

DESCRIPTION

This document describes the specification for the F1951 Digital Step Attenuator. The F1951 is part of a family of *Glitch-Free*TM DSAs optimized for the demanding requirements of communications Infrastructure. These devices are offered in a compact 4x4 QFN package with 50 Ω impedances for ease of integration into the radio system.

COMPETITIVE ADVANTAGE

Digital step attenuators are used in Receivers and Transmitters to provide gain control. The F1951 is a 6-bit step attenuator optimized for these demanding applications. The silicon design has very low insertion loss and low distortion (+65 dBm IP3_I.). The device has pinpoint accuracy and settles to final attenuation value within 400 nsec. Most importantly, the F1951 includes Renesas' *Glitch-Free*TM technology which results in less than 0.6 dB of overshoot ringing during MSB transitions. This is in stark contrast to competing DSAs that *glitch as much as 10 dB* during MSB transitions (see p.10).

- ✓ Lowest insertion loss for best SNR
- ✓ Glitch-Free[™] when transitioning won't damage PA or ADC
- ✓ Extremely accurate with low distortion



Glitch-Free[™]

APPLICATIONS

- Base Station 2G, 3G, 4G, TDD radiocards
- Repeaters and E911 systems
- Digital Pre-Distortion
- Point to Point Infrastructure
- Public Safety Infrastructure
- WIMAX Receivers and Transmitters
- Military Systems, JTRS radios
- RFID handheld and portable readers
- Cable Infrastructure

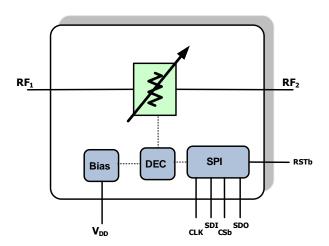
PART# MATRIX

Part#	Freq range (MHz)	Resolution / Range (dB)	Control	IL (dB)	Pinout
F1951	100 - 5000	0.50 / 31.5	Serial Only	-1.2	HITT
F1950	150 - 5000	0.25 / 31.5	Serial Only	-1.3	PE
F1952	100 – 4000	0.50 / 15.5	Serial Only	-0.9	HITT

FEATURES

- *Glitch-Free*[™], < 0.6 dB transient overshoot
- Spurious Free Design
- 3 V to 5.25 V supply
- Attenuation Error < 0.2 dB @ 2 GHz
- Low Insertion Loss < 1.2 dB @ 2 GHz
- Excellent Linearity +65 dBm IP3_I
- Fast settling time, < 450 ns
- Class 2 JEDEC ESD (> 2kV HBM)
- Serial Interface 31.5 dB Range
- Stable Integral Non-Linearity over temperature
- 4x4 mm Thin QFN 24 pin package

DEVICE BLOCK DIAGRAM



ORDERING INFORMATION





6-bit 0.5 dB Digital Step Attenuator 100MHz to 5000MHz

F1951 Datasheet

ABSOLUTE MAXIMUM RATINGS

 V_{DD} to GND D[5:0], DATA, CLK, CSb, SDO, RSTb RF Input Power (RF1, RF2) calibration and testing RF Input Power (RF1, RF2) continuous RF operation θ_{JA} (Junction – Ambient) θ_{JC} (Junction – Case) The Case is defined as the exposed paddle Operating Temperature Range (Case Temperature) Maximum Junction Temperature Storage Temperature Range Lead Temperature (soldering, 10s)

-0.3 V to +5.50V -0.3 V to 3.6 V +29 dBm +23 dBm +50 °C/W +3 °C/W Tc = -40 °C to +100°C 140 °C -65 °C to +150 °C

+260 °C

F1951 SPECIFICATION (31.5 dB Range)

Specifications apply at V_{DD} = +3.3V, f_{RF} = 2000MHz, T_C= +25°C unless otherwise noted, EVKit losses are de-embedded (see p. 17)

Parameter	Comment	Sym.	Min	Typical	Max	Units	
Logic Input High	CLK, CSb, DATA, D[5:0], RSTb	V _{IH}	2.3 ^[a]		3.6 ^[b]	V	
Logic Input Low	CLK, CSb, DATA, D[5:0], RSTb	VIL			0.7	V	
Logic Current	V _{MODE}	Ін, Іп	-5		+5	μA	
Supply Voltage(s)	Main Supply	V _{DD}	3.0		5.25	V	
Supply Current	Total	I _{DD}		1.1	2	mA	
Temperature Range	Operating Range (Case)	Tc	-40		100	°C	
Frequency Range	Operating Range	f _{RF}	100		5000	MHz	
RF1, RF2 Return Loss	dB(s11), dB(s22)	S ₁₁ , S ₂₂		-22		dB	
Minimum Attenuation	D[5:0] = [111111]	A _{MIN} or IL		1.2	1.9	dB	
Maximum Attenuation	D[5:0] = [000000]V_{DD} = 3.3V	Амах	32.2	32.5		dB	
Minimum Gain Step	Least Significant Bit	LSB		0.50		dB	
Phase Delta	Phase change A _{MIN} vs. A _{MAX}	ΦΔ		33		deg	
Differential Non-Linearity	Error: adjacent steps	DNL		0.08		dB	
Integral Non-Linearity	Error: absolute to 14 dB ATTN	INL ₁		0.03	0.34	dB	
Integral Non-Linearity	Max Error vs. line (A _{MIN} ref) to 31.5 dB ATTN [V _{DD} = 3.3V]	INL ₂		0.21	0.38	dB	
	 P_{IN} = +10 dBm per tone 50 MHz Tone Separation V_{DD} = 3.3V 						
Input IP3	D[5:0] = [111111] = A _{MIN}	IP3I₁	+61	+64		dBm	
	$D[5:0] = [100000] = A_{15.5}$	IP3I ₂	+59	+61			
	$D[5:0] = [000000] = A_{MAX}$	IP3I ₃	+57	+61			
0.1 dB Compression Please note ABS MAX	 D[5:0] = [111010] = A_{2.5} Baseline P_{IN} = 20 dBm 	P _{0.1}		29		dBm	
Settling Time	 Start LE rising edge > V_{IH} End +/-0.10 dB Pout settling 15.5 – 16.0 transition 	TLSB		400		ns	
Serial Clock Speed	SPI 4 wire bus	Fclk		20	50	MHz	
Reset to Serial Setup SPI 4 wire bus		Α	20			ns	
Serial Data Hold Time	SPI 4 wire bus	В	5			ns	
CSb setup delay	SPI 4 wire bus	С	40			ns	
Serial Data Out Delay	SPI 4 wire bus	D	8	8	8	Cycles	

[[]a] – Items in min/max columns in **bold italics** are Guaranteed by Test.

[[]b] – All other Items in min/max columns are Guaranteed by Design Characterization.

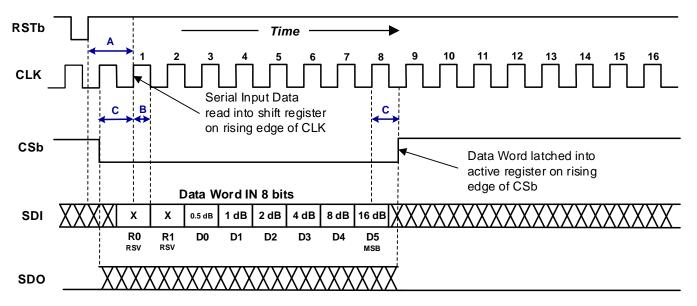
SERIAL CONTROL MODE

Data is clocked in LSB first via serial mode. Note the timing diagram below.

An RSTb pulse resets the shift register to [00000000]. If the RSTb pulse is followed immediately by a CSb pulse the device will be set to **Maximum Attenuation**.

Note – The F1951 includes a CLK inhibit feature designed to minimize sensitivity to CLK bus noise when the device is not being programmed. When CSb is high ($>V_{lH}$), the CLK input is disabled and serial data (SDI) will not be clocked into the shift register. It is recommended that CSb be pulled high ($>V_{lH}$) when the device is not being programmed

SERIAL REGISTER TIMING DIAGRAM [SINGLE DEVICE]: (Note the Timing Spec Intervals in Blue)

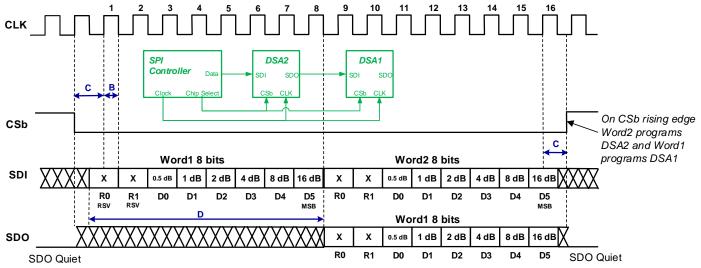


While CSb is low, SDO transmits the contents of the shift register delayed by 8 clock cycles

When CSb is high, SDO is quiet

SERIAL REGISTER TIMING DIAGRAM [TWO OR MORE DEVICES]:

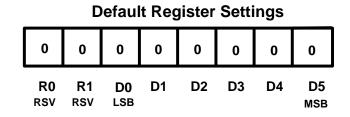
The SDO output is delayed by 8 clock cycles while CSb is low. The SDO low logic voltage is 0 volts and the SDO high logic voltage is VDD/2. This feature allows one to program multiple DSAs (in a MIMO transceiver for instance) with a single common CSb line by daisy-chaining the SDO of the 2nd DSA to the SDI of the 1st DSA and so forth:



SDO returns the 1st word written which will program DSA1

SERIAL REGISTER DEFAULT CONDITION [F1951]:

When the device is first powered up, it will default to the <u>Maximum Attenuation</u> setting as described below: Note that for the F1951 (High or 1) = Attenuation Stepped OUT. (0 or Low) = Attenuation Stepped IN.



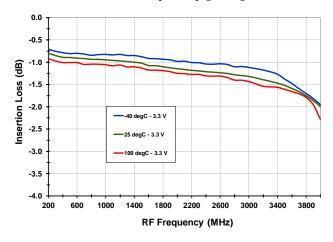
SERIAL REGISTER TIMING TABLE [F1951]:

Interval Symbol	Description	Min Spec	Max Spec	Units
Α	Reset to Serial Setup Time	20		ns
В	Serial Data Hold Time	5		ns
С	CSb setup delay	40		ns
D	Serial Data Out Delay	8	8	Cycles

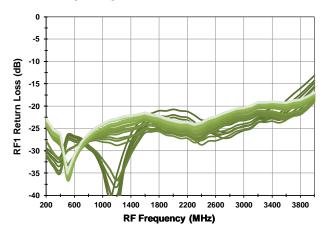


TYPICAL OPERATING PARAMETRIC CURVES (EVKit loss de-embedded, 3.3V unless otherwise noted)

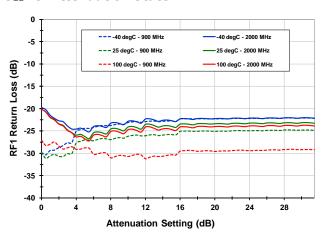
Insertion Loss vs. Frequency [AMIN]



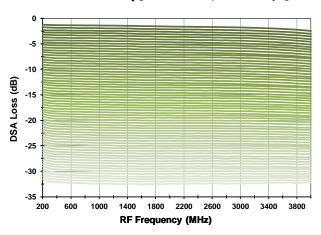
 S_{11} vs. Frequency [$T_{CASE} = +25C$, 0.5 dB steps]



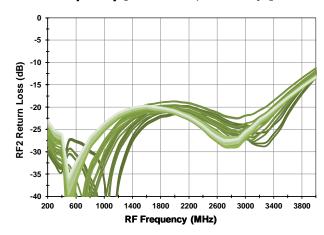
S₁₁ vs. Attenuation State



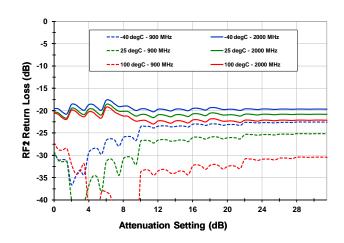
Attenuation vs. Freq [T_{CASE} = +25C, 0.5 dB steps]



 S_{22} vs. Frequency [$T_{CASE} = +25C$, 0.5 dB steps]



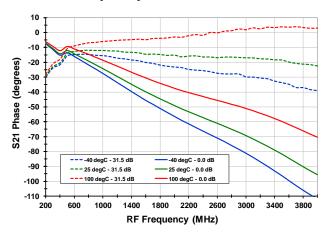
S₂₂ vs. Attenuation State



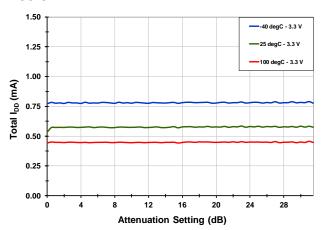


TOCs CONTINUED (-2-)

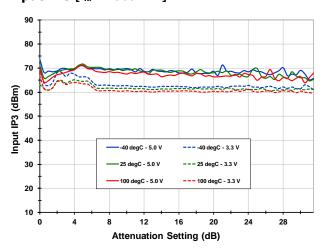
Phase vs. Frequency



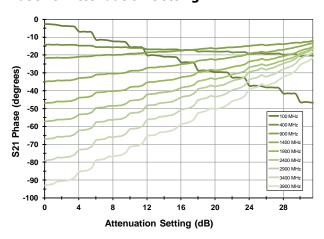
Supply Current IDD



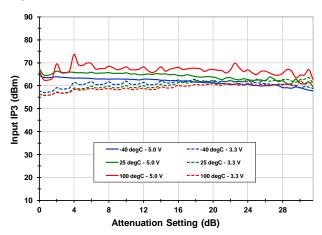
Input IP3 [$f_{RF} = 1900 \text{ MHz}$]



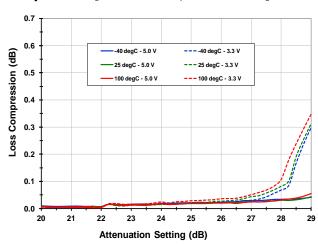
Phase vs. Attenuation Setting



Input IP3 $[f_{RF} = 900 \text{ MHz}]$



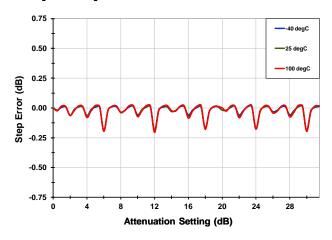
Compression [$f_{RF} = 2000 \text{ MHz}$, ATTN = 2.5 dB]



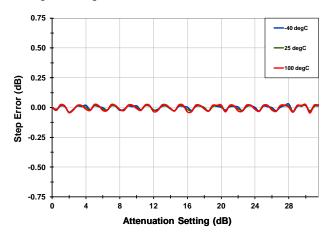


TOCs CONTINUED (-3-)

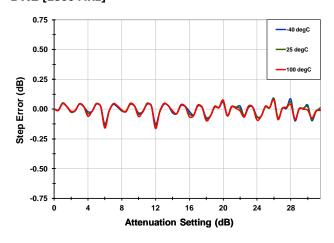
DNL [150 MHz]



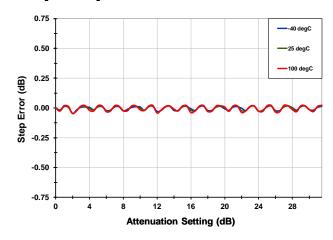
DNL [900 MHz]



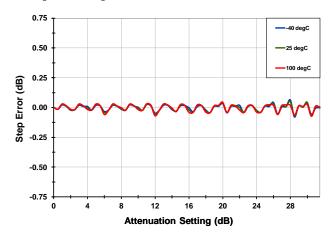
DNL [2800 MHz]



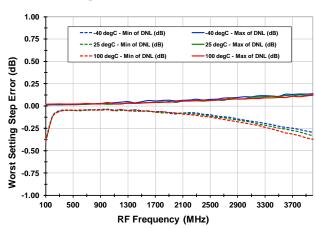
DNL [400 MHz]



DNL [1900 MHz]



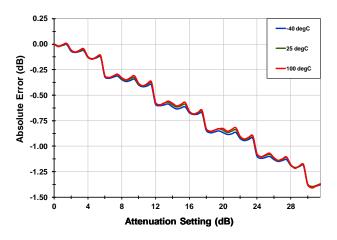
Worst Setting DNL



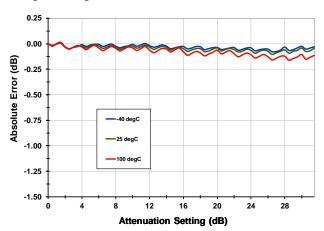


TOCs CONTINUED (-4-)

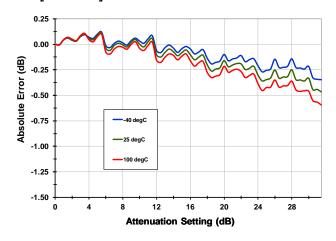
INL [150 MHz]



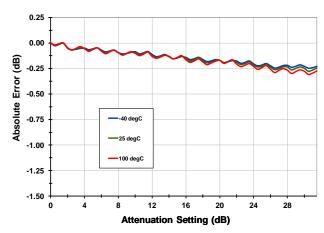
INL [900 MHz]



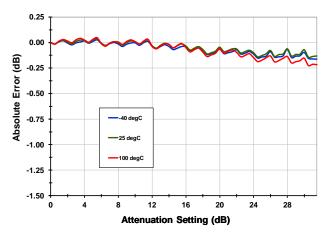
INL [2900 MHz]



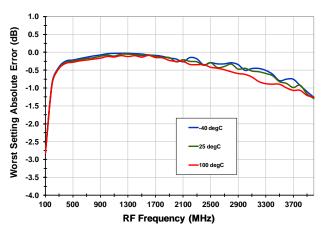
INL [400 MHz]



INL [1900 MHz]



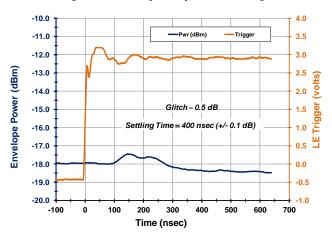
Worst Setting INL





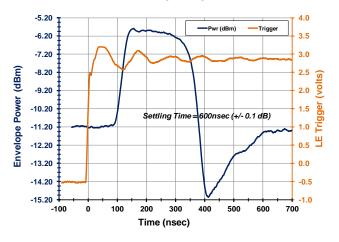
TOCs CONTINUED (-5-) [f_{RF} = 900 MHz]

Transient [15.5 to 16.0 (MSB+) 3.3V F1951]

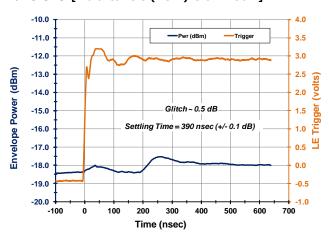


The graphs ABOVE show the transient overshoot and settling time performance for both the MSB+ and MSB-cases for the F1951. The device settles very quickly (~400 ns) with benign (~0.5 dB) overshoot.

Transient [15.75 to 16.00 (MSB+) Standard DSA]

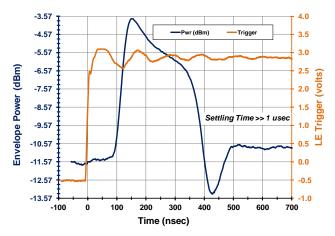


Transient [16.0 to 15.5 (MSB-) 5.0V F1951]



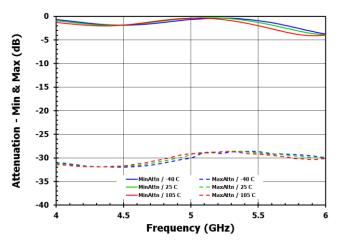
The graphs BELOW show the transient overshoot and settling time performance for a popular competing DSA. *Note the overshoot/undershoot excursion of almost 10 dB* and the very long settling time. For the MSB- case, the settling time is off the scale, $\sim 3 \mu s$.

Transient [16.00 to 15.75 (MSB-) Standard DSA]

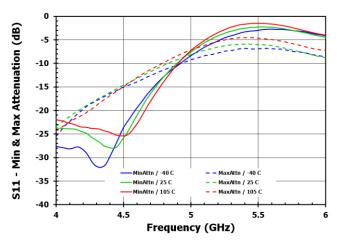


TOCs CONTINUED (-6-)

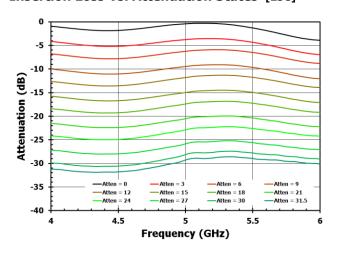
Insertion Loss — HB [Max & Min Attenuations]



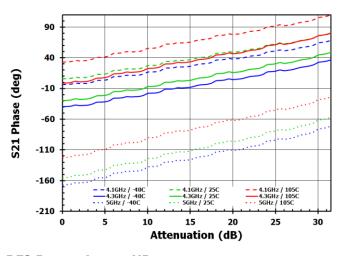
RF1 Return Loss - HB [Max & Min Attenuations]



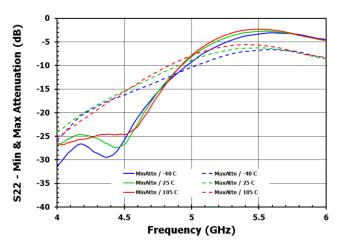
Insertion Loss Vs. Attenuation States [25C]



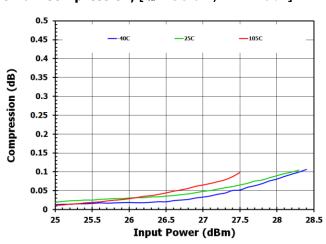
Phase Vs. Attenuation [4GHz to 4.3GHz]



RF2 Return Loss - HB [Max & Min Attenuations]

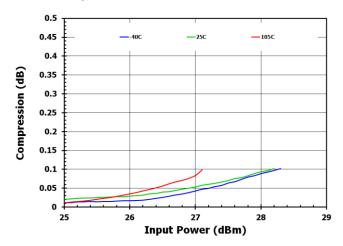


0.1dB Compression, [$f_{RF} = 3.9 \text{ GHz}$, ATTN = 0 dB]

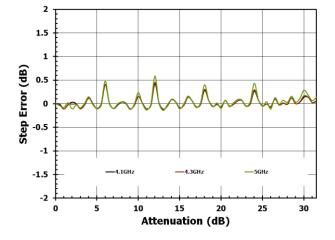


TOCs CONTINUED (-7-)

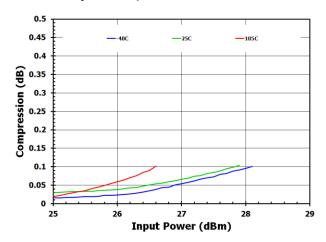
0.1dB Compression, [$f_{RF} = 4.1 \text{ GHz}$, ATTN = 0 dB]



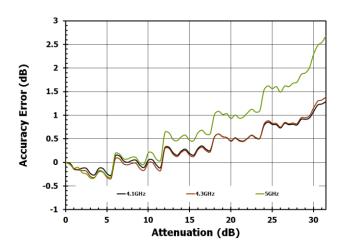
Step Error DNL [25C]



0.1dB Compression, [$f_{RF} = 4.3 \text{ GHz}$, ATTN = 0 dB]



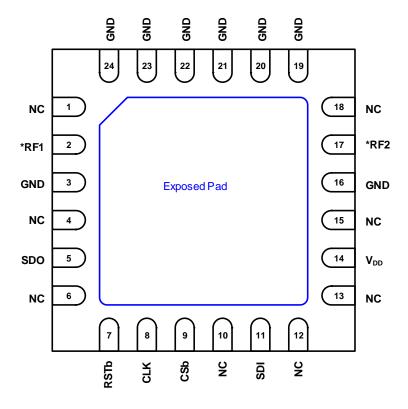
Accuracy Error INL [25C]





PIN DIAGRAM (F1951)

TOP View (looking through the top of the package)



^{*} Device is RF Bi-Directional



6-bit 0.5 dB Digital Step Attenuator 100MHz to 5000MHz

F1951 Datasheet

PACKAGE OUTLINE DRAWING (4x4mm, 24 PIN)

The package outline drawings are appended at the end of this document and are accessible from the link below. The package information is the most current data available.

 $\underline{www.idt.com/document/psc/24-vfqfpn-package-outline-drawing-40-x-40-x-075-mm-body-05mm-pitch-epad-26-x-26-mm-nbnbg24p2}$

6-bit 0.5 dB Digital Step Attenuator 100MHz to 5000MHz

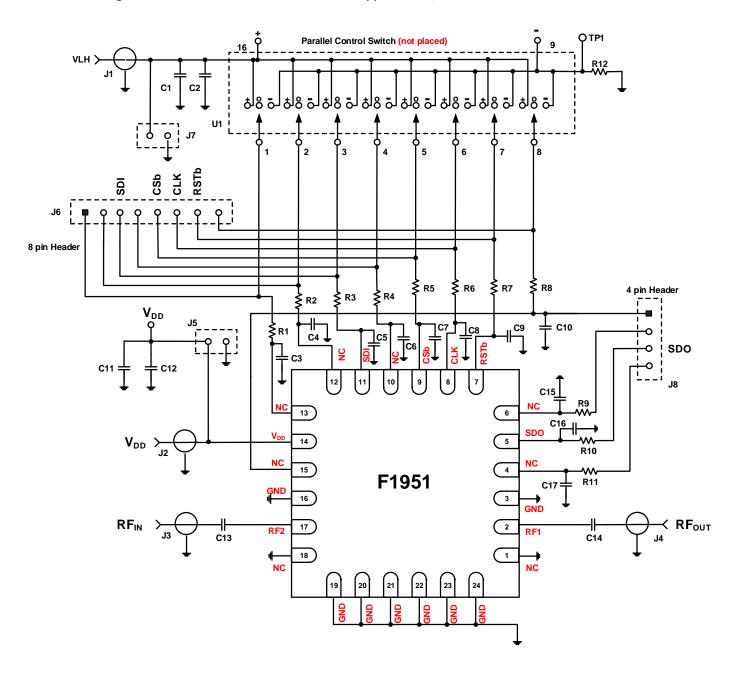
PIN DESCRIPTIONS

Pin#	Pin Name	Pin Function		
1	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).		
2	RF1	Device RF input or output (bi-directional). Requires a DC Block.		
3	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
4	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).		
5	SDO	Serial Data Out. Delayed 8 clock cycles from Serial Data In.		
6	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).		
7	RSTb	Reset BAR. Falling Edge resets the device to Max Attenuation [D5:D0] = [000000].		
8	CLK	Serial Clock.		
9	CSb	Chip Select Bar. Serial Data latched into active register on Rising Edge.		
10	NC No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).			
11	SDI	Serial Data Input.		
12	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).		
13	NC No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).			
14	VDD	Main Supply. Use 3.3V or 5V. Current is < 1 mA.		
15	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).		
16	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
17	RF2	Device RF output or input (bi-directional). Requires a DC Block.		
18	NC	No internal connection. These pins can be left unconnected, voltage applied, or connected to ground (recommended).		
19	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
20	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
21	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
22	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
23	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
24	GND	Connect directly to paddle ground or as close as possible to pin with thru via.		
EP	Exposed Paddle	Connect to Ground with multiple vias for good thermal relief.		



EVKIT SCHEMATIC

The diagram below describes the recommended applications / EVKit circuit:

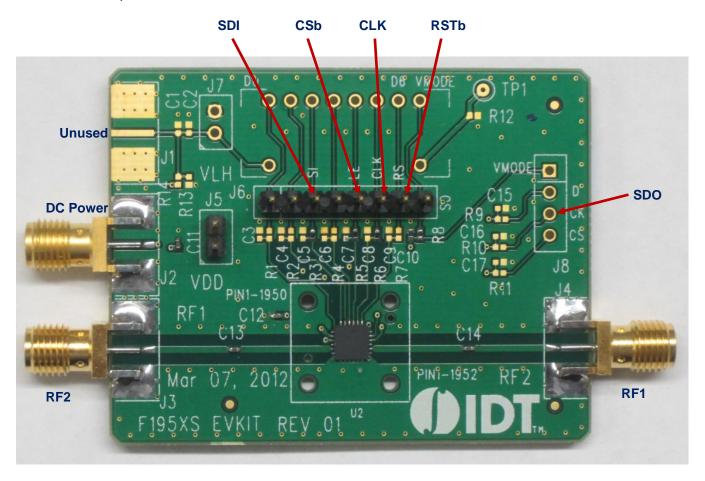




EVKIT OPERATION

The figure below shows the connections for operating the EVKit.

Please note that the RF ports (RF1 and RF2) labels on the evaluation board are reversed. The evaluation board is used for multiple devices.





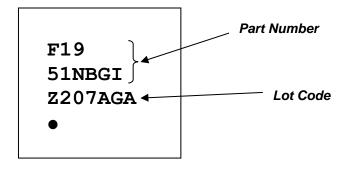
EVKIT BOM

F1951 BOM Rev 02 PCB Rev 01 10/26/2012

Item #	Value	Size	Description	Mfr. Part #	Mfr.	Ref Des	Qty
1	1000pF	0402	CAP CER 1000PF 50V C0G 0402	GRM1555C1H102JA01D	MURATA	C13,14	2
2	10nF	0402	CAP CER 10000PF 16V 10% X7R 0402	GRM155R71C103KA01D	MURATA	C12	1
3	0.1uF	0402	CAP CER 0.1UF 16V 10% X7R 0402	GRM155R71C104KA88D	MURATA	C11	1
4	Header 2 Pin	TH 2	CONN HEADER VERT SGL 2POS GOLD	961102-6404-AR	3M	J5	1
5	Header 4 Pin	TH 4	CONN HEADER VERT SGL 4POS GOLD	961104-6404-AR	3M	J8	1
6	Header 8 Pin	TH 8	CONN HEADER VERT SGL 8POS GOLD	961108-6404-AR	3M	J6	1
7	SMA_END_LAUNCH	.062	SMA_END_LAUNCH (Small)	142-0711-821	Emerson Johnson	J2,3,4	3
8	0	0402	RES 0.0 OHM 1/10W 0402 SMD	ERJ-2GE0R00X	Panasonic	R7,8,10	3
9	3К	0402	RES 3.00K OHM 1/10W 1% 0402 SMD	ERJ-2RKF3001X	Panasonic	R3,5,6	3
10	Digital Step Attenuator		F1951	F1951	IDT	U2	1
11	PCB		PCB Rev 01	F195XS Evkit Rev 01			1

Total 18

TOP MARKINGS





EVKIT THROUGH-REFLECT-LINE (TRL) CALIBRATION

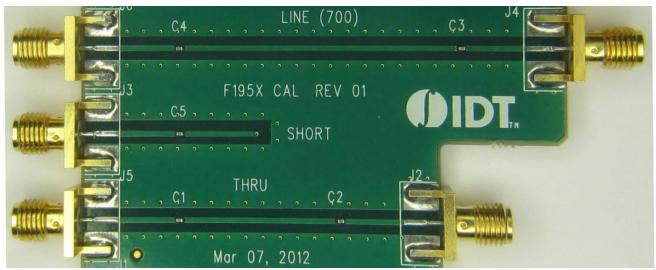
The "Through-Reflect-Line" (TRL) method [1] is used to de-embed the evaluation board losses from the S-parameter measurements of the F1951. This method requires the use of three standards: a through, a reflection, and a line. The TRL method has the advantage over other calibration methods in that it requires only one of these three standards to be well defined.

The TRL through which is used for the F1951 TRL calibration was constructed identically to the evaluation board, minus the DUT and its corresponding length. Therefore, the through corresponds to a precise zero length connection between the input and output reference planes of the DUT. This through satisfies the requirement of the TRL method that one of the three standards be precisely specified.

The TRL reflection standard used is constructed identically to the input and output lines of the evaluation board, with a short placed at the reference plane of the DUT. In accordance with the TRL method's requirements, the actual magnitude and phase were not accurately specified, but the phase was known to within 90 degrees and the TRL reflection standard has a magnitude close to one.

The TRL line standard is identical to the TRL through, but with an additional length of 0.8 inches (2 cm). This satisfies the TRL method's requirement that the TRL be a different length than the TRL through, that it have the same impedance and propagation constant as the through, and that the phase difference between the through and the line be between 20 degrees and 160 degrees. The difference in length yields a phase difference of approximately 20 degrees at 500 MHz, and a phase difference of 160 degrees at 4 GHz.

For characterization of performance from 150 to 500 MHz a separate TRL board with different "Line" length is used.



Standards used for F195x TRL calibration



F1951 evaluation circuit

[1] Engen, G.F.; Hoer, C.A.; "Thru-Reflect-Line: An Improved Technique for Calibrating the Dual Six-Port Automatic Network Analyzer," **IEEE Transactions on Microwave Theory and Techniques**, Volume: 27 Issue:12, pp. 987 – 993, Dec 1979.

6-bit 0.5 dB Digital Step Attenuator 100MHz to 5000MHz

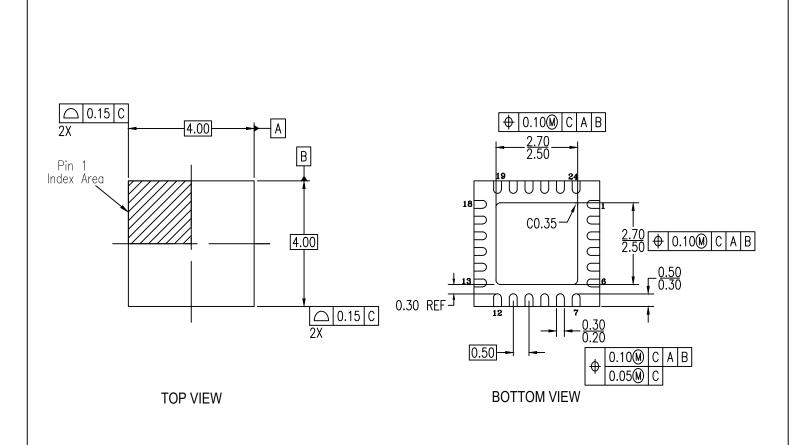
REVISION HISTORY

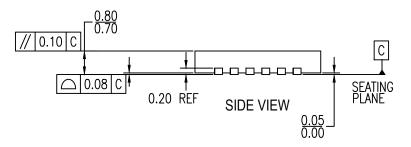
Rev	Date	Description of Change		
5	August 7, 2020	Updated Operating Range to 5GHz, Updated High Frequency Plots		
4	May 10, 2018	Removed maximum spec for CSb timing. Revision of voltage supply range on page 1 to match specification table. Revision of the package outline drawing (POD) section to explain that the POD is now given at the end of the document and to provide a link to the POD on the IDT website. POD is now NBG24P2. Revision of references to part name from IDTF1951 to F1951. Minor edits.		
3	July 21, 2017	Corrected Absolute Maximum Supply Voltage. Added information about Serial Output Line. Added Revision History Sheet		
2	Apil 02, 2014	Corrected Timing Decriptions		
1	March 20, 2013	Corrected Footer		
0	January 15, 2013	Initial Release		



24-VFQFPN, Package Outline Drawing

4.0 x 4.0 x 0.75 mm Body, 0.5mm Pitch, Epad 2.6 x 2.6 mm NB/NBG24P2, PSC-4313-02, Rev 01, Page 1





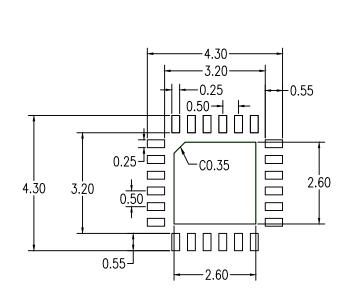
NOTES:

- 1. ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5M-1994
- 2. ALL DIMENSONS ARE IN MILLIMETERS
- 3. INDEX AREA PIN 1 IDENTIFIER



24-VFQFPN, Package Outline Drawing

4.0 x 4.0 x 0.75 mm Body, 0.5mm Pitch, Epad 2.6 x 2.6 mm NB/NBG24P2, PSC-4313-02, Rev 01, Page 2



RECOMMENDED LAND PATTERN DIMENSION

NOTES:

- 1. ALL DIMENSIONING AND TOLERANCING CONFORM TO ANSI Y14.5M-1994
- 2. ALL DIMENSONS ARE IN MILLIMETERS
- 3. LAND PATTERN RECOMMENDATION PER IPC-7351B GENERIC REQUIREMENT FOR SURFACE MOUNT DESIGN AND LAND PATTERN

Package Revision History				
Date Created	Rev No.	Description		
Jan 24, 2018	Rev 01	Change QFN to VFQFPN and New Format		
May 11, 2016	Rev 00	Initial Release		

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(Rev.1.0 Mar 2020)

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