The Intersil ISL90726 is a digitally controlled potentiometer (XDCP). The device consists of a resistor array, wiper switches, and a control section. The wiper position is controlled by an $\mathrm{I}^{2} \mathrm{C}$ interface.

The potentiometer is implemented by a resistor array composed of 127 resistive elements and a wiper switching network. Between each element and at either end are tap points accessible to the wiper terminal. The position of the wiper element is controlled by the SDA and SCL inputs.

## Pinout

ISL90726
( 6 LD SC-70)
TOP VIEW


## Features

- Volatile Solid-State Potentiometer
- $I^{2} C$ Serial Bus Interface
- DCP Terminal Voltage, 2.7V to 5.5 V
- Low Tempco
- Rheostat - $45 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typical
- Divider - $15 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ typical
- 128 Wiper Tap Points
- Wiper Resistance $70 \Omega$ typ at $\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}$
- Low Power CMOS
- Active Current, 200 1 A Max
- Standby Current, 500nA Max
- Available RTOTAL Values $=50 \mathrm{k} \Omega, 10 \mathrm{k} \Omega$
- Power on Preset to Midscale
- Packaging
- 6 Ld SC-70
- Pb-Free (RoHS compliant)


## Applications

- Mechanical Potentiometer Replacement
- Transducer Adjustment of Pressure, Temperature, Position, Chemical, and Optical Sensors
- Laser Diode and LED Biasing
- LCD Brightness and Contrast Adjustment
- Gain Control and Offset Adjustment
- DDR3 Margining


## Ordering Information

| PART NUMBER (Note) | PART MARKING | $\mathrm{R}_{\text {TOTAL }}(\mathrm{k} \Omega$ ) | TEMP RANGE ( $\left.{ }^{\circ} \mathrm{C}\right)$ | PACKAGE (Pb-Free) | PKG. DWG. \# |
| :---: | :---: | :---: | :---: | :---: | :---: |
| ISL90726WIE627Z-TK* | ANF | 10 | -40 to +85 | 6 Ld SC-70 | P6.049 |
| ISL90726UIE627Z-TK* | ANG | 50 | -40 to +85 | 6 Ld SC-70 | P6.049 |

*Please refer to TB347 for details on reel specifications.
NOTE: These Intersil Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials, and $100 \%$ matte tin plate plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb -free soldering operations). Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

## Pin Descriptions

| PIN NUMBER | SYMBOL | DESCRIPTION |
| :---: | :---: | :--- |
| 1 | VDD | Supply Voltage |
| 2 | GND | Ground |
| 3 | SCL | Open drain Serial Clock input |
| 4 | SDA | Open drain Serial Data I/O |
| 5 | RW | Potentiometer Wiper Terminal |
| 6 | RL | Potentiometer End Terminal |

## Block Diagram



| Absolute Maximum Ratings |  |
| :---: | :---: |
| Storage Temperature | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Voltage at any Digital Interface Pin with Respect to $\mathrm{V}_{\mathrm{SS}}$ | $-0.3 \mathrm{~V} \text { to } \mathrm{V}_{\mathrm{CC}}+0.3$ |
| $\mathrm{V}_{\mathrm{CC}}$ | -0.3 V to +7 V |
| Voltage at any DCP Pin with |  |
| Respect to $\mathrm{V}_{\mathrm{SS}}$ | -0.3 V to $\mathrm{V}_{\mathrm{CC}}$ |
| IW (10s) | ....... $\pm 6 \mathrm{~mA}$ |
| Latchup | II, Level B at $+85^{\circ} \mathrm{C}$ |
| ESD Rating |  |
| Human Body Model | .2kV |

## Thermal Information

```
Thermal Resistance (Typical, Note 1) \(\quad \theta_{\mathrm{JA}}\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)\)
    6 Ld SC-70
        590
```

Pb-Free Reflow Profile. . . . . . . . . . . . . . . . . . . . . . . . see link below
http://www.intersil.com/pbfree/Pb-FreeReflow.asp

## Recommended Operating Conditions

Industrial

$40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$
$\mathrm{V}_{\mathrm{CC}}$. . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 2.7 V to 5.5 V
Power rating of each DCP . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 5 mW

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.
NOTE:

1. $\theta_{\mathrm{JA}}$ is measured with the component mounted on a high effective thermal conductivity test board in free air. See Tech Brief TB379 for details.

Analog Specifications Over recommended operating conditions unless otherwise stated.

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN <br> (Note 12) | TYP <br> (Note 2) | MAX <br> (Note 12) | UNIT |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |

## RESISTOR MODE

| $\begin{gathered} R_{\text {INL }} \\ \text { (Note 7) } \end{gathered}$ | Integral Non-linearity | DCP register set between 20 hex and 7F hex. Monotonic over all tap positions (Note 3) |  | -2 | $\pm 0.25$ | 2 | $\begin{gathered} \mathrm{MI} \\ \text { (Note 4) } \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{R}_{\mathrm{DNL}}$ (Note 6) | Differential Non-linearity | DCP register set between 20 hex and 7F hex. Monotonic over all tap positions (Note 3) | W option | -1 | $\pm 0.1$ | 1 | $\begin{array}{c\|} \hline \mathrm{MI} \\ \text { (Note 4) } \end{array}$ |
|  |  |  | U option | -1 | $\pm 0.1$ | 1 | $\begin{gathered} \mathrm{MI} \\ \text { (Note 4) } \end{gathered}$ |
| $\begin{aligned} & \text { ROFFSET } \\ & \text { (Note 5) } \end{aligned}$ | Offset | W option |  | 0 | 1 | 3 | $\begin{gathered} \mathrm{MI} \\ \text { (Note 4) } \end{gathered}$ |
|  |  | U option |  | 0 | 0.5 | 2 | $\begin{gathered} \mathrm{MI} \\ \text { (Note 4) } \end{gathered}$ |
| $\mathrm{TC}_{\mathrm{R}}$ <br> (Notes 8, 9) | Resistance Temperature Coefficient | DCP register set between 20 hex and 7F hex (Note 3) |  |  | $\pm 45$ |  | ppm $/{ }^{\circ} \mathrm{C}$ |

## Operating Specifications

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN <br> (Note 12) | TYP <br> (Note 2) | MAX <br> (Note 12) | UNIT |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |

Operating Specifications (Continued)

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN <br> (Note 12) | TYP <br> (Note 2) | MAX <br> (Note 12) | UNIT |
| :---: | :--- | :--- | :--- | :---: | :---: | :---: |

SERIAL INTERFACE SPECIFICATIONS

| VIL (Note 10) | SDA, and SCL Input Buffer LOW Voltage |  | -0.3 | $0.3 * V_{C C}$ | V |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {IH }}$ (Note 10) | SDA, and SCL Input Buffer HIGH Voltage |  | $0.7{ }^{*} V_{\text {cc }}$ | $\mathrm{V}_{\mathrm{CC}}+0.3$ | V |
| Hysteresis | SDA and SCL Input Buffer Hysteresis |  | $0.05{ }^{*} \mathrm{~V}_{\text {cC }}$ |  | V |
| $\mathrm{V}_{\text {OL }}$ | SDA Output Buffer LOW Voltage, Sinking 4mA |  | 0 | 0.4 | V |
| Cpin (Note 9) | SDA, and SCL Pin Capacitance |  |  | 10 | pF |
| $\mathrm{f}_{\text {SCL }}$ | SCL Frequency |  |  | 400 | kHz |
| $\mathrm{t}_{\mathrm{N}}$ | Pulse Width Suppression Time at SDA and SCL Inputs | Any pulse narrower than the max spec is suppressed. |  | 50 | ns |
| $\mathrm{t}_{\mathrm{AA}}$ | SCL Falling Edge to SDA Output Data Valid | SCL falling edge crossing $30 \%$ of $\mathrm{V}_{\mathrm{CC}}$, until SDA exits the $30 \%$ to $70 \%$ of $V_{C C}$ window. |  | 900 | ns |
| $\mathrm{t}_{\text {BUF }}$ | Time the Bus Must be Free Before the Start of a New Transmission | SDA crossing $70 \%$ of $V_{C C}$ during a STOP condition, to SDA crossing $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$ during the following START condition. | 1300 |  | ns |
| tow | Clock LOW Time | Measured at the $30 \%$ of $\mathrm{V}_{\mathrm{CC}}$ crossing. | 1300 |  | ns |
| $\mathrm{t}_{\mathrm{HIGH}}$ | Clock HIGH Time | Measured at the $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$ crossing. | 600 |  | ns |
| tsu:STA | START Condition Setup Time | SCL rising edge to SDA falling edge. Both crossing $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$. | 600 |  | ns |
| $t_{\text {HD }}$ STA | START Condition Hold Time | From SDA falling edge crossing $30 \%$ of $\mathrm{V}_{\mathrm{Cc}}$ to SCL falling edge crossing $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$. | 600 |  | ns |
| ${ }^{\text {tsu }}$ DAT | Input Data Setup Time | From SDA exiting the $30 \%$ to $70 \%$ of $V_{C C}$ window, to SCL rising edge crossing $30 \%$ of $\mathrm{V}_{\mathrm{CC}}$ | 100 |  | ns |
| $t_{\text {HD }}$ DAT | Input Data Hold Time | From SCL rising edge crossing $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$ to SDA entering the $30 \%$ to $70 \%$ of $V_{C C}$ window. | 0 |  | ns |
| tsu:sto | STOP Condition Setup Time | From SCL rising edge crossing $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$, to SDA rising edge crossing $30 \%$ of $\mathrm{V}_{\mathrm{CC}}$. | 600 |  | ns |
| $\mathrm{t}_{\text {HD: }}$ STO | STOP Condition Hold Time for Read, or Volatile Only Write | From SDA rising edge to SCL falling edge. Both crossing $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$. | 600 |  | ns |
| $t_{\text {DH }}$ | Output Data Hold Time | From SCL falling edge crossing $30 \%$ of $\mathrm{V}_{\mathrm{CC}}$, until SDA enters the $30 \%$ to $70 \%$ of $V_{C C}$ window. | 0 |  | ns |
| $t_{R}$ (Note 11) | SDA and SCL Rise Time | From $30 \%$ to $70 \%$ of $\mathrm{V}_{\mathrm{CC}}$ | $\begin{gathered} 20+ \\ 0.1^{*} \mathrm{Cb} \end{gathered}$ | 250 | ns |
| $\mathrm{t}_{\mathrm{F}}$ (Note 11) | SDA and SCL Fall Time | From $70 \%$ to $30 \%$ of $\mathrm{V}_{\mathrm{CC}}$ | $\begin{gathered} 20+ \\ 0.1^{*} \mathrm{Cb} \end{gathered}$ | 250 | ns |

Operating Specifications (Continued)

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN <br> (Note 12) | TYP <br> (Note 2) | MAX <br> (Note 12) |
| :--- | :--- | :--- | :---: | :---: | :---: |
| Cb (Note 11) | Capacitive Loading of SDA or <br> SCL | Total on-chip and off-chip | 10 |  | 400 |
| Rpu (Note 11) | SDA and SCL Bus Pull-up <br> Resistor Off-chip | Maximum is determined by $t_{R}$ and $t_{F}$. <br> For $C b=400 \mathrm{pF}, \max$ is about $2 \mathrm{k} \Omega \sim 2.5 \mathrm{k} \Omega$. <br> For $\mathrm{Cb}=40 \mathrm{pF}, \max$ is about $15 \mathrm{k} \Omega \sim 20 \mathrm{k} \Omega$. | 1 | $\mathrm{k} \Omega$ |  |

NOTES:
2. Typical values are for $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ and 3.3 V supply voltage.
3. LSB: $\left[V\left(R_{W}\right)_{127}-V\left(R_{W}\right)_{0}\right] / 127 . V\left(R_{W}\right)_{127}$ and $V\left(R_{W}\right)_{0}$ are $V\left(R_{W}\right)$ for the $D C P$ register set to $F F$ hex and 00 hex respectively. LSB is the incremental voltage when changing from one tap to an adjacent tap.
4. $\mathrm{MI}=\left|R_{127}-R_{0}\right| / 127 . R_{127}$ and $R_{0}$ are the measured resistances for the DCP register set to FF hex and 00 hex respectively. $R_{\text {OFFSET }}=R_{0} / M I$, when measuring between $R_{W}$ and $R_{L}$.
5. $R_{\text {OFFSET }}=R_{127} / M I$, when measuring between $R_{W}$ and $R_{H}$.
6. $R_{D N L}=\left(R_{i}-R_{i-1}\right) / M I$, for $i=32$ to 127 .
7. $R_{I N L}=\left[R_{i}-(M I \cdot i)-R_{0}\right] / M I$, for $i=32$ to 127 .
8. $\mathrm{TC}_{\mathrm{R}}=\frac{[\mathrm{Max}(\mathrm{Ri})-\operatorname{Min}(\mathrm{Ri})]}{[\operatorname{Max}(\mathrm{Ri})+\operatorname{Min}(\mathrm{Ri})] / 2} \times \frac{10^{6}}{+125^{\circ} \mathrm{C}}$ for $\mathrm{i}=32$ to $127, \mathrm{~T}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$. $\operatorname{Max}()$ is the maximum value of the resistance and $\operatorname{Min}()$ is
9. This parameter is not $100 \%$ tested.
10. $\mathrm{V}_{\mathrm{IL}}=0 \mathrm{~V}, \mathrm{~V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{CC}}$.
11. These are $I^{2} \mathrm{C}$-specific parameters and are not directly tested. However, they are used in the device testing to validate specifications.
12. Parameters with MIN and/or MAX limits are $100 \%$ tested at $+25^{\circ} \mathrm{C}$, unless otherwise specified. Temperature limits established by characterization and are not production tested.

## SDA vs SCL Timing



## Principles of Operation

The ISL90726 is an integrated circuit incorporating one DCP with its associated registers and an $I^{2} \mathrm{C}$ serial interface providing direct communication between a host and the potentiometer.

## DCP Description

The DCP is implemented with a combination of resistor elements and CMOS switches. The physical ends of the DCP are equivalent to the fixed terminals of a mechanical potentiometer ( $R_{H}$ and $R_{L}$ pins). The $R_{W}$ pin of the DCP is connected to intermediate nodes, and is equivalent to the wiper terminal of a mechanical potentiometer. The position of the wiper terminal within the DCP is controlled by an 7-bit volatile Wiper Register (WR). The DCP has its own WR. When the WR of the DCP contains all zeroes $(W R<6: 0>=00 h)$, its wiper terminal $\left(R_{W}\right)$ is
closest to its "Low" terminal $\left(R_{L}\right)$. When the WR of the DCP contains all ones (WR<6:0> = 7Fh), its wiper terminal $\left(R_{W}\right)$ is closest to its "High" terminal $\left(\mathrm{R}_{\mathrm{H}}\right)$. As the value of the WR increases from all zeroes (00h) to all ones (127 decimal), the wiper moves monotonically from the position closest to $R_{L}$ to the position closest to $R_{H} . R_{H}$ is not connected to a device pin. The net effect is the resistance between $R_{W}$ and $R_{L}$ increases monotonically.

While the ISL90726 is being powered up, the WR is reset to 40h (64 decimal), which locates $\mathrm{R}_{\mathrm{W}}$ roughly at the center between $R_{L}$ and $R_{H}$.

The WR and IVR can be read or written directly using the $\mathrm{I}^{2} \mathrm{C}$ serial interface as described in the following sections.

## $I^{2}$ c Serial Interface

The ISL90726 supports bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is a master and the device being controlled is the slave. The master always initiates data transfers and provides the clock for both transmit and receive operations. Therefore, the ISL90726 operates as slave device in all applications.
All communication over the $\mathrm{I}^{2} \mathrm{C}$ interface is conducted by sending the MSB of each byte of data first.

## Protocol Conventions

Data states on the SDA line can change only during SCL LOW periods. SDA state changes during SCL HIGH are reserved for indicating START and STOP conditions (see Figure 1). On power-up of the ISL90726, the SDA pin is in the input mode.
All ${ }^{2} \mathrm{C}$ interface operations must begin with a START condition, which is a HIGH to LOW transition of SDA while SCL is HIGH. The ISL90726 continuously monitors the SDA and SCL lines for the START condition and does not respond to any command until this condition is met (see Figure 1). A START condition is ignored during the power-up sequence and during internal non-volatile write cycles.
All $I^{2} \mathrm{C}$ interface operations must be terminated by a STOP condition, which is a LOW to HIGH transition of SDA while SCL is HIGH (see Figure 1).

An ACK, Acknowledge, is a software convention used to indicate a successful data transfer. The transmitting device, either master or slave, releases the SDA bus after transmitting eight bits. During the ninth clock cycle, the receiver pulls the SDA line LOW to acknowledge the reception of the eight bits of data (see Figure 2).

The ISL90726 responds with an ACK after recognition of a START condition followed by a valid Identification Byte, and once again after successful receipt of an Address Byte. The ISL90726 also responds with an ACK after receiving a Data Byte of a write operation. The master must respond with an ACK after receiving a Data Byte of a read operation.

A valid Identification Byte contains 0101110 as the seven MSBs. The LSB in the Read/Write bit. Its value is " 1 " for a Read operation, and "0" for a Write operation (see Table 1).

TABLE 1. IDENTIFICATION BYTE FORMAT

| 0 1 0 1 1 1 0 $\mathrm{R} / \overline{\mathrm{W}}$ <br> (MSB)        |
| :--- |

## Write Operation

A Write operation requires a START condition, followed by a valid Identification Byte, a valid Address Byte, a Data Byte, and a STOP condition. After each of the three bytes, the ISL90726 responds with an ACK. At this time, the device enters its standby state (see Figure 3).

## Data Protection

A valid Identification Byte, Address Byte, and total number of SCL pulses act as a protection of both volatile and non-volatile registers. During a Write sequence, the Data Byte is loaded into an internal shift register as it is received. If the Address Byte is Oh, the Data Byte is transferred to the Wiper Register (WR) at the falling edge of the SCL pulse that loads the last bit (LSB) of the Data Byte. If an address other than 00h, or an invalid slave address is sent, then the device will respond with no ACK.

## Read Operation

A Read operation consist of a three byte instruction followed by one or more Data Bytes (see Figure 4). The master initiates the operation issuing the following sequence: a START, the Identification byte with the R/W bit set to " 0 ", an Address Byte, a second START, and a second Identification byte with the R/W bit set to "1". After each of the three bytes, the ISL90726 responds with an ACK. Then the ISL90726 transmits the Data Byte as long as the master responds with an ACK during the SCL cycle following the eighth bit of each byte. The master then terminates the read operation (issuing a STOP condition) following the last bit of the Data Byte (see Figure 4).


FIGURE 1. VALID DATA CHANGES, START, AND STOP CONDITIONS


FIGURE 2. ACKNOWLEDGE RESPONSE FROM RECEIVER


FIGURE 3. BYTE WRITE SEQUENCE


FIGURE 4. READ SEQUENCE

Small Outline Transistor Plastic Packages (SC70-6)

P6.049
6 LEAD SMALL OUTLINE TRANSISTOR PLASTIC PACKAGE

| SYMBOL | INCHES |  | MILLIMETERS |  | NOTES |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |  |
| A | 0.031 | 0.043 | 0.80 | 1.10 | - |
| A1 | 0.000 | 0.004 | 0.00 | 0.10 | - |
| A2 | 0.031 | 0.039 | 0.00 | 1.00 | - |
| b | 0.006 | 0.012 | 0.15 | 0.30 | - |
| b1 | 0.006 | 0.010 | 0.15 | 0.25 |  |
| c | 0.003 | 0.009 | 0.08 | 0.22 | 6 |
| c1 | 0.003 | 0.009 | 0.08 | 0.20 | 6 |
| D | 0.073 | 0.085 | 1.85 | 2.15 | 3 |
| E | 0.071 | 0.094 | 1.80 | 2.40 | - |
| E1 | 0.045 | 0.053 | 1.15 | 1.35 | 3 |
| e | 0.0256 Ref |  | 0.65 Ref |  | - |
| e1 | 0.0512 Ref |  | 1.30 Ref |  | - |
| L | 0.010 | 0.018 | 0.26 | 0.46 | 4 |
| L1 | 0.017 Ref. |  | 0.420 Ref. |  |  |
| L2 | 0.006 BSC |  | 0.15 BSC |  |  |
| N | 6 |  | 6 |  | 5 |
| R | 0.004 | - | 0.10 | - |  |
| R1 | 0.004 | 0.010 | 0.15 | 0.25 |  |
| $\alpha$ | $0^{0}$ | $8^{0}$ | $0^{0}$ | $8^{0}$ | - |

Rev. 2 9/03
NOTES:

1. Dimensioning and tolerance per ASME Y14.5M-1994.
2. Package conforms to EIAJ SC70 and JEDEC MO203AB.
3. Dimensions D and E1 are exclusive of mold flash, protrusions, or gate burrs.
4. Footlength $L$ measured at reference to gauge plane.
5. " $N$ " is the number of terminal positions.
6. These Dimensions apply to the flat section of the lead between 0.08 mm and 0.15 mm from the lead tip.
7. Controlling dimension: MILLIMETER. Converted inch dimensions are for reference only
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