# LED Driver, Constant Current Programmable, with 32 Dimming Levels

## Description

The CAT4003B and CAT4004B provide respectively three and four matched low dropout current sources to drive LEDs. The CAT400XB requires no external RSET resistor. The LED current is internally set to 25 mA when the device is first enabled. Each LED channel includes an individual control loop allowing the device to handle a wide range of LED forward voltages while still maintaining tight current matching.

The EN/DIM logic input supports the device enable and a digital dimming interface for setting the LED channel current with 32 linear dimming levels.

LEDs can be powered directly from a Lithium-ion battery due to the low dropout (75 mV at 20 mA) current sinks.

Package options are available in the 4-channel tiny 8-pad UDFN 2 mm x 2 mm with a max height of 0.55 mm, and 3- channel in the 6-lead TSOT-23, TSOP and SC-70.

#### **Features**

- 3, 4 LED Current Sinks with Tight Matching
- 32 Dimming Levels
- Low Dropout Driver 75 mV at 20 mA
- No Switching Noise
- Shutdown Current less than 1 μA
- 25 mA Max LED Current per Channel
- Dimming via 1-wire EZDim Interface
- Thermal Shutdown Protection
- RoHS Compliant
- 6-lead TSOT-23, TSOP, SC-70, and 8-pad UDFN 2 mm x 2 mm Packages

## **Typical Applications**

- LCD Display Backlight
- Cellular Phones
- Digital Still Cameras

This document contains information on some products that are still under development. ON Semiconductor reserves the right to change or discontinue these products without notice



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UDFN-8 HU2 SUFFIX CASE 517AW

TSOT23-6 TD SUFFIX CASE 419AF

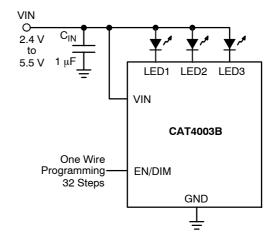




SC70-6 SD SUFFIX CASE 419AD

TSOP-6 TS SUFFIX CASE 318G

#### TYPICAL APPLICATION CIRCUIT



#### **ORDERING INFORMATION**

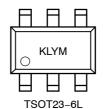
See detailed ordering information on page 2 of this data sheet.

## **MARKING DIAGRAMS**

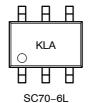


UDFN8 (2 x 2 mm)

BH = CAT4004B Device Code
A = Assembly Location Code
Y = Production Year (last digit)
M = Production Month: 1 - 9, O, N, D



KL = CAT4003B Device Code Y = Production Year (last digit) M = Production Month: 1 – 9, O, N, D



KL = CAT4003B Device CodeA = Assembly Location Code



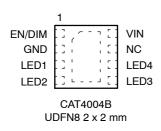
L4 = CAT4003B Device Code A = Assembly Location Code YW = Year and Work Week

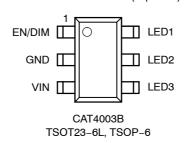
## **ORDERING INFORMATION (Note 1)**

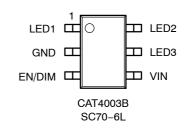
Orderable Part Number	Package	Finish	Shipping (Note 2)
CAT4003BTD-GT3	TSOT-23, 6-Lead	NiPdAu (RoHS Compliant)	3,000 / Tape & Reel
CAT4003BTS-T3	TSOP, 6-Lead	Matte-Tin (RoHS Compliant)	3,000 / Tape & Reel
CAT4003BSD-GT3	SC-70, 6-Lead	NiPdAu (RoHS Compliant)	3,000 / Tape & Reel
CAT4004BHU2-GT3	UDFN, 8-Pad, 2 x 2 mm	NiPdAu (RoHS Compliant)	3,000 / Tape & Reel

- 1. For additional package and temperature options, please contact your nearest ON Semiconductor Sales office.
- 2. For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.
- 3. For detailed information and a breakdown of device nomenclature and numbering systems, please see the ON Semiconductor Device Nomenclature document, TND310/D, available at <a href="https://www.onsemi.com">www.onsemi.com</a>

## PIN CONNECTIONS (Top View)







## **Table 1. PIN FUNCTIONS**

Pin Name	Function			
EN/DIM	Device Enable (active high) and Dimming Control			
GND	Ground Reference			
LED1	LED1 Cathode Terminal			
LED2	LED2 Cathode Terminal			
LED3	LED3 Cathode Terminal			
LED4	LED4 Cathode Terminal			
VIN	Device Supply Input, Connect to Battery or Supply			
TAB	Connect to GND on the PCB, for CAT4004B only.			

## **Table 2. ABSOLUTE MAXIMUM RATINGS**

Parameter	Value	Unit
VIN, LEDx Voltage	6	V
EN/DIM Voltage	VIN + 0.7	V
Storage Temperature Range	-65 to +150	°C
Junction Temperature Range	-40 to +125	°C
Lead Temperature	300	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

## **Table 3. RECOMMENDED OPERATING CONDITIONS**

Parameter	Value	Unit
VIN	2.4 to 5.5	٧
Ambient Temperature Range	-40 to +85	°C
LED Current Range	0 to 25	mA

<sup>4.</sup> Typical application circuit with external components is shown on page 1.

## **Table 4. ELECTRICAL OPERATING CHARACTERISTICS**

(over recommended operating conditions unless specified otherwise) ( $V_{IN} = 4.0 \text{ V}$ , EN = High,  $T_{AMB} = 25^{\circ}\text{C}$ ) (Note 6)

Parameter Conditions		Symbol	Min	Тур	Max	Units
Quiescent Current I <sub>LED</sub> = 25 mA/channel		IQ	0.5	0.7	1.5	mA
Shutdown Current	V <sub>EN</sub> = 0 V	I <sub>QSHDN</sub>			1	μΑ
Full Scale LED Current (Average) (Note 5)		I <sub>LED-FULL</sub>	24	25	26	mA
LED Channel Matching	I <sub>LED</sub> – I <sub>LEDAVG</sub> I <sub>LEDAVG</sub>	I <sub>LED-DEV</sub>	-5	±1	+5	%
Dropout Voltage	I <sub>LED</sub> = 20 mA I <sub>LED</sub> = 1 mA	V <sub>DOUT</sub>		75 45		mV
EN/DIM Pin  - Internal pull-down resistor  - Logic High Level  - Logic Low Level		R <sub>EN/DIM</sub> V <sub>HI</sub> V <sub>LO</sub>	1.3	200	0.4	kΩ V V
Thermal Shutdown		T <sub>SD</sub>		150		°C
Thermal Hysteresis		T <sub>HYS</sub>		20		°C
Undervoltage lockout (UVLO) threshold		V <sub>UVLO</sub>		2.0		V

Table 5. RECOMMENDED EN/DIM TIMING (For 3 V ≤ V<sub>IN</sub> ≤ 5.5 V, over full ambient temperature range -40°C to +85°C.) (Note 7)

Parameter	Conditions	Symbol	Min	Тур	Max	Units
Power-up Setup Time		T <sub>SETUP</sub>	10			μs
EN/DIM program low time		T <sub>LO</sub>	0.2		500	μs
EN/DIM program high time		T <sub>HI</sub>	0.2			μs
LED current settling time		T <sub>LED</sub>		10		μs
EN/DIM low time to shutdown		T <sub>PWRDWN</sub>	2	3	5	ms

The Min/Max limits apply across the -40°C to +85°C ambient temperature range and are assured by design, characterization and correlation with statistical analysis.

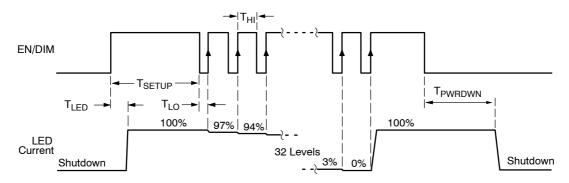


Figure 1. CAT400XB EN/DIM Dimming Timing Diagram

#### **LED Current Setting**

On the CAT400XB, the full scale LED current is internally set to 25 mA (no external resistor).

When the EN/DIM is first enabled, the CAT400XB sets the LED channel current to the full scale current. Each

consecutive rising edge on the EN/DIM decreases the LED current by one step until it goes to zero, as shown on Figure 1.

 <sup>5.</sup> For the CAT4003B, I<sub>LEDAVG</sub> = (I<sub>LED,CH1</sub> + I<sub>LED,CH2</sub> + I<sub>LED,CH3</sub>) / 3
 6. The Min/Max limits apply across the -40°C to +85°C ambient temperature range and are assured by design, characterization and correlation with statistical analysis.

## **TYPICAL CHARACTERISTICS**

(CAT4003B,  $V_{IN}$  = 4 V,  $V_F$  = 3.3 V,  $I_{OUT}$  = 75 mA (3 LEDs at 25 mA),  $C_{IN}$  = 1  $\mu$ F,  $T_{AMB}$  = 25 °C unless otherwise specified.)

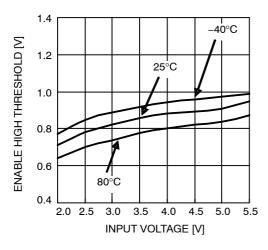


Figure 2. EN High Threshold vs. Input Voltage

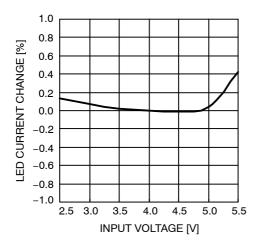


Figure 4. LED Current Change vs. Input Voltage

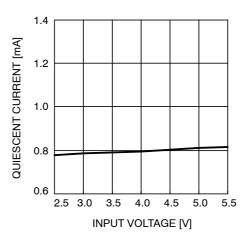


Figure 3. Quiescent Current vs. Input Voltage (full load)

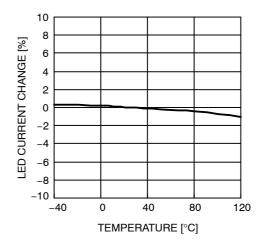


Figure 5. LED Current Change vs. Temperature

## **TYPICAL CHARACTERISTICS**

(CAT4003B,  $V_{IN}$  = 4 V,  $V_F$  = 3.3 V,  $I_{OUT}$  = 75 mA (3 LEDs at 25 mA),  $C_{IN}$  = 1  $\mu$ F,  $T_{AMB}$  = 25 °C unless otherwise specified.)

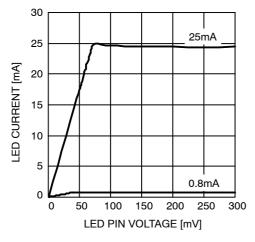


Figure 6. Dropout Characteristics

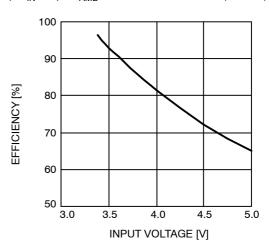


Figure 7. Efficiency vs. Input Voltage

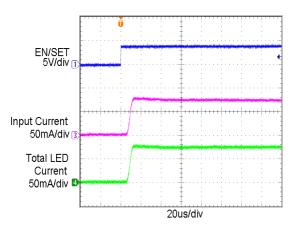


Figure 8. Power Up Waveform

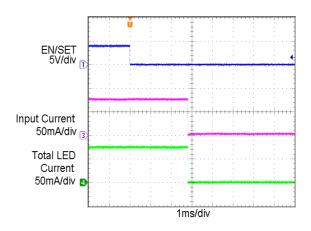


Figure 9. Power Down Waveform

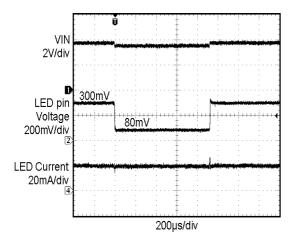


Figure 10. Line Transient Waveform

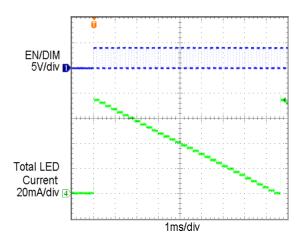


Figure 11. Dimming Levels

#### **Pin Functions**

VIN is the supply pin for the charge pump. A small  $1 \mu F$  ceramic bypass capacitor is required between the VIN pin and ground near the device. The operating input voltage range is from 2.4 V to 5.5 V. Whenever the input supply falls below the under-voltage threshold (2.0 V), all the LED channels are disabled and the device enters shutdown mode.

**EN/DIM** is the enable and one wire dimming input for all LED channels. Levels of logic high and logic low are set at 1.3 V and 0.4 V respectively. When EN/DIM is initially taken high, the CAT400XB becomes enabled and all LED currents are set to the full scale 25 mA. To place the device

into "zero current" shutdown mode, the EN/DIM pin must be held low for 3 ms typical

**LED1 to LED4** provide the internal regulated current for each of the LED cathodes. The pins enter a high impedance zero current state whenever the device is placed in shutdown mode.

**GND** is the ground reference for the device. The pin must be connected to the ground plane on the PCB.

**TAB** (CAT4004B only) is the exposed pad underneath the package. For best thermal performance, the tab should be soldered to the PCB and connected to the ground plane.

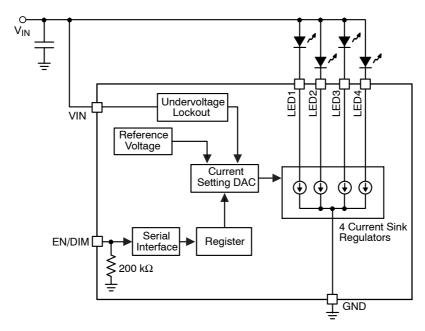


Figure 12. CAT4004B Functional Block Diagram

## **Basic Operation**

The CAT400XB uses tightly matched current sinks to accurately regulate LED current in each channel.

There are 32 different settings for LED brightness that can be programmed through the EN/DIM pin. Tight current regulation for all channels is possible over a wide range of input and LED voltages due to independent current sensing circuitry on each channel.

Each LED channel needs a minimum of 75 mV headroom to sink a constant regulated current of 20 mA. If the input supply falls below 2.0 V, the under-voltage lockout circuit disables all LED channels and resets the circuit to default values. Any unused LED channels should be left open.

## **CAT400XB LED Current Selection**

After power—up and once enabled, the LED current is set initially to the full scale current of 25 mA. The number of pulses (n) on the EN/DIM input does decrease the current value as follows:

LED current [mA] = 25 
$$\times \left(\frac{31-n}{31}\right)$$

The full scale current is calculated from the above formula with n equal to zero.

The EN/DIM pin has two primary functions. One function enables and disables the device. The other function is LED current dimming with 32 different levels by pulsing the input signal, as shown on Figure 1. On each successive pulse rising edge, the LED current is decreased by about 3.2% (1/31st of the full scale value). After 30 pulses, the LED current is 3.2% of the full scale current. On the 31st pulse, the current drops to zero, and then goes back to full scale on the following pulse.

Initially once the EN/DIM input is first pulled high, it must remain high for at least  $T_{SETUP}$  delay (10  $\mu$ s minimum) to allow the LED driver to complete its power–up. After this delay, EN/DIM can be pulsed in order to set the LED current to the desired level. Each pulse width should be between 1  $\mu$ s and 500  $\mu$ s. Pulses faster than the minimum  $T_{LO}$  may be ignored and filtered by the device. Pulses longer than the maximum  $T_{LO}$  may shutdown the device. By pulsing the EN/DIM signal at a high frequency, the LED current can quickly be set to zero or to any other level.

The LED driver enters a "zero current" shutdown mode if EN/DIM is held low for longer than 5 ms.

The dimming level is set by the number of pulses on the EN/DIM after the power-up, as shown in Table 6.

**Table 6. DIMMING LEVELS** 

Full Scale Current in %	Dimming Pulses [n]
100	0
97	1
94	2
90	3
87	4
84	5
81	6
77	7
74	8
71	9
68	10
65	11
61	12
58	13

Full Scale Current in %	Dimming Pulses [n]
55	14
52	15
48	16
45	17
42	18
39	19
35	20
32	21
29	22
26	23
23	24
19	25
16	26
13	27
10	28
6	29
3	30
0	31
100	32



## TSOP-6 CASE 318G-02 **ISSUE V**

L2

C

GAUGE

SEATING PLANE

**DATE 12 JUN 2012** 



- 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
- 2
- CONTROLLING DIMENSION: MILLIMETERS.
  MAXIMUM LEAD THICKNESS INCLUDES LEAD FINISH. MINIMUM LEAD THICKNESS IS THE MINIMUM THICKNESS OF BASE MATERIAL. DIMENSIONS D AND E1 DO NOT INCLUDE MOLD FLASH,
- PROTRUSIONS, OR GATE BURRS. MOLD FLASH, PROTRUSIONS, OR GATE BURRS SHALL NOT EXCEED 0.15 PER SIDE. DIMENSIONS D AND E1 ARE DETERMINED AT DATUM H.

  5. PIN ONE INDICATOR MUST BE LOCATED IN THE INDICATED ZONE.

	MILLIMETERS			
DIM	MIN	NOM	MAX	
Α	0.90	1.00	1.10	
A1	0.01	0.06	0.10	
b	0.25	0.38	0.50	
С	0.10	0.18	0.26	
D	2.90	3.00	3.10	
E	2.50	2.75	3.00	
E1	1.30	1.50	1.70	
е	0.85	0.95	1.05	
L	0.20	0.40	0.60	
L2	0.25 BSC			
М	0° – 10°			

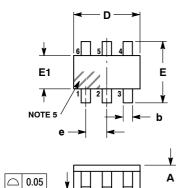
STYLE 5:

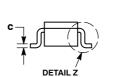
PIN 1. EMITTER 2

2. BASE 2

3. COLLECTOR 1 4. EMITTER 1

5. BASE 1 6. COLLECTOR 2





М

**DETAIL Z** 

Н

STYLE 1: PIN 1. DRAIN 2. DRAIN 3. GATE 4. SOURCE 5. DRAIN 6. DRAIN	STYLE 2 PIN 1. 2. 3. 4. 5.
STYLE 7:	STYLE 8
PIN 1. COLLECTOR	PIN 1.
2. COLLECTOR	2.
3. BASE	3.

4. N/C5. COLLECTOR

6. EMITTER

2. SOURCE 2 3. GATE 2

DRAIN 1

4. DRAIN 2

STYLE 13:

PIN 1. GATE 1

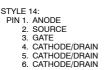
5. 6. SOURCE 1

Δ1

EMITTER 2 BASE 1 COLLECTOR 1 **EMITTER 1** BASE 2 COLLECTOR 2

Vbus D(in)

3. D(in)+ 4. D(out)+ 5. D(out) 6. GND





STYLE 3:

STYLE 9

PIN 1. ENABLE

4. Vz

5. V in 6. V out

N/C
 R BOOST

3. SOURCE

4. DRAIN 5. DRAIN

PIN 1. LOW VOLTAGE GATE 2. DRAIN

6. HIGH VOLTAGE GATE

STYLE 16:

5. 6. ANODE

PIN 1. ANODE
<ol><li>SOURCE</li></ol>
<ol><li>GATE</li></ol>
<ol><li>DRAIN</li></ol>
5. N/C
<ol><li>CATHODE</li></ol>

5. ENABLE 6. LOAD STYLE 10 STYLE 11: PIN 1. D(OUT)+ 2. GND 3. D(OUT)-

3. NOT USED 4. GROUND

STYLE 4:

PIN 1. N/C 2. V in

PIN 1. ANODE/CATHODE

COLLECTOR

CATHODE

BASE

3. EMITTER

4. D(IN)-5. VBUS 6. D(IN)-

PIN 1. SOURCE 1 2. DRAIN 2 3. DRAIN 2

4. SOURCE 2 6. DRAIN 1/GATE 2 STYLE 17: PIN 1. EMITTER 2. BASE

STYLE 12: PIN 1. I/O 2. GROUND 3. I/O 4. I/O 5. VCC 6. I/O

STYLE 6:

PIN 1. COLLECTOR 2. COLLECTOR

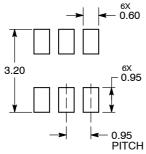
4. EMITTER

5. COLLECTOR 6. COLLECTOR

3. BASE

## 4. ANODE CATHODE COLLECTOR

## **RECOMMENDED SOLDERING FOOTPRINT\***



**DIMENSIONS: MILLIMETERS** 

## **GENERIC** MARKING DIAGRAM\*

3. ANODE/CATHODE





XXX = Specific Device Code Α =Assembly Location

Υ = Year

W = Work Week = Pb-Free Package XXX = Specific Device Code

М = Date Code = Pb-Free Package

\*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot " ", may or may not be present.

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DESCRIPTION:	TSOP-6		PAGE 1 OF 1	

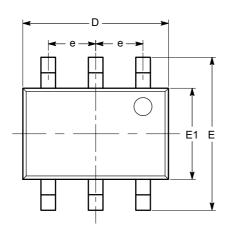
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<sup>\*</sup>For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

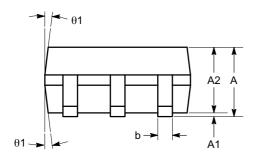


SC-88 (SC-70 6 Lead), 1.25x2 CASE 419AD-01 ISSUE A

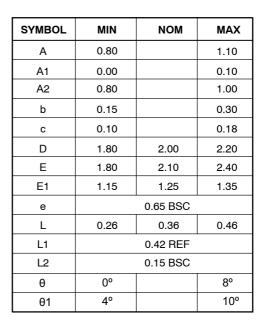
**DATE 07 JUL 2010** 

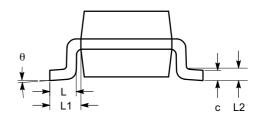


**TOP VIEW** 



SIDE VIEW





**END VIEW** 

#### Notes:

- (1) All dimensions are in millimeters. Angles in degrees.
- (2) Complies with JEDEC MO-203.

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DESCRIPTION:	SC-88 (SC-70 6 LEAD), 1.25X2		PAGE 1 OF 1

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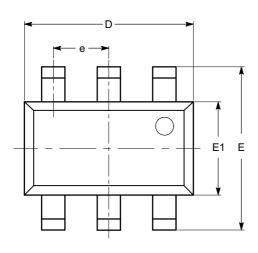


TSOT-23, 6 LEAD CASE 419AF-01 ISSUE O

SYMBOL

**DATE 19 DEC 2008** 

MAX

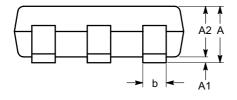


Α			1.00
A1	0.01	0.05	0.10
A2	0.80	0.87	0.90
b	0.30		0.45
С	0.12	0.15	0.20
D	2.90 BSC		
Е	2.80 BSC		
E1	1.60 BSC		
е	0.95 TYP		
L	0.30	0.40	0.50
L1	0.60 REF		
L2	0.25 BSC		
θ	0°		8°

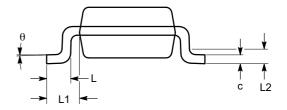
MIN

NOM





SIDE VIEW



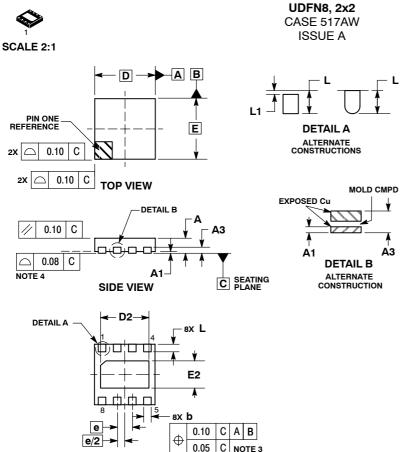
**END VIEW** 

#### Notes:

- (1) All dimensions are in millimeters. Angles in degrees.
- (2) Complies with JEDEC MO-193.

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DESCRIPTION:	TSOT-23, 6 LEAD		PAGE 1 OF 1

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## 17AW E A

**DATE 13 NOV 2015** 

#### NOTES:

- DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
- 2. CONTROLLING DIMENSION: MILLIMETERS.
- 2. DIMENSION & APPLIES TO PLATED TERMINALS AND IS MEASURED BETWEEN 0.15
  AND 0.30 MM FROM THE TERMINAL TIP.
- 4. COPLANARITY APPLIES TO THE EXPOSED
- PAD AS WELL AS THE TERMINALS.

  5. FOR DEVICE OPN CONTAINING W OPTION, DETAIL B ALTERNATE CONSTRUCTION IS NOT APPLICABLE.

	MILLIMETERS		
DIM	MIN	MAX	
Α	0.45	0.55	
A1	0.00	0.05	
АЗ	0.13 REF		
b	0.18	0.30	
D	2.00 BSC		
D2	1.50	1.70	
E	2.00 BSC		
E2	0.80	1.00	
е	0.50 BSC		
L	0.20	0.45	
L1		0.15	

# GENERIC MARKING DIAGRAM\*



XX = Specific Device Code

M = Date Code

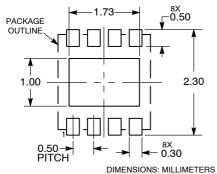
= Pb-Free Package

(Note: Microdot may be in either location)

\*This information is generic. Please refer to device data sheet for actual part marking. Pb-Free indicator, "G" or microdot " ■", may or may not be present.

# RECOMMENDED SOLDERING FOOTPRINT\*

**BOTTOM VIEW** 



\*For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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