

TDFN SO8 SM8



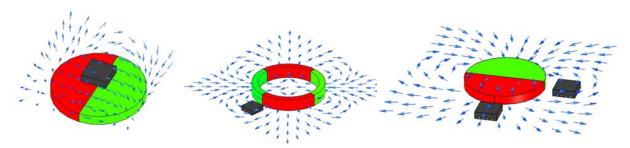




- AMR Sensor with 180° Period
- Moderate Field Strength
- High Accuracy
- TDFN Package
- Various Packages Available

DESCRIPTION

The KMT32B is a magnetic field sensor based on the anisotropic magnetoresistance effect, i.e. it is sensing the **magnetic field direction** independently on the magnetic field strength for applied field strengths H>25 kA/m. The sensor contains two parallel supplied Wheatstone bridges, which enclose a sensitive angle of 45 degrees.



A rotating magnetic field in the surface parallel to the chip (x-y plane) will deliver two independent sinusoidal output signals, one following a $\cos(2\alpha)$ and the second following a $\sin(2\alpha)$ function, α being the angle between sensor and field direction (see Figure 2).

FEATURES

- Contactless Angular Position
- SMD Package
- Design Optimized Linearity
- Low Cost
- High Accuracy
- High Rotational Speed up to 30,000 rpm
- Extended Operating Temperature Range (-40 °C to +150 °C, +160°C on request)
- Low Power
- RoHS Compliant (lead free)
- Ideal for Harsh Environments due to Magnetic Sensing

APPLICATIONS

- Absolute and Incremental Angle
- Angle Measurement
- Motor Motion Control
- Robotics
- Camera Positioning
- Potentiometer Replacement
- Automotive



CHARACTERISTIC VALUES

Parameter	Symbol	Condition	Min	Тур	Max	Unit	
A. Operating Limits							
max. supply voltage	Vcc _{,max}				10	V	
max. current (single bridge)	Icc _{,max}				4	mA	
operating temperature	T_{op}		-40		+150	°C	
storage temperature	T _{st}		-40		+150	°C	
B. Sensor Specifications (T=25 °C)						
Supply voltage	Vcc			5		V	
Resistance (single bridge)	R _b		2400	3000	3600	Ω	
Output signal range	ΔV _n /Vcc	Condition A, B	16	20		mV/V	
Offset voltage	Voff/Vcc	Condition A, B	-1	0	+1	mV/V	
angular inaccuracy	Δα	Condition A, B		0.05	0.2	deg	
angular hysteresis	ΔαΗ	Condition A, B			0.1	deg	
C. Sensor Specifications							
TC of amplitude	TCSV	Condition A, C	-0.36	-0.32	-0.28	%/K	
TC of resistance	TCBR	Condition A, C	+0.27	+0.32	+0.37	%/K	
TC of offset	TCVoff	Condition A, C	-4	0	+4	μV/V/K	

Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.

MEASUREMENT CONDITIONS

Parameter	Symbol	Unit	Condition		
A. Set Up Conditions	A. Set Up Conditions				
ambient temperature	Т	°C	T = 23±5 °C (unless otherwise noted)		
supply voltage	Vcc	V	Vcc = 5 V		
applied magnetic field	Н	kA/m	H = 25 kA/m		
B. Sensor Specifications (T	=25 °C, 360°	turn , H=25	kA/m , Vo _{max} >0, Vo _{min} <0)		
Output signal range	$\Delta V_n/Vcc$	mV/V	$\Delta V_n / Vcc = (Vo_{max} - Vo_{min}) / Vcc$		
Offset voltage	Voff/Vcc	mV/V	$Voff = (Vo_{max} + Vo_{min})/Vcc$		
angular inaccuracy	Δα	deg	$\Delta \alpha = MAX \alpha_0 - \alpha $ max. angular difference between actual value α_0 and measured angle; offset voltage error contributions not included		
angular hysteresis	ΔαΗ	deg	$\Delta \alpha H = \text{MAX} \alpha_{\text{left turn}} - \alpha_{\text{right turn}} $ max. angular difference between left and right turn		



MEASUREMENT CONDITIONS

Parameter	Symbol	Unit	Condition		
C. Sensor Specifications (1	C. Sensor Specifications (T=-25°C, +125°C)				
ambient temperatures	Т	°C	$T_1 = -25 ^{\circ}\text{C}, T_0 = +25 ^{\circ}\text{C}, T_2 = +125 ^{\circ}\text{C}$		
TC of amplitude	TCSV	%/K	$TCV = \frac{1}{(T_2 - T_1)} \cdot \frac{\frac{\Delta Vn}{Vcc} (T_2) - \frac{\Delta Vn}{Vcc} (T_1)}{\frac{\Delta Vn}{Vcc} (T_1)} \cdot 100\%$		
TC of resistance	TCBR	%/K	$TCR = \frac{1}{(T_2 - T_1)} \cdot \frac{R(T_2) - R(T_1)}{R(T_1)} \cdot 100\%$		
TC of offset	TCVoff	μV/(VK)	$TCVoff = \frac{Voff(T_2) - Voff(T_1)}{(T_2 - T_1)}$		

BLOCK DIAGRAM

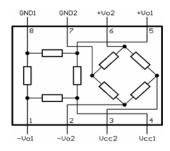
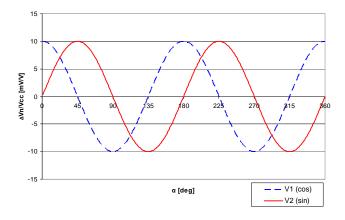


Figure 1: Circuit Diagram

The KMT32B magnetic field sensor is suited for high precision angle measurement applications under low field conditions (regularly $H_0 = 25$ kA/m, with reduced accuracy applicable down to $H_0 = 8$ kA/m; beware of earth's magnetic field!).

TYPICAL PERFORMANCE CURVES



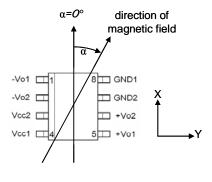
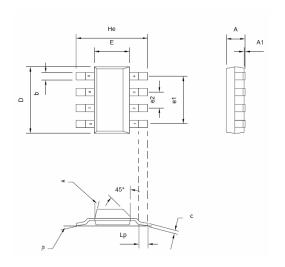


Figure 2: Characteristic curves for KMT32B



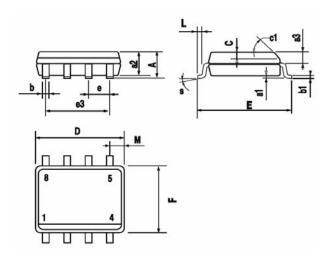
PACKAGES

SM8



Dim	Millimetres			Inches		
	Min	Тур	Max	Min	Тур	Max
Α	-	-	1.7	-	-	0.067
A1	0.02	-	0.1	0.0008	-	0.004
b	_	0.7	-	_	0.028	-
С	0.24	-	0.32	0.009	-	0.013
D	6.3	_	6.7	0.248	-	0.264
Е	3.3	-	3.7	0.130	-	0.145
e1	_	4.59	-	-	0.180	-
e2	_	1.53	-	-	0.060	-
Не	6.7	-	7.3	0.264	-	0.287
Lp	0.9	-	-	0.035	-	-
α	-	-	15°	-	-	15°
β	-	10°	-	-	10°	-

SO8



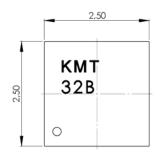
DIM.	mm			inch		
Diiii.	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
Α			1.75			0.069
a1	0.1		0.25	0.004		0.010
a2			1.65			0.065
a 3	0.65		0.85	0.026		0.033
b	0.35		0.48	0.014		0.019
b1	0.19		0.25	0.007		0.010
С	0.25		0.5	0.010		0.020
c1	45° (typ.)					
D (1)	4.8		5.0	0.189		0.197
Е	5.8		6.2	0.228		0.244
е		1.27			0.050	
е3		3.81			0.150	
F (1)	3.8		4.0	0.15		0.157
L	0.4		1.27	0.016		0.050
М			0.6			0.024
S	8° (max.)					

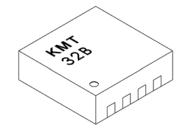
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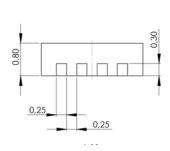


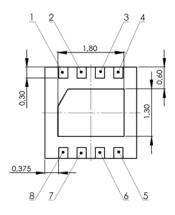
PACKAGES

TDFN8

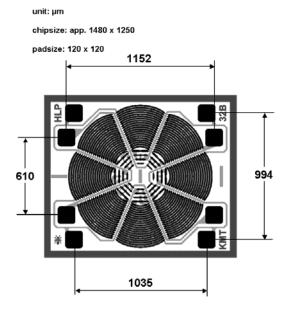


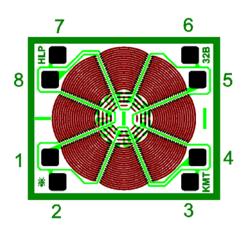






DIE







Pin assignment:

Pin	Symbol	Function
1	-Vo1	negative output Bridge 1
2	-Vo2	negative output Bridge 2
3	Vcc2	positive supply voltage Bridge 2
4	Vcc1	positive supply voltage Bridge 1
5	+Vo1	positive output Bridge 1
6	+Vo2	positive output Bridge 2
7	GND2	negative supply voltage Bridge 2
8	GND1	negative supply voltage Bridge 1

The bottom plate is designated to be a heat sink. It has no electrical connection to any pin. The sensitive area is positioned in the center of the housing.

ORDERING CODE

Device	Package	Part Number
KMT32B/SM	SM8	G-MRCO-014
KMT32B/SO	SO8	G-MRCO-015
KMT32B/TD	TDFN8	G-MRCO-016
KMT32B	Die	G-MRCH-011

ORDERING INFORMATION

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