## ST2S08B

## Dual synchronous rectification, 1.5 A, 1.5 MHz adjustable step-down switching regulator

## Datasheet - production data

## Features

■ Step-down current mode PWM (1.5 MHz) DCDC converter

- Adjustable output voltage from 0.8 V

■ 2 \% DC output voltage tolerance

- Synchronous rectification
- Integrated current limit
- Inhibit function
- Soft-start for start delay of $800 \mu \mathrm{~s}$ typ.

■ Typical efficiency: $>80 \%$ at $\mathrm{V}_{\text {OUT }}=1.2 \mathrm{~V}$
■ 1.5 A output current capability
■ Non-switching quiescent current: max 1.5 mA over temperature range

- $\mathrm{R}_{\mathrm{DS}(\mathrm{ON})} 150 \mathrm{~m} \Omega$ (typ.)
- Uses tiny capacitors and inductors
- Available in QFN12L (4 x 4 mm )


## Description

The ST2S08B is a dual step-down DC-DC converter optimized for powering low-voltage digital cores in ODD applications and, generally, to replace the high current linear solution when the power dissipation may cause a high heating of the application environment. It provides up to 1.5 A over an input voltage range of 3 V to 5.5 V . A high switching frequency of 1.5 MHz allows the use of tiny surface-mounted components as well as a resistor divider to set the output voltage value. Only an inductor and two capacitors are required. A low output ripple is guaranteed by the current mode PWM topology and the utilization of low ESR SMD ceramic capacitors. The device is thermally protected and current limited. The


ST2S08B is available in the QFN12L (4 x 4 mm) package.

Table 1. Device summary

| Order code | Package | Packaging |
| :---: | :---: | :---: |
| ST2S08BPQR | QFN12L $(4 \times 4 \mathrm{~mm})$ | Tape and reel |

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## 1 Diagram

Figure 1. Schematic diagram


* Not available on the ST2S08B version.


## 2 Pin configuration

Figure 2. Pin connections (top view)


Table 2. Pin description

| ${\text { Pin } \boldsymbol{n}^{\circ}}{ }^{\text {Name }}$ | Function |  |
| :---: | :---: | :--- |
| 1 | HV | Programing pin. It must be floating or connected to GND. |
| 2 | FB2 | Feedback voltage |
| 3 | GND2 | Power ground |
| 4 | SW2 | Switching pin |
| 5 | VIN_SW | Power input voltage pin |
| 6 | SW1 | Switching pin |
| 7 | GND1 | Power ground |
| 8 | FB1 | Feedback voltage/output voltage |
| 9 | NC | Not connect |
| 10 | INH | Inhibit pin: <br> - High device on <br> - Low device off |
| 11 | VIN_A | Supply for analog circuit |
| 12 | GND_A | System ground |

## 3 Maximum ratings

Table 3. Absolute maximum ratings

| Symbol | Parameter | Value | Unit |
| :---: | :--- | :---: | :---: |
| $\mathrm{V}_{\text {IN_SW }}$ | Positive power supply voltage | -0.3 to 7 | V |
| $\mathrm{~V}_{\text {IN_A }}$ | Positive power supply voltage | -0.3 to 7 | V |
| $\mathrm{~V}_{\text {INH }}$ | Inhibit voltage | -0.3 to 7 | V |
| SWITCH voltage | Max. voltage of output pin | -0.3 to 7 | V |
| $\mathrm{~V}_{\text {FB1,2 }}$ | Feedback voltage/output voltage | -0.3 to 2.5 | V |
| Current into $\mathrm{V}_{\text {FB }}$ pin | Common mode input voltage | +1 to -1 | mA |
| $\mathrm{~T}_{\mathrm{J}}$ | Max junction temperature | 150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {STG }}$ | Storage temperature range | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {LEAD }}$ | Lead temperature (soldering) 10 sec. | 300 | ${ }^{\circ} \mathrm{C}$ |

Note: $\quad$ Absolute maximum ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied.

Table 4. Thermal data

| Symbol | Parameter | Value | Unit |
| :---: | :--- | :---: | :---: |
| $\mathrm{R}_{\text {thJC }}$ | Thermal resistance junction-case | 10 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\mathrm{R}_{\text {thJA }}$ | Thermal resistance junction-ambient | 60 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

Table 5. ESD performance

| Symbol | Parameter | Test conditions | Value | Unit |
| :---: | :--- | :--- | :---: | :---: |
| ESD | ESD protection voltage | HBM-DH11C | 4 | kV |

## 4 Electrical characteristics

$\mathrm{V}_{\mathrm{IN} \_S W}=\mathrm{V}_{\mathrm{IN} \text { A }}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{O} 1,2}=1.2 \mathrm{~V}, \mathrm{C}_{1}=4.7 \mu \mathrm{~F}, \mathrm{C}_{2}=\mathrm{C}_{3}=22 \mu \mathrm{~F}, \mathrm{~L} 1=\mathrm{L} 2=3.3 \mu \mathrm{H}$,
$T_{J}=-30$ to $125{ }^{\circ} \mathrm{C}$, unless otherwise specified. Typical values refer to $25^{\circ} \mathrm{C}$.
Table 6. Electrical characteristics

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{FB}_{1,2}$ | Feedback voltage |  | 784 | 800 | 816 | mV |
| $\mathrm{I}_{\text {FB1,2 }}$ | $V_{\text {FB }}$ pin bias current | $V_{F B}=1 \mathrm{~V}$ |  |  | 600 | nA |
| $\mathrm{I}_{\mathrm{Q}}$ | Quiescent current | $\mathrm{V}_{\mathrm{INH}}>1.2 \mathrm{~V}, \mathrm{~V}_{\mathrm{FB}}=1 \mathrm{~V}$ |  |  | 1.5 | mA |
|  |  | $\mathrm{V}_{\text {INH }}=\mathrm{GND}$ |  | 20 |  | $\mu \mathrm{A}$ |
| $\mathrm{l}_{01,2}$ | Output current | $\begin{aligned} & \mathrm{V}_{\mathrm{IN}}=3.0 \text { to } 5.5 \mathrm{~V}^{(1)}, \\ & \mathrm{T}_{\mathrm{J}}=-30 \text { to } 85^{\circ} \mathrm{C} \end{aligned}$ | 1.5 |  |  | A |
| $\mathrm{I}_{\mathrm{MIN}}$ | Minimum output current |  | 1 |  |  | mA |
| $\mathrm{V}_{\text {INH }}$ | Inhibit threshold | $3.0 \mathrm{~V}<\mathrm{V}_{\text {IN }}<5 \mathrm{~V}$ | 1.2 |  |  | V |
|  |  | $3.0 \mathrm{~V}<\mathrm{V}_{\text {IN }}<5.5 \mathrm{~V}$ | 1.3 |  |  |  |
|  |  | Device OFF |  |  | 0.4 |  |
| $\mathrm{I}_{\text {INH1,2 }}$ | Inhibit pin current |  |  |  | 2 | $\mu \mathrm{A}$ |
| $\begin{gathered} \% \mathrm{~V}_{\mathrm{O} 1,2} \\ \Delta \mathrm{~V}_{\mathrm{IN}} \end{gathered}$ | Reference line regulation | $3.0 \mathrm{~V}<\mathrm{V}_{\text {IN }}<5.5 \mathrm{~V}$ |  | 0.04 |  | $\begin{aligned} & \% \mathrm{~V}_{\mathrm{O}} \\ & \mathrm{~V}_{\mathrm{IN}} \end{aligned}$ |
| $\Delta \mathrm{V}_{\text {O1,2 }}$ | Reference load regulation | $10 \mathrm{~mA}<\mathrm{l}_{\mathrm{O}}<1.5 \mathrm{~A}$ |  | 10 |  | mV |
| PWM fs | PWM switching frequency | $\mathrm{V}_{\mathrm{FB}}=0.7 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | 1.2 | 1.5 | 1.8 | MHz |
| $\mathrm{D}_{\text {MAX }}$ | Maximum duty cycle | $\mathrm{V}_{\mathrm{FB}}=0.7 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ | 85 | 94 |  | \% |
| $I_{\text {SWL }}$ | Switching current limitation | (2) |  | 2 |  | A |
| ILKN | NMOS leakage current | $\mathrm{V}_{\mathrm{FB}}=0.9 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  | 0.1 |  | $\mu \mathrm{A}$ |
| $\mathrm{I}_{\text {LKP }}$ | PMOS leakage current | $\mathrm{V}_{\mathrm{FB}}=0.9 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$ |  | 0.1 |  | $\mu \mathrm{A}$ |
| $\mathrm{R}_{\text {DSon }} \mathrm{N}$ | NMOS switch on resistance | $\mathrm{I}_{\text {SW }}=250 \mathrm{~mA}$ |  | 0.15 | 0.3 | $\Omega$ |
| $\mathrm{R}_{\text {DSon }}-\mathrm{P}$ | PMOS switch on resistance | $\mathrm{I}_{\text {Sw }}=250 \mathrm{~mA}$ |  | 0.2 | 0.4 | $\Omega$ |
| $\eta$ | Efficiency | $\mathrm{I}_{\mathrm{O}}=20 \mathrm{~mA}$ to 100 mA |  | 75 |  | \% |
|  |  | $\mathrm{I}_{\mathrm{O}}=100 \mathrm{~mA}$ to 1.5 A |  | 80 |  | \% |
| $\mathrm{T}_{\text {SHDN }}$ | Thermal shutdown |  |  | 150 |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{HYS}}$ | Thermal shutdown hysteresis |  |  | 15 |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{I}_{\mathrm{SC}}-\mathrm{V}_{\text {IN }}$ | Short-circuit $\mathrm{V}_{\text {IN }}$ range ${ }^{(2)}$ | Output short-circuit to ground | 3 |  | 5.3 | V |

1. $\mathrm{V}_{\mathrm{O}}=90 \%$ of nominal value.
2. Guaranteed by design, but not tested in production.

## 5 Typical application

Figure 3. Application circuit


Note: $\quad$ R1, R2 and R3, R4 are calculated according to the following equations:
$-V_{O 1}=V_{F B 1}(1+R 1 / R 2)$
$-V_{O 2}=V_{F B 2}(1+R 3 / R 4)$

## 6 Typical performance characteristics

Figure 4. Feedback voltage vs. temperature
Figure 5. Efficiency vs. output current 1


Figure 6. Efficiency vs. output current 2


Figure 7. Switching frequency vs. temperature


Figure 8. Duty cycle vs. temperature


Figure 9. Inhibit threshold vs. temperature


Figure 10. Switching current limitation vs. temperature


Figure 12. Inhibit transient


## 7 General information

The ST2S08B is a dual adjustable current mode PWM step-down DC-DC converter.
It is a complete 1.5 A switching regulator with internal compensation that eliminates the need for additional components.

The constant frequency, current mode, PWM architecture and stable operation with ceramic capacitors, results in low, predictable output ripple.

To clamp the error amplifier reference voltage, a soft-start control block, generating a voltage ramp, has been implemented. Other circuits fitted to the device protection are the thermal shut-down block, which turns off the regulator when the junction temperature exceeds $150{ }^{\circ} \mathrm{C}$ (typ.), and cycle-by-cycle switching current limiting.

Operation of the device requires few components: 2 inductors, 3 capacitors, and a resistor divider. The chosen inductor must be capable of not saturating at the peak current level. Its value should be selected keeping in mind that a large inductor value increases the efficiency at low output current and reduces output voltage ripple, while a smaller inductor can be chosen when it is important to reduce package size and total application cost.

Finally, the ST2S08 has been designed to work properly with X5R or X7R SMD ceramic capacitors both at input and at output. These types of capacitors, due to their very low series resistance (ESR), minimize the output voltage ripple. Other low ESR capacitors can be used, according to the needs of the application, without compromising the correct functioning of the device.

## 8 Application information

### 8.1 Introduction

The following technical information is used for estimating typical external component characteristics using standard equations. Nevertheless, it is strongly recommended to validate the suitability of external components to the application requirements by thoroughly testing any solution at bench level on a real evaluation circuit.

### 8.2 Programming the output voltage

The output voltage for both channels can be adjusted from 0.8 V up to $85 \%$ of the input voltage value by connecting a resistor divider between $\mathrm{V}_{\mathrm{O}}$ and GND, the middle point of the divider must be connected to the feedback (FB) pin, as shown in Figure 3.

The resistor divider must be chosen according to the following equations:

## Equation 1

$\mathrm{V}_{\mathrm{O} 1}=\mathrm{V}_{\mathrm{FB} 1} \times\left(1+\frac{\mathrm{R} 1}{\mathrm{R} 2}\right)$

## Equation 2

$\mathrm{V}_{\mathrm{O} 2}=\mathrm{V}_{\mathrm{FB} 2} \times\left(1+\frac{\mathrm{R} 3}{\mathrm{R} 4}\right)$
Using a resistor with a value in the range of $1 \mathrm{k} \Omega$ to $50 \mathrm{k} \Omega$ is recommended. Lower values are also suitable, but increase current consumption.

### 8.3 Inductor selection

The inductor is the key passive component for switching converters.
The critical inductance values can then be obtained according to the following formulas:

## Equation 3

$L_{\text {MIN }}=\frac{V_{O} \times\left(V_{\text {IN_MAX }}-V_{O}\right)}{V_{\text {IN_MAX }} \times F_{S W} \times \Delta \mathrm{I}_{\mathrm{L}}}$
$F_{S W}=$ switching frequency
$\Delta \mathrm{I}_{\mathrm{L}}=$ the peak-to-peak inductor ripple current. As a rule of thumb, the peak-to-peak ripple can be set at $20 \%-40 \%$ of the output current.

The peak current of the inductor can be calculated as:

## Equation 4

$I_{\text {PEAK }}=\left(\mathrm{l}_{\mathrm{O}} / 0.8\right)+\frac{\mathrm{V}_{\mathrm{O}} \times\left(\mathrm{V}_{\text {IN_MAX }}-\mathrm{V}_{\mathrm{O}}\right)}{2 \times \mathrm{V}_{\text {IN_MAX }} \times \mathrm{F}_{\text {SW }} \times \mathrm{L}}$
In addition to the inductance value, in order to avoid saturation, the maximum saturation current of the inductor must be higher than that of the IPEAK.

### 8.4 Input and output capacitor selection

It is recommended to use ceramic capacitors with X5R or X7R dielectric and low ESR as input and output capacitors, in order to filter any disturbance present in the input line and to obtain stable operation. The output capacitor is very important for satisfying the output voltage ripple requirements.

The output voltage ripple ( $\mathrm{V}_{\mathrm{O}}$ RIPPLE $)$, in continuous mode, for the step-down channel, can be calculated as:

## Equation 5

$\mathrm{V}_{\mathrm{O} \_ \text {RIPPLE }}=\Delta_{\mathrm{L}} \times\left[E S R+\frac{1}{8 \times C_{\text {OUT }} \times F_{S W}}\right]$
where $\Delta I_{L}$ is the ripple current and $F_{S W}$ is the switching frequency.
The use of ceramic capacitors with voltage ratings in the range higher than 1.5 times the maximum input or output voltage is recommended.

### 8.5 Layout considerations

Due to the high switching frequency and peak current, the layout is an important design step for all switching power supplies. Important parameters (efficiency, output voltage ripple, switching noise immunity, etc.) can be affected if the PCB layout is not designed paying close attention to the following DC-DC general layout rules:

- Short, wide traces must be implemented for mains current and for power ground paths. The input capacitor must be placed as close as possible to the IC pins as well as the inductor and output capacitor.
- The FB pin connection to the external resistor divider is a high impedance node, so interference can be minimized by placing the routing of the feedback node as far as possible from the high current paths. To reduce pick-up noise, the resistor divider must be placed very close to the device.
- A common ground node minimizes ground noise.
- The exposed pad of the package must be connected to the common ground node.

Moreover, the exposed pad ground connection must be properly designed in order to facilitate heat dissipation from the exposed pad to the ground layer using PCB vias.

## $9 \quad$ Package mechanical data

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK ${ }^{\circledR}$ packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions, and product status are available at: www.st.com. ECOPACK is an ST registered trademark.

## QFN12L (4x4) mechanical data

| Dim. | mm. |  |  | inch. |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A | 0.80 | 0.90 | 1.00 | 0.031 | 0.035 | 0.039 |
| A1 |  | 0.02 | 0.05 |  | 0.001 | 0.002 |
| A3 |  | 0.20 |  |  | 0.008 |  |
| b | 0.25 | 0.30 | 0.35 | 0.010 | 0.012 | 0.014 |
| D | 3.90 | 4.00 | 4.10 | 0.154 | 0.157 | 0.161 |
| D2 | 2.00 | 2.15 | 2.25 | 0.079 | 0.085 | 0.089 |
| E | 3.90 | 4.00 | 4.10 | 0.154 | 0.157 | 0.161 |
| E2 | 2.00 | 2.15 | 2.25 | 0.079 | 0.085 | 0.089 |
| e |  | 0.80 |  |  | 0.031 |  |
| L | 0.45 | 0.55 | 0.65 | 0.018 | 0.022 | 0.026 |



Tape \& reel QFNxx/DFNxx (4x4) mechanical data

| Dim. | mm. |  |  | inch. |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Min. | Typ. | Max. | Min. | Typ. | Max. |
| A |  |  | 330 |  |  | 12.992 |
| C | 12.8 |  | 13.2 | 0.504 |  | 0.519 |
| D | 20.2 |  |  | 0.795 |  |  |
| N | 99 |  | 101 | 3.898 |  | 3.976 |
| T |  |  | 14.4 |  |  | 0.567 |
| Ao |  | 4.35 |  |  | 0.171 |  |
| Bo |  | 4.35 |  |  | 0.171 |  |
| Ko |  | 1.1 |  |  | 0.043 |  |
| Po |  | 4 |  |  | 0.157 |  |
| P |  | 8 |  |  | 0.315 |  |



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Figure 13. QFN12L (4 x 4 mm ) footprint recommended data


## 10 Revision history

Table 7. Document revision history

| Date | Revision | Changes |
| :---: | :---: | :--- |
| 30-Nov-2010 | 1 | Initial release. |
| 18-May-2012 | 2 | Modified max $1.0 \mathrm{~mA}==>\max 1.5 \mathrm{~mA}$ : Features on page 1. |

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