

ISL8277M

Digital DC/DC PMBus 25A Module

FN8923
Rev.1.00
Aug 17, 2017

The [ISL8277M](#) is a 25A step-down DC/DC power supply module with an integrated digital PWM controller, synchronous power switches, an inductor, and passives. Only bulk input and output capacitors are needed to finish the design. The 25A of continuous output current can be delivered without a need of airflow or a heatsink. The thermally enhanced HDA module is capable of dissipating heat directly into the PCB.

The ISL8277M uses ChargeMode™ control architecture, which responds to a transient load within a single switching cycle. The ISL8277M comes with a preprogrammed configuration for operating in a pin-strap mode. Output voltage, switching frequency, and device SMBus address can be programmed with external resistors. More configuration such as soft-start and fault limits can be easily programmed or changed using the PMBus compliant serial bus interface. PMBus can be used to monitor voltages, current, temperatures, and fault status. The ISL8277M is supported by PowerNavigator™ software, a graphical user interface (GUI) that can be used to configure modules to a desired solution.

The ISL8277M is available in a 41-pin compact 17mmx19mm HDA module with very low profile height of 3.6mm, suitable for automated assembly by standard surface mount equipment. The ISL8277M is RoHS compliant by exemption.

Features

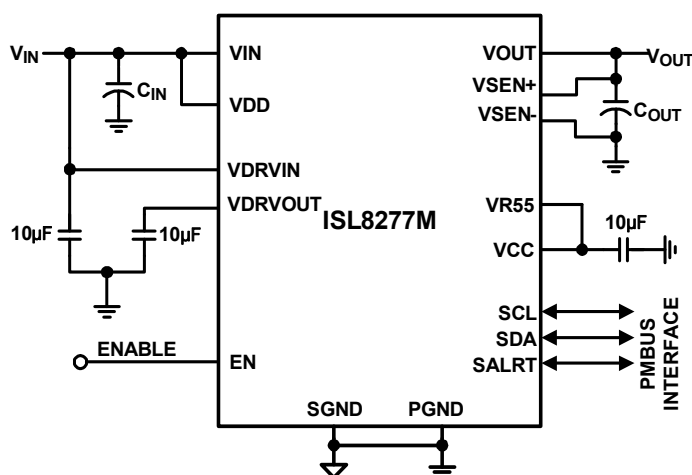
- Complete digital switch mode power supply
 - Wide V_{IN} range: 4.5V to 14V
 - Programmable V_{OUT} range: 0.6V to 5V
- PMBus compliant I^2C communication interface
 - Programmable V_{OUT} , margining, UV/OV, I_{OUT} limit, soft-start/stop, sequencing, and external synchronization
 - Monitor: V_{IN} , V_{OUT} , I_{OUT} , temperature, duty cycle, switching frequency, and faults
- ChargeMode control architecture
- $\pm 1.0\%$ V_{OUT} accuracy over line, load, and temperature
- Power-good indicator
- Over-temperature protection
- Internal nonvolatile memory and fault logging
- Patented thermally enhanced HDA package
- Intuitive configuration via [PowerNavigator](#)

Applications

- Server, telecom, storage, and datacom
- Industrial/ATE and networking equipment
- General purpose power for ASIC, FPGA, DSP, and memory

Related Literature

- For a full list of related documents, visit our website
 - [ISL8277M](#) product page



NOTE:

1. Only bulk input and output capacitors are required to finish the design.

FIGURE 1. COMPLETE DIGITAL SWITCH-MODE POWER SUPPLY

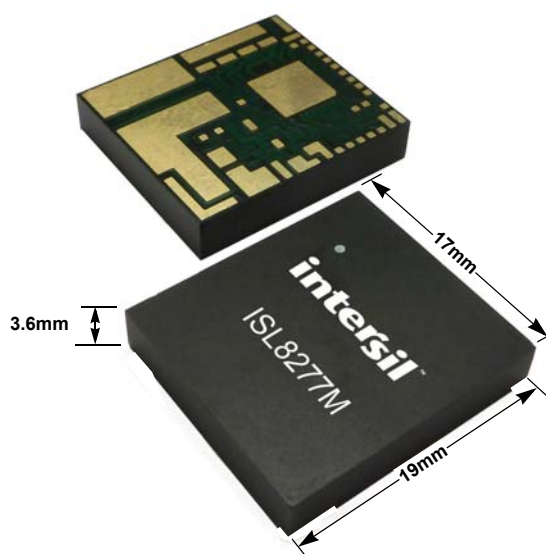


FIGURE 2. SMALL PACKAGE FOR HIGH POWER DENSITY

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Ordering Information

| PART NUMBER (Notes 2, 3, 4) | PART MARKING | TEMP RANGE (°C) | PACKAGE (RoHS Compliant) | PKG. DWG. # |
|--------------------------------|------------------|--------------------|-----------------------------|----------------|
| ISL8277MAIRZ | ISL8277MA | -40 to +85 | 41 Ld 17x19 HDA | Y41.17x19 |
| ISL8277MEVAL1Z | Evaluation Board | | | |

NOTES:

- Add "-T" suffix for 500 unit or "-T1" suffix for 100 unit tape and reel options. Refer to [TB347](#) for details on reel specifications.
- These Intersil Pb-free plastic packaged products are RoHS compliant by EU exemption 7C-I and 7A. They employ special Pb-free material sets; molding compounds/die attach materials and NiPdAu plate-e4 termination finish, which is compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.
- For Moisture Sensitivity Level (MSL), see the product information page for [ISL8277M](#). For more information on MSL, see tech brief [TB363](#).

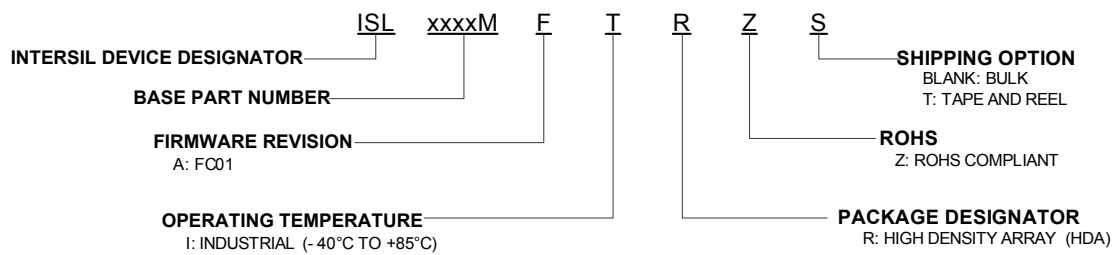
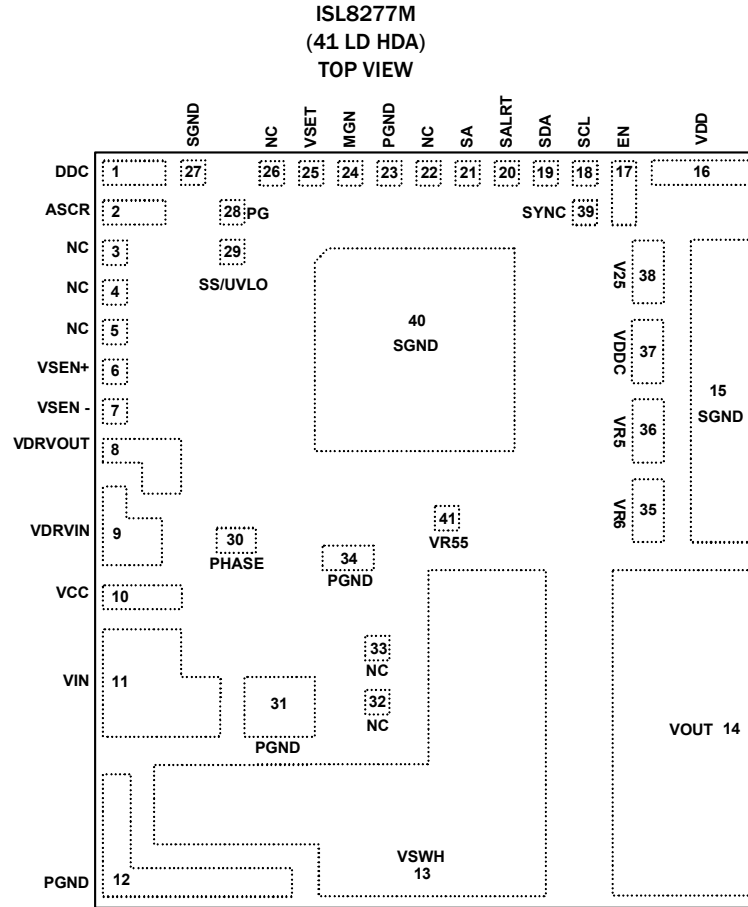


TABLE 1. TABLE OF DIFFERENCES AMONG THE FAMILY OF PARTS

| PARAMETERS | ISL8278M | ISL8271M | ISL8270M | ISL8277M |
|-----------------------------|----------|----------|----------|----------|
| V _{IN} (min) (V) | 4.5 | 4.5 | 4.5 | 4.5 |
| V _{IN} (max) (V) | 14 | 14 | 14 | 14 |
| V _{OUT} (min) (V) | 0.6 | 0.6 | 0.6 | 0.6 |
| V _{OUT} (max) (V) | 5 | 5 | 5 | 5 |
| I _{OUT} (max) (A) | 33 | 33 | 25 | 25 |
| I _Q (mA) | 40 | 40 | 40 | 40 |
| Peak Efficiency (%) | 96 | 96 | 96 | 96 |
| POR | Yes | Yes | Yes | Yes |
| Switching Freq. (min) (MHz) | 0.296 | 0.296 | 0.296 | 0.296 |
| Switching Freq. (max) (MHz) | 1.067 | 1.067 | 1.067 | 1.067 |
| Control Type | Digital | Digital | Digital | Digital |
| SYNCH Capability | Yes | Yes | Yes | Yes |
| Current Sharing | No | No | No | No |
| Tracking | No | No | No | No |
| Digital | Yes | Yes | Yes | Yes |
| Qualification Level | Standard | Standard | Standard | Standard |

Pin Configuration



Pin Descriptions

| PIN | LABEL | TYPE | DESCRIPTION |
|----------------|---------|------|--|
| 1 | DDC | I/O | A Digital-DC™ bus. This dedicated bus provides the communication channel between devices for features such as sequencing and fault spreading. The DDC pin on all Digital-DC devices should be connected together. A pull-up resistor is required for this application. |
| 2 | ASCR | I | ChargeMode control ASCR parameters selection pin. Used to set ASCR gain and residual values. |
| 6 | VSEN+ | I | Differential output voltage sense feedback. Connect to positive output regulation point. |
| 7 | VSEN- | I | Differential output voltage sense feedback. Connect to negative output regulation point. |
| 8 | VDRVOUT | PWR | Output of internal regulator for powering internal MOSFET driver. Connect a 10µF bypass capacitor to this pin. The regulator output is dedicated to powering internal MOSFET drivers. Do not use this regulator for any other purpose. For applications with VIN less than 5.2V, use an external 5V supply or connect this pad to VIN. |
| 9 | VDRVIN | PWR | Input supply to internal regulator for powering internal MOSFET drivers. Connect this pad to VIN. |
| 10 | VCC | PWR | Bias pin for internal regulator. Connect VCC pad to VR55 pin directly with a short loop trace. Not recommended to power external circuit. |
| 11 | VIN | PWR | Main input supply. Refer to "PCB Layout Guidelines" on page 21 for the decoupling capacitors placement from VIN to PGND. |
| 12, 23, 31, 34 | PGND | PWR | Power ground. Refer to "PCB Layout Guidelines" on page 21 for the PGND pad connections and decoupling capacitors placement. |
| 13 | VSWH | PWR | Switch node. Refer to "PCB Layout Guidelines" on page 21 for connecting VSWH pads to electrically isolated PCB copper island to dissipate internal heat. |

Pin Descriptions (Continued)

| PIN | LABEL | TYPE | DESCRIPTION |
|-------------------------|---------|------|---|
| 14 | VOUT | PWR | Power supply output. Range: 0.6V to 5V. Refer to the “Derating Curves” on page 12 for maximum recommended output current at various output voltages. |
| 15, 27, 40 | SGND | PWR | Controller signal ground. Refer to “PCB Layout Guidelines” on page 21 for the SGND pad connections. |
| 16 | VDD | PWR | Input supply to digital controller. Connect VDD pad to VIN supply. Refer to “PCB Layout Guidelines” on page 21 for the decoupling capacitors placement from VDD to SGND. |
| 17 | EN | I | External enable input. Logic high enables the module. |
| 18 | SCL | I/O | Serial clock input. A pull-up resistor is required for this application. |
| 19 | SDA | I/O | Serial data. A pull-up resistor is required for this application. |
| 20 | SALRT | O | Serial alert. A pull-up resistor is required for this application. |
| 21 | SA | I | Serial bus address select pin. Refer to Table 9 on page 19 for list of resistor values to set various serial bus address. |
| 24 | MGN | I | External V _{OUT} margin control pin. Active high (> 2V) signal at this pin sets V _{OUT} margin high, active low (< 0.8V) sets V _{OUT} margin low, and high impedance (float) will bring V _{OUT} back to nominal voltage. Factory default range for margining is nominal V _{OUT} ±5%. When using PMBus to control margin command, leave this pin as no connect. |
| 25 | VSET | I | Output voltage selection pin. Refer to Table 4 on page 17 for list of resistor values to set various output voltages. |
| 28 | PG | O | Power-good output. Power-good output can be an open drain that requires pull-up resistor or push-pull output that can drive a logic input. |
| 29 | SS/UVLO | I | Soft-start/stop and undervoltage lockout selection pin. Used to set turn on/off delay and ramp time as well as input UVLO threshold levels. Refer to Table 5 and Table 8 for list of resistors. |
| 30 | PHASE | PWR | Switch node pad for DCR sensing. Electrically shorted inside to VSWH, but for higher current sensing accuracy connect PHASE pad to VSWH pad externally. Refer to “PCB Layout Guidelines” on page 21 . |
| 35 | VR6 | PWR | 6V Internal reference supply voltage. |
| 36 | VR5 | PWR | 5V Internal reference supply voltage. |
| 37 | VDDC | PWR | VDD Clean. Noise at the VDD pin is filtered by an internal ferrite bead and capacitor. For VDD > 6V, leave this pin as no connect. For 5.5 ≤ VDD ≤ 6V, connect the VDDC pin to the VR6 pin. For 4.5 ≤ VDD < 5.5V, connect the VDDC pin to the VR6 and VR5 pin. |
| 38 | V25 | PWR | 2.5V Internal reference supply voltage. |
| 39 | SYNC | I/O | SYNC pin can be input to external clock for frequency synchronization or output to supply clock signal to other modules for synchronization. Refer to Table 6 on page 18 for list of resistor values to program various switching frequencies. |
| 41 | VR55 | PWR | Internal 5.5V bias for internal regulator use only. Connect VR55 pin directly to VCC pin. Not recommended to power external circuit. |
| 3, 4, 5, 22, 26, 32, 33 | NC | | These are test pins and are not electrically isolated. Leave these pins as no connect. |

ISL8277M Internal Block Diagram

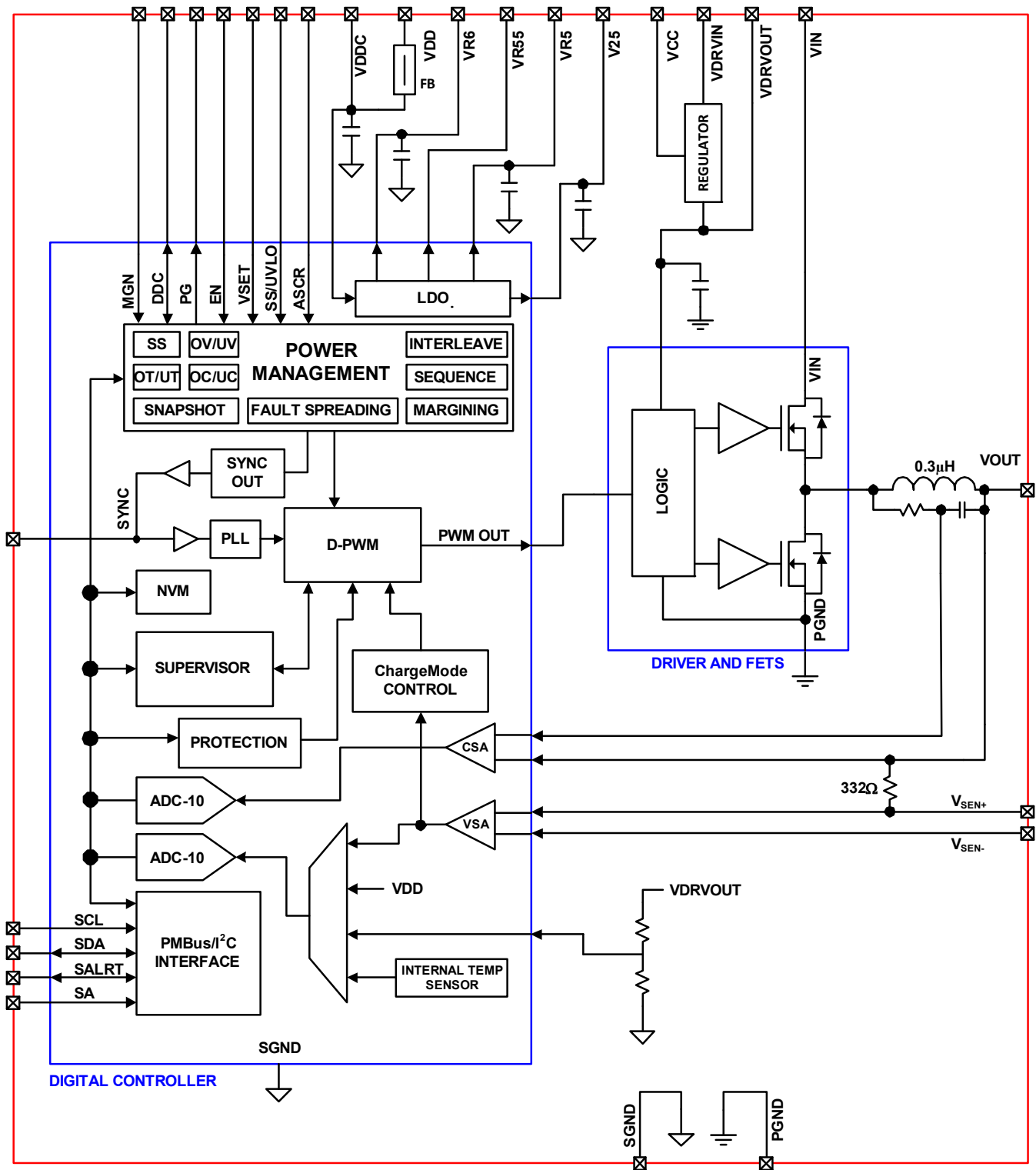


FIGURE 3. BLOCK DIAGRAM

Absolute Maximum Ratings

| | |
|---|---------------|
| Input Supply Voltage, VIN Pin | -0.3V to 17V |
| Input Supply Voltage for Controller, VDD, VDDC Pin | -0.3V to 17V |
| Input Gate Driver Supply Voltage, VDRVIN Pin | -0.3V to 17V |
| Output Voltage, VOUT Pin | -0.3V to 6V |
| Output Gate Driver Supply Voltage, VDRVOUT Pin | -0.3V to 6V |
| Switch Node Referenced to PGND Pin, VSWH Pin | -0.3V to 25V |
| Switch Node for DCR Sensing Referenced to SGND Pin, PHASE Pin | -0.3V to 25V |
| Input Bias Voltage for internal Regulator, VCC Pin | -0.3V to 6.5V |
| 6V Internal Reference Supply Voltage, VR6 Pin | -0.3V to 6.6V |
| Internal Reference Supply Voltage, VR5, VR55 Pin | -0.3V to 6.5V |
| 2.5V Internal Reference Supply Voltage, V25 Pin | -0.3V to 3V |
| Logic I/O Voltage for DDC, EN, MNG, PG, ASCR, SA, SCL, SDA, SALRT, SYNC, SS/UVLO, VSET | -0.3V to 6.0V |
| Analog Input Voltages for VSEN+, XTEMP+ | -0.3V to 6.0V |
| VSEN-, XTEMP- | -0.3V to 0.3V |
| ESD Rating | |
| Human Body Model (Tested per JS-001-2014) | 2000V |
| Machine Model (Tested per JESD22-A115C) | 200V |
| Charged Device Model (Tested per JS-002-2014) | 750V |
| Latch-Up (Tested per JESD78E; Class 2, Level A) | 100mA |

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTES:

- θ_{JA} is measured in free air with the module mounted on an evaluation board 3x4.5 inch in size with 2oz surface and 2oz buried planes and multiple via interconnects as specified in the ISL8277MEVAL1Z Evaluation Board User Guide on the [ISL8277M](#) product page.
- For θ_{JC} , the “case temp” location is the center of the package underside.

Thermal Information

| | | |
|--|------------------------------------|----------------------|
| Thermal Resistance (Typical) | θ_{JA} (°C/W) | θ_{JC} (°C/W) |
| 41 LD HDA Package (Notes 5, 6) | 7.5 | 2.2 |
| Maximum Junction Temperature (Plastic Package) | +125°C | |
| Storage Temperature Range | -55°C to +150°C | |
| Pb-Free Reflow Profile | Refer to Figure 31 | |

Recommended Operating Conditions

| | |
|--|-----------------|
| Input Supply Voltage Range, VIN | 4.5V to 14V |
| Input Supply Voltage Range for Controller, VDD | 4.5V to 14V |
| Output Voltage Range, VOUT | 0.6V to 5V |
| Output Current Range, IOUT(DC) (Note 9) | 0A to 25A |
| Operating Junction Temperature Range, Tj | -40°C to +125°C |

Electrical Specifications $V_{IN} = V_{DD} = 12V$, $f_{SW} = 533kHz$, $C_{OUT} = 1340\mu F$, $T_A = -40^\circ C$ to $+85^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. **Boldface limits apply across the operating temperature range, $-40^\circ C$ to $+85^\circ C$.**

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN (Note 7) | TYP | MAX (Note 7) | UNIT |
|--|----------------------|--|-----------------|-------------|-----------------|-------------|
| INPUT AND SUPPLY CHARACTERISTICS | | | | | | |
| Input Supply Current for Controller | I_{DD} | $V_{IN} = V_{DD} = 12V$, $V_{OUT} = 0V$, module not enabled | | 40 | 50 | mA |
| 6V Internal Reference Supply Voltage | V_{R6} | | 5.5 | 6.1 | 6.6 | V |
| Internal Regulator Output Voltage | VDRVOUT | V_{CC} connected to VR_{55} | | 5.2 | | V |
| 5V Internal Reference Supply Voltage | V_{R5} | $I_{VR5} < 5mA$ | 4.5 | 5.2 | 5.5 | V |
| 2.5V Internal Reference Supply Voltage | V_{25} | | 2.25 | 2.50 | 2.75 | V |
| 5.5V Internal Reference Supply Voltage | V_{R55} | $V_{DD} > 6V$; 0 - 80mA | | 5.7 | | V |
| Input Supply Voltage for Controller Readback Resolution | $V_{DD_READ_RES}$ | | | 10 | | Bits |
| Input Supply Voltage for Controller Readback Total Error (Note 10) | $V_{DD_READ_ERR}$ | PMBus read | | ± 2 | | %FS |
| OUTPUT CHARACTERISTICS | | | | | | |
| Output Voltage Adjustment Range | V_{OUT_RANGE} | $V_{IN} > V_{OUT} + 1.8V$ | 0.54 | | 5.50 | V |
| Output Voltage Set-Point Range | V_{OUT_RES} | Configured using PMBus | | ± 0.025 | | % |
| Output Voltage Set-Point Accuracy (Notes 8, 10) | V_{OUT_ACCY} | Includes line, load, and temperature ($-20^\circ C \leq T_A \leq +85^\circ C$) | -1 | | +1 | % V_{OUT} |
| Output Voltage Readback Resolution | $V_{OUT_READ_RES}$ | | | 10 | | Bits |

Electrical Specifications $V_{IN} = V_{DD} = 12V$, $f_{SW} = 533kHz$, $C_{OUT} = 1340\mu F$, $T_A = -40^\circ C$ to $+85^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. **Boldface limits apply across the operating temperature range, $-40^\circ C$ to $+85^\circ C$.** (Continued)

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN (Note 7) | TYP | MAX (Note 7) | UNIT |
|--|-------------------------|---|---------------------------------|----------------|----------------------------------|-------------|
| Output Voltage Readback Total Error (Note 10) | $V_{OUT_READ_ERR}$ | PMBus read | -2 | | +2 | % V_{OUT} |
| Output Current Readback Resolution | $I_{OUT_READ_RES}$ | | | 10 | | Bits |
| Output Current Range (Note 9) | I_{OUT_RANGE} | | | | 25 | A |
| Output Current Readback Total Error | $I_{OUT_READ_ERR}$ | PMBus read at max load | | ± 2 | | A |
| SOFT-START AND SEQUENCING | | | | | | |
| Delay Time From Enable to V_{OUT} Rise | t_{ON_DELAY} | Configured using PMBus | 2 | | 5000 | ms |
| t_{ON_DELAY} Accuracy | $t_{ON_DELAY_ACCY}$ | | | ± 2 | | ms |
| Output Voltage Ramp-Up Time | t_{ON_RISE} | Configured using PMBus | 0.5 | | 100.0 | ms |
| Output Voltage Ramp-Up Time Accuracy | $t_{ON_RISE_ACCY}$ | | | ± 250 | | μs |
| Delay Time From Disable to V_{OUT} Fall | t_{OFF_DELAY} | Configured using PMBus | 2 | | 5000 | ms |
| t_{OFF_DELAY} Accuracy | $t_{OFF_DELAY_ACCY}$ | | | ± 2 | | ms |
| Output Voltage Fall Time | t_{OFF_FALL} | Configured using PMBus | 0.5 | | 100.0 | ms |
| Output Voltage Fall Time Accuracy | $t_{ON_FALL_ACCY}$ | | | ± 250 | | μs |
| POWER-GOOD | | | | | | |
| Power-Good Delay | V_{PG_DELAY} | Configured using PMBus | 0 | | 5000 | ms |
| TEMPERATURE SENSE | | | | | | |
| Temperature Sense Range | T_{SENSE_RANGE} | Configurable via PMBus | -50 | | 150 | $^\circ C$ |
| Internal Temperature Sensor Accuracy | INT_TEMP_ACCY | Tested at $+100^\circ C$ | -5 | | +5 | $^\circ C$ |
| FAULT PROTECTION | | | | | | |
| V_{DD} Undervoltage Threshold Range | $V_{DD_UVLO_RANGE}$ | Measured internally | 4.18 | | 16 | V |
| V_{DD} Undervoltage Threshold Accuracy (Note 10) | $V_{DD_UVLO_ACCY}$ | | | ± 2 | | %FS |
| V_{DD} Undervoltage Response Time | $V_{DD_UVLO_DELAY}$ | | | 10 | | μs |
| V_{OUT} Overvoltage Threshold Range | $V_{OUT_OV_RANGE}$ | Factory default | | $V_{OUT} + 15$ | | % |
| | | Configured using PMBus | $V_{OUT} + 5$ | | V_{OUT_MAX} | % |
| V_{OUT} Undervoltage Threshold Range | $V_{OUT_UV_RANGE}$ | Factory default | | $V_{OUT} - 15$ | | % |
| | | Configured using PMBus | 0 | | $V_{OUT} - 5$ | % |
| V_{OUT} OV/UV Threshold Accuracy (Note 8) | V_{OUT_OV/UV_ACCY} | | -2 | | +2 | % |
| V_{OUT} OV/UV Response Time | V_{OUT_OV/UV_DELAY} | | | 10 | | μs |
| Output Current Limit Set-Point Accuracy (Note 10) | I_{LIMIT_ACCY} | Tested at $I_{OUT_OC_FAULT_LIMIT} = 30A$ | | ± 10 | | %FS |
| Output Current Fault Response Time (Note 11) | I_{LIMIT_DELAY} | Factory default | | 5 | | t_{sw} |
| Over-temperature Protection Threshold (Controller Junction Temperature) | $T_{JUNCTION}$ | Factory default | | 125 | | $^\circ C$ |
| | | Configured using PMBus | -40 | | 125 | $^\circ C$ |
| Thermal Protection Hysteresis | $T_{JUNCTION_HYS}$ | | | 15 | | $^\circ C$ |

Electrical Specifications $V_{IN} = V_{DD} = 12V$, $f_{SW} = 533kHz$, $C_{OUT} = 1340\mu F$, $T_A = -40^\circ C$ to $+85^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$. **Boldface limits apply across the operating temperature range, $-40^\circ C$ to $+85^\circ C$.** (Continued)

| PARAMETER | SYMBOL | TEST CONDITIONS | MIN (Note 7) | TYP | MAX (Note 7) | UNIT |
|---|------------------------|--|-----------------|-----|-----------------|------|
| OSCILLATOR AND SWITCHING CHARACTERISTICS | | | | | | |
| Switching Frequency Range | f_{SW_RANGE} | | 296 | | 1067 | kHz |
| Switching Frequency Set-Point Accuracy | f_{SW_ACCY} | | -5 | | +5 | % |
| Minimum Pulse Width Required from External SYNC Clock | EXT_SYNC_{PW} | Measured at 50% amplitude | 150 | | | ns |
| Drift Tolerance for External SYNC Clock | EXT_SYNC_{DRIFT} | External SYNC clock equal to 500kHz is not supported | -10 | | +10 | % |
| LOGIC INPUT/OUTPUT CHARACTERISTICS | | | | | | |
| Bias Current at the Logic Input Pins | I_{LOGIC_BIAS} | DDC, EN, MGN, PG, SA, SCL, SDA, SALRT, SYNC, UVLO, V_{MON} , V_{SET} | -100 | | +100 | nA |
| Logic Input Low Threshold Voltage | $V_{LOGIC_IN_LOW}$ | | | | 0.8 | V |
| Logic Input High Threshold Voltage | $V_{LOGIC_IN_HIGH}$ | | 2.0 | | | V |
| Logic Output Low Threshold Voltage | $V_{LOGIC_OUT_LOW}$ | 2mA sinking | | | 0.5 | V |
| Logic Output High Threshold Voltage | $V_{LOGIC_OUT_HIGH}$ | 2mA sourcing | 2.25 | | | V |
| PMBus INTERFACE TIMING CHARACTERISTIC | | | | | | |
| PMBus Operating Frequency | f_{SMB} | | 100 | | 400 | kHz |

NOTES:

7. Compliance to datasheet limits is assured by one or more methods: Production test, characterization, and/or design.
8. V_{OUT} measured at the termination of the V_{SEN+} and V_{SEN-} sense points.
9. The MAX load current is determined by the thermal ["Derating Curves" on page 12](#).
10. "FS" stand for full scale of recommended maximum operation range.
11. " t_{SW} " stands for time period of operation switching frequency.

Typical Performance Curves

Efficiency Performance Operating condition: $T_A = +25^\circ\text{C}$, No air flow. $C_{OUT} = 1340\mu\text{F}$. Typical values are used unless otherwise noted.

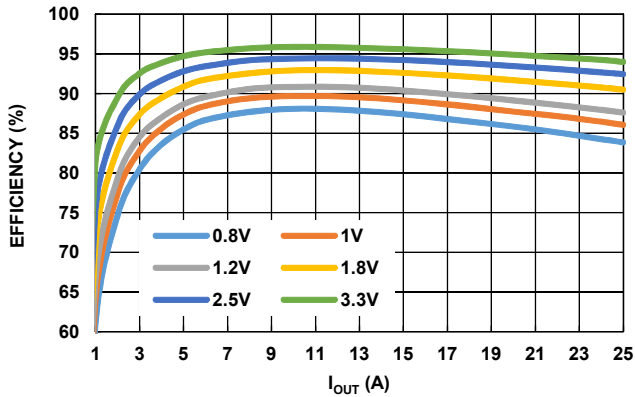


FIGURE 4. EFFICIENCY vs OUTPUT CURRENT AT $V_{IN} = 5\text{V}$, $f_{SW} = 533\text{kHz}$ FOR VARIOUS OUTPUT VOLTAGES

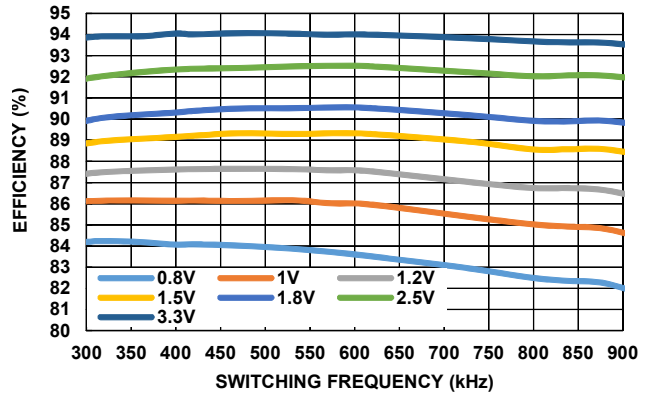


FIGURE 5. EFFICIENCY vs SWITCHING FREQUENCY AT $V_{IN} = 5\text{V}$, $I_{OUT} = 25\text{A}$ FOR VARIOUS OUTPUT VOLTAGES

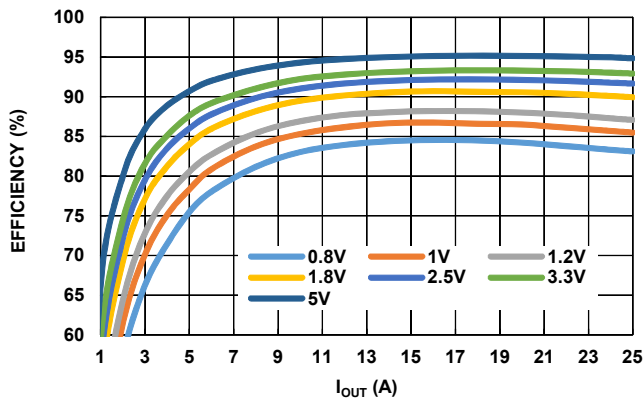


FIGURE 6. EFFICIENCY vs OUTPUT CURRENT AT $V_{IN} = 9\text{V}$, $f_{SW} = 533\text{kHz}$ FOR VARIOUS OUTPUT VOLTAGES

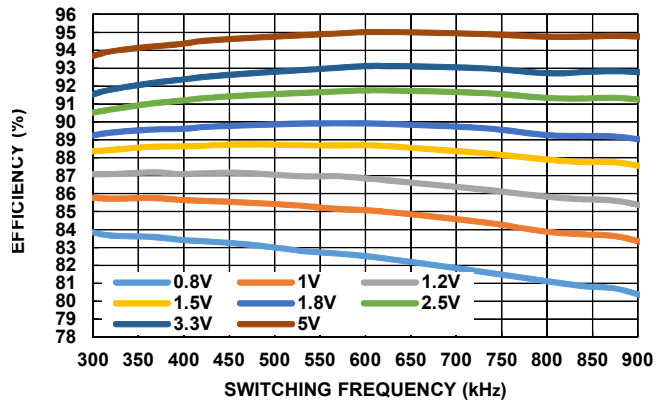


FIGURE 7. EFFICIENCY vs SWITCHING FREQUENCY AT $V_{IN} = 9\text{V}$, $I_{OUT} = 25\text{A}$ FOR VARIOUS OUTPUT VOLTAGES

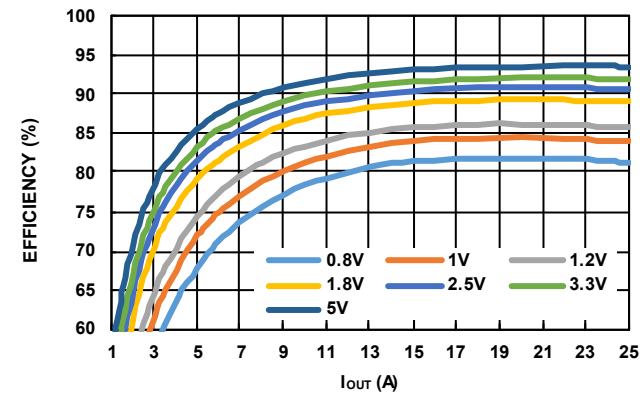


FIGURE 8. EFFICIENCY vs OUTPUT CURRENT AT $V_{IN} = 12\text{V}$, $f_{SW} = 533\text{kHz}$ FOR VARIOUS OUTPUT VOLTAGES

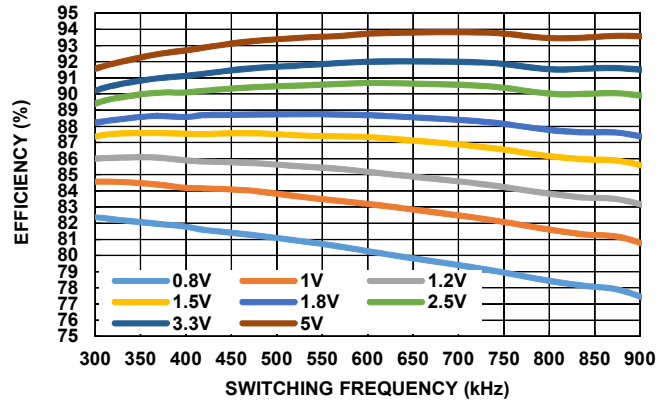


FIGURE 9. EFFICIENCY vs SWITCHING FREQUENCY AT $V_{IN} = 12\text{V}$, $I_{OUT} = 25\text{A}$ FOR VARIOUS OUTPUT VOLTAGES

Typical Performance Curves (Continued)

Transient Response Performance Operating conditions: $I_{OUT} = 0/12.5A$, I_{OUT} Slew rate $> 20A/\mu s$, $T_A = +25^\circ C$, OLFM airflow. Typical values are used unless otherwise noted.

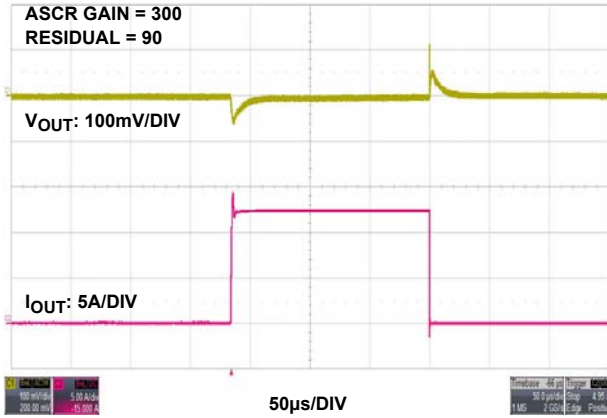


FIGURE 10. 5V_{IN} TO 1V_{OUT} TRANSIENT RESPONSE, $f_{SW}=533kHz$, $C_{OUT} = 4x100\mu F$ CERAMIC + 2x470 μF POSCAP

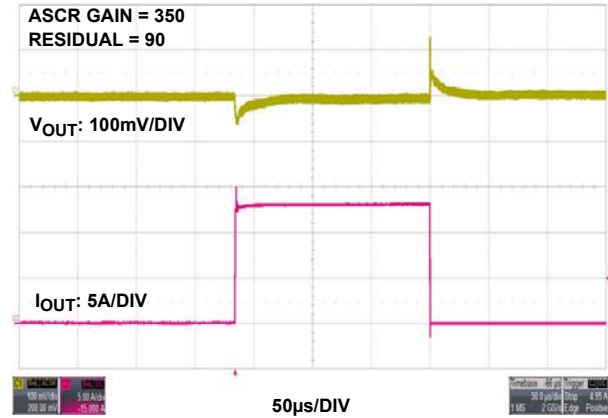


FIGURE 11. 5V_{IN} TO 1.8V_{OUT} TRANSIENT RESPONSE, $f_{SW} = 615kHz$, $C_{OUT} = 3x100\mu F$ CERAMIC + 2x470 μF POSCAP

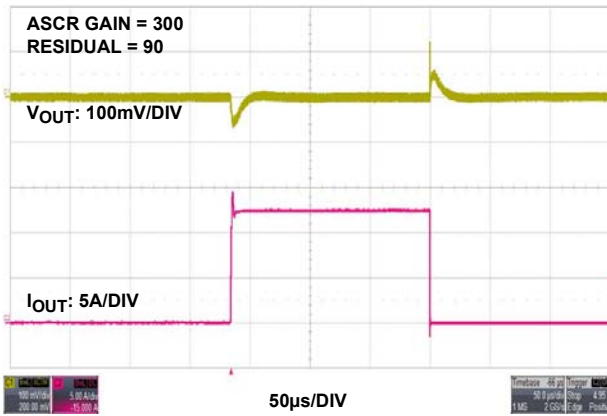


FIGURE 12. 12V_{IN} TO 1V_{OUT} TRANSIENT RESPONSE, $f_{SW} = 533kHz$, $C_{OUT} = 4x100\mu F$ CERAMIC + 2x470 μF POSCAP

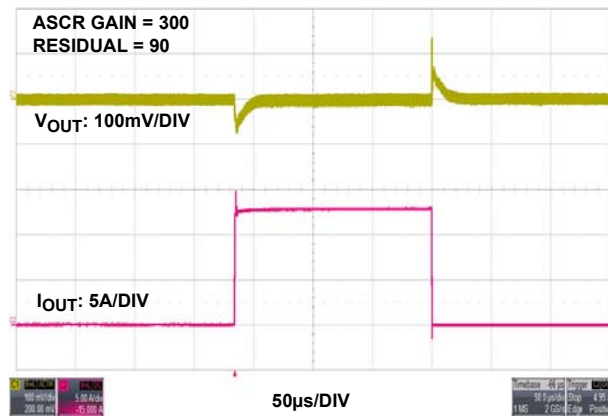


FIGURE 13. 12V_{IN} TO 1.8V_{OUT} TRANSIENT RESPONSE, $f_{SW} = 615kHz$, $C_{OUT} = 3x100\mu F$ CERAMIC + 2x470 μF POSCAP

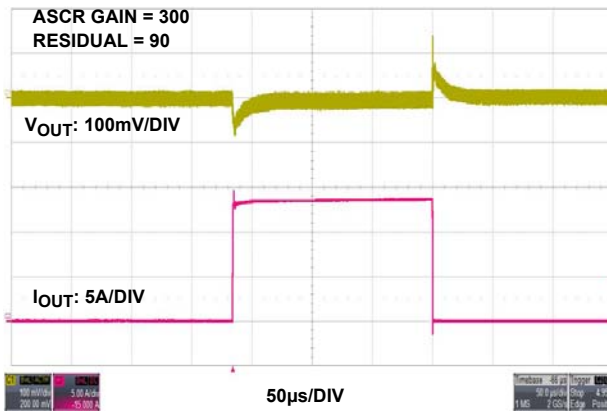


FIGURE 14. 12V_{IN} TO 3.3V_{OUT} TRANSIENT RESPONSE, $f_{SW} = 615kHz$, $C_{OUT} = 3x100\mu F$ CERAMIC + 2x470 μF POSCAP

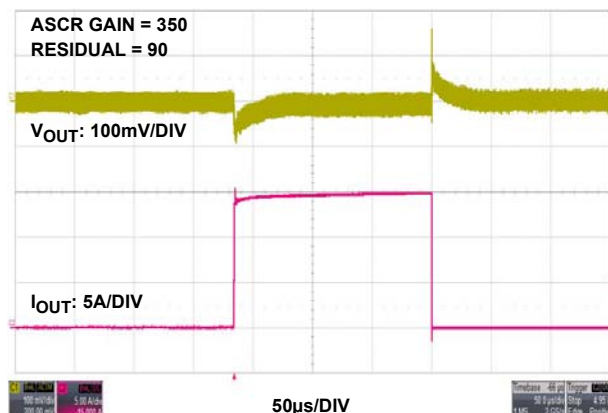


FIGURE 15. 12V_{IN} TO 5V_{OUT} TRANSIENT RESPONSE, $f_{SW} = 727kHz$, $C_{OUT} = 3x100\mu F$ CERAMIC + 2x470 μF POSCAP

Typical Performance Curves (Continued)

Derating Curves All of the following curves were plotted at $T_J = +115^\circ\text{C}$, $f_{SW} = 533\text{kHz}$

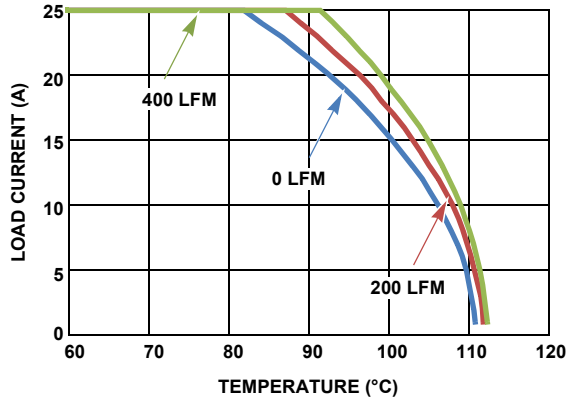


FIGURE 16. 5V_{IN} TO 1V_{OUT}

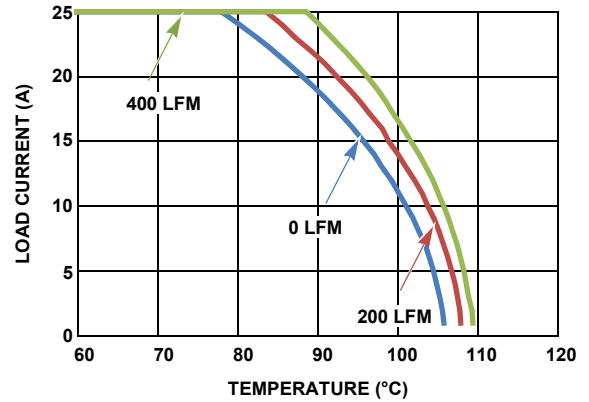


FIGURE 17. 12V_{IN} TO 1V_{OUT}

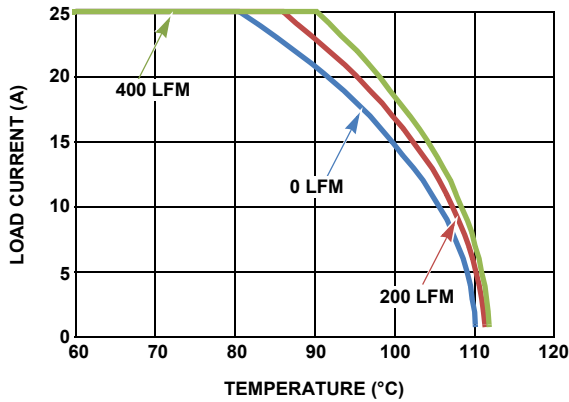


FIGURE 18. 5V_{IN} TO 1.2V_{OUT}

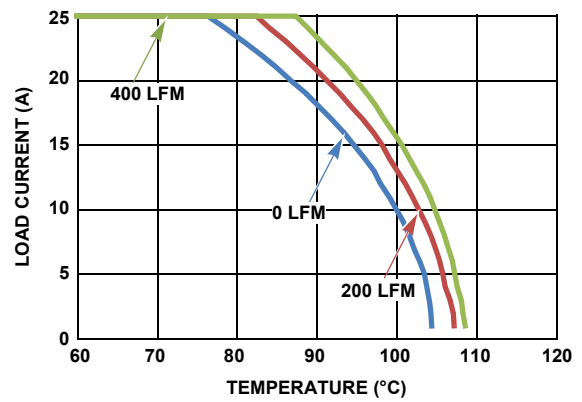


FIGURE 19. 12V_{IN} TO 1.2V_{OUT}

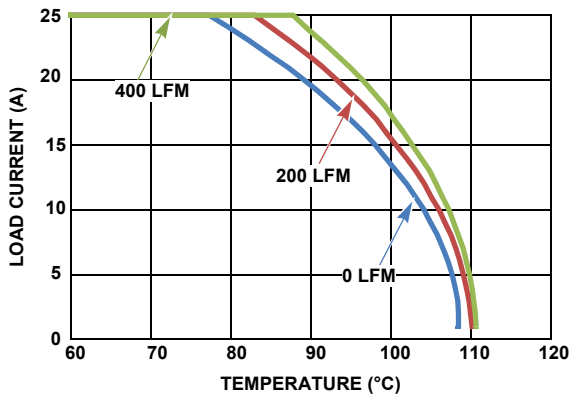


FIGURE 20. 5V_{IN} TO 1.8V_{OUT}

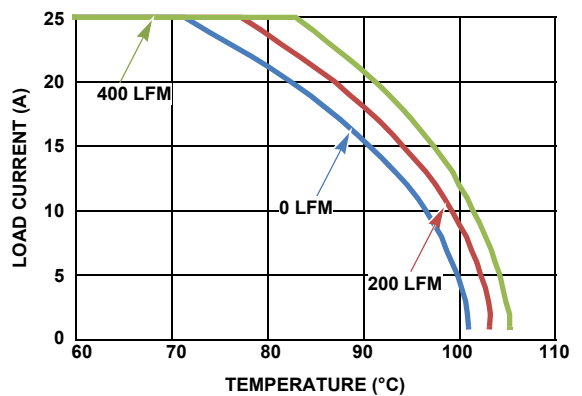


FIGURE 21. 12V_{IN} TO 1.8V_{OUT}

Typical Performance Curves (Continued)

Derating Curves All of the following curves were plotted at $T_J = +115^\circ\text{C}$, $f_{\text{SW}} = 533\text{kHz}$

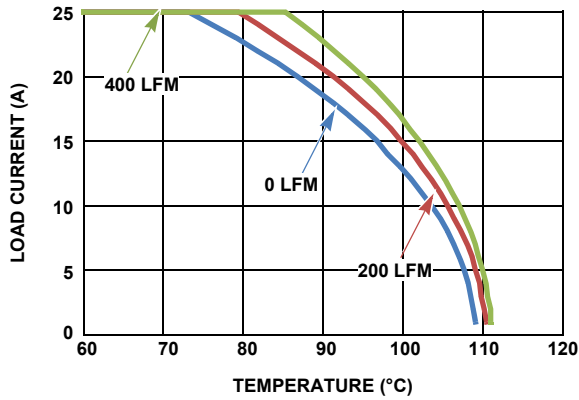


FIGURE 22. $5V_{\text{IN}}$ TO $2.5V_{\text{OUT}}$

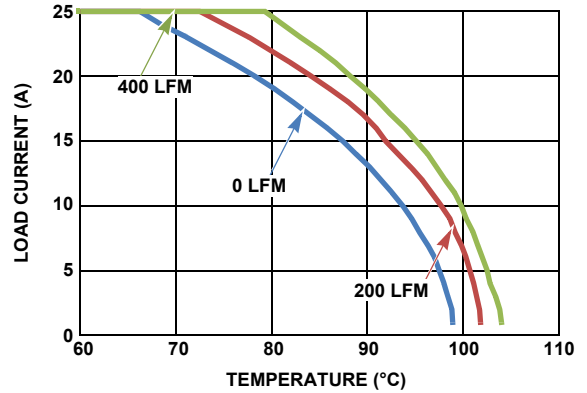


FIGURE 23. $12V_{\text{IN}}$ TO $2.5V_{\text{OUT}}$

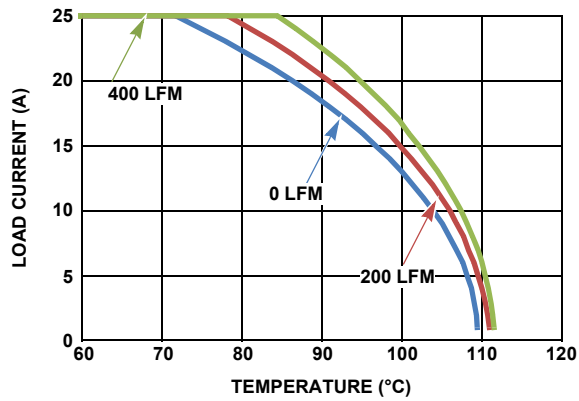


FIGURE 24. $5V_{\text{IN}}$ TO $3.3V_{\text{OUT}}$

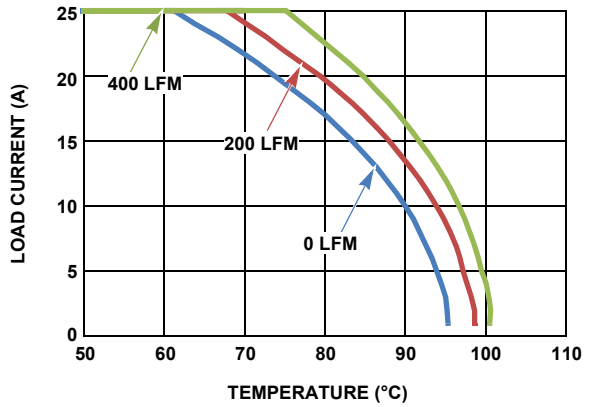


FIGURE 25. $12V_{\text{IN}}$ TO $3.3V_{\text{OUT}}$

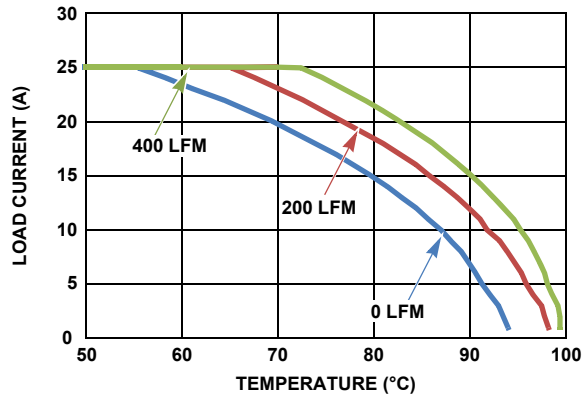
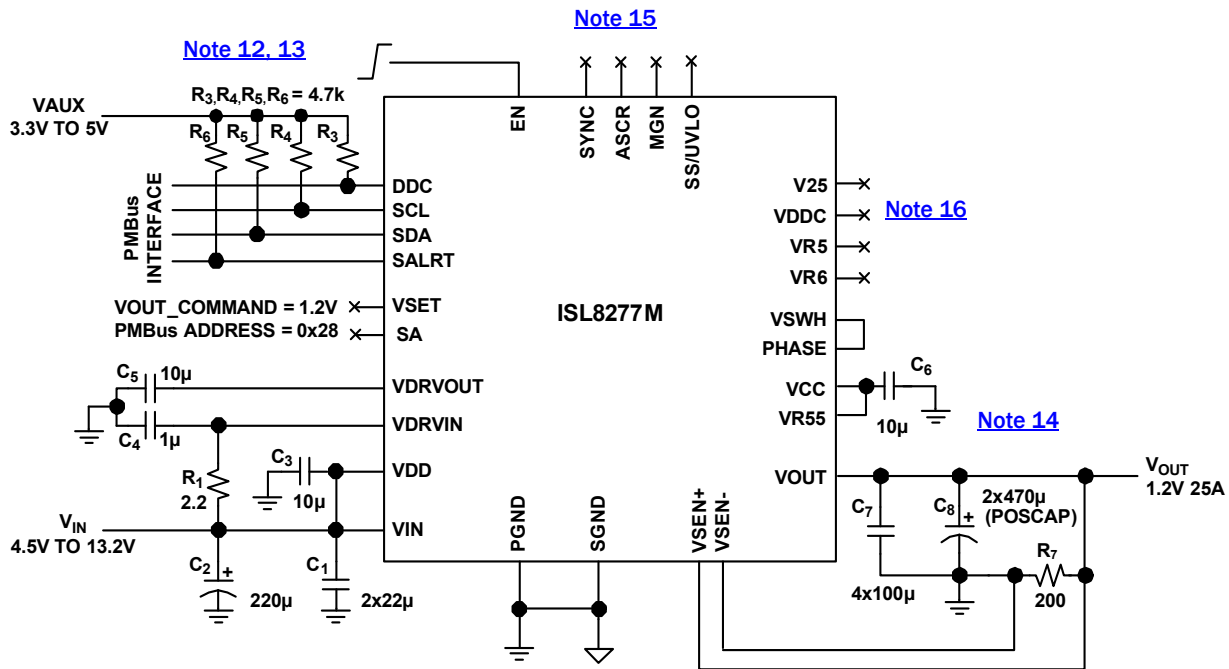


FIGURE 26. $12V_{\text{IN}}$ TO $5V_{\text{OUT}}$, 727kHz

Typical Application Circuit



NOTES:

12. R_4 and R_5 are not required if the PMBus host already has I^2C pull-up resistors.
13. Only one R_3 per DDC bus is required when DDC bus is shared with other modules.
14. R_7 is optional but recommended to sink possible $\sim 100\mu A$ back-flow current from the V_{SEN+} pin. Back-flow current is present only when the module is in a disabled state with power still available at the VDD pin.
15. Unused pins (SYNC, ASCR, MGN, SS/UVLO) can be no connect.
16. Internal reference supply pins (V25, VDDC, VR5, VR6) do not need external capacitors and can be no connect. Refer to ["PCB Layout Guidelines"](#) on page 21 for more information.

FIGURE 27. TYPICAL SINGLE-PHASE APPLICATION CIRCUIT FOR 1.2V/25A OUTPUT

TABLE 2. ISL8277M DESIGN GUIDE MATRIX AND OUTPUT VOLTAGE RESPONSE

| V _{IN} (V) | V _{OUT} (V) | C _{IN} (BULK) (Note 17) | C _{IN} (CERAMIC) | C _{OUT} (BULK) | C _{OUT} (CERAMIC) | ASCR GAIN (Note 18) | ASCR RESIDUAL (Note 18) | FREQUENCY | V _{OUT} DEVIATION (mV) | RECOVERY TIME (μ s) | STEP LOAD (A) (Note 19) |
|------------------------|-------------------------|--|------------------------------|----------------------------|-------------------------------|---------------------------|-------------------------------|-----------|---------------------------------------|--------------------------------|-------------------------------|
| 5 | 0.8 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 160 | 90 | 364 | 80 | 25 | 12.5A |
| 5 | 0.8 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 60 | 15 | 12.5A |
| 5 | 0.9 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 160 | 90 | 364 | 80 | 25 | 12.5A |
| 5 | 1 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 160 | 90 | 364 | 80 | 25 | 12.5A |
| 5 | 1 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 60 | 18 | 12.5A |
| 5 | 1.05 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 200 | 90 | 421 | 76 | 25 | 12.5A |
| 5 | 1.1 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 250 | 90 | 471 | 72 | 20 | 12.5A |
| 5 | 1.2 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 250 | 90 | 533 | 60 | 15 | 12.5A |
| 5 | 1.3 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 58 | 20 | 12.5A |
| 5 | 1.5 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 350 | 90 | 533 | 58 | 20 | 12.5A |
| 5 | 1.8 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 350 | 90 | 615 | 62 | 30 | 12.5A |
| 5 | 2.5 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 350 | 90 | 615 | 64 | 25 | 12.5A |
| 5 | 3.3 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 300 | 90 | 615 | 70 | 35 | 12.5A |
| 5 | 1.8 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 200 | 90 | 615 | 100 | 30 | 12.5A |
| 5 | 2.5 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 200 | 90 | 615 | 100 | 35 | 12.5A |
| 5 | 3.3 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 200 | 90 | 615 | 100 | 40 | 12.5A |
| 12 | 0.8 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 160 | 90 | 364 | 80 | 18 | 12.5A |
| 12 | 0.8 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 60 | 15 | 12.5A |
| 12 | 0.9 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 160 | 90 | 364 | 80 | 18 | 12.5A |
| 12 | 1 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 160 | 90 | 364 | 80 | 20 | 12.5A |
| 12 | 1 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 60 | 12 | 12.5A |
| 12 | 1.05 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 200 | 90 | 421 | 80 | 15 | 12.5A |
| 12 | 1.1 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 200 | 90 | 471 | 78 | 15 | 12.5A |
| 12 | 1.2 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 250 | 90 | 533 | 75 | 15 | 12.5A |
| 12 | 1.3 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 72 | 12 | 12.5A |
| 12 | 1.5 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 4x100 μ F | 300 | 90 | 533 | 75 | 12 | 12.5A |
| 12 | 1.8 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 300 | 90 | 615 | 78 | 10 | 12.5A |
| 12 | 2.5 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 300 | 90 | 615 | 80 | 10 | 12.5A |
| 12 | 3.3 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 300 | 90 | 615 | 82 | 10 | 12.5A |
| 12 | 5 | 2x150 μ F | 3x22 μ F | 2x470 μ F | 3x100 μ F | 350 | 90 | 727 | 95 | 10 | 12.5A |
| 12 | 1.8 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 200 | 90 | 615 | 102 | 12 | 12.5A |
| 12 | 2.5 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 200 | 90 | 615 | 110 | 12 | 12.5A |
| 12 | 3.3 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 200 | 90 | 615 | 118 | 12 | 12.5A |
| 12 | 5 | 2x150 μ F | 3x22 μ F | 1x470 μ F | 3x100 μ F | 250 | 90 | 727 | 120 | 12 | 12.5A |

NOTES:

17. C_{IN} bulk capacitor is optional only for energy buffer from the long input power supply cable.

18. ASCR gain and residual are selected to ensure that the phase margin is higher than 60° and gain margin is higher than 6dB at -40°C, +25°C, +85°C, and full load (25A).

19. Output voltage response is tested with load step slew rate higher than 20A/ μ s.

TABLE 3. RECOMMENDED I/O CAPACITOR IN [Table 2](#)

| VENDORS | VALUE | PART NUMBER |
|----------------------------|-------------------------|--------------------|
| MURATA, Input Ceramic | 47 μ F, 16V, 1210 | GRM32ER61C476ME15L |
| MURATA, Input Ceramic | 22 μ F, 16V, 1210 | GRM32ER61E226KE15L |
| TAIYO YUDEN, Input Ceramic | 47 μ F, 16V, 1210 | EMK325BJ476MM-T |
| TAIYO YUDEN, Input Ceramic | 22 μ F, 25V, 1210 | TMK325BJ226MM-T |
| MURATA, Output Ceramic | 100 μ F, 6.3V, 1210 | GRM32ER60J107M |
| TDK, Output Ceramic | 100 μ F, 6.3V, 1210 | C3225X5R0J107M |
| AVX, Output Ceramic | 100 μ F, 6.3V, 1210 | 12106D107MAT2A |
| SANYO POSCAP, Input Bulk | 150 μ F, 16V | 16TQC150MYF |
| SANYO POSCAP, Output Bulk | 470 μ F, 4V | 4TPE470MCL |
| SANYO POSCAP, Output Bulk | 470 μ F, 6.3V | 6TPF470MAH |

Functional Description

SMBus Communications

The ISL8277M provides an SMBus digital interface that enables the user to configure all aspects of the module operation as well as monitor the input and output parameters. The ISL8277M can be used with any SMBus host device. In addition, the module is compatible with PMBus Power System Management Protocol Specification Parts I & II version 1.2. The ISL8277M accepts most standard PMBus commands. When controlling the device with PMBus commands, it is recommended that the enable pin be tied to SGND.

The SMBus device address is the only parameter that must be set by external pins. All other device parameters can be set with PMBus commands.

Output Voltage Selection

The output voltage may be set to a voltage between 0.6V and 5V provided that the input voltage is higher than the desired output voltage by an amount sufficient to maintain regulation.

The VSET pin is used to set the output voltage to levels as shown in [Table 4](#). The R_{SET} resistor is placed between the VSET pin and SGND. A standard 1% resistor is recommend.

TABLE 4. OUTPUT VOLTAGE RESISTOR SETTINGS

| V _{OUT} (V) | R _{SET} (kΩ) |
|-------------------------|--------------------------|
| 0.60 | 10 |
| 0.65 | 11 |
| 0.70 | 12.1 |
| 0.75 | 13.3 |
| 0.80 | 14.7 |
| 0.85 | 16.2 |
| 0.90 | 17.8 |
| 0.95 | 19.6 |
| 1.00 | 21.5, or Connect to SGND |
| 1.05 | 23.7 |
| 1.10 | 26.1 |
| 1.15 | 28.7 |
| 1.20 | 31.6, or OPEN |
| 1.25 | 34.8 |
| 1.30 | 38.3 |
| 1.40 | 42.2 |
| 1.50 | 46.4 |
| 1.60 | 51.1 |
| 1.70 | 56.2 |
| 1.80 | 61.9 |
| 1.90 | 68.1 |
| 2.00 | 75 |

TABLE 4. OUTPUT VOLTAGE RESISTOR SETTINGS (Continued)

| V _{OUT} (V) | R _{SET} (kΩ) |
|-------------------------|--------------------------|
| 2.10 | 82.5 |
| 2.20 | 90.9 |
| 2.30 | 100 |
| 2.50 | 110, or Connect to V25 |
| 2.80 | 121 |
| 3.00 | 133 |
| 3.30 | 147 |
| 4.00 | 162 |
| 5.00 | 178 |

The output voltage may also be set to any value between 0.6V and 5V using a PMBus command VOUT_COMMAND.

By default, V_{OUT_MAX} is set 110% higher than V_{OUT} set by the pin-strap resistor, which can be changed to any value up to 5.5V with PMBus Command VOUT_MAX.

Soft-Start Delay and Ramp Times

The ISL8277M follows an internal start-up procedure after power

is applied to the VDD pin. The module requires approximately 60ms to 70ms to check for specific values stored in its internal memory and programmed by pin-strap resistors. Once this process is completed, the device is ready to accept commands via the PMBus interface and the module is ready to be enabled. If the module is to be synchronized to an external clock source, the clock frequency must be stable prior to asserting the EN pin.

It may be necessary to set a delay from when an enable signal is received until the output voltage starts to ramp to its target value. In addition, the designer may wish to precisely set the time required for V_{OUT} to ramp to its target value after the delay period has expired. These features may be used as part of an overall in-rush current management strategy or to precisely control how fast a load IC is turned on. The ISL8277M gives the system designer several options for precisely and independently controlling both the delay and ramp time periods. The soft-start delay period begins when the EN pin is asserted and ends when the delay time expires.

The soft-start delay and ramp times can be programmed to custom values with PMBus commands TON_DELAY and TON_RISE. When the delay time is set to 0ms, the device begins its ramp-up after the internal circuitry has initialized (approximately 2ms). When the soft-start ramp period is set to 0ms, the output ramps up as quickly as the output load capacitance and loop settings allow. It is generally recommended to set the soft-start ramp to a value greater than 500μs to prevent inadvertent fault conditions due to excessive in-rush current.

Similar to the soft-start delay and ramp-up time, the delay and ramp-down time for soft-stop/off can be programmed with the PMBus commands TOFF_DELAY and TOFF_FALL. In addition, the module can be configured as "immediate off" with the command

ON_OFF_CONFIG, such that the internal MOSFETs are turned off immediately after the delay time expires.

The SS/UVLO pin can be used to program the soft-start/stop delay time and ramp time to some typical values as shown in [Table 5](#).

TABLE 5. SOFT-START/STOP RESISTOR SETTINGS

| DELAY TIME (ms) | RAMP TIME (ms) | R _{SET} (kΩ) |
|-----------------|----------------|--------------------------------------|
| 5 | 2 | 12.1, 26.1, 56.2, or connect to SGND |
| 10 | 2 | 16.2, 34.8, 75 |
| 5 | 5 | 13.3, 28.7, 61.9, or OPEN |
| 10 | 5 | 17.8, 38.3, 82.5 |
| 20 | 5 | 21.5, 46.4, 100 |
| 5 | 10 | 14.7, 31.6, 68.1 |
| 10 | 10 | 19.6, 42.2, 90.9, or connect to V25 |
| 20 | 10 | 23.7, 51.1, 110 |

Power-Good

The ISL8277M provides a Power-Good (PG) signal that indicates the output voltage is within a specified tolerance of its target level and no fault condition exists. By default, the PG pin asserts if the output is within 10% of the target voltage. These limits and the polarity of the pin may be changed with PMBus command POWER_GOOD_ON.

A PG delay period is defined as the time from when all conditions within the ISL8277M for asserting PG are met to when the PG pin is actually asserted. This feature is commonly used instead of using an external reset controller to control external digital logic. A PG delay can be programmed with PMBus command POWER_GOOD_DELAY.

Switching Frequency and PLL

The device's switching frequency is set from 296kHz to 1067kHz using the pin-strap method as shown in [Table 6](#), or by using a PMBus command FREQUENCY_SWITCH. The ISL8277M incorporates an internal Phase-Locked Loop (PLL) to clock the internal circuitry. The PLL can be driven by an external clock source connected to the SYNC pin. When using the internal oscillator, the SYNC pin can be configured as a clock source that is an external sync to other modules. Refer to [“SYNC_CONFIG \(E9h\)” on page 47](#) for more information.

TABLE 6. SWITCHING FREQUENCY RESISTOR SETTINGS

| f _{sw} (V) | R _{SET} (kΩ) |
|---------------------|-------------------------|
| 296 | 14.7 or connect to SGND |
| 320 | 16.2 |
| 364 | 17.8 |
| 400 | 19.6 |

TABLE 6. SWITCHING FREQUENCY RESISTOR SETTINGS (Continued)

| f _{sw} (V) | R _{SET} (kΩ) |
|---------------------|------------------------|
| 421 | 21.5 |
| 471 | 23.7 |
| 533 | 26.1 or OPEN |
| 571 | 28.7 |
| 615 | 31.6 |
| 727 | 34.8 |
| 800 | 38.3 |
| 842 | 42.2 |
| 889 | 46.4 |
| 1067 | 51.1 or Connect to V25 |

Loop Compensation

The module loop response is programmable via the PMBus command ASCR_CONFIG or by using the pin-strap method (ASCR pin) according to [Table 7](#). The ISL8277M uses the ChargeMode control algorithm that responds to output current changes within a single PWM switching cycle, achieving a smaller total output voltage variation with less output capacitance than traditional PWM controllers.

TABLE 7. ASCR RESISTOR SETTINGS

| ASCR GAIN | ASCR RESIDUAL | R _{SET} (kΩ) |
|-----------|---------------|------------------------|
| 120 | 90 | 10 |
| 160 | 90 | 11, or Connect to SGND |
| 200 | 90 | 12.1 |
| 250 | 90 | 13.3, or OPEN |
| 300 | 90 | 14.7 |
| 350 | 90 | 16.2 |
| 400 | 90 | 17.8 |
| 500 | 90 | 19.6 |
| 600 | 90 | 21.5 |
| 120 | 80 | 23.7 |
| 160 | 80 | 26.1 |
| 200 | 80 | 28.7 |
| 250 | 80 | 31.6 |
| 300 | 80 | 34.8 |
| 350 | 80 | 38.3 |
| 400 | 80 | 42.2 |
| 80 | 70 | 46.4 |
| 120 | 70 | 51.1 |
| 160 | 70 | 56.2 |
| 200 | 70 | 61.9 |

TABLE 7. ASCR RESISTOR SETTINGS (Continued)

| | | |
|-----|-----|------------------------|
| 250 | 70 | 68.1 |
| 300 | 70 | 75 |
| 120 | 100 | 82.5 |
| 160 | 100 | 90.9 |
| 200 | 100 | 100 |
| 250 | 100 | 110, or Connect to V25 |
| 300 | 100 | 121 |
| 350 | 100 | 133 |
| 400 | 100 | 147 |
| 500 | 100 | 162 |
| 600 | 100 | 178 |

Input Undervoltage Lockout (UVLO)

The Input Undervoltage Lockout (UVLO) prevents the ISL8277M from operating when the input falls below a preset threshold, indicating the input supply is out of its specified range. The UVLO threshold (V_{UVLO}) can be set between 4.18V and 16V using the pin-strap method as shown in [Table 8](#), or by using a PMBus command `VIN_UV_FAULT_LIMIT`.

Fault response to an input undervoltage fault can be programmed with PMBus command `VIN_UV_FAULT_RESPONSE`.

TABLE 8. UVLO RESISTOR SETTINGS

| UVLO (V) | R_{UVLO} (k Ω) |
|----------|---|
| 4.5 | 12.1, 13.3, 14.7, 16.2, 17.8, 19.6, 21.5, 23.7, OPEN, Connect to V25 and SGND |
| 4.3 | 26.1 |
| 4.59 | 28.7 |
| 5.06 | 31.6 |
| 5.57 | 34.8 |
| 6.13 | 38.3 |
| 6.75 | 42.2 |
| 7.42 | 46.4 |
| 8.18 | 51.1 |
| 10.8 | 56.2 |
| 10.8 | 61.9 |
| 10.8 | 68.1 |
| 10.8 | 75 |
| 10.8 | 82.5 |
| 10.8 | 90.9 |
| 10.8 | 100 |

SMBus Module Address Selection

Each module must have its own unique serial address to distinguish between other devices on the bus. The module address is set by connecting a resistor between the SA pin and SGND. [Table 9](#) lists the available module addresses.

TABLE 9. SMBus ADDRESS RESISTOR SELECTION

| R_{SA} (k Ω) | SMBus ADDRESS |
|-------------------------|---------------|
| 10 | 19h |
| 11 | 1Ah |
| 12.1 | 1Bh |
| 13.3 | 1Ch |
| 14.7 | 1Dh |
| 16.2 | 1Eh |
| 17.8 | 1Fh |
| 19.6 | 20h |
| 21.5 | 21h |
| 23.7 | 22h |
| 26.1 | 23h |
| 28.7 | 24h |
| 31.6 | 25h |
| 34.8 or connect to SGND | 26h |
| 38.3 | 27h |
| 42.2 or Open | 28h |
| 46.4 | 29h |
| 51.1 | 2Ah |
| 56.2 | 2Bh |
| 61.9 | 2Ch |
| 68.1 | 2Dh |
| 75 | 2Eh |
| 82.5 | 2Fh |
| 90.9 | 30h |
| 100 | 31h |

Output Overvoltage Protection

The ISL8277M offers an internal output overvoltage protection circuit that can be used to protect sensitive load circuitry from being subjected to a voltage higher than its prescribed limits. A hardware comparator is used to compare the actual output voltage (seen at the V_{SEN+} and V_{SEN-} pins) to a threshold set to 15% higher than the target output voltage (the default setting). Fault threshold can be programmed to a desired level with PMBus command `VOUT_OV_FAULT_LIMIT`. If the V_{SEN+} voltage exceeds this threshold, the module will initiate an immediate shutdown without retry. Retry settings can be programmed with PMBus command `VOUT_OV_FAULT_RESPONSE`.

Internal to the module, two 100 Ω resistors are populated from VOUT to VSEN+ and SGND to VSEN- to protect the device from overvoltage conditions in case of an open at VSENSE pins and differential remote sense traces due to assembly error. As long as differential remote sense traces have low resistance, VOUT regulation accuracy is not sacrificed.

Output Prebias Protection

An output prebias condition exists when an externally applied voltage is present on a power supply's output before the power supply's control IC is enabled. Certain applications require that the converter not be allowed to sink current during start-up if a prebias condition exists at the output. The ISL8277M provides prebias protection by sampling the output voltage prior to initiating an output ramp.

If a prebias voltage lower than the target voltage exists after the preconfigured delay period has expired, the target voltage is set to match the existing prebias voltage, and both drivers are enabled. The output voltage is then ramped to the final regulation value at the preconfigured ramp rate.

The actual time the output takes to ramp from the prebias voltage to the target voltage varies, depending on the prebias voltage, however, the total time elapsed from when the delay period expires and when the output reaches its target value will match the preconfigured ramp time (see [Figure 28](#)).

If a prebias voltage is higher than the target voltage after the preconfigured delay period has expired, the target voltage is set to match the existing prebias voltage, and both drivers are enabled with a PWM duty cycle that would ideally create the prebias voltage.

Once the preconfigured soft-start ramp period has expired, the PG pin is asserted (assuming the prebias voltage is not higher than the overvoltage limit). The PWM then adjusts its duty cycle to match the original target voltage, and the output ramps down to the preconfigured output voltage.

If a prebias voltage is higher than the overvoltage limit, the device does not initiate a turn-on sequence and declares an overvoltage fault condition. The device then responds based on the output overvoltage fault response setting programmed with PMBus command `VOUT_OV_FAULT_RESPONSE`.

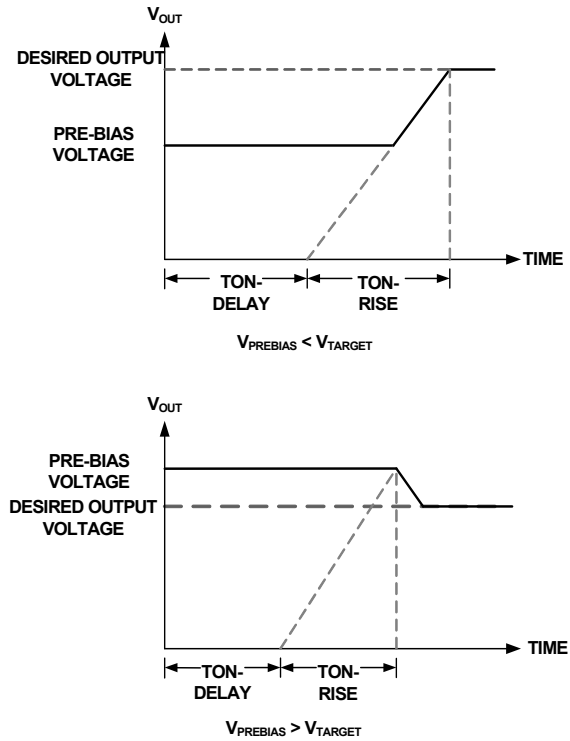


FIGURE 28. OUTPUT RESPONSES TO PRE-BIAS VOLTAGES

Output Overcurrent Protection

The ISL8277M can protect the power supply from damage if the output is shorted to ground or if an overload condition is imposed on the output. Average output overcurrent fault threshold can be programmed with PMBus command `IOUT_OC_FAULT_LIMIT`. The module automatically programs the peak inductor current fault threshold by reading real-time input voltage, switching frequency, and `VOUT_COMMAND` to calculate the inductor ripple current. When the peak inductor current crosses the peak inductor current fault threshold for five successive cycle modules, it will initiate an immediate shutdown.

The default response from an overcurrent fault is an immediate shutdown without retry. Retry settings can be programmed with PMBus command `MFR_IOUT_OC_FAULT_RESPONSE`.

Thermal Overload Protection

The ISL8277M includes a thermal sensor that continuously measures the internal temperature of the module and shuts down the controller when the temperature exceeds the preset limit. The default temperature limit is set to +125 $^{\circ}$ C in the factory, but can be changed with PMBus command `OT_FAULT_LIMIT`.

The default response from an over-temperature fault is an immediate shutdown without retry. Retry settings can be programmed with PMBus command `OT_FAULT_RESPONSE`.

If the user has configured the module to retry, the controller waits the preset delay period and then checks the module temperature. If the temperature has dropped below a threshold that is approximately +15 $^{\circ}$ C lower than the selected temperature fault limit, the controller attempts to restart. If the

temperature still exceeds the fault limit, the controller waits the preset delay period and retries the temperature.

Digital-DC Bus

The Digital-DC Communications (DDC) bus is used to communicate between Intersil digital power modules and digital controllers. This dedicated bus provides the communication channel between devices for features such as sequencing and fault spreading. The DDC pin on all Digital-DC devices in an application should be connected together. A pull-up resistor is required on the DDC bus to ensure the rise time as shown in [Equation 1](#):

$$\text{Rise Time} = R_{\text{PU}} * C_{\text{LOAD}} \approx 1 \mu\text{s} \quad (\text{EQ. 1})$$

where R_{PU} is the DDC bus pull-up resistance and C_{LOAD} is the bus loading. The pull-up resistor may be tied to an external 3.3V or 5V supply as long as this voltage is present before or during device power-up. In principle, each device connected to the DDC bus presents approximately 10pF of capacitive loading, and each inch of FR4 PCB trace introduces approximately 2pF. The ideal design uses a central pull-up resistor that is well-matched to the total load capacitance.

Phase Spreading

When multiple point-of-load converters share a common DC input supply, it is desirable to adjust the clock phase offset of each device, such that not all devices start to switch simultaneously. Setting each converter to start its switching cycle at a different point in time can dramatically reduce input capacitance requirements and efficiency losses. Because the peak current drawn from the input supply is effectively spread out over a period of time, the peak current drawn at any given moment is reduced, and the power losses proportional to the I_{RMS}^2 are reduced dramatically.

To enable phase spreading, all converters must be synchronized to the same switching clock. The phase offset of each device may also be set to any value between 0° and 360° in 22.5° increments with PMBus command INTERLEAVE.

Output Sequencing

A group of Digital-DC modules or devices may be configured to power-up in a predetermined sequence. This feature is especially useful for preventing latch-up when powering advanced processors (FPGAs and ASICs that require one supply to reach its operating voltage) prior to another supply reaching its operating voltage. Multi-device sequencing can be achieved by configuring each device with PMBus command SEQUENCE. Multiple device sequencing is configured by issuing PMBus commands to assign the preceding device in the sequencing chain as well as the device that follows in the sequencing chain.

The Enable pins of all devices in a sequencing group must be tied together and driven high to initiate a sequenced turn-on of the group. Enable must be driven low to initiate a sequenced turnoff of the group.

Fault Spreading

Digital DC modules and devices can be configured to broadcast a fault event over the DDC bus to the other devices in the group with PMBus command DDC_GROUP. When a non-destructive fault occurs and the device is configured to shutdown on a fault, the device shuts down and broadcasts the fault event over the DDC bus. The other devices on the DDC bus shutdown simultaneously, if configured to do so, and attempt to restart in their prescribed order.

Monitoring Via SMBus

A system controller can monitor a wide variety of different ISL8277M system parameters with PMBus commands:

- READ_VIN
- READ_VOUT
- READ_IOUT
- READ_INTERNAL_TEMP
- READ_EXTERNAL_TEMP
- READ_DUTY_CYCLE
- READ_FREQUENCY
- MFR_READ_VMON

Snapshot Parameter Capture

The ISL8277M offers a special feature to capture parametric data and some fault status following a fault. A detailed description is provided in [“SNAPSHOT \(EAh\)” on page 48](#).

Nonvolatile Memory

The ISL8277M has internal nonvolatile memory that stores user configurations. Integrated security measures ensure that users can only restore the module to a level that has been made available to them. During the initialization process, the ISL8277M checks for stored values contained in its internal nonvolatile memory.

Modules are shipped with factory default configurations. Most settings can be overwritten with PMBus commands and can be stored in nonvolatile memory with the PMBus command STORE_USER_ALL.

PCB Layout Guidelines

To achieve stable operation, low losses, and good thermal performance, some layout considerations are necessary.

- For $V_{\text{DD}} > 6\text{V}$, the recommended PCB layout is shown in [Figure 29](#). Leave V25, V_{DDC} , VR5, and VR6 as “No Connect (NC)”.
- For $5.5\text{V} \leq V_{\text{DD}} \leq 6\text{V}$, connect VDDC pin to VR6 pin. For $4.5 \leq V_{\text{DD}} < 5.5\text{V}$, connect VDDC pin to VR6 and VR5 pin. An RC filter is required at the input of VDRVIN pin if input supply is shared with the VIN pin.
- Establish a separate SGND plane and PGND plane, then connect the SGND to the PGND plane as shown in [Figure 30](#) in the middle layer. For making connections between SGND/PGND on the top layer and other layers, use multiple

vias for each pin to connect to the inner SGND/PGND layer. Do not connect SGND directly to PGND on a top layer. Connecting SGND directly to PGND without establishing an SGND plane will bypass the decoupling capacitor at internal reference supplies, making the controller susceptible to noise.

- Place ceramic capacitors between VIN and PGND, VOUT and PGND, and the bypass capacitors between VDD and the ground plane, as close to the module as possible to minimize high frequency noise.
- Use large copper areas for power path (VIN, PGND, VOUT) to minimize conduction loss and thermal stress. Also, use multiple vias to connect the power planes in different layers. Extra ceramic capacitors at VIN and VOUT can be placed on the bottom layer under VIN and VOUT pads when multiple vias are used for connecting copper pads on top and bottom layers.
- Connect differential remote-sensing traces to the regulation point to achieve a tight output voltage regulation. Route a trace from and V_{SEN+} to the point-of-load where the tight output voltage is desired. Avoid routing any sensitive signal traces, such as the VSENSE signal near VSWH pads.
- For noise sensitive applications, it is recommended that the user connect the VSWH pads only on the top layer; however, thermal performance will be sacrificed. External airflow might be required to keep module heat at desired level. For applications where switching noise is less critical, an excellent thermal performance can be achieved in the ISL8277M module by increasing copper mass attached to VSWH pad. To increase copper mass on the VSWH node, create copper islands in the middle and bottom layers under the VSWH pad and connect them to the top layer with multiple vias. Make sure to shield those copper islands with a PGND layer to avoid any interference to noise sensitive signals.

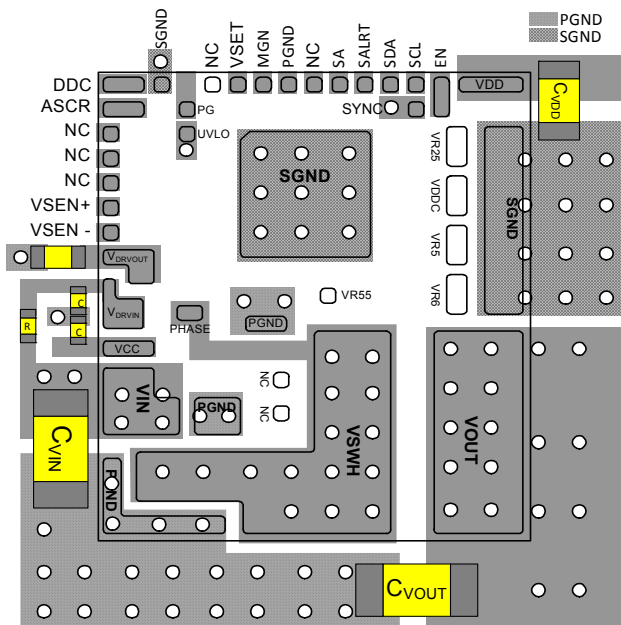


FIGURE 29. RECOMMENDED LAYOUT - TOP PCB LAYER

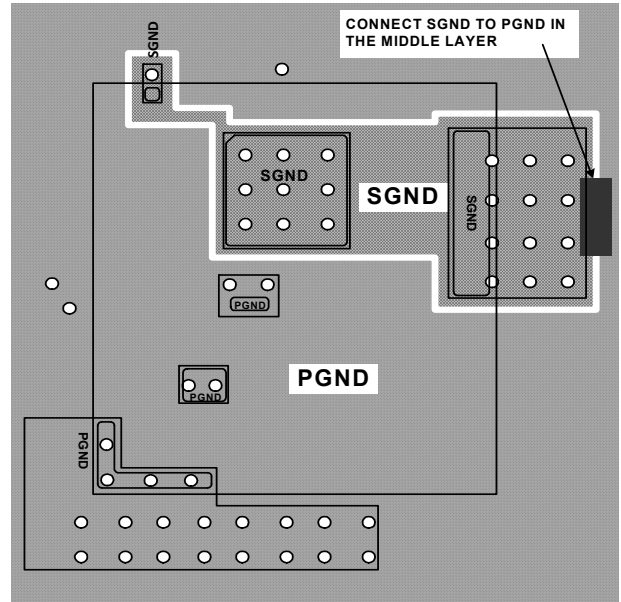


FIGURE 30. RECOMMENDED LAYOUT - CONNECT SGND TO PGND IN THE MIDDLE PCB LAYER AFTER ESTABLISHING SEPARATE SGND AND PGND

Thermal Considerations

Experimental power loss curves, along with θ_{JA} from thermal modeling analysis, can be used to evaluate the thermal consideration for the module. The derating curves are derived from the maximum power allowed while maintaining the temperature below the maximum junction temperature of +125°C. In actual application, other heat sources and design margins should be considered.

Package Description

The structure of the ISL8277M belongs to the High Density Array (HDA) no-lead package. This kind of package has advantages, such as good thermal and electrical conductivity, low weight, and small size. The HDA package is applicable for surface mounting technology and is being more readily used in the industry. The ISL8277M contains several types of devices, including resistors, capacitors, inductors, and control ICs. The ISL8277M is a copper lead-frame based package with exposed copper thermal pads, which have good electrical and thermal conductivity. The copper lead frame and multi-component assembly is over-molded with polymer mold compound to protect these devices.

The package outline, a typical PCB land pattern design, and a typical stencil opening edge position are shown in the “[Package Outline Drawing](#)” section starting on [page 51](#). The module has a small size of 17mmx19mmx3.6mm. [Figure 31](#) shows typical reflow profile parameters. These guidelines are general design rules. Users can modify parameters according to their application.

PCB Layout Pattern Design

The bottom of the ISL8277M is a lead-frame footprint, which is attached to the PCB by surface mounting process. The PCB land pattern is shown in the [“Package Outline Drawing”](#) section starting on [page 51](#).

The PCB layout pattern is an array of solder mask defined PCB lands which align with the perimeters of the HDA exposed pads and I/O termination dimensions. The thermal lands on the PCB layout also feature an array of solder mask defined lands and should match 1:1 with the package exposed die pad perimeters. The exposed solder mask defined PCB land area should be 50-80% of the available module I/O area.

Thermal Vias

A grid of 1.0mm to 1.2mm pitch thermal vias, which drops down and connects to buried copper plane(s), should be placed under the thermal land. The vias should be about 0.3mm to 0.33mm in diameter with the barrel plated to about 1.0 ounce copper. Although adding more vias (by decreasing via pitch) will improve the thermal performance, diminishing returns will be seen as more and more vias are added. Simply use as many vias as practical for the thermal land size and that your board design rules will allow.

Stencil Pattern Design

Reflowed solder joints on the perimeter I/O lands should have about a 50µm to 75µm (2mil to 3mil) standoff height. The solder paste stencil design is the first step in developing optimized, reliable solder joints.

The stencil aperture size to solder mask defined PCB land size ratio should typically be 1:1. The aperture width can be reduced slightly to help prevent solder bridging between adjacent I/O lands. A typical solder stencil pattern is shown in the [“Package Outline Drawing”](#) section starting on [page 51](#).

The user should consider the symmetry of the whole stencil pattern when designing its pads. A laser cut, stainless steel stencil with electropolished trapezoidal walls is recommended. Electropolishing “smooths” the aperture walls resulting in reduced surface friction and better paste release, which reduces voids. Using a Trapezoidal Section Aperture (TSA) also promotes paste release and forms a “brick like” paste deposit that assists in firm component placement. A 0.1mm to 0.15mm stencil thickness is recommended for this large pitch (1.3mm) HDA.

Reflow Parameters

Due to the low mount height of the HDA, a “No Clean” Type 3 solder paste per ANSI/J-STD-005 is recommended. Nitrogen purge is also recommended during reflow. A system board reflow profile depends on the thermal mass of the entire populated board, thus it is not practical to define a specific soldering profile just for the HDA. The profile given in [Figure 31](#) is provided as a guideline, to be customized for varying manufacturing practices and applications

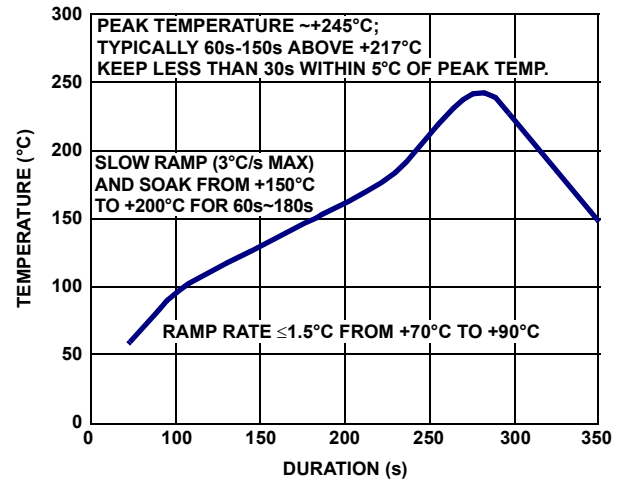


FIGURE 31. TYPICAL REFLOW PROFILE

PMBus Command Summary

| COMMAND CODE | COMMAND NAME | DESCRIPTION | TYPE | DATA FORMAT | DEFAULT VALUE | DEFAULT SETTING | PAGE |
|--------------|------------------------|--|-----------|-------------|---------------|--------------------------------|--------------------|
| 01h | OPERATION | Sets Enable, Disable, and V_{OUT} Margin modes. | R/W BYTE | BIT | | | 28 |
| 02h | ON_OFF_CONFIG | Configures the EN pin and PMBus commands to turn the unit ON/OFF. | R/W BYTE | BIT | 17h | Hardware Enable, Immediate Off | 28 |
| 03h | CLEAR_FAULTS | Clears fault indications. | SEND BYTE | | | | 29 |
| 15h | STORE_USER_ALL | Stores all PMBus values written since last restore at user level. | SEND BYTE | | | | 29 |
| 16h | RESTORE_USER_ALL | Restores PMBus settings that were stored using STORE_USER_ALL. | SEND BYTE | | | | 29 |
| 20h | VOUT_MODE | Preset to defined data format of V_{OUT} commands. | READ BYTE | BIT | 13h | Linear Mode, Exponent = -13 | 29 |
| 21h | VOUT_COMMAND | Sets the nominal value of the output voltage. | R/W WORD | L16u | | Pin-strap | 29 |
| 23h | VOUT_CAL_OFFSET | Applies a fixed offset voltage to the VOUT_COMMAND. | R/W WORD | L16s | 0000h | 0V | 30 |
| 24h | VOUT_MAX | Sets the maximum possible value of V_{OUT} . 110% of pin-strap V_{OUT} . | R/W WORD | L16u | | 1.1 * V_{OUT} Pin-strap | 30 |
| 25h | VOUT_MARGIN_HIGH | Sets the value of the V_{OUT} during a margin high. | R/W WORD | L16u | | 1.05 * V_{OUT} Pin-strap | 30 |
| 26h | VOUT_MARGIN_LOW | Sets the value of the V_{OUT} during a margin low. | R/W WORD | L16u | | 0.95 * V_{OUT} Pin-strap | 30 |
| 27h | VOUT_TRANSITION_RATE | Sets the transition rate during margin or other change of V_{OUT} . | R/W WORD | L11 | BA00h | 1V/ms | 30 |
| 28h | VOUT_DROOP | Sets the loadline (V/I Slope) resistance for the rail. | R/W WORD | L11 | 0000h | 0mV/A | 31 |
| 33h | FREQUENCY_SWITCH | Sets the switching frequency. | R/W WORD | L11 | | Pin-strap | 31 |
| 37h | INTERLEAVE | Configures a phase offset between devices sharing a SYNC clock. | R/W WORD | BIT | | Set based on PMBus Address | 31 |
| 38h | IOUT_CAL_GAIN | Sense resistance for inductor DCR current sensing. | R/W WORD | L11 | B380h | 0.875m Ω | 31 |
| 39h | IOUT_CAL_OFFSET | Sets the current-sense offset. | R/W WORD | L11 | 0000h | 0A | 31 |
| 40h | VOUT_OV_FAULT_LIMIT | Sets the V_{OUT} overvoltage fault threshold. | R/W WORD | L16u | | 1.15 * V_{OUT} Pin-strap | 32 |
| 41h | VOUT_OV_FAULT_RESPONSE | Configures the V_{OUT} overvoltage fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 32 |
| 42h | VOUT_OV_WARN_LIMIT | Sets the V_{OUT} overvoltage warn threshold. | R/W WORD | L16u | | 1.10 * V_{OUT} Pin-strap | 32 |
| 43h | VOUT_UV_WARN_LIMIT | Sets the V_{OUT} undervoltage warn threshold. | R/W WORD | L16u | | 0.9 * V_{OUT} Pin-Strap | 32 |
| 44h | VOUT_UV_FAULT_LIMIT | Sets the V_{OUT} undervoltage fault threshold. | R/W WORD | L16u | | 0.85 * V_{OUT} Pin-strap | 32 |
| 45h | VOUT_UV_FAULT_RESPONSE | Configures the V_{OUT} undervoltage fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 33 |
| 46h | IOUT_OC_FAULT_LIMIT | Sets the I_{OUT} average overcurrent fault threshold. | R/W WORD | L11 | DBC0h | 30A | 33 |
| 4Bh | IOUT_UC_FAULT_LIMIT | Sets the I_{OUT} average undercurrent fault threshold. | R/W WORD | L11 | DC3Fh | -30A | 33 |
| 4Fh | OT_FAULT_LIMIT | Sets the over-temperature fault threshold. | R/W WORD | L11 | EBE8h | +125°C | 33 |

PMBus Command Summary (Continued)

| COMMAND CODE | COMMAND NAME | DESCRIPTION | TYPE | DATA FORMAT | DEFAULT VALUE | DEFAULT SETTING | PAGE |
|--------------|-----------------------|---|-----------|-------------|---------------|-------------------------|--------------------|
| 50h | OT_FAULT_RESPONSE | Configures the over-temperature fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 33 |
| 51h | OT_WARN_LIMIT | Sets the over-temperature warning limit. | R/W WORD | L11 | Eb70h | +110 °C | 34 |
| 52h | UT_WARN_LIMIT | Sets the under-temperature warning limit. | R/W WORD | L11 | DC40h | -30 °C | 34 |
| 53h | UT_FAULT_LIMIT | Sets the under-temperature fault threshold. | R/W WORD | L11 | E530h | -45 °C | 34 |
| 54h | UT_FAULT_RESPONSE | Configures the under-temperature fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 34 |
| 55h | VIN_OV_FAULT_LIMIT | Sets the V_{IN} overvoltage fault threshold. | R/W WORD | L11 | D3A0h | 14.5V | 34 |
| 56h | VIN_OV_FAULT_RESPONSE | Configures the V_{IN} overvoltage fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 35 |
| 57h | VIN_OV_WARN_LIMIT | Sets the input overvoltage warning limit. | R/W WORD | L11 | D343h | 13.05V | 35 |
| 58h | VIN_UV_WARN_LIMIT | Sets the input undervoltage warning limit. | R/W WORD | L11 | | 1.10*VIN UV Fault Limit | 35 |
| 59h | VIN_UV_FAULT_LIMIT | Sets the V_{IN} undervoltage fault threshold. | R/W WORD | L11 | | Pin-Strap | 35 |
| 5Ah | VIN_UV_FAULT_RESPONSE | Configures the V_{IN} undervoltage fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 36 |
| 5Eh | POWER_GOOD_ON | Sets the voltage threshold for Power-good indication. | R/W WORD | L16u | | 0.9*VOUT Pin-strap | 36 |
| 60h | TON_DELAY | Sets the delay time from ENABLE to start of V_{OUT} rise. | R/W WORD | L11 | | Pin-Strap | 36 |
| 61h | TON_RISE | Sets the rise time of V_{OUT} after ENABLE and TON_DELAY. | R/W WORD | L11 | | Pin-Strap | 36 |
| 64h | TOFF_DELAY | Sets the delay time from DISABLE to start of V_{OUT} fall. | R/W WORD | L11 | | Pin-Strap | 36 |
| 65h | TOFF_FALL | Sets the fall time for V_{OUT} after DISABLE and TOFF_DELAY. | R/W WORD | L11 | | Pin-Strap | 37 |
| 78h | STATUS_BYTE | Returns an abbreviated status for fast reads. | READ BYTE | BIT | 00h | No Faults | 37 |
| 79h | STATUS_WORD | Returns information with a summary of the unit's fault condition. | READ WORD | BIT | 0000h | No Faults | 38 |
| 7Ah | STATUS_VOUT | Returns the V_{OUT} specific status. | READ BYTE | BIT | 00h | No Faults | 38 |
| 7Bh | STATUS_IOUT | Returns the I_{OUT} specific status. | READ BYTE | BIT | 00h | No Faults | 39 |
| 7Ch | STATUS_INPUT | Returns specific status specific to the input. | READ BYTE | BIT | 00h | No Faults | 39 |
| 7Dh | STATUS_TEMP | Returns the temperature specific status. | READ BYTE | BIT | 00h | No Faults | 39 |
| 7Eh | STATUS_CML | Returns the Communication, Logic, and Memory specific status. | READ BYTE | BIT | 00h | No Faults | 40 |
| 80h | STATUS_MFR_SPECIFIC | Returns the VMON and External Sync clock specific status. | READ BYTE | BIT | 00h | No Faults | 40 |
| 88h | READ_VIN | Returns the input voltage reading. | READ WORD | L11 | | | 40 |
| 8Bh | READ_VOUT | Returns the output voltage reading. | READ WORD | L16u | | | 40 |

PMBus Command Summary (Continued)

| COMMAND CODE | COMMAND NAME | DESCRIPTION | TYPE | DATA FORMAT | DEFAULT VALUE | DEFAULT SETTING | PAGE |
|--------------|----------------------------|---|-------------|-------------|---------------|--------------------------------|--------------------|
| 8Ch | READ_IOUT | Returns the output current reading. | READ WORD | L11 | | | 41 |
| 8Dh | READ_INTERNAL_TEMP | Returns the temperature reading internal to the device. | READ WORD | L11 | | | 41 |
| 8Eh | READ_EXTERNAL_TEMP | Returns the temperature reading from external monitor source. | READ WORD | L11 | | | 41 |
| 94h | READ_DUTY_CYCLE | Returns the duty cycle reading during the ENABLE state. | READ WORD | L11 | | | 41 |
| 95h | READ_FREQUENCY | Returns the measured operating switch frequency. | READ WORD | L11 | | | 41 |
| 99h | MFR_ID | Sets a user defined identification. | R/W BLOCK | ASCII | | Null | 41 |
| 9Ah | MFR_MODEL | Sets a user defined model. | R/W BLOCK | ASCII | | Null | 42 |
| 9Bh | MFR_REVISION | Sets a user defined revision. | R/W BLOCK | ASCII | | Null | 42 |
| 9Ch | MFR_LOCATION | Sets a user defined location identifier. | R/W BLOCK | ASCII | | Null | 42 |
| 9Dh | MFR_DATE | Sets a user defined date. | R/W BLOCK | ASCII | | Null | 42 |
| 9Eh | MFR_SERIAL | Sets a user defined serialized identifier. | R/W BLOCK | ASCII | | Null | 42 |
| A8h | LEGACY_FAULT_GROUP | Broadcast faults when mixed with old generation modules | R/W BLOCK | BIT | 0000000h | | 43 |
| B0h | USER_DATA_00 | Sets a user defined data. | R/W BLOCK | ASCII | | Null | 43 |
| D0h | ISENSE_CONFIG | Configures ISENSE related features. | R/W BYTE | BIT | 05h | 256ns Blanking Time, Mid Range | 44 |
| D1h | USER_CONFIG | Configures several user-level features. | R/W BYTE | BIT | 00h | Open-drain PG, XTEMP Disabled | 44 |
| D3h | DDC_CONFIG | Configures the DDC bus. | R/W BYTE | BIT | 00h | Set based on PMBus Address | 45 |
| D4h | POWER_GOOD_DELAY | Sets the delay between $V_{OUT} > PG$ threshold and asserting the PG pin. | R/W WORD | L11 | CA00h | 4ms | 45 |
| DFh | ASCR_CONFIG | Configures ASCR control loop. | R/W BLOCK | CUS | | Pin-Strap | 45 |
| E0h | SEQUENCE | Identifies the Rail DDC ID to perform multi-rail sequencing. | R/W WORD | BIT | 0000h | Prequel and Sequel Disabled | 46 |
| E2h | DDC_GROUP | Sets rail DDC IDs to obey faults and margining spreading information. | R/W BLOCK | BIT | 000000h | Broadcast Disabled | 46 |
| E4h | DEVICE_ID | Returns the 16-byte (character) device identifier string. | READ BLOCK | ASCII | | Reads Device Version | 47 |
| E5h | MFR_IOUT_OC_FAULT_RESPONSE | Configures the I_{OUT} overcurrent fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 47 |
| E6h | MFR_IOUT_UC_FAULT_RESPONSE | Configures the I_{OUT} undercurrent fault response. | R/W BYTE | BIT | 80h | Disable and No Retry | 47 |
| E9h | SYNC_CONFIG | Configures the Sync pin. | R/W BYTE | BIT | 00h | | 47 |
| EAh | SNAPSHOT | Returns 32-byte read-back of parametric and status values. | READ BLOCK | BIT | | | 48 |
| EBh | BLANK_PARAMS | Returns recently changed parameter values. | READ BLOCK | BIT | FF...FFh | | 48 |
| F3h | SNAPSHOT_CONTROL | Snapshot feature control command. | W BYTE | BIT | | | 48 |
| F4h | RESTORE_FACTORY | Restores device to the factory default values. | WRITE BLOCK | | | | 49 |

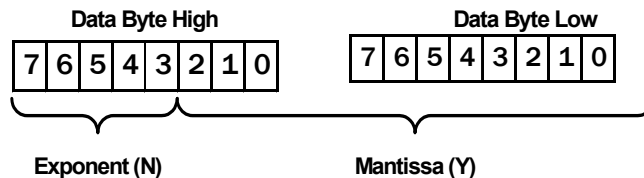
PMBus Command Summary (Continued)

| COMMAND CODE | COMMAND NAME | DESCRIPTION | TYPE | DATA FORMAT | DEFAULT VALUE | DEFAULT SETTING | PAGE |
|--------------|-------------------------|--|-----------|-------------|---------------|----------------------|--------------------|
| F5h | MFR_VMON_OV_FAULT_LIMIT | Returns the VMON overvoltage threshold. | READ WORD | L11 | CB00h | 6V | 49 |
| F6h | MFR_VMON_UV_FAULT_LIMIT | Returns the VMON undervoltage threshold. | READ WORD | L11 | CA00h | 4V | 49 |
| F7h | MFR_READ_VMON | Returns the VMON voltage reading. VMON is used to monitor VDRVOUT (Pin 8) voltage through an internal 16:1 resistor divider. | READ WORD | L11 | | | 49 |
| F8h | VMON_OV_FAULT_RESPONSE | Returns the VMON overvoltage response. | READ BYTE | BIT | 80h | Disable and No Retry | 49 |
| F9h | VMON_UV_FAULT_RESPONSE | Returns the VMON undervoltage response. | READ BYTE | BIT | 80h | Disable and No Retry | 49 |

PMBus Data Formats

Linear-11 (L11)

L11 data format uses 5-bit two's complement exponent (N) and 11-bit two's complement mantissa (Y) to represent real world decimal value (X).



Relation between real world decimal value (X), N and Y is: $X = Y \cdot 2^N$

Linear-16 Unsigned (L16u)

The L16u data format uses a fixed exponent (hard-coded to $N = -13h$) and a 16-bit unsigned integer mantissa (Y) to represent real world decimal value (X). Relation between real world decimal value (X), N and Y is: $X = Y \cdot 2^{-13}$

Linear-16 Signed (L16s)

The L16s data format uses a fixed exponent (hard-coded to $N = -13h$) and a 16-bit two's complement mantissa (Y) to represent real world decimal value (X).

Relation between real world decimal value (X), N, and Y is: $X = Y \cdot 2^{-13}$

Bit Field (BIT)

A break down of Bit Field is provided in PMBus on [“PMBus Command Descriptions” on page 28](#).

Custom (CUS)

A break down of custom data format is provided in PMBus [“PMBus Command Descriptions” on page 28](#). A combination of Bit Field and integer are common type of custom data format.

ASCII (ASC)

A variable length string of text characters that uses the ASCII data format.

PMBus Use Guidelines

The PMBus is a powerful tool that allows the user to optimize circuit performance by configuring devices for their application. When configuring a device in a circuit, the device should be disabled whenever most settings are changed with PMBus commands. Some exceptions to this recommendation are OPERATION, ON_OFF_CONFIG, CLEAR_FAULTS, VOUT_COMMAND, VOUT_MARGIN_HIGH, VOUT_MARGIN_LOW, and ASCCR_CONFIG. Any command can be read while the device is enabled. Many commands do not take effect until after the device has been re-enabled, hence the recommendation that commands that change device settings are written while the device is disabled.

When sending the STORE_DEFAULT_ALL, STORE_USER_ALL, RESTORE_DEFAULT_ALL, and RESTORE_USER_ALL commands, it is recommended that no other commands are sent to the device for 100ms after sending STORE or RESTORE commands.

In addition, there should be a 2ms delay between repeated READ commands sent to the same device. When sending any other command, a 5ms delay is recommended between repeated commands sent to the same device.

Summary

All commands can be read at any time.

Always disable the device when writing commands that change device settings. Exceptions to this rule are commands intended to be written while the device is enabled, for example, VOUT_MARGIN_HIGH.

To be sure a change to a device setting has taken effect, write the STORE_USER_ALL command, then cycle input power and re-enable.

PMBus Command Descriptions

OPERATION (01h)

Definition: Sets Enable, Disable, and V_{OUT} Margin settings. Data values of OPERATION that force margin high or low only take effect when the MGN pin is left open (i.e., in the NOMINAL margin state).

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value:

Units: N/A

| SETTINGS | ACTIONS |
|----------|-------------------------------|
| 04h | Immediate off (no sequencing) |
| 44h | Soft off (with sequencing) |
| 84h | On - Nominal |
| 94h | On - Margin low |
| A4h | On - Margin high |

ON_OFF_CONFIG (02h)

Definition: Configures the interpretation and coordination of the OPERATION command and the ENABLE pin (EN).

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 17h (Device starts from ENABLE pin with immediate off)

Units: N/A

| SETTINGS | ACTIONS |
|----------|---|
| 00h | Device starts any time power is present regardless of ENABLE pin or OPERATION command states. |
| 16h | Device starts from ENABLE pin with soft off. |
| 17h | Device starts from ENABLE pin with immediate off. |
| 1Ah | Device starts from OPERATION command. |

CLEAR_FAULTS (03h)

Definition: Clears all fault bits in all registers and releases the SALRT pin (if asserted) simultaneously. If a fault condition still exists, the bit will reassert immediately. This command will not restart a device if it has shut down, it will only clear the faults.

Data Length in Bytes: 0 Byte

Data Format: N/A

Type: Send only

Default Value: N/A

Units: N/A

Reference: N/A

STORE_USER_ALL (15h)

Definition: Stores all PMBus settings from the operating memory to the nonvolatile USER store memory. To clear the USER store, perform a RESTORE_FACTORY then STORE_USER_ALL. To add to the USER store, perform a RESTORE_USER_ALL, write commands to be added, then STORE_USER_ALL. This command can be used during device operation, but the device will be unresponsive for 20ms while storing values.

Data Length in Bytes: 0

Data Format: N/A

Type: Send only

Default Value: N/A

Units: N/A

RESTORE_USER_ALL (16h)

Definition: Restores all PMBus settings from the USER store memory to the operating memory. Command performed at power-up. Security level is changed to Level 1 following this command. This command can be used during device operation, but the device will be unresponsive for 20ms while storing values.

Data Length in Bytes: 0

Data Format: N/A

Type: Send only

Default Value: N/A

Units: N/A

VOUT_MODE (20h)

Definition: Reports the V_{OUT} mode and provides the exponent used in calculating several V_{OUT} settings. Fixed with linear mode with default exponent (N) = -13

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 13h (Linear Mode, N = -13)

Units: N/A

VOUT_COMMAND (21h)

Definition: Sets or reports the target output voltage. This command cannot set a value higher than either V_{OUT_MAX} or 110% of the pin-strap V_{OUT} setting.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: Pin-strap setting

Units: Volts

Range: 0V to V_{OUT_MAX}

VOUT_CAL_OFFSET (23h)

Definition: Applies a fixed offset voltage to the output voltage command value. This command is typically used by the user to calibrate a device in the application circuit.

Data Length in Bytes: 2

Data Format: L16s

Type: R/W

Default Value: 0000h

Units: Volts

VOUT_MAX (24h)

Definition: Sets an upper limit on the output voltage the unit can command regardless of any other commands or combinations. The intent of this command is to provide a safeguard against a user accidentally setting the output voltage to a possibly destructive level rather than to be the primary output overprotection. Default value can be changed via PMBus.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: 1.10xVOUT_COMMAND pin-strap setting

Units: Volts

Range: 0V to 6V

VOUT_MARGIN_HIGH (25h)

Definition: Sets the value of the V_{OUT} during a margin high. This VOUT_MARGIN_HIGH command loads the unit with the voltage to which the output is to be changed when the OPERATION command is set to "Margin High".

Data Length in Bytes: 2

Data Format: L16u

Type: R/W word

Default value: 1.05 x VOUT_COMMAND pin-strap setting

Units: V

Range: 0V to VOUT_MAX

VOUT_MARGIN_LOW (26h)

Definition: Sets the value of the V_{OUT} during a margin low. This VOUT_MARGIN_LOW command loads the unit with the voltage to which the output is to be changed when the OPERATION command is set to "Margin Low".

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default value: 0.95 x VOUT_COMMAND pin-strap setting

Units: V

Range: 0V to VOUT_MAX

VOUT_TRANSITION_RATE (27h)

Definition: Sets the rate at which the output should change voltage when the device receives an OPERATION command (Margin High, Margin Low) that causes the output voltage to change. The maximum possible positive value of the two data bytes indicates that the device should make the transition as quickly as possible.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default value: BA00h (1.0 V/ms)

Units: V/ms

Range: 0.1 to 4V/ms

VOUT_DROOP (28h)

Definition: Sets the effective load line (V/I slope) for the rail in which the device is used. It is the rate, in mV/A, at which the output voltage decreases (or increases) with increasing (or decreasing) output current for use with Adaptive Voltage Positioning schemes.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default value: 0000h (0mV/A)

Units: mV/A

Range: 0 to 40mV/A

FREQUENCY_SWITCH (33h)

Definition: Sets the switching frequency of the device. Initial default value is defined by a pin-strap and this value can be overridden by writing this command via PMBus. If an external SYNC is utilized, this value should be set as close as possible to the external clock value. The output must be disabled when writing this command.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: Pin-strap setting

Units: kHz

Range: 300kHz to 1066MHz

INTERLEAVE (37h)

Definition: Configures the phase offset of a device that is sharing a common SYNC clock with other devices. A value of 0 for the number in group field is interpreted as 16 to allow for phase spreading groups of up to 16 devices.

Data Length in Bytes: 2

Data Format: BIT

Type: R/W

Default Value: Pin-strap setting

Units: kHz

| BITS | PURPOSE | VALUE | DESCRIPTION |
|------|-------------------|---------|---|
| 15:2 | Reserved | 0 | Reserved |
| 11:8 | Group Number | 0 to 15 | Sets a number to a group of interleaved rails |
| 7:4 | Number in Group | 0 to 15 | Sets the number of rails in the group A value of 0 is interpreted as 16 |
| 3:0 | Position in Group | 0 to 15 | Sets position of the device's rail within the group |

IOUT_CAL_GAIN (38h)

Definition: Sets the effective impedance across the current sense circuit for use in calculating output current at +25°C.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: B380h (0.875mΩ)

Units: mΩ

IOUT_CAL_OFFSET (39h)

Definition: Used to null out any offsets in the output current-sensing circuit, and to compensate for delayed measurements of current ramp due to Isense blanking time.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: 0000h (0A)

Units: A

VOUT_OV_FAULT_LIMIT (40h)

Definition: Sets the V_{OUT} overvoltage fault threshold.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: 1.15xVOUT_COMMAND pin-strap setting

Units: V

Range: 0V to VOUT_MAX

VOUT_OV_FAULT_RESPONSE (41h)

Definition: Configures the V_{OUT} overvoltage fault response. Note that the device cannot be set to ignore this fault mode.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable and no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|--|
| 80h | Disable with no retry |
| BFh | Disable and continuous retry with 70ms delay |

VOUT_OV_WARNING_LIMIT (42h)

Definition: Sets the V_{OUT} overvoltage warning threshold. Power-good signal is pulled low when output voltage goes higher than this threshold.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: 1.1xVOUT_COMMAND pin-strap setting

Units: V

Range: 0V to VOUT_MAX

VOUT_UV_WARNING_LIMIT (43h)

Definition: Sets the V_{OUT} undervoltage warning threshold. Power-good signal is pulled low when output voltage goes lower than this threshold.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: 0.9xVOUT_COMMAND pin-strap setting

Units: V

Range: 0V to VOUT_MAX

VOUT_UV_FAULT_LIMIT (44h)

Definition: Sets the V_{OUT} undervoltage fault threshold. This fault is masked during ramp or when disabled.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: 0.85xVOUT_COMMAND pin-strap setting

Units: V

Range: 0V to VOUT_MAX

VOUT_UV_FAULT_RESPONSE (45h)

Definition: Configures the V_{OUT} undervoltage fault response.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable, no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|--|
| 80h | Disable with no retry |
| BFh | Disable and continuous retry with 70ms delay |

IOUT_OC_FAULT_LIMIT (46h)

Definition: Sets the I_{OUT} average overcurrent fault threshold. Device will automatically calculate peak inductor overcurrent fault limit.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: DBC0h 30A

Units: A

Range: -100 to 100A

IOUT_UC_FAULT_LIMIT (4Bh)

Definition: Sets the I_{OUT} average undercurrent fault threshold. Device will automatically calculate valley inductor undercurrent fault limit.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: DC3Fh -30A

Units: A

Range: -100 to 100A

OT_FAULT_LIMIT (4Fh)

Definition: Sets the temperature at which the device should indicate an over-temperature fault. Note that the temperature must drop below OT_WARN_LIMIT to clear this fault.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: EBE8h (+125°C)

Units: Celsius

Range: 0°C to +175°C

OT_FAULT_RESPONSE (50h)

Definition: Instructs the device on what action to take in response to an over-temperature fault.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Fault Value: 80h (Disable and no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|--|
| 80h | Disable with no retry |
| BFh | Disable and continuous retry with 70ms delay |

OT_WARN_LIMIT (51h)

Definition: Sets the temperature at which the device should indicate an over-temperature warning alarm. In response to the OT_WARN_LIMIT being exceeded, the device: Sets the TEMPERATURE bit in STATUS_WORD, sets the OT_WARNING bit in STATUS_TEMPERATURE, and notifies the host.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: EB70h (+110 °C)

Units: Celsius

Range: 0 °C to +175 °C

UT_WARN_LIMIT (52h)

Definition: Sets the temperature at which the device should indicate an under-temperature warning alarm. In response to the UT_WARN_LIMIT being exceeded, the device: Sets the TEMPERATURE bit in STATUS_WORD, sets the UT_WARNING bit in STATUS_TEMPERATURE, and notifies the host.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: DC40h (-30 °C)

Units: Celsius

Range: -55 °C to +25 °C

UT_FAULT_LIMIT (53h)

Definition: Sets the temperature, in degrees Celsius, of the unit where it should indicate an under-temperature fault. Note that the temperature must rise above UT_WARN_LIMIT to clear this fault.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: E530h (-45 °C)

Units: Celsius

Range: -55 °C to +25 °C

UT_FAULT_RESPONSE (54h)

Definition: Configures the under-temperature fault response as defined by the following table. The delay time is the time between restart attempts.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable, no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|--|
| 80h | Disable with no retry |
| BFh | Disable and continuous retry with 70ms delay |

VIN_OV_FAULT_LIMIT (55h)

Definition: Sets the V_{IN} overvoltage fault threshold.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: D3A0h (14.5V)

Units: V

Range: 0V to 16V

VIN_OV_FAULT_RESPONSE (56h)

Definition: Configures the V_{IN} overvoltage fault response as defined by the following table. The delay time is the time between restart attempts.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable and no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|--|
| 80h | Disable with no retry |
| BFh | Disable and continuous retry with 70ms delay |

VIN_OV_WARN_LIMIT (57h)

Definition: Sets the V_{IN} overvoltage warning threshold as defined by the table below. In response to the OV_WARN_LIMIT being exceeded, the device: Sets the NONE OF THE ABOVE and INPUT bits in STATUS_WORD, sets the VIN_OV_WARNING bit in STATUS_INPUT, and notifies the host.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Protectable: Yes

Default Value: D343h (13.05V)

Units: V

Range: 0V to 16V

VIN_UV_WARN_LIMIT (58h)

Definition: Sets the V_{IN} undervoltage warning threshold. If a VIN_UV_FAULT occurs, the input voltage must rise above VIN_UV_WARN_LIMIT to clear the fault, which provides hysteresis to the fault threshold. In response to the UV_WARN_LIMIT being exceeded, the device: Sets the NONE OF THE ABOVE and INPUT bits in STATUS_WORD, sets the VIN_UV_WARNING bit in STATUS_INPUT, and notifies the host.

Data Length in Bytes: 2

Data Format: Linear-11

Type: R/W

Default Value: 1.1 x VIN_UV_FAULT_LIMIT pin-strap setting

Units: V

Range: 0V to 12V

VIN_UV_FAULT_LIMIT (59h)

Definition: Sets the V_{IN} undervoltage fault threshold.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: Pin-strap setting

Units: V

Range: 0V to 12V

VIN_UV_FAULT_RESPONSE (5Ah)

Definition: Configures the V_{IN} undervoltage fault response as defined by the following table. The delay time is the time between restart attempts.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable and no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|--|
| 80h | Disable with no retry |
| BFh | Disable and continuous retry with 70ms delay |

POWER_GOOD_ON (5Eh)

Definition: Sets the voltage threshold for Power-good indication. Power-good asserts when the output voltage exceeds POWER_GOOD_ON and de-asserts when the output voltage is less than VOUT_UV_FAULT_LIMIT.

Data Length in Bytes: 2

Data Format: L16u

Type: R/W

Default Value: 0.9xVOUT_COMMAND pin-strap setting

Units: V

TON_DELAY (60h)

Definition: Sets the delay time from when the device is enabled to the start of V_{OUT} rise.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: CA80h, 5 ms

Units: ms

Range: 0 to 500ms

TON_RISE (61h)

Definition: Sets the rise time of V_{OUT} after ENABLE and TON_DELAY.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: CA80h, 5 ms

Units: ms

Range: 0 to 200ms

TOFF_DELAY (64h)

Definition: Sets the delay time from DISABLE to start of V_{OUT} fall.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: CA80h, 5 ms

Units: ms

Range: 0 to 500 seconds

TOFF_FALL (65h)

Definition: Sets the fall time for V_{OUT} after DISABLE and TOFF_DELAY.

Data Length in Bytes: 2

Data Format: L11

Type: R/W

Default Value: CA80h, 5 ms

Units: ms

Range: 0 to 200ms

STATUS_BYTE (78h)

Definition: Returns one byte of information with a summary of the most critical faults.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 00h

Units: N/A

| BIT NUMBER | STATUS BIT NAME | MEANING |
|------------|-------------------|--|
| 7 | BUSY | A fault was declared because the device was busy and unable to respond. |
| 6 | OFF | This bit is asserted if the unit is not providing power to the output, regardless of the reason, including simply not being enabled. |
| 5 | VOUT_OV_FAULT | An output overvoltage fault has occurred. |
| 4 | IOUT_OC_FAULT | An output overcurrent fault has occurred. |
| 3 | VIN_UV_FAULT | An input undervoltage fault has occurred. |
| 2 | TEMPERATURE | A temperature fault or warning has occurred. |
| 1 | CML | A communications, memory, or logic fault has occurred. |
| 0 | NONE OF THE ABOVE | A fault or warning not listed in Bits 7:1 has occurred. |

STATUS_WORD (79h)

Definition: Returns two bytes of information with a summary of the unit's fault condition. Based on the information in these bytes, the host can get more information by reading the appropriate status registers. The low byte of the STATUS_WORD is the same register as the STATUS_BYTE (78h) command.

Data Length in Bytes: 2

Data Format: BIT

Type: Read only

Default Value: 0000h

Units: N/A

| BIT NUMBER | STATUS BIT NAME | MEANING |
|------------|-------------------|--|
| 15 | VOUT | An output voltage fault or warning has occurred. |
| 14 | IOUT/POUT | An output current or output power fault or warning has occurred. |
| 13 | INPUT | An input voltage, input current, or input power fault or warning has occurred. |
| 12 | MFG_SPECIFIC | A manufacturer specific fault or warning has occurred. |
| 11 | POWER_GOOD# | The POWER_GOOD signal, if present, is negated. |
| 10 | FANS | A fan or airflow fault or warning has occurred. |
| 9 | OTHER | A bit in STATUS_OTHER is set. |
| 8 | UNKNOWN | A fault type not given in Bits 15:1 of the STATUS_WORD has been detected. |
| 7 | BUSY | A fault was declared because the device was busy and unable to respond. |
| 6 | OFF | This bit is asserted if the unit is not providing power to the output, regardless of the reason, including simply not being enabled. |
| 5 | VOUT_OV_FAULT | An output overvoltage fault has occurred. |
| 4 | IOUT_OC_FAULT | An output overcurrent fault has occurred. |
| 3 | VIN_UV_FAULT | An input undervoltage fault has occurred. |
| 2 | TEMPERATURE | A temperature fault or warning has occurred. |
| 1 | CML | A communications, memory or logic fault has occurred. |
| 0 | NONE OF THE ABOVE | A fault or warning not listed in Bits 7:1 has occurred. |

STATUS_VOUT (7Ah)

Definition: Returns one data byte with the status of the output voltage.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 00h

Units: N/A

| BIT NUMBER | STATUS BIT NAME | MEANING |
|------------|-----------------|---|
| 7 | VOUT_OV_FAULT | Indicates an output overvoltage fault. |
| 6 | VOUT_OV_WARNING | Indicates an output overvoltage warning. |
| 5 | VOUT_UV_WARNING | Indicates an output undervoltage warning. |
| 4 | VOUT_UV_FAULT | Indicates an output undervoltage fault. |
| 3:0 | N/A | These bits are not used. |

STATUS_IOUT (7Bh)

Definition: Returns one data byte with the status of the output current.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 00h

Units: N/A

| BIT NUMBER | STATUS BIT NAME | MEANING |
|------------|------------------|---|
| 7 | IOUT_OC_FAULT | An output overcurrent fault has occurred. |
| 6 | IOUT_OC_LV_FAULT | An output overcurrent and low voltage fault has occurred. |
| 5 | IOUT_OC_WARNING | An output overcurrent warning has occurred. |
| 4 | IOUT_UC_FAULT | An output undercurrent fault has occurred. |
| 3:0 | N/A | These bits are not used. |

STATUS_INPUT (7Ch)

Definition: Returns input voltage and input current status information.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 00h

Units: N/A

| BIT NUMBER | STATUS BIT NAME | MEANING |
|------------|-----------------|---|
| 7 | VIN_OV_FAULT | An input overvoltage fault has occurred. |
| 6 | VIN_OV_WARNING | An input overvoltage warning has occurred. |
| 5 | VIN_UV_WARNING | An input undervoltage warning has occurred. |
| 4 | VIN_UV_FAULT | An input undervoltage fault has occurred. |
| 3:0 | N/A | These bits are not used. |

STATUS_TEMP (7Dh)

Definition: Returns one byte of information with a summary of any temperature related faults or warnings.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 00h

Units: N/A

| BIT NUMBER | STATUS BIT NAME | MEANING |
|------------|-----------------|--|
| 7 | OT_FAULT | An over-temperature fault has occurred. |
| 6 | OT_WARNING | An over-temperature warning has occurred. |
| 5 | UT_WARNING | An under-temperature warning has occurred. |
| 4 | UT_FAULT | An under-temperature fault has occurred. |
| 3:0 | N/A | These bits are not used. |

STATUS_CML (7Eh)

Definition: Returns one byte of information with a summary of any Communications, Logic, and/or Memory errors.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 00h

Units: N/A

| BIT NUMBER | MEANING |
|------------|---|
| 7 | Invalid or unsupported PMBus command was received. |
| 6 | The PMBus command was sent with invalid or unsupported data. |
| 5 | Packet error was detected in the PMBus command. |
| 4:2 | Not used. |
| 1 | A PMBus command tried to write to a Read only or protected command, or a communication fault other than the ones listed in this table has occurred. |
| 0 | Not used. |

STATUS_MFR_SPECIFIC (80h)

Definition: Returns one byte of information providing the status of the device's voltage monitoring and clock synchronization faults.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default value: 00h

Units: N/A

| BIT NUMBER | FIELD NAME | MEANING |
|------------|---------------------------------|---|
| 7:6 | Reserved | |
| 5 | VMON UV Warning | The voltage on the VDRVOUT pin has dropped below 4.4V. |
| 4 | VMON OV Warning | The voltage on the VDRVOUT pin has risen above 5.5V. |
| 3 | External Switching Period Fault | Loss of external clock synchronization has occurred. |
| 2 | Reserved | |
| 1 | VMON UV Fault | The voltage on the VMON pin has dropped below the level set by VMON_UV_FAULT. |
| 0 | VMON OV Fault | The voltage on the VMON pin has risen above the level set by VMON_OV_FAULT. |

READ_VIN (88h)

Definition: Returns the input voltage reading.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Units: V

READ_VOUT (8Bh)

Definition: Returns the output voltage reading.

Data Length in Bytes: 2

Data Format: L16u

Type: Read only

Units: V

READ_IOUT (8Ch)

Definition: Returns the output current reading.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Default Value: N/A

Units: A

READ_INTERNAL_TEMP (8Dh)

Definition: Returns the controller junction temperature reading from internal temperature sensor.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Units: °C

READ_EXTERNAL_TEMP (8Eh)

Definition: Returns the temperature reading from the external temperature device connected to XTEMP pins.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Units: °C

READ_DUTY_CYCLE (94h)

Definition: Reports the actual duty cycle of the converter during the enable state.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Units: %

READ_FREQUENCY (95h)

Definition: Reports the actual switching frequency of the converter during the enable state.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Units: kHz

MFR_ID (99h)

Definition: Sets user defined identification. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command, then perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

MFR_MODEL (9Ah)

Definition: Sets a user defined model. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command, then perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

MFR_REVISION (9Bh)

Definition: Sets a user defined revision. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command, then perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

MFR_LOCATION (9Ch)

Definition: Sets a user defined location identifier. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command then, perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

MFR_DATE (9Dh)

Definition: Sets a user defined date. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command, then perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

Reference: N/A

MFR_SERIAL (9Eh)

Definition: Sets a user defined serialized identifier. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command, then perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

LEGACY_FAULT_GROUP (A8h)

Definition: This command is used only when the power system is created by mixing the ISL8277M module with old generation digital modules (ZL9101M, ZL9117M, ZL9006M, ZL9010M) to power various rails. This command provides an ability to power down the system by broadcast faults between old and new generation digital modules.

New generation module uses group ID to broadcast faults between each other. Refer to DDC_GROUP(E2h) command. Old generation module uses rail ID to broadcast fault. When new and old modules are mixed, ISL8277M can use GROUP-ID (new generation module) and/or RAIL-ID (old generation module) to execute shutdown as response to fault to selected GROUP_ID or RAIL-ID. A module can listen to multiple RAIL-IDs by writing 1 to a bit location representing RAIL-ID of old generation modules.

NOTE; Bit-5 in DDC_GROUP command should be programmed 1 to activate fault broadcast.

Data length in Bytes: 4

Data Format: BIT

Type: R/W Block

Default Value: 00000000h

Units: N/A

| BIT | DESCRIPTION | BIT | DESCRIPTION | BIT | DESCRIPTION | BIT | DESCRIPTION |
|-----|-------------------|-----|-------------------|-----|-------------------|-----|------------------|
| 31 | Listen to Rail-31 | 23 | Listen to Rail-23 | 15 | Listen to Rail-15 | 7 | Listen to Rail-7 |
| 30 | Listen to Rail-30 | 22 | Listen to Rail-22 | 14 | Listen to Rail-14 | 6 | Listen to Rail-6 |
| 29 | Listen to Rail-29 | 21 | Listen to Rail-21 | 13 | Listen to Rail-13 | 5 | Listen to Rail-5 |
| 28 | Listen to Rail-28 | 20 | Listen to Rail-20 | 12 | Listen to Rail-12 | 4 | Listen to Rail-4 |
| 27 | Listen to Rail-27 | 19 | Listen to Rail-19 | 11 | Listen to Rail-11 | 3 | Listen to Rail-3 |
| 26 | Listen to Rail-26 | 18 | Listen to Rail-18 | 10 | Listen to Rail-10 | 2 | Listen to Rail-2 |
| 25 | Listen to Rail-25 | 17 | Listen to Rail-17 | 9 | Listen to Rail-9 | 1 | Listen to Rail-1 |
| 24 | Listen to Rail-24 | 16 | Listen to Rail-16 | 8 | Listen to Rail-8 | 0 | Listen to Rail-0 |

USER_DATA_00 (B0h)

Definition: Sets a user defined data. The sum total of characters in MFR_ID, MFR_MODEL, MFR_REVISION, MFR_LOCATION, MFR_DATE, MFR_SERIAL, and USER_DATA_00 plus one byte per command cannot exceed 128 characters. This limitation includes multiple writes of this command before a STORE command. To clear multiple writes, perform a RESTORE, write this command then perform a STORE/RESTORE.

Data Length in Bytes: User defined

Data Format: ASCII

Type: Block R/W

Default Value: null

Units: N/A

ISENSE_CONFIG (D0h)**Definition:** Configures current sense circuitry.**Data Length in Bytes:** 1**Data Format:** BIT**Type:** R/W byte**Default Value:** 05h**Units:** N/A

| BIT | FIELD NAME | VALUE | SETTING | DESCRIPTION |
|-----|-----------------------------|-------|------------|---|
| 7:4 | Reserved | 000 | | |
| 3:2 | Current Sense Blanking Time | 00 | 192ns | Sets the blanking time current sense blanking time. |
| | | 01 | 256ns | |
| | | 10 | 412ns | |
| | | 11 | 640ns | |
| 1:0 | Current Sense Range | 00 | Low Range | ±25mV |
| | | 01 | Mid Range | ±35mV |
| | | 10 | High Range | ±50mV |
| | | 11 | Not Used | |

USER_CONFIG (D1h)**Definition:** Configures several user-level features. This command overrides the CONFIG pin settings.**Data Length in Bytes:** 1**Data Format:** BIT**Type:** R/W byte**Default Value:** 00h**Units:** N/A

| BIT | FIELD NAME | VALUE | SETTING | DESCRIPTION |
|-----|--|-------|------------|---|
| 7:5 | Reserved | 0 | | Reserved |
| 4:3 | Ramp-Up and Ramp-Down Minimum Duty Cycle | 00 | 0.39% | Sets the minimum duty-cycle during start-up and shutdown ramp. Must be enabled with Bit 10. |
| | | 01 | 0.78% | |
| | | 10 | 1.17% | |
| | | 11 | 1.56% | |
| 2 | Minimum Duty Cycle Control | 0 | Disable | Control for minimum duty cycle. |
| | | 1 | Enable | |
| 1 | Power-Good Pin Configuration | 0 | Open Drain | 0 = PG is an open-drain output. |
| | | 1 | Push-Pull | 1 = PG is a push-pull output. |
| 0 | XTEMP Enable | 0 | Disable | Enable external temperature monitoring. |
| | | 1 | Enable | |

DDC_CONFIG (D3h)**Definition:** Configures DDC addressing.**Data Length in Bytes:** 1**Data Format:** BIT**Type:** R/W**Default Value:** 00h**Units:** N/A

| BIT | FIELD NAME | VALUE | SETTING | DESCRIPTION |
|-----|------------|---------------------|----------|------------------------|
| 7:5 | Reserved | 00 | Reserved | Reserved |
| 4:0 | Rail ID | 0 to 31 (00 to 1Fh) | 0 | Configures DDC address |

POWER_GOOD_DELAY (D4h)**Definition:** Sets the delay applied between the output exceeding the PG threshold (POWER_GOOD_ON) and asserting the PG pin. The delay time can range from 0ms up to 500s, in steps of 125ns. A 1ms minimum configured value is recommended to apply proper de-bounce to this signal.**Data Length in Bytes:** 2**Data Format:** L11**Type:** R/W**Default Value:** 4ms**Units:** ms**Range:** 0 to 5s**ASCR_CONFIG (DFh)****Definition:** Allows user configuration of ASCR settings.**Data Length in Bytes:** 4**Data Format:** CUS**Type:** R/W**Default Value:** 015A0100h

| BIT | PURPOSE | DATA FORMAT | VALUE | DESCRIPTION |
|-------|-----------------------|-------------|----------|-------------|
| 31:25 | Unused | | 0000000h | Unused |
| 24 | ASCCR Enable | BIT | 1 | Enable |
| | | | 0 | Disable |
| 23:16 | ASCR Residual Setting | Integer | | |
| 15:0 | ASCR Gain Setting | Integer | | |

SEQUENCE (E0h)

Definition: Identifies the Rail DDC ID of the prequel and sequel rails when performing multi-rail sequencing. The device will enable its output when its EN or OPERATION enable states, as defined by ON_OFF_CONFIG, are set and the prequel device has issued a Power-good event on the DDC bus. The device will disable its output (using the programmed delay values) when the sequel device has issued a Power-down event on the DDC bus.

The data field is a two-byte value. The most significant byte contains the 5-bit Rail DDC ID of the prequel device. The least significant byte contains the 5-bit Rail DDC ID of the sequel device. The most significant bit of each byte contains the enable of the prequel or sequel mode. This command overrides the corresponding sequence configuration set by the CONFIG pin settings.

Data Length in Bytes: 2

Data Format: BIT

Type: R/W

Default Value: 0000h (Prequel and Sequel disabled)

| BIT | FIELD NAME | VALUE | SETTING | DESCRIPTION |
|-------|---------------------|-------|----------|---|
| 15 | Prequel Enable | 0 | Disable | Disable, no prequel preceding this rail. |
| | | 1 | Enable | Enable, prequel to this rail is defined by Bits 12:8. |
| 14:13 | Reserved | 0 | Reserved | Reserved |
| 12:8 | Prequel Rail DDC ID | 0-31 | DDC ID | Set to the DDC ID of the prequel rail. |
| 7 | Sequel Enable | 0 | Disable | Disable, no sequel following this rail. |
| | | 1 | Enable | Enable, sequel to this rail is defined by Bits 4:0. |
| 6:5 | Reserved | 0 | Reserved | Reserved |
| 4:0 | Sequel Rail DDC ID | 0-31 | DDC ID | Set to the DDC ID of the sequel rail. |

DDC_GROUP (E2h)

Definition: Configures fault spreading group ID and enable, broadcast OPERATION group ID and enable, and broadcast VOUT_COMMAND group ID and enable.

Data Length in Bytes: 3

Data Format: BIT

Type: R/W

Default Value: 000000h (Ignore BROADCAST VOUT_COMMAND and OPERATION, Sequence shutdown on POWER_FAIL event)

| BITS | PURPOSE | VALUE | DESCRIPTION |
|-------|---------------------------------|-------|--|
| 23:22 | Reserved | 0 | Reserved |
| 21 | BROADCAST_VOUT_COMMAND Response | 1 | Responds to BROADCAST_VOUT_COMMAND with same Group ID. |
| | | 0 | Ignores BROADCAST_VOUT_COMMAND. |
| 20:16 | BROADCAST_VOUT_COMMAND Group ID | 0-31d | Group ID sent as data for broadcast BROADCAST_VOUT_COMMAND events. |
| 15:14 | Reserved | 0 | Reserved |
| 13 | BROADCAST_OPERATION Response | 1 | Responds to BROADCAST_OPERATION with same Group ID. |
| | | 0 | Ignores BROADCAST_OPERATION. |
| 12:8 | BROADCAST_OPERATION Group ID | 0-31d | Group ID sent as data for broadcast BROADCAST_OPERATION events. |
| 7:6 | Reserved | 0 | Reserved |
| 5 | POWER_FAIL Response | 1 | Responds to POWER_FAIL events with same Group ID by shutting down immediately. |
| | | 0 | Responds to POWER_FAIL events with same Group ID with sequenced shutdown. |
| 4:0 | POWER_FAIL group ID | 0-31d | Group ID sent as data for broadcast POWER_FAIL events. |

DEVICE_ID (E4h)

Definition: Returns the 16-byte (character) device identifier string.

Data Length in Bytes: 16

Data Format: ASCII

Type: Block Read

Default Value: Part number/Die revision/Firmware revision

MFR_IOUT_OC_FAULT_RESPONSE (E5h)

Definition: Configures the I_{OUT} overcurrent fault response as defined by the following table. The command format is the same as the PMBus standard fault responses except that it sets the overcurrent status bit in STATUS_IOUT.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable, and no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|---|
| 80h | Disable with no retry. |
| BFh | Disable and continuous retry with 70ms delay. |

MFR_IOUT_UC_FAULT_RESPONSE (E6h)

Definition: Configures the I_{OUT} undercurrent fault response as defined by the following table. The command format is the same as the PMBus standard fault responses except that it sets the undercurrent status bit in STATUS_IOUT.

Data Length in Bytes: 1

Data Format: BIT

Type: R/W

Default Value: 80h (Disable and no retry)

Units: N/A

| SETTINGS | ACTIONS |
|----------|---|
| 80h | Disable with no retry. |
| BFh | Disable and continuous retry with 70ms delay. |

SYNC_CONFIG (E9h)

Definition: Sets options for SYNC output configurations.

Data Length in Bytes: 2

Data Format: BIT

Type: R/W

Default Value: 00h

| SETTINGS | ACTIONS |
|----------|---|
| 00h | Use internal clock. Clock frequency is set by pin-strap or PMBus command. |
| 02h | Use internal clock and output internal clock. |
| 04h | Use external clock. |

SNAPSHOT (EAh)

Definition: A 32-byte read-back of parametric and status values. It allows monitoring and status data to be stored to flash following a fault condition. In case of a fault, the most recently updated values are stored to the flash memory. When SNAPSHOT STATUS byte 22 is set stored, the device will no longer automatically capture parametric and status values following a fault until stored data are erased. Use the SNAPSHOT_CONTROL command to erase stored data and clear the status bit before the next ramp up. Data erased is not allowed when the module is enabled.

Data Length in Bytes: 32

Data Format: Bit field

Type: Block Read

| BYTE NUMBER | VALUE | PMBUS COMMAND | FORMAT |
|-------------|--|---------------------------|--------|
| 31:23 | Reserved | Reserved | 00h |
| 22 | Flash Memory Status Byte FF - Not Stored 00 - Stored | N/A | BIT |
| 21 | Manufacturer Specific Status Byte | STATUS_MFR_SPECIFIC (80h) | Byte |
| 20 | CML Status Byte | STATUS_CML (7Eh) | Byte |
| 19 | Temperature Status Byte | STATUS_TEMPERATURE (7Dh) | Byte |
| 18 | Input Status Byte | STATUS_INPUT (7Ch) | Byte |
| 17 | I _{OUT} Status Byte | STATUS_IOUT (7Bh) | Byte |
| 16 | V _{OUT} Status Byte | STATUS_VOUT (7Ah) | Byte |
| 15:14 | Switching Frequency | READ_FREQUENCY (95h) | L11 |
| 13:12 | External Temperature | READ_EXTERNAL_TEMP (8Eh) | L11 |
| 11:10 | Internal Temperature | READ_INTERNAL_TEMP (8Dh) | L11 |
| 9:8 | Duty Cycle | READ_DUTY_CYCLE (94h) | L11 |
| 7:6 | Highest Measured Output Current | N/A | L11 |
| 5:4 | Output Current | READ_IOUT (8Ch) | L11 |
| 3:2 | Output Voltage | READ_VOUT (8Bh) | L16u |
| 1:0 | Input Voltage | READ_VIN (88h) | L11 |

BLANK_PARAMS (EBh)

Definition: Returns a 16-byte string indicating which parameter values were either retrieved by the last RESTORE operation or have been written since that time. Reading BLANK_PARAMS immediately after a restore operation allows the user to determine which parameters are stored in that store. A "1" indicates the parameter is not present in the store and has not been written since the RESTORE operation.

Data Length in Bytes: 16

Data Format: BIT

Type: Block Read

Default Value: FF...FFh

SNAPSHOT_CONTROL (F3h)

Definition: Erases parametric and status values stored at SNAPSHOT, flash memory location.

Data Length in Bytes: 1

Data Format: BIT

Type: W Byte

| VALUE | DESCRIPTION |
|-------|--|
| 03h | Erase parametric and status values stored in SNAPSHOT. |

RESTORE_FACTORY (F4h)

Definition: Restores the device to the hard-coded factory default values and pin-strap definitions. The device retains the DEFAULT and USER stores for restoring. Security level is changed to Level 1 following this command.

Data Length in Bytes: 0

Data Format: N/A

Type: Write only

Default Value: N/A

Units: N/A

MFR_VMON_OV_FAULT_LIMIT (F5h)

Definition: Reads the VMON OV fault threshold.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Default Value: CB00h (6V)

Units:

Range: 4V to 6V

MFR_VMON_UV_FAULT_LIMIT (F6h)

Definition: Reads the VMON UV fault threshold.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Default Value: CA00h (4V)

Units: V

Range: 4V to 6V

MFR_READ_VMON (F7h)

Definition: Reads the VMON voltage. VMON is used to monitor VDRVOUT (Pin 8) voltage through an internal 16:1 resistor divider.

Data Length in Bytes: 2

Data Format: L11

Type: Read only

Default Value: N/A

Units: V

Range: 4V to 6V

VMON_OV_FAULT_RESPONSE (F8h)

Definition: Reads the VMON OV fault response.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 80h (Disable and no retry)

Units: N/A

VMON_UV_FAULT_RESPONSE (F9h)

Definition: Reads the VMON UV fault response.

Data Length in Bytes: 1

Data Format: BIT

Type: Read only

Default Value: 80h (Disable and no retry)

Units: N/A

Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please visit our website to make sure you have the latest revision.

| DATE | REVISION | CHANGE |
|--------------|----------|--|
| Aug 17, 2017 | FN8923.1 | <p>Added Table 1 on page 3.</p> <p>Changed the default value for 46h "IOUT_OC_FAULT_LIMIT" on page 24 to DBC0h, 30A.</p> <p>Changed the default value for 48h "IOUT_UC_FAULT_LIMIT" on page 24 to DC3Fh, -30A.</p> <p>Changed the type for F4h "RESTORE_FACTORY" on page 26 to Write Block.</p> <p>Changed the name of F5h "VMON_OV_FAULT_LIMIT" to "MFR_VMON_OV_FAULT_LIMIT" on page 27.</p> <p>Changed the name of F6h "VMON_UV_FAULT_LIMIT" to "MFR_VMON_UV_FAULT_LIMIT" on page 27.</p> <p>Changed the name of F7h "READ_VMON" to "MFR_READ_VMON" on page 27.</p> <p>In Table 5, changed the R_{SET} for the 5-5 entry to 13.3, 28.7, 61.9, or OPEN.</p> <p>In Table 8, changed the UVLO value for the last seven entries to 10.8</p> <p>Changed the default value for "SYNC_CONFIG (E9h)" on page 47 from 0000h to 00h.</p> <p>Changed the type for "SNAPSHOT_CONTROL (F3h)" on page 48 from R/W BYTE to W BYTE.</p> <p>Changed the range maximum for "VOUT_MAX (24h)" on page 30 from 4V to 6V.</p> <p>Changed the default value for "VOUT_OV_WARNING_LIMIT (42h)" on page 32 from 0.85 to 1.1.</p> <p>Changed the default value for "VOUT_UV_WARNING_LIMIT (43h)" on page 32 from 0.85 to 0.9.</p> <p>Updated Table 7 on page 18 with new values.</p> <p>Updated Figures 10 through 15.</p> <p>Updated Table 2 on page 15 with new values.</p> <p>Updated Table 5 on page 18 with new values.</p> <p>Updated Table 7 on page 18 with new values.</p> <p>Updated Table 8 on page 19 with new values.</p> <p>Changed the type for "DEVICE_ID" on page 26 from ASC to ASCII.</p> <p>Updated the descriptions for bits 4 and 5 in "STATUS_MFR_SPECIFIC" on page 25.</p> |
| Feb 28, 2017 | FN8923.0 | Initial release |

Firmware Revision History

| FIRMWARE REVISION CODE | CHANGE DESCRIPTION | NOTE |
|------------------------|--------------------|------|
| ISL8277-0-G0100 | Initial release | |

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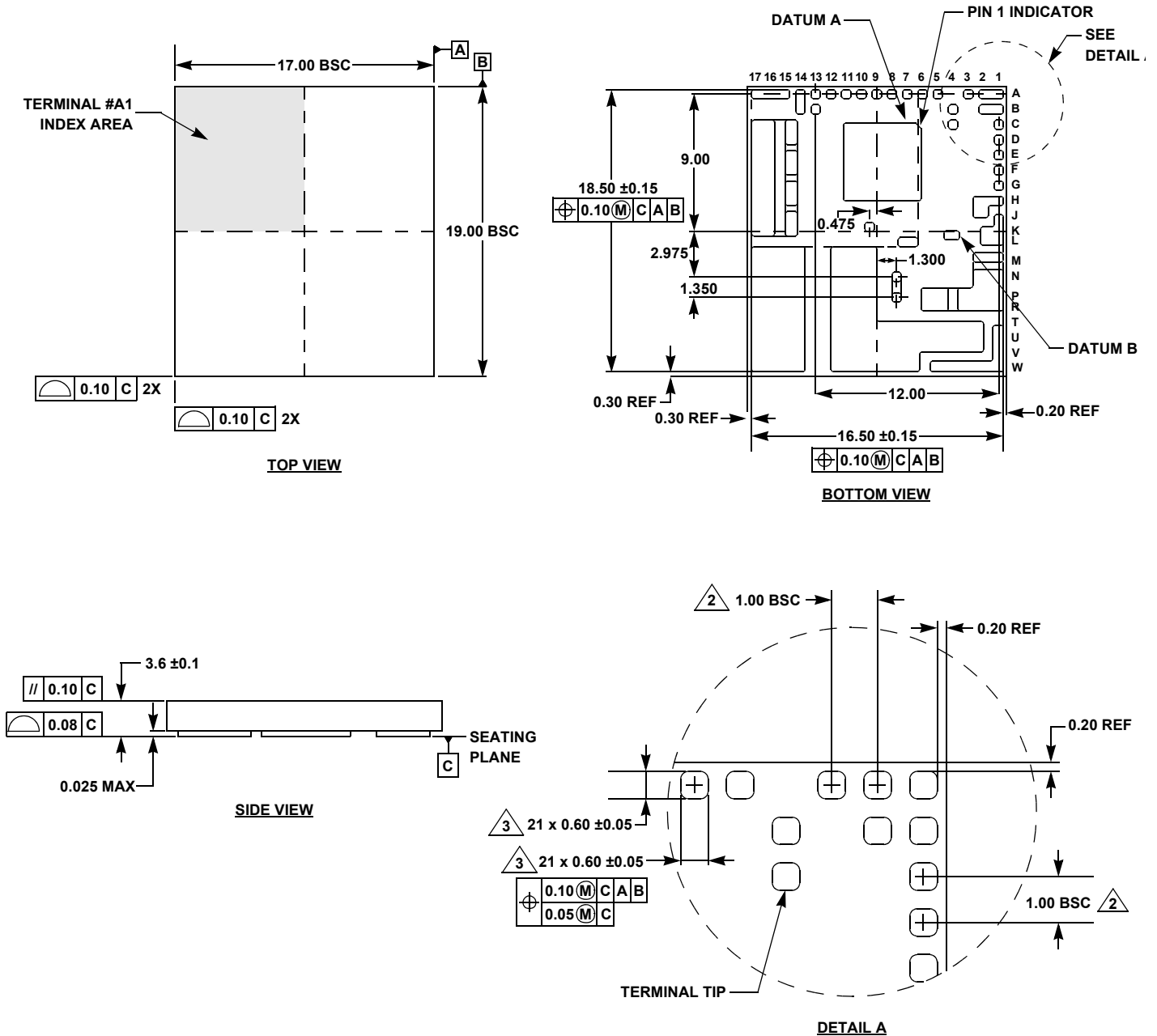
Package Outline Drawing

Y41.17x19

41 I/O 17.0mm x 19.0mm x 3.6mm HDA MODULE

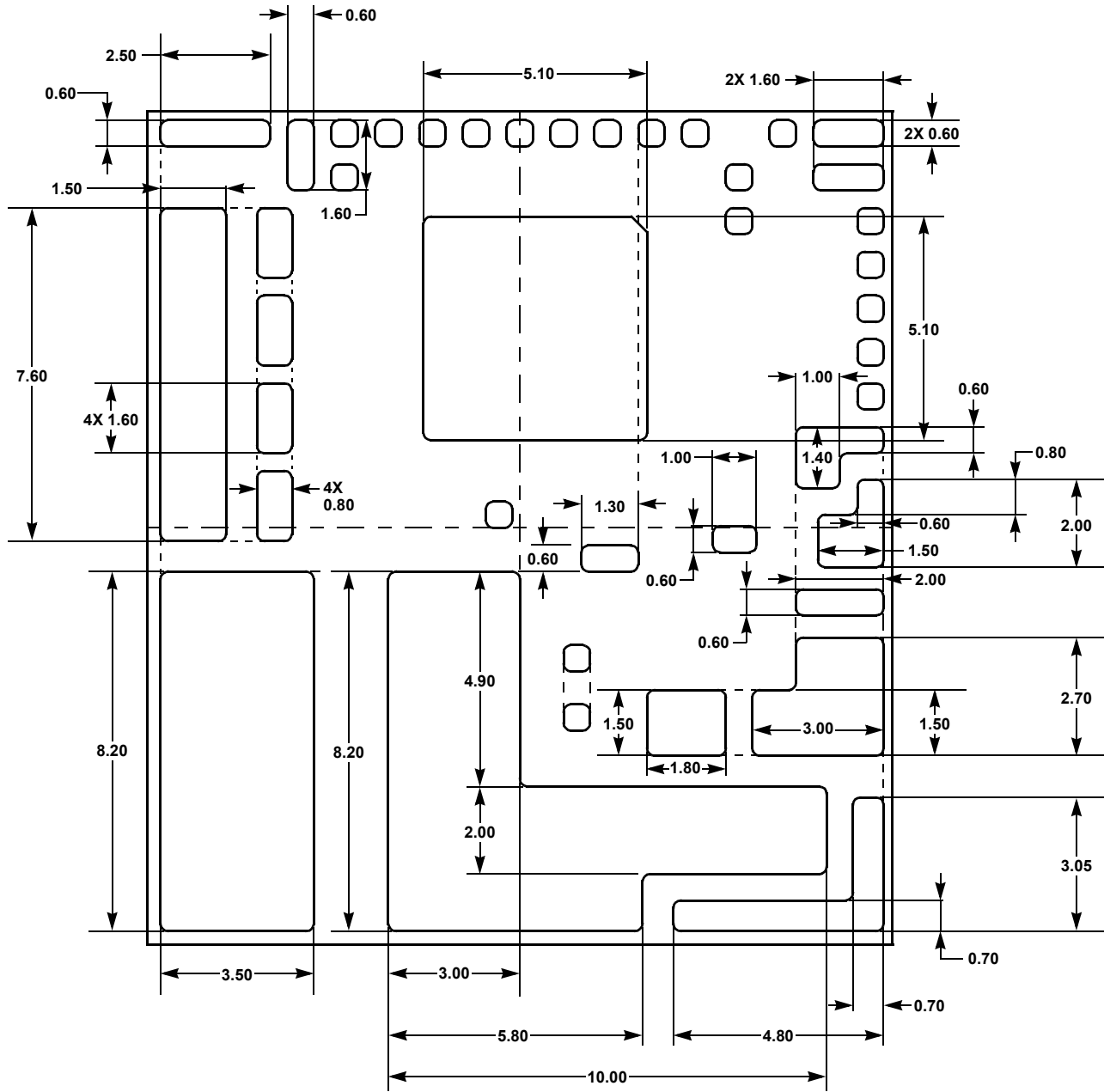
Rev 1, 5/16

For the most recent package outline drawing, see [Y41.17x19](#).

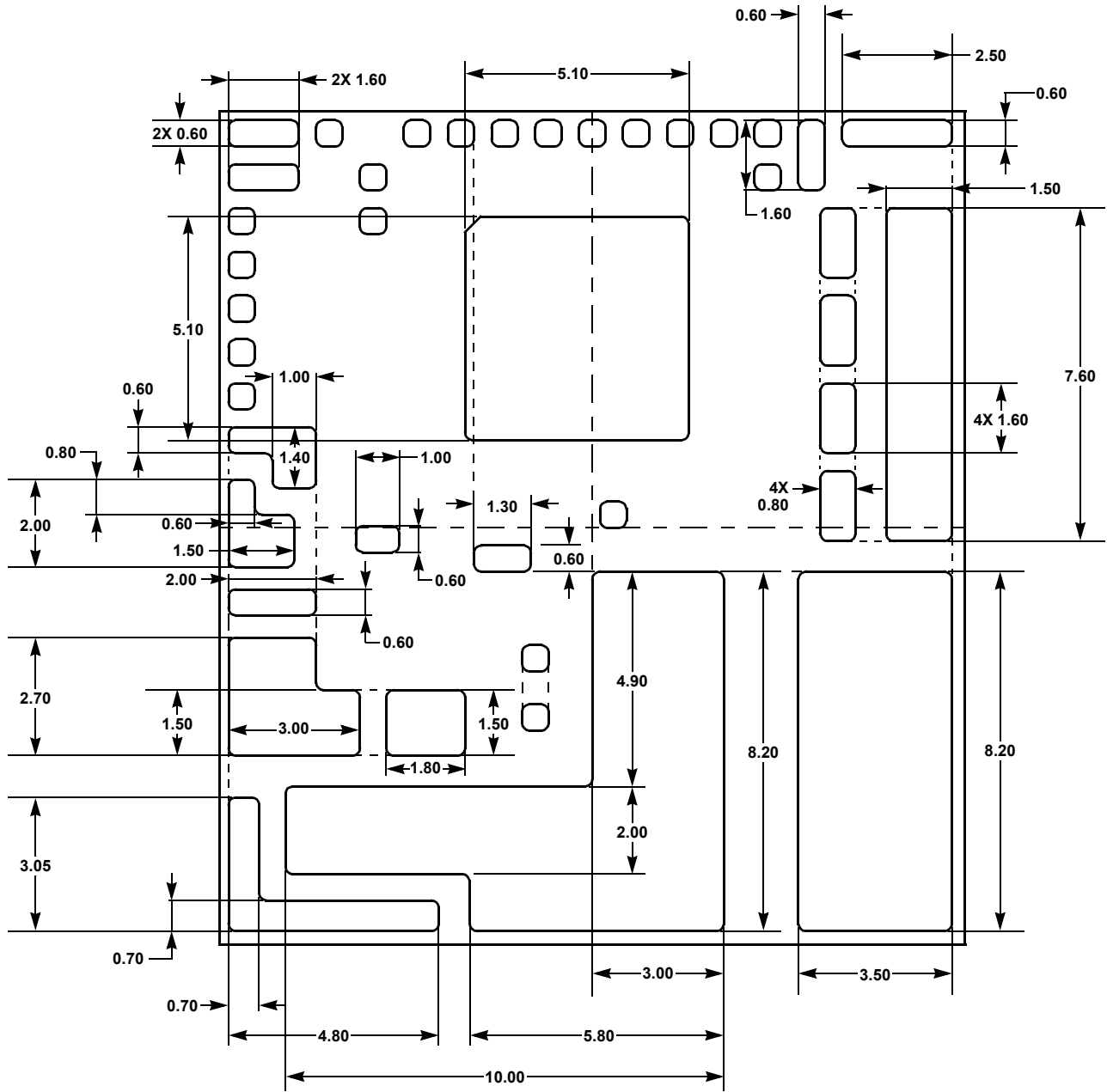


NOTES:

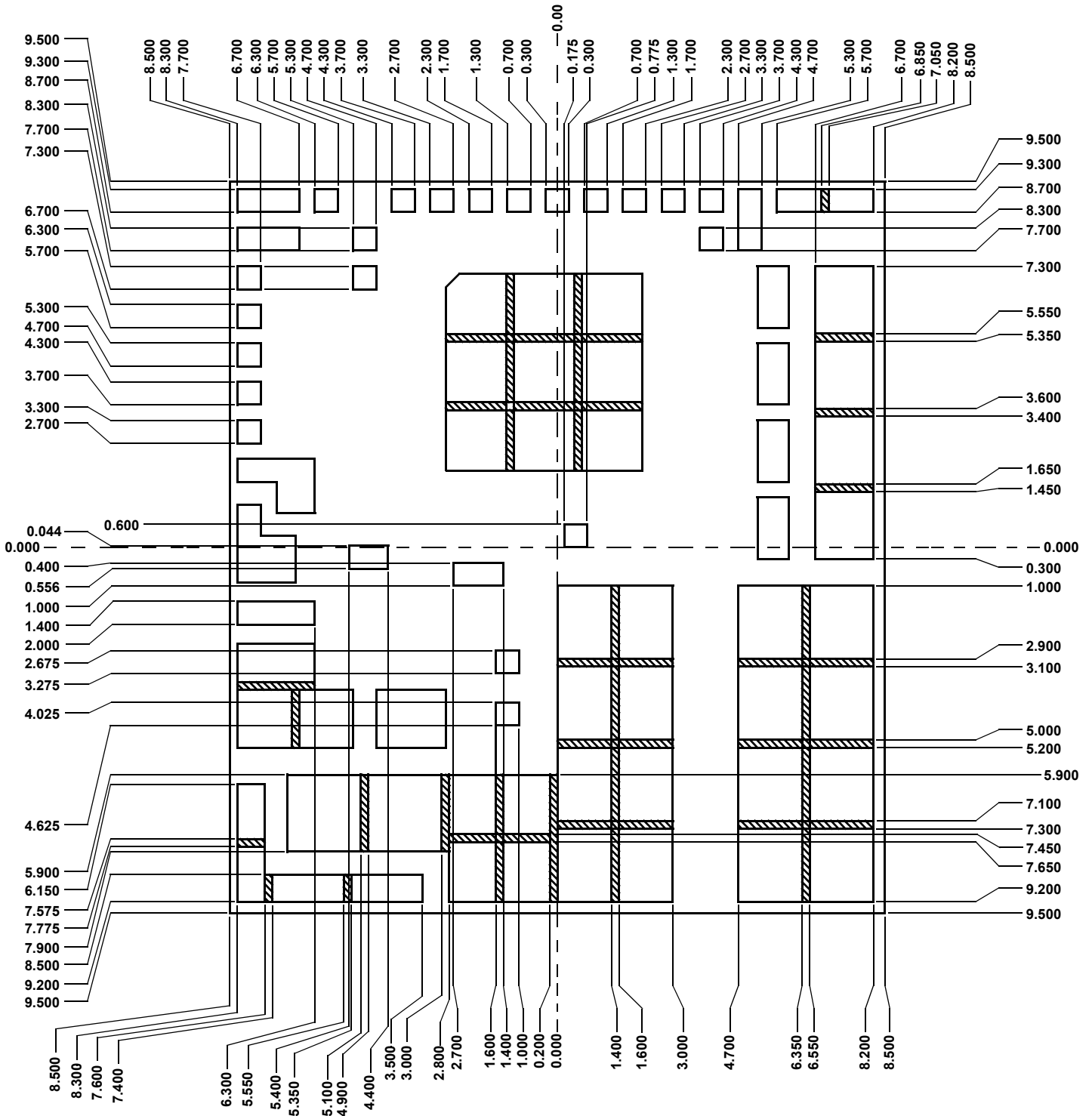
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- ② Represents the basic land grid pitch.
- ③ The total number of I/O (excluding dummy pads).
4. Unless otherwise specified, tolerance: decimal ±0.10.
5. Dimensioning and tolerancing per ASME Y14.M-2009.
6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated.
The pin #1 identifier may be either a mold or mark feature.



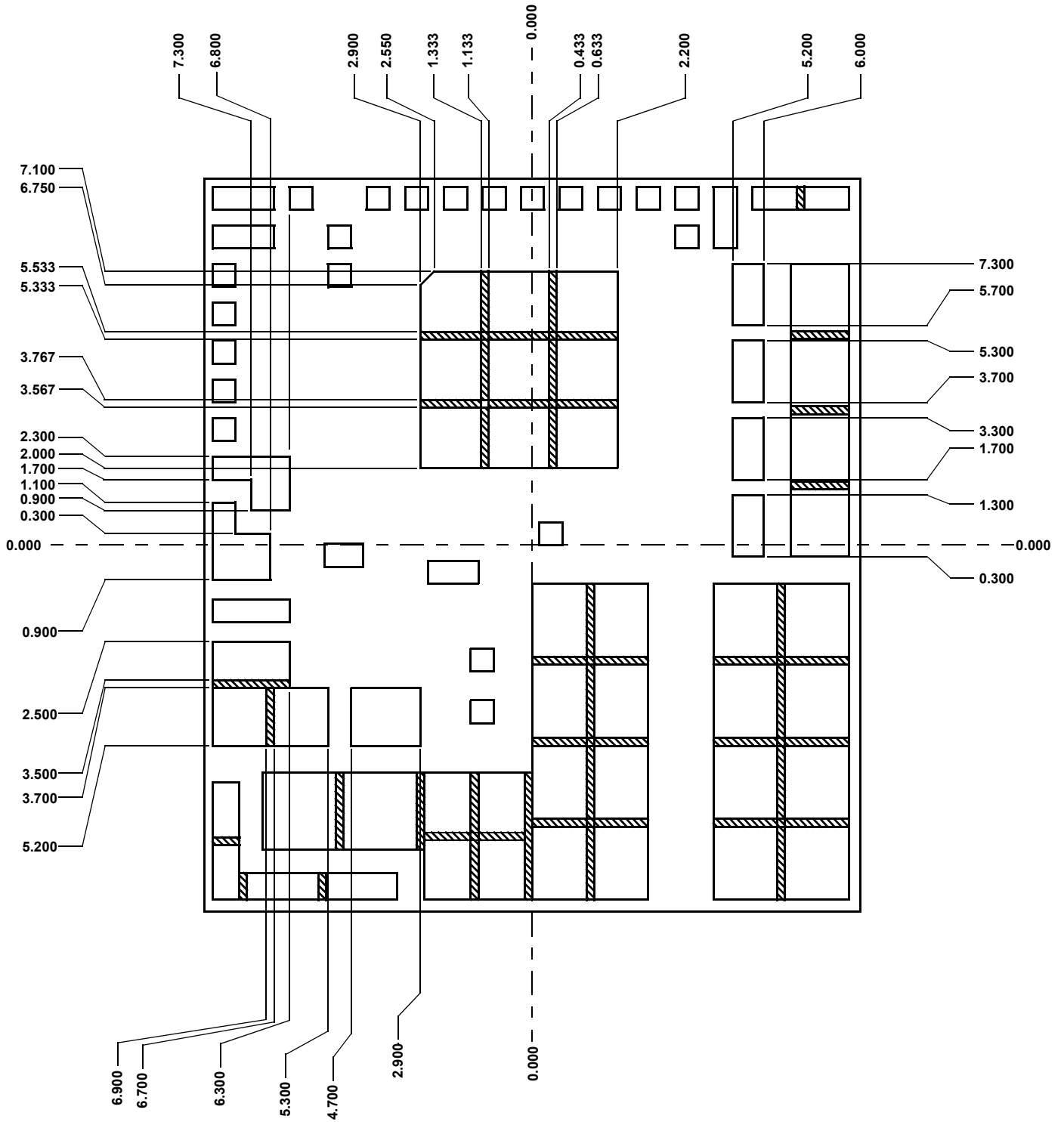
SIZE DETAILS FOR THE 16 EXPOSED DAPS
BOTTOM VIEW



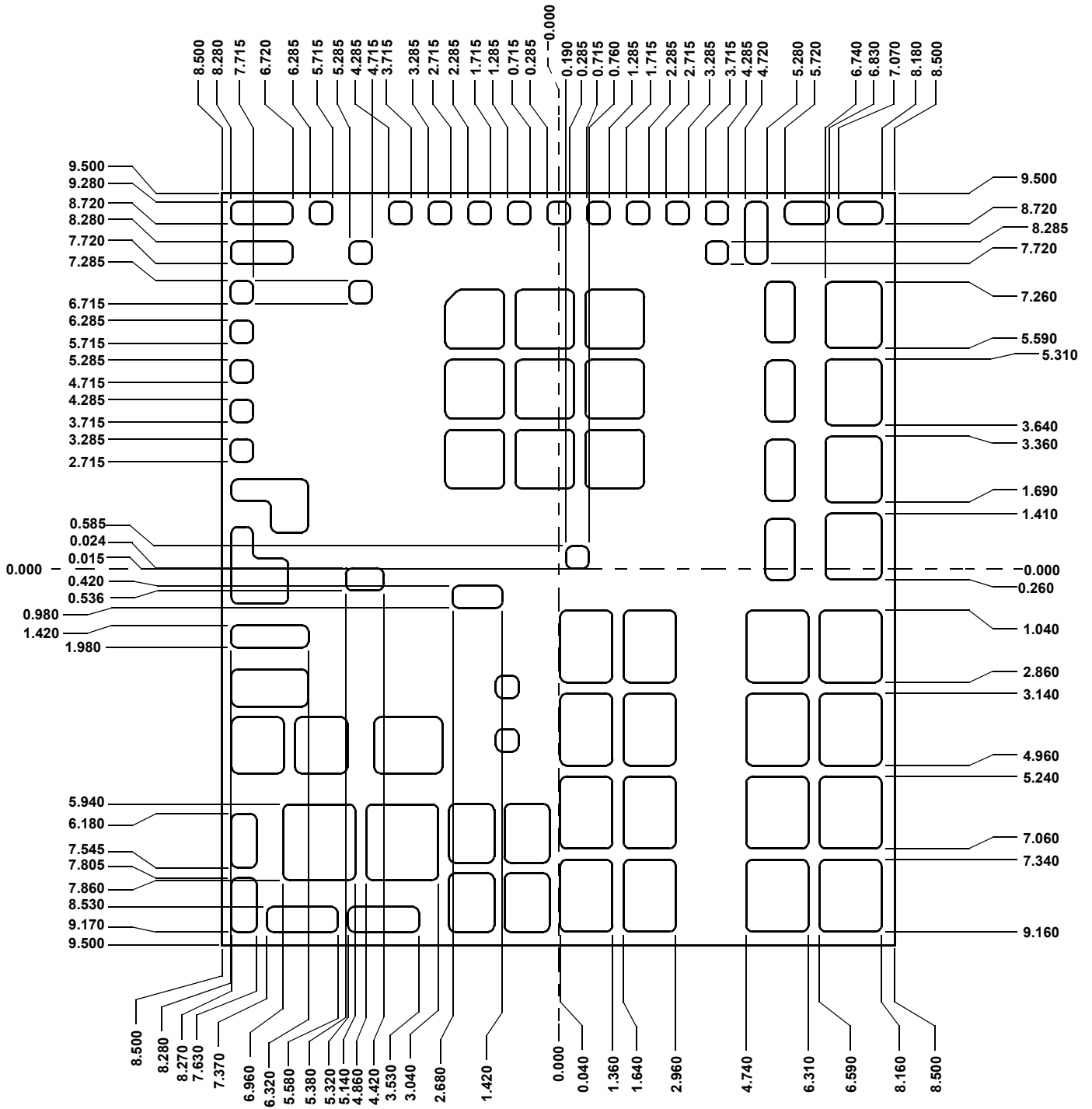
SIZE DETAILS FOR THE 16 EXPOSED DAPS
TOP VIEW



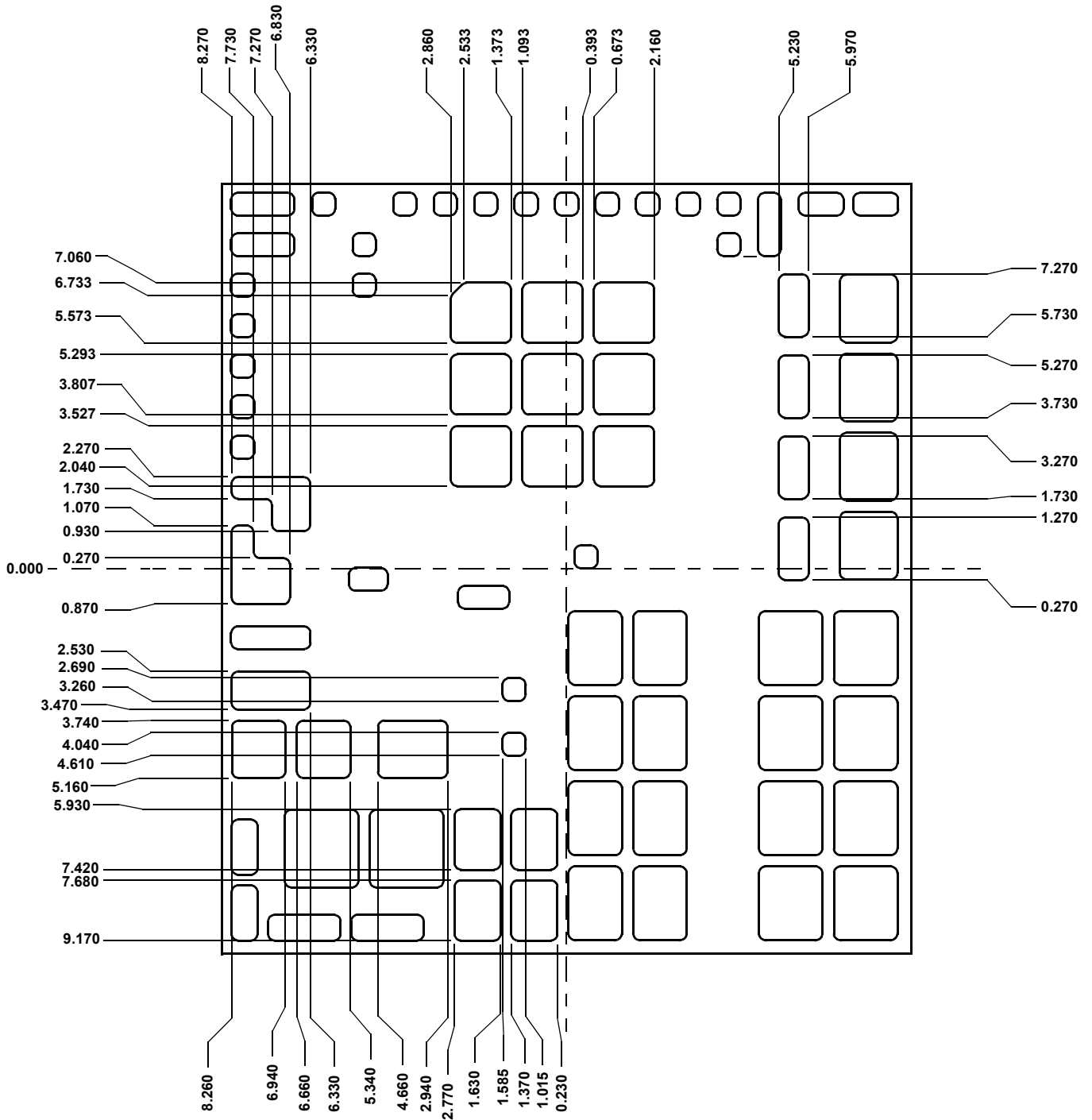
RECOMMENDED SOLDER MASK DEFINED PCB LAND PATTERN (1)
TOP VIEW



RECOMMENDED SOLDER MASK DEFINED PCB LAND PATTERN (2)
TOP VIEW



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