## LV8549MC

## Monolithic Linear IC

## 12V Low Saturation Voltage Drive Stepper Motor Driver

## ON Semiconductor ${ }^{\text {® }}$

http:/lonsemi.com


SOIC10

## Overview

The LV8549MC is a low saturation voltage stepper motor driver IC.
It is optimal for Full step motor drive in 12 V system products.

## Function

- DMOS output transistor adoption (Upper and lower total RON=1 $\Omega$ typ)
- The compact package (SOIC10) is adopted
- $\mathrm{V}_{\mathrm{CC}} \max =20 \mathrm{v}$, IO $\max =1 \mathrm{~A}$
- For one power supply (The control system power supply is unnecessary.)
- Current consumption 0 when standing by


## Specifications

Absolute Maximum Ratings at $\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Ratings | Unit |
| :--- | :--- | :--- | :--- | :---: |
| Maximum power supply voltage | V $_{\text {CC }}$ max | VCC | -0.3 to +20 | V |
| Output impression voltage | VOUT | OUT1, OUT2, OUT3, OUT4 | -0.3 to +20 | V |
| Input impression voltage | VIN | ENA, IN1, IN2 | -0.3 to +6 | V |
| GND pin outflow current | IGND | Per ch | 1.0 | A |
| Allowable Power dissipation | Pd max | ${ }^{*}$ |  | 1.0 |
| Operating temperature | Topr |  | W |  |
| Storage temperature | Tstg |  | -30 to +85 | ${ }^{\circ} \mathrm{C}$ |

*: When mounted on the specified printed circuit board ( $57.0 \mathrm{~mm} \times 57.0 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ ), glass epoxy, both sides
Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.
Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

Recommendation Operating Conditions at $\mathrm{Ta}=25^{\circ} \mathrm{C}$

| Parameter | Symbol | Conditions | Ratings | Unit |
| :--- | :--- | :--- | :--- | :---: |
| Power supply voltage | $\mathrm{V}_{\mathrm{CC}}$ | VCC | 4.0 to 16 | V |
| Input "H" level voltage | $\mathrm{V}_{I N} \mathrm{H}$ | ENA , IN1, IN2 | +1.8 to +5.5 | V |
| Input "L" level voltage | $\mathrm{V}_{I N} \mathrm{~L}$ |  | -0.3 to +0.7 | V |

Electrical Characteristics at $\mathrm{Ta}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{CC}}=12 \mathrm{~V}$

| Parameter | Symbol | Conditions | Ratings |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | min | typ | max |  |
| Power supply voltage | ${ }^{1} \mathrm{CCO}$ | Standby mode ENA=L |  |  | 1 | $\mu \mathrm{A}$ |
|  | ${ }^{\text {I CC }}{ }^{1}$ | ENA=H, no-load |  | 1.7 | 2.3 | mA |
| Input current | $\mathrm{I}_{\mathrm{IN}}$ | $\mathrm{V}_{1 \mathrm{~N}}=5 \mathrm{~V}$ | 30 | 50 | 65 | $\mu \mathrm{A}$ |
| Thermal shutdown operating temperature | Ttsd | Design certification | 150 | 180 | 210 | ${ }^{\circ} \mathrm{C}$ |
| Temperature hysteresis width | $\Delta$ Ttsd | Design certification |  | 40 |  | ${ }^{\circ} \mathrm{C}$ |
| Low voltage protection function operation voltage | VthV $\mathrm{C}_{\text {C }}$ |  | 3.3 | 3.5 | 3.65 | V |
| Release voltage | Vthret |  | 3.55 | 3.8 | 3.95 | V |
| Output ON resistance (Upper and lower total) | RON | ${ }^{\text {I OUT }}=1.0 \mathrm{~A}$ | 0.7 | 1 | 1.25 | $\Omega$ |
| Output leak current | Ioleak | $\mathrm{V}_{\mathrm{O}}=16 \mathrm{~V}$ |  |  | 10 | $\mu \mathrm{A}$ |
| Diode forward voltage | VD | ID=1.0A |  | 1.0 | 1.2 | V |

## Package Dimensions

## SOIC-10NB

CASE 751BQ-01
ISSUE A


NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
2. CONTROLLING DIMENSION: MILLIMETERS.
3. DIMENSION b DOES NOT INCLUDE DAMBAR

PROTRUSION. ALLOWABLE PROTRUSION SHALL BE 0.10 mm TOTAL IN EXCESS OF 'b
AT MAXIMUNS MATERIAL CONDION.
4. DIMENSIONS D AND E DO NOT INCLUDE

MOLD FLASH, PROTRUSIONS, OR GATE GATE BURRS SHALL NOT EXCEED 15 mm PER SIDE DIMENSIONS D AND E ARE DE ER SIDE. DIMENSIONS D AND E ARE DE
DIMENSIONS A AND B ARE TO BE DETERM INED AT DATUM F
6. A1 IS DEFINED AS THE VERTICAL DISTANCE FROM THE SEATING PLANE TO THE LOWEST POINT ON THE PACKAGE BODY.

| DIM | MILLIMETERS |  |
| :---: | :---: | :---: |
|  | MIN | MAX |
| A | 1.25 | 1.75 |
| A1 | 0.10 | 0.25 |
| A3 | 0.17 | 0.25 |
| b | 0.31 | 0.51 |
| D | 4.80 | 5.00 |
| E | 3.80 | 4.00 |
| e | 1.00 |  |
| BSC |  |  |
| H | 50 |  |
| h | 0.37 |  |
| REF |  |  |
| L | 0.40 |  |
| L2 | 0.25 |  |
| M | 1.27 |  |
| M | $0^{\circ}$ |  |

## GENERIC

 MARKING DIAGRAM*SOLDERING FOOTPRINT*

*For additional information on our Pb-Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.


## Block Diagram



## Pin Assignment

| $\mathrm{V}_{\mathrm{CC}} 1$ |  | 10 OUT1 |
| :---: | :---: | :---: |
| ENA 2 |  | 9 OUT2 |
| IN1 3 |  | 8 OUT3 |
| IN2 4 |  | 7 OUT4 |
| NC 5 |  | 6 GND |

## Pin function

| Pin No. | Pin name | Pin function | Equivalent Circuit |
| :---: | :---: | :---: | :---: |
| 1 | $\mathrm{V}_{\mathrm{CC}}$ | Power-supply voltage pin. <br> $\mathrm{V}_{\mathrm{CC}}$ voltage is impressed. The permissible operation voltage is from 4.0 to $16.0(\mathrm{~V})$. The capacitor is connected for stabilization for GND pin (6pin). |  |
| 2 | ENA | Motor drive control input pin. <br> ENA pin becomes the stand-by mode in "L" and can 0 circuitry current. When ENA pin are " H ", from the stand-by mode, the output state becomes an output corresponding to the input logic. It is a digital input, and the range of " L " level input is 0 to $0.7(\mathrm{~V})$. The range of " " H " level input is 1.8 to $5.5(\mathrm{~V})$. With built-in pull-down resistance $100(\mathrm{k} \Omega)$. |  |
| 3 | IN1 | Motor drive control input pin. <br> Driving control input pin of OUT1 (10pin) and OUT2 (9pin). With built-in pull-down resistance. | 5VREG |
| 4 | IN2 | Motor drive control input pin. <br> Driving control input pin of OUT3 (8pin) and OUT4 (7pin). With built-in pull-down resistance. |  |
| 5 | NC |  |  |
| 6 | GND | Ground pin. |  |
| 7 | OUT4 | Driving output pin. <br> The motor coil is connected between terminal OUT3 (8pin). |  |
| 8 | OUT3 | Driving output pin. <br> The motor coil is connected between terminal OUT4 (7pin). |  |
| 9 | OUT2 | Driving output pin. <br> The motor coil is connected between terminal OUT1 (10pin). |  |
| 10 | OUT1 | Driving output pin. <br> The motor coil is connected between terminal OUT2 (9pin). |  |

## Operation explanation

1. STM output control logic

| Input |  |  | Output |  |  |  | State |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ENA | IN1 | IN2 | OUT1 | OUT2 | OUT3 | OUT4 |  |
| L | - | - | OFF | OFF | OFF | OFF | Stand-by |
| H | L | L | H | L | H | L | Step 1 |
|  | H | L | L | H | H | L | Step2 |
|  | H | H | L | H | L | H | Step3 |
|  | L | H | H | L | L | H | Step4 |

2. About the switch time from the stand-by state to the state of operation

This IC has completely stopped operating when ENA pin is "L". After the reset time of about $7 \mu$ s internal settings it shifts to a prescribed output status corresponding to the state of the input when ENA pin is "H".
During reset time, all output TR OFF is maintained.

3. Example of current waveform at full-step mode.

4. Thermal shutdown function

The thermal shutdown circuit is incorporated and the output is turned off when junction temperature Tj exceeds $180^{\circ} \mathrm{C}$.
As the temperature falls by hysteresis, the output turned on again (automatic restoration).
The thermal shutdown circuit does not guarantee the protection of the final product because it operates when the temperature exceed the junction temperature of $\mathrm{Tjmax}=150^{\circ} \mathrm{C}$.
$\mathrm{TSD}=180^{\circ} \mathrm{C}$ (typ)
$\Delta \mathrm{TSD}=40^{\circ} \mathrm{C}$ (typ)

## Applied circuit example



* Bypass capacitor ( C 1 ) connected between $\mathrm{V}_{\mathrm{CC}}-\mathrm{GND}$ of all examples of applied circuit recommends the electric field capacitor of $0.1 \mu \mathrm{~F}$ to $10 \mu \mathrm{~F}$.
Confirm there is no problem in operation in the state of the motor load including the temperature property about the value of the capacitor.
Mount the position where the capacitor is mounted on nearest IC.


## Measurement connection diagram

(1) Current consumption when standing by $\mathrm{I}_{\mathrm{CC}} 0$

Current consumption ICC 1


Measure $\mathrm{I}_{\mathrm{CC}} 0$ with all SW OFF. Measure $\mathrm{I}_{\mathrm{CC}} 1$ with any of the SW1 ON.
(2) Input current $\mathrm{I}_{\mathrm{IN}}$


This is about the measurement of ENA pin. Measure the other IN1 and IN2 pins as is this case.
(3) Input "H" level voltage VINH


Measure the Vin value at the time VOUT1 changes to " H " while varying Vin 0 to 5 V .
This is about the measurement of ENA pin. Measure the other IN1 and IN2 pins as is this case.
When I measure IN1 and IN2 pins, ENA pin, please perform it in a state of "H".
(4) Low voltage protection function operation voltage $\mathrm{VthV}_{\mathrm{CC}}$ /Release voltage Vthret


Low voltage protection function
Operation voltage : VCC=12V to 0 V
Release voltage : VCC=0V to 12 V

To measure the operating voltage of the reduced voltage protection, measure the VCC value at the time VOUT1 becomes " L " while varying VCC from 12 V to 0 V .
To measure the release voltage of the reduced voltage protection, measure the VCC value at the time VOUT1 becomes " H " while varying VCC from 0 V to 12 V .
(5) Output ON resistance Ron


SW_a side :
OUT1 Upper-side/OUT2 Lower-side
OUT3 Upper-side/OUT4 Lower-side
SW_b side :
OUT1 Lower-side/OUT2 Upper-side
OUT3 Lower-side/OUT4 Upper-side

Measure OUT1 upper side and OUT2 lower side FET with the SW set to "a".
Measure OUT1 lower side and OUT2 upper side FET with the SW set to "b".
Measure OUT3 and OUT4 as are the cases of OUT1 and OUT2.
(6) Output leak current Ioleak

## <Each OUT Upper-side>


<Each OUT Lower-side>


To measure the upper FET output leak current, set the OUT to 0 V and measure the OUT current while varying VCC from 0 to 20 V .
To measure the lower FET output leak current, set the VCC to 20 V and measure the OUT current while varying OUT from 0 to 20 V .
This is about the measurement of OUT1 pin. Measure the other OUT2-4 pins as is this case.
(7) Diode forward voltage VD


SW_a side : Each OUT Upper-side
SW_b side : Each OUT Lower-side

Measure OUT1 and OUT2 upper FET with the SW set to "a".
Measure OUT1 and OUT2 lower FET with the SW set to "b".
Measure OUT3 and OUT4 as are the cases/connections of OUT1 and OUT2.

ORDERING INFORMATION

| Device | Package | Shipping (Qty / Packing) |
| :---: | :---: | :---: |
| LV8549MC-AH | SOIC10 | $2500 /$ Tape \& Reel |
| LV8549MC-BH | (Pb-Free / Halogen Free) | SOIC10 |

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