

Version: A00

DE LiDAR TF02



Benewake (Beijing) Co. Ltd.



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Preface

Distinguished user:

We would like to express our gratitude to you for choosing our product.

This specification is aimed to help you use our product in a proper manner. Before you install and use the product, please make sure you have carefully read the documents attached, which will contribute to your better using of our product. If you have read this specification, it is suggested that you should keep it properly for future reference.

If you have any questions, please feel free to contact our technical support or aftersales customer service. We will try our best to solve any problem related with the product. If you have any advice or suggestion for us, please go to our official website(www.benewake.com) and give us feedback in the community module. We listen to every customerwholeheartedly.

Benewake aims to make the best robot eyes worldwide. We will adhere to the "customer experience centered" principle.



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1. Product Overview

This product is based upon TOF (Time of Flight), supplemented by particular optics, electricity, and design, so as to measure distance with stability, precision, high sensitivity, and high speed.

Key Features:

- high sensitivity, and the ability of measuring as far as 22 meters
- high speed measurement with a maximum sampling frequency of 100Hz
- excellent anti-ambient light usability (operable under 100kLux ambient light)
- outdoor long distance and light weight (with a module weight of less than 50g)
- high precision; its precision can reach centimeter level within measuring range

Major Applications:

- drone altitude holding and terrain following
- machine control and safe sensors
- distance measuring instrument

2. Optical Principle

TOF is short for Time of Flight. It refers that a sensor emits modulated near infrared light, which reflects when objects are in the way. TOF then convert the distance away from the filmed scenery by calculating the time difference or phase difference between emission and reflection, thereby generating in-depth information.

3. Electrical Properties

| Project | Symbol | MinimumValue | Typical Value | Maximum Value | Unit |
|---------------|--------|--------------|---------------|------------------|------|
| Input Voltage | DC | 4.5 | 5 | 6 | V |
| Power | P | | 0.6 | | W |

4. Optical Properties

| Project | Symbol | Condition or Description | Typical Value | Unit |
|------------------|--------|--|--|------|
| Working Distance | L | Indoor | 0.4 - 10 (Reflectivity 10%) 0.4 - 22 (Reflectivity 90%) | m |
| | | Outdoor illumination intensity of 100k Lux | 0.4-10 | |

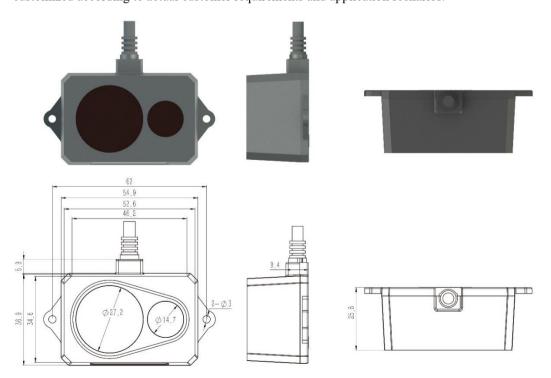


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| Emission Semi-angle of Signal Light | α | | 2 | Degree |
|--|----|--|--|--------|
| Reception Semi-angle of Signal Light | β | | 1.5 | Degree |
| Detection Range | D | Object size detected from 5m away | 26 | cm |
| Distance Resolution Ratio | Re | Sensitivity to distance change | 1 | cm |
| Distance Precision | σ | Deviation between measuring distance and actual distance | 1 - 5 (within 10m) 5 - 10 (10m - 22m) | cm |
| Working Temperature | T | | -10 - 60 | °C |
| Work Center Wave Length | λ | | 850 | nm |

5. Size and Specification

The module object figures and outline dimensional drawings below are reference designs and can be customized according to actual customer requirements and application scenarios.





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DELiDAR TF02Outline Dimensional Drawing

Installation Requirements:

- 1. M2.5 round Philip's head screw is suggested when installing LiDAR and peripheral structures.
- 2. Optical windows of LiDAR front panel φ27.2 and φ14.7 cannot be blocked and shall be kept clean.

Line Sequence Description:

| | Line Sequence of Serial Ports | Line Sequence of CAN |
|---------------|----------------------------------|----------------------|
| Red Line | +5V | +5V |
| Black Line | GND | GND |
| White Line | TTL-RXD | CAN-L |
| Green Line | TTL-TXD | CAN-H |

6. Data Format

6.1 Communication Protocols of Serial Port Output

The following is an introduction to the method of DE-LiDAR TF02 connecting and communicating with peripheral equipment using serial ports, including coded format of sent data, and communication protocols of modules with peripheral equipment. The serial port output level is TTL.

| Communication Protocol | UART | CAN |
|---------------------------|--------|------------|
| Baud Rate | 115200 | 1M |
| Data Bit | 8 | |
| Stop Bit | 1 | |
| Parity Bit | None | |
| ID | | 0x00480014 |

6.2 Standard Data Format of Serial Ports

The data output by TF02 is shown as follows. All the data are hexadecimal. Each frame of data totals 9 bytes. The data contains distance information (Dist), signal strength information (AMP), and reliability information (SIG). The frame tail is data parity bit.



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| Data Bit | Definition | Description |
|----------|-----------------|--|
| Byte0 | Frame Header | 0x59 |
| Byte1 | Frame Header | 0x59 |
| Byte2 | DIST_L | DIST Low 8 Bits |
| Byte3 | DIST_H | DIST High 8 Bits |
| Byte4 | AMP_L | AMP Low 8 Bits |
| Byte5 | AMP_H | AMP High 8 Bits |
| Byte6 | SIG | Reliability is divided into 9 levels, respectively indicated by 0x01-0x09. When the reliability level is 7 or 8, it means data reliable. When the reliability level is other values, the frame of data is not recommended. |
| Byte7 | Reserved Bit | Reserved Bit |
| Byte8 | Check | Checksum parity bit low 8 bits, Checksum = Byte0 + Byte2 + + Byte7. Checksum is the low 8 bits of the checksum of the former 8 bytes |

6.3 **Data Format of Serial Port Pix**

The output is in the form of a string with m as its unit. For example, if the measuring distance is 1.21m, then the output string is 1.21. Each distance value ends with line feed.

Note: if the output distance of TF02 is 22 (m), then it indicates outrange or insufficient signal intensity. Hence, the distance is not reliable. It is suggested to eliminate the data.

6.4 CAN Standard Data Format

The data output by TF02 is shown as follows. All the data are hexadecimal. Each frame of data totals 8 bytes. The data contains distance information(Dist), signal strength information (AMP), and reliability information (SIG).

Remarks: CAN communication protocols can be customized according to customer requirements.

| Data Bit | Definition | Description |
|----------|------------|-----------------|
| Byte0 | DIST_H | DISTHigh 8 Bits |
| Byte1 | DIST_L | DISTLow 8 Bits |
| Byte2 | AMP_H | AMPHigh 8 Bits |



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| Byte3 | AMP_L | AMPLow 8 Bits |
|-------|-----------------|---|
| Byte4 | Reserved Bit | Reserved Bit |
| Byte5 | SIG | Reliability is divided into 9 levels, respectively indicated by $0x01-0x09$. When the reliability level is 7 or 8, it means data are reliable. When the reliability level is other values, the frame of data is not recommended. |
| Byte6 | Reserved Bit | Reserved Bit |
| Byte7 | Reserved Bit | Reserved Bit |

Application Notice:

- This product is a custom-made precision optical instrument and must be maintained by engineers of our company.
- Working temperature: -10 60 °C
- Prevent foreign matters, such as dusts, from entering lens in case of bright dipping
- The product adopts moisture-sensitive components, thereforestorage, transportation, as well as working under high moisture and high temperature should be avoided. Moreover, avoid using the product in acid or concentrated sulfur environment.

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