XL3483 SOP8
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## General Description

3483 and 3485，3．3V，low－power transceivers for RS－485 and RS－422 communication．Each
part contains one driver and one receiver．The 3483 feature slew－rate－limited drivers that minimize EMI and reduce reflections caused
by improperly terminated cables，allowing error－free data transmission at data rates up to 250 kbps ．
2.5 Mbps ． 3485 ，transmit at up to 10 Mbps ．

Drivers are short－circuit current limited and are protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high－impedance state．The receiver input has a fail－safe feature that guarantees a logic－high output if both inputs are open circuit．
－Slew－Rate Limited for Errorless Data Transmission
－-7 V to +12 V Common－Mode Input Voltage Range
－Full－Duplex and Half－Duplex Versions Available

## Features

Operate from a Single 3．3V Supply－ No Charge Pump！
－Interoperable with＋5V Logic
－8ns Max Skew 3485 3483
－2nA Low－Current Shutdown Mode 3483／3485
－Allows up to 32 Transceivers on the Bus
－Current－Limiting and Thermal Shutdown for Driver Overload Protection

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## Applications

Low－Power RS－485／RS－422 Transceivers
Telecommunications
Transceivers for EMI－Sensitive Applications
Industrial－Control Local Area Networks

## ABSOLUTE MAXIMUM RATINGS



| 14-Pin Plastic DIP (derate $10 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) $\ldots . . . . .800 \mathrm{~mW}$ |
| :--- |
| 14-Pin SO (derate $8.33 \mathrm{mWW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )............. 667 mW |
| Operating Temperature Ranges |
| $3483 / 3485 . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~$ | $5^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}+160^{\circ} \mathrm{C}$. 14-Pin SO (derate $8.33 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ )................ 667 mW Operating Temperature Ranges

Storage Temperature Range $-65^{\circ} \mathrm{C}$ to $+160^{\circ} \mathrm{C}$ Lead Temperature (soldering, 10 sec
$+300^{\circ} \mathrm{C}$ Continuous Power Dissipation ( $\mathrm{T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ )
8-Pin Plastic DIP (derate $9.09 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) $\ldots . .727 \mathrm{~mW}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## DC ELECTRICAL CHARACTERISTICS

$\left(\mathrm{V}_{C C}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}\right.$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ )

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Differential Driver Output | VOD | $\mathrm{RL}=100 \Omega$ (RS-422) |  | 2.0 |  | V |
|  |  | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ (RS-485), Figure 2 |  | 1.5 |  |  |
|  |  | $\mathrm{R}_{\mathrm{L}}=60 \Omega$ (RS-485), $\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}$, Figure 3 |  | 1.5 |  |  |
| Change in Magnitude of Driver Differential Output Voltage for Complementary Output States (Note 1) | $\Delta \mathrm{V}_{\mathrm{OD}}$ | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ or $100 \Omega$, Figure 4 |  |  | 0.2 | V |
| Driver Common-Mode Output Voltage | VOC | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ or $100 \Omega$, Figure 4 |  |  | 3 | V |
| Change in Magnitude of Common-Mode Output Voltage (Note 1) | $\Delta \mathrm{V}_{\mathrm{OC}}$ | $\mathrm{R}_{\mathrm{L}}=54 \Omega$ or $100 \Omega$, Figure 4 |  |  | 0.2 | V |
| Input High Voltage | $\mathrm{V}_{\mathrm{IH}}$ | DE, DI, RE |  | 2.0 |  | V |
| Input Low Voltage | VIL | DE, DI, $\overline{\mathrm{RE}}$ |  |  | 0.8 | V |
| Logic Input Current | IIN1 | DE, DI, $\overline{\mathrm{RE}}$ |  |  | $\pm 2$ | $\mu \mathrm{A}$ |
| Input Current (A, B) | IIN2 | $\begin{aligned} & \mathrm{DE}=0 \mathrm{~V}, \\ & \mathrm{~V} C \mathrm{C}=0 \mathrm{~V} \text { or } 3.6 \mathrm{~V} \end{aligned}$ | V IN $=12 \mathrm{~V}$ |  | 1.0 | mA |
|  |  |  | V IN $=-7 \mathrm{~V}$ |  | -0.8 |  |
| Receiver Differential Threshold Voltage | $\mathrm{V}_{\text {TH }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq 12 \mathrm{~V}$ |  | -0.2 | 0.2 | V |
| Receiver Input Hysteresis | $\Delta \mathrm{V}_{\text {TH }}$ | $\mathrm{V}_{\mathrm{CM}}=0 \mathrm{~V}$ |  |  | 50 | mV |
| Receiver Output High Voltage | V OH | IOUT $=-1.5 \mathrm{~mA}, \mathrm{~V}$ ID $=200 \mathrm{mV}$, Figure 4 |  | VCC - 0.4 |  | V |
| Receiver Output Low Voltage | VOL | IOUT $=2.5 \mathrm{~mA}, \mathrm{~V} \mathrm{~V}$ ( $=200 \mathrm{mV}$, Figure 4 |  |  | 0.4 | V |
| Three-State (High Impedance) Output Current at Receiver | lozr | $\mathrm{V}_{\mathrm{CC}}=3.6 \mathrm{~V}, 0 \mathrm{~V} \leq \mathrm{V}_{\text {OUT }} \leq \mathrm{V}_{\text {CC }}$ |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| Receiver Input Resistance | RIN | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq 12 \mathrm{~V}$ |  | 12 |  | $\mathrm{k} \Omega$ |

DC ELECTRICAL CHARACTERISTICS (continued)
$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V} \pm 0.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\text {MIN }}\right.$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ )

| PARAMETER | SYMBOL | CONDITIONS |  | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Current | Icc | No load,$\mathrm{DI}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CC}}$ | $\begin{aligned} & \mathrm{DE}=\mathrm{V}_{\mathrm{CC}}, \\ & \mathrm{RE}=0 \mathrm{~V} \text { or } \mathrm{V}_{\mathrm{CC}} \end{aligned}$ |  | 1.1 | 2.2 | mA |
|  |  |  | $\begin{aligned} & \mathrm{DE}=0 \mathrm{~V}, \\ & \mathrm{RE}=0 \mathrm{~V} \end{aligned}$ |  | 0.95 | 1.9 |  |
| Supply Current in Shutdown Mode | ISHDN | $\mathrm{DE}=0 \mathrm{~V}, \overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{CC}}, \mathrm{DI}=\mathrm{V}_{\mathrm{CC}}$ or 0 V |  |  | 0.002 | 1 | $\mu \mathrm{A}$ |
| Driver Short-Circuit Output Current | IOSD | $V_{\text {OUT }}=-7 \mathrm{~V}$ |  |  |  | -250 | mA |
|  |  | VOUT $=12 \mathrm{~V}$ |  |  |  | 250 |  |
| Receiver Short-Circuit Output Current | IOSR | $\mathrm{OV} \leq \mathrm{V}_{\mathrm{RO}} \leq \mathrm{V}_{\mathrm{CC}}$ |  | $\pm 8$ |  | $\pm 60$ | mA |

## DRIVER SWITCHING CHARACTERISTICS-3485

$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Differential Output Delay | tDD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 5 | 1 | 22 | 35 | ns |
| Driver Differential Output Transition Time | tTD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 5 | 3 | 8 | 25 | ns |
| Driver Propagation Delay, Low-to-High Level | tPLH | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 6 | 7 | 22 | 35 | ns |
| Driver Propagation Delay, High-to-Low Level | tPHL | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 6 | 7 | 22 | 35 | ns |
| \|tPLH - tphl ${ }^{\text {d }}$ Driver Propagation Delay Skew (Note 2) | tpDS | $R \mathrm{~L}=27 \Omega$, Figure 6 |  |  | 8 | ns |
| DRIVER OUTPUT ENABLE/DISABLE TIMES (3485) |  |  |  |  |  |  |
| Driver Output Enable Time to Low Level | tPZL | $\mathrm{R} \mathrm{L}=110 \Omega$, Figure 8 |  | 45 | 90 | ns |
| Driver Output Enable Time to High Level | tpzH | $\mathrm{RL}=110 \Omega$, Figure 7 |  | 45 | 90 | ns |
| Driver Output Disable Time from High Level | tPHZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 7 |  | 40 | 80 | ns |
| Driver Output Disable Time from Low Level | tPLZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 8 |  | 40 | 80 | ns |

## DRIVER SWITCHING CHARACTERISTICS—3483

$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Differential Output Delay | tDD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 600 | 900 | 1400 | ns |
| Driver Differential Output Transition Time | tTD | $\mathrm{R}_{\mathrm{L}}=60 \Omega$, Figure 7 | 400 | 700 | 1200 | ns |
| Driver Propagation Delay, Low-to-High Level | tpLH | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 700 | 1000 | 1500 | ns |
| Driver Propagation Delay, High-to-Low Level | tpHL | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 | 700 | 1000 | 1500 | ns |
| \|tPLH - tphL ${ }^{\text {D }}$ Driver Propagation Delay Skew (Note 2) | tpDS | $\mathrm{R}_{\mathrm{L}}=27 \Omega$, Figure 8 |  | 100 |  | ns |
| DRIVER OUTPUT ENABLE/DISABLE TIMES (3483 only) |  |  |  |  |  |  |
| Driver Output Enable Time to Low Level | tPZL | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 900 | 1300 | ns |
| Driver Output Enable Time to High Level | tpZH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 600 | 800 | ns |
| Driver Output Disable Time from High Level | tPHZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 50 | 80 | ns |
| Driver Output Disable Time from Low Level | tpLZ | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 10 |  | 50 | 80 | ns |
| Driver Output Enable Time from Shutdown to Low Level | tpSL | $R_{L}=110 \Omega$, Figure 10 |  | 1.9 | 2.7 | $\mu \mathrm{s}$ |
| Driver Output Enable Time from Shutdown to High Level | tPSH | $\mathrm{R}_{\mathrm{L}}=110 \Omega$, Figure 9 |  | 2.2 | 3.0 | $\mu \mathrm{s}$ |

## RECEIVER SWITCHING CHARACTERISTICS

$\left(\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right)$

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Time to Shutdown | tSHDN | $\begin{aligned} & \hline 3483 / 3485 \\ & \text { (Note 3) } \end{aligned}$ | 80 | 190 | 300 | ns |
| Receiver Propagation Delay, Low-to-High Level | trPLH | $\mathrm{V}_{\mathrm{ID}}=0 \mathrm{~V}$ to 3.0V, $\mathrm{CL}_{\mathrm{L}}=15 \mathrm{pF}$, Figure 9 | 25 | 65 | 90 | ns |
|  |  | 3483 | 25 | 75 | 120 |  |
| Receiver Propagation Delay, High-to-Low Level | trPHL | $\mathrm{V}_{\mathrm{ID}}=0 \mathrm{~V}$ to 3.0V, $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$, Figure 9 | 25 | 65 | 90 | ns |
|  |  | 3483 | 25 | 75 | 120 |  |
| \|tPLH - tPHL| Receiver Propagation Delay Skew | trPDS | $\mathrm{V}_{\mathrm{ID}}=0 \mathrm{~V}$ to 3.0V, $\mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$, Figure 9 |  |  | 10 | ns |
|  |  | 3483 |  |  | 20 |  |
| Receiver Output Enable Time to Low Level | tPRZL | $\begin{aligned} & C_{L}=15 p F, \text { Figure 10, } \\ & 3483 / 3485 \end{aligned}$ |  | 25 |  | ns |
| Receiver Output Enable Time to High Level | tprzH | $\begin{aligned} & C_{L}=15 \mathrm{pF}, \text { Figure } 10, \\ & 3483 / 3485 \end{aligned}$ |  | 25 |  | ns |
| Receiver Output Disable Time from High Level | tPRHZ | $\begin{aligned} & C_{L}=15 p F, \text { Figure } 10, \\ & 3483 / 3485 \end{aligned}$ |  | 25 |  | ns |
| Receiver Output Disable Time from Low Level | tPRLZ | $\begin{aligned} & \hline C_{L}=15 \mathrm{pF} \text {, Figure } 10, \\ & 3483 / 3485 \end{aligned}$ |  | 25 |  | ns |
| Receiver Output Enable Time from Shutdown to Low Level | tPRSL | $\begin{aligned} & C_{L}=15 p F, \text { Figure 10, } \\ & 3483 / 3485 \end{aligned}$ |  | 720 |  | ns |
| Receiver Output Enable Time from Shutdown to High Level | tPRSH | $\begin{aligned} & C_{L}=15 \mathrm{pF}, \text { Figure } 10, \\ & 3483 / 3485 \end{aligned}$ |  | 720 |  | ns |

Note 1: $\Delta \mathrm{V}_{\mathrm{OD}}$ and $\Delta \mathrm{V}_{\mathrm{OC}}$ are the changes in $\mathrm{V}_{O D}$ and $\mathrm{V}_{\mathrm{OC}}$, respectively, when the DI input changes state.
Note 2: Measured on |tpLH (Y) - tphl (Y)| and |tpLH (Z) - tphl (Z)|.
Note 3: The transceivers are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 80 ns , the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 300 ns , the parts are guaranteed to have entered shutdown. See Low-Power Shutdown Mode section.

## Typic al Operating Characteristics

$\left(\mathrm{V} C \mathrm{C}=3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted.)


## Typical Operating Characteristics (continued)




## Pin Description

| PIN |  |  |
| :---: | :---: | :--- |
| $\mathbf{3 4 8 3 / 3 4 8 5}$ | NAME | $\quad$ FUNCTION |$|$| RO |
| :--- |
| 1 |



Figure 1. 3483/3485 Pin Configuration and Typical Operating Circuit


Figure 2. Driver $V_{O D}$ and $V_{O C}$


Figure 4. Receiver $V_{O H}$ and $V_{O L}$


Figure 5. Driver Differential Output Delay and Transition Times


Figure 6. Driver Propagation Times

in


Figure 7. Driver Enable and Disable Times ( $t_{\text {PZH }}, t_{P S H}, t_{\text {PHZ }}$ )


Figure 8. Driver Enable and Disable Times ( $\left.t_{\text {PZL }}, t_{P S L}, t_{P L Z}\right)$


Figure 9. Receiver Propagation Delay


Figure 10. Receiver Enable and Disable Times

Note 4: The input pulse is supplied by a generator with the following characteristics: $\mathrm{PRR}=250 \mathrm{kHz}, 50 \%$ duty cycle, $\mathrm{tr} \leq 6.0 \mathrm{~ns}, \mathrm{ZO}=50 \Omega$. Note 5: $\mathrm{C}_{\mathrm{L}}$ includes probe and stray capacitance.



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