

General Description

The AAT2148 SwitchReg is a 2MHz step-down converter with an input voltage range of 2.7V to 5.5V and output voltage as low as 0.6V. It is optimized to react quickly to a load variation. The AAT2148 incorporates a unique low noise architecture which reduces ripple and spectral noise.

The AAT2148 is available in fixed voltage versions with internal feedback and a programmable version with external feedback resistors. It can deliver 1A of load current while maintaining a low $37\mu A$ no load quiescent current. The 2MHz switching frequency minimizes the size of external components while keeping switching losses low.

The AAT2148 is designed to maintain high efficiency throughout the operating range, which is critical for portable applications.

The AAT2148 is available in the Pb-free, thermally enhanced 3x3mm QFN-16 package and is rated over the -40°C to +85°C temperature range.

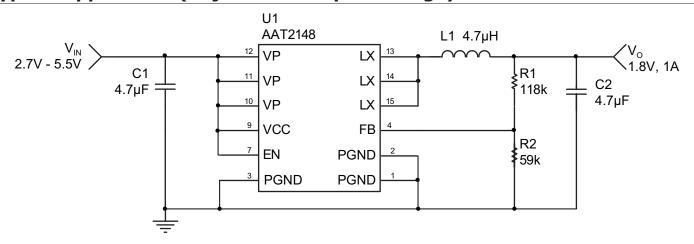
Features

- V_{IN} Range: 2.7V to 5.5V
- Low Noise Light Load Mode
- Low Ripple PWM Mode
- V_{OUT} Fixed or Adjustable from 0.6V to V_{IN}
- 37µA No Load Quiescent Current
- Up to 98% Efficiency
- 1A Max Output Current
- 2MHz Switching Frequency
- 150µs Soft Start
- Fast Load Transient
- Over-Temperature Protection
- Current Limit Protection
- 100% Duty Cycle Low-Dropout Operation
- <1µA Shutdown Current
- QFN33-16 Package
- Temperature Range: -40°C to +85°C

Applications

- · Cellular Phones
- Digital Cameras
- Handheld Instruments
- Microprocessor / DSP Core / IO Power
- PDAs and Handheld Computers
- USB Devices

Typical Application (Adjustable Output Voltage)

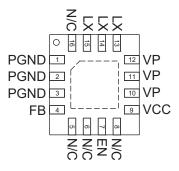


Pin Descriptions

| Pin # | Symbol | Function |
|-------------|--|---|
| 1, 2, 3 | PGND | Power ground pin |
| 4 | FB | Feedback input. This pin is connected either directly to the converter output or to an external resistive divider for an adjustable output. |
| 5, 6, 8, 16 | N/C | Not internally connected. |
| 9 | VCC | Bias supply. Supplies power for the internal circuitry. Connect to input power. |
| 10, 11, 12 | VP | Input supply voltage for the converter power stage. Must be closely decoupled to GND. |
| 13, 14, 15 | Switching node. Connect the inductor to this nin. It is internally connected to the drain of h | |
| EP | | Exposed paddle (bottom); connect to PGND directly beneath package. |

Pin Configuration

QFN33-16 (Top View)



Low-Noise, Fast Transient IA Step-Down Converter

Absolute Maximum Ratings¹

| Symbol | Description | Value | Units |
|-------------------|--|-------------------------------|-------|
| V _{IN} | Input Voltage GND | 6.0 | V |
| V_{LX} | LX to GND | -0.3 to V _{IN} + 0.3 | V |
| V _{OUT} | OUT to GND | -0.3 to V _{IN} + 0.3 | V |
| V_{EN} | EN to GND | -0.3 to V _{IN} + 0.3 | V |
| T ₃ | Operating Junction Temperature Range | -40 to 150 | °C |
| T _{LEAD} | Maximum Soldering Temperature (at leads, 10 sec) | 300 | °C |

Thermal Information

| Symbol | Symbol Description | | Units |
|----------------|--|----|-------|
| P _D | P _D Maximum Power Dissipation ^{2, 3} | | W |
| θ_{JA} | Thermal Resistance ² | 50 | °C/W |

^{1.} Stresses above those listed in Absolute Maximum Ratings may cause permanent damage to the device. Functional operation at conditions other than the operating conditions specified is not implied. Only one Absolute Maximum Rating should be applied at any one time.

^{2.} Mounted on an FR4 board.

^{3.} Derate 6.25mW/°C above 25°C.

Low-Noise, Fast Transient IA Step-Down Converter

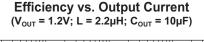
Electrical Characteristics¹

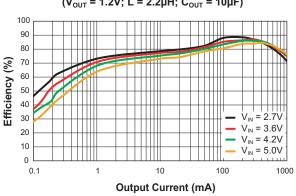
 $T_A = -40$ °C to +85 °C, unless otherwise noted. Typical values are $T_A = 25$ °C, $V_{IN} = 3.6$ V.

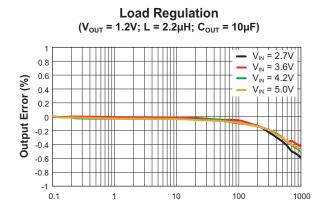
| Symbol | Description | Conditions | Min | Тур | Max | Units |
|----------------------|--------------------------------------|--|------|------|----------|-------|
| Step-Dow | Step-Down Converter | | | | | |
| V_{IN} | Input Voltage | | 2.7 | | 5.5 | V |
| .,, | UVLO Threshold | V _{IN} Rising | | 1.8 | 2.7 | V |
| V_{UVLO} | OVLO TITESTICIO | Hysteresis | | 100 | | mV |
| V _{out} | Output Voltage Tolerance | $I_{OUT} = 0$ mA to 1A, $V_{IN} = 2.7$ V to 5.5V | -3.0 | | +3.0 | % |
| V _{out} | Output Voltage Range | | 0.6 | | V_{IN} | V |
| ${ m I}_{ m Q}$ | Quiescent Current | No Load, 0.6V Adjustable Version | | 37 | 70 | μΑ |
| I_{SHDN} | Shutdown Current | EN = AGND = PGND | | | 1.0 | μA |
| I _{LIM} | P-Channel Current Limit | | 1300 | 1700 | | mA |
| R _{DS(ON)H} | High Side Switch On Resistance | | | 0.35 | | Ω |
| R _{DS(ON)L} | Low Side Switch On Resistance | | | 0.30 | | Ω |
| $\Delta V_{Linereg}$ | Line Regulation | $V_{IN} = 2.7V$ to 5.5V; $I_{OUT} = 1A$ | | 0.1 | | %/V |
| V_{FB} | Feedback Threshold Voltage Accuracy | 0.6V Output, No Load; T _A = 25°C | 591 | 600 | 609 | mV |
| I_{FB} | Feedback Leakage Current | 0.6V Output | | | 1 | μΑ |
| Ts | Start-Up Time | From Enable to Output Regulation | | 150 | | μs |
| Fosc | Oscillator Frequency | $T_A = 25$ °C | 0.9 | 2.0 | 2.6 | MHz |
| T _{SD} | Over-Temperature Shutdown Threshold | | | 140 | | °C |
| T _{HYS} | Over-Temperature Shutdown Hysteresis | | | 15 | | °C |
| EN | | | | | | |
| $V_{EN(L)}$ | Enable Threshold Low | | | | 0.6 | V |
| V _{EN(H)} | Enable Threshold High | | 1.4 | | | V |
| I_{EN} | Input Low Current | $V_{IN} = V_{OUT} = 5.5V$ | -1.0 | | 1.0 | μA |

^{1.} The AAT2148 is guaranteed to meet performance specifications over the -40°C to +85°C operating temperature range and is assured by design, characterization, and correlation with statistical process controls.

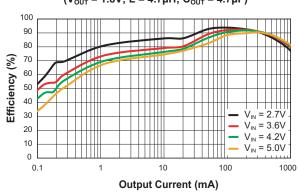
Typical Characteristics

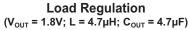




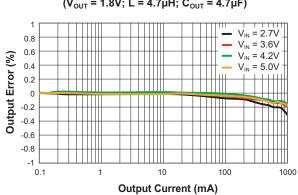


Efficiency vs. Output Current $(V_{OUT} = 1.8V; L = 4.7\mu H; C_{OUT} = 4.7\mu F)$

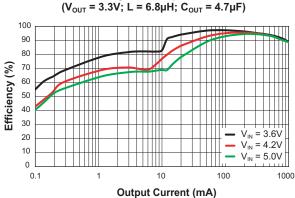




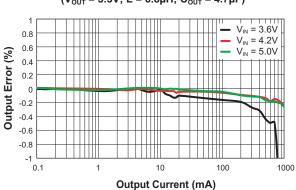
Output Current (mA)



Efficiency vs. Output Current

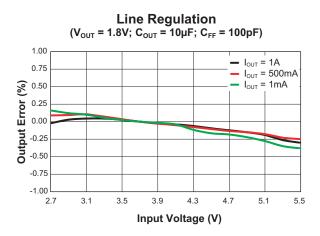


Load Regulation $(V_{OUT} = 3.3V; L = 6.8\mu H; C_{OUT} = 4.7\mu F)$

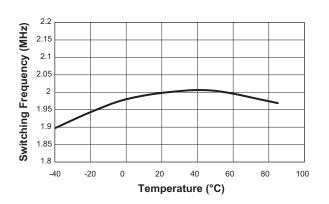


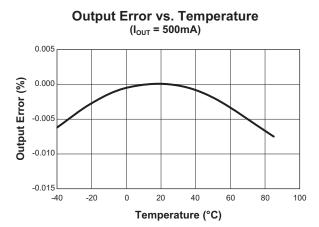
Low-Noise, Fast Transient IA Step-Down Converter

Typical Characteristics

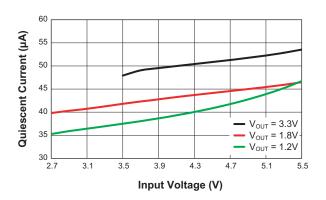


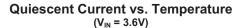
Switching Frequency vs. Temperature

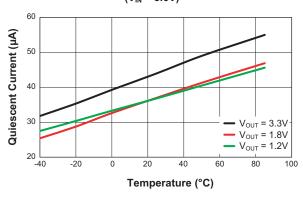




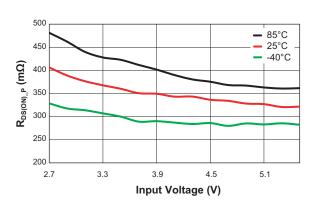
Quiescent Current vs. Input Voltage





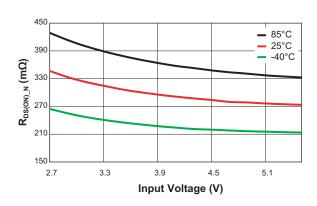


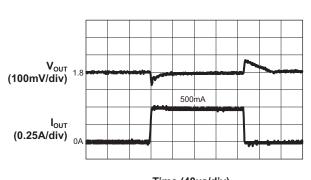
P-Channel $R_{DS(ON)}$ vs. Input Voltage



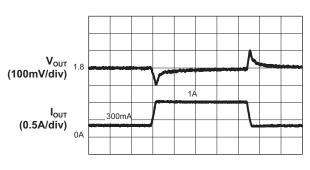
Typical Characteristics

N-Channel R_{DS(ON)} vs. Input Voltage

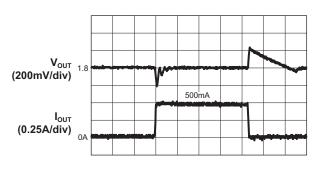




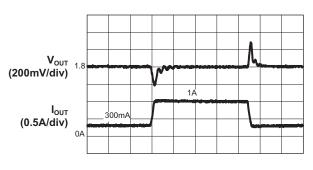
Time (40µs/div)



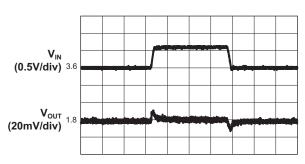
Time (16µs/div)



Time (40µs/div)



Time (16µs/div)

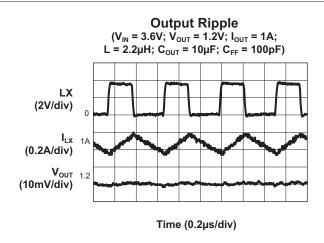


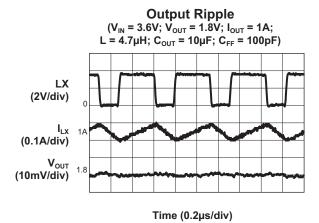
Time (200µs/div)

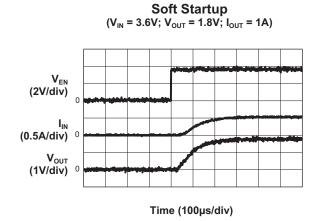
Typical Characteristics

Output Ripple (V_{IN} = 3.6V; V_{OUT} = 1.2V; I_{OUT} = 10mA; L = 2.2μH; C_{OUT} = 10μF; C_{FF} = 100pF) (2V/div) (0.1A/div) V_{OUT} 1.2 (20mV/div) 1.2

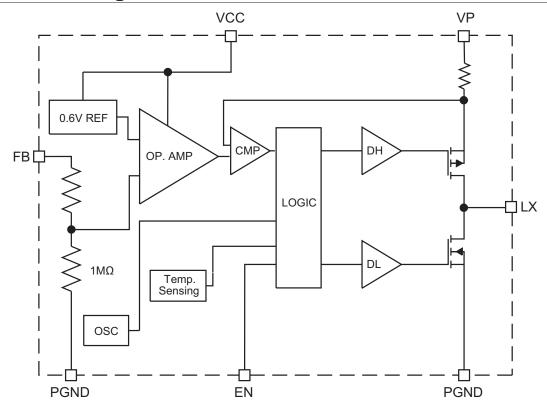
Time (1µs/div)







Functional Block Diagram



Functional Description

The AAT2148 is a high performance 1A 2MHz monolithic step-down converter. It has been designed with the goal of minimizing external component size and optimizing efficiency over the complete load range, and produces reduced ripple and spectral noise. Apart from the small bypass input capacitor, only a small L-C filter is required at the output. Typically, a $4.7\mu H$ inductor and a $4.7\mu F$ ceramic capacitor are recommended (see table of values).

The fixed output version requires only three external power components (C_{IN} , C_{OUT} , and L). The adjustable version can be programmed with external feedback to any voltage, ranging from 0.6V to the input voltage. An additional feed-forward capacitor can also be added to the external feedback to provide improved transient response (see Figure 1).

At dropout, the converter duty cycle increases to 100% and the output voltage tracks the input voltage minus the R_{DSON} drop of the P-channel high-side MOSFET.

The input voltage range is 2.7V to 5.5V. The converter efficiency has been optimized for all load conditions, ranging from no load to 1A.

The internal error amplifier and compensation provides excellent transient response, load, and line regulation. Soft start eliminates any output voltage overshoot and input inrush current when the enable or the input voltage is applied.

Control Loop

The AAT2148 is a peak current mode step-down converter. The current through the P-channel MOSFET (high side) is sensed for current loop control, as well as short circuit and overload protection. A fixed slope compensation signal is added to the sensed current to maintain stability for duty cycles greater than 50%. The peak current mode loop appears as a voltage-programmed current source in parallel with the output capacitor.

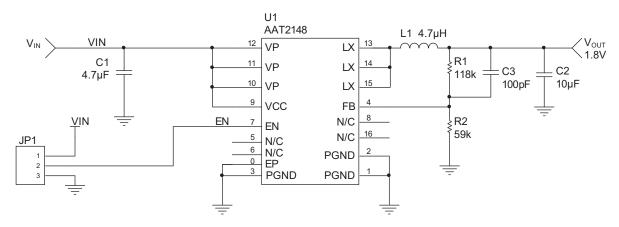


Figure 1: Enhanced Transient Response Schematic.

The output of the voltage error amplifier programs the current mode loop for the necessary peak switch current to force a constant output voltage for all load and line conditions. Internal loop compensation terminates the transconductance voltage error amplifier output. For fixed voltage versions, the error amplifier reference voltage is internally set to program the converter output voltage. For the adjustable output, the error amplifier reference is fixed at 0.6V.

Soft Start / Enable

Soft start limits the current surge seen at the input and eliminates output voltage overshoot. When pulled low, the enable input forces the AAT2148 into a low-power, non-switching state. The total input current during shutdown is less than 1μ A.

Current Limit and Over-Temperature Protection

For overload conditions, the peak input current is limited. To minimize power dissipation and stresses under current limit and short-circuit conditions, switching is terminated after entering current limit for a series of pulses. Switching is terminated for seven consecutive clock cycles after a current limit has been sensed for a series of four consecutive clock cycles.

Thermal protection completely disables switching when internal dissipation becomes excessive. The junction over-temperature threshold is 140°C with 15°C of hysteresis. Once an over-temperature or over-current fault conditions is removed, the output voltage automatically recovers.

Under-Voltage Lockout

Internal bias of all circuits is controlled via the $V_{\rm IN}$ input. Under-voltage lockout (UVLO) guarantees sufficient $V_{\rm IN}$ bias and proper operation of all internal circuitry prior to activation.

Applications Information

Inductor Selection

The step-down converter uses peak current mode control with slope compensation to maintain stability for duty cycles greater than 50%. The output inductor value must be selected so the inductor current down slope meets the internal slope compensation requirements. The internal slope compensation for the adjustable and low-voltage fixed versions of the AAT2148 is 0.24A/ μ s. This equates to a slope compensation that is 75% of the inductor current down slope for a 1.5V output and 4.7 μ H inductor.

$$m = \frac{0.75 \cdot V_0}{L} = \frac{0.75 \cdot 1.5V}{4.7 \mu H} = 0.24 \frac{A}{\mu s}$$

This is the internal slope compensation for the adjustable (0.6V) version or low-voltage fixed versions. When externally programming the 0.6V version to 2.5V, the calculated inductance is 7.5μ H.

$$L = \frac{0.75 \cdot V_{o}}{m} = \frac{0.75 \cdot V_{o}}{0.24A \frac{A}{\mu s}} \approx 3 \frac{\mu s}{A} \cdot V_{o}$$
$$= 3 \frac{\mu s}{A} \cdot 2.5V = 7.5\mu H$$

In this case, a standard 6.8µH value is selected.

For high-voltage fixed versions (≥ 2.5 V), m = 0.48A/ μ s. Table 1 displays inductor values for the AAT2148 fixed and adjustable options.

Manufacturer's specifications list both the inductor DC current rating, which is a thermal limitation, and the peak current rating, which is determined by the saturation characteristics. The inductor should not show any appreciable saturation under normal load conditions. Some inductors may meet the peak and average current ratings yet result in excessive losses due to a high DCR. Always consider the losses associated with the DCR and its effect on the total converter efficiency when selecting an inductor.

The $4.7\mu H$ SD3118 series inductor selected from Coilcraft has a $162m\Omega$ typical DCR and a 1.31A saturation current. At full load, the inductor DC loss is 162mW which gives a 9% loss in efficiency for a 1A, 1.8V output.

Input Capacitor

Select a 4.7µF to $10\mu F$ X7R or X5R ceramic capacitor for the input. To estimate the required input capacitor size, determine the acceptable input ripple level (V_{PP}) and solve for C. The calculated value varies with input voltage and is a maximum when V_{IN} is double the output voltage.

$$C_{IN} = \frac{\frac{V_O}{V_{IN}} \cdot \left(1 - \frac{V_O}{V_{IN}}\right)}{\left(\frac{V_{PP}}{I_O} - ESR\right) \cdot F_S}$$

$$\frac{V_O}{V_{IN}} \cdot \left(1 - \frac{V_O}{V_{IN}}\right) = \frac{1}{4} \text{ for } V_{IN} = 2 \cdot V_O$$

$$C_{IN(MIN)} = \frac{1}{\left(\frac{V_{PP}}{I_O} - ESR\right) \cdot 4 \cdot F_S}$$

Always examine the ceramic capacitor DC voltage coefficient characteristics when selecting the proper value. For example, the capacitance of a $10\mu F$, 6.3V, X5R ceramic capacitor with 5.0V DC applied is actually about $6\mu F$.

| Output Voltage (V) | Inductor (µH) | Output Capacitor (µF) |
|-----------------------|------------------|--------------------------|
| 1, 1.2 | 2.2 | 10 |
| 1.5, 1.8 | 4.7 | 4.7 |
| 2.5, 3.3 | 6.8 | 4.7 |

Table 1: Inductor and Output Capacitor Values.

The maximum input capacitor RMS current is:

$$I_{RMS} = I_{O} \cdot \sqrt{\frac{V_{O}}{V_{IN}} \cdot \left(1 - \frac{V_{O}}{V_{IN}}\right)}$$

The input capacitor RMS ripple current varies with the input and output voltage and will always be less than or equal to half of the total DC load current.

$$\sqrt{\frac{V_O}{V_{IN}} \cdot \left(1 - \frac{V_O}{V_{IN}}\right)} = \sqrt{D \cdot (1 - D)} = \sqrt{0.5^2} = \frac{1}{2}$$

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for $V_{IN} = 2 \cdot V_{O}$

$$I_{RMS(MAX)} = \frac{I_0}{2}$$

The term $\frac{V_o}{V_N} \cdot \left(1 \cdot \frac{V_o}{V_N}\right)$ appears in both the input voltage ripple and input capacitor RMS current equations and is a maximum when V_o is twice V_{IN} . This is why the input voltage ripple and the input capacitor RMS current ripple are a maximum at 50% duty cycle.

The input capacitor provides a low impedance loop for the edges of pulsed current drawn by the AAT2148. Low ESR/ESL X7R and X5R ceramic capacitors are ideal for this function. To minimize stray inductance, the capacitor should be placed as closely as possible to the IC. This keeps the high frequency content of the input current localized, minimizing EMI and input voltage ripple.

The proper placement of the input capacitor (C1) can be seen in the evaluation board layout in Figure 2.

A laboratory test set-up typically consists of two long wires running from the bench power supply to the evaluation board input voltage pins. The inductance of these wires, along with the low-ESR ceramic input capacitor, can create a high Q network that may affect converter performance. This problem often becomes apparent in the form of excessive ringing in the output voltage during load transients. Errors in the loop phase and gain measurements can also result.

Since the inductance of a short PCB trace feeding the input voltage is significantly lower than the power leads from the bench power supply, most applications do not exhibit this problem.

In applications where the input power source lead inductance cannot be reduced to a level that does not affect the converter performance, a high ESR tantalum or aluminum electrolytic should be placed in parallel with the low ESR, ESL bypass ceramic. This dampens the high Q network and stabilizes the system.

Output Capacitor

The output capacitor limits the output ripple and provides holdup during large load transitions. A 4.7 μ F to 10 μ F X5R or X7R ceramic capacitor typically provides sufficient bulk capacitance to stabilize the output during large load transitions and has the ESR and ESL characteristics necessary for low output ripple.

The output voltage droop due to a load transient is dominated by the capacitance of the ceramic output capacitor. During a step increase in load current, the ceramic output capacitor alone supplies the load current until the loop responds. Within two or three switching cycles, the loop responds and the inductor current increases to match the load current demand. The relationship of the output voltage droop during the three switching cycles to the output capacitance can be estimated by:

$$C_{OUT} = \frac{3 \cdot \Delta I_{LOAD}}{V_{DROOP} \cdot F_{S}}$$

Once the average inductor current increases to the DC load level, the output voltage recovers. The above equation establishes a limit on the minimum value for the output capacitor with respect to load transients.

The internal voltage loop compensation also limits the minimum output capacitor value to 4.7 μ F. This is due to its effect on the loop crossover frequency (bandwidth), phase margin, and gain margin. Increased output capacitance will reduce the crossover frequency with greater phase margin.

The maximum output capacitor RMS ripple current is given by:

$$I_{\text{RMS(MAX)}} = \frac{1}{2 \cdot \sqrt{3}} \cdot \frac{V_{\text{OUT}} \cdot (V_{\text{IN(MAX)}} - V_{\text{OUT}})}{L \cdot F \cdot V_{\text{IN(MAX)}}}$$

Dissipation due to the RMS current in the ceramic output capacitor ESR is typically minimal, resulting in less than a few degrees rise in hot-spot temperature.

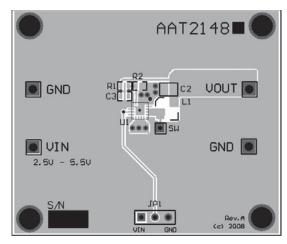


Figure 2: AAT2148 Evaluation Board Top Layer.

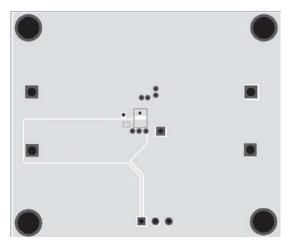


Figure 3: AAT2148 Evaluation Board Bottom Layer.

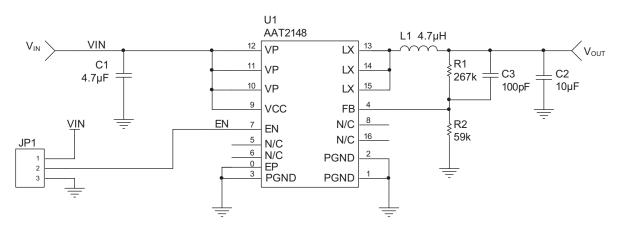


Figure 4: AAT2148 Evaluation Board Schematic.

Adjustable Output Resistor Selection

For applications requiring an adjustable output voltage, the 0.6V version can be externally programmed. Resistors R1 and R2 of Figure 4 program the output to regulate at a voltage higher than 0.6V. To limit the bias current required for the external feedback resistor string while maintaining good noise immunity, the minimum suggested value for R2 is $59k\Omega$. Although a larger value will further reduce quiescent current, it will also increase the impedance of the feedback node, making it more sensitive to external noise and interference. Table 2 summarizes the resistor values for various output volt-

ages with R2 set to either $59k\Omega$ for good noise immunity or $221k\Omega$ for reduced no load input current.

$$R3 = \left(\frac{V_{OUT}}{V_{REF}} - 1\right) \cdot R4 = \left(\frac{1.5V}{0.6V} - 1\right) \cdot 59k\Omega = 88.5k\Omega$$

The adjustable version of the AAT2148, combined with an external feedforward capacitor (C3 in Figure 1), delivers enhanced transient response for extreme pulsed load applications. The addition of the feedforward capacitor typically requires a larger output capacitor C2 for stability.

| | $R2 = 59k\Omega$ | $R2 = 221k\Omega$ |
|------------------------------------|------------------|-------------------|
| V _{OUT} (V) | R1 (k Ω) | R1 (Ω) |
| 0.8 | 19.6 | 75K |
| 0.9 | 29.4 | 113K |
| 1.0 | 39.2 | 150K |
| 1.1 | 49.9 | 187K |
| 1.2 | 59.0 | 221K |
| 1.3 | 68.1 | 261K |
| 1.4 | 78.7 | 301K |
| 1.5 | 88.7 | 332K |
| 1.8 | 118 | 442K |
| 1.85 | 124 | 464K |
| 2.0 | 137 | 523K |
| 2.5 | 187 | 715K |
| 3.3 | 267 | 1.00M |

Table 2: Adjustable Resistor Values For Use With 0.6V Step-Down Converter.

Thermal Calculations

There are three types of losses associated with the AAT2148 step-down converter: switching losses, conduction losses, and quiescent current losses. Conduction losses are associated with the $R_{\rm DS(ON)}$ characteristics of the power output switching devices. Switching losses are dominated by the gate charge of the power output switching devices. At full load, assuming continuous conduction mode (CCM), a simplified form of the losses is given by:

$$\mathsf{P}_{\mathsf{TOTAL}} = \frac{\mathsf{I_o}^2 \cdot (\mathsf{R}_{\mathsf{DSON}(\mathsf{HS})} \cdot \mathsf{V_O} + \mathsf{R}_{\mathsf{DSON}(\mathsf{LS})} \cdot [\mathsf{V_{\mathsf{IN}}} - \mathsf{V_O}])}{\mathsf{V_{\mathsf{IN}}}}$$

+
$$(t_{sw} \cdot F \cdot I_O + I_Q) \cdot V_{IN}$$

 I_{Q} is the step-down converter quiescent current. The term t_{sw} is used to estimate the full load step-down converter switching losses.

For the condition where the step-down converter is in dropout at 100% duty cycle, the total device dissipation reduces to:

$$P_{TOTAL} = I_O^2 \cdot R_{DSON(HS)} + I_Q \cdot V_{IN}$$

Since $R_{DS(ON)}$, quiescent current, and switching losses all vary with input voltage, the total losses should be investigated over the complete input voltage range.

Given the total losses, the maximum junction temperature can be derived from the θ_{JA} for the QFN33-16 package which is 50°C/W.

$$T_{J(MAX)} = P_{TOTAL} \cdot \Theta_{JA} + T_{AMB}$$

Layout

The suggested PCB layout for the AAT2148 is shown in Figures 2, 3, and 4. The following guidelines should be used to help ensure a proper layout.

- 1. The input capacitor (C1) should connect as closely as possible to $V_{\rm IN}$ (Pins 9-12) and PGND (Pins 1-3).
- 2. C2 and L1 should be connected as closely as possible. The connection of L1 to the LX pin should be as short as possible.
- 3. The feedback trace or FB pin (Pin 4) should be separate from any power trace and connect as closely as possible to the load point. Sensing along a high-current load trace will degrade DC load regulation. The external feedback resistors should be placed as closely as possible to the FB pin (Pin 4) to minimize the length of the high impedance feedback trace.
- 4. The resistance of the trace from the load return to PGND (Pins 1-3) should be kept to a minimum. This will help to minimize any error in DC regulation due to differences in the potential of the internal signal ground and the power ground.

Step-Down Converter Design Example

Specifications

 $V_{\text{O}}~=1.8V$ @ 1A (adjustable using 0.6V version), Pulsed Load $\Delta I_{\text{LOAD}}=300\text{mA}$

 $V_{IN} = 2.7V \text{ to } 4.2V \text{ (3.6V nominal)}$

 $F_s = 2MHz$

 $T_{AMB} = 85$ °C

1.8V Output Inductor

L1 =
$$3\frac{\mu s}{A} \cdot V_{O1} = 3\frac{\mu s}{A} \cdot 1.8V = 5.4\mu H \text{ (use 4.7}\mu H; see Table 1)}$$

For Coilcraft inductor SD3118, 4.7 μ H, DCR = 162m Ω .

$$\Delta I_{L1} = \frac{V_O}{L1 \cdot F_S} \cdot 1 - \frac{V_O}{V_{IN}} = \frac{1.8V}{4.7 \mu H \cdot 2.0 MHz} \cdot \left(1 - \frac{1.8V}{4.2V}\right) = 109 mA$$

$$I_{PKL1} = I_{O} + \frac{\Delta I_{L1}}{2} = 1A + 0.055A = 1.055A$$

$$P_{1,1} = I_0^2 \cdot DCR = 1A^2 \cdot 162m\Omega = 162mW$$

1.8V Output Capacitor

 $V_{DROOP} = 0.1V$

$$C_{\text{OUT}} = \frac{3 \cdot \Delta I_{\text{LOAD}}}{V_{\text{DROOP}} \cdot F_{\text{S}}} = \frac{3 \cdot 0.3 \text{A}}{0.1 \text{V} \cdot 2.0 \text{MHz}} = 4.5 \mu \text{F}; \text{ use } 4.7 \mu \text{F}$$

$$I_{RMS} = \frac{1}{2 \cdot \sqrt{3}} \cdot \frac{(V_O) \cdot (V_{IN(MAX)} - V_O)}{L1 \cdot F \cdot V_{IN(MAX)}} = \frac{1}{2 \cdot \sqrt{3}} \cdot \frac{1.8 \text{V} \cdot (4.2 \text{V} - 1.8 \text{V})}{4.7 \mu \text{H} \cdot 2.0 \text{MHz} \cdot 4.2 \text{V}} = 32 \text{mArms}$$

$$P_{esr} = esr \cdot I_{RMS}^2 = 5m\Omega \cdot (32mA)^2 = 6\mu W$$

Input Capacitor

Input Ripple $V_{PP} = 30mV$

$$C_{IN} = \frac{1}{\left(\frac{V_{PP}}{I_{O}} - ESR\right) \cdot 4 \cdot F_{S}} = \frac{1}{\left(\frac{30mV}{1A} - 5mW\right) \cdot 4 \cdot 2.0MHz} = 5\mu F; \text{ use } 4.7\mu F$$

$$I_{RMS} = \frac{I_O}{2} = 0.5 Arms$$

$$P = ESR \cdot I_{RMS}^2 = 5m\Omega \cdot (0.5A)^2 = 1.25mW$$

AAT2148 Losses

$$\begin{split} P_{TOTAL} &= \frac{I_{O}^{2} \cdot (R_{DSON(HS)} \cdot V_{O} + R_{DSON(LS)} \cdot [V_{IN} - V_{O}])}{V_{IN}} \\ &+ (t_{sw} \cdot F \cdot I_{O} + I_{Q}) \cdot V_{IN} \\ \\ &= \frac{1^{2} \cdot (0.35\Omega \cdot 1.8V + 0.3\Omega \cdot [4.2V - 1.8V])}{4.2V} \end{split}$$

$$\mathsf{T}_{\mathsf{J}(\mathsf{MAX})} = \mathsf{T}_{\mathsf{AMB}} + \Theta_{\mathsf{JA}} \cdot \mathsf{P}_{\mathsf{LOSS}} = 85^{\circ}\mathsf{C} + (50^{\circ}\mathsf{C/W}) \cdot 363 \mathsf{mW} = 103.2^{\circ}\mathsf{C}$$

+ $(5ns \cdot 2.0MHz \cdot 1A + 70\mu A) \cdot 4.2V = 363mW$

| Adjustable Version (0.6V device) V _{ουτ} (V) | R2 = 59kΩ R1 (kΩ) | $R2 = 221k\Omega^1$ $R1 (k\Omega)$ | L1 (µH) |
|---|----------------------------|------------------------------------|---------|
| 0.8 | 19.6 | 75.0 | 2.2 |
| 0.9 | 29.4 | 113 | 2.2 |
| 1.0 | 39.2 | 150 | 2.2 |
| 1.1 | 49.9 | 187 | 2.2 |
| 1.2 | 59.0 | 221 | 2.2 |
| 1.3 | 68.1 | 261 | 2.2 |
| 1.4 | 78.7 | 301 | 4.7 |
| 1.5 | 88.7 | 332 | 4.7 |
| 1.8 | 118 | 442 | 4.7 |
| 1.85 | 124 | 464 | 4.7 |
| 2.0 | 137 | 523 | 6.8 |
| 2.5 | 187 | 715 | 6.8 |
| 3.3 | 267 | 1000 | 6.8 |
| Fixed Version V _{ουτ} (V) | R2, R4 Not Used R1 (kΩ) | | L1 (µH) |
| 0.6-3.3V | | 0 | 4.7 |

Table 3: Evaluation Board Component Values.

| Manufacturer | Part Number | Inductance (µH) | Saturation Current (A) | DCR (Ω) | Size (mm) LxWxH | Туре |
|--------------|-----------------|-----------------|---------------------------|---------|--------------------|----------|
| | CDRH3D16/HP-2R2 | 2.2 | 1.75 | 47 | 4.0x4.0x1.8 | Shielded |
| Sumida | CDRH5D16-4R7 | 4.7 | 2.15 | 51.3 | 5.8x5.8x1.8 | Shielded |
| | CDRH5D16-6R8 | 6.8 | 1.8 | 64.7 | 5.8x5.8x1.8 | Shielded |
| | LQH3NPN2R2NG0 | 2.2 | 1.25 | 73 | 3.0x3.0x1.4 | Shielded |
| Murata | LQH32PN2R2NN0 | 2.2 | 1.55 | 76 | 3.2x2.7x1.55 | Shielded |
| | LQH32PN4R7NN0 | 4.7 | 1.0 | 180 | 3.2x2.7x1.55 | Shielded |
| | SD3118-2R2-R | 2.2 | 2.0 | 74 | 3.1x3.1x1.8 | Shielded |
| Coilcraft | SD3118-4R7-R | 4.7 | 1.31 | 162 | 3.1x3.1x1.8 | Shielded |
| | SD3118-6R8-R | 6.8 | 1.12 | 232 | 3.1x3.1x1.8 | Shielded |

Table 4: Typical Surface Mount Inductors.

| Manufacturer | Part Number | Value | Voltage | Temp. Co. | Case |
|--------------|-------------------|-------|---------|-----------|------|
| | GRM219R61A475KE19 | 4.7µF | 10V | X5R | 0805 |
| Murata | GRM21BR60J106KE19 | 10μF | 6.3V | X5R | 0805 |
| | GRM21BR60J226ME39 | 22µF | 6.3V | X5R | 0805 |

Table 5: Surface Mount Capacitors.

^{1.} For reduced quiescent current, R2 and R4 = $221k\Omega$.

Ordering Information

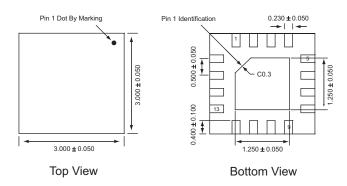
| Output Voltage ¹ | Package | Marking ² | Part Number (Tape and Reel) ³ |
|-----------------------------|----------|----------------------|--|
| Adj ≥ 0.6 | QFN33-16 | 6VXYY | AAT2148IVN-0.6-T1 |

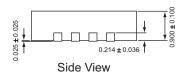


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Package Information

QFN33-16





All dimensions in millimeters.

- 1. Contact Sales for other voltage options.
- 2. XYY = assembly and date code.
- 3. Sample stock is typically held on part numbers listed in **BOLD**.

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