

RoHS

DC Brushless Fan Motor Drivers Multifunction Single-phase Full-wave Fan Motor Driver



General description

BD6975FV is a 1chip driver that composes H-bridge of power DMOS FET. Moreover, it corresponds to the large current motor, compared with old drivers, because the regenerative method of motor current and the driving block are optimized.

Features

- SSOP small package
- Driver including power DMOS FET
- Speed controllable by DC / direct PWM input
- Hi-Eff switching
- Quick start
- Current limit
- Lock protection and automatic restart
- Rotation speed pulse signal (FG) output

Application

Fan motors for general consumer equipment of desktop PC, and Projector, etc.

Absolute maximum ratings

Parameter	Symbol	Limit	Unit
Supply voltage	Vcc	20	V
Power dissipation	Pd	874.7 ^{*1}	mW
Operating temperature range	Topr	-40 to +100	°C
Storage temperature range	Tstg	-55 to +150	°C
Output voltage	Vo	20	V
Output current	lo	1.2 ^{*2}	Α
Rotation speed pulse signal (FG) output voltage	Vfg	20	V
Rotation speed pulse signal (FG) output current	lfg	10	mA
Reference voltage (REF) output current	Iref	5	mA
Hall bias (HB) output current 1	lhb1	12 ^{*3}	mA
Hall bias (HB) output current 2	lhb2	5 ^{*4}	mA
Input voltage (H+, H–, TH, MIN, CS, LZST)	Vin	7	V
Junction temperature	Tj	150	°C

*1 Reduce by 7.0mW/°C over Ta=25°C. (On 70.0mm×70.0mm×1.6mm glass epoxy board)

*2 This value is not to exceed Pd.

The condition of Ta=0°C or more and Vcc=9V or more *3

*4 The condition of less than Ta=0°C and less than Vcc=9V

Recommended operating conditions

Parameter	Symbol	Limit	Unit
Operating supply voltage range	Vcc	3.5 to 17.0	V
Operating input voltage range 1 (H+, H–) (more than Vcc=9V)	ating input voltage range 1 (H+, H–)		V
Operating input voltage range 1 (H+, H–) (less than Vcc=9V)	Vin1	0 to Vcc-2	V
Operating input voltage range 2 (TH, MIN, CS, LZST)	Vin2	0 to Vref	V

OProduct structure : Silicon monolithic integrated circuit OThis product is not designed protection against radioactive rays



SSOP-B14

Package SSOP-B14 W (Typ.) x D (Typ.) x H (Max.) 5.00mm x 6.40mm x 1.35mm

Pin configuration



Pir	Pin description					
	P/No.	T/Name	Function			
	1	FG	Speed pulse signal output terminal			
	2	H–	Hall – input terminal			
	3	HB	Hall bias terminal			
	4	H+	Hall + input terminal			
	5	CS	Output current detection terminal			
	6	OUT2	Motor output terminal 2			
	7	RNF	Output current detecting resistor			
	1		connecting terminal (motor ground)			
	8	OUT1	Motor output terminal 1			
	9	Vcc	Power supply terminal			
	10	REF	Reference voltage output terminal			
	11	TH	Output duty controllable input terminal			
	12	MIN	Minimum output duty setting terminal			
	13	LZST	Regenerative period setting terminal			
	14	GND	Ground terminal (signal ground)			

Block diagram



●I/O truth table

	-					
Hall	input	Driver output				
H+	H–	OUT1	OUT2	FG		
Н	L	L	Н	Hi-Z		
L	Н	Н	L	L		
H: High I: Low Hi-7: High impedance						

H; High, L; Low, Hi-Z; High impedance FG output is open-drain type.

●Electrical characteristics(Unless otherwise specified Ta=25°C, Vcc=12V)

Deservator	O maked	Limit		1.1	Osastitisms	Ref.	
Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions	data
Circuit current	lcc	1.5	3.3	5.0	mA		Fig.3
Hall input offset voltage	Vofs	-	-	±6	mV		Fig.4
Output voltage	Vo	-	0.4	0.6	V	lo=±400mA High and low side total	Fig.5 to 8
Lock detection ON time	Ton	0.3	0.5	0.7	s		Fig.9
Lock detection OFF time	Toff	3.0	5.0	7.0	s		Fig.10
Lock detection OFF/ON ratio	Rick	8.5	10.0	11.5	-	RIck=Toff / Ton	Fig.11
FG output low voltage	Vfgl	-	0.15	0.30	V	lfg=5mA	Fig.12, 13
FG output leak current	lfgl	-	-	10	μA	Vfg=17V	Fig.14
OSC frequency	Fosc	20.0	33.3	46.7	kHz		Fig.15
OSC high voltage	Vosch	2.3	2.5	2.7	V		Fig.16
OSC low voltage	Voscl	0.8	1.0	1.2	V		Fig.16
Output ON duty 1	Poh1	75	80	85	%	Vth=Vref x 0.217 Output 1kΩ load	Fig.17
Output ON duty 2	Poh2	45	50	55	%	Vth=Vref x 0.292 Output 1kΩ load	Fig.17
Output ON duty 3	Poh3	15	20	25	%	Vth=Vref x 0.367 Output 1kΩ load	Fig.17
Reference voltage	Vref	5.7	6.0	6.3	V	Iref=-2mA	Fig.18, 19
Hall bias voltage	Vhb	1.05	1.25	1.45	V	Ihb=-2mA	Fig.20, 21
Current limit setting voltage	Vcl	235	265	295	mV		Fig.22
TH input bias current	lth	-	-	-0.2	μA	Vth=0V	Fig.23
MIN input bias current	Imin	-	-	-0.2	μA	Vmin=0V	Fig.24
CS input bias current	lcs	-	-	-0.2	μA	Vcs=0V	Fig.25
LZST input bias current	llzst	-	-	-1.0	μA	VIzst=0V	Fig.26

About a current item, define the inflow current to IC as a positive notation, and the outflow current from IC as a negative notation.









Fig.10 Lock detection OFF time





Fig.13 FG output low voltage (Ta=25°C)

Fig.14 FG output leak current

Supply voltage: Vcc[V]











Fig.22 Current limit setting voltage





Application circuit example(Constant values are for reference)



Fig.27 Application of converting PWM duty to DC voltage

Substrate design note

- a) IC power, motor outputs, and motor ground lines are made as fat as possible.
- b) IC ground (signal ground) line is common with the application ground except motor ground (i.e. hall ground etc.), and arranged near to (–) land.
- c) The bypass capacitor and/or Zenner diode are arrangement near to Vcc terminal.
- d) H+ and H– lines are arranged side by side and made from the hall element to IC as shorter as possible, because it is easy for the noise to influence the hall lines.

Power dissipation

Power dissipation (total loss) indicates the power that can be consumed by IC at Ta=25°C (normal temperature). IC is heated when it consumes power, and the temperature of IC chip becomes higher than ambient temperature. The temperature that can be accepted by IC chip depends on circuit configuration, manufacturing process, etc, and consumable power is limited. Power dissipation is determined by the temperature allowed in IC chip (maximum junction temperature) and thermal resistance of package (heat dissipation capability). The maximum junction temperature is in general equal to the maximum value in the storage temperature range.

Heat generated by consumed power of IC is radiated from the mold resin or lead frame of package. The parameter which indicates this heat dissipation capability (hardness of heat release) is called heat resistance, represented by the symbol θ ja[°C/W]. This heat resistance can estimate the temperature of IC inside the package. Fig.28 shows the model of heat resistance of the package. Heat resistance θ ja, ambient temperature Ta, junction temperature Tj, and power consumption P can be calculated by the equation below:

 $\theta ja = (Tj - Ta) / P [^{\circ}C/W]$

Thermal de-rating curve indicates power that can be consumed by IC with reference to ambient temperature. Power that can be consumed by IC begins to attenuate at certain ambient temperature. This gradient is determined by thermal resistance θ_{ja} . Thermal resistance θ_{ja} depends on chip size, power consumption, package ambient temperature, packaging condition, wind velocity, etc., even when the same package is used. Thermal de-rating curve indicates a reference value measured at a specified condition. Fig.29 shows a thermal de-rating curve (Value when mounting FR4 glass epoxy board 70[mm] x 70[mm] x 1.6[mm] (copper foil area below 3[%])). Thermal resistance θ_{jc} from IC chip joint part to the package surface part of mounting the above-mentioned same substrate is shown in the following as a reference value.



Operational Notes

1) Absolute maximum ratings

An excess in the absolute maximum ratings, such as supply voltage, temperature range of operating conditions, etc., can break down the devices, thus making impossible to identify breaking mode, such as a short circuit or an open circuit. If any over rated values will expect to exceed the absolute maximum ratings, consider adding circuit protection devices, such as fuses.

2) Connecting the power supply connector backward

Connecting of the power supply in reverse polarity can damage IC. Take precautions when connecting the power supply lines. An external direction diode can be added.

3) Power supply line

Back electromotive force causes regenerated current to power supply line, therefore take a measure such as placing a capacitor between power supply and GND for routing regenerated current. And fully ensure that the capacitor characteristics have no problem before determine a capacitor value. (When applying electrolytic capacitors, capacitance characteristic values are reduced at low temperatures)

4) GND potential

It is possible that the motor output terminal may deflect below GND terminal because of influence by back electromotive force of motor. The potential of GND terminal must be minimum potential in all operating conditions, except that the levels of the motor outputs terminals are under GND level by the back electromotive force of the motor coil. Also ensure that all terminals except GND and motor output terminals do not fall below GND voltage including transient characteristics. Malfunction may possibly occur depending on use condition, environment, and property of individual motor. Please make fully confirmation that no problem is found on operation of IC.

5) Thermal design

Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions.

6) Inter-pin shorts and mounting errors

Use caution when positioning the IC for mounting on printed circuit boards. The IC may be damaged if there is any connection error or if pins are shorted together.

7) Actions in strong electromagnetic field

Use caution when using the IC in the presence of a strong electromagnetic field as doing so may cause the IC to malfunction.

8) ASO

When using the IC, set the output transistor so that it does not exceed absolute maximum rations or ASO.

9) Thermal shut down circuit

The IC incorporates a built-in thermal shutdown circuit (TSD circuit). Operation temperature is 175°C (typ.) and has a hysteresis width of 25°C (typ.). When IC chip temperature rises and TSD circuit works, the output terminal becomes an open state. TSD circuit is designed only to shut the IC off to prevent thermal runaway. It is not designed to protect the IC or guarantee its operation. Do not continue to use the IC after operation this circuit or use the IC in an environment where the operation of this circuit is assumed.

10) Testing on application boards

When testing the IC on an application board, connecting a capacitor to a pin with low impedance subjects the IC to stress. Always discharge capacitors after each process or step. Always turn the IC's power supply off before connecting it to or removing it from a jig or fixture during the inspection process. Ground the IC during assembly steps as an antistatic measure. Use similar precaution when transporting or storing the IC.

11) GND wiring pattern

When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the ground potential of application so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.

12) Capacitor between output and GND

When a large capacitor is connected between output and GND, if Vcc is shorted with 0V or GND for some cause, it is possible that the current charged in the capacitor may flow into the output resulting in destruction. Keep the capacitor between output and GND below 100μ F.

13) IC terminal input

When Vcc voltage is not applied to IC, do not apply voltage to each input terminal. When voltage above Vcc or below GND is applied to the input terminal, parasitic element is actuated due to the structure of IC. Operation of parasitic element causes mutual interference between circuits, resulting in malfunction as well as destruction in the last. Do not use in a manner where parasitic element is actuated.

14) In use

We are sure that the example of application circuit is preferable, but please check the character further more in application to a part that requires high precision. In using the unit with external circuit constant changed, consider the variation of externally equipped parts and our IC including not only static character but also transient character and allow sufficient margin in determining.

Status of this document

The Japanese version of this document is formal specification. A customer may use this translation version only for a reference to help reading the formal version.

If there are any differences in translation version of this document, formal version takes priority.

Physical dimension tape and reel information



Marking diagram



Revision history

Date	Revision	Comments
07.JUL.2012	001	New Release
28.JUL.2012	002	Color appearance change (There is no change in the content.)

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For details, please refer to ROHM Mounting specification

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