

General Description

The AD8631A (single), AD8632A (dual) and AD8634A (quad) are low noise, low voltage, and micro power operational amplifiers. With an excellent bandwidth of 6.5MHz, a slew rate of 4V/ μ s, and a quiescent current of 480 μ A per amplifier at 5V, the AD863xA family can be designed into a wide range of applications.

The AD863xA op-amps are designed to provide optimal performance in low voltage and low noise systems. The input common-mode voltage range includes ground, and the maximum input offset voltage are 4.2mV. These parts provide rail-to-rail output swing into heavy loads. The AD863xA family is specified for single or dual power supplies of +2.3V to +5.5V. All models are specified over the extended industrial temperature range of -40°C to +125°C.

The AD8631A is available in 5-lead SC70 and SOT-23 packages. The AD8632A is available in 8-lead MSOP, TSSOP and SOIC packages. The AD8634A is available in 14-lead TSSOP and SOIC packages.

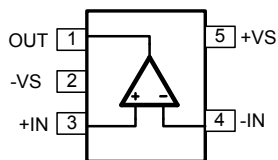
Features

- High Slew Rate: 4V/ μ s
- Wide Bandwidth: 6.5MHz
- Low Power: 480 μ A per Amplifier Supply Current
- Settling Time to 0.1% with 2V Step: 1 μ s
- Low Noise: 20 nV/ $\sqrt{\text{Hz}}$ @10KHz
- High Gains of 103 dB for Active Filters and Gain Stages
- Low Offset Voltage: 4.2 mV Maximum
- Unit Gain Stable
- Rail-to-Rail Input and Output
 - Input Voltage Range: -0.1V to +5.1V at 5V Supply
- Operating Power Supply: +2.3V to +5.5V
- Operating Temperature Range: -40°C to +125°C

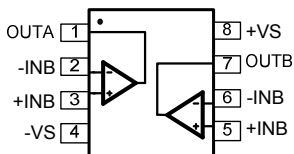
Applications

- Photodiode Amplification
- Sensor Interfaces
- Audio Outputs
- Active Filters
- Driving A/D Converters
- Portable Equipment & Battery-Powered Instrumentation

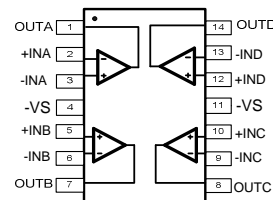
Pin Configurations



AD8631
SOT23-5



AD8632A
MSOP-8/SOP-8/TSSOP-8



AD8634
SOP-14

Pin Description

| Pin | Symbol | Description |
|-----|--------|---|
| 1 | -IN | Inverting Input of the Amplifier. The Voltage range can go from ($V_{S-} - 0.1V$) to ($V_{S+} + 0.1V$). |
| 2 | +IN | Non-Inverting Input of Amplifier. This pin has the same voltage range as -IN. |
| 3 | +VS | Positive Power Supply. The voltage is from 2.3V to 5.5V. Split supplies are possible as long as the voltage between V_{S+} and V_{S-} is between 2.3V and 5.5V. A bypass capacitor of 0.1µF as close to the part as possible should be used between power supply pins or between supply pins and ground |
| 4 | -VS | Negative Power Supply. It is normally tied to ground. It can also be tied to a voltage other than ground as long as the voltage between V_{S+} and V_{S-} is from 2.3V to 5.5V. If it is not connected to ground, bypass it with a capacitor of 0.1µF as close to the part as possible. |
| 5 | OUT | Amplifier Output |
| 6 | N/C | No Connection |

Absolute Maximum Ratings (T_A= 25°C)

| Symbol | Description | Value | Units |
|----------------------------------|--|--|--------|
| V _{S+} ,V _{S-} | Supply Voltage, V _{S+} to V _{S-} | 7.0 | V |
| V _{CM} | Common-Mode Input Voltage | V _{S-} - 0.3 to V _{S+} + 0.3 | V |
| ESD | Electrostatic Discharge Voltage | HBM ±4000 | V |
| | | CDM ±1000 | V |
| T _J | Junction Temperature | 160 | °C |
| T _{STG} | Storage Temperature Range | -65 to +150 | °C(TJ) |
| T _{JL} | Lead Temperature Range (Soldering 10 sec) | 260 | °C |

Note:

1. Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
2. Provided device does not exceed maximum junction temperature (T_J) at any time.

Electrical Characteristics

$V_S = 5.0V$, $T_A = +25^\circ C$, $V_{CM} = V_S/2$, $V_O = V_S/2$, and $R_L = 10k\Omega$ connected to $V_S/2$, unless otherwise noted.

| Symbol | Parameter | Conditions | Min. | Typ. | Max. | Unit |
|-------------------------------|------------------------------|--|--------------|--------------|--------------|------------------|
| INPUT CHARACTERISTICS | | | | | | |
| V_{OS} | Input offset voltage | | -4.2 | ± 0.8 | +4.2 | mV |
| | Over temperature | | -4.5 | | +4.5 | |
| V_{OSTC} | Offset voltage drift | | | 2 | | $\mu V/^\circ C$ |
| I_B | Input bias current | | | 1 | | pA |
| | Over temperature | | | 800 | | |
| I_{OS} | Input offset current | | | 1 | | pA |
| V_{CM} | Common-mode voltage range | | $V_{S-}-0.1$ | | $V_{S+}+0.1$ | V |
| CMRR | Common-mode rejection ratio | $V_{CM} = 0.05V$ to $3.5V$ | | 84 | | dB |
| | Over temperature | | | 80 | | |
| | | $V_{CM} = V_{S-}-0.1$ to $V_{S+}+0.1$ V | | 76 | | |
| A_{VOL} | Open-loop voltage gain | $R_L = 10k\Omega$, $V_O = 0.05$ to 3.5 V | | 100 | | dB |
| | Over temperature | | | 90 | | |
| | | $R_L = 600\Omega$, $V_O = 0.15$ to 3.5 V | | 86 | | |
| | Over temperature | | | 80 | | |
| R_{IN} | Input resistance | | | 100 | | G Ω |
| C_{IN} | Input capacitance | Differential | | 2.0 | | pF |
| | | Common mode | | 3.5 | | |
| OUTPUT CHARACTERISTICS | | | | | | |
| V_{OH} | High output voltage swing | $R_L = 600\Omega$ | | $V_{S+}-130$ | | mV |
| | | $R_L = 10k\Omega$ | | $V_{S+}-12$ | | |
| V_{OL} | Low output voltage swing | $R_L = 600\Omega$ | | 120 | | mV |
| | | $R_L = 10k\Omega$ | | 7 | | |
| Z_{OUT} | Closed-loop output impedance | $f = 200kHz$, $G = +1$ | | 0.4 | | Ω |
| | Open-loop output impedance | $f = 1MHz$, $I_O = 0$ | | 2.6 | | |
| I_{SC} | Short-circuit current | Source current through 10Ω | | 40 | | mA |
| | | Sink current through 10Ω | | 30 | | |
| DYNAMIC PERFORMANCE | | | | | | |
| GBW | Gain bandwidth product | $f = 1kHz$ | | 6.5 | | MHz |
| Φ_M | Phase margin | $C_L = 100pF$ | | 60 | | $^\circ$ |
| SR | Slew rate | $G = +1$, $C_L = 100pF$, $V_O = 1.5V$ to $3.5V$ | | 4 | | V/ μs |
| BW _P | Full power bandwidth | <1% distortion | | 300 | | KHz |

Electrical Characteristics

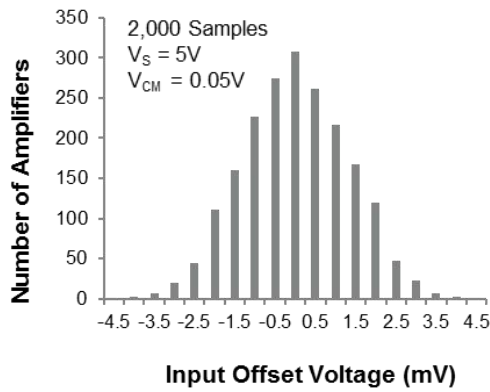
$V_S = 5.0V$, $T_A = +25^\circ C$, $V_{CM} = V_S/2$, $V_O = V_S/2$, and $R_L = 10k\Omega$ connected to $V_S/2$, unless otherwise noted.

| Symbol | Parameter | Conditions | Min. | Typ. | Max. | Unit |
|-------------------------|-----------------------------------|--|------|------|------|-------------------|
| t _s | Settling time | To 0.1%, G = +1, 2V step | | 1 | | µs |
| | | To 0.01%, G = +1, 2V step | | 1.2 | | |
| t _{OR} | Overload recovery time | V _{IN} * Gain > V _S | | 0.5 | | µs |
| NOISE PERFORMANCE | | | | | | |
| V _n | Input voltage noise | f = 0.1 to 10 Hz | | 12 | | µV _{P-P} |
| e _n | Input voltage noise density | f = 10kHz | | 20 | | nV/√Hz |
| I _n | Input current noise density | f = 10kHz | | 5 | | fA/√Hz |
| POWER SUPPLY | | | | | | |
| V _S | Operating supply voltage | | 2.3 | | 5.5 | V |
| PSRR | Power supply rejection ratio | V _S = 2.7V to 5.5V, V _{CM} < V _{S+} - 2V | | 84 | | dB |
| | Over temperature | | | 80 | | |
| I _Q | Quiescent current (per amplifier) | | | 480 | | µA |
| | Over temperature | | | 520 | | |
| THERMAL CHARACTERISTICS | | | | | | |
| T _A | Operating temperature range | | -40 | | +125 | °C |
| θ _{JA} | Package thermal resistance | SOT23-5 | | 190 | | °C/W |
| | | MSOP-8 | | 216 | | |
| | | SOP-8 | | 125 | | |
| | | TSSOP-8 | 6 | 153 | | |

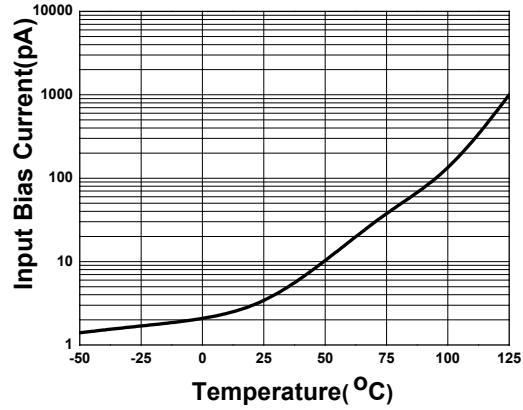
specifications subject to changes without notice

Typical Performance Characteristics

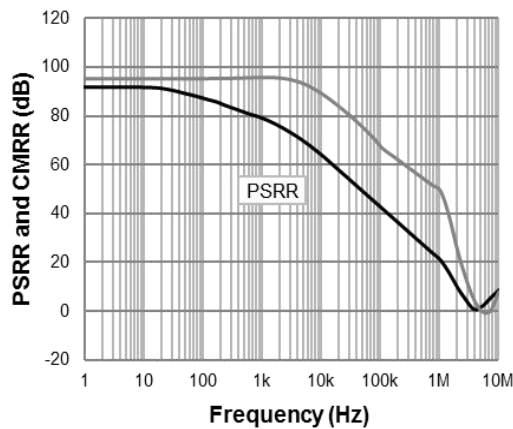
At $T_A = +25^\circ\text{C}$, $V_{CM} = V_S/2$, and $R_L = 10\text{k}\Omega$ connected to $V_S/2$, unless otherwise noted.



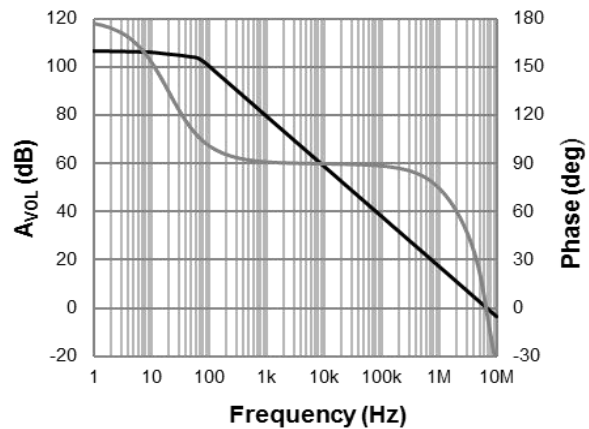
Input Offset Voltage Production Distribution



Input Bias Current as a function of Temperature



Power Supply and Common-mode Rejection Ratio as a function of Frequency.



Open-loop Gain and Phase as a function of Frequency

Application Notes

Low Input Bias Current

The AD863xA family is a CMOS op-amp family and features very low input bias current in pA range. The low input bias current allows the amplifiers to be used in applications with high resistance sources. Care must be taken to minimize PCB Surface Leakage. See below section on “PCB Surface Leakage” for more details.

PCB Surface Leakage

In applications where low input bias current is critical, Printed Circuit Board (PCB) surface leakage effects need to be considered. Surface leakage is caused by humidity, dust or other contamination on the board. Under low humidity conditions, a typical resistance between nearby traces is $10^{12}\Omega$. A 5V difference would cause 5pA of current to flow, which is greater than the AD863xA’s input bias current at +25°C ($\pm 1\text{fA}$, typical). It is recommended to use multi-layer PCB layout and route the op-amp’s –IN and +IN signal under the PCB surface.

The effective way to reduce surface leakage is to use a guard ring around sensitive pins (or traces). The guard ring is biased at the same voltage as the sensitive pin. An example of this type of layout is shown in Figure 1 for Inverting Gain application.

1. For Non-Inverting Gain and Unity-Gain Buffer:
 - a) Connect the non-inverting pin (+IN) to the input with a wire that does not touch the PCB surface.
 - b) Connect the guard ring to the inverting input pin (–IN). This biases the guard ring to the Common Mode input voltage.
2. For Inverting Gain and Trans-impedance Gain Amplifiers (convert current to voltage, such as photo detectors):
 - a) Connect the guard ring to the non-inverting input pin (+IN). This biases the guard ring to the same reference voltage as the op-amp (e.g., $V_s/2$ or ground).
 - b) Connect the inverting pin (–IN) to the input with a wire that does not touch the PCB surface

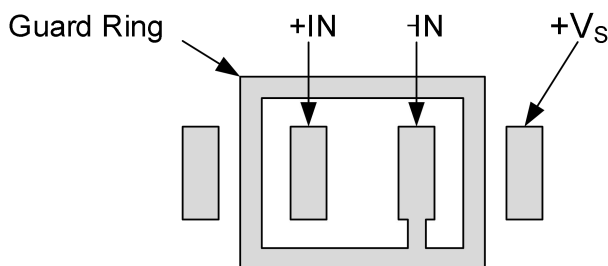


Figure 1. Use a guard ring around sensitive pins

Application Notes

Ground Sensing And Rail To Rail

The input common-mode voltage range of the AD863xA series extends 300mV beyond the supply rails. This is achieved with a complementary input stage—a N-channel input differential pair in parallel with a P-channel differential pair. For normal operation, inputs should be limited to this range. The absolute maximum input voltage is 500mV beyond the supplies. Inputs greater than the input common-mode range but less than the maximum input voltage, while not valid, will not cause any damage to the op-amp. Unlike some other op-amps, if input current is limited, the inputs may go beyond the supplies without phase inversion, as shown in Figure 2. Since the input common-mode range extends from $(V_{S-} - 0.1V)$ to $(V_{S+} + 0.1V)$, the AD863x op-amps can easily perform ‘true ground’ sensing.

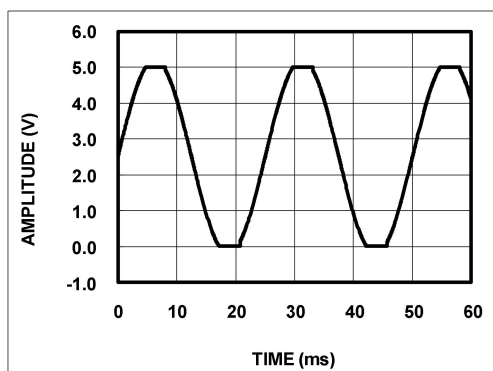


Figure 2. No Phase Inversion with Inputs Greater Than the Power-Supply Voltage

A topology of class AB output stage with common-source transistors is used to achieve rail-to-rail output. For light resistive loads (e.g. 100kΩ), the output voltage can typically swing to within 5mV from the supply rails. With moderate resistive loads (e.g. 10kΩ), the output can typically swing to within 10mV from the supply rails and maintain high open-loop gain. See the Typical Characteristic curve, Output Voltage Swing as a function of Output Current, for more information.

The maximum output current is a function of total supply voltage. As the supply voltage to the amplifier increases, the output current capability also increases. Attention must be paid to keep the junction temperature of the IC below 150°C when the output is in continuous short-circuit. The output of the amplifier has reverse-biased ESD diodes connected to each supply. The output should not be forced more than 0.5V beyond either supply, otherwise current will flow through these diodes.

Capacitive Load And Stability

The AD863xA can directly drive 1nF in unity-gain without oscillation. The unity-gain follower (buffer) is the most sensitive configuration to capacitive loading.

Application Notes

Direct capacitive loading reduces the phase margin of amplifiers and this results in ringing or even oscillation. Applications that require greater capacitive drive capability should use an isolation resistor between the output and the capacitive load like the circuit in Figure 3. The isolation resistor R_{ISO} and the load capacitor C_L form a zero to increase stability. The bigger the R_{ISO} resistor value, the more stable V_{OUT} will be. Note that this method results in a loss of gain accuracy because R_{ISO} forms a voltage divider with the R_L .

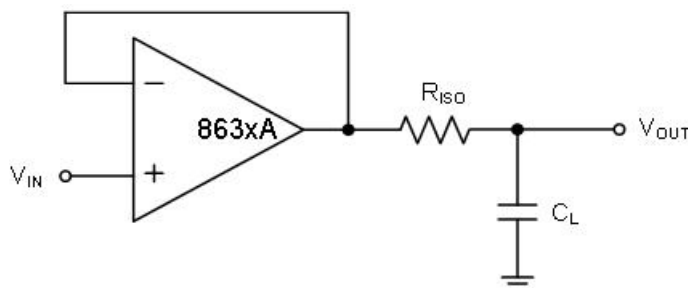


Figure 3. Indirectly Driving Heavy Capacitive Load

An improvement circuit is shown in Figure 4. It provides DC accuracy as well as AC stability. The R_F provides the DC accuracy by connecting the inverting signal with the output.

The C_F and R_{ISO} serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier’s inverting input, thereby preserving phase margin in the overall feedback loop.

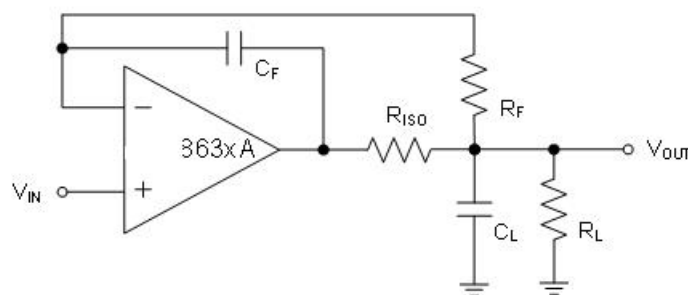


Figure 4. Indirectly Driving Heavy Capacitive Load with DC Accuracy

For no-buffer configuration, there are two other ways to increase the phase margin: (a) by increasing the amplifier’s gain, or (b) by placing a capacitor in parallel with the feedback resistor to counteract the parasitic capacitance associated with inverting node.

Power Supply Layout And Bypass

The AD863xA family operates from either a single +2.3V to +5.5V supply or dual ± 1.15 V to ± 2.25 V supplies. For single-supply operation, bypass the power supply

Application Notes

V_S with a ceramic capacitor (i.e. 0.01 μ F to 0.1 μ F) which should be placed close (within 2mm for good high frequency performance) to the V_S pin. For dual-supply operation, both the V_{S+} and the V_{S-} supplies should be bypassed to ground with separate 0.1 μ F ceramic capacitors. A bulk capacitor (i.e. 2.2 μ F or larger tantalum capacitor) within 100mm to provide large, slow currents and better performance. This bulk capacitor can be shared with other analog parts.

Good PC board layout techniques optimize performance by decreasing the amount of stray capacitance at the op-amp's inputs and output. To decrease stray capacitance, minimize trace lengths and widths by placing external components as close to the device as possible. Use surface-mount components whenever possible. For the op-amp, soldering the part to the board directly is strongly recommended. Try to keep the high frequency big current loop area small to minimize the EMI (electromagnetic interfacing).

Grounding

A ground plane layer is important for the AD863xA circuit design. The length of the current path speed currents in an inductive ground return will create an unwanted voltage noise. Broad ground plane areas will reduce the parasitic inductance.

Input To Output Coupling

To minimize capacitive coupling, the input and output signal traces should not be parallel. This helps reduce unwanted positive feedback.

Typical Application Circuits

Differential Amplifier

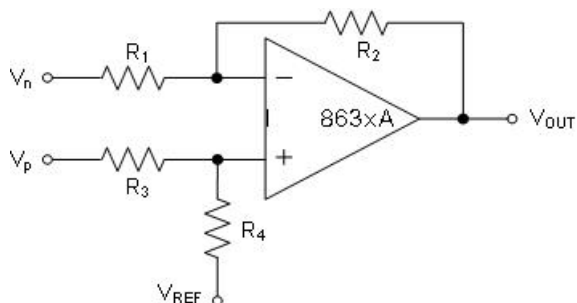
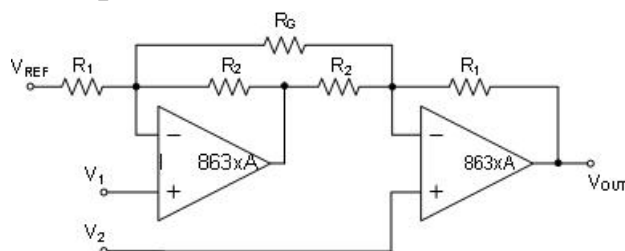


Figure 5. Differential Amplifier

The circuit shown in Figure 5 performs the difference function. If the resistors ratios are equal $R_4/R_3 = R_2/R_1$, then:

$$V_{OUT} = (V_p - V_n) \times R_2/R_1 + V_{REF}$$

Instrumentation Amplifier

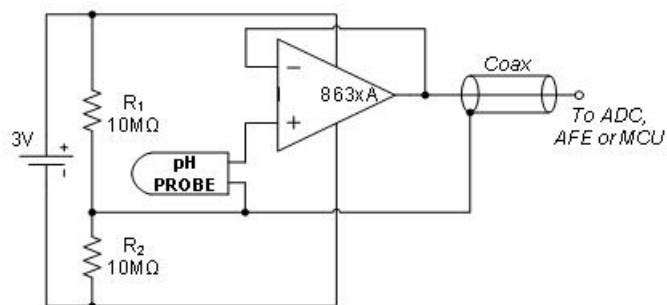


$$V_{OUT} = (V_1 - V_2) \left(1 + \frac{R_1}{R_2} + \frac{2R_1}{R_3} \right) + V_{REF}$$

Figure 6. Instrumentation Amplifier

The AD863xA family is well suited for conditioning sensor signals in battery-powered applications. Figure 6 shows a two op-amp instrumentation amplifier, using the AD863xA op-amps. The circuit works well for applications requiring rejection of common-mode noise at higher gains. The reference voltage (V_{REF}) is supplied by a low-impedance source. In single voltage supply applications, the V_{REF} is typically $V_S/2$.

Buffered Chemical Sensors



All components contained within the pH probe

Typical Application Circuits

The AD863xA family has input bias current in the pA range. This is ideal in buffering high impedance chemical sensors, such as pH probes. As an example, the circuit in Figure 7 eliminates expansive low-leakage cables that is required to connect a pH probe (general purpose combination pH probes, e.g Corning 476540) to metering ICs such as ADC, AFE and/or MCU. An AD863xA op-amp and a lithium battery are housed in the probe assembly. A conventional low-cost coaxial cable can be used to carry the op-amp’s output signal to subsequent ICs for pH reading.

Shunt-Based Current Sensing Amplifier

The current sensing amplification shown in Figure 8 has a slew rate of $2\pi fV_{PP}$ for the output of sine wave signal, and has a slew rate of $2fV_{PP}$ for the output of triangular wave signal. In most of motor control systems, the PWM frequency is at 10kHz to 20kHz, and one cycle time is 100µs for a 10kHz of PWM frequency. In current shunt monitoring for a motor phase, the phase current is converted to a phase voltage signal for ADC sampling. This sampling voltage signal must be settled before entering the ADC. As the Figure 8 shown, the total settling time of a current shunt monitor circuit includes: the rising edge delay time (t_{SR}) due to the op-amp’s slew rate, and the measurement settling time (t_{SET}). If the minimum duty cycle of the PWM is defined at 5%, and the t_{SR} is required at 20% of a total time window for a phase current monitoring, in case of a 3.3V motor control system (3.3V MCU with 12-bit ADC), the op-amp’s slew rate should be more than:

$$3.3V / (100\mu s \times 5\% \times 20\%) = 3.3 V/\mu s$$

At the same time, the op-amp’s bandwidth should be much greater than the PWM frequency, like 10 time at least.

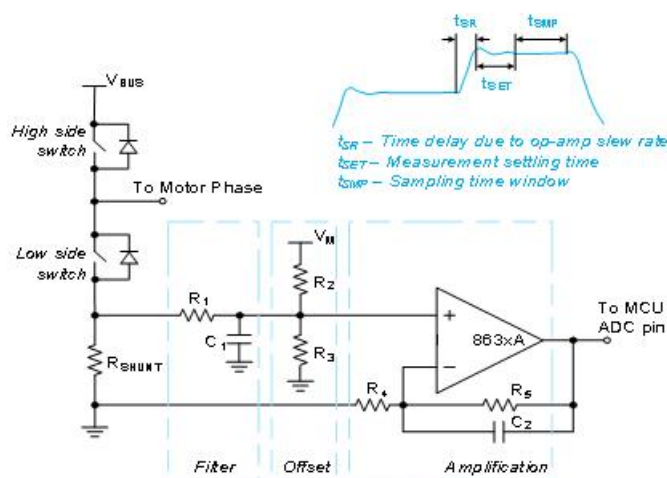
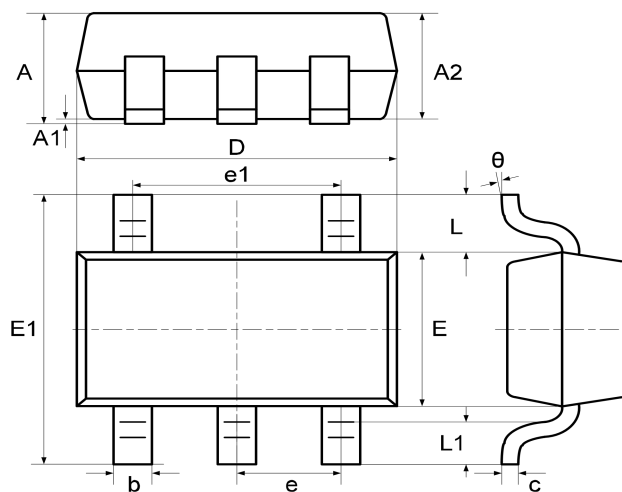


Figure 8. Current Shunt Monitor Circuit

Package Information

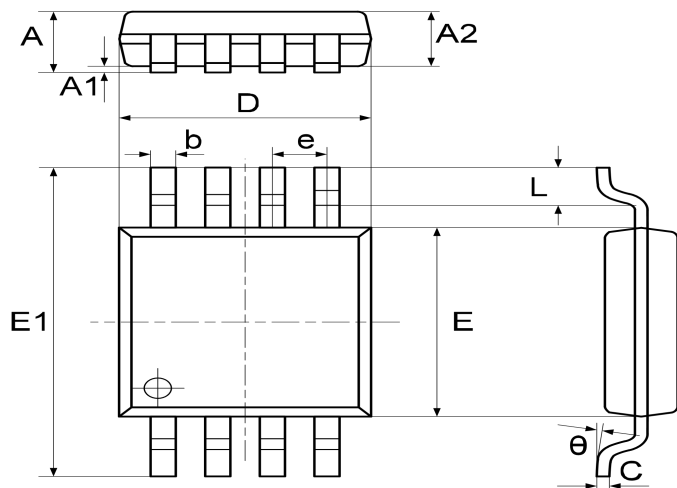
SOT23-5



| Symbol | Dimensions In Millimeters | | Dimensions In Inches | |
|--------|------------------------------|-------|-------------------------|-------|
| | Min | Max | Min | Max |
| A | 1.040 | 1.350 | 0.042 | 0.055 |
| A1 | 0.040 | 0.150 | 0.002 | 0.006 |
| A2 | 1.000 | 1.200 | 0.041 | 0.049 |
| b | 0.380 | 0.480 | 0.015 | 0.020 |
| c | 0.110 | 0.210 | 0.004 | 0.009 |
| D | 2.720 | 3.120 | 0.111 | 0.127 |
| E | 1.400 | 1.800 | 0.057 | 0.073 |
| E1 | 2.600 | 3.000 | 0.106 | 0.122 |
| e | 0.950 typ. | | 0.037 typ. | |
| e1 | 1.900 typ. | | 0.078 typ. | |
| L | 0.700 ref. | | 0.028 ref. | |
| L1 | 0.300 | 0.600 | 0.012 | 0.024 |
| θ | 0° | 8° | 0° | 8° |

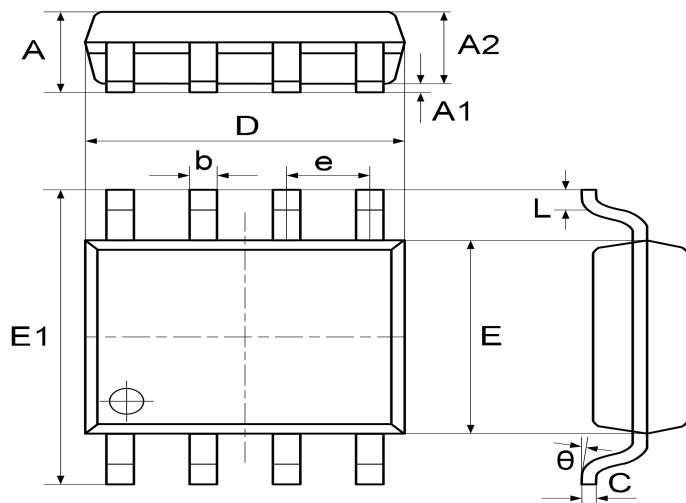
Package Information

MSOP-8



| Symbol | Dimensions In Millimeters | | Dimensions In Inches | |
|----------|---------------------------|-------|----------------------|-------|
| | Min | Max | Min | Max |
| A | 0.800 | 1.100 | 0.033 | 0.045 |
| A1 | 0.050 | 0.150 | 0.002 | 0.006 |
| A2 | 0.750 | 0.950 | 0.031 | 0.039 |
| b | 0.290 | 0.380 | 0.012 | 0.016 |
| C | 0.150 | 0.200 | 0.006 | 0.008 |
| D | 2.900 | 3.100 | 0.118 | 0.127 |
| E | 2.900 | 3.100 | 0.118 | 0.127 |
| E1 | 4.700 | 5.100 | 0.192 | 0.208 |
| e | 0.650 typ. | | 0.026 typ. | |
| L | 0.400 | 0.700 | 0.016 | 0.029 |
| θ | 0° 8° | | 0° 8° | |

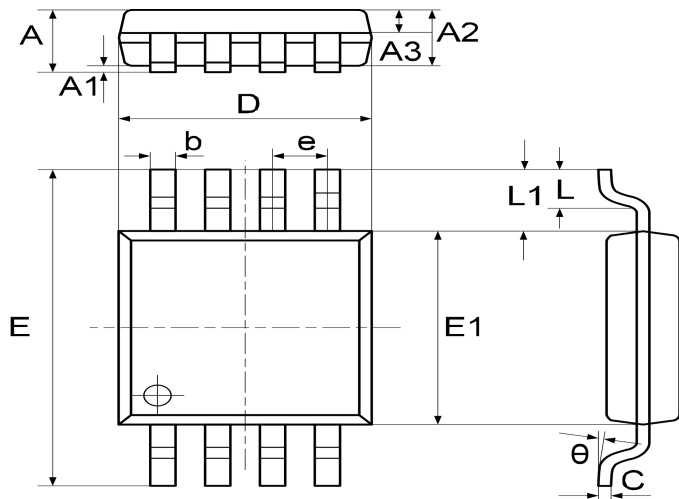
SOP-8



| Symbol | Dimensions In Millimeters | | Dimensions In Inches | |
|----------|---------------------------|-------|----------------------|-------|
| | Min | Max | Min | Max |
| A | 1.370 | 1.670 | 0.056 | 0.068 |
| A1 | 0.070 | 0.170 | 0.003 | 0.007 |
| A2 | 1.300 | 1.500 | 0.053 | 0.061 |
| b | 0.306 | 0.506 | 0.013 | 0.021 |
| C | 0.203 typ. | | 0.008 typ. | |
| D | 4.700 | 5.100 | 0.192 | 0.208 |
| E | 3.820 | 4.020 | 0.156 | 0.164 |
| E1 | 5.800 | 6.200 | 0.237 | 0.253 |
| e | 1.270 typ. | | 0.050 typ. | |
| L | 0.450 | 0.750 | 0.018 | 0.306 |
| θ | 0° 8° | | 0° 8° | |

Package Information

TSSOP-8



| Symbol | Dimensions In Millimeters | | |
|--------|------------------------------|-------|-------|
| | Min | Nom | Max |
| A | - | - | 1.200 |
| A1 | 0.050 | - | 0.150 |
| A2 | 0.900 | 1.000 | 1.050 |
| A3 | 0.390 | 0.440 | 0.490 |
| b | 0.200 | - | 0.280 |
| C | 0.130 | - | 0.170 |
| D | 2.900 | 3.000 | 3.100 |
| E | 6.200 | 6.400 | 6.600 |
| E1 | 4.300 | 4.400 | 4.500 |
| e | 0.65BSC | | |
| L | 0.450 | - | 0.750 |
| L1 | 1.000 ref | | |
| θ | 0° | - | 8° |

Ordering information

| Order code | Package | Baseqty | Deliverymode |
|----------------|---------|---------|---------------|
| UMW AD8631ARTZ | SOT23-5 | 3000 | Tape and reel |
| UMW AD8632ARZ | SOP-8 | 2500 | Tape and reel |
| UMW AD8632ARM | MSOP-8 | 2500 | Tape and reel |
| UMW AD8632ART | TSSOP-8 | 5000 | Tape and reel |

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