

Magnetic Proportion System / Compact size and High-speed response. Vcc = +3.3V

LA02P Series









ABSOLUTE MAXIMUM RATINGS

Parameters	Symbol	Unit	Value	Comment
Supply voltage	V _{DD}	V	6.5	
Jumper temperature	_	°C	120	
Output current	lout	mA	±1	Recommend ; $< \pm 0.5$ mA
ESD rating (HBM: Human Body Model)	_	kV	2	C=100pF, R=1.5k Ω

ISOLATION CHARACTERISTICS

Parameters	Symbol	Unit	Value	Comment
Insulation voltage	Vd	V	≥ AC3000V, 50/60Hz, for 1minute (Sensing current 0.5mA)	Primary ⇔ Secondary
Impulse withstand voltage	Vw	kV	6	Primary ⇔ Secondary Input waveform: • Front time 1.2μs • Time to half value 50μs • single
Clearance distance	dCi	mm	13.3	Primary ⇔ Secondary
Creepage distance	dCp	mm	13.3	Primary ⇔ Secondary
Case material	<u> </u>	_	UL94 V-0	
Comparative Tracking Index; (CTI)	СТІ	V	150	

ENVIRONMENTAL AND MECHANICAL CHARACTERISTICS

Parameters	Symbol	Unit		Value		Comment
			MIN	TYP	MAX	Comment
Ambient operating temperature	Та	°C	- 40		+ 110	
Ambient storage temperature	Ts	°C	- 40		+ 150	
Mass	m	g		5.5		
Internal magnetic core	_	_	Ferrite			

SPECIFICATIONS

Ta=+25°C,V_{DD}=+3.3V,RL \ge 10MΩ

Parameters		Symbol	Unit	Value			Comment
				MIN	TYP	MAX	Comment
Measurement current range	LA02P021S03			- 21		21	
	LA02P035S03			- 35		35	
	LA02P054S03	lf If	A	- 54		54	
	LA02P085S03			- 85		85	



 $\textbf{SPECIFICATIONS} \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{RL} \geq 10 \textbf{M} \Omega \\ \textbf{Ta=+25}^{\circ}\textbf{C}, \textbf{V}_{DD} = +3.3 \textbf{V}, \textbf{V}_{DD} =$

Parameters		Symbol	Unit	Value			Comment
				MIN	TYP	MAX	Comment
Maximum primary current (RMS)		Ip _(RMS) max	Α			50	*1
Supply Voltage		V _{DD}	V	2.97	3.3	3.63	
Number of primary turns		Np	T	1			
Primary Jumper resistance		Rp	mΩ		0.1		
Current consumption (at If)	I _{DD}	mA			10		
Offset voltage (at If=0A)	_			1.636	1.650	1.664	At factory shipment
	LA02P021S03			(1.565)	1.650	(1.735)	
	LA02P035S03	Vof	V	(1.593)	1.650	(1.707)	Reference value after the flow
	LA02P054S03			(1.608)	1.650	(1.692)	soldering and over the lifetime of this product.
	LA02P085S03			(1.618)	1.650	(1.682)	
Temperature drift of offset voltage	LA02P021S03		mV		± 9.0		
(at Ta= $-40 \sim + 110^{\circ}$ C, Variation from Vof (Ta=35°C), Ip=0A)	LA02P035S03				± 5.5		
(12 22 27, 14 21.)	LA02P054S03	TCVof			± 3.5		
	LA02P085S03				± 2.5		
Sensitivity	LA02P021S03		mV/A	61.1	62.5	63.9	
	LA02P035S03	G		36.7	37.5	38.3	
	LA02P054S03			23.9	24.5	25.1	
	LA02P085S03			15.1	15.5	15.9	
Temperature coefficient 1 of Sensitivity (at Ta= -40 ~+ 110°C, Variation ratio to G (Ta=35°C))		TCG1	%		± 0.4		
Output Linearity (at 0 If)		εμ	%F.S.	-1		1	
Output noise voltage		V _{NRMS}	mVrms		1.7		
Ratiometric error of sensitivity		V _{G-R}	%	- 1		1	
Ratiometric error of offset voltage	LA02P021S03			- 0.8		0.8	
	LA02P035S03] ,	0/50	- 0.6		0.6	
	LA02P054S03	- V _{of-R}	%F.S.	- 0.6		0.6	
	LA02P085S03	1		- 0.6		0.6	
Response time 1 (at 90% of If)		tr	μs		1		CL=100pF
Frequency bandwidth (- 3dB)		BW	kHz		300		CL=100pF

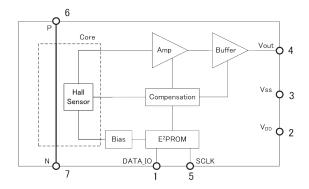
^{* 1} When $Ip_{\text{\tiny (RMS)}}\text{max}$ is bigger than the value of If, $Ip_{\text{\tiny (RMS)}}\text{max}$ restricts it to the value of If.

STANDARDS

IEC60950 , UL508 , CSA C22.2 No. 14

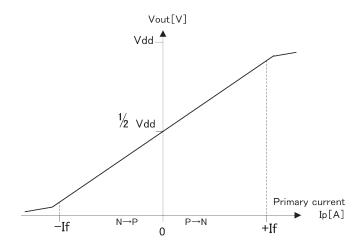
* Please refer to the another sheet about conditions of UL Recognition.

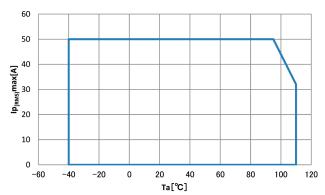
FUNCTIONAL BLOCK DIAGRAM





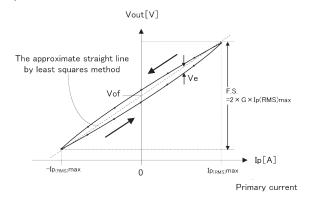
CHARACTERISTIC CURVE (TYP) AND PRIMARY CURRENT DERATING CURVE





Conditions : Mounted on the test board complying with the EIA/JEDEC Standards (EIA/JESD51.)

CHARACTERISTICS DEFINITIONS



• When $Ip_{(RMS)}$ max is bigger than the value of If, $Ip_{(RMS)}$ max restricts it to the value of If.

• Sensitivity G[mV/A],Offset voltage Vof[V]

Sensitivity (G) is defined as slope of the approximate straight line by least squares method, using the data of the output voltage (Vout) when sweeping the measured current lp at rated current range.

Also Offset voltage(Vof) is defined as the intercept of the approximate straight line.

Output linearity ε_L[%]

Output linearity (ϵ_L) is defined as the ratio of maximum error voltage (Ve) to the full scale (F.S.) , where Vd is maximum difference between the Output voltage (Vout) and the approximate straight line calculated in the sensitivity and offset voltage definition;

 ε_L =Ve/F.S.×100

 Ratiometric error of sensitivity V_{G-R}[%], ratiometric error of Offset voltage Vof._R[%]

Output of LA02P Series is ratiometric.

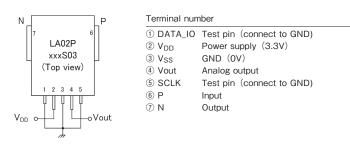
Sensitivity(G) and Offset voltage(Vof) are proportional to Supply voltage (VDD).

• Ratiometric error is defined as follows in the supply voltage range (2.97V<VDD1<3.63V);

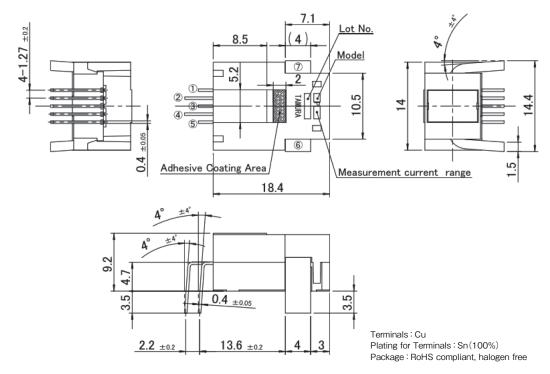
$$\begin{split} &V_{\text{G-R}} = &100 \times [(G(V_{\text{DD}} = V_{\text{DD}}1) / G(V_{\text{DD}} = 3.3 \text{V})) - (V_{\text{DD}}1 / 3.3)] / (V_{\text{DD}}1 / 3.3) \\ &Vof_{\text{R}} = &100 \times [Vof(V_{\text{DD}} = V_{\text{DD}}1) - Vof(V_{\text{DD}} = 3.3 \text{V}) \times (V_{\text{DD}}1 / 3.3)] / \text{F.S.} \end{split}$$



TERMINAL DESCRIPTIONS

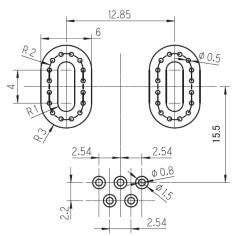


DIMENSIONS (mm)



Note1) The tolerances of dimensions without any mention are $\pm\,0.1\,\text{mm}.$

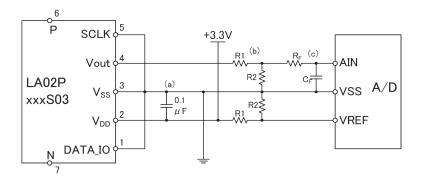
RECOMMENDED THROUGH-HOLE LAYOUTS (mm)



Note) If 2 or more trace layers are used as the current path, please make enough number of through-holes to flow current between the trace layers.

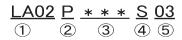


TYPICAL APPLICATION



- (a) Please be placed the bypass capacitor 0.1 μ F as close as possible to the V_{DD} and V_{SS} pins of LA02P Series.
- (b) LA02P Series have a ratiometric output. When received output by the A / D converter, it is possible to reduce the A / D conversion error due to supply voltage fluctuations by setting a common voltage level of the A / D converter and supply voltage. The resistive divider with R1 and R2 is required, if the reference voltage of the A / D converter is lower than + 3.3V.
- (c) If necessary, please insert a low-pass filter to Vout.

TYPE DESIGNATION



① Model (4 figures)

LA02: Series

② Mounting configuration (1 figure)

P:PCB Mounting type

③ Measurement current range (3 figures)

Ex) 035:35A 085:85A

4 Control power supply type (1 figure)

S : Single supply

5 Power supply voltage (2 digits)

RELIABILITY TEST

No.	Item	Test Conditions	n	Test Time
1	High Temp. High Humidity Bias Test	[JEITA EIAJ ED-4701 102] Ta=85°C, 8596RH, continuous operation	22	1000h
2	High Temperature Bias Test	[JEITA EIAJ ED-4701 101] Ta=125°C,continuous operation	22	1000h
3	High Temperature Storage Test	[JEITA EIAJ ED-4701 201] Ta=150°C	22	1000h
4	Low Temperature Storage Test	[JEITA EIAJ ED-4701 202] Ta=-55°C	22	1000h
5	Heat Cycle Test	[JEITA EIAJ ED-4701 105] -65°C(30min) ⇔ 150°C(30min) Tested in vapor phase	22	500 cycles
6	Vibration Test	[JEITA EIAJ ED-4701 403] Vibration frequency: 10∼55Hz(1 min.) Vibration amplitude: 1.5mm(x,y,z directions)	5	2h for each direction

Tested samples are pretreated as below before each reliability test:

Desiccation: 125°C /24h → Moisture Absorption: 85°C /85%RH/168h → Flow: 1 time (260°C, 10s)

Criterion for determining

Products whose drifts before and after the reliability tests do not exceed the values below are considered to be in spec.

Sensitivity G (Ta=25°C) : Within \pm 1.5% (All model)

Offset Voltage Vof (Ta=25°C): Within ± 100mV (LA02P021S03), Within ± 66mV (Other model)

Output Linearity ε_L (Ta=25°C) : Within \pm 1% (All model)



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- 1. The content of this information is subject to change without prior notice for the purpose of improvements, etc. Ensure that you are in possession of the most up-to-date information when using this product.
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 - · Use in liquids such as water, oil, chemical solutions, or organic solvents, and use in locations where the product will be exposed to such liquids.
 - · Use that involves exposure to direct sunlight, outdoor exposure, or dusty conditions.
 - · Use in locations where corrosive gases such as sea winds, CI2, H2S, NH3, S02, or NO2, are present. (Some product improves durability)
 - · Use in environments with strong static electricity or electromagnetic radiation.
 - · Use that involves placing inflammable material next to the
 - · Use of this product either sealed with a resin filling or coated with resin.
 - Use of water or a water soluble detergent for flux cleaning.
 - · Use in locations where condensation is liable to occur.
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Application notes

<General Considerations>

- 1. The sensor uses polar electronic components. When the polarity of the power supply is mistaken, the sensor is damaged.
- 2. Static electricity or excessive voltage can increase an offset voltage in the Hall element, and cause offset voltage to change. Please exercise care in handling and application.
- 3. In order to prevent the influence of noise, the use of twisted cable or shielded cable for the output line is recommended
- 4. If using this device within a magnetic field generated by other devices, the specified accuracy may not be obtainable.
- 5. Our products (several models are excluded) are adjusted with the trimming method by the measurement condition (Load resistance, Power supply voltage) of specification sheets. Therefore, characteristics (Offset, Output, etc.) and its deviation may be changed in different circuit conditions from the measurement condition. All change characteristic items are not indicated on specification sheets.
- 6. The performance of current sensors with through-hole (aperture) is dependent on the position of the primary conductor. Tamura specifications are based on a primary conductor completely filling the through-hole (aperture) area.
- 7. The current sensor rated current in DC Amps.
- 8. Please use mating connector with equivalent terminal plating material to insure proper operation and avoid possibility of 'galvanic corrosion'.
- 9. Please do not store in high-temperature and high-humidity storage environment. Please use it after confirming soldering when it is kept for six months or more. (product soldered with substrate)
- 10. We recommend performing a zero offset adjustment by measuring the offset voltage at startup. In continuously operation for a few months, or at change of ambient temperature or humidity is large, we recommend regularly performing a zero offset adjustment at being idling (it is clear that the current is not apply) .
- 11. The current sensor doesn't have built-in protection circuit (devices and fuses, etc.). As a failure mode of the sensor, there is a short circuit and open state. In the case of a shortcircuit state, the abnor-mal temperature rise of the internal parts is assumed, and there is a possibility to smoke and to ignite. If it is used in safety critical circuit blocks, please take appropriate measures by protection devices, protection circuits, etc. For closed loop -type sensors and flux gate (closed loop type) sensors, the consumption current of the secondary power supply varies in proportion to the measurement current.

<Open loop>

- 1. High frequency primary current may result in excessive heating in iron magnetic core and cause damage to internal circuitry; for high frequency applications select current sensor with ferrite core material.
- 2. If the measured current exceeds the rated current, magnetic core saturation will occur and the output voltage signal will not be linearly proportional to the measured current.

<Closed Loop>

- 1. For closed loop current sensors please insure the power supply voltage is balanced, symmetrical, and, applied simultaneously to avoid potential increase in DC offset error.
- 2. Maximum rated current measurement duration is timedependent. Maximum rated current applied in excess of the time limit can result in damage to internal electronic circuitry; please consult Tamura for assistance.
- 3. When using a measurement resistor to convert current output to voltage output select a resistor with stable temperature characteristic to insure accuracy of the output voltage.
- 4. Compensation current supplied to the secondary winding varies in proportion to the measured current based on the conversion ratio. (If/KN; KN = secondary turns) Please insure the PSU has required current capacity to supply compensation current to the secondary winding.

<Flux-Gate>

- 1. Compensation current supplied to the secondary winding varies in proportion to the measured current. Please insure the PSU has required current capacity to supply compensation current to the secondary winding.
- 2. There is 450kHz ripple voltage present on the output and reference output voltage signals . An external capacitor maybe added if necessary.

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100 CT-07-50 MR-1 MR-1-P5 T60404-N4646-X662 T60404-N4646-X664 DRV421RTJT CSNR161005 T60404-N4646-X651 MR-3 MR
2 MR-4 CT-06-100 CT-06-50 T60404-N4646-X412 CT-06-75 CSDA1BA-S CSDC1DA CSDD1EC CSLA1CF CSLA1DE CSLA1DG

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