Operational Amplifier, 1.0 A, Dual

The NCS2372 is a monolithic circuit intended for use as a power operational amplifier in a wide range of applications, including servo amplifiers and power supplies. No deadband crossover distortion provides better performance for driving coils.

Features

- Output Current to 1.0 A
- Slew Rate of 1.3 V/μs
- Wide Bandwidth of 1.1 MHz
- Internal Thermal Shutdown
- Single or Split Supply Operation
- Excellent Gain and Phase Margins
- Common Mode Input Includes Ground
- Zero Deadband Crossover Distortion
- These Devices are Pb-Free and are RoHS Compliant

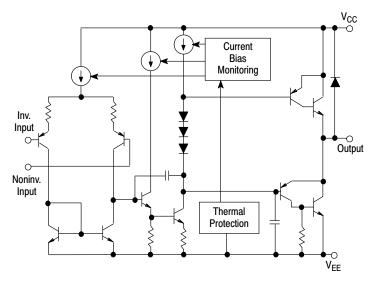


Figure 1. Representative Block Diagram

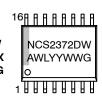


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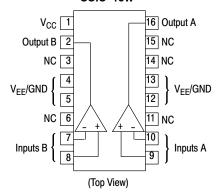


A = Assembly Location
WL = Wafer Lot

YY = Year
WW = Work Week
G = Pb-Free Package

PIN CONNECTIONS

SOIC-16W



ORDERING INFORMATION

Device	Package	Shipping [†]
NCS2372DWR2G	SOIC-16W (Pb-Free)	1000/Tape & Reel

†For information on tape and reel specifications, including part orientation and tape sizes, please refer to our Tape and Reel Packaging Specification Brochure, BRD8011/D.

MAXIMUM RATINGS

Rating	Symbol	Value	Unit	
Supply Voltage (from V _{CC} to V _{EE})	V _S	40	V	
Input Differential Voltage Range	V _{IDR}	Note 1	V	
Input Voltage Range	V _{IR}	Note 1	V	
Junction Temperature (Note 2)	T _J	+150	°C	
Operating Temperature Range	T _A	-40 to +125	°C	
Storage Temperature Range	T _{stg}	-55 to +150	°C	
DC Output Current	lo	1.0	Α	
Peak Output Current (Nonrepetitive) > 1 ms Duration < 1 ms Duration (Note 3)	I _(max)	1.5 2.0	А	
Thermal Resistance, Junction-to-Air	$R_{ hetaJA}$	80	°C/W	
Thermal Resistance, Junction-to-Case	$R_{ heta JC}$	12	°C/W	

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

- Either or both input voltages should not exceed the magnitude of V_{CC} or V_{EE}.
 Power dissipation must be considered to ensure maximum junction temperature (T_J) is not exceeded.
 When driving inductive loads, negative flyback voltage/current excursions may need to be constrained with Schottky diodes to protect the output drivers.

DC ELECTRICAL CHARACTERISTICS (V_{CC} = +15 V, V_{EE} = -15 V, R_L connected to ground, T_A = -40° to +125°C.)

Characteristics	Symbol	Min	Тур	Max	Unit
Input Offset Voltage (V _{CM} = 0)	V _{IO}				mV
$T_A = +25^{\circ}C$		_	1.0	15	
T _A , T _{low} to T _{high}		-	_	20	
Average Temperature Coefficient of Offset Voltage	$\Delta V_{IO}/\Delta T$	-	20	_	μV/°C
Input Bias Current (V _{CM} = 0)	I _{IB}	-	100	500	nA
Input Offset Current (V _{CM} = 0)	I _{IO}	-	10	50	nA
Large Signal Voltage Gain	A _{VOL}	30	100	-	V/mV
$V_{O} = \pm 10 \text{ V}, R_{L} = 2.0 \text{ k}$					
Output Voltage Swing (I _L = 100 mA)	V _{OH}				V
$T_A = +25^{\circ}C$		14.0	14.2	_	
$T_A = T_{low}$ to T_{high}	.,	13.9	-	-	
$T_A = +25^{\circ}C$	V _{OL}	_	-14.2	-14.0	
$T_A = T_{low}$ to T_{high}		-	_	-13.9	
Output Voltage Swing (I _L = 1.0 A)	V _{OH}				V
$V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = +25 ^{\circ}\text{C}$		22.5	22.7	_	
$V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = T_{low} \text{ to } T_{high}$		22.5			
$V_{CC} = +24 \text{ V}, V_{EE} = 0 \text{ V}, T_A = +25 ^{\circ}\text{C}$	V _{OL}	-	1.3	1.5	
V_{CC} = +24 V, V_{EE} = 0 V, T_A = T_{low} to T_{high}		-	_	1.6	
Input Common Mode Voltage Range	V_{ICR}				V
$T_A = +25^{\circ}C$		V_{EE} to (V_{CC} –1.0)			
$T_A = T_{low}$ to T_{high}		V_{EE} to $(V_{CC}$ –1.3)			
Common Mode Rejection Ratio (R _S = 10 k)	CMRR	70	90	_	dB
Power Supply Rejection Ratio ($R_S = 100 \Omega$)	PSRR	70	90	_	dB
Power Supply Current	I _D				mA
$T_A = +25$ °C		_	8.0	10	
$T_A = T_{low}$ to T_{high}		_	_	14	

$\textbf{AC ELECTRICAL CHARACTERISTICS} \ (V_{CC} = +15 \ V, \ V_{EE} = -15 \ V, \ R_L \ connected \ to \ ground, \ T_A = +25 ^{\circ}C, \ unless \ otherwise \ noted.)$

Characteristics	Symbol	Min	Тур	Max	Unit
Slew Rate (V_{in} = -10 V to +10 V, R_L = 2.0 k, C_L = 100 pF) A_V = -1.0, T_A = T_{low} to T_{high}	SR	1.0	1.4	-	V/μs
Gain Bandwidth Product (f = 100 kHz, C_L = 100 pF, R_L = 2.0 k) T_A = 25°C T_A = T_{low} to T_{high}	GBW	0.9 0.7	1.4	- -	MHz
Phase Margin $T_J = T_{low}$ to T_{high} $R_L = 2.0$ k, $C_L = 100$ pF	Фт	_	65	_	Degrees
Gain Margin $R_L = 2.0 \text{ k}, C_L = 100 \text{ pF}$	A _m	_	15	-	dB
Equivalent Input Noise Voltage $R_S = 100 \Omega$, $f = 1.0$ to 100 kHz	e _n	-	22	-	nV/√Hz
Total Harmonic Distortion $A_V = -1.0$, $R_L = 50 \Omega$, $V_O = 0.5 VRMS$, $f = 1.0 kHz$	THD	-	0.02	-	%

NOTE: In case V_{EE} is disconnected before V_{CC}, a diode between V_{EE} and Ground is recommended to avoid damaging the device.

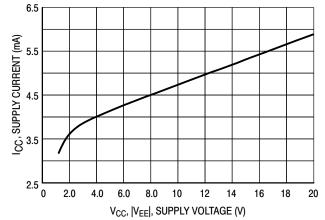


Figure 2. Supply Current versus Supply Voltage with No Load

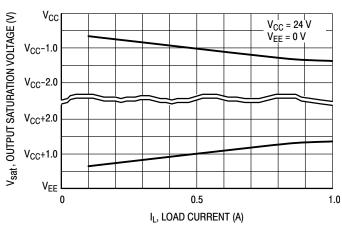


Figure 3. Output Saturation Voltage versus Load Current

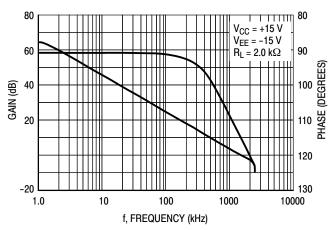


Figure 4. Voltage Gain and Phase versus Frequency

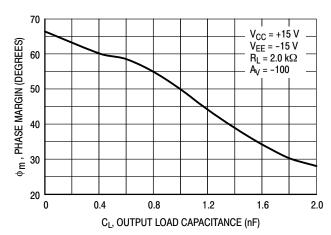


Figure 5. Phase Margin versus Output Load Capacitance

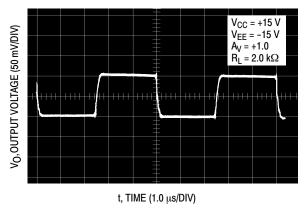


Figure 6. Small Signal Transient Response

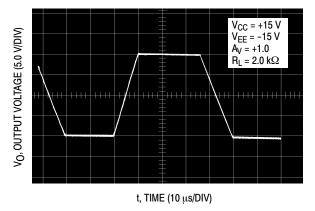


Figure 7. Large Signal Transient Response

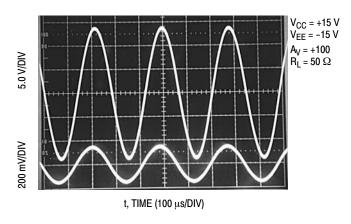


Figure 8. Sine Wave Response

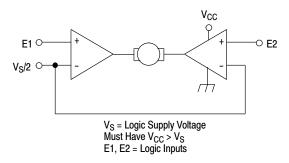
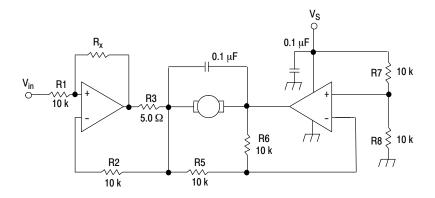


Figure 9. Bidirectional DC Motor Control with Microprocessor-Compatible Inputs



For circuit stability, ensure that $R_X > \frac{2R3 + R1}{R_M}$ where, R_M = internal resistance of motor. The voltage available at the terminals of the motor is: $V_M = 2 (V_1 - \frac{V_S}{2}) + |R_0| \cdot I_M$ where, $|R_0| = \frac{2R3 + R1}{R_X}$ and I_M is the motor current.

Figure 10. Bidirectional Speed Control of DC Motors



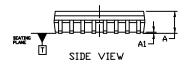


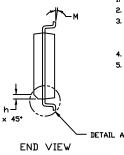
SOIC-16 WB CASE 751G ISSUE E

DATE 08 OCT 2021



SCALE 1:1 **♦** 0.25**₩** B**₩** RRRR PIN 1 --INDICATOR -16X R **♦** 0.25**®** TAS BS TOP VIEW





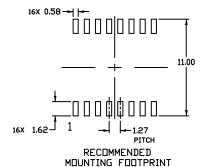


DETAIL A

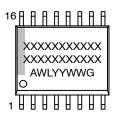
NOTES

- DIMENSIONING AND TOLERANCING PER ASME Y14.5M, 1994.
- CONTROLLING DIMENSION: MILLIMETERS
- DIMENSION 6 DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF B DIMENSION AT MAXIMUM MATERIAL CONDITION.
- DIMENSIONS D AND E DO NOT INCLUDE MOLD PROTRUSIONS.
- MAXIMUM MOLD PROTRUSION OR FLASH TO BE 0.15 PER SIDE.

	MILLIMETERS			
DIM	MIN.	MAX.		
Α	2.35	2.65		
A1	0.10	0.25		
В	0.35	0.49		
С	0.23	0.32		
D	10.15	10.45		
E	7.40	7.60		
е	1.27	BSC		
Н	10.05	10.55		
h	0.53 REF			
١	0.50	0.90		
М	0*	7*		



GENERIC MARKING DIAGRAM*



XXXXX = Specific Device Code = Assembly Location

WL = Wafer Lot YY = Year ww = Work Week G = Pb-Free Package

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