LC898240

Advance Information

High Efficient Stepper Motor Controller

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Overview

The LC898240 is a current controller IC for a stepper motor, co-working with a conventional driver. It provides additional functions to a stepper motor control system. The drive current of a motor coil is adopted for the motor load, so that minimize the waste of power. By this current control, the stepper motor moves smoothly. And, it gives higher efficiency power consumption, lower acoustic noise, lower vibration and lower heat generation.

The LC898240 also provides speed acceleration profile control function and step-out detection/prevention. These functions can be configured by the registers through an SPI serial port interface flexibly. The preset parameters and configuration can be stored to the companion non-volatile memory.

The LC898240 consists of the monitor inputs from motor terminal, serial port inter face, the step control signal inputs from a microprocessor and the outputs to a stepper motor driver. The topology of a microprocessor, a stepper motor driver and LC898240, can be arranged to match various drivers and system architecture. Thus, it can be used as an interface converter between a microprocessor and a driver with the advanced control functions.

Features

- Unipolar and bipolar motor applicable
- Supported excitation mode:
  - Half step
  - Quarter step
  - 1/8 step
  - 1/16 step
  - Full step (high efficient function not applicable)
- SPI interface for the motor control and setting
- Interface for the driver control
- Non-volatile memory (E2PROM)
  - Setting of the controller
  - Acceleration curve: 9 curves, 440 steps for each

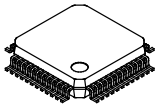
Recommended Stepper Motor Driver

- LV8726TA
- LV8736V
- LV8740V
- STK672-6XXX
- STK672-4XXX

Typical Applications

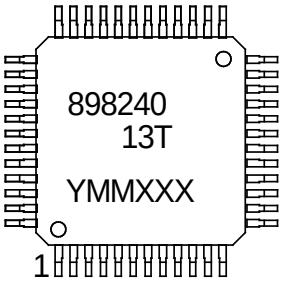
- Multi-Function Printer
- Consumer

PACKAGE PICTURE



SQFP48
0.5mm pitch

MARKING DIAGRAM



Y: Year
MM: Month
XXX: ID

ORDERING INFORMATION

Ordering Code:
LC898240-2H (tray)
LC898240-WH (reel)

Package
SQFP48
(Pb-Free / Halogen Free)

Shipping (Qty / packing)
1250 / Tray
1000 / Tape & Reel

† For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.
http://www.onsemi.com/pub_link/Collateral/BRD8011-D.PDF

This document contains information on a new product. Specifications and information herein are subject to change without notice.

LC898240 BLOCK DIAGRAM

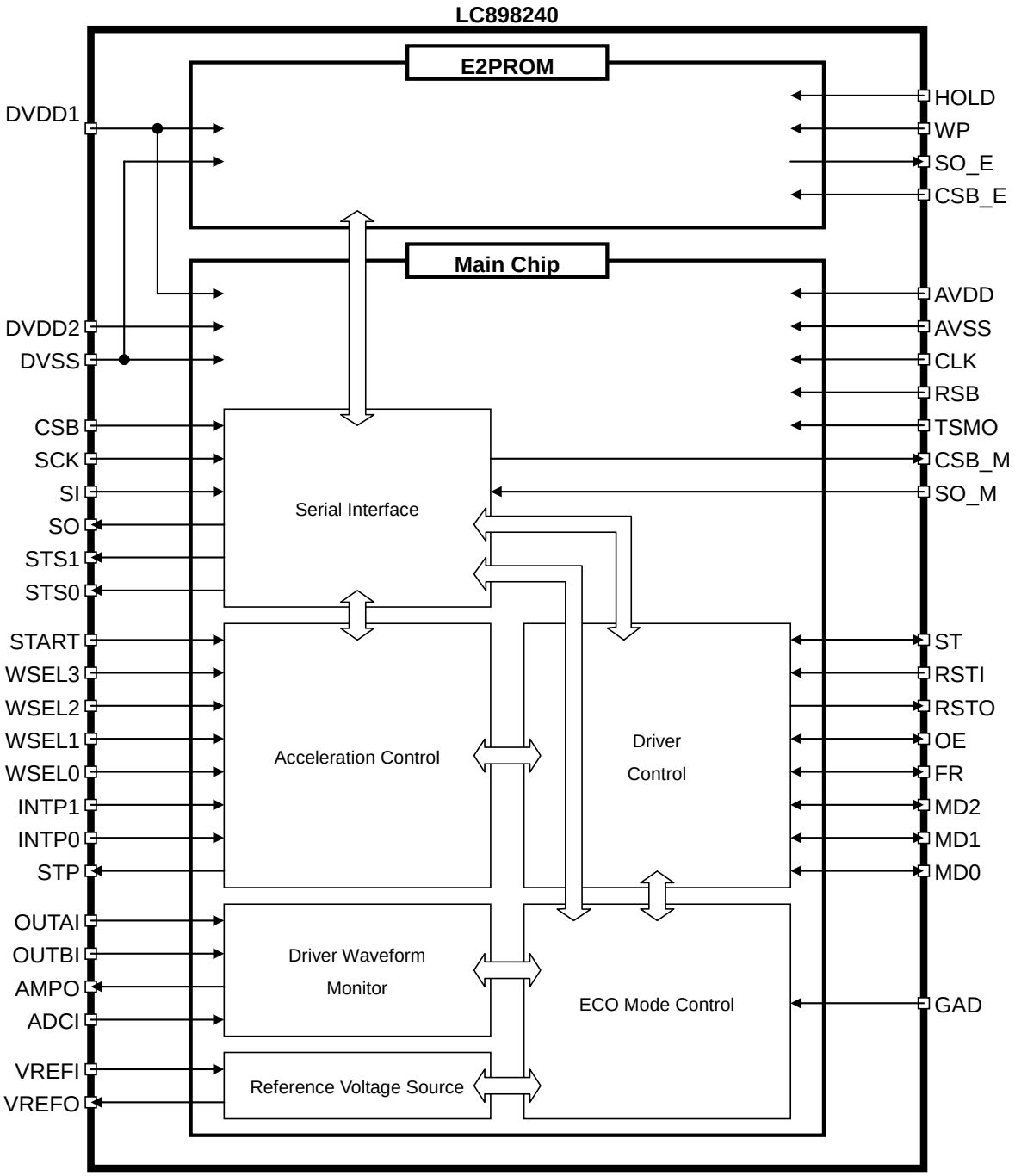


Figure 1 LC898240 Block Diagram

APPLICATION BLOCK DIAGRAM

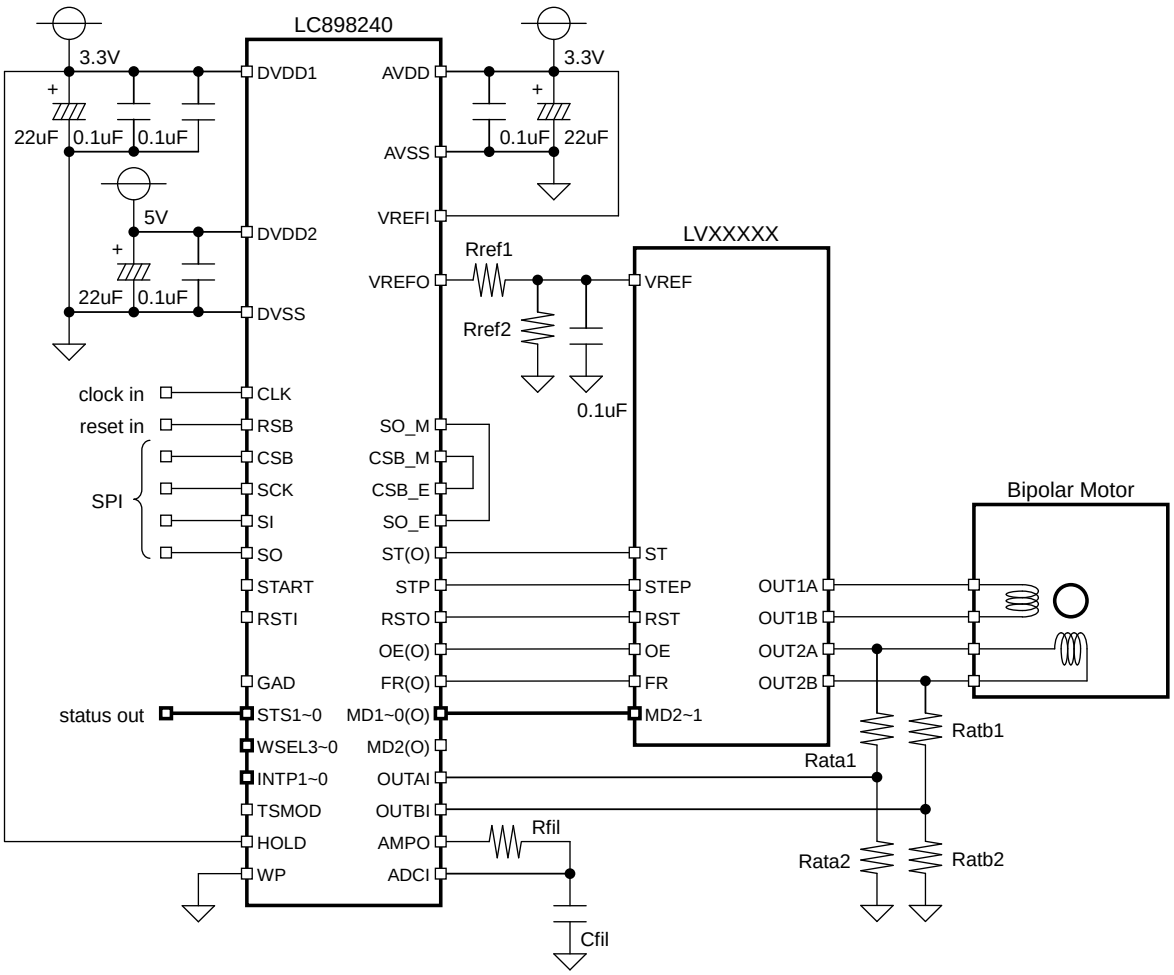


Figure 2 Example of SPI control for IO port control driver

PIN ASSIGNMENTS

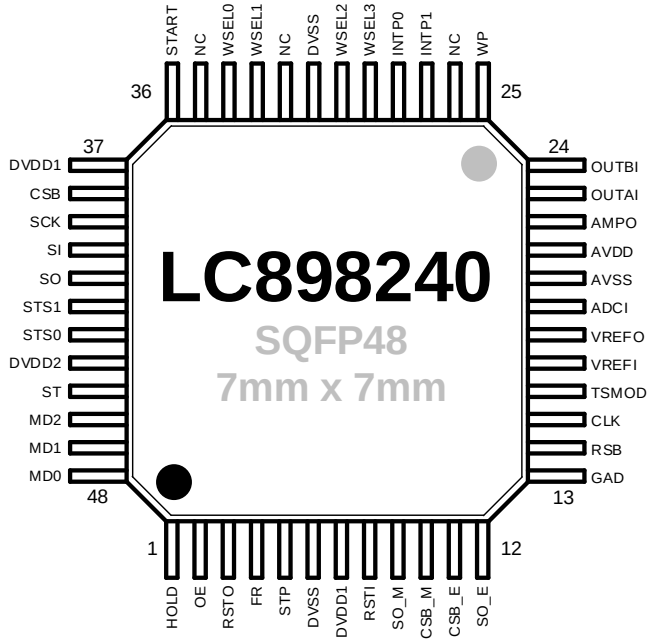


Figure 3: LC898240 Pinout

NUMBER	NAME	TYPE	NUMBER	NAME	TYPE
1	HOLD	I	48	MD0	B(I)
2	OE	B(I)	47	MD1	B(I)
3	RSTO	O	46	MD2	B(I)
4	FR	B(I)	45	ST	B(I)
5	STP	O	44	DVDD2	P
6	DVSS	P	43	STS0	O
7	DVDD1	P	42	STS1	O
8	RSTI	I	41	SO	O
9	SO_M	I	40	SI	I
10	CSB_M	O	39	SCK	I
11	CSB_E	I	38	CSB	I
12	SO_E	O	37	DVDD1	P
13	GAD	I	36	START	I
14	RSB	I	35	NC	-
15	CLK	I	34	WSEL0	I
16	TSMOD	I	33	WSEL1	I
17	VREFI	I	32	NC	-
18	VREFO	O	31	DVSS	P
19	ADCI	I	30	WSEL2	I
20	AVSS	P	29	WSEL3	I
21	AVDD	P	28	INTP0	I
22	AMPO	O	27	INTP1	I
23	OUTAI	I	26	NC	-
24	OUTBI	I	25	WP	I

Where,

I : input
O: output
B(I) : bidirectional (input at reset)
B(O) : bidirectional (output at reset)
P: power supply

Termination of unused pins

O: open
I : pull-up or pull-down if no on-chip pull-up/down
B: open (on-chip pull-down installed)

PIN DESCRIPTION

1. HOLD
   Hold E2PROM. It must be connected to DVDD1.
   For more detail, see the E2PROM datasheet.

2. OE
   Output Enable
   For IO port control mode:
   - bit OERST = 0: OE acts as an input.
   - bit OERST = 1: OE acts as an output with respect to the pin ST transparently.

   For register control mode:
   - OE outputs the value of the bit OE_REG.

3. RSTO
   Driver Reset Output
   To force synchronization of the step position with the driver, the driver reset pulse is output once an electrical cycle, while the bit RSTAD is set 1.
   For IO port control mode:
   - RSTO outputs with respect to the pin RSTI transparently.

   For register control mode:
   - RSTO outputs the value of the bit RST_REG.

4. FR
   Rotation Direction
   For IO port control mode:
   - Input

   For register control mode:
   - FR outputs the value of the bit FR_REG.

5. STP
   Step Pulse Output

6. DVSS
   Digital Ground

7. DVDD1
   Power Supply for the E2PROM and the Digital Portion of the Main Chip

8. RSTI
   Driver Reset Input for IO Port Control Mode
   For register control mode, it is ignored.

9. SO_M and 12. SO_E
   E2PROM output. They must be connected on a board.

10. CSB_M and 11. CSB_E
    E2PROM chip select pins. They must be connected on a board.

13. GAD
    High Efficient Current Control Mode
    The adaptive motor current control mode is enabled by GAD = H or the bit GAD_REG = 1.

14. RSB
    System Reset Input
    LC898240 is reset by RSB = L. After the reset is released, it will start the E2PROM data download to the registers.

15. CLK
    Clock Input
    Frequency range is from 840kHz through 10MHz

16. TSMOD
    Test Mode
    It must be connected to DVSS or open.

17. VREFI
    Reference Voltage Input
    It must be connected to AVDD.

18. VREFO
    Current Control Reference Voltage Output

19. ADCI
    ADC Input

20. AVSS
    Ground of the Analog Portion

21. AVDD
    Power Supply for the Analog Portion

22. AMPO
    Amplifier Output

23. OUTAI and 24. OUTBI
    Motor Signal Input

25. WP
    Write Protection of E2PROM

26. NC, 32. NC and 35. NC
    No Connection

27. INTP1 and 28. INTP0
    Interpolation Setting for the Acceleration Curve
    For IO port control mode:
    - INTP[1:0] = 0h: not interpolation
    - INTP[1:0] = 1h: interpolate 1 point between the steps based on E2PROM data
    - INTP[1:0] = 2h: interpolate 3 point between the steps based on E2PROM data
    - INTP[1:0] = 3h: interpolate 7 point between the steps based on E2PROM data

    For register control mode, it is ignored.

29. WSEL3, 30. WSEL2, 33. WSEL1 and 34. WSEL0
Acceleration Curve Selection
For IO port control mode:
- WSEL[3:0] = 0h: the acceleration curve #0
- WSEL[3:0] = 1h: the acceleration curve #1
- WSEL[3:0] = 2h: the acceleration curve #2
- WSEL[3:0] = 3h: the acceleration curve #3
- WSEL[3:0] = 4h: the acceleration curve #4
- WSEL[3:0] = 5h: the acceleration curve #5
- WSEL[3:0] = 6h: the acceleration curve #6
- WSEL[3:0] = 7h: the acceleration curve #7
- WSEL[3:0] = 8h: the acceleration curve #8
- WSEL[3:0] = 9h - Fh: N.A.

31. DVSS
Digital Ground

36. START
Motor Rotation Control
The bit STPSEL = 0: START acts as the step pulse input
The bit STPSEL = 1: START acts as the start/stop command input

37. DVDD1
Power Supply for the E2PROM and the Digital Portion of the Main Chip

38. CSB, 39. SCK, 40. SI and 41. SO
SPI Interface

42. STS1 and 43. STS0
Status Output of LC898240

44. DVDD2
Power Supply for the Digital Portion of the Main Chip

45. ST
Driver Standby
For IO port control mode:
- The bit DERST = 0: ST signal input
- The bit DERST = 1: ST signal input to output to OE

For register control mode:
- ST outputs the value of the bit ST_REG.
- For the unipolar driver STK672-XXXX, this pin must be open.

46. MD2, 47. MD1 and 48. MD0
Mode Switch
For IO port control mode: MD signal input
For register control mode: the value of the register MD_REG is output.

ABSOLUTE MAXIMUM RATINGS (Note 1)

Parameter		Pins	Ratings	Unit
Supply voltage		DVDD1	–0.3 to 4.6	V
		DVDD2	–0.3 to 6.0	V
		AVDD	–0.3 to 4.6	V
Input/output voltage	V_{INd1}, V_{OUTd1}		–0.3 to DVDD1 + 0.3	V
	V_{INd1t}		–0.3 to 6.0	V
	V_{INd2}, V_{OUTd2}		–0.3 to DVDD2 + 0.3	V
	V_{INa}, V_{OUTa}		–0.3 to AVDD + 0.3	V
Input/output current	I_i, I_o		±20	
Storage temperature	T_{stg}		–55 to 125	°C
Operating ambient temperature	T_{opg}		-40 to 85	°C

1. Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

ELECTRICAL CHARACTERISTICS T_a: -40 to 85°C (Note 2)

Parameter	Symbol	Condition	Min	Typ	Max	Unit
Supply-voltage range	DVDD1	|DVDD1 – AVDD| ≤ 0.3	3.0	3.3	3.6	V
	DVDD2	DVDD1 ≤ DVDD2 + 0.3 AVDD ≤ DVDD2 + 0.3	3.0	3.3	5.5	V
		|DVDD1 – AVDD| ≤ 0.3	3.0	3.3	3.6	V
DIGITAL INPUTS (HOLD, WP, CSB_E)						
High level input voltage	V_{IH}		0.7 × DVDD1		DVDD1	V
Low level input voltage	V_{IL}		0		0.3 × DVDD1	V
DIGITAL INPUTS (CLK)						
High level input voltage	V_{IH}		0.7 × DVDD1		5.5	V
Low level input voltage	V_{IL}		0		0.2 × DVDD1	V
DIGITAL INPUTS (RSB, RSTI, GAD, TSMOD, START, SO_M, WSEL3, WSEL2, WSEL1, WSEL0, INTP1, INTP0)						
High level input voltage	V_{IH}		0.75 × DVDD1		5.5	V
Low level input voltage	V_{IL}		0		0.15 × DVDD1	V
DIGITAL INPUTS (CSB, SCK, SI, OE, FR, ST, MD2, MD1, MD0)						
High level input voltage	V_{IH}		0.75 × DVDD2		DVDD2	V
Low level input voltage	V_{IL}		0		0.15 × DVDD2	V
DIGITAL OUTPUTS (SO_E)						
High level output voltage	V_{OH}	I_{OH} = -2mA	0.8 × DVDD1			V
Low level output voltage	V_{OL}	I_{OL} = 2mA			0.4	V
DIGITAL OUTPUTS (CSB_M)						
High level output voltage	V_{OH}	I_{OH} = -2mA	DVDD1 – 0.4			V
Low level output voltage	V_{OL}	I_{OL} = 2mA			0.4	V
DIGITAL OUTPUTS (RSTO, STP, STS1, STS0, SO, OE, FR, ST, MD2, MD1, MD0)						
High level output voltage	V_{OH}	I_{OH} = -2mA	DVDD2 – 0.4			V
Low level output voltage	V_{OL}	I_{OL} = 2mA			0.4	V

Continued on next page

Continued from preceding page

Parameter	Symbol	Condition	Min	Typ	Max	Unit
MOTOR SIGNAL INPUTS (OUTAI, OUTBI)						
Input voltage range	V_{OUTI}	T_a: -40 to 85°C	0		AVDD	V
AMPLIFIER OUTPUT (AMPO)						
Output voltage range	V_{AMPO}	T_a: -40 to 85°C	0		AVDD	V
Maximum gain	G_{HAMPO}	T_a = 25°C		16		V/V
Minimum gain	G_{LAMPO}	T_a = 25°C		1		V/V
ADC INPUTS (ADCI)						
Input voltage range	V_{ADCI}	T_a: -40 to 85°C	0		AVDD	V
ADC offset error	IL_{ADCI}	T_a = 25°C			±2.0	LSB
ADC differential non-linearity	DIL_{ADCI}	T_a = 25°C			±1.0	LSB
REFERENCE VOLTAGE INPUT (VREFI)						
Input voltage range	V_{VREFI}	T_a: -40 to 85°C		AVDD	AVDD	V
REFERENCE VOLTAGE OUTPUT (VREFO)						
Output voltage range	V_{VREFO}	T_a: -40 to 85°C AVDD = 3.3V VREFI = 3.3V	0.24		3.07	V
DAC integral non-linearity	INL_{VREFO}	T_a = 25°C			±2.0	LSB
DAC differential non-linearity	DNL_{VREFO}	T_a = 25°C			±1.0	LSB
DAC zero scale voltage	V_{ZVREFO}	T_a = 25°C	0.14	0.24	0.34	V
DAC full scale voltage	V_{FVREFO}	T_a = 25°C	2.97	3.07	3.17	V

2. Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

FUNCTIONAL DESCRIPTON

Control Functions

LC898240 provides the following control functions.

(1) Driver Control: It controls a stepper motor driver connected to LC898240.

(2) Programmable Speed Control: The step pulses are generated based on the target speed and acceleration/deceleration curve.

(3) High Efficient Current Control: The motor driving current is adapted against the load, and it gives high power efficiency.

Power On/Off

Ideally, he power should be supplied to DVDD1, AVDD, DVDD2 and driver at the same time. But, if the simultaneity is impossible, the power-on sequence must be conformed to the following order within 100ms.

DVDD1 > AVDD > DVDD2 > driver

The power-off should also be done at the same time as well as power-on. And, the power-off sequence must be conformed to the following order within 100ms.

Driver > DVDD2 > AVDD > DVDD1

Speed Acceleration Control

This function is activated by set 1 to the bit STPSEL. When the pin START is set H, or bit START_REG is set 1, the step pulses are generated and output to the pin STP, based on the acceleration curve data written in the E2PROM.

Current Control

The motor current is adjusted by the reference voltage at the pin VREFO driven by 8-bit DAC.

REGISTER DESCRIPTION

E2PROM

Register Map

Address from	to	Description
0000h	002Fh	initial default settings for the main chip registers
0030h	003Fh	unused (filled by FFh)
0040h	03AFh	acceleration curve #0
03B0h	03BFh	unused (filled by FFh)
03C0h	072Fh	acceleration curve #1
0730h	073Fh	unused (filled by FFh)
0740h	0AAFh	acceleration curve #2
0AB0h	0ABFh	unused (filled by FFh)
0AC0h	0E2Fh	acceleration curve #3
0E30h	0E3Fh	unused (filled by FFh)
0E40h	11AFh	acceleration curve #4
11B0h	11BFh	unused (filled by FFh)
11C0h	152Fh	acceleration curve #5
1530h	153Fh	unused (filled by FFh)
1540h	18AFh	acceleration curve #6
18B0h	18BFh	unused (filled by FFh)
18C0h	1C2Fh	acceleration curve #7
1C30h	1C3Fh	unused (filled by FFh)
1C40h	1FAFh	acceleration curve #8
1FB0h	1FFFh	unused (filled by FFh)

Initial Default Settings

After the reset is released, the data written in the address 0000h to 002Fh of the E2PROM will be downloaded to the same address of the main chip registers. This function allows to set the initial default value for the registers. The register setting can be overwritten through the SPI.

Acceleration Curve

The E2PROM has the registers for nine acceleration curves with 440 steps for each. The step interval time is represented in 16-bit code.

$$T_{STP} = (D_{ROM} + 1) \times T_{CLK}$$

Where,

T_{STP}: step interval time [s]

D_{ROM}: E2PROM data. MSB in even address, and LSB in odd address.

T_{CLK}: clock period [s]

The end of the acceleration curve sequence is set by D_{ROM} = FFFFh, and the motor rotation is kept in the constant speed.

Main Chip Register

Register Map

ADDR[6:0]	Register Name	Default	Function	R/W
0000h	AIFSEL	00h	acceleration control interface configuration	R/W
0001h	START	00h	start/stop acceleration control	R/W
0002h	WSEL	00h	acceleration curve selection	R/W
0003h	INTP	00h	interpolation setting between steps	R/W
0004h	DSKIP	00h	skip setting at deceleration	R/W
0005h	SETST	00h	wait time for acceleration	R/W
0006h	SETED	00h	wait time for stop	R/W
0007h	STMODE	00h	constant speed period programming mode selection	R/W
0008h	STCNTL	00h	step counts for constant speed period (LSB)	R/W
0009h	STCNTH	00h	step counts for constant speed period (MSB)	R/W
0010h	DPSTG	00h	driver initial setting	R/W
0011h	DTSTG	00h	driver active setting	R/W
0012h	GCKRTO	00h	clock setting	R/W
0013h	GADSLIM	00h	speed setting for high efficient mode	R/W
0014h	GPSTG	00h	initial setting for High efficient mode	R/W
0015h	NMBUSTG	00h	NM/BU setting	R/W
0016h	BDSTG	00h	BD setting	R/W
0017h	SOSTG	00h	step out detection setting	R/W
0018h	GADMAX	00h	upper limit of VREFO level	R/W
0019h	GADSTOP	00h	VREFO level setting at motor stop	R/W
001Ah	GADSTAT	00h	FF value	R/W
001Bh	ADTDLT	00h	AD increment value target	R/W
001Ch	ADTBSE	00h	AD base value target	R/W
001Dh	ADTLIM	00h	AD minimum value target	R/W
001Eh	ADMDRTO2	00h	excitation mode ratio setting #2	R/W
001Fh	ADMDRTO3	00h	excitation mode ratio setting #3	R/W
0020h	ADMDRTO4	00h	excitation mode ratio setting #4	R/W
0021h	ADBURTO	00h	burst up threshold	R/W
0022h	ADSTO	00h	AD step out level	R/W
0023h	IPSTG	00h	analog portion	R/W
0024h	STSSEL	00h	status out setting	R/W
0025h	IFSEL	00h	interface setting	R/W
0030h	STS	-	status	R
0031h	PHSCNT	-	phase	R
0032h	SPDCEF	-	speed coefficient	R
0033h	ADDAT_LT_ADJ	-	ADC judgement point voltage	R
0034h	GADDAT	-	VREFO coefficient	R

Register Function Description

AIFSEL: acceleration control interface configuration (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0000h	00h	-	-	-	-	-	-	-	AIFSEL

AIFSEL = 0: I/O port control mode, using pins; START, WSEL3/2/1/0 and INTP1/0.
AIFSEL = 1: register control mode, using registers; START_REG, WSEL_REG and INTP_REG.

START: start/stop acceleration control (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0001h	00h	-	-	-	-	-	-	-	START_REG

It is effective during the register control mode (AIFSEL = 1).
Set START_REG from 0 to 1 during motor stop: start acceleration
Set START_REG from 1 to 0 during motor running in the constant speed: start deceleration

WSEL acceleration curve selection (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0002h	00h	-	-	-	-	WSEL_REG[3:0]			

It is effective during the register control mode (AIFSEL = 1).
WSEL_REG[3:0] = 0h: the acceleration curve #0
WSEL_REG[3:0] = 1h: the acceleration curve #1
WSEL_REG[3:0] = 2h: the acceleration curve #2
WSEL_REG[3:0] = 3h: the acceleration curve #3
WSEL_REG[3:0] = 4h: the acceleration curve #4
WSEL_REG[3:0] = 5h: the acceleration curve #5
WSEL_REG[3:0] = 6h: the acceleration curve #6
WSEL_REG[3:0] = 7h: the acceleration curve #7
WSEL_REG[3:0] = 8h: the acceleration curve #8
WSEL_REG[3:0] = 9h - Fh: N.A.

INTP interpolation setting between steps (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0003h	00h	-	-	-	-	-	-	INTP_REG[1:0]	

It is effective during the register control mode (AIFSEL = 1).
INTP_REG[1:0] = 0h: not interpolation
INTP_REG[1:0] = 1h: interpolate 1 point between the steps based on E2PROM data
INTP_REG[1:0] = 2h: interpolate 3 point between the steps based on E2PROM data
INTP_REG[1:0] = 3h: interpolate 7 point between the steps based on E2PROM data

DSKIP skip setting at deceleration (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0004h	00h	-	-	-	-	-	-	DSKIP[1:0]	

The number of skip of the acceleration curve data for deceleration
DSKIP = 0: no skip
DSKIP = 1: 1 point skip
DSKIP = 2: 2 points skip
DSKIP = 3: 3 points skip

SETST wait time for acceleration R/W

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0005h	00h	SETST[7:0]							

Waiting time for acceleration
$T_{WAIT} = T_{INIT} \times SETST[7:0]$
Where,
T_{WAIT}: waiting time [s]
T_{INIT}: initial acceleration pulse width [s]

SETED wait time for stop R/W

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0006h	00h	SETED[7:0]							

Waiting time for stop
$T_{WAIT} = T_{INIT} \times SETED[7:0]$
Where,
T_{WAIT}: waiting time [s]
T_{INIT}: initial acceleration pulse width [s]

STMODE constant speed period programming mode selection (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0007h	00h	-	-	-	-	-	-	-	STMODE

STMODE = 0: continue rotation at the constant speed after the acceleration until START = 0
STMODE = 1: rotate at the constant speed after the acceleration for the number of steps which is set in the register STCNT, followed by automatic deceleration and stop
START must be set 0 after the motor stops.

STCNTL step counts for constant speed period (LSB) (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0008h	00h	STCNT[7:0]							

STCNTL step counts for constant speed period (MSB) (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0009h	00h	-	-	-	-	-	-	-	STCNT[8]

The number of steps for the constant speed in STMODE = 1
STCNT must not be zero.

DPSTG driver initial setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0010h	00h	RSTIV	RSTPHS	RSTAD	OERST	OEIV	OEMV	MDSEL[1:0]	

RSTIV

Polarity of RST signal.
RSTIV = 0: low active (reset by L)
RSTIV = 0: high active (reset by H)

RSTPHS

Synchronize with driver
RSTPHS = 0: reset at 315 degree
RSTPHS = 1: reset at 315 degree for full step excitation mode, reset at 0 degree for others

RSTAD

Reset phase adjustment
RSTAD = 0: no adjustment for bipolar driver
RSTAD = 1: adjustment enabled for unipolar driver

OERST

OE signal control
OERST = 0: no OE signal control. The pin OE is switched to input of OE signal during I/O port control mode
OERST = 1: activate OE single control. The pin OE is switched to output of OE signal. The pin ST is the OE signal input

OEIV

OE signal polarity
OEIV = 0: high active
OEIV = 1: low active

OEMV

OEMV = 0: ignore step pulse while the output is disabled
OEMV = 1: advance phase with respect to the step pulse input even though the output is disabled

MDSEL[1:0]

MDSEL = 0h

MD = 0h: full step, both edges
MD = 1h: half step, both edges
MD = 2h: full step, rising edge
MD = 3h: half step, rising edge
MD = 4h: quarter step, both edges
MD = 5h: 1/8 step, both edges
MD = 6h: quarter step, rising edge
MD = 7h: 1/8 step, rising edge

Pin connection
LC898240 pin MD2 --- open
LC898240 pin MD1 --- STK672-6XXX pin MODE2
LC898240 pin MD0 --- STK672-6XXX pin MODE1

MDSEL = 1h
MD = 0h: half step, both edges
MD = 1h: quarter step, both edges
MD = 2h: 1/8 step, both edges
MD = 3h: 1/16 step, both edges
MD = 4h: full step, rising edge
MD = 5h: half step, rising edge
MD = 6h: quarter step, rising edge
MD = 7h: 1/8 step, rising edge

Pin connection
LC898240 pin MD2 --- STK672-4XXX pin MODE3
LC898240 pin MD1 --- STK672-4XXX pin MODE2
LC898240 pin MD0 --- STK672-4XXX pin MODE1

MDSEL = 2h
MD = 0h: full step, rising edge
MD = 1h: half step, rising edge
MD = 2h: quarter step, rising edge
MD = 3h: 1/8 step, rising edge
MD = 4h: full step, rising edge
MD = 5h: half step, rising edge
MD = 6h: quarter step, rising edge
MD = 7h: 1/16 step, rising edge

Pin connection
LC898240 pin MD2 --- open
LC898240 pin MD1 --- LV8736V pin MD2
LC898240 pin MD0 --- LV8736V pin MD 1

MDSEL = 3h
MD = 0h: full step, rising edge
MD = 1h: half step, rising edge
MD = 2h: half step, rising edge
MD = 3h: quarter step, rising edge
MD = 4h: full step, rising edge
MD = 5h: half step, rising edge
MD = 6h: quarter step, rising edge
MD = 7h: half step, rising edge

Pin connection
LC898240 pin MD2 --- open
LC898240 pin MD1 --- LV8740V pin MD2
LC898240 pin MD0 --- LV8740V pin MD 1

DTSTG driver active setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0011h	00h	GAD_REG	ST_REG	RST_REG	OE_REG	FR_REG	MD_REG[2:0]		

GAD_REG
Enable/disable the high efficient (adaptive current control) function
Enabled when bit GAD_REG = 1 or pin GAD = H

ST_REG
Outputs ST signal from the pin ST during the register control mode
When it used with the unipolar driver STK672-XXXX, ST_REG value must be same as bit RST_REG.
During IO port control mode, ST_REG is ignored.

RST_REG
Outputs RST signal from the pin RSTO during the register control mode
During IO port control mode, RST_REG is ignored.

OE_REG
Outputs OE signal from the pin OE during the register control mode
During IO port control mode, OE_REG is ignored.

FR_REG

Outputs FR signal from the pin FR during the register control mode

During IO port control mode, FR_REG is ignored.

MD_REG[2:0]

Outputs MD signal from the pins MD2, MD1 and MD0 during the register control mode

During IO port control mode, MD_REG is ignored.

GCKRTOclock setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0012h	00h	-	-	GCKRTO[5:0]					

GCKRTO[5:0]

Defines the ratio between CLK and virtual clock (GCK = 840kHz)

$$\frac{f_{gck}}{f_{clk}} = 2^{-1}GCKRTO[5] + 2^{-2}GCKRTO[4] + \cdots + 2^{-6}GCKRTO[0]$$

For example, in case of a clock of 4MHz at the pin CLK,

$$\frac{f_{gck}}{f_{clk}} = \frac{0.84}{4} = 0.21$$

$$GCKRTO[5:0] = 0\text{Dh} \rightarrow 0.203125$$

The virtual step pulse velocity is defined by,

$$f_{\text{VSTP}} = \frac{f_{STP} \times f_{gck}}{f_{clk} \times GCKRTO[5:0] \times k_{MD}}$$

f_{VSTP}: virtual step pulse velocity [pps]

f_{STP}: step pulse velocity [pps]

k_{MD}: excitation mode factor (1 for half, 2 for quarter, 4 for 1/8 and 8 for 1/16 step)

GADSLIM speed setting for smooth stepper mode (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0013h	00h	-	GADAC	GADSLIM[5:0]					

GADAC

The high efficient mode (adoptive current control) and the acceleration control works concurrently.

GADAC = 0: not concurrent

GADAC = 1: high efficient mode activated after the acceleration completed

GADSLIM

The high efficient mode is activated when the motor speed is faster than the speed specified by GADSLIM.

For example, to specify the virtual step pulse speed threshold 1900pps, set 0Bh for GADSLM[5:0].

GPSTG initial setting for high efficient mode (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0014h	00h	-	GADPHS	GADNUM[1:0]		OVPSLIM[3:0]			

GADPHS

Defines the motor signal for OUTAI and OUTBI

GADPHS = 0: phase B (phase OUT2)

GADPHS = 1: phase A (phase OUT1)

GADNUM

VREFO control frequency (over sampling)

GADNUM = 0h: default

GADNUM = 1h: 2x

GADNUM = 2h: 4x

GADNUM = 3h: 8x

OVPSLIM

ADCI waveform tuning

NMBUSTG NM/BU setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0015h	00h	-	NMSEL	NMSTEP[1:0]		BUEN	BUSTEP[2:0]		

NMSEL

VREFO adjust method

NMSEL = 0: constant type

NMSEL = 1: differential type

NMSTEP

VREFO adjust step

NMSEL = 0

NMSTEP = 0h: 1/256 of VREFO full scale voltage

NMSTEP = 1h: 2/256 of VREFO full scale voltage

NMSTEP = 2h: 4/256 of VREFO full scale voltage

NMSTEP = 3h: 8/256 of VREFO full scale voltage

NMSEL = 1

NMSTEP = 0h: (|target – judge point| / 32) × (1/256 of VREFO full scale voltage)

NMSTEP = 1h: (|target – judge point| / 16) × (1/256 of VREFO full scale voltage)

NMSTEP = 2h: (|target – judge point| / 8) × (1/256 of VREFO full scale voltage)

NMSTEP = 3h: (|target – judge point| / 4) × (1/256 of VREFO full scale voltage)

BUEN

BUEN = 0: burst up off

BUEN = 1: burst up on

BUSTEP

VREFO adjustment resolution at the bust up

BUSTEP = 0h: 2/256 of the VREFO full scale voltage

BUSTEP = 1h: 4/256 of the VREFO full scale voltage

BUSTEP = 2h: 8/256 of the VREFO full scale voltage

BUSTEP = 3h: 16/256 of the VREFO full scale voltage

BUSTEP = 4h: 32/256 of the VREFO full scale voltage

BUSTEP = 5h: 64/256 of the VREFO full scale voltage

BUSTEP = 6h: 128/256 of the VREFO full scale voltage

BUSTEP = 7h: 256/256 of the VREFO full scale voltage

BDSTG BD setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0016h	00h	-	BDSEL	BDNUM[1:0]		BDEN	BDSTEP[2:0]		

BDSEL

Burst down condition

BDSEL = 0: higher voltage than the judgement point

BDSEL = 1: ADCI waveform is convex.

BDNUM

The bust down condition qualifier: when the event consecutively repeated for the following number of times, this function is activated.

BDNUM = 0h: twice

BDNUM = 0h: 4 times

BDNUM = 0h: 8 times

BDNUM = 0h: 16 times

BDEN

BDEN = 0: burst down deactivated

BDEN = 1: burst down activated

BDSTEP

VREFO adjustment resolution at the bust down

BDSTEP = 0h: 8/256 of the VREFO full scale voltage

BDSTEP = 1h: 12/256 of the VREFO full scale voltage

BDSTEP = 2h: 16/256 of the VREFO full scale voltage

BDSTEP = 3h: 24/256 of the VREFO full scale voltage

BDSTEP = 4h: 32/256 of the VREFO full scale voltage

BDSTEP = 5h: 48/256 of the VREFO full scale voltage

BDSTEP = 6h: 64/256 of the VREFO full scale voltage

BDSTEP = 7h: 96/256 of the VREFO full scale voltage

SOSTG step out detection setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0017h	00h	-	-	-	-	-	SOMD	SONUM	

SOMD

SOMD = 0: set the flag STPOUT = 1 whenever the step out is detected

SOMD = 1: latch the flag STPOUT = 1 when the step out is detected, and clear the flag by RST or ST reset

SONUM

The step out detection qualifier: when the event consecutively repeated for the following number of times, the step out detection is flagged.

SONUM = 0h: once

SONUM = 1h: twice

SONUM = 2h: 8 times

SONUM = 3h: 16 times

GADMAX upper limit of VREFO level (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0018h	00h	GADMAX[7:0]							

GADMAX[7:0]

Upper limit of VREFO voltage level

$$V_{LIMIT} = V_{FULL} \times \frac{GADMAX}{256}$$

GADSTOP VREFO level setting at motor stop (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0019h	00h	GADSTOP[7:0]							

GADSTOP

VREFO voltage level during motor stop (RDY = L and MACT L)

$$V_{STOP} = V_{FULL} \times \frac{GADSTOP}{256}$$

GADSTOP value must be equal to or less than GADMAX. If this function is not used, set the same value to GADSTOP as GADMAX.

GADSTAT FF value (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
001Ah	00h	GADSTAT[7:0]							

GADSTAT

The initial value of VREFO for the high efficient mode as feedforward control

$$V_{FF} = V_{FULL} \times \frac{GADSTAT}{256}$$

GADSTAT value must be equal to or less than GADMAX. If this function is not used, set the same value to GADSTAT as GADMAX.

ADTDLT AD increment value target (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
001Bh	00h	ADTDLT[7:0]							

See the illustration below.

ADTBSE AD base value target (R/W)

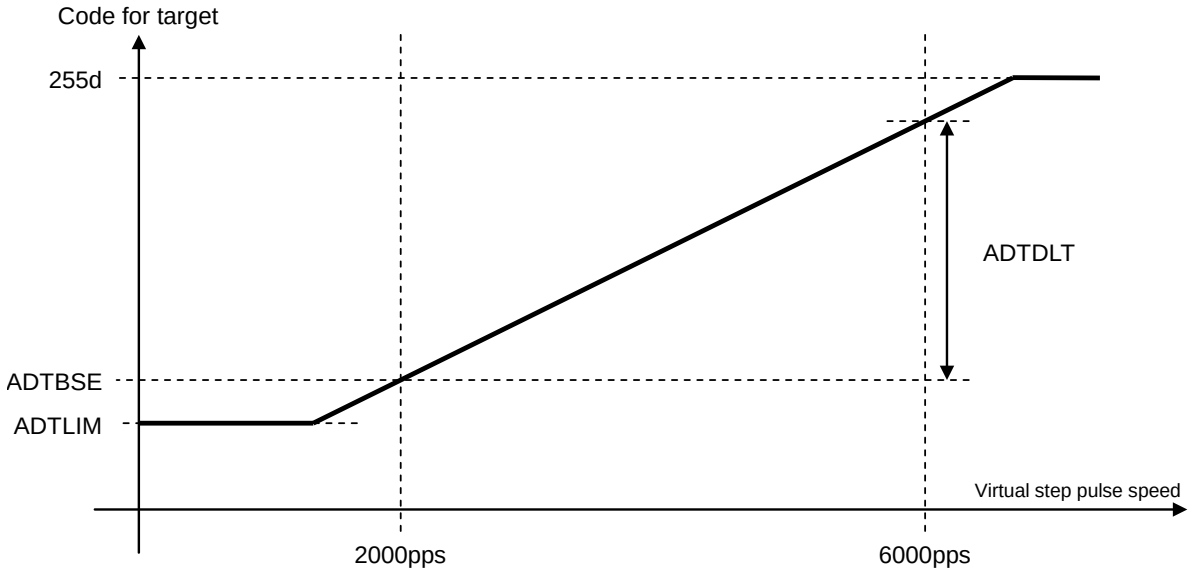
Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
001Ch	00h	ADTBSE[7:0]							

See the illustration below.

ADTLIM AD minimum value target (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
001Dh	00h	ADTLIM[7:0]							

See the illustration below.



ADMDRTO2 excitation mode ratio setting #2 (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
001Eh	00h	-	-	ADMDRTO2[5:0]					

ADMDRTO2[5:0]

The target value ratio between half step and quarter step excitation mode

$$\text{ratio} = 2^{-1}ADMDRTO2[5] + 2^{-2}ADMDRTO2[4] + \cdots + 2^{-6}ADMDRTO2[0]$$

ADMDRTO3 excitation mode ratio setting #3 (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
001Fh	00h	-	-	ADMDRTO3[5:0]					

ADMDRTO3[5:0]

The target value ratio between half step and 1/8 step excitation mode

$$\text{ratio} = 2^{-1}ADMDRTO3[5] + 2^{-2}ADMDRTO3[4] + \cdots + 2^{-6}ADMDRTO3[0]$$

ADMDRTO4 excitation mode ratio setting #4 (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0020h	00h	-	-	ADMDRTO4[5:0]					

ADMDRTO4[5:0]

The target value ratio between half step and 1/16 step excitation mode

$$\text{ratio} = 2^{-1}ADMDRTO4[5] + 2^{-2}ADMDRTO4[4] + \cdots + 2^{-6}ADMDRTO4[0]$$

ADBURTO burst up threshold (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0021h	00h	-	-	ADBURTO[5:0]					

ADBURTO[5:0]

The target value ration against the burst up threshold

$$\text{ratio} = 2^{-1}ADBURTO[5] + 2^{-2}ADBURTO[4] + \cdots + 2^{-6}ADBURTO[0]$$

ADSTO AD step out level (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0022h	00h	ADSTO[7:0]							

ADSTO[7:0]

The code for tentative step out judgement

IPSTG analog portion (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0023h	00h	-	-	ADCWDT[2:0]			AMPGN[2:0]		

ADCWDT[2:0]

Analog characteristics setting

It must be 2.

AMPGN[2:0]

Gain of the amplifier for AMPO output

AMPGN = 0h: 1x

AMPGN = 1h: 2x

AMPGN = 2h: 4x

AMPGN = 3h: 8x

AMPGN = 4h: 16x

AMPGN = 5h to 7h: inhibited

STSSEL status out setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0024h	00h	STS1SEL[3:0]				STS0SEL[3:0]			

STS1SEL[3:0]

Status signal selection for the pin STS1

STS0SEL[3:0]

Status signal selection for the spin STS0

The spins STS1 and STS0 get H during E2PROM down load, after the reset by RSB is released.

STS1SEL = 0h: L

STS1SEL = 1h: RDY

STS1SEL = 2h: MACT

STS1SEL = 3h: ACB

STS1SEL = 4h: MONI (driver home position)

STS1SEL = 5h: STPOUT (step out detected)

STS1SEL = 6h: GAD_EN (high efficient mode)

STS1SEL = 7h: ADJ_EN (VREF adjusted)

STS1SEL = Ah: BSTDWN (bust down)

STS1SEL = Bh: BSTUP (burst up)

STS1SEL = Ch to Fh: not allowed

IFSEL interface setting (R/W)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0025h	00h	-	-	-	-	-	-	STPSEL	IFSEL

STPSEL

Step pulse source selection

STPSEL = 0: input from external through the pin START

STPSEL = 1: acceleration control mode. The step pulse is generated by the acceleration controller. The pin START is used for acceleration start (START = H) and deceleration start (START = L)

IFSEL

Control mode selection

IFSEL = 0: IO port control mode

Input pins: ST, FR, MD2, MD1, MD0, and either OE (OERST = 0) or ST (OERST = 1, OE output)

Registers ST_REG, RST_REG, OE_REG, FR_REG and MD_REG are ignored.

IFSEL = 1: register control mode

Outputs ST, FR, MD2, MD1, MD0, OE and RSTO are driven by ST_REG, FR_REG, MD_REG, OE_REG and RST_REG.

STS status (Read Only)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0030h	00h	-	GAD_EN	STPOUT	MONI	ACB	MACT	RDY	INIT

GAD_EN
1: the high efficient mode
STPOUT
1: step out detected
MONI
1: driver home position
ACB
1: acceleration completed
MACT
1: motor active excluding wait time
0: motor inactive
If the acceleration function is not used, set 1 by step pulse input, and set 0 when speed gets lower than approximately 350pps (pulse interval equivalent to half step).
RDY
1: motor active including wait time
INIT
1: E2PROM download on-going

PHSCNT phase (Read Only)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0031h	00h	-	-	PHSCNT[5:0]					

PHSCNT
Phase count

$$\text{phase} = 360° \times \frac{PHSCNT[5:0]}{64}$$

SPDCEF speed coefficient (Read Only)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0032h	00h	-	-	SPDCEF[5:0]					

SPDCEF[5:0]
Motor speed coefficient

ADDAT_LT_ADJ ADC judgement point voltage (Read Only)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0033h	00h	ADDAT_LT_ADJ[7:0]							

ADDAT_LT_ADJ[7:0]
Code of the ADC judgement point voltage

GADDAT VREFO coefficient (Read Only)

Address	Default	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0034h	00h	GADDAT[7:0]							

GADAT

$$V_{DAT} = V_{FULL} \times \frac{GADDAT}{256}$$

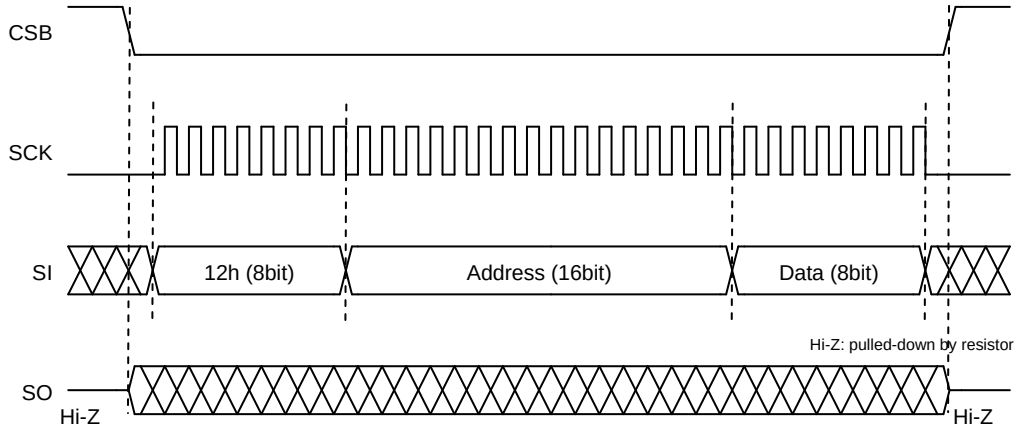
SERIAL INTERFACE (SPI)

LC898240 has the main chip registers and the non-volatile memory (E2PROM). They can be accessed through a serial interface (SPI).
During E2PROM data down load to the main chip registers, the only status register STS can be read.

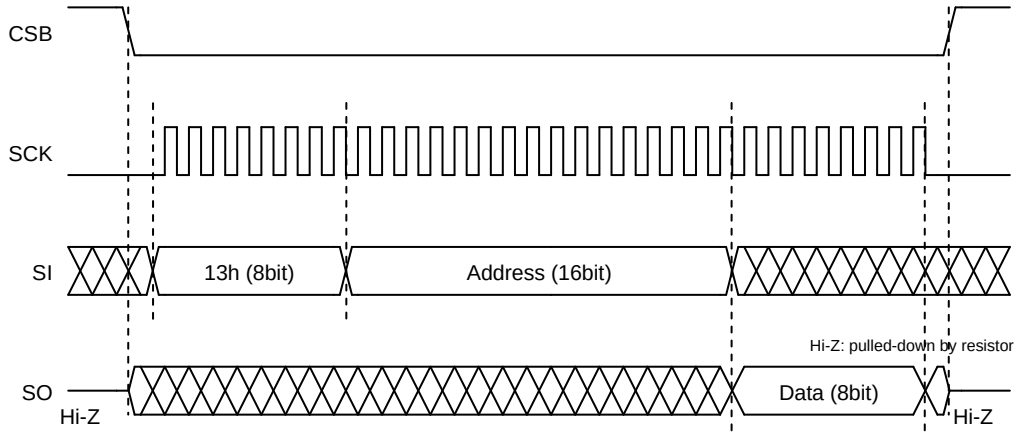
During acceleration operation, the only main chip registers can be access (write/read).
Regarding E3PROM access, refer to the E2PROM datasheet.

Write/Read Sequence

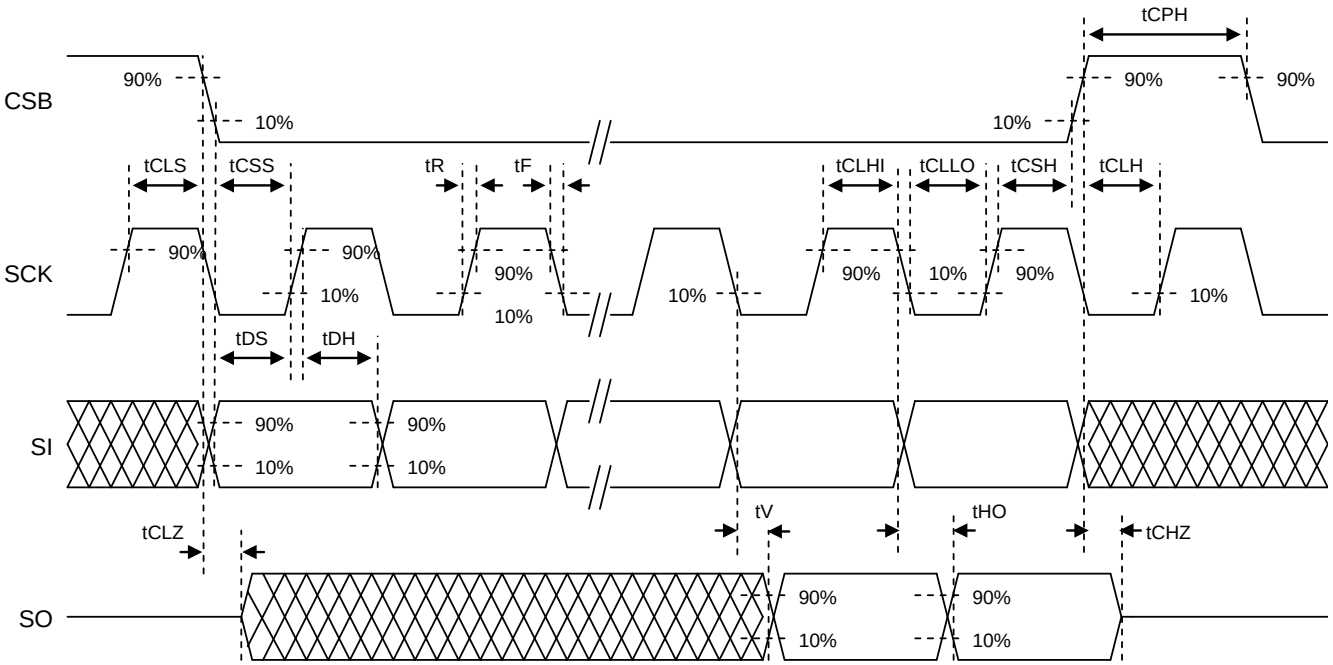
Main Chip Register Write



Main Chip Register Read



SPI Timing



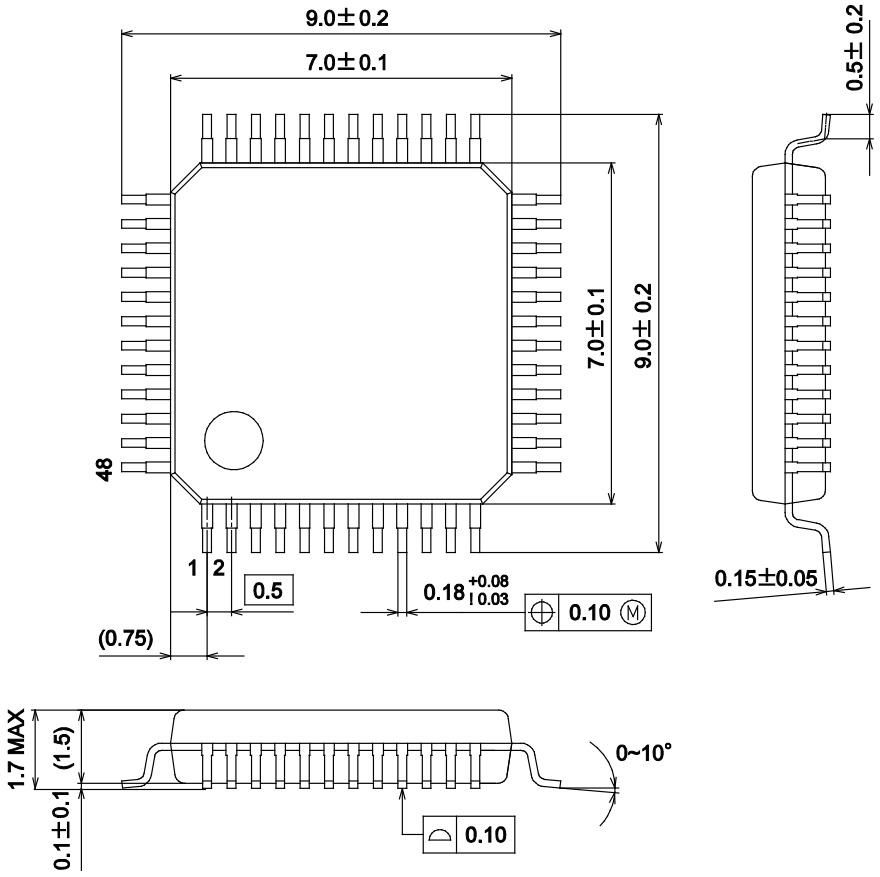
Ta = -40 to 85°C, DVSS = 0V, DVDD1 = 3.0 to 3.6V, DVDD2 = 3.0 to 5.0V, SO load = 30pF

Symbol	Parameter	min.	typ.	max.	unit
FCLK	SCK clock frequency			5	MHz
tR	SCK rising time			20	ns
tF	SCK falling time			20	ns
tCLHI	SCK H-pulse width	100			ns
tCLLO	SCK L-pulse width	100			ns
tCSS	CSB setup time	100			ns
tCLS	SCK setup time	100			ns
tDS	SI setup time	30			ns
tDH	SI hold time	40			ns
tCSH	CSB hold time	100			ns
tCLH	SCK hold time	100			ns
tCPH	CSB H-pules width	100			ns
tCHZ	SO transition time to high impedance state			170	ns
tV	SO data transition time			90	ns
tHO	SO data hold time	0			ns
tCLZ	SO high impedance state hold time	0			ns

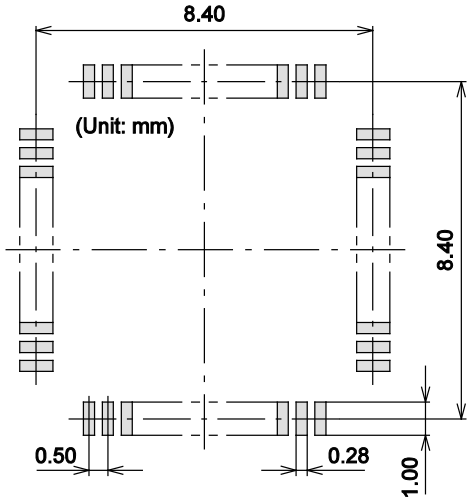
PACKAGE DIMENSIONS

unit : mm

SPQFP48 7x7 / SQFP48
CASE 131AJ
ISSUE A



SOLDERING FOOTPRINT*



NOTE: The measurements are not to guarantee but for reference only.

*For additional information on our Pb−Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

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