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LMV841, LMV842, LMV844

ZHCSGZ5I –OCTOBER 2006–REVISED OCTOBER 2017

LMV84x CMOS 输入、**RRIO**、低功耗、宽电源电压范围 **4.5MHz** 运算放大器

1 特性

Texas

INSTRUMENTS

- 除非另有说明,否则 T_A = 25°C 时的典型值为 V⁺ = 5V。
- 小型 5 引脚 SC70 封装 (2.00mm × 1.25mm × 0.95mm)
- 宽电源电压范围: 2.7V 至 12V
- 可在 3.3V、5V 和 ±5V 额定电压下工作
- 低电源电流: 每通道 1mA
- 单位增益带宽:4.5MHz
- 开环增益:133dB
- 输入失调电压: 最大值为 500µV
- 输入偏置电流:0.3pA
- CMRR 为 112dB, PSSR 为 108dB
- 输入电压噪声: 20nV/√Hz
- 温度范围:−40°C 至 125°C
- 轨至轨输入和输出 (RRIO)

2 应用

- 高阻抗传感器接口
- 电池供电仪表
- 高增益和仪表放大器
- DAC 缓冲器和有源滤波器

3 说明

LMV84x 器件是低电压和低功耗运算放大器, 在 2.7V 至 12V 电源电压范围内工作,具有轨至轨输入和输出 功能。其低失调电压、低电源电流和 CMOS 输入特性 使得它们非常适合高阻抗传感器接口和电池供电的 应 用。

单 LMV841 采用节省空间的 5 引脚 SC70 封装, 双 LMV842 采用 8 引脚 VSSOP 和 8 引脚 SOIC 封装, 而四 LMV844 采用 14 引脚 TSSOP 和 14 引脚 SOIC 封装。这些小型封装是空间受限型 PCB 和便携式电子 产品的理想解决方案。

器件信息**(1)**

(1) 如需了解所有可用封装,请参阅数据表末尾的可订购产品附 录。

典型 应用

4 修订历史记录

2

注:之前版本的页码可能与当前版本有所不同。

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5 Pin Configuration and Functions

Pin Functions

6 Specifications

6.1 Absolute Maximum Ratings

See (1)(2)

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) If Military/Aerospace specified devices are required, contact the Texas Instruments Sales Office / Distributors for availability and specifications.

(3) The maximum power dissipation is a function of $T_{J(MAX)}$, $R_{\theta JA}$, and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / R_{0JA}$. All numbers apply for packages soldered directly onto a PCB.

6.2 ESD Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

(1) The maximum power dissipation is a function of T_{J(MAX)}, R_{θJA}, and T_A. The maximum allowable power dissipation at any ambient temperature is ${\sf P}_{\sf D}$ = $({\sf T}_{\sf J(MAX)}-{\sf T}_{\sf A})$ / ${\sf R}_{\sf \sf \sf 0}$ All numbers apply for packages soldered directly onto a PCB.

6.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report.

The maximum power dissipation is a function of T_{J(MAX)}, R_{θJA}, and T_A. The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / R_{0JA}$. All numbers apply for packages soldered directly onto a PCB.

6.5 Electrical Characteristics – 3.3 V

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 3.3 V, V⁻ = 0 V, V_{CM} = V⁺ / 2, and R_L > 10 MΩ to V⁺ / $2^{(1)}$

(1) Electrical table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device.

(2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are ensured through correlations using statistical quality control (SQC) method.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

(4) This parameter is ensured by design and/or characterization and is not tested in production.
(5) Positive current corresponds to current flowing into the device.

Positive current corresponds to current flowing into the device.

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Electrical Characteristics – 3.3 V (continued)

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 3.3 V, V⁻ = 0 V, V_{CM} = V⁺ / 2, and R_L > 10 MΩ to V⁺ / $2(1)$

(6) The maximum power dissipation is a function of $T_{J(MAX)}$, $R_{\theta JA}$, and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / R_{\theta JA}$. All numbers apply for packages soldered directly onto a PCB.

(7) Short circuit test is a momentary test.

(8) Number specified is the slower of positive and negative slew rates.

6.6 Electrical Characteristics – 5 V

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 5 V, V⁻ = 0 V, V_{CM} = V⁺ / 2, and R_L > 10 MΩ to V⁺ / 2.⁽¹⁾

(1) Electrical table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device.

(2) Limits are 100% production tested at 25°C. Limits over the operating temperature range are ensured through correlations using statistical quality control (SQC) method.

(3) Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

- (4) This parameter is ensured by design and/or characterization and is not tested in production.
- (5) Positive current corresponds to current flowing into the device.

Electrical Characteristics – 5 V (continued)

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 5 V, V⁻ = 0 V, V_{CM} = V⁺ / 2, and R_L > 10 MΩ to V⁺ / 2.⁽¹⁾

(6) The maximum power dissipation is a function of T_{J(MAX)}, R_{θJA}, and T_A. The maximum allowable power dissipation at any ambient temperature is P_D = (T_{J(MAX)} - T_A) / R_{θJA}. All numbers apply for packages soldered directly onto a PCB.

(7) Short circuit test is a momentary test.
(8) Number specified is the slower of pos

Number specified is the slower of positive and negative slew rates.

6.7 Electrical Characteristics – ±5-V

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 5 V, V⁻ = -5 V, V_{CM} = 0 V, and R_L > 10 MΩ to V_{CM}.⁽¹⁾

(1) Electrical table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device.

XAS RUMENTS

Electrical Characteristics – ±5-V (continued)

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 5 V, V⁻ = -5 V, V_{CM} = 0 V, and R_L > 10 MΩ to V_{CM}.⁽¹⁾

PARAMETER		TEST CONDITIONS		MIN ⁽²⁾	TP ⁽³⁾	MAX ⁽²⁾	UNIT
Vos	Input offset voltage	at the temperature extremes		-500	±50	500	μV
				-800		800	
TCV_{OS}	Input offset voltage drift ⁽⁴⁾				0.25		µV/°C
		at the temperature extremes		-5		$\mathbf 5$	
Iв	Input bias current (4) (5)				0.3	10	рA
		at the temperature extremes				300	
I_{OS}	Input offset current				40		fА
CMRR	Common-mode rejection ratio LMV841	–5 V ≤ V _{CM} ≤ 5 V		86	112		dB
			at the temperature extremes	80			
	Common-mode rejection ratio LMV842 and LMV844	$-5 V \leq V_{CM} \leq 5 V$		86	106		dB
			at the temperature extremes	80			
PSRR	Power supply rejection ratio	2.7 V ≤ V ⁺ ≤ 12 V, V _O = 0 _V		86	108		dB
			at the temperature extremes	82			
CMVR	Input common-mode voltage range	CMRR \geq 50 dB		-5.2		5.2	V
A _{VOL}	Large signal voltage gain	$R_L = 2 k\Omega$ $V_O = -4.7 V$ to 4.7 V		100	126		dB
			at the temperature extremes	96			
		$R_1 = 10 k\Omega$ $V_O = -4.8$ V to 4.8 V		100	136		dB
			at the temperature extremes	96			
$V_{\rm O}$	Output swing high, (measured from V ⁺)	$R_L = 2 k\Omega$ to 0 V			95	130	mV
			at the temperature extremes			155	
		R_L = 10 kΩ to 0 V			44	75	mV
			at the temperature extremes			95	
	Output swing low, (measured from V ⁻)	$R_L = 2 k\Omega$ to 0 V			105	160	mV
			at the temperature extremes			200	
		$R_1 = 10 k\Omega$ to 0 V			52	80	mV
			at the temperature extremes			100	
l _O	Output short-circuit current (6) (7)	Sourcing $V_O = 0$ V V_{IN} = 100 mV		20	37		mA
			at the temperature extremes	15			
		Sinking $V_O = 0$ V $V_{\text{IN}} = -100 \text{ mV}$		20	29		mA
			at the temperature extremes	15			

⁽²⁾ Limits are 100% production tested at 25°C. Limits over the operating temperature range are ensured through correlations using statistical quality control (SQC) method.

⁽³⁾ Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not ensured on shipped production material.

⁽⁴⁾ This parameter is ensured by design and/or characterization and is not tested in production.
(5) Positive current corresponds to current flowing into the device.

Positive current corresponds to current flowing into the device.

⁽⁶⁾ The maximum power dissipation is a function of $T_{J(MAX)}$, $R_{\theta JA}$, and T_A . The maximum allowable power dissipation at any ambient temperature is $P_D = (T_{J(MAX)} - T_A) / R_{\theta JA}$. All numbers apply for packages soldered directly onto a PCB.

⁽⁷⁾ Short circuit test is a momentary test.

Electrical Characteristics – ±5-V (continued)

Unless otherwise specified, all limits are ensured for T_A = 25°C, V⁺ = 5 V, V⁻ = -5 V, V_{CM} = 0 V, and R_L > 10 MΩ to V_{CM}.⁽¹⁾

(8) Number specified is the slower of positive and negative slew rates.

6.8 Typical Characteristics

At $T_A = 25^{\circ}C$, $R_L = 10 k\Omega$, $V_S = 5 V$. Unless otherwise specified.

Typical Characteristics (continued)

EXAS **STRUMENTS**

Typical Characteristics (continued)

Typical Characteristics (continued)

EXAS STRUMENTS

Typical Characteristics (continued)

Typical Characteristics (continued)

ISTRUMENTS

7 Detailed Description

7.1 Overview

The LMV84x devices are operational amplifiers with near-precision specifications: low noise, low temperature drift, low offset, and rail-to-rail input and output. Possible application areas include instrumentation, medical, test equipment, audio, and automotive applications.

Its low supply current of 1 mA per amplifier, temperature range of −40°C to +125°C, 12-V supply with CMOS input, and the small SC70 package for the LMV841 make the LMV84x a unique op amp family and a perfect choice for portable electronics.

7.2 Functional Block Diagram

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7.3 Feature Description

7.3.1 Input Protection

The LMV84x devices have a set of anti-parallel diodes D_1 and D_2 between the input pins, as shown in Figure 34. These diodes are present to protect the input stage of the amplifier. At the same time, they limit the amount of differential input voltage that is allowed on the input pins.

A differential signal larger than one diode voltage drop can damage the diodes. The differential signal between the inputs needs to be limited to ± 300 mV or the input current needs to be limited to ± 10 mA.

NOTE

When the op amp is slewing, a differential input voltage exists that forward-biases the protection diodes. This may result in current being drawn from the signal source. While this current is already limited by the internal resistors R_1 and R_2 (both 130 Ω), a resistor of 1 kΩ can be placed in the feedback path, or a 500-Ω resistor can be placed in series with the input signal for further limitation.

Feature Description (continued)

Figure 34. Protection Diodes Between the Input Pins

7.3.2 Input Stage

The input stage of this amplifier consists of both a PMOS and an NMOS input pair to achieve a rail-to-rail input range. For input voltages close to the negative rail, only the PMOS pair is active. Close to the positive rail, only the NMOS pair is active. In a transition region that extends from approximately 2 V below V⁺ to 1 V below V⁺, both pairs are active, and one pair gradually takes over from the other. In this transition region, the input-referred offset voltage changes from the offset voltage associated with the PMOS pair to that of the NMOS pair. The input pairs are trimmed independently to ensure an input offset voltage of less then 0.5 mV at room temperature over the complete rail-to-rail input range. This also significantly improves the CMRR of the amplifier in the transition region.

NOTE

The CMRR and PSRR limits in the tables are large-signal numbers that express the maximum variation of the input offset of the amplifier over the full common-mode voltage and supply voltage range, respectively. When the common-mode input voltage of the amplifier is within the transition region, the small signal CMRR and PSRR may be slightly lower than the large signal limits.

7.4 Device Functional Modes

7.4.1 Driving Capacitive Load

The LMV84x can be connected as noninverting unity gain amplifiers. This configuration is the most sensitive to capacitive loading. The combination of a capacitive load placed on the output of an amplifier along with the output impedance of the amplifier creates a phase lag, which reduces the phase margin of the amplifier. If the phase margin is significantly reduced, the response is under-damped, which causes peaking in the transfer. When there is too much peaking, the op amp might start oscillating.

The LMV84x can directly drive capacitive loads up to 100 pF without any stability issues. To drive heavier capacitive loads, an isolation resistor ($R_{\rm ISO}$) must be used, as shown in Figure 35. By using this isolation resistor, the capacitive load is isolated from the output of the amplifier, and hence, the pole caused by C_L is no longer in the feedback loop. The larger the value of R_{ISO}, the more stable the output voltage is. If values of R_{ISO} are sufficiently large, the feedback loop is stable, independent of the value of C_L. However, larger values of R_{ISO} result in reduced output swing and reduced output current drive.

Figure 35. Isolating Capacitive Load

7.4.2 Noise Performance

The LMV84x devices have good noise specifications and are frequently used in low-noise applications. Therefore it is important to determine the noise of the total circuit. Besides the input-referred noise of the op amp, the feedback resistors may have an important contribution to the total noise.

For applications with a voltage input configuration, in general it is beneficial general, beneficial to keep the resistor values low. In these configurations high resistor values mean high noise levels. However, using low resistor values will increase the power consumption of the application. This is not always acceptable for portable applications, so there is a trade-off between noise level and power consumption.

Besides the noise contribution of the signal source, three types of noise need to be taken into account for calculating the noise performance of an op amp circuit:

- Input-referred voltage noise of the op amp
- Input-referred current noise of the op amp
- Noise sources of the resistors in the feedback network, configuring the op amp

To calculate the noise voltage at the output of the op amp, the first step is to determine a total equivalent noise source. This requires the transformation of all noise sources to the same reference node. A convenient choice for this node is the input of the op amp circuit. The next step is to add all the noise sources. The final step is to multiply the total equivalent input voltage noise with the gain of the op amp configuration.

If the input-referred voltage noise of the op amp is already placed at the input, the user can use the inputreferred voltage noise without further transferring. The input-referred current noise needs to be converted to an input-referred voltage noise. The current noise is negligibly small, as long as the equivalent resistance is not unrealistically large, so the user can leave the current noise out for these examples. That leaves the user with the noise sources of the resistors, being the thermal noise voltage. The influence of the resistors on the total noise can be seen in the following examples, one with high resistor values and one with low resistor values. Both examples describe an op amp configuration with a gain of 101 which gives the circuit a bandwidth of 44.5 kHz. The op amp noise is the same for both cases, that is, an input-referred noise voltage of 20 nV/ \sqrt{Hz} and a negligibly small input-referred noise current.

Figure 36. Noise Circuit

Device Functional Modes (continued)

To calculate the noise of the resistors in the feedback network, the equivalent input-referred noise resistance is needed. For the example in Figure 36, this equivalent resistance R_{eq} can be calculated using Equation 1:

$$
R_{eq} = \frac{R_F \times R_G}{R_F + R_G} \tag{1}
$$

The voltage noise of the equivalent resistance can be calculated using Equation 2:

$$
e_{nr} = \sqrt{4kTR_{eq}}
$$

where

 e_{nr} = thermal noise voltage of the equivalent resistor

 R_{eq} (V/ \sqrt{Hz})

 $k =$ Boltzmann constant (1.38 x 10⁻²³ J/K)

$$
• T = absolute temperature (K)
$$

• R_{eq} = resistance (Ω) (2) (2)

The total equivalent input voltage noise is given by Equation 3:

$$
e_{n\;in}=\sqrt{{e_{nv}}^2+{e_{nr}}^2}
$$

where

- $e_{n \text{ in}}$ = total input equivalent voltage noise of the circuit
- $e_{\text{nv}} =$ input voltage noise of the op amp (3)

The final step is multiplying the total input voltage noise by the noise gain using Equation 4, which is in this case the gain of the op amp configuration:

$$
e_{n \text{ out}} = e_{n \text{ in}} \times A_{noise} \tag{4}
$$

The equivalent resistance for the first example with a resistor R_F of 10 MΩ and a resistor R_G of 100 kΩ at 25°C (298 K) equals Equation 5:

$$
e_{n \text{ out}} = e_{n \text{ in}} \times A_{noise}
$$
\n
$$
equivalent resistance for the first example with a resistor RF of 10 M Ω and a resistor R_G of 100 k Ω at 25°C K) equals Equation 5:
\n
$$
R_{eq} = \frac{R_F \times R_G}{R_F + R_G} = \frac{10 M\Omega \times 100 k\Omega}{10 M\Omega + 100 k\Omega} = 99 k\Omega
$$
\n(5)
$$

Now the noise of the resistors can be calculated using Equation 6, yielding:

$$
e_{nr} = \sqrt{4kTR_{eq}}
$$

= $\sqrt{4 \times 1.38 \times 10^{-23} J/K \times 298K \times 99 k\Omega}$
= 40 nV/ \sqrt{Hz} (6)

The total noise at the input of the op amp is calculated in Equation 7:

$$
e_{n \text{ in}} = \sqrt{e_{n}^2 + e_{n}^2}
$$

= $\sqrt{(20 \text{ nV}/\sqrt{Hz})^2 + (40 \text{ nV}/\sqrt{Hz})^2} = 45 \text{ nV}/\sqrt{Hz}$ (7)

For the first example, this input noise, multiplied with the noise gain, in Equation 8 gives a total output noise of:

$$
e_{n \text{ out}} = e_{n \text{ in}} \times A_{noise}
$$

= 45 nV/ $\sqrt{Hz} \times 101 = 4.5 \mu V/\sqrt{Hz}$ (8)

In the second example, with a resistor R_F of 10 kΩ and a resistor R_G of 100 Ω at 25°C (298 K), the equivalent resistance equals Equation 9:

$$
R_{eq} = \frac{R_F \times R_G}{R_F + R_G} = \frac{10 \ k\Omega \times 100 \ \Omega}{10 \ k\Omega + 100 \ \Omega} = 99 \ \Omega
$$
\n(9)

The resistor noise for the second example is calculated in Equation 10:

Device Functional Modes (continued)

$$
e_{nr} = \sqrt{4kTR_{eq}}
$$

= $\sqrt{4 \times 1.38 \times 10^{-23} J/K \times 298 K \times 99 \Omega}$
= $1 \frac{nV}{\sqrt{Hz}}$ (10)

The total noise at the input of the op amp is calculated in Equation 10:

$$
e_{n \, in} = \sqrt{e_{nv}^2 + e_{nr}^2}
$$
\n
$$
= \sqrt{(20 \, nV/\sqrt{Hz})^2 + (1 \, nV/\sqrt{Hz})^2}
$$
\n
$$
= 20 \, nV/\sqrt{Hz}
$$
\n(11)

For the second example the input noise, multiplied with the noise gain, in Equation 12 gives an output noise of:

$$
e_{n \text{ out}} = e_{n \text{ in}} \times A_{noise}
$$

= 20 nV/ $\sqrt{Hz} \times 101 = 2 \mu V / \sqrt{Hz}$ (12)

In the first example the noise is dominated by the resistor noise due to the very high resistor values, in the second example the very low resistor values add only a negligible contribution to the noise and now the dominating factor is the op amp itself. When selecting the resistor values, it is important to choose values that do not add extra noise to the application. Choosing values above 100 kΩ may increase the noise too much. Low values keep the noise within acceptable levels; choosing very low values however, does not make the noise even lower, but can increase the current of the circuit.

7.5 Interfacing to High Impedance Sensor

With CMOS inputs, the LMV84x are particularly suited to be used as high impedance sensor interfaces.

Many sensors have high source impedances that may range up to 10 M Ω . The input bias current of an amplifier loads the output of the sensor, and thus cause a voltage drop across the source resistance, as shown in Figure 37. When an op amp is selected with a relatively high input bias current, this error may be unacceptable.

The low input current of the LMV84x significantly reduces such errors. The following examples show the difference between a standard op amp input and the CMOS input of the LMV84x.

The voltage at the input of the op amp can be calculated with Equation 13:

$$
V_{IN+} = V_S - I_B \times R_S \tag{13}
$$

For a standard op amp, the input bias Ib can be 10 nA. When the sensor generates a signal of 1 V (V_S) and the sensors impedance is 10 M Ω (R_s), the signal at the op amp input is calculated in Equation 14:

 V_{IN} = 1 V – 10 nA × 10 MΩ = 1 V - 0.1 V = 0.9 V (14)

For the CMOS input of the LMV84x, which has an input bias current of only 0.3 pA, this would give Equation 15: V_{IN} = 1 V – 0.3 pA × 10 MΩ = 1 V – 3 μV = 0.999997 V (15)

The conclusion is that a standard op amp, with its high input bias current input, is not a good choice for use in impedance sensor applications. The LMV84x devices, in contrast, are much more suitable due to the low input bias current. The error is negligibly small; therefore, the LMV84x are a must for use with high-impedance sensors.

Figure 37. High Impedance Sensor Interface

8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The rail-to-rail input and output of the LMV84x and the wide supply voltage range make these amplifiers ideal to use in numerous applications. Three sample applications, namely the active filter circuit, high-side current sensing, and thermocouple sensor interface, are provided in the *Typical Applications* section.

8.2 Typical Applications

8.2.1 Active Filter Circuit

Figure 38. Active Band-Pass Filter Implementation

8.2.1.1 Design Requirements

In this example it is required to design a bandpass filter with band-pass frequency of 10 kHz, and a center frequence of approximately 10% from the total frequence of the filter. This is achieved by cascading two bandpass filters, A and B, with slightly different center frequencies.

8.2.1.2 Detailed Design Procedure

The center frequency of the separate band-pass filters A, and B can be calculated by Equation 16:

$$
f_{mid} = \frac{1}{2\pi C} \sqrt{\frac{R_1 + R_3}{R_1 R_2 R_3}}
$$

where

 $C = 33$ nF

$$
• R1 = 2 K\Omega
$$

$$
R2 = 6.2 \text{ K}\Omega
$$

• and
$$
R3 = 45 \Omega
$$
 (16)

This gives Equation 17 for filter A:

$$
f_{\text{mid}} = \frac{1}{\pi \times 33 \text{ nF}} \sqrt{\frac{2 \text{ k}\Omega + 6.2 \text{ k}\Omega}{2 \text{ k}\Omega \times 6.2 \text{ k}\Omega \times 45 \text{ k}\Omega}} = 9.2 \text{ kHz}
$$
\n(17)

and Equation 18 for filter B with C = 27nF:

$$
T_{\text{mid}} = \frac{1}{\pi \times 33 \text{ nF}} \sqrt{\frac{2 \text{ k}\Omega \times 6.2 \text{ k}\Omega \times 45 \text{ k}\Omega}} = 9.2 \text{ kHz}
$$
\nEquation 18 for filter B with C = 27nF:\n
$$
f_{\text{mid}} = \frac{1}{\pi \times 27 \text{ nF}} \sqrt{\frac{2 \text{ k}\Omega + 6.2 \text{ k}\Omega}{2 \text{ k}\Omega \times 6.2 \text{ k}\Omega \times 45 \text{ k}\Omega}} = 11.2 \text{ kHz}
$$

Bandwidth can be calculated by Equation 19:

(18)

ISTRUMENTS

EXAS

Typical Applications (continued)

$$
B = \frac{1}{\pi R_2 C} \tag{19}
$$

For filter A, this gives Equation 20:

$$
B = \frac{1}{\pi \times 6.2 \text{ k}\Omega \times 33 \text{ nF}} = 1.6 \text{ kHz}
$$
 (20)

and Equation 21 for filter B:

$$
B = \frac{1}{\pi \times 6.2 \text{ k}\Omega \times 27 \text{ nF}} = 1.9 \text{ kHz}
$$
\n
$$
(21)
$$

8.2.1.3 Application Curve

The responses of filter A and filter B are shown as the thin lines in Figure 39; the response of the combined filter is shown as the thick line. Shifting the center frequencies of the separate filters farther apart, results in a wider band; however, positioning the center frequencies too far apart results in a less flat gain within the band. For wider bands more band-pass filters can be cascaded.

8.2.2 High-Side, Current-Sensing Circuit

Typical Applications (continued)

8.2.2.1 Design Requirements

In this example, it is desired to measure a current between 0 A and 2 A using a sense resistor of 100 mΩ, and convert it to an output voltage of 0 to 5 V. A current of 2 A flowing through the load and the sense resistor results in a voltage of 200 mV across the sense resistor. The op amp amplifies this 200 mV to fit the current range to the output voltage range.

8.2.2.2 Detailed Design Procedure

To measure current at a point in a circuit, a sense resistor is placed in series with the load, as shown in Figure 40. The current flowing through this sense resistor results in a voltage drop, that is amplified by the op amp. The rail-to-rail input and the low V_{OS} features make the LMV84x ideal op amps for high-side, currentsensing applications.

The input and the output relation of the circuit is given by Equation 22:

$$
V_{\text{OUT}} = R_{F}/R_{G} \times V_{\text{SENSE}} \tag{22}
$$

For a load current of 2 A and an output voltage of 5 V the gain would be $V_{\text{OUT}}/V_{\text{SENSE}} = 25$.

If the feedback resistor, R_F, is 100 kΩ, then the value for R_G is 4 kΩ. The tolerance of the resistors has to be low to obtain a good common-mode rejection.

8.2.3 Thermocouple Sensor Signal Amplification

Figure 41 is a typical example for a thermocouple amplifier application using an LMV841, LMV842, or LMV844. A thermocouple senses a temperature and converts it into a voltage. This signal is then amplified by the LMV841, LMV842, or LMV844. An ADC can then convert the amplified signal to a digital signal. For further processing the digital signal can be processed by a microprocessor, and can be used to display or log the temperature, or the temperature data can be used in a fabrication process.

Figure 41. Thermocouple Sensor Interface

8.2.3.1 Design Requirements

In this example it is desired to measure temperature in the range of 0°C to 500°C with a resolution of 0.5°C using a K-type thermocouple sensor. The power supply for both the LMV84x and the ADC is 3.3 V.

8.2.3.2 Detailed Design Procedure

A thermocouple is a junction of two different metals. These metals produce a small voltage that increases with temperature. A K-type thermocouple is a very common temperature sensor made of a junction between nickelchromium and nickel-aluminum. There are several reasons for using the K-type thermocouple. These include temperature range, the linearity, the sensitivity, and the cost.

STRUMENTS

Typical Applications (continued)

A K-type thermocouple has a wide temperature range. The range of this thermocouple is from approximately −200°C to approximately 1200°C, as can be seen in Figure 42. This covers the generally used temperature ranges.

Over the main part of the range the behavior is linear. This is important for converting the analog signal to a digital signal. The K-type thermocouple has good sensitivity when compared to many other types; the sensitivity is 41 µV/°C. Lower sensitivity requires more gain and makes the application more sensitive to noise. In addition, a K-type thermocouple is not expensive, many other thermocouples consist of more expensive materials or are more difficult to produce.

Figure 42. K-Type Thermocouple Response

The temperature range of 0°C to 500°C results in a voltage range from 0 mV to 20.6 mV produced by the thermocouple. This is shown in Figure 42.

To obtain the best accuracy the full ADC range of 0 to 3.3 V is used and the gain needed for this full range can be calculated Equation 23:

$$
A_V = 3.3 \text{ V} / 0.0206 \text{ V} = 160 \tag{23}
$$

If R_G is 2 kΩ, then the value for R_F can be calculated with this gain of 160. Because A_V = R_F / R_G, R_F can be calculated in Equation 24:

 $R_F = A_V \times R_G = 160 \times 2 \text{ k}\Omega = 320 \text{ k}\Omega$ (24)

To achieve a resolution of 0.5°C a step smaller than the minimum resolution is needed. This means that at least 1000 steps are necessary (500°C/0.5°C). A 10-bit ADC would be sufficient as this gives 1024 steps. A 10-bit ADC such as the two channel 10-bit ADC102S021 would be a good choice.

At the point where the thermocouple wires are connected to the circuit on the PCB unwanted parasitic thermocouple is formed, introducing error in the measurements of the actual thermocouple sensor.

Using an isothermal block as a reference will compensate for this additional thermocouple effect. An isothermal block is a good heat conductor. This means that the two thermocouple connections both have the same temperature. The temperature of the isothermal block can be measured, and thereby the temperature of the thermocouple connections. This is usually called the cold junction reference temperature. In the example, an LM35 is used to measure this temperature. This semiconductor temperature sensor can accurately measure temperatures from −55°C to 150°C.

The ADC in this example also coverts the signal from the LM35 to a digital signal, hence, the microprocessor can compensate for the amplified thermocouple signal of the unwanted thermocouple junction at the connector.

9 Power Supply Recommendations

The LMV84x is specified for operation from 2.7 V to 12 V (\pm 1.35 V to \pm 6 V) over a -40°C to 125°C temperature range. Parameters that can exhibit significant variance with regard to operating voltage or temperature are presented in the *Absolute Maximum Ratings*.

CAUTION

Supply voltages larger than 13.2 V can permanently damage the device.

For proper operation, the power supplies must be properly decoupled. For decoupling the supply lines, TI suggests placing 10-nF capacitors as close as possible to the operational amplifier power supply pins. For single supply, place a capacitor between V⁺ and V⁻ supply leads. For dual supplies, place one capacitor between V⁺ and ground, and one capacitor between V – and ground.

10 Layout

10.1 Layout Guidelines

- The V+ pin must be bypassed to ground with a low-ESR capacitor.
- The optimum placement is closest to the V+ and ground pins.
- Take care to minimize the loop area formed by the bypass capacitor connection between V+ and ground.
- The ground pin must be connected to the PCB ground plane at the pin of the device.
- The feedback components must be placed as close to the device as possible to minimize strays.

10.2 Layout Example

11 器件和文档支持

11.1 相关链接

下表列出了快速访问链接。类别包括技术文档、支持和社区资源、工具和软件以及立即订购快速访问。

表 **1.** 相关链接

11.2 接收文档更新通知

要接收文档更新通知,请导航至 Tl.com 上的器件产品文件夹。单击右上角的通知我进行注册,即可每周接收产品 信息更改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

11.3 社区资源

下列链接提供到 TI 社区资源的连接。链接的内容由各个分销商"按照原样"提供。这些内容并不构成 TI 技术规范, 并且不一定反映 TI 的观点;请参阅 TI 的 《使用条款》。

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11.6 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

12 机械、封装和可订购信息

以下页面包含机械、封装和可订购信息。这些信息是指定器件的最新可用数据。这些数据如有变更,恕不另行通知 和修订此文档。如欲获取此数据表的浏览器版本,请参阅左侧的导航。

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(1) The marketing status values are defined as follows:

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LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

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(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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OTHER QUALIFIED VERSIONS OF LMV841, LMV842, LMV844 :

• Automotive: LMV841-Q1, LMV842-Q1, LMV844-Q1

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

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PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal

 $D (R-PDSO-G14)$

PLASTIC SMALL OUTLINE

NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- 6 Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AB.

PW (R-PDSO-G14)

PLASTIC SMALL OUTLINE

This drawing is subject to change without notice. **B.**

 $\hat{\mathbb{C}}$ Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.

 $\hat{\mathbb{D}}$ Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.

E. Falls within JEDEC MO-153

 $D (R-PDSO-G8)$

PLASTIC SMALL OUTLINE

NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- 6 Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.

DGK (S-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE

A. All linear dimensions are in millimeters.

This drawing is subject to change without notice. **B.**

Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.

- Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
- E. Falls within JEDEC MO-187 variation AA, except interlead flash.

DGK (S-PDSO-G8)

PLASTIC SMALL OUTLINE PACKAGE

NOTES: Α. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

DCK (R-PDSO-G5)

PLASTIC SMALL-OUTLINE PACKAGE

- NOTES. A. All linear dimensions are in millimeters.
	- B. This drawing is subject to change without notice.
	- C. Body dimensions do not include mold flash or protrusion. Mold flash and protrusion shall not exceed 0.15 per side.
	- D. Falls within JEDEC MO-203 variation AA.

LAND PATTERN DATA

NOTES:

- All linear dimensions are in millimeters. А.
- **B.** This drawing is subject to change without notice.
- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.

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