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[^0]ON Semiconductor ${ }^{\text {® }}$
FXLA102

## Low-Voltage Dual-Supply 2-Bit Voltage Translator with Configurable Voltage Supplies and Signal Levels, 3-State Outputs, and Auto Direction Sensing

## Features

- Bi-Directional Interface betw een Tw o Levels: from 1.1 V to 3.6 V
- Fully Configurable: Inputs and Outputs Track Vcc Level
- Non-Preferential Pow er-Up; Either $\mathrm{V}_{\mathrm{cc}}$ May Be Pow ered Up First
- Outputs Sw itch to 3-State if Either $\mathrm{V}_{\mathrm{cc}}$ is at GND
- Pow er-Off Protection
- Bus-Hold on Data Inputs Eliminates the Need for Pull-Up Resistors; Do Not Use Pull-Up Resistors on A or B Ports
- Control Input (/OE) Referenced to $\mathrm{V}_{\mathrm{cca}}$ Voltage
- Packaged in MicroPak ${ }^{\text {TM }} 8(1.6 \mathrm{~mm} \times 1.6 \mathrm{~mm})$
- Direction Control Not Necessary
- 100 Mbps Throughput when Translating Betw een 1.8 V and 2.5 V
- ESD Protection Exceeds:
- 15 kV HBM ((B Port VO to GND) per JESD22-

A114 \& Mil Std 883e 3015.7)

- 8 kV HBM ((A Port VO to GND) per JESD22-A114 \& Mil Std 883e 3015.7)
- 2 kV CDM (per ESD STM 5.3)


## Description

The FXLA102 is a configurable dual-voltage supply translator for both uni-directional and bi-directional voltage translation betw een two logic levels. The device allows translation betw een voltages as high as 3.6 V to as low as 1.1 V . The A port tracks the $\mathrm{V}_{\mathrm{cca}}$ level and the B port tracks the $\mathrm{V}_{\text {ccB }}$ level. This allow s for bi-directional voltage translation over a variety of voltage levels: $1.2 \mathrm{~V}, 1.5 \mathrm{~V}, 1.8 \mathrm{~V}, 2.5 \mathrm{~V}$, and 3.3 V .

The device remains in three-state as long as either $\mathrm{V}_{\mathrm{cc}}=0 \mathrm{~V}$, allow ing either $\mathrm{V}_{\mathrm{cc}}$ to be pow ered up first. Internal pow er-down control circuits place the device in 3-state if either $\mathrm{V}_{\mathrm{Cc}}$ is removed.

The /OE input, when HIGH, disables both the A and B ports by placing them in a 3 -state condition. The /OE input is supplied by $V_{\text {CcA }}$.

The FXLA102 supports bi-directional translation without the need for a direction control pin. The tw o ports of the device have auto-direction sense capability. Ether port may sense an input signal and transfer it as an output signal to the other port.

## Ordering Information

| Part Number | Top <br> Mark | Operating <br> Temperature <br> Range | Package | Packing <br> Method |
| :--- | :---: | :---: | :---: | :---: |
| FXLA102L8X | XF | -40 to $85^{\circ} \mathrm{C}$ | 8 -Lead MicroPak ${ }^{\top M} 1.6 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ Package | 5 K Units Tape <br> and Reel |

## Pin Configuration



Figure 1. Pin Configuration (Top Through View)

## Pin Definitions

| Pin \# | Name |  |
| :---: | :---: | :--- |
| 1 | V CCA | A-Side Pow er Supply |
| 2 | $\mathrm{~A}_{0}$ | A Side Input or 3-State Output |
| 3 | $\mathrm{~A}_{1}$ | A Side Input or 3-State Output |
| 4 | GND | Ground |
| 5 | IOE | Output Enable Input |
| 6 | $\mathrm{~B}_{1}$ | B Side Input or 3-State Output |
| 7 | $\mathrm{~B}_{0}$ | B Side Input or 3-State Output |
| 8 | $\mathrm{~V}_{\text {CCB }}$ | B Side Pow er Supply |

## Functional Diagram



Figure 2. Functional Diagram

Function Table

| Control | Outputs |
| :---: | :---: |
| $/ \mathrm{OE}$ |  |
| L | Normal Operation |
| H | 3-State |

$\mathrm{H}=\mathrm{HIGH}$ Logic Level
L = LOW Logic Level

## Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol | Parameter | Conditions | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Vcc | Supply Voltage | $\mathrm{V}_{\text {CCA }}$ | -0.5 | 4.6 | V |
|  |  | $\mathrm{V}_{\text {CCB }}$ | -0.5 | 4.6 |  |
| V | DC Input Voltage | VO Ports A and B | -0.5 | 4.6 | V |
|  |  | Control Input (/OE) | -0.5 | 4.6 |  |
| Vo | Output Voltage ${ }^{\text {2 }}$ | Output 3-State | -0.5 | 4.6 | v |
|  |  | Output Active ( $\mathrm{A}_{\mathrm{n}}$ ) | -0.5 | $\mathrm{V}_{\text {CCA }}+0.5$ |  |
|  |  | Output Active ( $\mathrm{B}_{\mathrm{n}}$ ) | -0.5 | $\mathrm{V}_{\text {CCB }}+0.5$ |  |
| lik | DC Input Diode Current | V < 0 V |  | -50 | mA |
| 1ок | DC Output Diode Current | Vo<0V |  | -50 | mA |
|  |  | $\mathrm{V}_{\mathrm{o}}>\mathrm{V}$ cc |  | +50 |  |
| loh/loL | DC Output Source/Sink Current |  | -50 | +50 | mA |
| lcc | DC V Cc or Ground Current (per Supply Pin) |  |  | $\pm 100$ | mA |
| Tstg | Storage Temperature Range |  | -65 | +150 | ${ }^{\circ} \mathrm{C}$ |
| PD | Pow er Dissipation |  |  | 5 | mW |
| ESD | Human Body Model, JESD22-A114 | B Port VO to GND |  | 15 | kV |
|  |  | A Port VO to GND |  | 8 |  |
|  | Charged Device Model, JESD22-C101 |  |  | 2 |  |

## Notes:

1. lo absolute maximum ratings must be observed.
2. All unused inputs and input/outputs must be held at $\mathrm{V}_{\mathrm{CCi}}$ or GND.

## Recommended Operating Conditions

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. ON Semiconductor does not recommend exceeding them or designing to Absolute Maximum Ratings.

| Symbol | Parameter | Conditions | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| VCC | Pow er Supply | Operating $\mathrm{V}_{\text {CCA }}$ or $\mathrm{V}_{\text {CCB }}$ | 1.1 | 3.6 | V |
| $\mathrm{V}_{\text {IN }}$ | Input Voltage | Ports A and B | 0 | 3.6 | V |
|  |  | Control Input (/OE) | 0 | V CCA | V |
|  | Dynamic Output Current loh/loL | V cc $=3.0 \mathrm{~V}$ to 3.6 V |  | $\pm 12$ | mA |
|  |  | $\mathrm{V} \mathrm{cc}=2.3 \mathrm{~V}$ to 2.7 V |  | $\pm 8$ |  |
|  |  | $\mathrm{V}_{\mathrm{Cc}}=1.65 \mathrm{~V}$ to 1.95 V |  | $\pm 5$ |  |
|  |  | $\mathrm{V}_{\mathrm{Cc}}=1.40 \mathrm{~V}$ to 1.65 V |  | $\pm 3$ |  |
|  |  | $\mathrm{V}_{\mathrm{CC}}=1.1 \mathrm{~V}$ to 1.4 V |  | $\pm 2$ |  |
|  | Static Output Current | $\mathrm{V}_{\mathrm{cc}}=1.1 \mathrm{~V}$ to 3.6 V |  | $\pm 4$ | $\mu \mathrm{A}$ |
| $\mathrm{T}_{\mathrm{A}}$ | Operating Temperature, Free Air |  | -40 | +85 | ${ }^{\circ} \mathrm{C}$ |
| dt/dV | Maximum Input Edge Rate | $\mathrm{V}_{\text {CCAB }}=1.1$ to 3.6 V |  | 10 | $\mathrm{ns} / \mathrm{V}$ |
| $\Theta_{J A}$ | Thermal Resistance |  |  | 280 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

## Power-Up/Power-Down Sequence

FXL translators offer an advantage in that either Vcc may be pow ered up first. This benefit derives from the chip design. When either $\mathrm{V}_{\mathrm{cc}}$ is at 0 V , outputs are in a high-impedance state. The control input (/OE) is designed to track the $\mathrm{V}_{\text {CCA }}$ supply. A pull-up resistor tying /OE to Vcca should be used to ensure that bus contention, excessive currents, or oscillations do not occur during power-up or power-down. The size of the pull-up resistor is based upon the current-sinking capability of the device driving the /OE pin.

The recommended pow er-up sequence is:

1. Apply pow er to the first $\mathrm{V}_{\mathrm{cc}}$.
2. Apply pow er to the second $\mathrm{V}_{\text {cc }}$.
3. Drive the /OE input LOW to enable the device.

The recommended power-dow n sequence is:

1. Drive /OE input HIGH to disable the device.
2. Remove pow er from either $\mathrm{V}_{\mathrm{cc}}$.
3. Remove pow er from other V cc.

## Pull-Up/Pull-Down Resistors

Do not use pull-up or pull-down resistors. This device has bus-hold circuits: pull-up or pull-down resistors are not recommended because they interfere with the output state. The current through these resistors may exceed the hold drive, $l_{(\text {(HOLD })}$ and/or $l_{(O D)}$ bus-hold currents. The bus-hold feature eliminates the need for extra resistors.

## DC Electrical Characteristics

$\mathrm{T}_{A}=-40$ to $85^{\circ} \mathrm{C}$.

| Symbol | Parameter | Conditions | $\mathrm{V}_{\text {cca }}(\mathrm{V})$ | $\mathrm{V}_{\text {ccв }}(\mathrm{V})$ | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VIHA | High-Level Input Voltage | Data Inputs $A_{n}$ Control Pin /OE | 2.70 to 3.60 | 1.10 to 3.60 | 2.00 |  |  | V |
|  |  |  | 2.30 to 2.70 |  | 1.60 |  |  |  |
|  |  |  | 1.65 to 2.30 |  | . 65 xV cca |  |  |  |
|  |  |  | 1.40 to 1.65 |  | . $65 \times \mathrm{V}$ CCA |  |  |  |
|  |  |  | 1.10 to 1.40 |  | . $90 \times \mathrm{V}$ CCA |  |  |  |
| $\mathrm{V}_{\text {IHB }}$ |  | Data Inputs $\mathrm{B}_{\mathrm{n}}$ | 1.10 to 3.60 | 2.70 to 3.60 | 2.00 |  |  | V |
|  |  |  |  | 2.30 to 2.70 | 1.60 |  |  |  |
|  |  |  |  | 1.65 to 2.30 | . $65 \times \mathrm{V}$ ccв |  |  |  |
|  |  |  |  | 1.40 to 1.65 | . $65 \times \mathrm{V}$ ссв |  |  |  |
|  |  |  |  | 1.10 to 1.40 | . $90 x \mathrm{~V}$ ссв |  |  |  |
| $V_{\text {ILA }}$ | Low-Level Input Voltage | Data Inputs $A_{n}$ Control Pin /OE | 2.70 to 3.60 | 1.10 to 3.60 |  |  | . 80 | V |
|  |  |  | 2.30 to 2.70 |  |  |  | . 70 |  |
|  |  |  | 1.65 to 2.30 |  |  |  | . $35 \times \mathrm{V}$ CCA |  |
|  |  |  | 1.40 to 1.65 |  |  |  | . $35 \times \mathrm{V}$ CCA |  |
|  |  |  | 1.10 to 1.40 |  |  |  | .10xVcca |  |
| VILB |  | Data Inputs $\mathrm{B}_{\mathrm{n}}$ | 1.10 to 3.60 | 2.70 to 3.60 |  |  | . 80 | V |
|  |  |  |  | 2.30 to 2.70 |  |  | . 70 |  |
|  |  |  |  | 1.65 to 2.30 |  |  | . $35 \times \mathrm{V}$ CCB |  |
|  |  |  |  | 1.40 to 1.65 |  |  | . $35 \times \mathrm{x}$ ССС |  |
|  |  |  |  | 1.10 to 1.40 |  |  | . $10 \times \mathrm{V}$ CCB |  |
| $\mathrm{V}_{\text {OHA }}$ | High-Level Output Voltage 3 | ІОн $=-4 \mu \mathrm{~A}$ | 1.10 to 3.60 | 1.10 to 3.60 | $\mathrm{V}_{\text {CCA }}-.40$ |  |  | V |
| $\mathrm{V}_{\text {онв }}$ |  | $\mathrm{l}_{\text {OH }}=-4 \mu \mathrm{~A}$ | 1.10 to 3.60 | 1.10 to 3.60 | $\mathrm{V}_{\text {ccb }}-.40$ |  |  |  |
| V ${ }_{\text {OLA }}$ | Low -Level Output Voltage ${ }^{3}$ | $\mathrm{loL}=4 \mu \mathrm{~A}$ | 1.10 to 3.60 | 1.10 to 3.60 |  |  | . 4 | V |
| V OLB |  | loL=4 $\mu \mathrm{A}$ | 1.10 to 3.60 | 1.10 to 3.60 |  |  | . 4 |  |
| $l_{\text {(HOLD }}$ | Bus-Hold Input Minimum Drive Current | $\mathrm{V}_{\text {IN }}=0.80 \mathrm{~V}$ | 3.00 | 3.00 | 75.0 |  |  | $\mu \mathrm{A}$ |
|  |  | $\mathrm{V}_{\mathrm{IN}}=2.00 \mathrm{~V}$ | 3.00 | 3.00 | -75.0 |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{IN}}=0.70 \mathrm{~V}$ | 2.30 | 2.30 | 45.0 |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{IN}}=1.60 \mathrm{~V}$ | 2.30 | 2.30 | -45.0 |  |  |  |
|  |  | $\mathrm{V}_{\text {IN }}=0.57 \mathrm{~V}$ | 1.65 | 1.65 | 25.0 |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{IN}}=1.07 \mathrm{~V}$ | 1.65 | 1.65 | -25.0 |  |  |  |
|  |  | $\mathrm{V}_{\text {IN }}=0.49 \mathrm{~V}$ | 1.40 | 1.40 | 11.0 |  |  |  |
|  |  | $\mathrm{V}_{\text {IN }}=0.91 \mathrm{~V}$ | 1.40 | 1.40 | -11.0 |  |  |  |
|  |  | $\mathrm{V}_{\mathrm{IN}}=0.11 \mathrm{~V}$ | 1.10 | 1.10 |  | 4.0 |  |  |
|  |  | $\mathrm{V}_{\text {IN }}=0.99 \mathrm{~V}$ | 1.10 | 1.10 |  | -4.0 |  |  |

## DC Electrical Characteristics (Continued)

$\mathrm{T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | Conditions | $\mathrm{V}_{\text {cca }}(\mathrm{V})$ | $\mathrm{V}_{\text {ccb }}(\mathrm{V})$ | Min. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{l}_{( }(\mathrm{ODH})$ | Bus-Hold Input Overdrive High Current ${ }^{(4)}$ | Data Inputs $A_{n}, B_{n}$ | 3.60 | 3.60 | 450.00 |  | $\mu \mathrm{A}$ |
|  |  |  | 2.70 | 2.70 | 300.00 |  |  |
|  |  |  | 1.95 | 1.95 | 200.00 |  |  |
|  |  |  | 1.60 | 1.60 | 120.00 |  |  |
|  |  |  | 1.40 | 1.40 | 80.00 |  |  |
| $\mathrm{l}_{(\text {(ODL) }}$ | Bus-Hold Input Overdrive Low Current 5 ) | Data Inputs $A_{n}, B_{n}$ | 3.60 | 3.60 | -450.00 |  | $\mu \mathrm{A}$ |
|  |  |  | 2.70 | 2.70 | -300.00 |  |  |
|  |  |  | 1.95 | 1.95 | -200.00 |  |  |
|  |  |  | 1.60 | 1.60 | -120.00 |  |  |
|  |  |  | 1.40 | 1.40 | -80.00 |  |  |
| $\\|$ | Input Leakage Current | Control Inputs /OE, $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {cca }}$ or GND | 1.10 to 3.60 | 3.60 |  | $\pm 1.0$ | $\mu \mathrm{A}$ |
| loff | Pow er-Off Leakage Current | $\mathrm{A}_{\mathrm{n}}$ Port $\mathrm{V}_{\mathrm{o}}=0 \mathrm{~V}$ to 3.6 V | 0 | 3.6 |  | $\pm 2.0$ | $\mu \mathrm{A}$ |
|  |  | $\mathrm{B}_{\mathrm{n}}$ Port $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ to 3.6 V | 3.60 | 0 |  | $\pm 2.0$ |  |
| loz | 3-State Output Leakage | Data Outputs $A_{n}, B_{n}$ $\mathrm{V}_{\mathrm{O}}=0 \mathrm{~V}$ or 3.6 V , $/ \mathrm{OE}=\mathrm{V}_{\mathrm{IH}}$ | 3.60 | 3.60 |  | $\pm 5.0$ | $\mu \mathrm{A}$ |
|  |  | Data Outputs Data Outputs $A_{n} V_{0}=0 \mathrm{~V}$ or $3.6 \mathrm{~V}, / \mathrm{OE}=\mathrm{GND}$ | 3.60 | 0 |  | $\pm 5.0$ |  |
|  |  | Data Outputs $\mathrm{B}_{\mathrm{n}}$ $\mathrm{V}_{\mathrm{o}}=0 \mathrm{~V}$ or 3.6 V , /OE=GND | 0 | 3.60 |  | $\pm 5.0$ |  |
| Iccab | Quiescent Supply | $\begin{aligned} & \mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\mathrm{ccl}} \text { or } \mathrm{GND} ; \mathrm{l}=0, \\ & / \mathrm{OE}=\mathrm{GND} \end{aligned}$ | 1.10 to 3.60 | 1.10 to 3.60 |  | 10.0 | $\mu \mathrm{A}$ |
| Iccz | Current 6' 7 |  | 1.10 to 3.60 | 1.10 to 3.60 |  | 10.0 | $\mu \mathrm{A}$ |
| Icca | Quiescent Supply Current | $\begin{aligned} & \mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {CCB }} \text { or GND; } \mathrm{l}=0 \\ & \mathrm{~B} \text {-to-A Direction, } \\ & \text { /OE=GND } \end{aligned}$ | 0 | 1.10 to 3.60 |  | -10.0 | $\mu \mathrm{A}$ |
|  |  |  | 1.10 to 3.60 | 0 |  | 10.0 |  |
| Іссв |  | $\mathrm{V}_{\mathrm{I}}=\mathrm{V}_{\text {CCA }}$ or GND ; $\mathrm{l}=0$, A-to-B Direction, /OE=GND | 1.10 to 3.60 | 0 |  | -10.0 | $\mu \mathrm{A}$ |
|  |  |  | 0 | 1.10 to 3.60 |  | 10.0 |  |

Notes:
3. This is the output voltage for static conditions. Dynamic drive specifications are given in the Dynamic Output Electrical Characteristics table.
4. An external drive must source at least the specified current to sw itch LOW-to-HIGH
5. An external drive must source at least the specified current to sw itch HIGH-to-LOW.
6. $\quad \mathrm{V}_{\mathrm{Cc}}$ is the $\mathrm{V}_{\mathrm{Cc}}$ associated $w$ ith the input side.
7. Reflects current per supply, $\mathrm{V}_{\text {cca }}$ or V ссв. $^{\text {. }}$

## Dynamic Output Electrical Characteristic

A Port ( $A_{n}$ )
Output Load: $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{R}_{\mathrm{L}} \geq \mathrm{M} \Omega\left(\mathrm{C}_{10}=4 \mathrm{pF}\right), \mathrm{T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} \mathrm{V}_{\mathrm{CCA}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCA}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCA}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCA}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ |  | $\left.\begin{array}{\|c\|} \hline \mathrm{V}_{\text {CCA }}=1.1 \mathrm{~V} \\ \text { to } 1.3 \mathrm{~V} \end{array} \right\rvert\, \begin{gathered} \text { Typ. } \\ \hline \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Typ. | Max. | Typ. | Max. | Typ. | Max | Typ. | Max. |  |  |
| trise | Output Rise Time A Port'9 |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| trall | Output Fall <br> Time A <br> Port ${ }^{(10)}$ |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| IOHD | $\begin{aligned} & \hline \text { Dynamic } \\ & \text { Output } \\ & \text { Current } \\ & \text { High'9' } \end{aligned}$ | -11.4 |  | -7.5 |  | -4.7 |  | -3.2 |  | -1.7 | mA |
| lod | Dynamic <br> Output <br> Current <br> Low <br>  <br> (10) | +11.4 |  | +7.5 |  | +4.7 |  | +3.2 |  | +1.7 | mA |

## B Port ( $\mathrm{B}_{\mathrm{n}}$ )

Output Load: $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}, \mathrm{R}_{\mathrm{L}} \geq \mathrm{M} \Omega\left(\mathrm{C}_{10}=5 \mathrm{pF}\right), \mathrm{T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} \mathrm{V}_{\mathrm{ccB}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \hline \mathrm{V}_{\mathrm{CCB}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.1 \mathrm{~V} \\ \text { t } 1.3 \mathrm{~V} \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Typ. | Max. | Typ. | Max. | Typ. | Max | Typ. | Max. | Typ. |  |
| trise | Output Rise Time B Port 9 ) |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| trall | $\begin{aligned} & \text { Output Fall } \\ & \text { Time }{ }^{\text {Ti }} \\ & \text { Port }{ }^{10} \text { ) } \end{aligned}$ |  | 3.0 |  | 3.5 |  | 4.0 |  | 5.0 | 7.5 | ns |
| IOHD | $\begin{array}{\|l\|} \hline \text { Dynamic } \\ \text { Output } \\ \text { Current } \\ \text { High } 9 \text { ) } \\ \hline \end{array}$ | -12.0 |  | -7.9 |  | -5.0 |  | -3.4 |  | -1.8 | mA |
| loLo | Dynamic Output Current Low | +12.0 |  | +7.9 |  | +5.0 |  | +3.4 |  | +1.8 | mA |

## Notes:

8. Dynamic output characteristics are guaranteed, but not tested.
9. See Figure 7.
10. See Figure 8.

## AC Characteristics

$\mathrm{V}_{\mathrm{CCA}}=3.0 \mathrm{~V}$ to $3.6 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} \hline \mathrm{V}_{\mathrm{CCB}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{ccs}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ |  | $\left.\begin{array}{\|c\|} \hline \mathrm{V}_{\mathrm{cCB}}=1.1 \mathrm{~V} \\ \text { to } 1.3 \mathrm{~V} \end{array} \right\rvert\, \begin{gathered} \text { Typ. } \\ \hline \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Max. | Min. | Max. | Min. | Max | Min. | Max. |  |  |
| tPLH,tPHL | A to B | 0.2 | 3.5 | 0.3 | 3.9 | 0.5 | 5.4 | 0.6 | 6.8 | 10.0 | ns |
|  | B to A | 0.2 | 3.5 | 0.2 | 3.8 | 0.3 | 5.0 | 0.5 | 6.0 | 7.0 | ns |
| tPzL,tpzH | /OE to A, /OE to B |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| tskew | $\begin{array}{\|l} \hline \text { A Port }{ }^{111}, \\ \text { B Port } \end{array}$ |  | 0.5 |  | 0.5 |  | 0.5 |  | 1.0 | 1.0 | ns |

$\mathrm{V}_{\mathrm{CCA}}=2.3 \mathrm{~V}$ to $2.7 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} \mathrm{V}_{\mathrm{cCB}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{cCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \hline \mathrm{V}_{\mathrm{CCB}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ |  | $\begin{array}{\|c\|} \hline \mathrm{V}_{\mathrm{ccB}}=1.1 \mathrm{~V} \\ \text { to } 1.3 \mathrm{~V} \\ \hline \text { Typ. } \\ \hline \end{array}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Max. | Min. | Max. | Min. | Max | Min. | Max. |  |  |
| tPLH,tPHL | A to B | 0.2 | 3.8 | 0.4 | 4.2 | 0.5 | 5.6 | 0.8 | 6.9 | 10.5 | ns |
|  | B to A | 0.3 | 3.9 | 0.4 | 4.2 | 0.5 | 5.5 | 0.5 | 6.5 | 7.0 | ns |
| tpz,tpze | $\begin{aligned} & \hline \text { IOE to A, } \\ & \text { IOE to B } \end{aligned}$ |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| tskew | $\begin{aligned} & \text { A Port }{ }^{111}, \\ & \text { B Port }{ }^{(11)} \end{aligned}$ |  | 0.5 |  | 0.5 |  | 0.5 |  | 1.0 | 1.0 | ns |

$\mathrm{V}_{\mathrm{CCA}}=1.65 \mathrm{~V}$ to $1.95 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} V_{C C B}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ |  | $\begin{array}{\|c} \mathrm{V}_{\mathrm{CCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{array}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ |  | $\mathrm{v}_{\mathrm{ccB}}=1.1 \mathrm{~V}$ <br> to 1.3 V$\|$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Max. | Min. | Max. | Min. | Max | Min. | Max. |  |  |
| tPLH,tpHL | A to B | 0.3 | 5.0 | 0.5 | 5.5 | 0.8 | 6.7 | 0.9 | 7.5 | 11.0 | ns |
|  | B to A | 0.5 | 5.4 | 0.5 | 5.6 | 0.8 | 6.7 | 1.0 | 7.0 | 7.0 | ns |
| tPzL,tpzH | $\begin{aligned} & \hline \text { OE to A, } \\ & \text { IOE to B } \end{aligned}$ |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| tskew | $\begin{aligned} & \text { A Port }{ }^{111}, \\ & \text { B Port }{ }^{(11)} \end{aligned}$ |  | 0.5 |  | 0.5 |  | 0.5 |  | 1.0 | 1.0 | ns |

Note:
11. Skew is the variation of propagation delay betw een output signals and applies only to output signals on the same port ( $\mathrm{A}_{\mathrm{n}}$ or $\mathrm{B}_{\mathrm{n}}$ ) and sw itching w ith the same polarity (LOW-to-HIGH or HIGH-to-LOW) (see Figure 10). Skew is guaranteed, but not tested.

AC Characteristics (Continued)
$\mathrm{V}_{\mathrm{CCA}}=1.4 \mathrm{~V}$ to $1.6 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \hline \mathrm{V}_{\mathrm{CCB}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{ccB}}=1.1 \mathrm{~V} \\ \text { to } 1.3 \mathrm{~V} \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Max. | Min. | Max. | Min. | Max | Min. | Max. | Typ. |  |
| tPLL,tpHL | A to B | 0.5 | 6.0 | 0.5 | 6.5 | 1.0 | 7.0 | 1.0 | 8.5 | 11.5 | ns |
|  | B to A | 0.6 | 6.8 | 0.8 | 6.9 | 0.9 | 7.5 | 1.0 | 8.5 | 9.0 | ns |
| tPzL,tpzH | $\begin{aligned} & \hline \text { OE to A, } \\ & \text { /OE to B } \end{aligned}$ |  | 1.7 |  | 1.7 |  | 1.7 |  | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| tskew | $\begin{aligned} & \text { A Port }{ }^{112)} \\ & \text { B Port }{ }^{12)} \end{aligned}$ |  | 1.0 |  | 1.0 |  | 1.0 |  | 1.0 | 1.0 | ns |

$V_{C C A}=1.1 \mathrm{~V}$ to $1.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$

| Symbol | Parameter | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{ccB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{cCB}}=1.1 \mathrm{~V} \\ \text { to } 1.3 \mathrm{~V} \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Typ. | Typ. | Typ. | Typ. | Typ. |  |
| tpLu,tpHL | A to B | 7.1 | 6.5 | 7.0 | 7.1 | 13.5 | ns |
|  | B to A | 10.3 | 10.5 | 10.8 | 11.3 | 13.5 | ns |
| tpzL,tPzH | /OE to A, /OE to B | 1.7 | 1.7 | 1.7 | 1.7 | 1.7 | $\mu \mathrm{s}$ |
| tskew | A Port, B Port ${ }^{(12)}$ | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | ns |

Note:
12. Skew is the variation of propagation delay betw een output signals and applies only to output signals on the same port ( $\mathrm{A}_{\mathrm{n}}$ or $\mathrm{B}_{\mathrm{n}}$ ) and switching with the same polarity (LOW-to-HIGH or HIGH-to-LOW) (see Figure 10). Skew is guaranteed, but not tested.

## Maximum Data Rate

$\mathrm{T}_{\mathrm{A}}=-40$ to $85^{\circ} \mathrm{C}$.

| $\mathrm{V}_{\text {cca }}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=3.0 \mathrm{~V} \\ \text { to } 3.6 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=2.3 \mathrm{~V} \\ \text { to } 2.7 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.65 \mathrm{~V} \\ \text { to } 1.95 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{CCB}}=1.4 \mathrm{~V} \\ \text { to } 1.6 \mathrm{~V} \end{gathered}$ | $\begin{gathered} \mathrm{V}_{\mathrm{ccs}}=1.1 \mathrm{~V} \text { to } \\ 1.3 \mathrm{~V} \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min. | Min. | Min. | Min. | Typ. |  |
| $\mathrm{V}_{\text {CCA }}=3.00 \mathrm{~V}$ to 3.60 V | 140 | 120 | 100 | 80 | 40 | Mbps |
| $\mathrm{V}_{\text {CCA }}=2.30 \mathrm{~V}$ to 2.70 V | 120 | 120 | 100 | 80 | 40 | Mbps |
| $\mathrm{V}_{\text {CCA }}=1.65 \mathrm{~V}$ to 1.95 V | 100 | 100 | 80 | 60 | 40 | Mbps |
| $\mathrm{V}_{\text {CCA }}=1.40 \mathrm{~V}$ to 1.60 V | 80 | 80 | 60 | 60 | 40 | Mbps |
| $\mathrm{V}_{\text {cca }}=1.10 \mathrm{~V}$ to 1.30 V | Typ. | Typ. | Typ. | Typ. | Typ. |  |
|  | 40 | 40 | 40 | 40 | 40 | Mbps |

Notes:
13. Maximum data rate is guaranteed, but not tested.
14. Maximum data rate is specified in megabits per second (see Figure 9). It is equivalent to two otimes the F-toggle frequency, specified in megahertz. For example, 100 Mbps is equivalent to 50 MHz .

## Capacitance

| Symbol | Parameter |  | Conditions | $\begin{gathered} \mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C} \\ \text { Typical } \end{gathered}$ | Units |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Cln | Input Capacitance Control Pin (/OE) |  | $\mathrm{V}_{\text {CCA }}=\mathrm{V}_{\text {ccB }}=\mathrm{GND}$ | 3 | pF |
| C/oo | Input / Output Capacitance | $\mathrm{A}_{n}$ | $\mathrm{V}_{\text {cca }}=\mathrm{V}_{\text {ccb }}=3.3 \mathrm{~V}, / \mathrm{OE}=\mathrm{V}_{\text {cca }}$ | 4 | pF |
|  |  | $\mathrm{B}_{n}$ |  | 5 |  |
| $\mathrm{Cpp}_{\text {d }}$ | Pow er Dissipation Capacitance |  | $\begin{aligned} & \mathrm{V}_{\mathrm{CCA}}=\mathrm{V}_{\mathrm{CCB}}=3.3 \mathrm{~V}, \mathrm{~V}_{\mathrm{I}}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CC}}, \\ & \mathrm{f}=10 \mathrm{MHz} \end{aligned}$ | 25 | pF |

## I/O Architecture Benefit

The FXLA102 /O architecture benefits the end user, beyond level translation, in the follow ing three ways:

Auto Direction without an external direction pin.
Drive Capacitive Loads. Automatically shifts to a higher current drive mode only during "Dynamic Mode" or HL / LH transitions.

Lower Power Consumption. Automatically shifts to low -pow er mode during "Static Mode" (no transitions), low ering pow er consumption.
The FXLA102 does not require a direction pin. Instead, the VO architecture detects input transitions on both side and automatically transfers the data to the corresponding output. For example, for a given channel, if both $A$ and $B$ side are at a static LOW, the direction has been established as $A \rightarrow B$, and a LH transition occurs on the B port; the FXLA102 internal VO architecture automatically changes direction from $A \rightarrow B$ to $B \rightarrow A$.

During HL / LH transitions, or "Dynamic Mode," a strong output driver drives the output channel in parallel with a weak output driver. After a typical delay of approximately $10 \mathrm{~ns}-50 \mathrm{~ns}$, the strong driver is turned off, leaving the weak driver enabled for holding the logic state of the channel. This weak driver is called the "bus
hold." "Static Mode" is when only the bus hold drives the channel. The bus hold can be over ridden in the event of a direction change. The strong driver allows the FXLA102 to quickly charge and discharge capacitive transmission lines during dynamic mode. Static mode conserves pow er, where Icc is typically $<5 \mu \mathrm{~A}$.

## Bus Hold Minimum Drive Current

Specifies the minimum amount of current the bus hold driver can source/sink. The bus hold minimum drive current ( $\|_{\text {HOLD }}$ ) is $\mathrm{V}_{\text {CC }}$ dependent and guaranteed in the DC Electrical tables. The intent is to maintain a valid output state in a static mode, but that can be overridden $w$ hen an input data transition occurs.

## Bus Hold Input Overdrive Drive Current

Specifies the minimum amount of current required (by an external device) to overdrive the bus hold in the event of a direction change. The bus hold overdrive ( $\|_{\mathrm{ODH}}, \mathrm{ll}_{\mathrm{OdL}}$ ) is $\mathrm{V}_{\text {CC }}$ dependent and guaranteed in the DC Eectrical tables.

## Dynamic Output Current

The strength of the output driver during LH / HL transitions is referenced on page 8, Dynamic Output Electrical Characteristics, Іонд, and lold.

## Test Diagrams



Figure 3. Test ${ }^{-}$Circuit

Table 1. AC Test Conditions

| Test | Input Signal | Output Enable Control |
| :---: | :---: | :---: |
| $t_{\text {PLL }}, \mathrm{t}_{\mathrm{PHL}}$ | Data Pulses | 0 V |
| $\mathrm{t}_{\mathrm{PZL}}$ | 0 V | HIGH to LOW Sw itch |
| $\mathrm{t}_{\mathrm{PZH}}$ | $\mathrm{V}_{\mathrm{CCI}}$ | HIGH to LOW Sw itch |

Table 2. AC Load

| $\mathbf{V}_{\text {cco }}$ | $\mathbf{C 1}$ | $\mathbf{R 1}$ |
| :---: | :---: | :---: |
| $1.2 \mathrm{~V} \pm 0.1 \mathrm{~V}$ | 15 pF | $1 \mathrm{M} \Omega$ |
| $1.5 \mathrm{~V} \pm 0.1 \mathrm{~V}$ | 15 pF | $1 \mathrm{M} \Omega$ |
| $1.8 \mathrm{~V} \pm 0.15 \mathrm{~V}$ | 15 pF | $1 \mathrm{M} \Omega$ |
| $2.5 \mathrm{~V} \pm 0.2 \mathrm{~V}$ | 15 pF | $1 \mathrm{M} \Omega$ |
| $3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}$ | 15 pF | $1 \mathrm{M} \Omega$ |



Figure 4. Waveform for Inverting and Non-Inverting Functions
Notes:
15. Input $t_{R}=t_{F}=2.0 \mathrm{~ns}, 10 \%$ to $90 \%$.
16. Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, at $\mathrm{V}_{\mathrm{I}}=3.0 \mathrm{~V}$ to 3.6 V only.


Figure 5. 3-State Output Low Enable Time

## Notes:

17. Input $t_{R}=t_{F}=2.0 \mathrm{~ns}, 10 \%$ to $90 \%$.
18. Input $t_{R}=t_{F}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, at $V_{I}=3.0 \mathrm{~V}$ to 3.6 V only.


Figure 6. 3-State Output High Enable Time
Notes:
19. Input $t_{R}=t_{F}=2.0 \mathrm{~ns}, 10 \%$ to $90 \%$.
20. Input $\mathrm{t}_{\mathrm{R}}=\mathrm{t}_{\mathrm{F}}=2.5 \mathrm{~ns}, 10 \%$ to $90 \%$, at $\mathrm{V}_{\mathrm{I}}=3.0 \mathrm{~V}$ to 3.6 V only.

Table 3. Test Measure Points

| Symbol | $\mathbf{V}_{\text {cc }}$ |
| :---: | :---: |
| $\mathrm{V}_{\mathrm{MI}}{ }^{(21)}$ | $\mathrm{V}_{\mathrm{ClI}} / 2$ |
| $\mathrm{~V}_{\mathrm{MO}}$ | $\mathrm{V}_{\mathrm{cco}} / 2$ |
| $\mathrm{~V}_{\mathrm{X}}$ | $0.9 \times \mathrm{V}_{\mathrm{CCo}}$ |
| $\mathrm{V}_{\mathrm{Y}}$ | $0.1 \times \mathrm{V}_{\mathrm{CCo}}$ |

## Note:

21. $\mathrm{V}_{\mathrm{CCI}}=\mathrm{V}_{\mathrm{CCA}}$ for control pin /OE or $\mathrm{V}_{\mathrm{MI}}=\left(\mathrm{V}_{\mathrm{CCA}} / 2\right)$.

$$
\begin{aligned}
& \text { Vime } \\
& \mathrm{I}_{\text {OUT }} \\
& \mathrm{V}_{\mathrm{OH}} \approx\left(C_{L}+C_{I / O}\right) \times \frac{\Delta V_{O U T}}{\Delta t}=\left(C_{L}+C_{I / O}\right) \times \frac{(20 \%-80 \%) \cdot V_{C C O}}{t_{\text {RISE }}}
\end{aligned}
$$

Figure 7. Active Output Rise Time and Dynamic Output Current High


$$
I_{O L D} \approx\left(C_{L}+C_{I / O}\right) \times \frac{\Delta V_{O U T}}{\Delta t}=\left(C_{L}+C_{/ / O}\right) \times \frac{(80 \%-20 \%) \bullet V_{C C O}}{t_{F A L L}}
$$

Figure 8. Active Output Fall Time and Dynamic Output Current Low


Figure 9. Maximum Data Rate


Figure 10.Output Skew Time

## Note:



## Physical Dimensions



Figure 11.8-Lead, MicroPak ${ }^{\text {TM }}, 1.6 \mathrm{~mm}$ Wide

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