

# H-Bridge Drivers for DC Brush Motors

# Single H-Bridge Driver High-Speed Switching Type

#### RD65496MUV

#### **General Description**

The BD65496MUV provides a single H-bridge motor driver which features wide range of motor power supply voltage from 1.8V to 16.0V and low power consumption to switch low ON-Resistance DMOS transistors at high speed. This small surface mounting package is most suitable for mobile system, home appliance and various applications.

#### **Features**

- Low ON-Resistance Power DMOS Output
- Charge Pump-Less with PDMOS High-Side Driver
- Selective Switching Speed: 4 Modes
- Drive Mode Switch Function
- Control Input Voltage Range Fit 1.8V Controller
- Under Voltage Locked Out Protection
   & Thermal Shut Down Function

#### **Applications**

- Mobile System
- Home Appliance
- Amusement System, etc

# **Key Specifications**

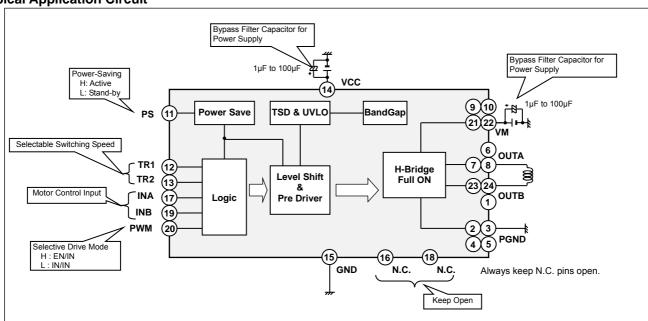
■ Power Supply Voltage Range: 2.5V to 5.5V ■ Motor Power Supply Voltage Range: 1.8V to 16.0V ■ Circuit Current (Open Mode): 0.80mA(Typ) ■ Stand-By Current: 1µA (Max) ■ Control Input Voltage Range: 0V to VccV ■ Logic Input Frequency: 500kHz(Max) ■ Minimum Logic Input Pulse Width: 0.2µs(Min) ■ Turn On Time (TR1=TR2=Low): 150ns(Typ) ■ Turn Off Time (TR1=TR2=Low): 50ns(Typ) ■ H-Bridge Output Current (DC): -1.2A to +1.2A ■ H-Bridge Output Current (Peak2): -5.0A to +5.0A ■ Output ON-Resistance (Total):  $0.35\Omega(Typ)$ ■ Operating Temperature Range: -30°C to +85°C

#### Package VQFN024V4040

**W(Typ) x D(Typ) x H(Max)** 4.00mm x 4.00mm x 1.00mm

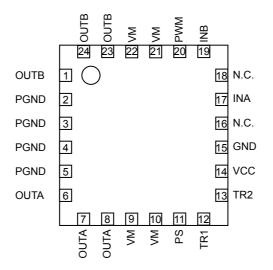


#### **Typical Application Circuit**



# **Pin Configuration**

(TOP VIEW)

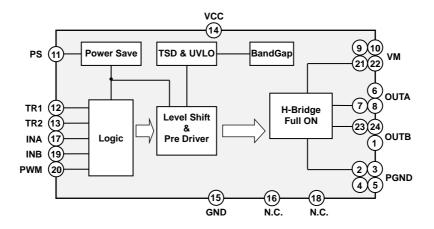


The pins of the same name, such as VM, PGND, OUTA and OUTB, must be shorted on printed circuit boards.

# **Pin Description**

II Descripti	Description							
Pin No.	Pin Name	Function	Pin No.	Pin Name	Function			
1	OUTB	H-bridge output B	13	TR2	Turn on & off time logic input 2			
2	PGND	Motor ground	14	VCC	Power supply			
3	PGND	Motor ground	15	GND	Ground			
4	PGND	Motor ground	16	N.C.	-			
5	PGND	Motor ground	17	INA	Control logic input A			
6	OUTA	H-bridge output A	18	N.C.	-			
7	OUTA	H-bridge output A	19	INB	Control logic input B			
8	OUTA	H-bridge output A	20	PWM	Drive mode logic input			
9	VM	Motor power supply	21	VM	Motor power supply			
10	VM	Motor power supply	22	VM	Motor power supply			
11	PS	Power-saving function	23	OUTB	H-bridge output B			
12	TR1	Turn on & off time logic input 1	24	OUTB	H-bridge output B			

# **Block Diagram**



#### **Description of Blocks**

1. Power-Saving Function

A power-saving function is included, which allows the system to save power when not driving the motor. The voltage level on this pin should be set high so as to keep the operation mode. (See the Electrical Characteristics; p.4/14)

- 2. Motor Control Input
  - (a) INA and INB Pins

Logic level controls the output logic of H-Bridge. (See the Electrical Characteristics; p.4/14, and I/O Truth Table; p.7/14)

(b) PWM Pin

Logic level sets the IN/IN or EN/IN drive mode. (See the Electrical Characteristics; p.4/14 and I/O Truth Table; p.7/14)

(c) TR1 and TR2 Pins

Logic level sets the switching speed of H-Bridge transistors, turn on time and turn off time. (See the Electrical Characteristics; p.4/14 and I/O Truth Table; p.7/14)

Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Limit	Unit
Power Supply Voltage	V <sub>CC</sub>	-0.3 to +7.0	V
Motor Power Supply Voltage	V <sub>M</sub>	-0.3 to +20.0	V
Control Input Voltage	VIN	-0.3 to +V <sub>CC</sub> +0.3	V
		0.70 (Note 1)	
Power Dissipation	Pd	2.20 (Note 2)	W
		3.56 (Note 3)	-
H-bridge Output Current (DC)	Іоит	-1.2 to +1.2 (Note 4)	Α
H-bridge Output Current (Peak1(Note 5))	I <sub>OUTP1</sub>	-3.2 to +3.2 (Note 4)	Α
H-bridge Output Current (Peak2(Note 5))	loutp2	-5.0 to +5.0 (Note 4)	Α
Storage Temperature Range	Tstg	-55 to +150	°C
Junction Temperature	Tjmax	+150	°C

<sup>(</sup>Note 1) Reduced by 5.6mW/°C over 25°C, when mounted on a glass epoxy 1-layer board (74.2mm x 74.2mm x 1.6mm)
In surface layer copper foil area: 10.29mm²

(Note 4) Must not exceed Pd, ASO, or Tjmax of 150°C

(Note 5) Peak1=100ms (Duty $\leq$ 20%), Peak2=10ms (Duty $\leq$ 5%)

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

**Recommended Operating Conditions** 

minorate operating contained							
Parameter	Symbol	Min	Тур	Max	Unit		
Power Supply Voltage	Vcc	2.5	-	5.5	V		
Motor Power Supply Voltage	V <sub>M</sub>	1.8	-	16.0	V		
Control Input Voltage	V <sub>IN</sub>	0	-	Vcc	V		
Logic Input Frequency	F <sub>IN</sub>	0	-	500	kHz		
Minimum Logic Input Pulse Width <sup>(Note 6)</sup>	T <sub>IN</sub>	0.2	-	-	μs		
Operating Temperature Range	Topr	-30	-	+85	°C		

(Note 6) TR1=TR2=Low

<sup>(</sup>Note 2) Reduced by 17.6mW/°C over 25°C, when mounted on a glass epoxy 4-layer board (74.2mm x 74.2mm x 1.6mm) In surface & back layers copper foil area: 10.29mm², 2&3 layers copper foil area: 5505mm²

<sup>(</sup>Note 3) Reduced by 28.4mW/°C over 25°C, when mounted on a glass epoxy 4-layer board (74.2mm x 74.2mm x 1.6mm) In all 4-layers copper foil area: 5505mm²

Electrical Characteristics (Unless otherwise specified V<sub>CC</sub>=3.0V, V<sub>M</sub>=5.0V, Ta=25°C)

cirical Characteristics (On	trical Characteristics (Unless otherwise specified Vcc=3.0V, VM=5.0V, Ta=25°C)						
Parameter	Symbol	Min	Тур	Max	Unit	Conditions	
All Circuits							
Stand-by Current	Іссят	-	0	1	μΑ	V <sub>PS</sub> =0V	
Circuit Current 1	Icc1	0.50	0.80	1.25	mA	V <sub>PS</sub> =3V, Open Mode	
Circuit Current 2	Icc2	0.50	0.85	1.30	mA	V <sub>PS</sub> =3V, CW & CCW Mode	
Circuit Current 3	I <sub>CC3</sub>	0.50	0.85	1.30	mA	V <sub>PS</sub> =3V, Short Brake Mode	
PS Input (PS)							
High-Level Input Voltage	V <sub>PSH</sub>	1.45	-	Vcc	V		
Low-Level Input Voltage	V <sub>PSL</sub>	0	-	0.5	V		
High-Level Input Current	IPSH	15	30	60	μA	V <sub>PS</sub> =3V	
Low-Level Input Current	I <sub>PSL</sub>	-1	0	+1	μΑ	V <sub>PS</sub> =0V	
Control Input (IN=INA, INB, P	WM, TR1,	ΓR2)					
High-Level Input Voltage	$V_{INH}$	1.45	-	Vcc	V		
Low-Level Input Voltage	VINL	0	-	0.5	V		
High-Level Input Current	Inh	15	30	60	μΑ	V <sub>IN</sub> =3V	
Low-Level Input Current	I <sub>INL</sub>	-1	0	+1	μΑ	V <sub>IN</sub> =0V	
Under Voltage Locked Out (U	VLO)						
UVLO Voltage	V <sub>UVLO</sub>	2.0	-	2.4	V		
Full ON Type H-Bridge Driver							
Output On-Resistance	Ron	-	0.35	0.50	Ω	I <sub>OUT</sub> =±500mA, High & Low-side total	
Turn On Time 0	T <sub>ON0</sub>	-	150	300	ns	20Ω Loading, TR1=Low, TR2=Low	
Turn Off Time 0	T <sub>OFF0</sub>	-	50	200	ns	20Ω Loading, TR1=Low, TR2=Low	
Turn On Time 1	T <sub>ON1</sub>	-	250	500	ns	20Ω Loading, TR1=High, TR2=Low	
Turn Off Time 1	T <sub>OFF1</sub>	-	70	200	ns	20Ω Loading, TR1=High, TR2=Low	
Turn On Time 2	T <sub>ON2</sub>	-	350	800	ns	20Ω Loading, TR1=Low, TR2=High	
Turn Off Time 2	T <sub>OFF2</sub>	-	90	250	ns	20Ω Loading, TR1=Low, TR2=High	
Turn On Time 3	T <sub>ON3</sub>	-	500	1000	ns	20Ω Loading, TR1=High, TR2=High	
Turn Off Time 3	T <sub>OFF3</sub>	-	110	250	ns	20Ω Loading, TR1=High, TR2=High	

# **Typical Performance Curves (Reference Data)**

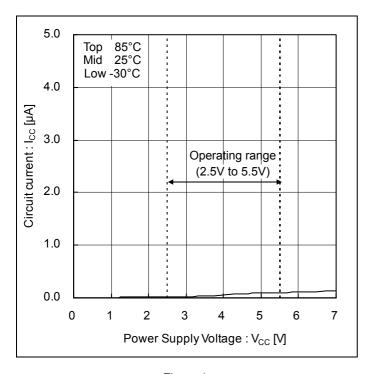


Figure 1.
Circuit Current vs Power Supply Voltage (Stand-by Mode)

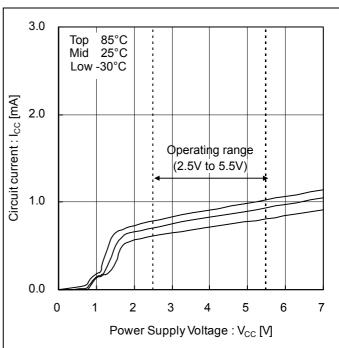
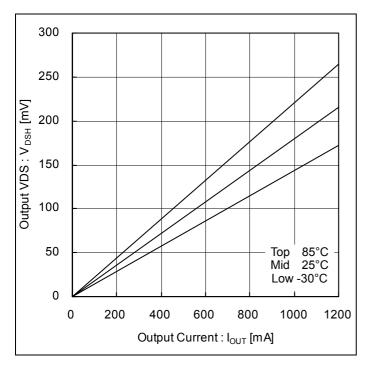


Figure 2.
Circuit Current vs Power Supply Voltage
(Open Mode)



 $\label{eq:figure 3.} Figure 3. \\ Output VDS vs Output Current \\ (Output On-Resistance on high-side, V_M=5V, V_{CC}=3V)$ 

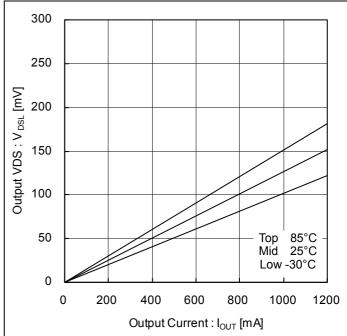
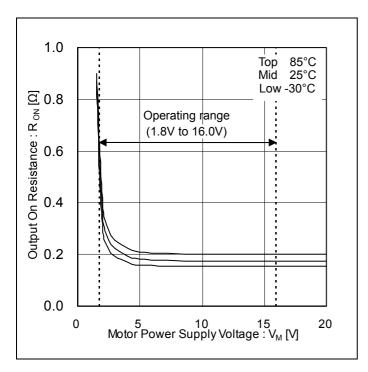


Figure 4.
Output VDS vs Output Current
(Output On-Resistance on low-side, V<sub>M</sub>=5V, V<sub>CC</sub>=3V)

# Typical Performance Curves (Reference Data) - continued



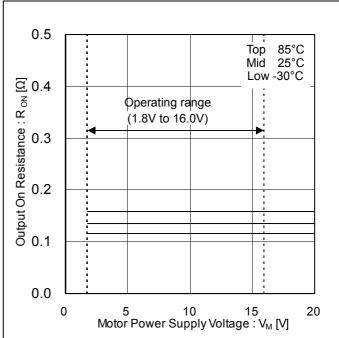


Figure 5.
Output On-Resistance vs Motor Power Supply Voltage
(Output On-Resistance on high-side V<sub>M</sub> Dependency, V<sub>CC</sub>=3V)

Figure 6. Output On-Resistance vs Motor Power Supply Voltage (Output On-Resistance on low-side  $V_M$  Dependency,  $V_{CC}$ =3V)

# **Timing Chart**

Table 1. I/O Truth Table

Innut Mada	INPUT			OUTPUT			
Input Mode	PS <sup>(Note 7)</sup>	PWM	INA	INB	OUTA	OUTB	Output Mode <sup>(Note 8)</sup>
			L	Х	L	L	Short Brake
EN/IN		Н	Н	L	Н	L	CW
			Н	Н	L	Н	CCW
IN/IN	H		L	L	Z	Z	Open
		Н	L	Н	L	CW	
		L	L	Н	L	Н	CCW
			Н	Н	L	L	Short Brake
-	L	Х	Х	Х	Z	Z	Open

L: Low, H: High, X: Don't care, Z: High-Impedance

(Note 7)PS=High: Operation Mode, PS=Low: Stand-by Mode

(Note 8)CW: Current flows from OUTA to OUTB, CCW: Current flows from OUTB to OUTA

Table 2. Switching Speed Control Table

TR1	TR2	Turn ON Time [ns]	Turn Off Time [ns]
L	L	150	50
Н	L	250	70
L	Н	350	90
Н	Н	500	110

L: Low, H: High

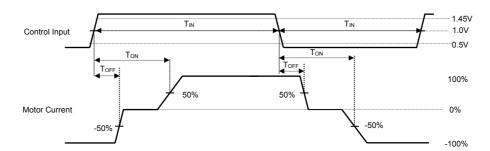
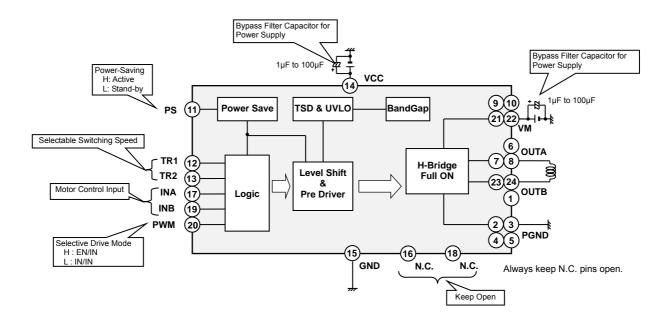


Figure 7.
Input-Output AC Characteristic

# **Application Example**



#### **Selection of Components Externally Connected**

When using the circuit with changes to the external circuit constants, make sure to leave an adequate margin for external components including static and transitional characteristics as well as dispersion of the IC.

# **Power Dissipation**

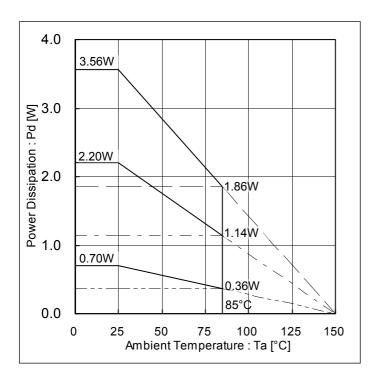
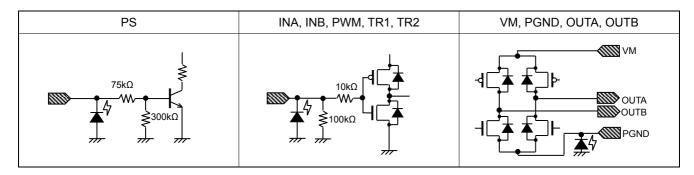


Figure 8. Power Dissipation vs Ambient Temperature

# I/O Equivalence Circuits



#### **Operational Notes**

#### 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

#### 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

#### 3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

#### 4. Ground Wiring Pattern

When using both small-signal(GND) and large-current ground(PGND) traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

#### 5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

#### 6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

#### 7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

#### 8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

#### 9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

## 10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

# 11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

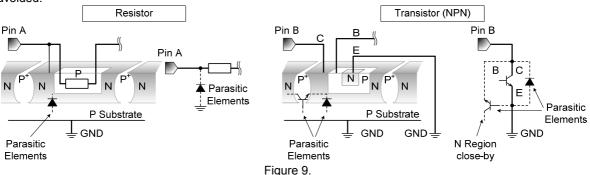
# **Operational Notes - continued**

#### 12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.



Example of monolithic IC structure

#### 13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

#### 14. Area of Safe Operation (ASO)

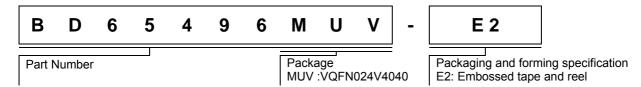
Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

#### 15. Thermal Shutdown Circuit(TSD)

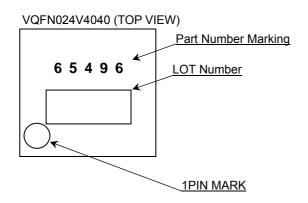
This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

# **Ordering Information**



# **Marking Diagram**



Part Number Marking	Package	Orderable Part Number	
65496	VQFN024V4040	BD65496MUV-E2	

Physical Dimension, Tape and Reel Information Package Name VQFN024V4040 4.  $0\pm0.1$  $0\pm0$ 1PIN MARK 0 MAX  $0.02^{+0.03}_{-0.02}$ △ 0. 08 S 0)  $2.4\pm0.1$ C0. 2 24  $4\pm0$ .  $4\pm 0.1$ 0 19 13 (U I NT: mm) 0.75 PKG: VQFN024V4040  $0.25_{\,-0.04}^{\,+0.05}$ 0. 5 Drawing No. EX463-5001-2 <Tape and Reel information> Tape Embossed carrier tape Quantity 2500pcs Direction ( The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand of feed 0 Direction of feed 1pin

\*Order quantity needs to be multiple of the minimum quantity.

# **Revision History**

Date	Revision	Changes
11.May.2013	001	New release
10.Feb.2016	002	Applied the ROHM Standard Style and improved understandability.

# **Notice**

#### **Precaution on using ROHM Products**

1. Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA	
CLASSⅢ	CLACCIII	CLASS II b	CL A CC TT	
CLASSIV	CLASSII	CLASSⅢ	CLASSⅢ	

- 2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
  - [a] Installation of protection circuits or other protective devices to improve system safety
  - [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure
- 3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
  - [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
  - [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
  - [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl<sub>2</sub>, H<sub>2</sub>S, NH<sub>3</sub>, SO<sub>2</sub>, and NO<sub>2</sub>
  - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

#### **Precaution for Mounting / Circuit board design**

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

#### **Precautions Regarding Application Examples and External Circuits**

- 1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
- 2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

#### **Precaution for Electrostatic**

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of lonizer, friction prevention and temperature / humidity control).

### **Precaution for Storage / Transportation**

- 1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
  - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
  - [b] the temperature or humidity exceeds those recommended by ROHM
  - [c] the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- Even under ROHM recommended storage condition, solderability of products out of recommended storage time period
  may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is
  exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

#### **Precaution for Product Label**

A two-dimensional barcode printed on ROHM Products label is for ROHM's internal use only.

#### **Precaution for Disposition**

When disposing Products please dispose them properly using an authorized industry waste company.

#### **Precaution for Foreign Exchange and Foreign Trade act**

Since concerned goods might be fallen under listed items of export control prescribed by Foreign exchange and Foreign trade act, please consult with ROHM in case of export.

#### **Precaution Regarding Intellectual Property Rights**

- 1. All information and data including but not limited to application example contained in this document is for reference only. ROHM does not warrant that foregoing information or data will not infringe any intellectual property rights or any other rights of any third party regarding such information or data.
- 2. ROHM shall not have any obligations where the claims, actions or demands arising from the combination of the Products with other articles such as components, circuits, systems or external equipment (including software).
- 3. No license, expressly or implied, is granted hereby under any intellectual property rights or other rights of ROHM or any third parties with respect to the Products or the information contained in this document. Provided, however, that ROHM will not assert its intellectual property rights or other rights against you or your customers to the extent necessary to manufacture or sell products containing the Products, subject to the terms and conditions herein.

#### **Other Precaution**

- 1. This document may not be reprinted or reproduced, in whole or in part, without prior written consent of ROHM.
- 2. The Products may not be disassembled, converted, modified, reproduced or otherwise changed without prior written consent of ROHM.
- In no event shall you use in any way whatsoever the Products and the related technical information contained in the Products or this document for any military purposes, including but not limited to, the development of mass-destruction weapons.
- 4. The proper names of companies or products described in this document are trademarks or registered trademarks of ROHM, its affiliated companies or third parties.

Notice-PGA-E Rev.003

#### **General Precaution**

- 1. Before you use our Products, you are requested to care fully read this document and fully understand its contents. ROHM shall not be in any way responsible or liable for failure, malfunction or accident arising from the use of a ny ROHM's Products against warning, caution or note contained in this document.
- 2. All information contained in this docume nt is current as of the issuing date and subj ect to change without any prior notice. Before purchasing or using ROHM's Products, please confirm the latest information with a ROHM sale s representative.
- 3. The information contained in this doc ument is provided on an "as is" basis and ROHM does not warrant that all information contained in this document is accurate an d/or error-free. ROHM shall not be in an y way responsible or liable for any damages, expenses or losses incurred by you or third parties resulting from inaccuracy or errors of or concerning such information.

Rev.001

# **X-ON Electronics**

Largest Supplier of Electrical and Electronic Components

Click to view similar products for Motor/Motion/Ignition Controllers & Drivers category:

Click to view products by ROHM manufacturer:

Other Similar products are found below:

FSB50550TB2 FSBF15CH60BTH MSVCPM2-63-12 MSVGW45-14-2 MSVGW54-14-3 MSVGW54-14-5 NTE7043 LA6565VR-TLM-E LB11650-E LB1837M-TLM-E LB1845DAZ-XE LC898300XA-MH SS30-TE-L-E 26700 LV8281VR-TLM-H BA5839FP-E2 IRAM236-1067A LA6584JA-AH LB11847L-E AH293-PL-B TND315S-TL-2H FNA23060 FSB50250AB FNA41060 MSVB54 MSVBTC50E MSVCPM3-54-12 MSVCPM3-63-12 MSVCPM4-63-12 MSVTA120 FSB50550AB NCV70501DW002G LC898301XA-MH LV8413GP-TE-L-E MSVGW45-14-3 MSVGW45-14-4 MSVGW45-14-5 MSVGW54-14-4 STK984-091A-E SLA7026M MP6519GQ-Z LB11651-E IRSM515-025DA4 LV8127T-TLM-H MC33812EKR2 NCP81382MNTXG TDA21801 LB11851FA-BH NCV70627DQ001R2G LB1938FAGEVB