

## Description

The 8Axxxx 48QFN EVK is designed to help customers evaluate IDT ClockMatrix devices. This document discusses the following about the EVK:

- Introduces the board and its power supply and jumper settings
- Describes the input and output connectors for normal operation
- Explains how to bring up the board using the Timing Commander software GUI
- Discusses how to configure and program the board to generate standard-compliant frequencies

## Requirements

- IDT Timing Commander Software Installed (available at [www.idt.com/timingcommander](http://www.idt.com/timingcommander))
- ClockMatrix GUI (available at [www.idt.com/clockmatrix](http://www.idt.com/clockmatrix))
- USB 2.0 or USB 3.0 interface
- Windows XP SP3 or later
- Processor: Minimum 1GHz
- Memory: Minimum 512MB; recommended 1GB
- Available disk space: Minimum 600MB (1.5GB 64-bit); recommended 1GB (2GB 64-bit)
- Network access during installation if the .NET framework is not currently installed on the system

## Kit Contents

- 8A34xxx 48QFN Evaluation Board
- USB Type A cable

## 8A3xxxx 48QFN EVK Board



**Important Notes**

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- (ii) non-observance of instructions contained in this manual and in any other documentation provided to user, or
- (iii) misuse, abuse, use under abnormal conditions, or alteration by anyone other than IDT.

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**Important Equipment Warning:** Ensure the correct connection of all cables. Supplying the board using the wrong polarity could result in damage to the board and/or the equipment. Check that all jumpers have been removed from the board before applying power.

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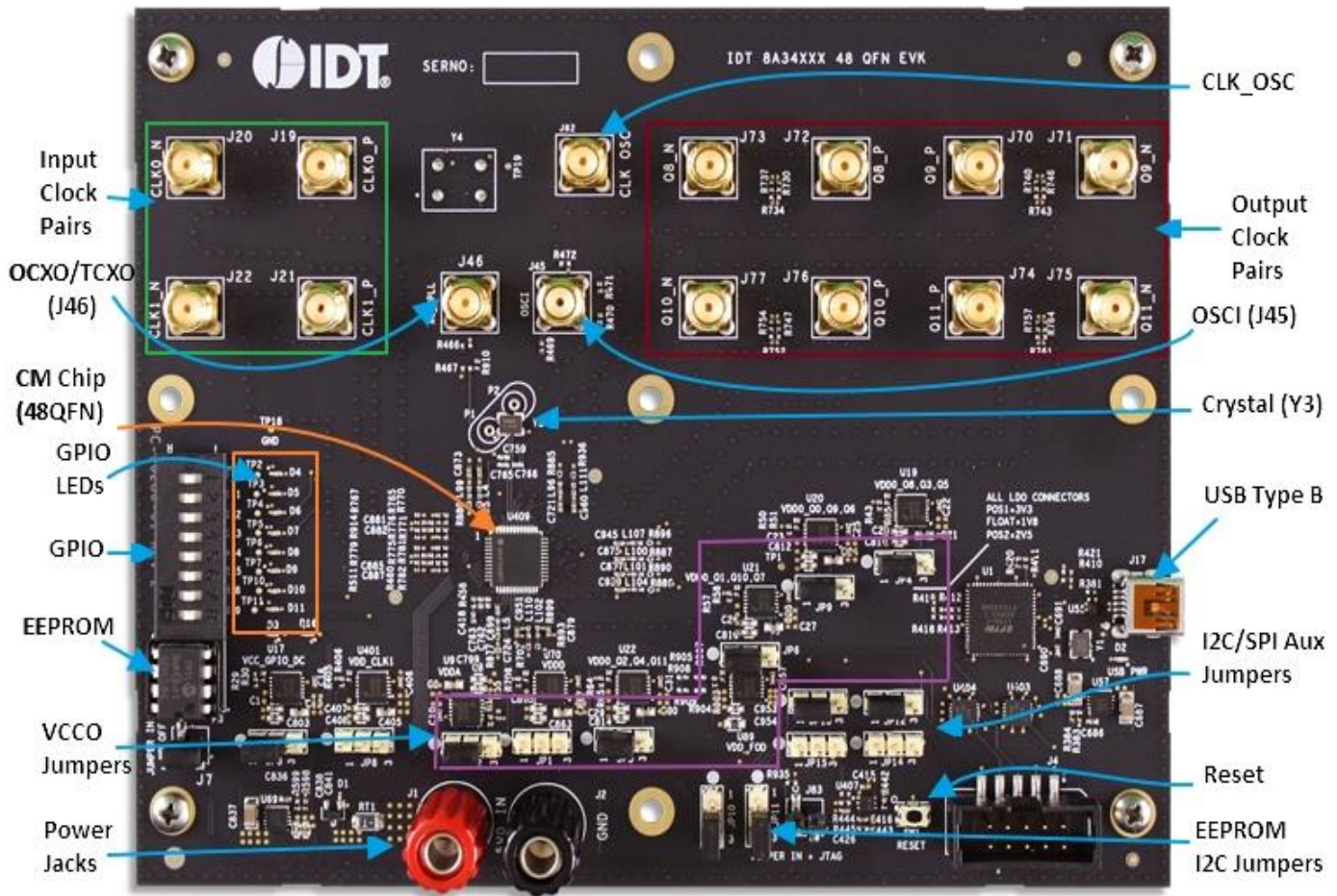
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# 1. Usage Guide

## 1.1 Board Overview

The following diagram identifies various components of the board: input and output SMA connectors, power supply jacks, and some jumper settings necessary for the board operations.

**Figure 1. Overview of 48QFN ClockMatrix Evaluation Board**



Detailed descriptions of the board are as follows.

- Input SMA Connectors – There are two differential inputs labeled CLK0/nCLK0–CLK1/nCLK1. Each input clock can be configured differentially (LVDS, PECL 2.5V, and PECL 3.3V) or in single-ended format (CMOS).
- Output SMA Connectors – There are four outputs labeled as Q8/nQ8–Q11/nQ11. Each output clock can be configured differentially (LVDS, LVPECL, or user-defined amplitude), or in single-ended format (LVCMOS – in-phase or out-of-phase)
- GPIO switch, LEDs, and test points – There are eight GPIOs available. Each GPIO can be set a “low” or “high” level (if input) or displayed with an LED (if output). Some GPIOs are used to set the chip in a certain working condition on power-up. For more information, see GPIO Switches, LEDs, and Test Points.
- USB connector – A USB mini-connector connects the evaluation board to a PC for GUI communications. No power is drawn from the USB connector other than to power the FTDI USB chip.



- VCCO voltage selection jumpers – Each output voltage can be individually supplied with 1.8V, 2.5V, or 3.3V. These jumpers are used to select the voltage for the output voltages.
- Reset button – A small button is used to reset the board.
- OSCI Input connector – An SMA connector, J45, can optionally supply a clock signal to overdrive the crystal.
- OCXO/TCXO reference – An SMA connector, J46, can supply a local OCXO/TCXO reference as an optional reference for System DPLL.
- Crystal – A crystal of various frequencies must be present for board operations. A 3225 footprint is provided for SMT crystals. For easy plug-in of a canned crystal, two through holes are also available.
- EEPROM – An SO-8 socket is provided to hold an EEPROM device of compatible package. EEPROM is used to store firmware and customer configuration data, if needed.

## 1.2 Board Power Supply

The board uses a single +5V supply for its power supplies. When running the board, set the bench power supply at 5V/2A. The red jack (J1) is positive; the black jack (J2) is the ground.

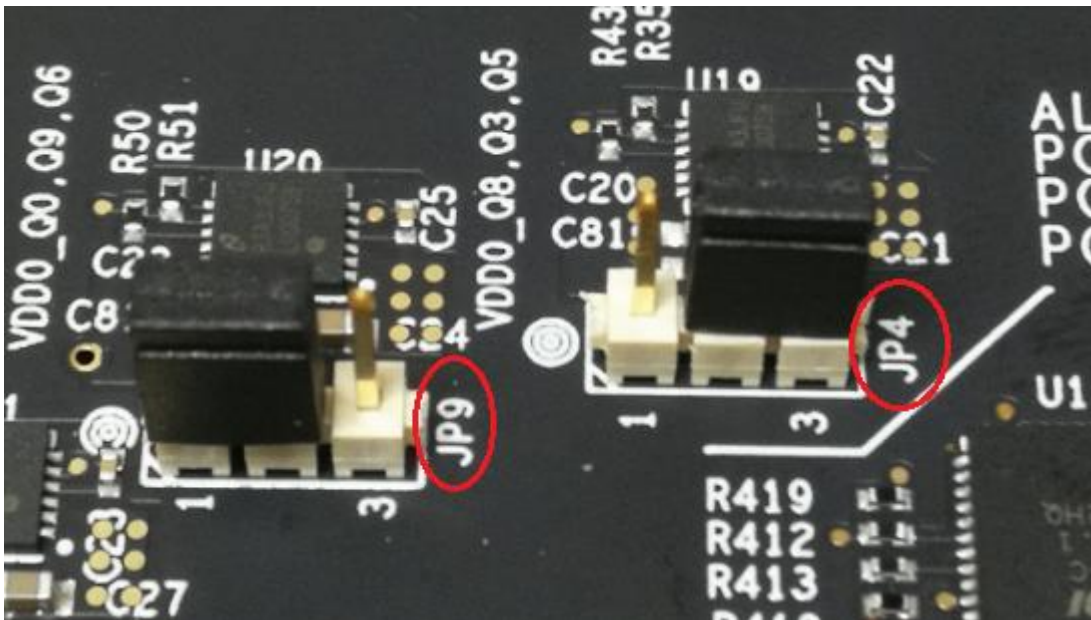
Multiple LDOs are used to generate 3.3V, 2.5V, and 1.8V from the +5V supply.

## 1.3 Voltage Selection Jumpers

There are nine headers/jumpers to select different voltages for different functional blocks of the chip. Each header is labeled pin 1 and pin 3 – jumping pin 1 and pin 2 will select 3.3V; jumping pin 2 and pin 3 will select 2.5V; no jumper will have 1.8V.

Please see the following example for JP4 and JP9 – JP4 will select 2.5V; JP9 will select 3.3V.

**Figure 2. Example of Voltage Jumpers**



The following list shows which header/jumper is used to select what voltage:

- JP1 – VDDD
- JP2 – VDDA
- JP3 – VCC\_GPIO\_DC
- JP4 – VDDO\_Q8\_3\_5
- JP5 – VDDO\_Q2\_4\_11
- JP6 – VDDO\_1\_10\_7
- JP7 – VDD\_CLK0
- JP8 – VDD\_CLK1
- JP9 – VDDO\_Q0\_9\_6



**Important Equipment Warning:** VDD\_FOD voltage is selected by resistors R908 and R909. In order to prevent damage to the device, both R908 and R909 should not be stuffed, in which case VDD\_FOD = 1.8V.

## 1.4 GPIO Switches, LEDs, and Test Points

An 8-bit dip switch sets the logic levels for eight GPIOs. The following table shows the GPIO levels for each setting and the corresponding LED state.

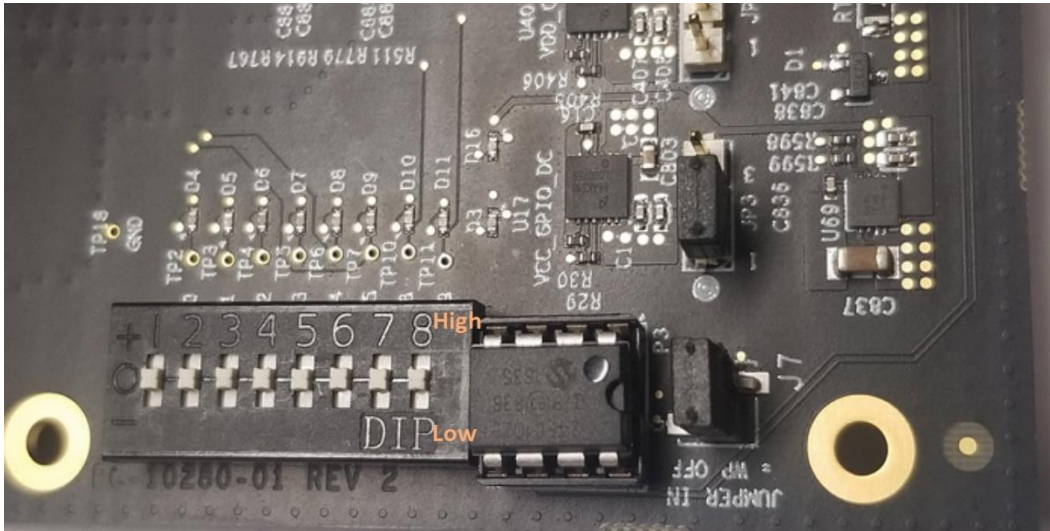
**Table 1. GPIO Settings**

Dip Switch Position	GPIO Logic Level	LED
Left	Low	On
Center	High if GPIO is configured as Input High or Low according to the GPIO output setting	High if GPIO is configured as Input High or Low according to the GPIO output setting
Right	High	Off

Please see the picture and labels in Figure 3.

When the GPIOs are configured as outputs (such as User-Controlled or LOL indicator), the dip switch for the corresponding GPIO should be placed in the center position. The LED will indicate the state of the GPIO.

**Figure 3. GPIO Setting and Status Display Area**



### 1.5 USB Jack

The board has a USB mini-connector. The other end of the USB cable is a USB Type A connector going to a PC.

### 1.6 Onboard EEPROM

An onboard EEPROM is used to store device firmware and/or customer's configuration data. There are two headers/jumpers, JP10 and JP11, used to select the I<sup>2</sup>C communication paths for the EEPROM.

**Table 2. EEPROM I<sup>2</sup>C Connections**

	JP10/JP11	JP10/JP11
Jumper Position	Both Pin 1 and 2	Both Pin 2 and 3
EEPROM I <sup>2</sup> C Path	FDTI and EEPROM	EEPROM and CM Chip

### 1.7 I<sup>2</sup>C/SPI Auxiliary Path Specifications

I<sup>2</sup>C and SPI connections can be configured using onboard jumpers. There are four headers/jumpers that control the auxiliary serial stream signals.

**Table 3. I<sup>2</sup>C/SPI Path Connections**

	JP12/JP13	JP12/JP13	JP14/JP15	JP14/JP15
Jumper Position	Pin 1 and 2	Pin 2 and 3	Pin 1 and 2	Pin 2 and 3
CM Chip Serial Port Path	SCLK/SDA Connected to on-board FTDI I <sup>2</sup> C Chip (Default)	SCLK/SDA Connected to J4 for external I <sup>2</sup> C/SPI controller use	NONE	SDI/nCS Connected to J4 for external I <sup>2</sup> C/SPI controller use

## 2. Working with Timing Commander™ for Programming/Configuration

The following sections are best cross-referenced with the *ClockMatrix GUI Step-by-Step User Guide* which is available on [www.idt.com](http://www.idt.com).

### 2.1 Default Operation

The board can operate off an EEPROM that has stored all information including firmware and a default configuration data. A default operation provides a sanity check on the board before running the board through the IDT Timing Commander. Please set the board in the following default conditions (see Figure 4 for jumper and switch positions).

- Set all the GPIOs to the center position. This will ensure that GPIO8 and GPIO9 are high and that the serial port is configured for I<sup>2</sup>C 1-byte addressing.
- VDDA = 3.3V, VCC\_GPIO\_DC = 3.3V, and VDDO\_Qx = 3.3V
- Crystal frequency = 50MHz
- CLK0 = 25MHz
- EEPROM is connected to ClockMatrix chip through an I<sup>2</sup>C bus by jumping Pin 2 and 3 of JP10 and JP11

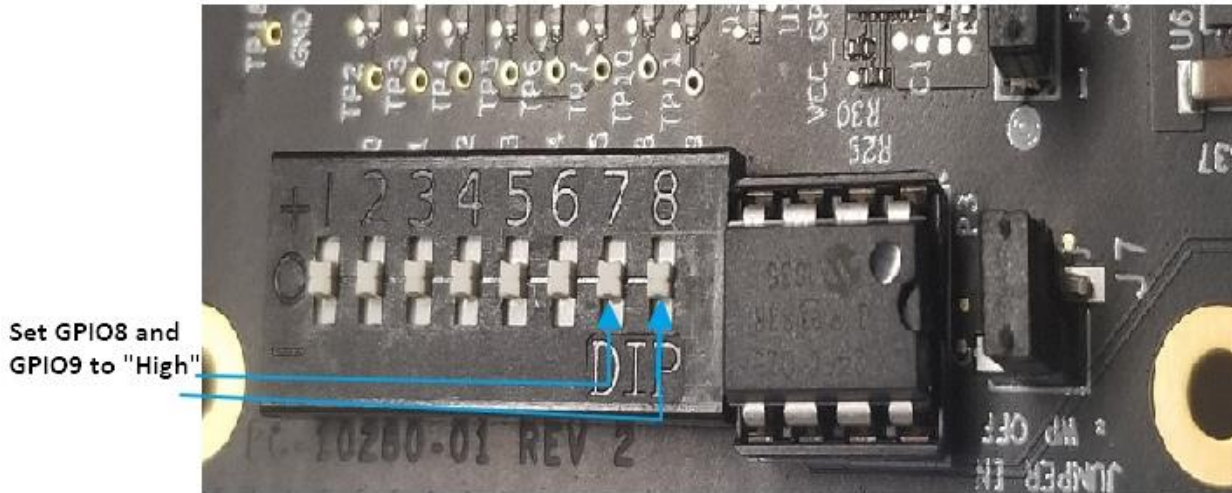
With the above default conditions ready, connect the board to the PC using a USB type A to USB mini cable, and power up the board using a single +5V supply. On power-up, the ClockMatrix chip will read its firmware and configuration data from EEPROM and update all registers. When this process is completed, the following frequencies are available:

Q0 = 122.88MHz

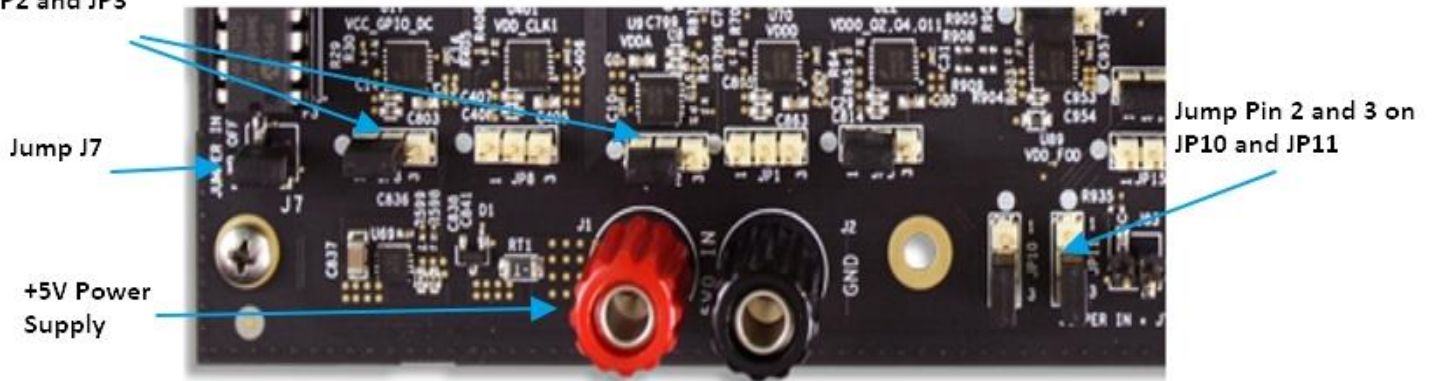
Q1 = 122.88MHz



Figure 4. Board Setting for Default Operation



Jump Pin 1 and 2 on JP2 and JP3



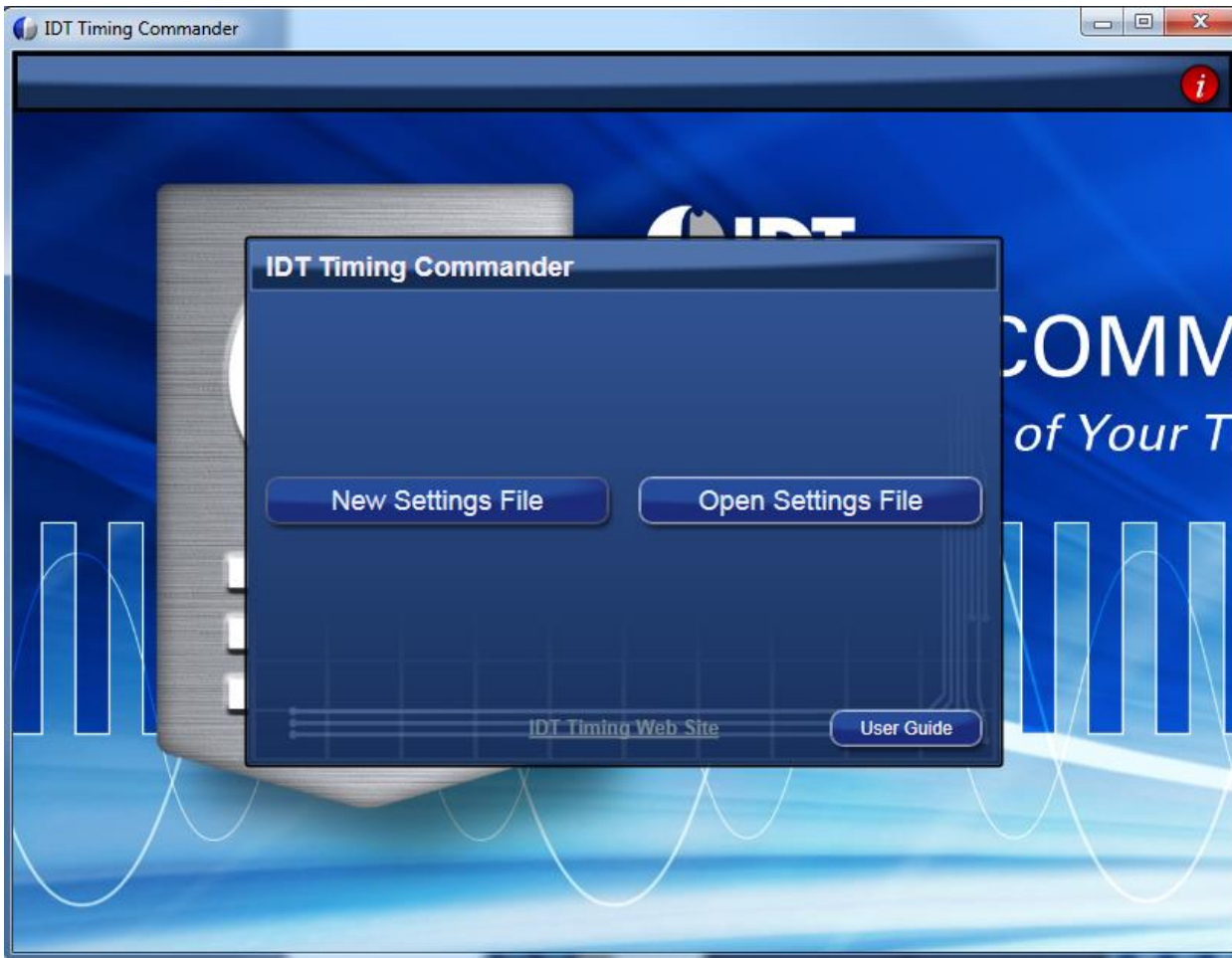
**Important Equipment Warning:** In order to set GPIO8 and GPIO9 to "High", the switches for GPIO8 and GPIO9 must be set either to the "+" (high) position or the center position.

## 2.2 Using Timing Commander to Control the Board

Once the default operation is successful, complete the following steps to configure and program the ClockMatrix device per your specific application requirements using Timing Commander GUI tools:

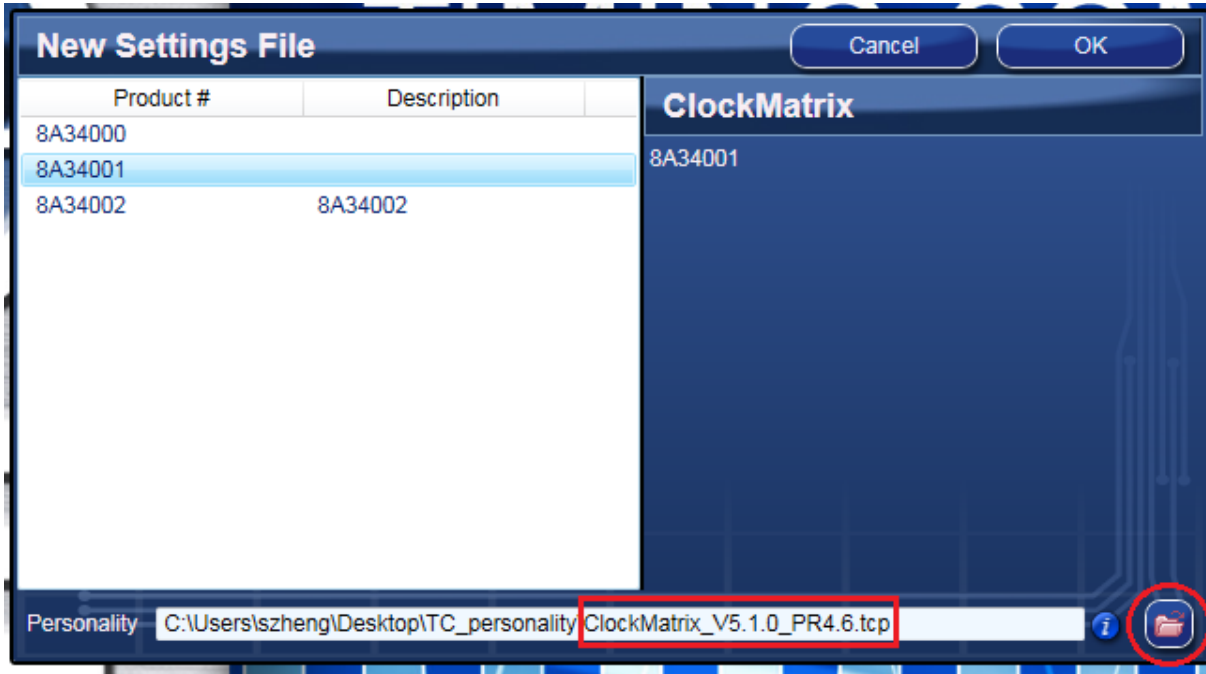
1. Power up the board and set the main serial port in I<sup>2</sup>C mode by GPIO9 = "high". Set GPIO8 = "High". Connect the board to the PC.
2. Start the Timing Commander software. You will see options of "New Setting File" and "Open Setting file". For a new configuration, select "New Setting File".

**Figure 5. Starting Up Timing Commander GUI**



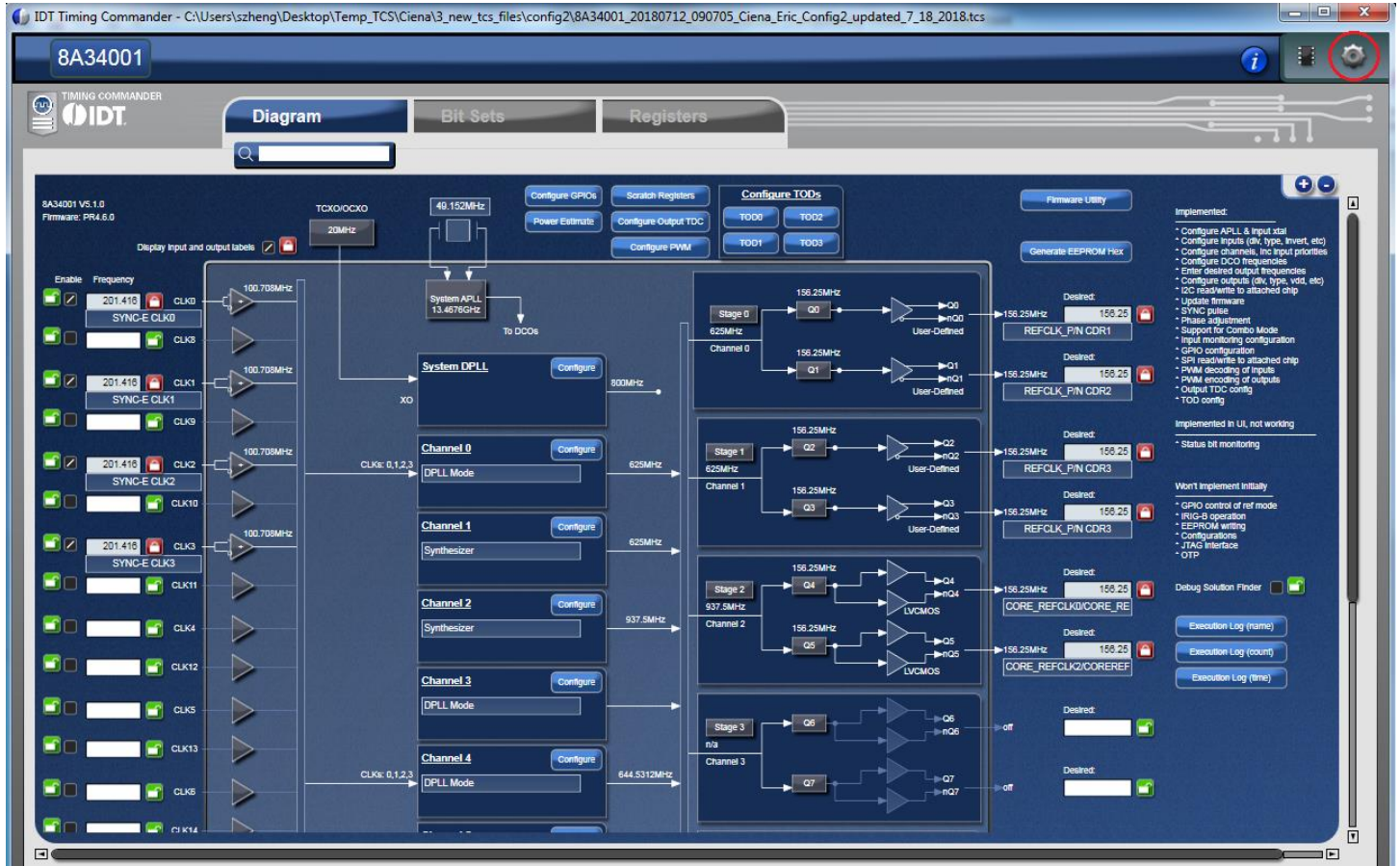
- After selecting "New Settings File", a device selection window will pop up. In the window, choose the intended device in the list (in this example, 8A34001 is selected). Click the button at the lower right corner of the window (red circle) to browse and select the correct personality file (in this example, personality v4.6 is selected). Click OK.

**Figure 6. Selecting 8A34001 using Personality File v4.6**



- The GUI window with the 8A34001 block diagram will open for configurations; or if “Open Settings File” is selected in Step 3, you will be prompted to browse and select an existing .tcs file and the personality file. When the configuration file is open, all configured values will be displayed (see Figure 7).

**Figure 7. Timing Commander GUI with a Settings File Opened**

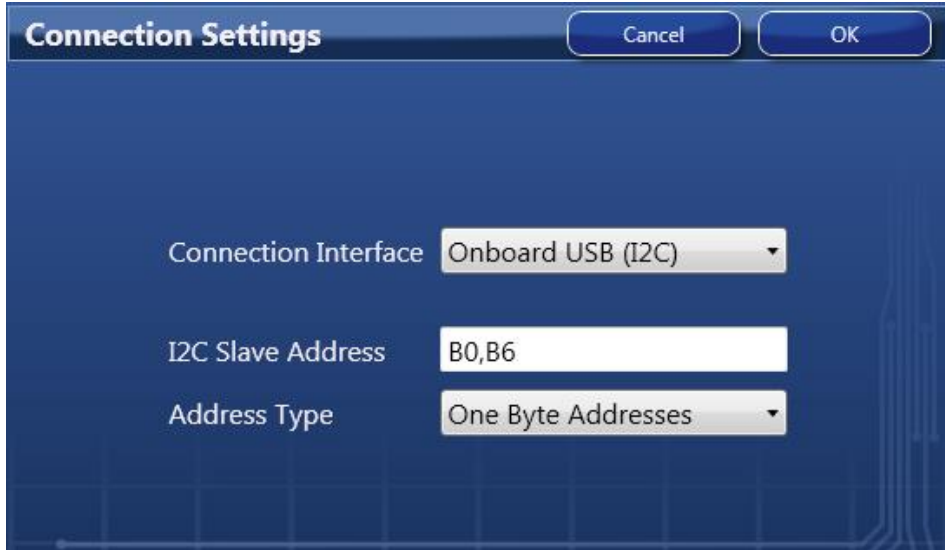




- In order to connect the board with Timing Commander (PC), click the button (red circle) at the up-right corner of the GUI to set up the communication protocols (see Figure 7).

After I<sup>2</sup>C and one-byte addressing are selected, click OK to close the window.

**Figure 8. Setting I<sup>2</sup>C for Connecting the Board with GUI**



- Click on the chip symbol at the upper-right corner to initiate the connection. The connection is valid when a green band appears at the upper-right corner of the window, as shown below.

**Figure 9. A Green Band appears when a Valid Connection is Made**





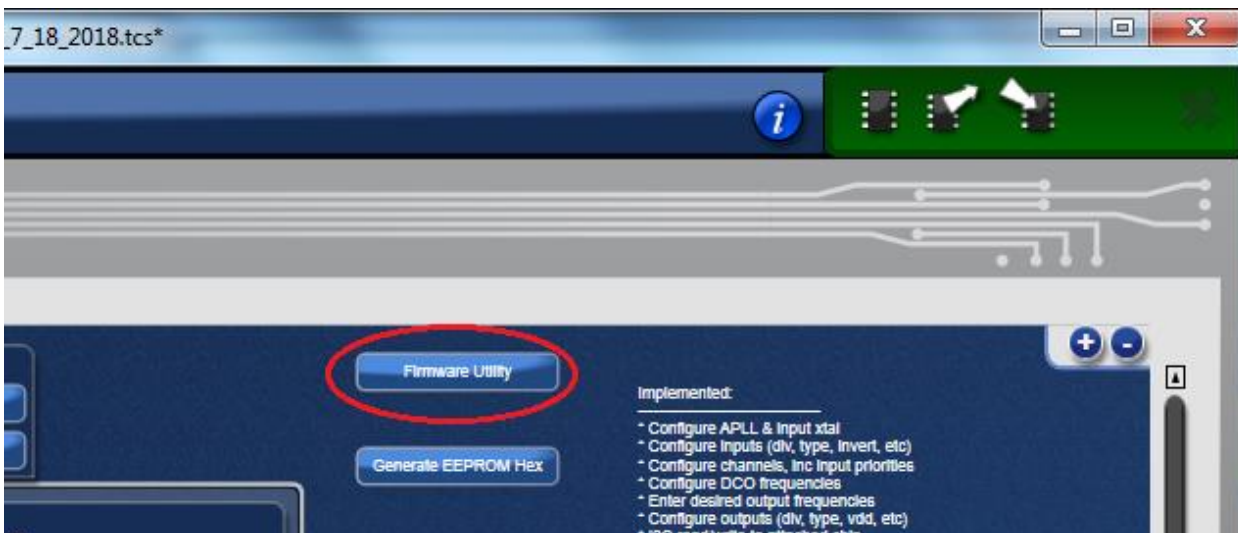
- If ClockMatrix chip's firmware, or firmware loaded from EEPROM, has a different version from that in the Personality file, a firmware version mismatch warning message will appear. Click "Close" button to close the message window and a connection is made.

**Figure 10. Firmware Version Mismatch Warning Message**



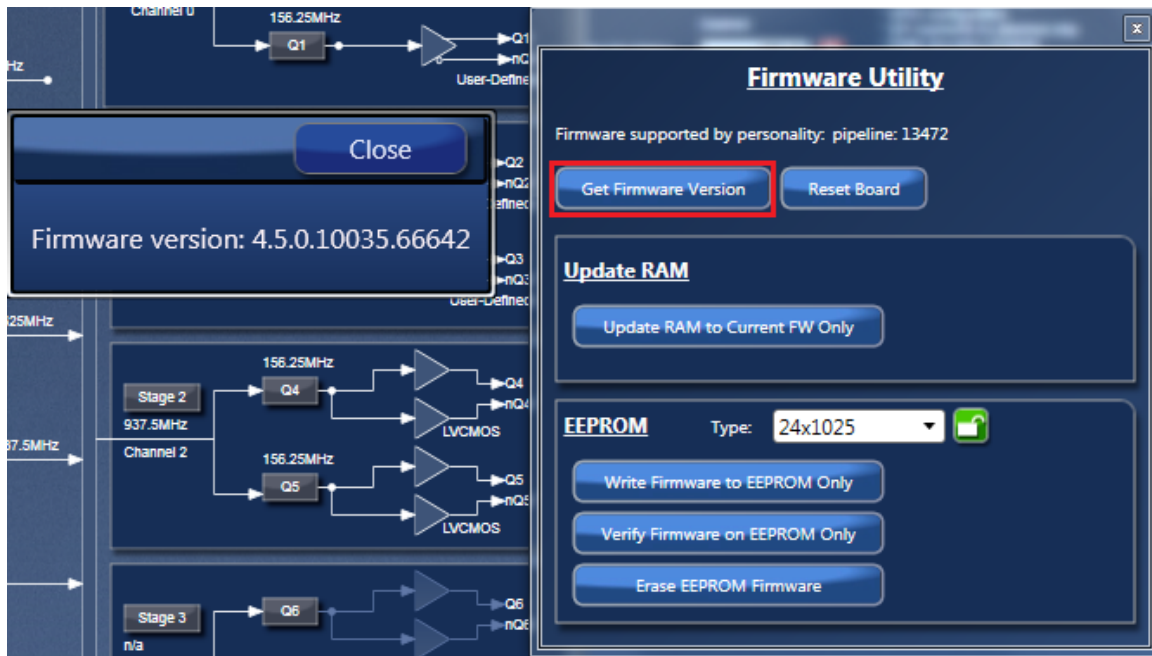
- Once the connection is made, the firmware version can be read within the GUI. Click the "Firmware Utility" button to bring up the Firmware Utility window, as shown below.

**Figure 11. Reading Firmware Version**



9. Within the Firmware Utility window, click the “Get Firmware Version” button to read the firmware version.

**Figure 12. Read Firmware Version of ClockMatrix Chip**



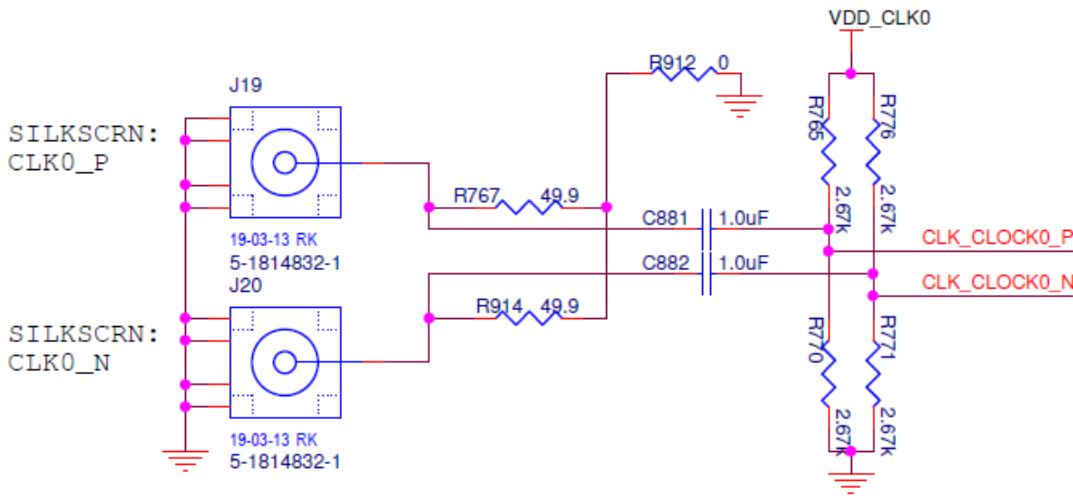
10. In the case where the firmware version mismatches each other, a firmware upgrade is necessary to update the chip’s firmware. To do so, complete the steps in How to Upgrade the Firmware to update the chip’s firmware.

### 2.3 Output Terminations and Rework to Take 1PPS Input

All outputs are terminated per LVDS with a 100Ω resistor across the output pair. When the output is configured as PECL2.5 and PECL3.3 or user-defined differential, the output clock will still be switching. The amplitude may be different from expected until the hardware termination matches the signaling type configured for the output.

The following rework must be implemented in order to support a 1PPS input clock. All input clocks for this board are ac-coupled and terminated as in the following figure.

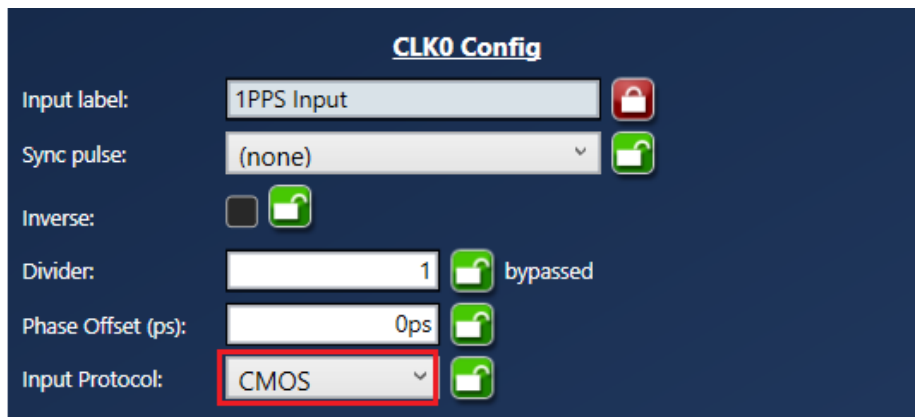
**Figure 13. AC Coupling and Terminations for Input Clock**



For a 1PPS input, a single-ended input with DC-coupling is recommended. As such, the populated AC-coupling capacitor must be removed and the input must be configured as LVCMOS, not differential.

1. In Figure 13, to make CLK0 supportive of 1PPS input, first configure CLK0 as LVCMOS in Timing Commander (see Figure 14).

**Figure 14. Configuring CLK0 as CMOS to Receive a 1PPS Input**



2. Once in LVCMOS mode, CLK0\_P and CLK0\_N will be two separate LVCMOS inputs instead of a differential pair. To make CLK0\_P receive a 1PPS input, replace C881 with a 0Ω resistor; and at the same time, remove R765 and R770.

### 3. How to Upgrade the Firmware

#### 3.1 Upload Firmware to the RAM

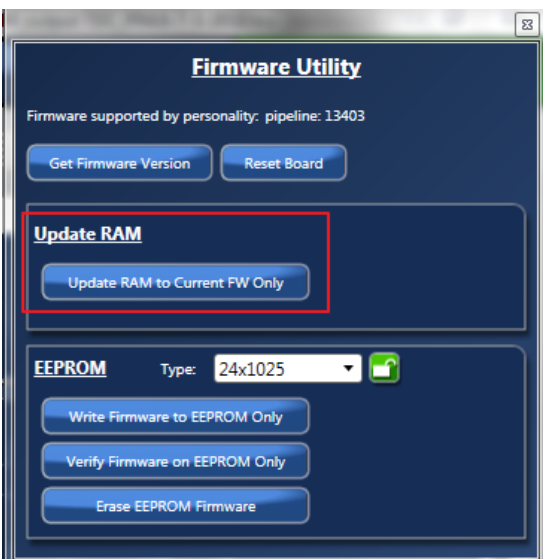
1. Connect to the EVK board.
2. Power up the board with no EEPROM present. This ensures the firmware is 4.0.2.7017, as displayed in the figure.
3. The GUI will indicate that the firmware on the chip does not match the GUI firmware. Press “Close”.



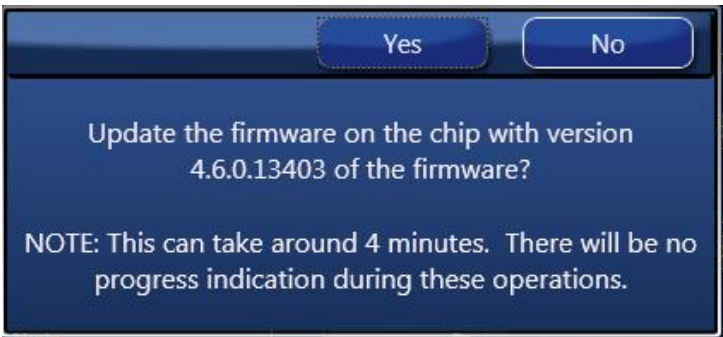
4. Open the “Firmware Utility” window by clicking on the button as follows.



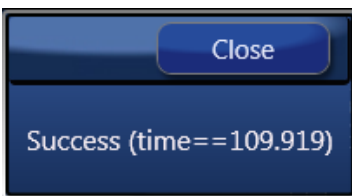
5. Update the Firmware first. Press “Update RAM to Current FW Only”.



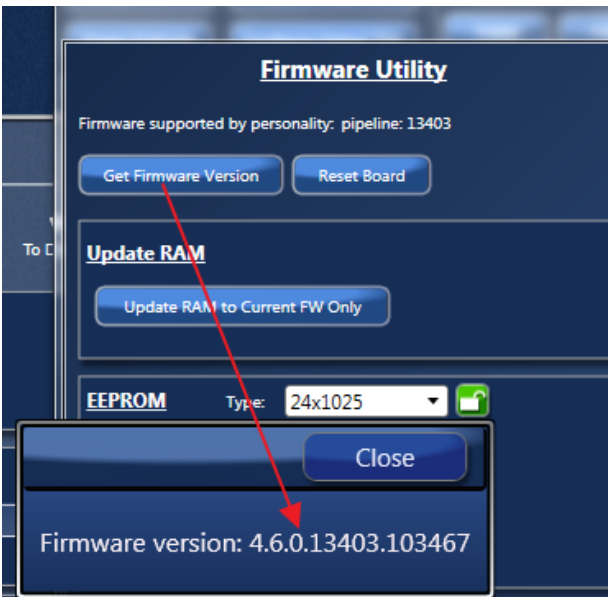
6. In the next window, press “Yes” and wait around 3-4 minutes.



7. Once the firmware is updated, the following window will indicate a successful update. Click “Close”.



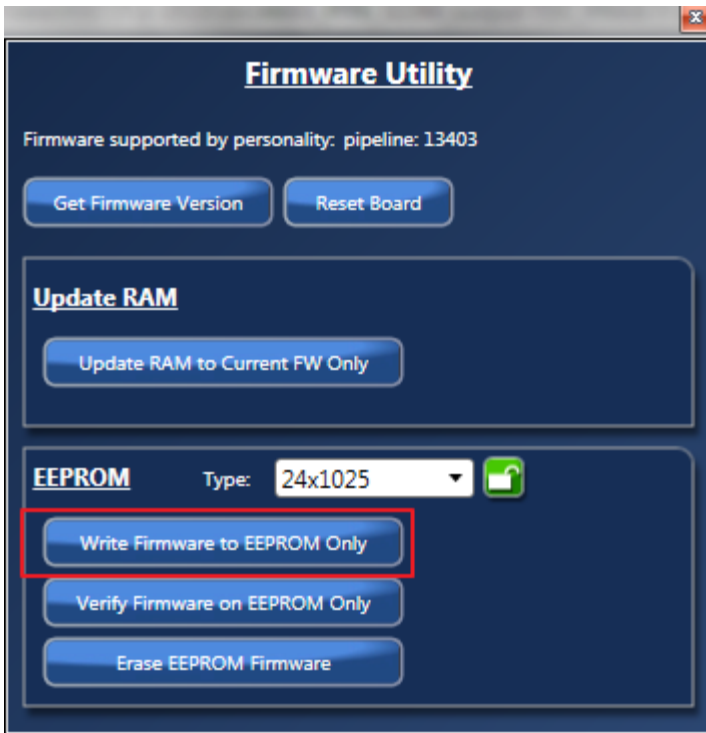
8. Press “Get Firmware Version” to verify that the RAM was updated correctly, then click “Close”.



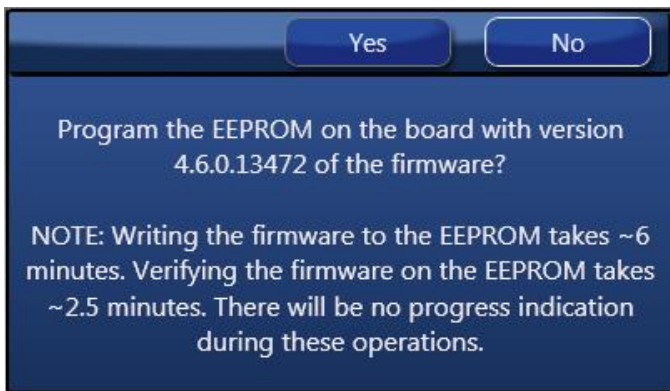


### 3.2 Upload Firmware into the EEPROM

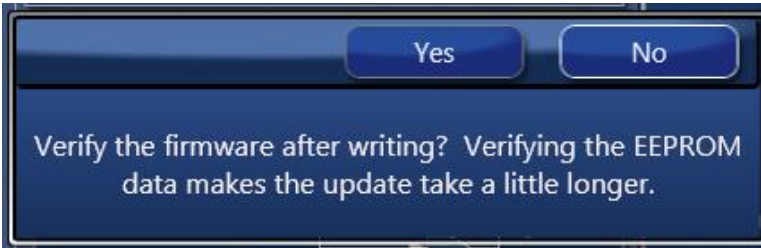
1. Once the firmware has been updated to the chip (steps 1 to 8), install the EEPROM on the EVK board.
2. Press "Write Firmware to EEPROM Only".



3. In the next window, press "Yes".



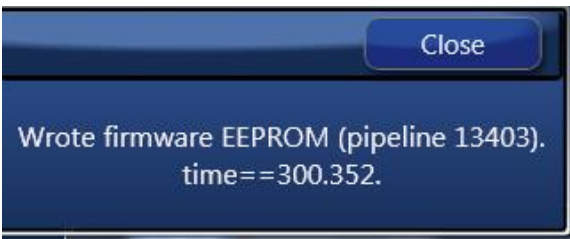
4. When asked to "Verify" the EEPROM, press "No".



5. In the next window, press "Close" to start the EEPROM write.



6. Wait about 5 minutes for the EEPROM write to complete. Click "Close" in the following window.



### 3.3 Verify the EEPROM Programming

7. Power cycle the board.
8. Disconnect and reconnect to the chip.
9. Read back the firmware version to ensure it is correct (see steps 3 to 7).

## 4. Schematics

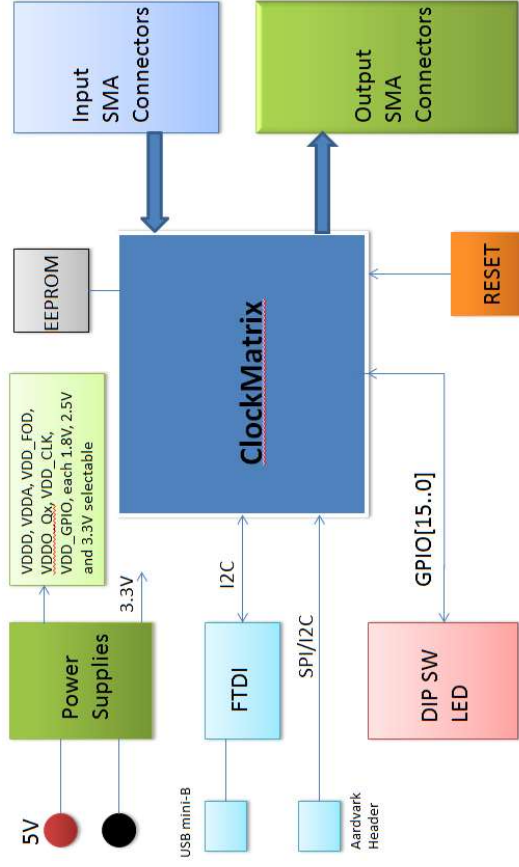
Please see the schematics located at the end of this document.

## 5. Ordering Information

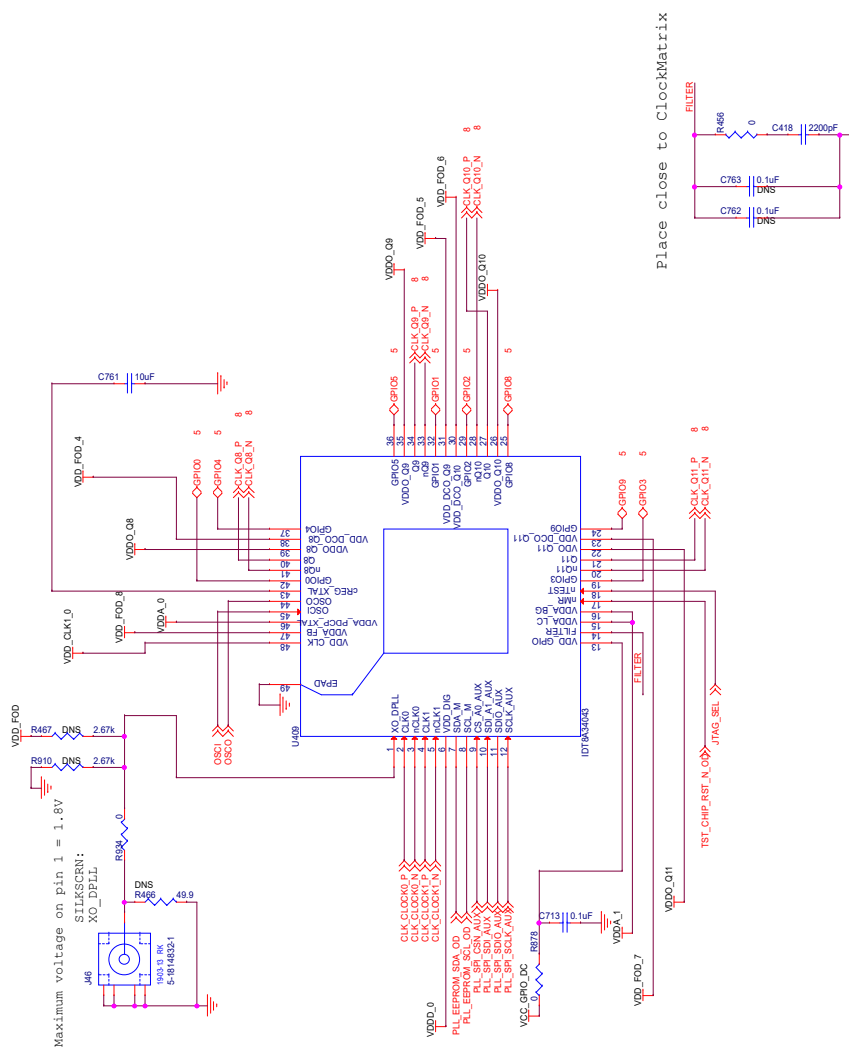
Orderable Part Number	Description
8A34043-EVK	8A3xxxx 48QFN Evaluation Kit

## 6. Revision History

Revision Date	Description of Change
February 15, 2019	Initial release.

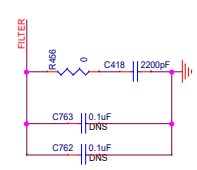


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DESIGN	IDT8A34001	375 Terry Fox Drive, Ottawa, ON K2K 0J8
DB		
DRAWN	Block Diagram	
DB	Author	
CHECK	SK-10280-01	REVISION 1.2
DB	27 October 2016	SHEET 1 OF 9



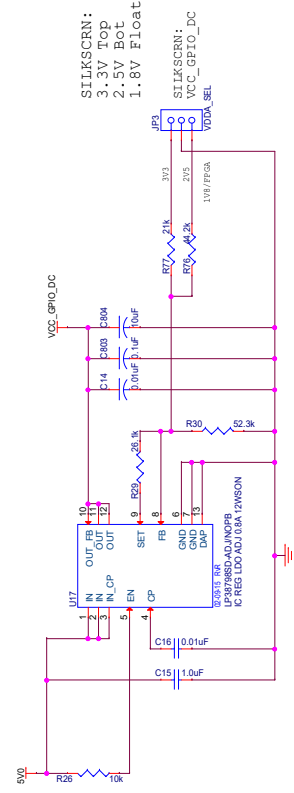
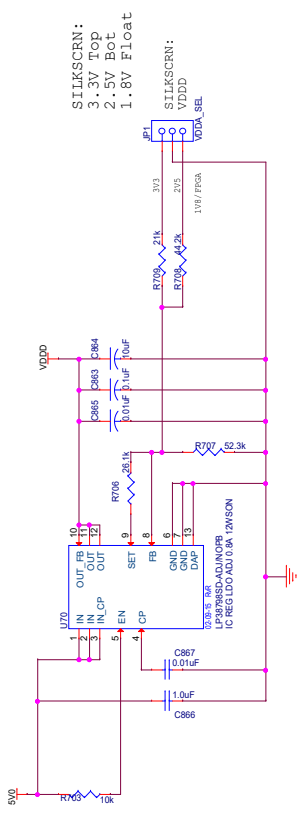
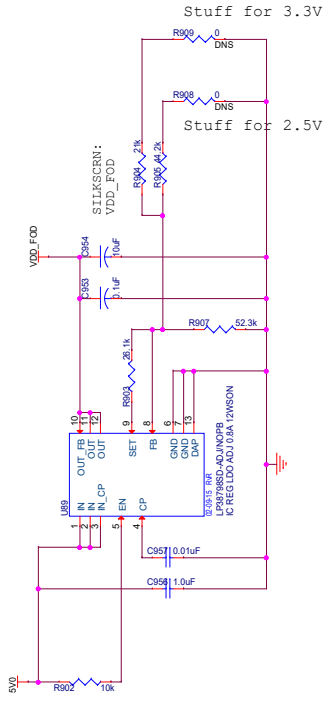
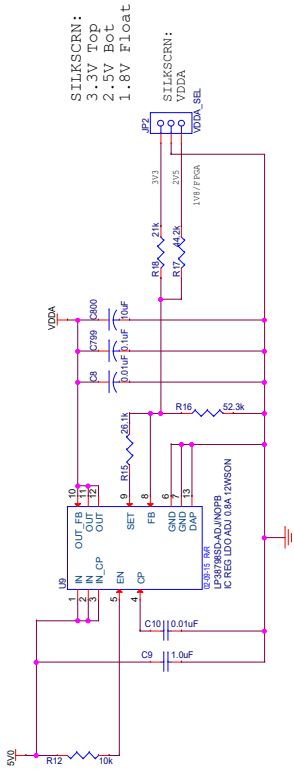
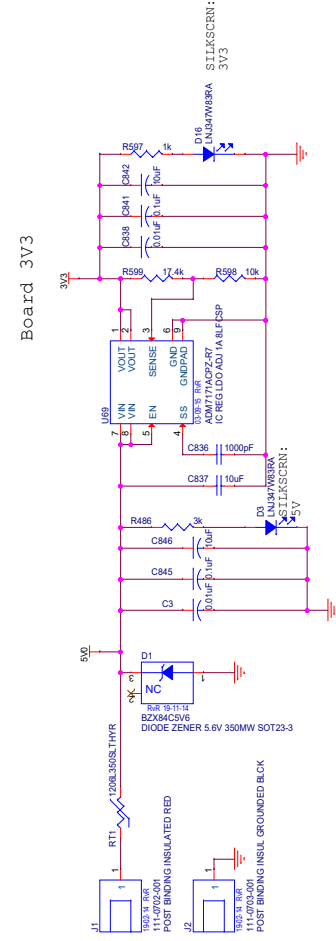
Maximum voltage on pin 1 = 1.8V

Place close to ClockMatrix

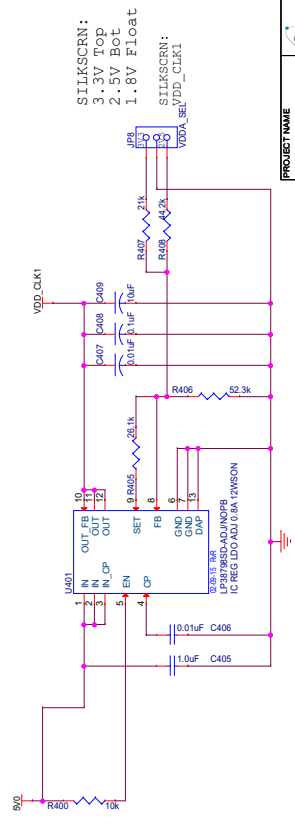
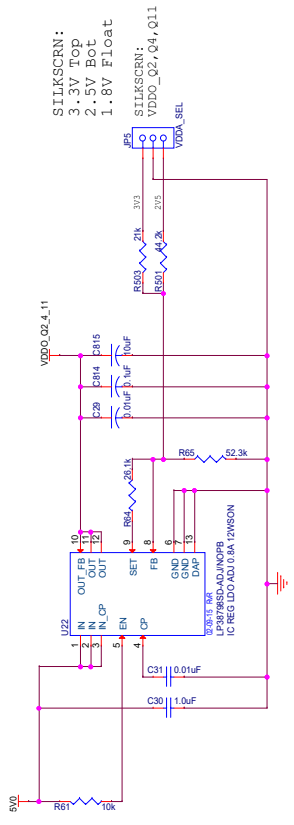
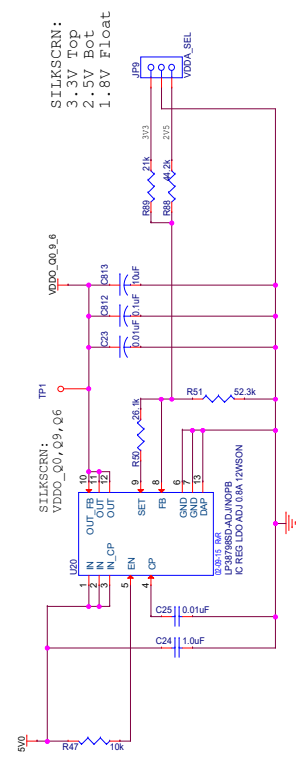
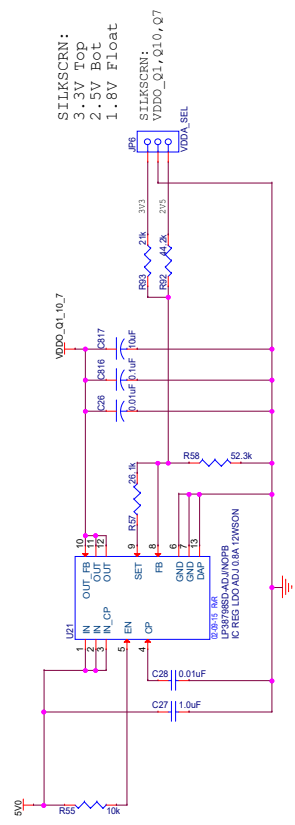
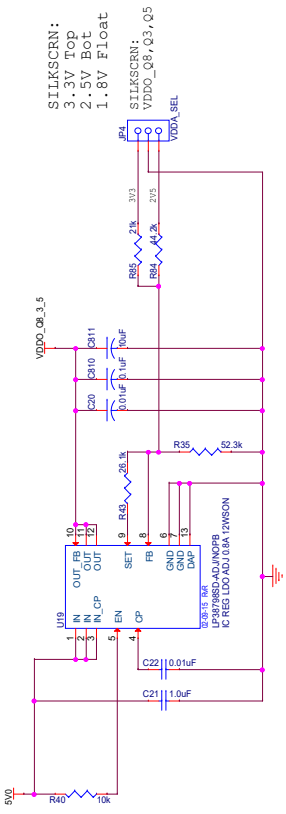




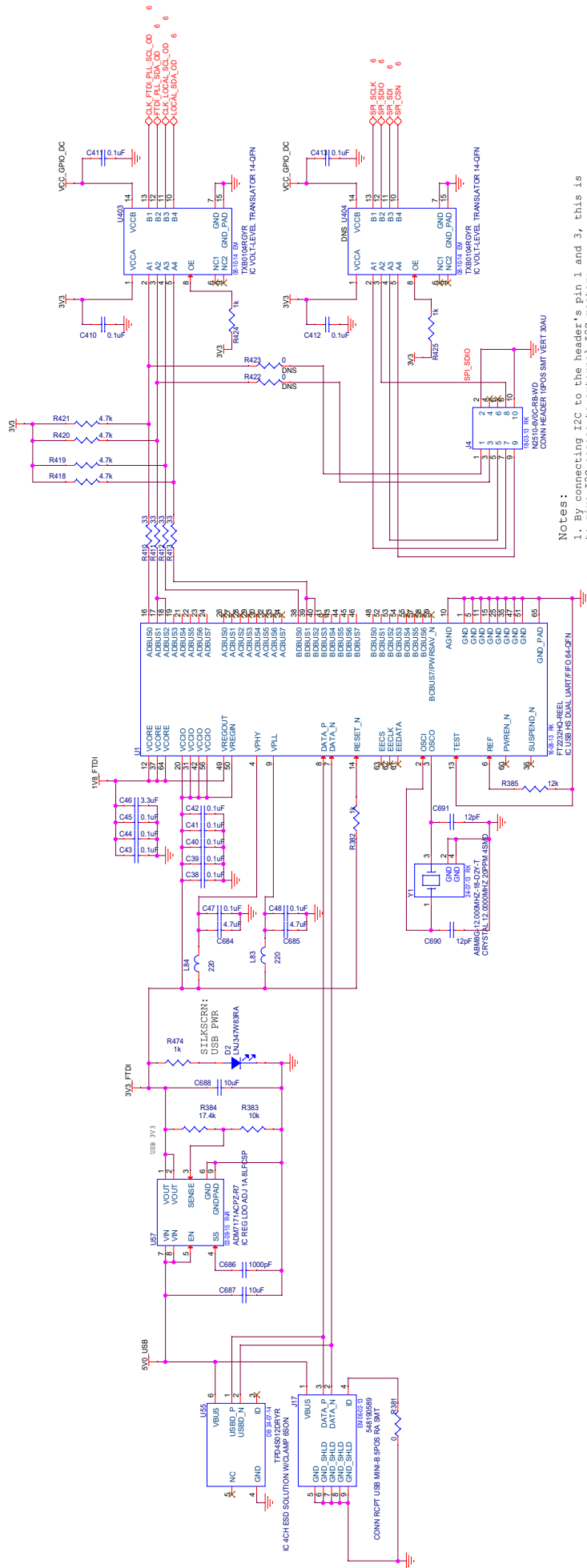
Board 3V3



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CHECK	SK-10280-01	REVISION
DB	27 October 2016	SHEET
		2 OF 9



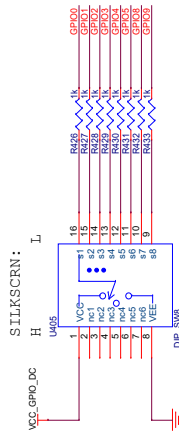
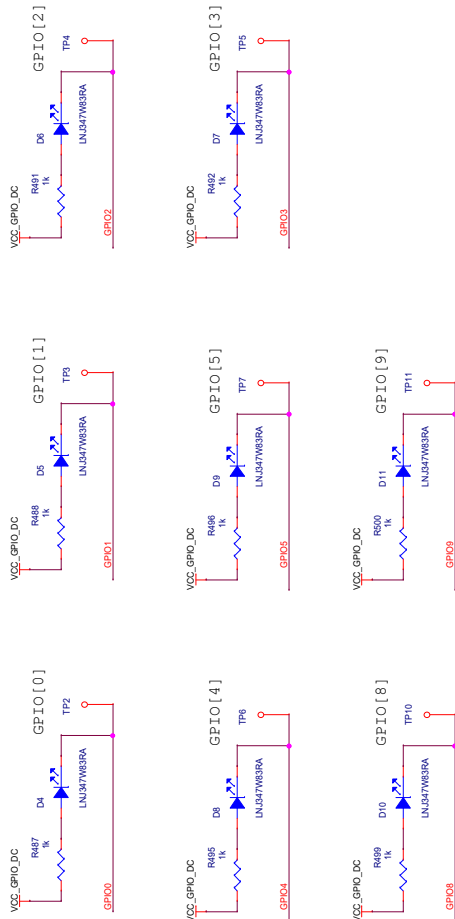
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DRAWN	Power Supplies 2	
CHECK	SK-10280-01	REVISION
DB	27 October 2016	SHEET
		3 OF 9



- NOTES:
1. By connecting I2C to the header's pin 1 and 3, this is to give I2C access to external I2C master;
  2. By installing R926 and R927, FTDI can also access Aux I/O pins (R928 and R929). This feature is not expected to be used by RS7 and RS9. This feature is not expected to be used by RS7 and RS9.
  3. Normal use: FTDI controls I2C port; Header is connected to Aux port in SPI configuration.

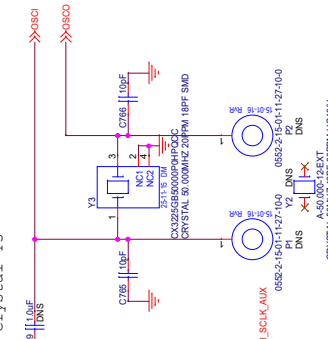
PROJECT NAME	fidus Systems
DESIGN	375 Terry Fox Drive, Ottawa, ON K2K 0J8
DB	
TITLE	IDT8A34001
DRAWN	FTDI USB Interface
CHECK	SK-10280-01
REVISION	1.2
SHEET	4 OF 9
DATE	27 October 2016

Note for Silkscreen:  
Place GPIO[x] label close to each  
corresponding LED and test point.



PROJECT NAME	fidius	Fidius Systems
DESIGN	IDT8A34001	375 Terry Fox Drive, Ottawa, ON K2K 0J8
REVISION	GPIO LEDs	
DRAWN	SK-10280-01	
CHECK	27 October 2016	
DB	5 OF 9	

Place close to  
Crystal Y3



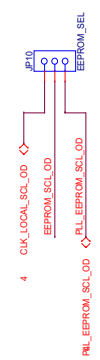
### JP12~JP15 Default Jump Up

#### I2 Bus

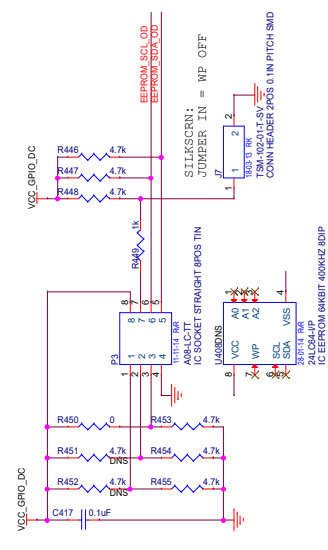
- 4 CLK\_FTDL\_PHL\_SCL\_OD
- 4 FTDL\_PHL\_SDA\_OD

#### SPI Bus

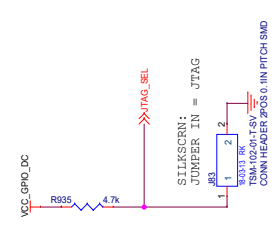
- 4 SP\_SCLK
- 4 SP\_SDO
- 4 SP\_SDI
- 4 SP\_LCSN



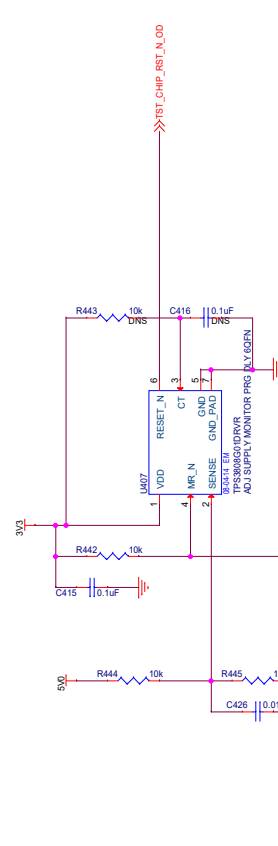
Default Jump  
between CK  
and EPPROM



SILKSCREEN:  
JUMPER IN = WP OFF



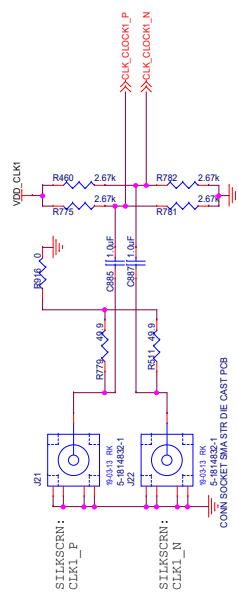
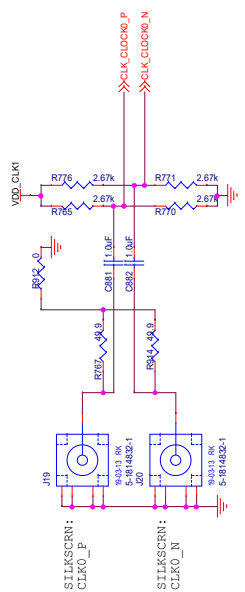
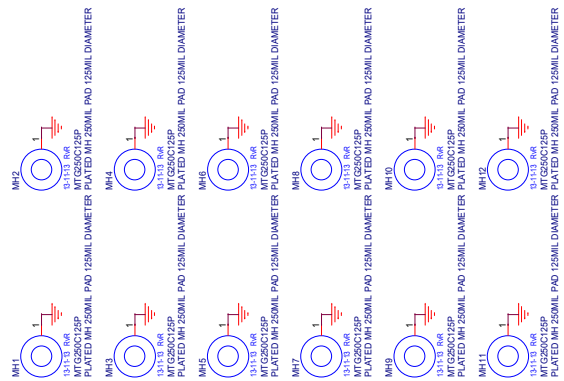
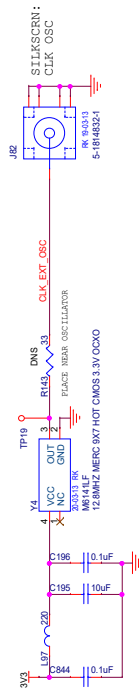
SILKSCREEN:  
JUMPER IN = JTAG



SILKSCREEN:  
RESET

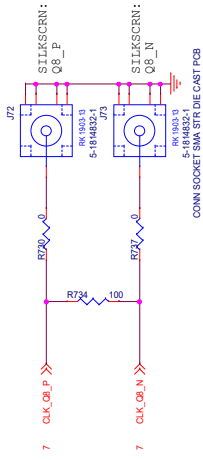
SWITCH TACTILE SPST-NO 0.05A 32V

PROJECT NAME	Indra3	fidus	Fidus Systems
DESIGN	IDT8A34001	375 Terry Fox Drive, Ottawa, ON K2K 0J8	
DRAWN	PLL Core		
DB	SK-10280-01		
CHECK	REVISION	REVISION	1.2
DB	DATE	DATE	27 October 2016
	SHEET	SHEET	6 OF 9

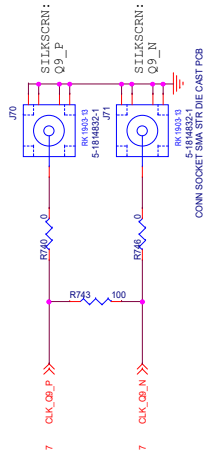


PROJECT NAME	fidus Systems
DESIGN	375 Terry Fox Drive, Ottawa, ON K2K 0J8
TITLE	IDT8A34001
REVISION	PLL Input Clocks
DRAWN	SK-10280-01
CHECK	SK-10280-01
DATE	27 October 2016
SHEET	7 OF 9

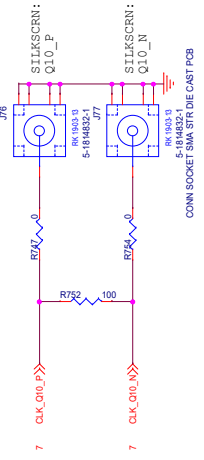
PLACE PARALLEL  
TERMINATIONS  
CLOSE TO USE



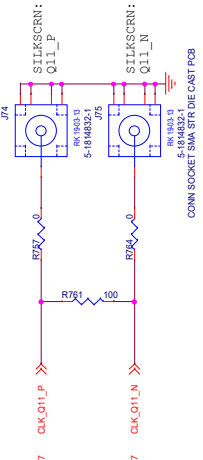
CONN SOCKET SMA STR DIE CAST PCB



CONN SOCKET SMA STR DIE CAST PCB



CONN SOCKET SMA STR DIE CAST PCB



CONN SOCKET SMA STR DIE CAST PCB

PROJECT NAME	fidius Systems
DESIGN	375 Terry Fox Drive, Ottawa, ON K2K 0J8
DB	IDT8A34001
DRAWN	REV DLE
DB	PLL Output Clocks
CHECK	DESIGNED BY: SK-10280-01
DB	REVISION: 1.2
	DATE: 27 October 2016
	SHEET: 8 OF 9





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