

# DACxx6xT 具有 2.5V、4PPM/°C 内部基准和 5V TTL I/O 的双路 16 位、14 位、12 位低功耗电压输出 DAC

## 1 特性

- 相对精度：16 位时为 4 最低有效位 (LSB) 最大积分非线性 (INL)
- 低毛刺脉冲：0.1nV-s
- 双向基准引脚：输入或 2.5V 输出
  - 4ppm/°C 温度漂移（典型值）
- 上电复位至零量程或量程中点
- 低功耗：5V AVDD 时为 4mW
- 宽电源范围：2.7V 至 5.5V
- 带有施密特触发输入的 50MHz 串行外设接口 (SPI)
- LDAC 和 CLR 功能
- 支持轨到轨运行的输出缓冲器
- 与 DAC8562 系列引脚到引脚兼容
- 支持 5V 晶体管晶体管逻辑电路 (TTL) I/O
- 封装：晶圆级小外形无引线 (WSON)-10 (3mm x 3mm)，超薄小外形尺寸 (VSSOP)-10
- 温度范围：-40°C 至 125°C

## 2 应用

- 便携式仪表
- 可编程逻辑控制器 (PLC) 模拟输出模块
- 双极输出（第 9.2.2 节）
- 闭环伺服器控制
- 压控振荡器调谐
- 数据采集系统
- 可编程增益和偏移调整

## 3 说明

DAC856xT、DAC816xT 和 DAC756xT 器件分别为 16 位、14 位和 12 位低功耗电压输出双通道数模转换器 (DAC)。这些器件包括一个 2.5V、4ppm/°C 内部基准，从而提供了一个 2.5V 或 5V 的满量程输出电压范围。此内部基准有一个  $\pm 5\text{mV}$  的初始精度，并且能够在  $V_{\text{REFIN}}/V_{\text{REFOUT}}$  引脚上提供或吸收高达 20mA 的电流。

这些器件是单片器件，从而提供了出色的线性并大大降低了有害的代码至代码转换时的瞬态电压（毛刺脉冲）。它们使用一个运行时速率高达 50MHz 的多用途 3 线制串口。此接口与标准 SPI™，QSPI™，Microwire，以及数字信号处理器 (DSP) 接口兼容。DACxx62T 器件配有一个上电复位电路，此电路可确保在一个有效代码被写入此器件前，DAC 输出上电并保持零量程，而 DACxx63T 在量程中点上电。这些器件包含一个断电特性，此特性可将 5V 电压时的流耗减少至 550nA（典型值）。此低功耗、内部基准和小封装尺寸使得这些器件非常适合于便携式、电池供电运行类设备。

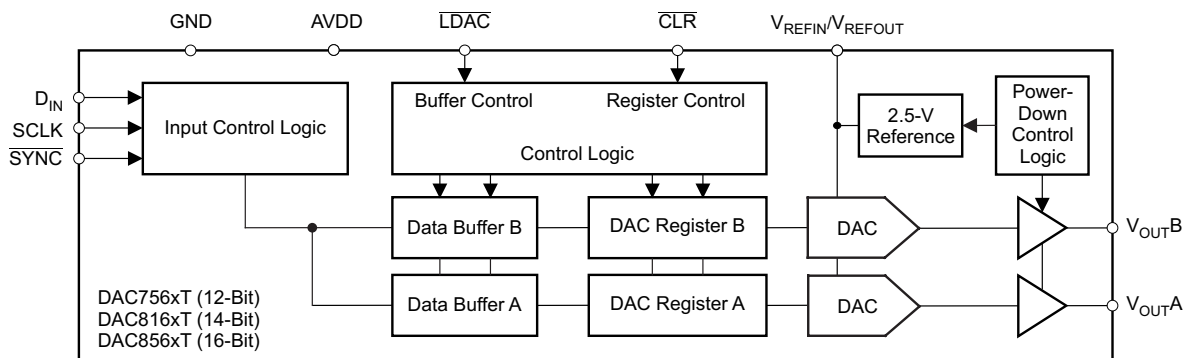
与 DACxx62T 器件一样，DACxx63T 器件之间可互相插接并且功能兼容。整个系列均提供 VSSOP-10 和 WSON-10 封装。

器件信息<sup>(1)</sup>

器件型号	封装	封装尺寸 (标称值)
DAC8562T	VSSOP (10), WSON (10)	3.00mm x 3.00mm
DAC8162T		
DAC7562T		

(1) 要了解所有可用封装，请见数据表末尾的可订购产品附录。

简化框图



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## 4 修订历史记录

注：之前版本的页码可能与当前版本有所不同。

### Changes from Original (September 2015) to Revision A

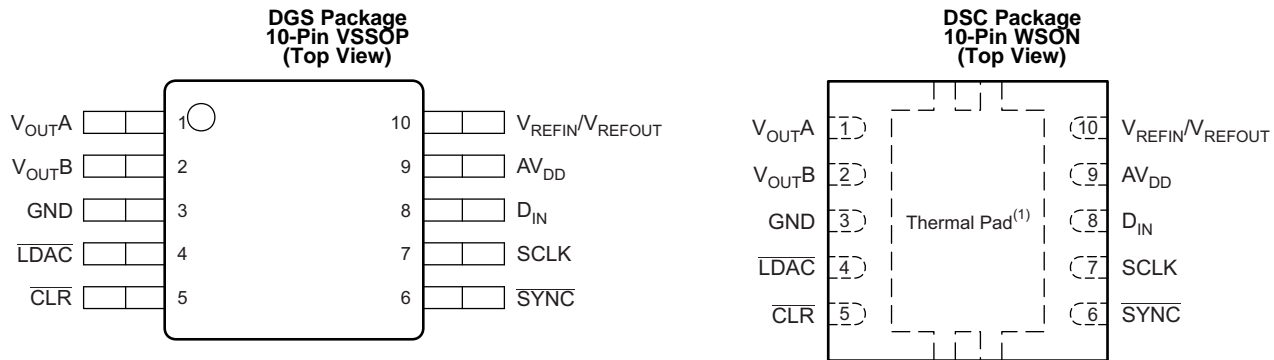
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## 5 Device Comparison Table

DEVICE	MAXIMUM RELATIVE ACCURACY (LSB)	MAXIMUM DIFFERENTIAL NONLINEARITY (LSB)	MAXIMUM REFERENCE DRIFT (ppm/°C)	RESET TO
DAC7562T	±0.75	±0.25	10	Zero
DAC7563T				Mid-scale
DAC8162T	±3	±0.5	10	Zero
DAC8163T				Mid-scale
DAC8562T	±12	±1	10	Zero
DAC8563T				Mid-scale

## 6 Pin Configuration and Functions



(1) TI recommends connecting the thermal pad to the ground plane for better thermal dissipation.

### Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
AV <sub>DD</sub>	9	I	Power-supply input, 2.7 V to 5.5 V
$\overline{\text{CLR}}$	5	I	Asynchronous clear input. The $\overline{\text{CLR}}$ input is falling-edge sensitive. On activation of $\overline{\text{CLR}}$ , zero scale (DACxx62T) or mid-scale (DACxx63T) is loaded to all input and DAC registers. This sets the DAC output voltages accordingly. The device exits clear code mode on the 24 <sup>th</sup> falling edge of the next write to the device. Activating $\overline{\text{CLR}}$ during a write sequence aborts the write.
D <sub>IN</sub>	8	I	Serial data input. Data are clocked into the 24-bit input shift register on each falling edge of the serial clock input. Schmitt-trigger logic input
GND	3	—	Ground reference point for all circuitry on the device
$\overline{\text{LDAC}}$	4	I	In <i>synchronous</i> mode, data update occurs with the falling edge of the 24 <sup>th</sup> SCLK cycle, which follows a falling edge of SYNC. Such <i>synchronous</i> updates do not require the LDAC, which must be connected to GND permanently or asserted and held low before sending commands to the device. In <i>asynchronous</i> mode, the $\overline{\text{LDAC}}$ pin is used as a negative edge-triggered timing signal for simultaneous DAC updates. Multiple single-channel commands can be written in order to set different channel buffers to desired values and then make a falling edge on the LDAC pin to update the DAC output registers simultaneously.
SCLK	7	I	Serial clock input. Data can be transferred at rates up to 50 MHz. Schmitt-trigger logic input
$\overline{\text{SYNC}}$	6	I	Level-triggered control input (active-low). This input is the frame synchronization signal for the input data. When $\overline{\text{SYNC}}$ goes low, it enables the input shift register, and data are sampled on subsequent falling clock edges. The DAC output updates following the 24 <sup>th</sup> clock falling edge. If $\overline{\text{SYNC}}$ is taken high before the 23 <sup>rd</sup> clock edge, the rising edge of SYNC acts as an interrupt, and the write sequence is ignored by the DAC756xT, DAC816xT, and DAC856xT devices. Schmitt-trigger logic input
V <sub>OUTA</sub>	1	O	Analog output voltage from DAC-A
V <sub>OUTB</sub>	2	O	Analog output voltage from DAC-B
V <sub>REFIN</sub> /V <sub>REFOUT</sub>	10	I/O	Bidirectional voltage reference pin. If internal reference is used, 2.5-V output.

## 7 Specifications

### 7.1 Absolute Maximum Ratings<sup>(1)</sup>

Over operating ambient temperature range (unless otherwise noted).

	MIN	MAX	UNIT
$V_{DD}$ to GND	-0.3	6	V
$\overline{CLR}$ , $D_{IN}$ , $\overline{LDAC}$ , $SCLK$ and $\overline{SYNC}$ input voltage to GND	-0.3	$V_{DD} + 0.3$	V
$V_{OUT[A, B]}$ to GND	-0.3	$V_{DD} + 0.3$	V
$V_{REFIN}/V_{REFOUT}$ to GND	-0.3	$V_{DD} + 0.3$	V
Operating temperature range	-40	125	°C
Junction temperature, $T_J$		150	°C
Storage temperature, $T_{stg}$	-65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 7.2 ESD Ratings

		VALUE	UNIT
$V_{(ESD)}$ Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1000	V
	Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

- (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 7.3 Recommended Operating Conditions

over operating ambient temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
<b>POWER SUPPLY</b>					
Supply voltage	$V_{DD}$ to GND	2.7		5.5	V
<b>DIGITAL INPUTS</b>					
Digital input voltage	$\overline{CLR}$ , $D_{IN}$ , $\overline{LDAC}$ , $SCLK$ and $\overline{SYNC}$	0		$V_{DD}$	V
<b>REFERENCE INPUT</b>					
$V_{REFIN}$ Reference input voltage		0		$V_{DD}$	V
<b>TEMPERATURE RANGE</b>					
$T_A$ Operating ambient temperature		-40		125	°C

### 7.4 Thermal Information

THERMAL METRIC		DAC756xT, DAC816xT, DAC856xT		UNIT
		DSC (WSON)	DGS (VSSOP)	
		10 PINS	10 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	62.8	173.8	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	44.3	48.5	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	26.5	79.9	°C/W
$\Psi_{JT}$	Junction-to-top characterization parameter	0.4	1.7	°C/W
$\Psi_{JB}$	Junction-to-board characterization parameter	25.5	68.4	°C/W
$R_{\theta JC(bot)}$	Junction-to-case (bottom) thermal resistance	46.2	N/A	°C/W

## 7.5 Electrical Characteristics

At  $V_{DD} = 2.7\text{ V to }5.5\text{ V}$  and  $T_A = -40^\circ\text{C to }125^\circ\text{C}$  (unless otherwise noted).

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
<b>STATIC PERFORMANCE<sup>(1)</sup></b>						
DAC756xT	Resolution		12			Bits
	Relative accuracy	Using line passing through codes 32 and 4,064		±0.3	±0.75	LSB
	Differential nonlinearity	12-bit monotonic		±0.05	±0.25	
DAC816xT	Resolution		14			Bits
	Relative accuracy	Using line passing through codes 128 and 16,256		±1	±3	LSB
	Differential nonlinearity	14-bit monotonic		±0.1	±0.5	
DAC856xT	Resolution		16			Bits
	Relative accuracy	Using line passing through codes 512 and 65,024		±4	±12	LSB
	Differential nonlinearity	16-bit monotonic		±0.2	±1	
Offset error		Extrapolated from two-point line <sup>(1)</sup> , unloaded		±1	±4	mV
Offset error drift				±2		μV/°C
Full-scale error		DAC register loaded with all 1s, DAC output unloaded		±0.03	±0.2	% FSR
Zero-code error		DAC register loaded with all 0s, DAC output unloaded		1	4	mV
Zero-code error drift				±2		μV/°C
Gain error		Extrapolated from two-point line <sup>(1)</sup> , unloaded		±0.01	±0.15	% FSR
Gain temperature coefficient				±1		ppm FSR/°C
<b>OUTPUT CHARACTERISTICS<sup>(2)</sup></b>						
Output voltage range			0		$V_{DD}$	V
Output voltage settling time <sup>(3)</sup>	DACs unloaded			7		μs
	$R_L = 1\text{ M}\Omega$			10		
Slew rate		Measured between 20%–80% of a full-scale transition		0.75		V/μs
Capacitive load stability	$R_L = \infty$			1		nF
	$R_L = 2\text{ k}\Omega$			3		
Code-change glitch impulse		1-LSB change around major carry		0.1		nV-s
Digital feedthrough		SCLK toggling, SYNC high		0.1		nV-s
Power-on glitch impulse		$R_L = 2\text{ k}\Omega$ , $C_L = 470\text{ pF}$ , $V_{DD} = 5.5\text{ V}$		40		mV
Channel-to-channel dc crosstalk	Full-scale swing on adjacent channel, External reference			5		μV
	Full-scale swing on adjacent channel, Internal reference			15		
DC output impedance		At mid-scale input		5		Ω
Short-circuit current		DAC outputs at full-scale, DAC outputs shorted to GND		40		mA
Power-up time, including settling time		Coming out of power-down mode		50		μs
<b>AC PERFORMANCE<sup>(2)</sup></b>						
DAC output noise density		$T_A = 25^\circ\text{C}$ , at mid-scale input, $f_{OUT} = 1\text{ kHz}$		90		nV/√Hz
DAC output noise		$T_A = 25^\circ\text{C}$ , at mid-scale input, 0.1 Hz to 10 Hz		2.6		μV <sub>PP</sub>
<b>LOGIC INPUTS<sup>(2)</sup></b>						
Input-pin leakage current			-1	±0.1	1	μA
Logic input LOW voltage $V_{IL}$			0		0.8	V
Logic input HIGH voltage $V_{IH}$			2.1		$V_{DD}$	V
Pin capacitance					3	pF

(1) 16-bit: codes 512 and 65,024; 14-bit: codes 128 and 16,256; 12-bit: codes 32 and 4,064, All digital inputs kept at same IO levels before and after write to the DAC

(2) Specification based on design or characterization

(3) Transition time between 1 / 4 scale and 3 / 4 scale, including settling to within ±0.024% FSR

## Electrical Characteristics (continued)

 At  $AV_{DD} = 2.7\text{ V to }5.5\text{ V}$  and  $T_A = -40^\circ\text{C to }125^\circ\text{C}$  (unless otherwise noted).

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
<b>REFERENCE</b>						
External reference current	External $V_{REF} = 2.5\text{ V}$ (when internal reference is disabled), all channels active using gain = 1		15		$\mu\text{A}$	
Reference input impedance	Internal reference disabled, gain = 1		170		$\text{k}\Omega$	
	Internal reference disabled, gain = 2		85			
<b>REFERENCE OUTPUT</b>						
Output voltage	$T_A = 25^\circ\text{C}$	2.495	2.5	2.505	V	
Initial accuracy	$T_A = 25^\circ\text{C}$	-5	$\pm 0.1$	5	mV	
Output-voltage temperature drift	Internal reference output voltage temperature drift is characterized from $-40^\circ\text{C}$ to $125^\circ\text{C}$ .		4	10	ppm/ $^\circ\text{C}$	
Output-voltage noise	$f = 0.1\text{ Hz to }10\text{ Hz}$		12		$\mu\text{V}_{PP}$	
Output-voltage noise density (high-frequency noise)	$T_A = 25^\circ\text{C}$ , $f = 1\text{ kHz}$ , $C_L = 0\text{ }\mu\text{F}$		250		$\text{nV}/\sqrt{\text{Hz}}$	
	$T_A = 25^\circ\text{C}$ , $f = 1\text{ MHz}$ , $C_L = 0\text{ }\mu\text{F}$		30			
	$T_A = 25^\circ\text{C}$ , $f = 1\text{ MHz}$ , $C_L = 4.7\text{ }\mu\text{F}$		10			
Load regulation, sourcing <sup>(4)</sup>	$T_A = 25^\circ\text{C}$		20		$\mu\text{V}/\text{mA}$	
Load regulation, sinking <sup>(4)</sup>	$T_A = 25^\circ\text{C}$		185		$\mu\text{V}/\text{mA}$	
Output-current load capability <sup>(2)</sup>			$\pm 20$		mA	
Line regulation	$T_A = 25^\circ\text{C}$		50		$\mu\text{V}/\text{V}$	
Long-term stability or drift (aging) <sup>(4)</sup>	$T_A = 25^\circ\text{C}$ , time = 0 to 1900 hours		100		ppm	
Thermal hysteresis <sup>(4)</sup>	First cycle		200		ppm	
	Additional cycles		50			
<b>POWER REQUIREMENTS<sup>(5)</sup></b>						
Power supply current ( $I_{DD}$ )	$AV_{DD} = 3.6\text{ V to }5.5\text{ V}$ , normal mode, internal reference off, Digital inputs at VDD or GND		0.25	0.5	mA	
	$AV_{DD} = 3.6\text{ V to }5.5\text{ V}$ , normal mode, internal reference off, Digital inputs at TTL level			4		
	$AV_{DD} = 3.6\text{ V to }5.5\text{ V}$ , normal mode, internal reference on, Digital inputs at VDD or GND		0.9	1.6		
	$AV_{DD} = 3.6\text{ V to }5.5\text{ V}$ , normal mode, internal reference on, Digital inputs at TTL level			5		
	$AV_{DD} = 3.6\text{ V to }5.5\text{ V}$ , power-down modes, Digital inputs at VDD or GND		0.55	4	$\mu\text{A}$	
	$AV_{DD} = 2.7\text{ V to }3.6\text{ V}$ , normal mode, internal reference off, Digital inputs at VDD or GND			0.2	0.4	mA
	$AV_{DD} = 2.7\text{ V to }3.6\text{ V}$ , normal mode, internal reference off, Digital inputs at TTL level				0.8	
	$AV_{DD} = 2.7\text{ V to }3.6\text{ V}$ , normal mode, internal reference on, Digital inputs at VDD or GND		0.73	1.4		
	$AV_{DD} = 2.7\text{ V to }3.6\text{ V}$ , normal mode, internal reference on, Digital inputs at TTL level				1.8	
	$AV_{DD} = 2.7\text{ V to }3.6\text{ V}$ , power-down modes, Digital inputs at VDD or GND		0.35	3	$\mu\text{A}$	

 (4) See the [Application Information](#) section of this data sheet.

(5) Input code = mid-scale, no load

## Electrical Characteristics (continued)

At  $V_{DD} = 2.7\text{ V to }5.5\text{ V}$  and  $T_A = -40^\circ\text{C to }125^\circ\text{C}$  (unless otherwise noted).

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Power dissipation	$V_{DD} = 3.6\text{ V to }5.5\text{ V}$ , normal mode, internal reference off, Digital inputs at VDD or GND		0.9	2.75	mW
	$V_{DD} = 3.6\text{ V to }5.5\text{ V}$ , normal mode, internal reference on, Digital inputs at VDD or GND		3.2	8.8	
	$V_{DD} = 3.6\text{ V to }5.5\text{ V}$ , power-down modes, Digital inputs at VDD or GND		2	22	$\mu\text{W}$
	$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ , normal mode, internal reference off, Digital inputs at VDD or GND		0.54	1.44	mW
	$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ , normal mode, internal reference on, Digital inputs at VDD or GND		1.97	5	
	$V_{DD} = 2.7\text{ V to }3.6\text{ V}$ , power-down modes, Digital inputs at VDD or GND		0.95	10.8	$\mu\text{W}$

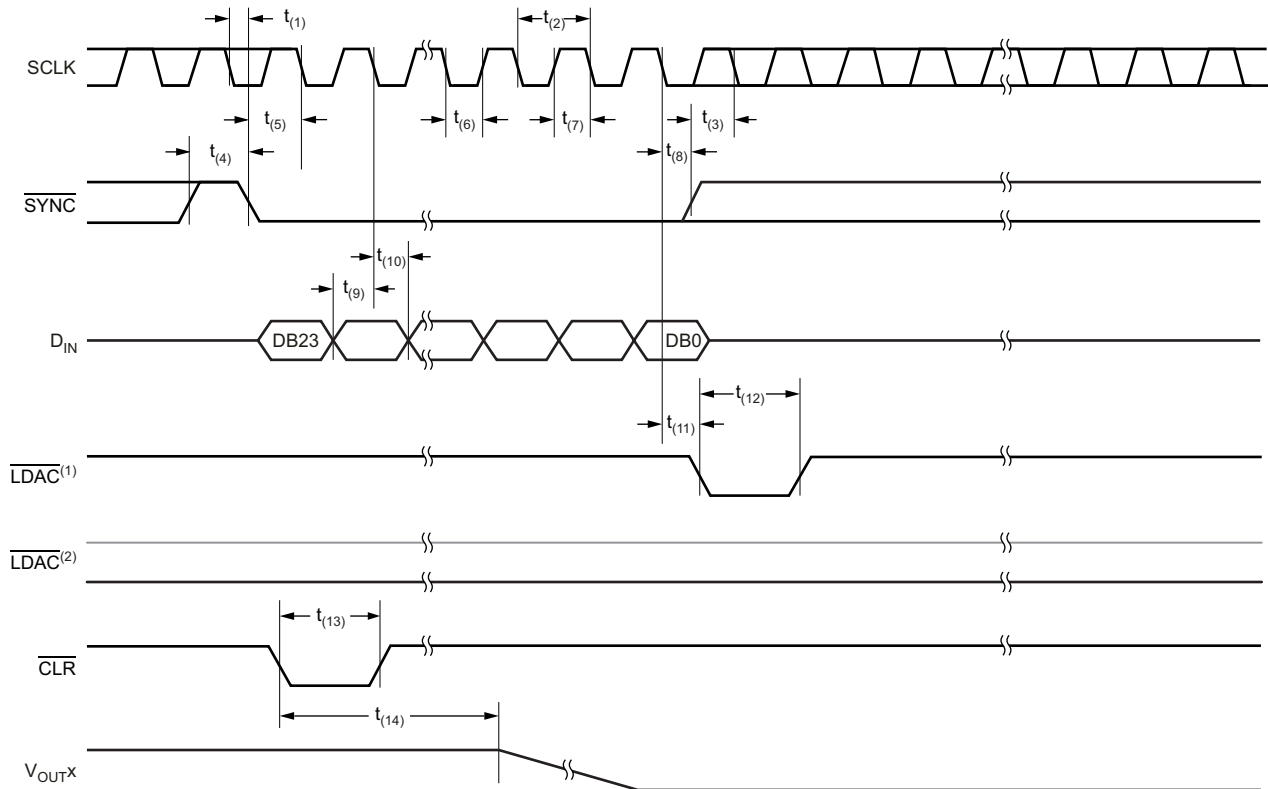


## 7.6 Timing Requirements<sup>(1)(2)</sup>

At  $AV_{DD} = 2.7\text{ V}$  to  $5.5\text{ V}$ , external  $V_{REFIN} = 2.5\text{ V}$  to  $5.5\text{ V}$ , and over  $-40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$  (unless otherwise noted). See [Figure 1](#).

		DAC756xT, DAC816xT, DAC856xT			UNIT
		MIN	TYP	MAX	
$f_{(SCLK)}$	Serial clock frequency			50	MHz
$t_{(1)}$	SCLK falling edge to $\overline{SYNC}$ falling edge (for successful write operation)	10			ns
$t_{(2)}$	SCLK cycle time	20			ns
$t_{(3)}$	$\overline{SYNC}$ rising edge to 23 <sup>rd</sup> SCLK falling edge (for successful $\overline{SYNC}$ interrupt)	13			ns
$t_{(4)}$	Minimum $\overline{SYNC}$ HIGH time	15			ns
$t_{(5)}$	$\overline{SYNC}$ to SCLK falling edge setup time	13			ns
$t_{(6)}$	SCLK LOW time	8			ns
$t_{(7)}$	SCLK HIGH time	8			ns
$t_{(8)}$	SCLK falling edge to $\overline{SYNC}$ rising edge	10			ns
$t_{(9)}$	Data setup time	6			ns
$t_{(10)}$	Data hold time	6			ns
$t_{(11)}$	SCLK falling edge to $\overline{LDAC}$ falling edge for asynchronous LDAC update mode	5			ns
$t_{(12)}$	$\overline{LDAC}$ pulse duration, LOW time	10			ns
$t_{(13)}$	$\overline{CLR}$ pulse duration, LOW time	80			ns
$t_{(14)}$	$\overline{CLR}$ falling edge to start of $V_{OUTX}$ transition			100	ns

- (1) All input signals are specified with  $t_r = t_f = 1\text{ ns/V}$  (10% to 90% of  $AV_{DD}$ ) and timed from a voltage level of  $(V_{IL} + V_{IH}) / 2$ .  
 (2) See the *Serial Write Operation* timing diagram ([Figure 1](#)).



- (1) Asynchronous  $\overline{LDAC}$  update mode. For more information, see the [LDAC Functionality](#) section.  
 (2) Synchronous  $\overline{LDAC}$  update mode;  $\overline{LDAC}$  remains low. For more information, see the [LDAC Functionality](#) section.

**Figure 1. Timing Diagram, Serial Write Operation**

## 7.7 Typical Characteristics

**Table 1. Typical Characteristics: Internal Reference Performance**

MEASUREMENT	POWER-SUPPLY VOLTAGE	FIGURE NUMBER
Internal Reference Voltage vs Temperature	5.5 V	Figure 2
Internal Reference Voltage Temperature Drift Histogram		Figure 3
Internal Reference Voltage vs Load Current		Figure 4
Internal Reference Voltage vs Time		Figure 5
Internal Reference Noise Density vs Frequency		Figure 6
Internal Reference Voltage vs Supply Voltage	2.7 V–5.5 V	Figure 7

**Table 2. Typical Characteristics: DAC Static Performance**

MEASUREMENT	POWER-SUPPLY VOLTAGE	FIGURE NUMBER	
<b>FULL-SCALE, GAIN, OFFSET AND ZERO-CODE ERRORS</b>			
Full-Scale Error vs Temperature	5.5 V	Figure 16	
Gain Error vs Temperature		Figure 17	
Offset Error vs Temperature		Figure 18	
Zero-Code Error vs Temperature		Figure 19	
Full-Scale Error vs Temperature	2.7 V	Figure 63	
Gain Error vs Temperature		Figure 64	
Offset Error vs Temperature		Figure 65	
Zero-Code Error vs Temperature		Figure 66	
<b>LOAD REGULATION</b>			
DAC Output Voltage vs Load Current	5.5 V	Figure 30	
	2.7 V	Figure 74	
<b>DIFFERENTIAL NONLINEARITY ERROR</b>			
Differential Linearity Error vs Digital Input Code	T = –40°C	Figure 9	
	T = 25°C	Figure 11	
	T = 125°C	Figure 13	
Differential Linearity Error vs Temperature	5.5 V	Figure 15	
Differential Linearity Error vs Digital Input Code		T = –40°C	Figure 56
		T = 25°C	Figure 58
		T = 125°C	Figure 60
Differential Linearity Error vs Temperature	2.7 V	Figure 62	
<b>INTEGRAL NONLINEARITY ERROR (RELATIVE ACCURACY)</b>			
Linearity Error vs Digital Input Code	T = –40°C	Figure 8	
	T = 25°C	Figure 10	
	T = 125°C	Figure 12	
Linearity Error vs Temperature	5.5 V	Figure 14	
Linearity Error vs Digital Input Code		T = –40°C	Figure 55
		T = 25°C	Figure 57
		T = 125°C	Figure 59
Linearity Error vs Temperature	2.7 V	Figure 61	

**Table 2. Typical Characteristics: DAC Static Performance (continued)**

MEASUREMENT		POWER-SUPPLY VOLTAGE	FIGURE NUMBER	
<b>POWER-DOWN CURRENT</b>				
Power-Down Current vs Temperature		5.5 V	<a href="#">Figure 28</a>	
Power-Down Current vs Power-Supply Voltage		2.7 V – 5.5 V	<a href="#">Figure 29</a>	
Power-Down Current vs Temperature		2.7 V	<a href="#">Figure 73</a>	
<b>POWER-SUPPLY CURRENT</b>				
Power-Supply Current vs Temperature	External $V_{REF}$	5.5 V	<a href="#">Figure 20</a>	
	Internal $V_{REF}$		<a href="#">Figure 21</a>	
Power-Supply Current vs Digital Input Code	External $V_{REF}$		<a href="#">Figure 22</a>	
	Internal $V_{REF}$		<a href="#">Figure 23</a>	
Power-Supply Current Histogram	External $V_{REF}$		<a href="#">Figure 24</a>	
	Internal $V_{REF}$		<a href="#">Figure 25</a>	
Power-Supply Current vs Power-Supply Voltage	External $V_{REF}$		2.7 V – 5.5 V	<a href="#">Figure 26</a>
	Internal $V_{REF}$			<a href="#">Figure 27</a>
Power-Supply Current vs Temperature	External $V_{REF}$		3.6 V	<a href="#">Figure 49</a>
	Internal $V_{REF}$			<a href="#">Figure 50</a>
Power-Supply Current vs Digital Input Code	External $V_{REF}$	<a href="#">Figure 51</a>		
	Internal $V_{REF}$	<a href="#">Figure 52</a>		
Power-Supply Current Histogram	External $V_{REF}$	<a href="#">Figure 53</a>		
	Internal $V_{REF}$	<a href="#">Figure 54</a>		
Power-Supply Current vs Temperature	External $V_{REF}$	2.7 V		<a href="#">Figure 67</a>
	Internal $V_{REF}$			<a href="#">Figure 68</a>
Power-Supply Current vs Digital Input Code	External $V_{REF}$		<a href="#">Figure 69</a>	
	Internal $V_{REF}$		<a href="#">Figure 70</a>	
Power-Supply Current Histogram	External $V_{REF}$		<a href="#">Figure 71</a>	
	Internal $V_{REF}$		<a href="#">Figure 72</a>	

**Table 3. Typical Characteristics: DAC Dynamic Performance**

MEASUREMENT		POWER-SUPPLY VOLTAGE	FIGURE NUMBER
<b>CHANNEL-TO-CHANNEL CROSSTALK</b>			
Channel-to-Channel Crosstalk	5-V Rising Edge	5.5 V	<a href="#">Figure 43</a>
	5-V Falling Edge		<a href="#">Figure 44</a>
<b>CLOCK FEEDTHROUGH</b>			
Clock Feedthrough	500 kHz, Midscale	5.5 V	<a href="#">Figure 48</a>
		2.7 V	<a href="#">Figure 87</a>
<b>GLITCH IMPULSE</b>			
Glitch Impulse, 1-LSB Step	Rising Edge, Code 7FFFh to 8000h	5.5 V	<a href="#">Figure 37</a>
	Falling Edge, Code 8000h to 7FFFh		<a href="#">Figure 38</a>
Glitch Impulse, 4-LSB Step	Rising Edge, Code 7FFCh to 8000h		<a href="#">Figure 39</a>
	Falling Edge, Code 8000h to 7FFCh		<a href="#">Figure 40</a>
Glitch Impulse, 16-LSB Step	Rising Edge, Code 7FF0h to 8000h		<a href="#">Figure 41</a>
	Falling Edge, Code 8000h to 7FF0h		<a href="#">Figure 42</a>

**Table 3. Typical Characteristics: DAC Dynamic Performance (continued)**

MEASUREMENT		POWER-SUPPLY VOLTAGE	FIGURE NUMBER
Glitch Impulse, 1-LSB Step	Rising Edge, Code 7FFFh to 8000h	2.7 V	<a href="#">Figure 79</a>
	Falling Edge, Code 8000h to 7FFFh		<a href="#">Figure 80</a>
Glitch Impulse, 4-LSB Step	Rising Edge, Code 7FFCh to 8000h		<a href="#">Figure 81</a>
	Falling Edge, Code 8000h to 7FFCh		<a href="#">Figure 82</a>
Glitch Impulse, 16-LSB Step	Rising Edge, Code 7FF0h to 8000h		<a href="#">Figure 83</a>
	Falling Edge, Code 8000h to 7FF0h		<a href="#">Figure 84</a>
<b>NOISE</b>			
DAC Output Noise Density vs Frequency	External $V_{REF}$	5.5 V	<a href="#">Figure 45</a>
	Internal $V_{REF}$		<a href="#">Figure 46</a>
DAC Output Noise 0.1 Hz to 10 Hz	External $V_{REF}$		<a href="#">Figure 47</a>
<b>POWER-ON GLITCH</b>			
Power-On Glitch	Reset to Zero Scale	5.5 V	<a href="#">Figure 35</a>
	Reset to Midscale		<a href="#">Figure 36</a>
	Reset to Zero Scale	2.7 V	<a href="#">Figure 85</a>
	Reset to Midscale		<a href="#">Figure 86</a>
<b>SETTLING TIME</b>			
Full-Scale Settling Time	Rising Edge, Code 0h to FFFFh	5.5 V	<a href="#">Figure 31</a>
	Falling Edge, Code FFFFh to 0h		<a href="#">Figure 32</a>
Half-Scale Settling Time	Rising Edge, Code 4000h to C000h		<a href="#">Figure 33</a>
	Falling Edge, Code C000h to 4000h		<a href="#">Figure 34</a>
Full-Scale Settling Time	Rising Edge, Code 0h to FFFFh	2.7 V	<a href="#">Figure 75</a>
	Falling Edge, Code FFFFh to 0h		<a href="#">Figure 76</a>
Half-Scale Settling Time	Rising Edge, Code 4000h to C000h		<a href="#">Figure 77</a>
	Falling Edge, Code C000h to 4000h		<a href="#">Figure 78</a>

### 7.7.1 Typical Characteristics: Internal Reference

At  $T_A = 25^\circ\text{C}$ ,  $AV_{DD} = 5.5\text{ V}$ , gain = 2, and  $V_{REFOUT}$  unloaded, unless otherwise noted.

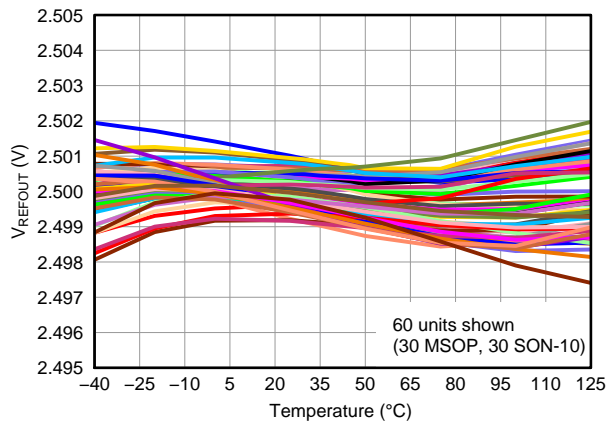


Figure 2. Internal Reference Voltage vs Temperature

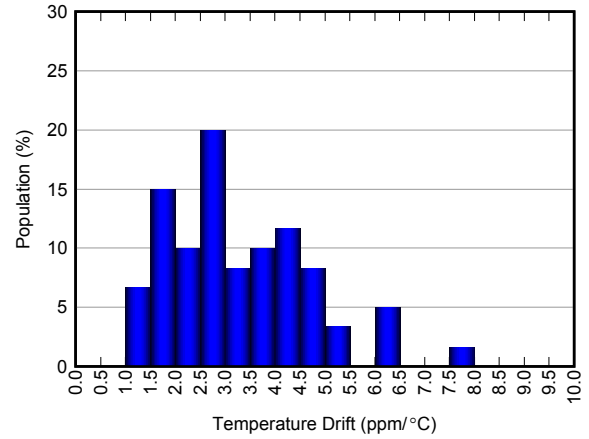


Figure 3. Internal Reference Voltage, Temperature Drift Histogram

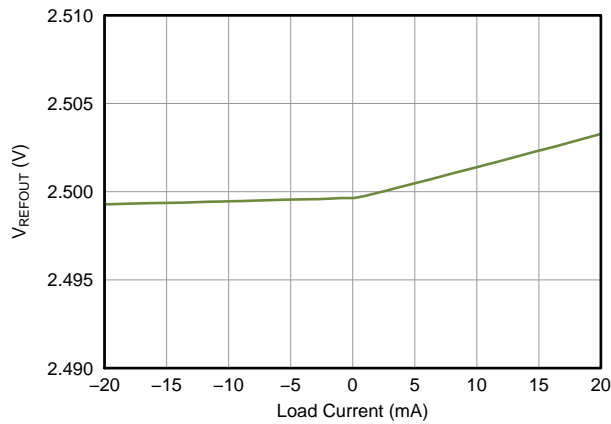


Figure 4. Internal Reference Voltage vs Load Current

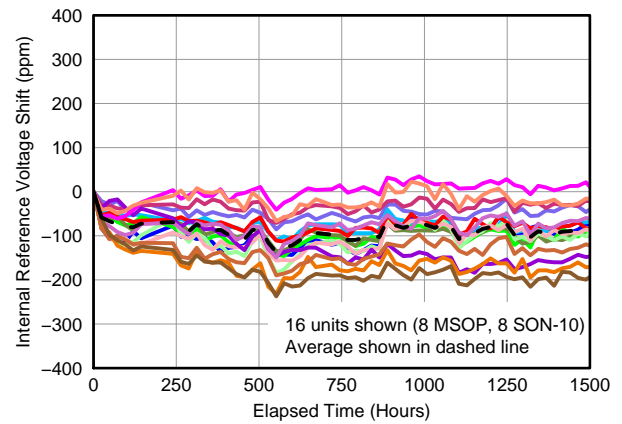


Figure 5. Internal Reference Voltage vs Time

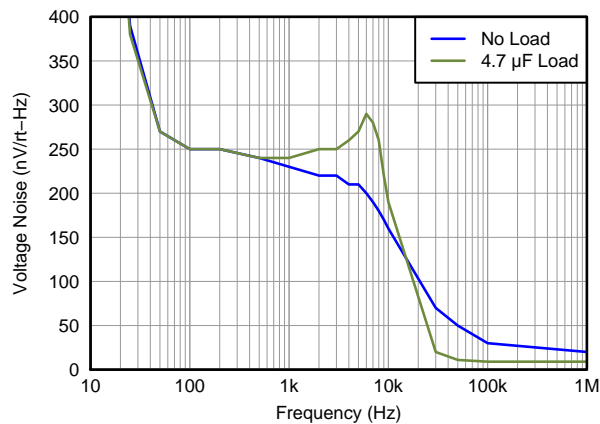


Figure 6. Internal Reference Noise Density vs Frequency

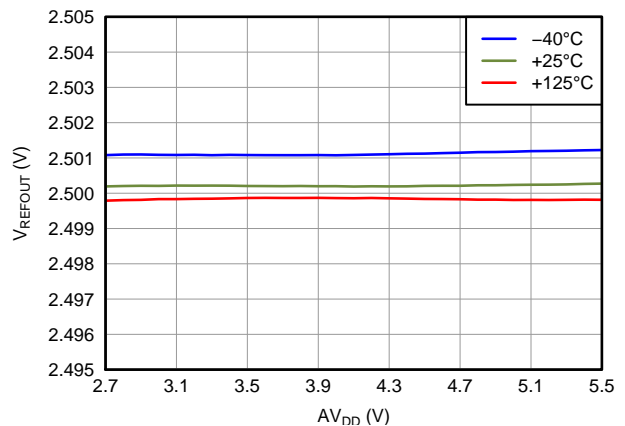


Figure 7. Internal Reference Voltage vs Supply Voltage

### 7.7.2 Typical Characteristics: DAC at $V_{DD} = 5.5\text{ V}$

At  $T_A = 25^\circ\text{C}$ , 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.

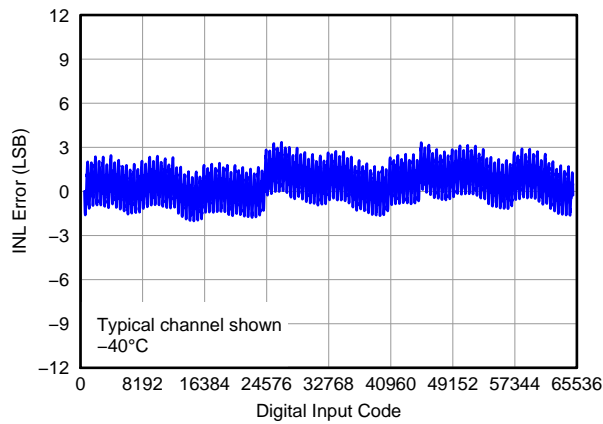


Figure 8. Linearity Error vs Digital Input Code ( $-40^\circ\text{C}$ )

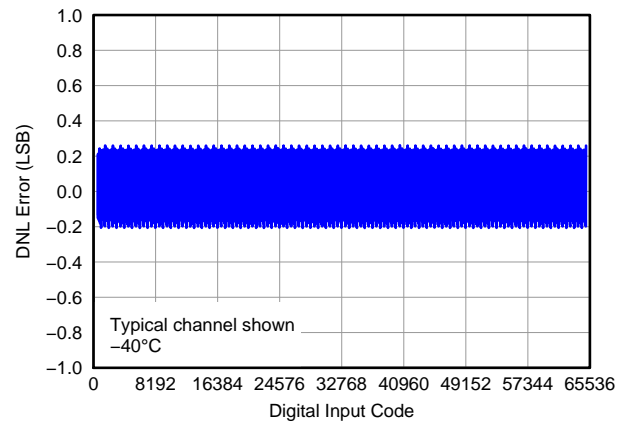


Figure 9. Differential Linearity Error vs Digital Input Code ( $-40^\circ\text{C}$ )

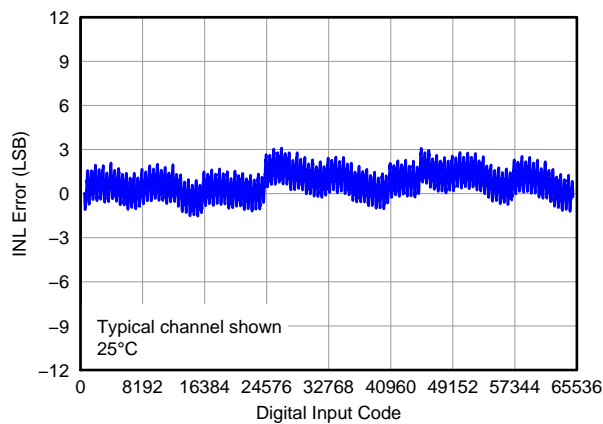


Figure 10. Linearity Error vs Digital Input Code ( $25^\circ\text{C}$ )

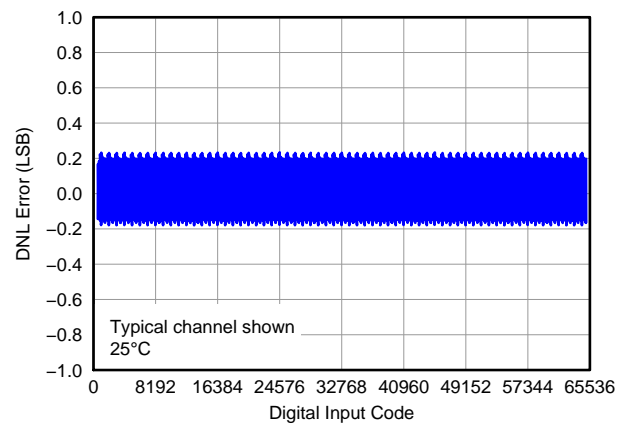


Figure 11. Differential Linearity Error vs Digital Input Code ( $25^\circ\text{C}$ )

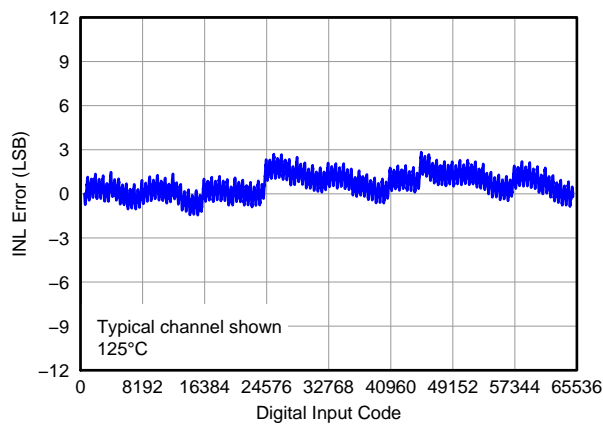


Figure 12. Linearity Error vs Digital Input Code ( $125^\circ\text{C}$ )

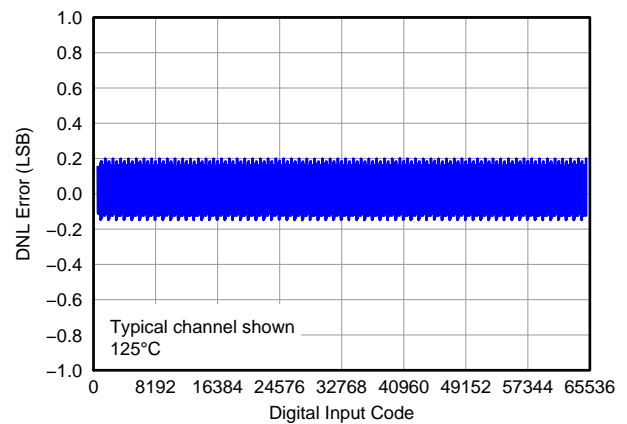
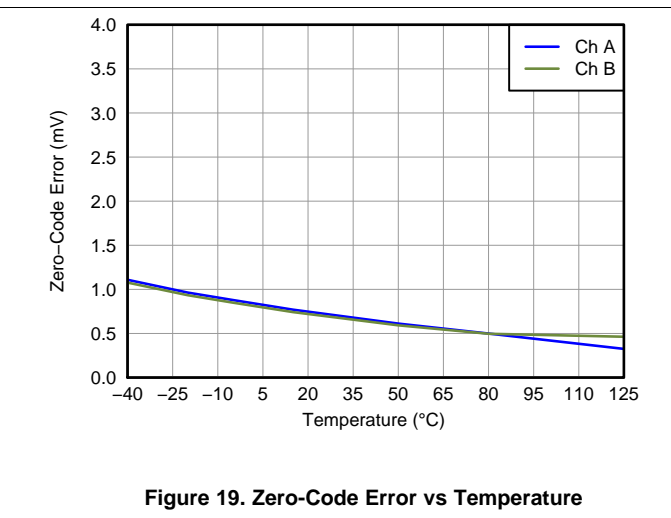
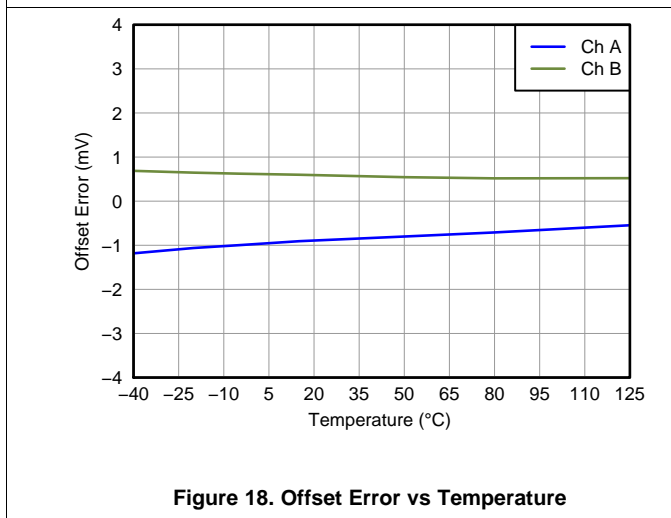
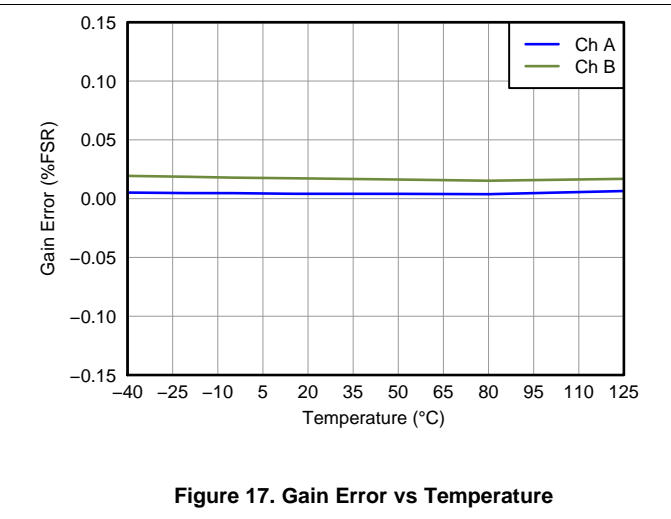
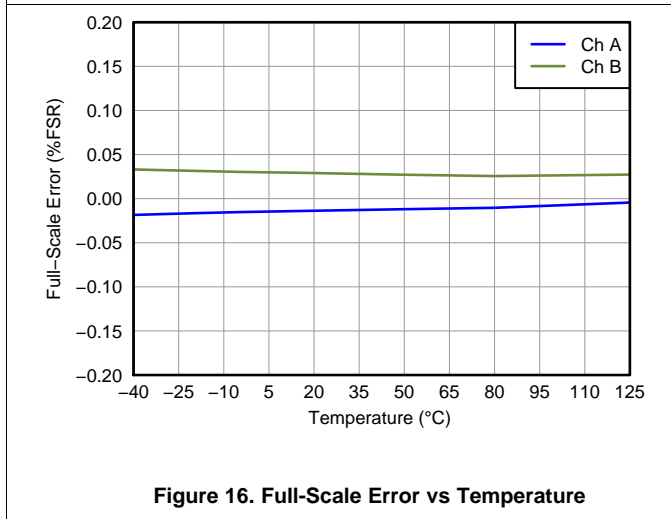
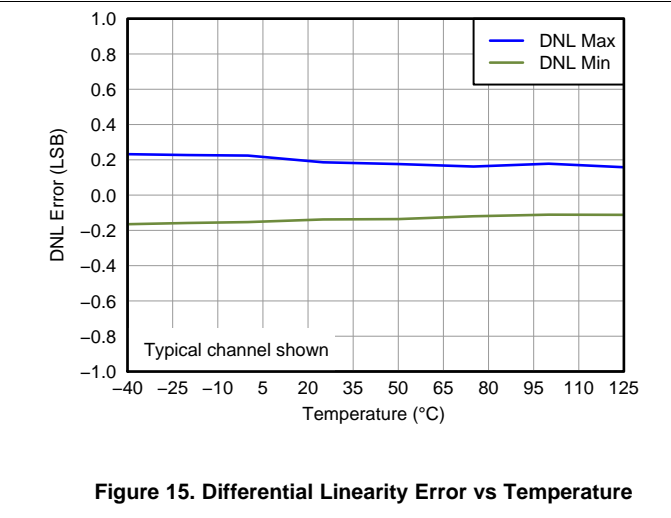
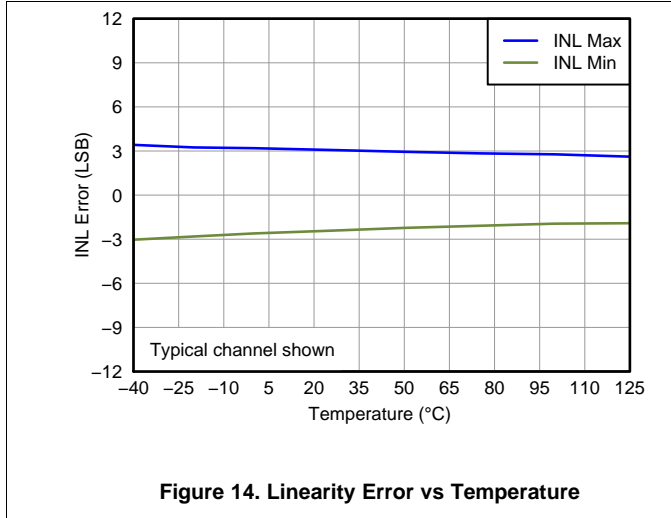


Figure 13. Differential Linearity Error vs Digital Input Code ( $125^\circ\text{C}$ )

Typical Characteristics: DAC at AV<sub>DD</sub> = 5.5 V (continued)

At T<sub>A</sub> = 25°C, 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.



**Typical Characteristics: DAC at  $V_{DD} = 5.5\text{ V}$  (continued)**

At  $T_A = 25^\circ\text{C}$ , 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.

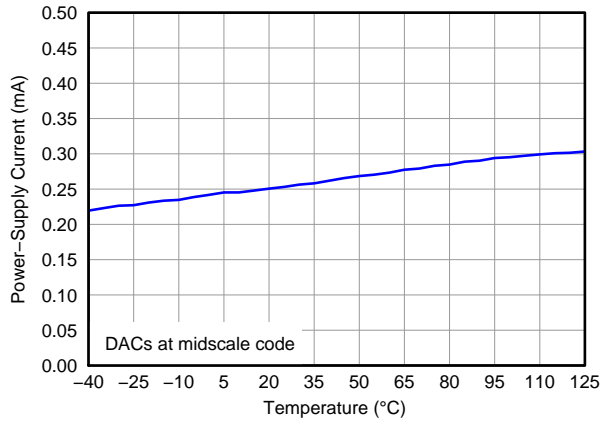


Figure 20. Power-Supply Current vs Temperature

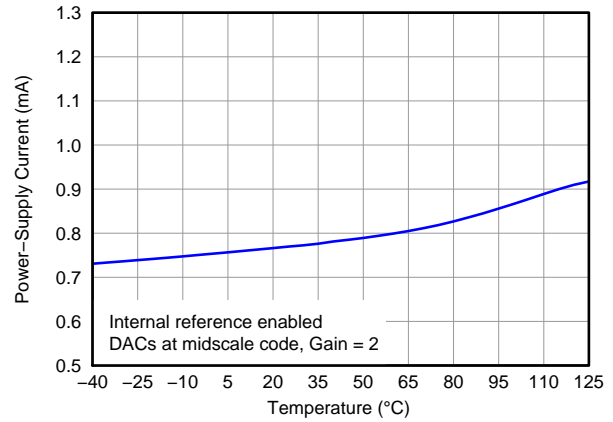


Figure 21. Power-Supply Current vs Temperature

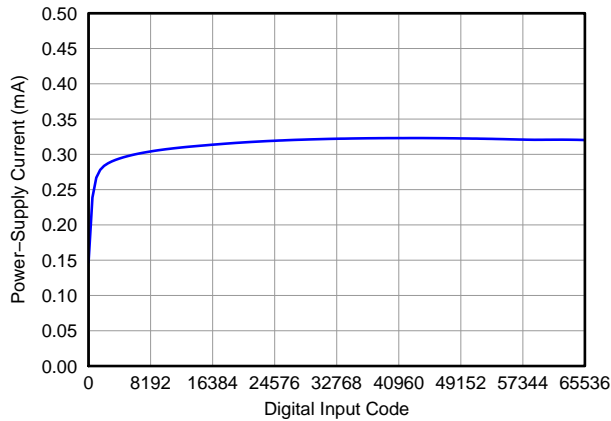


Figure 22. Power-Supply Current vs Digital Input Code

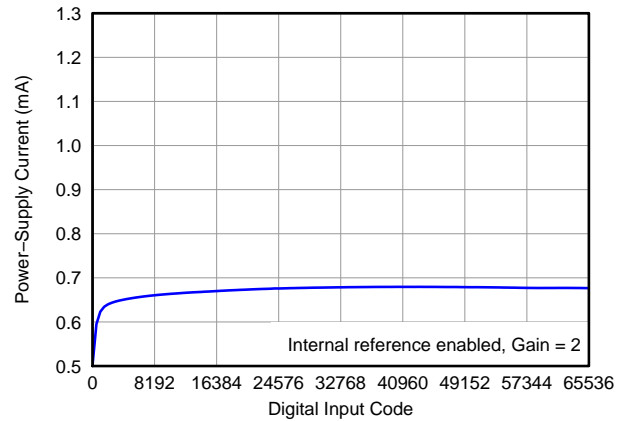


Figure 23. Power-Supply Current vs Digital Input Code

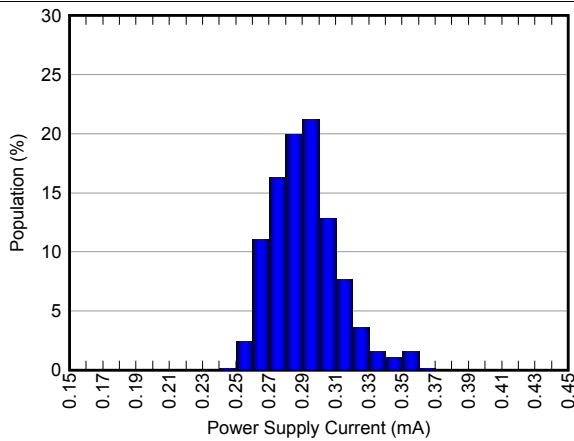


Figure 24. Power-Supply Current Histogram

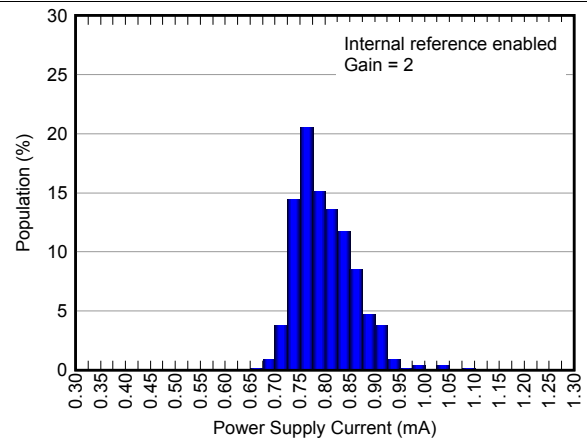


Figure 25. Power-Supply Current Histogram



Typical Characteristics: DAC at AV<sub>DD</sub> = 5.5 V (continued)

At T<sub>A</sub> = 25°C, 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.

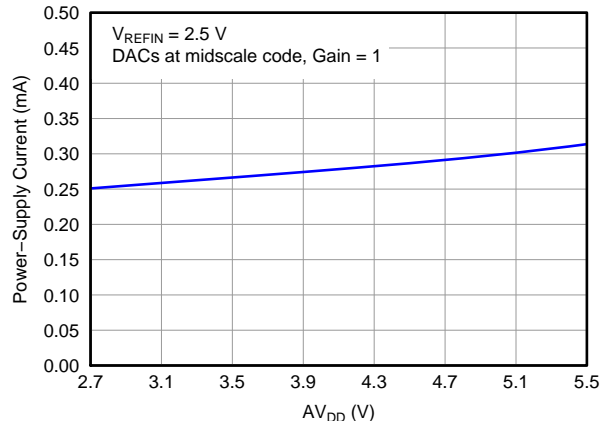


Figure 26. Power-Supply Current vs Power-Supply Voltage

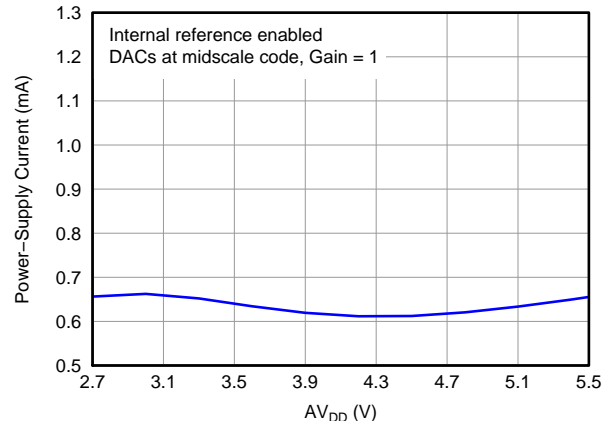


Figure 27. Power-Supply Current vs Power-Supply Voltage

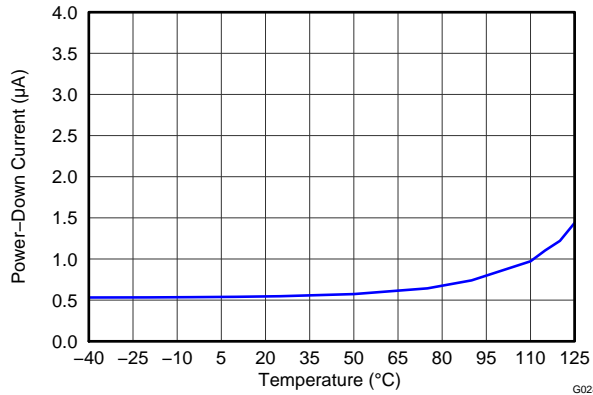


Figure 28. Power-Down Current vs Temperature

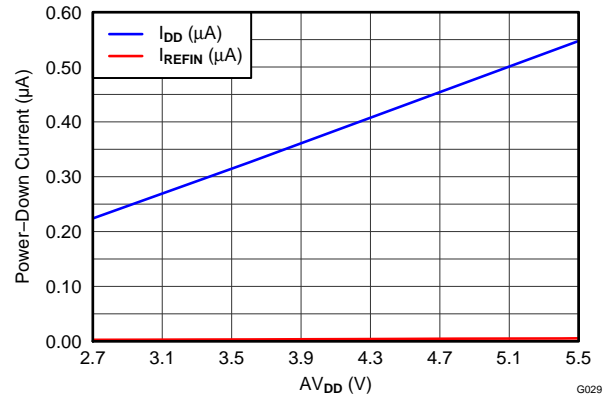


Figure 29. Power-Down Current vs Power-Supply Voltage

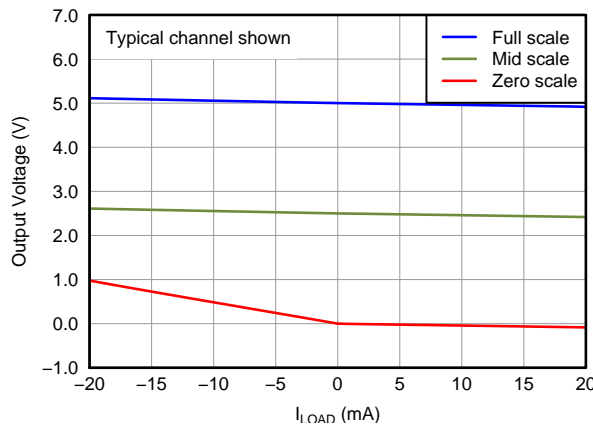
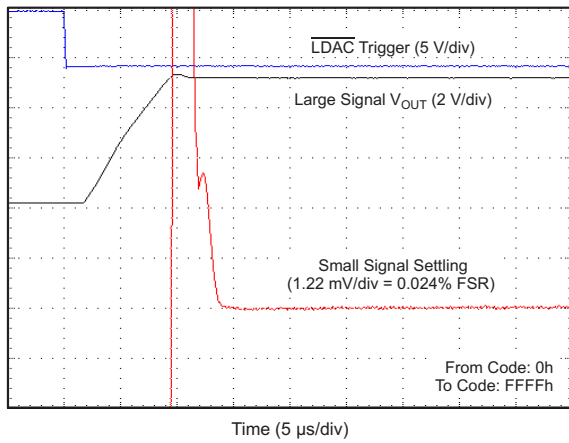


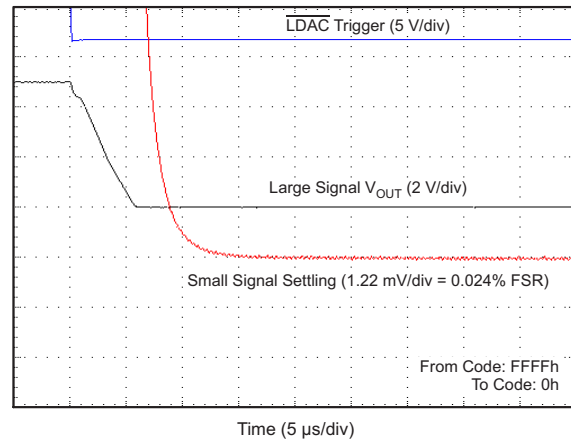
Figure 30. DAC Output Voltage vs Load Current

**Typical Characteristics: DAC at  $V_{DD} = 5.5\text{ V}$  (continued)**

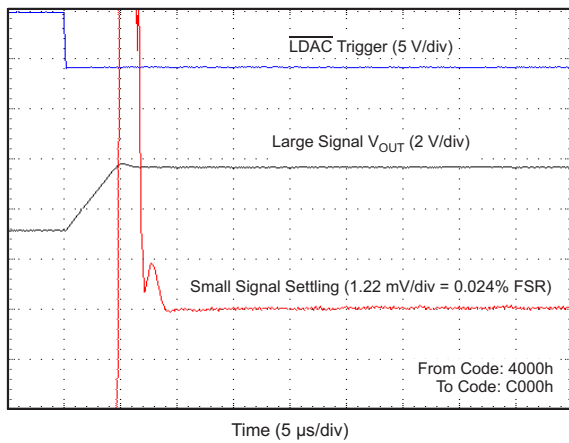
At  $T_A = 25^\circ\text{C}$ , 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.



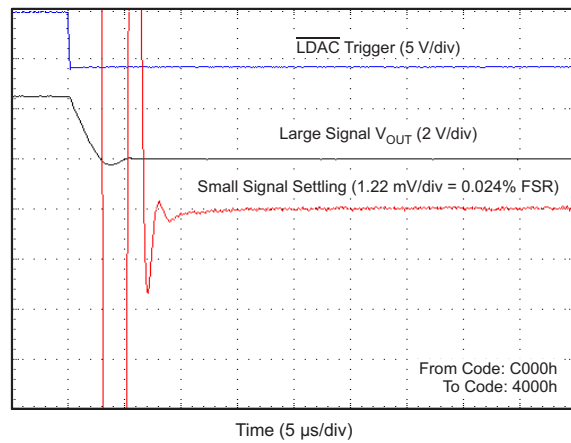
**Figure 31. Full-Scale Settling Time, Rising Edge**



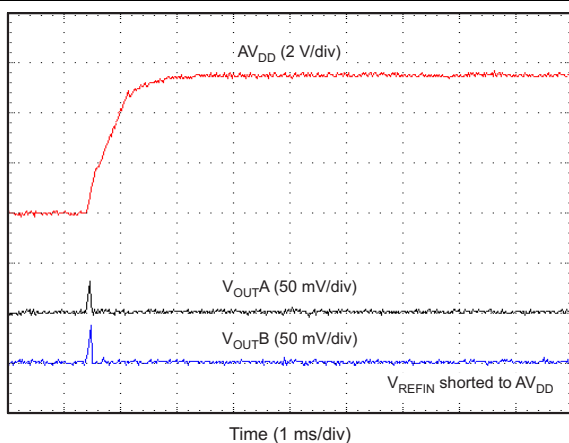
**Figure 32. Full-Scale Settling Time, Falling Edge**



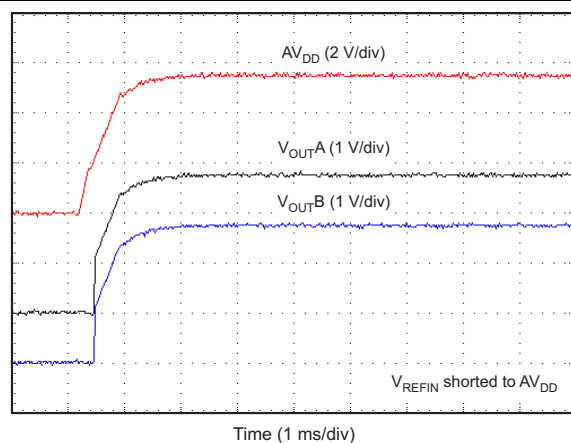
**Figure 33. Half-Scale Settling Time, Rising Edge**



**Figure 34. Half-Scale Settling Time, Falling Edge**



**Figure 35. Power-On Glitch, Reset to Zero Scale**



**Figure 36. Power-On Glitch, Reset to Midscale**

Typical Characteristics: DAC at  $AV_{DD} = 5.5\text{ V}$  (continued)

At  $T_A = 25^\circ\text{C}$ , 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.

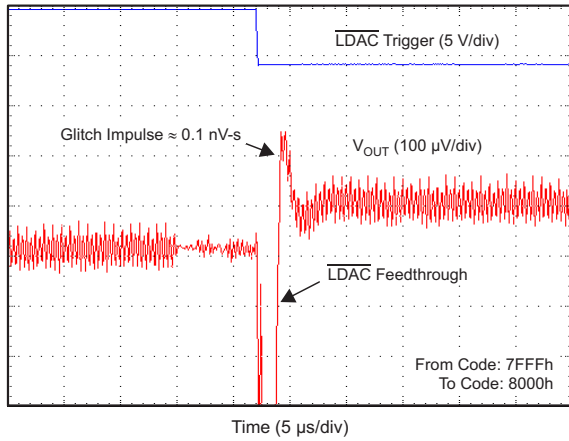


Figure 37. Glitch Impulse, Rising Edge, 1-LSB Step

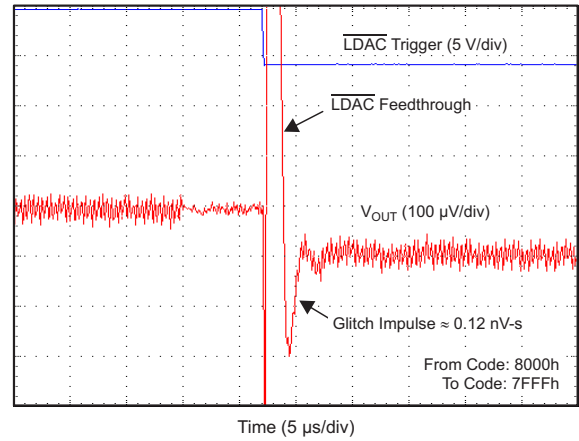


Figure 38. Glitch Impulse, Falling Edge, 1-LSB Step

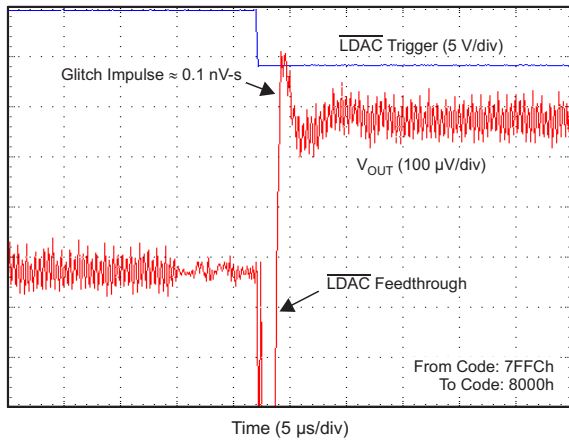


Figure 39. Glitch Impulse, Rising Edge, 4-LSB Step

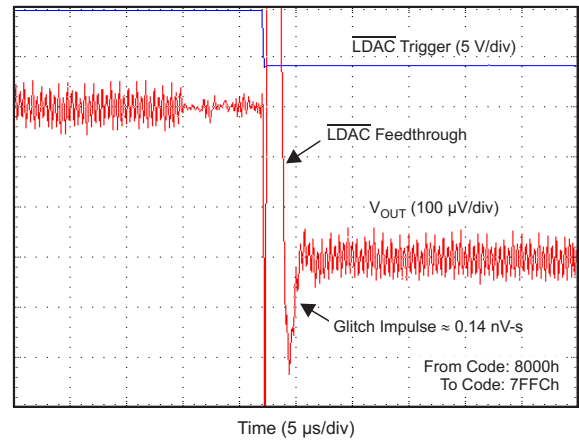


Figure 40. Glitch Impulse, Falling Edge, 4-LSB Step

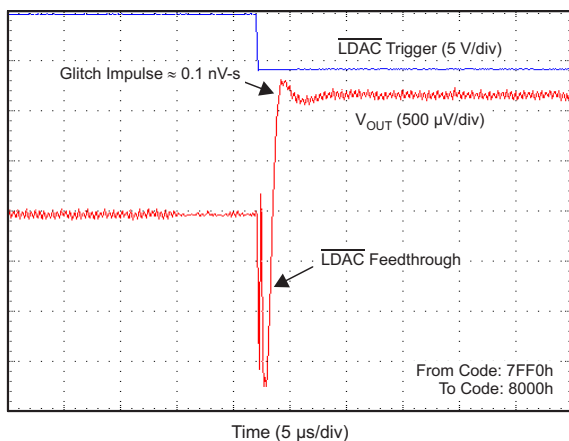


Figure 41. Glitch Impulse, Rising Edge, 16-LSB Step

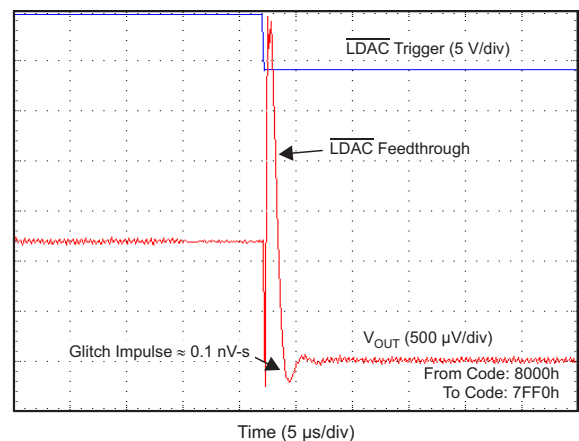
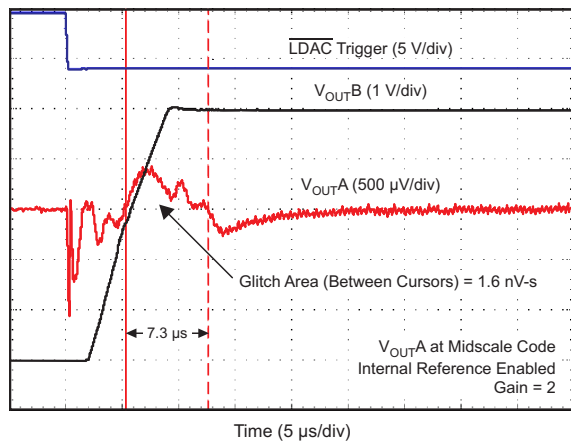


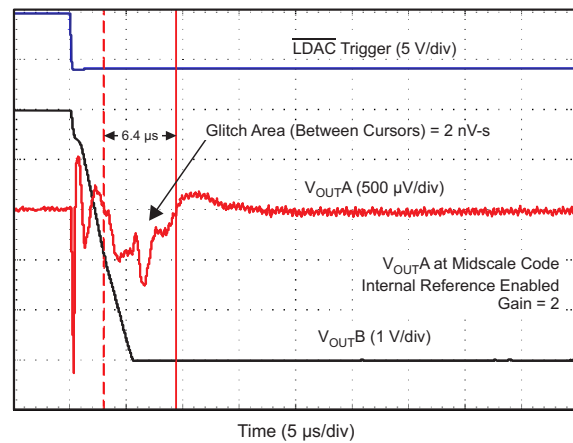
Figure 42. Glitch Impulse, Falling Edge, 16-LSB Step

**Typical Characteristics: DAC at  $V_{DD} = 5.5\text{ V}$  (continued)**

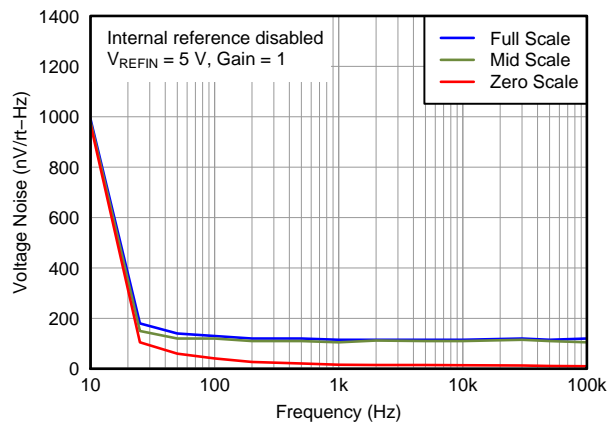
At  $T_A = 25^\circ\text{C}$ , 5-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.



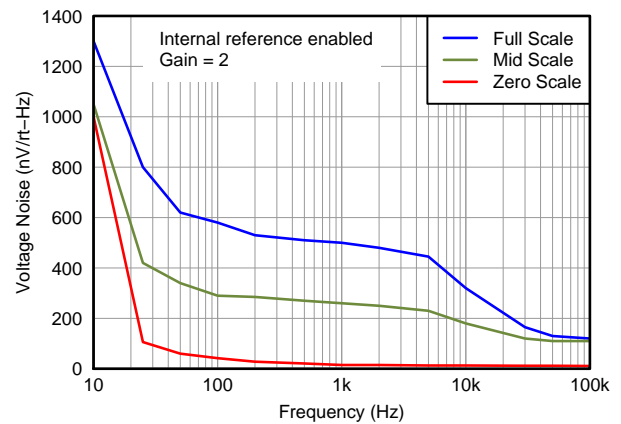
**Figure 43. Channel-to-Channel Crosstalk, 5-V Rising Edge**



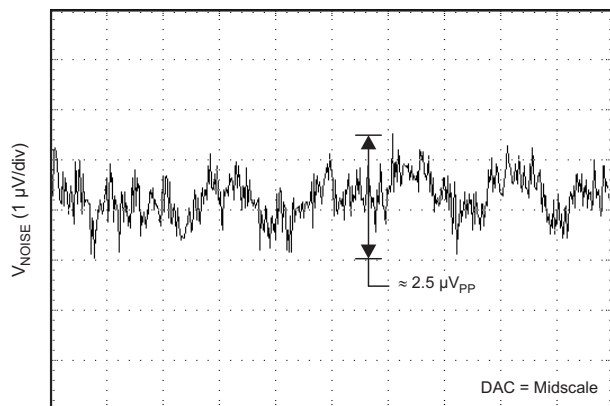
**Figure 44. Channel-to-Channel Crosstalk, 5-V Falling Edge**



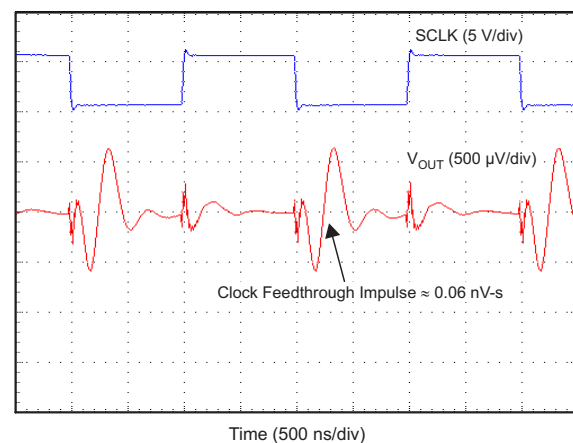
**Figure 45. DAC Output Noise Density vs Frequency**



**Figure 46. DAC Output Noise Density vs Frequency**



**Figure 47. DAC Output Noise, 0.1 Hz to 10 Hz**



**Figure 48. Clock Feedthrough, 500 kHz, Midscale**

### 7.7.3 Typical Characteristics: DAC at $V_{DD} = 3.6\text{ V}$

At  $T_A = 25^\circ\text{C}$ , 3.3-V external reference used, gain = 1 and DAC output not loaded, unless otherwise noted.

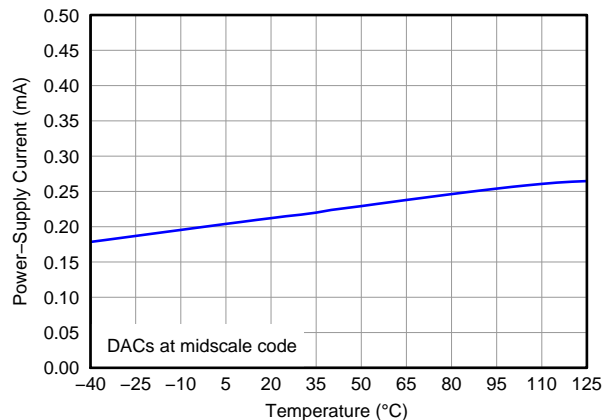


Figure 49. Power-Supply Current vs Temperature

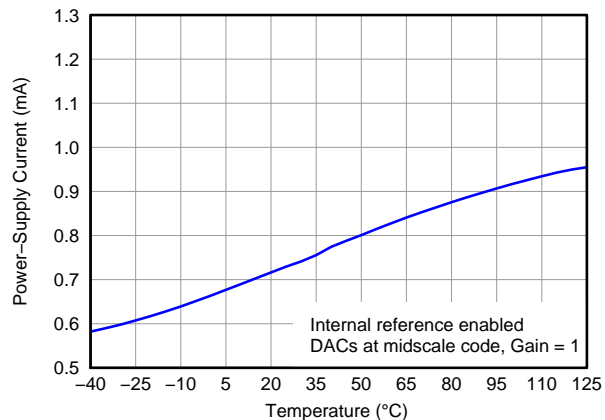


Figure 50. Power-Supply Current vs Temperature

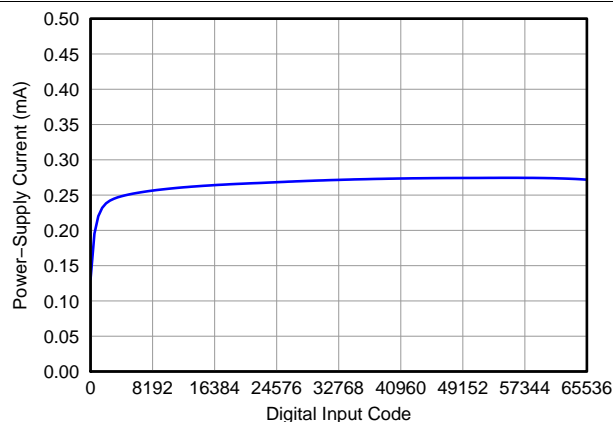


Figure 51. Power-Supply Current vs Digital Input Code

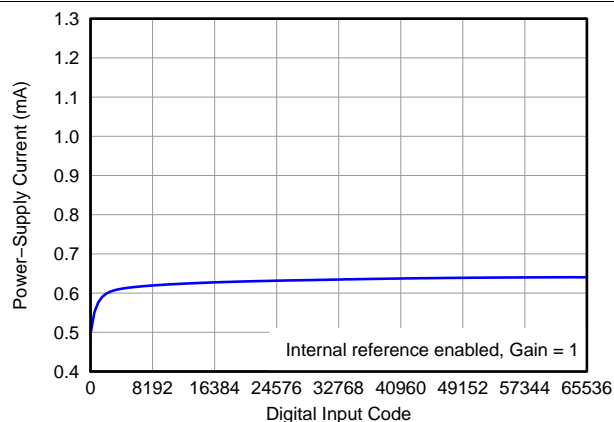


Figure 52. Power-Supply Current vs Digital Input Code

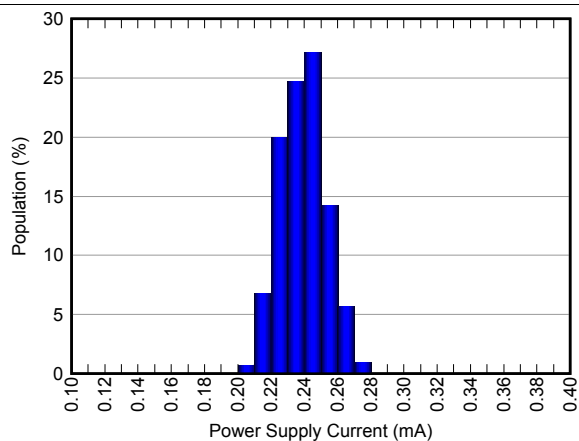


Figure 53. Power-Supply Current Histogram

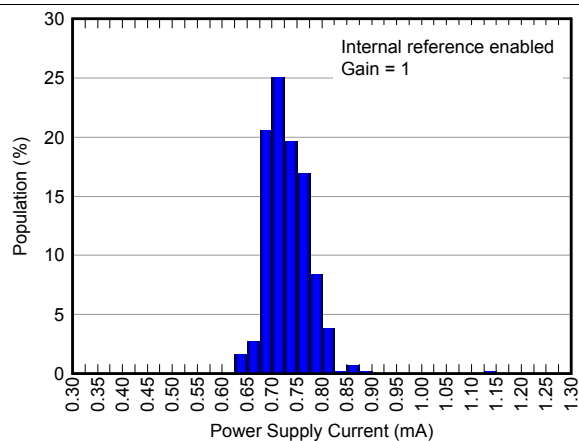


Figure 54. Power-Supply Current Histogram

### 7.7.4 Typical Characteristics: DAC at $V_{DD} = 2.7\text{ V}$

At  $T_A = 25^\circ\text{C}$ , 2.5-V external reference used, gain = 1, and DAC output not loaded, unless otherwise noted.

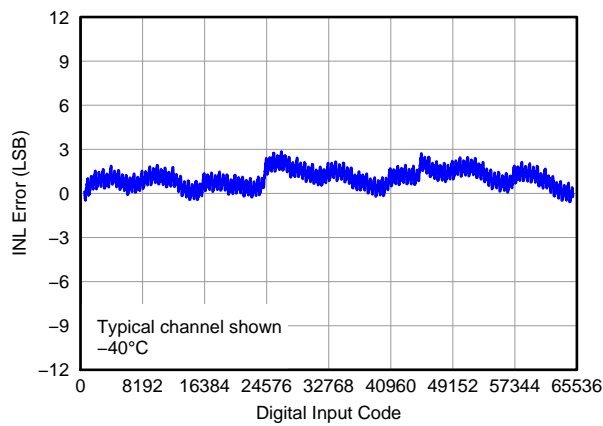


Figure 55. Linearity Error vs Digital Input Code ( $-40^\circ\text{C}$ )

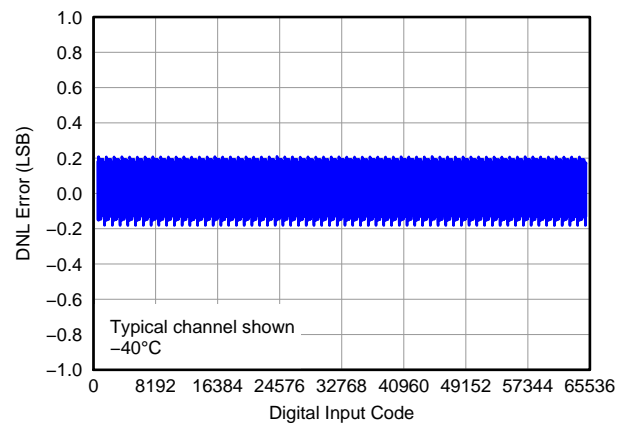


Figure 56. Differential Linearity Error vs Digital Input Code ( $-40^\circ\text{C}$ )

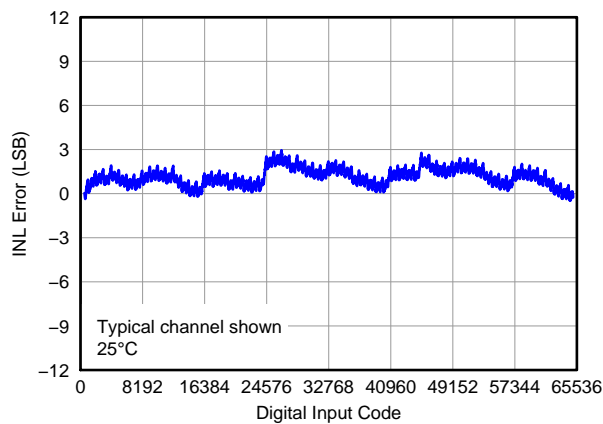


Figure 57. Linearity Error vs Digital Input Code ( $25^\circ\text{C}$ )

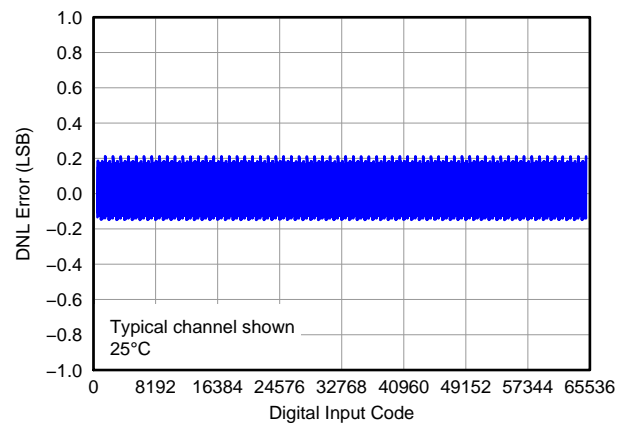


Figure 58. Differential Linearity Error vs Digital Input Code ( $25^\circ\text{C}$ )

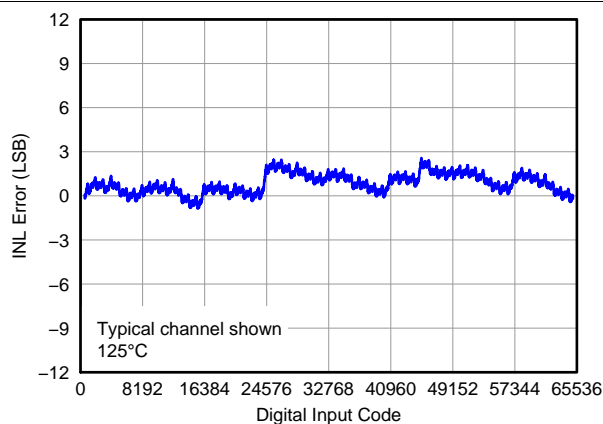


Figure 59. Linearity Error vs Digital Input Code ( $125^\circ\text{C}$ )

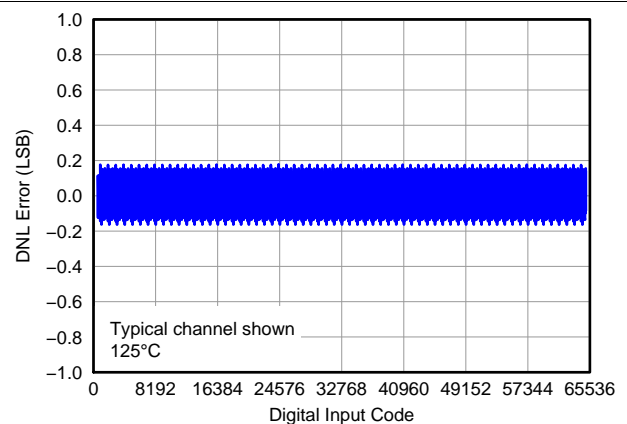
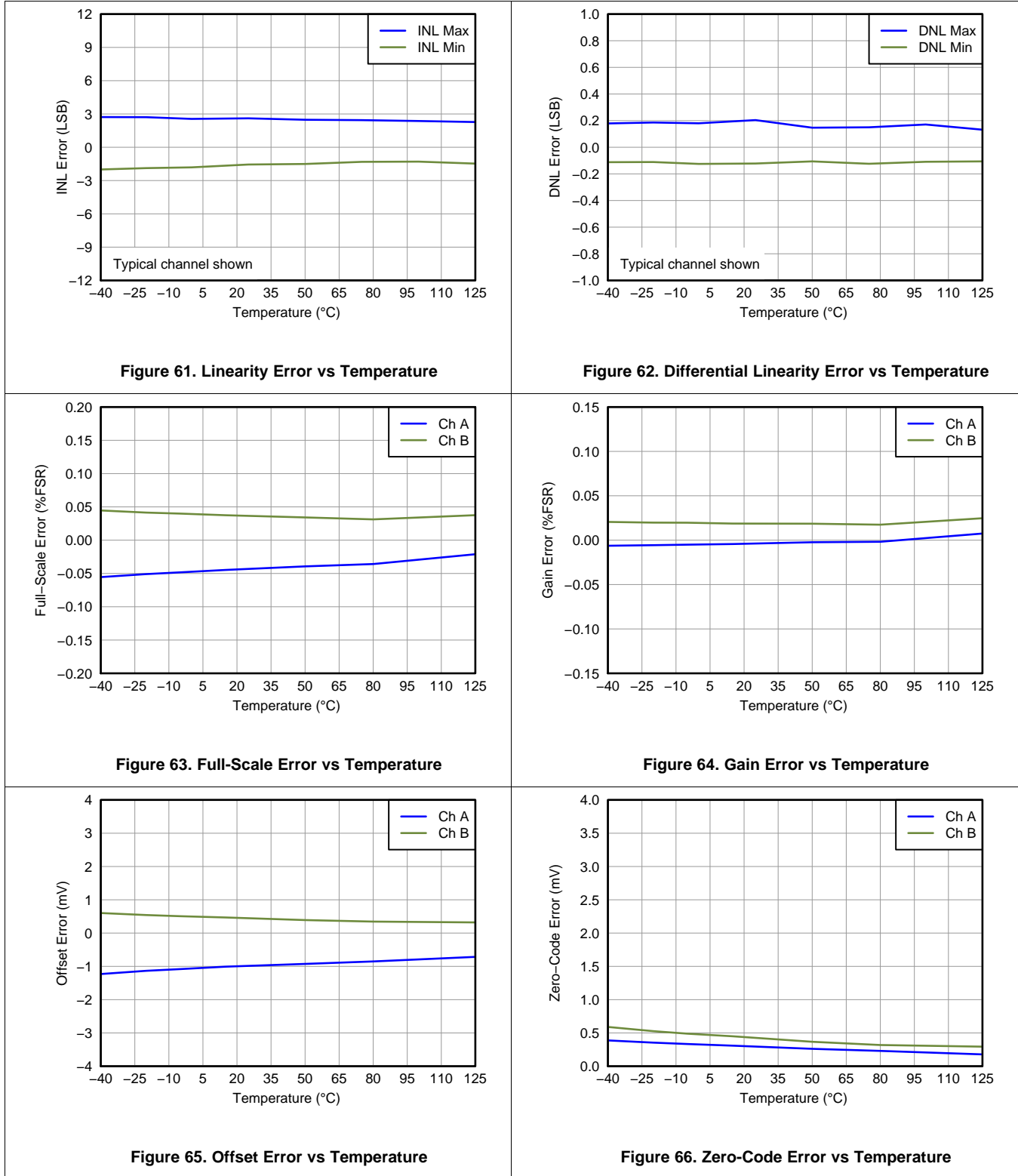


Figure 60. Differential Linearity Error vs Digital Input Code ( $125^\circ\text{C}$ )

Typical Characteristics: DAC at  $AV_{DD} = 2.7\text{ V}$  (continued)

At  $T_A = 25^\circ\text{C}$ , 2.5-V external reference used, gain = 1, and DAC output not loaded, unless otherwise noted.



Typical Characteristics: DAC at  $V_{DD} = 2.7\text{ V}$  (continued)

At  $T_A = 25^\circ\text{C}$ , 2.5-V external reference used, gain = 1, and DAC output not loaded, unless otherwise noted.

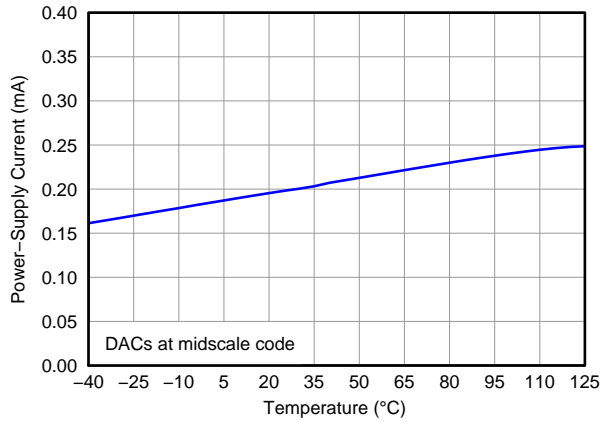


Figure 67. Power-Supply Current vs Temperature

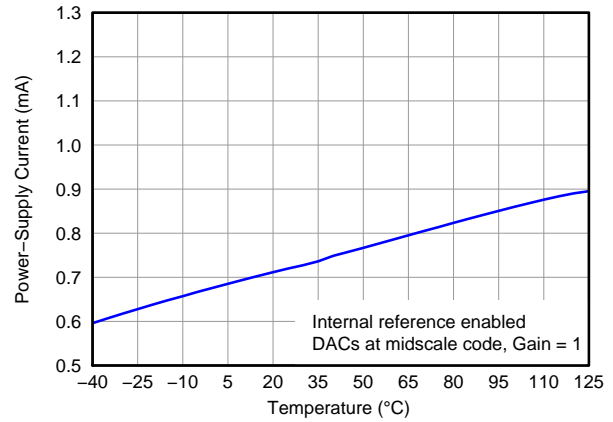


Figure 68. Power-Supply Current vs Temperature

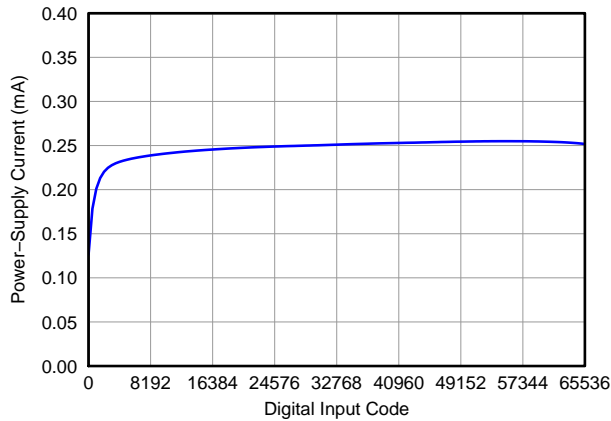


Figure 69. Power-Supply Current vs Digital Input Code

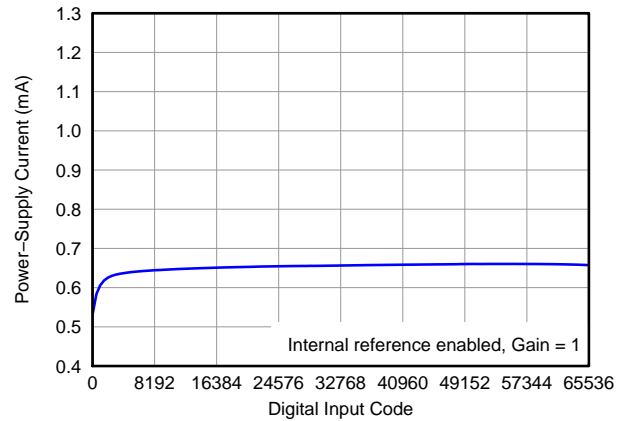


Figure 70. Power-Supply Current vs Digital Input Code

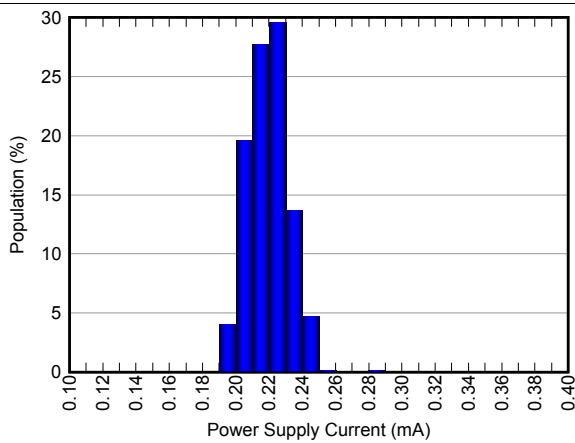


Figure 71. Power-Supply Current Histogram

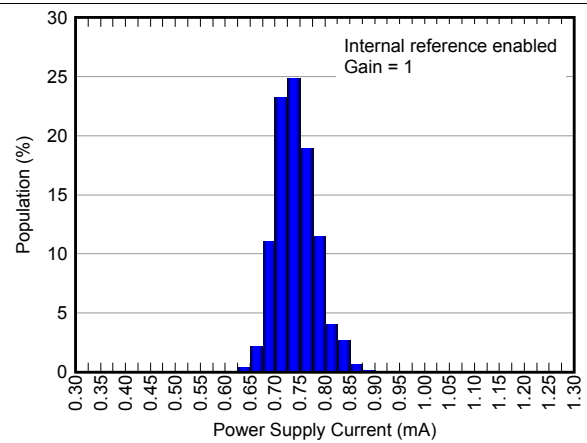


Figure 72. Power-Supply Current Histogram



Typical Characteristics: DAC at AV<sub>DD</sub> = 2.7 V (continued)

At T<sub>A</sub> = 25°C, 2.5-V external reference used, gain = 1, and DAC output not loaded, unless otherwise noted.

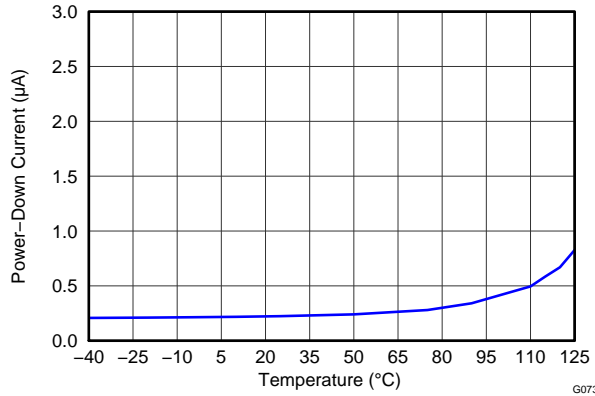


Figure 73. Power-Down Current vs Temperature

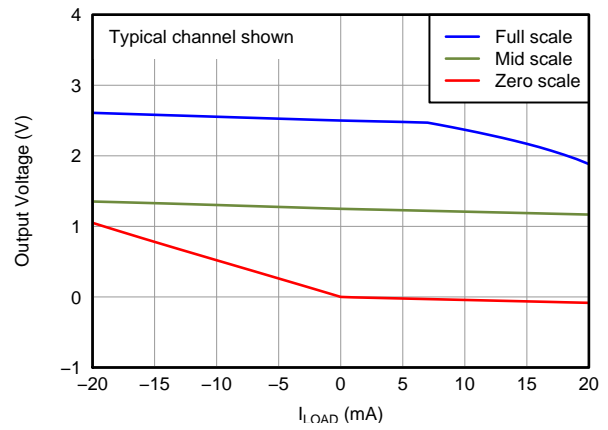


Figure 74. DAC Output Voltage vs Load Current

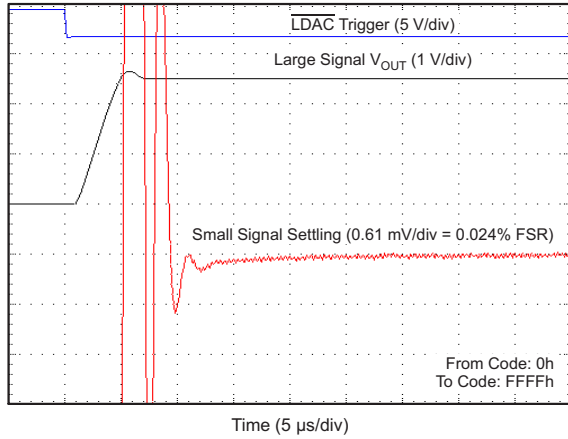


Figure 75. Full-Scale Settling Time, Rising Edge

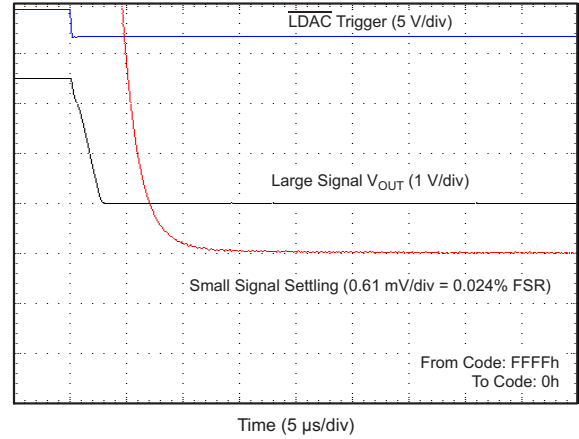


Figure 76. Full-Scale Settling Time, Falling Edge

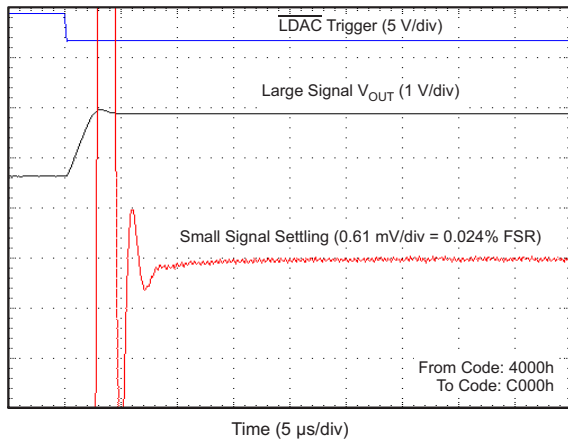


Figure 77. Half-Scale Settling Time, Rising Edge

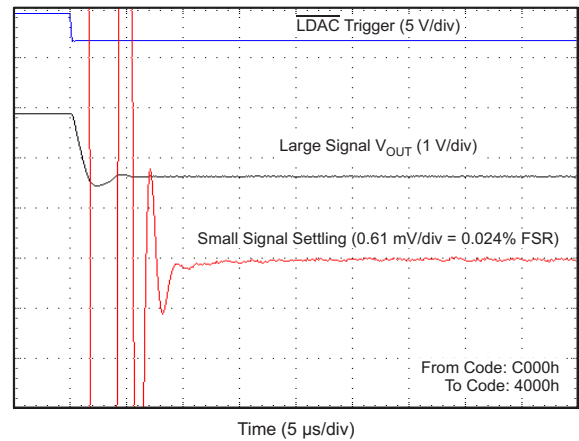


Figure 78. Half-Scale Settling Time, Falling Edge

Typical Characteristics: DAC at  $AV_{DD} = 2.7\text{ V}$  (continued)

At  $T_A = 25^\circ\text{C}$ , 2.5-V external reference used, gain = 1, and DAC output not loaded, unless otherwise noted.

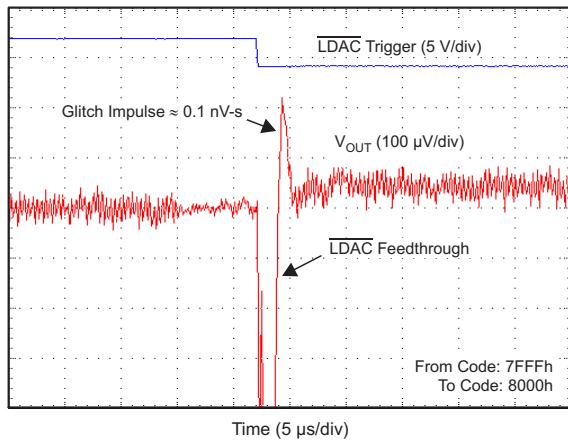


Figure 79. Glitch Impulse, Rising Edge, 1-LSB Step

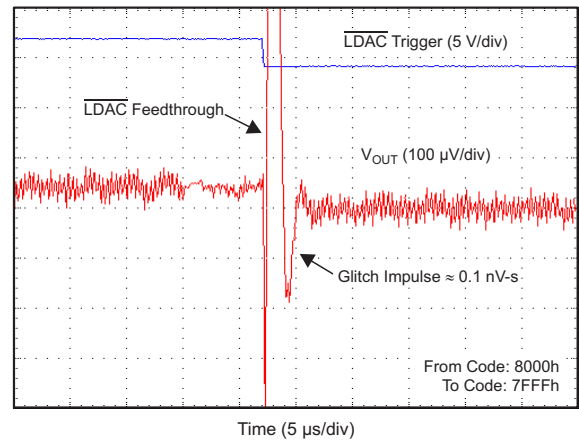


Figure 80. Glitch Impulse, Falling Edge, 1-LSB Step

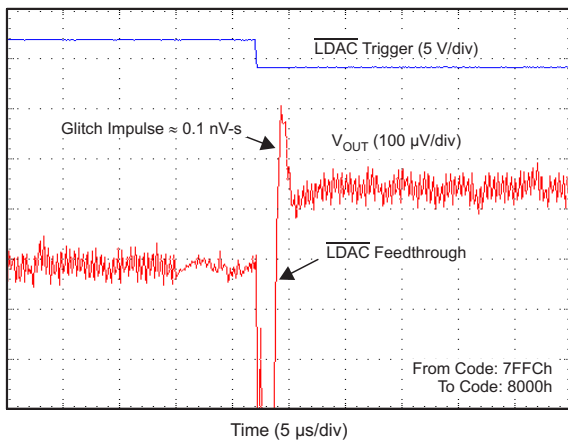


Figure 81. Glitch Impulse, Rising Edge, 4-LSB Step



Figure 82. Glitch Impulse, Falling Edge, 4-LSB Step

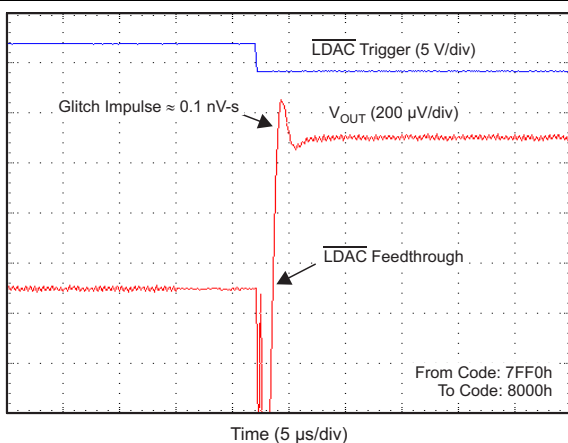


Figure 83. Glitch Impulse, Rising Edge, 16-LSB Step

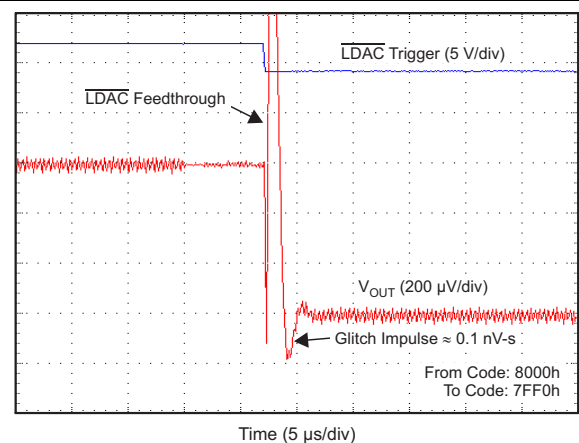
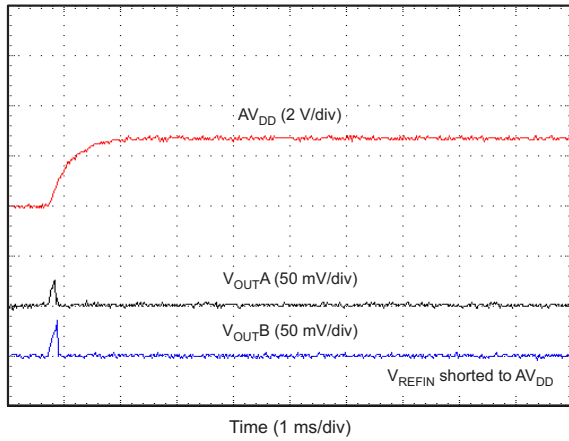


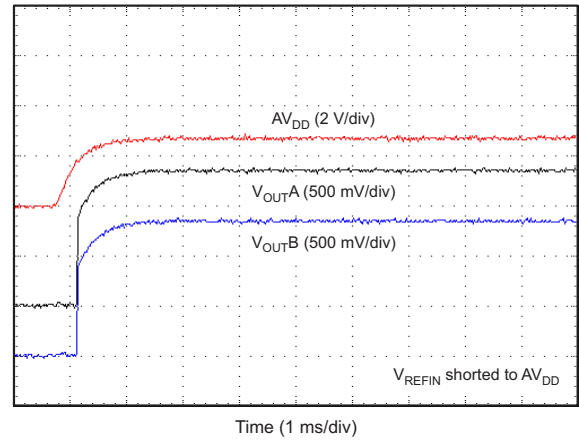
Figure 84. Glitch Impulse, Falling Edge, 16-LSB Step

**Typical Characteristics: DAC at  $AV_{DD} = 2.7\text{ V}$  (continued)**

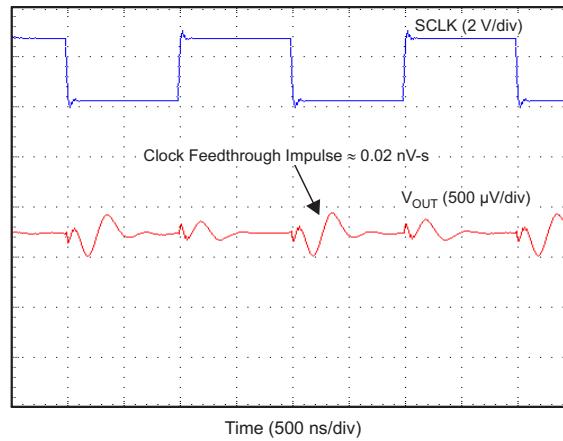
At  $T_A = 25^\circ\text{C}$ , 2.5-V external reference used, gain = 1, and DAC output not loaded, unless otherwise noted.



**Figure 85. Power-On Glitch, Reset to Zero Scale**



**Figure 86. Power-On Glitch, Reset to Midscale**



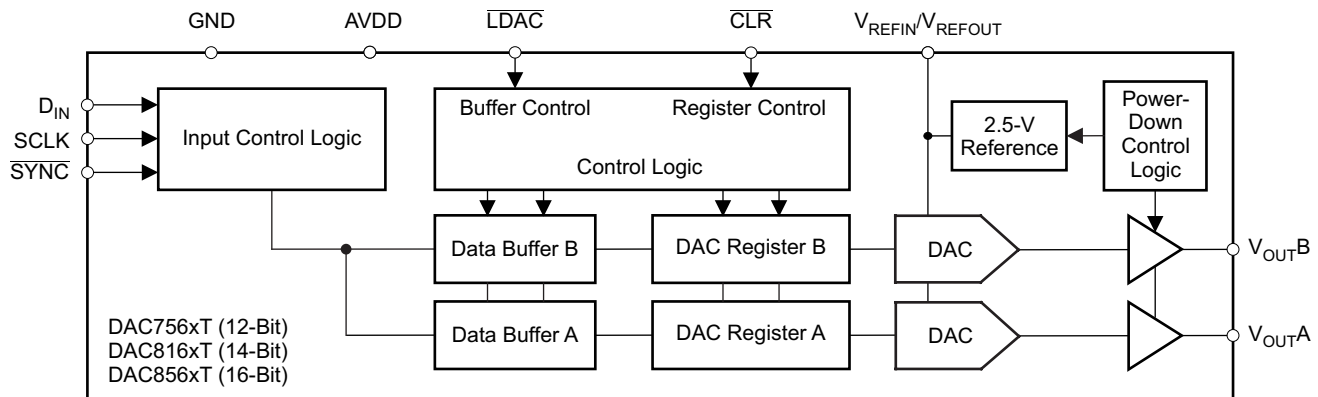
**Figure 87. Clock Feedthrough, 500 kHz, Midscale**

## 8 Detailed Description

### 8.1 Overview

The DAC756xT, DAC816xT, and DAC856xT devices are low-power, voltage-output, dual-channel, 16-, 14-, and 12-bit digital-to-analog converters (DACs), respectively. These devices include a 2.5-V, 4-ppm/°C internal reference, giving a full-scale output voltage range of 2.5 V or 5 V. The internal reference has an initial accuracy of ±5 mV and can source or sink up to 20 mA at the  $V_{REFIN}/V_{REFOUT}$  pin.

### 8.2 Functional Block Diagram



### 8.3 Feature Description

#### 8.3.1 Digital-to-Analog Converter (DAC)

The DAC756xT, DAC816xT, and DAC856xT architecture consists of two string DACs, each followed by an output buffer amplifier. The devices include an internal 2.5-V reference with 4-ppm/°C temperature drift performance. Figure 88 shows a principal block diagram of the DAC architecture.

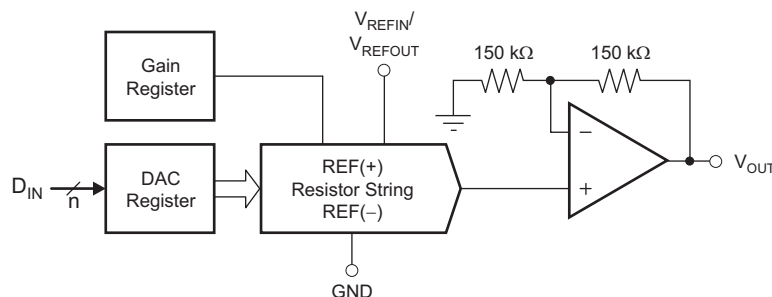


Figure 88. DAC Architecture

The input coding to the DAC756xT, DAC816xT, and DAC856xT devices is straight binary, so the ideal output voltage is given by Equation 1:

$$V_{OUT} = \left( \frac{D_{IN}}{2^n} \right) \times V_{REF} \times \text{Gain} \quad (1)$$

where:

$n$  = resolution in bits; either 12 (DAC756xT), 14 (DAC816xT) or 16 (DAC856xT)

$D_{IN}$  = decimal equivalent of the binary code that is loaded to the DAC register.  $D_{IN}$  ranges from 0 to  $2^n - 1$ .  
 $V_{REF}$  = DAC reference voltage; either  $V_{REFOUT}$  from the internal 2.5-V reference or  $V_{REFIN}$  from an external reference.

Gain = 1 by default when internal reference is disabled (using external reference), and gain = 2 by default when using internal reference. Gain can also be manually set to either 1 or 2 using the gain register. See the [Gain Function](#) section for more information.

## Feature Description (continued)

### 8.3.1.1 Resistor String

The resistor string section is shown in [Figure 89](#). It is simply a string of resistors, each of value  $R$ . The code loaded into the DAC register determines at which node on the string the voltage is tapped off to be fed into the output amplifier by closing one of the switches connecting the string to the amplifier. The resistor string architecture results in monotonicity. The  $R_{\text{DIVIDER}}$  switch is controlled by the gain registers (see the [Gain Function](#) section). Because the output amplifier has a gain of 2,  $R_{\text{DIVIDER}}$  is not shorted when the DAC-n gain is set to 1 (default if internal reference is disabled), and is shorted when the DAC-n gain is set to 2 (default if internal reference is enabled).

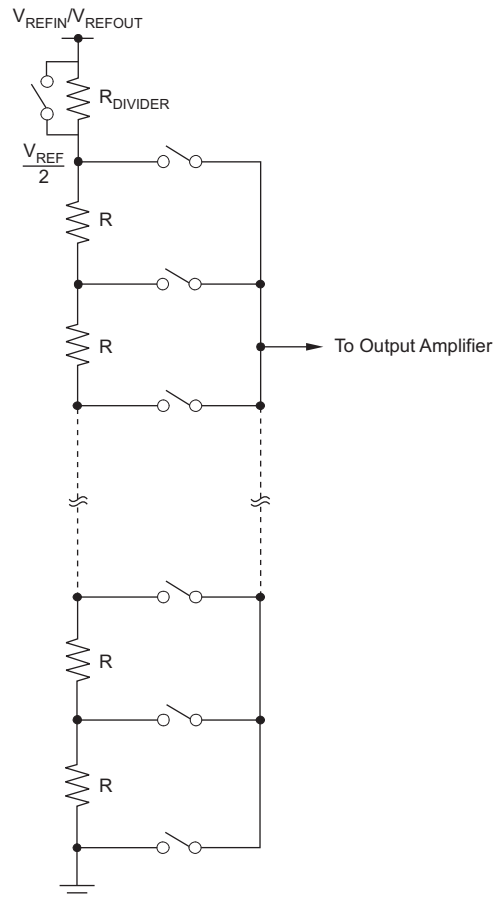


Figure 89. Resistor String

### 8.3.1.2 Output Amplifier

The output buffer amplifier is capable of generating rail-to-rail voltages on its output, giving a maximum output range of 0 V to  $AV_{\text{DD}}$ . It is capable of driving a load of 2 k $\Omega$  in parallel with 3 nF to GND. The typical slew rate is 0.75 V/ $\mu\text{s}$ , with a typical full-scale settling time of 14  $\mu\text{s}$  as shown in [Figure 31](#), [Figure 32](#), [Figure 75](#) and [Figure 76](#).

## Feature Description (continued)

### 8.3.2 Internal Reference

The DAC756xT, DAC816xT, and DAC856xT devices include a 2.5-V internal reference that is disabled by default. The internal reference is externally available at the  $V_{REFIN}/V_{REFOUT}$  pin. The internal reference output voltage is 2.5 V and can sink and source up to 20 mA.

A minimum 150-nF capacitor is recommended between the reference output and GND for noise filtering.

The internal reference of the DAC756xT, DAC816xT, and DAC856xT devices is a bipolar transistor-based precision band-gap voltage reference. Figure 90 shows the basic band-gap topology. Transistors  $Q_1$  and  $Q_2$  are biased such that the current density of  $Q_1$  is greater than that of  $Q_2$ . The difference of the two base-emitter voltages ( $V_{BE1} - V_{BE2}$ ) has a positive temperature coefficient and is forced across resistor  $R_1$ . This voltage is amplified and added to the base-emitter voltage of  $Q_2$ , which has a negative temperature coefficient. The resulting output voltage is virtually independent of temperature. The short-circuit current is limited by design to approximately 100 mA.

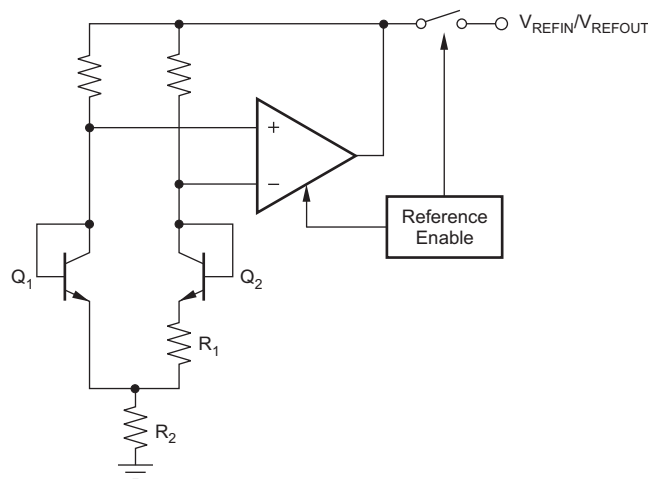


Figure 90. Band-Gap Reference Simplified Schematic

### 8.3.3 Power-On Reset

#### 8.3.3.1 Power-On Reset to Zero-Scale

The DAC7562T, DAC8162T, and DAC8562T devices contain a power-on-reset circuit that controls the output voltage during power up. All device registers are reset as shown in Table 4. At power up, all DAC registers are filled with zeros and the output voltages of all DAC channels are set to zero volts. Each DAC channel remains that way until a valid load command is written to it. The power-on reset is useful in applications where it is important to know the state of the output of each DAC while the device is in the process of powering up. No device pin should be brought high before applying power to the device. The internal reference is disabled by default and remains that way until a valid reference-change command is executed.

#### 8.3.3.2 Power-On Reset to Mid-Scale

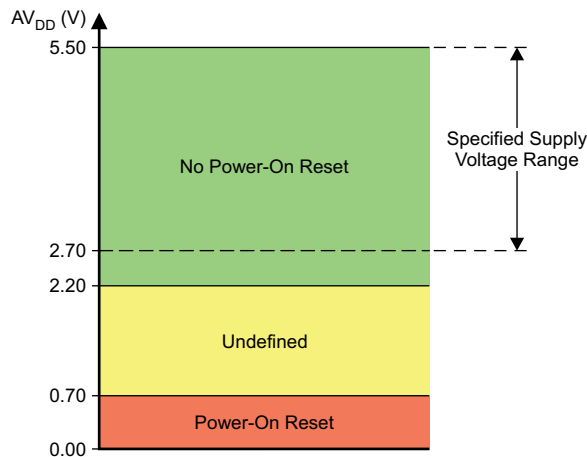
The DAC7563T, DAC8163T, and DAC8563T devices contain a power-on reset circuit that controls the output voltage during power up. At power up, all DAC registers are reset to mid-scale code and the output voltages of all DAC channels are set to  $V_{REFIN} / 2$  volts. Each DAC channel remains that way until a valid load command is written to it. The power-on reset is useful in applications where it is important to know the state of the output of each DAC while the device is in the process of powering up. No device pin should be brought high before applying power to the device. The internal reference is powered off or down by default and remains that way until a valid reference-change command is executed. If using an external reference, it is acceptable to power on the  $V_{REFIN}$  pin either at the same time as or after applying  $AV_{DD}$ .

**Table 4. DACxx62T and DACxx63T Power-On Reset Values**

REGISTER	DEFAULT SETTING	
DAC and input registers	DACxx62T	Zero-scale
	DACxx63T	Mid-scale
LDAC registers	LDAC pin enabled for both channels	
Power-down registers	DACs powered up	
Internal reference register	Internal reference disabled	
Gain registers	Gain = 1 for both channels	

**8.3.3.3 Power-On Reset (POR) Levels**

When the device powers up, a POR circuit sets the device in default mode as shown in Table 4. The POR circuit requires specific AV<sub>DD</sub> levels, as indicated in Figure 91, to ensure discharging of internal capacitors and to reset the device on power up. In order to ensure a power-on reset, AV<sub>DD</sub> must be below 0.7 V for at least 1 ms. When AV<sub>DD</sub> drops below 2.2 V but remains above 0.7 V (shown as the undefined region), the device may or may not reset under all specified temperature and power-supply conditions. In this case, TI recommends a power-on reset. When AV<sub>DD</sub> remains above 2.2 V, a power-on reset does not occur.



**Figure 91. Relevant Voltage Levels for POR Circuit**

## 8.4 Device Functional Modes

### 8.4.1 Power-Down Modes

The DAC756xT, DAC816xT, and DAC856xT devices have two separate sets of power-down commands. One set is for the DAC channels and the other set is for the internal reference. The internal reference is forced to a powered-down state while both DAC channels are powered down, and is only enabled if any DAC channel is also in the normal mode of operation. For more information on the internal reference control, see the [Internal Reference Enable Register](#) section.

#### 8.4.1.1 DAC Power-Down Commands

The DAC756xT, DAC816xT, and DAC856xT DACs use four modes of operation. These modes are accessed by setting the serial interface command bits to 100. Once the command bits are set correctly, the four different power-down modes are software programmable by setting bits DB5 and DB4 in the shift register. [Table 5](#) and [Table 6](#) show the different power-down options. For more information on how to set the DAC operating mode see [Table 17](#).

**Table 5. DAC-n Operating Modes**

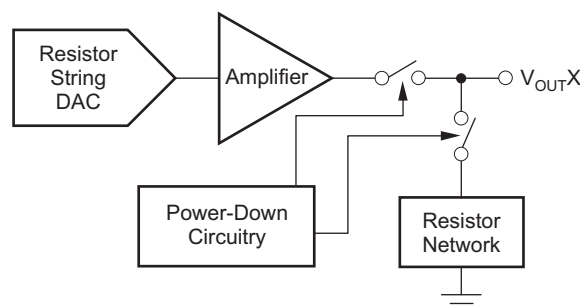
DB5	DB4	DAC Modes of Operation
0	0	Selected DACs power up (normal mode, default)
0	1	Selected DACs power down, output 1 kΩ to GND
1	0	Selected DACs power down, output 100 kΩ to GND
1	1	Selected DACs power down, output Hi-Z to GND

**Table 6. DAC-n Selection for Operating Modes**

DAC-B (DB1), DAC-A (DB0)	Operating Mode
0	DAC-n does not change operating mode
1	DAC-n operating mode set to value on PD1 and PD0

It is possible to write to the DAC register or buffer of the DAC channel that is powered down. When the DAC channel is then powered up, it powers up to this new value.

The advantage of the available power-down modes is that the output impedance of the device is known while it is in power-down mode. As described in [Table 5](#), there are three different power-down options.  $V_{OUT}$  can be connected internally to GND through a 1-kΩ resistor, a 100-kΩ resistor, or open-circuited (Hi-Z). The DAC power-down circuitry is shown in [Figure 92](#).



**Figure 92. Output Stage**



### 8.4.2 Gain Function

The gain register controls the GAIN setting in the DAC transfer function:

$$V_{OUT} = \left( \frac{D_{IN}}{2^n} \right) \times V_{REF} \times \text{Gain} \quad (2)$$

The DAC756xT, DAC816xT, and DAC856xT devices have a gain register for each channel. The gain for each channel, in [Equation 2](#), is either 1 or 2. This gain is automatically set to 2 when using the internal reference, and is automatically set to 1 when the internal reference is disabled (default). However, each channel can have either gain by setting the registers appropriately. The gain registers are accessible by setting the serial interface command bits to 000, address bits to 010, and using DB1 for DAC-B and DB0 for DAC-A. See [Table 7](#) and [Table 17](#) for the full command structure. The gain registers are automatically reset to provide either gain of 1 or 2 when the internal reference is powered off or on, respectively. After the reference is powered off or on, the gain register is again accessible to change the gain.

**Table 7. DAC-n Selection for Gain Register Command**

DB1, DB0	Value	Gain
DB0	0	DAC-A uses gain = 2 (default with internal reference)
	1	DAC-A uses gain = 1 (default with external reference)
DB1	0	DAC-B uses gain = 2 (default with internal reference)
	1	DAC-B uses gain = 1 (default with external reference)

### 8.4.3 Software Reset Function

The DAC756xT, DAC816xT, and DAC856xT devices contain a software reset feature. The software reset function is accessed by setting the serial interface command bits to 101. The software reset command contains two reset modes which are software-programmable by setting bit DB0 in the shift register. [Table 8](#) and [Table 17](#) show the available software reset commands.

**Table 8. Software Reset**

DB0	Registers Reset to Default Values
0	DAC registers Input registers
1	DAC registers Input registers LDAC registers Power-down registers Internal reference register Gain registers

### 8.4.4 Internal Reference Enable Register

The internal reference in the DAC756xT, DAC816xT, and DAC856xT devices is disabled by default for debugging, evaluation purposes, or when using an external reference. The internal reference can be powered up and powered down by setting the serial interface command bits to 111 and configuring DB0 (see [Table 9](#)). The internal reference is forced to a powered down state while both DAC channels are powered down, and can only be enabled if any DAC channel is in normal mode of operation. During the time that the internal reference is disabled, the DAC functions normally using an external reference. At this point, the internal reference is disconnected from the  $V_{REFIN}/V_{REFOUT}$  pin (Hi-Z output).

**Table 9. Internal Reference**

DB0	Internal Reference Configuration
0	Disable internal reference and reset DACs to gain = 1
1	Enable internal reference and reset DACs to gain = 2

#### 8.4.4.1 Enabling Internal Reference

To enable the internal reference, refer to the command structure in [Table 17](#). When performing a power cycle to reset the device, the internal reference is switched off (default mode). In the default mode, the internal reference is powered down until a valid write sequence powers up the internal reference. However, the internal reference is forced to a disabled state while both DAC channels are powered down, and remains disabled until either DAC channel is returned to the normal mode of operation. See [DAC Power-Down Commands](#) for more information on DAC channel modes of operation.

#### 8.4.4.2 Disabling Internal Reference

To disable the internal reference, refer to the command structure in [Table 17](#). When performing a power cycle to reset the device, the internal reference is disabled (default mode).

### 8.4.5 CLR Functionality

The edge-triggered  $\overline{\text{CLR}}$  pin can be used to set the input and DAC registers immediately according to [Table 10](#). When the  $\overline{\text{CLR}}$  pin receives a falling edge signal the clear mode is activated and changes the DAC output voltages accordingly. The device exits clear mode on the 24<sup>th</sup> falling edge of the next write to the device. If the  $\overline{\text{CLR}}$  pin receives a falling edge signal during a write sequence in normal operation, the clear mode is activated and changes the input and DAC registers immediately according to [Table 10](#).

**Table 10. Clear Mode Reset Values**

DEVICE	DAC Output Entering Clear Mode
DAC8562T, DAC8162T, DAC7562T	Zero-scale
DAC8563T, DAC8163T, DAC7563T	Mid-scale

### 8.4.6 LDAC Functionality

The DAC756xT, DAC816xT, and DAC856xT devices offer both a software and hardware simultaneous update and control function. The DAC double-buffered architecture has been designed so that new data can be entered for each DAC without disturbing the analog outputs.

DAC756xT, DAC816xT, and DAC856xT data updates can be performed either in *synchronous* or in *asynchronous* mode.

In *asynchronous* mode, the  $\overline{\text{LDAC}}$  pin is used as a negative edge-triggered timing signal for simultaneous DAC updates. Multiple single-channel writes can be done in order to set different channel buffers to desired values and then make a falling edge on  $\overline{\text{LDAC}}$  pin to simultaneously update the DAC output registers. Data buffers of all channels must be loaded with desired data before an  $\overline{\text{LDAC}}$  falling edge. After a high-to-low  $\overline{\text{LDAC}}$  transition, all DACs are simultaneously updated with the last contents of the corresponding data buffers. If the content of a data buffer is not changed, the corresponding DAC output remains unchanged after the  $\overline{\text{LDAC}}$  pin is triggered.  $\overline{\text{LDAC}}$  must be returned high before the next serial command is initiated.

In *synchronous* mode, data are updated with the falling edge of the 24<sup>th</sup> SCLK cycle, which follows a falling edge of SYNC. For such *synchronous* updates, the  $\overline{\text{LDAC}}$  pin is not required, and it must be connected to GND permanently or asserted and held low before sending commands to the device.

Alternatively, all DAC outputs can be updated simultaneously using the built-in software function of LDAC. The LDAC register offers additional flexibility and control by allowing the selection of which DAC channel(s) should be updated simultaneously when the  $\overline{\text{LDAC}}$  pin is being brought low. The LDAC register is loaded with a 2-bit word (DB1 and DB0) using command bits C2, C1, and C0 (see Table 17). The default value for each bit, and therefore for each DAC channel, is zero. If the LDAC register bit is set to 1, it overrides the  $\overline{\text{LDAC}}$  pin (the  $\overline{\text{LDAC}}$  pin is internally tied low for that particular DAC channel) and this DAC channel updates synchronously after the falling edge of the 24<sup>th</sup> SCLK cycle. However, if the LDAC register bit is set to 0, the DAC channel is controlled by the  $\overline{\text{LDAC}}$  pin.

The combination of software and hardware simultaneous update functions is particularly useful in applications when updating a DAC channel, while keeping the other channel unaffected; see Table 11 and Table 17 for more information.

**Table 11. DAC-n Selection for LDAC Register Command**

DB1, DB0	Value	$\overline{\text{LDAC}}$ Pin Functionality
DB0	0	DAC-A uses $\overline{\text{LDAC}}$ pin
	1	DAC-A operates in synchronous mode
DB1	0	DAC-B uses $\overline{\text{LDAC}}$ pin
	1	DAC-B operates in synchronous mode

## 8.5 Programming

The DAC756xT, DAC816xT, and DAC856xT devices have a three-wire serial interface ( $\overline{\text{SYNC}}$ , SCLK, and  $\text{D}_{\text{IN}}$ ; see the table) compatible with SPI, QSPI, and Microwire interface standards, as well as most DSPs. See the Serial Write Operation timing diagram (Figure 1) for an example of a typical write sequence.

The DAC756xT, DAC816xT, or DAC856xT input shift register is 24 bits wide, consisting of two *don't care* bits (DB23 to DB22), three command bits (DB21 to DB19), three address bits (DB18 to DB16), and 16 data bits (DB15 to DB0). All 24 bits of data are loaded into the DAC under the control of the serial clock input, SCLK. DB23 (MSB) is the first bit that is loaded into the DAC shift register. DB23 is followed by the rest of the 24-bit word pattern, left-aligned. This configuration means that the first 24 bits of data are latched into the shift register, and any further clocking of data is ignored.

The write sequence begins by bringing the  $\overline{\text{SYNC}}$  line low. Data from the  $\text{D}_{\text{IN}}$  line are clocked into the 24-bit shift register on each falling edge of SCLK. The serial clock frequency can be as high as 50 MHz, making the DAC756xT, DAC816xT, and DAC856xT devices compatible with high-speed DSPs. On the 24<sup>th</sup> falling edge of the serial clock, the last data bit is clocked into the shift register and the shift register locks. Further clocking does not change the shift register data.

After receiving the 24<sup>th</sup> falling clock edge, the DAC756xT, DAC816xT, and DAC856xT devices decode the three command bits, three address bits and 16 data bits to perform the required function, without waiting for a  $\overline{\text{SYNC}}$  rising edge. After the 24<sup>th</sup> falling edge of SCLK is received, the  $\overline{\text{SYNC}}$  line may be kept low or brought high. In either case, the minimum delay time from the 24<sup>th</sup> falling SCLK edge to the next falling  $\overline{\text{SYNC}}$  edge must be met in order to begin the next cycle properly; see the Serial Write Operation timing diagram (Figure 1).

A rising edge of  $\overline{\text{SYNC}}$  before the 24-bit sequence is complete resets the SPI interface; no data transfer occurs. A new write sequence starts at the next falling edge of  $\overline{\text{SYNC}}$ . To assure the lowest power consumption of the device, care should be taken that the levels are as close to each rail as possible.

### 8.5.1 $\overline{\text{SYNC}}$ Interrupt

In a normal write sequence, the  $\overline{\text{SYNC}}$  line stays low for at least 24 falling edges of SCLK and the addressed DAC register updates on the 24<sup>th</sup> falling edge. However, if  $\overline{\text{SYNC}}$  is brought high before the 23<sup>rd</sup> falling edge, it acts as an interrupt to the write sequence; the shift register resets and the write sequence is discarded. Neither an update of the data buffer contents, DAC register contents, nor a change in the operating mode occurs (as shown in Figure 93).

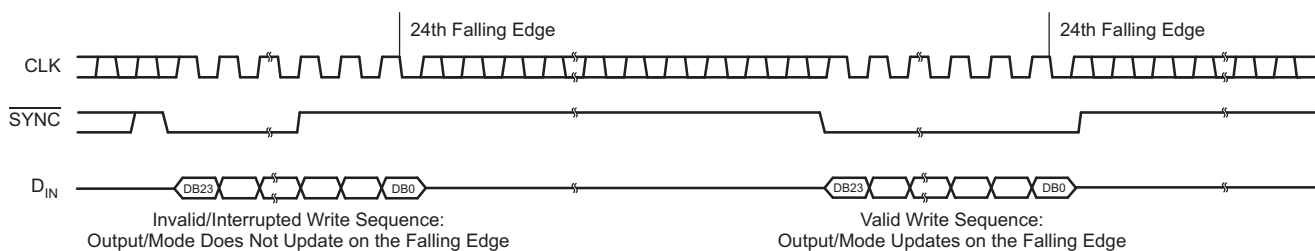


Figure 93.  $\overline{\text{SYNC}}$  Interrupt Facility

## Programming (continued)

### 8.5.2 DAC Register Configuration

When the DAC registers are being written to, the DAC756xT, DAC816xT, and DAC856xT devices receive all 24 bits of data, ignore DB23 and DB22, and decode the next three bits (DB21 to DB19) in order to determine the DAC operating or control mode (see [Table 12](#)). Bits DB18 to DB16 are used to address the DAC channels (see [Table 13](#)).

**Table 12. Commands for the DAC756xT, DAC816xT, and DAC856xT Devices**

C2 (DB21)	C1 (DB20)	C0 (DB19)	Command
0	0	0	Write to input register n ( <a href="#">Table 13</a> )
0	0	1	Software LDAC, update DAC register n ( <a href="#">Table 13</a> )
0	1	0	Write to input register n ( <a href="#">Table 13</a> ) and update all DAC registers
0	1	1	Write to input register n and update DAC register n ( <a href="#">Table 13</a> )
1	0	0	Set DAC power up or -down mode
1	0	1	Software reset
1	1	0	Set LDAC registers
1	1	1	Enable or disable the internal reference

**Table 13. Address Select for the DAC756xT, DAC816xT, and DAC856xT Devices**

A2 (DB18)	A1 (DB17)	A0 (DB16)	Channel (n)
0	0	0	DAC-A
0	0	1	DAC-B
0	1	0	Gain (only use with command 000)
0	1	1	Reserved
1	0	0	Reserved
1	0	1	Reserved
1	1	0	Reserved
1	1	1	DAC-A and DAC-B

When writing to the DAC input registers the next 16, 14, or 12 bits of data that follow are decoded by the DAC to determine the equivalent analog output (see [Table 14](#) through [Table 16](#)). The data format is straight binary, with all 0s corresponding to 0-V output and all 1s corresponding to full-scale output. For all documentation purposes, the data format and representation used here is a true 16-bit pattern (that is, FFFFh data word for full scale) that the DAC756xT, DAC816xT, and DAC856xT devices require.

**Table 14. DAC856xT Data Input Register Format**

		COMMAND			ADDRESS			DATA															
X <sup>(1)</sup>	X	C2	C1	C0	A2	A1	A0	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
DB23																							DB0

(1) X denotes *don't care* bits.

**Table 15. DAC816xT Data Input Register Format**

		COMMAND			ADDRESS			DATA																	
X	X	C2	C1	C0	A2	A1	A0	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	X	X		
DB23																							DB0		

**Table 16. DAC756xT Data Input Register Format**

		COMMAND			ADDRESS			DATA																			
X	X	C2	C1	C0	A2	A1	A0	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	X	X	X	X				
DB23																							DB0				

In addition to DAC input register updates, the DAC756xT, DAC816xT, and DAC856xT devices support a number of functional mode commands (such as write to LDAC register, power down DACs and so on). The complete set of functional mode commands is shown in Table 17.

**Table 17. Command Matrix for the DAC756xT, DAC816xT, and DAC856xT Devices**

DB23-DB22	Command			Address			Data						DESCRIPTION		
	C2	C1	C0	A2	A1	A0	DB15-DB6	DB5	DB4	DB3-DB2	DB1	DB0			
X <sup>(1)</sup>	0	0	0	0	0	0	16-, 14-, or 12-bit DAC data						Write to DAC-A input register		
				0	0	1	16-, 14-, or 12-bit DAC data						Write to DAC-B input register		
				1	1	1	16-, 14-, or 12-bit DAC data						Write to DAC-A and DAC-B input registers		
X	0	1	0	0	0	0	16-, 14-, or 12-bit DAC data						Write to DAC-A input register and update all DACs		
				0	0	1	16-, 14-, or 12-bit DAC data						Write to DAC-B input register and update all DACs		
				1	1	1	16-, 14-, or 12-bit DAC data						Write to DAC-A and DAC-B input register and update all DACs		
X	0	1	1	0	0	0	16-, 14-, or 12-bit DAC data						Write to DAC-A input register and update DAC-A		
				0	0	1	16-, 14-, or 12-bit DAC data						Write to DAC-B input register and update DAC-B		
				1	1	1	16-, 14-, or 12-bit DAC data						Write to DAC-A and DAC-B input register and update all DACs		
X	0	0	1	0	0	0	X						Update DAC-A		
				0	0	1	X						Update DAC-B		
				1	1	1	X						Update all DACs		
X	0	0	0	0	1	0	X						0	0	Gain: DAC-B gain = 2, DAC-A gain = 2 (default with internal V <sub>REF</sub> )
													0	1	Gain: DAC-B gain = 2, DAC-A gain = 1
													1	0	Gain: DAC-B gain = 1, DAC-A gain = 2
													1	1	Gain: DAC-B gain = 1, DAC-A gain = 1 (power-on default)
X	1	0	0	X			X	0	0	X	0	1	Power up DAC-A		
											1	0	Power up DAC-B		
											1	1	Power up DAC-A and DAC-B		
X	1	0	0	X			X	0	1	X	0	1	Power down DAC-A; 1 kΩ to GND		
											1	0	Power down DAC-B; 1 kΩ to GND		
											1	1	Power down DAC-A and DAC-B; 1 kΩ to GND		
X	1	0	0	X			X	1	0	X	0	1	Power down DAC-A; 100 kΩ to GND		
											1	0	Power down DAC-B; 100 kΩ to GND		
											1	1	Power down DAC-A and DAC-B; 100 kΩ to GND		
X	1	0	0	X			X	1	1	X	0	1	Power down DAC-A; Hi-Z		
											1	0	Power down DAC-B; Hi-Z		
											1	1	Power down DAC-A and DAC-B; Hi-Z		
X	1	0	1	X			X						X	0	Reset DAC-A and DAC-B input register and update all DACs
													X	1	Reset all registers and update all DACs (Power-on-reset update)
X	1	1	0	X			X						0	0	$\overline{\text{LDAC}}$ pin active for DAC-B and DAC-A
													0	1	$\overline{\text{LDAC}}$ pin active for DAC-B; inactive for DAC-A
													1	0	$\overline{\text{LDAC}}$ pin inactive for DAC-B; active for DAC-A
													1	1	$\overline{\text{LDAC}}$ pin inactive for DAC-B and DAC-A
X	1	1	1	X			X						X	0	Disable internal reference and reset DACs to gain = 1
													X	1	Enable internal reference and reset DACs to gain = 2

(1) X denotes *don't care* bits.

## 9 Application and Implementation

### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 9.1 Application Information

#### 9.1.1 DAC Internal Reference

The internal reference of the DAC756xT, DAC816xT, and DAC856xT devices does not require an external load capacitor for stability because it is stable without any capacitive load. However, for improved noise performance, an external load capacitor of 150 nF or larger connected to the  $V_{REFIN}/V_{REFOUT}$  output is recommended. Figure 94 shows the typical connections required for operation of the DAC756xT, DAC816xT, and DAC856xT internal reference. A supply bypass capacitor at the  $AV_{DD}$  input is also recommended.

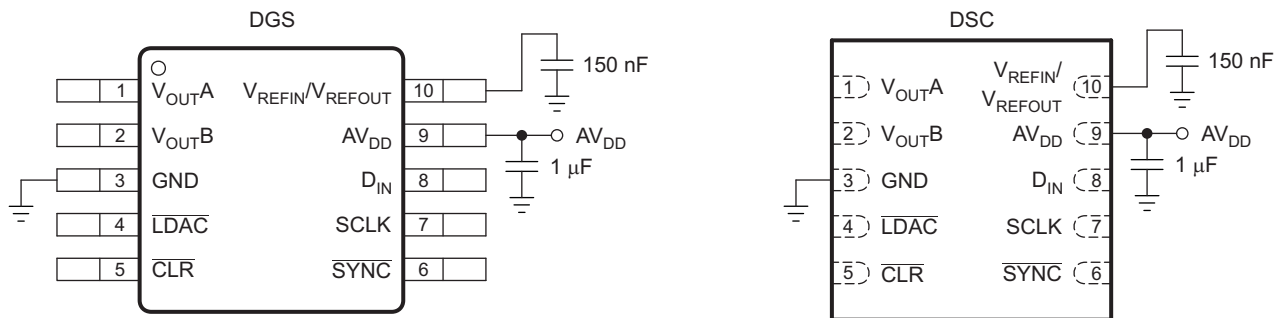


Figure 94. Typical Connections for Operating the DAC756xT, DAC816xT, and DAC856xT Internal Reference

##### 9.1.1.1 Supply Voltage

The internal reference features an extremely low dropout voltage. It can be operated with a supply of only 5 mV above the reference output voltage in an unloaded condition. For loaded conditions, see the [Load Regulation](#) section. The stability of the internal reference with variations in supply voltage (line regulation, dc PSRR) is also exceptional. Within the specified supply voltage range of 2.7 V to 5.5 V, the variation at  $V_{REFIN}/V_{REFOUT}$  is typically 50  $\mu$ V/V; see [Figure 7](#).

##### 9.1.1.2 Temperature Drift

The internal reference is designed to exhibit minimal drift error, defined as the change in reference output voltage over varying temperature. The drift is calculated using the box method described by [Equation 3](#):

$$\text{Drift Error} = \left( \frac{V_{REF\_MAX} - V_{REF\_MIN}}{V_{REF} \times T_{RANGE}} \right) \times 10^6 \text{ (ppm/}^\circ\text{C)} \quad (3)$$

where:

$V_{REF\_MAX}$  = maximum reference voltage observed within temperature range  $T_{RANGE}$ .

$V_{REF\_MIN}$  = minimum reference voltage observed within temperature range  $T_{RANGE}$ .

$V_{REF}$  = 2.5 V, target value for reference output voltage.

$T_{RANGE}$  = the characterized range from  $-40^\circ\text{C}$  to  $125^\circ\text{C}$  (165 $^\circ\text{C}$  range)

The internal reference features an exceptional typical drift coefficient of 4 ppm/ $^\circ\text{C}$  from  $-40^\circ\text{C}$  to  $125^\circ\text{C}$ . Characterizing a large number of units, a maximum drift coefficient of 10 ppm/ $^\circ\text{C}$  is observed. Temperature drift results are summarized in [Figure 3](#).



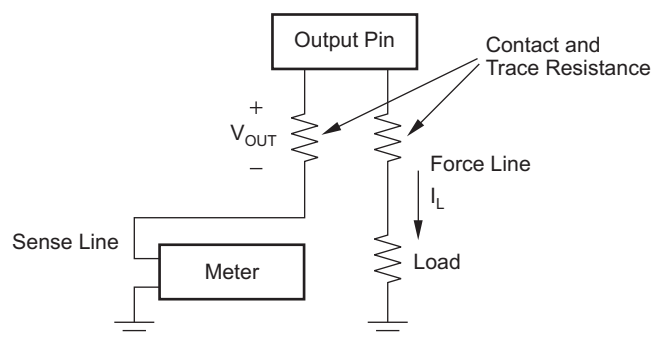
## Application Information (continued)

### 9.1.1.3 Noise Performance

Typical 0.1-Hz to 10-Hz voltage noise and noise spectral density performance are listed in the [Electrical Characteristics](#). Additional filtering can be used to improve output noise levels, although care should be taken to ensure the output impedance does not degrade the ac performance. The output noise spectrum at the  $V_{REFIN}/V_{REFOUT}$  pin, both unloaded and with an external 4.7- $\mu$ F load capacitor, is shown in [Figure 6](#). Internal reference noise impacts the DAC output noise when the internal reference is used.

### 9.1.1.4 Load Regulation

Load regulation is defined as the change in reference output voltage as a result of changes in load current. The load regulation of the internal reference is measured using force and sense contacts as shown in [Figure 95](#). The force and sense lines reduce the impact of contact and trace resistance, resulting in accurate measurement of the load regulation contributed solely by the internal reference. Measurement results are shown in [Figure 4](#). Force and sense lines should be used for applications that require improved load regulation.



**Figure 95. Accurate Load Regulation of the DAC756xT, DAC816xT, and DAC856xT Internal Reference**

#### 9.1.1.4.1 Long-Term Stability

Long-term stability or aging refers to the change of the output voltage of a reference over a period of months or years. This effect lessens as time progresses. The typical drift value for the internal reference is listed in the [Electrical Characteristics](#) and measurement results are shown in [Figure 5](#). This parameter is characterized by powering up multiple devices and measuring them at regular intervals.

#### 9.1.1.5 Thermal Hysteresis

Thermal hysteresis for a reference is defined as the change in output voltage after operating the device at 25°C, cycling the device through the operating temperature range, and returning to 25°C. Hysteresis is expressed by [Equation 4](#):

$$V_{HYST} = \left[ \frac{V_{REF\_PRE} - V_{REF\_POST}}{V_{REF\_NOM}} \right] \times 10^6 (\text{ppm}/^\circ\text{C}) \quad (4)$$

where:

$V_{HYST}$  = thermal hysteresis.

$V_{REF\_PRE}$  = output voltage measured at 25°C pre-temperature cycling.

$V_{REF\_POST}$  = output voltage measured after the device cycles through the temperature range of –40°C to 125°C, and returns to 25°C.

$V_{REF\_NOM}$  = 2.5 V, target value for reference output voltage.

### 9.1.2 DAC Noise Performance

Output noise spectral density at the  $V_{OUT-n}$  pin versus frequency is depicted in [Figure 45](#) and [Figure 46](#) for full-scale, mid-scale, and zero-scale input codes. The typical noise density for mid-scale code is 90 nV/ $\sqrt{\text{Hz}}$  at 1 kHz. High-frequency noise can be improved by filtering the reference noise. Integrated output noise between 0.1 Hz and 10 Hz is close to 2.5  $\mu$ V<sub>PP</sub> (mid-scale), as shown in [Figure 47](#).



## 9.2 Typical Applications

### 9.2.1 Combined Voltage and Current Analog Output Module Using the XTR300

The design features two independent outputs that can source and sink voltage and current over the standard industrial output ranges. The possible outputs of the design include:  $-24\text{ mA}$  to  $24\text{ mA}$ ,  $4\text{ mA}$ – $20\text{ mA}$ ,  $0\text{ mA}$  to  $24\text{ mA}$ ,  $0\text{ V}$  to  $5\text{ V}$ ,  $0\text{ V}$  to  $10\text{ V}$ ,  $-5\text{ V}$  to  $5\text{ V}$ , and  $-10\text{ V}$  to  $10\text{ V}$ .

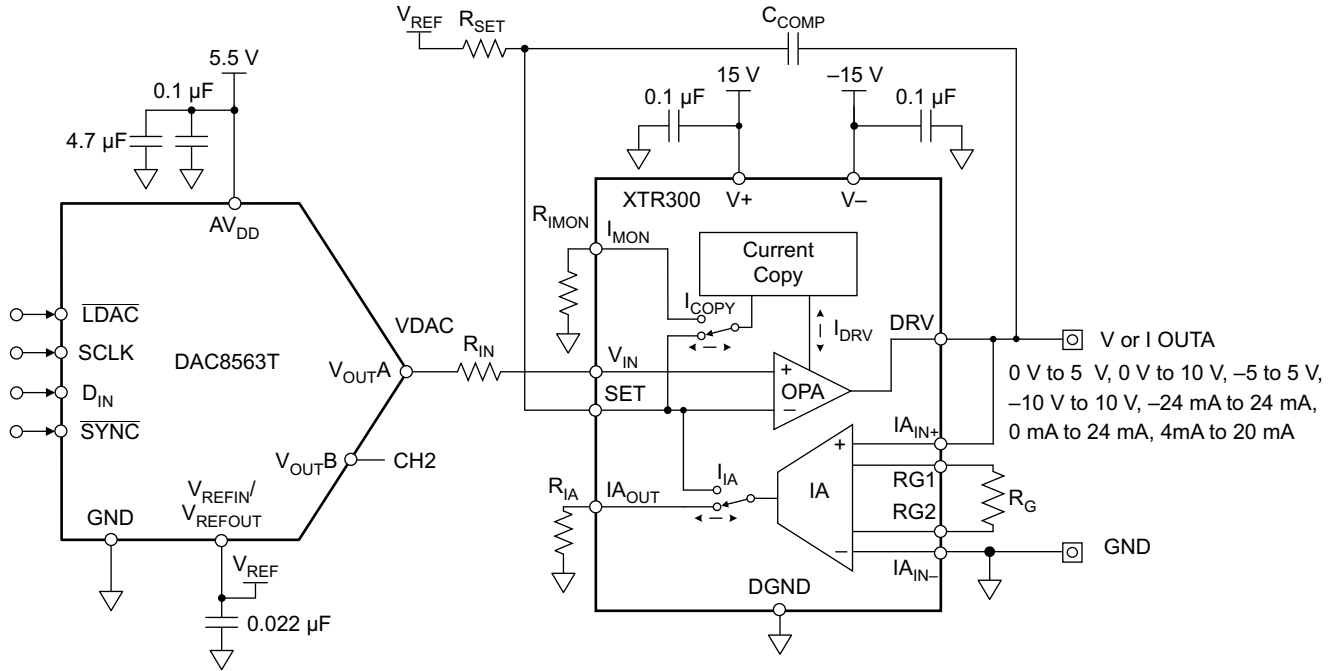


Figure 96. DAC8563T and XTR300 Discrete Analog Output Module

#### 9.2.1.1 Design Requirements

The design uses a DAC and a current-or-voltage output driver to create a discrete analog output design that can output either voltage or current from the same pin while focusing on high-accuracy specifications. The choice of the DAC8563T device takes advantage of its 16-bit resolution as well as its low typical offset error of  $1\text{ mV}$  and gain error of  $0.01\%$  FSR. The choice of the XTR300 device is based on its strong dc performance, having a typical error of  $400\text{ }\mu\text{V}$  and  $0.04\%$  FSR gain error. The XTR300 device allows a variety of both current and voltage outputs on the same pin while providing load monitoring and error status pins.

The power-on reset-to-midscale feature of the DAC8563T makes the bipolar output of the XTR300 power up at  $0\text{ V}$  or  $0\text{ A}$ . If using a unipolar output, the recommended device to achieve a system power-on output of  $0\text{ V}$ ,  $0\text{ A}$  or  $4\text{ mA}$  is the DAC8562T device.

A recommendation for minimizing the introduction of errors into the system is to use  $\pm 0.01\%$  tolerance  $R_G$  and  $R_{SET}$  resistors. The bypass capacitors on  $AV_{DD}$ ,  $V_{REF}$ ,  $V_+$  and  $V_-$  should have values between  $100\text{ nF}$  and  $10\text{ }\mu\text{F}$ . Smaller capacitors filter fast low-energy transients, whereas the large capacitors filter the slow high-energy transients. If there is an expectation of both types of signals in the system, the recommendation is to use a pair of small and large values as shown on the  $AV_{DD}$  pin of the DAC8563T device in Figure 96.

#### 9.2.1.2 Detailed Design Procedure

When configured for voltage mode, the output of the instrumentation amplifier (IA), internal to the XTR300 device, is routed to the SET pin. The SET output provides feedback for the IA based on the IA input voltage. The feedback from the IA provides high-impedance remote sensing of the voltage at the output load. Using the output voltage can overcome errors from PCB traces and protection component impedances. The DAC provides a unipolar input voltage to the  $V_{IN}$  pin of the XTR300 device. The XTR300 device offsets the  $V_{DAC}$  range by a negative  $V_{REF}$  and amplifies the difference by a value set by the  $R_G$  and  $R_{SET}$  resistors, as shown in Equation 5.

## Typical Applications (continued)

$$V_{OUT} = \frac{R_G}{2} \times \left( \frac{V_{DAC} - V_{REF}}{R_{SET}} \right) \quad (5)$$

When configured for current mode, the XTR300 routes the internal output of its current copy circuitry to the SET pin. This provides feedback for the internal OPA driver based on 1 / 10th of the output current, resulting in a voltage-to-current transfer function. Generating bipolar current outputs from the single-ended DAC output voltage,  $V_{DAC}$ , requires the application of an offset to the XTR300 SET pin. Connect the  $R_{SET}$  resistor from the SET pin to  $V_{REF}$  to apply the offset and obtain the transfer function shown in [Equation 6](#).

$$I_{OUT} = 10 \times \left( \frac{V_{DAC} - V_{REF}}{R_{SET}} \right) \quad (6)$$

The desired output ranges for  $V_{DAC}$  and  $V_{REF}$  voltages determine the  $R_{SET}$  and  $R_G$  resistor values, calculated using [Equation 7](#) and [Equation 8](#). The system design requires a  $V_{DAC}$  voltage range of 0.04 V to 4.96 V in order to operate the DAC8563T in the specified linear output range from codes 512 to 65 024.

$$R_{SET} = 10 \times \left( \frac{V_{DAC} - V_{REF}}{I_{OUT}} \right) = 10 \times \left( \frac{4.96 \text{ V} - 2.5 \text{ V}}{0.024 \text{ A}} \right) = 1025 \ \Omega \quad (7)$$

$$R_G = \frac{2 \times V_{OUT\_MAX} \times R_{SET}}{V_{DAC} - V_{REF}} = \frac{2 \times 10 \text{ V} \times 1020 \ \Omega}{4.96 \text{ V} - 2.5 \text{ V}} = 8292 \ \Omega \quad (8)$$

$I_{MON}$  and  $I_{A\_OUT}$  accomplish load monitoring. The sizing of  $R_{IMON}$  and  $R_{IA}$  determine the monitoring output voltage across the resistors. Size the resistors according to [Equation 9](#) and [Equation 10](#) and the expected output load current  $I_{DRV}$ .

$$R_{IMON} = \frac{10 \times V_{IMON}}{I_{DRV}} \quad (9)$$

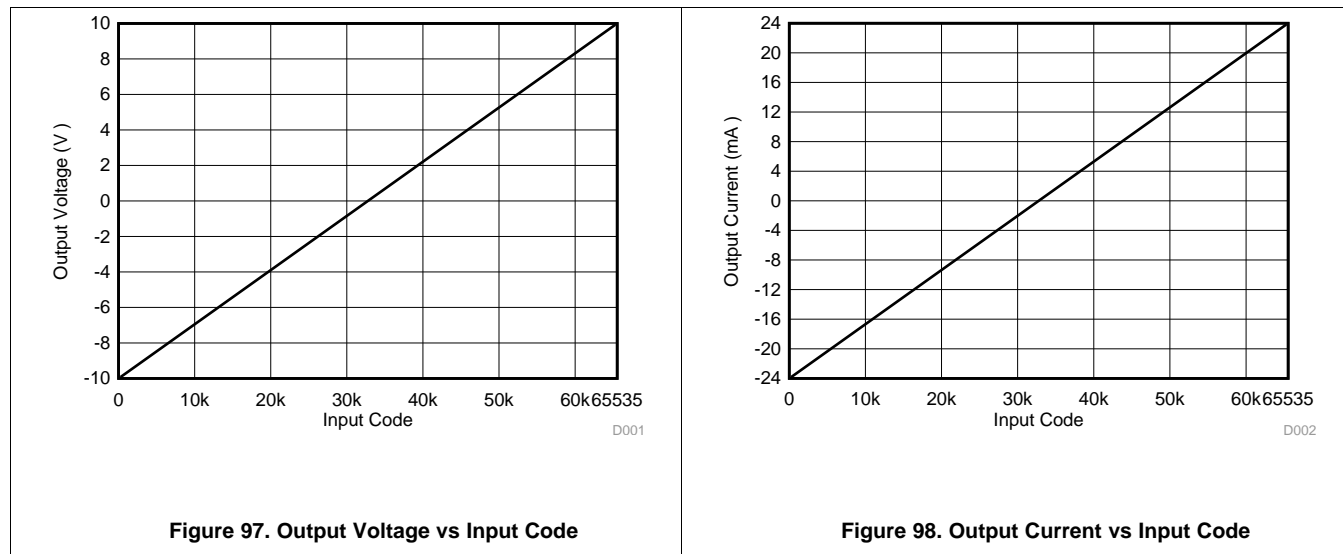
$$R_{IA} = \frac{10 \times V_{IA}}{I_{IA}} \quad (10)$$

For more detailed information about the design procedure of this circuit and how to isolate it, see *Two-Channel Source/Sink Combined Voltage & Current Output, Isolated, EMC/EMI Tested Reference Design (TIDU434)*.

## Typical Applications (continued)

### 9.2.1.3 Application Curves

Figure 97 shows the transfer function for the bipolar  $\pm 10$  V voltage range. This design also supports output voltage ranges of 0–5 V, 0–10 V and  $\pm 5$  V. Figure 98 shows the transfer function for the unipolar 0–24 mA current range. This design also supports output current ranges of  $\pm 24$  mA and 4 mA–20 mA.



## Typical Applications (continued)

### 9.2.2 Up to ±15-V Bipolar Output Using the DAC8562T

The DAC8562T is designed to be operate from a single power supply providing a maximum output range of  $AV_{DD}$  volts. However, the DAC can be placed in the configuration shown in Figure 99 in order to be designed into bipolar systems. Depending on the ratio of the resistor values, the output of the circuit can range anywhere from ±5 V to ±15 V. The design example below shows that the DAC is configured to have its internal reference enabled and the DAC8562T internal gain set to 2, however, an external 2.5-V reference could also be used (with DAC8562T internal gain set to 2).

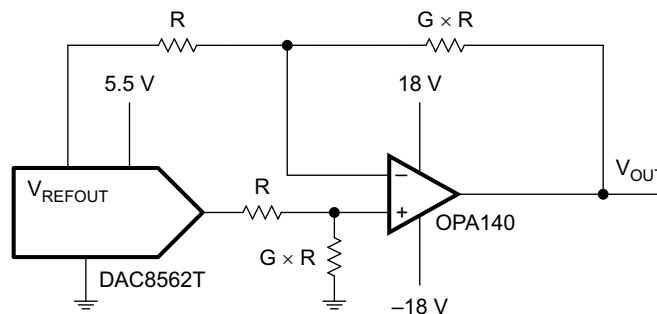


Figure 99. Bipolar Output Range Circuit Using DAC8562T

The transfer function shown in Equation 11 can be used to calculate the output voltage as a function of the DAC code, reference voltage and resistor ratio:

$$V_{OUT} = G \times V_{REFOUT} \left( 2 \times \frac{D_{IN}}{65,536} - 1 \right) \quad (11)$$

where:

$D_{IN}$  = decimal equivalent of the binary code that is loaded to the DAC register, ranging from 0 to 65,535 for DAC8562T (16 bit).

$V_{REFOUT}$  = reference output voltage with the internal reference enabled from the DAC  $V_{REFIN}/V_{REFOUT}$  pin

$G$  = ratio of the resistors

An example configuration to generate a ±10-V output range is shown below in Equation 6 with  $G = 4$  and  $V_{REFOUT} = 2.5$  V:

$$V_{OUT} = 20 \times \frac{D_{IN}}{65,536} - 10 \text{ V} \quad (12)$$

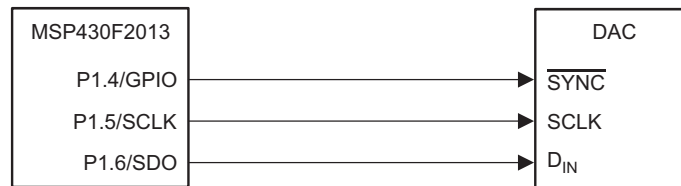
In this example, the range is set to ±10 V by using a resistor ratio of four,  $V_{REFOUT}$  of 2.5 V, and DAC8562T internal gain of 2. The resistor sizes must be selected keeping in mind the current sink or source capability of the DAC8562T internal reference. Using larger resistor values, for example,  $R = 10$  kΩ or larger, is recommended. The operational amplifier is selectable depending on the requirements of the system.

The DAC8562TEVM and DAC7562TEVM boards have the option to evaluate the bipolar output application by installing the components on the pre-placed footprints. For more information see either the [DAC8562EVM](#) or [DAC7562EVM](#) product folder.

## 9.3 System Examples

### 9.3.1 MSP430 Microprocessor Interfacing

Figure 100 shows a serial interface between the DAC756xT, DAC816xT, or DAC856xT device and a typical MSP430 USI port such as the one found on the MSP430F2013. The port is configured in SPI master mode by setting bits 3, 5, 6, and 7 in USICTL0. The USI counter interrupt is set in USICTL1 to provide an efficient means of SPI communication with minimal software overhead. The serial clock polarity, source, and speed are controlled by settings in the USI clock control register (USICKCTL). The SYNC signal is derived from a bit-programmable pin on port 1; in this case, port line P1.4 is used. When data are to be transmitted to the DAC756xT, DAC816xT, or DAC856xT device, P1.4 is taken low. The USI transmits data in 8-bit bytes; thus, only eight falling clock edges occur in the transmit cycle. To load data to the DAC, P1.4 is left low after the first eight bits are transmitted; then, a second write cycle is initiated to transmit the second byte of data. P1.4 is taken high following the completion of the third write cycle.

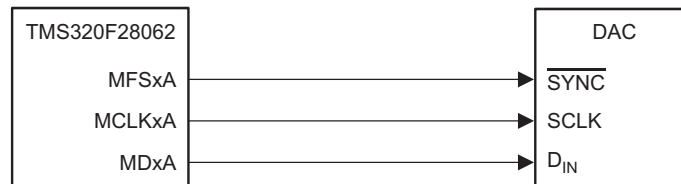


NOTE: Additional pins omitted for clarity.

Figure 100. DAC756xT, DAC816xT, or DAC856xT Device to MSP430 Interface

### 9.3.2 TMS320 McBSP Microprocessor Interfacing

Figure 101 shows an interface between the DAC756xT, DAC816xT, or DAC856xT device and any TMS320 series DSP from Texas Instruments with a multi-channel buffered serial port (McBSP). Serial data are shifted out on the rising edge of the serial clock and are clocked into the DAC756xT, DAC816xT, or DAC856xT device on the falling edge of the SCLK signal.

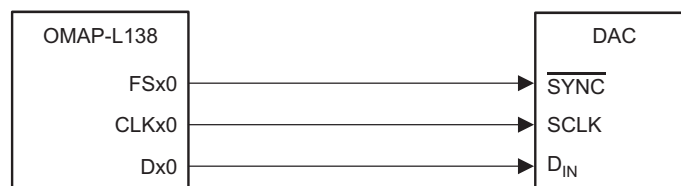


NOTE: Additional pins omitted for clarity.

Figure 101. DAC756xT, DAC816xT, or DAC856xT Device to TMS320 McBSP Interface

### 9.3.3 OMAP-L1x Processor Interfacing

Figure 102 shows a serial interface between the DAC756xT, DAC816xT, or DAC856xT device and the OMAP-L138 processor. The transmit clock CLKx0 of the L138 drives SCLK of the DAC756xT, DAC816xT, or DAC856xT device, and the data transmit (Dx0) output drives the serial data line of the DAC. The SYNC signal is derived from the frame sync transmit (FSx0) line, similar to the TMS320 interface.



NOTE: Additional pins omitted for clarity.

Figure 102. DAC756xT, DAC816xT, or DAC856xT Device to OMAP-L1x Processor

## 10 Power Supply Recommendations

These devices can operate within the specified supply voltage range of 2.7 V to 5.5 V. The power applied to  $AV_{DD}$  should be well-regulated and low-noise. In order to further minimize noise from the power supplies, a strong recommendation is to include a pair of 100-pF and 1-nF capacitors and a 0.1- $\mu$ F to 1- $\mu$ F bypass capacitor. The current consumption of the  $AV_{DD}$  pin, the short-circuit current limit, and the load current for these devices are listed in the [Electrical Characteristics](#) table. Choose the power supplies for these devices to meet the aforementioned current requirements.

## 11 Layout

### 11.1 Layout Guidelines

A precision analog component requires careful layout, adequate bypassing, and clean, well-regulated power supplies. The DAC756xT, DAC816xT, and DAC856xT devices offer single-supply operation, and are often used in close proximity with digital logic, microcontrollers, microprocessors, and digital signal processors. The more digital logic present in the design and the higher the switching speed, the more difficult it is to keep digital noise from appearing at the output. As a result of the single ground pin of the DAC756xT, DAC816xT, and DAC856xT devices, all return currents (including digital and analog return currents for the DAC) must flow through a single point. Ideally, GND would be connected directly to an analog ground plane. This plane would be separate from the ground connection for the digital components until they were connected at the power-entry point of the system. The power applied to  $AV_{DD}$  should be well-regulated and low noise. Switching power supplies and dc-dc converters often have high-frequency glitches or spikes riding on the output voltage. In addition, digital components can create similar high-frequency spikes as their internal logic switches states. This noise can easily couple into the DAC output voltage through various paths between the power connections and analog output. As with the GND connection,  $AV_{DD}$  should be connected to a power-supply plane or trace that is separate from the connection for digital logic until they are connected at the power-entry point. In addition, a pair of 100-pF to 1-nF capacitors and a 0.1- $\mu$ F to 1- $\mu$ F bypass capacitor are strongly recommended. In some situations, additional bypassing may be required, such as a 100- $\mu$ F electrolytic capacitor or even a pi filter made up of inductors and capacitors – all designed essentially to provide low-pass filtering for the supply and remove the high-frequency noise.

## 11.2 Layout Example

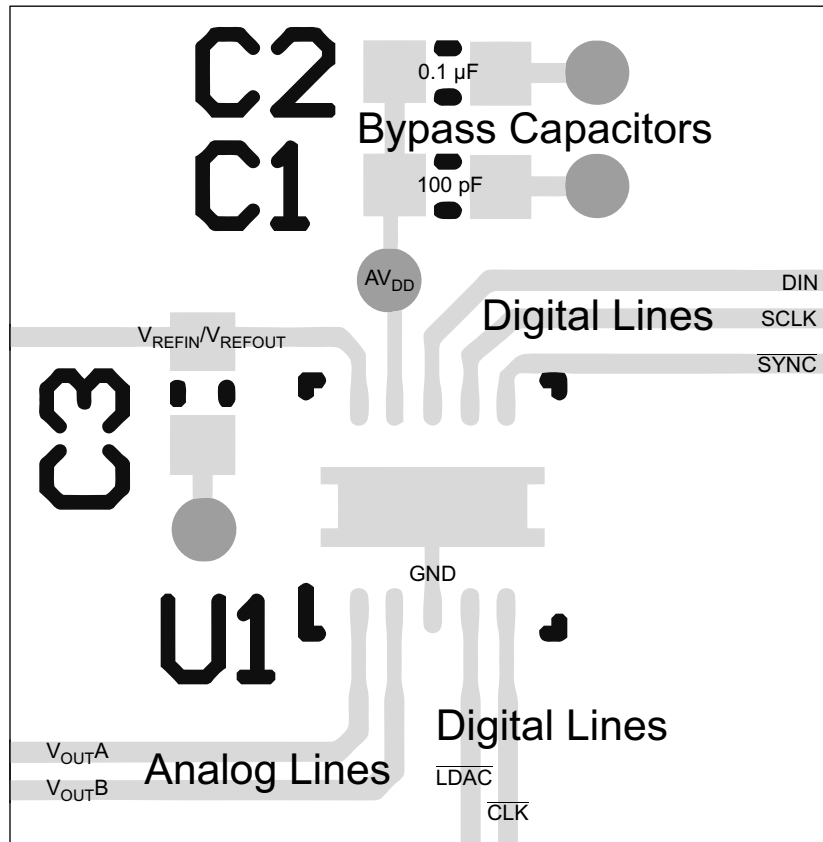


Figure 103. DACxx6xT Layout Example

## 12 器件和文档支持

### 12.1 相关链接

下面的表格列出了快速访问链接。 范围包括技术文档、支持与社区资源、工具和软件，以及样片或购买的快速访问。

**Table 18. 相关链接**

器件	产品文件夹	样片与购买	技术文档	工具与软件	支持与社区
DAC7562T	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>
DAC7563T	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>
DAC8162T	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>
DAC8163T	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>
DAC8562T	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>
DAC8563T	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>	<a href="#">请单击此处</a>

### 12.2 社区资源

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

**TI E2E™ Online Community** *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At [e2e.ti.com](http://e2e.ti.com), you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

### 12.3 Trademarks

SPI, QSPI are trademarks of Motorola, Inc.  
All other trademarks are the property of their respective owners.

### 12.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 13 机械、封装和可订购信息

以下页中包括机械、封装和可订购信息。 这些信息是针对指定器件可提供的最新数据。 本数据随时可能发生变更并且不对本文档进行修订，恕不另行通知。 要获得这份数据表的浏览器版本，请查阅左侧的导航窗格。



**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
DAC7562TDGSR	ACTIVE	VSSOP	DGS	10	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	75T2	<a href="#">Samples</a>
DAC7562TDGST	ACTIVE	VSSOP	DGS	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	75T2	<a href="#">Samples</a>
DAC7562TDSCR	ACTIVE	WSOP	DSC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	7562T	<a href="#">Samples</a>
DAC7562TDSCCT	ACTIVE	WSOP	DSC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	7562T	<a href="#">Samples</a>
DAC7563TDGSR	ACTIVE	VSSOP	DGS	10	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	75T3	<a href="#">Samples</a>
DAC7563TDGST	ACTIVE	VSSOP	DGS	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	75T3	<a href="#">Samples</a>
DAC7563TDSCR	ACTIVE	WSOP	DSC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	7563T	<a href="#">Samples</a>
DAC7563TDSCCT	ACTIVE	WSOP	DSC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	7563T	<a href="#">Samples</a>
DAC8162TDGSR	ACTIVE	VSSOP	DGS	10	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	81T2	<a href="#">Samples</a>
DAC8162TDGST	ACTIVE	VSSOP	DGS	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	81T2	<a href="#">Samples</a>
DAC8162TDSCR	ACTIVE	WSOP	DSC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8162T	<a href="#">Samples</a>
DAC8162TDSCCT	ACTIVE	WSOP	DSC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8162T	<a href="#">Samples</a>
DAC8163TDGSR	ACTIVE	VSSOP	DGS	10	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	81T3	<a href="#">Samples</a>
DAC8163TDGST	ACTIVE	VSSOP	DGS	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	81T3	<a href="#">Samples</a>
DAC8163TDSCR	ACTIVE	WSOP	DSC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8163T	<a href="#">Samples</a>
DAC8163TDSCCT	ACTIVE	WSOP	DSC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8163T	<a href="#">Samples</a>
DAC8562TDGSR	ACTIVE	VSSOP	DGS	10	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	85T2	<a href="#">Samples</a>
DAC8562TDGST	ACTIVE	VSSOP	DGS	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	85T2	<a href="#">Samples</a>
DAC8562TDSCR	ACTIVE	WSOP	DSC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8562T	<a href="#">Samples</a>
DAC8562TDSCCT	ACTIVE	WSOP	DSC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8562T	<a href="#">Samples</a>

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
DAC8563TDGSR	ACTIVE	VSSOP	DGS	10	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	85T3	<a href="#">Samples</a>
DAC8563TDGST	ACTIVE	VSSOP	DGS	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	85T3	<a href="#">Samples</a>
DAC8563TDSCR	ACTIVE	WSOP	DSC	10	3000	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8563T	<a href="#">Samples</a>
DAC8563TDST	ACTIVE	WSOP	DSC	10	250	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	8563T	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSELETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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## TAPE AND REEL INFORMATION



### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DAC7562TDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC7562TDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC7562TDSCR	WSOP	DSC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC7562TDSCT	WSOP	DSC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC7563TDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC7563TDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC7563TDSCR	WSOP	DSC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC7563TDSCT	WSOP	DSC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8162TDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8162TDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8162TDSCR	WSOP	DSC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8162TDSCT	WSOP	DSC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8163TDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8163TDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8163TDSCR	WSOP	DSC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8163TDSCT	WSOP	DSC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8562TDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8562TDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DAC8562TDSCR	WSON	DSC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8562TDSCT	WSON	DSC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8563TDGSR	VSSOP	DGS	10	2500	330.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8563TDGST	VSSOP	DGS	10	250	180.0	12.4	5.3	3.3	1.3	8.0	12.0	Q1
DAC8563TDSCR	WSON	DSC	10	3000	330.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2
DAC8563TDSCT	WSON	DSC	10	250	180.0	12.4	3.3	3.3	1.1	8.0	12.0	Q2

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DAC7562TDGSR	VSSOP	DGS	10	2500	367.0	367.0	38.0
DAC7562TDGST	VSSOP	DGS	10	250	213.0	191.0	35.0
DAC7562TDSCR	WSON	DSC	10	3000	367.0	367.0	35.0
DAC7562TDSCT	WSON	DSC	10	250	210.0	185.0	35.0
DAC7563TDGSR	VSSOP	DGS	10	2500	367.0	367.0	38.0
DAC7563TDGST	VSSOP	DGS	10	250	213.0	191.0	35.0
DAC7563TDSCR	WSON	DSC	10	3000	367.0	367.0	35.0
DAC7563TDSCT	WSON	DSC	10	250	210.0	185.0	35.0
DAC8162TDGSR	VSSOP	DGS	10	2500	367.0	367.0	38.0
DAC8162TDGST	VSSOP	DGS	10	250	213.0	191.0	35.0
DAC8162TDSCR	WSON	DSC	10	3000	367.0	367.0	35.0

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DAC8162TDSC	WSON	DSC	10	250	210.0	185.0	35.0
DAC8163TDGSR	VSSOP	DGS	10	2500	367.0	367.0	38.0
DAC8163TDGST	VSSOP	DGS	10	250	213.0	191.0	35.0
DAC8163TDSCR	WSON	DSC	10	3000	367.0	367.0	35.0
DAC8163TDSC	WSON	DSC	10	250	210.0	185.0	35.0
DAC8562TDGSR	VSSOP	DGS	10	2500	367.0	367.0	38.0
DAC8562TDGST	VSSOP	DGS	10	250	213.0	191.0	35.0
DAC8562TDSCR	WSON	DSC	10	3000	367.0	367.0	35.0
DAC8562TDSC	WSON	DSC	10	250	210.0	185.0	35.0
DAC8563TDGSR	VSSOP	DGS	10	2500	367.0	367.0	38.0
DAC8563TDGST	VSSOP	DGS	10	250	213.0	191.0	35.0
DAC8563TDSCR	WSON	DSC	10	3000	367.0	367.0	35.0
DAC8563TDSC	WSON	DSC	10	250	210.0	185.0	35.0

# DGS0010A



# PACKAGE OUTLINE

## VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



4221984/A 05/2015

### NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
5. Reference JEDEC registration MO-187, variation BA.

# EXAMPLE BOARD LAYOUT

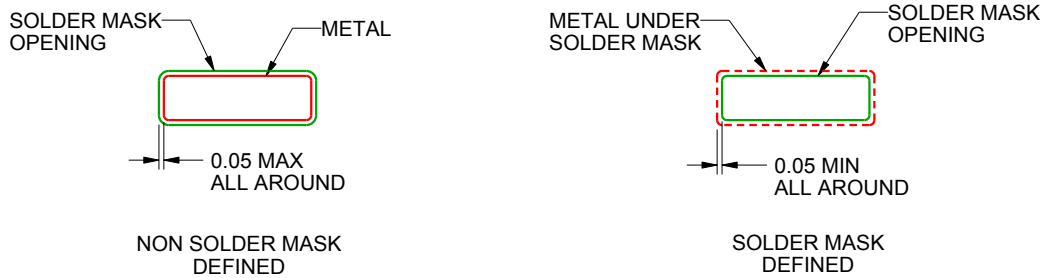
DGS0010A

VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE  
SCALE:10X



SOLDER MASK DETAILS  
NOT TO SCALE

4221984/A 05/2015

NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



# EXAMPLE STENCIL DESIGN

DGS0010A

VSSOP - 1.1 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:10X

4221984/A 05/2015

NOTES: (continued)

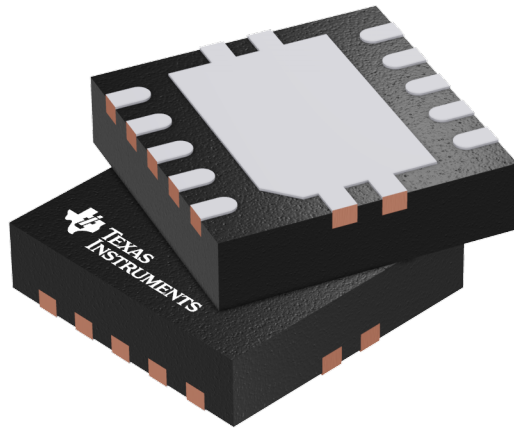
8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

## GENERIC PACKAGE VIEW

DSC 10

WSON - 0.8 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

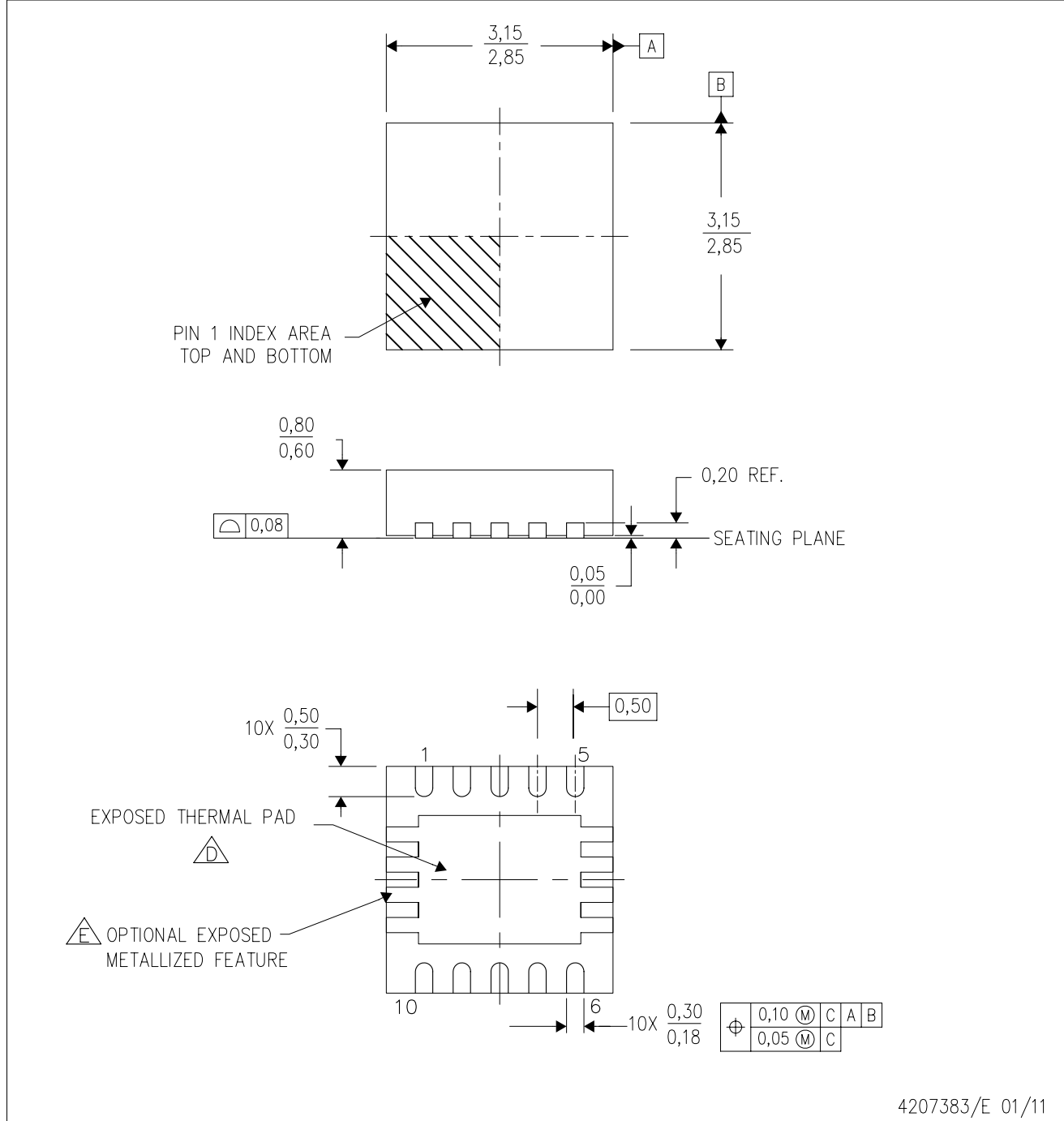


Images above are just a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

4207383/F

DSC (S-PWSON-N10)

PLASTIC SMALL OUTLINE NO-LEAD



- NOTES:
- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.
  - B. This drawing is subject to change without notice.
  - C. Small Outline No-Lead (SON) package configuration.
  - D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
  - E. See the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.

# THERMAL PAD MECHANICAL DATA

DSC (S-PWSON-N10)

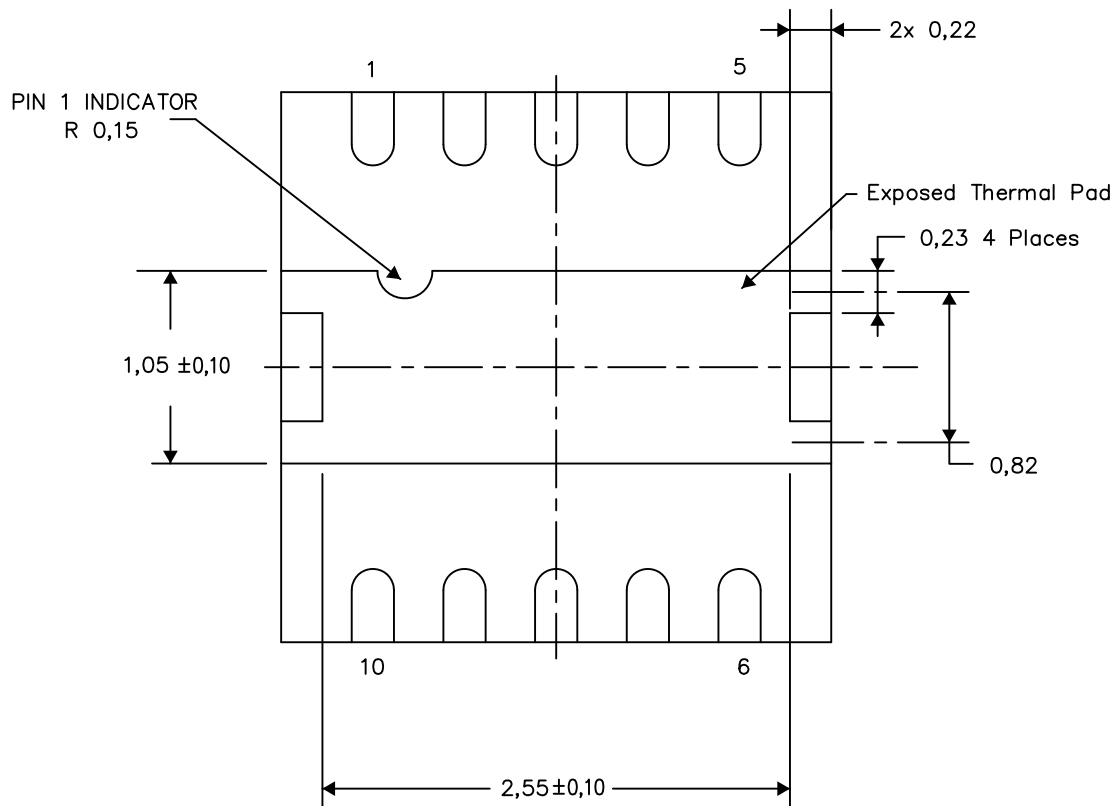
PLASTIC SMALL OUTLINE NO-LEAD

## THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



Bottom View

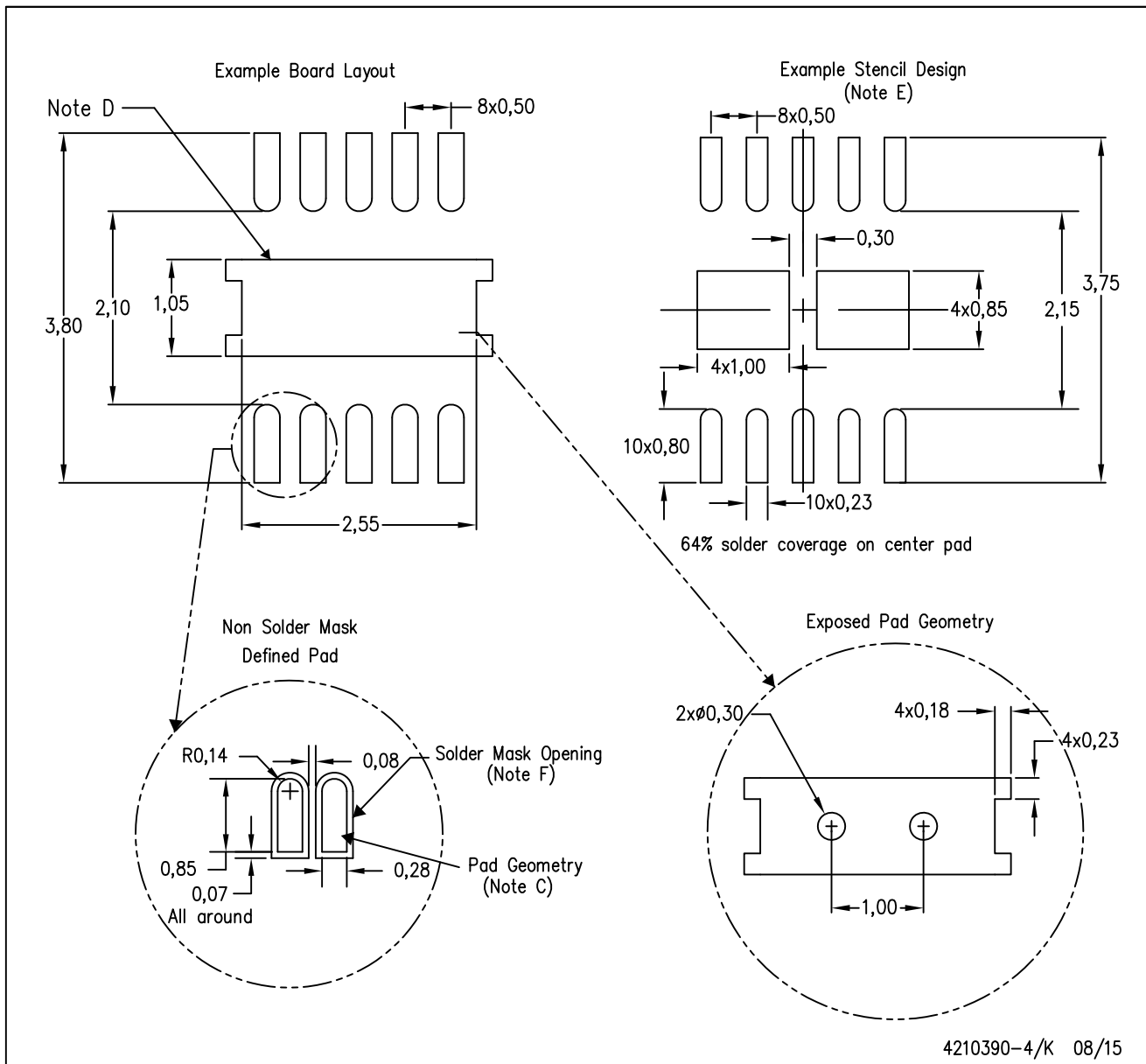
Exposed Thermal Pad Dimensions

4210391-4/Q 08/15

NOTE: A. All linear dimensions are in millimeters

DSC (S-PWSON-N10)

PLASTIC SMALL OUTLINE NO-LEAD



- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Publication IPC-7351 is recommended for alternate designs.
  - This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
  - Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.

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