## FEATURES:

- 0.5 MICRON CMOS Technology
- Guaranteed low skew < 500ps (max.)
- Very low duty cycle distortion < 1.0ns (max.)
- Very low CMOS power levels
- TTL compatible inputs and outputs
- Inputs can be driven from 3.3V or 5V components
- Two independent output banks with 3-state control
- 1:5 fanout per bank
- "Heartbeat" monitor output
- $\mathrm{Vcc}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}$
- Available in SSOP, SOIC, and QSOP packages


## DESCRIPTION:

The FCT3805 is a 3.3 volt, non-inverting clock driver built using advanced dual metal CMOS technology. The device consists of two banks of drivers, each with a 1:5 fanout and its own output enable control. The device has a "heartbeat" monitor for diagnostics and PLL driving. The MON output is identical to all other outputs and complies with the output specifications in this document. The FCT3805 offers low capacitance inputs with hysteresis.

The FCT3805 is designed for high speed clock distribution where signal quality and skew are critical. The FCT3805 also allows single point-toquality and skew are critical. The FCT3805 also allows single point-to-
point transmission line driving in applications such as address distribution, where one signal must be distributed to multiple recievers with low skew and high signal quality.

For more information on using the FCT3805 with two different input
frequencies on bank A and B, please see AN-236.

## FUNCTIONAL BLOCK DIAGRAM




## PIN CONFIGURATION



## ABSOLUTE MAXIMUM RATINGS(1)

| Symbol | Description | Max | Unit |
| :---: | :--- | :---: | :---: |
| VTERm $^{(2)}$ | Terminal Voltage with Respectto GND | -0.5 to +4.6 | V |
| VTERm $^{(3)}$ | Terminal Voltagewith Respecto GND | -0.5 to +7 | V |
| VTERm $^{(4)}$ | Terminal Voltage with Respectto GND | -0.5 to $\mathrm{Vcc}+0.5$ | V |
| Tstg | Storage Temperature | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| Iout | DCOutputCurrent | -60 to +60 | mA |

## NOTES:

1. Stresses greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
2. Vcc terminals.
3. Input terminals.
4. Outputs and I/O terminals.

CAPACITANCE ( $\mathrm{TA}_{\mathrm{A}}=+25^{\circ} \mathrm{C}, \mathrm{f}=1.0 \mathrm{MHz}$ )

| Symbol | Parameter ${ }^{(1)}$ | Conditions | Typ. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| CIN | InputCapacitance | $\mathrm{VIN}=0 \mathrm{~V}$ | 4.5 | 6 | pF |
| Cout | OutputCapacitance | Vout $=0 \mathrm{~V}$ | 5.5 | 8 | pF |

## NOTE:

1. This parameter is measured at characterization but not tested.

## PIN DESCRIPTION

| Pin Names | Description |
| :---: | :--- |
| OEA, OEB | 3-State OutputEnable Inputs(Active LOW) |
| INA, INB | Clock Inputs |
| OAn, OBn | ClockOutputs |
| MON | MonitorOutput |

FUNCTION TABLE (1)

| Inputs |  | Outputs |  |
| :---: | :---: | :---: | :---: |
| ОЕА, ОЕв | $\mathrm{INA}_{\mathrm{A}}, \mathrm{INB}$ | OAn, OBn | MON |
| L | L | L | L |
| L | H | H | H |
| $H$ | L | Z | L |
| $H$ | $H$ | $Z$ | $H$ |

## NOTE:

1. $\mathrm{H}=\mathrm{HIGH}$
$\mathrm{L}=\mathrm{LOW}$
Z $=$ High-Impedance

DC ELECTRICAL CHARACTERISTICS OVER OPERATING RANGE
Following Conditions Apply Unless Otherwise Specified
Commercial: $\mathrm{T}_{\mathrm{A}}=0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$, Industrial: $\mathrm{T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}, \mathrm{Vcc}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}$

| Symbol | Parameter | Test Conditions ${ }^{(1)}$ |  | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VIH | Input HIGH Level (Input pins) | Guaranteed Logic HIGH Level |  | 2 | - | 5.5 | V |
|  | Input HIGH Level (I/O pins) |  |  | 2 | - | Vcc +0.5 |  |
| VIL | Input LOW Level (Input and I/O pins) | Guaranteed Logic LOW Level |  | -0.5 | - | 0.8 | V |
| 1 IH | Input HIGH Current (Input pins) | Vcc $=$ Max. | $\mathrm{VI}=5.5 \mathrm{~V}$ | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
|  | Input HIGH Current (I/O pins) |  | $\mathrm{V}_{1}=\mathrm{Vcc}$ | - | - | $\pm 1$ |  |
| IIL | InputLOWCurrent(Inputpins) | Vcc $=$ Max. | $\mathrm{V}_{1}=$ GND | - | - | $\pm 1$ |  |
|  | Input LOW Current (I/O pins) |  | $\mathrm{V}_{1}=\mathrm{GND}$ | - | - | $\pm 1$ |  |
| IozH | High ImpedenceOutputCurrent (3-State OutputPins) | Vcc = Max. | Vo = Vcc | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| Iozl |  |  | Vo = GND | - | - | $\pm 1$ |  |
| VIK | Clamp Diode Voltage | VcC $=$ Min., $\mathrm{lin}=-18 \mathrm{~mA}$ |  | - | -0.7 | -1.2 | V |
| IODH | Output HIGH Current | $\mathrm{VCC}=3.3 \mathrm{~V}, \mathrm{VIN}=\mathrm{VIH}$ or $\mathrm{VIL}, \mathrm{Vo}=1.5 \mathrm{~V}{ }^{(3)}$ |  | -36 | -60 | -110 | mA |
| IODL | OutputLOWCurrent | $\mathrm{VCC}=3.3 \mathrm{~V}, \mathrm{VIN}=\mathrm{VIH}$ or VIL, $\mathrm{Vo}=1.5 \mathrm{~V}{ }^{(3)}$ |  | 50 | 90 | 200 | mA |
| VoH | Output HIGH Voltage | $\begin{aligned} & \text { VCC }=\operatorname{Min} . \\ & \text { VIN }=\text { VIH or VIL } \end{aligned}$ | $1 \mathrm{OH}=-0.1 \mathrm{~mA}$ | Vcc-0.2 | - | - | V |
|  |  |  | $\mathrm{IOH}=-8 \mathrm{~mA}$ | $2.4{ }^{(5)}$ | 3 | - |  |
| VoL | OutputLOWVoltage | $\begin{aligned} & \text { VCC }=\mathrm{Min} . \\ & \mathrm{VIN}_{\mathrm{IN}}=\mathrm{V} H \text { or } \mathrm{VIL} \end{aligned}$ | $\mathrm{IOL}=0.1 \mathrm{~mA}$ | - | - | 0.2 | V |
|  |  |  | $\mathrm{IOL}=16 \mathrm{~mA}$ | - | 0.2 | 0.4 |  |
|  |  |  | $\mathrm{loL}=24 \mathrm{~mA}$ | - | 0.3 | 0.5 |  |
| IOFF | InputPower OffLeakage | $\mathrm{Vcc}=0 \mathrm{~V}, \mathrm{VIN}=4.5 \mathrm{~V}$ |  | - | - | $\pm 1$ | $\mu \mathrm{A}$ |
| los | ShortCircuit Current ${ }^{(4)}$ | Vcc = Max., Vo = GND ${ }^{(3)}$ |  | -60 | -135 | -240 | mA |
| VH | Input Hysteresis | - |  | - | 150 | - | mV |
| ICCL <br> IcCH <br> Iccz | Quiescent Power Supply Current | $\begin{aligned} & \text { Vcc }=\text { Max. } \\ & \text { VIN }=\text { GND or Vcc } \end{aligned}$ |  | - | 0.1 | 10 | $\mu \mathrm{A}$ |

## NOTES:

1. For conditions shown as Max. or Min., use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values are at $\mathrm{Vcc}=3.3 \mathrm{~V},+25^{\circ} \mathrm{C}$ ambient.
3. Not more than one output should be shorted at one time. Duration of the test should not exceed one second.
4. This parameter is guaranteed but not tested.
5. $\mathrm{VOH}=\mathrm{Vcc}-0.6 \mathrm{~V}$ at rated current.

POWER SUPPLY CHARACTERISTICS

\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline Symbol \& Parameter \& \multicolumn{2}{|c|}{TestConditions \({ }^{(1)}\)} \& Min. \& Typ. \({ }^{(2)}\) \& Max. \& Unit \\
\hline \(\Delta \mathrm{lcc}\) \& Quiescent Power Supply Current TTL Inputs HIGH \& \multicolumn{2}{|l|}{\[
\begin{aligned}
\& \mathrm{Vcc}=\mathrm{Max} . \\
\& \mathrm{VIN}=\mathrm{Vcc}-0.6 \mathrm{~V}(3)
\end{aligned}
\]} \& - \& 10 \& 30 \& \(\mu \mathrm{A}\) \\
\hline ICCD \& Dynamic Power Supply Current \({ }^{(4)}\) \& \begin{tabular}{l}
\[
\text { Vcc }=\text { Max. }
\] \\
Outputs Open
\[
O E A=O E B=G N D
\] \\
PerOutputToggling \\
50\% Duty Cycle
\end{tabular} \& \[
\begin{aligned}
\& \mathrm{VIN}=\mathrm{VCC} \\
\& \mathrm{VIN}=\mathrm{GND}
\end{aligned}
\] \& - \& 0.035 \& 0.06 \& mA/MHz \\
\hline Ic \& Total Power Supply Current \({ }^{(6)}\) \& \begin{tabular}{l}
Vcc \(=\) Max. \\
Outputs Open \\
fo \(=25 \mathrm{MHz}\) \\
50\% Duty Cycle \\
\(\mathrm{OEA}=\mathrm{OEB}=\mathrm{VCC}\) \\
Mon. Output Toggling
\end{tabular} \& \[
\begin{aligned}
\& \text { VIN }=\mathrm{VCC} \\
\& \mathrm{VIN}=\mathrm{GND} \\
\& \hline \mathrm{VIN}=\mathrm{VCC}-0.6 \mathrm{~V} \\
\& \mathrm{VIN}=\mathrm{GND}
\end{aligned}
\] \& - \& 0.9

0.9 \& 1.6 \& <br>

\hline \& \& | Vcc $=$ Max. |
| :--- |
| Outputs Open $\mathrm{fo}=50 \mathrm{MHz}$ |
| 50\% Duty Cycle OEA = OEB = GND |
| Eleven Outputs Toggling | \& \[

$$
\begin{aligned}
& \mathrm{VIN}=\mathrm{VCC} \\
& \mathrm{VIN}=\mathrm{GND}
\end{aligned}
$$
\]

\[
$$
\begin{aligned}
& \mathrm{VIN}=\mathrm{VCC}-0.6 \mathrm{~V} \\
& \mathrm{VIN}=\mathrm{GND}
\end{aligned}
$$

\] \& | - |
| :---: |
|  | \& 20 \& $33^{(5)}$

$33^{(5)}$ \& mA <br>
\hline
\end{tabular}

## NOTES:

1. For conditions shown as Max. or Min., use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values are at $\mathrm{Vcc}=3.3 \mathrm{~V},+25^{\circ} \mathrm{C}$ ambient.
3. Per TTL driven input ( V IN $=\mathrm{Vcc}-0.6 \mathrm{~V}$ ); all other inputs at Vcc or GND .
4. This parameter is not directly testable, but is derived for use in Total Power Supply calculations.
5. Values for these conditions are examples of the Ic formula. These limits are guaranteed but not tested.
6. Ic = IqUIESCENT + linputs + Idynamic
$\mathrm{IC}=\mathrm{ICC}+\triangle \mathrm{ICC} D \mathrm{DNT}+\mathrm{ICCD}$ (foNo)
ICC = Quiescent Current (ICCL, ICCH and ICCz)
$\Delta \mathrm{Icc}=$ Power Supply Current for a TTL High Input $(\mathrm{VIN}=\mathrm{Vcc}-0.6 \mathrm{~V})$
Dh = Duty Cycle for TTL Inputs High
NT = Number of TTL Inputs at DH
ICCD = Dynamic Current Caused by an Input Transition Pair (HLH or LHL)
fo = Output Frequency
No = Number of Outputs at fo
All currents are in milliamps and all frequencies are in megahertz.

SWITCHING CHARACTERISTICS OVER OPERATING RANGE -COMMERCIAL(3,4)

| Symbol | Parameter | Conditions ${ }^{(1)}$ | FCT3805 |  | FCT3805A |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. ${ }^{(2)}$ | Max. | Min. ${ }^{(2)}$ | Max. |  |
| tPLH | PropagationDelay | $\mathrm{CL}=50 \mathrm{pF}$ | 1.5 | 5.8 | 1.5 | 5 | ns |
| tPHL | INA to OAn, INB to OBn | $\mathrm{RL}=500 \Omega$ |  |  |  |  |  |
| R | OutputRise Time |  | - | 2 | - | 2 | ns |
| tF | Output Fall Time |  | - | 2 | - | 2 | ns |
| tsk(0) | Output skew: skew between outputs of all banks of same package (inputstiedtogether) |  | - | 0.5 | - | 0.5 | ns |
| tsk(P) | Pulse skew: skew between opposite transitions of same output(\|tPHL--tPLH|) |  | - | 1 | - | 1 | ns |
| tsk( ${ }^{\text {( }}$ | Package skew: skew between outputs of different packages being driven by the same input source, power supply voltage, temperature, frequency, and speedgrade. |  | - | 1.5 | - | 1.2 | ns |
| $\begin{aligned} & \text { tPZL } \\ & \text { tPZH } \end{aligned}$ | OutputEnable Time $\overline{\mathrm{OE}}$ to OAn, $\overline{\mathrm{OEB}}$ to OBn |  | 1.5 | 6.5 | 1.5 | 6 | ns |
| $\begin{aligned} & \text { tPLZ } \\ & \text { tPHZ } \end{aligned}$ | OutputDisable Time OEA to OAn, OEB to OBn |  | 1.5 | 5.5 | 1.5 | 5 | ns |

SWITCHING CHARACTERISTICS OVER OPERATING RANGE -INDUSTRIAL(3,4)

| Symbol | Parameter | Conditions ${ }^{(1)}$ | FCT3805 |  | FCT3805A |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. ${ }^{(2)}$ | Max. | Min. ${ }^{(2)}$ | Max. |  |
| tPLH | PropagationDelay | $\begin{aligned} & \mathrm{CL}=50 \mathrm{pF} \\ & \mathrm{RL}=500 \Omega \end{aligned}$ | 1.5 | 5.8 | 1.5 | 5.2 | ns |
| tPHL | INA to OAn, INB to OBn |  |  |  |  |  |  |
| R | OutputRise Time |  | - | 2 | - | 2 | ns |
| tF | Output Fall Time |  | - | 2 | - | 2 | ns |
| tsk(0) | Output skew: skew between outputs of all banks of same package (inputstied together) |  | - | 0.6 | - | 0.6 | ns |
| tSk(P) | Pulse skew: skew between opposite transitions ofsameoutput(\|tPHL--tPLH|) |  | - | 1 | - | 1 | ns |
| tsk( ${ }^{\text {( }}$ | Package skew: skew between outputs of different packages being driven by the same input source, power supply voltage, temperature, frequency, and speedgrade. |  | - | 1.5 | - | 1.2 | ns |
| $\begin{aligned} & \text { tPZL } \\ & \text { tPZH } \end{aligned}$ | OutputEnable Time $\overline{O E A}$ to OAn, $\overline{O E B}$ to OBn |  | 1.5 | 6.5 | 1.5 | 6 | ns |
| $\begin{aligned} & \text { tPLZ } \\ & \text { tPHZ } \end{aligned}$ | OutputDisable Time OEA to OAn, $\overline{O E B}$ to OBn |  | 1.5 | 5.5 | 1.5 | 5 | ns |

## NOTES:

1. See test circuits and waveforms.
2. Minimum limits are guaranteed but not tested on Propagation Delays.
3. $\operatorname{tPLH}, \operatorname{tPHL}, \operatorname{tsK}(\mathrm{t})$ are production tested. All other parameters guaranteed but not production tested.
4. Propagation delay range indicated by Min. and Max. limit is due to Vcc, operating temperature and process parameters. These propagation delay limits do not imply skew.

## TEST CIRCUITS AND WAVEFORMS



Test Circuits for All Outputs


## Package Delay



Pulse Skew-tSK(P)


Output Skew - tSK(X)

## SWITCH POSITION

| Test | Switch |
| :---: | :---: |
| Disable LOW | 6 V |
| Enable LOW | GND |
| Disable HIGH |  |
| Enable HIGH |  |

DEFINITIONS:
$C L=$ Load capacitance: includes jig and probe capacitance.
RT = Termination resistance: should be equal to Zout of the Pulse Generator.

tSK $(0)=|t P L H 2-t P L H 1|$ or $\operatorname{ItPHL2}-$ tPHL1 $\mid$
Output Skew-tsK(O)

tSK $(\mathrm{t})=|\mathrm{tPLH} 2-\mathrm{tPLH} 1|$ or $|\mathrm{tPHL} 2-\mathrm{tPHL} 1|$

Package Skew- tSK(T)

NOTES:

1. Diagram shown for input Control Enable-LOW and input Control Disable-HIGH
2. Pulse Generator for All Pulses: $\mathrm{f} \leq 1.0 \mathrm{MHz}$; tF $\leq 2.5 \mathrm{~ns}$; tR $\leq 2.5 \mathrm{~ns}$

## ORDERINGINFORMATION



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