## MC33039，NCV33039

## Closed Loop Brushless Motor Adapter

The MC33039 is a high performance closed－loop speed control adapter specifically designed for use in brushless DC motor control systems．Implementation will allow precise speed regulation without the need for a magnetic or optical tachometer．This device contains three input buffers each with hysteresis for noise immunity，three digital edge detectors，a programmable monostable，and an internal shunt regulator．Also included is an inverter output for use in systems that require conversion of sensor phasing．Although this device is primarily intended for use with the MC33035 brushless motor controller，it can be used cost effectively in many other closed－loop speed control applications．

## Features

－Digital Detection of Each Input Transition for Improved Low Speed Motor Operation
－TTL Compatible Inputs With Hysteresis
－Operation Down to 5．5 V for Direct Powering from MC33035 Reference
－Internal Shunt Regulator Allows Operation from a Non－Regulated Voltage Source
－Inverter Output for Easy Conversion between $60^{\circ} / 300^{\circ}$ and $120^{\circ} / 240^{\circ}$ Sensor Phasing Conventions
－ $\mathrm{Pb}-$ Free Packages are Available


Representative Block Diagram


## PIN CONNECTIONS



ORDERING INFORMATION
See detailed ordering and shipping information in the package dimensions section on page 6 of this data sheet．

MAXIMUM RATINGS

| Rating | Symbol | Value | Unit |
| :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{CC}}$ Zener Current | ${ }^{\mathrm{Z}}$ (V $\left.\mathrm{V}_{\mathrm{CC}}\right)$ | 30 | mA |
| Logic Input Current (Pins 1, 2, 3) | $\mathrm{I}_{\mathrm{H}}$ | 5.0 | mA |
| Output Current (Pins 4, 5), Sink or Source | IDRV | 20 | mA |
| Power Dissipation and Thermal Characteristics Maximum Power Dissipation @ $\mathrm{T}_{\mathrm{A}}=+85^{\circ} \mathrm{C}$ Thermal Resistance, Junction-to-Air | $\begin{gathered} \mathrm{P}_{\mathrm{D}} \\ \mathrm{R}_{\theta \mathrm{BA}} \end{gathered}$ | $\begin{aligned} & 650 \\ & 100 \end{aligned}$ | $\begin{gathered} \mathrm{mW} \\ { }^{\circ} \mathrm{C} / \mathrm{W} \end{gathered}$ |
| Operating Junction Temperature | $\mathrm{T}_{J}$ | +150 | ${ }^{\circ} \mathrm{C}$ |
| Operating Ambient Temperature Range MC33039 <br> NCV33039 | $\mathrm{T}_{\mathrm{A}}$ | $\begin{aligned} & -40 \text { to }+85 \\ & -40 \text { to }+125 \end{aligned}$ | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $\mathrm{T}_{\text {stg }}$ | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

ELECTRICAL CHARACTERISTICS $\left(\mathrm{V}_{\mathrm{CC}}=6.25 \mathrm{~V}, \mathrm{R}_{\mathrm{T}}=10 \mathrm{k}, \mathrm{C}_{\mathrm{T}}=22 \mathrm{nF}, \mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right.$, unless otherwise noted)

| Characteristic | Symbol | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LOGIC INPUTS |  |  |  |  |  |
| Input Threshold Voltage <br> High State <br> Low State <br> Hysteresis | $\begin{aligned} & \mathrm{V}_{\mathrm{IH}} \\ & \mathrm{~V}_{\mathrm{IL}} \\ & \mathrm{~V}_{\mathrm{H}} \end{aligned}$ | $\begin{gathered} 2.4 \\ - \\ 0.4 \end{gathered}$ | $\begin{aligned} & 2.1 \\ & 1.4 \\ & 0.7 \end{aligned}$ | $\begin{gathered} - \\ 1.0 \\ 0.9 \end{gathered}$ | V |
| ```Input Current High State (V V  \phiA фв, фС Low State (VIL = 0 V) \phiA фB, фC``` | $\mathrm{I}_{\mathrm{IH}}$ $I_{I L}$ | $\begin{gathered} -40 \\ - \\ -190 \end{gathered}$ | $\begin{aligned} & -60 \\ & -0.3 \\ & \\ & -300 \\ & -0.3 \end{aligned}$ | $\begin{aligned} & -80 \\ & -5.0 \\ & \\ & -380 \\ & -5.0 \end{aligned}$ | $\mu \mathrm{A}$ |

## MONOSTABLE AND OUTPUT SECTIONS

| Output Voltage | $\mathrm{V}_{\mathrm{OH}}$ |  |  |  | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| High State |  |  |  |  |  |
| $\mathrm{f}_{\text {out }}\left(l_{\text {source }}=5.0 \mathrm{~mA}\right)$ |  | 3.60 | 3.95 | 4.20 |  |
| $\phi_{\text {A }}^{\bar{A}}\left(l_{\text {source }}=2.0 \mathrm{~mA}\right)$ |  | 4.20 | 4.75 | - |  |
| Low State | $\mathrm{V}_{\text {OL }}$ |  |  |  |  |
| $\mathrm{f}_{\text {out }}\left(l_{\text {sink }}=10 \mathrm{~mA}\right)$ |  | - | 0.25 | 0.50 |  |
| $\phi_{\text {A }}^{\bar{A}}\left(\mathrm{l}_{\text {sink }}=10 \mathrm{~mA}\right)$ |  | - | 0.25 | 0.50 |  |
| Capacitor $\mathrm{C}_{\text {T }}$ Discharge Current | $I_{\text {dischg }}$ | 20 | 35 | 60 | mA |
| Output Pulse Width (Pin 5) | tpW | 205 | 225 | 245 | $\mu \mathrm{S}$ |
| POWER SUPPLY SECTION |  |  |  |  |  |
| Power Supply Operating Voltage Range MC33039 ( $\mathrm{T}_{\mathrm{A}}=-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ ) <br> NCV33039 ( $\mathrm{T}_{\mathrm{A}}=-40^{\circ}$ to $+125^{\circ} \mathrm{C}$ ) | $\mathrm{V}_{\mathrm{CC}}$ | 5.5 | - | $\mathrm{V}_{\mathrm{z}}$ | V |
| Power Supply Current | $\mathrm{I}_{\mathrm{Cc}}$ | 1.8 | 3.9 | 5.0 | mA |
| Zener Voltage ( $\mathrm{Iz}=10 \mathrm{~mA}$ ) | $\mathrm{V}_{\mathrm{Z}}$ | 7.5 | 8.25 | 9.0 | V |
| Zener Dynamic Impedance ( $\Delta \mathrm{I}_{\mathrm{Z}}=10 \mathrm{~mA}$ to $20 \mathrm{~mA}, \mathrm{f} \leqslant 1.0 \mathrm{kHz}$ ) | $\left\|z_{\text {ka }}\right\|$ | - | 2.0 | 5.0 | $\Omega$ |



Figure 1. Typical Three Phase, Six Step Motor Application

## OPERATING DESCRIPTION

The MC33039 provides an economical method of implementing closed-loop speed control of brushless DC motors by eliminating the need for a magnetic or optical tachometer. Shown in the timing diagram of Figure 1, the three inputs (Pins 1, 2, 3) monitor the brushless motor rotor position sensors. Each sensor signal transition is digitally detected, OR'ed at the Latch 'Set' Input, and causes $\mathrm{C}_{\mathrm{T}}$ to discharge. A corresponding output pulse is generated at $f_{\text {out }}$ (Pin 5) of a defined amplitude, and programmable width determined by the values selected for $\mathrm{R}_{\mathrm{T}}$ and $\mathrm{C}_{\mathrm{T}}$ (Pin 6). The average voltage of the output pulse train increases with motor speed. When fed through a low pass filter or integrator, a DC voltage proportional to speed is generated. Figure 2 shows the proper connections for a typical closed
loop application using the MC33035 brushless motor controller. Constant speed operation down to 100 RPM is possible with economical three phase four pole motors.

The $\phi_{\mathrm{A}}$ inverter output ( Pin 4 ) is used in systems where the controller and motor sensor phasing conventions are not compatible. A method of converting from either convention to the other is shown in Figure 3. For a more detailed explanation of this subject, refer to the text above Figure 39 on the MC33035 data sheet.

The output pulse amplitude $\mathrm{V}_{\mathrm{OH}}$ is constant with temperature and controlled by the supply voltage on $\mathrm{V}_{\mathrm{CC}}$ (Pin 8). Operation down to 5.5 V is guaranteed over temperature. For systems without a regulated power supply, an internal 8.25 V shunt regulator is provided.

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Figure 2. Typical Closed Loop Speed Control Application


Figure 3. $\mathrm{f}_{\text {out }}$, Pulse Width
versus Timing Resistor


Figure 5. $\mathrm{f}_{\text {out }}$, Pulse Width Change versus Supply Voltage


Figure 4. $f_{\text {out }}$, Pulse Width Change versus Temperature


Figure 6. Supply Current versus Supply Voltage


Figure 7. $f_{\text {out }}$, Saturation versus Load Current
$\mathrm{I}_{0}$, OUTut LOADCURAEN(ma)


Figure 8. $\mathrm{f}_{\text {out }}$, Saturation Change versus Temperature

## ORDERING INFORMATION

| Device | Operating Temperature Range | Package | Shipping ${ }^{\dagger}$ |
| :---: | :---: | :---: | :---: |
| MC33039D | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | SOIC-8 | 98 Units / Rail |
| MC33039DG |  |  |  |
| MC33039DR2 |  |  | 2500 / Tape \& Reel |
| MC33039DR2G |  |  |  |
| MC33039P |  | PDIP-8 | 50 Units / Rail |
| MC33039PG |  |  |  |
| NCV33039DR2* | $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+125^{\circ} \mathrm{C}$ | SOIC-8 | 2500 / Tape \& Reel |
| NCV33039DR2G* |  |  |  |

$\dagger$ For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specifications Brochure, BRD8011/D.
*NCV33039: $T_{\text {low }}=-40 C, T_{\text {high }}=+125 \mathrm{C}$. Guaranteed by design. NCV prefix is for automotive and other applications requiring site and change control.

## SCALE 1:1



$$
\begin{aligned}
& \text { STYLE 1: } \\
& \text { PIN 1. AC IN } \\
& \text { 2. DC }+I N \\
& \text { 3. DC }-I N \\
& \text { 4. AC IN } \\
& \text { 5. GROUND } \\
& \text { 6. OUTPUT } \\
& \text { 7. AUXILIARY } \\
& \text { 8. VCC }
\end{aligned}
$$

NOTES:

1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994. 2. CONTROLLING DIMENSION: INCHES.
2. DIMENSIONS A, A1 AND L ARE MEASURED WITH THE PACK AGE SEATED IN JEDEC SEATING PLANE GAUGE GS-3.
3. DIMENSIONS D, D1 AND E1 DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS ARE OR PROTRUSIONS. MOLD F
NOT TO EXCEED 0.10 INCH. NOT TO EXCEED 0.10 INCH.
4. DIMENSION E IS MEASURED AT A POINT 0.015 BELOW DATUM PLANE H WITH THE LEADS CONSTRAINED PERPENDICULAR TO DATUM C.
5. DIMENSION eB IS MEASURED AT THE LEAD TIPS WITH THE LEADS UNCONSTRAINED.
6. DATUM PLANE H IS COINCIDENT WITH THE BOTTOM OF THE LEADS, WHERE THE LEADS EXIT THE BODY
7. PACKAGE CONTOUR IS OPTIONAL (ROUNDED OR SQUARE CORNERS).

|  | INCHES |  | MILLIMETERS |  |
| :---: | :---: | :---: | :---: | :---: |
| DIM | MIN | MAX | MIN | MAX |
| A | ---- | 0.210 | --- | 5.33 |
| A1 | 0.015 | ---- | 0.38 | --- |
| A2 | 0.115 | 0.195 | 2.92 | 4.95 |
| b | 0.014 | 0.022 | 0.35 | 0.56 |
| b2 | 0.060 | TYP | 1.3 | 1.52 TYP |
| C | 0.008 | 0.014 | 0.20 | 0.36 |
| D | 0.355 | 0.400 | 9.0 | 10.16 |
| D1 | 0.005 | ---- | 0.13 | --- |
| E | 0.300 | 0.325 | 7.62 | 8.26 |
| E1 | 0.240 | 0.280 | 6.10 | 7.11 |
| e | 0.100 | BSC | 2.54 | BSC |
| eB | ---- | 0.430 | --- | 10.92 |
| L | 0.115 | 0.150 | 2.92 | 3.81 |
| M | ---- | $10^{\circ}$ | --- | $10^{\circ}$ |

GENERIC MARKING DIAGRAM*


XXXX = Specific Device Code
A = Assembly Location
WL = Wafer Lot
YY = Year
WW = Work Week
$\mathrm{G} \quad=\mathrm{Pb}$-Free Package
*This information is generic. Please refer to device data sheet for actual part marking $\mathrm{Pb}-$ Free indicator, "G" or microdot " $\cdot$ ", may or may not be present.

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## SOLDERING FOOTPRINT＊



GENERIC
MARKING DIAGRAM＊
NOTES：
1．DIMENSIONING AND TOLERANCING PER ANSI Y14．5M， 1982.
2．CONTROLLING DIMENSION：MILLIMETER．
3．DIMENSION A AND B DO NOT INCLUDE MOLD PROTRUSION．
4．MAXIMUM MOLD PROTRUSION 0.15 （0．006） PER SIDE．
5．DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION．ALLOWABLE DAMBAR
PROTRUSION SHALL BE 0.127 （0．005）TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION．
6．751－01 THRU 751－06 ARE OBSOLETE．NEW STANDARD IS 751－07．

| DIM | MILLIMETERS |  | INCHES |  |
| :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |
| A | 4.80 | 5.00 | 0.189 | 0.197 |
| B | 3.80 | 4.00 | 0.150 | 0.157 |
| C | 1.35 | 1.75 | 0.053 | 0.069 |
| D | 0.33 | 0.51 | 0.013 | 0.020 |
| G | 1.27 BSC |  | 0.050 BSC |  |
| H | 0.10 | 0.25 | 0.004 | 0.010 |
| J | 0.19 | 0.25 | 0.007 | 0.010 |
| K | 0.40 | 1.27 | 0.016 | 0.050 |
| M | 0 | ${ }^{\circ}$ | $8{ }^{\circ}$ | 0 |
|  | 8 | 8 |  |  |
| N | 0.25 | 0.50 | 0.010 | 0.020 |
| S | 5.80 | 6.20 | 0.228 | 0.244 |


| 8 月且且且 | 8 月且且且 |
| :---: | :---: |
| XXXXXX | XXXXXX |
| AYWW | AYWW |
| \＃$\because 甘 甘$ | 1 \＃\＃\＃ |
| Discrete | Discrete （Pb－Free） |

XXXXX＝Specific Device Code
A＝Assembly Location
L＝Wafer Lot
＝Year WW Work
＝Work Week
$=$ Work Week $\quad$＝Pb－Free Package
$=\mathrm{Pb}-$ Free Package
＊This information is generic．Please refer to device data sheet for actual part marking． $\mathrm{Pb}-\mathrm{Free}$ indicator，＂ G ＂or microdot＂ r ＂，may or may not be present．Some products may not follow the Generic Marking．
＊For additional information on our Pb －Free strategy and soldering details，please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual，SOLDERRM／D．

## STYLES ON PAGE 2

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[^1]STYLE 1:

| PIN 1. | EMITTER |
| ---: | :--- |
| 2. | COLLECTOR |
| 3. | COLLECTOR |
| 4. | EMITTER |
| 5. | EMITTER |
| 6. | BASE |
| 7. | BASE |
| 8. | EMITTER |
| STYLE 5: |  |
| PIN 1. | DRAIN |
| 2. | DRAIN |
| 3. | DRAIN |
| 4. | DRAIN |
| 5. | GATE |
| 6. | GATE |
| 7. | SOURCE |
| 8. | SOURCE |

STYLE 9:

PIN 1. EMITTER, COMMON
COLLECTOR, DIE \#1 COLLECTOR, DIE \#2 EMITTER, COMMON EMITTER, COMMON BASE, DIE \#2
BASE, DIE \#1
8. EMITTER, COMMON

STYLE 13:
PIN 1. N.C.
2. SOURCE

SOURCE
GATE
DRAIN
DRAIN
DRAIN
8. DRAIN

STYLE 17:
PIN 1. VCC
V2OUT
V10U
TXE
RXE
VEE
7. GND
8. ACC

STYLE 21:
PIN 1. CATHODE 1
CATHODE 2
CATHODE 3
CATHODE 4
CATHODE 5
COMMON ANODE
COMMON ANODE
8. CATHODE 6

STYLE 25:
PIN 1. VIN
2. $N / C$

REXT
GND
IOUT
IOUT
IOUT
IOUT
STYLE 29:
PIN 1. BASE, DIE \#1
EMITTER, \#1
BASE, \#2
EMITTER, \#2
COLLECTOR, \#2
COLLECTOR, \#2
COLLECTOR, \#1
COLLECTOR, \#1

STYLE 2:
PIN 1. COLIECTOR, DIE,
COLLECTOR, \#1
COLLECTOR, \#1
COLLECTOR, \#2
COLLECTOR, \#2
COLLECTOR, \#2
BASE, \#2
EMITTER, \#2
BASE, \#1
EMITTER, \#1
STYLE 6:
PIN 1. SOURCE
DRAIN
DRAIN
DRAIN
SOURCE
SOURCE
. GATE
7. GATE
8. SOURCE

STYLE 10:
PIN 1. GROUND
BIAS 1 OUTPUT GROUND GROUND BIAS 2 7. INPUT 8. GROUND

STYLE 14:
PIN 1. N-SOURCE
N-GATE
P-SOURCE
P-GATE
P-DRAIN
P-DRAIN
. N-DRAIN
8. N-DRAIN

STYLE 18:
PIN 1. ANODE
2. ANODE

SOURCE
GATE
DRAIN
DRAIN
7. CATHODE
8. CATHODE

STYLE 22:
PIN 1. I/O LINE 1
COMMON CATHODE/VCC
COMMON CATHODE/VCC
I/O LINE 3
COMMON ANODE/GND
I/O LINE 4
7. I/O LINE 5
8. COMMON ANODE/GND

STYLE 26:
PIN 1. GND
2. $\mathrm{dv} / \mathrm{dt}$

ENABLE
ILIMIT
SOURCE
SOURCE
SOURCE
8. VCC

STYLE 30:
PIN 1. DRAIN 1
2. DRAIN 1
3. GATE 2
4. SOURCE 2
5. SOURCE 1/DRAIN 2
6. SOURCE 1/DRAIN 2
. SOURCE 1/DRAIN 2
. GATE 1

STYLE 3
PIN

1. DRAIN, DIE \#1
2. DRAIN, \#1
3. DRAIN, \#2

DRAIN, \#2
5. GATE, \#2
6. SOURCE, \#2
7. GATE, \#1
8. SOURCE, \#

STYLE 7:
PIN 1. INPUT
2. EXTERNAL BYPASS
3. THIRD STAGE SOURCE
4. GROUND
5. DRAIN
6. GATE 3
7. SECOND STAGE Vd
8. FIRST STAGE Vd

## STYLE 11:

PIN 1. SOURCE
2. GATE 1
3. SOURCE 2
4. GATE 2
5. DRAIN 2
6. DRAIN 2
7. DRAIN 1
8. DRAIN 1

STYLE 15:
PIN 1. ANODE 1
2. ANODE 1
3. ANODE
3. ANODE 1
5. CATHODE, COMMON
6. CATHODE, COMMON
7. CATHODE, COMMON
8. CATHODE, COMMON

## STYLE 19:

PIN 1. SOURCE 1
2. GATE 1
3. SOURCE 2
4. GATE 2
5. DRAIN 2
6. MIRROR 2
7. DRAIN 1
8. MIRROR 1

## STYLE 23:

PIN 1. LINE 1 IN
2. COMMON ANODE/GND
3. COMMON ANODE/GND
4. LINE 2 IN
5. LINE 2 OUT
6. COMMON ANODE/GND
7. COMMON ANODE/GND
8. LINE 1 OUT

## STYLE 27:

PIN 1. ILIMIT
2. OVLO

UVLO
INPUT+
SOURCE
SOURCE
SOURCE
8. DRAIN

STYLE 4:
PIN 1. ANODE
2. ANODE
3. ANODE
4. ANODE
5. ANODE
7. ANODE
8. COMMON CATHODE

## STYLE 8

PIN 1. COLLECTOR, DIE \#1
2. BASE, \#1
3. BASE, \#2
4. COLLECTOR, \#2
5. COLLECTOR, \#2
6. EMITTER, \#2
7. EMITTER, \#1
8. COLLECTOR, \#1

## STYLE 12:

PIN 1. SOURCE
2. SOURCE
3. SOURCE
4. GATE
5. DRAIN
6. DRAIN
7. DRAIN
8. DRAIN

## STYLE 16:

PIN 1. EMITTER, DIE \#
2. BASE, DIE \#1
3. EMITTER, DIE \#
3. EMITTER, DIE
4. BASE, DIE \#2
6. COLLECTOR, DIE \#2
7. COLLECTOR, DIE \#1
8. COLLECTOR, DIE \#1

## STYLE 20:

PIN 1. SOURCE (N)
2. GATE (N)
3. SOURCE (P)
4. GATE (P)
5. DRAIN
6. DRAIN
7. DRAIN
8. DRAIN

## STYLE 24:

PIN 1. BASE
2. EMITTER
3. COLLECTOR/ANODE
4. COLLECTOR/ANODE
5. CATHODE
6. CATHODE
7. COLLECTOR/ANODE
8. COLLECTOR/ANODE

## STYLE 28:

PIN 1. SW_TO_GND
2. DASIIC_OFF
3. DASIC_SW_DET
4. GND
5. V MON
6. VBULK
7. VBULK
8. VIN

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