

TSV791, TSV792

Datasheet

High bandwidth (50 MHz) low offset (200 μ V) rail-to-rail 5 V op-amp



TSV791 SOT23-5



TSV792 MiniSO8

TSV792

DFN8 2x2 mm



TSV792 SO8

Features

- Gain bandwidth product 50 MHz, unity gain stable
- Slew rate 30 V/µs
- Low input offset voltage 50 µV typ., 200 µV max.
- Low input bias current: 2 pA typ.
- Low input voltage noise density 6.5 nV/√Hz @ 10 kHz
- Wide supply voltage range: 2.2 V to 5.5 V
- Rail-to-rail input and output
- Extended temperature range: 40 °C to +125 °C
- Automotive grade version available
- Benefits:
 - Accuracy of measurement virtually unaffected by noise or input bias current
 - Signal conditioning for high frequencies

Applications

- High bandwidth low-side and high-side current sensing
- Photodiode transimpedance amplification
- A/D converters input buffers
- Power management in solar-powered systems
- Power management in automotive applications

Description

The TSV791 and TSV792 are single and dual 50 MHz-bandwidth unity-gain-stable amplifiers. The rail-to-rail input stage and the slew rate of 30 V/µs make the TSV791 and TSV792 ideal for low-side current measurement. The excellent accuracy provided by maximum input voltage of 200 µV allows amplifying accurately small-amplitude input signal. The TSV79x can operate from a 2.2 V to 5.5 V single supply; it can typically handle an output capacitor up to 1 nF and is fully specified on a load of 22 pF, therefore allowing easy usage as A/D converters input buffer.

N	laturity status link			
	TSV791, TSV792			
Related products				
TSZ181 TSZ182	Zero drift amplifiers with more power savings (3 MHz)			
TSB712	36 V high-bandwidth amplifiers (6 MHz)			
TSB7192	36 V high-bandwidth amplifiers (20 MHz)			

1 Pin description

1.1 TSV791 single operational amplifier

Figure 1. Pin connections (top view)

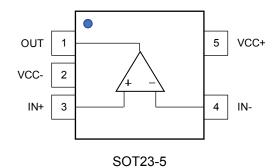


Table 1. Pin description

Pin n°	Pin name	Description
1	OUT	Output channel
2	VCC-	Negative supply voltage
3	IN+	Non-inverting input channel
4	IN-	Inverting input channel
5	VCC+	Positive supply voltage

1.2 TSV792 dual operational amplifier

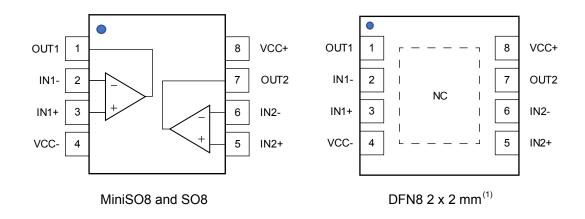


Figure 2. Pin connections (top view)

1. The exposed pad of the DFN8 2x2 can be connected to VCC- or left floating.

Pin n°	Pin name	Description
1	OUT1	Output channel 1
2	IN1-	Inverting input channel 1
3	IN1+	Non-inverting input channel 1
4	VCC-	Negative supply voltage
5	IN2+	Non-inverting input channel 2
6	IN2-	Inverting input channel 2
7	OUT2	Output channel 2
8	VCC+	Positive supply voltage

Table 2. Pin description

2 Absolute maximum ratings and operating conditions

Symbol	Parameter ⁽¹⁾	Value	Unit
V _{CC}	Supply voltage	6	V
V _{id}	Input voltage differential (V _{IN+} - V _{IN-}) $^{(2)}$	±V _{CC}	V
V _{in}	Input voltage	(V_{CC-}) - 0.2 to (V_{CC+}) + 0.2	V
l _{in}	Input current	±10	mA
T _{stg}	Storage temperature	-65 to +150	°C
Тj	Maximum junction temperature	150	°C
	Thermal resistance junction-to-ambient		
	SOT23-5	250	
R _{th-ja} ⁽³⁾	DFN8 2x2	57	°C / W
	MiniSO8	127	
	SO8	125	
	HBM: human body model (industrial grade) (4)	4	kV
ESD	HBM: human body model (automotive grade) ⁽⁵⁾	4	kV
	CDM: charged device model ⁽⁶⁾	1	kV

Table 3. Absolute maximum ratings

1. All voltage values are with respect to the VCC- pin, unless otherwise specified.

2. The maximum input voltage differential value may be extended to the condition that the input current is limited to ±10 mA.

3. R_{th-ja} is a typical value, obtained with PCB according to JEDEC 2s2p without vias.

4. Human body model: HBM test according to the standard ESDA-JS-001-2017.

5. Human body model: HBM test according to the standard AEC-Q100-002.

6. Charged device model: the CDM test is done according to the standard AEC-Q100-011.

Table 4. Operating conditions

Symbol	Parameter	Value
V _{CC}	Supply voltage	2.2 V to 5.5 V
V _{icm}	Common mode input voltage range	V_{CC-} – 0.1 V to V_{CC+} + 0.1 V
T _{oper}	Operating free air temperature range	-40 °C to +125 °C

3 Electrical characteristics

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Table 5. Electrical characteristics at V_{CC} = 5 V, V_{icm} = V_{OUT} = V_{CC} / 2, T = 25 °C, R_L = 10 k Ω connected to V_{CC} / 2 and C_L = 22 pF (unless otherwise specified).

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
		DC performance				
M		T = 25 °C			± 200	
V _{io}	Input offset voltage	-40 °C ≤ T ≤ 125 °C			± 700	μV
ΔV _{io} /ΔT	Input offset voltage temperature drift (1)	-40 °C ≤ T ≤ 125 °C			± 5	µV/°C
ΔV_{io} ⁽²⁾	Input offset voltage long-term drift	T = 25 °C		750		nV/√mont
		T = 25 °C		2		
I _{ib} ⁽³⁾	Input bias current	-40 °C ≤ T ≤ 125 °C		75		рА
. (2)		T = 25 °C		1		
l _{io} ⁽³⁾	Input offset current	-40 °C ≤ T ≤ 125 °C		20		рА
		V_{CC-} + 200 mV $\leq V_{OUT} \leq V_{CC+}$ - 200 mV T = 25 °C	110	133		
		$V_{CC-} + 200 \text{ mV} \le V_{OUT} \le V_{CC+} - 200 \text{ mV}$	00	110		
	Open loop gain	-40 °C ≤ T ≤ 125 °C	90	113		
A _{VD}		R _L = 600 Ω, T = 25 °C	105	400		dB
		$V_{CC-} + 300 \text{ mV} \leq V_{OUT} \leq V_{CC+} - 300 \text{ mV}$		132		
		R_L = 600 Ω , -40 °C ≤ T ≤ 125 °C	85			
		V_{CC-} + 300 mV $\leq V_{OUT} \leq V_{CC+}$ - 300 mV				
		$V_{CC-} \le V_{icm} \le V_{CC+} - 2 V, T = 25 °C$	100	120		
CMR1		$V_{CC-} \le V_{iCM} \le V_{CC+} - 2 V,$	00	400		dB
	Common-mode rejection ratio	-40 °C ≤ T ≤ 125 °C	90	120		
	20.log (ΔV _{io} /ΔV _{icm})	$V_{CC-} \le V_{icm} \le V_{CC+}, T = 25 \ ^{\circ}C$	80	100		
CMR2		$V_{CC-} \le V_{iCm} \le V_{CC+},$	76	02		dB
		-40 °C ≤ T ≤ 125 °C	76	92		
		$2.2 \text{ V} \le \text{V}_{\text{CC}} \le 5.5 \text{ V}, \text{ T} = 25^{\circ}\text{C},$	90	109		
	Supply-voltage rejection ratio 20.log	V _{icm} = 0 V	90	109		dD
SVR	$(\Delta V_{io}/\Delta V_{CC})$	$2.2 \text{ V} \le \text{V}_{\text{CC}} \le 5.5 \text{ V},$	00	400		dB
		-40 °C \leq T \leq 125 °C, V _{icm} = 0 V	90	108		
Maria	High level output voltage drop	T = 25°C			20	
V _{OH}	$(V_{OH} = V_{CC^+} - V_{OUT})$	-40 °C ≤ T ≤ 125 °C			25	mV
Ve	Low level output voltage drop	T = 25 °C			10	mV
V _{OL}	$(V_{OL} = V_{OUT})$	-40 °C ≤ T ≤ 125 °C			15	IIIV
		OUT connected to V _{CC+} , T = 25 °C	60	70		
	I _{SINK}	OUT connected to V _{CC+} ,	25			
I _{OUT}		-40 °C ≤ T ≤ 125 °C	35			mA
	ISOURCE	OUT connected to V_{CC-} , T = 25°C	50	60		



Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
I _{OUT}	ISOURCE	OUT connected to V _{CC-} ,	40			mA
1001	SURCE	-40 °C ≤ T ≤ 125 °C	40			ШA
امم	Supply surrent (by exerctional emplifier)	T = 25 °C		5.5	6	
I _{CC}	Supply current (by operational amplifier)	-40 °C ≤ T ≤ 125 °C			6	mA
	·	AC performance				
GBP	Gain bandwidth product	R_L = 10 k Ω , C_L = 22 pF	35	50		MHz
0.0	Slew rate	R_L = 10 k Ω , C_L = 22 pF, A_V = 1 V/V,		30		\//h : -
SR		10 % to 90 %		30		V/µs
0.5	Cross talk	V_{OUT} = 4 V_{pp} , R_L = 10 k Ω ,		126		15
CR		A _V = +101, f = 1 kHz				dB
Φm	Phase margin	R _L = 10 kΩ		53		degrees
		f = 10 Hz		140		
en	Input voltage noise density	f = 100 Hz		43		nV/√Hz
		f = 10 kHz		6.5		
en p-p	Input noise voltage	0.1 Hz ≤ f ≤ 10 Hz		9		μV _{pp}
C		Differential		6.3		~ Г
C _{in}	Input capacitance	Input capacitance Common mode		1.6		pF

1. See Section 5.2 Input offset voltage drift overtemperature.

2. See Section 5.3 Long term input offset voltage drift.

3. Guaranteed by characterization.

Table 6. Electrical characteristics at V_{CC} = 3.3 V, V_{icm} = V_{OUT} = V_{CC} / 2, T = 25 °C, R_L = 10 k Ω connected to V_{CC} / 2 and C_L = 22 pF (unless otherwise specified).

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit	
		DC performance					
		V _{icm} = 0 V, T = 25 °C			± 200		
V _{io}	Input offset voltage	V _{icm} = 0 V, -40 °C ≤ T ≤ 125 °C			± 700	μV	
$\Delta V_{io} / \Delta T^{(1)}$	Input offset voltage temperature drift	V _{icm} = 0 V, -40 °C ≤ T ≤ 125 °C			± 5	μV/°C	
		T = 25 °C		1.5			
l _{ib} ⁽²⁾	Input bias current	-40 °C ≤ T ≤ 125 °C		60		pА	
		T = 25 °C		1			
l _{io} ⁽²⁾	Input offset current	-40 °C ≤ T ≤ 125 °C		20		pА	
		V_{CC-} + 200 mV ≤ V_{OUT} ≤ V_{CC+} - 200 mV, T = 25 °C	105	130			
		$V_{CC_{-}}$ + 200 mV ≤ V_{OUT} ≤ $V_{CC_{+}}$ - 200 mV, -40 °C ≤ T ≤ 125 °C	90	113			
A_{VD}	Open loop gain	$R_{L} = 600 \Omega, T = 25 °C$				dB	
		V_{CC-} + 300 mV ≤ V_{OUT} ≤ V_{CC+} - 300 mV,	100	129			
		R_L = 600 Ω, -40 °C ≤ T ≤ 125 °C V _{CC-} + 300 mV ≤ V _{OUT} ≤ V _{CC+} - 300 mV	85	99			
CMR1	Common-mode rejection ratio 20.log $(\Delta V_{io}/\Delta V_{icm})$	$V_{CC-} \le V_{icm} \le V_{CC+} - 2 V, T = 25^{\circ}C$	95 116	116			
		$V_{CC-} \le V_{icm} \le V_{CC+} - 2 V,$ -40 °C ≤ T ≤ 125 °C	85	111		dB	
		$V_{CC-} \le V_{icm} \le V_{CC+}, T = 25 \text{ °C}$	77	97			
CMR2		$V_{CC-} \le V_{icm} \le V_{CC+},$ -40 °C ≤ T ≤ 125 °C	70	90		dB	
	High level output voltage drop	T = 25 °C			25		
V _{OH}	$(V_{OH} = V_{CC+} - V_{OUT})$	-40 °C ≤ T ≤ 125 °C			40	mV	
	Low level output voltage drop	T = 25 °C			15		
V _{OL}	$(V_{OL} = V_{OUT})$	-40 °C ≤ T ≤ 125 °C			30	mV	
		OUT connected to V_{CC+} , T = 25 °C	55	63			
	Isink	OUT connected to V_{CC^+} , -40 °C ≤ T ≤ 125 °C	35				
Ι _{ΟυΤ}		OUT connected to V _{CC-} , T = 25 °C	50	63		mA	
	ISOURCE	OUT connected to V_{CC-} , -40 °C ≤ T ≤ 125 °C	35				
		T = 25 °C		5.3	5.8		
Icc	Supply current (by operational amplifier)	-40 °C ≤ T ≤ 125 °C			5.8	mA	
		AC performance		1			
GBP	Gain bandwidth product	$R_{L} = 10 \text{ k}\Omega, C_{L} = 22 \text{ pF}$	35	50		MHz	



Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
SR	Slew rate	R_L = 10 kΩ, C_L = 22 pF, A_V = 1 V/V,		30		V/µs
ÖR		10 % to 90 %		00		v/µ5
CR	Cross talk	V_{OUT} = 4 V_{pp} , R_L = 10 k Ω , A_V = +101,		126		dB
CK	Closs taik	f = 1 kHz		120		UD
Φm	Phase margin	R _L = 10 kΩ		53		degrees
		f = 10 Hz		140		
en	Input voltage noise density	f = 100 Hz		43		nV/√Hz
		f = 10 kHz		6.5		1
C		Differential		6.3		ъĘ
C _{in}	Input capacitance	Common mode		1.6		pF

1. See Section 5.2 Input offset voltage drift overtemperature.

2. Guaranteed by characterization.

Table 7. Electrical characteristics at V_{CC} = 2.2 V, V_{icm} = V_{OUT} = V_{CC} / 2, T = 25 °C, R_L = 10 k Ω connected to V_{CC} / 2 and C_L = 22 pF (unless otherwise specified).

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit	
		DC performance					
		V _{icm} = 0 V, T = 25 °C		± 50	± 200		
V _{io}	Input offset voltage	V _{icm} = 0 V, -40 °C ≤ T ≤ 125 °C			± 700	μV	
$\Delta V_{io} / \Delta T^{(1)}$	Input offset voltage temperature drift	V _{icm} = 0 V, -40 °C ≤ T ≤ 125 °C			± 5	μV/°C	
		T = 25 °C		1			
l _{ib} ⁽²⁾	Input bias current	-40 °C ≤ T ≤ 125 °C		45		рA	
. (2)		T = 25 °C		1			
l _{io} ⁽²⁾	Input offset current	-40 °C ≤ T ≤ 125 °C		13		рА	
		V_{CC-} + 200 mV $\leq V_{OUT} \leq V_{CC+}$ - 200 mV, T = 25 °C	95	120			
		V_{CC-} + 200 mV ≤ V_{OUT} ≤ V_{CC+} - 200 mV, -40 °C ≤ T ≤ 125 °C	85	107			
		$R_{\rm L} = 600 \ \Omega,$					
A _{VD}	Open loop gain	V_{CC-} + 300 mV $\leq V_{OUT} \leq V_{CC+}$ - 300 mV, T = 25 °C	90	119	9	dB	
		R _L = 600 Ω,	80				
		V_{CC-} + 300 mV $\leq V_{OUT} \leq V_{CC+}$ - 300 mV		99			
		-40 °C ≤ T ≤ 125 °C					
	Common-mode rejection ratio 20.log $(\Delta V_{io}/\Delta V_{icm})$	$V_{CC-} \le V_{icm} \le V_{CC+}, T = 25 \text{ °C}$	73	94			
CMR		$V_{CC-} \le V_{icm} \le V_{CC+},$	67	85		dB	
		-40 °C ≤ T ≤ 125 °C	07	CO			
V _{OH}	High level output voltage drop	T = 25 °C			25	mV	
VОН	$(V_{OH} = V_{CC+} - V_{OUT})$	-40 °C ≤ T ≤ 125 °C			40	IIIV	
V _{OL}	Low level output voltage drop	T = 25 °C			15	mV	
♥OL	$(V_{OL} = V_{OUT})$	-40 °C ≤ T ≤ 125 °C			30	IIIV	
		OUT connected to V _{CC+} , T = 25 °C	55	62			
	Isink	OUT connected to V_{CC+} , -40 °C ≤ T ≤ 125 °C	35				
I _{OUT}		OUT connected to V _{CC-} , T = 25 °C	50	62		mA	
	I _{SOURCE}	OUT connected to V _{CC-} ,					
		-40 °C ≤ T ≤ 125 °C	35				
		V _{icm} = 0 V, T = 25 °C		5	5.5		
ICC	Supply current (by operational amplifier)	V _{icm} = 0 V, -40 °C ≤ T ≤ 125 °C			5.5	mA	
	1	AC performance	1				
GBP	Gain bandwidth product	R _L = 10 kΩ	35	50		MHz	
SR	Slew rate	R_L = 10 kΩ, A_V = 1 V/V, 10 % to 90 %		30		V/µs	
CR	Cross talk	$V_{OUT} = 4 V_{pp}, R_L = 10 k\Omega, A_V = +101,$		126		dB	

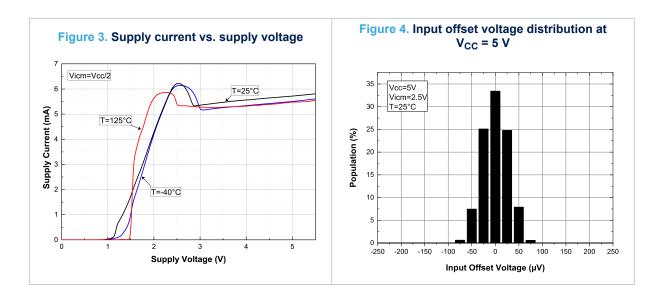


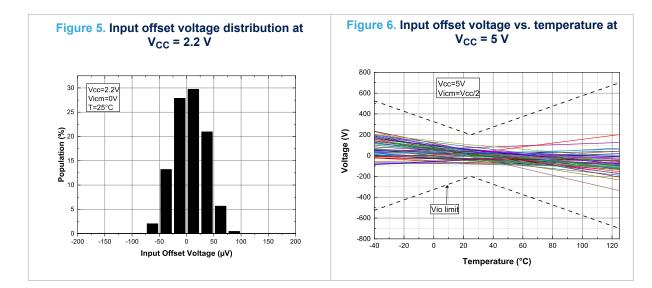
Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Φm	Phase margin	R _L = 10 kΩ		69		degrees
	Input voltage noise density	f = 10 Hz		250		
en		f = 100 Hz		94		nV/√Hz
		f = 10 kHz		15		
C _{in}	Input capacitance	Differential		6.3		pF
Cin		Common mode		1.6		pr

1. See Section 5.2 Input offset voltage drift overtemperature.

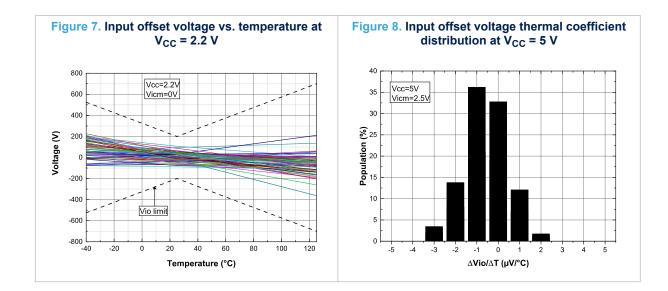
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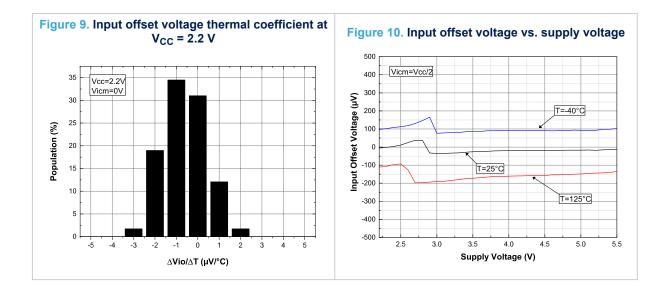
4 Typical performance characteristics

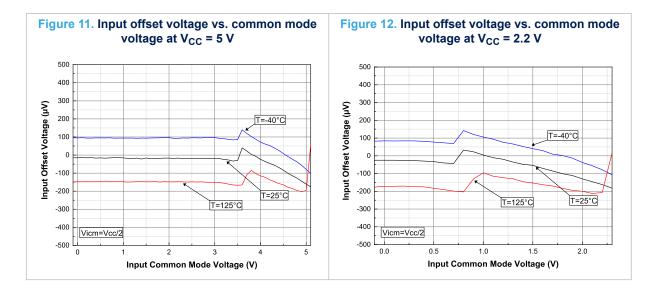


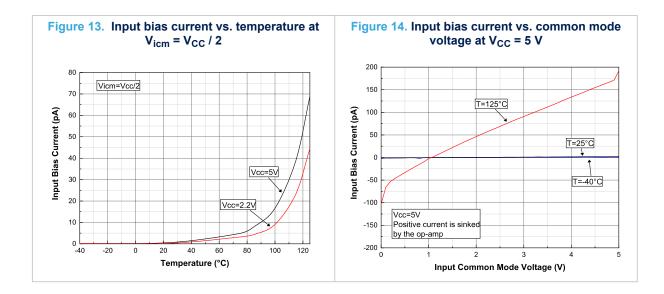


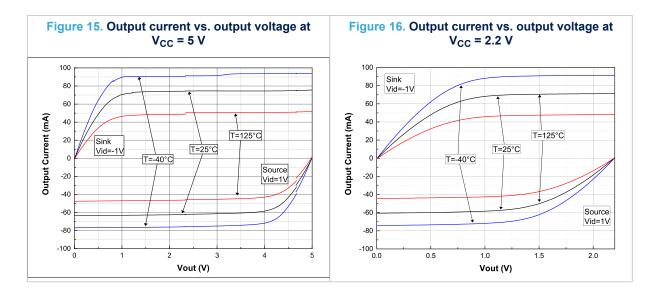
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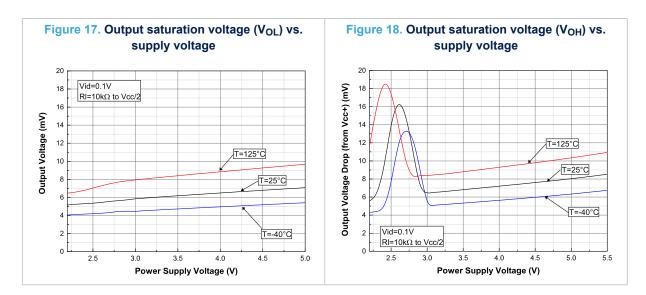




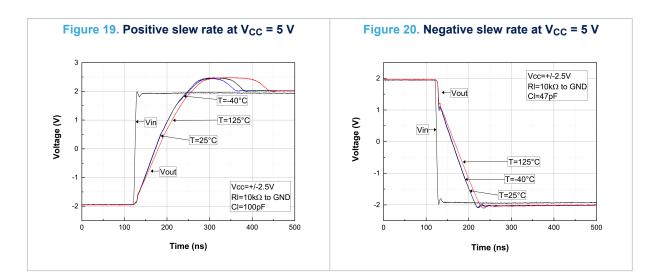


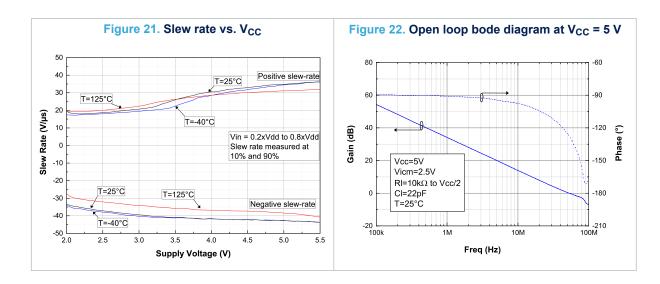


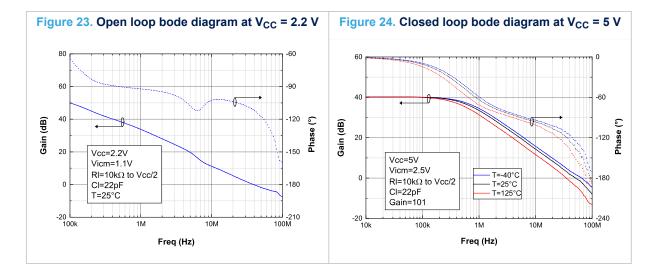


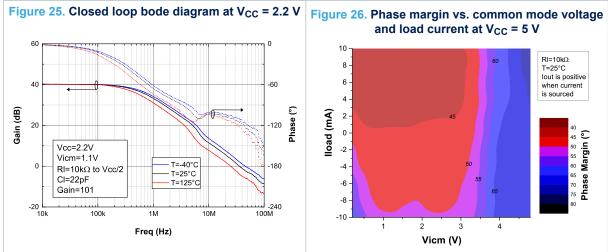


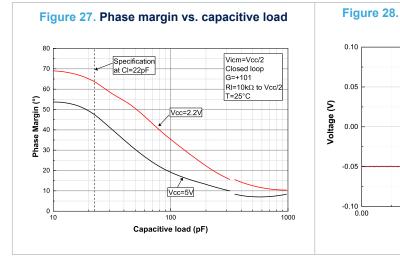


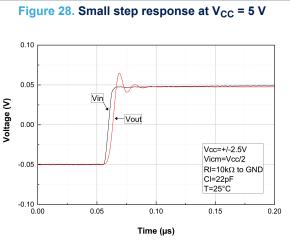


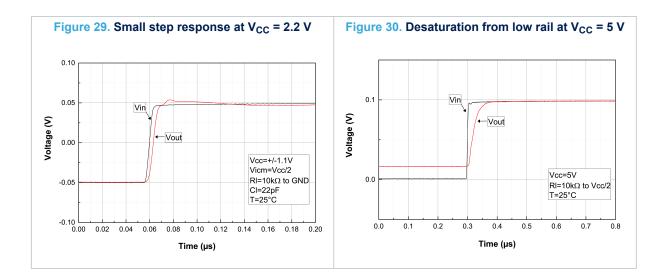


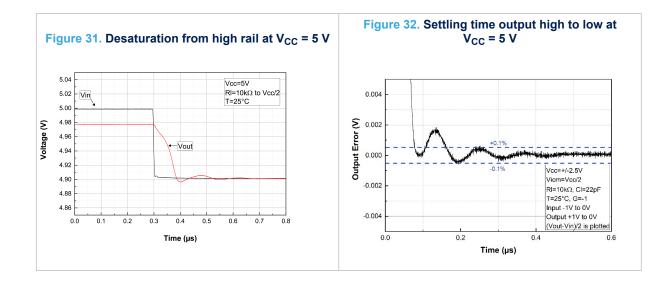


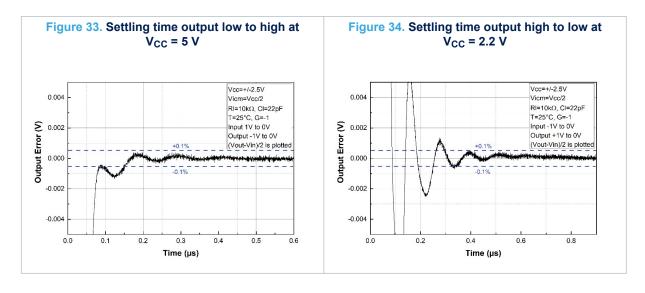


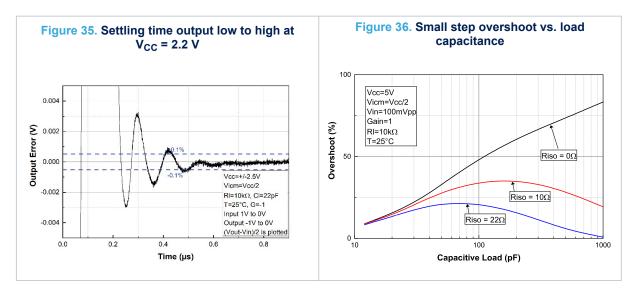


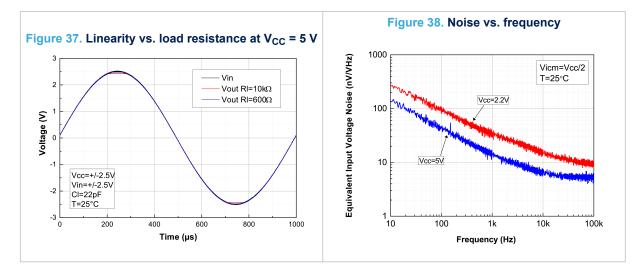


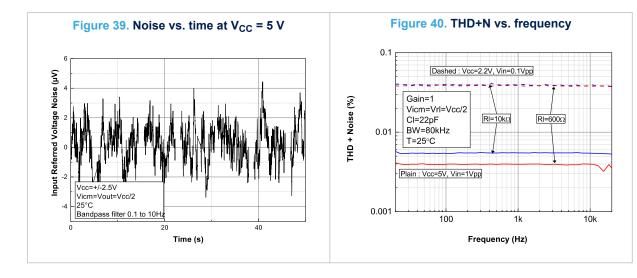


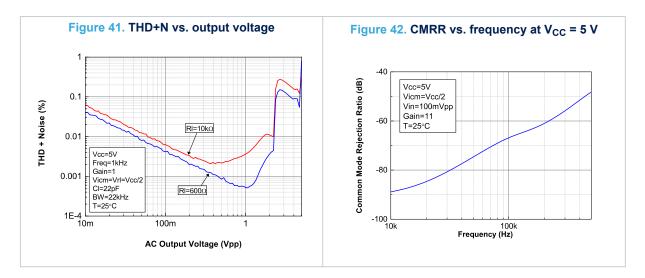


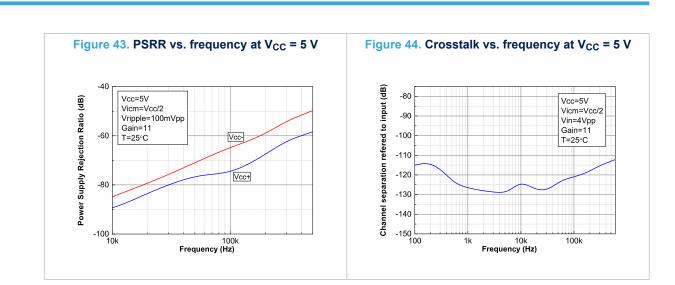












5 Application information

5.1 Operating voltages

The TSV79x devices can operate from 2.2 to 5.5 V. The parameters are fully specified at 2.2 V, 3.3 V and 5 V power supplies. However, the parameters are very stable over the full V_{CC} range and several characterization curves show the TSV79x device characteristics over the full operating range. Additionally, the main specifications are guaranteed in extended temperature range from - 40 to 125 °C.

The TSV79X devices are rail-to-rail input and output, and feature two input transistor pairs, allowing the op-amp to operate over all the common mode range, from $V_{cc^-} - 0.1 V$, to $V_{cc^+} + 0.1 V$. The input pair transition typically occurs at $V_{cc^+} - 1.4 V$, as seen in figures 11 and 12. The precision and dynamic performances are particularly optimized on the low pair, from $V_{cc^-} - 0.1 V$ to $V_{cc^+} - 2 V$, and operating in this V_{icm} range is advised for best performance whenever possible. Also, operating near the pair transition should be avoided when precision is a concern, as CMRR can be lower in these conditions.

5.2 Input offset voltage drift overtemperature

The maximum input voltage drift variation overtemperature is defined as the offset variation related to the offset value measured at 25 °C. The operational amplifier is one of the main circuits of the signal conditioning chain, and the amplifier input offset (V_{io}) is a major contributor to the chain accuracy.

The signal chain accuracy at 25 °C can be compensated during production at application level. The maximum input voltage drift overtemperature enables the system designer to anticipate the effect of temperature variations. The maximum input voltage drift overtemperature is computed using Equation 1.

$$\frac{\Delta V_{io}}{\Delta T} = max \left| \frac{V_{io}(T) - V_{io}(25^{\circ}C)}{T - 25^{\circ}C} \right|_{T = -40^{\circ}C \text{ and } T = 125^{\circ}C}$$
(1)

The datasheet maximum value is guaranteed by a measurement on a representative sample size ensuring a C_{pk} (process capability index) greater than 1.3.

5.3 Long term input offset voltage drift

To evaluate product reliability, two types of stress acceleration are used:

- Voltage acceleration, by changing the applied voltage
- Temperature acceleration, by changing the die temperature (below the maximum junction temperature allowed by the technology) with the ambient temperature.

The voltage acceleration has been defined based on JEDEC results, and is defined using Equation 2

$$A_{FV} = e^{\beta \cdot (V_S - V_U)} \tag{2}$$

Where:

A_{FV} is the voltage acceleration factor

 β is the voltage acceleration constant in 1/V, constant technology parameter (β = 1)

V_S is the stress voltage used for the accelerated test

 V_U is the voltage used for the application

The temperature acceleration is driven by the Arrhenius model, and is defined in Equation 3.

$$A_{FT} = e^{\frac{E_a}{k}} \cdot \left(\frac{1}{T_U} - \frac{1}{T_S}\right) \tag{3}$$

Where:

A_{FT} is the temperature acceleration factor

Ea is the activation energy of the technology based on the failure rate

k is the Boltzmann constant (8.6173 x 10⁻⁵ eV . K⁻¹)

 T_U is the temperature of the die when V_U is used (K)

 T_S is the temperature of the die under temperature stress (K)

The final acceleration factor, A_F , is the multiplication of the voltage acceleration factor and the temperature acceleration factor (Equation 4).

$$A_F = A_{FT} \cdot A_{FV} \tag{4}$$

 A_F is calculated using the temperature and voltage defined in the mission profile of the product. The A_F value can then be used in Equation x to calculate the number of months of use equivalent to 1000 hours of reliable stress duration.

Months = $A_F \times 1000 \text{ h} \times 12 \text{ months} / (24 \text{ h} \times 365.25 \text{ days})$

To evaluate the op-amp reliability, a follower stress condition is used where V_{CC} is defined as a function of the maximum operating voltage and the absolute maximum rating (as recommended by JEDEC rules). The V_{io} drift (in μV) of the product after 1000 h of stress is tracked with parameters at different measurement conditions (see Equation 5).

$$V_{CC} = max(V_{op}) \text{ with } V_{iCM} = \frac{V_{CC}}{2}$$
(5)

The long term drift parameter ΔV_{io} (in μV .month^{-1/2}), estimating the reliability performance of the product, is obtained using the ratio of the Vio (input offset voltage value) drift over the square root of the calculated number of months (Equation 6).

$$\Delta V_{io} = \frac{V_{io}drift}{\sqrt{months}} \tag{6}$$

Where V_{io} drift is the measured drift value in the specified test conditions after 1000 h stress duration. The V_{io} final drift, in μV , to be measured on the device in real operation conditions can be computed from Equation 7.

$$V_{io\,final\,drift}(t_{op}, T_{op}, V_{CC}) = \Delta V_{io} \cdot \sqrt{t_{op} \cdot e^{\beta \cdot (V_{CC} - V_{CC\,nom})} \cdot e^{\frac{E_a}{k} \cdot \left(\frac{1}{297} - \frac{1}{T_{op}}\right)}$$
(7)

Where:

 ΔV_{io} is the long term drift parameter in $\mu V.\sqrt{month}$

top is the operating time seen by the device, in months

Top is the operating temperature

 V_{CC} is the power supply during operating time

 V_{CC} nom is the nominal V_{CC} at which the ΔV_{io} is computed (5 V for TSV79x)

 E_a is the activation energy of the technology (here 0.7 eV).

5.4 Unused channel

When one of the two channels of the TSV792 is not used, it must be properly connected in order to avoid internal oscillations that can negatively impact the signal integrity on the other channel, as well as the current consumption. Two different configurations can be used:

Gain configuration: the channel can be set in gain, the input can be set to any voltage within the V_{icm} operating range.

Comparator configuration: the channel can be set to a comparator configuration (without negative feedback). In this case, positive and negative inputs can be set to any value provided these values are significantly different (100 mV or more, to avoid oscillation between positive and negative state).

5.5 EMI rejection

The electromagnetic interference (EMI) rejection ratio, or EMIRR, describes the EMI immunity of operational amplifiers. An adverse effect that is common to many op-amps is a change in the offset voltage as a result of RF signal rectification. EMIRR is defined in Equation 8:

$$EMIRR = 20 . log \left(\frac{V_{in} pp}{\Delta V_{io}}\right)$$

(8)

The TSV79x has been specially designed to minimize susceptibility to EMIRR and shows a low sensitivity. As seen in Figure 45, EMI rejection ratio has been measured on both inputs and output, from 400 MHz to 2.4 GHz.

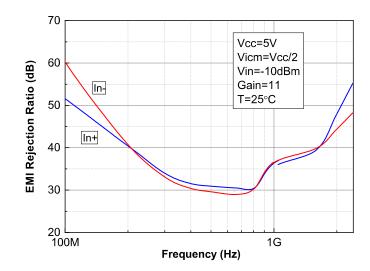


Figure 45. EMIRR on IN+ and IN- pins

EMIRR performances might be improved by adding small capacitances (in the pF range) on the inputs, power supply and output pins. These capacitances help to minimize the impedance of these nodes at high frequencies.

5.6 Maximum power dissipation

The usable output load current drive is limited by the maximum power dissipation allowed by the device package. The absolute maximum junction temperature for the TSV79x is 150 °C. The junction temperature can be estimated as follows:

$$T_I = P_D \times \theta_{IA} + T_A \tag{9}$$

T_J is the die junction temperature

P_D is the power dissipated in the package

 θ_{JA} is the junction to ambient thermal resistance of the package.

T_A is the ambient temperature.

The power dissipated in the package P_D is the sum of the quiescent power dissipated and the power dissipated by the output stage transistor. It is calculated as follows:

 $P_D = (V_{CC} \times I_{CC}) + (V_{CC+} - V_{OUT}) \times ILoad$ when the op-amp is sourcing the current.

 $P_D = (V_{CC} \times I_{CC}) + (V_{OUT} - V_{CC}) \times ILoad$ when the op-amp is sinking the current.

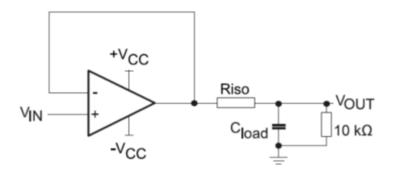
Do not exceed the 150 °C maximum junction temperature for the device. Exceeding the junction temperature limit can cause degradation in the parametric performance or even destroy the device.

5.7 Capacitive load and stability

Stability analysis must be performed for large capacitive loads over 22 pF. Increasing the load capacitance to high values produces gain peaking in the frequency response, with overshoot and ringing in the step response.

Generally, unity gain configuration is the worst situation for stability and the ability to drive large capacitive loads. For additional capacitive load drive capability in unity-gain configuration, stability can be improved by inserting a small resistor R_{ISO} (10 Ω to 22 Ω) in series with the output (see Figure 36). This resistor significantly reduces ringing while maintaining DC performance for purely capacitive loads. However, if there is a resistive load in parallel with the capacitive load, a voltage divider is created introducing a gain error at the output and slightly reducing the output swing. The error introduced is proportional to the ratio R_{ISO} / R_L . R_{ISO} modifies the maximum capacitive load acceptable from a stability point-of-view as described in the figure below:

Figure 46. Test configuration for RISO



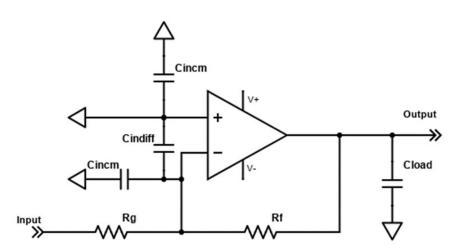
Please note that R_{ISO} = 22 Ω is sufficient to make the TSV79x stable whatever the capacitive load.

5.8 Resistor values for high speed op-amp design

Due to its high gain bandwidth product (GBP), this op-amp is particularly sensitive to parasitic impedances. Board parasitics should be taken into account in any sensitive design. Indeed, excessive parasitics (both capacitive and inductive) in the op-amp frequency range can alter performances and stability. These issues can often be mitigated by lowering the resistive impedances.

More specifically, the RC network created by the schematic resistors (R_f and R_g) and the parasitic capacitances of both the op-amp (as documented in Table 5 to Table 7 and illustrated in Figure 46) and the PCB can generate a pole below or in the same order of magnitude than the closed-loop bandwidth of the circuit. In this case, the feedback circuit is not able to fully play its role at high frequency, and the application can be unstable. This issue can happen when the schematic gain is low (typically < 5), or the device is used in follower mode with a resistor in the feedback. In these cases, it is advised to use a low value feedback resistor (R_f), typically 600 Ω .





Also, some designs use an input resistor on the positive input, generally of the same value than the input on the negative resistor. This resistor can be useful to balance the input currents on the positive and negative inputs, and reduce the impact of those input currents on precision. However, this is not useful on TSV79x as the input currents are very low. Furthermore, this resistor can also interact with the input capacitances to generate a pole. The frequency of this pole should be kept higher than the closed-loop bandwidth frequency.

The macromodel provided takes into account the circuit parasitic capacitors. Thus, a transient SPICE simulation (100 mV step) is an easy way to evaluate the stability of the application. However, this cannot replace hardware evaluation of the application circuit.

5.9 Settling time

Settling time in an application can be defined as the amount of time between the input changes, and the output reaching its final value. It is usually defined with a given tolerance, so the output stability is reached when the output stays within the given range around the final value.

In Figure 32 to Figure 35, the settling time is measured in an inverting configuration, using the so-called "false summing node" circuit.

G=-1 V = Vcc/2 V = Vcc/2 V = Vcc/2 $R = 10k\Omega$ C = 100pF C = 100pF C = 100pF C = 100pF C = 100pF

Figure 48. Settling time measurement configuration

This circuit is used with a step input voltage from a positive or negative value, to 0 V. The measurement point being $(V_{in} - V_{out}) / 2$, and V_{out} being in an ideal circuit equal to $-V_{in}$, the measurement point gives half of the error on V_{out} , comparatively to V_{in} . This error is compared to the tolerance, 0.1% for this circuit, to deduce the settling time.

This characteristic is particularly useful when driving an ADC. It is related to the slew rate, GBP and stability of the circuit. It also varies with the circuit gain, the circuit load, and the input voltage step value. However, computing the value of the settling time in a given configuration is not straightforward. The macromodel can give a good estimation, but prototyping can be needed for fine circuit optimization.

5.10 PCB layout recommendations

Particular attention must be paid to the layout of the PCB tracks connected to the amplifier, load, and power supply. The power and ground traces are critical as they must provide adequate energy and grounding for all circuits. The best practice is to use short and wide PCB traces to minimize voltage drops and parasitic inductance. In addition, to minimize parasitic impedance over the entire surface, a multi-via technique that connects the bottom and top layer ground planes together in many locations is often used. The copper traces that connect the output pins to the load and supply pins should be as wide as possible to minimize trace resistance.

5.11 Decoupling capacitor

In order to ensure op-amp full functionality, it is mandatory to place a decoupling capacitor of at least 22 nF as close as possible to the op-amp supply pins. A good decoupling helps to reduce electromagnetic interference impact.

5.12 Macro model

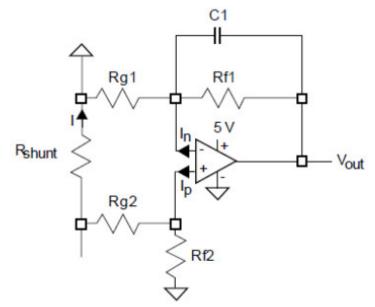
Accurate macro models of the TSV79x device are available on the STMicroelectronics' website at: www.st.com. These models are a trade-off between accuracy and complexity (that is, time simulation) of the TSV79x operational amplifier. They emulate the nominal performance of a typical device at 25 °C within the specified operating conditions mentioned in the datasheet. They also help to validate a design approach and to select the right operational amplifier, but they do not replace onboard measurements.

6 Typical applications

6.1 Low-side current sensing

Power management mechanisms are found in most electronic systems. Current sensing is useful for protecting applications. The low-side current sensing method consists of placing a sense resistor between the load and the circuit ground. The resulting voltage drop is amplified using the TSV79x (see Figure 48).

Figure 49. Low-side current sensing schematic



Vout can be expressed as follows:

$$V_{Out} = R_{shunt} \cdot I \left(1 - \frac{R_{g2}}{R_{g2} + R_{f2}} \right) \cdot \left(1 + \frac{R_{f1}}{R_{g1}} \right) + I_p \cdot \frac{R_{g2} \cdot R_{f2}}{R_{g2} + R_{f2}} \cdot \left(1 + \frac{R_{f1}}{R_{g1}} \right) - I_n \cdot R_{f1}$$
(10)
$$- V_{io} \cdot \left(1 + \frac{R_{f1}}{R_{g1}} \right)$$

Assuming that $R_{f2} = R_{f1} = R_f$ and $R_{q2} = R_{q1} = R_q$, Equation 10 can be simplified as follows:

$$V_{Out} = R_{shunt} \cdot I \cdot \frac{R_f}{R_g} - V_{io} \cdot \left(1 + \frac{R_f}{R_g}\right) + R_f \cdot I_{io}$$
⁽¹¹⁾

The main advantage of using the TSV79x for a low-side current sensing relies on its low Vio, compared to general purpose operational amplifiers. For the same current and targeted accuracy, the shunt resistor can be chosen with a lower value, resulting in lower power dissipation, lower drop in the ground path, and lower cost. Particular attention must be paid to the matching and precision of R_{g1} , R_{g2} , R_{f1} , and R_{f2} , to maximize the accuracy of the measurement.

6.2 Photodiode transimpedance amplification

The TSV79x, with high bandwidth and slew rate, is well suited for photodiode signal conditioning in a transimpedance amplifier circuit. This application is useful in high performance UV sensors, smoke detectors or particle sensors.

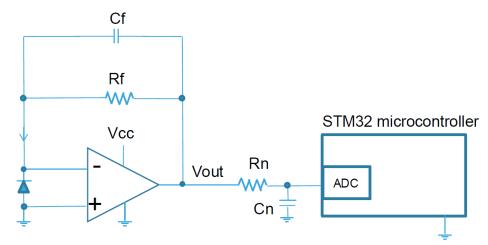


Figure 50. Photodiode transimpedance amplifier circuit

The transimpedance amplifier circuit converts the small photodiode output current in the nA range, into a voltage signal readable by an ADC following Equation 12:

$V_{Out} = R_f . I_{photodiode}$

The feedback resistance is usually in the M Ω range, in order to get a large enough voltage output range. However, together with the diode parasitic capacitance, the op-amp input capacitances and the PCB stray capacitance, this feedback network creates a pole that makes the circuit oscillate. Using a small (few pF) capacitor in parallel with the feedback resistor is mandatory to stabilize the circuit. The value of this capacitor can be tuned to optimize the application settling time with a spice simulation using the op-amp macromodel, or by prototyping.

For more details on tuning this circuit, please read the application note AN4451.

(12)

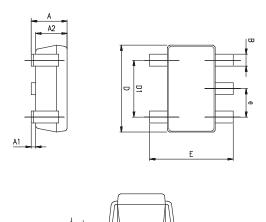
7 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.

7.1 SOT23-5 package information

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Figure 51. SOT23-5 package outline





	Dimensions						
Ref.		Millimeters			Inches		
	Min.	Тур.	Max.	Min.	Тур.	Max.	
A	0.90	1.20	1.45	0.035	0.047	0.057	
A1			0.15			0.006	
A2	0.90	1.05	1.30	0.035	0.041	0.051	
В	0.35	0.40	0.50	0.014	0.016	0.020	
С	0.09	0.15	0.20	0.004	0.006	0.020	
D	2.80	2.90	3.00	0.110	0.114	0.118	
D1		1.90			0.075		
е		0.95			0.037		
E	2.60	2.80	3.00	0.102	0.110	0.118	
F	1.50	1.60	1.75	0.059	0.063	0.069	
L	0.10	0.35	0.60	0.004	0.014	0.024	
К	0°		10°	0°		10°	

DFN8 2x2 package information 7.2

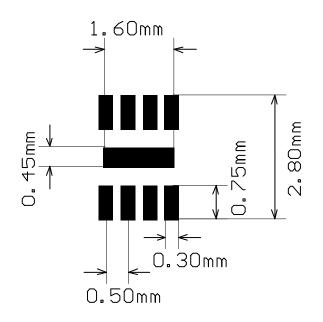
SEATING PLANE ပ ppp С A3 A1 \triangleleft D PIN#1 ID 2 3 1 4 U IJ EZ ш 8 7 6 5 b D2

Table 9. DFN8 2x2 package mechanical data

	Dimensions					
Ref.	Millimeters			Inches		
	Min.	Тур.	Max.	Min.	Тур.	Max.
А	0.51	0.55	0.60	0.020	0.022	0.024
A1			0.05			0.002
A3		0.15			0.006	
b	0.18	0.25	0.30	0.007	0.010	0.012
D	1.85	2.00	2.15	0.073	0.079	0.085
D2	1.45	1.60	1.70	0.057	0.063	0.067
E	1.85	2.00	2.15	0.073	0.079	0.085
E2	0.75	0.90	1.00	0.030	0.035	0.039
е		0.50			0.020	
L	0.225	0.325	0.425	0.009	0.013	0.017
ddd			0.08			0.003

Figure 52. DFN8 2x2 package outline

Figure 53. DFN8 2x2 recommended footprint



Note: The exposed pad of the DFN8 2x2 can be connected to VCC- or left floating.

7.3 MiniSO8 package information

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Figure 54. MiniSO8 package outline

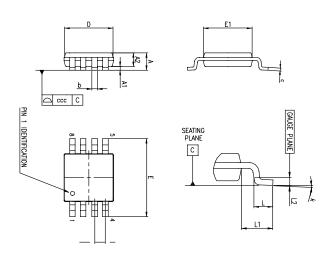


Table 10. MiniSO8 package mechanical data

	Dimensions					
Ref.	Millimeters			Inches		
	Min.	Тур.	Max.	Min.	Тур.	Max.
А			1.1			0.043
A1	0		0.15	0		0.0006
A2	0.75	0.85	0.95	0.030	0.033	0.037
b	0.22		0.40	0.009		0.016
С	0.08		0.23	0.003		0.009
D	2.80	3.00	3.20	0.11	0.118	0.126
Е	4.65	4.90	5.15	0.183	0.193	0.203
E1	2.80	3.00	3.10	0.11	0.118	0.122
е		0.65			0.026	
L	0.40	0.60	0.80	0.016	0.024	0.031
L1		0.95			0.037	
L2		0.25			0.010	
k	0°		8°	0°		8°
ccc			0.10			0.004

DS13480 - Rev 3

7.4 SO-8 package information

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Figure 55. SO-8 package outline

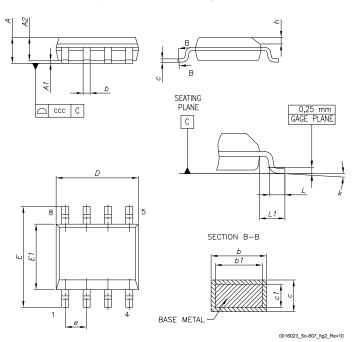


Table 11. SO-8 mechanical data

Dim.	mm				
Dim.	Min.	Тур.	Max.		
A			1.75		
A1	0.10		0.25		
A2	1.25				
b	0.31		0.51		
b1	0.28		0.48		
С	0.10		0.25		
c1	0.10		0.23		
D	4.80	4.90	5.00		
E	5.80	6.00	6.20		
E1	3.80	3.90	4.00		
е		1.27			
h	0.25		0.50		
L	0.40		1.27		
L1		1.04			
L2		0.25			
k	0°		8°		
CCC			0.10		

8 Ordering information

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Order code	Channel	Temperature range	Package	Marking
TSV791ILT	1	-40 °C to 125 °C	SOT23-5	K2B
TSV792IQ2T	2		DFN8 2x2	K2B
TSV792IST	2		MiniSO8	K2B
TSV792IDT	2		SO8	TSV792I
TSV791IYLT	1	-40 °C to 125 °C automotive grade ⁽¹⁾	SOT23-5	K227
TSV792IYST	2		MiniSO8	K227
TSV792IYDT	2		SO8	TSV792Y

Table 12. Order code

1. Qualification and characterization according to AEC Q100 and Q003 or equivalent, advanced screening according to AEC Q001 & Q 002 or equivalent are on-going.

Revision history

Table 13. Document revision history

Date	Revision	Changes
11-Nov-2020	1	Initial release.
11-Jan-2021	2	Updated V _{io} and CMR condititions in Table 7.
26-May-2021	3	Updated V_{io} and $\Delta V_{io}/\Delta T$ conditions in Table 6 and Table 7



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