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March 2016

FNB33060T

Motion SPM® 3 Series

Features

- 600 V 30 A 3-Phase IGBT Inverter with Integral Gate Drivers and Protection
- · Low-Loss. Short-Circuit Rated IGBTs
- Very Low Thermal Resistance Using Al₂O₃ DBC Substrate
- Built-In Bootstrap Diodes and Dedicated Vs Pins Simplify PCB Layout
- Separate Open-Emitter Pins from Low-Side IGBTs for Three-Phase Current Sensing
- Single-Grounded Power Supply
- LVIC Temperature-Sensing Built-In for Temperature Monitoring
- Isolation Rating: 2500 V_{rms} / 1 min.

Applications

• Motion Control - Home Appliance / Industrial Motor

Related Resources

- AN-9088 Motion SPM[®] 3 V6 Series Users Guide
- AN-9086 SPM 3 Package Mounting Guide

General Description

FNB33060T is an advanced Motion SPM® 3 module providing a fully-featured, high-performance inverter output stage for AC Induction, BLDC, and PMSM motors. These modules integrate optimized gate drive of the built-in IGBTs to minimize EMI and losses, while also providing multiple on-module protection features including under-voltage lockouts, over-current shutdown, thermal monitoring of drive IC, and fault reporting. The built-in, high-speed HVIC requires only a single supply voltage and translates the incoming logic-level gate inputs to the high-voltage, high-current drive signals required to properly drive the module's internal IGBTs. Separate negative IGBT terminals are available for each phase to support the widest variety of control algorithms.



Package Marking and Ordering Information

Device	Device Marking	Package	Packing Type	Quantity
FNB33060T	FNB33060T	SPM27-RA	Rail	10

Integrated Power Functions

• 600 V - 30 A IGBT inverter for three-phase DC / AC power conversion (Please refer to Figure 3)

Integrated Drive, Protection and System Control Functions

- For inverter high-side IGBTs: gate drive circuit, high-voltage isolated high-speed level shifting
 control circuit Under-Voltage Lock-Out Protection (UVLO)
 Note: Available bootstrap circuit example is given in Figures 5 and 15.
- For inverter low-side IGBTs: gate drive circuit, Short-Circuit Protection (SCP)
 control supply circuit Under-Voltage Lock-Out Protection (UVLO)
- Fault signaling: corresponding to UVLO (low-side supply) and SC faults
- Input interface: active-HIGH interface, works with 3.3 / 5 V logic, Schmitt-trigger input

Pin Configuration

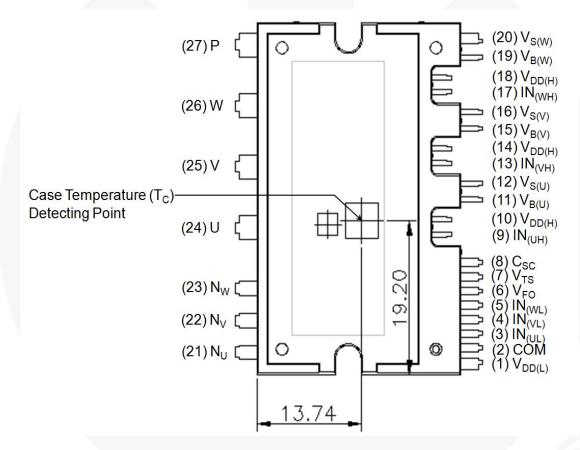


Figure 2. Top View

Pin Descriptions

Pin Number	Pin Name	Pin Description
1	$V_{DD(L)}$	Low-Side Common Bias Voltage for IC and IGBTs Driving
2	COM	Common Supply Ground
3	IN _(UL)	Signal Input for Low-Side U-Phase
4	IN _(VL)	Signal Input for Low-Side V-Phase
5	IN _(WL)	Signal Input for Low-Side W-Phase
6	V _{FO}	Fault Output
7	V _{TS}	Output for LVIC Temperature Sensing Voltage Output
8	C _{SC}	Shut Down Input for Short-Circuit Current Detection Input
9	IN _(UH)	Signal Input for High-Side U-Phase
10	V _{DD(H)}	High-Side Common Bias Voltage for IC and IGBTs Driving
11	V _{B(U)}	High-Side Bias Voltage for U-Phase IGBT Driving
12	V _{S(U)}	High-Side Bias Voltage Ground for U-Phase IGBT Driving
13	IN _(VH)	Signal Input for High-Side V-Phase
14	V _{DD(H)}	High-Side Common Bias Voltage for IC and IGBTs Driving
15	V _{B(V)}	High-Side Bias Voltage for V-Phase IGBT Driving
16	V _{S(V)}	High-Side Bias Voltage Ground for V Phase IGBT Driving
17	IN _(WH)	Signal Input for High-Side W-Phase
18	V _{DD(H)}	High-Side Common Bias Voltage for IC and IGBTs Driving
19	V _{B(W)}	High-Side Bias Voltage for W-Phase IGBT Driving
20	V _{S(W)}	High-Side Bias Voltage Ground for W-Phase IGBT Driving
21	N _U	Negative DC-Link Input for U-Phase
22	N _V	Negative DC-Link Input for V-Phase
23	N _W	Negative DC-Link Input for W-Phase
24	U	Output for U-Phase
25	V	Output for V-Phase
26	W	Output for W-Phase
27	Р	Positive DC-Link Input

Internal Equivalent Circuit and Input/Output Pins

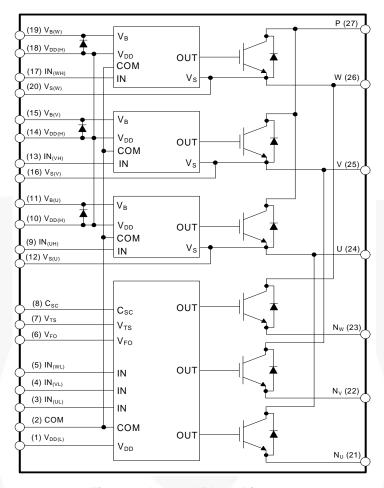


Figure 3. Internal Block Diagram

Notes

- 1. Inverter low-side is composed of three IGBTs, freewheeling diodes for each IGBT, and one control IC. It has gate drive and protection functions.
- 2. Inverter power side is composed of four inverter DC-link input terminals and three inverter output terminals.
- 3. Inverter high-side is composed of three IGBTs, freewheeling diodes, and three drive ICs for each IGBT.

Absolute Maximum Ratings ($T_J = 25^{\circ}C$, Unless Otherwise Specified)

Inverter Part

Symbol	Parameter	Conditions	Rating	Unit
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	450	V
V _{PN(Surge)}	Supply Voltage (Surge)	Applied between P - N _U , N _V , N _W	500	V
V _{CES}	Collector - Emitter Voltage		600	V
± I _C	Each IGBT Collector Current	$T_C = 25$ °C, $T_J \le 150$ °C (Note 4)	30	Α
± I _{CP}	Each IGBT Collector Current (Peak)	T_C = 25°C, $T_J \le$ 150°C, Under 1 ms Pulse Width (Note 4)	60	А
P _C	Collector Dissipation	T _C = 25°C per One Chip (Note 4)	89	W
TJ	Operating Junction Temperature		-40 ~ 150	°C

Control Part

Symbol	Parameter	Conditions	Rating	Unit
V _{DD}	Control Supply Voltage	Applied between V _{DD(H)} , V _{DD(L)} - COM	20	V
V _{BS}	High-Side Control Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}$, $V_{B(V)}$ - $V_{S(V)}$, $V_{B(W)}$ - $V_{S(W)}$	20	V
V _{IN}	Input Signal Voltage	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	-0.3 ~ V _{DD} +0.3	V
V _{FO}	Fault Output Supply Voltage	Applied between V _{FO} - COM	-0.3 ~ V _{DD} +0.3	V
I _{FO}	Fault Output Current	Sink Current at V _{FO} pin	2	mA
V _{SC}	Current Sensing Input Voltage	Applied between C _{SC} - COM	-0.3 ~ V _{DD} +0.3	٧

Bootstrap Diode Part

Symbol	Parameter	Conditions	Rating	Unit
V_{RRM}	Maximum Repetitive Reverse Voltage		600	V
l _F	Forward Current	$T_C = 25^{\circ}C$, $T_J \le 150^{\circ}C$ (Note 4)	0.5	Α
I _{FP}	Forward Current (Peak)	T_C = 25°C, $T_J \le$ 150°C, Under 1 ms Pulse Width (Note 4)	2.0	Α
T_J	Operating Junction Temperature		-40 ~ 150	°C

Total System

Symbol	Parameter	Conditions	Rating	Unit
V _{PN(PROT)}	Self Protection Supply Voltage Limit (Short Circuit Protection Capability)	$V_{DD} = V_{BS} = 13.5 \sim 16.5 \text{ V}, T_{J} = 150 ^{\circ}\text{C},$ Non-repetitive, < 2 μs	400	V
T _C	Module Case Operation Temperature	See Figure 2	-40 ~ 125	°C
T _{STG}	Storage Temperature		-40 ~ 125	°C
V _{ISO}	Isolation Voltage	60 Hz, Sinusoidal, AC 1 minute, Connection Pins to Heat Sink Plate	2500	V _{rms}

Thermal Resistance

Ī	Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Ī	R _{th(j-c)Q}		Inverter IGBT part (per 1 / 6 module)	-	-	1.4	°C / W
ĺ	R _{th(j-c)F}	(Note 5)	Inverter FWD part (per 1 / 6 module)	-	-	2.4	°C/W

- ${\it 4. \ \, These \, values \, had \, been \, made \, an \, acquisition \, by \, the \, calculation \, considered \, to \, design \, factor.}$
- 5. For the measurement point of case temperature (T_{C}), please refer to Figure 2.

$\textbf{Electrical Characteristics} \ \, (T_J = 25^{\circ}C, \, \text{Unless Otherwise Specified})$

Inverter Part

Symbol		Parameter	Cond	itions	Min.	Тур.	Max.	Unit
V	CE(SAT)	Collector - Emitter Saturation Voltage	$V_{DD} = V_{BS} = 15 \text{ V}$ $V_{IN} = 5 \text{ V}$	I _C = 30 A, T _J = 25°C	-	1.6	2.2	V
	V _F	FWDi Forward Voltage	V _{IN} = 0 V	I _F = 30 A, T _J = 25°C	-	2.0	2.6	V
HS	t _{ON}	Switching Times	$V_{PN} = 300 \text{ V}, V_{DD} = 15$	V, I _C = 30 A	0.50	0.90	1.40	μS
	t _{C(ON)}		$T_J = 25^{\circ}C$ $V_{IN} = 0 \text{ V} \leftrightarrow 5 \text{ V}, \text{ Induc}$	tive Load	-	0.20	0.60	μS
	t _{OFF}		See Figure 5	MIVE LOUG	-	0.85	1.35	μS
	t _{C(OFF)}		(Note 6)	(Note 6)	-	0.15	0.45	μS
	t _{rr}				-	0.08	-	μS
LS	t _{ON}		$V_{PN} = 300 \text{ V}, V_{DD} = 15$	V, I _C = 30 A	0.40	0.80	1.30	μS
	t _{C(ON)}		$T_J = 25^{\circ}C$ $V_{IN} = 0 V \leftrightarrow 5 V$, Induc	tive Load	-	0.25	0.60	μS
	t _{OFF}		See Figure 5	NIVO LOUG	-	0.90	1.40	μS
	t _{C(OFF)}		(Note 6)	Note 6)	-	0.15	0.45	μS
	t _{rr}				-	0.10	-	μS
	I _{CES}	Collector - Emitter Leakage Current	V _{CE} = V _{CES}		-	=	5	mA

^{6.} t_{ON} and t_{OFF} include the propagation delay time of the internal drive IC. t_{C(ON)} and t_{C(OFF)} are the switching time of IGBT itself under the given gate driving condition internally. For the detailed information, *please see Figure 4*.

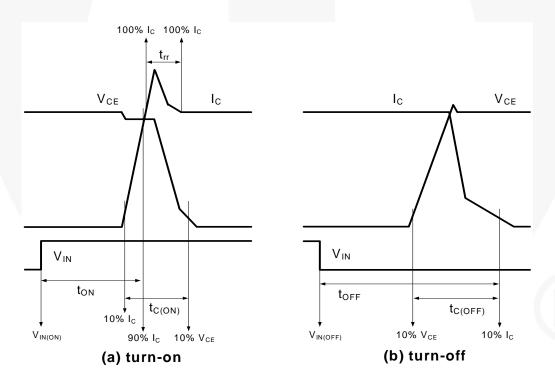


Figure 4. Switching Time Definition

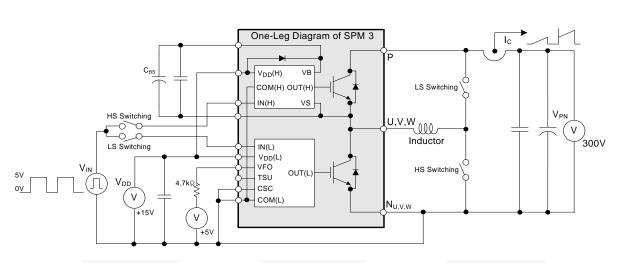


Figure 5. Example Circuit for Switching Test

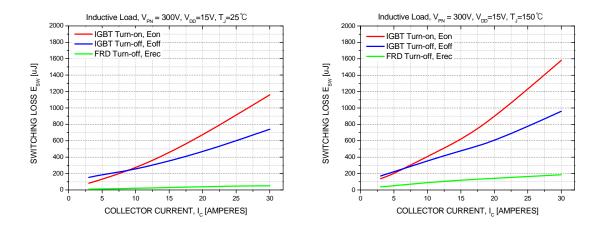


Figure 6. Switching Loss Characteristics

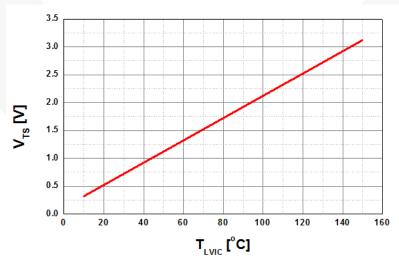


Figure 7. Temperature Profile of V_{TS} (Typical)

Bootstrap Diode Part

S	Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
	V_{F}	Forward Voltage	$I_F = 0.1 \text{ A}, T_J = 25^{\circ}\text{C}$	-	2.5	-	V
	t _{rr}	Reverse Recovery Time	I_F = 0.1 A, dI_F / dt = 50 A / μ s, T_J = 25°C	-	80	-	ns

Control Part

Symbol	Parameter	Condition	s	Min.	Тур.	Max.	Unit
I _{QDDH}	Quiescent V _{DD} Supply Current	V _{DD(H)} = 15 V, IN _(UH,VH,WH) = 0 V	V _{DD(H)} - COM	-	-	0.50	mA
I _{QDDL}		V _{DD(L)} = 15 V, IN _(UL,VL, WL) = 0 V	V _{DD(L)} - COM	-	-	6.00	mA
I _{PDDH}	Operating V _{DD} Supply Current	$V_{\mathrm{DD(H)}} = 15$ V, $f_{\mathrm{PWM}} = 20$ kHz, duty = 50%, applied to one PWM signal input for High-Side	V _{DD(H)} - COM	-	-	0.50	mA
I _{PDDL}		$V_{DD(L)} = 15V$, $f_{PWM} = 20$ kHz, duty = 50%, applied to one PWM signal input for Low- Side	V _{DD(L)} - COM	-	-	10.0	mA
I _{QBS}	Quiescent V _{BS} Supply Current	$V_{BS} = 15 \text{ V},$ $IN_{(UH, VH, WH)} = 0 \text{ V}$	$V_{B(U)} - V_{S(U)},$ $V_{B(V)} - V_{S(V)},$ $V_{B(W)} - V_{S(W)}$		-	0.30	mA
I _{PBS}	Operating V _{BS} Supply Current	$\begin{split} &V_{DD}=V_{BS}=15\text{ V,}\\ &f_{PWM}=20\text{ kHz, duty}=50\%,\\ &\text{applied to one PWM signal}\\ &\text{input for High-Side} \end{split}$		- \	-	4.50	mA
V _{FOH}	Fault Output Voltage	V_{DD} = 15 V, V_{SC} = 0 V, V_{FO} Ci Pull-up	rcuit: 4.7 kΩ to 5 V	4.5	-	-	V
V _{FOL}		V_{DD} = 15 V, V_{SC} = 1 V, V_{FO} Ci Pull-up	rcuit: 4.7 kΩ to 5 V	-	-	0.5	V
V _{SC(ref)}	Short Circuit Trip Level	V _{DD} = 15 V (Note 7)	C _{SC} - COM _(L)	0.45	0.50	0.55	V
UV_DDD	Supply Circuit Under-	Detection Level	7	9.8	-	13.3	V
UV_DDR	Voltage Protection	Reset Level		10.3	-	13.8	V
UV _{BSD}		Detection Level	Detection Level		-	12.5	>
UV_{BSR}		Reset Level		9.5	-	13.0	V
t _{FOD}	Fault-Out Pulse Width			50	-	-	μS
V _{TS}	LVIC Temperature Sensing Voltage Output	$V_{DD(L)} = 15 \text{ V}, T_{LVIC} = 25^{\circ}\text{C} \text{ (No See Figure 7)}$	ote 8)	540	640	740	mV
V _{IN(ON)}	ON Threshold Voltage	Applied between IN _(UH, VH, WH)	- COM,	-	-	2.6	V
V _{IN(OFF)}	OFF Threshold Voltage	IN _(UL, VL, WL) - COM		0.8	-	J/ -	V

^{7.} Short-circuit current protection is functioning only at the low-sides.

 $^{8.\} T_{LVIC} \ is \ the \ temperature \ of \ LVIC \ itself. \ V_{TS} \ is \ only \ for \ sensing \ temperature \ of \ LVIC \ and \ can \ not \ shutdown \ IGBTs \ automatically.$

Recommended Operating Conditions

Symbol	Parameter	Conditions		Value		Unit
Symbol	Parameter	Conditions		Тур.	Max.	Jill
V _{PN}	Supply Voltage	Applied between P - N _U , N _V , N _W	-	300	400	V
V _{DD}	Control Supply Voltage	Applied between V _{DD(H)} - COM, V _{DD(L)} - COM	14.0	15	16.5	V
V _{BS}	High-Side Bias Voltage	Applied between $V_{B(U)}$ - $V_{S(U)}$, $V_{B(V)}$ - $V_{S(V)}$, $V_{B(W)}$ - $V_{S(W)}$	13.0	15	18.5	V
dV _{DD} / dt, dV _{BS} / dt	Control Supply Variation		- 1	-	1	V / μs
t _{dead}	Blanking Time for Preventing Arm - Short	For Each Input Signal	1.0	-	-	μS
f _{PWM}	PWM Input Signal	$-40^{\circ}C \le T_{C} \le 125^{\circ}C, -40^{\circ}C \le T_{J} \le 150^{\circ}C$	-	-	20	kHz
V _{SEN}	Voltage for Current Sensing	Applied between N _U , N _V , N _W - COM (Including Surge Voltage)	- 5		5	V
PW _{IN(ON)}	Minimum Input Pulse	V_{DD} = V_{BS} = 15 V, I_{C} \leq 60 A, Wiring Inductance	2.0	-	-	μS
PW _{IN(OFF)}	Width	between N _{U, V, W} and DC Link N < 10nH (Note 9)	2.0	-	-	
TJ	Junction Temperature		- 40	-	150	°C

Note:

^{9.} This product might not make response if input pulse width is less than the recommanded value.

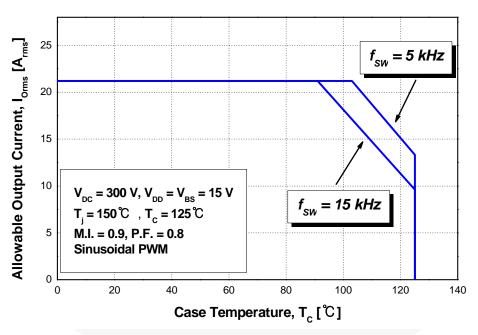


Figure 8. Allowable Maximum Output Current

Note:

10. This allowable output current value is the reference data for the safe operation of this product. This may be different from the actual application and operating condition.

Mechanical Characteristics and Ratings

Doromotor	Con	ditions		Limits		l lmi4
Parameter	Con	aitions	Min.	Тур.	Max.	Unit
Device Flatness	See Figure 9		0	-	+150	μm
Mounting Torque	Mounting Screw: M3	Recommended 0.7 N • m	0.6	0.7	0.8	N•m
	See Figure 10	Recommended 7.1 kg • cm	6.2	7.1	8.1	kg • cm
Terminal Pulling Strength	Load 19.6 N		10	-	-	S
Terminal Bending Strength	Load 9.8 N, 90 deg. bend		2	-	-	times
Weight			-	15	-	g

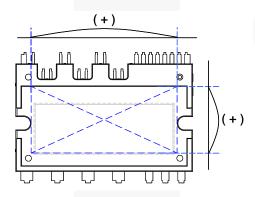


Figure 9. Flatness Measurement Position

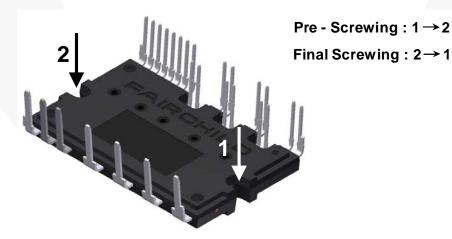


Figure 10. Mounting Screws Torque Order

- 11. Do not make over torque when mounting screws. Much mounting torque may cause DBC cracks, as well as bolts and Al heat-sink destruction.
- 12. Avoid one-sided tightening stress. Figure 10 shows the recommended torque order for mounting screws. Uneven mounting can cause the DBC substrate of package to be damaged. The pre-screwing torque is set to 20 ~ 30% of maximum torque rating.

Time Charts of SPMs Protective Function

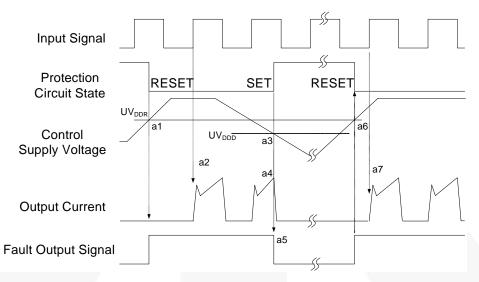


Figure 11. Under-Voltage Protection (Low-Side)

- a1 : Control supply voltage rises: After the voltage rises UV_{DDR}, the circuits start to operate when next input is applied.
- a2: Normal operation: IGBT ON and carrying current.
- a3 : Under voltage detection (UV_{DDD}).
- a4: IGBT OFF in spite of control input condition.
- a5: Fault output operation starts with a fixed pulse width.
- a6: Under voltage reset (UV_{DDR}).
- a7: Normal operation: IGBT ON and carrying current by triggering next signal from LOW to HIGH.

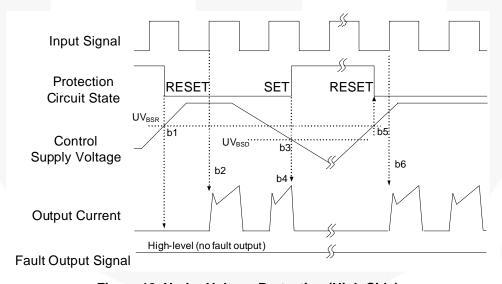


Figure 12. Under-Voltage Protection (High-Side)

- b1 : Control supply voltage rises: After the voltage reaches UV_{BSR}, the circuits start to operate when next input is applied.
- b2: Normal operation: IGBT ON and carrying current.
- b3 : Under voltage detection (UV_{BSD}).
- b4: IGBT OFF in spite of control input condition, but there is no fault output signal.
- b5 : Under voltage reset (UV_{BSR}).
- b6: Normal operation: IGBT ON and carrying current by triggering next signal from LOW to HIGH.

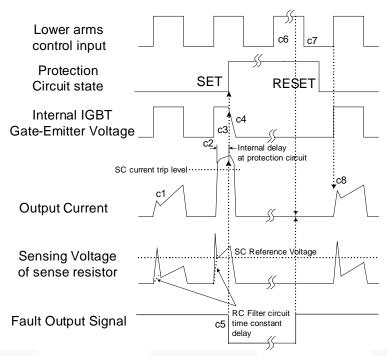


Figure 13. Short-Circuit Current Protection (Low-Side Operation only)

(with the external sense resistance and RC filter connection)

- c1: Normal operation: IGBT ON and carrying current.
- c2 : Short circuit current detection (SC trigger).
- c3: All low-side IGBT's gate are hard interrupted.
- c4: All low-side IGBTs turn OFF.
- c5: Fault output operation starts with a fixed pulse width.
- c6: Input HIGH: IGBT ON state, but during the active period of fault output the IGBT doesn't turn ON.
- c7: Fault output operation finishes, but IGBT doesn't turn on until triggering next signal from LOW to HIGH.
- c8: Normal operation: IGBT ON and carrying current.

Input/Output Interface Circuit

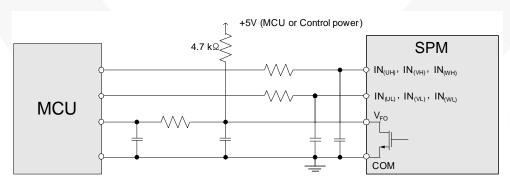


Figure 14. Recommended CPU I/O Interface Circuit

Note:

13. RC coupling at each input might change depending on the PWM control scheme used in the application and the wiring impedance of the application's printed circuit board. The input signal section of the Motion SPM 3 product integrates 5 k Ω (typ.) pull-down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.

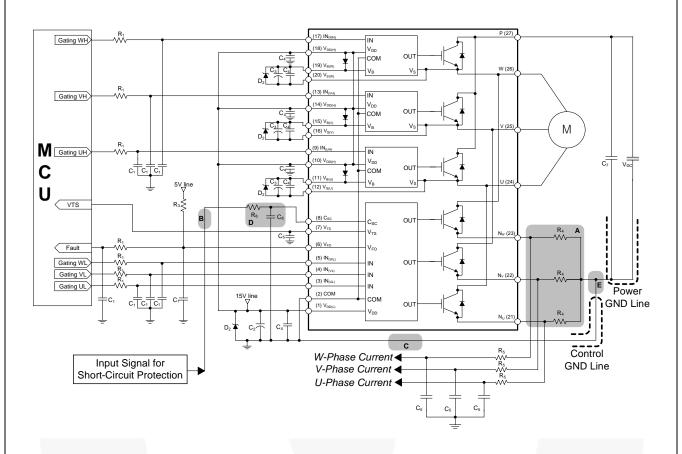
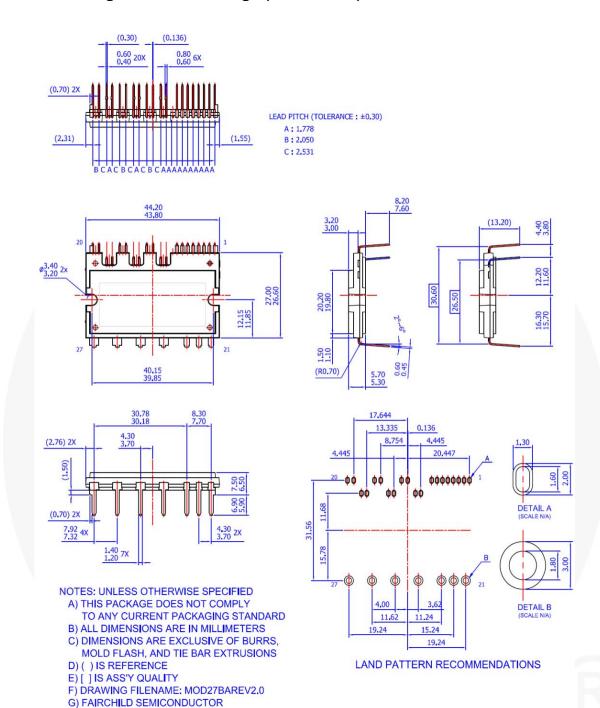


Figure 15. Typical Application Circuit

- 14. To avoid malfunction, the wiring of each input should be as short as possible. (less than 2 3 cm)
- 15. V_{FO} output is open-drain type. This signal line should be pulled up to the positive side of the MCU or control power supply with a resistor that makes I_{FO} up to 2 mA. Please refer to Figure 14.
- 16. Input signal is active-HIGH type. There is a 5 k Ω resistor inside the IC to pull-down each input signal line to GND. RC coupling circuits should be adopted for the prevention of input signal oscillation. R_1C_1 time constant should be selected in the range 50 150 ns. (Recommended R_1 = 100 Ω , C_1 = 1 nF)
- 17. Each wiring pattern inductance of A point should be minimized (Recommend less than 10nH). Use the shunt resistor R₄ of surface mounted (SMD) type to reduce wiring inductance. To prevent malfunction, wiring of point E should be connected to the terminal of the shunt resistor R₄ as close as possible.
- 18. To prevent errors of the protection function, the wiring of B, C, and D point should be as short as possible.
- 19. In the short-circuit protection circuit, please select the R_6C_6 time constant in the range 1.5 ~ 2 μ s. Do enough evaluaiton on the real system because short-circuit protection time may vary wiring pattern layout and value of the R_6C_6 time constant.
- 20. Each capacitor should be mounted as close to the pins of the Motion SPM® 3 product as possible.
- 21. To prevent surge destruction, the wiring between the smoothing capacitor C₇ and the P & GND pins should be as short as possible. The use of a high-frequency non-inductive capacitor of around 0.1 ~ 0.22 µF between the P & GND pins is recommended.
- 22. Relays are used at almost every systems of electrical equipments at industrial application. In these cases, there should be sufficient distance between the CPU and the relays.
- 23. The zener diode or transient voltage suppressor should be adopted for the protection of ICs from the surge destruction between each pair of control supply terminals (Recommanded zener diode is 22 V / 1 W, which has the lower zener impedance characteristic than about 15 \(\Omega \)).
- 24. C₂ of around 7 times larger than bootstrap capacitor C₃ is recommended.
- 25. Please choose the electrolytic capacitor with good temperature characteristic in C_3 . Also, choose 0.1 ~ 0.2 μF R-category ceramic capacitors with good temperature and frequency characteristics in C_4 .

Detailed Package Outline Drawings (FNB33060T)



Package drawings are provided as a service to customers considering Fairchild components. Drawings may change in any manner without notice. Please note the revision and/or data on the drawing and contact a FairchildSemiconductor representative to verify or obtain the most recent revision. Package specifications do not expand the terms of Fairchild's worldwide therm and conditions, specifically the the warranty therein, which covers Fairchild products.

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http://www.fairchildsemi.com/dwg/MO/MOD27BA.pdf





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Definition of Terms		
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