### 1.5A Synchronous Step-Down DC/DC Converter

## GENERAL DESCRIPTION

XCA201A06BCR is a high efficiency step-down DC/DC converter operated with the current mode and the constant frequency. The internal switch and synchronous rectifier are integrated for high efficiency. External Schottky diodes are not required. The supply current is only $200 \mu \mathrm{~A}$ during operation and drops to less than $1 \mu \mathrm{~A}$ in shutdown. XCA201A06BCR can supply 1.5 A of load current from 2.5 V to 5.5 V supply voltage. The output voltage can be regulated as low as 0.6 V .
The switching frequency is set at 1.5 MHz , allowing the use of small surface mount inductors and capacitors. It can run $100 \%$ duty cycle for low dropout application. XCA201A06BCR is available in the DFN2x2-6L package.

## APPLICATIONS

-W-LAN (Module \& Router)
-SSD
-POS
-DTV
Ultra NB

- STB


## FEATURES

| Input Voltage | $: 2.5 \mathrm{~V} \sim 5.5 \mathrm{~V}$ |
| :--- | :--- |
| Output Voltage | $: 0.6 \sim 5.5 \mathrm{~V}$ (External Setting: 0.6 V ) |
| Output Current | $: 1.5 \mathrm{~A}$ |
| Oscillation Frequency | $: 1.5 \mathrm{MHz}$ |
| Stand-by Current | $:$ Less than $0.1 \mu \mathrm{~A}$ |
| Protection Circuits | $:$ Thermal Fault Protection |
|  | Short Circuit Protection |
| Control Method | $:$ PWM |
| Operating Ambient Temperature | $:-40^{\circ} \mathrm{C} \sim+85^{\circ} \mathrm{C}$ |
| Package | $:$ DFN $2 \times 2-6 \mathrm{~L}$ |
| Environmentally Friendly | $:$ EU RoHS Compliant, Pb Free |

## -TYPICAL APPLICATON CIRCUIT

Figure1. Typical Application Circuit


■TYPICAL PERFORMANCE CHARACTERISTICS


## BLOCK DIAGRAM



Figure2. Functional Block Diagram

## IPRODUCT CLASSIFICATION

| PRODUCT NAME | PACKAGE | ORDER UNIT |
| :---: | :---: | :---: |
| XCA201A06BCR | DFN2×2-6L | $3,000 /$ Reel |

## PIN CONFIGURATION



* If the dissipation pad needs to be connected to other pins, it should be connected to the GND pin.


## PIN ASSIGNMENT

| PIN NUMBER | PIN NAME | FUNCTIONS |
| :---: | :---: | :---: |
| 1 | NC | No Connection |
| 2 | CE | Chip Enable |
| 3 | $\mathrm{~V}_{\text {IN }}$ | Power Input |
| 4 | $\mathrm{~L}_{\mathrm{x}}$ | Switching Output |
| 5 | GND | Ground |
| 6 | FB | Output Voltage Sense PIN |

## FUNCTION

| PIN NAME | SIGNAL | STATUS |
| :---: | :---: | :---: |
| CE | H | Active |
|  | L | Stand-by |

* Please do not leave the CE pin open.


## ■ABSOLUTE MAXIMUM RATINGS

$\mathrm{Ta}=25^{\circ} \mathrm{C}$

| PARAMETER | SYMBOL | RATINGS | UNITS |
| :---: | :---: | :---: | :---: |
| Input Voltage | $\mathrm{V}_{\text {IN }}$ | $-0.3 \sim 6.0$ | V |
| Lx Pin Voltage | $\mathrm{V}_{\mathrm{Lx}}$ | $-0.3 \sim \mathrm{~V}_{\text {IN }}+0.3$ | V |
| Output Voltage | $\mathrm{V}_{\text {OUT }}$ | $-0.3 \sim 6.0$ | V |
| CE Input Voltage | $\mathrm{V}_{\mathrm{CE}}$ | $-0.3 \sim 6.0$ | V |
| Junction Temperature | Tj | 150 | ${ }^{\circ} \mathrm{C}$ |
| Thermal resistance (Junction-Air) | $\theta_{\mathrm{JA}}$ | 120 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Thermal resistance (Junction-Case) | $\theta_{\text {Jc }}$ | 20 | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |
| Operating Ambient Temperature | Topr | $-40 \sim+85$ | ${ }^{\circ} \mathrm{C}$ |
| Storage Temperature | Tstg | $-65 \sim+150$ | ${ }^{\circ} \mathrm{C}$ |

Note 1: Stresses exceed those ratings may damage the device.
Note 2: If out of its operating conditions, the device is not guaranteed to function.

## ELECTRICAL CHARACTERISTICS

$\left(\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}, \mathrm{Ta}=25^{\circ} \mathrm{C}\right.$, unless otherwise specified)

| PARAMETER | SYMBOL | CONDITIONS | MIN. | TYP. | MAX. | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Operating Voltage Range | $\mathrm{V}_{\text {IN }}$ |  | 2.5 | - | 5.5 | V |
| Supply Current | $\mathrm{I}_{\mathrm{DD}}$ | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\mathrm{CE}}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {FB }}=0.65 \mathrm{~V}$ | - | 150 | 350 | $\mu \mathrm{A}$ |
| Stand-by Current | Istd | $\mathrm{V}_{\text {IN }}=5.5 \mathrm{~V}, \mathrm{~V}_{\text {CE }}=0 \mathrm{~V}$, | - | 0.1 | 1.0 | $\mu \mathrm{A}$ |
| UVLO Voltage | Vuvio | Rising Edge | 1.9 | 2.1 | 2.4 | V |
| UVLO Hystericis Voltage | VuvLo |  | - | 0.2 | - | V |
| FB Voltage | $\mathrm{V}_{\text {FB }}$ | $\mathrm{V}_{\mathrm{IN}}=\mathrm{V}_{\text {CE }}=3.6 \mathrm{~V}$ | 0.582 | 0.6 | 0.618 | V |
| FB Input Current | $\mathrm{I}_{\text {FB }}$ | $\mathrm{V}_{\text {FB }}=0.65 \mathrm{~V}$ | -50 |  | 50 | nA |
| PFET On Resistance ${ }^{(*)}$ | $\mathrm{R}_{\text {(ON) }+\mathrm{P}}$ | ILx $=200 \mathrm{~mA}$ | - | 0.28 | - | $\Omega$ |
| NFET On Resistance ${ }^{(*)}$ | $\mathrm{R}_{\text {(ON)_N }}$ | ILx $=-200 \mathrm{~mA}$ | - | 0.25 | - | $\Omega$ |
| PFET Current Limit | Ilimt | Duty Cycle=100\%,Current Pulse, Width<1ms | 1.8 | 2.2 | - | A |
| Oscillator Frequency | $\mathrm{f}_{\text {osc }}$ | $\mathrm{V}_{\text {IN }}=\mathrm{V}_{\text {CE }}=3.6 \mathrm{~V}$, $\mathrm{I}_{\text {OUT }}=200 \mathrm{~mA}$ | 1.2 | 1.5 | 1.8 | MHz |
| Maximum Duty Cycle | $\mathrm{D}_{\text {max }}$ |  | - | 100 | - | \% |
| Minimum On-Time ${ }^{(*)}$ | ton_min |  | - | 80 | - | ns |
| Thermal Shutdown Trip Threshold ${ }^{(*)}$ | $\mathrm{T}_{\text {SD }}$ |  | - | 145 | - | ${ }^{\circ} \mathrm{C}$ |
| CE High-Level Input Voltage | CE_H | $-40^{\circ} \mathrm{C} \leq \mathrm{Ta} \leq+85^{\circ} \mathrm{C}$ | 1.5 | - | - | V |
| CE Low-Level Input Voltage | CE_L | $-40^{\circ} \mathrm{C} \leq \mathrm{Ta} \leq+85^{\circ} \mathrm{C}$ | - | - | 0.4 | V |
| CE Input Current | $\mathrm{I}_{\text {CE }}$ | $\mathrm{V}_{\text {CE }}=0 \mathrm{~V}$ to 5.5 V | -1 | - | 1 | $\mu \mathrm{A}$ |

[^0]
## TYPICAL APPLICATION CIRCUIT



| Vout(V) | R1( $\Omega$ ) | R2( $\Omega$ ) | $\mathrm{C}_{\text {IN }}$ | $\mathrm{C}_{\mathrm{L}}$ |
| :---: | :---: | :---: | :---: | :---: |
| 1.0 | 100k | 150k | Ceramic Cap. $25 \mathrm{~V} / 10 \mu \mathrm{~F}$ | Ceramic Cap.$25 \mathrm{~V} / 10 \mu \mathrm{~F}$ |
| 1.2 | 100k | 100k |  |  |
| 1.8 | 200k | 100k |  |  |
| 2.5 | 150k | 47k |  |  |
| 3.3 | 300k | 68k |  |  |

$V_{\text {OUT }}=F B \times(1+R 1 / R 2)$ with $R 2=300 \mathrm{k} \Omega$ to $60 \mathrm{k} \Omega$ and $(R 1 \times C F B)$ should be in the range $3 \times 10^{-6}$ and $1.2 \times 10^{-5}$ for component selection.
(Note)
In order to avoid the possibility that output ripple might become bigger in case of using a small size ceramic capacitor at low temperature, the fllowings are recommended:
(1)To add a $C F B=10 \mathrm{pF}$.
(2)To use $\mathrm{C}_{\mathrm{L}}=20 \mu \mathrm{~F}(10 \mu \mathrm{~F}+10 \mu \mathrm{~F})$
(3)To use 3216 Size ( $3.2 \mathrm{~mm} \times 1.6 \mathrm{~mm}$ ) For $10 \mu \mathrm{~F}$ capacitor.
e.g. TMK3216BJ106KL (25V/10 $\mu$ F, Taiyo Yuden), C3216X5R1E106K (25V/10 $\mu$ F, TDK)

## OPERATIONAL DESCRIPTION

## <Function Description>

The XCA201A06BCR high-efficiency switching regulator is a small, simple, DC/DC step-down converters capable of delivering up to 1.5 A of output current. The device operates in pulse-width modulation (PWM) at a fixed frequency of 1.5 MHz from a 2.5 V to 5.5 V input voltage and provides an output voltage from 0.6 V to $\mathrm{V}_{\mathbb{I N}}$, making the XCA201A06BCR ideal for on-board post-regulation applications. The high switching frequency allows for the use of smaller external components, and internal synchronous rectifiers improve efficiency and eliminate the typical Schottky free-wheeling diode. Using the on-resistance of the internal high-side MOSFET to sense switching currents eliminates current-sense resistors, further improving efficiency and cost.

## <Controller Block Function>

The XCA201A06BCR step-down converters use a PWM current-mode control scheme. An open-loop modulator compares the amplified voltage feedback signal against the sum of the amplified current-sense signal and the slope compensation ramp. At each rising edge of the internal clock, the internal high-side MOSFET turns on until the PWM comparator trips. During this on-time, current ramps up through the inductor, sourcing current to the output and storing energy in the inductor. The current-mode feedback system regulates the peak inductor current as a function of the output voltage error signal. Since the average inductor current is nearly the same as the peak inductor current ( $<30 \%$ ripple current), the circuit acts as a switch-mode transconductance amplifier. To preserve inner-loop stability and eliminate inductor stair-casing, a slope compensation ramp is summed into the main PWM comparator. During the second half of the cycle, the internal high-side P-channel MOSFET turns off, and the internal low-side N-channel MOSFET turns on. The inductor releases the stored energy as its current ramps down while still providing current to the output. The output capacitor stores charge when the inductor current exceeds the load current, and discharges when the inductor current is lower, smoothing the voltage across the load.

## <Over current Protection>

The XCA201A06BCR offers cycle-to-cycle current limiting for both high-side and low-side switches. The internal high-side MOSFET has a current limit. If the current flowing out of LX exceeds this limit, the high-side MOSFET turns off and the synchronous rectifier turns on. This lowers the duty cycle and causes the output voltage to droop until the current limit is no longer exceeded. A synchronous rectifier current limit protects the device from current flowing into LX.
When the output is shorted to ground, causing the output voltage to drop below $70 \%$ of its nominal output, the XCA201A06BCR is shut down momentarily and begins discharging the soft start capacitor. It will restart with a full soft-start when the soft- start capacitor is fully discharged. This hiccup process is repeated until the fault is removed. You can refer this to Figure3.


Figure3. The illustration of OCP and SCP

## <Soft-Start>

The XCA201A06BCR employ soft-start circuitry to reduce supply inrush current during startup conditions. When the device exits under-voltage lockout (UVLO) or shut-down mode, the soft-start circuitry will slowly ramp up the output voltage.

## <Shutdown Mode>

The CE pin allows for power sequencing between the PWM controller bias voltage and another voltage rail. The XCA201A06BCR remains in shutdown if the CE pin is lower than 400 mV . When the CE pin rises above the $\mathrm{V}_{\text {CE }}$ trip point, the XCA201A06BCR begins a new initialization and soft-start cycle.

## OPERATIONAL DESCRIPTION (Continued)

## <Thermal-Overload Protection>

Thermal-overload protection limits total power dissipation in the device. When the junction temperature exceeds $\mathrm{Tj}=+145^{\circ} \mathrm{C}$, a thermal sensor forces the device into shutdown, allowing the die to cool. The thermal sensor turns the device on again after the junction temperature cools by $15^{\circ} \mathrm{C}$, resulting in a pulsed output during continuous overload conditions. Following a thermal-shutdown condition, the soft-start sequence begins.

## IAPPLICATION INFORMATION

## <Setting Output Voltage>

The external resistor divider sets the output voltage. The feedback resistor R1 also sets the feedback loop bandwidth with the internal compensation capacitor. Table 1 shows a list of resistor selection for common output voltages.

$$
\text { Vout }=0.6 \times\left(1+\frac{\mathrm{R} 1}{\mathrm{R} 2}\right)
$$

<Selecting the Inductor>
A $1 \mu \mathrm{H}$ to $4.7 \mu \mathrm{H}$ inductor with DC current rating at least $25 \%$ higher than the maximum lout current is recommended for most applications. For best efficiency, the inductor DC resistance shall be $<20 \mathrm{~m} \Omega$.
For most designs, the required inductance value can be derived from the following equation.

$$
\mathrm{L}=\frac{\text { Vout } \times(\text { Vin-Vout })}{\text { Vin } \times \Delta \mathrm{IL} \times \text { fosc }}
$$

Where $\Delta I_{L}$ is the inductor ripple current. Choose inductor ripple current approximately $30 \%$ of the maximum lout current, 1.5A. The maximum inductor peak current is:

$$
\operatorname{IOUT}(\text { MAX })=\text { IOUT }+\frac{\Delta \mathrm{IL}}{2}
$$

Under light lout conditions below 100mA, larger inductance is recommended for improved efficiency.

## <Selecting the Input Capacitor>

The input capacitor reduces the surge current drawn from the input and switching noise from the device. The input capacitor impedance at the switching frequency shall be less than input source impedance to prevent high frequency switching current passing to the input. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, a $10 \mu \mathrm{~F}$ capacitor is sufficient.

## <Selecting the Output Capacitor>

The output capacitor keeps output voltage ripple small and ensures regulation loop stable. The output capacitor impedance shall be low at the switching frequency. Ceramic capacitors with X5R or X7R dielectrics are recommended.
The output ripple $\Delta \mathrm{V}_{\text {OUT }}$ is approximately:

$$
\Delta \text { Vout } \leqq \frac{\text { Vout } \times(\text { VIN-Vout })}{\operatorname{VIN} \times \mathrm{L} \times \text { fosc }} \times\left(\mathrm{ESR}+\frac{1}{8 \times \mathrm{CL} \times \text { fosc }}\right)
$$

## ■PCB PATTERN LAYOUT



FRONT


BACK (Flip Horizontal)


FRONT (PCB mounted)

## TYPICAL PERFORMANCE CHARACTERISTICS

(1) Efficiency vs. Output Current

(3)Ripple Voltage vs. Output Current

(5) Load Transient Response

(2) Output Voltage vs. Output Current

(4) Output Voltage Rise Wave Form


[^1]
## PACKAGING INFORMATION

## - DFN2×2-6L

## TIP VIEW



BZTTGM VIEW


| SYMBOLS | MIN. | TYP. | MAX. |
| :---: | :---: | :---: | :---: |
| A | 0.7 | 0.75 | 0.8 |
| A3 | - | 0.2 | - |
| b | 0.25 | 0.3 | 0.35 |
| D | - | 2 | - |
| D2 | 1.3 | 1.4 | 1.5 |
| E | - | 2 | - |
| E2 | 0.5 | 0.6 | 0.7 |
| e | - | 0.65 | - |
| L | 0.25 | 0.3 | 0.35 |

Unit:mm

PACKAGING INFORMATION (Continued)

## - DFN2×2-6L Reference Pattern Layout



MARKING RULE


01: Part No. XCA201A06BCR
XXXX: Denotes assembly Data Code \& Lot No.

1. The products and product specifications contained herein are subject to change without notice to improve performance characteristics. Consult us, or our representatives before use, to confirm that the information in this datasheet is up to date.
2. We assume no responsibility for any infringement of patents, patent rights, or other rights arising from the use of any information and circuitry in this datasheet.
3. Please ensure suitable shipping controls (including fail-safe designs and aging protection) are in force for equipment employing products listed in this datasheet.
4. The products in this datasheet are not developed, designed, or approved for use with such equipment whose failure of malfunction can be reasonably expected to directly endanger the life of, or cause significant injury to, the user.
(e.g. Atomic energy; aerospace; transport; combustion and associated safety equipment thereof.)
5. Please use the products listed in this datasheet within the specified ranges.

Should you wish to use the products under conditions exceeding the specifications, please consult us or our representatives.
6. We assume no responsibility for damage or loss due to abnormal use.
7. All rights reserved. No part of this datasheet may be copied or reproduced without the prior permission of TOREX SEMICONDUCTOR LTD.

TOREX SEMICONDUCTOR LTD.

## X-ON Electronics

Largest Supplier of Electrical and Electronic Components
Click to view similar products for Power Management Modules category:
Click to view products by Torex Semiconductor manufacturer:

Other Similar products are found below :
FPF1C2P5BF07A FPF1C2P5MF07AM FH2000NPBAP B0505S-2W HLK-5D1205 HLK-10D4805B B0505XT-1WR2-R B0505S-1W B1224S-1WR2 AP24N20-HV TAS25-24-W TAS10-5-W TAS10-24-W TAD10-1505-NI LS03-13B09R3 HCES1-05D12 HCS2-12D15 DC2626A DFR0756 CS-POWEREVER-02 CS-POWEREVER-01 01D-6R5-2A 11D-05S05NANL 12D-03S05N3KVAC 12D05S05N3WNL 12D-05S05RNL 12D-24S05R2W 12DA-05S05N2W 13D-05S05NCNL 13DS1-12D09NNL 13DSB-05S05N1.5KV 14D12S03R1KVNL 14DB-05S05N1.5KV 14DZ-05S05R2W MEE1S0309SC 22D-12D12NCNL EN5322QI LTM4624EY\#PBF 1SP0340V2M045 IGD515EI 1SP0335D2S1-5SNA0750G650300 2SP0115T2A0-FF600R12ME4 2SP0115T2A0-12 2SD106AI-17 UL 2SC0635T2A1-45 2SC0115T2A0-12 2SC0108T2F1-17 1SD210F2-MBN1200H45E2-H_Opt1 A0505S-1W A0505S-1WR2


[^0]:    * Guaranteed by design

[^1]:    time: $20 \mu \mathrm{~s} / \mathrm{div}$

