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Tiny/Super Low Power E7 Emulator

Additional Document for User's Manual Notes on Connecting the H8/38602RF

Renesas Microcomputer Development Environment System H8 Family / H8/300H Tiny Series Tiny/Super Low Power E7 HS0007TCU01HEP8

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**Table 1.1 Recommended Connector** 

Type Number	Manufacturer	Specifications
2514-6002	3M Limited	14-pin straight type

Connect pins 2, 4, 6, 10, 12, and 14 of the user system connector to GND firmly on the These pins are used as electrical GND and to monitor the connection of the user system Note the pin assignments of the user system connector.

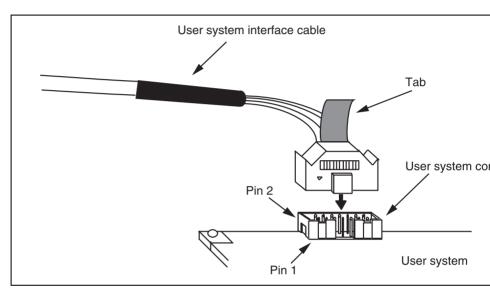


Figure 1.1 Connecting the User System Interface Cable to the User System



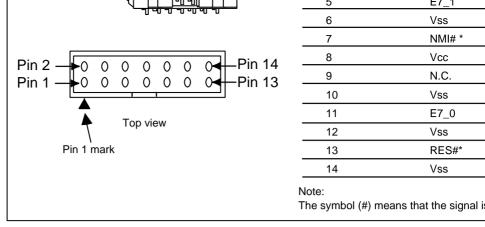


Figure 2.1 Pin Assignments of the Connector



4

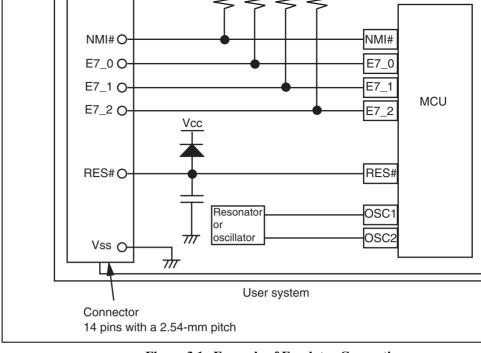


Figure 3.1 Example of Emulator Connection

2. The NMI# signal is used for forced break control by the emulator. Connect to emulator and MCU pins directly. In debugging without forced break control the mode with the HEW. Then, when the user logic is connected with the optical content of collector output buffer, the NMI# pin can be used in the user system (however power-on, the NMI# pin is used by the emulator).

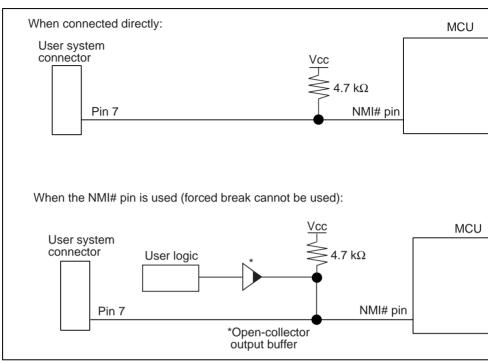


Figure 3.3 Connection of Emulator and NMI# Pin



#### Figure 3.4 Example of a Reset Circuit

- 4. Connect Vss and Vcc with the Vss and Vcc of the MCU, respectively.
- 5. Connect nothing with N.C.
- 6. The input voltage, Vcc, must be connected to the user system Vcc (power s The amount of voltage permitted to input to Vcc must be within the guarant of the microcomputer.
- 7. Refer to the hardware manual for the recommended capacitance of the capa is connected to the RES# pin.
- Use of the internal oscillator circuit is available in the H8/38602RF. Howeveresonator or an oscillator must be connected to OSC1 and OSC2 pins when emulator is connected.



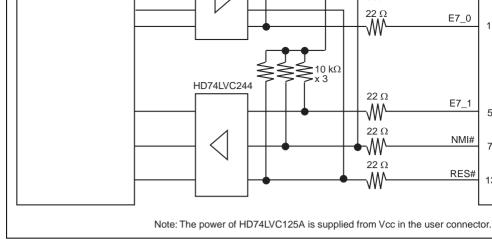


Figure 3.5 Interface Circuit in the Emulator (Reference)



ER0 to ER6	H'0000				
ER7 (SP)	H'FF80				
CCR	H'80				

## 2. Low-Power Mode

During a user program break, the CPU operating frequency is forced to a system clohigh-speed operation.

#### 3. RES# Signal

window.

The MCU signals are only valid during user program execution started with clicking or STEP-type button. During a user program break, the RES# signal is not sent to the

Note: Do not start user program execution or access the memory while control input s (RES#) is being low. A TIMEOUT error will occur.

## 4. System Control Register

In the emulator, the internal I/O registers can be accessed from the [IO] window. He careful when accessing the system control register. The emulator saves the register the system control register at a break and returns the value when the user program is Since this is done during a break, do not rewrite the system control register in the [IO]

#### 5. Memory Access during Emulation

If the memory contents are referenced or modified during emulation, realtime emula cannot be performed because the user program is temporarily halted.



- 9. The power consumed by the MCU can reach several milliamperes. This is because to power supply drives one HD74LVC125A to make the communication signal level muser-system power-supply voltage. The power consumed rises little during user progressions since the emulator does not perform communication; it rises more during a second power consumed.
- 10. Program Area for the Emulator

Do not access a part of areas in the flash memory or the internal RAM since the emulator are characteristic the emulator will not operate normally. In this case, restart the emulator with the Doesemulator firmware mode.

Table 4.2 Program Area for the E7 Emulator

MCU Name	Program Area
H8/38602RF	Flash memory: H'4000 to H'4FFF
	Internal RAM: H'F780 to H'FB7F
	Vector, etc.: H'0002 to H'000F, H'0018 to H'0019, H'4FF8 to H'

11. The emulator uses a two-word stack pointer for values stored on a user program brea

- Therefore, the stack area must accept two-word addresses.
- 12. Do not use an MCU that has been used for debugging.

  If the flash memory is rewritten many times, data may be lost due to retention proble the emulator has been left for a few days and the data will be erased. If an error mes displayed, exchange the MCU for a new one.



Be sure to initialize the following internal I/O registers by the user program since the initialized by selecting [Debug] – [Reset CPU] or using the RESET command: SYSCR1, SYSCR2, IEGR, IENR1, and IRR1

#### 16. Step Execution of the SLEEP Instruction

When the interrupt mask bit (I) in the condition code register (CCR) is 1, do not per execution of the SLEEP instruction. If the step execution is performed and not finis correctly, restart the emulator.

- 17. Use of the internal oscillator circuit is available in the H8/38602RF. However, a rese an oscillator must be connected to OSC1 and OSC2 pins when the emulator is connected to OSC1 and OSC2 pins when the oSC1 pins when the oSC1 pins when the
- 18. Processing at Emulator Activation

differs from that of the actual MCU.

When the emulator is activated, the watchdog timer is not active; the operation of th

• In the H8/38602RF E7 emulator, conditions of Break Condition 1,2 can be set. T

- 19. Hardware Break Functions
  - lists the items that can be specified.
- 20. Restriction on Software Write Enable (SWE) Bit

If the SWE bit is set to 1 during execution of the user program, a communication tin will occur. Do not set this bit to 1.



dialog box.

Table 4.4 Conditions Set in [Break condition] Dialog Box

	Condition					
Dialog Box	Address Bus Condition	Data Condition	Read or Write Condition			
[Break condition 1]	0	0	0			
[Break condition 2]	0	Х	Х			

Note: O: Can be set by checking the radio button in the dialog box.

Table 4.5 lists the combinations of conditions that can be set by the BREAKCON SET command.

Table 4.5 Conditions Set by BREAKCONDITION\_SET Command

	Condition					
Channel	Address Bus Condition ( <addropt> option)</addropt>	Data Condition ( <dataopt> option)</dataopt>	Read or Write Condition ( <r wopt=""> opt</r>			
Break condition 1	0	0	0			
Break condition 2	0	X	Х			

Note: O: Can be set by the BREAKCONDITION\_SET command.



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