Dear customer

LAPIS Semiconductor Co., Ltd. ("LAPIS Semiconductor"), on the 1st day of October, 2020, implemented the incorporation-type company split (shinsetsu-bunkatsu) in which LAPIS established a new company, LAPIS Technology Co., Ltd. ("LAPIS Technology") and LAPIS Technology succeeded LAPIS Semiconductor's LSI business.

Therefore, all references to "LAPIS Semiconductor Co., Ltd.", "LAPIS Semiconductor" and/or "LAPIS" in this document shall be replaced with "LAPIS Technology Co., Ltd."

Furthermore, there are no changes to the documents relating to our products other than the company name, the company trademark, logo, etc.

Thank you for your understanding.

LAPIS Technology Co., Ltd.
October 1, 2020





Issue Date: Jan 08, 2016

MR45V064B

64k(8,192-Word × 8-Bit) FeRAM (Ferroelectric Random Access Memory) SPI

GENERAL DESCRIPTION

The MR45V064B is a nonvolatile 8,192-word x 8-bit ferroelectric random access memory (FeRAM) developed in the ferroelectric process and silicon-gate CMOS technology. The MR45V064B is accessed using Serial Peripheral Interface. Unlike SRAMs, this device, whose cells are nonvolatile, eliminates battery backup required to hold data. This device has no mechanisms of erasing and programming memory cells and blocks, such as those used for various EEPROMs. Therefore, the write cycle time can be equal to the read cycle time and the power consumption during a write can be reduced significantly.

The MR45V064B can be used in various applications, because the device is guaranteed for the write/read tolerance of 10^{12} cycles per bit and the rewrite count can be extended significantly.

FEATURES

• 8,192-word × 8-bit configuration (Serial Peripheral Interface : SPI)

• A single 1.8V to 3.6V (3.3 V typ) power supply

Operating frequency: 40MHz
 Read/write tolerance 10¹² cycles/bit
 Data retention 10 years

• Guaranteed operating temperature range —40 to 85°C (Extended temperature version)

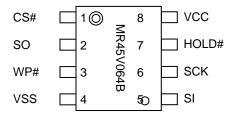
• Package options:

8-pin plastic SOP (P-SOP8-200-1.27-T2K)



PIN CONFIGURATION

8-pin plastic SOP



Note:

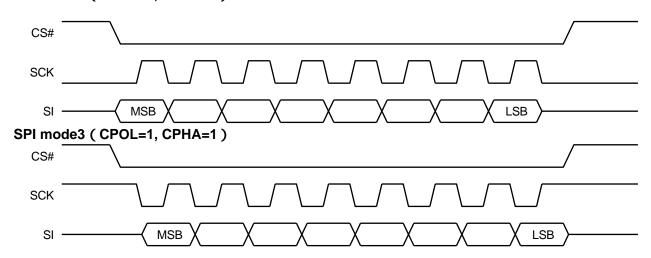
Signal names that end with # indicate that the signals are negative-true logic.

PIN DESCRIPTIONS

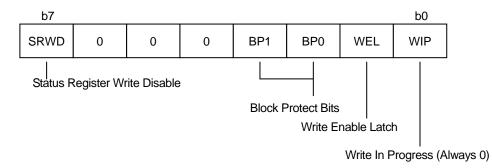
Pin Name	Description				
CS#	Chip Select (input, negative logic) Latches an address by low input, activates the FeRAM, and enables a read or write operation.				
WP#	Write Protect(input , negative logic) Write Protect pin controls write-operation to the status-register(BP0,BP1). This pin should be fixed low or high in write-operations.				
HOLD#	HOLD(input , negative logic) Hold pin is used when the serial-communication suspended without disable the chip select. When HOLD# is low ,the serial-output is in High-Z status and serial-input/serial-clock are "Don' t Care" . CS# should be low in hold operation.				
SCK	Serial Clock Serial Clock is the clock input pin for setting for serial data timing. Inputs are latched on the rising edge and output occur on the falling edge.				
SI	Serial input SI pins are serial input pins for Operation-code , addresses ,and data-inputs .				
so	Serial output SO pins are serial output pins.				
V _{CC} , V _{SS}	Power supply $ \text{Apply the specified voltage to } V_{\text{CC}}. \text{ Connect } V_{\text{SS}} \text{ to ground}. $				

SPIMODE

SPI mode0 (CPOL=0, CPHA=0)



STATUS REGISTER



Name	Function
WIP	Fixed to 0.
WEL	Write Enable Latch. This indicates internal WEL condition.
BP0,BP1	Block Protect: These bits can be changed protect area.
	This is the software protect.
SRWD	Status Register Write Disable (SRWD): SRWD controls the effect of the hardware WP# pin. This device will be in hardware-protect by combination of SRWD and WP#.
0	Fixed to 0.

OPERATION-CODE

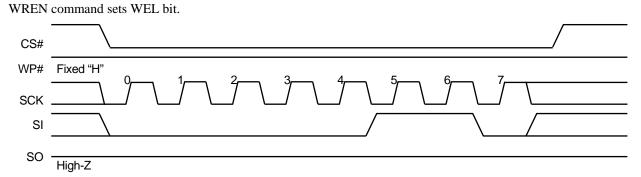
Operation codes are listed in the table below. If the device receives invalid operation code, the device will be diselected.

Instruction	Description	Instruction format
WREN	Write Enable	0000 0110
WRDI	Write Disable	0000 0100
RDSR	Read Status Register	0000 0101
WRSR	Write Status Register	0000 0001
READ	Read from Memory Array	0000 0011
WRITE	Write to Memory Array	0000 0010
FSTRD	Fast Read from Memory Array	0000 1011
RDID	Read device ID	1001 1111

COMMANDS

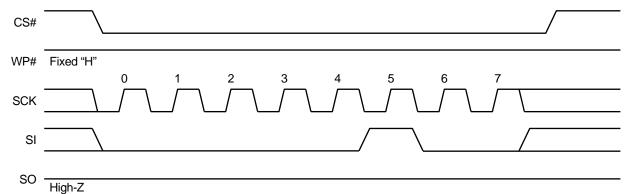
WREN (Write Enable)

It is necessary to set Write Enable Latch (WEL) bit before write-operation (WRITE and WRSR).



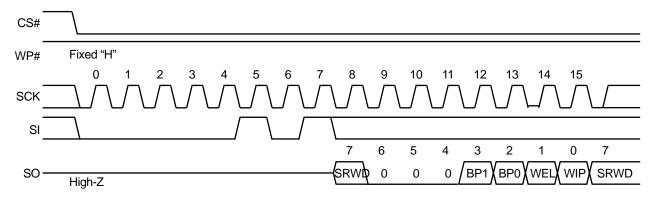
WRDI (Write Disable)

WRDI command resets WEL bit.



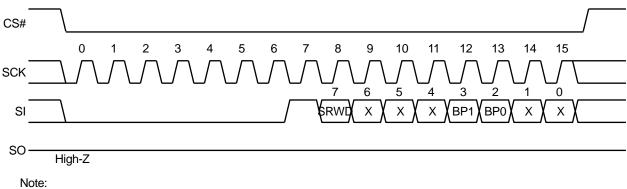
RDSR (READ Status Register)

The RDSR command allows to read data of status register.



WRSR (WRITE Status Register)

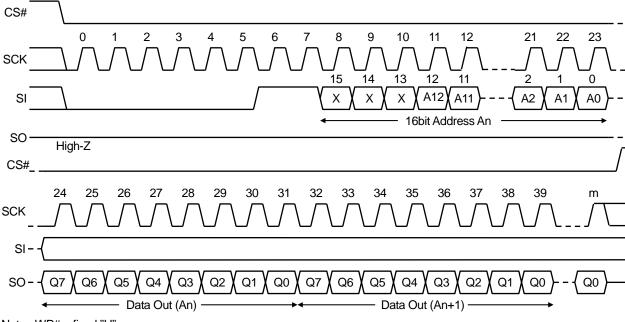
WRSR command allows to write data to status register(SRWD,BP0,BP1). It is necessary to set Write Enable Latch (WEL) bit by WREN command before executing WRSR.



WP#=Fix "H"

READ (Read from Memory Array)

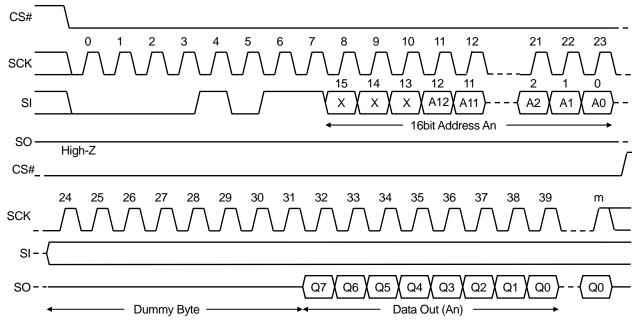
READ command can be valid when CS# goes "L", then the op-code and 16bit-adresses are inputted to serial input"SI". The inputted adresses are loaded to internal register, then the data from corresponded address is output at serial-output "SO". If CS# will keep "L", the internal adress will be incressed automatically after 8 clocks and will output the data from new-address. When it reaches the most significant adress, the adress counter rolls over tostarting adress, and reading cycle can be continued infinitely.



Note: WP# = fixed "H"

FSTRD (Fast Read from Memory Array)

FSTRD command can be valid when CS# goes "L", then the op-code and 16bit-adresses are inputted to serial input "SI". After 8bits for dummy byte, the data from corresponded address is output at serial-output "SO".

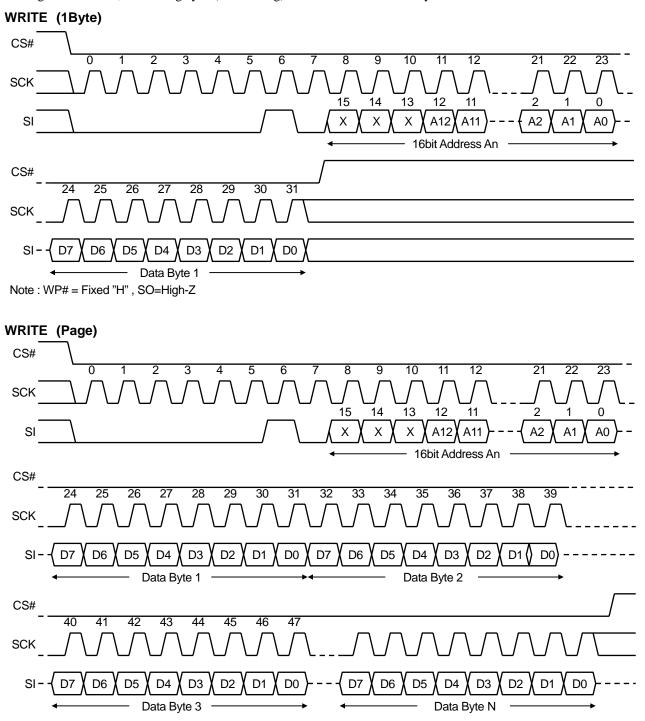


Note: WP# = fixed "H"

WRITE (Write to Memory Array)

Note: WP# = Fixed "H", SO=High-Z

Write command can be valid when CS# goes "L",then the op-code and 16bit-adresses are inputted to serial input"SI". Writing is terminated when CS# goes high after data-input. If CS# will keep "L",the internal adress will be incressed automatically. When it reaches the most significant adress, the adress counter rolls over to starting adress 0000h, and writing cycle(overwriting) can be continued infinitely.



WRITE PROTECTION

Writing protection block is shown as follows:

Protect Block size

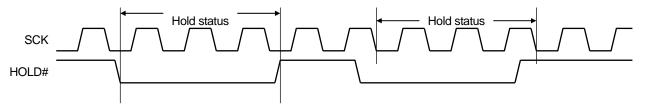
Block Protect BIT		Drotootod Plank	Dratastad Address Area	
BP1		BP0	Protected Block Protected Address Area	
0	0		None	None
0	1		Upper 1/4 block	1800h – 1FFFh
1	0		Upper 1/2 block	1000h – 1FFFh
1	1		All	0000h – 1FFFh

Writing Protect

			Writing protection status	Protection sta	itus in memory	
WP#	SRWD	mode	Writing protection status in status register	Protected blocks	Unprotected blocks	
1	0	0-4	Status register is			
0	0	Software protection (SPM)	unprotected when WEL-bit is set by WREN command. BP0 and BP1	Protected	Unprotected	
1	1	(3)	are unprotected.			
0	1	Hardware protection (HPM)	Status register is protected. BP0 and BP1 are protected.	Protected	Unprotected	

HOLD

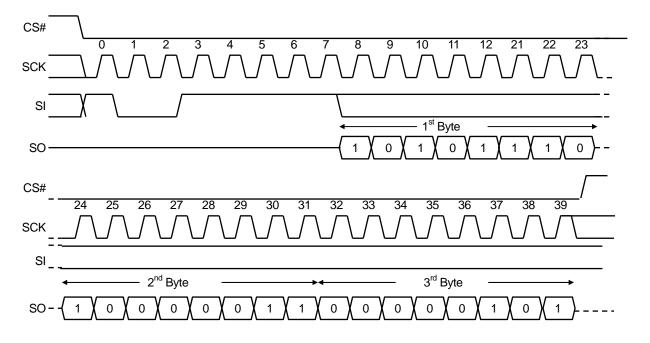
Hold status is used for suspending serial comunication without disable the chip. SO becomes "High-Z" and SI is "Don't care" during the hold status. It is necessary to keep CS#=L in hold status.



RDID (Read device ID)

RDID command can be valid when CS# goes "L",then the op-code are inputted to serial input"SI". Then 3bytes of device ID is output at serial-output "SO".

Manufacture id (LAPIS)	device type (I	MR45V064B)
1 st Byte	2 nd Byte	3 rd Byte
AEh	83h	05h



Note: WP# = Fixed "H"

ELECTRICAL CHARACTERISTICS

ABSOLUTE MAXIMUM RATINGS

The application of stress (voltage, current, or temperature) that exceeds the absolute maximum rating may damage the device. Therefore, do not allow actual characteristics to exceed any one parameter ratings

PIN VOLTAGES

Dovometer	Cymphol	Rat	Lloit	
Parameter	Symbol	Min.	Max.	Unit
Pin Voltage (Input Signal)	V _{IN}	-0.5	V _{CC} + 0.5	V
Pin Voltage (Input/Output Voltage)	V_{INQ}, V_{OUTQ}	-0.5	V _{CC} + 0.5	V
Power Supply Voltage	V _{CC}	-0.5	4.0	V

TEMPERATURE RANGE

Dorometer	Symbol	Symbol		Unit	Note
Parameter	Symbol	Min.	Max.	Offic	Note
Storage Temperature (Extended Temperature Version)	Tstg	– 55	125	°C	
Operating Temperature (Extended Temperature Version)	Topr	-40	85	°C	

OTHERS

Parameter	Symbol	Rating	Note
Power Dissipation	P_{D}	1,000mW	Ta=25°C

RECOMMENDED OPERATING CONDITIONS

POWER SUPPLY VOLTAGE

[V]

Parameter	Symbol	Min.	Тур.	Max.	Note
Power Supply Voltage	V _{CC}	1.8	3.3	3.6	
Ground Voltage	V_{SS}	0	0	0	

DC INPUT VOLTAGE

[V]

Parameter	Symbol	Min.	Max.	Note
Input High Voltage	V _{IH}	V _{CC} x 0.7	V _{CC} +0.3	
Input Low Voltage	V_{IL}	-0.3	V _{CC} x 0.3	

OVERSHOOT/UNDERSHOOT TOLERANCE

Parameter	Parameter Symbol		Peak
"H" input	V _{IH} OVERSHOOT	≤ 20ns	V _{CC} +1.0V
"L" input	V _{IL UNDERSHOOT}	≤ 20ns	- 1.0V

DC CHARACTERISTICS

DC INPUT/OUTPUT CHARACTERISTICS

Parameter	Symbol	Condition	Min.	Max.	Unit	Note
Outrout High Voltage		l2mΛ	V _{CC} ×0.85	_	V	V _{CC} 2.0V
Output High Voltage	V _{OH}	I _{OH} =-2mA	V _{CC} ×0.80	_	V	V _{CC} <2.0V
Output Low Voltage	V _{OL}	I _{OL} =2mA	_	V _{CC} ×0.15	V	
Input Leakage Current	I _{LI}	_	-10	10	μA	
Output Leakage Current	I _{LO}	_	-10	10	μΑ	

POWER SUPPLY CURRENT

V_{CC}=Max.to Min, Ta=Topr

Parameter	Symbol	Condition	Max.	Unit	Note
Power Supply Current (Standby)	I _{CCS}	V _{IN} =0.2V or V _{CC} -0.2V	10	μΑ	
Power Supply Current (Operating)	I _{CCA}	V _{IN} =0.2V or V _{CC} -0.2V, SCK=40MHz, I _{OUT} =0mA	3	mA	

AC CHARACTERISTICS (Read Cycle)

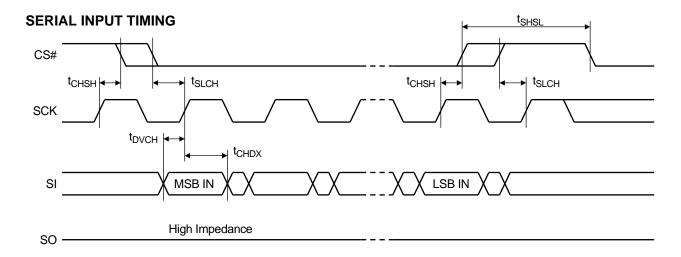
V_{CC}=Max. to Min., Ta=Topr.

					o wiii., ia-iopi.
	Symbol	MR45V064B		l lait	Maria
Parameter		Min.	Max.	Unit	Note
Clock frequency	f _C	D.C.	40	MHz	
CS# setup time	t _{SLCH}	10	_	ns	
CS# De-select time	t _{SHSL}	40	_	ns	
CS# hold time	t _{CHSH}	10	_	ns	
SCK High time	t _{CH}	11	_	ns	1
SCK Low time	t _{CL}	11	_	ns	1
Data Setup time	t _{DVCH}	5	_	ns	
Data Hold time	t _{CHDX}	5	_	ns	
SCK Low Hold time after HOLD# inactive	t _{HHCH}	10	_	ns	
SCK Low Hold time after HOLD# active	t _{HLCH}	10	_	ns	
SCK High Setup time before HOLD# active	t _{CHHL}	10	_	ns	
SCK High Setup time before HOLD# inactive	t _{CHHH}	10	_	ns	
Output disable time	t _{SHQZ}		12	ns	2
SCK Low to Output Volid time	t	_	9	ns	V _{CC} ≧2.7V
SCK Low to Output Valid time	t _{CLQV}	_	10	ns	V _{CC} <2.7V
Output Hold time	t _{CLQX}	0	_	ns	
HOLD# High to Output Low impedance time	t _{HHQX}	_	20	ns	2
HOLD# High to Output High impedance time	t _{HLQZ}	_	20	ns	2

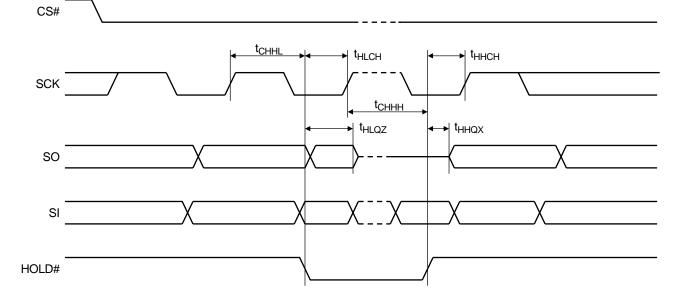
Note: $1. t_{CH} + t_{CL} \ge 1/f_C$

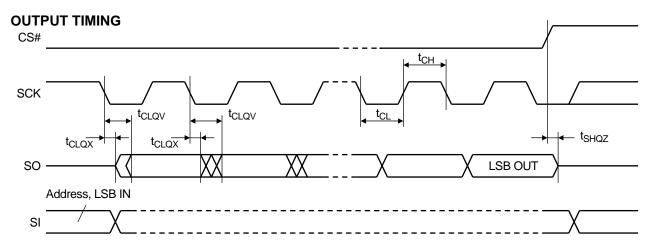
2. sample value

TIMING DIAGRAMS



HOLD TIMING





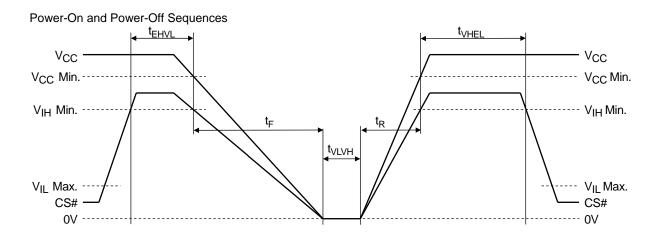
POWER-ON and POWER-OFF CHARACTERISTICS

(Under recommended operating conditions)

Parameter	Symbol	Min.	Max.	Unit	Note
Power-On CS# High Hold Time	t _{VHEL}	100	_	ns	1, 2
Power-Off CS# High Hold Time	t _{EHVL}	0	_	ns	1
Power-On Interval Time	t _{VLVH}	0		μs	2
Power-On time	tR	30	_	μs/V	
Power-Off time	tF	30		μs/V	

Notes:

- 1. To prevent an erroneous operation, be sure to maintain CS#="H", and set the FeRAM in an inactive state (standby mode) before and after power-on and power-off.
- 2. Powering on at the intermediate voltage level will cause an erroneous operation; thus, be sure to power up from 0 V.
- 3. Enter all signals at the same time as power-on or enter all signals after power-on.



READ/WRITE CYCLES and DATA RETENTION

(Under recommended operating conditions)

Parameter	Min.	Max.	Unit	Note
Read/Write Cycle	10 ¹²	_	Cycle	
Data Retention	10	_	Year	

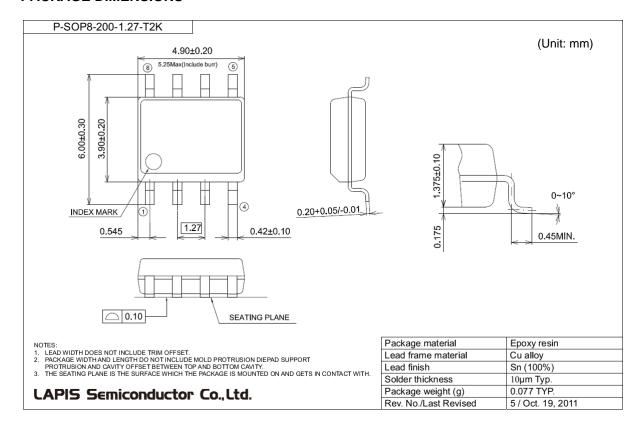
CAPACITANCE

Signal	Symbol	Min.	Max.	Unit	Note
Input Capacitance	C _{IN}	_	10	pF	1
Input/Output Capacitance	Соит	_	10	pF	1

Note:

Sampling value. Measurement conditions are $V_{\text{IN}} = V_{\text{OUT}} = \text{GND}, \, f = 1 \text{MHz}, \, \text{and} \, \, \text{Ta} = 25 ^{\circ} \text{C}$

PACKAGE DIMENSIONS



Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

Revision History

		Page			
Document No.	Date	Previous Edition	Current Edition	Description	
FEDR45V064B-01	Jan. 08, 2016	-	-	Final edition 1	

Notes

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