

3 Channel 1A DC/DC Step-Down PMU

FEATURES

- 2.7V to 6.0V Input Voltage Range
- Output Voltage as Low as 0.6V
- 100% Duty Cycle in Dropout Operation
- High-Efficiency Synchronous-Mode Operation
- Input Voltage UVP&OVP
- Thermal Fault Protection
- Internal Soft-Start
- Fixed 2.3MHz Switching Frequency
- Over-Current Protection and Hiccup
- Available in a 20-pin 3mm x 3mm QFN Package

GENERAL DESCRIPTION

The TMI7003B is a Highly integrated power management IC designed to minimize power consumption in consumer and multimedia applications. It is targeted at Tablet, Mobile Internet Devices, Personal Navigation Devices, Digital Photo Frame, Portable DVD Player, Entertaining and Education Machine. Providing a complete system power management solution, the TMI7003B integrates 3-channel synchronous buck converter. The converters are optimized for high efficiency (greater than 93%) and feature integrated low impedance FETs.

APPLICATIONS

- Digital Set-top Box (STB)
- Flat-Panel Television and Monitors
- Portable Media Player (PMP)

TYPICAL APPLICATION

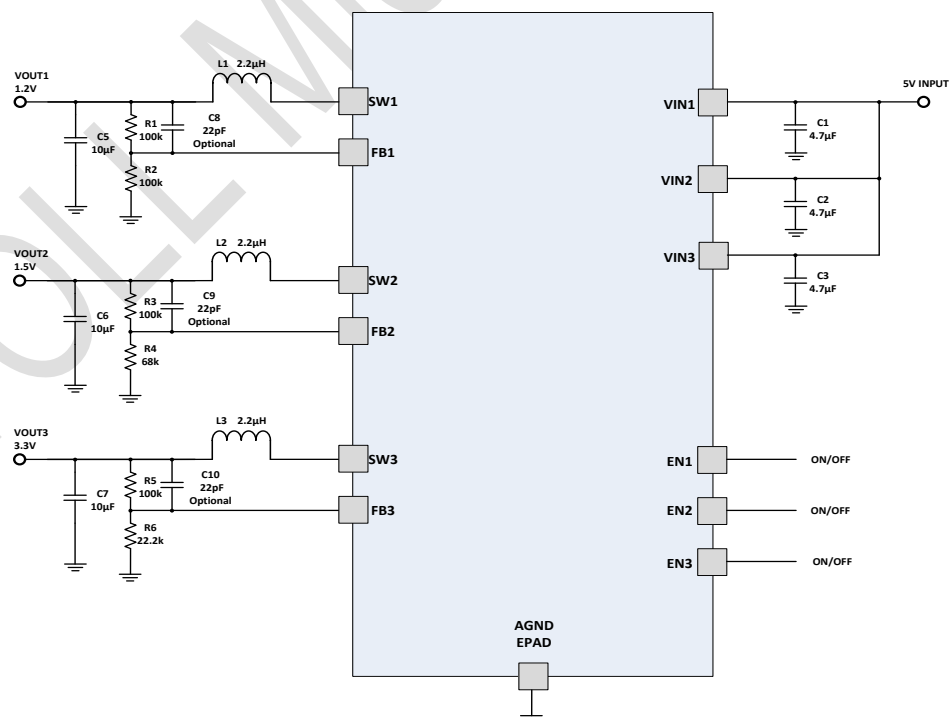
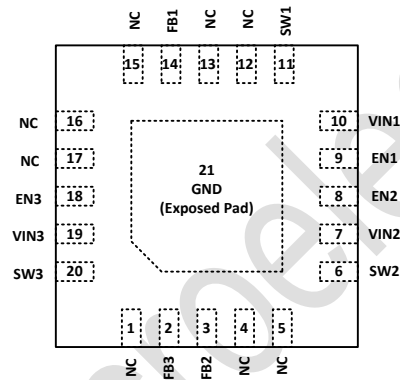


Figure 1. Basic Application Circuit

ABSOLUTE MAXIMUM RATINGS (Note 1)

Parameter	Value	Unit
Input Supply Voltage	-0.3~7.0	V
SW Voltages	-0.3~7.0	V
EN, FB Voltage	-0.3~7.0	V
Peak Current limit	1.2	A
Junction Temperature (Note 2)	150	°C
Power Dissipation	1.6	W
Lead Temperature (Soldering,10s)	260	°C

PIN CONFIGURATION



QFN3X3-20L (top view)

Top Mark: T7003B/XXXXX (T7003B: Device Code, XXXXX: Inside Code)

Part Number	Package	Top mark	Quantity/ Reel
TMI7003B	QFN3X3-20L	T7003B XXXXX	3000

TMI7003B devices are Pb-free and RoHS compliant.

PIN FUNCTIONS

Pin	Name	Function
1	NC	No Connection.
2	FB3	Feedback input of CH3. Connect to output voltage with a resistor divider
3	FB2	Feedback input of CH2. Connect to output voltage with a resistor divider
4	NC	No Connection.
5	NC	No Connection.
6	SW2	Internal MOSFET switching output of CH2
7	VIN2	Power input pin of CH2. Recommended to use a 10 μ F MLCC capacitor between VIN2 pin and GND.
8	EN2	CH2 turn on/turns off control input. Don't leave this pin floating
9	EN1	CH1 turn on/turns off control input. Don't leave this pin floating
10	VIN1	Power input pin of CH1. Recommended to use a 10 μ F MLCC capacitor between VIN1 pin and GND.
11	SW1	Internal MOSFET switching output of CH1
12	NC	No Connection.
13	NC	No Connection.
14	FB1	Feedback input of CH1. Connect to output voltage with a resistor divider
15	NC	No Connection.
16	NC	No connection.
17	NC	No Connection.
18	EN3	CH3 turn on/turns off control input. Don't leave this pin floating
19	VIN3	Power input pin of CH3. Recommended to use a 10 μ F MLCC capacitor between VIN3 pin and GND.
20	SW3	Internal MOSFET switching output of CH3.
21	GND(EP)	The Exposed Pad must be soldered to a large PCB copper plane and connected to GND for appropriate dissipation

ESD RATING

Items	Description	Value	Unit
V _{ESD}	Human Body Model for all pins	±2000	V

JEDEC specification JS-001

RECOMMENDED OPERATING CONDITIONS

Items	Description	Min	Max	Unit
Voltage Range	IN	2.7	6.0	V
T _J	Operating Junction Temperature Range	-40	125	°C

THERMAL RESISTANCE (Note 3)

Items	Description	Value	Unit
θ _{JA}	Junction-to-ambient thermal resistance	75	°C/W

ELECTRICAL CHARACTERISTICS
(V_{IN}=5V, T_A = 25°C, unless otherwise noted.)

Parameter	Test Conditions	Min	Typ	Max	Unit
Input Voltage Range		2.7		6.0	V
Buck Regulator 1, 2, 3					
OVP Threshold			6.1		V
UVLO Threshold			2.3		V
Input DC Supply Current					
PWM Mode	V _{OUT} = 90%, I _{LOAD} =0mA		150	300	μA
PFM Mode	V _{OUT} = 105%, I _{LOAD} =0mA		40	75	μA
Shutdown Mode	V _{EN} = 0V, V _{IN} =4.2V		0.1	1.0	μA
Regulated Feedback Voltage V _{FB}	T _A = 25°C, PWM operation	0.588	0.600	0.612	V
Oscillation Frequency	V _{OUT} =100%		2.3		MHz
	V _{OUT} =0V		300		kHz
On Resistance of PMOS	I _{SW} =100mA		300		mΩ
On Resistance of NMOS	I _{SW} =-100mA		150		mΩ
Peak Current Limit	V _{IN} = 5V, V _{OUT} =90%	1.2			A
EN Input High Voltage		1.5			V
EN Input Low Voltage				0.3	V
EN Leakage Current			±0.01	±1.0	μA
SW Leakage Current	V _{EN} =0V, V _{IN} =V _{SW} =5V		±0.01	±1.0	μA
Thermal Shutdown Threshold <small>(Note 4)</small>			160		°C
Thermal Shutdown Hysteresis <small>(Note 4)</small>			20		°C

Note 1: Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

Note 2: T_J is calculated from the ambient temperature T_A and power dissipation P_D according to the following formula: T_J = T_A + (P_D) × θ_{JA}.

Note 3: Measured on JESD51-7, 4-layer PCB.

Note 4: Thermal shutdown threshold and hysteresis are guaranteed by design.

GENERAL DESCRIPTION

Feature Description

TMI7003B is a highly efficient and integrated Power Management IC for Systems-on-a-Chip (SoCs), ASICs, and processors. The device incorporates 3 high-efficiency synchronous buck regulators.

Each of the buck regulators is specially designed for high-efficiency operation throughout the load range. With 2.3MHz typical switching frequency, the external L-C filter can be small and still provide very low output voltage ripple. The bucks are internally compensated to be stable with the recommended external inductors and capacitors as detailed in the application diagram. Synchronous rectification yields high efficiency for low voltage and high output currents.

Additional features include soft-start, under-voltage lockout, bypass, and current and thermal overload protection.

3 channel BUCKs are nearly identical in performance and mode of operation. They can operate in automatic mode (PWM/PFM). At very light loads, BUCKs enter PFM mode and operate with reduced switching frequency and supply current to maintain high efficiency.

Soft-Start

Each of BUCKs has an internal soft-start circuit that limits the in-rush current during startup. This allows the converters to gradually reach the steady-state operating point, thus reducing startup stresses and surges. During startup, the switch current limit is increased in steps. The startup time depends on the output capacitor size, load current and output voltage.

Current Limiting

A current limit feature protects the device and any external components during overload conditions. In PWM mode the current limiting is implemented by using an internal comparator that trips at current levels according to the buck capability. If the output is shorted to ground the device enters a timed current limit mode where the NFET is turned on for a longer duration until the inductor current falls below a low threshold, ensuring inductor current has more time to decay, thereby preventing runaway.

Under Voltage Lock Out (UVLO)

The VIN voltage is monitored for a supply under voltage condition, for which the operation of the device cannot be guaranteed. The part will automatically disable PMIC. To prevent unstable operation, the UVLO has a hysteresis window. An under-voltage lockout (UVLO) will disable BUCKs outputs, Once the supply voltage is above the UVLO hysteresis, the device will initiate a power-up sequence and then enter the active state.

Over Voltage Lack Out (OVLO)

The VIN voltage is monitored for a supply over voltage condition, for which the operation of the device cannot be guaranteed. The purpose of OVLO is to protect the part and all other components connected to the PMIC outputs from any damage and malfunction. Once VIN rises over about 6.2V, BUCKs will be disabled automatically. To prevent unstable operation, the OVLO has a hysteresis window. An over voltage lockout

(OVLO) will force the device into the reset state, Once the supply voltage goes below the OVLO lower threshold, the device will initiate a power-up sequence and then enter the active state.

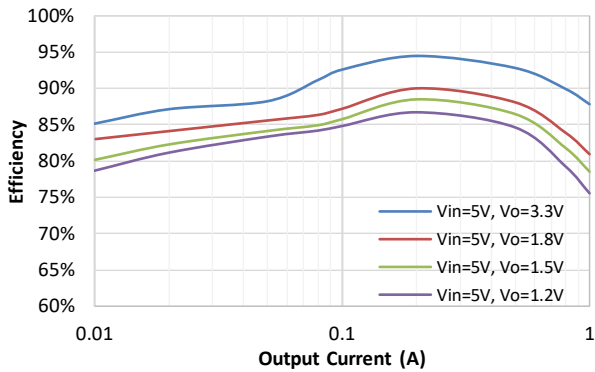
Thermal Shutdown (OTP)

The temperature of the silicon die is monitored for an over-temperature condition, for which the operation of the device cannot be guaranteed. The part will automatically be disabled if the temperature is too high. The thermal shutdown (OTP) will force the device into the reset state. In reset, all circuitry is disabled. To prevent unstable operation, the OTP has a hysteresis window of about 20°C. Once the temperature has decreased below the OTP hysteresis, the device will initiate a power-up sequence and then enter the active state. In the active state, the part will start up as if for the first time.

TYPICAL PERFORMANCE CHARACTERISTICS

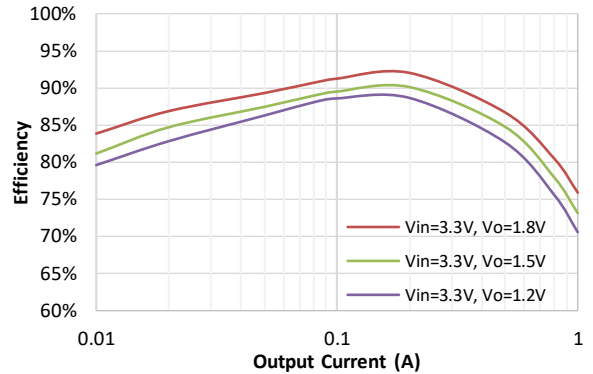
Efficiency at $V_{IN} = 5V$

$V_{IN} = 5V, L = 2.2\mu H, DCR = 20m\Omega$



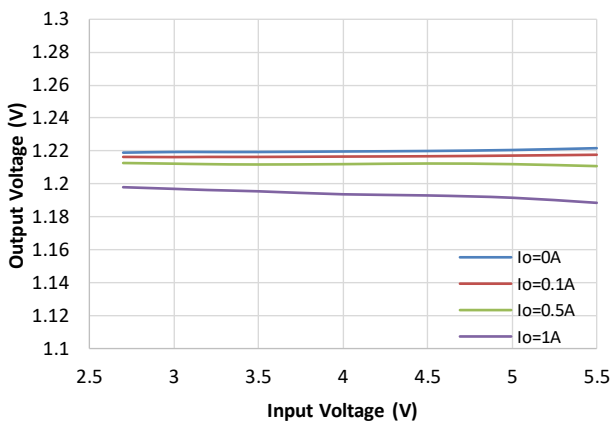
Efficiency at $V_{IN} = 3.3V$

$V_{IN} = 3.3V, L = 2.2\mu H, DCR = 20m\Omega$



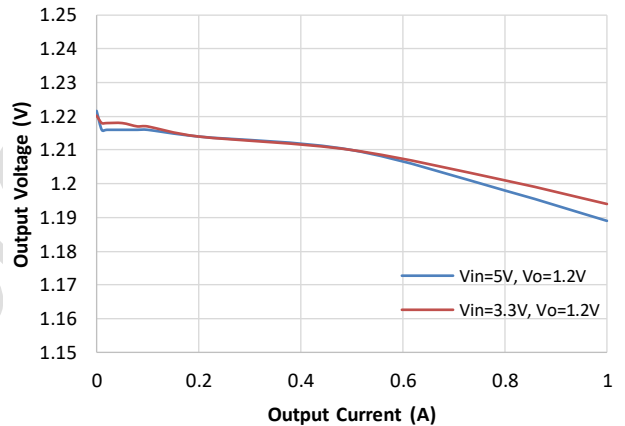
Line Regulation at $V_{OUT} = 1.2V$

$V_{OUT} = 1.2V, T_A = 25^\circ C$



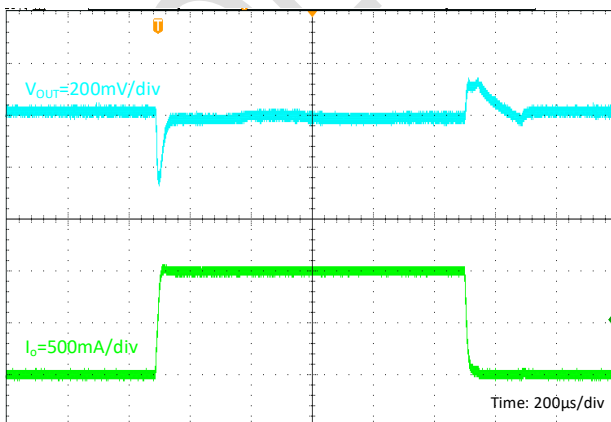
Load Regulation at $V_{OUT} = 1.2V$

$V_{OUT} = 1.2V, T_A = 25^\circ C$



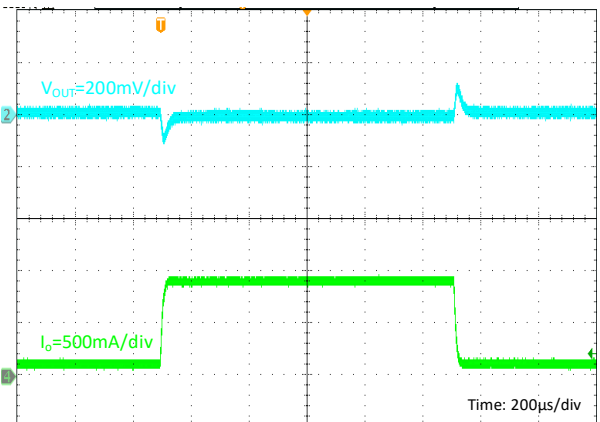
Load Transient

$V_{IN} = 5V, V_{OUT} = 3.3V, I_o = 0A \text{ to } 1A$



Load Transient

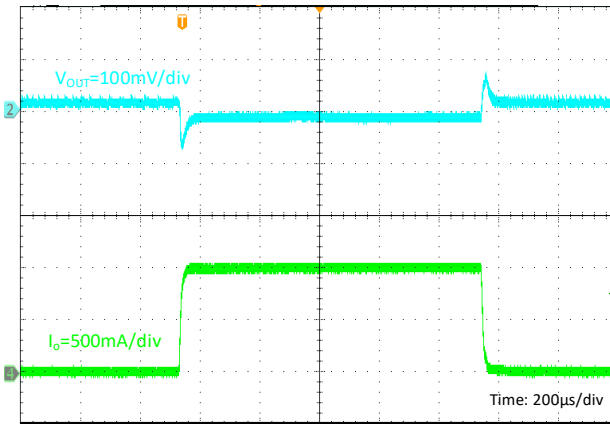
$V_{IN} = 5V, V_{OUT} = 3.3V, I_o = 0.1A \text{ to } 0.9A$



TYPICAL PERFORMANCE CHARACTERISTICS (continued)

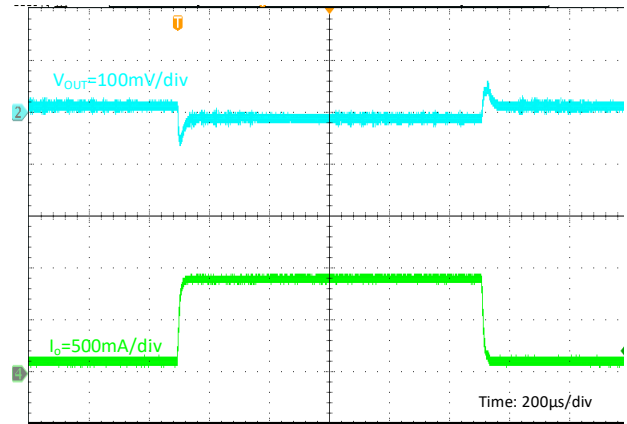
Load Transient

$V_{IN} = 5V, V_{OUT} = 1.2V, I_o = 0A \text{ to } 1A$



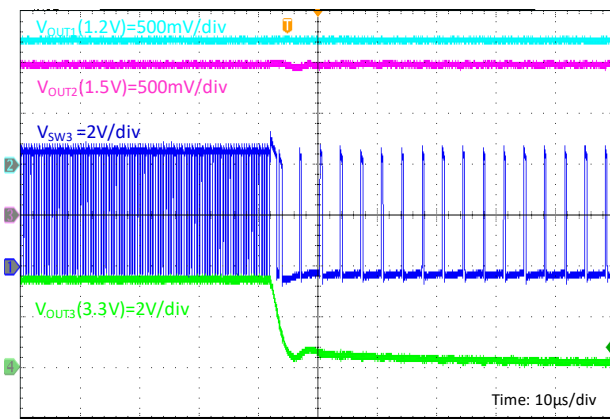
Load Transient

$V_{IN} = 5V, V_{OUT} = 1.2V, I_o = 0.1A \text{ to } 0.9A$



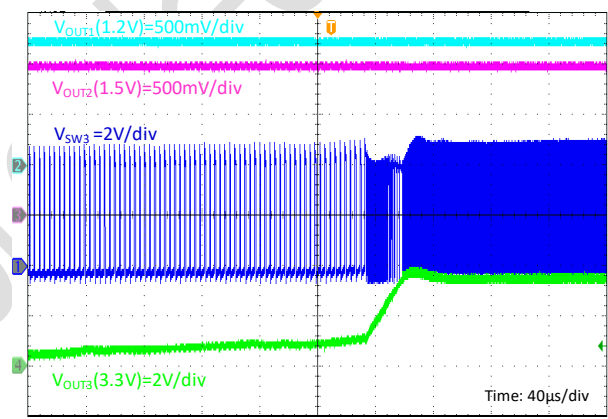
Output Short Entry

$V_{IN} = 5V, V_{OUT} = 3.3V, I_{OUT} = 0.5A$



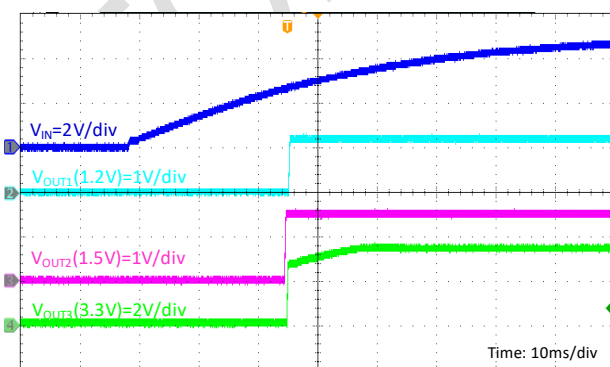
Output Short Recovery

$V_{IN} = 5V, V_{OUT} = 3.3V, I_{OUT} = 0.5A$



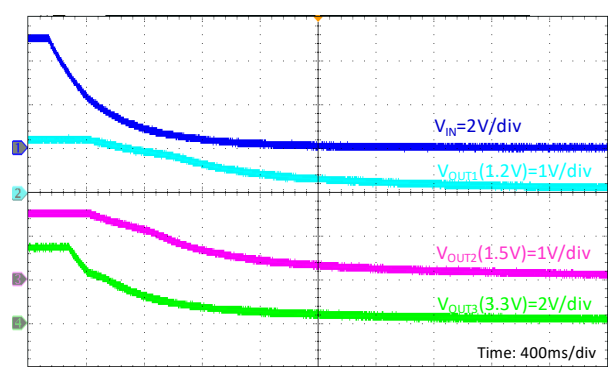
VIN Power On

$V_{IN} = 5V, \text{No Load}$



VIN Power down

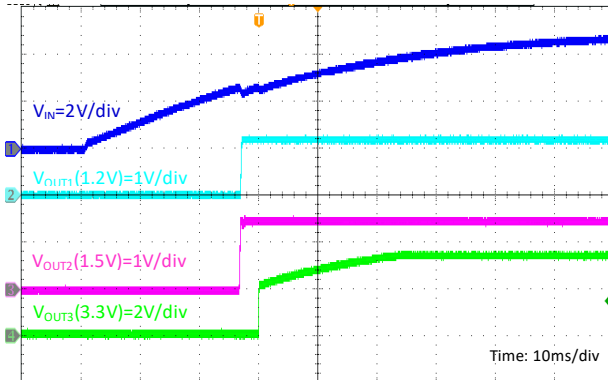
$V_{IN} = 5V, \text{No Load}$



TYPICAL PERFORMANCE CHARACTERISTICS (continued)

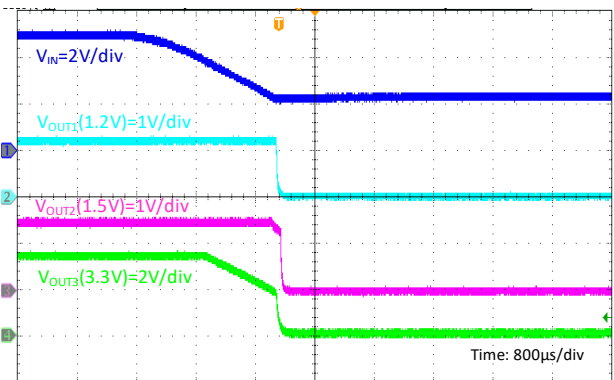
VIN Power On

V_{IN} = 5V, Full Load



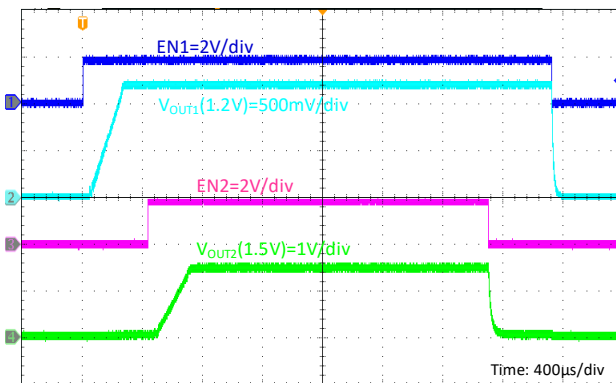
VIN Power down

V_{IN} = 5V, Full Load



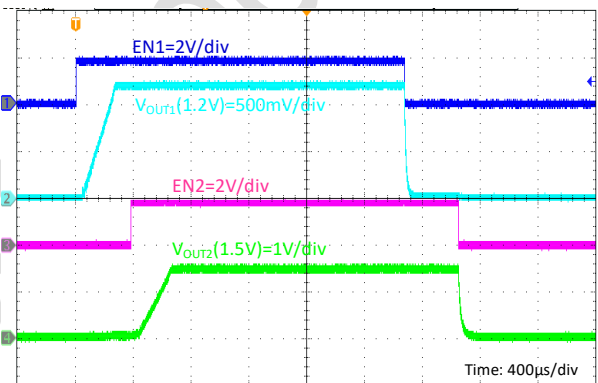
EN Enable Power On/Off

V_{IN} = 5V, EN1 and EN2, Full Load



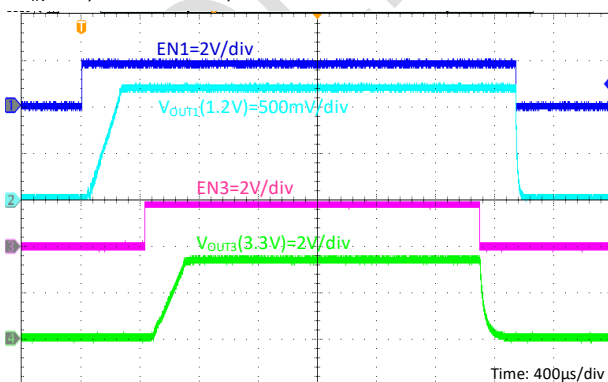
EN Disable Power down

V_{IN} = 5V, EN1 and EN2, Full Load



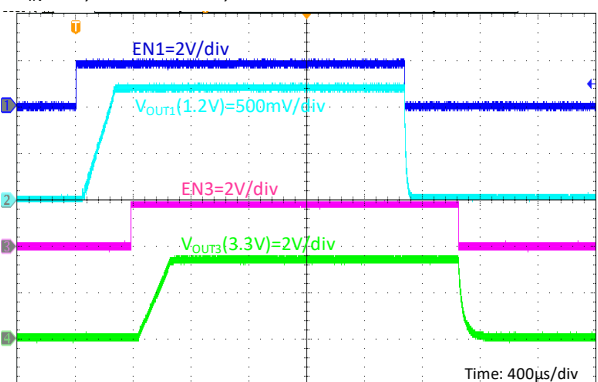
EN Enable Power On/Off

V_{IN} = 5V, EN1 and EN3, Full Load



EN Disable Power down

V_{IN} = 5V, EN1 and EN3, Full Load



DETAILED DESIGN PROCEDURE

External Components Selection

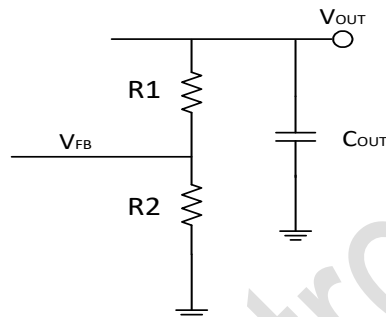
TMI7003B require an input capacitor, an output capacitor and an inductor. These components are critical to the performance of the device. TMI7003B are internally compensated and do not require external components to achieve stable operation. The output voltage can be programmed by resistor divider.

$$V_{OUT} = V_{FB} * \frac{R1+R2}{R2}$$

Select R1 value around 50kΩ

$$R2 = R1 * \frac{V_{FB}}{V_{OUT} - V_{FB}}$$

Where V_{FB} as 0.6V



Output Inductors and Capacitors Selection

There are several design considerations related to the selection of output inductors and capacitors:

- Load transient response
- Stability
- Efficiency
- Output ripple voltage
- Over current ruggedness

The device has been optimized for use with nominal LC values as shown in the Application Diagram.

BUCK Power Supply Recommendations

TMI7003B are designed to operate from input voltage supply range between 2.7 V and 6.0 V. This input supply must be well regulated. If the input supply is located more than a few inches, additional bulk capacitance may be required in addition to the ceramic bypass capacitors. A ceramic capacitor with an effective value of 4.7μF is a typical choice.

V_{IN} must be connected to input capacitors as close as possible.

BUCK Inductor Selection

The recommended inductor values are shown in the Application Diagram. It is important to guarantee the inductor core does not saturate during any foreseeable operational situation. The inductor should be rated to handle the peak load current plus the ripple current: Care should be taken when reviewing the different saturation current ratings that are specified by different manufacturers. Saturation current ratings are typically specified at 25°C, so ratings at maximum ambient temperature of the application should be requested from the manufacturer.

$$I_{L(MAX)} = I_{LOAD(MAX)} + I_{RIPPLE} = I_{LOAD(MAX)} + \frac{D * (V_{IN} - V_{OUT})}{2 * L * F_S}$$

$$D = \frac{V_{OUT}}{V_{IN}}, F_S = 1\text{MHz}, L = 2.2\mu\text{H}$$

where

- $I_{L(MAX)}$: Max inductor Current
- $I_{LOAD(MAX)}$: Max load current
- I_{RIPPLE} : Peak-to-Peak inductor current
- D: Estimated duty factor
- V_{IN} : Input voltage
- V_{OUT} : Output voltage
- F_S : Switching frequency, Hertz

Recommended Method for BUCK Inductor Selection

The best way to guarantee the inductor does not saturate is to choose an inductor that has saturation current rating greater than the maximum device current limit, as specified in the Electrical Characteristics. In this case the device will prevent inductor saturation by going into current limit before the saturation level is reached.

Alternate Method for BUCK Inductor Selection

If the recommended approach cannot be used care must be taken to guarantee that the saturation current is greater than the peak inductor current:

$$I_{SAT} > I_{LPEAK}$$

$$I_{LPEAK} = I_{OUTMAX} + \frac{I_{RIPPLE}}{2}$$

$$I_{RIPPLE} = \frac{D * (V_{IN} - V_{OUT})}{L * F_S}$$

$$D = \frac{V_{OUT}}{V_{IN} * EFF}$$

where

- I_{SAT} : Inductor saturation current at operating temperature
- I_{LPEAK} : Peak inductor current during worst case conditions
- I_{OUTMAX} : Maximum average inductor current
- I_{RIPPLE} : Peak-to-Peak inductor current
- V_{OUT} : Output voltage
- V_{IN} : Input voltage
- L: Inductor value in Henries at I_{OUTMAX}
- F_S : Switching frequency, Hertz
- D: Estimated duty factor
- EFF: Estimated power supply efficiency

I_{SAT} may not be exceeded during any operation, including transients, startup, high temperature, worst case conditions, etc.

Output and Input Capacitors Characteristics

Special attention should be paid when selecting these components. The DC bias of these capacitors can result in a capacitance value that falls below the minimum value given in the recommended capacitor specifications table.

The ceramic capacitor's actual capacitance can vary with temperature. The capacitor type X7R, which operates over a temperature range of -55°C to $+125^{\circ}\text{C}$, will only vary the capacitance to within $\pm 15\%$. The capacitor type X5R has a similar tolerance over a reduced temperature range of -55°C to $+85^{\circ}\text{C}$. Many large value ceramic capacitors, larger than $1\mu\text{F}$ are manufactured with Z5U or Y5V temperature characteristics. Their capacitance can drop by more than 50% as the temperature varies from 25°C to 85°C , therefore X5R or X7R is recommended over Z5U and Y5V in applications where the ambient temperature will change significantly above or below 25°C .

BUCK Output Capacitor Selection

The output capacitor of a switching converter absorbs the AC ripple current from the inductor and provides the initial response to a load transient. The ripple voltage at the output of the converter is the product of the ripple current flowing through the output capacitor and the impedance of the capacitor. The impedance of the capacitor can be dominated by capacitive, resistive, or inductive elements within the capacitor, depending on the frequency of the ripple current. Ceramic capacitors have very low ESR and remain capacitive up to high frequencies. Their inductive component can be usually neglected at the frequency ranges the switcher operates.

The output-filter capacitor smooths out the current flow from the inductor to the load and helps maintain a steady output voltage during transient load changes. It also reduces output voltage ripple. These capacitors must be selected with sufficient capacitance and low enough ESR to perform these functions.

Note that the output voltage ripple increases with the inductor current ripple and the Equivalent Series Resistance of the output capacitor (ESRCOUT), also note that the actual value of the capacitor's ESRCOUT is frequency and temperature dependent, as specified by its manufacturer. The ESR should be calculated at the applicable switching frequency and ambient temperature.

$$V_{\text{OUT-RIPPLE-PP}} = \frac{I_{\text{RIPPLE}}}{8 * F_s * C_{\text{OUT}}}$$

Where

$$I_{\text{RIPPLE}} = \frac{D * (V_{\text{IN}} - V_{\text{OUT}})}{2 * L * F_s}$$

$$D = \frac{V_{\text{OUT}}}{V_{\text{IN}}}$$

where

- $V_{\text{OUT-RIPPLE-PP}}$: estimated output voltage ripple
- I_{RIPPLE} : estimated current ripple
- D : Estimated duty factor

Output ripple can be estimated from the vector sum of the reactive (capacitance) voltage component and the real (ESR) voltage component of the output capacitor:

$$V_{\text{OUT-RIPPLE-PP}} = \sqrt{V_{\text{ROUT}}^2 + V_{\text{COUT}}^2}$$

where

$$V_{ROUT} = I_{RIPPLE} * ESR_{COUT}$$

$$V_{COUT} = \frac{I_{RIPPLE}}{8 * F_S * C_{OUT}}$$

where

- $V_{OUT-RIPPLE-PP}$: estimated output ripple,
- V_{ROUT} : estimated real output ripple,
- V_{COUT} : estimated reactive output ripple.

The device is designed to be used with ceramic capacitors on the outputs of the buck regulators. The recommended dielectric type of these capacitors is X5R, X7R, or of comparable material to maintain proper tolerances over voltage and temperature. The recommended effective value for the output capacitors is 10 μ F with an ESR of 2m Ω or less. The output capacitors need to be mounted as close as possible to the output/ground terminals of the device.

BUCK Input Capacitor Selection

Input capacitor should be located as close as possible to their corresponding VIN and GND terminals, tantalum capacitor can also be located in the proximity of the device.

The input capacitor supplies the AC switching current drawn from the switching action of the internal power MOSFETs. The input current of a buck converter is discontinuous, so the ripple current supplied by the input capacitor is large. The input capacitor must be rated to handle both the RMS current and the dissipated power. The input capacitor must be rated to handle this current:

$$V_{RMS_CIN} = I_{OUT} \frac{\sqrt{V_{OUT} * (V_{IN} - V_{OUT})}}{V_{IN}}$$

The power dissipated in the input capacitor is given by:

$$P_{D_CIN} = I_{RMS_CIN}^2 * R_{ESR_CIN}$$

The device is designed to be used with ceramic capacitors on the inputs of the buck regulators. The recommended dielectric type of these capacitors is X5R, X7R, or of comparable material to maintain proper tolerances over voltage and temperature. The minimum recommended effective value for the input capacitor is larger than 4.7 μ F with an ESR of 10m Ω or less. The input capacitors need to be mounted as close as possible to the power/ground input terminals of the device.

The input power source supplies the average current continuously. During the high side MOSFET switch on-time, however, the demanded di/dt is higher than can be typically supplied by the input power source. This delta is supplied by the input capacitor.

A simplified “worst case” assumption is that all of the high side MOSFET current is supplied by the input capacitor. This will result in conservative estimates of input ripple voltage and capacitor RMS current.

Input ripple voltage is estimated as follows:

$$V_{PPIN} = \frac{I_{OUT} * D}{C_{IN} * F_S} + I_{OUT} * ESR_{CIN}$$

where

- V_{PPIN} : Estimated peak-to-peak input ripple voltage
- I_{OUT} : Output current
- C_{IN} : Input capacitor value

- $ESRC_{IN}$: Input capacitor ESR

This capacitor is exposed to significant RMS current, so it is important to select a capacitor with an adequate RMS current rating. Capacitor RMS current estimated as follows:

$$I_{RMS_{CIN}} = \sqrt{D \cdot (I_{OUT}^2 + \frac{I_{RIPPLE}^2}{12})}$$

Where

- $I_{RMS_{CIN}}$: Estimated input capacitor RMS current

Layout Guidelines

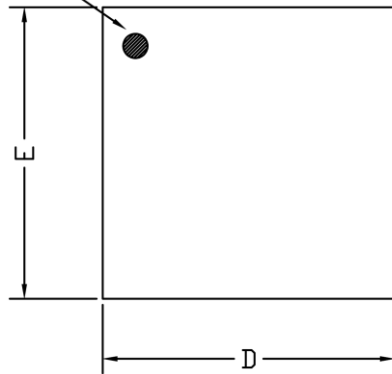
PC board layout is an important part of DC-DC converter design. Poor board layout can disrupt the performance of a DC-DC converter and surrounding circuitry by contributing to EMI, ground bounce, and resistive voltage loss in the traces. These can send erroneous signals to the DC-DC converter resulting in poor regulation or instability. Good layout can be implemented by following a few simple design rules.

1. Minimize area of switched current loops. In a buck regulator there are two loops where currents are switched rapidly. The first loop starts from the C_{IN} input capacitor, to the regulator VIN terminal, to the regulator SW terminal, to the inductor then out to the output capacitor C_{OUT} and load. The second loop starts from the output capacitor ground, to the regulator GND terminals, to the inductor and then out to C_{OUT} and the load. To minimize both loop areas the input capacitor should be placed as close as possible to the VIN terminal. Grounding for both the input and output capacitors should consist of a small localized top side plane that connects to GND. The inductor should be placed as close as possible to the SW pin and output capacitor.
2. Minimize the copper area of the switch node. The SW terminals should be directly connected with a trace that runs on top side directly to the inductor. To minimize IR losses this trace should be as short as possible and with a sufficient width. However, a trace that is wider than 100 mils will increase the copper area and cause too much capacitive loading on the SW terminal. The inductors should be placed as close as possible to the SW terminals to further minimize the copper area of the switch node.
3. Have a single point ground for all device analog grounds. The ground connections for the feedback components should be connected together then routed to the GND of the device. This prevents any switched or load currents from flowing in the analog ground plane. If not properly handled, poor grounding can result in degraded load regulation or erratic switching behavior.
4. Minimize trace length to the FB terminal. The feedback trace should be routed away from the SW pin and inductor to avoid contaminating the feedback signal with switch noise.
5. Make input and output bus connections as wide as possible. This reduces any voltage drops on the input or output of the converter and can improve efficiency. If voltage accuracy at the load is important make sure feedback voltage sense is made at the load. Doing so will correct for voltage drops at the load and provide the best output accuracy.

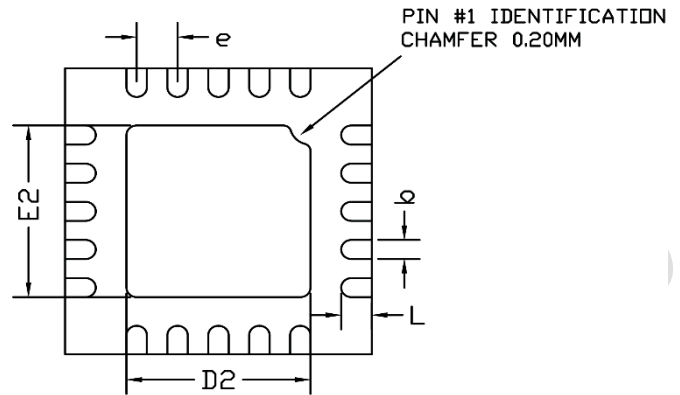
PACKAGE INFORMATION

QFN3x3-20L

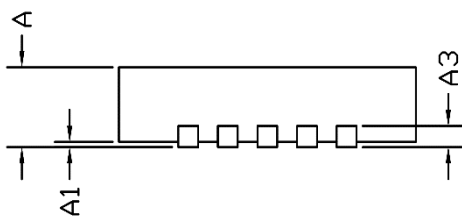
PIN 1 DOT BY MARKING



TOP VIEW



BOTTOM VIEW



SIDE VIEW

Unit: mm

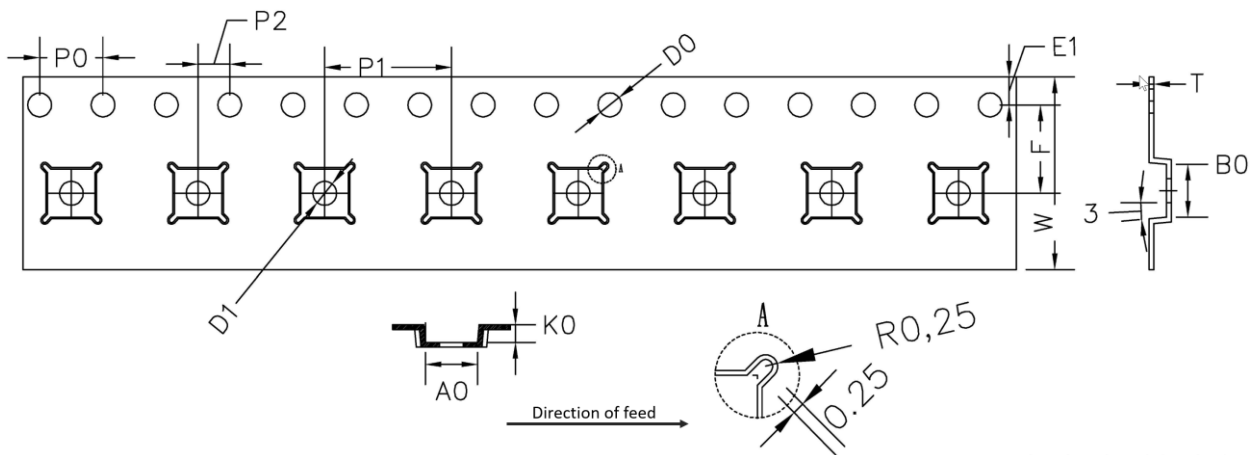
Symbol	Dimensions In Millimeters			Symbol	Dimensions In Millimeters		
	Min	Typ	Max		Min	Typ	Max
A	0.70	0.75	0.80	b	0.15	0.20	0.25
A1	0.00	-	0.05	L	0.25	0.30	0.35
A3	-	0.20 REF	-	D2	1.65	1.80	1.90
D	2.95	3.00	3.05	E2	1.65	1.80	1.90
E	2.95	3.00	3.05	e	0.40 BSC		

Note:

- 1) All dimensions are in millimeters.

TAPE AND REEL INFORMATION

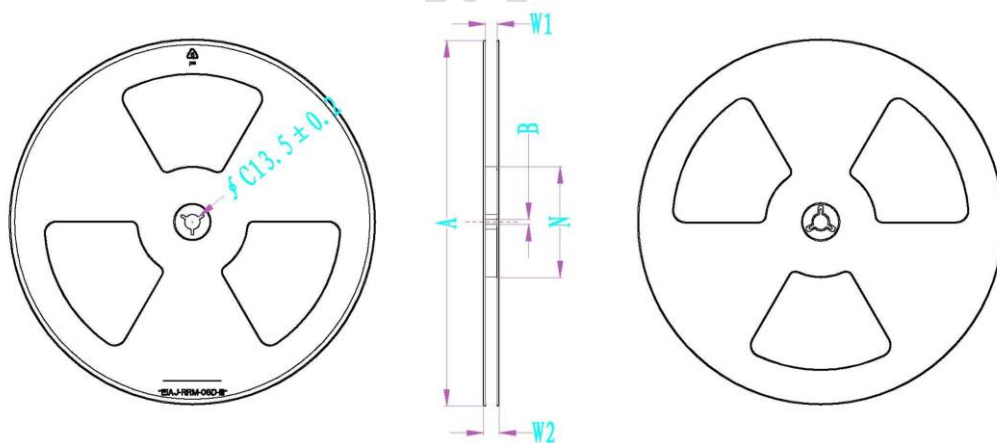
TAPE DIMENSIONS: QFN3x3-20L



Unit: mm

Symbol	Dimensions	Symbol	Dimensions	Symbol	Dimensions	Symbol	Dimensions
A0	3.30±0.10	P0	4.00±0.10	E1	1.75±0.10	D1	1.55±0.05
B0	3.30±0.10	P1	8.00±0.10	F	5.50±0.10	T	0.30±0.05
K0	1.10±0.10	P2	2.00±0.10	D0	1.55±0.05	W	12.00±0.30

REEL DIMENSIONS: QFN3x3-20L



Unit: mm

∅ A	B	∅ C	∅ N	W1	W2
330±1.0	4.7±0.5	13.5±0.2	100±0.5	13.4±0.5	17.4±0.5

Note:

- 1) All Dimensions are in Millimeter
- 2) Quantity of Units per Reel is 3000
- 3) MSL level is level 3.

X-ON Electronics

Largest Supplier of Electrical and Electronic Components

Click to view similar products for [Switching Controllers](#) category:

Click to view products by [TMI](#) manufacturer:

Other Similar products are found below :

[LV5065VB-TLM-H](#) [LV5066V-TLM-H](#) [LV5725JAZ-AH](#) [633888R](#) [MP2908AGF](#) [AZ7500EP-E1](#) [NCP1012AP133G](#) [NCP1217P133G](#)
[NCP1218AD65R2G](#) [NCP1234AD100R2G](#) [NCP1244BD065R2G](#) [NCP1336ADR2G](#) [NCP1587GDR2G](#) [NCP6153MNTWG](#)
[NCP81005MNTWG](#) [NCP81101BMNTXG](#) [NCP81205MNTXG](#) [HV9123NG-G-M934](#) [IR35207MTRPBF](#) [ISL6367HIRZ](#) [CAT874-80ULGT3](#)
[SJ6522AG](#) [SJE6600](#) [TLE63893GV50XUMA1](#) [IR35215MTRPBF](#) [SG3845DM](#) [NCP1216P133G](#) [NCP1236DD65R2G](#) [NCP1247BD100R2G](#)
[NCP1250BP65G](#) [NCP4202MNR2G](#) [NCP4204MNTXG](#) [NCP6132AMNR2G](#) [NCP81141MNTXG](#) [NCP81142MNTXG](#) [NCP81172MNTXG](#)
[NCP81203MNTXG](#) [NCP81206MNTXG](#) [NX2155HCUPTR](#) [UC3845ADM](#) [UBA2051C](#) [IR35201MTRPBF](#) [MAX8778ETJ+](#)
[MAX17500AAUB+T](#) [MAX17411GTM+T](#) [MAX16933ATIR/V+](#) [NCP1010AP130G](#) [NCP1063AD100R2G](#) [NCP1216AP133G](#)
[NCP1217AP100G](#)