

## Short Distance Proximity/Ambient Light Sensor with I<sup>2</sup>C Bus Interface



#### DESCRIPTION

VCNL4000 is a fully integrated proximity and ambient light digital 16-bit resolution sensor in a miniature lead less package (LLP) for surface mounting. It includes a signal processing IC and supports an easy to use I<sup>2</sup>C bus communication interface.

#### **FEATURES**

- Package type: surface mount
- Dimensions (L x W x H in mm): 3.95 x 3.95 x 0.75
- Integrated module with ambient light sensor, proximity sensor and signal conditioning IC
- Supply voltage range: 2.5 V to 3.6 V
- Communication via I<sup>2</sup>C interface
- I<sup>2</sup>C Bus H-level range: 1.7 V to 5 V
- Floor life: 168 h, MSL 3, acc. J-STD-020
- Low stand by current consumption: 1.5 µA
- Compliant to RoHS Directive 2002/95/EC and in accordance to WEEE 2002/96/EC

#### **PROXIMITY FUNCTION**

- · Built in infrared LED and photo-pin-diode for proximity function
- 16-bit effective resolution for proximity detection range ensures excellent cross talk immunity
- Programmable LED drive current from 10 mA to 200 mA (in 10 mA steps)
- Excellent ambient light suppression by signal modulation
- · Proximity distance up to 200 mm

#### **AMBIENT LIGHT FUNCTION**

- · Built in ambient light photo-pin-diode with close to human eye sensitivity characteristic
- 16-bit dynamic range for ambient light detection from 0.2 lx to 13 klx
- 100 Hz and 120 Hz flicker noise rejection

#### **APPLICATIONS**

- Proximity sensor for mobile devices (e.g. smart phones, touch phones, PDA, GPS) for touch screen locking, power saving, etc.
- Integrated ambient light function for display/keypad contrast control and dimming of mobile devices
- · Proximity/optical switch for consumer, computing and industrial devices and displays
- · Dimming control for consumer, computing and industrial displays

PRODUCT SUMMARY										
PART NUMBER	OPERATING RANGE	OPERATING VOLTAGE RANGE	I <sup>2</sup> C BUS VOLTAGE RANGE	LED PULSE CURRENT <sup>(1)</sup>	AMBIENT LIGHT RANGE	AMBIENT LIGHT RESOLUTION	OUTPUT CODE			
	mm	V	V	mA	lux	lux				
VCNL4000	1 to 200	2.5 to 3.6	1.7 to 5	10 to 200	0.2 to 13 000	0.2	16 bit, I <sup>2</sup> C			

Note

<sup>(1)</sup> Adjustable through I<sup>2</sup>C interface

\*\* Please see document "Vishay Material Category Policy": www.vishay.com/doc?99902



**RoHS** COMPLIANT

GREEN

(5-2008)



## Vishay Semiconductors Short Distance Proximity/Ambient Light Sensor with I<sup>2</sup>C Bus Interface

ORDERING INFORMATION								
ORDERING CODE PACKAGING		VOLUME <sup>(1)</sup>	REMARKS					
VCNL4000-GS08	Tapa and roal	MOQ: 1800 pcs	- 3.95 mm x 3.95 mm x 0.75 mm					
VCNL4000-GS18	Tape and Teel	MOQ: 7000 pcs						

Note

<sup>(1)</sup> MOQ: minimum order quantity

<b>ABSOLUTE MAXIMUM RATINGS</b> ( $T_{amb} = 25 \text{ °C}$ , unless otherwise specified)										
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT					
Supply voltage		V <sub>DD</sub>	- 0.3	5.5	V					
Operation temperature range		T <sub>amb</sub>	- 40	+ 85	°C					
Storage temperature range		T <sub>stg</sub>	- 40	+ 100	°C					
Total power dissipation	T <sub>amb</sub> ≤ 25 °C	P <sub>tot</sub>		50	mW					
Junction temperature		Tj		100	°C					

BASIC CHARACTERIST	<b>ICS</b> (T <sub>amb</sub> = 25 °C, unless o	therwise spe	ecified)			
PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage			2.5		3.6	V
I <sup>2</sup> C Bus H-level range			1.7		5	V
Current consumption	Standby current, no IRED-operation			1.5	2	μΑ
	2 measurements per second, IRED current 20 mA			4		μΑ
Current consumption proximity mode incl. IRED (averaged)	250 measurements per second, IRED current 20 mA			500		μA
	2 measurements per second, IRED current 200 mA			31		μA
	250 measurements per second, IRED current 200 mA			3.8		mA
	2 measurements per second averaging = 1			2.5		μA
Current consumption ambient	8 measurements per second averaging = 1			10		μA
light mode	2 measurements per second averaging = 64			160		μΑ
	8 measurements per second averaging = 64			635		μΑ
Ambient light resolution	Digital resolution (LSB count )			0.2		lx
Ambient light output when dark	E <sub>V</sub> = 0 averaging = 64	E <sub>V</sub> = 0 averaging = 64 0		5	counts	
Ambient light output	E <sub>V</sub> = 100 lx averaging = 64			500		counts
I <sup>2</sup> C clock rate range		f <sub>I2C</sub>			3400	kHz



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#### CIRCUIT BLOCK DIAGRAM



#### **TEST CIRCUIT**



#### Note

 nc must not be electrically connected Pads 8 to 11 are only considered as solder pads

#### BASIC CHARACTERISTICS (T<sub>amb</sub> = 25 °C, unless otherwise specified)



Fig. 1 - Idle Current vs. Ambient Temperature









## Vishay Semiconductors Short Distance Proximity/Ambient Light Sensor with I<sup>2</sup>C Bus Interface





Fig. 5 - Relative Radiant Intensity vs. Wavelength



Fig. 6 - Relative Radiant Intensity vs. Angular Displacement



Fig. 7 - Relative Spectral Sensitivity vs. Wavelength



Fig. 8 - Relative Radiant Sensitivity vs. Angular Displacement







Fig. 10 - Relative Spectral Sensitivity vs. Wavelength





Fig. 11 - Relative Radiant Sensitivity vs. Angular Displacement

#### **APPLICATION INFORMATION**

VCNL4000 is a cost effective solution of proximity and ambient light sensor with I<sup>2</sup>C Bus interface. The standard serial digital interface is easy to access "Proximity Signal" and "Light intensity" without complex calculation and programming by external controller.

#### **1. Application Circuit**





### Vishay Semiconductors Short Distance Proximity/Ambient Light Sensor with I<sup>2</sup>C Bus Interface

#### 2. I<sup>2</sup>C Interface

The VCNL4000 contains twelve 8 bit registers for operation control, parameter setup and result buffering. All registers are accessible via I<sup>2</sup>C communication. Figure 13 shows the basic I<sup>2</sup>C communication with VCNL4000. The built in I<sup>2</sup>C interface is compatible with all I<sup>2</sup>C modes (standard, fast and high speed).

 $I^2C$  H-level range = 1.7 V to 5 V.

Please refer to the I<sup>2</sup>C specification from NXP for details.



Fig. 13 - Send Byte/Receive Byte Protocol

#### **Device Address**

The VCNL4000 has a fix slave address for the host programming and accessing selection. The predefined 7 bit  $I^2C$  bus address is set to 0010 011 = 13h. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0010 011x = 26h for write, 27h for read.

#### **Register Addresses**

VCNL4000 has twelve user accessible 8 bit registers. The register addresses are 80h (register #0) to 8Bh (register #11).

#### **REGISTER FUNCTIONS**

#### **Register #0 Command Register**

Register address = 80h

The register #0 is for starting ambient light or proximity measurements. This register contains 2 flag bits for data ready indication.

TABLE 1 -	TABLE 1 - COMMAND REGISTER #0										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0				
Config log	als data rdy	Prox. data rdy	als od	Prox. od	N/A	N/A	N/A				
Description											
Config log Read only bit. Value = 1											
als data rdy Read only bit. Value = 1 when ambient light measurement data is available in the result registers. This will be reset when one of the corresponding result registers (reg #5, reg #6) is read.						egisters. This bit s read.					
Prox. c	lata rdy	Read only bit. Va be re	lue = 1 when prox eset when one of	imity measuremer the corresponding	nt data is available g result registers (r	e in the result regis reg #7, reg #8) is r	sters. This bit will ead.				
R/W bit. Starts a single on-demand measurement for ambient light. If averaging is enabled, starts als od sequence of readings and stores the averaged result. Result is available at the end of conversion f reading in the registers #5(HB) and #6(LB).						abled, starts a conversion for					
Prox. od R/W bit. Starts a single on-demand measurement for proximity. Result is available at the end of conversion for reading in the registers #7(HB) and #						nd #8(LB).					

With setting bit 3 and bit 4 at the same write command, a simultaneously measurement of ambient light and proximity is done.



#### **Register #1 Product ID Revision Register**

Register address = 81h. This register contains information about product ID and product revision. Register data value of current revision = 11h.

TABLE 2 - PRODUCT ID REVISION REGISTER #1										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
	Produ	uct ID		Revision ID						
			Descr	iption						
Prod	uct ID	Developed with Mallor of								
Revision ID										

#### **Register #2 without Function in Current Version**

Register address = 82h.

#### Register #3 LED Current Setting for Proximity Mode

Register address = 83h. This register is to set the LED current value for proximity measurement.

The value is adjustable in steps of 10 mA from 0 mA to 200 mA.

This register also contains information about the used device fuse program ID.

TABLE 3 - IR LED CURRENT REGISTER #3										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
Fuse prog ID IR LED current value										
Description										
Fuse p	orog ID	Informa	tion about fuse pr	Read of or	nly bits. ed for initial setup	/calibration of the	device.			
IR LED cu	R/W bits. IR LED current = Value (dec.) x 10 mA.IR LED current valueValid Range = 0 to 20d. e.g. 0 = 0 mA , 1 = 10 mA,, 20 = 200 mA (2 = 20 mA = DEFAULT)LED Current is limited to 200 mA for values higher as 20d.									

#### Register #4 Ambient Light Parameter Register

Register address = 84h.

TABLE 4 -	TABLE 4 - AMBIENT LIGHT PARAMETER REGISTER #4											
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0					
Cont. conv. mode		N/A		Auto offset compensation	Averaging function (number of measurements per run)							
			Desci	ription								
Bit 7       Enable = 1; Disable = 0 = DEFAULT         Cont. conversion mode       This function can be used for performing faster ambient light measurements. Please refer to application information chapter 3.3 for details about this function.						e refer to the						
Bi Auto offset c	t 3 compensation	In order to com With active auto o	R/W bit. Automatic offset compensation. Enable = 1 = DEFAULT Disable = 0 n order to compensate a technology, package or temperature related drift of the ambient light values there is a built in automatic offset compensation function. th active auto offset compensation the offset value is measured before each ambient light measurement and subtracted automatically from actual reading.									
Bit 0 t Averagin	o bit 2 g function	Bit values sets Number of c	R/W bits. Averaging function. the number of single conversions done during one measurement cycle. Result is the average value of all conversions. onversions = 2 <sup>decimal_value</sup> e.g. 0 = 1 conv., 1 = 2 conv, 2 = 4 conv.,7 = 128 conv. DEFAULT = 32 conv.									



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#### Register #5 and #6 Ambient Light Result Register

Register address = 85h and 86h. These registers are the result registers for ambient light measurement readings. The result is a 16 bit value. The high byte is stored in register #5 and the low byte in register #6.

TABLE 5 - AMBIENT LIGHT RESULT REGISTER #5										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
	Description									
Read only bits. High byte (15:8) of ambient light measurement result										

TABLE 6 - AMBIENT LIGHT RESULT REGISTER #6										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
	Description									
Read only bits. Low byte (7:0) of ambient light measurement result										

#### Register #7 and #8 Proximity Measurement Result Register

Register address = 87h and 88h. These registers are the result registers for proximity measurement readings. The result is a 16 bit value. The high byte is stored in register #7 and the low byte in register #8.

TABLE 7 - PROXIMITY RESULT REGISTER #7										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
Description										
Read only bits. High byte (15:8) of proximity measurement result										

TABLE 8 - PROXIMITY RESULT REGISTER #8										
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
Description										
Read only bits. Low byte (7:0) of proximity measurement result										

#### **Register #9 Proximity Measurement Signal Frequency**

Register address = 89h.

TABLE 9 - PROXIMITY MEASUREMENT SIGNAL FREQUENCY #9									
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
		N	/Α	Proximity frequency					
Description									
Bit 0 and 1 Proximity frequency		R/W bits. Setting the proximity IR test signal frequency. The proximity measurement is using a square IR signal as measurement signal. Four different values are possible: 00 = 3.125 MHz 01 = 1.5625 MHz 02 = 781.25 kHz (DEFAULT) 03 = 390.625 kHz							

#### Register #10 Proximity Modulator Timing Adjustment

Register address = 8Ah.

TABLE 10 - PROXIMITY MODULATOR TIMING ADJUSTMENT #10								
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
Modulation delay time			N/A		Modulation dead Time			
Description								
Modulation delay time A		R/W b Thi Also	/ bits. Setting a delay time between IR LED signal and IR input signal evaluation. This function is for compensation of delays from IR LED and IR photo diode. Iso in respect to the possibility for setting different proximity signal frequency. Correct adjustment is optimizing measurement signal level.					
R/W b Modulation dead Time		its. Setting a dead time in evaluation of IR signal at the slopes of the IR signal. This function is for reducing of possible disturbance effects. This function is reducing signal level and should be used carefully.						

Note

• The settings for best performance will be provided by Vishay. With first samples this is evaluated to: delay time = 4 and dead time = 1, with that register #10 should be programmed with: 129 (dez.)

#### Register #11 Ambient IR Light Level Register

Register address = 8Bh.

This register is not intended to be used by customer.

#### **3. IMPORTANT APPLICATION HINTS AND EXAMPLES**

#### 3.1 Receiver standby mode

In standby mode the receiver has the lowest current consumption of about 1.6 µA. In this mode only the I<sup>2</sup>C interface is active. This is always valid, when there are no measurement demands for proximity and ambient light executed. Also the current sink for the IR-LED is inactive, so there is no need for changing register #3 (IR LED current).

#### 3.2 Data Read

In order to get a certain register value, the register has to be addressed without data like shown in the following scheme. After this register addressing, the data from the addressed register is written after a subsequent read command.



The stop condition between these write and read sequences is not mandatory. It works also with a repeated start condition.

Note

• For reading out 2 (or more) subsequent registers like the result registers, it is not necessary to address each of the registers separately. After one read command the internal register counter is increased automatically and any subsequent read command is accessing the next register.

Example:read register #5 and #6:

Addressing:	command 26h 85h
Read register #5:	$command \ge 27h$
Read register #6:	$command \ge 27h$



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#### 3.3 Continuous Conversion Mode in Ambient Light Measurement

In the following is a detail description of the function "continuous conversion" (bit 7 of register #4)

#### Standard mode (bit 7 of reg #4 = 0):

In standard mode the ambient light measurement is done during a fixed time frame of 100 ms. The single measurement itself takes actually only appr. 300 µs.

The following figures show examples of this measurement timing in standard mode using averaging function 2 and 8 as examples for illustration (possible values up to 128).





Fig. 15 - Ambient Light Measurement with Averaging = 2; Final Measurement Result = Average of these 2 Measurements



Fig. 16 - Ambient Light Measurement with Averaging = 8; Final Measurement Result = Average of these 8 Measurements

#### Note

• ≥ Independent of setting of averaging the result is available only after 100 ms.

#### Continuous conversion mode (bit7 of reg #4 = 1):

In continuous conversion mode the single measurements are done directly subsequent after each other. See following examples in figure 17 and 18



Fig. 17 - Ambient Light Measurement with Averaging = 2; using Continuous Conversion Mode



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Fig. 18 - Ambient Light Measurement with Averaging = 8; using Continuous Conversion Mode



#### **PACKAGE DIMENSIONS** in millimeters





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#### TAPE AND REEL DIMENSIONS in millimeters



Drawing-No.: 9.800-510301-4 Issue: prel; 02.12.09 22319



#### SOLDER PROFILE



Fig. 19 - Lead (Pb)-free Reflow Solder Profile acc. J-STD-020

#### DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

#### **FLOOR LIFE**

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label: Floor life: 168 h Conditions:  $T_{amb} < 30$  °C, RH < 60 % Moisture sensitivity level 3, acc. to J-STD-020.

#### DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 °C (+ 5 °C), RH < 5 %.



Vishay

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