NOT RECOMMENDED FOR NEW DESIGNS

## Dual Digitally Controlled Potentiometer (XDCP ${ }^{\text {TM }}$ ) with Operational Amplifier

## FEATURES

- Two CMOS voltage operational amplifiers
- Two digitally controlled potentiometers
- Can be combined or used separately
- Amplifiers:
-Low voltage operation
$-\mathrm{V}+/ \mathrm{V}-= \pm 2.7 \mathrm{~V}$ to $\pm 5.5 \mathrm{~V}$
—Rail-to-rail CMOS performance
-1 MHz gain bandwidth product
- Digitally controlled potentiometers
-Dual 64 tap potentiometers
$-R_{\text {total }}=10 \mathrm{k} \Omega$
-2-wire serial interface
$-\mathrm{V}_{\mathrm{cc}}=2.7 \mathrm{~V}$ to 5.5 V


## DESCRIPTION

The X9438 is a monolithic CMOS IC that incorporates two operational amplifiers and two nonvolatile digitally controlled potentiometers. The amplifiers are CMOS differential input voltage operational amplifiers with near rail-to-rail outputs. All pins for the two amplifiers are brought out of the package to allow combining them with the potentiometers, or using them as complete stand-alone amplifiers.

The digitally controlled potentiometers consist of a series string of 63 polycrystalline resistors that behave as standard integrated circuit resistors. The two-wire serial port, common to both pots, allows the user to program the connection of the wiper output to any of the resistor nodes in the series string. The wiper position is saved in the on board E2 memory to allow for nonvolatile restoration of the wiper position.

A wide variety of applications can be implemented using the potentiometers and the amplifiers. A typical application is to implement the amplifier as a wiper buffer in circuits that use the potentiometer as a voltage reference. The potentiometer can also be combined with the amplifier yielding a digitally programmable gain amplifier or programmable current source.

## BLOCK DIAGRAM



## PIN DESCRIPTIONS

## Host Interface Pins

## Serial Clock (SCL)

The SCL input is used to clock data into and out of the X9438.

## Serial Data (SDA)

SDA is a bidirectional pin used to transfer data into and out of the device. It is an open drain output and may be wire-ORed with any number of open drain or open collector outputs. An open drain output requires the use of a pull-up resistor.

## Device Address ( $\mathrm{A}_{0}-\mathrm{A}_{3}$ )

The address inputs are used to set the least significant 4 bits of the 8 -bit slave address. A match in the slave address serial data stream must be made with the address input in order to initiate communication with the X9438. A maximum of 16 devices may share the same 2-wire serial bus.

## Potentiometer Pins ${ }^{(1)}$

$\mathbf{R}_{\mathbf{H}}\left(\mathbf{R}_{\mathrm{H} 0}-\mathbf{R}_{\mathrm{H} 1}\right), \mathbf{R}_{\mathrm{L}}\left(\mathbf{R}_{\mathrm{L} 0}-\mathbf{R}_{\mathrm{L} 1}\right)$
The $R_{H}$ and $R_{L}$ inputs are equivalent to the terminal connections on either end of a mechanical potentiometer.
$\mathrm{R}_{\mathrm{W}}\left(\mathrm{R}_{\mathrm{W} 0}-\mathrm{R}_{\mathrm{W}_{1}}\right)$
The wiper output is equivalent to the wiper output of a mechanical potentiometer.

## Amplifier and Device Pins

Amplifier Input Voltage $\mathrm{V}_{\mathrm{NI}}(\mathbf{0}, \mathbf{1})$ and $\mathrm{V}_{\mathrm{INV}}(\mathbf{0}, \mathbf{1})$
$\mathrm{V}_{\mathrm{NI}}$ and $\mathrm{V}_{\text {INV }}$ are inputs to the noninverting (+) and inverting (-) inputs of the operational amplifiers.

## Amplifier Output Voltage $\mathrm{V}_{\text {OUT }}(\mathbf{0}, \mathbf{1})$

$\mathrm{V}_{\text {OUT }}$ is the voltage output pin of the operational amplifier.

## Hardware Write Protect Input $\overline{\mathrm{WP}}$

The $\overline{W P}$ pin, when low, prevents non-volatile writes to the wiper counter registers.

Note: (1) Alternate designations for $\mathrm{R}_{\mathrm{H}}, \mathrm{R}_{\mathrm{L}}, \mathrm{R}_{\mathrm{W}}$ are $\mathrm{V}_{\mathrm{H}}, \mathrm{V}_{\mathrm{L}}, \mathrm{V}_{\mathrm{W}}$

## Analog Supplies $\mathrm{V}_{\mathbf{+}}$, V -

The analog supplies $\mathrm{V}+$, V - are the supply voltages for the XDCP analog section and the operational amplifiers.

System Supply $\mathbf{V}_{\mathbf{C C}}$ and Ground $\mathbf{V}_{\mathbf{S S}}$.
The system supply $\mathrm{V}_{\mathrm{CC}}$ and its reference $\mathrm{V}_{\mathrm{SS}}$ is used to bias the interface and control circuits.

## PIN CONFIGURATION



## PIN NAMES

| Symbol | Description |
| :---: | :---: |
| SCL | Serial Clock |
| SDA | Serial Data |
| A0-A3 | Device Address |
| $\begin{aligned} & \mathrm{R}_{\mathrm{HO}}-\mathrm{R}_{\mathrm{H} 1}, \\ & \mathrm{R}_{\mathrm{LO}}-\mathrm{R}_{\mathrm{L} 1} \end{aligned}$ | Potentiometers (terminal equivalent) |
| $\mathrm{R}_{\mathrm{W} 0}-\mathrm{R}_{\mathrm{W} 1}$ | Potentiometers (wiper equivalent) |
| $\mathrm{V}_{\mathrm{NI}(0,1)}$, <br> $\mathrm{V}_{\operatorname{INV}(0,1)}$ | Amplifier Input Voltages |
| $\mathrm{V}_{\text {OUTO, }} \mathrm{V}_{\text {OUT1 }}$ | Amplifier Outputs |
| WP | Hardware Write Protection |
| V+,V- | Analog and Voltage Amplifier Supplies |
| $\mathrm{V}_{\text {CC }}$ | System/Digital Supply Voltage |
| $\mathrm{V}_{\text {SS }}$ | System Ground |
| NC | No Connection |

## PRINCIPLES OF OPERATION

The X9438 is an integrated microcircuit incorporating two resistor arrays, two operational amplifiers and their associated registers and counters; and the serial interface logic providing direct communication between the host and the digitally controlled potentiometers and operational amplifiers.

## Serial Interface

The X9438 supports a bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is a master and the device being controlled is the slave. The master will always initiate data transfers and provide the clock for both transmit and receive operations. Therefore, the X9438 will be considered a slave device in all applications.

## Clock and Data Conventions

Data states on the SDA line can change only during SCL LOW periods (thow). SDA state changes during SCL HIGH are reserved for indicating start and stop conditions.

## Start Condition

All commands to the X9438 are preceded by the start condition, which is a HIGH to LOW transition of SDA while SCL is HIGH ( $\mathrm{t}_{\text {HIGH }}$ ). The X9438 continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition is met.

## Stop Condition

All communications must be terminated by a stop condition, which is a LOW to HIGH transition of SDA while SCL is HIGH.

## Acknowledge

Acknowledge is a software convention used to provide a positive handshake between the master and slave devices on the bus to indicate the successful receipt of data. The transmitting device, either the master or the slave, will release the SDA bus after transmitting eight bits. The master generates a ninth clock cycle and during this period the receiver pulls the SDA line LOW to acknowledge that it successfully received the eight bits of data.

The X9438 will respond with an acknowledge after recognition of a start condition and its slave address and once again after successful receipt of the command byte. If the command is followed by a data byte the X9438 will respond with a final acknowledge.

## Operational Amplifier

The voltage operational amplifiers are CMOS rail-torail output general purpose amplifiers. They are designed to operate from dual ( $\pm$ ) power supplies. The amplifiers may be configured like any standard amplifier. All pins are externally available to allow connections with the potentiometers or as stand alone amplifiers.

## Potentiometer/Array Description

The X9438 is comprised of two resistor arrays and two operational amplifiers. Each array contains 63 discrete resistive segments that are connected in series. The physical ends of each array are equivalent to the fixed terminals of a mechanical potentiometer (RH and RL inputs).

At both ends of each array and between each resistor segment is a CMOS switch connected to the wiper ( $\mathrm{R}_{\mathrm{W}}$ ) output. Within each individual array only one switch may be turned on at a time. These switches are controlled by a volatile wiper counter register (WCR). The six bits of the WCR are decoded to select, and enable, one of sixty-four switches.

The WCR may be written directly, or it can be changed by transferring the contents of one of four associated data registers into the WCR. These data registers and the WCR can be read and written by the host system.

## INSTRUCTIONS AND PROGRAMMING

## Device Addressing

Following a start condition the master must output the address of the slave it is accessing. The most significant four bits of the slave address are the device type identifier (refer to Figure 1). For the X9438 this is fixed as $0101[\mathrm{~B}]$.

Figure 1. Address/Identification Byte Format


The next four bits of the slave address are the device address. The physical device address is defined by the state of the $\mathrm{A}_{0}-\mathrm{A}_{3}$ inputs. The X9438 compares the serial data stream with the address input state; a successful compare of all four address bits is required for the X9438 to respond with an acknowledge. The $A_{0}-A_{3}$ inputs can be actively driven by CMOS input signals or tied to $\mathrm{V}_{\mathrm{CC}}$ or $\mathrm{V}_{\mathrm{SS}}$.

## Acknowledge Polling

The disabling of the inputs, during the internal non-volatile write operation, can be used to take advantage of the typical 5ms EEPROM write cycle time. Once the stop condition is issued to indicate the end of the nonvolatile write command the X9438 initiates the internal write cycle. ACK polling (Flow 1) can be initiated immediately. This involves issuing the start condition followed by the device slave address. If the X9438 is still busy with the write operation no ACK will be returned. If the X9438 has completed the write operation an ACK will be returned and the master can then proceed with the next operation.

Flow 1. ACK Polling Sequence


## Instruction Structure

The byte following the address contains the instruction and register pointer information. The four most significant bits are the instruction. The next four bits point to one of the two pots and when applicable they point to one of the four WCRs associated data registers. The format is shown below in Figure 2.

Figure 2. Instruction Byte Format


The four high order bits define the instruction. The next two bits (R1 and R0) select one of the two registers that is to be acted upon when a register oriented instruction is issued. The last bit (P0) selects which one of the two potentiometers is to be affected by the instruction.

Four of the nine instructions end with the transmission of the instruction byte. The basic sequence is illustrated in Figure 3. These two-byte instructions exchange data between the wiper counter register and one of the data registers. A transfer from a data register to a wiper counter register is essentially a write to a static RAM. The response of the wiper to this action will be delayed $t_{\text {wRL }}$. A transfer from the wiper counter register (current wiper position) to a data register is a write to non-volatile memory and takes a minimum of $t_{W R}$ to complete. The transfer can occur between one of the two potentiometers and one of its associated registers; or it may occur globally, wherein the transfer occurs between all of the potentiometers and one of their associated registers.

Four instructions require a three-byte sequence to complete. The basic sequence is illustrated in Figure 4. These instructions transfer data between the host and the X9438; either between the host and one of the data registers or directly between the host and the wiper counter and analog control registers. These instructions are: 1) Read Wiper Counter Register or read the current wiper position of the selected pot, 2) Write Wiper Counter Register, i.e. change current wiper position of the selected pot; 3) Read Data Register, read the contents of the selected non-volatile register; 4) Write Data Register, write a new value to the selected data register. The bit structures of the instructions are shown in Figure 6.

Figure 3. Two-Byte Command Sequence


Figure 4. Three-Byte Command Sequence


The Increment/Decrement command is different from the other commands. Once the command is issued and the X9438 has responded with an acknowledge, the master can clock the selected wiper up and/or down in one segment steps; thereby, providing a fine tuning capability to the host. For each SCL clock pulse
( $\mathrm{t}_{\text {HIGH }}$ ) while SDA is HIGH, the selected wiper will move one resistor segment towards the $\mathrm{V}_{\mathrm{H}}$ terminal. Similarly, for each SCL clock pulse while SDA is LOW, the selected wiper will move one resistor segment towards the $\mathrm{V}_{\mathrm{L}}$ terminal. A detailed illustration of the sequence for this operation is shown in Figure 5.

Figure 5. Increment/Decrement Command Sequence


Figure 6. Instruction Set

## Read Wiper Counter Register (WCR)

Read the contents of the Wiper Counter Register $\mathrm{P}_{0}$.


## Write Wiper Counter Register (WCR)

Write new value to the Wiper Counter Register $\mathrm{P}_{0}$.


## Read Data Register (DR)

Read the contents of the Register pointed to by $\mathrm{P}_{0}$ and $\mathrm{R}_{1}-\mathrm{R}_{0}$.


## Write Data Register (DR)

Write new value to the Register pointed to by $\mathrm{P}_{0}$ and $\mathrm{R}_{1}-\mathrm{R}_{0}$.

| $\mathrm{S}$ | device type identifier |  |  |  | device addresses |  |  |  |  | instruction opcode |  |  | WCR/DR addresses |  |  |  |  | register data (sent by master on SDA) |  |  |  |  |  |  |  | $\left\|\begin{array}{c} \mathrm{S} \\ \mathrm{~A} \\ \mathrm{C} \\ \mathrm{~K} \end{array}\right\|$ |  | HIGH-VOLTAGE WRITE CYCLE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R | 0 | 1 | 0 | 1 | A | A | A <br> 1 | A | K | 1 | 0 | 0 | $\begin{gathered} \mathrm{R} \\ 1 \end{gathered}$ | $\begin{aligned} & \mathrm{R} \\ & 0 \end{aligned}$ | 0 | P 0 | K | 0 | 0 | D |  | 3 | 2 | D | 0 |  |  |  |

## Definitions:

SACK - Slave acknowledge, MACK - Master acknowledge, I/D - Increment/Decrement (1/0), R - Register, P-Potentiometer

Figure 6. Instruction Set (continued)
Transfer Data Register to Wiper Counter Register
Transfer the contents of the Register pointed to by $R_{1}-R_{0}$ to the WCR pointed to by $P_{0}$.

| $S$ | device type identifier |  |  |  | device addresses |  |  |  | $\begin{aligned} & \mathrm{A} \\ & \mathrm{C} \\ & \mathrm{~K} \end{aligned}$ | instruction opcode |  |  |  | WCR/DR <br> addresses |  |  |  | $\begin{aligned} & \mathrm{S} \\ & \mathrm{~A} \\ & \mathrm{C} \\ & \mathrm{~K} \end{aligned}$ |  | S |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & R \\ & T \end{aligned}$ | 0 | 1 | 0 | 1 | $\begin{aligned} & \mathrm{A} \\ & 3 \end{aligned}$ | A 2 | A 1 | A 0 |  | 1 | 1 | 0 | 1 | $R$ 1 | $R$ 0 | 0 | 0 |  | P | P |

## Transfer Wiper Counter Register to Data Register

Transfer the contents of the WCR pointed to by $P_{0}$ to the Register pointed to by $R_{1}-R_{0}$.

| $\begin{array}{\|l\|} \hline S \\ T \end{array}$ | device type identifier |  |  |  | device addresses |  |  |  | S | instruction opcode |  |  | WCR/DR addresses |  |  |  | $\begin{aligned} & \mathrm{S} \\ & \mathrm{~A} \\ & \mathrm{C} \\ & \mathrm{~K} \end{aligned}$ |  | HIGH-VOLTAGE WRITE CYCLE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $R$ | 0 | 1 | 0 | 1 | A 3 | A | A <br> 1 | A | K | 1 | 1 | 0 | R | R | 0 | P |  |  |  |

## Global Transfer Data Register to Wiper Counter Register

Transfer the contents of all four Data Registers pointed to by $R_{1}-R_{0}$ to their respective WCR.

| $\mathrm{S}$ | device type identifier |  |  |  | device addresses |  |  |  | $\left\|\begin{array}{l} \mathrm{S} \\ \mathrm{~A} \\ \mathrm{C} \\ \mathrm{~K} \end{array}\right\|$ | instruction opcode |  |  |  | $\overline{\mathrm{DR}}$ <br> addresses |  |  |  | $\begin{aligned} & \mathrm{S} \\ & \mathrm{~A} \\ & \mathrm{C} \\ & \mathrm{~K} \end{aligned}$ | S$T$$O$$P$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R | 0 | 1 | 0 | 1 | $\begin{aligned} & A \\ & 3 \end{aligned}$ | $\begin{aligned} & A \\ & 2 \end{aligned}$ | A 1 | 0 |  | 0 | 0 | 0 | 1 | $R$ 1 | $R$ 0 | 0 | 0 |  |  |  |

## Global Transfer Wiper Counter Register to Data Register

Transfer the contents of all WCRs to their respective data Registers pointed to by $R_{1}-R_{0}$.

| $\begin{aligned} & \mathrm{S} \\ & \mathrm{~T} \end{aligned}$ | device type identifier |  |  |  | device addresses |  |  |  | instruction opcode |  |  |  |  | DR <br> addresses |  |  |  | $\begin{aligned} & \mathrm{S} \\ & \mathrm{~A} \\ & \mathrm{C} \\ & \mathrm{~K} \end{aligned}$ | S | HIGH-VOLTAGE WRITE CYCLE |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| R | 0 | 1 | 0 | 1 | $\begin{aligned} & \mathrm{A} \\ & 3 \end{aligned}$ | $\begin{aligned} & \mathrm{A} \\ & 2 \end{aligned}$ | $\begin{gathered} A \\ 1 \end{gathered}$ | $\begin{gathered} \mathrm{A} \\ 0 \end{gathered}$ | $\left\|\begin{array}{l} C \\ K \end{array}\right\|$ | 1 | 0 | 0 | 0 | $\begin{gathered} R \\ 1 \end{gathered}$ | $R$ 0 | 0 | 0 |  | O |  |

## Increment/Decrement Wiper Counter Register

Enable Increment/decrement of the WCR pointed to by $\mathrm{P}_{0}$.


P0: 0 or 1 only.

## REGISTER OPERATION

Both digitally controlled potentiometers share the serial interface and share a common architecture. Each potentiometer is associated with a Wiper Counter Register (WCR), and four Data Registers. Figure 7 illustrates the control, registers, and system features of the device.

Figure 7. System Block Diagram


Wiper Counter (WCR) and Analog Control Registers (ACR)
The X9438 contains two wiper counter registers, one for each XDCP. The wiper counter register is equivalent to a serial-in, parallel-out counter, with its outputs decoded to select one of sixty-four switches along its resistor array. The contents of the wiper counter register can be altered in four ways: it may be written directly by the host via the write WCR Instruction (serial load); it may be written indirectly by transferring the contents of one of four associated data registers (DR) via the XFR data register instruction (parallel load); it can be modified one step at a time by the increment/decrement instruction (WCR only). Finally, it is loaded with the contents of its data register zero (RO) upon power-up.

The wiper counter register is a volatile register; that is, its contents are lost when the X9438 is powered-down. Although the registers are automatically loaded with the value in RO upon power-up, it should be noted this may be different from the value present at power-down.

## Data Registers (DR)

Each potentiometer has four non-volatile data registers (DR). These can be read or written directly by the host and data can be transferred between any of the four data registers and the WCR. It should be noted all operations changing data in one of these registers is a nonvolatile operation and will take a maximum of 10 ms .

If the application does not require storage of multiple settings for the potentiometer, these registers can be used as regular memory locations that could store system parameters or user preference data.

## REGISTER DESCRIPTIONS AND MEMORY MAP

Memory Map

| WCRO | WCR1 |
| :---: | :---: |
| DR0 | DR0 |
| DR1 | DR1 |
| DR2 | DR2 |
| DR3 | DR3 |

## Wiper Counter Register (WCR)

| $\mathbf{0}$ | $\mathbf{0}$ | WP5 | WP4 | WP3 | WP2 | WP1 | WP0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | (volatile) |  |  |  |  | (LSB) |

WPO-WP5 identify wiper position.
Data Registers (DR, R0-R3)


## ABSOLUTE MAXIMUM RATINGS

Temperature under bias $\qquad$
Storage temperature $\qquad$ $-65^{\circ} \mathrm{C}$ to $+135^{\circ} \mathrm{C}$

Voltage on SDA, SCL or any address input with respect to $\mathrm{V}_{\mathrm{SS}}$ $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$
input wh
Voltage on any $\mathrm{V}_{+}$(referenced to $\mathrm{V}_{\mathrm{SS}}$ ) ................ +7 V
Voltage on any V - (referenced to $\mathrm{V}_{\mathrm{SS}}$ ) .................. 7 V
(V+) - (V-) ...........................................................10V
Any $\mathrm{R}_{\mathrm{H}}$................................................................. $\mathrm{V}_{+}$
Any $\mathrm{R}_{\mathrm{L}}$....................................................................VLead temperature (soldering, 10 seconds)........ $300^{\circ} \mathrm{C}$

## COMMENT

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device (at these or any other conditions above those listed in the operational sections of this specification) is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

| Device | Supply Voltage $\left(\mathbf{V}_{\text {CC }}\right)$ Limits |
| :---: | :---: |
| X 9438 | $5 \mathrm{~V} \pm 10 \%$ |
| $\mathrm{X} 9438-2.7$ | 2.7 V to 5.5 V |

POTENTIOMETER CHARACTERISTICS (Over recommended operating conditions unless otherwise stated.)

| Symbol | Parameter |  | Limits |  |  |  | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. | Unit |  |
| $\mathrm{R}_{\text {TOTAL }}$ | End to end resistance |  | -20 |  | +20 | \% |  |
|  | Power rating |  |  |  | 50 | mW | $25^{\circ} \mathrm{C}$, each pot |
| $\mathrm{I}_{\mathrm{W}}$ | Wiper current |  | -3 |  | +3 | mA |  |
| $\mathrm{R}_{\mathrm{W}}$ | Wiper resistance |  |  | 40 | 100 | $\Omega$ | $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V}$, Wiper Current $=3 \mathrm{~mA}$ |
|  |  |  |  | 100 | 250 | $\Omega$ | $\mathrm{V}_{\mathrm{CC}}=2.7$, Wiper Current $=1 \mathrm{~mA}$ |
| Vv+ | Voltage on V+ pin | X9438 | +4.5 |  | +5.5 | V |  |
|  |  | X9438-2.7 | +2.7 |  | +5.5 |  |  |
| Vv- | Voltage on V- pin | X9438 | -5.5 |  | -4.5 | V |  |
|  |  | X9438-2.7 | -5.5 |  | -2.7 |  |  |
| $\mathrm{V}_{\text {TERM }}$ | Voltage on any $\mathrm{R}_{\mathrm{H}}$ or $\mathrm{R}_{\mathrm{L}}$ pin |  | V- |  | V+ | V |  |
|  | Noise |  |  | -100 |  | dBv | Ref: 1V |
|  | Resolution (4) |  |  | 1.6 |  | \% |  |
|  | Absolute linearity ${ }^{(1)}$ |  | -1 |  | +1 | MI ${ }^{(3)}$ | $\mathrm{V}_{\mathrm{w}(\mathrm{n}) \text { (actual) }}-\mathrm{V}_{\mathrm{w}(\mathrm{n}) \text { (expected) }}$ |
|  | Relative linearity ${ }^{(2)}$ |  | -0.2 |  | +0.2 | MI ${ }^{(3)}$ | $\mathrm{V}_{\mathrm{w}(\mathrm{n}+1)}-\left[\mathrm{V}_{\mathrm{w}(\mathrm{n})+\mathrm{Ml}}\right]$ |
|  | Temperature coefficient of $\mathrm{R}_{\text {TOTAL }}$ |  |  | $\pm 300$ |  | ppm $/{ }^{\circ} \mathrm{C}$ |  |
|  | Ratiometric temperature coefficient |  |  |  | $\pm 20$ | ppm $/{ }^{\circ} \mathrm{C}$ |  |

Notes: (1) Absolute linearity is utilized to determine actual wiper voltage versus expected voltage as determined by wiper position when used as a potentiometer.
(2) Relative linearity is utilized to determine the actual change in voltage between two successive tap positions when used as a potentiometer. It is a measure of the error in step size.
(3) $\mathrm{MI}=\mathrm{RTOT} / 63$ or $\left(\mathrm{R}_{\mathrm{H}}-\mathrm{R}_{\mathrm{L}}\right) / 63$, single pot $(=\mathrm{LSB})$
(4) Individual array resolutions

AMPLIFIER ELECTRICAL CHARACTERISTICS
(Over the recommended operating conditions unless otherwise specified.)

| Symbol | Parameter | Condition | Industrial |  |  | Commercial |  |  | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min. | Typ. | Max. | Min. | Typ. | Max. |  |
| $\mathrm{V}_{\mathrm{OS}}$ | Input offset voltage | $\mathrm{V}+/ \mathrm{V}- \pm 3 \mathrm{~V}$ to $\pm 5 \mathrm{~V}$ |  | 1 | 3 |  | 1 | 2 | mV |
| TC vos | Input offset voltage temp. coefficient | $\mathrm{V}+/ \mathrm{V}- \pm 3 \mathrm{~V}$ to $\pm 5 \mathrm{~V}$ |  | -10 |  |  | -10 |  | $\mu \mathrm{V} /{ }^{\circ} \mathrm{C}$ |
| $\mathrm{I}_{\mathrm{B}}$ | Input bias current | $\mathrm{V}+/ \mathrm{V}- \pm 3 \mathrm{~V}$ to $\pm 5 \mathrm{~V}$ |  | 50 |  |  | 50 |  | pA |
| los | Input offset current | $\mathrm{V}+/ \mathrm{V}- \pm 3 \mathrm{~V}$ to $\pm 5 \mathrm{~V}$ |  | 25 |  |  | 25 |  | pA |
| CMRR | Common mode rejection ratio | $\mathrm{V}_{\text {CM }}=-1 \mathrm{~V}$ to +1 V | 70 |  |  | 70 |  |  | dB |
| PSRR | Power supply rejection ratio | $\mathrm{V}+/ \mathrm{V}- \pm 3 \mathrm{~V}$ to $\pm 5 \mathrm{~V}$ | 70 |  |  | 70 |  |  | dB |
| $\mathrm{V}_{\mathrm{CM}}$ | Input common mode voltage range | $\mathrm{T}_{\mathrm{j}}=25^{\circ} \mathrm{C}$ | V- |  | V+ | V- |  | V+ | V |
| $\mathrm{A}_{V}$ | Large signal voltage gain | $\mathrm{V}_{\mathrm{O}}=-1 \mathrm{~V}$ to +1 V | 30 | 50 |  | 30 | 50 |  | V/mV |
| $\mathrm{V}_{\mathrm{O}}$ | Output voltage swing | $\begin{aligned} & \text { V- } \\ & \mathrm{V}_{+} \end{aligned}$ | +0.1 |  | -. 15 | +0.1 |  | -. 15 | $\begin{aligned} & \hline \mathrm{V} \\ & \mathrm{~V} \end{aligned}$ |
| lo | Output current | $\begin{aligned} & V+/ V-= \pm 5.5 \mathrm{~V} \\ & \mathrm{~V}+/ \mathrm{V}-= \pm 3.3 \mathrm{~V} \end{aligned}$ | $\begin{aligned} & 50 \\ & 30 \end{aligned}$ |  |  | $\begin{aligned} & 50 \\ & 30 \end{aligned}$ |  |  | $\begin{aligned} & \mathrm{mA} \\ & \mathrm{~mA} \end{aligned}$ |
| Is | Supply current | $\mathrm{V}+/ \mathrm{V}-= \pm 5.0 \mathrm{~V}$ |  |  | 3 |  |  | 3 | mA |
|  |  | $\mathrm{V}+/ \mathrm{V}-= \pm 3.0 \mathrm{~V}$ |  |  | 1.5 |  |  | 1.5 | mA |
| GB | Gain-bandwidth prod | $\mathrm{R}_{\mathrm{L}}=100 \mathrm{k}, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pf}$ |  | 1.0 |  |  | 1.0 |  | MHz |
| SR | Slew rate | $\mathrm{R}_{\mathrm{L}}=100 \mathrm{k}, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pf}$ |  | 1.5 |  |  | 1.5 |  | V/usec |
| $\Phi_{\text {M }}$ | Phase margin | $\mathrm{R}_{\mathrm{L}}=100 \mathrm{k}, \mathrm{C}_{\mathrm{L}}=50 \mathrm{pf}$ |  | 80 |  |  | 80 |  | Deg. |

$\mathrm{V}+$ and V - $( \pm 5 \mathrm{~V}$ to $\pm 3 \mathrm{~V})$ are the amplifier power supplies. The amplifiers are specified with dual power supplies. $\mathrm{V}_{\mathrm{CC}}$ and $\mathrm{V}_{\text {SS }}$ is the logic supply. All ratings are over the temperature range for the Industrial ( -40 to $+85^{\circ} \mathrm{C}$ ) and Commercial ( 0 to $70^{\circ} \mathrm{C}$ ) versions of the part unless specified differently.

## SYSTEM/DIGITAL D.C. OPERATING CHARACTERISTICS

(Over the recommended operating conditions unless otherwise specified.)

| Symbol | Parameter | Limits |  |  |  | Test Conditions |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Min. | Typ. | Max. | Unit |  |
| $\mathrm{I}_{\mathrm{CC}}$ | $\mathrm{V}_{\text {CC }}$ supply current (active) |  |  | 400 | $\mu \mathrm{A}$ | $\begin{aligned} & \mathrm{f}_{\mathrm{SCL}}=400 \mathrm{kHz}, \mathrm{SDA}=\text { Open, } \\ & \text { Other Inputs }=V_{S S} \end{aligned}$ |
| $\mathrm{I}_{\text {SB }}$ | $\mathrm{V}_{\text {CC }}$ current (standby) |  |  | 1 | $\mu \mathrm{A}$ | SCL $=$ SDA $=\mathrm{V}_{\text {CC }}$, Addr. $=\mathrm{V}_{\text {SS }}$ |
| $\mathrm{ILI}^{\prime}$ | Input leakage current |  |  | 10 | $\mu \mathrm{A}$ | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {SS }}$ to $\mathrm{V}_{\text {CC }}$ |
| Lo | Output leakage current |  |  | 10 | $\mu \mathrm{A}$ | $\mathrm{V}_{\text {OUT }}=\mathrm{V}_{\text {SS }}$ to $\mathrm{V}_{\text {CC }}$ |
| $\mathrm{V}_{\mathrm{IH}}$ | Input HIGH voltage | $\mathrm{V}_{\text {CC }} \times 0.7$ |  | $\mathrm{V}_{\mathrm{CC}}+0.5$ | V |  |
| $\mathrm{V}_{\text {IL }}$ | Input LOW voltage | -0.5 |  | $\mathrm{V}_{\text {CC }} \times 0.1$ | V |  |
| $\mathrm{V}_{\mathrm{OL}}$ | Output LOW voltage |  |  | 0.4 | V | $\mathrm{I}_{\mathrm{OL}}=3 \mathrm{~mA}$ |

## ENDURANCE AND DATA RETENTION

| Parameter | Min. | Unit |
| :---: | :---: | :---: |
| Minimum endurance | 100,000 | Data changes per bit per register |
| Data retention | 100 | Years |

## CAPACITANCE

| Symbol | Test | Typical | Unit | Test Conditions |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{C}_{/ / \mathrm{O}}$ | Input/output capacitance (SDA) | 8 | pF | $\mathrm{V}_{/ / \mathrm{O}}=0 \mathrm{~V}$ |
| $\mathrm{C}_{\mathrm{IN}}$ | Input capacitance (A0, A1, A2, A3, and SCL) | 6 | pF | $\mathrm{V}_{I N}=0 \mathrm{~V}$ |
| $\mathrm{C}_{\mathrm{L}}\left\|\mathrm{C}_{\mathrm{H}}\right\| \mathrm{C}_{\mathrm{W}}$ | Potentiometer capacitance | $10 / 10 / 25$ | pF | See SPICE Model |

## POWER-UP TIMING AND SEQUENCE

| Power-up sequence ${ }^{(1)}$ : (1) $\mathrm{V}_{\mathrm{CC}} \quad$ (2) $\mathrm{V}+$ and V - |
| :--- | :--- |
| Power-down sequence: no limitation |

## A.C. TEST CONDITIONS

| Input pulse levels | $\mathrm{V}_{\mathrm{CC}} \times 0.1$ to $\mathrm{V}_{\mathrm{CC}} \times 0.9$ |
| :--- | :--- |
| Input rise and fall times | 10 ns |
| Input and output timing level | $\mathrm{V}_{\mathrm{CC}} \times 0.5$ |

Note: (1) Applicable to recall and power consumption applications

## EQUIVALENT A.C. LOAD CIRCUIT



## SPICE Macro Model



## TIMING DIAGRAMS

## START and STOP Timing



Input Timing


Output Timing


DCP Timing (for All Load Instructions)


## DCP Timing (for Increment/Decrement Instruction)



Write Protect and Device Address Pins Timing


## AC TIMING

| Symbol | Parameter | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{f}_{\text {SCL }}$ | Clock frequency |  | 400 | kHz |
| $\mathrm{t}_{\mathrm{CYC}}$ | Clock cycle time | 2500 |  | ns |
| $\mathrm{t}_{\text {HIGH }}$ | Clock high time | 600 |  | ns |
| t LOW | Clock low time | 1300 |  | ns |
| $\mathrm{t}_{\text {SU:STA }}$ | Start setup time | 600 |  | ns |
| $t_{\text {HD: STA }}$ | Start hold time | 600 |  | ns |
| $\mathrm{t}_{\text {SU:STO }}$ | Stop setup time | 600 |  | ns |
| $t_{\text {SU:DAT }}$ | SDA data input setup time | 100 |  | ns |
| $\mathrm{t}_{\mathrm{HD}: \mathrm{DAT}}{ }^{(4)}$ | SDA data input hold time | 0/30 |  | ns |
| $\mathrm{t}_{\mathrm{R}}$ | SCL and SDA rise time |  | 300 | ns |
| $\mathrm{t}_{\mathrm{F}}$ | SCL and SDA fall time |  | 300 | ns |
| $\mathrm{t}_{\mathrm{AA}}$ | SCL low to SDA data output valid time | 100 | 900 | ns |
| $t_{\text {DH }}$ | SDA data output hold time | 50 |  | ns |
| $\mathrm{T}_{1}$ | Noise suppression time constant at SCL and SDA inputs | 50 |  | ns |
| $\mathrm{t}_{\text {BUF }}$ | Bus free time (Prior to Any Transmission) | 1300 |  | ns |
| $t_{\text {SU:WPA }}$ | $\overline{\mathrm{WP}}, \mathrm{A} 0, \mathrm{~A} 1, \mathrm{~A} 2$ and A 3 setup time | 0 |  | ns |
| $\mathrm{t}_{\text {HD:WPA }}$ | $\overline{\mathrm{WP}}, \mathrm{A} 0, \mathrm{~A} 1, \mathrm{~A} 2$ and A 3 hold time | 0 |  | ns |

Note: (4) $\mathrm{V}_{\mathrm{CC}}=5 \mathrm{~V} / 2.7 \mathrm{~V}$

## HIGH-VOLTAGE WRITE CYCLE TIMING

| Symbol | Parameter | Typ. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{t}_{\mathrm{WR}}$ | High-voltage write cycle time (store instructions) | 5 | 10 | ms |

## DCP TIMING

| Symbol | Parameter | Min. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| $\mathrm{t}_{\text {WRL }}$ | Wiper response time after instruction issued (All load instructions) |  | 10 | $\mu \mathrm{~s}$ |

$\mathrm{V}_{\text {cc }}$ RAMP (sample tester)

| Symbol | Parameter | Typ. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: |
| trV ${ }_{C C}$ | $\mathrm{~V}_{\mathrm{CC}}$ Power-up rate | .2 | 50 | $\mathrm{~V} / \mathrm{ms}$ |

## BASIC APPLICATIONS

I to V Converter



$$
\begin{aligned}
& V_{O}=G V_{S} \\
& -1 / 2 \leq G \leq+1 / 2
\end{aligned}
$$

Absolute Value Amplifier with Gain


Phase Shifter

$\measuredangle \mathrm{V}_{\mathrm{O}} / \mathrm{V}_{\mathrm{S}}=180^{\circ}-2 \tan ^{-1} \mathrm{wRC}$


$$
\begin{aligned}
& \text { frequency } \propto R_{1}, R_{2}, C \\
& \text { amplitude } \propto R_{A}, R_{B}
\end{aligned}
$$

## PACKAGING INFORMATION

## 24-Lead Plastic Small Outline Gull Wing Package Type S



NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)

## PACKAGING INFORMATION

## 24-Lead Plastic, TSSOP Package Type V



NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)

## Ordering Information



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