# LB1935FA

# Monolithic Digital IC Stepping Motor Driver IC



#### **Overview**

LB1935FA is IC with forward/reverse motor drive 2-channel in which low saturation voltage and low voltage operation possible. Its small sized package is optimal for 2 phase excitation drive of 2 phase bipolar stepping motors for various portable devices such as digital still cameras.

#### **Features**

- Low saturation voltage,  $V_O$  (sat) = 0.3V typ at  $I_O$  = 150mA
- Built-in shoot-through current protection circuit
- No standby current consumption (or zero)
- Built-in thermal shutdown circuit
- Micro10 small-sized package

#### **Absolute Maximum Ratings** at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Maximum power source voltage	V <sub>CC</sub> max		-0.3 to +8.0	V
Applied output voltage	V <sub>OUT</sub> max	OUT1, OUT2, OUT3, OUT4 pin	V <sub>CC</sub> +VSF	V
Applied input voltage	V <sub>IN</sub> max	ENA, IN1, IN2 pin	-0.3 to +8.0	V
GND Pin outflow current	I GND	Per channel	400	mA
Allowable power dissipation	Pd max	With substrate*	400	mW
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-40 to +150	°C

\* Specified substrate: 20.0mm×10.0mm×0.8mm, paper phenol

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

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#### Allowable Operating Range at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Source voltage	V <sub>CC</sub>		2.2 to 7.5	V
Input high level voltage	VIH	ENA, IN1, IN2 pin	1.8 to 7.5	V
Input low level voltage	VIL	ENA, IN1, IN2 pin	-0.3 to +0.7	V

#### **Electric Characteristics** at $Ta = 25^{\circ}C$ , $V_{CC} = 3.3V$

Deremeter	Symbol	Conditions	Ratings			Linit		
Parameter		Conditions	min	typ	max	Unit		
Power source current	ICC0	ENA = 0V, V <sub>IN</sub> = 3V or 0V		0.1	1	μΑ		
	ICC1	$ENA = 3V, V_{IN} = 3V \text{ or } 0V$		13	19	mA		
Output saturation voltage	V <sub>OUT</sub> 1	ENA = 3V, $V_{IN}$ = 3V or 0V, $I_{OUT}$ = 100mA		0.2	0.3	V		
	V <sub>OUT</sub> 2	ENA = 3V, $V_{IN}$ = 3V or 0V, $I_{OUT}$ = 200mA		0.4	0.6	V		
Input current	I <sub>IN</sub>	V <sub>IN</sub> = 3V		40	60	μA		
	IENA	VENA = 3V		40	60	μΑ		
Spark killer diode								
Reverse current	IS(leak)				1	μA		
Forward voltage	VSF	I <sub>OUT</sub> = 200mA			1.7	V		

## **Package Dimensions**

unit : mm (typ) 3428





## **Pin Assignments**



# Block Diagram



# Truth Table

	Input		Output				Damadua	
ENA	IN1	IN2	OUT1	OUT2	OUT3	OUT4	Remarks	
L	-	-	OFF	OFF	OFF	OFF	Standby	
н	L	L	Н	L	Н	L	2-phase excitation	
	L	Н	Н	L	L	Н		
	Н	Н	L	Н	L	Н		
	Н	L	L	Н	Н	L		

### **Timing Chart**

Timing chart below shows the 2 phase excitation stepping motor.



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