Ordering number : EN8297A

LC87F5JC8A

CMOS IC
FROM 128K byte, RAM 4096 byte on-chip
8-bit 1-chip Microcontroller

ON Semiconductor®
http://onsemi.com

Overview

The LC87F5JC8A is an 8-bit microcomputer that, centered around a CPU running at a minimum bus cycle time of 83.3ns, integrates on a single chip a number of hardware features such as 128K byte flash ROM (onboard programmable), 4096 byte RAM, an on-chip debugger, sophisticated 16-bit timers/counters (may be divided into 8-bit timers), a 16-bit timer/counter (may be divided into 8-bit timers/counters or 8-bit PWMs), four 8-bit timers with a prescaler, a 16-bit timer with a prescaler (may be divided into 8-bit timers), a base timer serving as a time-of-day clock,
a high-speed clock counter, a synchronous SIO interface (with automatic block transmission/reception capabilities), an asynchronous/synchronous SIO interface, a UART interface (full duplex), an 8-bit 11-channel AD converter, two 12-bit PWM channels, a system clock frequency divider, ROM correction function, and a 26-source 10-vector interrupt feature.

Features

■Flash ROM
- Capable of on-board-programing with wide range, 3.0 to 5.5V, of voltage source.
- Block-erasable in 128 byte units
- 131072 × 8-bits (LC87F5JC8A)

■RAM
- 4096 × 9-bits (LC87F5JC8A)

■Minimum Bus Cycle
- 83.3ns (12MHz) V_{DD}=3.0 to 5.5V
- 125ns (8MHz) V_{DD}=2.5 to 5.5V
- 500ns (2MHz) V_{DD}=2.2 to 5.5V

Note: The bus cycle time here refers to the ROM read speed.

* This product is licensed from Silicon Storage Technology, Inc. (USA).

■Minimum Instruction Cycle Time
- 250ns (12MHz) V_{DD}=3.0 to 5.5V
- 375ns (8MHz) V_{DD}=2.5 to 5.5V
- 1.5μs (2MHz) V_{DD}=2.2 to 5.5V

■Ports
- Normal withstand voltage I/O ports
  - Ports whose I/O direction can be designated in 1-bit units: 46 (P1n, P2n, P70 to P73, P80 to P86, PBn, PCn, PWM2, PWM3, XT2)
  - Ports whose I/O direction can be designated in 4-bit units: 8 (P0n)
- Normal withstand voltage input port: 1 (XT1)
- Dedicated oscillator ports: 2 (CF1, CF2)
- Reset pins: 1 ($\overline{RES}$)
- Power pins: 6 (V_{SS}1 to 3, V_{DD}1 to 3)

■Timers
- Timer 0: 16-bit timer/counter with two capture registers.
  - Mode 0: 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) × 2-channels
  - Mode 1: 8-bit timer with an 8-bit programmable prescaler (with two 8-bit capture registers) + 8-bit counter (with two 8-bit capture registers)
  - Mode 2: 16-bit timer with an 8-bit programmable prescaler (with two 16-bit capture registers)
  - Mode 3: 16-bit counter (with two 16-bit capture registers)
- Timer 1: 16-bit timer/counter that supports PWM/toggle outputs
  - Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/counter with an 8-bit prescaler (with toggle outputs)
  - Mode 1: 8-bit PWM with an 8-bit prescaler × 2-channels
  - Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs) (toggle outputs also possible from the lower-order 8-bits)
  - Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs) (The lower-order 8-bits can be used as PWM)
- Timer 4: 8-bit timer with a 6-bit prescaler
- Timer 5: 8-bit timer with a 6-bit prescaler
- Timer 6: 8-bit timer with a 6-bit prescaler (with toggle output)
- Timer 7: 8-bit timer with a 6-bit prescaler (with toggle output)
- Timer 8: 16-bit timer
  - Mode 0: 8-bit timer with an 8-bit prescaler ×2-channels
  - Mode 1: 16-bit timer with an 8-bit prescaler

* Timer 8 is not supported in this version of Emulator. Please use on-chip-debugger for debugging when developing software.

- Base Timer
  1) The clock is selectable from the subclock (32.768kHz crystal oscillation), system clock, and timer 0 prescaler output.
  2) Interrupts programmable in 5 different time schemes

■High-speed Clock Counter
1. Can count clocks with a maximum clock rate of 20MHz (at a main clock of 10MHz).
2. Can generate output real-time.

■SIO
- SIO0: 8-bit synchronous serial interface
  1) LSB first/MSB first mode selectable
  2) Built-in 8-bit baudrate generator (maximum transfer clock cycle = 4/3 tCYC)
  3) Automatic continuous data transmission (1 to 256 bits, specifiable in 1 bit units, suspension and resumption of data transmission possible in 1 byte units)
- SIO1: 8-bit asynchronous/synchronous serial interface
  - Mode 0: Synchronous 8-bit serial I/O (2- or 3-wire configuration, 2 to 512 tCYC transfer clocks)
  - Mode 1: Asynchronous serial I/O (half-duplex, 8 data bits, 1 stop bit, 8 to 2048 tCYC baudrates)
  - Mode 2: Bus mode 1 (start bit, 8 data bits, 2 to 512 tCYC transfer clocks)
  - Mode 3: Bus mode 2 (start detect, 8 data bits, stop detect)

■UART
- Full duplex
- 7/8/9 bit data bits selectable
- 1 stop bit(2-bit in continuous data transmission)
- Built-in baudrate generator

■AD Converter: 8-bit × 11-channels

■PWM: Multifrequency 12-bit PWM × 2-channels

■Remote Control Receiver Circuit (sharing pins with P73, INT3, and T0IN)
- Noise rejection function (noise filter time constant selectable from 1 tCYC, 32 tCYC, and 128 tCYC)

■Watchdog Timer
- External RC watchdog timer
- Interrupt and reset signals selectable

■Clock Output Function
1) Able to output selected oscillation clock 1/1, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64 as system clock.
2) Able to output oscillation clock of sub clock.

■Interrupts
- 26 sources, 10 vector addresses

1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INT0
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/T0L/INT4
4	0001BH	H or L	INT3/INT5/base timer
5	00023H	H or L	T0H/INT6
6	0002BH	H or L	T1L/T1H/INT7
7	00033H	H or L	SIO0/UART1 receive/T8L/T8H
8	0003BH	H or L	SIO1/UART1 transmit
9	00043H	H or L	ADC/T6/T7
10	0004BH	H or L	Port 0/T4/T5/PWM2, PWM3

- Priority levels X > H > L
- Of interrupts of the same level, the one with the smallest vector address takes precedence.

- IFLG (list of interrupt source flag function)

3) Shows a list of interrupt source flags that caused a branching to a particular vector address (shown in the diagram above).

■Subroutine Stack Levels: 2048 levels (the stack is allocated in RAM)

■High-speed Multiplication/Division Instructions
- 16-bits × 8-bits (5 tCYC execution time)
- 24-bits × 16-bits (12 tCYC execution time)
- 16-bits ÷ 8-bits (8 tCYC execution time)
- 24-bits ÷ 16-bits (12 tCYC execution time)

■Oscillation Circuits

- RC oscillation circuit (internal): For system clock
- CF oscillation circuit: For system clock, with internal Rf
- Crystal oscillation circuit: For low-speed system clock, with internal Rf
- Frequency variable RC oscillation circuit (internal): For system clock

■System Clock Divider Function

- Can run on low current.
- The minimum instruction cycle selectable from 300ns, 600ns, 1.2µs, 2.4µs, 4.8µs, 9.6µs, 19.2µs, 38.4µs, and 76.8µs (at a main clock rate of 10MHz).

■Standby Function

- HALT mode: Halts instruction execution while allowing the peripheral circuits to continue operation.
  1) Oscillation is not halted automatically.
  2) Canceled by a system reset or occurrence of an interrupt
- HOLD mode: Suspends instruction execution and the operation of the peripheral circuits.
  1) The CF, RC, and crystal oscillators automatically stop operation.
  2) There are three ways of resetting the HOLD mode.
     (1) Setting the reset pin to the low level.
     (2) Setting at least one of the INT0, INT1, INT2, INT4, and INT5 pins to the specified level
     (3) Having an interrupt source established at port 0
- X'tal HOLD mode: Suspends instruction execution and the operation of the peripheral circuits except the base timer.
  1) The CF and RC oscillators automatically stop operation.
  2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
  3) There are four ways of resetting the X'tal HOLD mode.
     (1) Setting the reset pin to the low level
     (2) Setting at least one of the INT0, INT1, INT2, INT4, and INT5 pins to the specified level
     (3) Having an interrupt source established at port 0
     (4) Having an interrupt source established in the base timer circuit

■ROM Correction Function

- Executes the correction program on detection of a match with the program counter value.
- Correction program area size: 128 bytes

■On-chip Debugger

- Supports software debugging with the IC mounted on the target board.

■Package Form

- QIP64E (14×14): Lead-free type
- TQFP64J (10×10): Lead-free type
- TQFP64J (7×7): Lead-free type

■Development Tools

- Evaluation chip: LC87EV690
- Emulator: EVA62S + ECB876600D + SUB875800 + POD64QFP or POD64SQFP
  ICE-B877300 + SUB875800 + POD64QFP or POD64SQFP
- On-chip debugger: TCB87-TypeA or TCB87-TypeB+LC87F5JC8A

■Flash ROM Programming Boards

Package	Programming boards
QIP64E (14×14)	W87F50256Q
TQFP64J (10×10)	W87F57256SQ
TQFP64J (7×7)	W87F58256TQ7

■Flash ROM Programmer

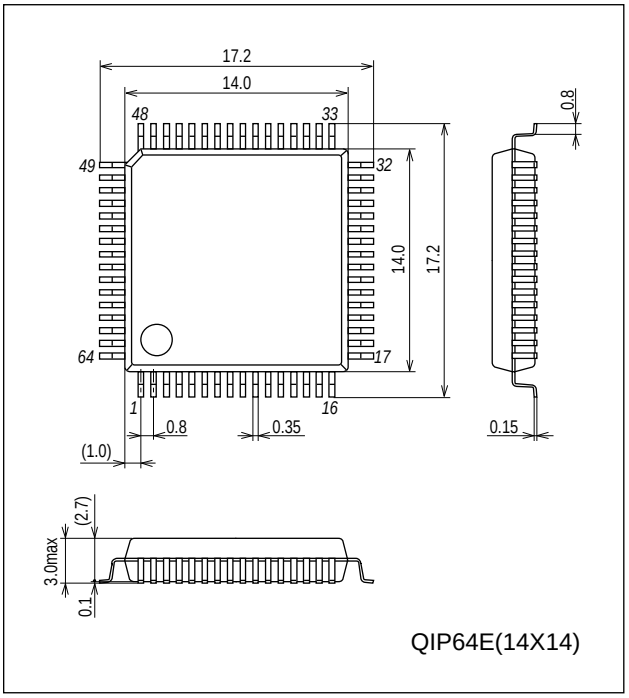
Maker	Model		Supported version (Note)	Device
Flash Support Group, Inc. (Formerly Ando Electric Co., Ltd.)	Single	AF9708/AF9709/ AF9709B	After 02.40	LC87F5JC8A FAST
	Gang	AF9723 (Main body)	After 02.04	
		AF9833 (Unit)	After 01.84	
Our company	SKK (Sanyo FWS)		After 1.02C (Install CD)	LC87F5JC8A

Note: Please check the latest version.

Package Dimensions

unit : mm (typ)

3159A

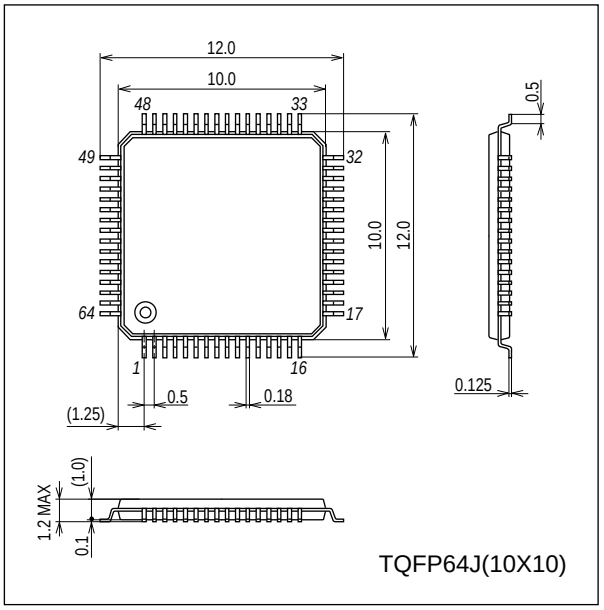


QIP64E(14X14)

Package Dimensions

unit : mm (typ)

3310

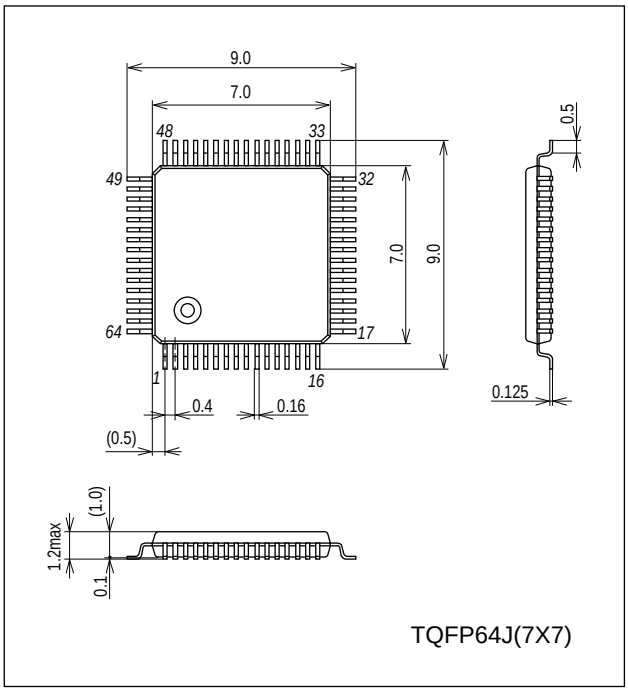


TQFP64J(10X10)

Package Dimensions

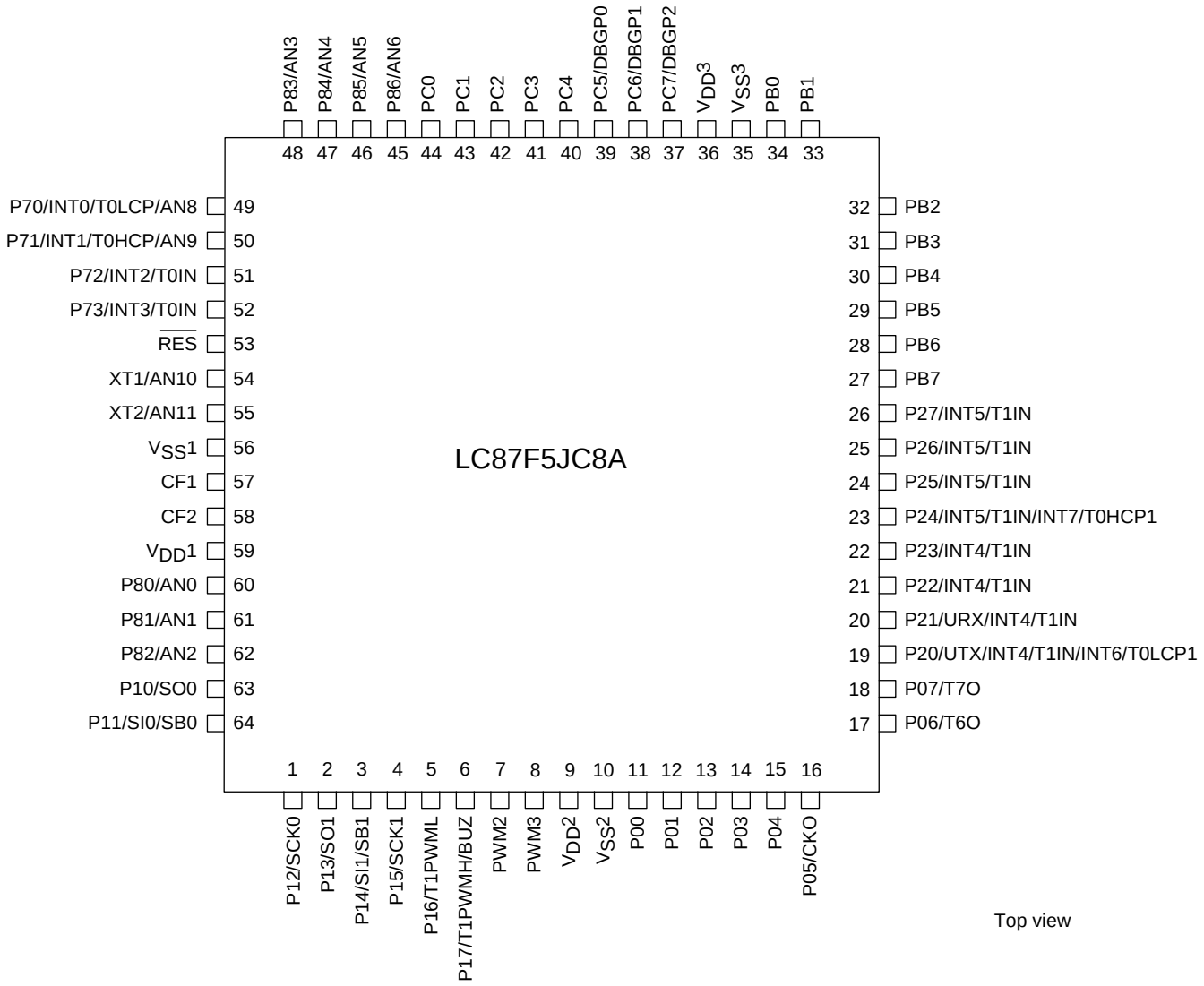
unit : mm (typ)

3289



TQFP64J(7X7)

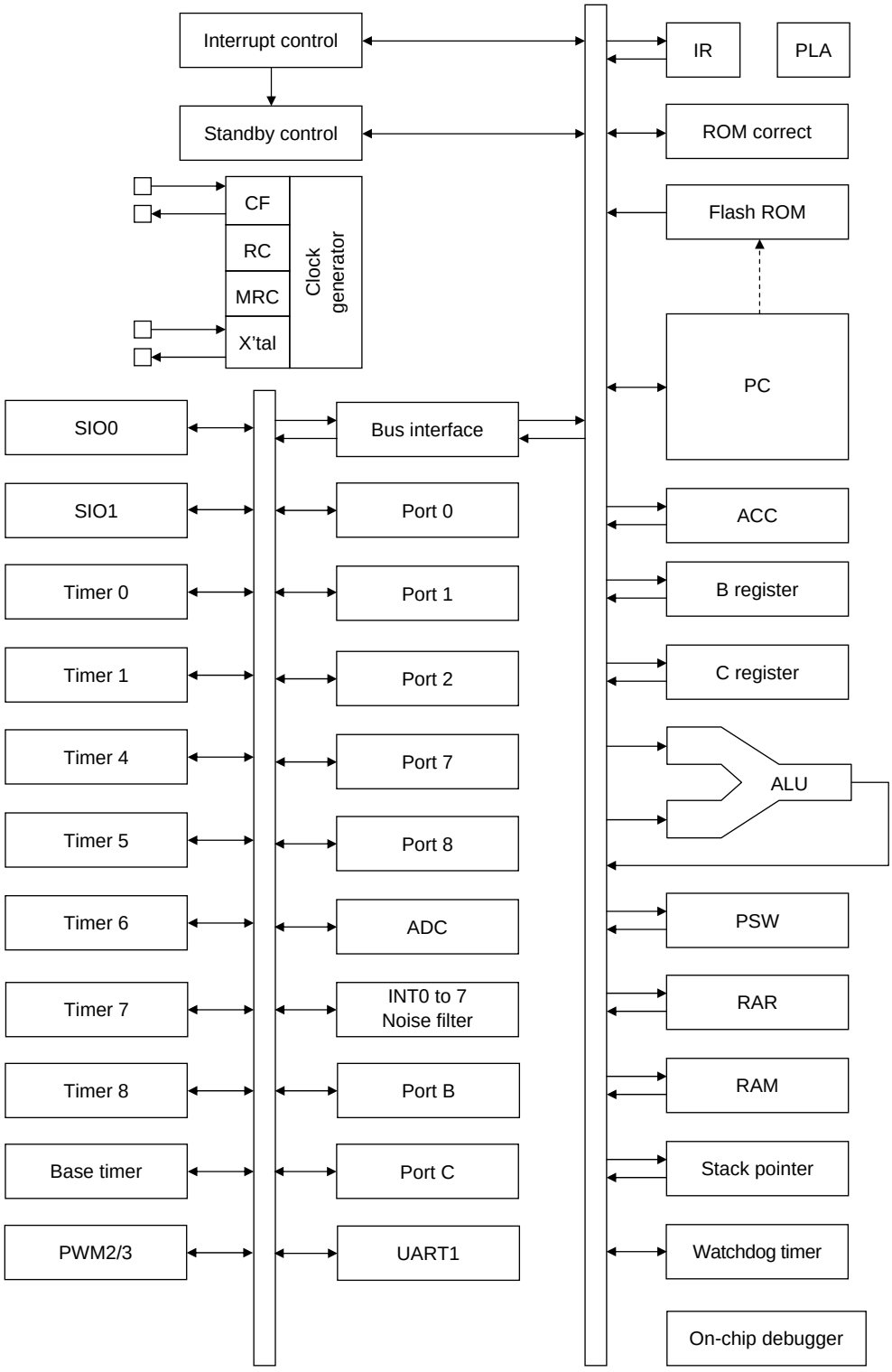
Pin Assignment



Top view

QIP64E(14×14) “Lead-free Type”
TQFP64J(10×10) “Lead-free Type”
TQFP64J(7×7) “Lead-free Type”

System Block Diagram



Pin Description

<table>
<tr><th>Pin Name</th><th>I/O</th><th>Description</th><th>Option</th></tr>
<tr><td>$V_{SS}1$
$V_{SS}2$
$V_{SS}3$</td><td>-</td><td>-Power supply pin</td><td>No</td></tr>
<tr><td>$V_{DD}1$
$V_{DD}2$
$V_{DD}3$</td><td>-</td><td>+Power supply pin</td><td>No</td></tr>
<tr><td>Port 0
P00 to P07</td><td>I/O</td><td>• 8-bit I/O port
• I/O specifiable in 4-bit units
• Pull-up resistors can be turned on and off in 4-bit units.
• HOLD reset input
• Port 0 interrupt input
• Shared pins
P05 : Clock output (system clock/can selected from sub clock)
P06 : Timer 6 toggle output
P07 : Timer 7 toggle output</td><td>Yes</td></tr>
<tr><td>Port 1
P10 to P17</td><td>I/O</td><td>• 8-bit I/O port
• I/O specifiable in 1-bit units
• Pull-up resistors can be turned on and off in 1-bit units.
• Pin functions
P10 : SIO0 data output
P11 : SIO0 data input/bus I/O
P12 : SIO0 clock I/O
P13 : SIO1 data output
P14 : SIO1 data input/bus I/O
P15 : SIO1 clock I/O
P16 : Timer 1PWML output
P17 : Timer 1PWMH output/beeper output</td><td>Yes</td></tr>
<tr><td>Port 2
P20 to P27</td><td>I/O</td><td>• 8-bit I/O port
• I/O specifiable in 1-bit units
• Pull-up resistors can be turned on and off in 1-bit units.
• Pin functions
P20 : UART transmit
P21 : UART receive
P20 to P23 : INT4 input/HOLD reset input/timer 1 event input/timer 0L capture input/timer 0H capture input
P24 to P27 : INT5 input/HOLD reset input/timer 1 event input/timer 0L capture input/timer 0H capture input
P20 : INT6 input/timer 0L capture 1 input
P24 : INT7 input/timer 0H capture 1 input
Interrupt acknowledge type
<table>
<tr><th></th><th>Rising</th><th>Falling</th><th>Rising & Falling</th><th>H level</th><th>L level</th></tr>
<tr><td>INT4</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td></tr>
<tr><td>INT5</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td></tr>
<tr><td>INT6</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td></tr>
<tr><td>INT7</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td></tr>
</table>
</td><td>Yes</td></tr>
</table>

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<table>
<tr><th>Pin Name</th><th>I/O</th><th>Description</th><th>Option</th></tr>
<tr><td>Port 7
P70 to P73</td><td>I/O</td><td>• 4-bit I/O port
• I/O specifiable in 1-bit units
• Pull-up resistors can be turned on and off in 1-bit units.
• Shared pins
P70 : INT0 input/HOLD reset input/timer 0L capture input/watchdog timer output
P71 : INT1 input/HOLD reset input/timer 0H capture input
P72 : INT2 input/HOLD reset input/timer 0 event input/timer 0L capture input/High speed clock counter input
P73 : INT3 input (with noise filter)/timer 0 event input/timer 0H capture input
AD converter input port : AN8 (P70), AN9 (P71)
Interrupt acknowledge type
<table>
<tr><th></th><th>Rising</th><th>Falling</th><th>Rising & Falling</th><th>H level</th><th>L level</th></tr>
<tr><td>INT0</td><td>enable</td><td>enable</td><td>disable</td><td>enable</td><td>enable</td></tr>
<tr><td>INT1</td><td>enable</td><td>enable</td><td>disable</td><td>enable</td><td>enable</td></tr>
<tr><td>INT2</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td></tr>
<tr><td>INT3</td><td>enable</td><td>enable</td><td>enable</td><td>disable</td><td>disable</td></tr>
</table></td><td>No</td></tr>
<tr><td>Port 8
P80 to P86</td><td>I/O</td><td>• 7-bit I/O port
• I/O specifiable in 1-bit units
• Shared pins
AD converter input : port: AN0 (P80) to AN6 (P86)</td><td>No</td></tr>
<tr><td>PWM2
PWM3</td><td>I/O</td><td>• PWM2 and PWM3 output ports
• General-purpose I/O available</td><td>No</td></tr>
<tr><td>Port B
PB0 to PB7</td><td>I/O</td><td>• 8-bit I/O port
• I/O specifiable in 1-bit units
• Pull-up resistors can be turned on and off in 1-bit units.</td><td>Yes</td></tr>
<tr><td>Port C
PC0 to PC7</td><td>I/O</td><td>• 8-bit I/O port
• I/O specifiable in 1-bit units
• Pull-up resistors can be turned on and off in 1-bit units.
• Shared pins
On-chip debugger pins : DBGP0 to DBGP2 (PC5 to PC7)</td><td>Yes</td></tr>
<tr><td>$\overline{\text{RES}}$</td><td>Input</td><td>Reset pin</td><td>No</td></tr>
<tr><td>XT1</td><td>Input</td><td>• 32.768kHz crystal oscillator input pin
• Shared pins
General-purpose input port
AD converter input port : AN10
Must be connected to $V_{DD}1$ if not to be used.</td><td>No</td></tr>
<tr><td>XT2</td><td>I/O</td><td>• 32.768kHz crystal oscillator output pin
• Shared pins
General-purpose I/O port
AD converter input port : AN11
Must be set for oscillation and kept open if not to be used.</td><td>No</td></tr>
<tr><td>CF1</td><td>Input</td><td>Ceramic resonator input pin</td><td>No</td></tr>
<tr><td>CF2</td><td>Output</td><td>Ceramic resonator output pin</td><td>No</td></tr>
</table>

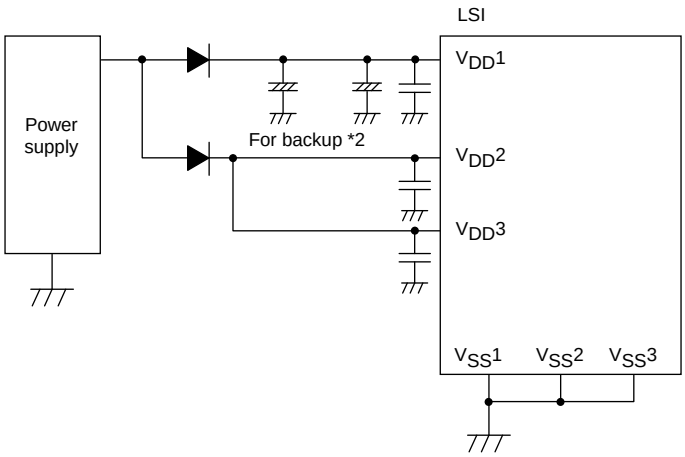
Port Output Configuration

The table below lists the types of port outputs and the presence/absence of a pull-up resistor.
Data can be read into any input port even if it is in the output mode.

Port Name	Option Selected in Units of	Option Type	Output Type	Pull-Up Resistor
P00 to P07	1-bit	1	CMOS	Programmable (Note 1)
		2	Nch-open drain	No
P10 to P17	1-bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P20 to P27	1-bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
P70	-	No	Nch-open drain	Programmable
P71 to P73	-	No	CMOS	Programmable
P80 to P86	-	No	Nch-open drain	No
PWM2, PWM3	-	No	CMOS	No
PB0 to PB7	1-bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
PC0 to PC7	1-bit	1	CMOS	Programmable
		2	Nch-open drain	Programmable
XT1	-	No	Input for 32.768kHz crystal oscillator (Input only)	No
XT2	-	No	Output for 32.768kHz crystal oscillator (Nch-open drain when in general-purpose output mode)	No

Note 1 : Programmable pull-up resistors for port 0 are controlled in 4-bit units (P00 to 03, P04 to 07).

*1 : Connect the IC as shown below to minimize the noise input to the $V_{DD}1$ pin.
Be sure to electrically short the $V_{SS}1$, $V_{SS}2$, and $V_{SS}3$ pins.



*2 : The internal memory is sustained by $V_{DD}1$. If none of $V_{DD}2$ and $V_{DD}3$ are backed up, the high level output at the ports are unstable in the HOLD backup mode, allowing through current to flow into the input buffer and thus shortening the backup time.
Make sure that the port outputs are held at the low level in the HOLD backup mode.

Absolute Maximum Ratings / Ta = 25°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter		Symbol	Pin/Remarks	Conditions	V_{DD} [V]	Specification min	typ	max	unit
Maximum supply voltage		V_{DD} max	$V_{DD}1$, $V_{DD}2$, $V_{DD}3$	$V_{DD}1=V_{DD}2=V_{DD}3$		-0.3		+6.5	V
Input voltage		V_I(1)	XT1, CF1			-0.3		V_{DD}+0.3	V
Input/output voltage		VIO(1)	Ports 0, 1, 2 Ports 7, 8 Ports B, C PWM2, PWM3, XT2			-0.3		V_{DD}+0.3	V
High level output current	Peak output current	IOPH(1)	Ports 0, 1, 2 Ports B, C	CMOS output select Per 1 applicable pin		-10			mA
		IOPH(2)	PWM2, PWM3	Per 1 applicable pin		-20			mA
		IOPH(3)	P71 to P73	Per 1 applicable pin		-5			mA
	Mean output current (Note 1-1)	IOMH(1)	Ports 0, 1, 2 Ports B, C	CMOS output select Per 1 applicable pin		-7.5			mA
		IOMH(2)	PWM2, PWM3	Per 1 applicable pin		-15			mA
		IOMH(3)	P71 to P73	Per 1 applicable pin		-3			mA
	Total output current	ΣIOAH(1)	P71 to P73	Total of all applicable pins		-10			mA
		ΣIOAH(2)	Port 1 PWM2, PWM3	Total of all applicable pins		-25			mA
		ΣIOAH(3)	Ports 0, 2	Total of all applicable pins		-25			mA
		ΣIOAH(4)	Ports 0, 1, 2 PWM2, PWM3	Total of all applicable pins		-45			mA
		ΣIOAH(5)	Port B	Total of all applicable pins		-25			mA
		ΣIOAH(6)	Port C	Total of all applicable pins		-25			mA
		ΣIOAH(7)	Ports B, C	Total of all applicable pins		-45			mA
Low level output current	Peak output current	IOPL(1)	P02 to P07 Ports 1, 2 Ports B, C PWM2, PWM3	Per 1 applicable pin				20	mA
		IOPL(2)	P00, P01	Per 1 applicable pin				30	mA
		IOPL(3)	Ports 7, 8 XT2	Per 1 applicable pin				10	mA
	Mean output current (Note 1-1)	IOML(1)	P02 to P07 Ports 1, 2 Ports B, C PWM2, PWM3	Per 1 applicable pin				15	mA
		IOML(2)	P00, P01	Per 1 applicable pin				20	mA
		IOML(3)	Ports 7, 8 XT2	Per 1 applicable pin				7.5	mA
	Total output current	ΣIOAL(1)	Port 7 P83 to P86, XT2	Total of all applicable pins				15	mA
		ΣIOAL(2)	P80 to P82	Total of all applicable pins				15	mA
		ΣIOAL(3)	Ports 7, 8 XT2	Total of all applicable pins				20	mA
		ΣIOAL(4)	Port 1 PWM2, PWM3	Total of all applicable pins				45	mA
		ΣIOAL(5)	Ports 0, 2	Total of all applicable pins				45	mA
		ΣIOAL(6)	Ports 0, 1, 2 PWM2, PWM3	Total of all applicable pins				80	mA
		ΣIOAL(7)	Port B	Total of all applicable pins				45	mA
		ΣIOAL(8)	Port C	Total of all applicable pins				45	mA
		ΣIOAL(9)	Ports B, C	Total of all applicable pins				80	mA

Note 1-1: The mean output current is a mean value measured over 100ms.

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Parameter	Symbol	Pin/Remarks	Conditions		Specification			
				V_{DD} [V]	min	typ	max	unit
Power dissipation	Pd max	QIP64E (14×14)	Ta= -20 to +70°C				377	mW
		TQFP64J (10×10)					246	
		TQFP64J (7×7)					164	
Operating ambient temperature	Topr				-20		+70	°C
Storage ambient temperature	Tstg				-55		+125	

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Recommended Operating Range / Ta = -20°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V_{DD} [V]	min	typ	max	unit
Operating supply voltage (Note 2-1)	$V_{DD}(1)$	$V_{DD}1=V_{DD}2=V_{DD}3$	0.245µs ≤ tCYC ≤ 200µs		3.0		5.5	V
			0.367µs ≤ tCYC ≤ 200µs		2.5		5.5	
			1.47µs ≤ tCYC ≤ 200µs		2.2		5.5	
Memory sustaining supply voltage	VHD	$V_{DD}1=V_{DD}2=V_{DD}3$	RAM and register contents sustained in HOLD mode.		2.0		5.5	
High level input voltage	$V_{IH}(1)$	Ports 1, 2 P71 to P73 P70 port input /interrupt side		2.2 to 5.5	$0.3V_{DD}$ +0.7		V_{DD}	
	$V_{IH}(2)$	Ports 0, 8, B, C PWM2, PWM3		2.2 to 5.5	$0.3V_{DD}$ +0.7		V_{DD}	
	$V_{IH}(3)$	Port 70 watchdog timer side		2.2 to 5.5	$0.9V_{DD}$		V_{DD}	
	$V_{IH}(4)$	XT1, XT2, CF1 $\overline{RES}$		2.2 to 5.5	$0.75V_{DD}$		V_{DD}	
Low level input voltage	$V_{IL}(1)$	Ports 1, 2 P71 to P73 P70 port input /interrupt side		4.0 to 5.5	VSS		$0.1V_{DD}$ +0.4	
				2.2 to 4.0	V_{SS}		$0.2V_{DD}$	
	$V_{IL}(2)$	Ports 0, 8, B, C PWM2, PWM3		4.0 to 5.5	V_{SS}		$0.15V_{DD}$ +0.4	
				2.2 to 4.0	V_{SS}		$0.2V_{DD}$	
	$V_{IL}(3)$	Port 70 watchdog timer side		2.2 to 5.5	V_{SS}		$0.8V_{DD}$ -1.0	
	$V_{IL}(4)$	XT1, XT2, CF1 $\overline{RES}$		2.2 to 5.5	V_{SS}		$0.25V_{DD}$	
Instruction cycle time (Note 2-2)	tCYC			3.0 to 5.5	0.245		200	µs
				2.5 to 5.5	0.367		200	
				2.2 to 5.5	1.47		200	
External system clock frequency	FEXCF(1)	CF1	• CF2 pin open • System clock frequency division ratio=1/1 • External system clock duty =50 ± 5%	3.0 to 5.5	0.1		12	MHz
				2.5 to 5.5	0.1		8	
				2.2 to 5.5	0.1		2	
			• CF2 pin open • System clock frequency division ratio=1/2	3.0 to 5.5	0.2		24.4	
				2.5 to 5.5	0.2		16	
				2.2 to 5.5	0.2		4	
Oscillation frequency range (Note 2-3)	FmCF(1)	CF1, CF2	12MHz ceramic oscillation See Fig. 1.	3.0 to 5.5		12		MHz
	FmCF(2)	CF1, CF2	8MHz ceramic oscillation See Fig. 1.	2.5 to 5.5		8		
	FmCF(3)	CF1, CF2	4MHz ceramic oscillation See Fig. 1.	2.2 to 5.5		4		
	FmRC		Internal RC oscillation	2.2 to 5.5	0.3	1.0	2.0	
	FmMRC		Frequency variable RC oscillation source oscillation	2.2 to 5.5		16		
	FsX'tal	XT1, XT2	32.768kHz crystal oscillation See Fig. 2.	2.2 to 5.5		32.768		kHz

Note 2-1: V_{DD} must be held greater than or equal to 3.0V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

Note 2-3: See Tables 1 and 2 for the oscillation constants.

Electrical Characteristics / Ta = -20°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V_{DD} [V]	min	typ	max	unit
High level input current	$I_{IH}(1)$	Ports 0, 1, 2 Ports 7, 8 Ports B, C $\overline{RES}$ PWM2, PWM3	Output disabled Pull-up resistor off $V_{IN}=V_{DD}$ (Including output Tr's off leakage current)	2.2 to 5.5			1	µA
	$I_{IH}(2)$	XT1, XT2	For input port specification $V_{IN}=V_{DD}$	2.2 to 5.5			1	
	$I_{IH}(3)$	CF1	$V_{IN}=V_{DD}$	2.2 to 5.5			15	
Low level input current	$I_{IL}(1)$	Ports 0, 1, 2 Ports 7, 8 Ports B, C $\overline{RES}$ PWM2, PWM3	Output disabled Pull-up resistor off $V_{IN}=V_{SS}$ (Including output Tr's off leakage current)	2.2 to 5.5	-1			
	$I_{IL}(2)$	XT1, XT2	For input port specification $V_{IN}=V_{SS}$	2.2 to 5.5	-1			
	$I_{IL}(3)$	CF1	$V_{IN}=V_{SS}$	2.2 to 5.5	-15			
High level output voltage	$V_{OH}(1)$	Ports 0, 1, 2 Ports B, C	I_{OH}= -1mA	4.5 to 5.5	V_{DD}-1			V
	$V_{OH}(2)$		I_{OH}= -0.4mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(3)$		I_{OH}= -0.2mA	2.2 to 5.5	V_{DD}-0.4			
	$V_{OH}(4)$	P71 to P73	I_{OH}= -0.4mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(5)$		I_{OH}= -0.2mA	2.2 to 5.5	V_{DD}-0.4			
	$V_{OH}(6)$	PWM2, PWM3	I_{OH}= -10mA	4.5 to 5.5	V_{DD}-1.5			
	$V_{OH}(7)$		I_{OH}= -1.6mA	3.0 to 5.5	V_{DD}-0.4			
	$V_{OH}(8)$		I_{OH}= -1mA	2.2 to 5.5	V_{DD}-0.4			
Low level output voltage	$V_{OL}(1)$	Ports 0, 1, 2 Ports B, C PWM2, PWM3	I_{OL}=10mA	4.5 to 5.5			1.5	
	$V_{OL}(2)$		I_{OL}=1.6mA	3.0 to 5.5			0.4	
	$V_{OL}(3)$		I_{OL}=1mA	2.2 to 5.5			0.4	
	$V_{OL}(4)$	Ports 7, 8 XT2	I_{OL}=1.6mA	3.0 to 5.5			0.4	
	$V_{OL}(5)$		I_{OL}=1mA	2.2 to 5.5			0.4	
	$V_{OL}(6)$	P00, P01	I_{OL}=30mA	4.5 to 5.5			1.5	
	$V_{OL}(7)$		I_{OL}=5mA	3.0 to 5.5			0.4	
	$V_{OL}(8)$		I_{OL}=2.5mA	2.2 to 5.5			0.4	
Pull-up resistance	Rpu(1)	Ports 0, 1, 2, 7 Ports B, C	$V_{OH}=0.9V_{DD}$	4.5 to 5.5	15	35	80	kΩ
	Rpu(2)			2.2 to 5.5	18	50	150	
Hysteresis voltage	VHYS	$\overline{RES}$ Ports 1, 2, 7		2.2 to 5.5		0.1 V_{DD}		V
Pin capacitance	CP	All pins	For pins other than that under test: $V_{IN}=V_{SS}$ f=1MHz Ta=25°C	2.2 to 5.5		10		pF

Serial I/O Characteristics at Ta=-20 to +70°C, $V_{SS}1=V_{SS}2=V_{SS}3=0V$

1. SIO0 Serial I/O Characteristics (Note 4-1-1)

Parameter			Symbol	Pin/Remarks	Conditions	V_{DD}[V]	Specification min	typ	max	unit
Serial clock	Input clock	Frequency	tSCK(1)	SCK0(P12)	See Fig. 6.	2.2 to 5.5	2			tCYC
		Low level pulse width	tSCKL(1)				1			
		High level pulse width	tSCKH(1)				1			
			tSCKHA(1)		• Continuous data transmission/reception mode • See Fig. 6. • (Note 4-1-2)		4			
	Output clock	Frequency	tSCK(2)	SCK0(P12)	• CMOS output selected • See Fig. 6.	2.2 to 5.5	4/3			
		Low level pulse width	tSCKL(2)				1/2			tSCK
		High level pulse width	tSCKH(2)				1/2			
			tSCKHA(2)		• Continuous data transmission/reception mode • CMOS output selected • See Fig. 6.		tSCKH(2) +2tCYC		tSCKH(2) +(10/3) tCYC	tCYC
Serial input	Data setup time		tsDI(1)	SB0(P11), SI0(P11)	• Must be specified with respect to rising edge of SIOCLK. • See Fig. 6.	2.2 to 5.5	0.03			µs
	Data hold time		thDI(1)				0.03			
Serial output	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	• Continuous data transmission/reception mode • (Note 4-1-3)	2.2 to 5.5			(1/3)tCYC +0.05	
			tdD0(2)		• Synchronous 8-bit mode • (Note 4-1-3)				1tCYC +0.05	
	Output clock		TdD0(3)		(Note 4-1-3)				(1/3)tCYC +0.05	

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: To use serial-clock-input in continuous trans/rec mode, a time from SI0RUN being set when serial clock is "H" to the first negative edge of the serial clock must be longer than tSCKHA.

Note 4-1-3: Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 6.

2. SIO1 Serial I/O Characteristics (Note 4-2-1)

Parameter			Symbol	Pin/Remarks	Conditions		Specification			
						V_{DD}[V]	min	typ	max	unit
Serial clock	Input clock	Frequency	tSCK(3)	SCK1(P15)	See Fig. 6.	2.2 to 5.5	2			tCYC
		Low level pulse width	tSCKL(3)				1			
		High level pulse width	tSCKH(3)				1			
	Output clock	Frequency	tSCK(4)	SCK1(P15)	• CMOS output selected • See Fig. 6.	2.2 to 5.5	2			tSCK
		Low level pulse width	tSCKL(4)				1/2			
		High level pulse width	tSCKH(4)				1/2			
Serial input	Data setup time		tsDI(2)	SB1(P14), SI1(P14)	• Must be specified with respect to rising edge of SIOCLK. • See Fig. 6.	2.2 to 5.5	0.03			µs
	Data hold time		thDI(2)				0.03			
Serial output	Output delay time		tdD0(4)	SO1(P13), SB1(P14)	• Must be specified with respect to falling edge of SIOCLK. • Must be specified as the time to the beginning of output state change in open drain output mode. • See Fig. 6.	2.2 to 5.5			(1/3)tCYC +0.05	

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

Pulse Input Conditions / Ta = -20°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V_{DD} [V]	min	typ	max	unit
High/low level pulse width	tPIH(1) tPIL(1)	INT0(P70), INT1(P71), INT2(P72), INT4(P20 to P23), INT5(P24 to P27), INT6(P20), INT7(P24)	• Interrupt source flag can be set. • Event inputs for timer 0 or 1 are enabled.	2.2 to 5.5	1			tCYC
	tPIH(2) tPIL(2)	INT3(P73) when noise filter time constant is 1/1	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	2.2 to 5.5	2			
	tPIH(3) tPIL(3)	INT3(P73) when noise filter time constant is 1/32	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	2.2 to 5.5	64			
	tPIH(4) tPIL(4)	INT3(P73) when noise filter time constant is 1/128	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	2.2 to 5.5	256			
	tPIL(5)	$\overline{RES}$	Resetting is enabled.	2.2 to 5.5	200			µs

AD Converter Characteristics / Ta = -20°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V_{DD} [V]	min	typ	max	unit
Resolution	N	AN0(P80) to AN6(P86), AN8(P70), AN9(P71), AN10(XT1), AN11(XT2)		3.0 to 5.5		8		bit
Absolute accuracy	ET		(Note 6-1)	3.0 to 5.5			±1.5	LSB
Conversion time	TCAD		AD conversion time=32 × tCYC (when ADCR2=0) (Note 6-2)	4.5 to 5.5	15.68 (tCYC= 0.49µs)		97.92 (tCYC= 3.06µs)	µs
				3.0 to 5.5	23.52 (tCYC= 0.735µs)		97.92 (tCYC= 3.06µs)	
			AD conversion time=64 × tCYC (when ADCR2=1) (Note 6-2)	4.5 to 5.5	18.82 (tCYC= 0.294µs)		97.92 (tCYC= 1.53µs)	
				3.0 to 5.5	47.04 (tCYC= 0.735µs)		97.92 (tCYC= 1.53µs)	
Analog input voltage range	VAIN			3.0 to 5.5	V_{SS}		V_{DD}	V
Analog port input current	IAINH		VAIN=V_{DD}	3.0 to 5.5			1	µA
	IAINL		VAIN=V_{SS}	3.0 to 5.5	-1			

Note 6-1: The quantization error (±1/2LSB) is excluded from the absolute accuracy value.

Note 6-2: The conversion time refers to the interval from the time the instruction for starting the converter is issued till the time the complete digital value corresponding to the analog input value is loaded in the required register.

Current Dissipation Characteristics / Ta = -20°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

Parameter	Symbol	Pin/ Remarks	Conditions	V_{DD} [V]	Specification min	typ	max	unit
Normal mode consumption current (Note 7-1)	IDDOP(1)	$V_{DD}1$ =$V_{DD}2$ =$V_{DD}3$	• FmCF=12MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 12MHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/1 frequency division ratio	4.5 to 5.5		8.7	22	mA
	IDDOP(2)			3.0 to 3.6		5	12.5	
	IDDOP(3)		• CF1=24MHz external clock • FmX'tal=32.768kHz crystal oscillation mode • System clock set to CF1 side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		10	24.5	
	IDDOP(4)			3.0 to 3.6		5.5	14	
	IDDOP(5)		• FmCF=8MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 8MHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/1 frequency division ratio	4.5 to 5.5		6.6	16.5	
	IDDOP(6)			3.0 to 3.6		3.8	9.6	
	IDDOP(7)			2.5 to 3.0		2.5	7.4	
	IDDOP(8)		• FmCF=4MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 4MHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		2.5	6.3	
	IDDOP(9)			3.0 to 3.6		1.4	3.5	
	IDDOP(10)			2.2 to 3.0		0.9	2.7	
	IDDOP(11)		• FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to internal RC oscillation • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		0.75	3.1	
	IDDOP(12)			3.0 to 3.6		0.4	1.7	
	IDDOP(13)			2.2 to 3.0		0.28	1.35	
	IDDOP(14)		• FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • Internal RC oscillation stopped • System clock set to 1MHz with frequency variable RC oscillation • 1/2 frequency division ratio	4.5 to 5.5		1.3	5.4	
	IDDOP(15)			3.0 to 3.6		0.7	3.1	
	IDDOP(16)			2.2 to 3.0		0.5	2.4	
	IDDOP(17)		• FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 32.768kHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		35	115	µA
	IDDOP(18)			3.0 to 3.6		18	65	
	IDDOP(19)			2.2 to 3.0		12	46	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

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Parameter	Symbol	Pin/ Remarks	Conditions	Specification				
				V_{DD} [V]	min	typ	max	unit
HALT mode consumption current (Note 7-1)	IDDHALT(1)	$V_{DD}1$ =$V_{DD}2$ =$V_{DD}3$	• HALT mode • FmCF=12MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 12MHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/1 frequency division ratio	4.5 to 5.5		3.6	8.2	mA
	IDDHALT(2)			3.0 to 3.6		2	4.6	
	IDDHALT(3)		• HALT mode • CF1=24MHz external clock • FmX'tal=32.768kHz crystal oscillation mode • System clock set to CF1 side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		4.7	10.5	
	IDDHALT(4)			3.0 to 3.6		2.5	5.8	
	IDDHALT(5)		• HALT mode • FmCF=8MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 8MHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/1 frequency division ratio	4.5 to 5.5		2.6	5.9	
	IDDHALT(6)			3.0 to 3.6		1.4	3.3	
	IDDHALT(7)			2.5 to 3.0		1	2.5	
	IDDHALT(8)		• HALT mode • FmCF=4MHz ceramic oscillation mode • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 4MHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		1.15	2.65	
	IDDHALT(9)			3.0 to 3.6		0.6	1.5	
	IDDHALT(10)			2.2 to 3.0		0.4	1.1	
	IDDHALT(11)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to internal RC oscillation • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		0.37	1.3	
	IDDHALT(12)			3.0 to 3.6		0.2	0.75	
	IDDHALT(13)			2.2 to 3.0		0.13	0.54	
	IDDHALT(14)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • Internal RC oscillation stopped • System clock set to 1MHz with frequency variable RC oscillation • 1/2 frequency division ratio	4.5 to 5.5		1	3.5	
	IDDHALT(15)			3.0 to 3.6		0.55	2	
	IDDHALT(16)			2.2 to 3.0		0.37	1.5	
	IDDHALT(17)		• HALT mode • FmCF=0Hz (oscillation stopped) • FmX'tal=32.768kHz crystal oscillation mode • System clock set to 32.768kHz side • Internal RC oscillation stopped • Frequency variable RC oscillation stopped • 1/2 frequency division ratio	4.5 to 5.5		18.5	68	µA
	IDDHALT(18)			3.0 to 3.6		10	38	
	IDDHALT(19)			2.2 to 3.0		6.5	26	
HOLD mode consumption current	IDDHOLD(1)	$V_{DD}1$	• HOLD mode • CF1=V_{DD} or open (External clock mode)	4.5 to 5.5		0.05	20	
	IDDHOLD(2)			3.0 to 3.6		0.03	12	
	IDDHOLD(3)			2.2 to 3.0		0.02	8	
Timer HOLD mode consumption current	IDDHOLD(4)		• Timer HOLD mode • CF1=V_{DD} or open (External clock mode) • FmX'tal=32.768kHz crystal oscillation mode	4.5 to 5.5		16	58	
	IDDHOLD(5)			3.0 to 3.6		8.5	32	
	IDDHOLD(6)			2.2 to 3.0		5	20	

Note 7-1: The consumption current value includes none of the currents that flow into the output Tr and internal pull-up resistors.

F-ROM Programming Characteristics / Ta = +10°C to +55°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

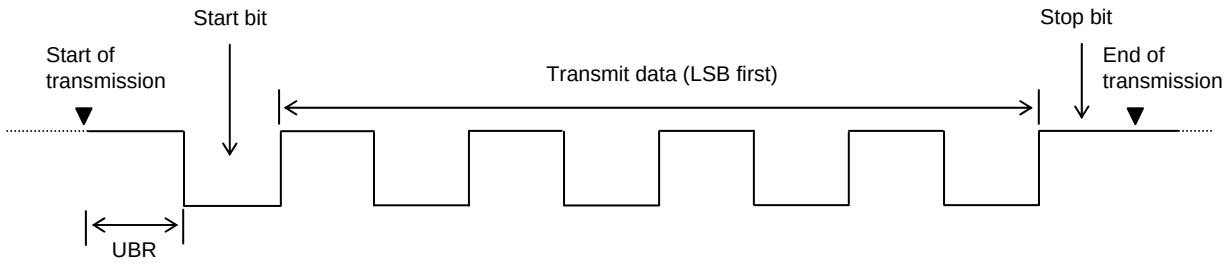
Parameter	Symbol	Pin/Remarks	Conditions		Specification			
				V_{DD} [V]	min	typ	max	unit
Onboard programming current	IDDFW(1)	$V_{DD}1$	• 128 byte programming • Erasing current included	3.0 to 5.5		25	40	mA
Programming time	tFW(1)		• 128 byte programming • Erasing current included • Time for setting up 128 byte data is excluded.	3.0 to 5.5		22.5	45	ms

UART (Full Duplex) Operating Conditions / Ta = -20°C to +70°C, $V_{SS}1 = V_{SS}2 = V_{SS}3 = 0V$

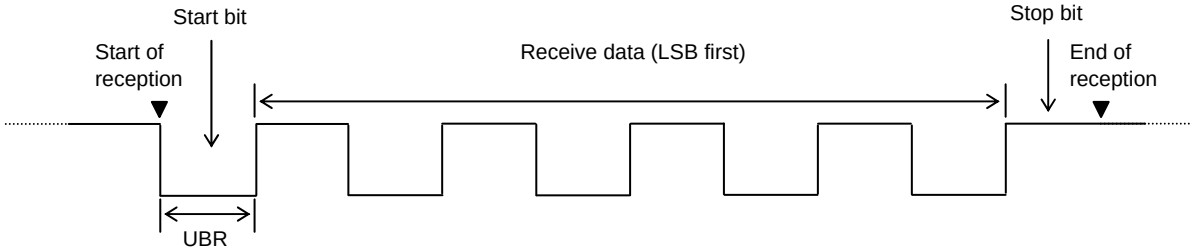
Parameter	Symbol	Pin/Remarks	Conditions		Specification			
				V_{DD} [V]	min	typ	max	unit
Transfer rate	UBR	UTX(P20), URX(P21)		2.2 to 5.5	16/3		8192/3	tCYC

Data length: 7/8/9 bits (LSB first)
Stop bits: 1-bit
Parity bits: None

*Example of Continuous 8-bit Data Transmission Mode Processing (First Transmit Data=55H)



*Example of Continuous 8-bit Data Reception Mode Processing (First Receive Data=55H)



Characteristics of a Sample Main System Clock Oscillation Circuit

Given below are the characteristics of a sample main system clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 1 Characteristics of a Sample Main System Clock Oscillator Circuit with a Ceramic Oscillator

Nominal Frequency	Vendor Name	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C1 [pF]	C2 [pF]	Rf [Ω]	Rd1 [Ω]		typ [ms]	max [ms]	
12MHz	MURATA	CSTCE12M0G52-R0	(10)	(10)	1M	680	3.0 to 5.5	0.1	0.5	Internal C1, C2
8MHz	MURATA	CSTCE8M00G52-R0	(10)	(10)	1M	680	2.5 to 5.5	0.1	0.5	Internal C1, C2
4MHz	MURATA	CSTCR4M00G53-R0	(15)	(15)	1M	2.2k	2.2 to 5.5	0.2	0.6	Internal C1, C2

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after V_{DD} goes above the operating voltage lower limit (see Figure 4).

Characteristics of a Sample Subsystem Clock Oscillator Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit with a Crystal Oscillator

Nominal Frequency	Vendor Name	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C3 [pF]	C4 [pF]	Rf [Ω]	Rd2 [Ω]		typ [s]	max [s]	
32.768kHz	SEIKO EPSON	MC-306	18	18	Open	560k	2.2 to 5.5	1.4	3.0	Applicable CL value = 12.5pF

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after the instruction for starting the subclock oscillation circuit is executed and to the time interval that is required for the oscillation to get stabilized after the HOLD mode is reset (see Figure 4).

Note : The components that are involved in oscillation should be placed as close to the IC and to one another as possible because they are vulnerable to the influences of the circuit pattern.

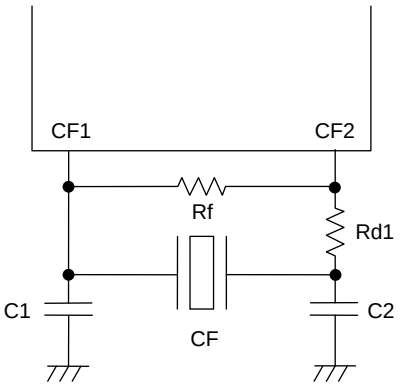


Figure 1 CF Oscillator Circuit

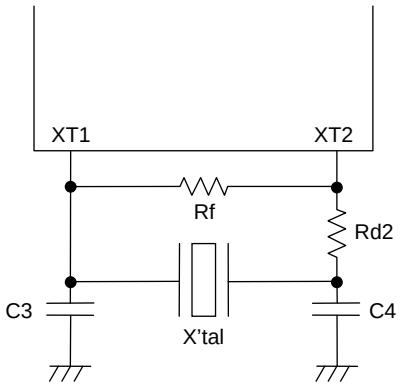


Figure 2 XT Oscillator Circuit

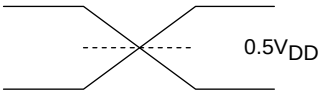
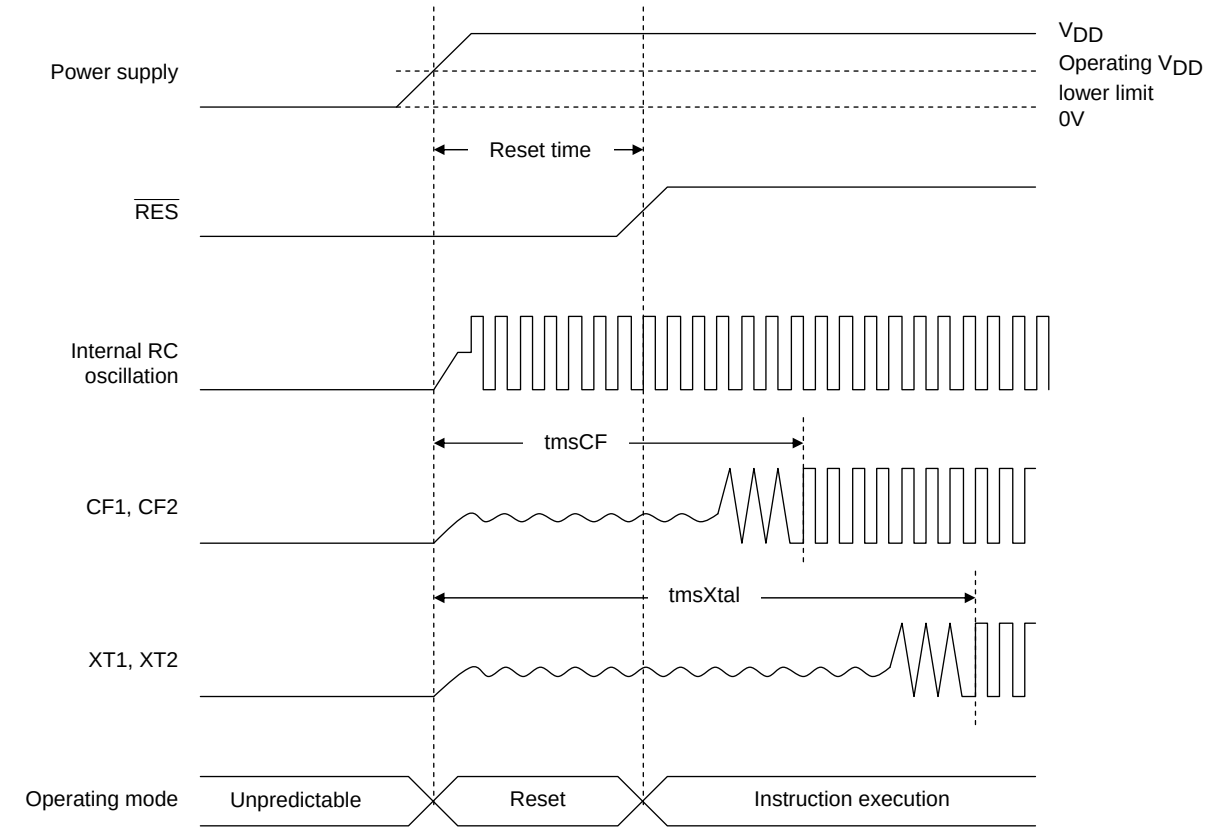
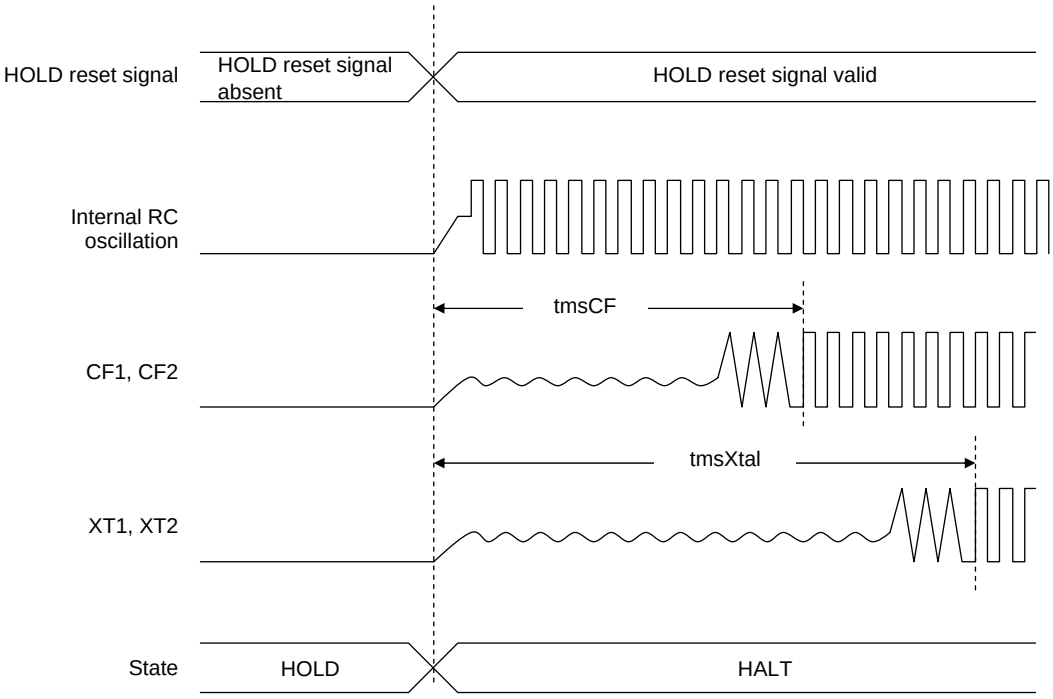


Figure 3 AC Timing Measurement Point

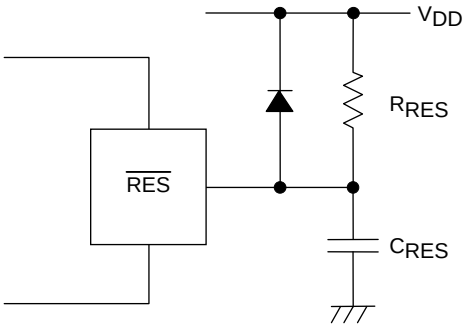


Reset Time and Oscillation Stabilizing Time



HOLD Reset Signal and Oscillation Stabilization Time

Figure 4 Oscillation Stabilization Times



Note :
Determine the value of C_{RES} and R_{RES} so that the reset signal is present for a period of 200µs after the supply voltage goes beyond the lower limit of the IC's operating voltage.

Figure 5 Reset Circuit

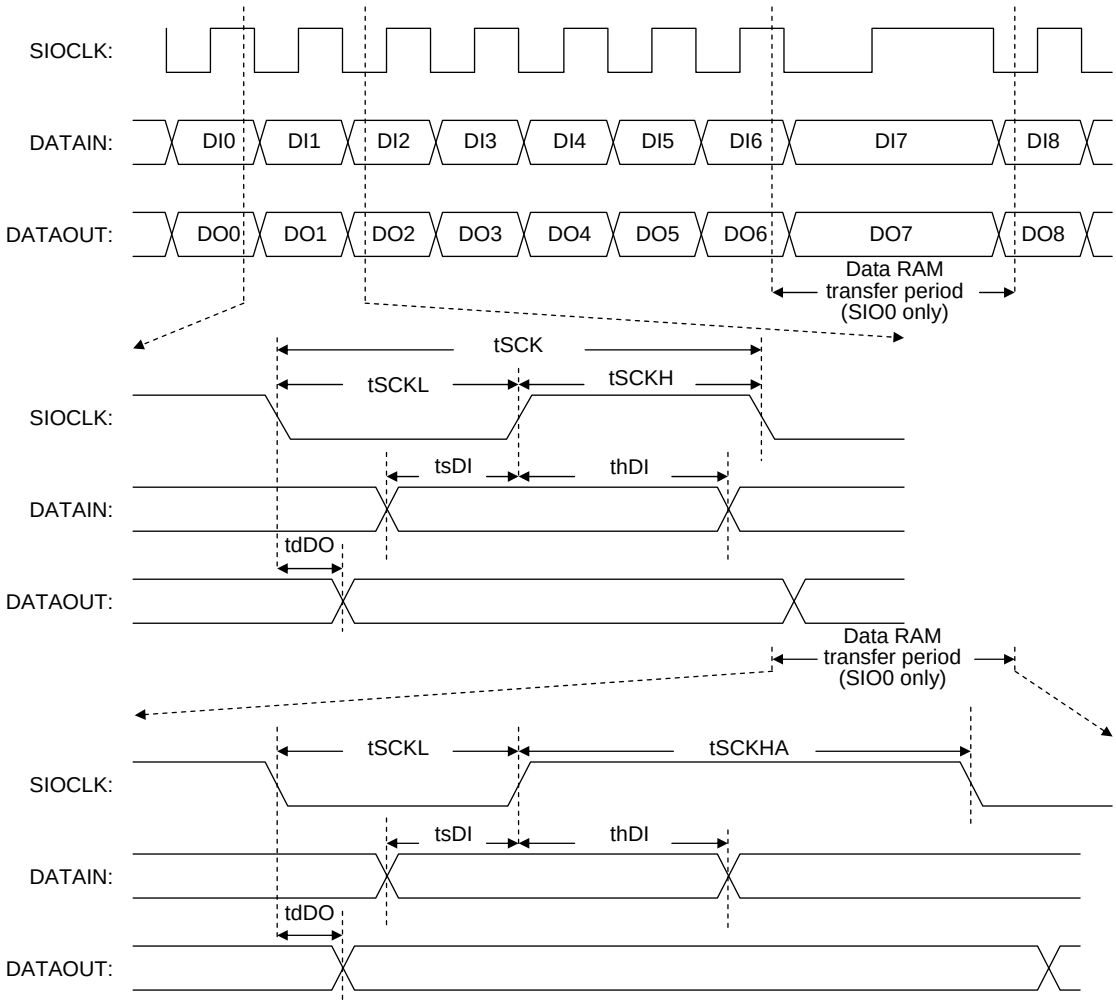


Figure 6 Serial I/O Output Waveforms

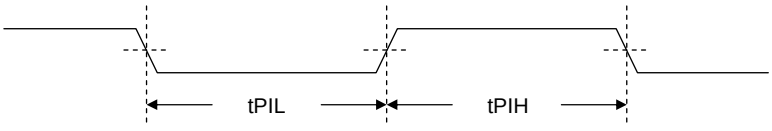


Figure 7 Pulse Input Timing Signal Waveform

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