DATA SHEET

General Description

The IDT8T49N203I is a highly flexible FemtoClock® NG general purpose, low phase noise Universal Frequency Translator / Synthesizer with alarm and monitoring functions suitable for networking and communications applications. It is able to generate any output frequency in the 0.98MHz - 312.5MHz range and most output frequencies in the 312.5MHz - 1,300MHz range (see Table 3 for details). A wide range of input reference clocks and a range of low-cost fundamental mode crystal frequencies may be used as the source for the output frequency.

The IDT8T49N203I has three operating modes to support a very broad spectrum of applications:

- 1) Frequency Synthesizer
 - Synthesizes output frequencies from a 16MHz 40MHz fundamental mode crystal.
 - Fractional feedback division is used, so there are no requirements for any specific crystal frequency to produce the desired output frequency with a high degree of accuracy.
- 2) High-Bandwidth Frequency Translator
 - Applications: PCI Express, Computing, General Purpose
 - Translates any input clock in the 16MHz 710MHz frequency range into any supported output frequency.
 - This mode has a high PLL loop bandwidth in order to track input reference changes, such as Spread-Spectrum Clock modulation, so it will not attenuate much jitter on the input reference.
- 3) Low-Bandwidth Frequency Translator
 - Applications: Networking & Communications.
 - Translates any input clock in the 8kHz -710MHz frequency range into any supported output frequency.
 - This mode supports PLL loop bandwidths in the 10Hz 580Hz range and makes use of an external crystal to provide significant jitter attenuation.

This device provides two factory-programmed default power-up configurations burned into One-Time Programmable (OTP) memory. The configuration to be used is selected by the CONFIG pin. The two configurations are specified by the customer and are programmed by IDT during the final test phase from an on-hand stock of blank devices. The two configurations may be completely independent of one another.

One usage example might be to install the device on a line card with two optional daughter cards: an OC-12 option requiring a 622.08MHz LVDS clock translated from a 19.44MHz input and a Gigabit Ethernet option requiring a 125MHz LVPECL clock translated from the same 19.44MHz input reference.

To implement other configurations, these power-up default settings can be overwritten after power-up using the $l^{\rm 2}C$ interface and the device can be completely reconfigured. However, these settings would have to be re-written next time the device powers-up.

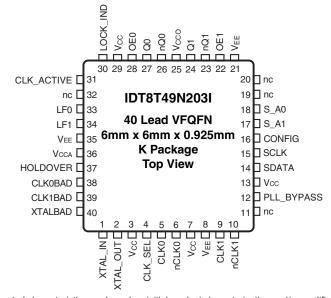
Features

- Fourth generation FemtoClock® NG technology
- Universal Frequency Translator (UFT) / Frequency Synthesizer
- Two outputs, individually programmable as LVPECL or LVDS
 - Both outputs may be set to use 2.5V or 3.3V output levels
 - Programmable output frequency: 0.98MHz up to 1,300MHz
- Zero ppm frequency translation
- Two differential inputs support the following input types: LVPECL, LVDS, LVHSTL, HCSL
- Input frequency range: 8kHz 710MHz
- Crystal input frequency range: 16MHz 40MHz
- Two factory-set register configurations for power-up default state
 - Power-up default configuration pin or register selectable
 - Configurations customized via One-Time Programmable ROM
 - Settings may be overwritten after power-up via I²C
 - I²C Serial interface for register programming
- RMS phase jitter at 155.52MHz, using a 40MHz crystal LVDS Output (12kHz - 20MHz): 439fs (typical), Low Bandwidth Mode (FracN)
- RMS phase jitter at 400MHz, using a 40MHz crystal (12kHz - 40MHz):285fs (typical), Synthesizer Mode (Integer FB)
- Output supply voltage modes:

V_{CC}/V_{CCA}/V_{CCO} 3.3V/3.3V/3.3V 3.3V/3.3V/2.5V (LVPECL only) 2.5V/2.5V/2.5V

- -40°C to 85°C ambient operating temperature
- Available in lead-free (RoHS 6) package

Pin Assignment



The Preliminary Information presented herein represents a product in pre-production. The noted characteristics are based on initial product characterization and/or qualification. Integrated Device Technology, Incorporated (IDT) reserves the right to change any circuitry or specifications without notice



Complete Block Diagram

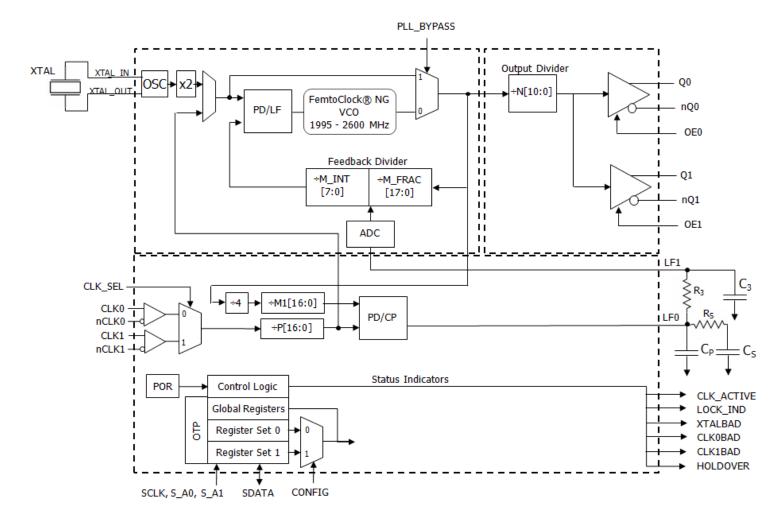




Table 1. Pin Descriptions

| Number | Name | Т | уре | Description |
|-------------------|------------------|--------|---------------------|---|
| 1 | XTAL_IN | Input | | Crystal Oscillator interface designed for 12pF parallel resonant crystals. |
| 2 | XTAL_OUT | put | | XTAL_IN (pin 1) is the input and XTAL_OUT (pin 2) is the output. |
| 3, 7, 13, 29 | V _{CC} | Power | | Core supply pins. All must be either 3.3V or 2.5V. |
| 4 | CLK_SEL | Input | Pulldown | Input clock select. Selects the active differential clock input. LVCMOS/LVTTL interface levels. 0 = CLK0, nCLK0 (default) 1 = CLK1, nCLK1 |
| 5 | CLK0 | Input | Pulldown | Non-inverting differential clock input. |
| 6 | nCLK0 | Input | Pullup/ Pulldown | Inverting differential clock input. $V_{CC}/2$ default when left floating (set by the internal pullup and pulldown resistors). |
| 8, 21, 35 | V _{EE} | Power | | Negative supply pins. |
| 9 | CLK1 | Input | Pulldown | Non-inverting differential clock input. |
| 10 | nCLK1 | Input | Pullup/ Pulldown | Inverting differential clock input. $V_{\rm CC}/2$ default when left floating (set by the internal pullup and pulldown resistors). |
| 11, 19, 20, 32 | nc | Unused | | No connect. These pins are to be left unconnected. |
| 12 | PLL_BYPASS | Input | Pulldown | Bypasses the VCXO PLL. In bypass mode, outputs are clocked off the falling edge of the input reference. LVCMOS/LVTTL interface levels. 0 = PLL Mode (default) 1 = PLL Bypassed |
| 14 | SDATA | I/O | Pullup | I ² C Data Input/Output. Open drain. |
| 15 | SCLK | Input | Pullup | I ² C Clock Input. LVCMOS/LVTTL interface levels. |
| 16 | CONFIG | Input | Pulldown | Configuration Pin. Selects between one of two factory programmable pre-set power-up default configurations. The two configurations can have different output/input frequency translation ratios, different PLL loop bandwidths, etc. These default configurations can be overwritten after power-up via I²C if the user so desires. LVCMOS/LVTTL interface levels. 0 = Configuration 0 (default) 1 = Configuration 1 |
| 17 | S_A1 | Input | Pulldown | I ² C Address Bit 1. LVCMOS/LVTTL interface levels. |
| 18 | S_A0 | Input | Pulldown | I ² C Address Bit 0. LVCMOS/LVTTL interface levels. |
| 22 | OE1 | Input | Pullup | Active High Output Enable for Q1, nQ1. LVCMOS/LVTTL interface levels. 0 = Output pins high-impedance 1 = Output switching (default) |
| 23, 24 | nQ1, Q1 | Output | | Differential output pair. Output type is programmable to LVDS or LVPECL interface levels. |
| 25 | V _{CCO} | Power | | Output supply pins for Q1, nQ1 and Q0, nQ0 outputs. Either 2.5V or 3.3V. |
| 26, 27 | nQ0, Q0 | Output | | Differential output pair. Output type is programmable to LVDS or LVPECL interface levels. |
| 28 | OE0 | Input | Pullup | Active High Output Enable for Q0, nQ0. LVCMOS/LVTTL interface levels. 0 = Output pins high-impedance 1 = Output switching (default) |
| 30 | LOCK_IND | Output | | Lock Indicator - indicates that the PLL is in a locked condition. LVCMOS/LVTTL interface levels. |
| 31 | CLK_ACTIVE | Output | | Indicates which of the two differential clock inputs is currently selected. LVCMOS/LVTTL interface levels. 0 = CLK0, nCLK0 differential input pair 1 = CLK1, nCLK1 differential input pair |



| Number | Name | Туре | Description |
|--------|------------------|---------------|--|
| 33, 34 | LF0, LF1 | Analog I/O | Loop filter connection node pins. LF0 is the output. LF1 is the input. |
| 36 | V _{CCA} | Power | Analog supply voltage. See Applications section for details on how to connect this pin. |
| 37 | HOLDOVER | Output | Alarm output reflecting if the device is in a holdover state. LVCMOS/LVTTL interface levels. 0 = Device is locked to a valid input reference 1 = Device is not locked to a valid input reference |
| 38 | CLK0BAD | Output | Alarm output reflecting the state of CLK0. LVCMOS/LVTTL interface levels. 0 = Input Clock 0 is switching within specifications 1 = Input Clock 0 is out of specification |
| 39 | CLK1BAD | Output | Alarm output reflecting the state of CLK1. LVCMOS/LVTTL interface levels. 0 = Input Clock 1 is switching within specifications 1 = Input Clock 1 is out of specification |
| 40 | XTALBAD | Output | Alarm output reflecting the state of XTAL. LVCMOS/LVTTL interface levels. 0 = crystal is switching within specifications 1 = crystal is out of specification |

NOTE: Pullup and Pulldown refer to internal input resistors. See Table 2, Pin Characteristics, for typical values.

Table 2. Pin Characteristics

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|-----------------------|-------------------------|-----------------|---------|---------|---------|-------|
| C _{IN} | Input Capacitance | | | 3.5 | | pF |
| R _{PULLUP} | Input Pullup Resistor | | | 51 | | kΩ |
| R _{PULLDOWN} | Input Pulldown Resistor | | | 51 | | kΩ |



Functional Description

The IDT8T49N203I is designed to provide two copies of almost any desired output frequency within its operating range (0.98 - 1300MHz) from any input source in the operating range (8kHz - 710MHz). It is capable of synthesizing frequencies from a crystal or crystal oscillator source. The output frequency is generated regardless of the relationship to the input frequency. The output frequency will be exactly the required frequency in most cases. In most others, it will only differ from the desired frequency by a few ppb. IDT configuration software will indicate the frequency error, if any. The IDT8T49N203I can translate the desired output frequency from one of two input clocks. Again, no relationship is required between the input and output frequencies in order to translate to the output clock rate. In this frequency translation mode, a low-bandwidth, jitter attenuation option is available that makes use of an external fixed-frequency crystal or crystal oscillator to translate from a noisy input source. If the input clock is known to be fairly clean or if some modulation on the input needs to be tracked, then the high-bandwidth frequency translation mode can be used, without the need for the external crystal.

The input clock references and crystal input are monitored continuously and appropriate alarm outputs are raised both as register bits and hard-wired pins in the event of any out-of-specification conditions arising. Clock switching is supported in manual, revertive & non-revertive modes.

The IDT8T49N203I has two factory-programmed configurations that may be chosen from as the default operating state after reset. This is intended to allow the same device to be used in two different applications without any need for access to the I²C registers. These defaults may be over-written by I²C register access at any time, but those over-written settings will be lost on power-down. Please contact IDT if a specific set of power-up default settings is desired.

Configuration Selection

The IDT8T49N203I comes with two factory-programmed default configurations. When the device comes out of power-up reset the selected configuration is loaded into operating registers. The IDT8T49N203I uses the state of the CONFIG pin or CONFIG register bit (controlled by the CFG_PIN_REG bit) to determine which configuration is active. When the output frequency is changed either via the CONFIG pin or via internal registers, the output behavior may not be predictable during the register writing and output settling periods. Devices sensitive to glitches or runt pulses may have to be reset once reconfiguration is complete.

Once the device is out of reset, the contents of the operating registers can be modified by write access from the l^2C serial port. Users that have a custom configuration programmed may not require l^2C access.

It is expected that the IDT8T49N203I will be used almost exclusively in a mode where the selected configuration will be used from device power-up without any changes during operation. For example, the device may be designed into a communications line card that supports different I/O modules such as a standard OC-12 module running at 622.08MHz or a (255/237) FEC rate OC-12 module running at 669.32MHz. The different I/O modules would result in a different level on the CONFIG pin which would select different divider

ratios within the IDT8T49N203I for the two different card configurations. Access via I²C would not be necessary for operation using either of the internal configurations.

Operating Modes

The IDT8T49N203I has three operating modes which are set by the MODE_SEL[1:0] bits. There are two frequency translator modes - low bandwidth and high bandwidth and a frequency synthesizer mode. The device will operate in the same mode regardless of which configuration is active.

Please make use of IDT-provided configuration applications to determine the best operating settings for the desired configurations of the device.

Output Dividers & Supported Output Frequencies

In all 3 operating modes, the output stage behaves the same way, but different operating frequencies can be specified in the two configurations.

The internal VCO is capable of operating in a range anywhere from 1.995GHz - 2.6GHz. It is necessary to choose an integer multiplier of the desired output frequency that results in a VCO operating frequency within that range. The output divider stage N[10:0] is limited to selection of integers from 2 to 2046. Please refer to Table 3 for the values of N applicable to the desired output frequency.

Table 3. Output Divider Settings & Frequency Ranges

| Register Setting | Frequency Divider | Minimum f _{OUT} | Maximum f _{OUT} |
|--|----------------------|-----------------------------|-----------------------------|
| Nn[10:0] | N | (MHz) | (MHz) |
| 000000000x | 2 | 997.5 | 1300 |
| 0000000010 | 2 | 997.5 | 1300 |
| 0000000011 | 3 | 665 | 866.7 |
| 0000000100 | 4 | 498.75 | 650 |
| 0000000101 | 5 | 399 | 520 |
| 000000011x | 6 | 332.5 | 433.3 |
| 000000100x | 8 | 249.4 | 325 |
| 000000101x | 10 | 199.5 | 260 |
| 0000000110x | 12 | 166.3 | 216.7 |
| 0000000111x | 14 | 142.5 | 185.7 |
| 0000001000x | 16 | 124.7 | 162.5 |
| 0000001001x | 18 | 110.8 | 144.4 |
| | Even N | 1995 / N | 2600 / N |
| 11111111111111111111111111111111111111 | 2046 | 0.98 | 1.27 |



Frequency Synthesizer Mode

This mode of operation allows an arbitrary output frequency to be generated from a fundamental mode crystal input. For improved phase noise performance, the crystal input frequency may be doubled. As can be seen from the block diagram in *Figure 1*, only the upper feedback loop is used in this mode of operation. It is recommended that CLK0 and CLK1 be left unused in this mode of operation.

The upper feedback loop supports a delta-sigma fractional feedback divider. This allows the VCO operating frequency to be a non-integer multiple of the crystal frequency. By using an integer multiple only, lower phase noise jitter on the output can be achieved, however the use of the delta-sigma divider logic will provide excellent performance on the output if a fractional divisor is used.

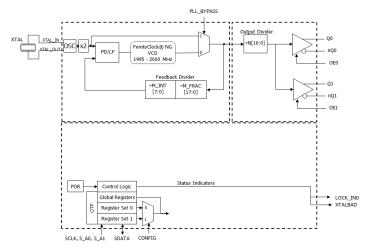


Figure 1. Frequency Synthesizer Mode Block Diagram

High-Bandwidth Frequency Translator Mode

This mode of operation is used to translate one of two input clocks of the same nominal frequency into an output frequency with little jitter attenuation. As can be seen from the block diagram in Figure 2, similarly to the Frequency Synthesizer mode, only the upper feedback loop is used.

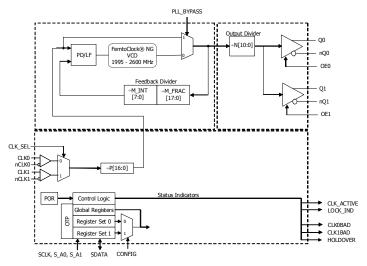


Figure 2. High Bandwidth Frequency Translator Mode Block Diagram

The input reference frequency range is now extended up to 710MHz. A pre-divider stage P is needed to keep the operating frequencies at the phase detector within limits.

Low-Bandwidth Frequency Translator Mode

As can be seen from the block diagram in Figure 3, this mode involves two PLL loops. The lower loop with the large integer dividers is the low bandwidth loop and it sets the output-to-input frequency translation ratio. This loop drives the upper DCXO loop (digitally controlled crystal oscillator) via an analog-digital converter.

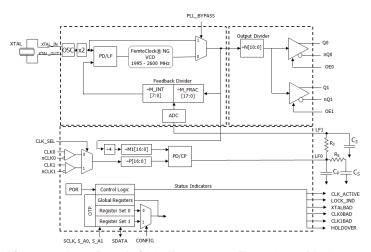


Figure 3. Low Bandwidth Frequency Translator Mode Block Diagram

The pre-divider stage is used to scale down the input frequency by an integer value to achieve a frequency in this range. By dividing down the fed-back VCO operating frequency by the integer divider M1[16:0] to as close as possible to the same frequency, exact output frequency translations can be achieved. The phase detector of the lower loop is designed to work with frequencies in the 8kHz - 16kHz range. For improved phase noise performance, the crystal input frequency may be doubled.

Alarm Conditions & Status Bits

The IDT8T49N203I monitors a number of conditions and reports their status via both output pins and register bits. All alarms will behave as indicated below in all modes of operation, but some of the conditions monitored have no valid meaning in some operating modes. For example, the status of CLK0BAD, CLK1BAD and CLK_ACTIVE are not relevant in Frequency Synthesizer mode. The outputs will still be active and it is left to the user to determine which to monitor and how to respond to them based on the known operating mode.

CLK_ACTIVE - indicates which input clock reference is being used to derive the output frequency.

LOCK_IND - This status is asserted on the pin & register bit when the PLL is locked to the appropriate input reference for the chosen mode of operation. The status bit will not assert until frequency lock has been achieved, but will de-assert once lock is lost.



XTALBAD - indicates if valid edges are being received on the crystal input. Detection is performed by comparing the input to the feedback signal at the upper loop's Phase / Frequency Detector (PFD). If three edges are received on the feedback without an edge on the crystal input, the XTALBAD alarm is asserted on the pin & register bit. Once an edge is detected on the crystal input, the alarm is immediately deasserted.

CLK0BAD - indicates if valid edges are being received on the CLK0 reference input. Detection is performed by comparing the input to the feedback signal at the appropriate Phase / Frequency Detector (PFD). When operating in high-bandwidth mode, the feedback at the upper PFD is used. In low-bandwidth mode, the feedback at the lower PFD is used. If three edges are received on the feedback without an edge on the divided down (÷P) CLK0 reference input, the CLK0BAD alarm is asserted on the pin & register bit. Once an edge is detected on the CLK0 reference input, the alarm is deasserted.

CLK1BAD - indicates if valid edges are being received on the CLK1 reference input. Behavior is as indicated for the CLK0BAD alarm, but with the CLK1 input being monitored and the CLK1BAD output pin & register bits being affected.

HOLDOVER - indicates that the device is not locked to a valid input reference clock. This can occur in Manual switchover mode if the selected reference input has gone bad, even if the other reference input is still good. In automatic mode, this will only assert if both input references are bad.

Input Reference Selection and Switching

When operating in Frequency Synthesizer mode, the CLK0 and CLK1 inputs are not used and the contents of this section do not apply. Except as noted below, when operating in either High or Low Bandwidth Frequency Translator mode, the contents of this section apply equally when in either of those modes.

Both input references CLK0 and CLK1 must be the same nominal frequency. These may be driven by any type of clock source, including crystal oscillator modules. A difference in frequency may cause the PLL to lose lock when switching between input references. Please contact IDT for the exact limits for your situation.

The global control bits AUTO_MAN[1:0] dictate the order of priority and switching mode to be used between the CLK0 and CLK1 inputs.

Manual Switching Mode

When the AUTO_MAN[1:0] field is set to Manual via Pin, then the IDT8T49N203I will use the CLK_SEL input pin to determine which input to use as a reference. Similarly, if set to Manual via Register, then the device will use the CLK_SEL register bit to determine the input reference. In either case, the PLL will lock to the selected reference if there is a valid clock present on that input.

If there is not a valid clock present on the selected input, the IDT8T49N203I will go into holdover (Low Bandwidth Frequency Translator mode) or free-run (High Bandwidth Frequency Translator

mode) state. In either case, the HOLDOVER alarm will be raised. This will occur even if there is a valid clock on the non-selected reference input. The device will recover from holdover / free-run state once a valid clock is re-established on the selected reference input.

The IDT8T49N203I will only switch input references on command from the user. The user must either change the CLK_SEL register bit (if in Manual via Register) or CLK_SEL input pin (if in Manual via Pin).

Automatic Switching Mode

When the AUTO_MAN[1:0] field is set to either of the automatic selection modes (Revertive or Non-Revertive), the IDT8T49N203I determines which input reference it prefers / starts from by the state of the CLK_SEL register bit only. The CLK_SEL input pin is not used in either Automatic switching mode.

When starting from an unlocked condition, the device will lock to the input reference indicated by the CLK_SEL register bit. It will not pay attention to the non-selected input reference until a locked state has been achieved. This is necessary to prevent 'hunting' behavior during the locking phase.

Once the IDT8T49N203I has achieved a stable lock, it will remain locked to the preferred input reference as long as there is a valid clock on it. If at some point, that clock fails, then the device will automatically switch to the other input reference as long as there is a valid clock there. If there is not a valid clock on either input reference, the IDT8T49N203I will go into holdover (Low Bandwidth Frequency Translator mode) or free-run (High Bandwidth Frequency Translator mode) state. In either case, the HOLDOVER alarm will be raised.

The device will recover from holdover / free-run state once a valid clock is re-established on either reference input. If clocks are valid on both input references, the device will choose the reference indicated by the CLK_SEL register bit.

If running from the non-preferred input reference and a valid clock returns, there is a difference in behavior between Revertive and Non-revertive modes. In Revertive mode, the device will switch back to the reference indicated by the CLK_SEL register bit even if there is still a valid clock on the non-preferred reference input. In Non-revertive mode, the IDT8T49N203I will not switch back as long as the non-preferred input reference still has a valid clock on it.

Switchover Behavior of the PLL

Even though the two input references have the same nominal frequency, there may be minor differences in frequency and potentially large differences in phase between them. The IDT8T49N203I will adjust its output to the new input reference. It will use Phase Slope Limiting to adjust the output phase at a fixed maximum rate until the output phase and frequency are now aligned to the new input reference. Phase will always be adjusted by extending the clock period of the output so that no unacceptably short clock periods are generated on the output IDT8T49N203I.



Holdover / Free-run Behavior

When both input references have failed (Automatic mode) or the selected input has failed (Manual mode), the IDT8T49N203I will enter holdover (Low Bandwidth Frequency Translator mode) or free-run (High Bandwidth Frequency Translator mode) state . In both cases, once the input reference is lost, the PLL will stop making adjustments to the output phase.

If operating in Low Bandwidth Frequency Translation mode, the PLL will continue to reference itself to the local oscillator and will hold its output phase and frequency in relation to that source. Output stability is determined by the stability of the local oscillator in this case.

However, if operating in High Bandwidth Frequency Translation mode, the PLL no longer has any frequency reference to use and output stability is now determined by the stability of the internal VCO.

If the device is programmed to perform Manual switching, once the selected input reference recovers, the IDT8T49N203I will switch back to that input reference. If programmed for either Automatic mode, the device will switch back to whichever input reference has a valid clock first.

The switchover that results from returning from holdover or free-run is handled in the same way as a switch between two valid input references as described in the previous section.

Output Configuration

The two outputs of the IDT8T49N203I both provide the same clock frequency. Both must operate from the same output voltage level of 3.3V or 2.5V, although this output voltage may be less than or equal to the core voltage (3.3V or 2.5V) the rest of the device is operating from. The output voltage level used on the two outputs is supplied on the $V_{\rm CCO}$ pin.

The two outputs are individually selectable as LVDS or LVPECL output types via the Q0_TYPE and Q1_TYPE register bits. These two selection bits are provided in each configuration to allow different output type settings under each configuration.

The two outputs can be enabled individually also via both register control bits and input pins. When both the OEn register bit and OEn pin are enabled, then the appropriate output is enabled. The OEn register bits default to enabled so that by default the outputs can be directly controlled by the input pins. Similarly, the input pins are provisioned with weak pull-ups so that if they are left unconnected, the output state can be directly controlled by the register bits. When the differential output is in the disabled state, it will show a high impedance condition.

Serial Interface Configuration Description

The IDT8T49N203I has an I²C-compatible configuration interface to access any of the internal registers (Table 4D) for frequency and PLL parameter programming. The IDT8T49N203I acts as a slave device on the I²C bus and has the address 0b11011xx, where xx is set by the values on the S_A0 & S_A1 pins (see Table 4A for details). The interface accepts byte-oriented block write and block read operations. An address byte (P) specifies the register address (Table 4D) as the byte position of the first register to write or read. Data bytes (registers) are accessed in sequential order from the lowest to the highest byte (most significant bit first, see table 4B, 4C). Read and write block transfers can be stopped after any complete byte transfer. It is recommended to terminate I²C the read or write transfer after accessing byte #23.

For full electrical ${}^{12}\text{C}$ compliance, it is recommended to use external pull-up resistors for SDATA and SCLK. The internal pull-up resistors have a size of $50\text{k}\Omega$ typical.

Note: if a different device slave address is desired, please contact IDT.

Table 4A. I²C Device Slave Address

| 1 1 0 1 | 1 | S_A1 | S_A0 | R/W |
|---------|---|------|------|-----|
|---------|---|------|------|-----|

Table 4B. Block Write Operation

| Bit | 1 | 2:8 | 9 | 10 | 11:18 | 19 | 20:27 | 28 | 29-36 | 37 | ••• | | |
|---------------|-------|------------------|-------|-----|---------------------|-----|------------------|-----|--------------------|-----|-----------|-----|------|
| Description | START | Slave Address | W (0) | ACK | Address Byte (P) | ACK | Data Byte (P) | ACK | Data Byte (P+1) | ACK | Data Byte | ACK | STOP |
| Length (bits) | 1 | 7 | 1 | 1 | 8 | 1 | 8 | 1 | 8 | 1 | 8 | 1 | 1 |

Table 4C. Block Read Operation

| Bit | 1 | 2:8 | 9 | 10 | 11:18 | 19 | 20 | 21:27 | 28 | 29 | 30:37 | 38 | 39-46 | 47 | | | |
|---------------|-------|------------------|----------|-------------|---------------------|-------------|--------------------|------------------|----------|-------------|------------------|-------------|--------------------|-------------|-----------|-------------|------|
| Description | START | Slave Address | W (0) | A C K | Address Byte (P) | A C K | Repeate d START | Slave Address | R (1) | A C K | Data Byte (P) | A C K | Data Byte (P+1) | A C K | Data Byte | A C K | STOP |
| Length (bits) | 1 | 7 | 1 | 1 | 8 | 1 | 1 | 7 | 1 | 1 | 8 | 1 | 8 | 1 | 8 | 1 | 1 |



Register Descriptions

Please consult IDT for configuration software and/or programming guides to assist in selection of optimal register settings for the desired configurations.

Table 4D. I²C Register Map

| | Binary | | Register Bit | | | | | | | | | | |
|-----|---------------------|-------------|--------------|-------------|-------------|-------------|-------------|------------|------------|--|--|--|--|
| Reg | Register Address | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | | | |
| 0 | 00000 | MFRAC0[17] | MFRAC0[16] | MFRAC0[15] | MFRAC0[14] | MFRAC0[13] | MFRAC0[12] | MFRAC0[11] | MFRAC0[10] | | | | |
| 1 | 00001 | MFRAC1[17] | MFRAC1[16] | MFRAC1[15] | MFRAC1[14] | MFRAC1[13] | MFRAC1[12] | MFRAC1[11] | MFRAC1[10] | | | | |
| 2 | 00010 | MFRAC0[9] | MFRAC0[8] | MFRAC0[7] | MFRAC0[6] | MFRAC0[5] | MFRAC0[4] | MFRAC0[3] | MFRAC0[2] | | | | |
| 3 | 00011 | MFRAC1[9] | MFRAC1[8] | MFRAC1[7] | MFRAC1[6] | MFRAC1[5] | MFRAC1[4] | MFRAC1[3] | MFRAC1[2] | | | | |
| 4 | 00100 | MFRAC0[1] | MFRAC0[0] | MINT0[7] | MINT0[6] | MINT0[5] | MINT0[4] | MINT0[3] | MINT0[2] | | | | |
| 5 | 00101 | MFRAC1[1] | MFRAC1[0] | MINT1[7] | MINT1[6] | MINT1[5] | MINT1[4] | MINT1[3] | MINT1[2] | | | | |
| 6 | 00110 | MINT0[1] | MINTO[0] | P0[16] | P0[15] | P0[14] | P0[13] | P0[12] | P0[11] | | | | |
| 7 | 00111 | MINT1[1] | MINT1[0] | P1[16] | P1[15] | P1[14] | P1[13] | P1[12] | P1[11] | | | | |
| 8 | 01000 | P0[10] | P0[9] | P0[8] | P0[7] | P0[6] | P0[5] | P0[4] | P0[3] | | | | |
| 9 | 01001 | P1[10] | P1[9] | P1[8] | P1[7] | P1[6] | P1[5] | P1[4] | P1[3] | | | | |
| 10 | 01010 | P0[2] | P0[1] | P0[0] | M1_0[16] | M1_0[15] | M1_0[14] | M1_0[13] | M1_0[12] | | | | |
| 11 | 01011 | P1[2] | P1[1] | P1[0] | M1_1[16] | M1_1[15] | M1_1[14] | M1_1[13] | M1_1[12] | | | | |
| 12 | 01100 | M1_0[11] | M1_0[10] | M1_0[9] | M1_0[8] | M1_0[7] | M1_0[6] | M1_0[5] | M1_0[4] | | | | |
| 13 | 01101 | M1_1[11] | M1_1[10] | M1_1[9] | M1_1[8] | M1_1[7] | M1_1[6] | M1_1[5] | M1_1[4] | | | | |
| 14 | 01110 | M1_0[3] | M1_0[2] | M1_0[1] | M1_0[0] | N0[10] | N0[9] | N0[8] | N0[7] | | | | |
| 15 | 01111 | M1_1[3] | M1_1[2] | M1_1[1] | M1_1[0] | N1[10] | N1[9] | N1[8] | N1[7] | | | | |
| 16 | 10000 | N0[6] | N0[5] | N0[4] | N0[3] | N0[2] | N0[1] | N0[0] | BW0[6] | | | | |
| 17 | 10001 | N1[6] | N1[5] | N1[4] | N1[3] | N1[2] | N1[1] | N1[0] | BW1[6] | | | | |
| 18 | 10010 | BW0[5] | BW0[4] | BW0[3] | BW0[2] | BW0[1] | BW0[0] | Q1_TYPE0 | Q0_TYPE0 | | | | |
| 19 | 10011 | BW1[5] | BW1[4] | BW1[3] | BW1[2] | BW1[1] | BW1[0] | Q1_TYPE1 | Q0_TYPE1 | | | | |
| 20 | 10100 | MODE_SEL[1] | MODE_SEL[0] | CONFIG | CFG_PIN_REG | OE1 | OE0 | Rsvd | Rsvd | | | | |
| 21 | 10101 | CLK_SEL | AUTO_MAN[1] | AUTO_MAN[0] | 0 | ADC_RATE[1] | ADC_RATE[0] | LCK_WIN[1] | LCK_WIN[0] | | | | |
| 22 | 10110 | 1 | 0 | 1 | 0 | DBL_XTAL | 0 | 0 | 0 | | | | |
| 23 | 10111 | CLK_ACTIVE | HOLDOVER | CLK1BAD | CLK0BAD | XTAL_BAD | LOCK_IND | Rsvd | Rsvd | | | | |

Register Bit Color Key

| Configuration 0 Specific Bits |
|-------------------------------|
| Configuration 1 Specific Bits |
| Global Control & Status Bits |



The register bits described in Table 4E are duplicated, with one set applying for Configuration 0 and the other for Configuration 1. The functions of the bits are identical, but only apply when the

configuration they apply to is enabled. Replace the lowercase n in the bit field description with 0 or 1 to find the field's location in the bitmap in Table 4D.

Table 4E. Configuration-Specific Control Bits

| Register Bits | Function |
|---------------|--|
| Q0_TYPEn | Determines the output type for output pair Q0, nQ0 for Configuration n. 0 = LVPECL 1 = LVDS |
| Q1_TYPEn | Determines the output type for output pair Q1, nQ1 for Configuration n. 0 = LVPECL 1 = LVDS |
| Pn[16:0] | Reference Pre-Divider for Configuration n. |
| M1_n[16:0] | Integer Feedback Divider in Lower Feedback Loop for Configuration n. |
| M_INTn[7:0] | Feedback Divider, Integer Value in Upper Feedback Loop for Configuration n. |
| M_FRACn[17:0] | Feedback Divider, Fractional Value in Upper Feedback Loop for Configuration n. |
| Nn[10:0] | Output Divider for Configuration n. |
| BWn[6:0] | Internal Operation Settings for Configuration n. Please use IDT IDT8T49N203I Configuration Software to determine the correct settings for these bits for the specific configuration. Alternatively, please consult with IDT directly for further information on the functions of these bits. The function of these bits are explained in Tables 4J and 4K. |

Table 4F. Global Control Bits

| Register Bits | Function |
|---------------|---|
| MODE_SEL[1:0] | PLL Mode Select 00 = Low Bandwidth Frequency Translator 01 = Frequency Synthesizer 10 = High Bandwidth Frequency Translator 11 = High Bandwidth Frequency Translator |
| CFG_PIN_REG | Configuration Control. Selects whether the configuration selection function is under pin or register control. 0 = Pin Control 1 = Register Control |
| CONFIG | Configuration Selection. Selects whether the device uses the register configuration set 0 or 1. This bit only has an effect when the CONFIG_PIN_REG bit is set to 1 to enable register control. |
| OE0 | Output Enable Control for Output 0. Both this register bit and the corresponding Output Enable pin OE0 must be asserted to enable the Q0, nQ0 output. 0 = Output Q0, nQ0 disabled 1 = Output Q0, nQ0 under control of the OE0 pin |
| OE1 | Output Enable Control for Output 1. Both this register bit and the corresponding Output Enable pin OE1 must be asserted to enable the Q1, nQ1 output. 0 = Output Q1, nQ1 disabled 1 = Output Q1, nQ1 under control of the OE1 pin |
| Rsvd | Reserved bits - user should write a '0' to these bit positions if a write to these registers is needed |
| AUTO_MAN[1:0] | Selects how input clock selection is performed. 00 = Manual Selection via pin only 01 = Automatic, non-revertive 10 = Automatic, revertive 11 = Manual Selection via register only |
| CLK_SEL | In manual clock selection via register mode, this bit will command which input clock is selected. In the automatic modes, this indicates the primary clock input. In manual selection via pin mode, this bit has no effect. 0 = CLK0 1 = CLK1 |



| ADC_RATE[1:0] | Sets the ADC sampling rate in Low-Bandwidth Mode as a fraction of the crystal input frequency. 00 = Crystal Frequency / 16 01 = Crystal Frequency / 8 10 = Crystal Frequency / 4 (recommended) 11 = Crystal Frequency / 2 |
|---------------|---|
| LCK_WIN[1:0] | Sets the width of the window in which a new reference edge must fall relative to the feedback edge: 00 = 2usec (recommended), 01 = 4usec, 10 = 8usec, 11 = 16usec |
| DBL_XTAL | When set, this bit will double the frequency of the crystal input before applying it to the Phase_Frequency Detector. |

Table 4G. Global Status Bits

| Register Bits | Function |
|---------------|---|
| CLK0BAD | Status Bit for input clock 0. This function is mirrored in the CLK0BAD pin. 0 = input CLK0 is good 1 = input CLK0 is bad. Self clears when input clock returns to good status |
| CLK1BAD | Status Bit for input clock 1. This function is mirrored in the CLK1BAD pin. 0 = input CLK1 is good 1 = input CLK1 is bad. Self clears when input clock returns to good status |
| XTALBAD | Status Bit. This function is mirrored on the XTALBAD pin. 0 = crystal input good 1 = crystal input bad. Self-clears when the XTAL clock returns to good status |
| LOCK_IND | Status bit. This function is mirrored on the LOCK_IND pin. 0 = PLL unlocked 1 = PLL locked |
| HOLDOVER | Status Bit. This function is mirrored on the HOLDOVER pin. 0 = Input to phase detector is within specifications and device is tracking to it 1 = Phase detector input is not within specifications and DCXO is frozen at last value |
| CLK_ACTIVE | Status Bit. Indicates which input clock is active. Automatically updates during fail-over switching. Status also indicated on CLK_ACTIVE pin. |



Table 4J. BW[6:0] Bits

| Mode | BW[6] | BW[5] | BW[4] | BW[3] | BW[2] | BW[1] | BW[0] |
|---------------------|-------------|-------------|-------------|-------------|------------|------------|--------------|
| Synthesizer Mode | PLL2_LF[1] | PLL2_LF[0] | DSM_ORD | DSM_EN | PLL2_CP[1] | PLL2_CP[0] | PLL2_LOW_ICP |
| High-Bandwidth Mode | PLL2_LF[1] | PLL2_LF[0] | DSM_ORD | DSM_EN | PLL2_CP[1] | PLL2_CP[0] | PLL2_LOW_ICP |
| Low-Bandwidth Mode | ADC_GAIN[3] | ADC_GAIN[2] | ADC_GAIN[1] | ADC_GAIN[0] | PLL1_CP[1] | PLL1_CP[0] | PLL2_LOW_ICP |

Table 4K. Functions of Fields in BW[6:0]

| Register Bits | Function |
|---------------|---|
| PLL2_LF[1:0] | Sets loop filter values for upper loop PLL in Frequency Synthesizer & High-Bandwidth modes. Defaults to setting of 00 when in Low Bandwidth Mode. See Table 4L for settings. |
| DSM_ORD | Sets Delta-Sigma Modulation to 2nd (0) or 3rd order (1) operation |
| DSM_EN | Enables Delta-Sigma Modulator 0 = Disabled - feedback in integer mode only 1 = Enabled - feedback in fractional mode |
| PLL2_CP[1:0] | Upper loop PLL charge pump current settings: $00 = 173 \mu A \text{ (defaults to this setting in Low Bandwidth Mode)} $ $01 = 346 \mu A $ $10 = 692 \mu A $ $11 = reserved$ |
| PLL2_LOW_ICP | Reduces Charge Pump current by 1/3 to reduce bandwidth variations resulting from higher feedback register settings or high VCO operating frequency (>2.4GHz). |
| ADC_GAIN[3:0] | Gain setting for ADC in Low Bandwidth Mode. |
| PLL1_CP[1:0] | Lower loop PLL charge pump current settings (lower loop is only used in Low Bandwidth Mode): $00=800\mu A$ $01=400\mu A$ $10=200\mu A$ $11=100\mu A$ |

Table 4L. High Bandwidth Frequency and Frequency Synthesizer Bandwidth Settings

| Desired Bandwidth | PLL2_CP | PLL2_LOW_ICP | PLL2_LF | | | | | | |
|-------------------|----------------------------|----------------------|---------|--|--|--|--|--|--|
| | Frequency Synthesizer Mode | | | | | | | | |
| 200kHz | 200kHz 00 1 00 | | | | | | | | |
| 400kHz | 01 | 1 | 01 | | | | | | |
| 800kHz | 10 | 1 | 10 | | | | | | |
| 2MHz | 10 | 1 | 11 | | | | | | |
| High | Bandwidth Freque | ency Translator Mode | | | | | | | |
| 200kHz | 00 | 1 | 00 | | | | | | |
| 400kHz | 01 | 1 | 01 | | | | | | |
| 800kHz | 10 | 1 | 10 | | | | | | |
| 4MHz | 10 | 0 | 11 | | | | | | |

NOTE: To achieve 4MHz bandwidth, reference to the phase detector should be 80MHz.



Absolute Maximum Ratings

NOTE: Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These ratings are stress specifications only. Functional operation of product at these conditions or any conditions beyond those listed in the *DC Characteristics* or *AC Characteristics* is not implied. Exposure to absolute maximum rating conditions for extended periods may affect product reliability.

| Item | Rating |
|--|----------------------------------|
| Supply Voltage, V _{CC} | 3.63V |
| Inputs, V _I | |
| XTAL_IN | 0V to 2V |
| Other Inputs | -0.5V to V _{CC} + 0.5V |
| Outputs, V _O (LVCMOS) | -0.5V to V _{CCO} + 0.5V |
| Outputs, I _O (LVPECL) | |
| Continuous Current | 50mA |
| Surge Current | 100mA |
| Outputs, I _O (LVDS) | |
| Continuous Current | 10mA |
| Surge Current | 15mA |
| Package Thermal Impedance, θ_{JA} | 32.4°C/W (0 mps) |
| Storage Temperature, T _{STG} | -65°C to 150°C |

DC Electrical Characteristics

Table 5A. LVPECL Power Supply DC Characteristics, $V_{CC} = V_{CCO} = 3.3V \pm 5\%$, $V_{EE} = 0V$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|-----------------------|-----------------|------------------------|---------|-----------------|-------|
| V _{CC} | Core Supply Voltage | | 3.135 | 3.3 | 3.465 | V |
| V _{CCA} | Analog Supply Voltage | | V _{CC} - 0.30 | 3.3 | V _{CC} | V |
| V _{CCO} | Output Supply Voltage | | 3.135 | 3.3 | 3.465 | V |
| I _{EE} | Power Supply Current | | | | 332 | mA |
| I _{CCA} | Analog Supply Current | | | | 30 | mA |

Table 5B. LVPECL Power Supply DC Characteristics, $V_{CC} = 3.3V \pm 5\%$, $V_{CCO} = 2.5V \pm 5\%$, $V_{EE} = 0V$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

| | • • • | , 33 | | | , , | |
|------------------|-----------------------|-----------------|------------------------|---------|-----------------|-------|
| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
| V _{CC} | Core Supply Voltage | | 3.135 | 3.3 | 3.465 | V |
| V _{CCA} | Analog Supply Voltage | | V _{CC} - 0.30 | 3.3 | V _{CC} | V |
| V _{CCO} | Output Supply Voltage | | 2.375 | 2.5 | 2.625 | V |
| I _{EE} | Power Supply Current | | | | 332 | mA |
| I _{CCA} | Analog Supply Current | | | | 30 | mA |



$\textbf{Table 5C. LVPECL Power Supply DC Characteristics}, \ V_{CC} = V_{CCO} = 2.5V \pm 5\%, \ V_{EE} = 0V, \ T_A = -40^{\circ}C \ to \ 85^{\circ}C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|-----------------------|-----------------|------------------------|---------|-----------------|-------|
| V _{CC} | Core Supply Voltage | | 2.375 | 2.5 | 2.625 | V |
| V _{CCA} | Analog Supply Voltage | | V _{CC} - 0.26 | 2.5 | V _{CC} | V |
| V _{CCO} | Output Supply Voltage | | 2.375 | 2.5 | 2.625 | V |
| I _{EE} | Power Supply Current | | | | 319 | mA |
| I _{CCA} | Analog Supply Current | | | | 26 | mA |

Table 5D. LVDS Power Supply DC Characteristics, $V_{CC} = V_{CCO} = 3.3V \pm 5\%, \ T_A = -40 ^{\circ} C$ to $85 ^{\circ} C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|-----------------------|-----------------|------------------------|---------|-----------------|-------|
| V _{CC} | Core Supply Voltage | | 3.135 | 3.3 | 3.465 | V |
| V _{CCA} | Analog Supply Voltage | | V _{CC} - 0.30 | 3.3 | V _{CC} | V |
| V _{CCO} | Output Supply Voltage | | 3.135 | 3.3 | 3.465 | V |
| I _{CC} | Power Supply Current | | | | 284 | mA |
| I _{CCA} | Analog Supply Current | | | | 30 | mA |
| I _{CCO} | Output Supply Current | | | | 40 | mA |

Table 5E. LVDS Power Supply DC Characteristics, $V_{CC} = V_{CCO} = 2.5V \pm 5\%$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|-----------------------|-----------------|------------------------|---------|-----------------|-------|
| V _{CC} | Core Supply Voltage | | 2.375 | 2.5 | 2.625 | V |
| V _{CCA} | Analog Supply Voltage | | V _{CC} - 0.26 | 2.5 | V _{CC} | V |
| V _{CCO} | Output Supply Voltage | | 2.375 | 2.5 | 2.625 | V |
| I _{CC} | Power Supply Current | | | | 275 | mA |
| I _{CCA} | Analog Supply Current | | | | 26 | mA |
| I _{CCO} | Output Supply Current | | | | 40 | mA |



Table 5F. LVCMOS/LVTTL DC Characteristics, $T_A = -40^{\circ} C$ to $85^{\circ} C$

| Symbol | Parameter | | Test Conditions | Minimum | Typical | Maximum | Units |
|-----------------|------------------------|--|--|---------|---------|--|-------|
| | Input Lligh Volt | togo | V _{CC} = 3.3V | 2 | | V _{CC} + 0.3 | V |
| VIH | Input High Volt | lage | V _{CC} = 2.5V | 1.7 | | | V |
| V | Input Low Volta | 200 | V _{CC} = 3.3V | -0.3 | | 0.8 | V |
| VIH I VIL I IIH | input Low Voite | aye | V _{CC} = 2.5V | -0.3 | | 0.7 | V |
| I _{IH} | Input | CLK_SEL, CONFIG, PLL_BYPASS, S_A[0:1] | V _{CC} = V _{IN} = 3.465V or 2.625V | | | 150 | μA |
| ΊΗ | High Current | OE0, OE1, SCLK, SDATA | V _{CC} = V _{IN} = 3.465V or 2.625V | | | V _{CC} + 0.3 V _{CC} + 0.3 0.8 0.7 150 5 | μA |
| | Input | CLK_SEL, CONFIG, PLL_BYPASS, S_A[0:1] | $V_{CC} = 3.465V \text{ or } 2.625V,$ $V_{IN} = 0V$ | -5 | | | μA |
| 'IL | Low Current | OE0, OE1, SCLK, SDATA | $V_{CC} = 3.465V \text{ or } 2.625V,$ $V_{IN} = 0V$ | -150 | | | μA |
| | | HOLDOVER, SDATA | $V_{CC} = 3.3V \pm 5\%, I_{OH} = -8mA$ | 2.6 | | | V |
| V _{OH} | Output High Voltage | CLK_ACTIVE, LOCK_IND, XTALBAD, CLK0BAD, CLK1BAD | $V_{CC} = 2.5V \pm 5\%, I_{OH} = -8mA$ | 1.8 | | | ٧ |
| V _{OL} | Output Low Voltage | HOLDOVER, SDATA CLK_ACTIVE, LOCK_IND, XTALBAD, CLK0BAD, CLK1BAD | $V_{CC} = 3.3V \pm 5\%$ or 2.5V ± 5%, $I_{OL} = 8mA$ | | | 0.5 | V |

 $\textbf{Table 5G. Differential DC Characteristics, } V_{CC} = V_{CCO} = 3.3V \pm 5\% \text{ or } 2.5V \pm 5\%, V_{EE} = 0V, T_A = -40^{\circ}C \text{ to } 85^{\circ}C$

| Symbol | Parameter | | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|--------------------------|-----------------------------|--|-----------------------|---------|-----------------------|-------|
| I _{IH} | Input High Current | CLK0, nCLK0, CLK1, nCLK1 | V _{CC} = V _{IN} = 3.465V or 2.625V | | | 150 | μΑ |
| I _{IL} | Input | CLK0, CLK1 | $V_{CC} = 3.465V \text{ or } 2.625V, V_{IN} = 0V$ | -5 | | | μA |
| "- | Low Current | nCLK0, nCLK1 | $V_{CC} = 3.465V \text{ or } 2.625V, V_{IN} = 0V$ | -150 | | | μΑ |
| V_{PP} | Peak-to-Peak V | oltage; Note 1 | | 0.15 | | 1.3 | V |
| V _{CMR} | Common Mode NOTE 1, 2 | Input Voltage; | | V _{EE} + 0.5 | | V _{CC} - 1.0 | V |

NOTE 1: $V_{\rm IL}$ should not be less than -0.3v. NOTE 2: Common mode input voltage is defined as the crosspoint.

Table 5H. LVPECL DC Characteristics, $V_{CC} = V_{CCO} = 3.3V \pm 5\%, \ V_{EE} = 0V, \ T_A = -40^{\circ}C$ to $85^{\circ}C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|--------------------|-----------------------------------|-----------------|------------------------|---------|------------------------|-------|
| V _{OH} | Output High Voltage; NOTE 1 | | V _{CCO} – 1.1 | | V _{CCO} – 0.7 | V |
| V _{OL} | Output Low Voltage NOTE 1 | | V _{CCO} - 2.0 | | V _{CCO} – 1.5 | V |
| V _{SWING} | Peak-to-Peak Output Voltage Swing | | 0.6 | | 1.0 | V |

NOTE 1: Outputs terminated with 50Ω to $\mbox{V}_{\mbox{CCO}}$ – 2V.



 $\textbf{Table 5I. LVPECL DC Characteristics}, \ V_{CC} = 3.3V \pm 5\% \ or \ 2.5V \pm 5\%, \ V_{CCO} = 2.5V \pm 5\%, \ V_{EE} = 0V, \ T_A = -40^{\circ}C \ to \ 85^{\circ}C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|--------------------|-----------------------------------|-----------------|------------------------|---------|------------------------|-------|
| V _{OH} | Output High Voltage; NOTE 1 | | V _{CCO} - 1.1 | | V _{CCO} - 0.8 | V |
| V _{OL} | Output Low Voltage NOTE 1 | | V _{CCO} - 2.0 | | V _{CCO} – 1.5 | V |
| V _{SWING} | Peak-to-Peak Output Voltage Swing | | 0.6 | | 1.0 | V |

NOTE 1: Outputs terminated with 50Ω to $V_{\mbox{\footnotesize{CCO}}}$ – 2V.

Table 5J. LVDS DC Characteristics, V_{CC} = V_{CCO} = 3.3V \pm 5%, T_A = -40°C to 85°C

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|----------------------------------|-----------------|---------|---------|---------|-------|
| V _{OD} | Differential Output Voltage | | 247 | | 454 | mV |
| ΔV_{OD} | V _{OD} Magnitude Change | | | | 50 | mV |
| V _{OS} | Offset Voltage | | 1.125 | | 1.375 | V |
| ΔV _{OS} | V _{OS} Magnitude Change | | | | 50 | mV |

Table 5K. LVDS DC Characteristics, $V_{CC} = V_{CCO} = 2.5V \pm 5\%$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

| Symbol | Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------|----------------------------------|-----------------|---------|---------|---------|-------|
| V _{OD} | Differential Output Voltage | | 247 | | 454 | mV |
| ΔV_{OD} | V _{OD} Magnitude Change | | | | 50 | mV |
| V _{OS} | Offset Voltage | | 1.125 | | 1.375 | V |
| ΔV _{OS} | V _{OS} Magnitude Change | | | | 50 | mV |

Table 6. Input Frequency Characteristics, $V_{CC} = V_{CCO} = 3.3V \pm 5\%$, $T_A = -40^{\circ}C$ to $85^{\circ}C$

| Symbol | Parameter | | Test Conditions | Minimum | Typical | Maximum | Units |
|-----------------|-----------|-----------------------------|---------------------|---------|---------|---------|-------|
| | | XTAL_IN, XTAL_OUT NOTE 1 | | 16 | | 40 | MHz |
| f _{IN} | Input | · CIKO NCIKO | High Bandwidth Mode | 16 | | 710 | MHz |
| | Frequency | Frequency CLK1, nCLK1 | Low Bandwidth Mode | 0.008 | | 710 | MHz |
| | | SCLK | | | | 5 | MHz |

NOTE 1: For the input crystal and CLKx, nCLKx frequency range, the M value must be set for the VCO to operate within the 1995MHz to 2600MHz range.

Table 7. Crystal Characteristics

| Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
|------------------------------------|-----------------|---------|---------|---------|-------|
| Mode of Oscillation Fundamental | | ıl | | | |
| Frequency | | 16 | | 40 | MHz |
| Equivalent Series Resistance (ESR) | | | | 100 | Ω |
| Shunt Capacitance | | | | 7 | pF |
| Load Capacitance (CL) | | | 12 | | pF |



AC Electrical Characteristics

Table 8. AC Characteristics, $V_{CC} = V_{CCO} = 3.3V \pm 5\%$ or $2.5V \pm 5\%$, or $V_{CC} = 3.3V \pm 5\%$, $V_{CCO} = 2.5V \pm 5\%$ (LVPECL Only), $V_{EE} = 0V$, $T_A = -40$ °C to 85°C

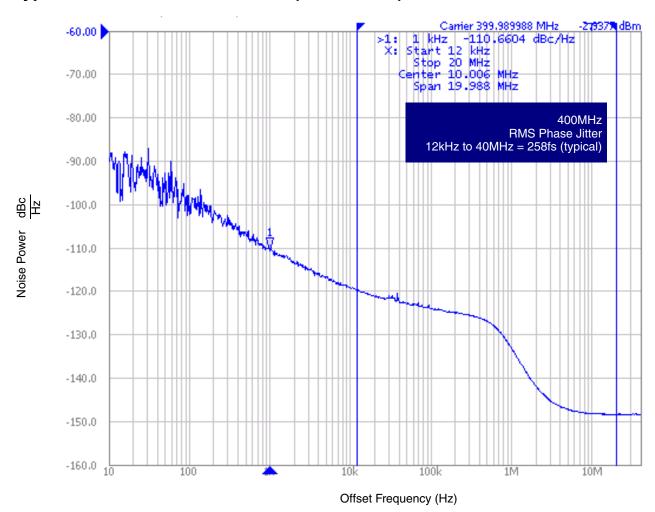
| Symbol | Parameter | | Test Conditions | Minimum | Typical | Maximum | Units |
|---------------------------------|--------------------------------------|----------------|---|---------|---------|---------|-------|
| f _{OUT} | Output Frequence | у | | 0.98 | | 1300 | MHz |
| | | | Synth Mode (Integer FB), f _{OUT} = 400MHz, 40MHz XTAL, Integration Range: 12kHz – 40MHz | | 285 | 446 | fs |
| | | | Synth Mode (FracN FB), f _{OUT} = 698.81MHz, 40MHz XTAL, Integration Range: 12kHz – 20MHz | | 363 | 521 | fs |
| fjit(∅) | RMS Phase Jitte Integer Divide Ra | • | HBW Mode, (NOTE 1) f _{IN} = 133.33MHz, f _{OUT} = 400MHz, Integration Range: 12kHz – 20MHz | | 313 | 490 | fs |
| | Integer Divide Hatio | | LBW Mode (FracN), 40MHz XTAL, f _{IN} = 19.44MHz, f _{OUT} = 155.52MHz, Integration Range: 12kHz – 20MHz (LVDS Output) | | 439 | 670 | fs |
| | | | LBW Mode (FracN), 40MHz XTAL, f _{IN} = 25MHz, f _{OUT} = 161.1328125MHz, Integration Range: 12kHz – 20MHz (LVDS Output) | | 450 | 670 | fs |
| r:./ \ | DMO D : 1 1:11 | NOTE 5 | LVPECL Outputs | | 2.2 | 5.3 | ps |
| tjit(per) | RMS Period Jitte | r NOTE 5 | LVDS Output | | 5.1 | 8.7 | ps |
| £:4/a-a\ | Cycle to Cycle II | How NOTE O | Frequency Synthesizer Mode | | | 30 | ps |
| tjit(cc) | Cycle-to-Cycle J | itter; NOTE 2 | Frequency Translator Mode | | | 40 | ps |
| tsk(o) | Output Skew; NO | OTE 2, 3 | | | | 42 | ps |
| + /+ | Output | LVPECL Outputs | 20% to 80% | 100 | | 520 | ps |
| t _R / t _F | Rise/Fall Time | LVDS Outputs | 20% to 80% | 80 | | 520 | ps |
| odc | lc Output Duty Cycle | | f _{OUT} < 600MHz | 45 | | 55 | % |
| Juc | Julput Duty Cyc | ı c | f _{OUT} ≥ 600MHz | 40 | | 60 | % |
| t _{SET} | Output Re-configuration Settling | | from falling edge of the 8th SCLK for a register change | | 200 | | ns |
| | Time | | from edge on CONFIG pin | | 10 | | ns |

NOTE: Electrical parameters are guaranteed over the specified ambient operating temperature range, which is established when the device is mounted in a test socket with maintained transverse airflow greater than 500 lfpm. The device will meet specifications after thermal equilibrium has been reached under these conditions.

- NOTE 1: Measured using a Rohde & Schwarz SMA100 Signal Generator, 9kHz to 6GHz as the input source.
- NOTE 2: This parameter is defined in accordance with JEDEC Standard 65.
- NOTE 3: Defined as skew between outputs at the same supply voltage and with equal load conditions. Measured at the output differential cross points.
- NOTE 4: RMS Phase Jitter are measured with DBL_XTAL bit set to 1 and crystal CL = 12pf.
- NOTE 5: This parameter is defined in accordance with Jedec Standard 65.

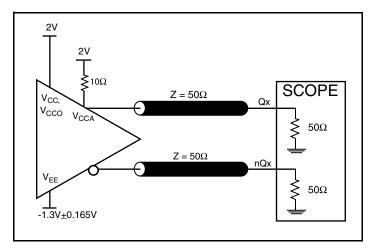


Typical Phase Noise at 400MHz (HBW Mode)

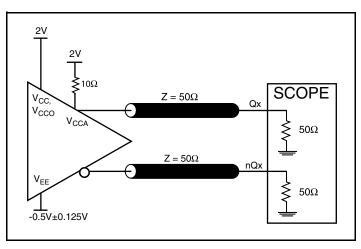




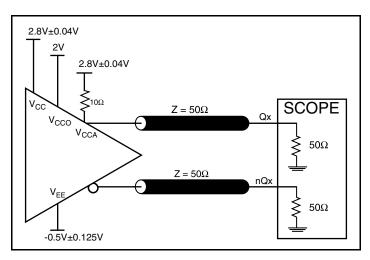
Parameter Measurement Information



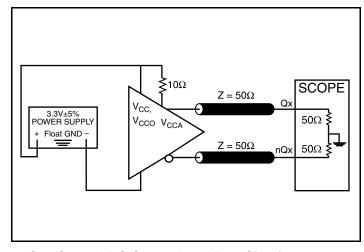
3.3 Core/3.3V LVPECL Output Load Test Circuit



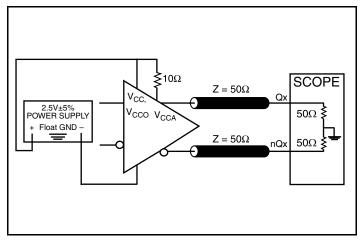
2.5 Core/2.5V LVPECL Output Load Test Circuit



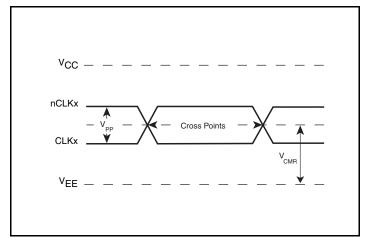
3.3 Core/2.5V LVPECL Output Load Test Circuit



3.3 Core/3.3V LVDS Output Load Test Circuit

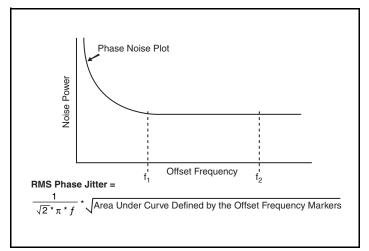


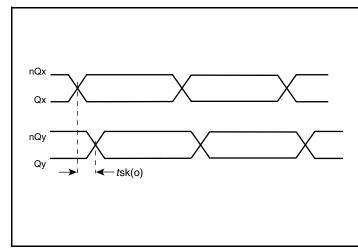
2.5 Core/2.5V LVDS Output Load Test Circuit



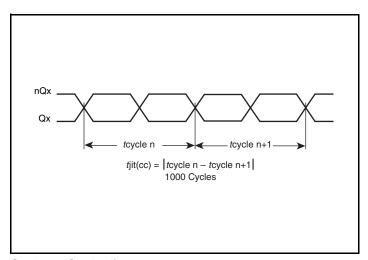
Differential Input Levels

Parameter Measurement Information, continued

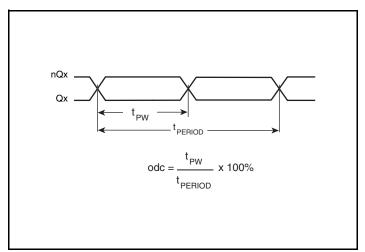




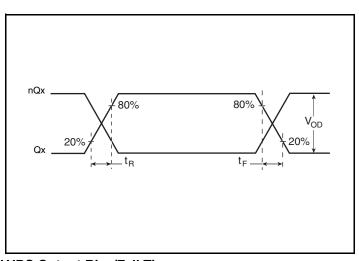
RMS Phase Jitter



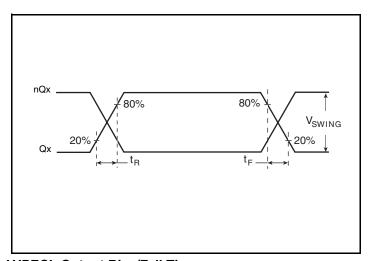
Output Skew



Cycle-to-Cycle Jitter



Differential Output Duty Cycle/Output Pulse Width/Period



LVDS Output Rise/Fall Time

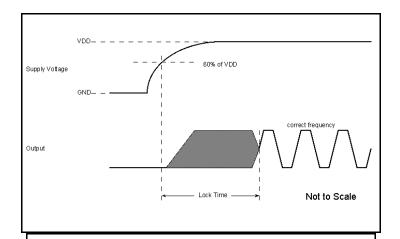
LVPECL Output Rise/Fall Time

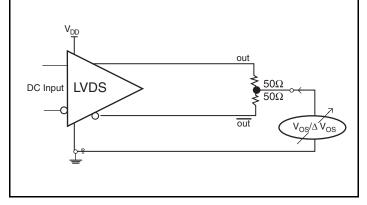


Parameter Measurement Information, continued

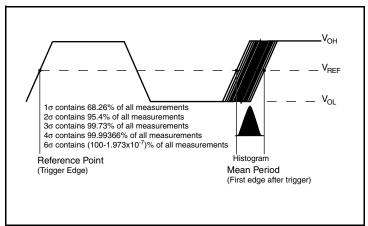
DC Input LVDS \$100Ω V_{OD}/ΔV_{OD}

Differential Output Voltage Setup





Offset Voltage Setup



Period Jitter



Applications Information

Recommendations for Unused Input and Output Pins

Inputs:

Crystal Inputs

For applications not requiring the use of the crystal oscillator input, both XTAL_IN and XTAL_OUT can be left floating. Though not required, but for additional protection, a $1k\Omega$ resistor can be tied from XTAL_IN to ground.

CLKx/nCLKx Inputs

For applications not requiring the use of either differential input, both CLKx and nCLKx can be left floating. Though not required, but for additional protection, a $1k\Omega$ resistor can be tied from CLKx to ground. It is recommended that CLKx, nCLKx be left unconnected in frequency synthesizer mode.

LVCMOS Control Pins

All control pins have internal pullups or pulldowns; additional resistance is not required but can be added for additional protection. A $1k\Omega$ resistor can be used.

Outputs:

LVPECL Outputs

All unused LVPECL outputs can be left floating. We recommend that there is no trace attached. Both sides of the differential output pair should either be left floating or terminated.

LVDS Outputs

All unused LVDS output pairs can be either left floating or terminated with 100 Ω across. If they are left floating there should be no trace attached.

LVCMOS Outputs

All unused LVCMOS output can be left floating. There should be no trace attached.

Recommended Values for Low-Bandwidth Mode Loop Filter

External loop filter components are not needed in Frequency Synthesizer or High-Bandwidth modes. In Low-Bandwidth mode, the loop filter structure and components shown in *Figure 11* are recommended. Please consult IDT if other values are needed.



Wiring the Differential Input to Accept Single-Ended Levels

Figure 4 shows how a differential input can be wired to accept single ended levels. The reference voltage $V_{REF} = V_{CC}/2$ is generated by the bias resistors R1 and R2. The bypass capacitor (C1) is used to help filter noise on the DC bias. This bias circuit should be located as close to the input pin as possible. The ratio of R1 and R2 might need to be adjusted to position the V_{REF} in the center of the input voltage swing. For example, if the input clock swing is 2.5V and $V_{CC} = 3.3V$, R1 and R2 value should be adjusted to set V_{REF} at 1.25V. The values below are for when both the single ended swing and V_{CC} are at the same voltage. This configuration requires that the sum of the output impedance of the driver (Ro) and the series resistance (Rs) equals the transmission line impedance. In addition, matched termination at the input will attenuate the signal in half. This can be done in one of two ways. First, R3 and R4 in parallel should equal the transmission

line impedance. For most 50Ω applications, R3 and R4 can be 100Ω . The values of the resistors can be increased to reduce the loading for slower and weaker LVCMOS driver. When using single-ended signaling, the noise rejection benefits of differential signaling are reduced. Even though the differential input can handle full rail LVCMOS signaling, it is recommended that the amplitude be reduced. The datasheet specifies a lower differential amplitude, however this only applies to differential signals. For single-ended applications, the swing can be larger, however V_{IL} cannot be less than -0.3V and V_{IH} cannot be more than V_{CC} + 0.3V. Though some of the recommended components might not be used, the pads should be placed in the layout. They can be utilized for debugging purposes. The datasheet specifications are characterized and guaranteed by using a differential signal.

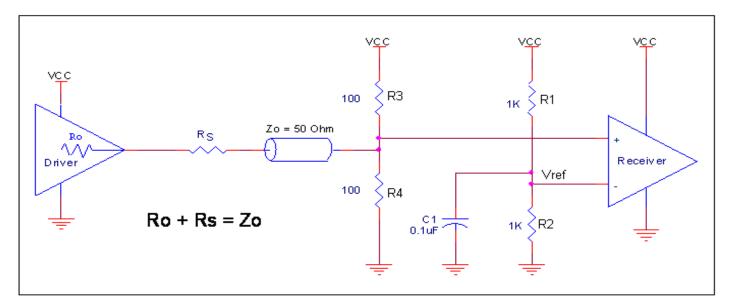


Figure 4. Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels



Overdriving the XTAL Interface

The XTAL_IN input can be overdriven by an LVCMOS driver or by one side of a differential driver through an AC coupling capacitor. The XTAL_OUT pin can be left floating. The amplitude of the input signal should be between 500mV and 1.8V and the slew rate should not be less than 0.2V/nS. For 3.3V LVCMOS inputs, the amplitude must be reduced from full swing to at least half the swing in order to prevent signal interference with the power rail and to reduce internal noise. *Figure 5A* shows an example of the interface diagram for a high speed 3.3V LVCMOS driver. This configuration requires that the sum of the output impedance of the driver (Ro) and the series resistance (Rs) equals the transmission line impedance. In addition, matched termination at the crystal input will attenuate the signal in half. This

can be done in one of two ways. First, R1 and R2 in parallel should equal the transmission line impedance. For most 50Ω applications, R1 and R2 can be 100Ω . This can also be accomplished by removing R1 and changing R2 to 50Ω . The values of the resistors can be increased to reduce the loading for a slower and weaker LVCMOS driver. Figure 5B shows an example of the interface diagram for an LVPECL driver. This is a standard LVPECL termination with one side of the driver feeding the XTAL_IN input. It is recommended that all components in the schematics be placed in the layout. Though some components might not be used, they can be utilized for debugging purposes. The datasheet specifications are characterized and quaranteed by using a quartz crystal as the input.

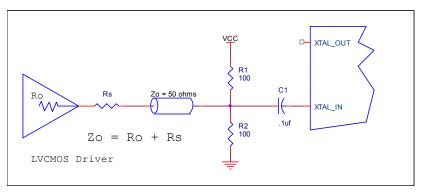


Figure 5A. General Diagram for LVCMOS Driver to XTAL Input Interface

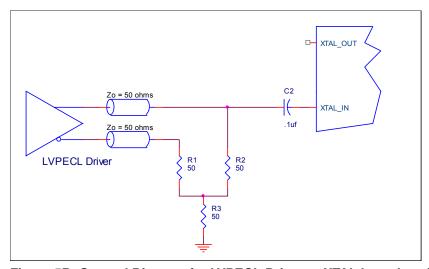


Figure 5B. General Diagram for LVPECL Driver to XTAL Input Interface



Differential Clock Input Interface

The CLK /nCLK accepts LVDS, LVPECL, LVHSTL, HCSL and other differential signals. Both V_{SWING} and V_{OH} must meet the V_{PP} and V_{CMR} input requirements. Figures 6A to 6E show interface examples for the CLK/nCLK input driven by the most common driver types. The input interfaces suggested here are examples only. Please consult

with the vendor of the driver component to confirm the driver termination requirements. For example, in Figure 6A, the input termination applies for IDT open emitter LVHSTL drivers. If you are using an LVHSTL driver from another vendor, use their termination recommendation.

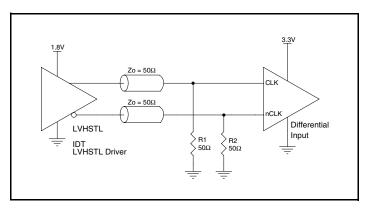


Figure 6A. CLK/nCLK Input

Driven by an IDT Open Emitter LVHSTL Driver

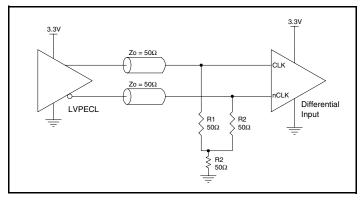


Figure 6B. CLK/nCLK Input
Driven by a 3.3V LVPECL Driver

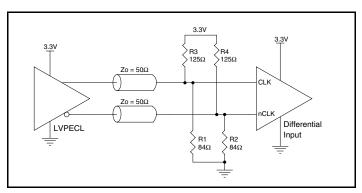


Figure 6C. CLK/nCLK Input
Driven by a 3.3V LVPECL Driver

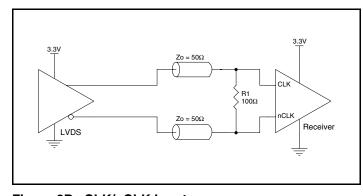


Figure 6D. CLK/nCLK Input
Driven by a 3.3V LVDS Driver

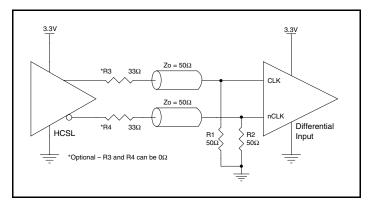


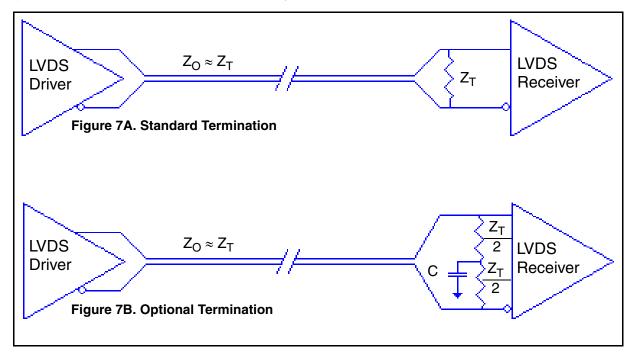
Figure 6E. CLK/nCLK Input
Driven by a 3.3V HCSL Driver



LVDS Driver Termination

For a general LVDS interface, the recommended value for the termination impedance (Z_T) is between 90Ω and 132Ω . The actual value should be selected to match the differential impedance (Z_0) of your transmission line. A typical point-to-point LVDS design uses a 100Ω parallel resistor at the receiver and a 100Ω differential transmission-line environment. In order to avoid any transmission-line reflection issues, the components should be surface mounted and must be placed as close to the receiver as possible. IDT offers a full line of LVDS compliant devices with two types of output structures: current source and voltage source. The

standard termination schematic as shown in *Figure 7A* can be used with either type of output structure. *Figure 7B*, which can also be used with both output types, is an optional termination with center tap capacitance to help filter common mode noise. The capacitor value should be approximately 50pF. If using a non-standard termination, it is recommended to contact IDT and confirm if the output structure is current source or voltage source type. In addition, since these outputs are LVDS compatible, the input receiver's amplitude and common-mode input range should be verified for compatibility with the output.





Termination for 3.3V LVPECL Outputs

The clock layout topology shown below is a typical termination for LVPECL outputs. The two different layouts mentioned are recommended only as guidelines.

The differential outputs are low impedance follower outputs that generate ECL/LVPECL compatible outputs. Therefore, terminating resistors (DC current path to ground) or current sources must be used for functionality. These outputs are designed to drive 50Ω

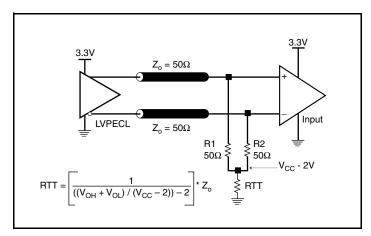


Figure 8A. 3.3V LVPECL Output Termination

transmission lines. Matched impedance techniques should be used to maximize operating frequency and minimize signal distortion. *Figures 8A and 8B* show two different layouts which are recommended only as guidelines. Other suitable clock layouts may exist and it would be recommended that the board designers simulate to guarantee compatibility across all printed circuit and clock component process variations.

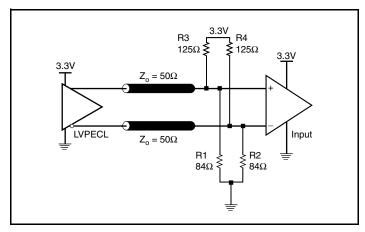


Figure 8B. 3.3V LVPECL Output Termination



Termination for 2.5V LVPECL Outputs

Figure 9A and Figure 9B show examples of termination for 2.5V LVPECL driver. These terminations are equivalent to terminating 50Ω to $V_{CCO}-2V$. For $V_{CCO}=2.5V$, the $V_{CCO}-2V$ is very close to ground

level. The R3 in Figure 9B can be eliminated and the termination is shown in *Figure 9C*.

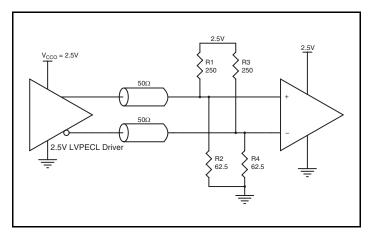


Figure 9A. 2.5V LVPECL Driver Termination Example

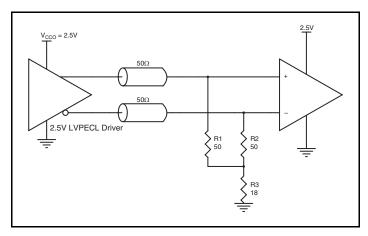


Figure 9B. 2.5V LVPECL Driver Termination Example

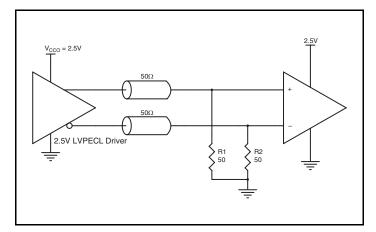


Figure 9C. 2.5V LVPECL Driver Termination Example



VFQFN EPAD Thermal Release Path

In order to maximize both the removal of heat from the package and the electrical performance, a land pattern must be incorporated on the Printed Circuit Board (PCB) within the footprint of the package corresponding to the exposed metal pad or exposed heat slug on the package, as shown in *Figure 10*. The solderable area on the PCB, as defined by the solder mask, should be at least the same size/shape as the exposed pad/slug area on the package to maximize the thermal/electrical performance. Sufficient clearance should be designed on the PCB between the outer edges of the land pattern and the inner edges of pad pattern for the leads to avoid any shorts.

While the land pattern on the PCB provides a means of heat transfer and electrical grounding from the package to the board through a solder joint, thermal vias are necessary to effectively conduct from the surface of the PCB to the ground plane(s). The land pattern must be connected to ground through these vias. The vias act as "heat pipes". The number of vias (i.e. "heat pipes") are application specific

and dependent upon the package power dissipation as well as electrical conductivity requirements. Thus, thermal and electrical analysis and/or testing are recommended to determine the minimum number needed. Maximum thermal and electrical performance is achieved when an array of vias is incorporated in the land pattern. It is recommended to use as many vias connected to ground as possible. It is also recommended that the via diameter should be 12 to 13mils (0.30 to 0.33mm) with 1oz copper via barrel plating. This is desirable to avoid any solder wicking inside the via during the soldering process which may result in voids in solder between the exposed pad/slug and the thermal land. Precautions should be taken to eliminate any solder voids between the exposed heat slug and the land pattern. Note: These recommendations are to be used as a guideline only. For further information, please refer to the Application Note on the Surface Mount Assembly of Amkor's Thermally/ Electrically Enhance Lead frame Base Package, Amkor Technology.

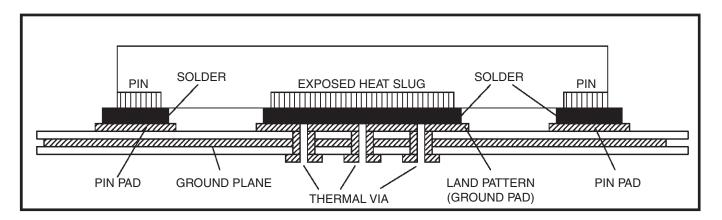


Figure 10. P.C. Assembly for Exposed Pad Thermal Release Path – Side View (drawing not to scale)



Schematic Layout

Figure 11 (next page), shows an example of the UFT (IDT8T49N203I) application schematic. Input and output terminations shown are intended as examples only and may not represent the exact user configuration. In this example, the device is operated at V_{CC} = 3.3V. For 2.5V option, please refer to the "Termination for 2.5V LVPECL Outputs" for output termination recommendation. The decoupling capacitors should be located as close as possible to the power pin. A 12pF parallel resonant 16MHz to 40MHz crystal is used in this example. Different crystal frequencies may be used. The C1 = C2 = 5pF are recommended for frequency accuracy. If different crystal types are used, please consult IDT for recommendations. For different board layout, the C1 and C2 may be slightly adjusted for optimizing frequency accuracy. It is recommended that the loop filter components be laid out for the 3-pole option. This will also allow either 2-pole or 3-pole filter to be used. The 3-pole filter can be used for additional spur reduction. If a 2-pole filter construction is used, the LF0 and LF1 pins must be tied-together to the filter.

As with any high speed analog circuitry, the power supply pins are vulnerable to random noise. To achieve optimum jitter performance, power supply isolation is required. The UFT (IDT8T49N203I) provides separate power supplies to isolate any high switching noise from coupling into the internal PLL.

In order to achieve the best possible filtering, it is recommended that the placement of the filter components be on the device side of the PCB as close to the power pins as possible. If space is limited, the 0.1uf capacitor in each power pin filter should be placed on the device side. The other components can be on the opposite side of the PCB.

Power supply filter recommendations are a general guideline to be used for reducing external noise from coupling into the devices. The filter performance is designed for a wide range of noise frequencies. This low-pass filter starts to attenuate noise at approximately 10 kHz. If a specific frequency noise component is known, such as switching power supplies frequencies, it is recommended that component values be adjusted and if required, additional filtering be added. Additionally, good general design practices for power plane voltage stability suggests adding bulk capacitance in the local area of all devices.

The schematic example focuses on functional connections and is not configuration specific. Refer to the pin description and functional tables in the datasheet to ensure the logic control inputs are properly set



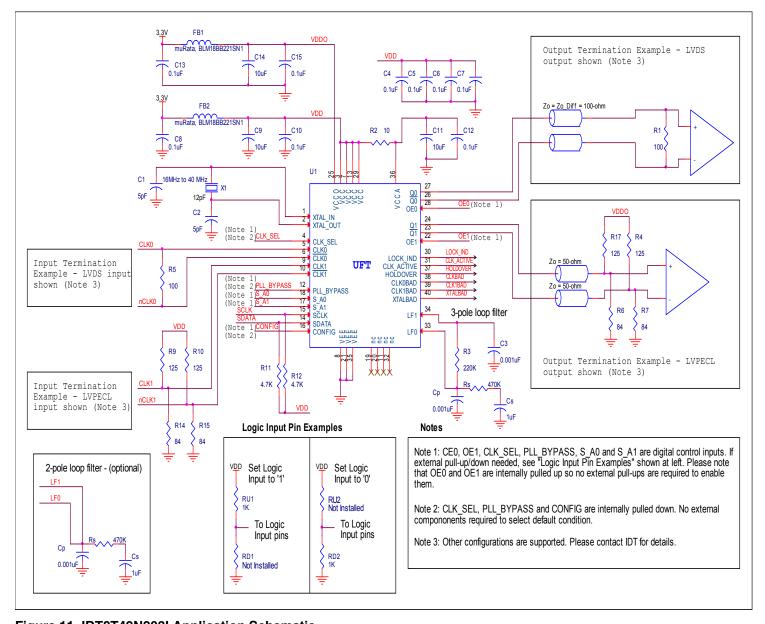


Figure 11. IDT8T49N203I Application Schematic



LVPECL Power Considerations

This section provides information on power dissipation and junction temperature for the IDT8T49N203I. Equations and example calculations are also provided.

1. Power Dissipation.

The total power dissipation for the IDT8T49N203I is the sum of the core power plus the power dissipated in the load(s).

The following is the power dissipation for $V_{CC} = 3.3V + 5\% = 3.465V$, which gives worst case results.

NOTE: Please refer to Section 3 for details on calculating power dissipated in the load.

- Power (core)_{MAX} = V_{CC MAX} * I_{EE MAX} = 3.465V * 332mA = 1150.4W
- Power (outputs)_{MAX} = 33.2mW/Loaded Output pair
 If all outputs are loaded, the total power is 2 * 33.2mW = 66.4mW

Total Power_MAX (3.465V, with all outputs switching) = 1150.4mW + 66.4mW = 1216.8mW

2. Junction Temperature.

Junction temperature, Tj, is the temperature at the junction of the bond wire and bond pad directly affects the reliability of the device. The maximum recommended junction temperature is 125°C. Limiting the internal transistor junction temperature, Tj, to 125°C ensures that the bond wire and bond pad temperature remains below 125°C.

The equation for Tj is as follows: Tj = θ_{JA} * Pd_total + T_A

Tj = Junction Temperature

 θ_{JA} = Junction-to-Ambient Thermal Resistance

Pd_total = Total Device Power Dissipation (example calculation is in section 1 above)

T_A = Ambient Temperature

In order to calculate junction temperature, the appropriate junction-to-ambient thermal resistance θ_{JA} must be used. Assuming no air flow and a multi-layer board, the appropriate value is 32.4°C/W per Table 9 below.

Therefore, Tj for an ambient temperature of 85°C with all outputs switching is:

$$85^{\circ}\text{C} + 1.127\text{W} * 32.4^{\circ}\text{C/W} = 124.4^{\circ}\text{C}$$
. This is below the limit of 125°C .

This calculation is only an example. Tj will obviously vary depending on the number of loaded outputs, supply voltage, air flow and the type of board (multi-layer).

Table 9. Thermal Resistance θ_{JA} for 40 Lead VFQFN, Forced Convection

| θ_{JA} by Velocity | | | | | | | |
|---|----------|----------|----------|--|--|--|--|
| Meters per Second | 0 | 1 | 2.5 | | | | |
| Multi-Layer PCB, JEDEC Standard Test Boards | 32.4°C/W | 25.7°C/W | 23.4°C/W | | | | |



3. Calculations and Equations.

The purpose of this section is to calculate the power dissipation for the LVPECL output pairs.

LVPECL output driver circuit and termination are shown in Figure 12.

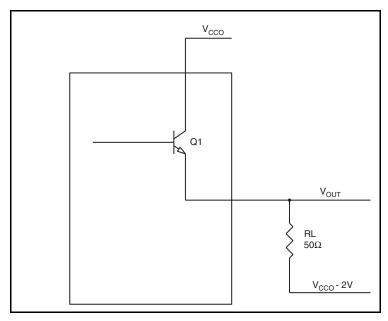


Figure 12. LVPECL Driver Circuit and Termination

To calculate worst case power dissipation into the load, use the following equations which assume a 50Ω load, and a termination voltage of $V_{CCO} - 2V$.

- For logic high, $V_{OUT} = V_{OH_MAX} = V_{CCO_MAX} 0.7V$ $(V_{CCO_MAX} - V_{OH_MAX}) = 0.7V$
- For logic low, $V_{OUT} = V_{OL_MAX} = V_{CCO_MAX} 1.5V$ $(V_{CCO_MAX} V_{OL_MAX}) = 1.5V$

Pd_H is power dissipation when the output drives high.

Pd_L is the power dissipation when the output drives low.

$$Pd_H = [(V_{OH_MAX} - (V_{CCO_MAX} - 2V))/R_L] * (V_{CCO_MAX} - V_{OH_MAX}) = [(2V - (V_{CCO_MAX} - V_{OH_MAX}))/R_L] * (V_{CCO_MAX} - V_{OH_MAX}) = [(2V - 0.7V)/50\Omega] * 0.7V = \textbf{18.2mW}$$

$$Pd_L = [(V_{OL_MAX} - (V_{CCO_MAX} - 2V))/R_L] * (V_{CCO_MAX} - V_{OL_MAX}) = [(2V - (V_{CCO_MAX} - V_{OL_MAX}))/R_L] * (V_{CCO_MAX} - V_{OL_MAX}) = [(2V - 1.5V)/50\Omega] * 1.5V = 15mW$$

Total Power Dissipation per output pair = Pd_H + Pd_L = 33.2mW



LVDS Power Considerations

This section provides information on power dissipation and junction temperature for the IDT8T49N203I. Equations and example calculations are also provided.

1. Power Dissipation.

The total power dissipation for the IDT8T49N203I is the sum of the core power plus the power dissipated in the load(s).

The following is the power dissipation for $V_{CC} = 3.3V + 5\% = 3.465V$, which gives worst case results.

NOTE: Please refer to Section 3 for details on calculating power dissipated in the load.

- Power (core)_{MAX} = $V_{CC\ MAX}$ * ($I_{CC\ MAX}$ + $I_{CCA\ MAX}$) = 3.465V * (284mA + 30mA) = **1088.01mW**
- Power (outputs)_{MAX} = $V_{CCO_MAX} * I_{CCO_MAX} = 3.465V * 40mA = 138.6mW$

Total Power $_{MAX} = 1088.01 \text{mW} + 138.6 \text{mW} = 1226.61 \text{mW}$

2. Junction Temperature.

Junction temperature, Tj, is the temperature at the junction of the bond wire and bond pad directly affects the reliability of the device. The maximum recommended junction temperature is 125°C. Limiting the internal transistor junction temperature, Tj, to 125°C ensures that the bond wire and bond pad temperature remains below 125°C.

The equation for Tj is as follows: Tj = θ_{JA} * Pd_total + T_A

Tj = Junction Temperature

 θ_{JA} = Junction-to-Ambient Thermal Resistance

Pd_total = Total Device Power Dissipation (example calculation is in section 1 above)

T_A = Ambient Temperature

In order to calculate junction temperature, the appropriate junction-to-ambient thermal resistance θ_{JA} must be used. Assuming no air flow and a multi-layer board, the appropriate value is 32.4°C/W per Table 10 below.

Therefore, Tj for an ambient temperature of 85°C with all outputs switching is:

 85° C + 1.227W * 32.4°C/W = 124.8°C. This is below the limit of 125°C.

This calculation is only an example. Tj will obviously vary depending on the number of loaded outputs, supply voltage, air flow and the type of board (multi-layer).

Table 10. Thermal Resistance θ_{JA} for 40 Lead VFQFN, Forced Convection

| θ_{JA} by Velocity | | | | | | | |
|---|----------|----------|----------|--|--|--|--|
| Meters per Second | 0 | 1 | 2.5 | | | | |
| Multi-Layer PCB, JEDEC Standard Test Boards | 32.4°C/W | 25.7°C/W | 23.4°C/W | | | | |



Reliability Information

Table 11. θ_{JA} vs. Air Flow Table for a 40 Lead VFQFN

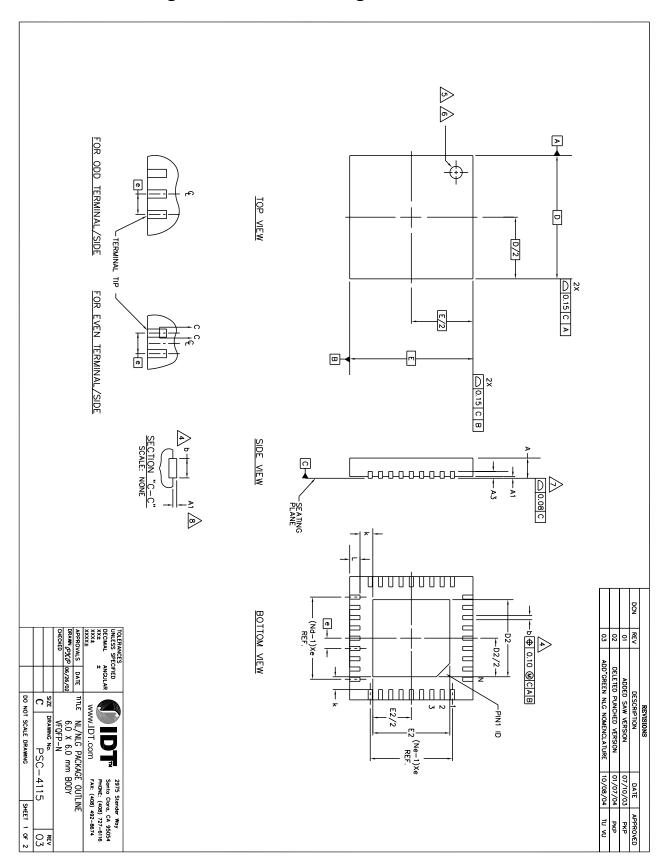
| θ_{JA} vs. Air Flow | | | | | | | |
|---|----------|----------|----------|--|--|--|--|
| Meters per Second | 0 | 1 | 2.5 | | | | |
| Multi-Layer PCB, JEDEC Standard Test Boards | 32.4°C/W | 25.7°C/W | 23.4°C/W | | | | |

Transistor Count

The transistor count for IDT8T49N203I is: 50,917



40 Lead VFQFN Package Outline and Package Dimensions





40 Lead VFQFN Package Outline and Package Dimensions, continued

| 10. DIMENSIONS D2 & E2 VARY DEPENDING ON DEVICE, SUPPLIER, ETC. 40 Lead VFQFN, D2/E2 EPAD Dimensions: 4.65mm x 4.65mm | THE PIN #1 IDENTIFIER MUST EXIST ON THE TOP SURFACE OF THE PACKAGE BY USING INDENTATION MARK OR OTHER FEATURE OF PACKAGE BODY. ABY USING INDENTATION MARK OR OTHER FEATURE OF PACKAGE BODY. ABY USING INDENTATION MARK OR OTHER FEATURE OF PACKAGE BODY. APPLIED TO EXPOSED PAD AND TERMINALS. EXCLUDE EMBEDDED PART OF EXPOSED PAD FROM MEASURING. APPLIED ONLY FOR TERMINALS. THIS OUTLINES CONFORMS TO JEDEC PUBLICATION 95 REGISTRATION MO-220, VARIATION VJJC-3 & VJJD-5 MTH THE EXCEPTION OF D2 & E2. | NOTES: 1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M. — 1994. 2. N IS THE NUMBER OF TERMINALS. No IS THE NUMBER OF TERMINALS IN X-DIRECTION & No IS THE NUMBER OF TERMINALS IN Y-DIRECTION. 3. ALL DIMENSIONS ARE IN MILLIMETERS. ADDIMENSION & APPLIES TO PLATED TERMINAL AND IS MEASURED BETWEEN 0.20 AND 0.30mm FROM TERMINAL TIP. | V JEDEC VARIATION VJJC-3 V VEDEC VARIATION VJJD-5 V V V V V V V V V | |
|---|--|--|---|-----------|
| TOLERANCES | | | DCN | REVISIONS |



Ordering Information

Table 12. Ordering Information

| Part/Order Number | Marking | Package | Shipping Packaging | Temperature |
|--------------------|----------------------|---------------------------|--------------------|----------------|
| 8T49N203A-dddNLGI | IDT8T49N203A-dddNLGI | "Lead-Free" 40 Lead VFQFN | Tray | -40°C to +85°C |
| 8T49N203A-dddNLGI8 | IDT8T49N203A-dddNLGI | "Lead-Free" 40 Lead VFQFN | Tape & Reel | -40°C to +85°C |

NOTE: For the specific -ddd order codes, refer to FemtoClock NG Universal Frequency Translator Ordering Product Information document.



Revision History Sheet

| Rev | Table | Page | Description of Change | Date |
|-----|-----------|---------------|--|-----------|
| Α | T12 | 38 | Ordering Information Table - deleted quantity from tape & reel. | 5/29/2012 |
| В | T8 | 17 | Per Errata #NEN-12-02, AC Characteristics Table - corrected fourth row test condition of RMS Phase Jitter LBW Mode from f_{IN} - 25MHz to f_{IN} - 19.44MHz. | 8/10/2012 |
| С | T5A - T5E | 13 - 14 34 | Per Errata #NEN-12-07, Power Supply Tables - changed V _{CCA} min. specs and I _{CCA} max specs. LVDS Power Considerations - updated calculations to correspond to I _{CCA} spec. | 10/9/2012 |



IMPORTANT NOTICE AND DISCLAIMER

RENESAS ELECTRONICS CORPORATION AND ITS SUBSIDIARIES ("RENESAS") PROVIDES TECHNICAL SPECIFICATIONS AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING, WITHOUT LIMITATION, ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for developers skilled in the art designing with Renesas products. You are solely responsible for (1) selecting the appropriate products for your application, (2) designing, validating, and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. Renesas grants you permission to use these resources only for development of an application that uses Renesas products. Other reproduction or use of these resources is strictly prohibited. No license is granted to any other Renesas intellectual property or to any third party intellectual property. Renesas disclaims responsibility for, and you will fully indemnify Renesas and its representatives against, any claims, damages, costs, losses, or liabilities arising out of your use of these resources. Renesas' products are provided only subject to Renesas' Terms and Conditions of Sale or other applicable terms agreed to in writing. No use of any Renesas resources expands or otherwise alters any applicable warranties or warranty disclaimers for these products.

(Rev.1.0 Mar 2020)

Corporate Headquarters

TOYOSU FORESIA, 3-2-24 Toyosu, Koto-ku, Tokyo 135-0061, Japan www.renesas.com

Trademarks

Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.

Contact Information

For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit:

www.renesas.com/contact/

X-ON Electronics

Largest Supplier of Electrical and Electronic Components

Click to view similar products for Clock Generators & Support Products category:

Click to view products by Renesas manufacturer:

Other Similar products are found below:

CV183-2TPAG 950810CGLF 9DBV0741AKILF 9VRS4420DKLF CY25404ZXI226 CY25422SXI-004 MPC9893AE NB3H515001MNTXG PL602-20-K52TC ICS557GI-03LF PI6LC48P0101LIE 82P33814ANLG 840021AGLF ZL30244LFG7 PI6LC48C21LE
ZL30245LFG7 PI6LC48P0405LIE PI6LC48P03LE MAX24505EXG+ ZL30163GDG2 5L1503L-000NVGI8 ZL30673LFG7
MAX24188ETK2 ZL30152GGG2 5L1503-000NVGI8 PI6C557-01BZHIEX PI6LC48C21LIE CY2542QC002 5P35023-106NLGI
5X1503L-000NLGI8 ZL30121GGG2V2 ZL30282LDG1 ZL30102QDG1 ZL30159GGG2 DS1070K ZL30145GGG2 ZL30312GKG2
MAX24405EXG2 ZL30237GGG2 SY100EL34LZG 9FGV1002BQ506LTGI AD9518-4ABCPZ MX852BB0030 PI6LC4840ZHE AD95160BCPZ-REEL7 AD9574BCPZ-REEL7 PL602-21TC-R ZL30105QDG1 ZL30100QDG1 ZL30142GGG2