



## **Integrated DrMOS Power Stage**

#### **DESCRIPTION**

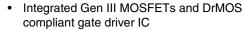
The SiC762CD is an integrated solution that contains PWM optimized n-channel MOSFETs (high side and low side) and a full featured MOSFET driver IC. The device complies with the Intel DrMOS standard for desktop and server  $V_{\rm core}$  power stages. The SiC762CD delivers up to 35 A continuous output current and operates from an input voltage range of 3 V to 27 V. The integrated MOSFETs are optimized for output voltages in the ranges of 0.8 V to 2.0 V with a nominal input voltage of 24 V. The device can also deliver very high power at 5 V output for ASIC applications.

The SiC762CD incorporates an advanced MOSFET gate driver IC. This IC accepts a single PWM input from the  $\rm V_R$  controller and converts it into the high side and low side MOSFET gate drive signals. The driver IC is designed to implement the skip mode (SMOD) function for light load efficiency improvement. Adaptive dead time control also works to improve efficiency at all load points. The SiC762CD has a thermal warning (THDN) that alerts the system of excessive junction temperature. The driver IC includes an enable pin, UVLO and shoot through protection.

The SiC762CD is optimized for high frequency buck applications. Operating frequencies in excess of 1 MHz can easily be achieved.

The SiC762CD is packaged in Vishay Siliconix high performance PowerPAK MLP6 x 6 package. Compact co-packaging of components helps to reduce stray inductance, and hence increases efficiency.

#### FEATURES



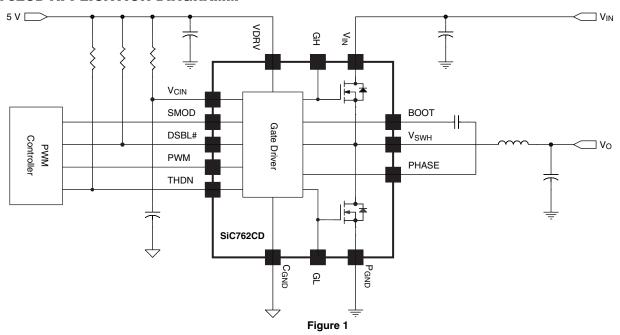


- Enables V<sub>core</sub> switching at 1 MHz
- Easily achieve > 90 % efficiency in multi-phase, low output voltage solutions
- Low ringing on the VSWH pin reduces EMI
- Pin compatible with DrMOS 6 x 6 version 3.0
- Tri-state PWM input function prevents negative output voltage swing
- 5 V logic levels on PWM
- MOSFET threshold voltage optimized for 5 V driver bias supply
- Automatic skip mode operation (SMOD) for light load efficiency
- Under-voltage lockout
- Built-in bootstrap schottky diode
- Adaptive deadtime and shoot through protection
- · Thermal shutdown warning flag
- Low profile, thermally enhanced PowerPAK<sup>®</sup> MLP 6 x 6 40 pin package
- Halogen-free according to IEC 61249-2-21 definition
- Compliant to RoHS directive 2002/95/EC

#### **APPLICATIONS**

- · CPU and GPU core voltage regulation
- Server, computer, workstation, game console, graphics boards, PC

#### **SIC762CD APPLICATION DIAGRAMM**



## SiC762CD

## Vishay Siliconix



ORDERING INFORMATION	
Part Number	Package
SiC762CD-T1-GE3	PowerPAK MLP66-40
SiC762DB	Reference board

Parameter	Symbol	Min.	Max.	Unit
Input Voltage	V <sub>IN</sub>	- 0.3	30	
Switch Node Voltage (DC)	V <sub>SW</sub>	- 0.3	30	
Drive Input Voltage	V <sub>DRV</sub>	- 0.3	7.0	
Control Input Voltage	V <sub>CIN</sub>	- 0.3	7.0	
Logic Pins	V <sub>PWM</sub> , V <sub>DSBL#</sub> , V <sub>THDN</sub> , V <sub>SMOD</sub>	- 0.3	V <sub>CIN</sub> + 0.3	V
Boot Voltage DC (referenced to C <sub>GND</sub> )	V <sub>BS</sub>	- 0.3	33	
Boot to Phase Voltage DC	V	- 0.3	7	
Boot to Phase Voltage < 200 ns	V <sub>BS_PH</sub>	- 0.3	9	
Ambient Temperature Range	T <sub>A</sub>	- 40	125	
Maximum Junction Temperature	T <sub>J</sub>		150	°C
Storage Junction Temperature	T <sub>STG</sub>	- 65	150	٠.
Soldering Peak Temperature			260	

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating/conditions for extended periods may affect device reliability.

RECOMMENDED OPERA	RECOMMENDED OPERATING CONDITIONS					
Parameter	Symbol	Min.	Тур.	Max.	Unit	
Input Voltage	V <sub>IN</sub>	3.0	12	24		
Control Input Voltage	V <sub>CIN</sub>	4.5		5.5	\ <u>\</u>	
Drive Input Voltage	V <sub>DRV</sub>	4.5		5.5	ľ	
Switch Node	V <sub>SW_DC</sub>		12	24		

a. Recommended operating conditions are specified over the entire temperature range, and all voltages referenced to  $P_{GND} = C_{GND}$  unless otherwise noted.

THERMAL RESISTANCE RATINGS					
Parameter	Symbol	Тур.	Max.	Unit	
Maximum Power Dissipation at T <sub>PCB</sub> = 25 °C	P <sub>D 25C</sub>		25	10/	
Maximum Power Dissipation at T <sub>PCB</sub> = 100 °C	P <sub>D_100C</sub>		10	W	
Thermal Resistance from Junction to Top	R <sub>th_J_TOP</sub>		15	0000	
Thermal Resistance from Junction to PCB	R <sub>th J PCB</sub>		5	°C/W	

a.  $T_A$  = 25 °C and all voltages referenced to  $P_{GND}$  =  $C_{GND}$  unless otherwise noted.



## SiC762CD Vishay Siliconix

ELECTRICAL SPECIFICATION	NS					
Parameter	Symbol	Test Conditions Unless Specified $V_{DSBL\#} = V_{SMOD} = 5 \text{ V}, \\ V_{IN} = 12 \text{ V}, V_{VDRV} = V_{VCIN} = 5 \text{ V}, \\ T_A = 25 \text{ °C}$	Min.	Typ. <sup>a</sup>	Max.	Unit
Power Supplies	- 1				I	l
-		V <sub>DSBL#</sub> = 0 V, no switching		21		
V <sub>CIN</sub> Control Input Current	I <sub>VCIN</sub>	V <sub>DSBL#</sub> = 5 V, no switching		350		μΑ
		$V_{DSBL\#} = 5 \text{ V, } f_s = 300 \text{ kHz, } D = 0.1$		500		
Drive Issuel Osmanl (Demonis)		f <sub>s</sub> = 300 kHz, D = 0.1		14	18	
Drive Input Current (Dynamic)	$I_{VDRV}$	f <sub>s</sub> = 1000 kHz, D = 0.1		40	54	mA
Bootstrap Supply			•	•		
Bootstrap Switch Forward Voltage	V <sub>BS Diode</sub>	V <sub>VCIN</sub> = 5 V, forward bias current 2 mA		0.60	0.75	V
Control Inputs (PWM, DSBL#, SMOD)			•			
PWM Rising Threshold	$V_{th\_pwm\_r}$		3.5	3.9	4.2	
PWM Falling Threshold	V <sub>th_pwm_f</sub>		0.8	1.0	1.2	v
PWM Tristate Rising Threshold	V <sub>th_tri_r</sub>		0.9	1.3	1.8	V
PWM Tristate Falling Threshold	$V_{th\_tri\_f}$		3.4	3.7	4.0	
PWM Tristate Rising Threshold Hysteresis	V <sub>hys_tri_r</sub>			280		mV
PWM Tristate Falling Threshold Hysteresis	V <sub>hys_tri_f</sub>			180		IIIV
Tristate Hold-Off Time <sup>b</sup>	t <sub>TSHO</sub>			150		ns
PWM Input Current	I	V <sub>PWM</sub> = 5 V		250		μΑ
r www imput Guiterit	I <sub>PWM</sub>	$V_{PWM} = 0 V$		- 250		μΑ
SMOD, DSBL# Logic Input Voltage	V <sub>LOGIC_LH</sub>	Rising (low to high)	2.0			V
SWOD, DSBL# Logic Input Voltage	$V_{LOGIC\_LH}$	Falling (high to low)			0.8	v
Pull Down Impedance	R <sub>THDN</sub>	5 k $\Omega$ resistor pull-up to $V_{CIN}$		40		Ω
THDN Output Low	$V_{THDNL}$	2 kzs resistor ball-ab to ACIN		0.04		V
Protection						
Thermal Warning Flag Set				150		
Thermal Warning Flag Clear				135		°C
Thermal Warning Flag Hysteresis				15		
Under Voltage Lockout V <sub>CIN</sub>	V 2	Rising, on threshold		3.3	3.9	V
Under Voltage Lockout V <sub>CIN</sub>	V <sub>UVLO</sub>	Falling, off threshold	2.3	2.95		
Under Voltage Lockout Hysteresis V <sub>CIN</sub>	V <sub>UVLO_HYST</sub>			400		mV
High Side Gate Discharge Resistor <sup>b</sup>	R <sub>HS_DSCRG</sub>	$V_{VDRV} = V_{VCIN} = 0 \text{ V}; V_{IN} = 12 \text{ V}$		20.2		kΩ

#### Notes:

a. Typical limits are established by characterization and are not production tested.

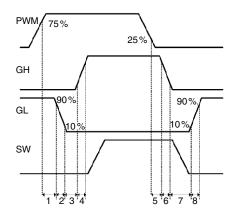
b. Guaranteed by design.



TIMING SPECIFICATION	S					
Parameter	Symbol	Test Conditions Unless Specified $V_{VDRV} = V_{VCIN} = V_{DSBL\#} = 5 \text{ V},$ $V_{VIN} = 12 \text{ V}, T_A = 25 \text{ °C}$	Min.	Тур.	Max.	Unit
Turn Off Propagation Delay High Side <sup>a</sup>	t <sub>d_off_</sub> HS	25 % of PWM to 90 % of GH	10	20	35	
Rise Time High Side	t <sub>r_HS</sub>	10 % to 90 % of GH		10		
Fall Time High Side	t <sub>f_HS</sub>	90 % to 10 % of GH		8		
Turn Off Propagation Delay Low Side <sup>a</sup>	t <sub>d_off_LS</sub>	75 % of PWM to 90 % of GL	10	37	45	ns
Rise Time Low Side	t <sub>r_LS</sub>	10 % to 90 % of GL		6		
Fall Time Low Side	t <sub>f_LS</sub>	90 % to 10 % of GL		5		
Dead Time Rising	t <sub>dead_on</sub>	10 % of GL to 10 % of GH		27		
Dead Time Falling	t <sub>dead_off</sub>	10 % of GH to 10 % of GL		19		

Note:

#### **TIMING DEFINITIONS**



Region	Definition	Symbol
1	Turn off propagation delay LS	t <sub>d_off_</sub> LS
2	Fall time LS	t <sub>f_LS</sub>
3	Dead time rising	t <sub>dead_on</sub>
4	Rise time HS	t <sub>r_HS</sub>
5	Turn off propagation delay HS	t <sub>d_off_</sub> HS
6	Fall time HS	t <sub>f_HS</sub>
7	Dead time falling	t <sub>dead_off</sub>
8	Rise time LS	t <sub>r LS</sub>

Note:

GH is referenced to the high side source. GL is referenced to the low side source.

a. Min. and Max. are not 100 % production tested.



#### SIC762CD BLOCK DIAGRAM

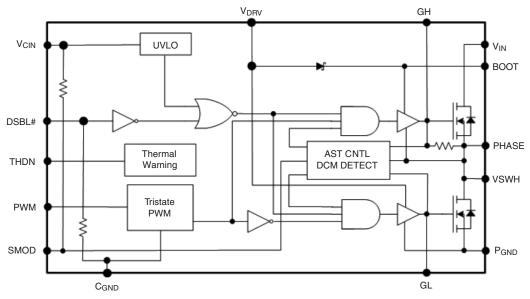


Figure 2

#### **DETAILED OPERATIONAL DESCRIPTION**

#### **PWM Input with Tristate Function**

The PWM input receives the PWM control signal from the V<sub>R</sub> controller IC. The PWM input is designed to be compatible with standard controllers using two state logic (H and L) and advanced controllers that incorporate Tristate logic (H. L and Tristate) on the PWM output. For two state logic, the PWM input operates as follows. When PWM is driven above  $V_{th\ pwm\ r}$  the low side is turned off and the high side is turned on. When PWM input is driven below  $V_{\mbox{\scriptsize th\_pwm\_f}}$  the high side turns off and the Low side turns on. For Tristate logic, the PWM input operates as above for driving the MOSFETs. However, there is an third state that is entered into as the PWM output of Tristate compatible controller enters its high impedance state during shut-down. The high impedance state of the controller's PWM output allows the SiC762CD to pull the PWM input into the Tristate region (see the Tristate Voltage Threshold Diagram below). If the PWM input stays in this region for the Tristate Hold-Off Period, t<sub>TSHO</sub>, both high side and low side MOSFETs are turned off. This function allows the V<sub>R</sub> phase to be disabled without negative output voltage swing caused by inductor ringing and saves a Schottky diode clamp. The PWM and Tristate regions are separated by hysteresis to prevent false triggering. The SiC762CD incorporates PWM voltage thresholds that are compatible with 5 V logic.

#### Disable (DSBL#)

In the low state, the DSBL# pin shuts down the driver IC and disables both high-side and low-side MOSFET. In this state, the standby current is minimized. If DSBL# is left unconnected an internal pull-down resistor will pull the pin down to  $C_{\mbox{\footnotesize GND}}$  and shut down the IC.

#### Diode Emulation Mode (SMOD) Skip Mode

When SMOD pin is low the diode emulation mode is enabled. This is a non-synchronous conversion mode that improves light load efficiency by reducing switching losses. Conducted losses that occur in synchronous buck regulators when inductor current is negative are also reduced. Circuitry in the gate drive IC detects when inductor current crosses zero and automatically stops switching the low side MOSFET. See SMOD Operation Diagram for additional details. This function can also be used for a pre-biased output voltage. If SMOD is left unconnected, an internal pull up resistor will pull the pin up to  $V_{\mbox{\footnotesize{CIN}}}$  (Logic High) to disable the diode emulation function.

#### Thermal Shutdown Warning (THDN)

The THDN pin is an open drain signal that flags the presence of excessive junction temperature. Connect a maximum of 20 k $\Omega$  to pull this pin up to  $V_{\text{CIN}}.$  An internal temperature sensor detects the junction temperature. The temperature threshold is 150 °C. When this junction temperature is exceeded the THDN flag is set. When the junction temperature drops below 135 °C the device will clear the THDN signal. The SiC762CD does not stop operation when the flag is set. The decision to shutdown must be made by an external thermal control function.

#### Voltage Input (V<sub>IN</sub>)

This is the power input to the drain of the high-side Power MOSFET. This pin is connected to the high power intermediate BUS rail.

#### Switch Node (V<sub>SWH</sub> and PHASE)

The Switch node  $V_{SWH}$  is the circuit PWM regulated output. This is the output applied to the filter circuit to deliver the



regulated high output for the buck converter. The PHASE pin is internally connected to the switch node  $V_{SWH}.$  This pin is to be used exclusively as the return pin for the BOOT capacitor. A 20.2  $k\Omega$  resistor is connected between GH and PHASE to provide a discharge path for the HS MOSFET in the event that  $V_{CIN}$  goes to zero while  $V_{IN}$  is still applied.

#### Ground connections (C<sub>GND</sub> and P<sub>GND</sub>)

 $P_{GND}$  (power ground) should be externally connected to  $C_{GND}$  (control signal ground). The layout of the Printed Circuit Board should be such that the inductance separating the  $C_{GND}$  and  $P_{GND}$  should be a minimum. Transient differences due to inductance effects between these two pins should not exceed 0.5 V.

#### Control and Drive Supply Voltage Input (VDRV, VCIN)

 $V_{CIN}$  is the bias supply for the gate drive control IC.  $V_{DRV}$  is the bias supply for the gate drivers. It is recommended to separate these pins through a resistor. This creates a low pass filtering effect to avoid coupling of high frequency gate drive noise into the IC.

#### **Bootstrap Circuit (BOOT)**

The internal bootstrap switch and an external bootstrap capacitor form a charge pump that supplies voltage to the BOOT pin. An integrated bootstrap diode is incorporated so that only an external capacitor is necessary to complete the bootstrap circuit. Connect a boot strap capacitor with one leg tied to BOOT pin and the other tied to PHASE pin.

## Shoot-Through Protection and Adaptive Dead Time (AST)

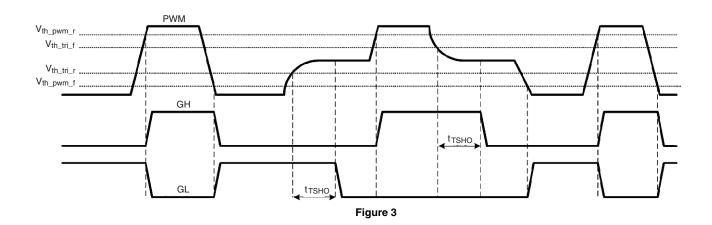
The SiC762CD has an internal adaptive logic to avoid shoot through and optimize dead time. The shoot through protection ensures that both high-side and low-side MOSFET are not turned on the same time. The adaptive dead time control operates as follows. When PWM input goes high the LS gate starts to go low after a few ns. When this signal crosses through 1.7 V the logic to switch the HS gate on is activated. When PWM goes low the HS gate goes low. When the HS gate-to-source drive signal crosses through 1.7 V the logic to turn on the LS gate is activated. This feature helps to adjust dead time as gate transitions change with respect to output current and temperature.

#### **Under Voltage Lockout (UVLO)**

During the start up cycle, the UVLO disables the gate drive holding high-side and low-side MOSFET gate low until the input voltage rail has reached a point at which the logic circuitry can be safely activated. The SiC762CD also incorporates logic to clamp the gate drive signals to zero when the UVLO falling edge triggers the shutdown of the device. As an added precaution, a 20.2  $k\Omega$  resistor is connected between GH and PHASE to provide a discharge path for the HS MOSFET.

DEVICE TRUTH T	ABLE			
DSBL#	SMOD	PWM	GH	GL
Open	X	X	L	L
L	X	X	L	L
Н	L	L	L	$H (I_L > 0), L (I_L \le 0)$
Н	L	Н	Н	L
Н	Н	Н	Н	L
Н	Н	Ĺ	L	Н

#### TRISTATE PWM VOLTAGE THRESHOLD DIAGRAM





#### **SMOD OPERATION DIAGRAM**

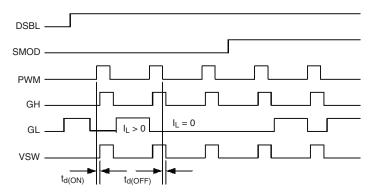


Figure 4

#### **PIN CONFIGURATION**

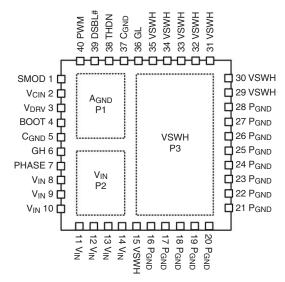
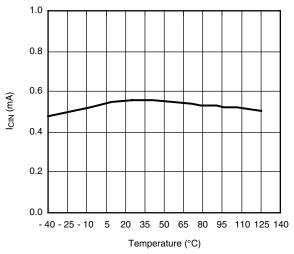


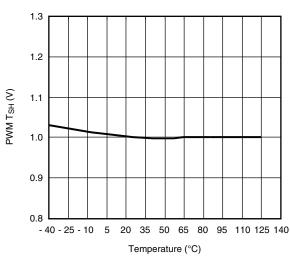
Figure 5 - PowerPAK MLP 6 x 6 40P Pin Out - Top View

PIN DESCR	RIPTION	
Pin Number	Symbol	Description
1	SMOD	Disable low side gate operation. Active low.
2	$V_{CIN}$	This will be the bias supply input for control IC (5 V).
3	$V_{DRV}$	IC bias supply and gate drive supply voltage (5 V).
4	BOOT	High side driver bootstrap voltage pin for external bootstrap capacitor.
5, 37, PAD1	$C_{GND}$	Control signal ground. It should be connected to P <sub>GND</sub> externally. All pins internally connected.
6	GH	Gate signal output pin for high side MOSFET. Pin for monitoring.
7	PHASE	Return pin for the HS bootstrap capacitor. Connect a 0.1 µF ceramic capacitor from this pin to the boot pin (4).
8 to 14, PAD2	$V_{IN}$	Input voltage for power stage. It is the drain of the high-side MOSFET.
15, 29 to 35, PAD3	VSWH	It is the phase node between high side MOSFET source and low side MOSFET drain. It should be connected to an output inductor. All pins internally connected.
16 to 28	$P_{GND}$	Power ground.
36	GL	Gate signal output pin for low side MOSFET. Pin for monitoring.
38	THDN	Thermal shutdown open drain output. Use a 10K pull up resistor to V <sub>CIN</sub> .
39	DSBL#	Disable pin. Active low.
40	PWM	PWM input logic signal. Compatible with Tristate controller function.

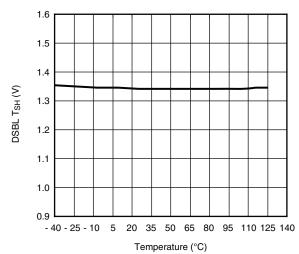
# VISHAY



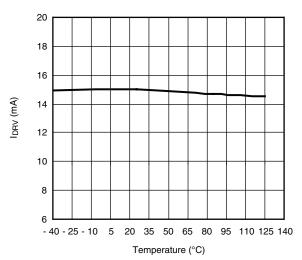
 $I_{CIN}$  (mA) vs. Temperature at Frequency = 300 kHz D = 10 %,  $V_{CIN}$  =  $V_{DRV}$  = 5 V



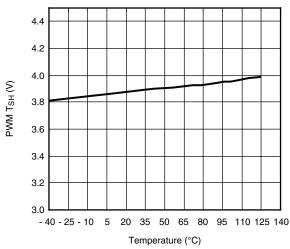
PWM Falling Threshold (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 \text{ V}$ 



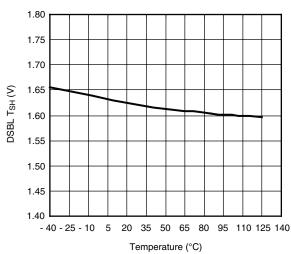
DSBL Falling Threshold (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 \text{ V}$ 



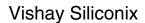
 $I_{DRV}$  (mA) vs. Temperature at Frequency = 300 kHz D = 10 %,  $V_{CIN}$  =  $V_{DRV}$  = 5 V



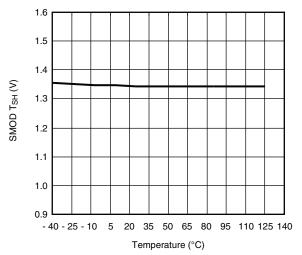
PWM Rising Threshold (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 \text{ V}$ 



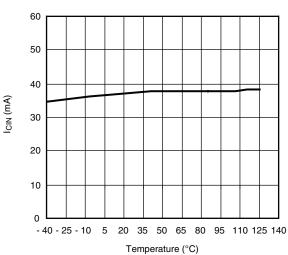
DSBL Rising Threshold (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 \ V$ 



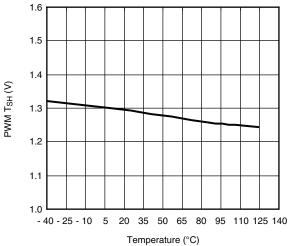




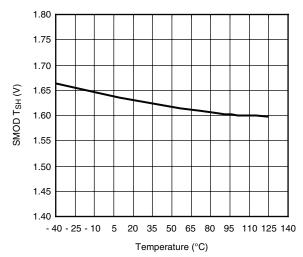
SMOD Falling Threshold (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 \text{ V}$ 



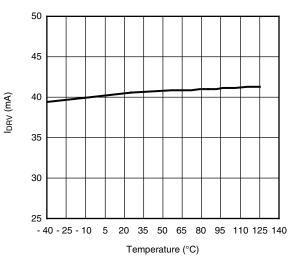
 $I_{CIN}$  +  $I_{DRV}$  (mA) vs. Temperature at Frequency = 1 MHz D = 10 %,  $V_{CIN}$  =  $V_{DRV}$  = 5 V



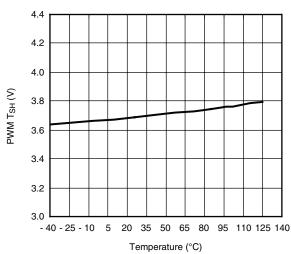
PWM Falling Tristate (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 V$ 



SMOD Rising Threshold (V) vs. Temperature (°C) V<sub>CIN</sub> = V<sub>DRV</sub> = 5 V

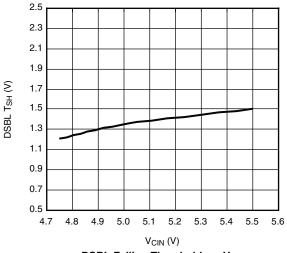


 $I_{DRV}$  (mA) vs. Temperature at Frequency = 1 MHz D = 10 %,  $V_{CIN}$  =  $V_{DRV}$  = 5 V

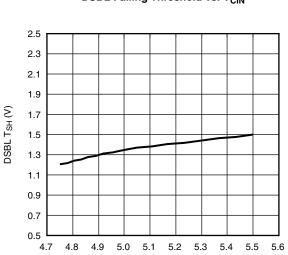


PWM Rising Tristate Threshold (V) vs. Temperature (°C)  $V_{CIN} = V_{DRV} = 5 \text{ V}$ 

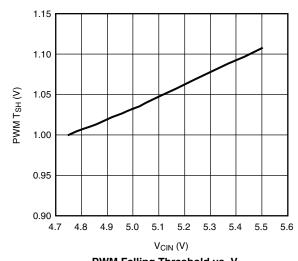
## VISHAY.



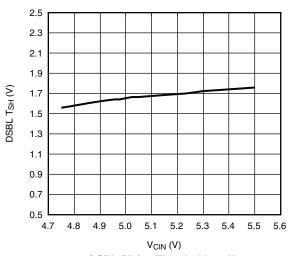
DSBL Falling Threshold vs.  $V_{CIN}$ 



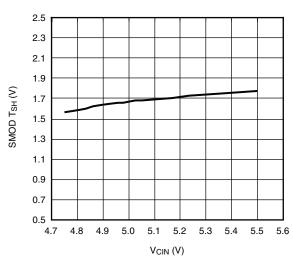
 $\label{eq:Vcin} \mathbf{V_{CIN}}\left(\mathbf{V}\right)$  SMOD Falling Threshold vs.  $\mathbf{V_{CIN}}$ 



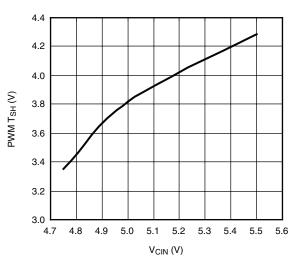
PWM Falling Threshold vs.  $V_{\text{CIN}}$ 



DSBL Rising Threshold vs. V<sub>CIN</sub>



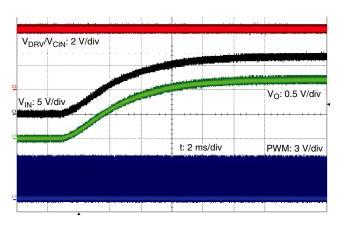
SMOD Rising Threshold vs.  $V_{CIN}$ 



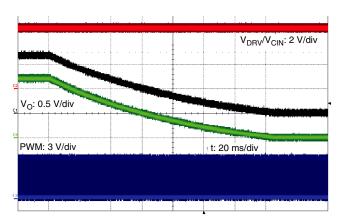
PWM Rising Threshold vs.  $V_{\rm CIN}$ 



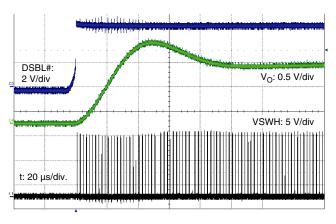




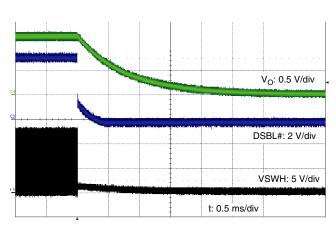
Startup with  $V_{IN}$  ramping up  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz



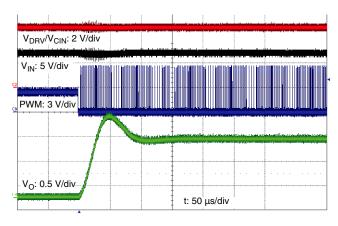
Power Off with  $V_{IN}$  ramping down  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_{S}$  = 500 kHz



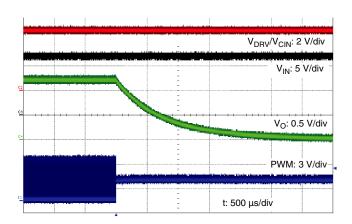
Enable with  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz



Disable with  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_{S}$  = 500 kHz

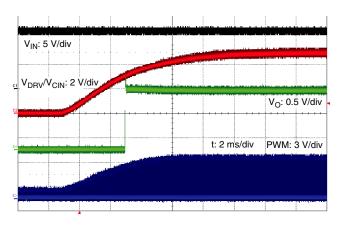


PWM Start with  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz

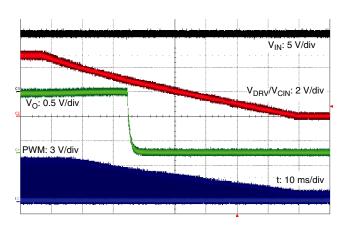


PWM Turn-off with  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz

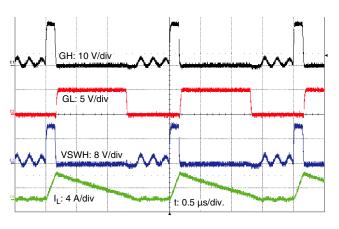
## VISHAY



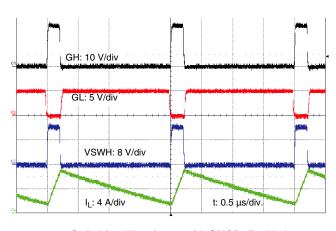
Startup with  $V_{DRV}/V_{CIN}$  ramping up  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_{S}$  = 500 kHz



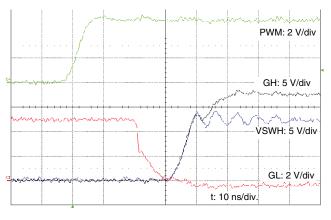
Power Off with  $V_{DRV}/V_{CIN}$  ramping down  $V_{IN} = 12 \text{ V}$ ,  $V_{OUT} = 1.2 \text{ V}$ ,  $F_S = 500 \text{ kHz}$ 



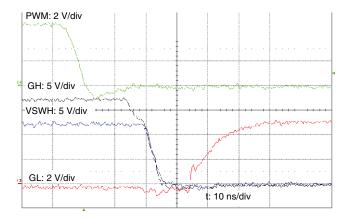
Switching Waveforms with SMOD enabled  $\rm V_{IN}$  = 12 V,  $\rm V_{OUT}$  = 1.2 V,  $\rm F_{S}$  = 500 kHz,  $\rm I_{OUT}$  = 1.5 A



Switching Waveforms with SMOD disabled  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz,  $I_{OUT}$  = 4 A



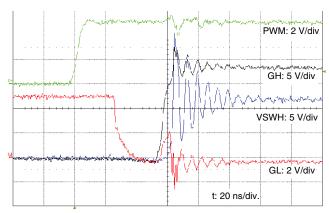
Switching Waveforms at PWM rising edge  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz,  $I_{OUT}$  = 0 A



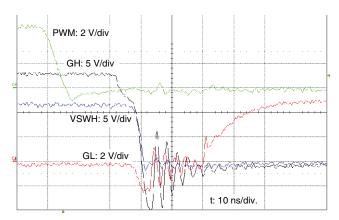
Switching Waveforms at PWM falling edge  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_{S}$  = 500 kHz,  $I_{OUT}$  = 0 A







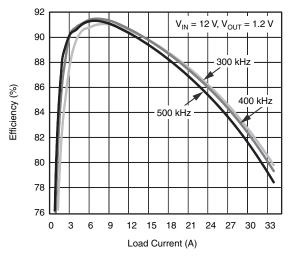
Switching Waveforms at PWM rising edge  $\rm V_{IN}=12~V,\,V_{OUT}=1.2~V,\,F_{S}=500~kHz,\,I_{OUT}=30~A$ 

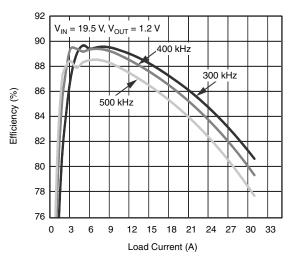


Switching Waveforms at PWM falling edge  $V_{IN}$  = 12 V,  $V_{OUT}$  = 1.2 V,  $F_S$  = 500 kHz,  $I_{OUT}$  = 30 A

# VISHAY

#### **TYPICAL SYSTEM EFFICIENCY WITH SIC762CD**

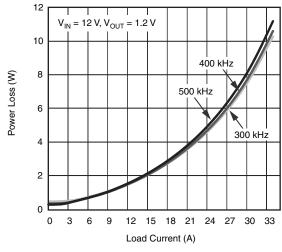


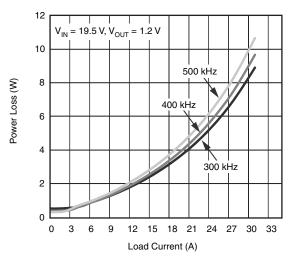


 $V_{IN}$  = 12 V and 19.5 V,  $V_{OUT}$  = 1.2 V,  $V_{DRV}$  =  $V_{CIN}$  = 5 V; No Air Flow IHLP5050FDERR33M01 Inductor L = 330 nH, DER = 0.83  $m\Omega$ 

Figure 6 - System Efficiency with SiC762

#### **TYPICAL SYSTEM POWER LOSS WITH SIC762CD**



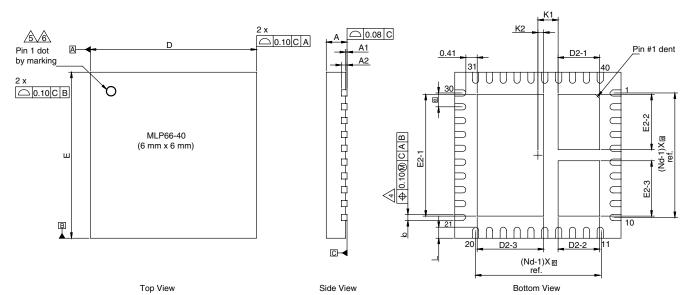


 $V_{IN}$  = 12 V and 19.5 V,  $V_{OUT}$  = 1.2 V,  $V_{DRV}$  =  $V_{CIN}$  = 5 V; No Air Flow IHLP5050FDERR33M01 Inductor L = 330 nH, DER = 0.83  $m\Omega$ 

Figure 7 - System Power Loss with SiC762



#### **PACKAGE DIMENSIONS**



DIM		MILLIMETERS			INCHES	
DIM	Min.	Nom.	Max.	Min.	Nom.	Max.
A <sup>(8)</sup>	0.70	0.75	0.80	0.027	0.029	0.031
A1	0.00	-	0.05	0.000	-	0.002
A2		0.20 ref.			0.008 ref.	
b <sup>(4)</sup>	0.20	0.25	0.30	0.078	0.098	0.011
D		6.00 BSC			0.236 BSC	
е		0.50 BSC			0.019 BSC	
E	6.00 BSC		0.236 BSC			
L	0.35	0.40	0.45	0.013	0.015	0.017
N <sup>(3)</sup>		40		40		
Nd <sup>(3)</sup>		10		10		
Ne <sup>(3)</sup>		10		10		
D2-1	1.45	1.50	1.55	0.057	0.059	0.061
D2-2	1.45	1.50	1.55	0.057	0.059	0.061
D2-3	2.35	2.40	2.45	0.095	0.094	0.096
E2-1	4.35	4.40	4.45	0.171	0.173	0.175
E2-2	1.95	2.00	2.05	0.076	0.078	0.080
E2-3	1.95	2.00	2.05	0.076	0.078	0.080
K1		0.73 BSC		0.028 BSC		
K2		0.21 BSC			0.008 BSC	

#### Notes:

- 1. Use millimeters as the primary measurement.
- 2. Dimensioning and tolerances conform to ASME Y14.5M-1994.
- 3. N is the number of terminals.

 $\operatorname{Nd}$  is the number of terminals in X-direction and  $\operatorname{Ne}$  is the number of terminals in Y-direction .

- Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip.
- $\sqrt{5}$ . The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body.
- 6. Exact shape and size of this feature is optional.
  - 7. Package warpage max. 0.08 mm.
  - 8. Applied only for terminals.

Figure 8 - PowerPAK MLP 66-40



#### LAND PATTERN DIMENSIONS

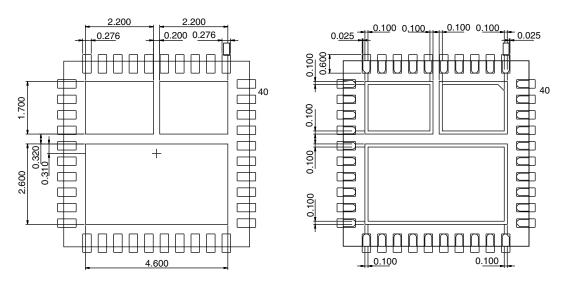
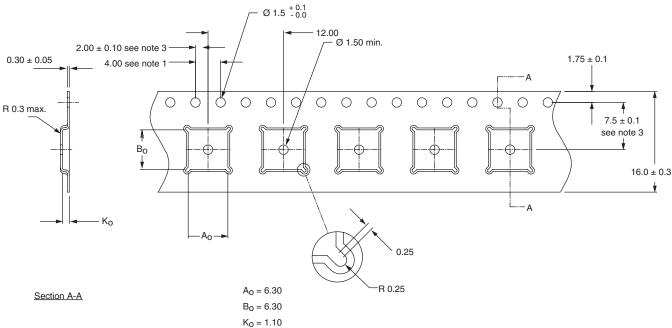


Figure 9 - PowerPAK MLP 66-40

#### TAPE AND REEL CARRIER TAPE DIMENSIONS



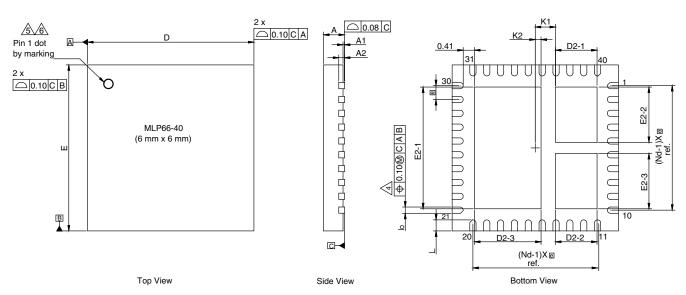
#### Notes:

- 1. 10 sprocket hole pitch cumulative tolerance  $\pm$  0.2.
- 2. Camber in compliance with EIA 481.
- 3. Pocket position relative to sprocket hole measured as true position of pocket, not pocket hole.

Figure 10 - PowerPAK MLP 66-40

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## PowerPAK® MLP66-40 Case Outline



DIM.	MILLIMETERS INCHES				INCHES	
Dilvi.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A <sup>(8)</sup>	0.70	0.75	0.80	0.027	0.029	0.031
A1	0.00	-	0.05	0.000	-	0.002
A2		0.20 ref.			0.008 ref.	
b <sup>(4)</sup>	0.20	0.25	0.30	0.078	0.098	0.011
D		6.00 BSC 0.236 BSC			0.236 BSC	
е		0.50 BSC			0.019 BSC	
Е		6.00 BSC	6.00 BSC 0.236 BSC			
L	0.35	0.40	0.45	0.013	0.015	0.017
N <sup>(3)</sup>	40			40		
Nd <sup>(3)</sup>		10		10		
Ne <sup>(3)</sup>		10		10		
D2-1	1.45	1.50	1.55	0.057	0.059	0.061
D2-2	1.45	1.50	1.55	0.057	0.059	0.061
D2-3	2.35	2.40	2.45	0.095	0.094	0.096
E2-1	4.35	4.40	4.45	0.171	0.173	0.175
E2-2	1.95	2.00	2.05	0.076	0.078	0.080
E2-3	1.95	2.00	2.05	0.076	0.078	0.080
K1		0.73 BSC		0.028 BSC		
K2	0.21 BSC 0.008 BSC					

#### Notes

DWG: 5986

- 1. Use millimeters as the primary measurement
- 2. Dimensioning and tolerances conform to ASME Y14.5M. 1994
- 3. N is the number of terminals. Nd is the number of terminals in X-direction and Ne is the number of terminals in Y-direction

 $\Delta$ Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip

The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body Exact shape and size of this feature is optional

7. Package warpage max. 0.08 mm

Applied only for terminals

Revision: 12-Jan-15 1 Document Number: 64846



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