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# 100-tap Digital Potentiometer (POT) with Buffered Wiper

#### Description

The CAT5111 is a single digital POT designed as an electronic replacement for mechanical potentiometers. Ideal for automated adjustments on high volume production lines, they are also well suited for applications where equipment requiring periodic adjustment is either difficult to access or located in a hazardous or remote environment.

The CAT5111 contains a 100-tap series resistor array connected between two terminals  $R_H$  and  $R_L$ . An up/down counter and decoder that are controlled by three input pins, determines which tap is connected to the wiper,  $R_{WB}$ . The CAT5111 wiper is buffered by an op amp that operates rail to rail. The wiper setting, stored in non-volatile memory, is not lost when the device is powered down and is automatically recalled when power is returned. The wiper can be adjusted to test new system values without effecting the stored setting. Wiper-control of the CAT5111 is accomplished with three input control pins,  $\overline{CS}$ , U/ $\overline{D}$ , and  $\overline{INC}$ . The  $\overline{INC}$  input increments the wiper in the direction which is determined by the logic state of the U/ $\overline{D}$  input. The  $\overline{CS}$  input is used to select the device and also store the wiper position prior to power down.

The digital POT can be used as a buffered voltage divider. For applications where the potentiometer is used as a 2-terminal variable resistor, please refer to the CAT5113. The buffered wiper of the CAT5111 is not compatible with that application.

#### Features

- 100-position Linear Taper Potentiometer
- Non-volatile EEPROM Wiper Storage; Buffered Wiper
- Low Power CMOS Technology
- Single Supply Operation: 2.5 V 6.0 V
- Increment Up/Down Serial Interface
- Resistance Values:  $10 \text{ k}\Omega$ ,  $50 \text{ k}\Omega$  and  $100 \text{ k}\Omega$
- Available in PDIP, SOIC, TSSOP and MSOP Packages
- These Devices are Pb-Free, Halogen Free/BFR Free and are RoHS Compliant

#### Applications

- Automated Product Calibration
- Remote Control Adjustments
- Offset, Gain and Zero Control
- Tamper-proof Calibrations
- Contrast, Brightness and Volume Controls
- Motor Controls and Feedback Systems
- Programmable Analog Functions



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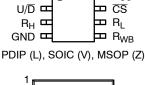
http://onsemi.com

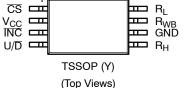


PDIP-8 L SUFFIX CASE 646AA

TSSOP-8 Y SUFFIX CASE 948AL

#### 





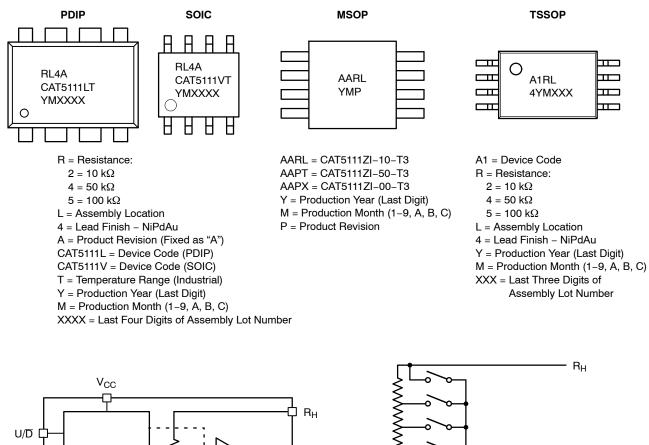
#### PIN FUNCTION

Pin Name	Function	
INC	Increment Control	
U/D	Up/Down Control	
R <sub>H</sub>	Potentiometer High Terminal	
GND	Ground	
R <sub>WB</sub>	Buffered Wiper Terminal	
RL	Potentiometer Low Terminal	
CS	Chip Select	
V <sub>CC</sub>	Supply Voltage	

#### ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 9 of this data sheet.

#### **DEVICE MARKING INFORMATION**



R<sub>WB</sub>

 $\mathsf{R}_\mathsf{L}$ 

Ş

R<sub>WB</sub>

 $R_L$ 

Figure 2. Electronic Potentiometer Implementation

Control

and

Memory

Power On Recall

-D-GND

Figure 1. Functional Diagram

INC

CS

# **Pin Description**

## **INC:** Increment Control Input

The  $\overline{INC}$  input (on the falling edge) moves the wiper in the up or down direction determined by the condition of the U/ $\overline{D}$  input.

## U/D: Up/Down Control Input

The  $U/\overline{D}$  input controls the direction of the wiper movement. When in a high state and  $\overline{CS}$  is low, any high-to-low transition on  $\overline{INC}$  will cause the wiper to move one increment toward the  $R_H$  terminal. When in a low state and  $\overline{CS}$  is low, any high-to-low transition on  $\overline{INC}$  will cause the wiper to move one increment towards the  $R_L$  terminal.

## $\mathbf{R}_{\mathbf{H}}$ : High End Potentiometer Terminal

 $R_{\rm H}$  is the high end terminal of the potentiometer. It is not required that this terminal be connected to a potential greater than the  $R_{\rm L}$  terminal. Voltage applied to the  $R_{\rm H}$  terminal cannot exceed the supply voltage,  $V_{\rm CC}$  or go below ground, GND.

**R**<sub>WB</sub>: Wiper Potentiometer Terminal (Buffered)

 $R_{WB}$  is the buffered wiper terminal of the potentiometer. Its position on the resistor array is controlled by the control inputs,  $\overline{INC}$ ,  $U/\overline{D}$  and  $\overline{CS}$ .

# **R**<sub>L</sub>: Low End Potentiometer Terminal

 $R_L$  is the low end terminal of the potentiometer. It is not required that this terminal be connected to a potential less than the  $R_H$  terminal. Voltage applied to the  $R_L$  terminal cannot exceed the supply voltage,  $V_{CC}$  or go below ground, GND.  $R_L$  and  $R_H$  are electrically interchangeable.

# **CS**: Chip Select

The chip select input is used to activate the control input of the CAT5111 and is active low. When in a high state, activity on the  $\overline{INC}$  and  $U/\overline{D}$  inputs will not affect or change the position of the wiper.

## **Device Operation**

The CAT5111 operates like a digitally controlled potentiometer with  $R_H$  and  $R_L$  equivalent to the high and low terminals and  $R_{WB}$  equivalent to the mechanical potentiometer's wiper. There are 100 available tap positions including the resistor end points,  $R_H$  and  $R_L$ . There are 99 resistor elements connected in series between the  $R_H$  and  $R_L$  terminals. The wiper terminal is connected to one of the 100 taps and controlled by three inputs,  $\overline{INC}$ ,  $U/\overline{D}$  and  $\overline{CS}$ . These inputs control a seven-bit up/down counter whose output is decoded to select the wiper position. The selected wiper position can be stored in nonvolatile memory using the  $\overline{INC}$  and  $\overline{CS}$  inputs.

With  $\overline{CS}$  set LOW the CAT5111 is selected and will respond to the U/ $\overline{D}$  and  $\overline{INC}$  inputs. HIGH to LOW transitions on  $\overline{INC}$  will increment or decrement the wiper (depending on the state of the U/ $\overline{D}$  input and seven-bit counter). The wiper, when at either fixed terminal, acts like its mechanical equivalent and does not move beyond the last position. The value of the counter is stored in nonvolatile memory whenever  $\overline{CS}$  transitions HIGH while the  $\overline{INC}$  input is also HIGH. When the CAT5111 is powered-down, the last stored wiper counter position is maintained in the nonvolatile memory. When power is restored, the contents of the memory are recalled and the counter is set to the value stored.

With  $\overline{INC}$  set low, the CAT5111 may be de-selected and powered down without storing the current wiper position in nonvolatile memory. This allows the system to always power up to a preset value stored in nonvolatile memory.

#### **Table 1. OPERATION MODES**

INC	CS	U/D	Operation
High to Low	Low	High	Wiper toward R <sub>H</sub>
High to Low	Low	Low	Wiper toward R <sub>L</sub>
High	Low to High	х	Store Wiper Position
Low	Low to High	х	No Store, Return to Standby
Х	High	Х	Standby

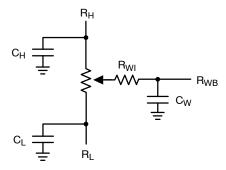


Figure 3. Potentiometer Equivalent Circuit

#### **Table 2. ABSOLUTE MAXIMUM RATINGS**

Parameters	Ratings	Units
Supply Voltage V <sub>CC</sub> to GND	–0.5 to +7	V
Inputs CS to GND	–0.5 to V <sub>CC</sub> +0.5	V
INC to GND	-0.5 to V <sub>CC</sub> +0.5	V
U/D to GND	–0.5 to V <sub>CC</sub> +0.5	V
R <sub>H</sub> to GND	–0.5 to V <sub>CC</sub> +0.5	V
R <sub>L</sub> to GND	–0.5 to V <sub>CC</sub> +0.5	V
R <sub>WB</sub> to GND	–0.5 to V <sub>CC</sub> +0.5	V
Operating Ambient Temperature Commercial ('C' or Blank suffix)	0 to 70	°C
Industrial ('I' suffix)	-40 to +85	°C
Junction Temperature	+150	°C
Storage Temperature	–65 to 150	°C
Lead Soldering (10 s max)	+300	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

#### **Table 3. RELIABILITY CHARACTERISTICS**

Symbol	Parameter	Test Method	Min	Тур	Max	Units
V <sub>ZAP</sub> (Note 1)	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000			V
I <sub>LTH</sub> (Notes 1, 2)	Latch-Up	JEDEC Standard 17	100			mA
T <sub>DR</sub>	Data Retention	MIL-STD-883, Test Method 1008	100			Years
N <sub>END</sub>	Endurance	MIL-STD-883, Test Method 1003	1,000,000			Stores

This parameter is tested initially and after a design or process change that affects the parameter.
 Latch-up protection is provided for stresses up to 100 mA on address and data pins from -1 V to V<sub>CC</sub> + 1 V

# Table 4. DC ELECTRICAL CHARACTERISTICS (V<sub>CC</sub> = +2.5 V to +6 V unless otherwise specified)

Symbol	Parameter	Conditions	Min	Тур	Max	Units
POWER SUPPL	Y		•			
V <sub>CC</sub>	Operating Voltage Range		2.5	-	6	V
I <sub>CC1</sub>	Supply Current (Increment)	$V_{CC} = 6 V, f = 1 MHz, I_W = 0$	-	-	200	μΑ
		V <sub>CC</sub> = 6 V, f = 250 kHz, I <sub>W</sub> = 0	-	-	100	μΑ
I <sub>CC2</sub>	Supply Current (Write)	Programming, V <sub>CC</sub> = 6 V	-	-	1000	μA
		V <sub>CC</sub> = 3 V	-	-	500	μA
I <sub>SB1</sub> (Note 4)	Supply Current (Standby)	$\frac{\overline{\text{CS}}}{\text{U/D}} = \frac{\text{V}_{\text{CC}}}{\text{INC}} = \text{V}_{\text{CC}} - 0.3 \text{ V}$ or GND	-	75	150	μΑ
LOGIC INPUTS	•	•				
I <sub>IH</sub>	Input Leakage Current	V <sub>IN</sub> = V <sub>CC</sub>	-	-	10	μA
IIL	Input Leakage Current	V <sub>IN</sub> = 0 V	-	-	-10	μΑ
V <sub>IH1</sub>	TTL High Level Input Voltage	$4.5~\textrm{V} \leq \textrm{V}_{\textrm{CC}} \leq 5.5~\textrm{V}$	2	-	V <sub>CC</sub>	V
V <sub>IL1</sub>	TTL Low Level Input Voltage		0	-	0.8	V
V <sub>IH2</sub>	CMOS High Level Input Voltage	$2.5 \text{ V} \le \text{V}_{\text{CC}} \le 6 \text{ V}$	V <sub>CC</sub> x 0.7	-	V <sub>CC</sub> + 0.3	V
V <sub>IL2</sub>	CMOS Low Level Input Voltage		-0.3	—	V <sub>CC</sub> x 0.2	V
POTENTIOMET	ER CHARACTERISTICS					-
R <sub>POT</sub>	Potentiometer Resistance	-10 Device		10		kΩ
		-50 Device	1	50		1
		-00 Device	1	100		1
	Pot. Resistance Tolerance				±20	%
V <sub>RH</sub>	Voltage on R <sub>H</sub> pin		0		V <sub>CC</sub>	V
V <sub>RL</sub>	Voltage on R <sub>L</sub> pin		0		V <sub>CC</sub>	V
	Resolution			1		%
INL	Integral Linearity Error	I <sub>W</sub> ≤ 2 μA		0.5	1	LSB
DNL	Differential Linearity Error	I <sub>W</sub> ≤ 2 μA		0.25	0.5	LSB
R <sub>OUT</sub>	Buffer Output Resistance	$\begin{array}{l} 0.05 \; V_{CC} \leq V_{WB} \leq 0.95 \; V_{CC}, \\ V_{CC} = 5 \; V \end{array}$			1	Ω
I <sub>OUT</sub>	Buffer Output Current	$\begin{array}{l} 0.05 \; V_{\mathrm{CC}} \leq V_{\mathrm{WB}} \leq 0.95 \; V_{\mathrm{CC}}, \\ V_{\mathrm{CC}} = 5 \; V \end{array}$			3	mA
TC <sub>RPOT</sub>	TC of Pot Resistance		1	300		ppm/°C
TC <sub>RATIO</sub>	Ratiometric TC		1		20	ppm/°C
C <sub>RH</sub> /C <sub>RL</sub> /C <sub>RW</sub>	Potentiometer Capacitances		1	8/8/25		pF
fc	Frequency Response	Passive Attenuator, 10 k $\Omega$		1.7		MHz
V <sub>WB(SWING)</sub>	Output Voltage Range	I <sub>OUT</sub> ≤ 100 μA, V <sub>CC</sub> = 5 V	0.01 V <sub>CC</sub>		0.99 V <sub>CC</sub>	İ

This parameter is tested initially and after a design or process change that affects the parameter.
 Latch-up protection is provided for stresses up to 100 mA on address and data pins from -1 V to V<sub>CC</sub> + 1 V
 I<sub>W</sub> = source or sink
 These parameters are periodically sampled and are not 100% tested.

#### Table 5. AC TEST CONDITIONS

V <sub>CC</sub> Range	$2.5~\textrm{V} \leq \textrm{V}_{\textrm{CC}} \leq 6~\textrm{V}$
Input Pulse Levels	0.2 $V_{CC}$ to 0.7 $V_{CC}$
Input Rise and Fall Times	10 ns
Input Reference Levels	0.5 V <sub>CC</sub>

## Table 6. AC OPERATING CHARACTERISTICS ( $V_{CC}$ = +2.5 V to +6.0 V, $V_{H}$ = $V_{CC}$ , $V_{L}$ = 0 V, unless otherwise specified)

Symbol	Parameter	Min	Typ (Note 7)	Max	Units
t <sub>CI</sub>	CS to INC Setup	100	-	-	ns
t <sub>DI</sub>	U/D to INC Setup	50	-	-	ns
t <sub>ID</sub>	U/D to INC Hold	100	-	-	ns
t <sub>IL</sub>	INC LOW Period	250	-	-	ns
t <sub>IH</sub>	INC HIGH Period	250	-	-	ns
t <sub>IC</sub>	INC Inactive to CS Inactive	1	-	-	μs
t <sub>CPH</sub>	CS Deselect Time (NO STORE)	100	-	-	ns
t <sub>CPH</sub>	CS Deselect Time (STORE)	10	-	-	ms
t <sub>IW</sub>	INC to V <sub>OUT</sub> Change	-	1	5	μs
t <sub>CYC</sub>	INC Cycle Time	1	-	-	μs
t <sub>R</sub> , t <sub>F</sub> (Note 8)	INC Input Rise and Fall Time	-	-	500	μs
t <sub>PU</sub> (Note 8)	Power-up to Wiper Stable	-	-	1	ms
t <sub>WR</sub>	Store Cycle	_	5	10	ms

7. Typical values are for  $T_A = 25^{\circ}C$  and nominal supply voltage. 8. This parameter is periodically sampled and not 100% tested.

9. MI in the A.C. Timing diagram refers to the minimum incremental change in the W output due to a change in the wiper position.

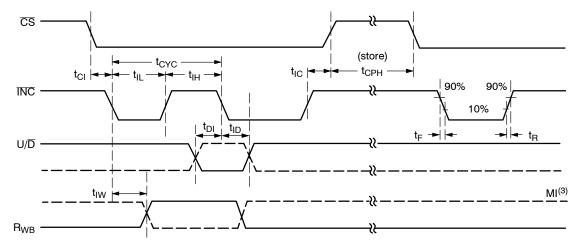


Figure 4. A.C. Timing

#### **APPLICATIONS INFORMATION**

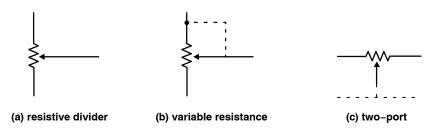
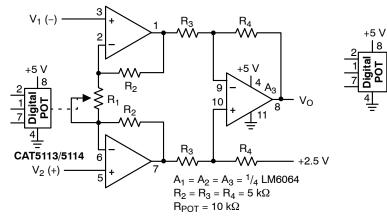


Figure 5. Potentiometer Configuration

Applications





 $C = 0.01 \ \mu F = 0.003 \ \mu F = 0.003 \ \mu F = 0.01 \ \mu F$ 

R

5

 $R_2$ 

3

 $\mathsf{R}_\mathsf{B}$ 

(1

pR<sub>POT</sub>

-p)R<sub>POT</sub>

+5 V

лπ.

3

555

Figure 7. Programmable Sq. Wave Oscillator (555)

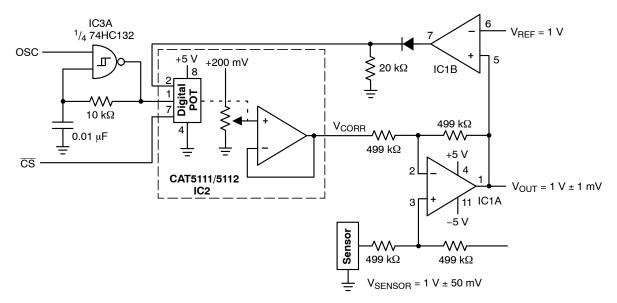
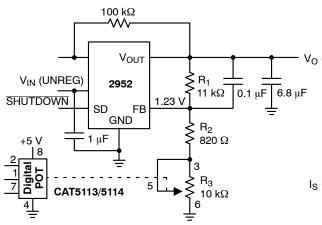
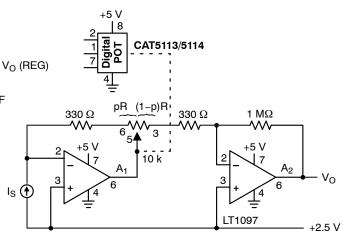
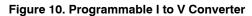


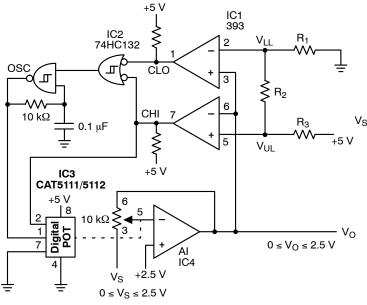
Figure 8. Sensor Auto Referencing Circuit

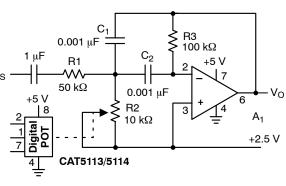


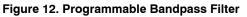


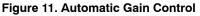












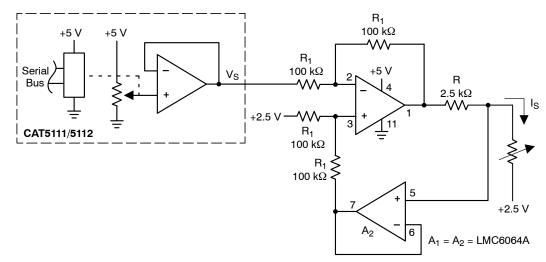


Figure 13. Programmable Current Source/Sink

#### **Table 7. ORDERING INFORMATION**

Orderable Part Number	Resistance (k $\Omega$ )	Lead Finish	Package-Pins	Shipping <sup>†</sup>	
CAT5111LI-10-G	10				
CAT5111LI-50-G	50	NiPdAu (PDIP-8 50 Un	50 Units / Tube		
CAT5111LI-00-G	100		(* = * * = = )		
CAT5111VI-10-GT3	10				
CAT5111VI-50-GT3	50	NiPdAu	SOIC-8 (Pb-Free)	3000 / Tape & Reel	
CAT5111VI-00-GT3	100				
CAT5111YI-10-GT3	10				
CAT5111YI-50-GT3	50	NiPdAu	TSSOP-8 (Pb-Free)	3000 / Tape & Reel	
CAT5111YI-00-GT3	100		(* = * * = = )		
CAT5111ZI-10-T3	10				
CAT5111ZI-50-T3	50	Matte-Tin	MSOP-8 (Pb-Free)	3000 / Tape & Reel	
CAT5111ZI-00-T3	100	1	(		

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.

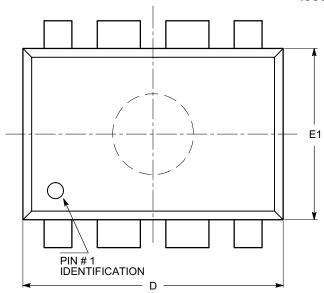
For detailed information and a breakdown of device nomenclature and numbering systems, please see the ON Semiconductor Device Nomenclature document, TND310/D, available at <u>www.onsemi.com</u>.

11. All packages are RoHS compliant.

Standard lead finish is NiPdAu, except MSOP package is Matte–Tin.
 Contact factory for Matte–Tin finish availability for PDIP, SOIC and TSSOP packages.

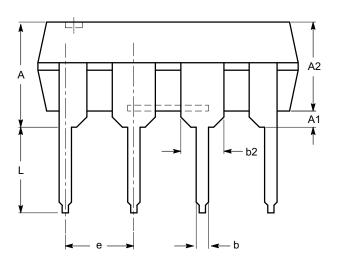
#### PACKAGE DIMENSIONS

PDIP-8, 300 mils CASE 646AA ISSUE A



SYMBOL	MIN	NOM	MAX	
А			5.33	
A1	0.38			
A2	2.92	3.30	4.95	
b	0.36	0.46	0.56	
b2	1.14	1.52	1.78	
с	0.20	0.25	0.36	
D	9.02	9.27	10.16	
E	7.62	7.87	8.25	
E1	6.10	6.35	7.11	
е	2.54 BSC			
eB	7.87		10.92	
L	2.92	3.30	3.80	

TOP VIEW

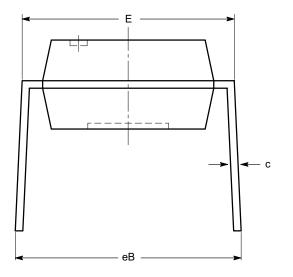


SIDE VIEW

#### Notes:

(1) All dimensions are in millimeters.

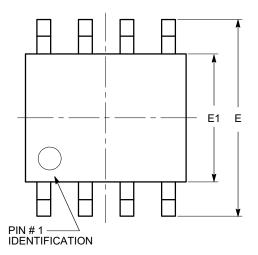
(2) Complies with JEDEC MS-001.



END VIEW

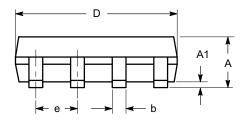
# PACKAGE DIMENSIONS

SOIC 8, 150 mils CASE 751BD ISSUE O



SYMBOL	MIN	NOM	MAX
А	1.35		1.75
A1	0.10		0.25
b	0.33		0.51
с	0.19		0.25
D	4.80		5.00
E	5.80		6.20
E1	3.80		4.00
е		1.27 BSC	
h	0.25		0.50
L	0.40		1.27
θ	0°		8°

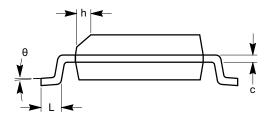
TOP VIEW



SIDE VIEW

#### Notes:

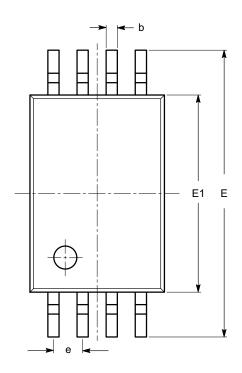
(1) All dimensions are in millimeters. Angles in degrees.
 (2) Complies with JEDEC MS-012.



END VIEW

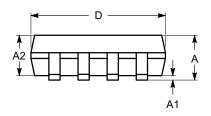
# PACKAGE DIMENSIONS

TSSOP8, 4.4x3 CASE 948AL ISSUE O

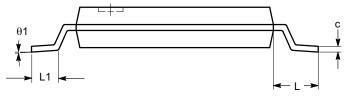


SYMBOL	MIN	NOM	MAX	
А			1.20	
A1	0.05		0.15	
A2	0.80	0.90	1.05	
b	0.19		0.30	
с	0.09		0.20	
D	2.90	3.00	3.10	
E	6.30	6.40	6.50	
E1	4.30	4.40	4.50	
е		0.65 BSC		
L	1.00 REF			
L1	0.50	0.60	0.75	
θ	0°		8°	

#### TOP VIEW



SIDE VIEW



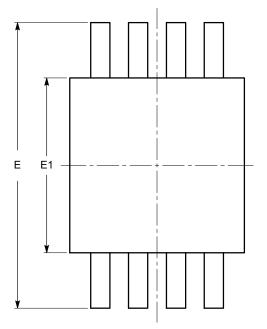
END VIEW

#### Notes:

All dimensions are in millimeters. Angles in degrees.
 Complies with JEDEC MO-153.

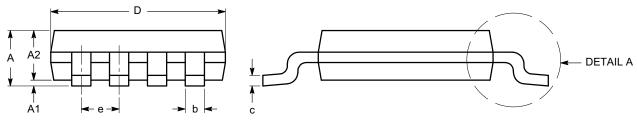
# PACKAGE DIMENSIONS

MSOP 8, 3x3 CASE 846AD ISSUE O



TOP VIEW

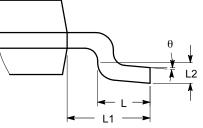
SYMBOL	MIN	NOM	MAX
A			1.10
A1	0.05	0.10	0.15
A2	0.75	0.85	0.95
b	0.22		0.38
с	0.13		0.23
D	2.90	3.00	3.10
E	4.80	4.90	5.00
E1	2.90	3.00	3.10
е		0.65 BSC	
L	0.40	0.60	0.80
L1	0.95 REF		
L2	0.25 BSC		
θ	0°		6°



SIDE VIEW

END VIEW

DETAIL A





#### Notes:

- All dimensions are in millimeters. Angles in degrees.
  Complies with JEDEC MO-187.

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