DATASHEET

General Description

The 9DMV0431 is a member of IDT's SOC-Friendly 1.8V Very-Low-Power (VLP) PCIe Gen1-2-3 family. Each of the 4 outputs has its own dedicated OE# pin for optimal system control and power management. The part provides asynchronous and glitch-free switching modes.

Recommended Application

2:4 PCIe Gen1-2-3 clock multiplexer

Output Features

• 4 -Low-Power (LP) HCSL DIF pairs

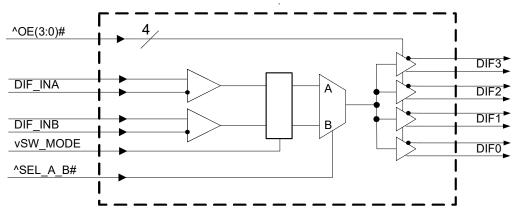
Key Specifications

- DIF additive cycle-to-cycle jitter <5ps
- DIF phase jitter is PCIe Gen1-2-3 compliant
- Additive phase jitter @ 125MHz: 420fs rms typical (12kHz to 20MHz)
- DIF output-to-output skew <50ps

Features/Benefits

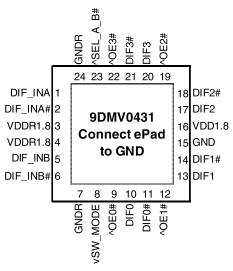
- LP-HCSL outputs; save 8 resistors compared to standard HCSL outputs
- 1.8V operation; 36mW typical power consumption
- Selectable asynchronous or glitch-free switching; allows the mux to be selected at power up even if both inputs are not running, then transition to glitch-free switching mode
- Spread Spectrum Compatible; supports EMI reduction
- OE# pins; support DIF power management
- HCSL differential inputs; can be driven by common clock sources
- 1MHz to 200MHz operating frequency
- Space saving 24-pin 4x4mm VFQFPN; minimal board space

Block Diagram



1

Pin Configuration



24 VFQFPN, 4x4 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor v prefix indicates internal 120KOhm pull down resistor

Power Management Table

OEx# Pin	DIF IN	DIFx				
OLX#1 III	Dii _iiv	True O/P	Comp. O/P			
0	Running	Running	Running			
1	Running	Low	Low			

Power Connections

Pin N	umber	Description
VDD	GND	Description
3	24	Input A receiver analog
4	7	Input B receiver analog
16	15	DIF outputs

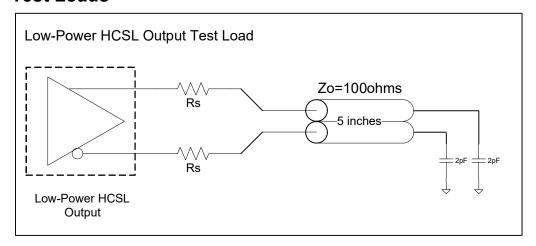
Pin Descriptions

Pin#	Pin Name	Type	Pin Description						
1	DIF_INA	IN	HCSL Differential True input						
2	DIF_INA#	IN	CSL Differential Complement Input						
3	VDDR1.8	PWR	1.8V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.						
4	VDDR1.8	PWR	1.8V power for differential input clock (receiver). This VDD should be treated as an Analog power rail and filtered appropriately.						
5	DIF_INB	IN	HCSL Differential True input						
6	DIF_INB#	IN	HCSL Differential Complement Input						
7	GNDR	GND	Analog Ground pin for the differential input (receiver)						
8	vSW_MODE	IN	Switch Mode. This pin selects either asynchronous or glitch-free switching of the mux. Use asynchronous mode if 0 or 1 of the input clocks is running. Use glitch-free mode if both input clocks are running. This pin has an internal pull down resistor of ~120kohms. 0 = asynchronous mode 1 = glitch-free mode						
9	^OE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs						
10	DIF0	OUT	Differential true clock output						
11	DIF0#	OUT	Differential Complementary clock output						
12	^OE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs						
13	DIF1	OUT	Differential true clock output						
14	DIF1#	OUT	Differential Complementary clock output						
15	GND	GND	round pin.						

Pin Descriptions (cont.)

Pin#	Pin Name	Type	Pin Description
16	VDD1.8	PWR	Power supply, nominal 1.8V
17	DIF2	OUT	Differential true clock output
18	DIF2#	OUT	Differential Complementary clock output
19 ^OE2# IN		IN	Active low input for enabling DIF pair 2. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs
20	DIF3	OUT	Differential true clock output
21	DIF3#	OUT	Differential Complementary clock output
22	^OE3#	IN	Active low input for enabling DIF pair 3. This pin has an internal pull-up resistor. 1 =disable outputs, 0 = enable outputs
23	^SEL_A_B#	IN	Input to select differential input clock A or differential input clock B. This input has an internal pull-up resistor. 0 = Input B selected, 1 = Input A selected.
24	GNDR	GND	Analog Ground pin for the differential input (receiver)
25	EPAD	GND	Connect to Ground.

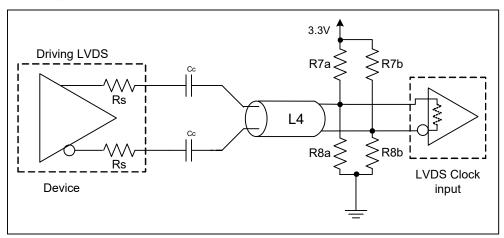
Test Loads



Alternate Differential Output Terminations

Rs	Zo	Units
33	100	Ohms
27	85	Offilis

Driving LVDS



Driving LVDS inputs

	,		
	Receiver has Receiver does not		
Component	termination	have termination	Note
R7a, R7b	10K ohm	140 ohm	
R8a, R8b	5.6K ohm	75 ohm	
Cc	0.1 uF	0.1 uF	
Vcm	1.2 volts	1.2 volts	

Electrical Characteristics-Absolute Maximum Ratings

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx		-0.5		2.5	V	1,2
Input Voltage	V_{IN}		-0.5		$V_{DD} + 0.5$	V	1,3
Input High Voltage, SMBus	V_{IHSMB}	SMBus clock and data pins			3.3	V	1
Storage Temperature	Ts		-65		150	°C	1
Junction Temperature	Tj				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2000			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Input/Supply/Common Parameters-Normal Operating Conditions

TA = T_{AMB.} Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx	Supply voltage for core and analog	1.7	1.8	1.9	V	
Ambient Operating Temperature	T _{AMB}	Industrial range	-40	25	85	°C	1
Input High Voltage	V_{IH}	Single-ended inputs, except SMBus	0.75 V _{DD}		$V_{DD} + 0.3$	V	
Input Low Voltage	V_{IL}	Single-ended inputs, except SMBus	-0.3		0.25 V _{DD}	V	
	I _{IN}	Single-ended inputs, $V_{IN} = GND$, $V_{IN} = VDD$	-5		5	uA	
Input Current Input Frequency	I _{INP}	Single-ended inputs $V_{IN} = 0 \text{ V}$; Inputs with internal pull-up resistors $V_{IN} = \text{VDD}$; Inputs with internal pull-down resistors	-200		200	uA	
Input Frequency	F _{in}		1		200	MHz	2
Pin Inductance	L_{pin}				7	nH	1
	C_{IN}	Logic Inputs, except DIF_IN	1.5		5	рF	1
Capacitance	C _{INDIF_IN}	DIF_IN differential clock inputs	1.5		2.7	рF	1,4
	C _{OUT}	Output pin capacitance			6	рF	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock			1	ms	1,2
Input SS Modulation Frequency PCIe	f _{MODINPCle}	Allowable Frequency for PCIe Applications (Triangular Modulation)	30		33	kHz	
Input SS Modulation Frequency non-PCle	f _{MODIN}	Allowable Frequency for non-PCle Applications (Triangular Modulation)	0		66	kHz	
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	capacitance o and after input clock of and after input clock of or PCle Applications of Modulation) or non-PCle Applications of Modulation) or OE# assertion oE# deassertion 6 pr 1 nn 1 n	clocks	1,3		
Tfall	t _F	Fall time of single-ended control inputs			5	ns	2
Trise	t _R	Rise time of single-ended control inputs			5	ns	2

¹Guaranteed by design and characterization, not 100% tested in production.

² Operation under these conditions is neither implied nor guaranteed.

³ Not to exceed 2.5V.

²Control input must be monotonic from 20% to 80% of input swing.

³Time from deassertion until outputs are >200 mV

⁴ DIF_IN input

Electrical Characteristics-Clock Input Parameters

TA = T_{AMB}. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

AND,		peramen community con recording con					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V _{IHDIF}	Differential inputs (single-ended measurement)	300	750	1150	mV	1
Input Low Voltage - DIF_IN	V_{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1
Input Common Mode Voltage - DIF_IN	V_{COM}	Common Mode Input Voltage	200		725	mV	1
Input Amplitude - DIF_IN	V_{SWING}	Peak to Peak value (V _{IHDIF} - V _{ILDIF})	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.35		8	V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45	50	55	%	1
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		150	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-DIF Low-Power HCSL Outputs

TA = T_{AMB} Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	dV/dt	Scope averaging on, fast setting	2.2	3.4	4.9	V/ns	1,2,3
Slew rate matching	∆dV/dt	Slew rate matching, Scope averaging on		3	20	%	1,2,4
Voltage High	V_{HIGH}	Statistical measurement on single-ended signal using oscilloscope math function. (Scope	660	789	850	mV	
Voltage Low	V_{LOW}	l	-150	38	150] ''' [
Max Voltage	Vmax	Measurement on single ended signal using		829	1150	mV	
Min Voltage	Vmin	absolute value. (Scope averaging off)	-300	-20] ''''	
Vswing	Vswing	Scope averaging off	300	1501		mV	1,2
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	419	550	mV	1,5
Crossing Voltage (var)	∆-Vcross	Scope averaging off		10	140	mV	1,6

¹Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Current Consumption

 $TA = T_{AMB}$, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Operating Supply Current	I _{DD}	VDD, All outputs active @100MHz		20	28	mA	1
Powerdown Current	I _{DDPD}	VDD, all outputs disabled		1.5	2.5	mA	1, 2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Slew rate measured through +/-75mV window centered around differential zero

² Measured from differential waveform

³ Slew rate is measured through the Vswing voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.

⁴ Matching applies to rising edge rate for Clock and falling edge rate for Clock#. It is measured using a +/-75mV window centered on the average cross point where Clock rising meets Clock# falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations.

⁵ Vcross is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).

⁶ The total variation of all Vcross measurements in any particular system. Note that this is a subset of Vcross_min/max (Vcross absolute) allowed. The intent is to limit Vcross induced modulation by setting Δ-Vcross to be smaller than Vcross absolute.

² Input clock stopped.

Electrical Characteristics-Output Duty Cycle, Jitter, Skew and PLL Characteristics

TA = T_{AMR} Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

-	ANID,							
	PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
	Duty Cycle Distortion	t _{DCD}	Measured differentially, Bypass Mode @100MHz	-1	-0.15	1	%	1,3
I	Skew, Input to Output	t _{pdBYP}	Bypass Mode, V _T = 50%	1819	2365	3075	ps	1
I	Skew, Output to Output	t _{sk3}	V _T = 50%		16	50	ps	1,4
	Jitter, Cycle to cycle	t _{jcyc-cyc}	Additive Jitter in Bypass Mode	·	0.1	5	ps	1,2

¹ Guaranteed by design and characterization, not 100% tested in production.

Electrical Characteristics-Phase Jitter Parameters

 $TA = T_{AMB}$, Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

						INDUSTRY		
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	LIMIT	UNITS	Notes
	t _{jphPCleG1}	PCle Gen 1		1.3	5	N/A	ps (p-p)	1,2,3,5
		PCIe Gen 2 Lo Band		0.1	0.3	N/A	ps	1,2,3,4,
		10kHz < f < 1.5MHz		0.1		IN/A	(rms)	5
		PCIe Gen 2 High Band		0.1		N/A	ps	1,2,3,4
		1.5MHz < f < Nyquist (50MHz)		0.1	0.2		(rms)	1,2,0,4
Additive Phase Jitter,		$t_{\text{jphPCleG3}}$ PCIe Gen 3 (PLL BW of 2-4 or 2-5MHz, CDR = 10MHz)		0.065	0.1	N/A	ps	1,2,3,4
Bypass Mode				0.000	0.1	1471	(rms)	1,2,0,4
		125MHz, 1.5MHz to 10MHz, -20dB/decade			300	N/A	fs	
	t _{jph125M0}			285			(rms)	1,6
	t _{iph125M1}	125MHz, 12KHz to 20MHz, -20dB/decade		420	450	N/A	fs	1,6
	*Jpn 125M1	rollover < 12kHz, -40db/decade rolloff > 20MHz				14//((rms)	.,0

¹Guaranteed by design and characterization, not 100% tested in production.

² Measured from differential waveform

³ Duty cycle distortion is the difference in duty cycle between the output and the input clock when the device is operated in bypass mode

⁴ All outputs at default slew rate

⁵ The MIN/TYP/MAX values of each BW setting track each other, i.e., Low BW MAX will never occur with Hi BW MIN.

² See http://www.pcisig.com for complete specs

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

⁴ For RMS figures, additive jitter is calculated by solving the following equation: Additive jitter = SQRT[(total jitter)^2 - (input jitter)^2]

⁵ Driven by 9FGU0831 or equivalent

⁶ Rohde&Schartz SMA100

Marking Diagram



Notes:

- 1. "LOT" denotes the lot number.
- 2. "YYWW" is the last two digits of the year and week that the part was assembled.
- 3. Line 2: truncated part number
- 4. "L" denotes RoHS compliant package.
- 5. "I" denotes industrial temperature grade.

Thermal Characteristics

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP VALUE	UNITS	NOTES
	θ_{JC}	Junction to Case		42	°C/W	1
Thermal Resistance	θ_{Jb}	Junction to Base	NLG24	2.4	°C/W	1
	θ_{JA0}	Junction to Air, still air		39	°C/W	1
	θ_{JA1}	Junction to Air, 1 m/s air flow		33	°C/W	1
	θ_{JA3}	Junction to Air, 3 m/s air flow		28	°C/W	1
	θ_{JA5}	Junction to Air, 5 m/s air flow		27	°C/W	1

¹ePad soldered to board

0.20 DIA

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ADD LAND PATTERN INITIAL RELEASE DESCRIPTION

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2X 0.10 C

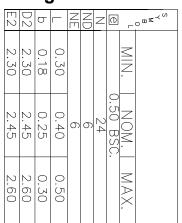
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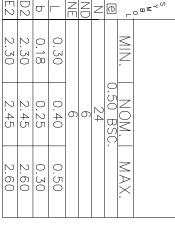
VIEW.

Package Outline and Package Dimensions (NLG24)

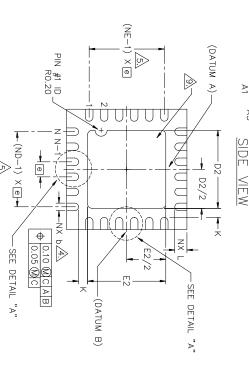
BOTTOM

VIEW





_	Ε	D	K	Φ	АЗ	Α1	Α	٥ ا	ω≤	≺ ⁽⁵⁾
O 15 mm MAX	4.0 BSC	4.0 BSC	0.20 MIN.	0 — 12	EF.	0.00 0.02 0.05	0.80 0.90 1.0	MIN. NOM. MAX.		
~									oz	



EVEN TERMINAL/SIDE DETAIL "A" DATUM A TERMINAL 유 Ħ <u>ODD</u> TERMINAL/SIDE

1. DIMENSIONING AND TOLERANCING CONFORME TO ASME Y14.5M - 2. ALL DIMENSIONS ARE IN MILLIMETERS, $\boldsymbol{\theta}$ IS IN DEGREES. 1994.

3. N IS THE TOTAL NUMBER OF TERMINALS.

ADDIMENSION B APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15 AND 0.30mm FROM TERMINAL TIP. IF THE TERMINAL THE OPTIONAL RADIUS ON THE OTHER END OF THE TERMINAL, THE DIMENSION B SHOULD NOT BE MEASURED IN THAT RADIUS AREA. S ND AND NE REFER TO THE NUMBER OF

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SEATING PLANE ○ 0.05 C

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TERMINALS ON EACH D AND

6. MAX. PACKAGE WARPAGE IS 0.05 mm.
7. MAXIMUM ALLOWABLE BURRS IS 0.076 mm.
8. PIN #1 ID ON TOP WILL BE LASER MARKED.

Z

ALL DIRECTIONS

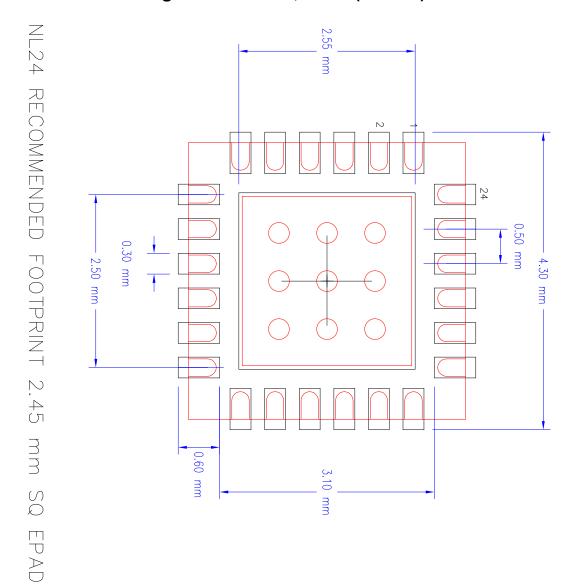
 $\angle 9$ bilateral coplanarity zone applies to the exposed heat sink SLUG AS WELL AS THE TERMINALS.

10. THIS DRAWING CONFORMES TO JEDEC REGISTERED OUTLINE MO-220

AD DEPENDING ON THE METHOD OF LEAD TERMINATION AT THE EDGE OF THE PACKAGE, PULLBACK DESIGN OPTION IS FOR 0.50mm NOMINAL LANDLENGTH ONLY. PULLBACK (L1) MAYBE PRESENT

DRAWN RAC DECIMAL TOLERANCES
JNLESS SPECIFIED 10/15/08 DATE DO NOT SCALE DRAWING www.IDT.com NL/NIC24 PACKAGE OUTLINE 4.0 x 4.0 mm BODY 0.5 mm PITCH OFN PSC-4192 FAX: (408) 284-859 PHONE: San Jose, CA 95138 (408) 284-8 SHEET

Package Outline and Package Dimensions, cont. (NLG24)



CHECKED	DRAWN 28 11/19/10	APPROVALS DATE TITLE	TOLERANCES UNLESS SPECIFIED DECIMAL ANGULAR XXX± XXXX± XXXXX
0.5 mm PITCH VFQFPN	4.0 x 4.0 mm BODY	NL/NLG24 PACKAGE OUTLINE	6024 Silver Creek Valley Son Jose, CA 95138 PHONE: (408) 284-8590 WWW.IDT.com FAX: (408) 284-8591

	91	00	REV	
	ADD LAND PATTERN	INITIAL RELEASE	DESCRIPTION	REVISIONS
	11/19/10	11/19/10	DATE	
	JG	JG	APPROVE	
F	2	Λ1	26	/15

Ordering Information

Part / Order Number	Shipping Packaging	Package	Temperature
9DMV0431AKILF	Tubes	24-pin VFQFPN	-40 to +85° C
9DMV0431AKILFT	Tape and Reel	24-pin VFQFPN	-40 to +85° C

[&]quot;LF" to the suffix denotes Pb-Free configuration, RoHS compliant.

Revision History

Rev.	Initiator	Issue Date	Description	Page #
			Updated Electrical Tables with Char data	
Α	RDW	9/24/2014	Updated General Description	Various
			3. Move to final	
В	RDW	1/26/2015	Updated package drawing and dimensions	9

[&]quot;A" is the device revision designator (will not correlate with the datasheet revision).

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(Rev.1.0 Mar 2020)

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