The EL5462 is a current feedback amplifier with a bandwidth of 500 MHz which makes this amplifier ideal for today's high speed video and monitor applications.

With a supply current of just 1.5 mA per amplifier and the ability to run from a single supply voltage from 5 V to 12 V , the EL5462 is also ideal for handheld, portable or batterypowered equipment.

The EL5462 is available in a 14 -pin SO package and operates over the industrial temperature range of $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.

## Pinout



## Features

- $500 \mathrm{MHz}-3 \mathrm{~dB}$ bandwidth
- $4000 \mathrm{~V} / \mu$ s slew rate
- 1.5 mA supply current per amplifier
- Single and dual supply operation, from 5 V to 12 V supply span
- High speed, 1.4 GHz product available (EL5167 \& EL5167)
- High speed, $4 \mathrm{~mA}, 630 \mathrm{MHz}$ product available (EL5164 \& EL5165)
- Pb-free available (RoHS compliant)


## Applications

- Battery-powered equipment
- Handheld, portable devices
- Video amplifiers
- Cable drivers
- RGB amplifiers
- Test equipment
- Instrumentation
- Current-to-voltage converters


## Ordering Information

| PART NUMBER | PACKAGE |  <br> REEL | PKG. DWG. \# |
| :--- | :---: | :---: | :---: |
| EL5462IS | 14-Pin SO | - | MDP0027 |
| EL5462IS-T7 | 14-Pin SO | $7 "$ | MDP0027 |
| EL5462IS-T13 | 14-Pin SO | $13 "$ | MDP0027 |
| EL5462ISZ <br> (See Note) | 14-Pin SO <br> (Pb-Free) | - | MDP0027 |
| EL5462ISZ-T7 <br> (See Note) | 14-Pin SO <br> (Pb-Free) | $7 "$ | MDP0027 |
| EL5462ISZ-T13 <br> (See Note) | 14-Pin SO <br> (Pb-Free) | $13 "$ | MDP0027 |

NOTE: Intersil Pb-free products employ special Pb -free material sets; molding compounds/die attach materials and 100\% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb -free soldering operations. Intersil Pb -free products are MSL classified at Pb -free peak reflow temperatures that meet or exceed the Pb -free requirements of IPC/JEDEC J STD-020.


#### Abstract

Absolute Maximum Ratings $\left(\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}\right)$ Supply Voltage between $\mathrm{V}_{\mathrm{S}^{+}}$and $\mathrm{V}_{\mathrm{S}^{-}} \ldots \ldots . .$. Maximum Continuous Output Current . . . . . . . . . . . . . . . . . . . . 50mA Maximum Voltage between IN+ and IN-, Disabled . . . . . . . . $\pm 1.5 \mathrm{~V}$ Current into IN+, IN-, CE . . . Slew Rate from $\mathrm{V}_{\mathrm{S}^{+}}$to $\mathrm{V}_{\mathrm{S}}$ - $\qquad$ $\pm 5 \mathrm{~mA}$

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.


IMPORTANT NOTE: All parameters having Min/Max specifications are guaranteed. Typical values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore: $T_{J}=T_{C}=T_{A}$

Electrical Specifications $\quad V_{S^{+}}=+5 V, V_{S^{-}}=-5 \mathrm{~V}, R_{F}=750 \Omega$ for $A_{V}=1, R_{F}=400 \Omega$ for $A_{V}=2, R_{L}=150 \Omega, T_{A}=25^{\circ} \mathrm{C}$ unless otherwise specified.

| PARAMETER | DESCRIPTION | CONDITIONS | MIN | TYP | MAX | UNIT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| AC PERFORMANCE |  |  |  |  |  |  |
| BW | -3dB Bandwidth | $A_{V}=+1, R_{L}=500 \Omega, R_{F}=598 \Omega$ |  | 500 |  | MHz |
|  |  | $A_{V}=+2, R_{L}=150 \Omega, R_{F}=422 \Omega$ |  | 233 |  | MHz |
| BW1 | 0.1dB Bandwidth |  |  | 30 |  | MHz |
| SR | Slew Rate | $\mathrm{V}_{\mathrm{O}}=-2.5 \mathrm{~V}$ to $+2.5 \mathrm{~V}, \mathrm{~A}_{\mathrm{V}}=+2, \mathrm{R}_{\mathrm{L}}=100 \Omega$ | 2500 | 4000 | 5000 | V/ $/ \mathrm{s}$ |
| $\mathrm{t}_{5}$ | 0.1\% Settling Time | $\mathrm{V}_{\text {OUT }}=-2.5 \mathrm{~V}$ to $+2.5 \mathrm{~V}, \mathrm{~A}_{\mathrm{V}}=+1$ |  | 25 |  | ns |
| $\mathrm{e}_{\mathrm{N}}$ | Input Voltage Noise |  |  | 3 |  | $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ |
| $\mathrm{i}^{-}$- | IN- Input Current Noise |  |  | 10 |  | $\mathrm{pA} / \sqrt{\mathrm{Hz}}$ |
| $\mathrm{i}^{+}{ }^{+}$ | IN+ Input Current Noise |  |  | 6.5 |  | $\mathrm{pA} / \sqrt{\mathrm{Hz}}$ |
| dG | Differential Gain Error (Note 1) | $A_{V}=+2$ |  | 0.05 |  | \% |
| dP | Differential Phase Error (Note 1) | $A_{V}=+2$ |  | 0.15 |  | - |
| DC PERFORMANCE |  |  |  |  |  |  |
| V ${ }_{\text {OS }}$ | Offset Voltage |  | -5 | 1.5 | +5 | mV |
| $\mathrm{T}_{\mathrm{C}} \mathrm{V}_{\text {OS }}$ | Input Offset Voltage Temperature Coefficient | Measured from $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\text {MAX }}$ |  | 6 |  | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| $\mathrm{R}_{\text {OL }}$ | Transimpedance |  | 500 | 1000 |  | k $\Omega$ |
| INPUT CHARACTERISTICS |  |  |  |  |  |  |
| CMIR | Common Mode Input Range | Guaranteed by CMRR test | $\pm 3$ | $\pm 3.3$ |  | V |
| CMRR | Common Mode Rejection Ratio | $\mathrm{V}_{\mathrm{IN}}= \pm 3 \mathrm{~V}$ | 50 | 62 | 75 | dB |
| -ICMR | - Input Current Common Mode Rejection |  | -1 | 0.22 | +1 | $\mu \mathrm{A} / \mathrm{V}$ |
| $+\mathrm{I}_{\text {IN }}$ | + Input Current |  | -8 | 0.5 | +8 | $\mu \mathrm{A}$ |
| $-_{\text {IN }}$ | - Input Current |  | -10 | 2 | +10 | $\mu \mathrm{A}$ |
| $\mathrm{R}_{\text {IN }}$ | Input Resistance |  | 0.8 | 1.6 | 3 | $\mathrm{M} \Omega$ |
| $\mathrm{C}_{\text {IN }}$ | Input Capacitance |  |  | 1 |  | pF |
| OUTPUT CHARACTERISTICS |  |  |  |  |  |  |
| $\mathrm{V}_{\mathrm{O}}$ | Output Voltage Swing | $\mathrm{R}_{\mathrm{L}}=150 \Omega$ to GND | $\pm 3.35$ | $\pm 3.6$ | $\pm 3.75$ | V |
|  |  | $\mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$ to GND | $\pm 3.75$ | $\pm 3.9$ | $\pm 4.15$ | V |
| Iout | Output Current | $\mathrm{R}_{\mathrm{L}}=10 \Omega$ to GND | 60 | 100 |  | mA |

Electrical Specifications $V_{S^{+}}=+5 \mathrm{~V}, \mathrm{~V}_{S^{-}}=-5 \mathrm{~V}, R_{F}=750 \Omega$ for $A_{V}=1, R_{F}=400 \Omega$ for $A_{V}=2, R_{L}=150 \Omega, T_{A}=25^{\circ} \mathrm{C}$ unless otherwise specified. (Continued)

| PARAMETER | DESCRIPTION | CONDITIONS | MIN | TYP | MAX | UNIT |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| SUPPLY | Supply Current - Enabled, per Amplifier | No load, $\mathrm{V}_{\text {IN }}=0 \mathrm{~V}$ | 1.3 | 1.5 | 1.7 | mA |  |
| ISON | DC, $\mathrm{V}_{\mathrm{S}}= \pm 4.75 \mathrm{~V}$ to $\pm 5.25 \mathrm{~V}$ | 65 | 76 |  | dB |  |  |
| PSRR | Power Supply Rejection Ratio | (Input Current Power Supply Rejection | DC, $\mathrm{V}_{\mathrm{S}}= \pm 4.75 \mathrm{~V}$ to $\pm 5.25 \mathrm{~V}$ | -0.5 | 0.1 | +0.5 | $\mu \mathrm{~A} / \mathrm{V}$ |
| -IPSR |  |  |  |  |  |  |  |

NOTE:

1. Standard NTSC test, AC signal amplitude $=286 \mathrm{mV} \mathrm{V}_{\text {- } \mathrm{P},} \mathrm{f}=3.58 \mathrm{MHz}$

## Typical Performance Curves



FREQUENCY (Hz)
FIGURE 1. FREQUENCY RESPONSE FOR $A_{V}=+1$


FIGURE 3. FREQUENCY RESPONSE FOR $A_{V}=+10$


FIGURE 2. FREQUENCY RESPONSE FOR $A_{V}=+4.6$


FIGURE 4. FREQUENCY RESPONSE FOR $A_{V}=+2$

## Typical Performance Curves (Continued)



FIGURE 5. FREQUENCY RESPONSE FOR $A_{V}=+4$


FIGURE 7. CLOSED LOOP OUTPUT IMPEDANCE


4ns/DIV

FIGURE 9. OUTPUT FALL TIME


FIGURE 6. FREQUENCY RESPONSE FOR VARIOUS $\mathrm{V}_{\mathrm{CC}}, \mathrm{V}_{\mathrm{EE}}$


FIGURE 8. OUTPUT RISE TIME


100ns/DIV

FIGURE 10. TURN ON TIME

## Typical Performance Curves (Continued)



100ns/DIV

FIGURE 11. TURN OFF TIME


FIGURE 13. PSRR ( $\mathrm{V}_{\mathrm{EE}}$ )


FIGURE 15. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE


FIGURE 12. PSRR ( $\mathrm{V}_{\mathrm{CC}}$ )


FIGURE 14. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

Pin Descriptions

| EL5462 | PIN NAME | FUNCTION | EQUIVALENT CIRCUIT |
| :---: | :---: | :---: | :---: |
| 2, 6, 9, 13 | IN - | Inverting input |  |
| $3,5,10,12$ | $\mathrm{IN}+$ | Non-inverting input | (See circuit 1) |
| 11 | VS- | Negative supply |  |
| 1, 7, 8, 14 | OUT | Output | Circuit 2 |
| 4 | VS+ | Positive supply |  |

## Applications Information

## Product Description

The EL5462 is a low power, current-feedback operational amplifier that offers a wide -3 dB bandwidth of 500 MHz and a low supply current of 1.5 mA per amplifier. The EL5462 works with supply voltages ranging from a single 5 V to 10 V and they are also capable of swinging to within 1 V of either supply on the output. Because of its current-feedback topology, the EL5462 does not have the normal gainbandwidth product associated with voltage-feedback operational amplifiers. Instead, its -3dB bandwidth to remain relatively constant as closed-loop gain is increased. This combination of high bandwidth and low power, together with aggressive pricing makes the EL5462 the ideal choice for many low-power/high-bandwidth applications such as portable, handheld, or battery-powered equipment.

## Power Supply Bypassing and Printed Circuit Board Layout

As with any high frequency device, a good printed circuit board layout is necessary for optimum performance. Low impedance ground plane construction is essential. Surface mount components are recommended, but if leaded components are used, lead lengths should be as short as possible. The power supply pins must be well bypassed to reduce the risk of oscillation. The combination of a $4.7 \mu \mathrm{~F}$ tantalum capacitor in parallel with a $0.01 \mu \mathrm{~F}$ capacitor has been shown to work well when placed at each supply pin.

For good AC performance, parasitic capacitance should be kept to a minimum, especially at the inverting input. (See the Capacitance at the Inverting Input section) Even when
ground plane construction is used, it should be removed from the area near the inverting input to minimize any stray capacitance at that node. Carbon or Metal-Film resistors are acceptable with the Metal-Film resistors giving slightly less peaking and bandwidth because of additional series inductance. Use of sockets, particularly for the SO package, should be avoided if possible. Sockets add parasitic inductance and capacitance which will result in additional peaking and overshoot.

## Capacitance at the Inverting Input

Any manufacturer's high-speed voltage or current-feedback amplifier can be affected by stray capacitance at the inverting input. For inverting gains, this parasitic capacitance has little effect because the inverting input is a virtual ground, but for non-inverting gains, this capacitance (in conjunction with the feedback and gain resistors) creates a pole in the feedback path of the amplifier. This pole, if low enough in frequency, has the same destabilizing effect as a zero in the forward open-loop response. The use of largevalue feedback and gain resistors exacerbates the problem by further lowering the pole frequency (increasing the possibility of oscillation.)

The EL5462 has been optimized with a $600 \Omega$ feedback resistor. With the high bandwidth of these amplifiers, these resistor values might cause stability problems when combined with parasitic capacitance, thus ground plane is not recommended around the inverting input pin of the amplifier.

## Feedback Resistor Values

The EL5462 has been designed and specified at a gain of +1 with $R_{F}$ approximately $606 \Omega$. This value of feedback resistor gives 500 MHz of -3 dB bandwidth at $A_{V}=1$ with 0.5 dB of peaking. With $A_{V}=-2$, an $R_{F}$ of approximately $600 \Omega$ gives 300 MHz of bandwidth with 1 dB of peaking. Since the EL5462 is a current-feedback amplifier, it is also possible to change the value of $R_{F}$ to get more bandwidth. As seen in the curve of Frequency Response for Various $R_{F}$ and $R_{G}$, bandwidth and peaking can be easily modified by varying the value of the feedback resistor.

Because the EL5462 is a current-feedback amplifier, its gainbandwidth product is not a constant for different closed-loop gains. This feature actually allows the EL5462 to maintain about the same -3dB bandwidth. As gain is increased, bandwidth decreases slightly while stability increases. Since the loop stability is improving with higher closed-loop gains, it becomes possible to reduce the value of $R_{F}$ below the specified TBD $\Omega$ and still retain stability, resulting in only a slight loss of bandwidth with increased closed-loop gain.

## Supply Voltage Range and Single-Supply Operation

The EL5462 has been designed to operate with supply voltages having a span of greater than 5 V and less than 10 V . In practical terms, this means that they will operate on dual supplies ranging from $\pm 2.5 \mathrm{~V}$ to $\pm 5 \mathrm{~V}$. With single-supply, the EL5462 will operate from 5 V to 10 V .
As supply voltages continue to decrease, it becomes necessary to provide input and output voltage ranges that can get as close as possible to the supply voltages. The EL5462 has an input range which extends to within 2 V of either supply. So, for example, on +5 V supplies, the EL5462 has an input range which spans $\pm 3 \mathrm{~V}$. The output range of the EL5462 is also quite large, extending to within 1 V of the supply rail. On a $\pm 5 \mathrm{~V}$ supply, the output is therefore capable of swinging from 4 V to +4 V . Single-supply output range is larger because of the increased negative swing due to the external pull-down resistor to ground.

## Video Performance

For good video performance, an amplifier is required to maintain the same output impedance and the same frequency response as DC levels are changed at the output. This is especially difficult when driving a standard video load of $150 \Omega$, because of the change in output current with DC level. Previously, good differential gain could only be achieved by running high idle currents through the output transistors (to reduce variations in output impedance.) These currents were typically comparable to the entire 1 mA supply current of the EL5462 amplifier. Special circuitry has been incorporated in the EL5462 to reduce the variation of output impedance with current output. This results in dG and dP specifications of $0.1 \%$ and $0.1^{\circ}$, while driving $150 \Omega$ at a gain of 2 .

Video performance has also been measured with a $500 \Omega$ load at a gain of +1 . Under these conditions, the EL5462 has dG and dP specifications of $0.1 \%$ and $0.1^{\circ}$.

## Output Drive Capability

In spite of its low 1.5 mA of supply current, the EL5462 is capable of providing a minimum of $\pm 50 \mathrm{~mA}$ of output current. With a minimum of $\pm 50 \mathrm{~mA}$ of output drive, the EL5462 is capable of driving $50 \Omega$ loads to both rails, making it an excellent choice for driving isolation transformers in telecommunications applications.

## Driving Cables and Capacitive Loads

When used as a cable driver, double termination is always recommended for reflection-free performance. For those applications, the back-termination series resistor will decouple the EL5462 from the cable and allow extensive capacitive drive. However, other applications may have high capacitive loads without a back-termination resistor. In these applications, a small series resistor (usually between $5 \Omega$ and $50 \Omega$ ) can be placed in series with the output to eliminate most peaking. The gain resistor ( $\mathrm{R}_{\mathrm{G}}$ ) can then be chosen to make up for any gain loss which may be created by this additional resistor at the output. In many cases it is also possible to simply increase the value of the feedback resistor $\left(\mathrm{R}_{\mathrm{F}}\right)$ to reduce the peaking.

## Current Limiting

The EL5462 has no internal current-limiting circuitry. If the output is shorted, it is possible to exceed the Absolute Maximum Rating for output current or power dissipation, potentially resulting in the destruction of the device.

## Power Dissipation

With the high output drive capability of the EL5462, it is possible to exceed the $125^{\circ} \mathrm{C}$ Absolute Maximum junction temperature under certain very high load current conditions. Generally speaking when $R_{L}$ falls below about $25 \Omega$, it is important to calculate the maximum junction temperature ( $T J_{\text {MAX }}$ ) for the application to determine if power supply voltages, load conditions, or package type need to be modified for the EL5462 to remain in the safe operating area. These parameters are calculated as follows:
$T_{\text {JMAX }}=T_{M A X}+\left(\theta_{J A} \times n \times D_{M A X}\right)$
where:

- $\mathrm{T}_{\mathrm{MAX}}=$ Maximum ambient temperature
- $\theta_{\mathrm{JA}}=$ Thermal resistance of the package
- $\mathrm{n}=$ Number of amplifiers in the package
- $P_{\text {MAX }}=$ Maximum power dissipation of each amplifier in the package
PD ${ }_{\text {MAX }}$ for each amplifier can be calculated as follows:
$P D_{\text {MAX }}=\left(2 \times V_{S} \times I_{\text {SMAX }}\right)+\left[\left(V_{S}-V_{\text {OUTMAX }}\right) \times \frac{V_{\text {OUTMAX }}}{R_{L}}\right]$
where:
- $\mathrm{V}_{\mathrm{S}}=$ Supply voltage
- ISMAX = Maximum supply current of 1.5 mA
- VOUTMAX $=$ Maximum output voltage (required)
- $\mathrm{R}_{\mathrm{L}}=$ Load resistance


## Typical Application Circuits



FIGURE 16. INVERTING 200mA OUTPUT CURRENT DISTRIBUTION AMPLIFIER


FIGURE 17. FAST-SETTLING PRECISION AMPLIFIER

## SO Package Outline Drawing



NOTE: The package drawing shown here may not be the latest version. To check the latest revision, please refer to the Intersil website at [http://www.intersil.com/design/packages/index.asp](http://www.intersil.com/design/packages/index.asp)

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