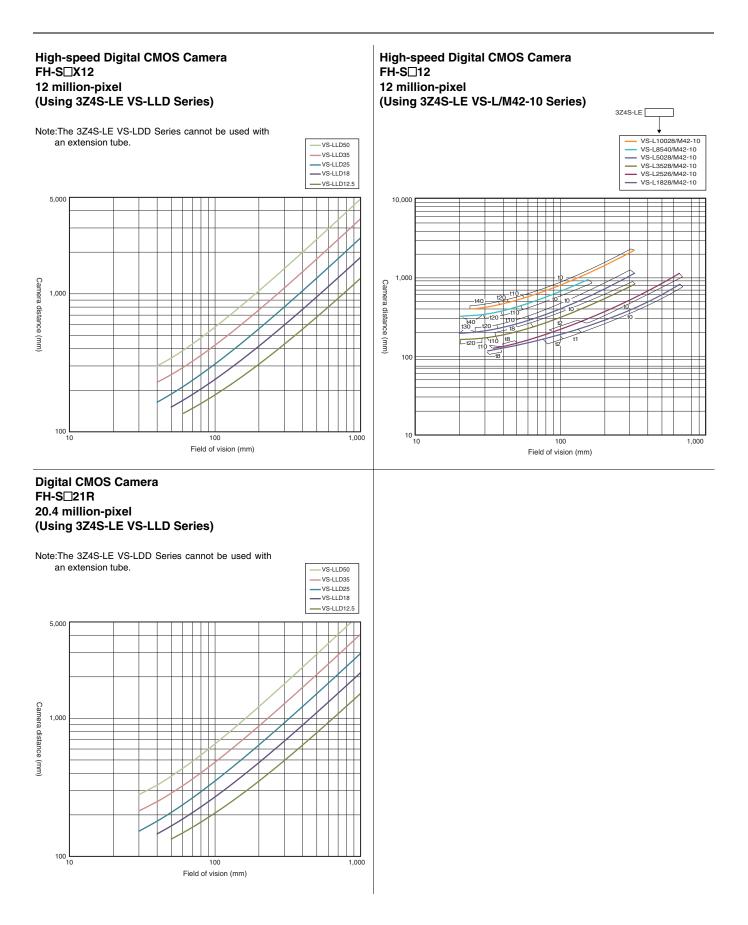
The X axis of the optical chart shows the field of vision (mm) (\*1), and the Y axis of the optical chart shows the camera installation distance (mm) (\*2).



#### **Standard Lenses**

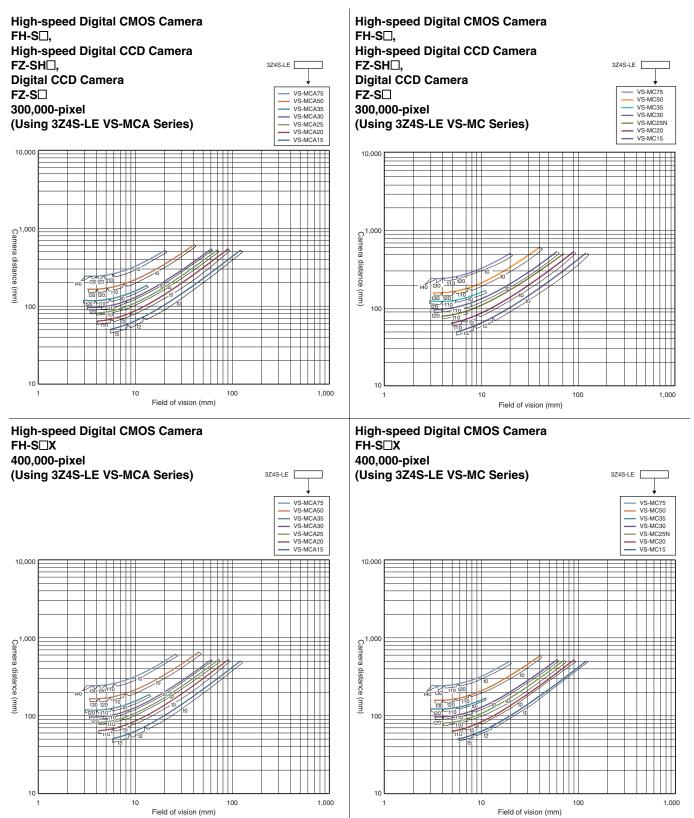


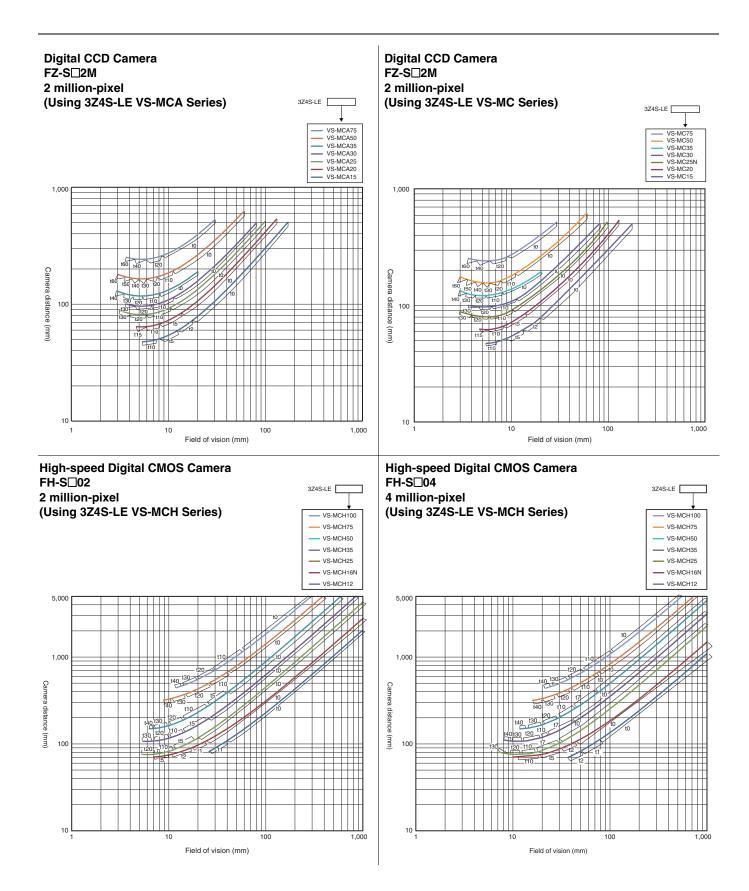


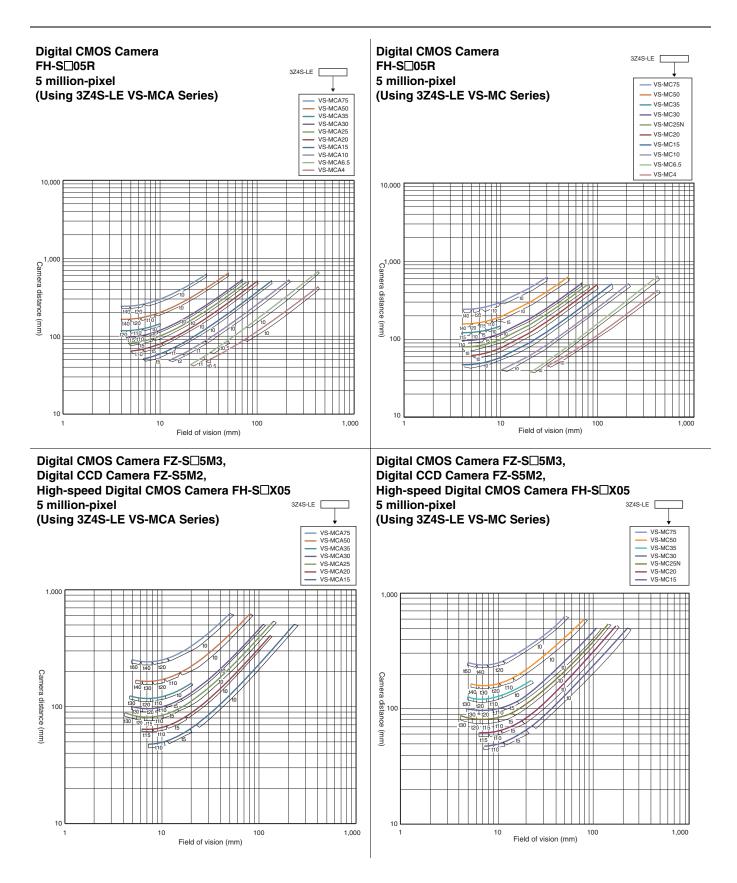


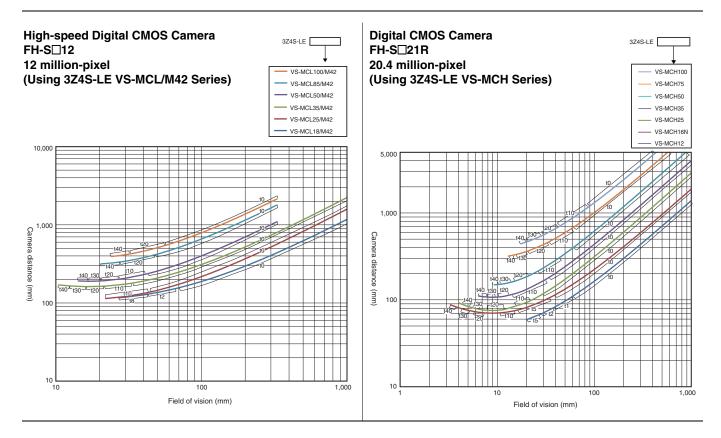
56

#### Vibrations and Shocks Resistant Lenses/Telecentric Lenses









### **Related Manuals**

Man.No.	Model number	Manual
Z365	FH/FZ5	Vision System FH/FZ5 Series User's Manual
Z341	FH/FZ5	Vision System FH/FZ5 series Processing Item Function Reference Manual
Z342	FH/FZ5	Vision System FH/FZ5 Series User's Manual for Communications Settings
Z343	FH	Vision System FH Series Operation Manual for Sysmac Studio
Z366	FH/FZ5	Vision System FH/FZ5 series Hardware Setup Manual
Z367	FH/FZ5	Vision System FH/FZ5 series Macro Customize Functions Programming Manual

# **Terms and Conditions Agreement**

#### Read and understand this catalog.

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

#### Warranties.

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